Welcome to E-XFL.COM

Understanding Embedded - DSP (Digital Signal Processors)

Embedded - DSP (Digital Signal Processors) are specialized microprocessors designed to perform complex mathematical computations on digital signals in real-time. Unlike general-purpose processors, DSPs are optimized for high-speed numeric processing tasks, making them ideal for applications that require efficient and precise manipulation of digital data. These processors are fundamental in converting and processing signals in various forms, including audio, video, and communication signals, ensuring that data is accurately interpreted and utilized in embedded systems.

Applications of Embedded - DSP (Digital Signal Processors)

Details	
Product Status	Obsolete
Type	Fixed Point
Interface	Synchronous Serial Port (SSP)
Clock Rate	40MHz
Non-Volatile Memory	External
On-Chip RAM	80kB
Voltage - I/O	5.00V
Voltage - Core	5.00V
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	128-LQFP
Supplier Device Package	128-TQFP (14x20)
Purchase URL	https://www.e-xfl.com/product-detail/analog-devices/adsp-2181kstz-160

ADSP-2181* PRODUCT PAGE QUICK LINKS

Last Content Update: 02/23/2017

COMPARABLE PARTS

View a parametric search of comparable parts.

EVALUATION KITS

- EZ-ICE® Serial Emulator for ADSP-218x Processor Family

DOCUMENTATION

Application Notes

- AN-1: ADSP-21xx Legacy Application Notes
- AN-227: Digital Control System Design with the ADSP-2100 Family
- AN-227: Digital Control System Design with the ADSP-2100 Family
- AN-334: Digital Signal Processing Techniques
- AN-348: Avoiding Passive-Component Pitfalls
- AN-400: Considerations for Selecting a DSP Processor -- Why Buy the ADSP-2181?
- AN-415: ADSP-2181 IDMA Interface to Motorola MC68300 Family of Microprocessors
- AN-524: ADV601/ADV611 Bin Width Calculation in ADSP-21xx DSP
- AN-543: High Quality, All-Digital RF Frequency Modulation Generation with the ADSP-2181 and the AD9850 DDS
- EE-06: ADSP-21xx Serial Port Startup Issues
- EE-100: ADSP-218x External Overlay Memory
- EE-102: Mode D and ADSP-218x Pin Compatibility - the FAQs
- EE-103: Performing Level Conversion Between 5v and 3.3v IC's
- EE-104: Setting Up Streams with the VisualDSP Debugger
- EE-11: ADSP-2181 Priority Chain & IDMA Holdoffs
- EE-110: A Quick Primer on ELF and DWARF File Formats
- EE-115: ADSP-2189 IDMA Interface to Motorola MC68300 Family of Microprocessors
- EE-12: Interrupts and Programmable Flags on the ADSP-2185/2186
- EE-121: Porting Code from ADSP-21xx to ADSP-219x
- EE-122: Coding for Performance on the ADSP-219x
- EE-123: An Overview of the ADSP-219x Pipeline
- EE-124: Booting up the ADSP-2192
- EE-125: ADSP-218x Embedded System Software Management and In-System-Programming (ISP)
- EE-128: DSP in C++: Calling Assembly Class Member Functions From C++
- EE-129: ADSP-2192 Interprocessor Communication
- EE-130: Making Fast Transition from ADSP-21xx to ADSP-219x

- VisualDSP++ 3.5 C/C++ Compiler and Library Manual for ADSP-219x Processors
- VisualDSP++ 3.5 Linker and Utilities Manual for 16-Bit Processors

SOFTWARE AND SYSTEMS REQUIREMENTS

- Software and Tools Anomalies Search

TOOLS AND SIMULATIONS

- ADSP-21xx Processors: Software and Tools

DESIGN RESOURCES

- ADSP-2181 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

DISCUSSIONS

View all ADSP-2181 EngineerZone Discussions.

SAMPLE AND BUY

Visit the product page to see pricing options.

TECHNICAL SUPPORT

Submit a technical question or find your regional support number.

DOCUMENT FEEDBACK

Submit feedback for this data sheet.

This takes place while the processor continues to:

- Receive and transmit data through the two serial ports
- Receive and/or transmit data through the internal DMA port
- Receive and/or transmit data through the byte DMA port
- Decrement timer

Development System

The ADSP-2100 Family Development Software, a complete set of tools for software and hardware system development, supports the ADSP-2181. The System Builder provides a high level method for defining the architecture of systems under development. The Assembler has an algebraic syntax that is easy to program and debug. The Linker combines object files into an executable file. The Simulator provides an interactive instruction-level simulation with a reconfigurable user interface to display different portions of the hardware environment. A PROM Splitter generates PROM programmer compatible files. The C Compiler, based on the Free Software Foundation's GNU C Compiler, generates ADSP-2181 assembly source code. The source code debugger allows programs to be corrected in the C environment. The Runtime Library includes over 100 ANSI-standard mathematical and DSP-specific functions.

The EZ-KIT Lite is a hardware/software kit offering a complete development environment for the entire ADSP-21xx family: an ADSP-2181 evaluation board with PC monitor software plus Assembler, Linker, Simulator, and PROM Splitter software. The ADSP-218x EZ-KIT Lite is a low-cost, easy to use hardware platform on which you can quickly get started with your DSP software design. The EZ-KIT Lite includes the following features:

- 33 MHz ADSP-2181
- Full 16-bit Stereo Audio I/O with AD1847 SoundPort® Codec
- RS-232 Interface to PC with Windows 3.1 Control Software
- Stand-Alone Operation with Socketed EPROM
- EZ-ICE® Connector for Emulator Control
- DSP Demo Programs

The ADSP-218x EZ-ICE Emulator aids in the hardware debugging of ADSP-218x systems. The emulator consists of hardware, host computer resident software and the target board connector. The ADSP-218x integrates on-chip emulation support with a 14-pin ICE-Port interface. This interface provides a simpler target board connection requiring fewer mechanical clearance considerations than other ADSP-2100 Family EZ-ICEs. The ADSP-218x device need not be removed from the target system when using the EZ-ICE, nor are any adapters needed. Due to the small footprint of the EZ-ICE connector, emulation can be supported in final board designs.

The EZ-ICE performs a full range of functions, including:

- In-target operation
- Up to 20 breakpoints
- Single-step or full-speed operation
- Registers and memory values can be examined and altered
- PC upload and download functions
- Instruction-level emulation of program booting and execution
- Complete assembly and disassembly of instructions
- C source-level debugging

See the Designing An EZ-ICE-Compatible Target System section of this data sheet for exact specifications of the EZ-ICE target board connector.

EZ-ICE and SoundPort are registered trademarks of Analog Devices, Inc.

Additional Information

This data sheet provides a general overview of ADSP-2181 functionality. For additional information on the architecture and instruction set of the processor, refer to the *ADSP-2100 Family User's Manual, Third Edition*. For more information about the development tools, refer to the *ADSP-2100 Family Development Tools Data Sheet*.

ARCHITECTURE OVERVIEW

The ADSP-2181 instruction set provides flexible data moves and multifunction (one or two data moves with a computation) instructions. Every instruction can be executed in a single processor cycle. The ADSP-2181 assembly language uses an algebraic syntax for ease of coding and readability. A comprehensive set of development tools supports program development.

Figure 1 is an overall block diagram of the ADSP-2181. The processor contains three independent computational units: the ALU, the multiplier/accumulator (MAC) and the shifter. The computational units process 16-bit data directly and have provisions to support multiprecision computations. The ALU performs a standard set of arithmetic and logic operations; division primitives are also supported. The MAC performs single-cycle multiply, multiply/add and multiply/subtract operations with 40 bits of accumulation. The shifter performs logical and arithmetic shifts, normalization, denormalization and derive exponent operations. The shifter can be used to efficiently implement numeric format control including multiword and block floating-point representations.

The internal result (R) bus connects the computational units so that the output of any unit may be the input of any unit on the next cycle.

A powerful program sequencer and two dedicated data address generators ensure efficient delivery of operands to these computational units. The sequencer supports conditional jumps, subroutine calls and returns in a single cycle. With internal loop counters and loop stacks, the ADSP-2181 executes looped code with zero overhead; no explicit jump instructions are required to maintain loops.

Two data address generators (DAGs) provide addresses for simultaneous dual operand fetches (from data memory and program memory). Each DAG maintains and updates four address pointers. Whenever the pointer is used to access data (indirect addressing), it is post-modified by the value of one of four possible modify registers. A length value may be associated with each pointer to implement automatic modulo addressing for circular buffers.

Efficient data transfer is achieved with the use of five internal buses:

- Program Memory Address (PMA) Bus
- Program Memory Data (PMD) Bus
- Data Memory Address (DMA) Bus
- Data Memory Data (DMD) Bus
- Result (R) Bus

The two address buses (PMA and DMA) share a single external address bus, allowing memory to be expanded off-chip, and the two data buses (PMD and DMD) share a single external data bus. Byte memory space and I/O memory space also share the external buses.

