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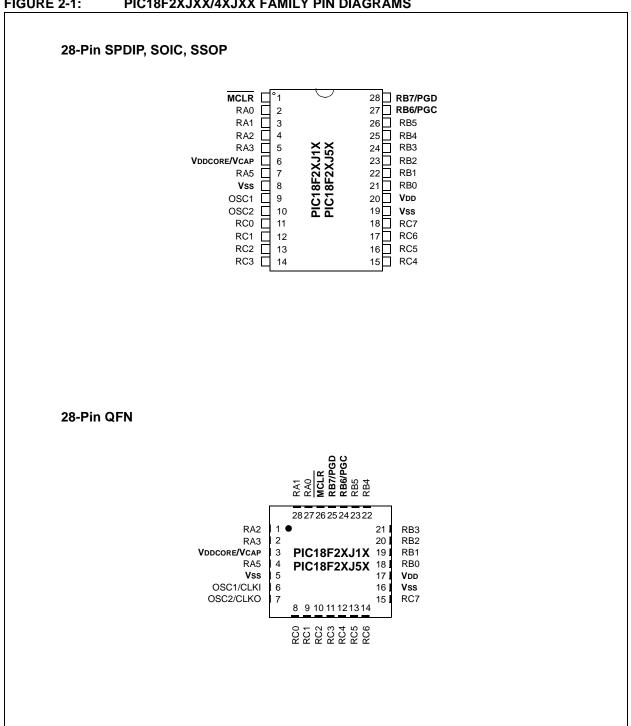
What is "Embedded - Microcontrollers"?

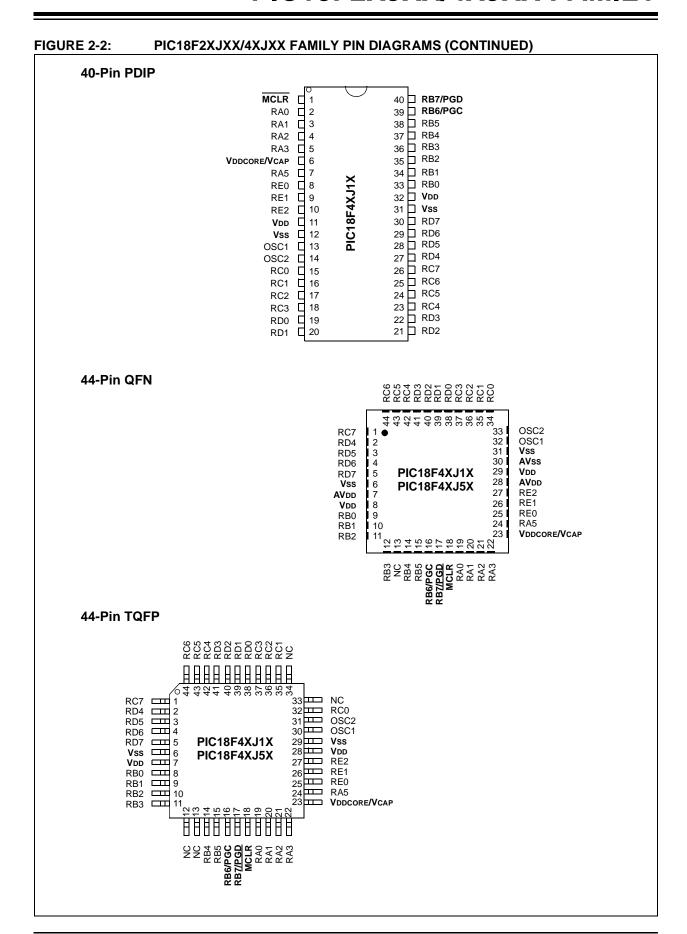
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	48MHz
Connectivity	I ² C, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	16
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3.8K x 8
Voltage - Supply (Vcc/Vdd)	2.15V ~ 3.6V
Data Converters	A/D 10x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f25j50t-i-so

FIGURE 2-1: PIC18F2XJXX/4XJXX FAMILY PIN DIAGRAMS





The Configuration Words for these devices are located at addresses 300000h through 300007h. These are implemented as three pairs of volatile memory registers. Each register is automatically loaded from a copy stored at the end of program memory. For this reason, the last four words (or eight bytes) of the code space (also called the Flash Configuration Words) should be written with Configuration data and not executable code. The addresses of the Flash Configuration Words are listed in Table 2-2. Refer to section Section 5.0 "Configuration Word" for more information.

Locations 3FFFFEh and 3FFFFFh are reserved for the Device ID bits. These bits, which may be used by the programmer to identify what device type is being programmed, are described in **Section 5.1 "Device ID Word"**. These Device ID bits read out normally, even after code protection.

