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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	65
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D - 12b SAR
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TJ)
Mounting Type	Surface Mount
Package / Case	125-VFBGA
Supplier Device Package	125-BGA (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/efm32pg12b500f1024il125-cr">https://www.e-xfl.com/product-detail/silicon-labs/efm32pg12b500f1024il125-cr</a>

## 3.2 Power

The EFM32PG12 has an Energy Management Unit (EMU) and efficient integrated regulators to generate internal supply voltages. Only a single external supply voltage is required, from which all internal voltages are created. An optional integrated DC-DC buck regulator can be utilized to further reduce the current consumption. The DC-DC regulator requires one external inductor and one external capacitor.

The EFM32PG12 device family includes support for internal supply voltage scaling, as well as two different power domains groups for peripherals. These enhancements allow for further supply current reductions and lower overall power consumption.

AVDD and VREGVDD need to be 1.8 V or higher for the MCU to operate across all conditions; however the rest of the system will operate down to 1.62 V, including the digital supply and I/O. This means that the device is fully compatible with 1.8 V components. Running from a sufficiently high supply, the device can use the DC-DC to regulate voltage not only for itself, but also for other PCB components, supplying up to a total of 200 mA.

### 3.2.1 Energy Management Unit (EMU)

The Energy Management Unit manages transitions of energy modes in the device. Each energy mode defines which peripherals and features are available and the amount of current the device consumes. The EMU can also be used to turn off the power to unused RAM blocks, and it contains control registers for the DC-DC regulator and the Voltage Monitor (VMON). The VMON is used to monitor multiple supply voltages. It has multiple channels which can be programmed individually by the user to determine if a sensed supply has fallen below a chosen threshold.

### 3.2.2 DC-DC Converter

The DC-DC buck converter covers a wide range of load currents and provides up to 90% efficiency in energy modes EM0, EM1, EM2 and EM3, and can supply up to 200 mA to the device and surrounding PCB components. Protection features include programmable current limiting, short-circuit protection, and dead-time protection. The DC-DC converter may also enter bypass mode when the input voltage is too low for efficient operation. In bypass mode, the DC-DC input supply is internally connected directly to its output through a low resistance switch. Bypass mode also supports in-rush current limiting to prevent input supply voltage droops due to excessive output current transients.

### 3.2.3 Power Domains

The EFM32PG12 has two peripheral power domains for operation in EM2 and lower. If all of the peripherals in a peripheral power domain are configured as unused, the power domain for that group will be powered off in the low-power mode, reducing the overall current consumption of the device.

**Table 3.1. Peripheral Power Subdomains**

Peripheral Power Domain 1	Peripheral Power Domain 2
ACMP0	ACMP1
PCNT0	PCNT1
ADC0	PCNT2
LETIMER0	CSEN
LESENSE	DAC0
APORT	LEUART0
-	I2C0
-	I2C1
-	IDAC

### 3.10.2 Memory System Controller (MSC)

The Memory System Controller (MSC) is the program memory unit of the microcontroller. The flash memory is readable and writable from both the Cortex-M and DMA. The flash memory is divided into two blocks; the main block and the information block. Program code is normally written to the main block, whereas the information block is available for special user data and flash lock bits. There is also a read-only page in the information block containing system and device calibration data. Read and write operations are supported in energy modes EM0 Active and EM1 Sleep.

### 3.10.3 Linked Direct Memory Access Controller (LDMA)

The Linked Direct Memory Access (LDMA) controller allows the system to perform memory operations independently of software. This reduces both energy consumption and software workload. The LDMA allows operations to be linked together and staged, enabling sophisticated operations to be implemented.

