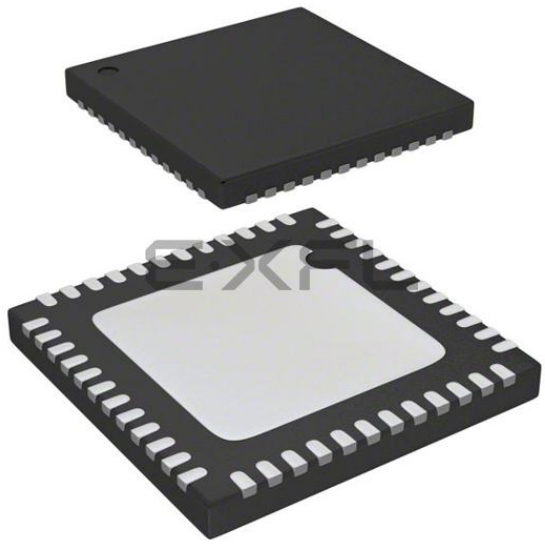
Silicon Labs - EFM32PG12B500F1024GM48-B Datasheet



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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	I²C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	33
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D - 12b SAR
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-VFQFN Exposed Pad
Supplier Device Package	48-QFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32pg12b500f1024gm48-b

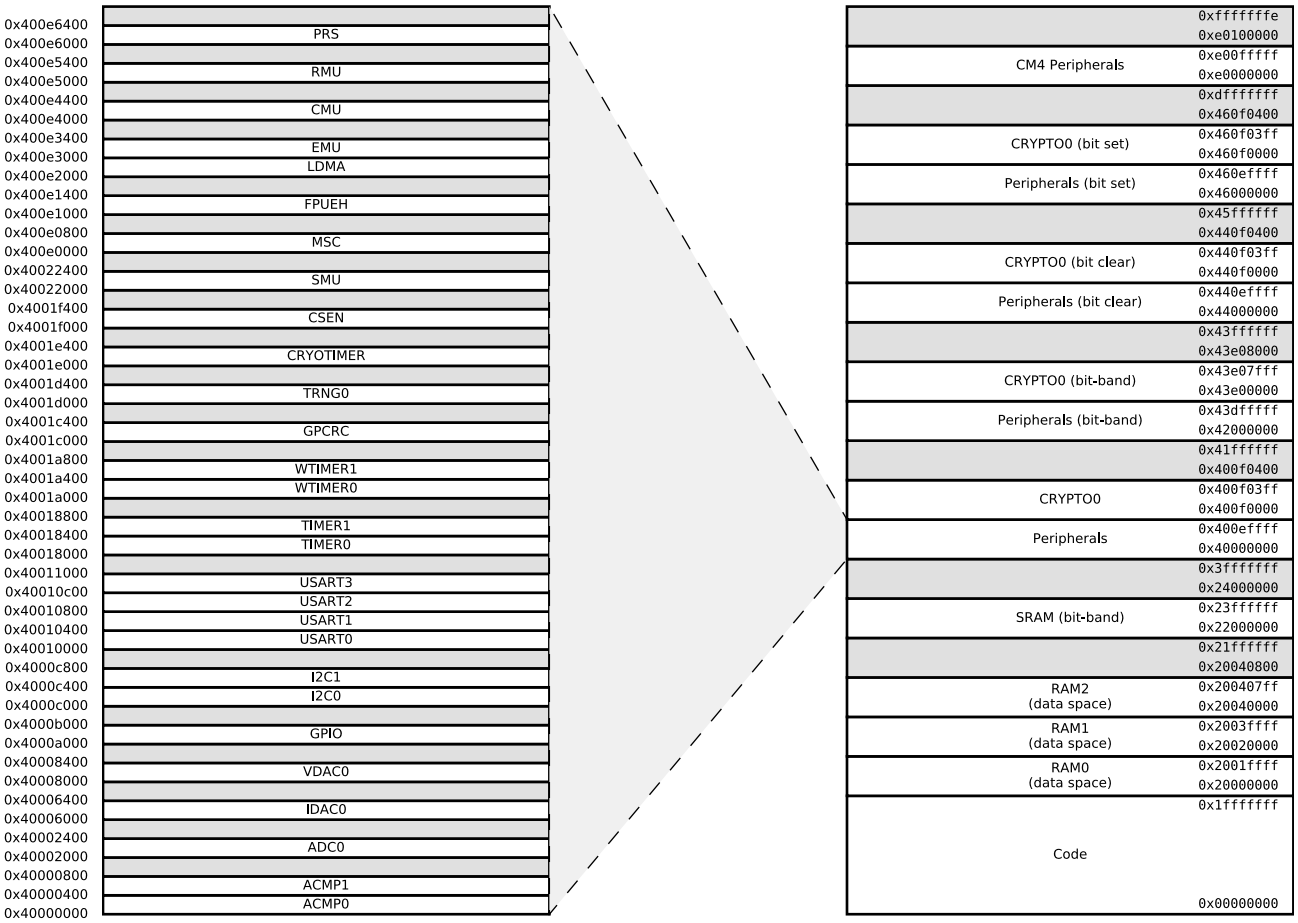

Figure 3.3. EFM32PG12 Memory Map — Peripherals

3.12 Configuration Summary

The features of the EFM32PG12 are a subset of the feature set described in the device reference manual. The table below describes device specific implementation of the features. Remaining modules support full configuration.

Table 3.2. Configuration Summary

Module	Configuration	Pin Connections
USART0	IrDA SmartCard	US0_TX, US0_RX, US0_CLK, US0_CS
USART1	IrDA I^2S SmartCard	US1_TX, US1_RX, US1_CLK, US1_CS
USART2	IrDA SmartCard	US2_TX, US2_RX, US2_CLK, US2_CS
USART3	IrDA I^2S SmartCard	US3_TX, US3_RX, US3_CLK, US3_CS
TIMER0	with DTI	TIM0_CC[2:0], TIM0_CDTI[2:0]
TIMER1	-	TIM1_CC[3:0]
WTIMER0	with DTI	WTIM0_CC[2:0], WTIM0_CDTI[2:0]
WTIMER1	-	WTIM1_CC[3:0]

4.1.5.3 Current Consumption 1.8 V without DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = DVDD = 1.8 V. T_{OP} = 25 °C. DCDC is off. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T_{OP} = 25 °C.