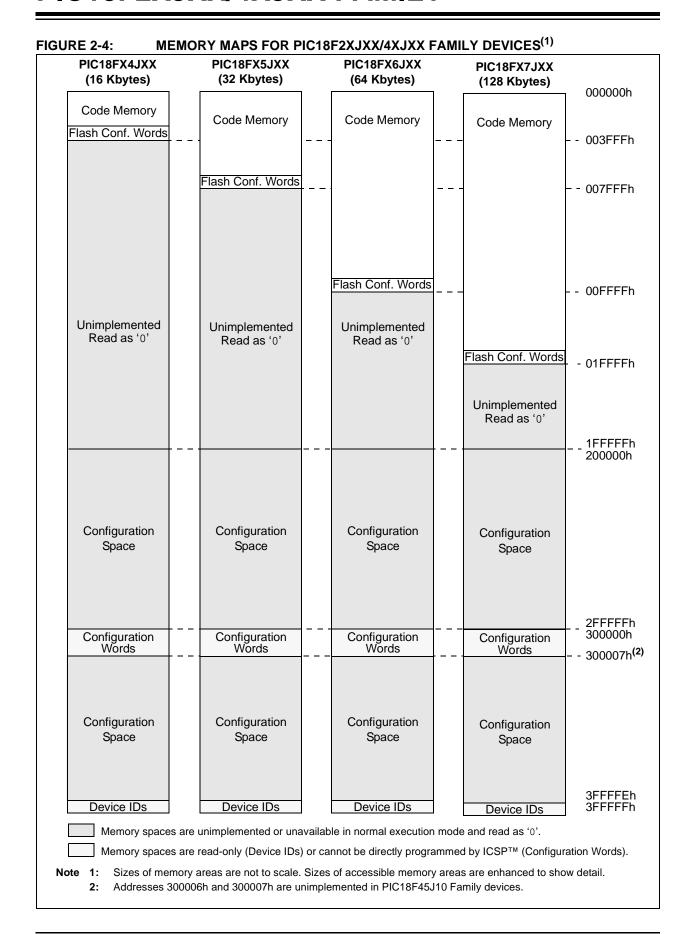
2.2.1 MEMORY ADDRESS POINTER

Memory in the device address space (000000h to 3FFFFFh) is addressed via the Table Pointer register, which in turn is comprised of three registers:

- · TBLPTRU at RAM address 0FF8h
- · TBLPTRH at RAM address 0FF7h
- · TBLPTRL at RAM address 0FF6h

TBLPTRU	TBLPTRH	TBLPTRL
Addr[21:16]	Addr[15:8]	Addr[7:0]

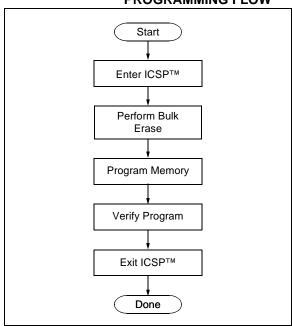
The 4-bit command, '0000' (core instruction), is used to load the Table Pointer prior to using many read or write operations.



2.3 Overview of the Programming Process

Figure 2-5 shows the high-level overview of the programming process in which a Bulk Erase is performed first, then the code memory is programmed. Since only nonvolatile Configuration Words are within the code memory space, the Configuration Words are also programmed as code. Code memory (including the Configuration Words) is then verified to ensure that programming was successful.

FIGURE 2-5: HIGH-LEVEL PROGRAMMING FLOW



2.4 Entering and Exiting ICSP™ Program/Verify Mode

Entry into ICSP modes for PIC18F2XJXX/4XJXX Family devices is somewhat different than previous PIC18 devices. As shown in Figure 2-6, entering ICSP Program/Verify mode requires three steps:

- Voltage is briefly applied to the MCLR pin.
- 2. A 32-bit key sequence is presented on PGD.
- 3. Voltage is reapplied to MCLR and held.

The programming voltage applied to $\overline{\text{MCLR}}$ is VIH, or essentially, VDD. There is no minimum time requirement for holding at VIH. After VIH is removed, an interval of at least P19 must elapse before presenting the key sequence on PGD.

The key sequence is a specific 32-bit pattern, '0100 1101 0100 0011 0100 1000 0101 0000', which is more easily remembered as 4D434850h in hexadecimal. The device will enter Program/Verify mode only if the sequence is valid. The Most Significant bit of the Most Significant nibble must be shifted in first.

Once the key sequence is complete, VIH must be applied to MCLR and held at that level for as long as Program/Verify mode is to be maintained. An interval of at least time, P20 and P12, must elapse before presenting data on PGD. Signals appearing on PGD before P12 has elapsed may not be interpreted as valid.

On successful entry, the program memory can be accessed and programmed in serial fashion. While in the Program/Verify mode, all unused I/Os are placed in the high-impedance state.

Exiting Program/Verify mode is done by removing VIH from MCLR, as shown in Figure 2-7. The only requirement for exit is that an interval, P16, should elapse between the last clock and program signals on PGC and PGD before removing VIH.

When VIH is reapplied to $\overline{\text{MCLR}}$, the device will enter the ordinary operational mode and begin executing the application instructions.

FIGURE 2-6: ENTERING PROGRAM/VERIFY MODE

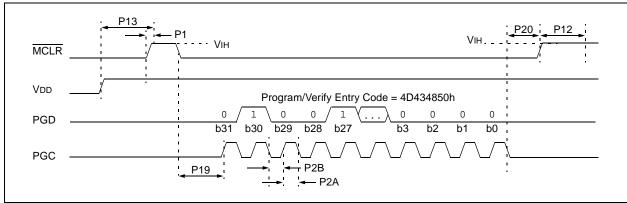
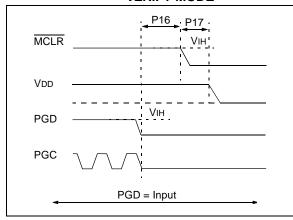


FIGURE 2-7: EXITING PROGRAM/ VERIFY MODE



2.5 Serial Program/Verify Operation

The PGC pin is used as a clock input pin and the PGD pin is used for entering command bits and data input/output during serial operation. Commands and data are transmitted on the rising edge of PGC, latched on the falling edge of PGC, and are Least Significant bit (LSb) first.

2.5.1 FOUR-BIT COMMANDS

All instructions are 20 bits, consisting of a leading 4-bit command followed by a 16-bit operand, which depends on the type of command being executed. To input a command, PGC is cycled four times. The commands needed for programming and verification are shown in Table 2-3.

Depending on the 4-bit command, the 16-bit operand represents 16 bits of input data or eight bits of input data and eight bits of output data.

Throughout this specification, commands and data are presented as illustrated in Table 2-4. The 4-bit command is shown Most Significant bit (MSb) first. The command operand or "Data Payload" is shown <MSB><LSB>. Figure 2-8 demonstrates how to serially present a 20-bit command/operand to the device.

2.5.2 CORE INSTRUCTION

The core instruction passes a 16-bit instruction to the CPU core for execution. This is needed to set up registers as appropriate for use with other commands.

