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#### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	11
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	14-SOIC (0.154", 3.90mm Width)
Supplier Device Package	14-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16f1825-e-sl

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

#### 3.5.1 TRADITIONAL DATA MEMORY

The traditional data memory is a region from FSR address 0x000 to FSR address 0xFFF. The addresses correspond to the absolute addresses of all SFR, GPR and common registers.





#### FIGURE 5-3:

#### QUARTZ CRYSTAL OPERATION (LP, XT OR HS MODE)



- **2:** Always verify oscillator performance over the VDD and temperature range that is expected for the application.
- **3:** For oscillator design assistance, reference the following Microchip Application Notes:
  - AN826, "Crystal Oscillator Basics and Crystal Selection for rfPIC<sup>®</sup> and PIC<sup>®</sup> Devices" (DS00826)
  - AN849, "Basic PIC<sup>®</sup> Oscillator Design" (DS00849)
  - AN943, "Practical PIC<sup>®</sup> Oscillator Analysis and Design" (DS00943)
  - AN949, "Making Your Oscillator Work" (DS00949)

#### FIGURE 5-4: CERAMIC RESONATOR OPERATION



**3:** An additional parallel feedback resistor (RP) may be required for proper ceramic resonator operation.

### 5.2.1.3 Oscillator Start-up Timer (OST)

If the oscillator module is configured for LP, XT or HS modes, the Oscillator Start-up Timer (OST) counts 1024 oscillations from OSC1. This occurs following a Power-on Reset (POR) and when the Power-up Timer (PWRT) has expired (if configured), or a wake-up from Sleep. During this time, the program counter does not increment and program execution is suspended unless either FSCM or Two-Speed Start-up are enabled. In this case, the code will continue to execute at the selected INTOSC frequency while the OST is counting. The OST ensures that the oscillator circuit, using a quartz crystal resonator or ceramic resonator, has started and is providing a stable system clock to the oscillator module.

In order to minimize latency between external oscillator start-up and code execution, the Two-Speed Clock Start-up mode can be selected (see **Section 5.4 "Two-Speed Clock Start-up Mode"**).

#### 8.6.2 PIE1 REGISTER

The PIE1 register contains the interrupt enable bits, as shown in Register 8-2.

**Note:** Bit PEIE of the INTCON register must be set to enable any peripheral interrupt.

#### REGISTER 8-2: PIE1: PERIPHERAL INTERRUPT ENABLE REGISTER 1

| R/W-0/0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| TMR1GIE | ADIE    | RCIE    | TXIE    | SSP1IE  | CCP1IE  | TMR2IE  | TMR1IE  |
| bit 7   |         |         |         |         |         |         | bit 0   |

Legend:			
R = Readable	bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged		x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set		'0' = Bit is cleared	
bit 7	TMR1GIE: Ti	mer1 Gate Interrupt Enable	bit
	1 = Enables t	the Timer1 Gate Acquisition	interrupt
	0 = Disables	the Timer1 Gate Acquisition	interrupt
bit 6	ADIE: A/D Co	onverter (ADC) Interrupt Ena	ble bit
	1 = Enables t	the ADC interrupt	
bit 5	RCIE: USAR	I Receive Interrupt Enable b	nt
	1 = Enables t 0 = Disables	the USART receive interrupt	
bit 4		T Transmit Interrupt Enable k	, sit
bit 4	1 = Enables t	the LISART transmit interrupt	
	0 = Disables	the USART transmit interrup	t
bit 3	SSP1IE: Syn	chronous Serial Port (MSSP	) Interrupt Enable bit
	1 = Enables t	the MSSP interrupt	
	0 = Disables	the MSSP interrupt	
bit 2	CCP1IE: CCI	P1 Interrupt Enable bit	
	1 = Enables t	the CCP1 interrupt	
	0 = Disables	the CCP1 interrupt	
bit 1	TMR2IE: TM	R2 to PR2 Match Interrupt E	nable bit
	1 = Enables t	the Timer2 to PR2 match inte	errupt
		the Timer2 to PR2 match int	errupt
bit 0	TMR1IE: Tim	er1 Overflow Interrupt Enabl	e bit
	1 = Enables t	the Timer1 overflow interrupt	+
	U - Disables	the miller overnow interrup	l