Table 4.7. Current Consumption 1.8 V without DC-DC Converter

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 mode with all peripherals disabled	I_{ACTIVE}	38.4 MHz crystal, CPU running while loop from flash[1]	—	126	—	µA/MHz
		38 MHz HFRCO, CPU running Prime from flash	—	99	—	µA/MHz
		38 MHz HFRCO, CPU running while loop from flash	—	99	—	µA/MHz
		38 MHz HFRCO, CPU running CoreMark from flash	—	124	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	102	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	277	—	µA/MHz
Current consumption in EM0 mode with all peripherals disabled and voltage scaling enabled	I_{ACTIVE_VS}	19 MHz HFRCO, CPU running while loop from flash	—	87	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	231	—	µA/MHz
Current consumption in EM1 mode with all peripherals disabled	I_{EM1}	38.4 MHz crystal[1]	—	76	—	µA/MHz
		38 MHz HFRCO	—	50	—	µA/MHz
		26 MHz HFRCO	—	52	—	µA/MHz
		1 MHz HFRCO	—	227	—	µA/MHz
Current consumption in EM1 mode with all peripherals disabled and voltage scaling enabled	I_{EM1_VS}	19 MHz HFRCO	—	47	—	µA/MHz
		1 MHz HFRCO	—	190	—	µA/MHz
Current consumption in EM2 mode, with votage scaling enabled.	I_{EM2_VS}	Full 256 kB RAM retention and RTCC running from LFXO	—	2.8	—	µA
		Full 256 kB RAM retention and RTCC running from LFRCO	—	3.0	—	µA
		16 kB (1 bank) RAM retention and RTCC running from LFRCO[2]	—	1.9	—	µA
Current consumption in EM3 mode, with voltage scaling enabled.	I_{EM3_VS}	Full 256 kB RAM retention and CRYOTIMER running from ULFRCO	—	2.47	—	µA
Current consumption in EM4H mode, with voltage scaling enabled.	I_{EM4H_VS}	128 byte RAM retention, RTCC running from LFXO	—	0.91	—	µA
		128 byte RAM retention, CRYOTIMER running from ULFRCO	—	0.35	—	µA
		128 byte RAM retention, no RTCC	—	0.35	—	µA
Current consumption in EM4S mode	I_{EM4S}	no RAM retention, no RTCC	—	0.04	—	µA

4.1.11 Voltage Monitor (VMON)

Table 4.18. Voltage Monitor (VMON)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Supply current (including I_SENSE)	I_{VMON}	In EM0 or EM1, 1 supply monitored	—	6.3	TBD	µA
		In EM0 or EM1, 4 supplies monitored	—	12.5	TBD	µA
		In EM2, EM3 or EM4, 1 supply monitored and above threshol	—	62	—	nA
		In EM2, EM3 or EM4, 1 supply monitored and below threshold	—	62	—	nA
		In EM2, EM3 or EM4, 4 supplies monitored and all above threshold	—	99	—	nA
		In EM2, EM3 or EM4, 4 supplies monitored and all below threshold	—	99	—	nA
Loading of monitored supply	I_{SENSE}	In EM0 or EM1	—	2	—	µA
		In EM2, EM3 or EM4	—	2	—	nA
Threshold range	V_{VMON_RANGE}		1.62	—	3.4	V
Threshold step size	N_{VMON_STESP}	Coarse	—	200	—	mV
		Fine	—	20	—	mV
Response time	t_{VMON_RES}	Supply drops at 1V/µs rate	—	460	—	ns
Hysteresis	V_{VMON_HYST}		—	26	—	mV

4.1.13 Analog Comparator (ACMP)

Table 4.20. Analog Comparator (ACMP)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input voltage range	V_{ACMPIN}	ACMPVDD = ACMPn_CTRL_PWRSEL [1]	—	—	$V_{ACMPVDD}$	V
Supply voltage	$V_{ACMPVDD}$	BIASPROG[4] ≤ 0x10 or FULLBIAS[4] = 0	1.8	—	$V_{VREGVDD\_MAX}$	V
		0x10 < BIASPROG[4] ≤ 0x20 and FULLBIAS[4] = 1	2.1	—	$V_{VREGVDD\_MAX}$	V
Active current not including voltage reference[2]	I_{ACMP}	BIASPROG[4] = 1, FULLBIAS[4] = 0	—	50	—	nA
		BIASPROG[4] = 0x10, FULLBIAS[4] = 0	—	306	—	nA
		BIASPROG[4] = 0x02, FULLBIAS[4] = 1	—	6.5	—	µA
		BIASPROG[4] = 0x20, FULLBIAS[4] = 1	—	74	TBD	µA
Current consumption of internal voltage reference[2]	$I_{ACMPREF}$	VLP selected as input using 2.5 V Reference / 4 (0.625 V)	—	50	—	nA
		VLP selected as input using VDD	—	20	—	nA
		VBDIV selected as input using 1.25 V reference / 1	—	4.1	—	µA
		VADIV selected as input using VDD/1	—	2.4	—	µA

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit

Note:

1. ACMPVDD is a supply chosen by the setting in ACMPn_CTRL_PWRSEL and may be IOVDD, AVDD or DVDD.
2. The total ACMP current is the sum of the contributions from the ACMP and its internal voltage reference. $I_{ACMPTOTAL} = I_{ACMP} + I_{ACMPREF}$.
3. ± 100 mV differential drive.
4. In ACMPn_CTRL register.
5. In ACMPn_HYSTERESIS register.
6. In ACMPn_INPUTSEL register.

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Settling time, (output settled within 1% of steady state value),	t_{IDAC_SETTLE}	Range setting is changed	—	5	—	µs
		Step value is changed	—	1	—	µs
Current consumption[2]	I_{IDAC}	EM0 or EM1 Source mode, excluding output current	—	8.9	TBD	µA
		EM0 or EM1 Sink mode, excluding output current	—	12	TBD	µA
		EM2 or EM3 Source mode, excluding output current, T = 25 °C	—	1.04	—	µA
		EM2 or EM3 Sink mode, excluding output current, T = 25 °C	—	1.08	—	µA
		EM2 or EM3 Source mode, excluding output current, T ≥ 85 °C	—	8.9	—	µA
		EM2 or EM3 Sink mode, excluding output current, T ≥ 85 °C	—	12	—	µA
Output voltage compliance in source mode, source current change relative to current sourced at 0 V	I_{COMP_SRC}	RANGESEL1=0, output voltage = min(V_{IOVDD}, V_{AVDD}[2]-100 mv)	—	0.11	—	%
		RANGESEL1=1, output voltage = min(V_{IOVDD}, V_{AVDD}[2]-100 mV)	—	0.06	—	%
		RANGESEL1=2, output voltage = min(V_{IOVDD}, V_{AVDD}[2]-150 mV)	—	0.04	—	%
		RANGESEL1=3, output voltage = min(V_{IOVDD}, V_{AVDD}[2]-250 mV)	—	0.03	—	%
Output voltage compliance in sink mode, sink current change relative to current sunk at IOVDD	I_{COMP_SINK}	RANGESEL1=0, output voltage = 100 mV	—	0.12	—	%
		RANGESEL1=1, output voltage = 100 mV	—	0.05	—	%
		RANGESEL1=2, output voltage = 150 mV	—	0.04	—	%
		RANGESEL1=3, output voltage = 250 mV	—	0.03	—	%

Note:

1. In IDAC_CURPROG register.
2. The IDAC is supplied by either AVDD, DVDD, or IOVDD based on the setting of ANASW in the EMU_PWRCTRL register and PWRSEL in the IDAC_CTRL register. Setting PWRSEL to 1 selects IOVDD. With PWRSEL cleared to 0, ANASW selects between AVDD (0) and DVDD (1).