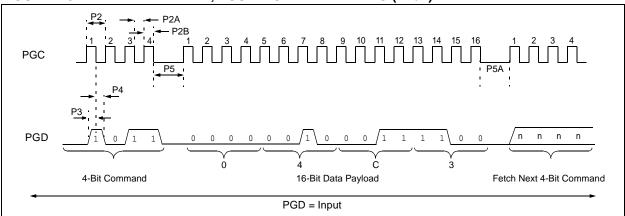
TABLE 2-3: COMMANDS FOR PROGRAMMING

Description	4-Bit Command
Core Instruction (Shift in 16-bit instruction)	0000
Shift out TABLAT register	0010
Table Read	1000
Table Read, Post-Increment	1001
Table Read, Post-Decrement	1010
Table Read, Pre-Increment	1011
Table Write	1100
Table Write, Post-Increment by 2	1101
Table Write, Start Programming, Post-Increment by 2	1110
Table Write, Start Programming	1111

TABLE 2-4: SAMPLE COMMAND SEQUENCE

4-Bit Command	4-Bit Data Core Instruction	
1101	3C 40	Table Write, post-increment by 2

FIGURE 2-8: TABLE WRITE, POST-INCREMENT TIMING (1101)



3.0 DEVICE PROGRAMMING

Programming includes the ability to erase or write the memory within the device.

The EECON1 register is used to control Write or Row Erase operations. The WREN bit must be set to enable writes; this must be done prior to initiating a write sequence. It is strongly recommended that the WREN bit only be set immediately prior to a program or erase operation.

The FREE bit must be set in order to erase the program space being pointed to by the Table Pointer. The erase or write sequence is initiated by setting the WR bit.

3.1 ICSP™ Erase

3.1.1 ICSP BULK ERASE

The PIC18F2XJXX/4XJXX Family devices may be Bulk Erased by writing 0180h to the table address, 3C0005h:3C0004h. The basic sequence is shown in Table 3-1 and demonstrated in Figure 3-1.

Since the code-protect Configuration bit is stored in the program code within code memory, a Bulk Erase operation will also clear any code-protect settings for the device.

The actual Bulk Erase function is a self-timed operation. Once the erase has started (falling edge of the 4th PGC after the NOP command), serial execution will cease until the erase completes (parameter P11). During this time, PGC may continue to toggle but PGD must be held low.

TABLE 3-1: BULK ERASE COMMAND SEQUENCE

4-Bit Command	Data Payload	Core Instruction
0000	0E 3C	MOVLW 3Ch
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPTRH
0000	0E 05	MOVLW 05h
0000	6E F6	MOVWF TBLPTRL
1100	01 01	Write 01h to 3C0005h
0000	0E 3C	MOVLW 3Ch
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPTRH
0000	0E 04	MOVLW 04h
0000	6E F6	MOVWF TBLPTRL
1100	80 80	Write 80h TO 3C0004h to
		erase entire device.
0000	00 00	NOP
0000	00 00	Hold PGD low until erase
		completes.

FIGURE 3-1: BULK ERASE FLOW

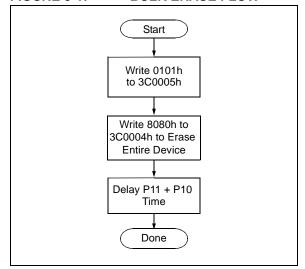
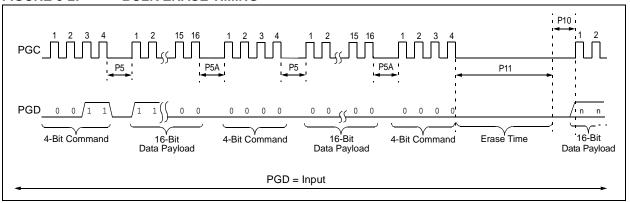


FIGURE 3-2: BULK ERASE TIMING



3.2 Code Memory Programming

Programming code memory is accomplished by first loading data into the write buffer and then initiating a programming sequence. The write buffer for all devices in the PIC18F2XJXX/4XJXX Family is 64 bytes. It can be mapped to any 64-byte block beginning at 000000h. The actual memory write sequence takes the contents of this buffer and programs the 64-byte block of code memory indicated by the Table Pointer.

Write buffer locations are not cleared following a write operation; the buffer retains its data after the write is complete. This means that the buffer must be written with 64 bytes on each operation. If there are locations in the code memory that are to remain empty, the corresponding locations in the buffer must be filled with FFFFh. This avoids rewriting old data from the previous cycle.

The programming duration is internally timed. After a Start Programming command is issued (4-bit command, '1111'), a NOP is issued, where the 4th PGC is held high for the duration of the programming time, P9.

The code sequence to program a PIC18F2XJXX/4XJXX Family device is shown in Table 3-3. The flowchart shown in Figure 3-5 depicts the logic necessary to completely write a PIC18F2XJXX/4XJXX Family device. The timing diagram that details the Start Programming command and parameter P9 is shown in Figure 3-6.

Note 1: The TBLPTR register must point to the same region when initiating the programming sequence as it did when the write buffers were loaded.

TABLE 3-3: WRITE CODE MEMORY CODE SEQUENCE

IADEL 3-3.	WINTE CODE MEMORY CODE SEQUENCE			
4-Bit Command	Data Payload	Core Instruction		
Step 1: Enable wi	rites.			
0000	84 A6	BSF EECON1, WREN		
Step 2: Load write	e buffer.			
0000 0000 0000 0000 0000 Step 3: Repeat fo	0E <addr[21:16]> 6E F8 0E <addr[15:8]> 6E F7 0E <addr[7:0]> 6E F6 r all but the last two byte</addr[7:0]></addr[15:8]></addr[21:16]>	MOVLW <addr[21:16]> MOVWF TBLPTRU MOVLW <addr[15:8]> MOVWF TBLPTRH MOVLW <addr[7:0]> MOVWF TBLPTRL as. Any unused locations should be filled with FFFFh.</addr[7:0]></addr[15:8]></addr[21:16]>		
1101	<msb><lsb></lsb></msb>	Write 2 bytes and post-increment address by 2.		
Step 4: Load write	e buffer for last two bytes	S.		
1111 0000	<msb><lsb></lsb></msb>	Write 2 bytes and start programming. NOP - hold PGC high for time P9.		
To continue writin	To continue writing data, repeat Steps 2 through 4, where the Address Pointer is incremented by 2 at each iteration of the loop.			