Program memory can store both instructions and data, permitting the ADSP-2181 to fetch two operands in a single cycle, one from program memory and one from data memory. The

ADSP-2181 can fetch an operand from program memory and the next instruction in the same cycle.

In addition to the address and data bus for external memory connection, the ADSP-2181 has a 16-bit Internal DMA port (IDMA port) for connection to external systems. The IDMA port is made up of 16 data/address pins and five control pins. The IDMA port provides transparent, direct access to the DSPs on-chip program and data RAM.

An interface to low cost byte-wide memory is provided by the Byte DMA port (BDMA port). The BDMA port is bidirectional and can directly address up to four megabytes of external RAM or ROM for off-chip storage of program overlays or data tables.

The byte memory and I/O memory space interface supports slow memories and I/O memory-mapped peripherals with programmable wait state generation. External devices can gain control of external buses with bus request/grant signals ($\overline{BR}$, $\overline{BGH}$ and $\overline{BG}$). One execution mode (Go Mode) allows the ADSP-2181 to continue running from on-chip memory. Normal execution mode requires the processor to halt while buses are granted.

The ADSP-2181 can respond to 13 possible interrupts, eleven of which are accessible at any given time. There can be up to six external interrupts (one edge-sensitive, two level-sensitive and three configurable) and seven internal interrupts generated by the timer, the serial ports (SPORTs), the Byte DMA port and the power-down circuitry. There is also a master $\overline{RESET}$ signal.

The two serial ports provide a complete synchronous serial interface with optional companding in hardware and a wide variety of framed or frameless data transmit and receive modes of operation. Each port can generate an internal programmable serial clock or accept an external serial clock.

The ADSP-2181 provides up to 13 general-purpose flag pins. The data input and output pins on SPORT1 can be alternatively configured as an input flag and an output flag. In addition, there are eight flags that are programmable as inputs or outputs and three flags that are always outputs.

A programmable interval timer generates periodic interrupts. A 16-bit count register (TCOUNT) is decremented every *n* processor cycles, where *n* is a scaling value stored in an 8-bit register (TSCALE). When the value of the count register reaches zero, an interrupt is generated and the count register is reloaded from a 16-bit period register (TPERIOD).

Serial Ports

The ADSP-2181 incorporates two complete synchronous serial ports (SPORT0 and SPORT1) for serial communications and multiprocessor communication.

Here is a brief list of the capabilities of the ADSP-2181 SPORTs. Refer to the *ADSP-2100 Family User's Manual, Third Edition* for further details.

- SPORTs are bidirectional and have a separate, double-buffered transmit and receive section.
- SPORTs can use an external serial clock or generate their own serial clock internally.
- SPORTs have independent framing for the receive and transmit sections. Sections run in a frameless mode or with frame synchronization signals internally or externally generated. Frame sync signals are active high or inverted, with either of two pulsewidths and timings.

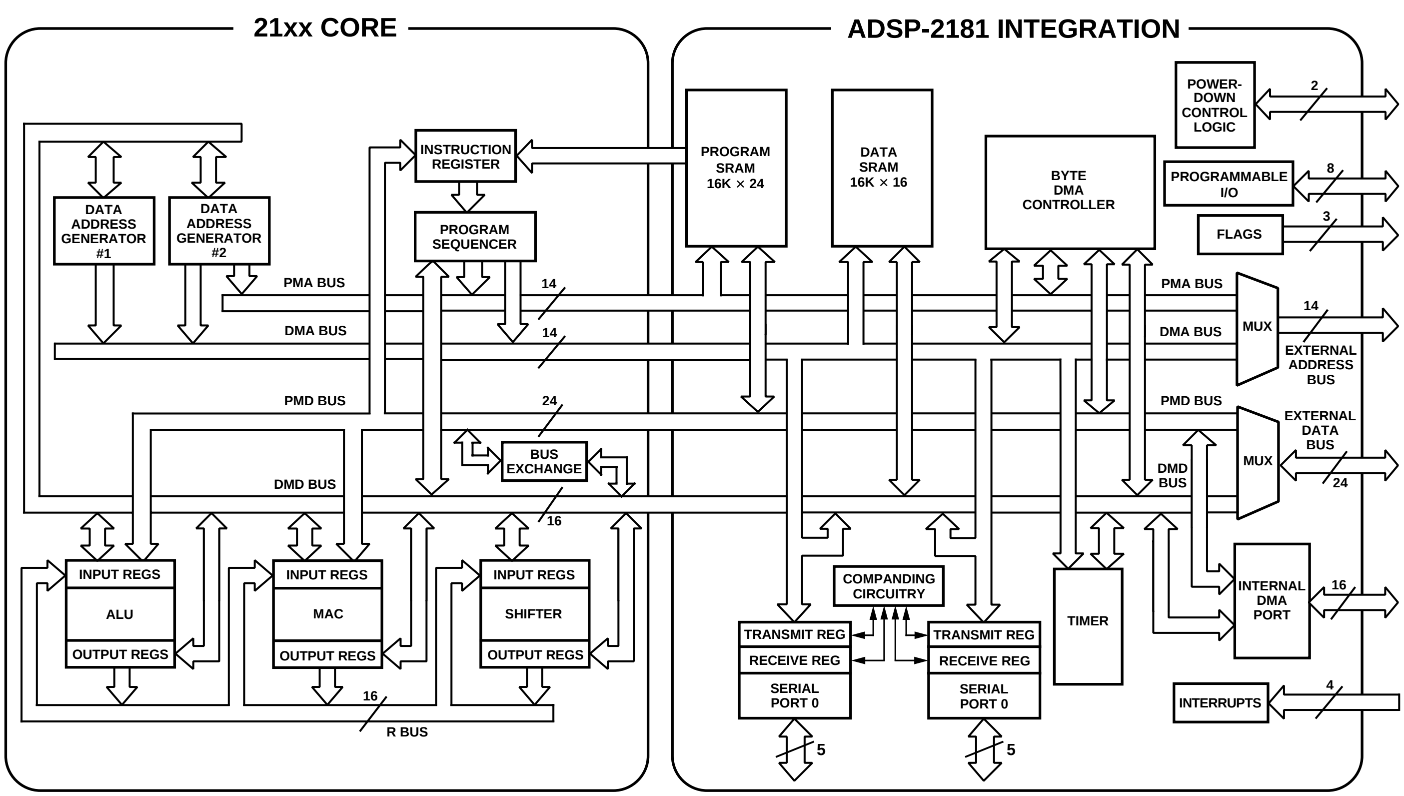


Figure 1. ADSP-2181 Block Diagram

Memory Architecture

The ADSP-2181 provides a variety of memory and peripheral interface options. The key functional groups are Program Memory, Data Memory, Byte Memory and I/O.

Program Memory is a 24-bit-wide space for storing both instruction opcodes and data. The ADSP-2181 has 16K words of Program Memory RAM on chip and the capability of accessing up to two 8K external memory overlay spaces using the external data bus. Both an instruction opcode and a data value can be read from on-chip program memory in a single cycle.

Data Memory is a 16-bit-wide space used for the storage of data variables and for memory-mapped control registers. The ADSP-2181 has 16K words on Data Memory RAM on chip, consisting of 16,352 user-accessible locations and 32 memory-mapped registers. Support also exists for up to two 8K external memory overlay spaces through the external data bus.

Byte Memory provides access to an 8-bit wide memory space through the Byte DMA (BDMA) port. The Byte Memory interface provides access to 4 MBytes of memory by utilizing eight data lines as additional address lines. This gives the BDMA Port an effective 22-bit address range. On power-up, the DSP can automatically load bootstrap code from byte memory.

I/O Space allows access to 2048 locations of 16-bit-wide data. It is intended to be used to communicate with parallel peripheral devices such as data converters and external registers or latches.

Program Memory

The ADSP-2181 contains a 16K × 24 on-chip program RAM. The on-chip program memory is designed to allow up to two accesses each cycle so that all operations can complete in a single cycle. In addition, the ADSP-2181 allows the use of 8K external memory overlays.

The program memory space organization is controlled by the MMAP pin and the PMOVLAY register. Normally, the ADSP-2181 is configured with MMAP = 0 and program memory organized as shown in Figure 4.

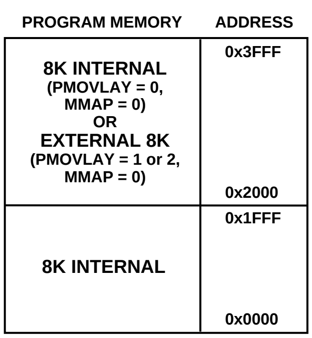


Figure 4. Program Memory (MMAP = 0)

There are 16K words of memory accessible internally when the PMOVLAY register is set to 0. When PMOVLAY is set to something other than 0, external accesses occur at addresses 0x2000 through 0x3FFF. The external address is generated as shown in Table II.

Table II.