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Slew rate[5]	SR	DRIVESTRENGTH = 3, INCBW=1[3]	—	4.7	—	V/µs
		DRIVESTRENGTH = 3, INCBW=0	—	1.5	—	V/µs
		DRIVESTRENGTH = 2, INCBW=1[3]	—	1.27	—	V/µs
		DRIVESTRENGTH = 2, INCBW=0	—	0.42	—	V/µs
		DRIVESTRENGTH = 1, INCBW=1[3]	—	0.17	—	V/µs
		DRIVESTRENGTH = 1, INCBW=0	—	0.058	—	V/µs
		DRIVESTRENGTH = 0, INCBW=1[3]	—	0.044	—	V/µs
		DRIVESTRENGTH = 0, INCBW=0	—	0.015	—	V/µs
Startup time[6]	T_{START}	DRIVESTRENGTH = 3	—	—	TBD	µs
		DRIVESTRENGTH = 2	—	—	TBD	µs
		DRIVESTRENGTH = 1	—	—	TBD	µs
		DRIVESTRENGTH = 0	—	—	TBD	µs
Input offset voltage	V_{OSI}	DRIVESTRENGTH = 2 or 3, T_J = 25 °C	TBD	—	TBD	mV
		DRIVESTRENGTH = 1 or 0, T_J = 25 °C	TBD	—	TBD	mV
		DRIVESTRENGTH = 2 or 3, across operating temperature range	TBD	—	TBD	mV
		DRIVESTRENGTH = 1 or 0, across operating temperature range	TBD	—	TBD	mV
DC power supply rejection ratio[9]	$PSRR_{DC}$	Input referred	—	70	—	dB
DC common-mode rejection ratio[9]	$CMRR_{DC}$	Input referred	—	70	—	dB
Total harmonic distortion	THD_{OPA}	DRIVESTRENGTH = 2, 3x Gain connection, 1 kHz, V_{OUT} = 0.1 V to V_{OPA} - 0.1 V	—	90	—	dB
		DRIVESTRENGTH = 0, 3x Gain connection, 0.1 kHz, V_{OUT} = 0.1 V to V_{OPA} - 0.1 V	—	90	—	dB