FIGURE 3-5: PROGRAM CODE MEMORY FLOW

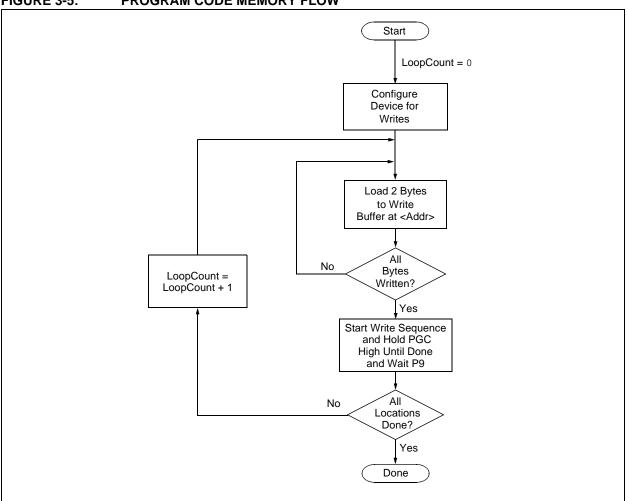
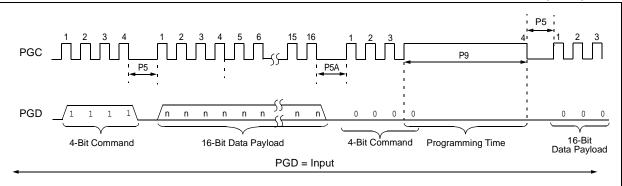


FIGURE 3-6: TABLE WRITE AND START PROGRAMMING INSTRUCTION TIMING (1111)



3.3 Endurance and Retention

To maintain the endurance specification of the Flash program memory cells, each byte should never be programmed more than once between erase operations. Before attempting to modify the contents of a specific byte of Flash memory a second time, an erase operation (either a Bulk Erase or a Row Erase which includes that byte) should be performed.

4.0 READING THE DEVICE

4.1 Read Code Memory

Code memory is accessed one byte at a time via the 4-bit command, '1001' (table read, post-increment). The contents of memory pointed to by the Table Pointer (TBLPTRU:TBLPTRH:TBLPTRL) are serially output on PGD.

The 4-bit command is shifted in LSb first. The read is executed during the next eight clocks, then shifted out on PGD during the last eight clocks, LSb to MSb. A

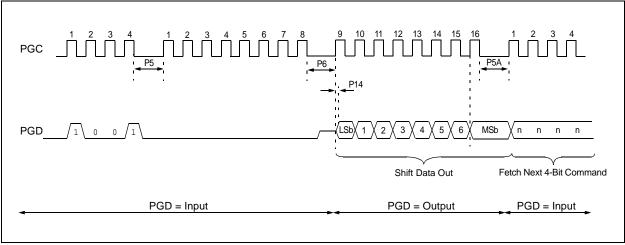
delay of P6 must be introduced after the falling edge of the 8th PGC of the operand to allow PGD to transition from an input to an output. During this time, PGC must be held low (see Figure 4-1). This operation also increments the Table Pointer by one, pointing to the next byte in code memory for the next read.

This technique will work to read any memory in the 000000h to 3FFFFFh address space, so it also applies to reading the Configuration registers.

TABLE 4-1: READ CODE MEMORY SEQUENCE

4-Bit Command	Data Payload	Core Instruction
Step 1: Set Table	Pointer.	
0000 0000 0000 0000 0000	0E <addr[21:16]> 6E F8 0E <addr[15:8]> 6E F7 0E <addr[7:0]> 6E F6</addr[7:0]></addr[15:8]></addr[21:16]>	MOVLW Addr[21:16] MOVWF TBLPTRU MOVLW <addr[15:8]> MOVWF TBLPTRH MOVLW <addr[7:0]> MOVWF TBLPTRL</addr[7:0]></addr[15:8]>
Step 2: Read mer	mory and then shift out on P	PGD, LSb to MSb.
1001	00 00	TBLRD *+





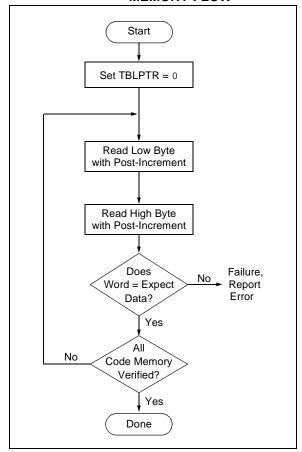
4.2 Verify Code Memory and Configuration Word

The verify step involves reading back the code memory space and comparing it against the copy held in the programmer's buffer. Because the Flash Configuration Words are stored at the end of program memory, it is verified with the rest of the code at this time.

The verify process is shown in the flowchart in Figure 4-2. Memory reads occur a single byte at a time, so two bytes must be read to compare against the word in the programmer's buffer. Refer to **Section 4.1** "**Read Code Memory**" for implementation details of reading code memory.

Note 1: Because the Flash Configuration Word contains the device code protection bit, code memory should be verified immediately after writing if code protection is enabled. This is because the device will not be readable or verifiable if a device Reset occurs after the Flash Configuration Words (and the CP0 bit) have been cleared.

FIGURE 4-2: VERIFY CODE MEMORY FLOW



4.3 Blank Check

The term Blank Check means to verify that the device has no programmed memory cells. All memories, code memory and Configuration bits, must be verified. The Device ID registers (3FFFEh:3FFFFh) should be ignored.

A "blank" or "erased" memory cell will read as a '1', so Blank Checking a device merely means to verify that all bytes read as FFh. The overall process flow is shown in Figure 4-3.

Blank Checking is merely code verification with FFh expect data. For implementation details, refer to Section 4.2 "Verify Code Memory and Configuration Word".