PMOVLAY	Memory	A13	A12:0
0	Internal	Not Applicable	Not Applicable
1	External Overlay 1	0	13 LSBs of Address Between 0x2000 and 0x3FFF
2	External Overlay 2	1	13 LSBs of Address Between 0x2000 and 0x3FFF

This organization provides for two external 8K overlay segments using only the normal 14 address bits. This allows for simple program overlays using one of the two external segments in place of the on-chip memory. Care must be taken in using this overlay space in that the processor core (i.e., the sequencer) does not take into account the PMOVLAY register value. For example, if a loop operation was occurring on one of the external overlays and the program changes to another external overlay or internal memory, an incorrect loop operation could occur. In addition, care must be taken in interrupt service routines as the overlay registers are not automatically saved and restored on the processor mode stack.

For ADSP-2100 Family compatibility, MMAP = 1 is allowed. In this mode, booting is disabled and overlay memory is disabled (PMOVLAY must be 0). Figure 5 shows the memory map in this configuration.

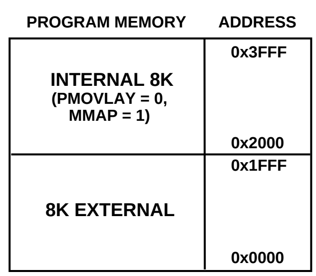


Figure 5. Program Memory (MMAP = 1)

Data Memory

The ADSP-2181 has 16,352 16-bit words of internal data memory. In addition, the ADSP-2181 allows the use of 8K external memory overlays. Figure 6 shows the organization of the data memory.

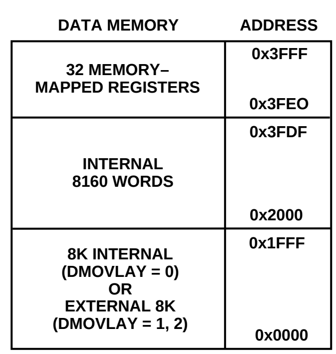


Figure 6. Data Memory

There are 16,352 words of memory accessible internally when the DMOVLAY register is set to 0. When DMOVLAY is set to something other than 0, external accesses occur at addresses 0x0000 through 0x1FFF. The external address is generated as shown in Table III.

Table III.

DMOVLAY	Memory	A13	A12:0
0	Internal	Not Applicable	Not Applicable
1	External Overlay 1	0	13 LSBs of Address Between 0x0000 and 0x1FFF
2	External Overlay 2	1	13 LSBs of Address Between 0x0000 and 0x1FFF

This organization allows for two external 8K overlays using only the normal 14 address bits.

All internal accesses complete in one cycle. Accesses to external memory are timed using the wait states specified by the DWAIT register.

I/O Space

The ADSP-2181 supports an additional external memory space called I/O space. This space is designed to support simple connections to peripherals or to bus interface ASIC data registers. I/O space supports 2048 locations. The lower eleven bits of the external address bus are used; the upper three bits are undefined. Two instructions were added to the core ADSP-2100 Family instruction set to read from and write to I/O memory space. The I/O space also has four dedicated 3-bit wait state registers, IOWAIT0-3, which specify up to seven wait states to be automatically generated for each of four regions. The wait states act on address ranges as shown in Table IV.

Table IV.

Address Range	Wait State Register
0x000–0x1FF	IOWAIT0
0x200–0x3FF	IOWAIT1
0x400–0x5FF	IOWAIT2
0x600–0x7FF	IOWAIT3

Composite Memory Select ($\overline{\text{CMS}}$)

The ADSP-2181 has a programmable memory select signal that is useful for generating memory select signals for memories mapped to more than one space. The $\overline{\text{CMS}}$ signal is generated to have the same timing as each of the individual memory select signals ($\overline{\text{PMS}}$, $\overline{\text{DMS}}$, $\overline{\text{BMS}}$, $\overline{\text{IOMS}}$) but can combine their functionality.

When set, each bit in the CMSSEL register, causes the $\overline{\text{CMS}}$ signal to be asserted when the selected memory select is asserted. For example, to use a 32K word memory to act as both program and data memory, set the PMS and DMS bits in the CMSSEL register and use the $\overline{\text{CMS}}$ pin to drive the chip select of the memory; use either $\overline{\text{DMS}}$ or $\overline{\text{PMS}}$ as the additional address bit.

The $\overline{\text{CMS}}$ pin functions like the other memory select signals, with the same timing and bus request logic. A 1 in the enable bit causes the assertion of the $\overline{\text{CMS}}$ signal at the same time as the selected memory select signal. All enable bits, except the $\overline{\text{BMS}}$ bit, default to 1 at reset.

Byte Memory

The byte memory space is a bidirectional, 8-bit-wide, external memory space used to store programs and data. Byte memory is accessed using the BDMA feature. The byte memory space consists of 256 pages, each of which is 16K × 8.

The byte memory space on the ADSP-2181 supports read and write operations as well as four different data formats. The byte memory uses data bits 15:8 for data. The byte memory uses data bits 23:16 and address bits 13:0 to create a 22-bit address. This allows up to a 4 meg × 8 (32 megabit) ROM or RAM to be used without glue logic. All byte memory accesses are timed by the BMWAIT register.

Byte Memory DMA (BDMA)

The Byte memory DMA controller allows loading and storing of program instructions and data using the byte memory space. The BDMA circuit is able to access the byte memory space while the processor is operating normally, and steals only one DSP cycle per 8-, 16- or 24-bit word transferred.

The BDMA circuit supports four different data formats which are selected by the BTYPE register field. The appropriate number of 8-bit accesses are done from the byte memory space to build the word size selected. Table V shows the data formats supported by the BDMA circuit.

Table V.

BTYPE	Internal Memory Space	Word Size	Alignment
00	Program Memory	24	Full Word
01	Data Memory	16	Full Word
10	Data Memory	8	MSBs
11	Data Memory	8	LSBs

Unused bits in the 8-bit data memory formats are filled with 0s. The BIAD register field is used to specify the starting address for the on-chip memory involved with the transfer. The 14-bit BEAD register specifies the starting address for the external byte memory space. The 8-bit BMPAGE register specifies the starting page for the external byte memory space. The BDIR register field selects the direction of the transfer. Finally the 14-bit BWCOUNT register specifies the number of DSP words to transfer and initiates the BDMA circuit transfers.

BDMA accesses can cross page boundaries during sequential addressing. A BDMA interrupt is generated on the completion of the number of transfers specified by the BWCOUNT register. The BWCOUNT register is updated after each transfer so it can be used to check the status of the transfers. When it reaches zero, the transfers have finished and a BDMA interrupt is generated. The BMPAGE and BEAD registers must not be accessed by the DSP during BDMA operations.

The source or destination of a BDMA transfer will always be on-chip program or data memory, regardless of the values of MMAP, PMOVLAY or DMOVLAY.

When the BWCOUNT register is written with a nonzero value, the BDMA circuit starts executing byte memory accesses with wait states set by BMWAIT. These accesses continue until the count reaches zero. When enough accesses have occurred to create a destination word, it is transferred to or from on-chip memory. The transfer takes one DSP cycle. DSP accesses to external memory have priority over BDMA byte memory accesses.

The BDMA Context Reset bit (BCR) controls whether the processor is held off while the BDMA accesses are occurring. Setting the BCR bit to 0 allows the processor to continue operations. Setting the BCR bit to 1 causes the processor to stop execution while the BDMA accesses are occurring, to clear the context of the processor and start execution at address 0 when the BDMA accesses have completed.

Internal Memory DMA Port (IDMA Port)

The IDMA Port provides an efficient means of communication between a host system and the ADSP-2181. The port is used to access the on-chip program memory and data memory of the DSP with only one DSP cycle per word overhead. The IDMA port cannot, however, be used to write to the DSP's memory-mapped control registers.

The IDMA port has a 16-bit multiplexed address and data bus and supports 24-bit program memory. The IDMA port is completely asynchronous and can be written to while the ADSP-2181 is operating at full speed.

The DSP memory address is latched and then automatically incremented after each IDMA transaction. An external device can therefore access a block of sequentially addressed memory by specifying only the starting address of the block. This increases throughput as the address does not have to be sent for each memory access.

IDMA Port access occurs in two phases. The first is the IDMA Address Latch cycle. When the acknowledge is asserted, a 14-bit address and 1-bit destination type can be driven onto the bus by an external device. The address specifies an on-chip memory location; the destination type specifies whether it is a DM or PM access. The falling edge of the address latch signal latches this value into the IDMAA register.

Once the address is stored, data can either be read from or written to the ADSP-2181's on-chip memory. Asserting the select line ($\overline{IS}$) and the appropriate read or write line ($\overline{IRD}$ and $\overline{IWR}$ respectively) signals the ADSP-2181 that a particular transaction is required. In either case, there is a one-processor-cycle delay for synchronization. The memory access consumes one additional processor cycle.

Once an access has occurred, the latched address is automatically incremented and another access can occur.

Through the IDMAA register, the DSP can also specify the starting address and data format for DMA operation.

Bootstrap Loading (Booting)

The ADSP-2181 has two mechanisms to allow automatic loading of the on-chip program memory after reset. The method for booting after reset is controlled by the MMAP and BMODE pins as shown in Table VI.