4.2.1 Supply Current

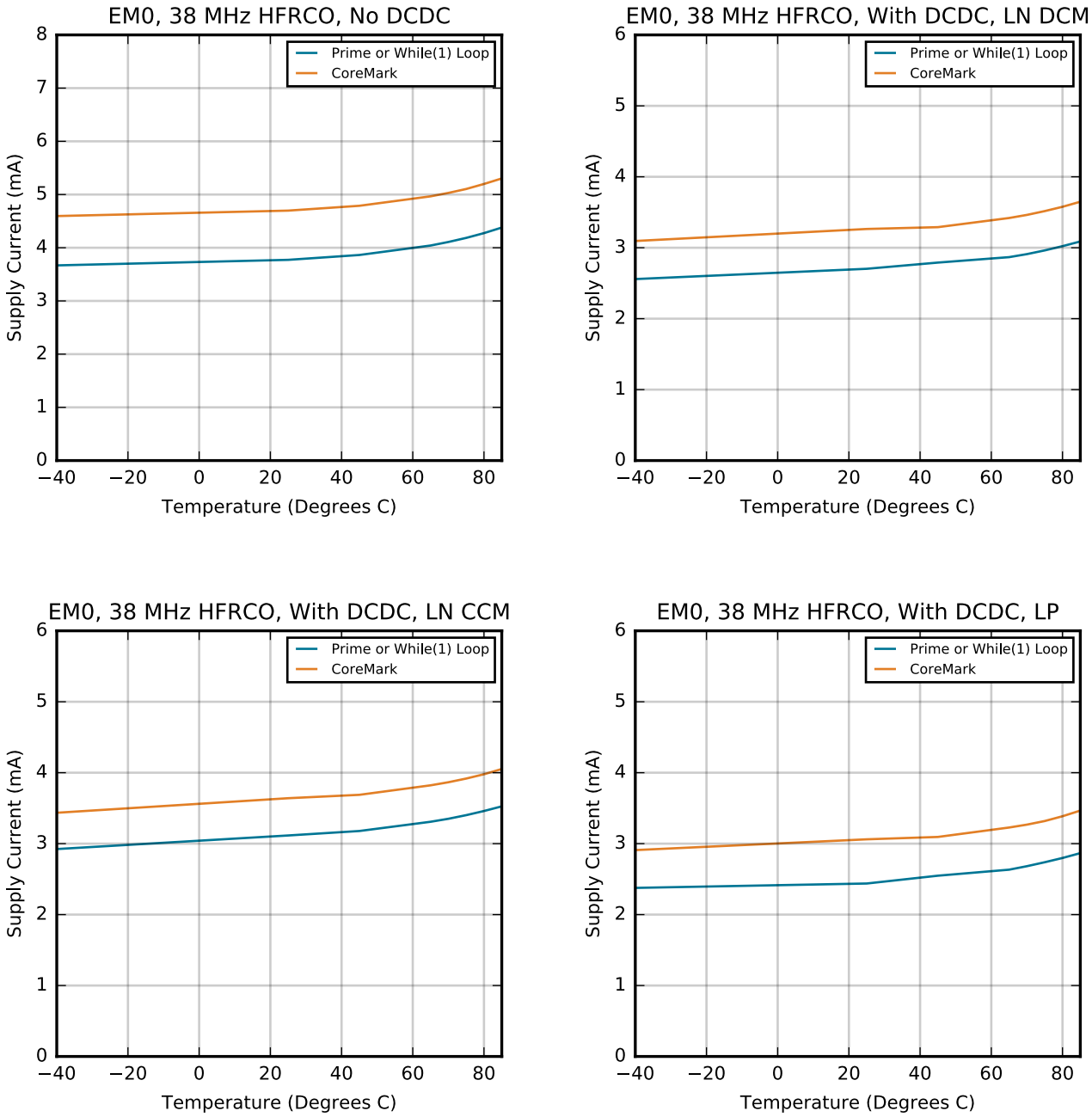

Figure 4.3. EM0 Active Mode Typical Supply Current vs. Temperature

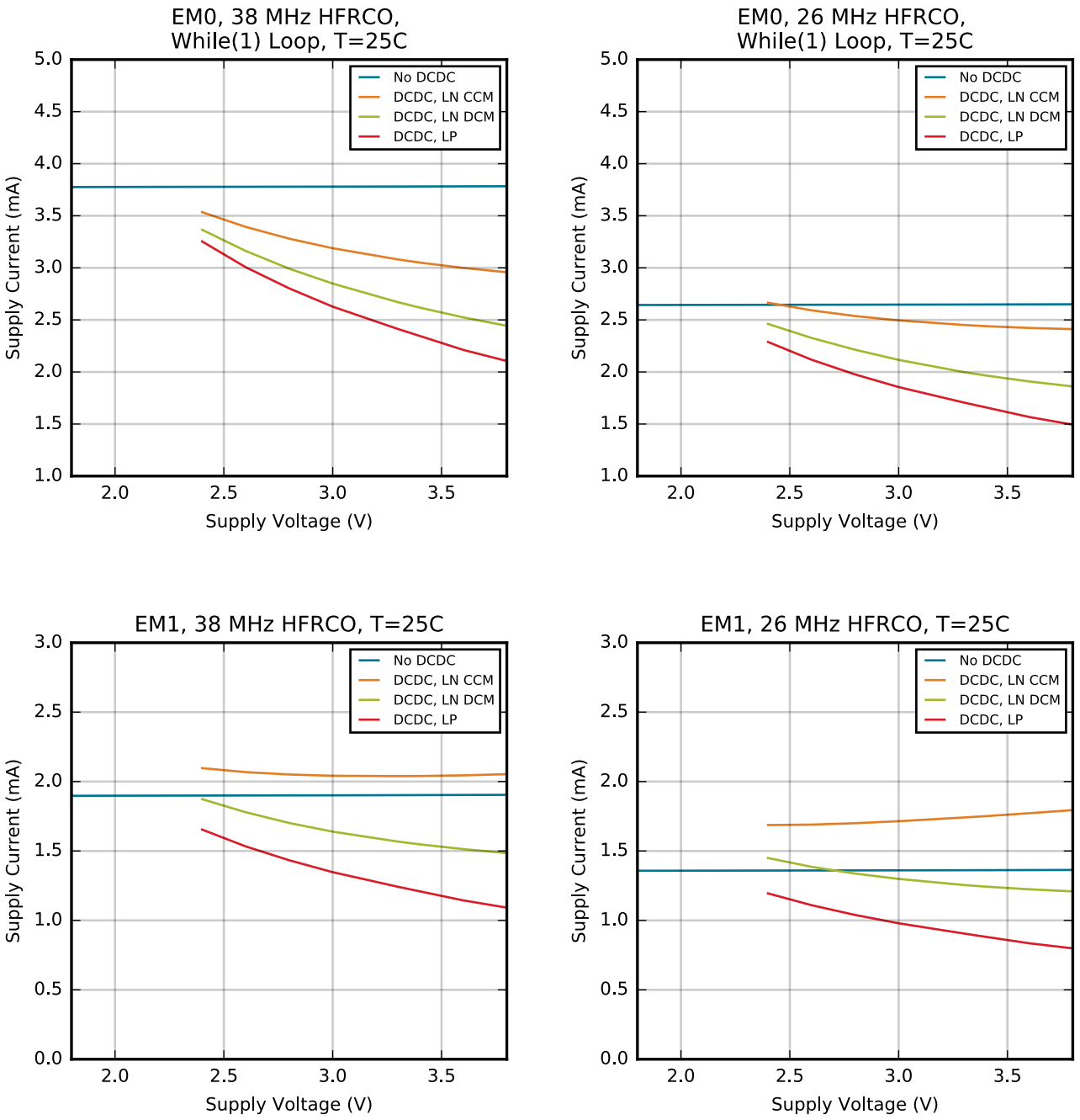

Figure 4.6. EM0 and EM1 Mode Typical Supply Current vs. Supply

Typical supply current for EM2, EM3 and EM4H using standard software libraries from Silicon Laboratories.