FIGURE 4-3: BLANK CHECK FLOW

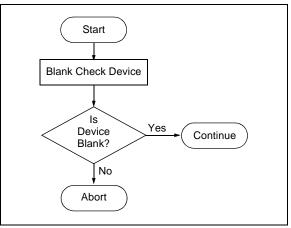


TABLE 5-3: PIC18F45J10 FAMILY DEVICES: BIT DESCRIPTIONS

Bit Name	Configuration Words	Description		
DEBUG	CONFIG1L	Background Debugger Enable bit 1 = Background debugger disabled, RB6 and RB7 configured as general purpose I/O pins 0 = Background debugger enabled, RB6 and RB7 are dedicated to in-circuit debug		
XINST	CONFIG1L	Extended Instruction Set Enable bit 1 = Instruction set extension and Indexed Addressing mode enabled 0 = Instruction set extension and Indexed Addressing mode disabled (Legacy mode)		
STVREN	CONFIG1L	Stack Overflow/Underflow Reset Enable bit 1 = Reset on stack overflow/underflow enabled 0 = Reset on stack overflow/underflow disabled		
WDTEN	CONFIG1L	Watchdog Timer Enable bit 1 = WDT enabled 0 = WDT disabled (control is placed on SWDTEN bit)		
CP0	CONFIG1H	Code Protection bit 1 = Program memory is not code-protected 0 = Program memory is code-protected		
IESO	CONFIG2L	Internal/External Oscillator Switchover bit 1 = Oscillator Switchover mode enabled 0 = Oscillator Switchover mode disabled		
FCMEN	CONFIG2L	Fail-Safe Clock Monitor Enable bit 1 = Fail-Safe Clock Monitor enabled 0 = Fail-Safe Clock Monitor disabled		
FOSC2	CONFIG2L	Default Oscillator Select bit 1 = Clock designated by FOSC<1:0> is enabled as system clock when OSCCON<1:0> = 00 0 = INTRC is enabled as system clock when OSCCON<1:0> = 00		
FOSC<1:0>	CONFIG2L	Primary Oscillator Select bits 11 = EC oscillator, PLL enabled and under software control, CLKO function on OSC2 10 = EC oscillator, CLKO function on OSC2 01 = HS oscillator, PLL enabled and under software control 00 = HS oscillator		
WDTPS<3:0>	CONFIG2H	Watchdog Timer Postscale Select bits 1111 = 1:32,768 1110 = 1:16,384 1101 = 1:8,192 1100 = 1:4,096 1011 = 1:2,048 1010 = 1:512 1000 = 1:256 0111 = 1:128 0110 = 1:64 0101 = 1:32 0100 = 1:16 0011 = 1:8 0010 = 1:4 0001 = 1:2 0000 = 1:1		
CCP2MX	CONFIG3H	CCP2 MUX bit 1 = CCP2 is multiplexed with RC1 0 = CCP2 is multiplexed with RB3		

TABLE 5-4: PIC18F46J11 AND PIC18F46J50 FAMILY DEVICES: CONFIGURATION BITS AND DEVICE IDs

File	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default/ Unprogrammed Value ⁽¹⁾
300000h	CONFIG1L	DEBUG	XINST	STVREN	_	PLLDIV2 ⁽³⁾	PLLDIV1 ⁽³⁾	PLLDIV0(3)	WDTEN	111- 1111
300001h	CONFIG1H	(2)	(2)	(2)	(2)	(4)	CP0	CPDIV1 ⁽³⁾	CPDIV0(3)	0111
300002h	CONFIG2L	IESO	FCMEN	_	LPT1OSC	T1DIG	FOSC2	FOSC1	FOSC0	11-1 1111
300003h	CONFIG2H	(2)	(2)	(2)	(2)	WDTPS3	WDTPS2	WDTPS1	WDTPS0	1111
300004h	CONFIG3L	DSWDTPS3	DSWDTPS2	DSWDTPS1	DSWDTPS0	DSWDTEN	DSBOREN	RTCOSC	DSWDTOSC	1111 1111
300005h	CONFIG3H	(2)	(2)	(2)	(2)	MSSPMSK	_	1	IOL1WAY	11
300006h	CONFIG4L	WPCFG	WPEND	WPFP5 ⁽⁵⁾	WPFP4 ⁽⁶⁾	WPFP3	WPFP2	WPFP1	WPFP0	1111 1111
300007h	CONFIG4H	(2)	(2)	(2)	(2)	_	_	_	WPDIS	1
3FFFFEh	DEVID1	DEV2	DEV1	DEV0	REV4	REV3	REV2	REV1	REV0	xxxx xxxx
3FFFFFh	DEVID2	DEV10	DEV9	DEV8	DEV7	DEV6	DEV5	DEV4	DEV3	0100 00xx

Legend: x = unknown, u = unchanged, - = unimplemented. Shaded cells are unimplemented, read as '0'.

Note 1: Values reflect the unprogrammed state as received from the factory and following Power-on Resets. In all other Reset states, the configuration bytes maintain their previously programmed states.

- 2: The value of these bits in program memory should always be '1'. This ensures that the location is executed as a NOP if it is accidentally executed.
- 3: These bits are not implemented in PIC18F46J11 family devices.
- 4: This bit should always be maintained at '0'.
- 5: This bit is not available on 32K and 16K memory devices (X4J11, X4J50, X5J11, and X5J50 devices) and should always be maintained at '0' on those devices.
- 6: This bit is not available on 16K memory devices (X4J11 and X4J50 devices) and should always be maintained at '0' on those devices.