### 4.1.3 Thermal Characteristics

**Table 4.3. Thermal Characteristics**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Thermal Resistance	THETA <sub>JA</sub>	QFN48 Package, 2-Layer PCB, Air velocity = 0 m/s	—	75.7	—	°C/W
		QFN48 Package, 2-Layer PCB, Air velocity = 1 m/s	—	61.5	—	°C/W
		QFN48 Package, 2-Layer PCB, Air velocity = 2 m/s	—	55.4	—	°C/W
		QFN48 Package, 4-Layer PCB, Air velocity = 0 m/s	—	30.2	—	°C/W
		QFN48 Package, 4-Layer PCB, Air velocity = 1 m/s	—	26.3	—	°C/W
		QFN48 Package, 4-Layer PCB, Air velocity = 2 m/s	—	24.9	—	°C/W
		BGA125 Package, 2-Layer PCB, Air velocity = 0 m/s	—	90.7	—	°C/W
		BGA125 Package, 2-Layer PCB, Air velocity = 1 m/s	—	73.7	—	°C/W
		BGA125 Package, 2-Layer PCB, Air velocity = 2 m/s	—	66.4	—	°C/W
		BGA125 Package, 4-Layer PCB, Air velocity = 0 m/s	—	45	—	°C/W
		BGA125 Package, 4-Layer PCB, Air velocity = 1 m/s	—	39.6	—	°C/W
		BGA125 Package, 4-Layer PCB, Air velocity = 2 m/s	—	37.6	—	°C/W

### 4.1.5.3 Current Consumption 1.8 V without DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = DVDD = 1.8 V. T<sub>OP</sub> = 25 °C. DCDC is off. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T<sub>OP</sub> = 25 °C.

**Table 4.7. Current Consumption 1.8 V without DC-DC Converter**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 mode with all peripherals disabled	I <sub>ACTIVE</sub>	38.4 MHz crystal, CPU running while loop from flash <sup>1</sup>	—	126	—	μA/MHz
		38 MHz HFRCO, CPU running Prime from flash	—	99	—	μA/MHz
		38 MHz HFRCO, CPU running while loop from flash	—	99	—	μA/MHz
		38 MHz HFRCO, CPU running CoreMark from flash	—	124	—	μA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	102	—	μA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	277	—	μA/MHz
Current consumption in EM0 mode with all peripherals disabled and voltage scaling enabled	I <sub>ACTIVE_VS</sub>	19 MHz HFRCO, CPU running while loop from flash	—	87	—	μA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	231	—	μA/MHz
Current consumption in EM1 mode with all peripherals disabled	I <sub>EM1</sub>	38.4 MHz crystal <sup>1</sup>	—	76	—	μA/MHz
		38 MHz HFRCO	—	50	—	μA/MHz
		26 MHz HFRCO	—	52	—	μA/MHz
		1 MHz HFRCO	—	227	—	μA/MHz
Current consumption in EM1 mode with all peripherals disabled and voltage scaling enabled	I <sub>EM1_VS</sub>	19 MHz HFRCO	—	47	—	μA/MHz
		1 MHz HFRCO	—	190	—	μA/MHz
Current consumption in EM2 mode, with voltage scaling enabled.	I <sub>EM2_VS</sub>	Full 256 kB RAM retention and RTCC running from LFXO	—	2.8	—	μA
		Full 256 kB RAM retention and RTCC running from LFRCO	—	3.0	—	μA
		16 kB (1 bank) RAM retention and RTCC running from LFRCO <sup>2</sup>	—	1.9	—	μA
Current consumption in EM3 mode, with voltage scaling enabled.	I <sub>EM3_VS</sub>	Full 256 kB RAM retention and CRYOTIMER running from ULFR-CO	—	2.47	—	μA
Current consumption in EM4H mode, with voltage scaling enabled.	I <sub>EM4H_VS</sub>	128 byte RAM retention, RTCC running from LFXO	—	0.91	—	μA
		128 byte RAM retention, CRYOTIMER running from ULFRCO	—	0.35	—	μA
		128 byte RAM retention, no RTCC	—	0.35	—	μA
Current consumption in EM4S mode	I <sub>EM4S</sub>	no RAM retention, no RTCC	—	0.04	—	μA