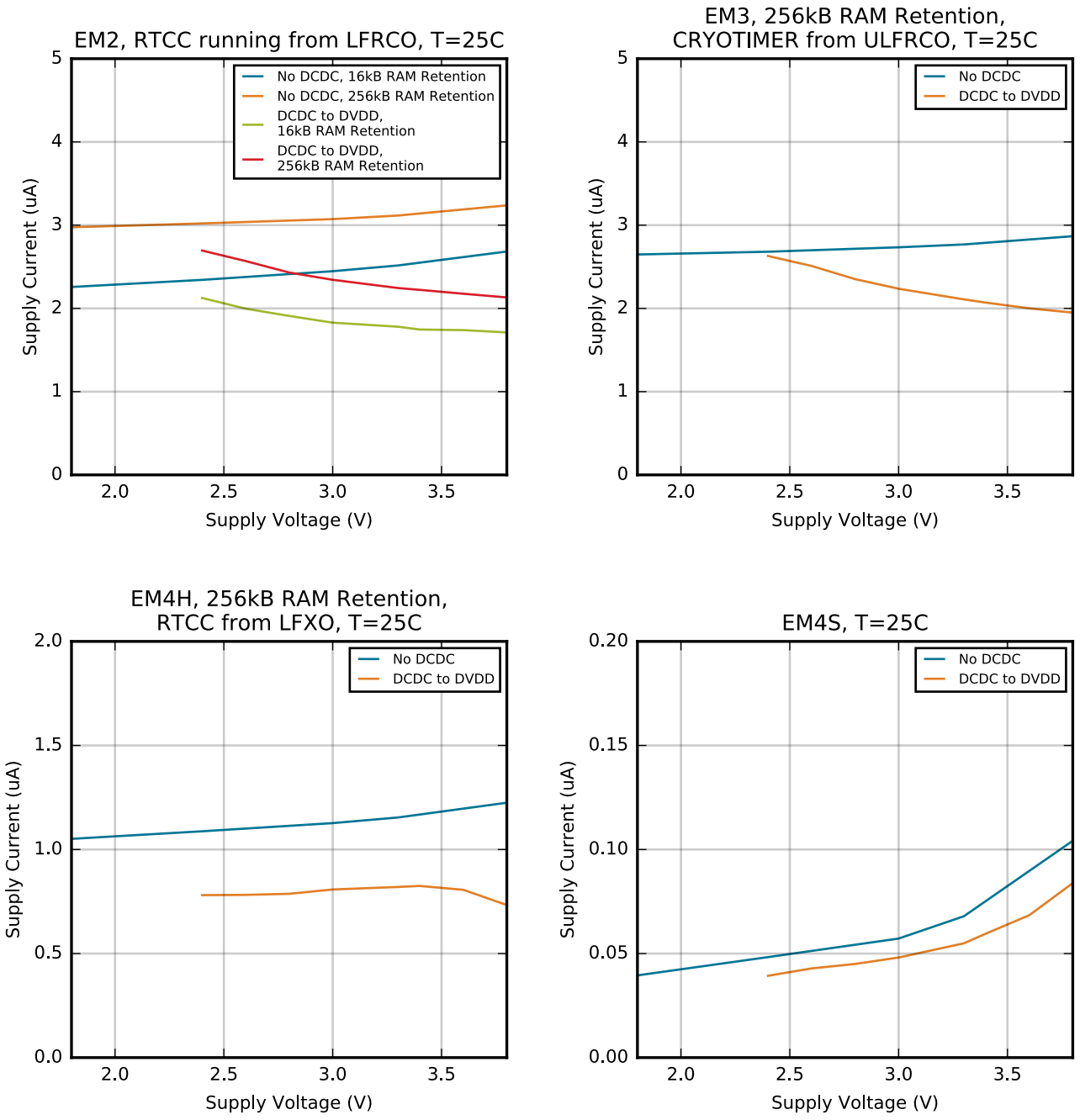

Figure 4.7. EM2, EM3, EM4H and EM4S Typical Supply Current vs. Supply

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
A7	PC9	BUSAY BUSBX	TIM0_CC0 #14 TIM0_CC1 #13 TIM0_CC2 #12 TIM0_CDTI0 #11 TIM0_CDTI1 #10 TIM0_CDTI2 #9 TIM1_CC0 #14 TIM1_CC1 #13 TIM1_CC2 #12 TIM1_CC3 #11 WTIM0_CC0 #29 WTIM0_CC1 #27 WTIM0_CC2 #25 WTIM0_CDTI0 #21 WTIM0_CDTI1 #19 WTIM0_CDTI2 #17 WTIM1_CC0 #13 WTIM1_CC1 #11 WTIM1_CC2 #9 WTIM1_CC3 #7 LE-TIM0_OUT0 #14 LE-TIM0_OUT1 #13 PCNT0_S0IN #14 PCNT0_S1IN #13	US0_TX #14 US0_RX #13 US0_CLK #12 US0_CS #11 US0_CTS #10 US0_RTS #9 US1_TX #14 US1_RX #13 US1_CLK #12 US1_CS #11 US1_CTS #10 US1_RTS #9 LEU0_TX #14 LEU0_RX #13 I2C0_SDA #14 I2C0_SCL #13	PRS_CH0 #11 PRS_CH9 #14 PRS_CH10 #3 PRS_CH11 #2 ACMP0_O #14 ACMP1_O #14 ETM_TD2 #3
A8	PC7	BUSAY BUSBX	TIM0_CC0 #12 TIM0_CC1 #11 TIM0_CC2 #10 TIM0_CDTI0 #9 TIM0_CDTI1 #8 TIM0_CDTI2 #7 TIM1_CC0 #12 TIM1_CC1 #11 TIM1_CC2 #10 TIM1_CC3 #9 WTIM0_CC0 #27 WTIM0_CC1 #25 WTIM0_CC2 #23 WTIM0_CDTI0 #19 WTIM0_CDTI1 #17 WTIM0_CDTI2 #15 WTIM1_CC0 #11 WTIM1_CC1 #9 WTIM1_CC2 #7 WTIM1_CC3 #5 LE-TIM0_OUT0 #12 LE-TIM0_OUT1 #11 PCNT0_S0IN #12 PCNT0_S1IN #11	US0_TX #12 US0_RX #11 US0_CLK #10 US0_CS #9 US0_CTS #8 US0_RTS #7 US1_TX #12 US1_RX #11 US1_CLK #10 US1_CS #9 US1_CTS #8 US1_RTS #7 LEU0_TX #12 LEU0_RX #11 I2C0_SDA #12 I2C0_SCL #11	CMU_CLK1 #2 PRS_CH0 #9 PRS_CH9 #12 PRS_CH10 #1 PRS_CH11 #0 ACMP0_O #12 ACMP1_O #12 ETM_TD0 #3
A9	DECOUPLE	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.			
A10	DVDD	Digital power supply .			
A11	VREGVDD	Voltage regulator VDD input			
A12	VREGSW	DCDC regulator switching node			
A13	VREGVSS	Voltage regulator VSS			

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
D13	PB9	OPA2_OUTALT #0 BUSCY BUSDX	WTIM0_CC0 #13 WTIM0_CC1 #11 WTIM0_CC2 #9 WTIM0_CDTI0 #5 WTIM0_CDTI1 #3 WTIM0_CDTI2 #1 PCNT1_S0IN #9 PCNT1_S1IN #8 PCNT2_S0IN #9 PCNT2_S1IN #8	US2_TX #12 US2_RX #11 US2_CLK #10 US2_CS #9 US2_CTS #8 US2_RTS #7 US3_TX #13 US3_RX #12 US3_CLK #11 US3_CS #10 US3_CTS #9 US3_RTS #8 I2C1_SDA #9 I2C1_SCL #8	
E1	PK1		PCNT1_S0IN #30 PCNT1_S1IN #29 PCNT2_S0IN #30 PCNT2_S1IN #29	US2_TX #30 US2_RX #29 US2_CLK #28 US2_CS #27 US2_CTS #26 US2_RTS #25 US3_TX #30 US3_RX #29 US3_CLK #28 US3_CS #27 US3_CTS #26 US3_RTS #25 I2C1_SDA #30 I2C1_SCL #29	
E2	PK0	IDAC0_OUT	PCNT1_S0IN #29 PCNT1_S1IN #28 PCNT2_S0IN #29 PCNT2_S1IN #28	US2_TX #29 US2_RX #28 US2_CLK #27 US2_CS #26 US2_CTS #25 US2_RTS #24 US3_TX #29 US3_RX #28 US3_CLK #27 US3_CS #26 US3_CTS #25 US3_RTS #24 I2C1_SDA #29 I2C1_SCL #28	
E3	PF15	BUSAY BUSBX	PCNT1_S0IN #28 PCNT1_S1IN #27 PCNT2_S0IN #28 PCNT2_S1IN #27	US2_TX #28 US2_RX #27 US2_CLK #26 US2_CS #25 US2_CTS #24 US2_RTS #23 US3_TX #28 US3_RX #27 US3_CLK #26 US3_CS #25 US3_CTS #24 US3_RTS #23 I2C1_SDA #28 I2C1_SCL #27	
E5	VSS	Ground			
E6	VSS	Ground			
E7	VSS	Ground			
E8	VSS	Ground			
E9	VSS	Ground			
E12	PB8	BUSDY BUSCX	WTIM0_CC0 #12 WTIM0_CC1 #10 WTIM0_CC2 #8 WTIM0_CDTI0 #4 WTIM0_CDTI1 #2 WTIM0_CDTI2 #0 PCNT1_S0IN #8 PCNT1_S1IN #7 PCNT2_S0IN #8 PCNT2_S1IN #7	US2_TX #11 US2_RX #10 US2_CLK #9 US2_CS #8 US2_CTS #7 US2_RTS #6 US3_TX #12 US3_RX #11 US3_CLK #10 US3_CS #9 US3_CTS #8 US3_RTS #7 I2C1_SDA #8 I2C1_SCL #7	ETM_TD3 #2