Table VI. Boot Summary Table

MMAP	BMODE	Booting Method
0	0	BDMA feature is used in default mode to load the first 32 program memory words from the byte memory space. Program execution is held off until all 32 words have been loaded.
0	1	IDMA feature is used to load any internal memory as desired. Program execution is held off until internal program memory location 0 is written to.
1	X	Bootstrap features disabled. Program execution immediately starts from location 0.

BDMA Booting

When the BMODE and MMAP pins specify BDMA booting (MMAP = 0, BMODE = 0), the ADSP-2181 initiates a BDMA boot sequence when reset is released. The BDMA interface is set up during reset to the following defaults when BDMA booting is specified: the BDIR, BMPAGE, BIAD and BEAD registers are set to 0, the BTYPE register is set to 0 to specify program memory 24 bit words, and the BWCOUNT register is set to 32. This causes 32 words of on-chip program memory to be loaded from byte memory. These 32 words are used to set up the BDMA to load in the remaining program code. The BCR bit is also set to 1, which causes program execution to be held off until all 32 words are loaded into on-chip program memory. Execution then begins at address 0.

The ADSP-2100 Family Development Software (Revision 5.02 and later) fully supports the BDMA booting feature and can generate byte memory space compatible boot code.

The IDLE instruction can also be used to allow the processor to hold off execution while booting continues through the BDMA interface.

IDMA Booting

The ADSP-2181 can also boot programs through its Internal DMA port. If BMODE = 1 and MMAP = 0, the ADSP-2181 boots from the IDMA port. IDMA feature can load as much on-chip memory as desired. Program execution is held off until on-chip program memory location 0 is written to.

The ADSP-2100 Family Development Software (Revision 5.02 and later) can generate IDMA compatible boot code.

Bus Request and Bus Grant

The ADSP-2181 can relinquish control of the data and address buses to an external device. When the external device requires access to memory, it asserts the bus request ($\overline{BR}$) signal. If the ADSP-2181 is not performing an external memory access, then it responds to the active $\overline{BR}$ input in the following processor cycle by:

- three-stating the data and address buses and the $\overline{PMS}$, $\overline{DMS}$, $\overline{BMS}$, $\overline{CMS}$, $\overline{IOMS}$, $\overline{RD}$, $\overline{WR}$ output drivers,
- asserting the bus grant ($\overline{BG}$) signal, and
- halting program execution.

If Go Mode is enabled, the ADSP-2181 will not halt program execution until it encounters an instruction that requires an external memory access.

If the ADSP-2181 is performing an external memory access when the external device asserts the $\overline{BR}$ signal, then it will not three-state the memory interfaces or assert the $\overline{BG}$ signal until the processor cycle after the access completes. The instruction does not need to be completed when the bus is granted. If a single instruction requires two external memory accesses, the bus will be granted between the two accesses.

When the $\overline{BR}$ signal is released, the processor releases the $\overline{BG}$ signal, reenables the output drivers and continues program execution from the point where it stopped.

The bus request feature operates at all times, including when the processor is booting and when $\overline{RESET}$ is active.

The $\overline{BGH}$ pin is asserted when the ADSP-2181 is ready to execute an instruction, but is stopped because the external bus is already granted to another device. The other device can release the bus by deasserting bus request. Once the bus is released, the ADSP-2181 deasserts $\overline{BG}$ and $\overline{BGH}$ and executes the external memory access.

Flag I/O Pins

The ADSP-2181 has eight general purpose programmable input/output flag pins. They are controlled by two memory mapped registers. The PFTYPE register determines the direction, 1 = output and 0 = input. The PFDATA register is used to read and write the values on the pins. Data being read from a pin configured as an input is synchronized to the ADSP-2181's clock. Bits that are programmed as outputs will read the value being output. The PF pins default to input during reset.

In addition to the programmable flags, the ADSP-2181 has five fixed-mode flags, FLAG_IN, FLAG_OUT, FL0, FL1 and FL2. FL0-FL2 are dedicated output flags. FLAG_IN and FLAG_OUT are available as an alternate configuration of SPORT1.

INSTRUCTION SET DESCRIPTION

The ADSP-2181 assembly language instruction set has an algebraic syntax that was designed for ease of coding and readability. The assembly language, which takes full advantage of the processor's unique architecture, offers the following benefits:

- The algebraic syntax eliminates the need to remember cryptic assembler mnemonics. For example, a typical arithmetic add instruction, such as AR = AX0 + AY0, resembles a simple equation.
- Every instruction assembles into a single, 24-bit word that can execute in a single instruction cycle.
- The syntax is a superset ADSP-2100 Family assembly language and is completely source and object code compatible with other family members. Programs may need to be relocated to utilize on-chip memory and conform to the ADSP-2181's interrupt vector and reset vector map.
- Sixteen condition codes are available. For conditional jump, call, return or arithmetic instructions, the condition can be checked and the operation executed in the same instruction cycle.
- Multifunction instructions allow parallel execution of an arithmetic instruction with up to two fetches or one write to processor memory space during a single instruction cycle.

DESIGNING AN EZ-ICE-COMPATIBLE SYSTEM

The ADSP-2181 has on-chip emulation support and an ICE-Port, a special set of pins that interface to the EZ-ICE. These features allow in-circuit emulation without replacing the target system processor by using only a 14-pin connection from the target system to the EZ-ICE. Target systems must have a 14-pin connector to accept the EZ-ICE 's in-circuit probe, a 14-pin plug.

The ICE-Port interface consists of the following ADSP-2181 pins:

$\overline{EBR}$	$\overline{EMS}$	ELIN
$\overline{EBG}$	$\overline{EINT}$	ELOUT
$\overline{ERESET}$	ECLK	EE

These ADSP-2181 pins must be connected *only* to the EZ-ICE connector in the target system. These pins have no function except during emulation, and do not require pull-up or pull-down resistors. The traces for these signals between the ADSP-2181 and the connector must be kept as short as possible, no longer than three inches.

The following pins are also used by the EZ-ICE:

$\overline{BR}$	$\overline{BG}$
GND	$\overline{RESET}$

The EZ-ICE uses the EE (emulator enable) signal to take control of the ADSP-2181 in the target system. This causes the processor to use its $\overline{ERESET}$, $\overline{EBR}$ and $\overline{EBG}$ pins instead of the $\overline{RESET}$, $\overline{BR}$ and $\overline{BG}$ pins. The $\overline{BG}$ output is three-stated. These signals do not need to be jumper-isolated in your system.

The EZ-ICE connects to the target system via a ribbon cable and a 14-pin female plug. The ribbon cable is 10 inches in length with one end fixed to the EZ-ICE. The female plug is plugged onto the 14-pin connector (a pin strip header) on the target board.

Target Board Connector for EZ-ICE Probe

The EZ-ICE connector (a standard pin strip header) is shown in Figure 7. You must add this connector to your target board design if you intend to use the EZ-ICE. Be sure to allow enough room in your system to fit the EZ-ICE probe onto the 14-pin connector.

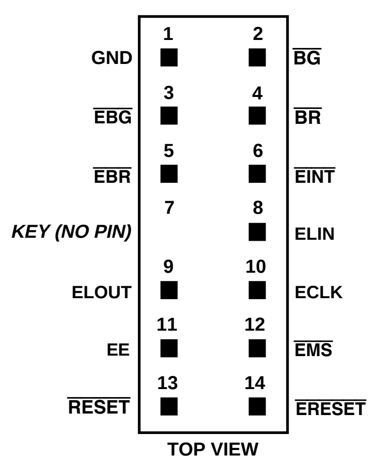


Figure 7. Target Board Connector for EZ-ICE

ABSOLUTE MAXIMUM RATINGS*

Supply Voltage . . . . –0.3 V to +7 V
Input Voltage . . . . –0.3 V to V_{DD} + 0.3 V
Output Voltage Swing . . . . –0.3 V to V_{DD} + 0.3 V
Operating Temperature Range (Ambient) . . . . –40°C to +85°C
Storage Temperature Range . . . . –65°C to +150°C
Lead Temperature (5 sec) TQFP . . . . +280°C
Lead Temperature (5 sec) PQFP . . . . +280°C

*Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ESD SENSITIVITY

The ADSP-2181 is an ESD (electrostatic discharge) sensitive device. Electrostatic charges readily accumulate on the human body and equipment and can discharge without detection. Permanent damage may occur to devices subjected to high energy electrostatic discharges.

The ADSP-2181 features proprietary ESD protection circuitry to dissipate high energy discharges (Human Body Model). Per method 3015 of MIL-STD-883, the ADSP-2181 has been classified as a Class 1 device.

Proper ESD precautions are recommended to avoid performance degradation or loss of functionality. Unused devices must be stored in conductive foam or shunts, and the foam should be discharged to the destination before devices are removed.

TIMING PARAMETERS

GENERAL NOTES

Use the exact timing information given. Do not attempt to derive parameters from the addition or subtraction of others. While addition or subtraction would yield meaningful results for an individual device, the values given in this data sheet reflect statistical variations and worst cases. Consequently, you cannot meaningfully add up parameters to derive longer times.