### 4.1.9 Flash Memory Characteristics<sup>3</sup>

**Table 4.16. Flash Memory Characteristics<sup>3</sup>**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Flash erase cycles before failure	EC <sub>FLASH</sub>		10000	—	—	cycles
Flash data retention	RET <sub>FLASH</sub>	T <sub>AMB</sub> ≤ 85 °C	10	—	—	years
		T <sub>AMB</sub> ≤ 125 °C	10	—	—	years
Word (32-bit) programming time	t <sub>W_PROG</sub>		20	24.4	30	μs
Page erase time	t <sub>PERASE</sub>		20	26.4	35	ms
Mass erase time <sup>1</sup>	t <sub>MERASE</sub>		20	26.5	35	ms
Device erase time <sup>2</sup>	t <sub>DERASE</sub>	T <sub>AMB</sub> ≤ 85 °C	—	69	100	ms
		T <sub>AMB</sub> ≤ 125 °C	—	69	110	ms
Page erase current <sup>4</sup>	I <sub>ERASE</sub>		—	—	1.6	mA
Write current <sup>4</sup>	I <sub>WRITE</sub>		—	—	3.8	mA
Supply voltage during flash erase and write	V <sub>FLASH</sub>		1.62	—	TBD	V

**Note:**

1. Mass erase is issued by the CPU and erases all flash.
2. Device erase is issued over the AAP interface and erases all flash, SRAM, the Lock Bit (LB) page, and the User data page Lock Word (ULW).
3. Flash data retention information is published in the Quarterly Quality and Reliability Report.
4. Measured at 25 °C.

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output fall time, From 70% to 30% of $V_{IO}$	$t_{IOF}$	$C_L = 50\text{ pF}$ , DRIVESTRENGTH <sup>1</sup> = STRONG, SLEWRATE <sup>1</sup> = 0x6	—	1.8	—	ns
		$C_L = 50\text{ pF}$ , DRIVESTRENGTH <sup>1</sup> = WEAK, SLEWRATE <sup>1</sup> = 0x6	—	4.5	—	ns
Output rise time, From 30% to 70% of $V_{IO}$	$t_{IOR}$	$C_L = 50\text{ pF}$ , DRIVESTRENGTH <sup>1</sup> = STRONG, SLEWRATE = 0x6 <sup>1</sup>	—	2.2	—	ns
		$C_L = 50\text{ pF}$ , DRIVESTRENGTH <sup>1</sup> = WEAK, SLEWRATE <sup>1</sup> = 0x6	—	7.4	—	ns

**Note:**  
1. In GPIO\_Pn\_CTRL register.

#### 4.1.16 Capacitive Sense (CSEN)

**Table 4.23. Capacitive Sense (CSEN)**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Single conversion time (1x accumulation)	$t_{CNV}$	12-bit SAR Conversions	—	20.2	—	$\mu s$
		16-bit SAR Conversions	—	26.4	—	$\mu s$
		Delta Modulation Conversion (single comparison)	—	1.55	—	$\mu s$
Maximum external capacitive load	$C_{EXTMAX}$	CS0CG=7 (Gain = 1x), including routing parasitics	—	68	—	pF
		CS0CG=0 (Gain = 10x), including routing parasitics	—	680	—	pF
Maximum external series impedance	$R_{EXTMAX}$		—	1	—	k $\Omega$
Supply current, EM2 scan conversions, WARMUP-MODE=NORMAL, WARMUPCNT=0	$I_{CSEN\_EM2}$	12-bit SAR conversions, 20 ms scan rate, 8 samples per scan <sup>1</sup>	—	800	—	nA
		Delta Modulation conversions, 20 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), 8 samples per scan <sup>1</sup>	—	590	—	nA
		12-bit SAR conversions, 200 ms scan rate, 8 samples per scan <sup>1</sup>	—	80	—	nA
		Delta Modulation conversions, 200 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), 8 samples per scan <sup>1</sup>	—	59	—	nA
Supply current, continuous conversions, WARMUP-MODE=KEEPCSENWARM	$I_{CSEN\_ACTIVE}$	SAR or Delta Modulation conversions of 33 pF capacitor, always on	—	90.5	—	$\mu A$

**Note:**

- Current is specified with a total external capacitance of 33 pF. Average current is dependent on how long the module is actively sampling channels within the scan period, and will scale linearly with the number of samples acquired. Supply current for a specific application can be calculated by multiplying the current per sample by the total number of samples per period ( $total\_current = single\_sample\_current * (number\_of\_channels * accumulation)$ ).