R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	U-0	U-0
RXDTSEL	SDO1SEL	SS1SEL	—	T1GSEL	TXCKSEL		_
bit 7					1		bit 0
Legend:							
R = Readable I	bit	W = Writable	bit	U = Unimplen	nented bit, read	l as '0'	
u = Bit is uncha	anged	x = Bit is unkn	nown	-n/n = Value a	at POR and BO	R/Value at all o	ther Resets
'1' = Bit is set		'0' = Bit is clea	ared				
bit 7	<b>RXDTSEL:</b> Pi For 14 Pin De 0 = RX/DT fi 1 = RX/DT fi For 20 Pin De 0 = RX/DT fi	in Selection bit evices (PIC16(L unction is on R unction is on R evices (PIC16(L unction is on R	. <u>)F1825):</u> C5 A1 . <u>)F1829):</u> B5				
bit 6	<b>SDO1SEL:</b> Pi For 14 Pin De 0 = SDO1 fu 1 = SDO1 fu For 20 Pin De Bit is read-onl SDO1 function	in Selection bit evices (PIC16(L unction is on R unction is on R evices (PIC16(L ly, '0' n is always on	_)F1825): C2 A4 _)F1829): RC7				
bit 5	<b>SS1SEL:</b> Pin For 14 Pin De $0 = \overline{SS1}$ fun $1 = \overline{SS1}$ fun For 20 Pin De Bit is read-onl $\overline{SS1}$ function i	Selection bit evices (PIC16(L ction is on RC3 ction is on RA3 evices (PIC16(L ly, '0' is always on R <sup>6</sup>	_)F1825): } _)F1829): _)F1829):				
bit 4	Unimplemen	ted: Read as '	D'				
bit 3	<b>T1GSEL:</b> Pin 0 = T1G fun 1 = T1G fun	Selection bit ction is on RA4 ction is on RA3	L 3				
bit 2 bit 1-0	<b>TXCKSEL:</b> Pi For 14 Pin De 0 = TX/CK ft 1 = TX/CK ft For 20 Pin De 0 = TX/CK ft 1 = TX/CK ft <b>Unimplement</b>	in Selection bit evices (PIC16(L unction is on R unction is on R evices (PIC16(L unction is on R unction is on R ted: Read as '(	<u>.)F1825):</u> C4 A0 . <u>)F1829):</u> B7 C4 D'				

### REGISTER 12-1: APFCON0: ALTERNATE PIN FUNCTION CONTROL REGISTER 0

#### **REGISTER 13-2: IOCAN: INTERRUPT-ON-CHANGE PORTA NEGATIVE EDGE REGISTER**

U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	
—	—	IOCAN5	IOCAN4	IOCAN3	IOCAN2	IOCAN1	IOCAN0	
bit 7							bit 0	
Legend:								
R = Readable bit	:	W = Writable bi	t	U = Unimplemented bit, read as '0'				
u = Bit is unchanged x = Bit is unknown		-n/n = Value at POR and BOR/Value at all other Resets						
'1' = Bit is set		'0' = Bit is clear	ed					

bit 7-6 Unimplemented: Read as '0'

bit 5-0

IOCAN<5:0>: Interrupt-on-Change PORTA Negative Edge Enable bits

1 = Interrupt-on-change enabled on the pin for a negative going edge. Associated Status bit and interrupt flag will be set upon detecting an edge.

0 = Interrupt-on-change disabled for the associated pin.

#### REGISTER 13-3: IOCAF: INTERRUPT-ON-CHANGE PORTA FLAG REGISTER

U-0	U-0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
—	—	IOCAF5	IOCAF4	IOCAF3	IOCAF2	IOCAF1	IOCAF0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HS - Bit is set in hardware

#### bit 7-6 Unimplemented: Read as '0'

bit 5-0 IOCAF<5:0>: Interrupt-on-Change PORTA Flag bits

1 = An enabled change was detected on the associated pin. Set when IOCAPx = 1 and a rising edge was detected on RAx, or when IOCANx = 1 and a falling edge was detected on RAx.

0 = No change was detected, or the user cleared the detected change.