TABLE 5-5: PIC18F46J11 AND PIC18F46J50 FAMILY DEVICES: BIT DESCRIPTIONS

Bit Name	Configuration Words	Description
DEBUG	CONFIG1L	Background Debugger Enable bit 1 = Background debugger disabled, RB6 and RB7 configured as general purpose I/O pins 0 = Background debugger enabled, RB6 and RB7 are dedicated to in-circuit debug
XINST	CONFIG1L	Enhanced Instruction Set Enable bit 1 = Instruction set extension and Indexed Addressing mode enabled 0 = Instruction set extension and Indexed Addressing mode disabled (Legacy mode)
STVREN	CONFIG1L	Stack Overflow/Underflow Reset Enable bit 1 = Reset on stack overflow/underflow enabled 0 = Reset on stack overflow/underflow disabled
PLLDIV<2:0>(3)	CONFIG1L	PLL Input Divider bits Divider must be selected to provide a 4 MHz input into the 96 MHz PLL. 111 = No divide – oscillator used directly (4 MHz input) 110 = Oscillator divided by 2 (8 MHz input) 101 = Oscillator divided by 3 (12 MHz input) 100 = Oscillator divided by 4 (16 MHz input) 011 = Oscillator divided by 5 (20 MHz input) 010 = Oscillator divided by 6 (24 MHz input) 001 = Oscillator divided by 10 (40 MHz input) 000 = Oscillator divided by 12 (48 MHz input)
WDTEN	CONFIG1L	Watchdog Timer Enable bit 1 = WDT enabled 0 = WDT disabled (control is placed on SWDTEN bit)

Note 1: The Configuration bits can only be programmed indirectly by programming the Flash Configuration Word.

- 2: The Configuration bits are reset to '1' only on VDD Reset; it is reloaded with the programmed value at any device Reset.
- 3: These bits are not implemented in PIC18F46J11 family devices.
- **4:** Once this bit is cleared, all the Configuration registers which reside in the last page are also protected. To disable code protection, perform an ICSP™ Bulk Erase operation.

TABLE 5-7: PIC18F47J13 AND PIC18F47J53 FAMILY DEVICES: BIT DESCRIPTIONS

Bit Name	Configuration Words	Description
DEBUG	CONFIG1L	Background Debugger Enable bit 1 = Background debugger disabled, RB6 and RB7 configured as general purpose I/O pins 0 = Background debugger enabled, RB6 and RB7 are dedicated to in-circuit debug
XINST	CONFIG1L	Enhanced Instruction Set Enable bit 1 = Instruction set extension and Indexed Addressing mode enabled 0 = Instruction set extension and Indexed Addressing mode disabled (Legacy mode)
STVREN	CONFIG1L	Stack Overflow/Underflow Reset Enable bit 1 = Reset on stack overflow/underflow enabled 0 = Reset on stack overflow/underflow disabled
CFGPLLEN	CONFIG1L	Enable PLL on Start-up bit 1 = PLL enabled on start-up. Not recommended for low-voltage designs. 0 = PLL disabled on start-up. Firmware may later enable PLL through OSCTUNE<6>.
PLLDIV<2:0>	CONFIG1L	96 MHz PLL Input Divider bits Divider must be selected to provide a 4 MHz input into the 96 MHz PLL. 111 =No divide — oscillator used directly (4 MHz input) 110 =Oscillator divided by 2 (8 MHz input) 101 =Oscillator divided by 3 (12 MHz input) 100 =Oscillator divided by 4 (16 MHz input) 011 =Oscillator divided by 5 (20 MHz input) 010 =Oscillator divided by 6 (24 MHz input) 010 =Oscillator divided by 10 (40 MHz input) 001 =Oscillator divided by 12 (48 MHz input)
WDTEN	CONFIG1L	Watchdog Timer Enable bit 1 = WDT enabled 0 = WDT disabled (control is placed on the SWDTEN bit)
CP0 ⁽⁴⁾	CONFIG1H	Code Protection bit 1 = Program memory is not code-protected 0 = Program memory is code-protected
CPDIV<1:0> ⁽³⁾	CONFIG1H	CPU System Clock Selection bits 11 = No CPU system clock divide 10 = CPU system clock divided by 2 01 = CPU system clock divided by 3 00 = CPU system clock divided by 6
IESO	CONFIG2L ^(1,2)	Two-Speed Start-up (Internal/External Oscillator Switchover) Control bit 1 = Oscillator Switchover mode enabled 0 = Oscillator Switchover mode disabled
FCMEN	CONFIG2L ^(1,2)	Fail-Safe Clock Monitor Enable bit 1 = Fail-Safe Clock Monitor enabled 0 = Fail-Safe Clock Monitor disabled
CLKOEC	CONFIG2L	EC Mode Clock Output Enable bit 1 = CLKO output signal active on the RA6 pin (EC mode only) 0 = CLKO output disabled
SOSCSEL<1:0>	CONFIG2L	Secondary Oscillator Circuit Selection bits 11 = High-power SOSC circuit selected 10 = Digital Input mode (SCLKI) 01 = Low-power SOSC circuit selected 00 = Reserved

Note 1: The Configuration bits can only be programmed indirectly by programming the Flash Configuration Word.

- 2: The Configuration bits are reset to '1' only on VDD Reset; it is reloaded with the programmed value at any device Reset.
- 3: These bits are not implemented in PIC18F47J13 family devices.
- **4:** Once this bit is cleared, all the Configuration registers which reside in the last page are also protected. To disable code protection, perform an ICSP™ Bulk Erase operation.
- 5: Not implemented on PIC18F47J53 family devices.

TABLE 5-7: PIC18F47J13 AND PIC18F47J53 FAMILY DEVICES: BIT DESCRIPTIONS (CONTINUED)