## 4.2.1 Supply Current

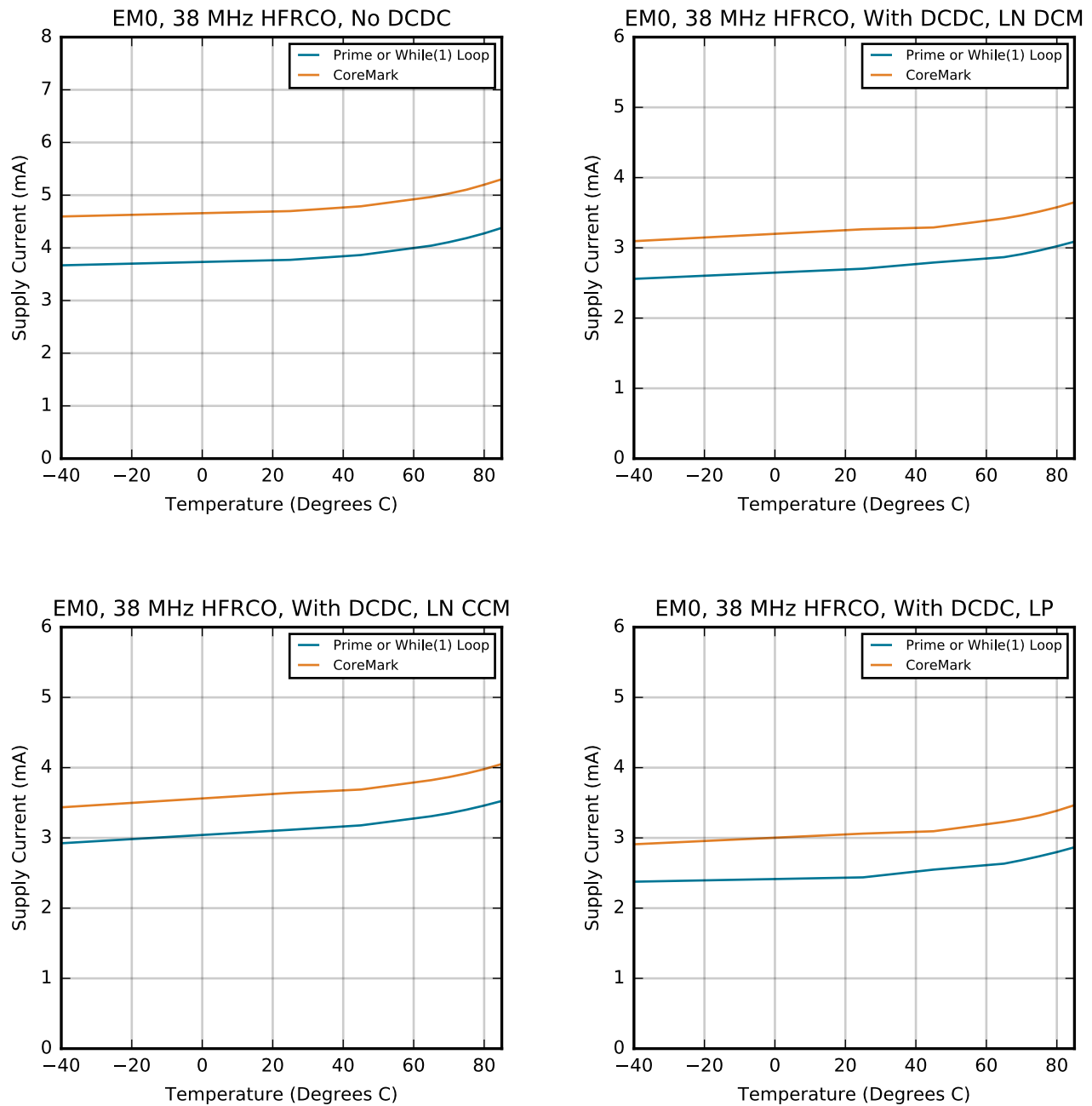
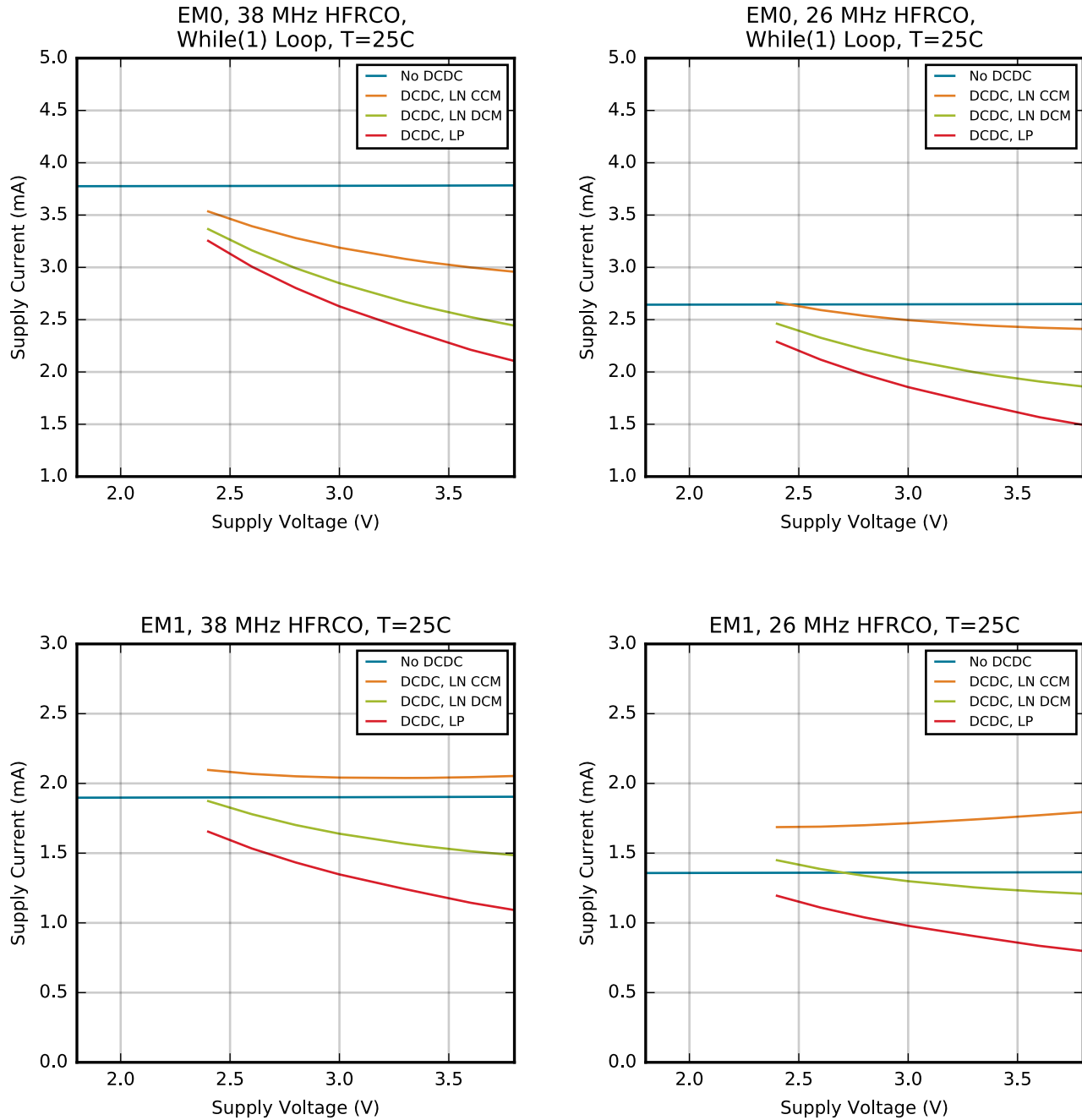


Figure 4.3. EM0 Active Mode Typical Supply Current vs. Temperature



**Figure 4.6. EM0 and EM1 Mode Typical Supply Current vs. Supply**

Typical supply current for EM2, EM3 and EM4H using standard software libraries from Silicon Laboratories.