TIMING NOTES

Switching Characteristics specify how the processor changes its signals. You have no control over this timing—circuitry external to the processor must be designed for compatibility with these signal characteristics. Switching characteristics tell you what the processor will do in a given circumstance. You can also use switching characteristics to ensure that any timing requirement of a device connected to the processor (such as memory) is satisfied.

Timing Requirements apply to signals that are controlled by circuitry external to the processor, such as the data input for a read operation. Timing requirements guarantee that the processor operates correctly with other devices.

MEMORY TIMING SPECIFICATIONS

The table below shows common memory device specifications and the corresponding ADSP-2181 timing parameters, for your convenience.

Memory Device Specification	ADSP-2181 Timing Parameter	Timing Parameter Definition
Address Setup to Write Start	t_{ASW}	A0–A13, $\overline{xMS}$ Setup before $\overline{WR}$ Low
Address Setup to Write End	t_{AW}	A0–A13, $\overline{xMS}$ Setup before $\overline{WR}$ Deasserted
Address Hold Time	t_{WRA}	A0–A13, $\overline{xMS}$ Hold after $\overline{WR}$ Deasserted
Data Setup Time	t_{DW}	Data Setup before $\overline{WR}$ High
Data Hold Time	t_{DH}	Data Hold after $\overline{WR}$ High
$\overline{OE}$ to Data Valid	t_{RDD}	$\overline{RD}$ Low to Data Valid
Address Access Time	t_{AA}	A0–A13, $\overline{xMS}$ to Data Valid

$\overline{xMS}$ = $\overline{PMS}$, $\overline{DMS}$, $\overline{BMS}$, $\overline{CMS}$, $\overline{IOMS}$.

FREQUENCY DEPENDENCY FOR TIMING SPECIFICATIONS

t_{CK} is defined as $0.5t_{CKI}$. The ADSP-2181 uses an input clock with a frequency equal to half the instruction rate: a 16.67 MHz input clock (which is equivalent to 60 ns) yields a 30 ns processor cycle (equivalent to 33 MHz). t_{CK} values within the range of $0.5t_{CKI}$ period should be substituted for all relevant timing parameters to obtain the specification value.

Example: $t_{CKH} = 0.5t_{CK} – 7$ ns = 0.5 (25 ns) – 7 ns = 8 ns

Parameter		Min	Max	Unit
Clock Signals and Reset				
Timing Requirements:				
t_{CKI}	CLKIN Period	50	150	ns
t_{CKIL}	CLKIN Width Low	20		ns
t_{CKIH}	CLKIN Width High	20		ns
Switching Characteristics:				
t_{CKL}	CLKOUT Width Low	$0.5t_{CK} – 7$		ns
t_{CKH}	CLKOUT Width High	$0.5t_{CK} – 7$		ns
t_{CKOH}	CLKIN High to CLKOUT High	0	20	ns
Control Signals				
Timing Requirement:				
t_{RSP}	$\overline{RESET}$ Width Low	$5t_{CK}$[1]		ns

NOTE
[1]Applies after power-up sequence is complete. Internal phase lock loop requires no more than 2000 CLKIN cycles assuming stable CLKIN (not including crystal oscillator start-up time).

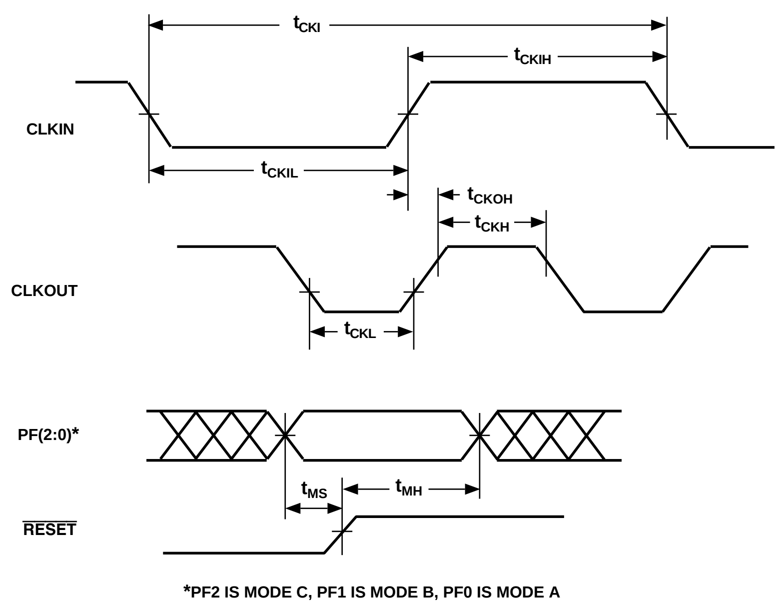


Figure 8. Clock Signals

Parameter		Min	Max	Unit
Interrupts and Flag				
Timing Requirements:				
t_{IFS}	$\overline{IRQx}$, FI, or PFx Setup before CLKOUT Low[1, 2, 3, 4]	$0.25t_{CK} + 15$		ns
t_{IFH}	$\overline{IRQx}$, FI, or PFx Hold after CLKOUT High[1, 2, 3, 4]	$0.25t_{CK}$		ns
Switching Characteristics:				
t_{FOH}	Flag Output Hold after CLKOUT Low[5]	$0.5t_{CK} - 7$		ns
t_{FOD}	Flag Output Delay from CLKOUT Low[5]		$0.5t_{CK} + 5$	ns

NOTES

[1]If $\overline{IRQx}$ and FI inputs meet t_{IFS} and t_{IFH} setup/hold requirements, they will be recognized during the current clock cycle; otherwise the signals will be recognized on the following cycle. (Refer to "Interrupt Controller Operation" in the Program Control chapter of the User's Manual for further information on interrupt servicing.)

[2]Edge-sensitive interrupts require pulsewidths greater than 10 ns; level-sensitive interrupts must be held low until serviced.

[3]$\overline{IRQx}$ = $\overline{IRQ0}$, $\overline{IRQ1}$, $\overline{IRQ2}$, $\overline{IRQL0}$, $\overline{IRQL1}$, $\overline{IRQE}$.

[4]PFx = PF0, PF1, PF2, PF3, PF4, PF5, PF6, PF7.

[5]Flag outputs = PFx, FL0, FL1, FL2, Flag_out4.

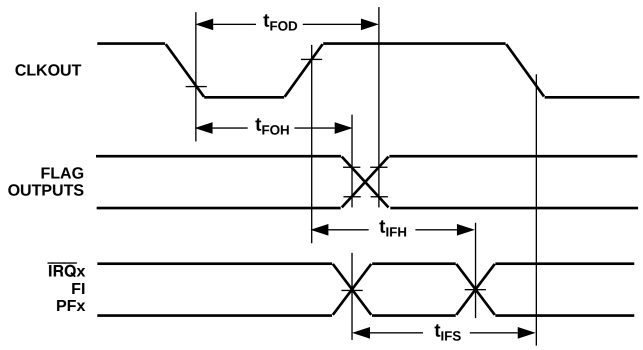


Figure 9. Interrupts and Flags

Parameter		Min	Max	Unit
Bus Request/Grant				
Timing Requirements:				
t_{BH}	$\overline{BR}$ Hold after CLKOUT High[1]	$0.25t_{CK} + 2$		ns
t_{BS}	$\overline{BR}$ Setup before CLKOUT Low[1]	$0.25t_{CK} + 17$		ns
Switching Characteristics:				
t_{SD}	CLKOUT High to $\overline{xMS}$, $\overline{RD}$, $\overline{WR}$ Disable		$0.25t_{CK} + 10$	ns
t_{SDB}	$\overline{xMS}$, $\overline{RD}$, $\overline{WR}$ Disable to $\overline{BG}$ Low	0		ns
t_{SE}	$\overline{BG}$ High to $\overline{xMS}$, $\overline{RD}$, $\overline{WR}$ Enable	0		ns
t_{SEC}	$\overline{xMS}$, $\overline{RD}$, $\overline{WR}$ Enable to CLKOUT High	$0.25t_{CK} - 4$		ns
t_{SDBH}	$\overline{xMS}$, $\overline{RD}$, $\overline{WR}$ Disable to $\overline{BGH}$ Low[2]	0		ns
t_{SEH}	$\overline{BGH}$ High to $\overline{xMS}$, $\overline{RD}$, $\overline{WR}$ Enable[2]	0		ns

NOTES

$\overline{xMS}$ = $\overline{PMS}$, $\overline{DMS}$, $\overline{CMS}$, $\overline{IOMS}$, $\overline{BMS}$.

[1] $\overline{BR}$ is an asynchronous signal. If $\overline{BR}$ meets the setup/hold requirements, it will be recognized during the current clock cycle; otherwise the signal will be recognized on the following cycle. Refer to the *ADSP-2100 Family User's Manual, Third Edition* for $\overline{BR}$/$\overline{BG}$ cycle relationships.