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
N9	PD8	BUSDY BUSCX	WTIM0_CC1 #30 WTIM0_CC2 #28 WTIM0_CDTI0 #24 WTIM0_CDTI1 #22 WTIM0_CDTI2 #20 WTIM1_CC0 #16 WTIM1_CC1 #14 WTIM1_CC2 #12 WTIM1_CC3 #10	US3_TX #0 US3_RX #31 US3_CLK #30 US3_CS #29 US3_CTS #28 US3_RTS #27	LES_CH0
N10	PD10	BUSDY BUSCX	TIM0_CC0 #18 TIM0_CC1 #17 TIM0_CC2 #16 TIM0_CDTI0 #15 TIM0_CDTI1 #14 TIM0_CDTI2 #13 TIM1_CC0 #18 TIM1_CC1 #17 TIM1_CC2 #16 TIM1_CC3 #15 WTIM0_CC2 #30 WTIM0_CDTI0 #26 WTIM0_CDTI1 #24 WTIM0_CDTI2 #22 WTIM1_CC0 #18 WTIM1_CC1 #16 WTIM1_CC2 #14 WTIM1_CC3 #12 LE-TIM0_OUT0 #18 LE-TIM0_OUT1 #17 PCNT0_S0IN #18 PCNT0_S1IN #17	US0_TX #18 US0_RX #17 US0_CLK #16 US0_CS #15 US0_CTS #14 US0_RTS #13 US1_TX #18 US1_RX #17 US1_CLK #16 US1_CS #15 US1_CTS #14 US1_RTS #13 US3_TX #2 US3_RX #1 US3_CLK #0 US3_CS #31 US3_CTS #30 US3_RTS #29 LEU0_TX #18 LEU0_RX #17 I2C0_SDA #18 I2C0_SCL #17	CMU_CLK1 #4 PRS_CH3 #9 PRS_CH4 #1 PRS_CH5 #0 PRS_CH6 #12 ACMP0_O #18 ACMP1_O #18 LES_CH2
N11	PD12	VDAC0_OUT1ALT / OPA1_OUTALT #0 BUSDY BUSCX	TIM0_CC0 #20 TIM0_CC1 #19 TIM0_CC2 #18 TIM0_CDTI0 #17 TIM0_CDTI1 #16 TIM0_CDTI2 #15 TIM1_CC0 #20 TIM1_CC1 #19 TIM1_CC2 #18 TIM1_CC3 #17 WTIM0_CDTI0 #28 WTIM0_CDTI1 #26 WTIM0_CDTI2 #24 WTIM1_CC0 #20 WTIM1_CC1 #18 WTIM1_CC2 #16 WTIM1_CC3 #14 LE-TIM0_OUT0 #20 LE-TIM0_OUT1 #19 PCNT0_S0IN #20 PCNT0_S1IN #19	US0_TX #20 US0_RX #19 US0_CLK #18 US0_CS #17 US0_CTS #16 US0_RTS #15 US1_TX #20 US1_RX #19 US1_CLK #18 US1_CS #17 US1_CTS #16 US1_RTS #15 US3_TX #4 US3_RX #3 US3_CLK #2 US3_CS #1 US3_CTS #0 US3_RTS #31 LEU0_TX #20 LEU0_RX #19 I2C0_SDA #20 I2C0_SCL #19	PRS_CH3 #11 PRS_CH4 #3 PRS_CH5 #2 PRS_CH6 #14 ACMP0_O #20 ACMP1_O #20 LES_CH4

6.2.1 EFM32PG12B5xx in QFN48 GPIO Overview

The GPIO pins are organized as 16-bit ports indicated by letters (A, B, C...), with individual pins on each port indicated by a number from 15 down to 0.

Table 6.4. EFM32PG12B5xx in QFN48 GPIO Pinout

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	-	-	-	-	-	-	-	-	-	-	PA5 (5V)	PA4	PA3	PA2	PA1	PA0
Port B	PB15	PB14	PB13	PB12	PB11	-	-	-	-	-	-	-	-	-	-	-
Port C	-	-	-	-	PC11 (5V)	PC10 (5V)	PC9 (5V)	PC8 (5V)	PC7 (5V)	PC6 (5V)	-	-	-	-	-	-
Port D	PD15	PD14	PD13	PD12 (5V)	PD11 (5V)	PD10 (5V)	PD9 (5V)	PD8 (5V)	-	-	-	-	-	-	-	-
Port F	-	-	-	-	-	-	-	-	PF7 (5V)	PF6 (5V)	PF5 (5V)	PF4 (5V)	PF3 (5V)	PF2 (5V)	PF1 (5V)	PF0 (5V)

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The PD8 GPIO pin is not available (no-connect) on other device families, and should not be used if direct pin compatibility across multiple families is required.