#### REGISTER 13-4: IOCBP: INTERRUPT-ON-CHANGE PORTB POSITIVE EDGE REGISTER (PIC16(L)F1829 ONLY)

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	U-0	U-0	U-0
IOCBP7	IOCBP6	IOCBP5	IOCBP4	—	—	—	—
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-4	IOCBP<7:4>: Interrupt-on-Change PORTB Positive Edge Enable bits						
	1 = Interrupt-on-change enabled on the pin for a positive going edge. Associated Status bit and interrupt						
	flag will be set upon detecting an edge.						
	0 = Interrupt-on-change disabled for the associated pin.						
bit 3-0	Unimplemented: Read as '0'						

SRCLK	Divider	Fosc = 32 MHz	Fosc = 20 MHz	Fosc = 16 MHz	Fosc = 4 MHz	Fosc = 1 MHz
111	512	62.5 kHz	39.0 kHz	31.3 kHz	7.81 kHz	1.95 kHz
110	256	125 kHz	78.1 kHz	62.5 kHz	15.6 kHz	3.90 kHz
101	128	250 kHz	156 kHz	125 kHz	31.25 kHz	7.81 kHz
100	64	500 kHz	313 kHz	250 kHz	62.5 kHz	15.6 kHz
011	32	1 MHz	625 kHz	500 kHz	125 kHz	31.3 kHz
010	16	2 MHz	1.25 MHz	1 MHz	250 kHz	62.5 kHz
001	8	4 MHz	2.5 MHz	2 MHz	500 kHz	125 kHz
000	4	8 MHz	5 MHz	4 MHz	1 MHz	250 kHz

#### TABLE 18-1: SRCLK FREQUENCY TABLE

#### REGISTER 18-1: SRCON0: SR LATCH CONTROL 0 REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/S-0/0	R/S-0/0
SRLEN		SRCLK<2:0>		SRQEN	SRNQEN	SRPS	SRPR
bit 7							bit 0

Legend:			
R = Readable bit		W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged		x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is s	et	'0' = Bit is cleared	S = Bit is set only
bit 7	SRLEN: SR 1 = SR latcl 0 = SR latcl	Latch Enable bit n is enabled n is disabled	
bit 6-4	SRCLK<2:0 000 = Gener 001 = Gener 010 = Gener 100 = Gener 101 = Gener 110 = Gener 111 = Gener	>: SR Latch Clock Divider bits rates a 1 Fosc wide pulse ever rates a 1 Fosc wide pulse ever	s ery 4th Fosc cycle clock ery 8th Fosc cycle clock ery 16th Fosc cycle clock ery 32nd Fosc cycle clock ery 64th Fosc cycle clock ery 128th Fosc cycle clock ery 256th Fosc cycle clock ery 512th Fosc cycle clock
bit 3	SRQEN: SR <u>If SRLEN = 1</u> 1 = Q i 0 = Ex <u>If SRLEN = 1</u> SR latch is d	Latch Q Output Enable bit <u>1</u> : s present on the SRQ pin ternal Q output is disabled <u>2</u> : isabled	
bit 2	SRNQEN: S           If SRLEN = 1           1 = Q i           0 = Ex           If SRLEN = 1           SR latch	R Latch $\overline{Q}$ Output Enable bit 1: s present on the SRnQ pin ternal $\overline{Q}$ output is disabled 2: n is disabled	
bit 1	<b>SRPS:</b> Pulse 1 = Pulse so 0 = No effect	e Set Input of the SR Latch bi et input for 1 Q-clock period ct on set input.	<sub>t</sub> (1)
bit 0	SRPR: Pulse 1 = Pulse R 0 = No effect	e Reset Input of the SR Latch eset input for 1 Q-clock perio ct on Reset input.	bit <sup>(1)</sup> d
Note 1:	Set only, always r	eads back '0'.	

#### 21.1 Timer1 Operation

The Timer1 module is a 16-bit incrementing counter which is accessed through the TMR1H:TMR1L register pair. Writes to TMR1H or TMR1L directly update the counter.

When used with an internal clock source, the module is a timer and increments on every instruction cycle. When used with an external clock source, the module can be used as either a timer or counter and increments on every selected edge of the external source.

Timer1 is enabled by configuring the TMR1ON and TMR1GE bits in the T1CON and T1GCON registers, respectively. Table 21-1 displays the Timer1 enable selections.

TABLE 21-1:	TIMER1 ENABLE
	SELECTIONS

TMR10N	TMR1GE	Timer1 Operation
0	0	Off
0	1	Off
1	0	Always On
1	1	Count Enabled

#### 21.2 Clock Source Selection

The TMR1CS<1:0> and T1OSCEN bits of the T1CON register are used to select the clock source for Timer1. Table 21-2 displays the clock source selections.