[2] $\overline{BGH}$ is asserted when the bus is granted and the processor requires control of the bus to continue.

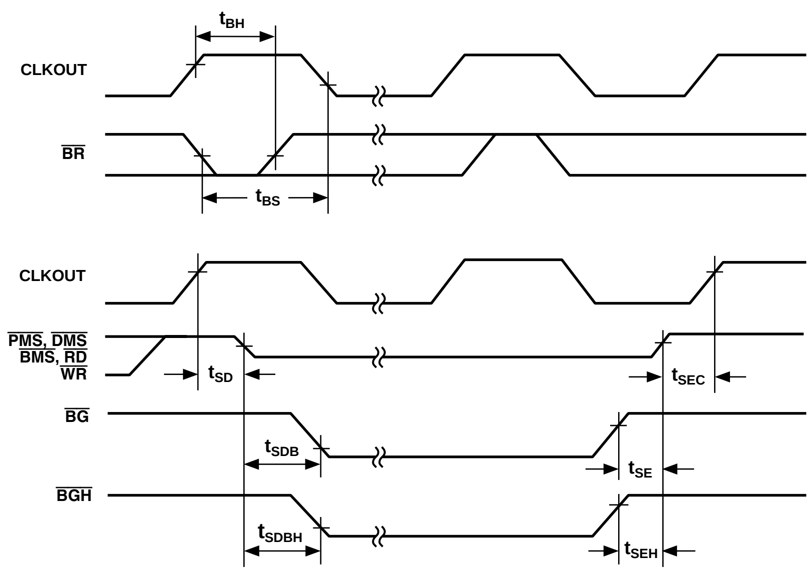


Figure 10. Bus Request–Bus Grant

Parameter		Min	Max	Unit
Serial Ports				
Timing Requirements:				
t_{SCK}	SCLK Period	50		ns
t_{SCS}	DR/TFS/RFS Setup before SCLK Low	4		ns
t_{SCH}	DR/TFS/RFS Hold after SCLK Low	7		ns
t_{SCP}	$SCLK_{IN}$ Width	20		ns
Switching Characteristics:				
t_{CC}	CLKOUT High to $SCLK_{OUT}$	$0.25t_{CK}$	$0.25t_{CK} + 10$	ns
t_{SCDE}	SCLK High to DT Enable	0		ns
t_{SCDV}	SCLK High to DT Valid		15	ns
t_{RH}	TFS/RFS_{OUT} Hold after SCLK High	0		ns
t_{RD}	TFS/RFS_{OUT} Delay from SCLK High		15	ns
t_{SCDH}	DT Hold after SCLK High	0		ns
t_{TDE}	TFS (Alt) to DT Enable	0		ns
t_{TDV}	TFS (Alt) to DT Valid		14	ns
t_{SCDD}	SCLK High to DT Disable		15	ns
t_{RDV}	RFS (Multichannel, Frame Delay Zero) to DT Valid		15	ns

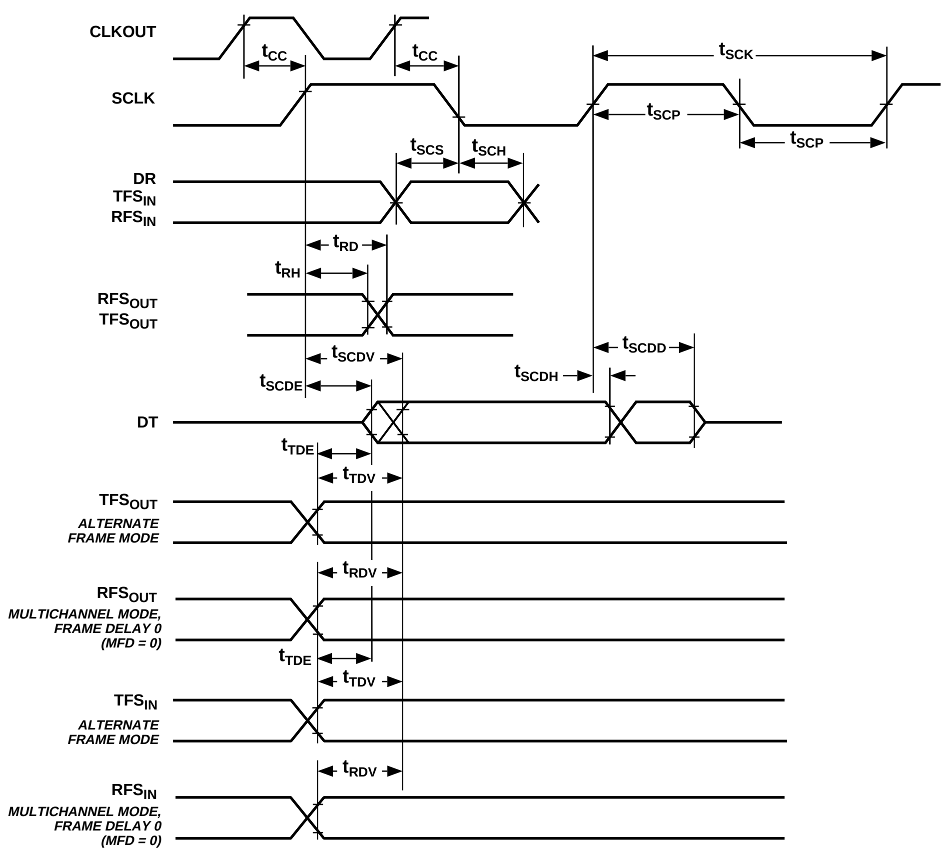


Figure 13. Serial Ports

Parameter		Min	Max	Unit
IDMA Address Latch				
Timing Requirements:				
t_{IALP}	Duration of Address Latch[1, 2]	10		ns
t_{IASU}	IAD15–0 Address Setup before Address Latch End[2]	5		ns
t_{IAH}	IAD15–0 Address Hold after Address Latch End[2]	2		ns
t_{IKA}	$\overline{\text{IACK}}$ Low before Start of Address Latch[1]	0		ns
t_{IALS}	Start of Write or Read after Address Latch End[2, 3]	3		ns

NOTES
[1]Start of Address Latch = $\overline{\text{IS}}$ Low and IAL High.
[2]End of Address Latch = $\overline{\text{IS}}$ High or IAL Low.
[3]Start of Write or Read = $\overline{\text{IS}}$ Low and $\overline{\text{IWR}}$ Low or $\overline{\text{IRD}}$ Low.

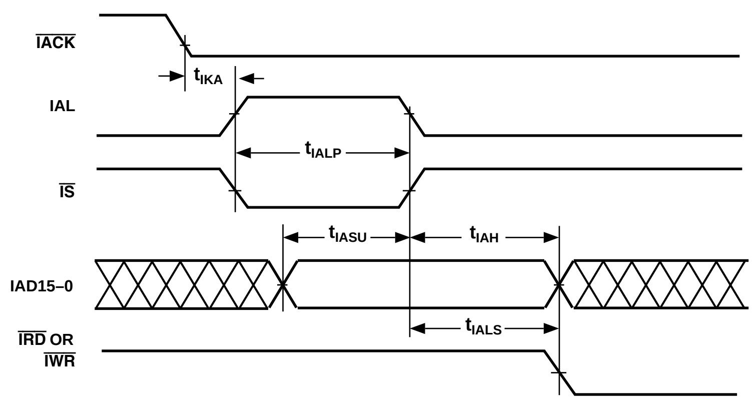


Figure 14. IDMA Address Latch

Parameter		Min	Max	Unit
IDMA Write, Long Write Cycle				
Timing Requirements:				
t_{IKW}	$\overline{IACK}$ Low before Start of Write[1]	0		ns
t_{IKSU}	IAD15–0 Data Setup before $\overline{IACK}$ Low[2, 3]	$0.5t_{CK} + 10$		ns
t_{IKH}	IAD15–0 Data Hold after $\overline{IACK}$ Low[2, 3]	2		ns
Switching Characteristics:				
t_{IKLW}	Start of Write to $\overline{IACK}$ Low[4]	$1.5t_{CK}$		ns
t_{IKHW}	Start of Write to $\overline{IACK}$ High		15	ns

NOTES
[1]Start of Write = $\overline{IS}$ Low and $\overline{IWR}$ Low.
[2]If Write Pulse ends before $\overline{IACK}$ Low, use specifications t_{IDSU}, t_{IDH}.
[3]If Write Pulse ends after $\overline{IACK}$ Low, use specifications t_{IKSU}, t_{IKH}.
[4]This is the earliest time for $\overline{IACK}$ Low from Start of Write. For IDMA Write cycle relationships, please refer to the User's Manual.