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
ETM_TD2	0: PF11 1: PA8 2: PB7 3: PC9								Embedded Trace Module ETM data 2.
ETM_TD3	0: PF12 1: PA9 2: PB8 3: PC10								Embedded Trace Module ETM data 3.
GPIO_EM4WU0	0: PF2								Pin can be used to wake the system up from EM4
GPIO_EM4WU1	0: PF7								Pin can be used to wake the system up from EM4
GPIO_EM4WU4	0: PD14								Pin can be used to wake the system up from EM4
GPIO_EM4WU8	0: PA3								Pin can be used to wake the system up from EM4
GPIO_EM4WU9	0: PB13								Pin can be used to wake the system up from EM4
GPIO_EM4WU12	0: PC10								Pin can be used to wake the system up from EM4
I2C0_SCL	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	I2C0 Serial Clock Line input / output.
I2C0_SDA	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	I2C0 Serial Data input / output.
I2C1_SCL	0: PA7 1: PA8 2: PA9 3: PI2	4: PI3 5: PB6 6: PB7 7: PB8	8: PB9 9: PB10 10: PJ14 11: PJ15	12: PC0 13: PC1 14: PC2 15: PC3	16: PC4 17: PC5 18: PC10 19: PC11	20: PF8 21: PF9 22: PF10 23: PF11	24: PF12 25: PF13 26: PF14 27: PF15	28: PK0 29: PK1 30: PK2 31: PA6	I2C1 Serial Clock Line input / output.
I2C1_SDA	0: PA6 1: PA7 2: PA8 3: PA9	4: PI2 5: PI3 6: PB6 7: PB7	8: PB8 9: PB9 10: PB10 11: PJ14	12: PJ15 13: PC0 14: PC1 15: PC2	16: PC3 17: PC4 18: PC5 19: PC10	20: PC11 21: PF8 22: PF9 23: PF10	24: PF11 25: PF12 26: PF13 27: PF14	28: PF15 29: PK0 30: PK1 31: PK2	I2C1 Serial Data input / output.
IDAC0_OUT	0: PK0								IDAC0 output.

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
US1_RTS	0: PA5 1: PB11 2: PB12 3: PB13	4: PB14 5: PB15 6: PC6 7: PC7	8: PC8 9: PC9 10: PC10 11: PC11	12: PD9 13: PD10 14: PD11 15: PD12	16: PD13 17: PD14 18: PD15 19: PF0	20: PF1 21: PF2 22: PF3 23: PF4	24: PF5 25: PF6 26: PF7 27: PA0	28: PA1 29: PA2 30: PA3 31: PA4	USART1 Request To Send hardware flow control output.
US1_RX	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	USART1 Asynchronous Receive. USART1 Synchronous mode Master Input / Slave Output (MISO).
US1_TX	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	USART1 Asynchronous Transmit. Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).
US2_CLK	0: PA7 1: PA8 2: PA9 3: PI0	4: PI1 5: PI2 6: PI3 7: PB6	8: PB7 9: PB8 10: PB9 11: PB10	12: PF0 13: PF1 14: PF3 15: PF4	16: PF5 17: PF6 18: PF7 19: PF8	20: PF9 21: PF10 22: PF11 23: PF12	24: PF13 25: PF14 26: PF15 27: PK0	28: PK1 29: PK2 30: PA5 31: PA6	USART2 clock input / output.
US2_CS	0: PA8 1: PA9 2: PI0 3: PI1	4: PI2 5: PI3 6: PB6 7: PB7	8: PB8 9: PB9 10: PB10 11: PF0	12: PF1 13: PF3 14: PF4 15: PF5	16: PF6 17: PF7 18: PF8 19: PF9	20: PF10 21: PF11 22: PF12 23: PF13	24: PF14 25: PF15 26: PK0 27: PK1	28: PK2 29: PA5 30: PA6 31: PA7	USART2 chip select input / output.
US2_CTS	0: PA9 1: PI0 2: PI1 3: PI2	4: PI3 5: PB6 6: PB7 7: PB8	8: PB9 9: PB10 10: PF0 11: PF1	12: PF3 13: PF4 14: PF5 15: PF6	16: PF7 17: PF8 18: PF9 19: PF10	20: PF11 21: PF12 22: PF13 23: PF14	24: PF15 25: PK0 26: PK1 27: PK2	28: PA5 29: PA6 30: PA7 31: PA8	USART2 Clear To Send hardware flow control input.
US2_RTS	0: PI0 1: PI1 2: PI2 3: PI3	4: PB6 5: PB7 6: PB8 7: PB9	8: PB10 9: PF0 10: PF1 11: PF3	12: PF4 13: PF5 14: PF6 15: PF7	16: PF8 17: PF9 18: PF10 19: PF11	20: PF12 21: PF13 22: PF14 23: PF15	24: PK0 25: PK1 26: PK2 27: PA5	28: PA6 29: PA7 30: PA8 31: PA9	USART2 Request To Send hardware flow control output.
US2_RX	0: PA6 1: PA7 2: PA8 3: PA9	4: PI0 5: PI1 6: PI2 7: PI3	8: PB6 9: PB7 10: PB8 11: PB9	12: PB10 13: PF0 14: PF1 15: PF3	16: PF4 17: PF5 18: PF6 19: PF7	20: PF8 21: PF9 22: PF10 23: PF11	24: PF12 25: PF13 26: PF14 27: PF15	28: PK0 29: PK1 30: PK2 31: PA5	USART2 Asynchronous Receive. USART2 Synchronous mode Master Input / Slave Output (MISO).
US2_TX	0: PA5 1: PA6 2: PA7 3: PA8	4: PA9 5: PI0 6: PI1 7: PI2	8: PI3 9: PB6 10: PB7 11: PB8	12: PB9 13: PB10 14: PF0 15: PF1	16: PF3 17: PF4 18: PF5 19: PF6	20: PF7 21: PF8 22: PF9 23: PF10	24: PF11 25: PF12 26: PF13 27: PF14	28: PF15 29: PK0 30: PK1 31: PK2	USART2 Asynchronous Transmit. Also used as receive input in half duplex communication. USART2 Synchronous mode Master Output / Slave Input (MOSI).