#### 21.2.1 INTERNAL CLOCK SOURCE

When the internal clock source is selected the TMR1H:TMR1L register pair will increment on multiples of Fosc as determined by the Timer1 prescaler.

When the Fosc internal clock source is selected, the Timer1 register value will increment by four counts every instruction clock cycle. Due to this condition, a 2 LSB error in resolution will occur when reading the Timer1 value. To utilize the full resolution of Timer1, an asynchronous input signal must be used to gate the Timer1 clock input.

The following asynchronous sources may be used:

- Asynchronous event on the T1G pin to Timer1 gate
- C1 or C2 comparator input to Timer1 gate

#### 21.2.2 EXTERNAL CLOCK SOURCE

When the external clock source is selected, the Timer1 module may work as a timer or a counter.

When enabled to count, Timer1 is incremented on the rising edge of the external clock input T1CKI or the capacitive sensing oscillator signal. Either of these external clock sources can be synchronized to the microcontroller system clock or they can run asynchronously.

When used as a timer with a clock oscillator, an external 32.768 kHz crystal can be used in conjunction with the dedicated internal oscillator circuit.

- **Note:** In Counter mode, a falling edge must be registered by the counter prior to the first incrementing rising edge after any one or more of the following conditions:
  - Timer1 enabled after POR
  - Write to TMR1H or TMR1L
  - Timer1 is disabled
  - Timer1 is disabled (TMR1ON = 0) when T1CKI is high then Timer1 is enabled (TMR1ON=1) when T1CKI is low.

TMR1CS1	TMR1CS0	T10SCEN	Clock Source	
0	0	x	Instruction Clock (Fosc/4)	
0	1	x	System Clock (Fosc)	
1	0	0	External Clocking on T1CKI Pin	
1	0	0	External Clocking on T1CKI Pin	
1	1	x	Capacitive Sensing Oscillator	

#### TABLE 21-2: CLOCK SOURCE SELECTIONS

#### 25.2.6 SPI OPERATION IN SLEEP MODE

In SPI Master mode, module clocks may be operating at a different speed than when in full power mode; in the case of the Sleep mode, all clocks are halted.

Special care must be taken by the user when the MSSPx clock is much faster than the system clock.

In Slave mode, when MSSPx interrupts are enabled, after the master completes sending data, an MSSPx interrupt will wake the controller from Sleep.

If an exit from Sleep mode is not desired, MSSPx interrupts should be disabled.

In SPI Master mode, when the Sleep mode is selected, all module clocks are halted and the transmission/reception will remain in that state until the device wakes. After the device returns to Run mode, the module will resume transmitting and receiving data.

In SPI Slave mode, the SPI Transmit/Receive Shift register operates asynchronously to the device. This allows the device to be placed in Sleep mode and data to be shifted into the SPI Transmit/Receive Shift register. When all eight bits have been received, the MSSPx interrupt flag bit will be set and if enabled, will wake the device.

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELA	—	_	—	ANSA4	_	ANSA2	ANSA1	ANSA0	122
ANSELB <sup>(1)</sup>	_	_	ANSB5	ANSB4	_	_	_	—	129
ANSELC	ANSC7 <sup>(1)</sup>	ANSC6 <sup>(1)</sup>	_	_	ANSC3	ANSC2	ANSC1	ANSC0	134
APFCON0	RXDTSEL	SDO1SEL <sup>(2)</sup>	SS1SEL <sup>(2)</sup>	_	T1GSEL	TXCKSEL	—	_	118
APFCON1	—	-	SDO2SEL <sup>(1)</sup>	SS2SEL <sup>(1)</sup>	P1DSEL	P1CSEL	P2BSEL	CCP2SEL	119
INLVLA	—	_	INLVLA5 <sup>(1)</sup>	INLVLA4 <sup>(1)</sup>	INLVLA3	INLVLA2	INLVLA1	INLVLA0	124
INLVLB <sup>(1)</sup>	INLVLB7	INLVLB6	INLVLB5	INLVLB4	-	—	—	—	129
INLVLC	INLVLC7 <sup>(1)</sup>	INLVLC6 <sup>(1)</sup>	INLVLC5	INLVLC4	INLVLC3	INLVLC2	INLVLC1 <sup>(1)</sup>	INLVLC0 <sup>(1)</sup>	135
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	87
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSP1IE	CCP1IE	TMR2IE	TMR1IE	88
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSP1IF	CCP1IF	TMR2IF	TMR1IF	92
SSP1BUF	- Synchronous Serial Port Receive Buffer/Transmit Register							233*	
SSP1CON1	WCOL	SSPOV	SSPEN	CKP	SSPM<3:0>			277	
SSP1CON3	ACKTIM	PCIE	SCIE	BOEN	SDAHT	SBCDE	AHEN	DHEN	279
SSP1STAT	SMP	CKE	D/Ā	Р	S	R/W	UA	BF	276
TRISA	_	_	TRISA5 <sup>(1)</sup>	TRISA4 <sup>(1)</sup>	TRISA3	TRISA2	TRISA1	TRISA0	122
TRISB <sup>(1)</sup>	TRISB7	TRISB6	TRISB5	TRISB4	_	—	—	_	128
TRISC	TRISC7(1)	TRISC6 <sup>(1)</sup>	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1 <sup>(1)</sup>	TRISC0 <sup>(1)</sup>	133