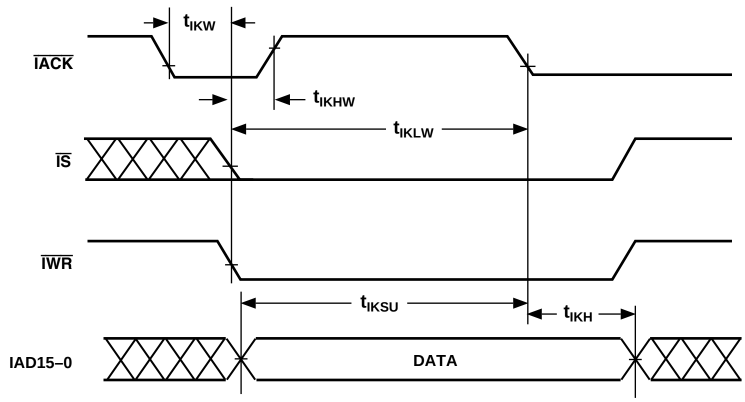


Figure 16. IDMA Write, Long Write Cycle

Parameter		Min	Max	Unit
IDMA Read, Long Read Cycle				
Timing Requirements:				
t_{IKR}	$\overline{IACK}$ Low before Start of Read[1]	0		ns
t_{IRP}	Duration of Read	15		ns
Switching Characteristics:				
t_{IKHR}	$\overline{IACK}$ High after Start of Read[1]		15	ns
t_{IKDS}	IAD15–0 Data Setup before IACK Low	$0.5t_{CK} - 10$		ns
t_{IKDH}	IAD15–0 Data Hold after End of Read[2]	0		ns
t_{IKDD}	IAD15–0 Data Disabled after End of Read[2]		12	ns
t_{IRDE}	IAD15–0 Previous Data Enabled after Start of Read	0		ns
t_{IRDV}	IAD15–0 Previous Data Valid after Start of Read		15	ns
t_{IRDH1}	IAD15–0 Previous Data Hold after Start of Read (DM/PM1)[3]	$2t_{CK} - 5$		ns
t_{IRDH2}	IAD15–0 Previous Data Hold after Start of Read (PM2)[4]	$t_{CK} - 5$		ns

NOTES
[1]Start of Read = $\overline{IS}$ Low and $\overline{IRD}$ Low.
[2]End of Read = $\overline{IS}$ High or $\overline{IRD}$ High.
[3]DM read or first half of PM read.
[4]Second half of PM read.

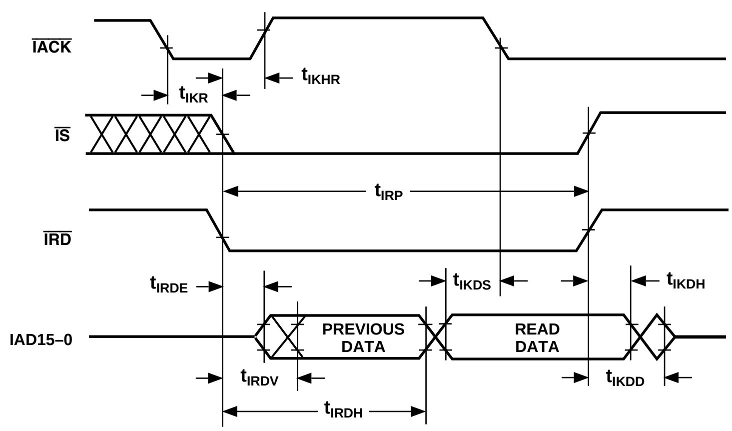


Figure 17. IDMA Read, Long Read Cycle

CAPACITIVE LOADING

Figures 22 and 23 show the capacitive loading characteristics of the ADSP-2181.

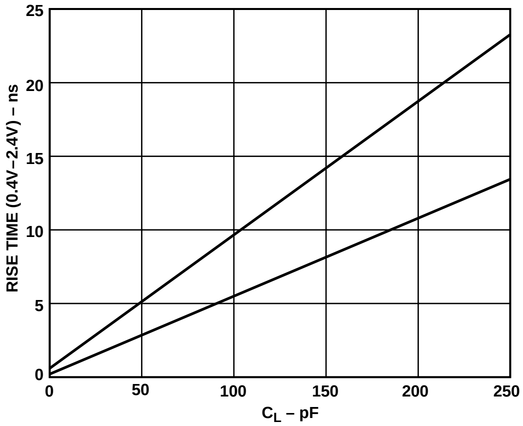


Figure 22. Range of Output Rise Time vs. Load Capacitance, C_L (at Maximum Ambient Operating Temperature)

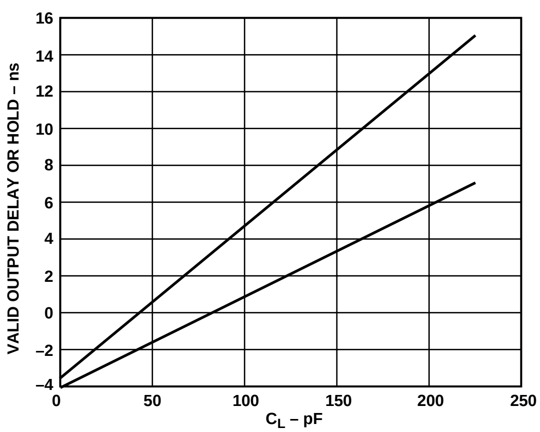


Figure 23. Range of Output Valid Delay or Hold vs. Load Capacitance, C_L (at Maximum Ambient Operating Temperature)

TEST CONDITIONS

Output Disable Time

Output pins are considered to be disabled when they have stopped driving and started a transition from the measured output high or low voltage to a high impedance state. The output disable time (t_{DIS}) is the difference of $t_{MEASURED}$ and t_{DECAY}, as shown in the Output Enable/Disable diagram. The time is the interval from when a reference signal reaches a high or low voltage level to when the output voltages have changed by 0.5 V from the measured output high or low voltage. The decay time, t_{DECAY}, is dependent on the capacitive load, C_L, and the current load, i_L, on the output pin. It can be approximated by the following equation:

$$t_{DECAY} = \frac{C_L \times 0.5V}{i_L}$$

from which

$$t_{DIS} = t_{MEASURED} - t_{DECAY}$$

is calculated. If multiple pins (such as the data bus) are disabled, the measurement value is that of the last pin to stop driving.

Figure 24. Voltage Reference Levels for AC Measurements (Except Output Enable/Disable)

Output Enable Time

Output pins are considered to be enabled when they have made a transition from a high-impedance state to when they start driving. The output enable time (t_{ENA}) is the interval from when a reference signal reaches a high or low voltage level to when the output has reached a specified high or low trip point, as shown in the Output Enable/Disable diagram. If multiple pins (such as the data bus) are enabled, the measurement value is that of the first pin to start driving.

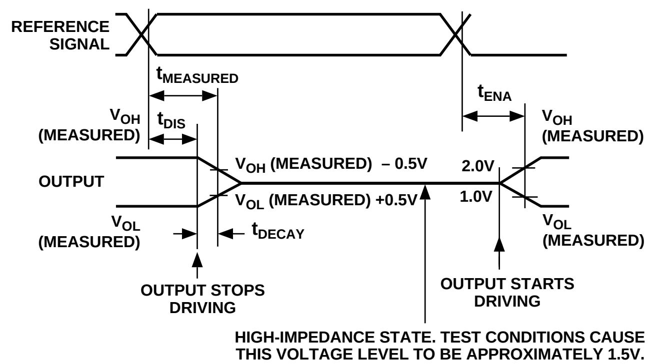


Figure 25. Output Enable/Disable

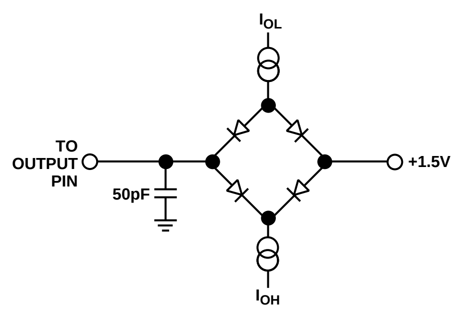
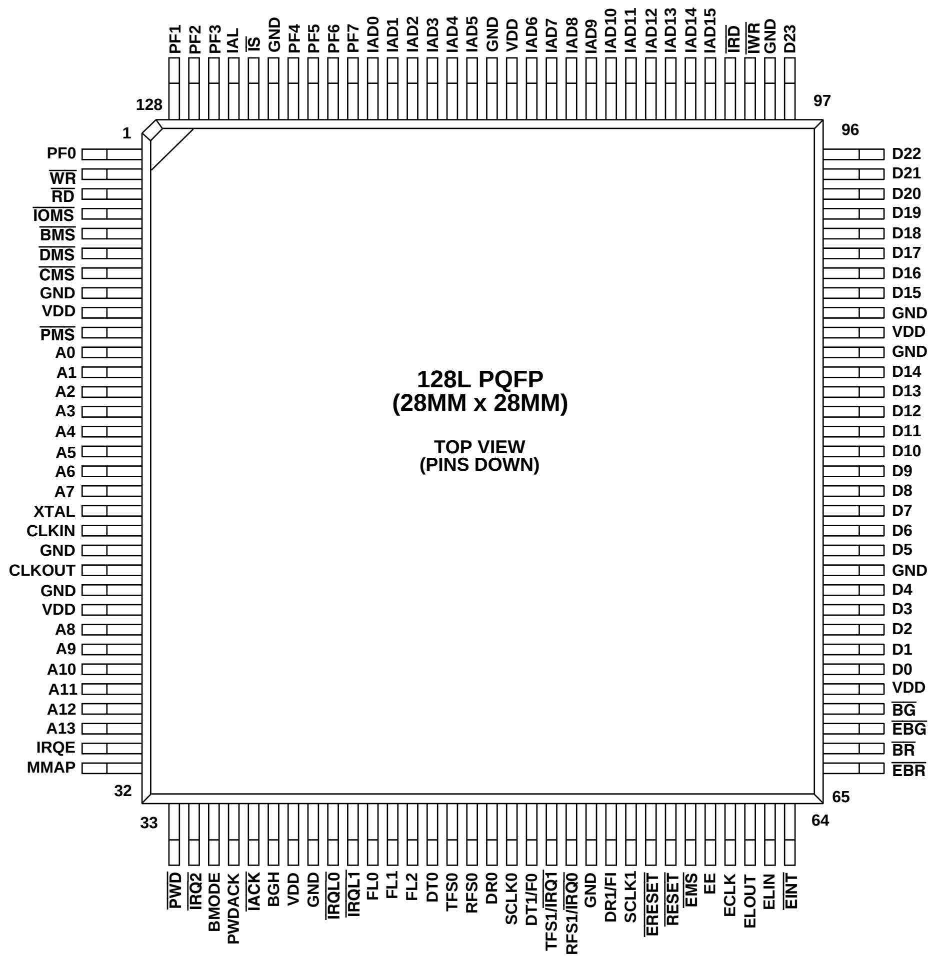