Bit Name	Configuration Words	Description
FOSC<2:0>	CONFIG2L ^(1,2)	Oscillator Selection bits 111 =EC+PLL (S/W controlled by PLLEN bit), CLKO on RA6 110 =EC oscillator (PLL always disabled) with CLKO on RA6 110 =HS+PLL (S/W controlled by PLLEN bit) 100 =HS oscillator (PLL always disabled) 011 =INTOSCPLLO, internal oscillator with PLL (S/W controlled by PLLEN bit), CLKO on RA6, port function on RA7 010 =INTOSCPLL, internal oscillator with PLL (S/W controlled by PLLEN bit), port function on RA6 and RA7 001 =INTOSCO, internal oscillator, INTOSC or INTRC (PLL always disabled), CLKO on RA6, port function on RA7 000 =INTOSC, internal oscillator INTOSC or INTRC (PLL always disabled), port function on RA6 and RA7
WDTPS<3:0>	CONFIG2H ^(1,2)	Watchdog Timer Postscale Select bits 1111 = 1:32,768 1110 = 1:16,384 1101 = 1:8,192 1100 = 1:4,096 1011 = 1:2,048 1010 = 1:512 1000 = 1:552 1000 = 1:256 0111 = 1:128 0110 = 1:64 0101 = 1:32 0100 = 1:16 0011 = 1:8 0010 = 1:4 0001 = 1:2 0000 = 1:1
DSWTPS<3:0>	CONFIG3L	Deep Sleep Watchdog Timer Postscale Select bits The DSWDT prescaler is 32; this creates an approximate base time unit of 1 ms. 1111 = 1:2,147,483,648 (25.7 days) 1110 = 1:536,870,912 (6.4 days) 1101 = 1:134,217,728 (38.5 hours) 1100 = 1:33,554,432 (9.6 hours) 1011 = 1:8,388,608 (2.4 hours) 1010 = 1:2,097,152 (36 minutes) 1001 = 1:524,288 (9 minutes) 1000 = 1:131,072 (135 seconds) 0111 = 1:32,768 (34 seconds) 0110 = 1:8,192 (8.5 seconds) 0110 = 1:2,048 (2.1 seconds) 0100 = 1:512 (528 ms) 0011 = 1:128 (132 ms) 0010 = 1:32 (33 ms) 0001 = 1:8 (8.3 ms) 0000 = 1:2 (2.1 ms)
DSWDTEN	CONFIG3L	Deep Sleep Watchdog Timer Enable bit 1 = DSWDT enabled 0 = DSWDT disabled
DSBOREN	CONFIG3L	Deep Sleep BOR Enable bit 1 = BOR enabled in Deep Sleep 0 = BOR disabled in Deep Sleep (does not affect operation in non Deep Sleep modes)

- Note 1: The Configuration bits can only be programmed indirectly by programming the Flash Configuration Word.
 - 2: The Configuration bits are reset to '1' only on VDD Reset; it is reloaded with the programmed value at any device Reset.
 - **3:** These bits are not implemented in PIC18F47J13 family devices.
 - **4:** Once this bit is cleared, all the Configuration registers which reside in the last page are also protected. To disable code protection, perform an ICSP™ Bulk Erase operation.
 - 5: Not implemented on PIC18F47J53 family devices.

5.1 Device ID Word

The Device ID Word for the PIC18F2XJXX/4XJXX Family devices is located at 3FFFEh:3FFFFh. These read-only bits may be used by the programmer to identify what device type is being programmed and read out normally, even after code protection has been enabled. The process for reading the Device IDs is shown in Figure 5-1. A complete list of Device ID values for the PIC18F2XJXX/4XJXX Family is presented in Table 5-8.

FIGURE 5-1: READ DEVICE ID WORD FLOW

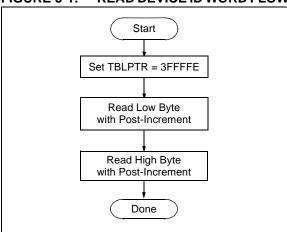


TABLE 5-8: DEVICE ID VALUE

Device	Device ID Value				
Device	DEVID2	DEVID1			
PIC18F24J10	1Dh	000x xxxx			
PIC18F25J10	1Ch	000x xxxx			
PIC18F44J10	1Dh	001x xxxx			
PIC18F45J10	1Ch	001x xxxx			
PIC18LF24J10	1Dh	010x xxxx			
PIC18LF25J10	1Ch	010x xxxx			
PIC18LF44J10	1Dh	011x xxxx			
PIC18LF45J10	1Ch	011x xxxx			
PIC18F25J11	4Dh	101x xxxx			
PIC18F24J11	4Dh	100x xxxx			
PIC18F26J11	4Dh	110x xxxx			
PIC18F45J11	4Eh	000x xxxx			
PIC18F44J11	4Dh	111x xxxx			
PIC18F46J11	4Eh	001x xxxx			
PIC18F24J50	4Ch	000x xxxx			
PIC18F25J50	4Ch	001x xxxx			
PIC18F26J50	4Ch	010x xxxx			
PIC18F44J50	4Ch	011x xxxx			
PIC18F45J50	4Ch	100x xxxx			

TABLE 5-8: DEVICE ID VALUE (CONTINUED)

Davisa	Device ID Value			
Device	DEVID2	DEVID1		
PIC18F46J50	4Ch	101x xxxx		
PIC18LF2450	4Ch	110x xxxx		
PIC18LF25J50	4Ch	111x xxxx		
PIC18LF26J50	4Dh	000x xxxx		
PIC18LF44J50	4Dh	001x xxxx		
PIC18LF45J50	4Dh	010x xxxx		
PIC18LF46J50	4Dh	011x xxxx		
PIC18LF24J11	4Eh	010x xxxx		
PIC18LF25J11	4Eh	011x xxxx		
PIC18LF26J11	4Eh	100x xxxx		
PIC18LF44J11	4Eh	101x xxxx		
PIC18LF45J11	4Eh	110x xxxx		
PIC18LF46J11	4Eh	111x xxxx		
PIC18F26J13	59h	001x xxxx		
PIC18F27J13	59h	011x xxxx		
PIC18F46J13	59h	101x xxxx		
PIC18F47J13	59h	111x xxxx		
PIC18LF26J13	5Bh	001x xxxx		
PIC18LF27J13	5Bh	011x xxxx		
PIC18LF46J13	5Bh	101x xxxx		
PIC18LF47J13	5Bh	111x xxxx		
PIC18F26J53	58h	001x xxxx		
PIC18F27J53	58h	011x xxxx		
PIC18F46J53	58h	101x xxxx		
PIC18F47J53	58h	111x xxxx		
PIC18LF26J53	5Ah	001x xxxx		
PIC18LF27J53	5Ah	011x xxxx		
PIC18LF46J53	5Ah	101x xxxx		
PIC18LF47J53	5Ah	111x xxxx		

5.2 Checksum Computation

The checksum is calculated by summing the contents of all code memory locations and the device Configuration Words, appropriately masked. The Least Significant 16 bits of this sum are the checksum.