#### TABLE 25-1: SUMMARY OF REGISTERS ASSOCIATED WITH SPI OPERATION

Legend: — Unimplemented location, read as '0'. Shaded cells are not used by the MSSP1 in SPI mode.

\* Page provides register information.

Note 1: PIC16(L)F1829 only.

2: PIC16(L)F1825 only.



#### 25.6.4 I<sup>2</sup>C MASTER MODE START CONDITION TIMING

To initiate a Start condition (Figure 25-26), the user sets the Start Enable bit, SEN bit of the SSPxCON2 register. If the SDAx and SCLx pins are sampled high, the Baud Rate Generator is reloaded with the contents of SSPxADD<7:0> and starts its count. If SCLx and SDAx are both sampled high when the Baud Rate Generator times out (TBRG), the SDAx pin is driven low. The action of the SDAx being driven low while SCLx is high is the Start condition and causes the S bit of the SSPxADD<7:0> and resumes its count. When the Baud Rate Generator times out (TBRG), the SDAx bit of the SSPxSTAT1 register to be set. Following this, the Baud Rate Generator is reloaded with the contents of SSPxADD<7:0> and resumes its count. When the Baud Rate Generator times out (TBRG), the SEN bit of the SSPxCON2 register will be automatically cleared

#### FIGURE 25-26: FIRST START BIT TIMING

by hardware; the Baud Rate Generator is suspended, leaving the SDAx line held low and the Start condition is complete.

- Note 1: If at the beginning of the Start condition, the SDAx and SCLx pins are already sampled low, or if during the Start condition, the SCLx line is sampled low before the SDAx line is driven low, a bus collision occurs, the Bus Collision Interrupt Flag, BCLxIF, is set, the Start condition is aborted and the I<sup>2</sup>C module is reset into its Idle state.
  - 2: The Philips I<sup>2</sup>C<sup>™</sup> Specification states that a bus collision cannot occur on a Start.



#### 25.6.13.3 Bus Collision During a Stop Condition

Bus collision occurs during a Stop condition if:

- a) After the SDAx pin has been deasserted and allowed to float high, SDAx is sampled low after the BRG has timed out. (CASE 1)
- b) After the SCLx pin is deasserted, SCLx is sampled low before SDAx goes high. (CASE 2)

The Stop condition begins with SDAx asserted low. When SDAx is sampled low, the SCLx pin is allowed to float. When the pin is sampled high (clock arbitration), the Baud Rate Generator is loaded with SSPxADD and counts down to zero. After the BRG times out, SDAx is sampled. If SDAx is sampled low, a bus collision has occurred. This is due to another master attempting to drive a data '0' (Figure 25-38). If the SCLx pin is sampled low before SDAx is allowed to float high, a bus collision occurs. This is another case of another master attempting to drive a data '0' (Figure 25-39).

#### FIGURE 25-38: BUS COLLISION DURING A STOP CONDITION (CASE 1)



#### FIGURE 25-39: BUS COLLISION DURING A STOP CONDITION (CASE 2)



#### 26.4.1.5 Synchronous Master Reception

Data is received at the RX/DT pin. The RX/DT pin output driver is automatically disabled when the EUSART is configured for synchronous master receive operation.