Figure 26. Equivalent Device Loading for AC Measurements (Including All Fixtures)

128-Lead PQFP Package Pinout



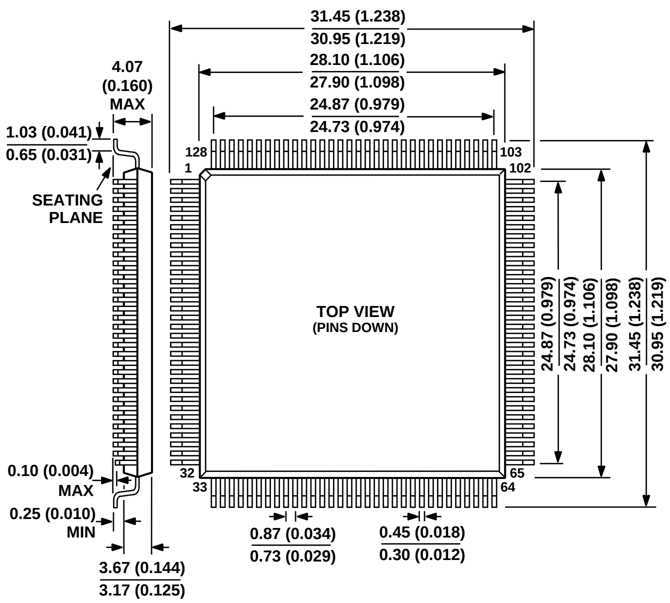
PQFP Pin Configurations

PQFP Number	Pin Name	PQFP Number	Pin Name	PQFP Number	Pin Name	PQFP Number	Pin Name
1	PF0	33	$\overline{\text{PWD}}$	65	$\overline{\text{EBR}}$	97	D23
2	$\overline{\text{WR}}$	34	$\overline{\text{IRQ2}}$	66	$\overline{\text{BR}}$	98	GND
3	$\overline{\text{RD}}$	35	BMODE	67	$\overline{\text{EBG}}$	99	$\overline{\text{IWR}}$
4	$\overline{\text{IOMS}}$	36	PWDACK	68	$\overline{\text{BG}}$	100	$\overline{\text{IRD}}$
5	$\overline{\text{BMS}}$	37	$\overline{\text{IACK}}$	69	VDD	101	IAD15
6	$\overline{\text{DMS}}$	38	$\overline{\text{BGH}}$	70	D0	102	IAD14
7	$\overline{\text{CMS}}$	39	VDD	71	D1	103	IAD13
8	GND	40	GND	72	D2	104	IAD12
9	VDD	41	$\overline{\text{IRQL0}}$	73	D3	105	IAD11
10	$\overline{\text{PMS}}$	42	$\overline{\text{IRQL1}}$	74	D4	106	IAD10
11	A0	43	FL0	75	GND	107	IAD9
12	A1	44	FL1	76	D5	108	IAD8
13	A2	45	FL2	77	D6	109	IAD7
14	A3	46	DT0	78	D7	110	IAD6
15	A4	47	TFS0	79	D8	111	VDD
16	A5	48	RFS0	80	D9	112	GND
17	A6	49	DR0	81	D10	113	IAD5
18	A7	50	SCLK0	82	D11	114	IAD4
19	XTAL	51	DT1/FO	83	D12	115	IAD3
20	CLKIN	52	TFS1/$\overline{\text{IRQ1}}$	84	D13	116	IAD2
21	GND	53	RFS1/$\overline{\text{IRQ0}}$	85	D14	117	IAD1
22	CLKOUT	54	GND	86	GND	118	IAD0
23	GND	55	DR1/FI	87	VDD	119	PF7
24	VDD	56	SCLK1	88	GND	120	PF6
25	A8	57	$\overline{\text{ERESET}}$	89	D15	121	PF5
26	A9	58	$\overline{\text{RESET}}$	90	D16	122	PF4
27	A10	59	$\overline{\text{EMS}}$	91	D17	123	GND
28	A11	60	EE	92	D18	124	$\overline{\text{IS}}$
29	A12	61	ECLK	93	D19	125	IAL
30	A13	62	ELOUT	94	D20	126	PF3
31	$\overline{\text{IRQE}}$	63	ELIN	95	D21	127	PF2
32	MMAP	64	$\overline{\text{EINT}}$	96	D22	128	PF1

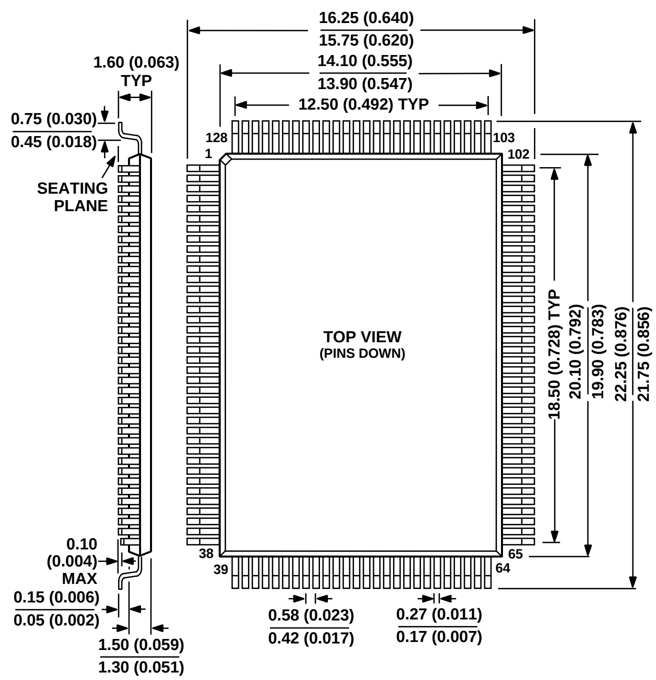
OUTLINE DIMENSIONS

Dimensions shown in mm and (inches).

128-Lead Metric Plastic Quad Flatpack (PQFP) (S-128)



128-Lead Metric Thin Plastic Quad Flatpack (TQFP) (ST-128)



C2041c–3–3/98

ORDERING GUIDE

Part Number	Ambient Temperature Range	Instruction Rate (MHz)	Package Description	Package Options*
ADSP-2181KST-115	0°C to +70°C	28.8	128-Lead TQFP	ST-128
ADSP-2181BST-115	–40°C to +85°C	28.8	128-Lead TQFP	ST-128
ADSP-2181KS-115	0°C to +70°C	28.8	128-Lead PQFP	S-128
ADSP-2181BS-115	–40°C to +85°C	28.8	128-Lead PQFP	S-128
ADSP-2181KST-133	0°C to +70°C	33.3	128-Lead TQFP	ST-128
ADSP-2181BST-133	–40°C to +85°C	33.3	128-Lead TQFP	ST-128
ADSP-2181KS-133	0°C to +70°C	33.3	128-Lead PQFP	S-128
ADSP-2181BS-133	–40°C to +85°C	33.3	128-Lead PQFP	S-128
ADSP-2181KST-160	0°C to +70°C	40	128-Lead TQFP	ST-128
ADSP-2181KS-160	0°C to +70°C	40	128-Lead PQFP	S-128

*S = Plastic Quad Flatpack (PQFP), ST = Plastic Thin Quad Flatpack (TQFP).

PRINTED IN U.S.A.