The checksum calculation differs depending on whether or not code protection is enabled. Since the code memory locations read out differently depending on the code-protect setting, the table describes how to manipulate the actual code memory values to simulate the values that would be read from a protected device. When calculating a checksum by reading a device, the entire code memory can simply be read and summed. The Configuration Words can always be read.

6.0 AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY TEST MODE

Standard Operating Conditions

Operating Temperature: 25°C is recommended

- 1	The same of the sa						
Param No.	Symbol	Characteristic		Min.	Max.	Units	Conditions
	VDDCORE	External Supply Voltage for Microcontroller Core During Programming Operations (PIC18LF devices)		2.25	2.75	V	(Note 1)
D111 VDD	VDD	Dra gramamin a	PIC18 LF XXJXX	VDDCORE	3.60	V	Normal programming (Note 2)
			PIC18FXXJ10	2.70	3.60	V	
			PIC18FXXJ50 PIC18FXXJ11 PIC18FXXJ53 PIC18FXXJ13	2.35	3.60	V	
D112	IPP	Programming Current on MCLR			5	μΑ	
D113	IDDP	Supply Current During Programming			10	mA	
D031	VIL	Input Low Voltage		Vss	0.2 VDD	٧	
D041	VIH	Input High Voltage		0.8 VDD	Vdd	٧	
D080	Vol	Output Low Voltage			0.4	V	IOL = 3.4 mA @ 3.3V
D090	Vон	Output High Voltage		2.4	_	٧	IOH = -2.0 mA @ 3.3V
D012	Сю	Capacitive Loading on I/O pin (PGD)			50	рF	To meet AC specifications
	CF	Filter Capacitor Value on	PIC18 LF XXJXX	0.1	_	μF	(Note 1)
		VCAP	PIC18FXXJ10	4.7	18	μF	
			PIC18FXXJ13 PIC18FXXJ11 PIC18FXXJ5X	5.4	18	μF	

- Note 1: External power must be supplied to the VDDCORE/VCAP pin if the on-chip voltage regulator is disabled. See Section 2.1.1 "PIC18F2XJXX/4XJXX/ LF2XJXX/LF4XJXX Devices and the On-Chip Voltage Regulator" for more information.
 - 2: VDD must also be supplied to the AVDD pins during programming. AVDD and AVss should always be within ±0.3V of VDD and Vss, respectively.

6.0 AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY TEST MODE (CONTINUED)

Standard Operating Conditions

Operating Temperature: 25°C is recommended

Operat	Operating Temperature: 25°C is recommended						
Param No.	Symbol	Characteristic	Min.	Max.	Units	Conditions	
P1	TR	MCLR Rise Time to Enter Program/Verify mode	_	1.0	μS		
P2	TPGC	Serial Clock (PGC) Period	100	_	ns		
P2A	TPGCL	Serial Clock (PGC) Low Time	50	_	ns		
P2B	TPGCH	Serial Clock (PGC) High Time	50	_	ns		
P3	TSET1	Input Data Setup Time to Serial Clock ↓	20	_	ns		
P4	THLD1	Input Data Hold Time from PGC ↓	20	_	ns		
P5	TDLY1	Delay Between 4-Bit Command and Command Operand	50	_	ns		
P5A	TDLY1A	Delay Between 4-Bit Command Operand and Next 4-Bit Command	50	_	ns		
P6	TDLY2	Delay Between Last PGC ↓ of Command Byte to First PGC ↑ of Read of Data Word	20	_	ns		
P9	TDLY5	Delay to allow Block Programming to occur	3.4	_	ms	PIC18F2XJ10/PIC18F4XJ10	
			1.2	_	ms	PIC18F2XJ11/PIC18F4XJ11/ PIC18F2XJ13/PIC18F4XJ13/ PIC18F2XJ5X/PIC18F4XJ5X	
P10	TDLY6	Delay to allow Row Erase to occur	49	_	ms	PIC18F2XJ10/PIC18F4XJ10/ PIC18F2XJ13/PIC18F4XJ13/ PIC18F2XJ53/PIC18F4XJ53	
			54	_	ms	PIC18F2XJ11/PIC18F4XJ11/ PIC18F2XJ50/PIC18F4XJ50	
P11	TDLY7	Delay to allow Bulk Erase to occur	475	_	ms	PIC18F2XJ10/PIC18F4XJ10/ PIC18F2XJ13/PIC18F4XJ13/ PIC18F2XJ53/PIC18F4XJ53	
			524	_	ms	PIC18F2XJ11/PIC18F4XJ11/ PIC18F2XJ50/PIC18F4XJ50	
P12	THLD2	Input Data Hold Time from MCLR ↑	400	_	μS		
P13	TSET2	VDD ↑ Setup Time to MCLR ↑	100	_	ns		
P14	TVALID	Data Out Valid from PGC ↑	25	_	ns		
P16	TDLY8	Delay between Last PGC ↓ and MCLR ↓	20	_	ns		
P17	THLD3	MCLR ↓ to VDD ↓	3	_	μS		
P19	TKEY1	Delay from First MCLR ↓ to First PGC ↑ for Key Sequence on PGD	4	_	ms		
P20	TKEY2	Delay from Last <u>PGC</u> ↓ for Key Sequence on PGD to Second MCLR ↑	50	_	ns		

Note 1: External power must be supplied to the VDDCORE/VCAP pin if the on-chip voltage regulator is disabled. See Section 2.1.1 "PIC18F2XJXX/4XJXX/ LF2XJXX/LF4XJXX Devices and the On-Chip Voltage Regulator" for more information.

^{2:} VDD must also be supplied to the AVDD pins during programming. AVDD and AVSS should always be within ±0.3V of VDD and VSS, respectively.

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