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
WTIM0_CC0	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PA6 7: PA7	8: PA8 9: PA9 10: PB6 11: PB7	12: PB8 13: PB9 14: PB10 15: PB11	16: PB12 17: PB13 18: PB14 19: PB15	20: PC0 21: PC1 22: PC2 23: PC3	24: PC4 25: PC5 26: PC6 27: PC7	28: PC8 29: PC9 30: PC10 31: PC11	Wide timer 0 Capture Compare input / output channel 0.
WTIM0_CC1	0: PA2 1: PA3 2: PA4 3: PA5	4: PA6 5: PA7 6: PA8 7: PA9	8: PB6 9: PB7 10: PB8 11: PB9	12: PB10 13: PB11 14: PB12 15: PB13	16: PB14 17: PB15 18: PC0 19: PC1	20: PC2 21: PC3 22: PC4 23: PC5	24: PC6 25: PC7 26: PC8 27: PC9	28: PC10 29: PC11 30: PD8 31: PD9	Wide timer 0 Capture Compare input / output channel 1.
WTIM0_CC2	0: PA4 1: PA5 2: PA6 3: PA7	4: PA8 5: PA9 6: PB6 7: PB7	8: PB8 9: PB9 10: PB10 11: PB11	12: PB12 13: PB13 14: PB14 15: PB15	16: PC0 17: PC1 18: PC2 19: PC3	20: PC4 21: PC5 22: PC6 23: PC7	24: PC8 25: PC9 26: PC10 27: PC11	28: PD8 29: PD9 30: PD10 31: PD11	Wide timer 0 Capture Compare input / output channel 2.
WTIM0_CDTI0	0: PA8 1: PA9 2: PB6 3: PB7	4: PB8 5: PB9 6: PB10 7: PB11	8: PB12 9: PB13 10: PB14 11: PB15	12: PC0 13: PC1 14: PC2 15: PC3	16: PC4 17: PC5 18: PC6 19: PC7	20: PC8 21: PC9 22: PC10 23: PC11	24: PD8 25: PD9 26: PD10 27: PD11	28: PD12 29: PD13 30: PD14 31: PD15	Wide timer 0 Complimentary Dead Time Insertion channel 0.
WTIM0_CDTI1	0: PB6 1: PB7 2: PB8 3: PB9	4: PB10 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC0 11: PC1	12: PC2 13: PC3 14: PC4 15: PC5	16: PC6 17: PC7 18: PC8 19: PC9	20: PC10 21: PC11 22: PD8 23: PD9	24: PD10 25: PD11 26: PD12 27: PD13	28: PD14 29: PD15 30: PF0 31: PF1	Wide timer 0 Complimentary Dead Time Insertion channel 1.
WTIM0_CDTI2	0: PB8 1: PB9 2: PB10 3: PB11	4: PB12 5: PB13 6: PB14 7: PB15	8: PC0 9: PC1 10: PC2 11: PC3	12: PC4 13: PC5 14: PC6 15: PC7	16: PC8 17: PC9 18: PC10 19: PC11	20: PD8 21: PD9 22: PD10 23: PD11	24: PD12 25: PD13 26: PD14 27: PD15	28: PF0 29: PF1 30: PF2 31: PF3	Wide timer 0 Complimentary Dead Time Insertion channel 2.
WTIM1_CC0	0: PB12 1: PB13 2: PB14 3: PB15	4: PC0 5: PC1 6: PC2 7: PC3	8: PC4 9: PC5 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD8 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	Wide timer 1 Capture Compare input / output channel 0.
WTIM1_CC1	0: PB14 1: PB15 2: PC0 3: PC1	4: PC2 5: PC3 6: PC4 7: PC5	8: PC6 9: PC7 10: PC8 11: PC9	12: PC10 13: PC11 14: PD8 15: PD9	16: PD10 17: PD11 18: PD12 19: PD13	20: PD14 21: PD15 22: PF0 23: PF1	24: PF2 25: PF3 26: PF4 27: PF5	28: PF6 29: PF7 30: PF8 31: PF9	Wide timer 1 Capture Compare input / output channel 1.
WTIM1_CC2	0: PC0 1: PC1 2: PC2 3: PC3	4: PC4 5: PC5 6: PC6 7: PC7	8: PC8 9: PC9 10: PC10 11: PC11	12: PD8 13: PD9 14: PD10 15: PD11	16: PD12 17: PD13 18: PD14 19: PD15	20: PF0 21: PF1 22: PF2 23: PF3	24: PF4 25: PF5 26: PF6 27: PF7	28: PF8 29: PF9 30: PF10 31: PF11	Wide timer 1 Capture Compare input / output channel 2.
WTIM1_CC3	0: PC2 1: PC3 2: PC4 3: PC5	4: PC6 5: PC7 6: PC8 7: PC9	8: PC10 9: PC11 10: PD8 11: PD9	12: PD10 13: PD11 14: PD12 15: PD13	16: PD14 17: PD15 18: PF0 19: PF1	20: PF2 21: PF3 22: PF4 23: PF5	24: PF6 25: PF7 26: PF8 27: PF9	28: PF10 29: PF11 30: PF12 31: PF13	Wide timer 1 Capture Compare input / output channel 3.

Table 6.9. CSEN Bus and Pin Mapping

Port	Bus	CH31	CH30	CH29	CH28	CH27	CH26	CH25	CH24	CH23	CH22	CH21	CH20	CH19	CH18	CH17	CH16	CH15	CH14	CH13	CH12	CH11	CH10	CH9	CH8	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0
CEXT																																	
APORT1X	BUSAX		PF14		PF12		PF10		PF8		PF6		PF4		PF2		PF0						PC10		PC8		PC6		PC4		PC2		PC0
APORT1Y	BUSAY	PF15		PF13		PF11		PF9		PF7		PF5		PF3		PF1						PC11		PC9		PC7		PC5		PC3		PC1	
APORT3X	BUSCX		PB14		PB12		PB10		PB8		PB6								PA6		PA4		PA2		PA0		PD14		PD12		PD10		PD8
APORT3Y	BUSCY	PB15		PB13		PB11		PB9		PB7								PA7		PA5		PA3		PA1		PD15		PD13		PD11		PD9	
CEXT_SENSE																																	
APORT2X	BUSBX	PF15		PF13		PF11		PF9		PF7		PF5		PF3		PF1						PC11		PC9		PC7		PC5		PC3		PC1	
APORT2Y	BUSBY		PF14		PF12		PF10		PF8		PF6		PF4		PF2		PF0						PC10		PC8		PC6		PC4		PC2		PC0
APORT4X	BUSDX	PB15		PB13		PB11		PB9		PB7								PA7		PA5		PA3		PA1		PD15		PD13		PD11		PD9	
APORT4Y	BUSDY		PB14		PB12		PB10		PB8		PB6								PA6		PA4		PA2		PA0		PD14		PD12		PD10		PD8

Table 6.10. IDAC0 Bus and Pin Mapping

Port	Bus	CH31	CH30	CH29	CH28	CH27	CH26	CH25	CH24	CH23	CH22	CH21	CH20	CH19	CH18	CH17	CH16	CH15	CH14	CH13	CH12	CH11	CH10	CH9	CH8	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0
APORT1X	BUSCX		PB14		PB12		PB10		PB8		PB6								PA6		PA4		PA2		PA0		PD14		PD12		PD10		PD8
APORT1Y	BUSCY	PB15		PB13		PB11		PB9		PB7								PA7		PA5		PA3		PA1		PD15		PD13		PD11		PD9	

Table 7.1. BGA125 Package Dimensions

Dimension	Min	Typ	Max
A	0.80	0.87	0.94
A1	0.16	0.21	0.26
A2	0.61	0.66	0.71
c	0.17	0.21	0.25
D	6.90	7.00	7.10
E	6.90	7.00	7.10
D1	---	6.00	---
E1	---	6.00	---
e	---	0.50	---
b	0.25	0.30	0.35
aaa	0.10		
bbb	0.10		
ddd	0.08		
eee	0.15		
fff	0.05		

Note:
1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.