In Synchronous mode, reception is enabled by setting either the Single Receive Enable bit (SREN of the RCSTA register) or the Continuous Receive Enable bit (CREN of the RCSTA register).

When SREN is set and CREN is clear, only as many clock cycles are generated as there are data bits in a single character. The SREN bit is automatically cleared at the completion of one character. When CREN is set, clocks are continuously generated until CREN is cleared. If CREN is cleared in the middle of a character the CK clock stops immediately and the partial character is discarded. If SREN and CREN are both set, then SREN is cleared at the completion of the first character and CREN takes precedence.

To initiate reception, set either SREN or CREN. Data is sampled at the RX/DT pin on the trailing edge of the TX/CK clock pin and is shifted into the Receive Shift Register (RSR). When a complete character is received into the RSR, the RCIF bit is set and the character is automatically transferred to the two character receive FIFO. The Least Significant eight bits of the top character in the receive FIFO are available in RCREG. The RCIF bit remains set as long as there are unread characters in the receive FIFO.

Note:	If the RX/DT function is on an analog pin,			
	the corresponding ANSEL bit must be			
	cleared for the receiver to function.			

#### 26.4.1.6 Slave Clock

Synchronous data transfers use a separate clock line, which is synchronous with the data. A device configured as a slave receives the clock on the TX/CK line. The TX/CK pin output driver is automatically disabled when the device is configured for synchronous slave transmit or receive operation. Serial data bits change on the leading edge to ensure they are valid at the trailing edge of each clock. One data bit is transferred for each clock cycle. Only as many clock cycles should be received as there are data bits.

**Note:** If the device is configured as a slave and the TX/CK function is on an analog pin, the corresponding ANSEL bit must be cleared.

#### 26.4.1.7 Receive Overrun Error

The receive FIFO buffer can hold two characters. An overrun error will be generated if a third character, in its entirety, is received before RCREG is read to access the FIFO. When this happens the OERR bit of the RCSTA register is set. Previous data in the FIFO will not be overwritten. The two characters in the FIFO buffer can be read, however, no additional characters will be received until the error is cleared. The OERR bit can only be cleared by clearing the overrun condition. If the overrun error occurred when the SREN bit is set and CREN is clear then the error is cleared by reading RCREG. If the overrun occurred when the CREN bit is set then the error condition is cleared by either clearing the CREN bit of the RCSTA register or by clearing the SPEN bit which resets the EUSART.

#### 26.4.1.8 Receiving 9-bit Characters

The EUSART supports 9-bit character reception. When the RX9 bit of the RCSTA register is set the EUSART will shift 9-bits into the RSR for each character received. The RX9D bit of the RCSTA register is the ninth, and Most Significant, data bit of the top unread character in the receive FIFO. When reading 9-bit data from the receive FIFO buffer, the RX9D data bit must be read before reading the eight Least Significant bits from the RCREG.

# 26.4.1.9 Synchronous Master Reception Setup:

- 1. Initialize the SPBRGH, SPBRGL register pair for the appropriate baud rate. Set or clear the BRGH and BRG16 bits, as required, to achieve the desired baud rate.
- 2. Clear the ANSEL bit for the RX pin (if applicable).
- 3. Enable the synchronous master serial port by setting bits SYNC, SPEN and CSRC.
- 4. Ensure bits CREN and SREN are clear.
- 5. If interrupts are desired, set the RCIE bit of the PIE1 register and the GIE and PEIE bits of the INTCON register.
- 6. If 9-bit reception is desired, set bit RX9.
- 7. Start reception by setting the SREN bit or for continuous reception, set the CREN bit.
- 8. Interrupt flag bit RCIF will be set when reception of a character is complete. An interrupt will be generated if the enable bit RCIE was set.
- 9. Read the RCSTA register to get the ninth bit (if enabled) and determine if any error occurred during reception.
- 10. Read the 8-bit received data by reading the RCREG register.
- 11. If an overrun error occurs, clear the error by either clearing the CREN bit of the RCSTA register or by clearing the SPEN bit which resets the EUSART.

### 27.4 Current Ranges

The Capacitive Sensing Oscillator can operate within several different current ranges, depending on the Voltage Reference mode and current range selections. Within each of the two Voltage Reference modes there are four current ranges.

Selection between the Voltage Reference modes is controlled by the CPSRM bit of the CPSCON0 register. Clearing this bit selects the Fixed Voltage References provided by the Capacitive Sensing Oscillator module. Setting this bit selects the variable voltage references supplied by the Fixed Voltage Reference (FVR) module and the Digital-to-Analog Converter (DAC) module. See **Section 27.3 "Voltage References"** for more information on configuring the voltage references. Selecting the current range within the voltage reference mode is controlled by configuring the CPSRNG<1:0> bits in the CPSCON0 register. See Table 27-1 for proper current mode selection.

The Noise Detection mode is unique in that it disables the constant current source associated with the selected input pin, but leaves the rest of the oscillator circuitry and pin structure active. This eliminates the oscillation frequency on the analog pin and greatly reduces the current consumed by the Oscillator module. When noise is introduced onto the pin, the oscillator is driven at the frequency determined by the noise. This produces a detectable signal at the comparator stage, indicating the presence of activity on the pin. Figure 27-2 shows a more detailed drawing of the constant current sources and comparators associated with the oscillator and input pin.

CPSRM	Voltage Reference Mode	CPSRNG<1:0>	Current Range <sup>(1)</sup>
		00	Off
0	Tixed	01	Low
U	Fixed	10	Medium
		11	High
		00	Noise Detection
1	Variable	01	Low
Ţ	variable	10	Medium
		11	High

TABLE 27-1: CURRENT MODE SELECTION

Note 1: See Power-Down Currents (IPD) in Section 30.3 "DC Characteristics: PIC16(L)F1825/9-I/E (Power-Down)" for more information.



#### 32.11 Demonstration/Development Boards, Evaluation Kits, and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM<sup>™</sup> and dsPICDEM<sup>™</sup> demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ<sup>®</sup> security ICs, CAN, IrDA<sup>®</sup>, PowerSmart battery management, SEEVAL<sup>®</sup> evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page (www.microchip.com) for the complete list of demonstration, development and evaluation kits.

### 32.12 Third-Party Development Tools

Microchip also offers a great collection of tools from third-party vendors. These tools are carefully selected to offer good value and unique functionality.

- Device Programmers and Gang Programmers from companies, such as SoftLog and CCS
- Software Tools from companies, such as Gimpel and Trace Systems
- Protocol Analyzers from companies, such as Saleae and Total Phase
- Demonstration Boards from companies, such as MikroElektronika, Digilent<sup>®</sup> and Olimex
- Embedded Ethernet Solutions from companies, such as EZ Web Lynx, WIZnet and IPLogika<sup>®</sup>

# 33.1 Package Marking Information (Continued)



#### 14-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



### RECOMMENDED LAND PATTERN

	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	E		0.65 BSC	
Contact Pad Spacing	C1		5.90	
Contact Pad Width (X14)	X1			0.45
Contact Pad Length (X14)	Y1			1.45
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2087A

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To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO.	[X]     -     X     /XX                                 Tape and Reel     Temperature     Package       Option     Range	XXX Pattern	<ul> <li>Examples:</li> <li>a) PIC16F1825 - E/SL 301 = Extended temp., SOIC package, QTP pattern #301.</li> <li>b) PIC16LF1829 - E/SS = Extended temp., SSOP package.</li> </ul>
Device:	PIC16F1825, PIC16LF1825 PIC16F1829T, PIC16LF1829		<ul> <li>c) PIC16LF1829 - E/ML= Extended temp., QFN package.</li> </ul>
Tape and Reel Option:	Blank = Standard packaging (tube or tray) T = Tape and Reel <sup>(1)</sup>		
Temperature Range:	I = $-40^{\circ}$ C to $+85^{\circ}$ C (Industrial) E = $-40^{\circ}$ C to $+125^{\circ}$ C (Extended)		
Package: <sup>(2)</sup>	GZ = UQFN, 20-lead (4x4x0.5mm) JQ = UQFN, 16-lead (4x4x0.5mm) ML = QFN, 16-lead, 20-lead (4x4x0.9mm) P = Plastic DIP SL = SOIC, 14-lead SO = SOIC, 20-lead SS = SSOP, 20-lead ST = TSSOP, 14-lead		<ul> <li>Note 1: Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.</li> <li>2: For other small form-factor package availability and marking information, please visit www.microchip.com/packaging or</li> </ul>
Pattern:	QTP, SQTP, Code or Special Requirements (blank otherwise)		contact your local sales office.

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