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
E13	PB7	BUSCY BUSDX	WTIM0_CC0 #11 WTIM0_CC1 #9 WTIM0_CC2 #7 WTIM0_CDTI0 #3 WTIM0_CDTI1 #1 PCNT1_S0IN #7 PCNT1_S1IN #6 PCNT2_S0IN #7 PCNT2_S1IN #6	US2_TX #10 US2_RX #9 US2_CLK #8 US2_CS #7 US2_CTS #6 US2_RTS #5 US3_TX #11 US3_RX #10 US3_CLK #9 US3_CS #8 US3_CTS #7 US3_RTS #6 I2C1_SDA #7 I2C1_SCL #6	ETM_TD2 #2
F1	PK2		PCNT1_S0IN #31 PCNT1_S1IN #30 PCNT2_S0IN #31 PCNT2_S1IN #30	US2_TX #31 US2_RX #30 US2_CLK #29 US2_CS #28 US2_CTS #27 US2_RTS #26 US3_TX #31 US3_RX #30 US3_CLK #29 US3_CS #28 US3_CTS #27 US3_RTS #26 I2C1_SDA #31 I2C1_SCL #30	
F2	IOVDD	Digital IO power supply .			
F5	VSS	Ground			
F6	VSS	Ground			
F7	VSS	Ground			
F8	VSS	Ground			
F9	VSS	Ground			
F11	IOVDD	Digital IO power supply .			
F12	PB6	BUSDY BUSCX	WTIM0_CC0 #10 WTIM0_CC1 #8 WTIM0_CC2 #6 WTIM0_CDTI0 #2 WTIM0_CDTI1 #0 PCNT1_S0IN #6 PCNT1_S1IN #5 PCNT2_S0IN #6 PCNT2_S1IN #5	US2_TX #9 US2_RX #8 US2_CLK #7 US2_CS #6 US2_CTS #5 US2_RTS #4 US3_TX #10 US3_RX #9 US3_CLK #8 US3_CS #7 US3_CTS #6 US3_RTS #5 I2C1_SDA #6 I2C1_SCL #5	CMU_CLKI0 #3 ETM_TD1 #2
F13	PI3	BUSADC0Y BU-SADC0X	PCNT1_S0IN #5 PCNT1_S1IN #4 PCNT2_S0IN #5 PCNT2_S1IN #4	US2_TX #8 US2_RX #7 US2_CLK #6 US2_CS #5 US2_CTS #4 US2_RTS #3 US3_TX #9 US3_RX #8 US3_CLK #7 US3_CS #6 US3_CTS #5 US3_RTS #4 I2C1_SDA #5 I2C1_SCL #4	LES_ALTEX7 ETM_TD0 #2

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
19	PD10	BUSDY BUSCX	TIM0_CC0 #18 TIM0_CC1 #17 TIM0_CC2 #16 TIM0_CDTI0 #15 TIM0_CDTI1 #14 TIM0_CDTI2 #13 TIM1_CC0 #18 TIM1_CC1 #17 TIM1_CC2 #16 TIM1_CC3 #15 WTIM0_CC2 #30 WTIM0_CDTI0 #26 WTIM0_CDTI1 #24 WTIM0_CDTI2 #22 WTIM1_CC0 #18 WTIM1_CC1 #16 WTIM1_CC2 #14 WTIM1_CC3 #12 LE- TIM0_OUT0 #18 LE- TIM0_OUT1 #17 PCNT0_S0IN #18 PCNT0_S1IN #17	US0_TX #18 US0_RX #17 US0_CLK #16 US0_CS #15 US0_CTS #14 US0_RTS #13 US1_TX #18 US1_RX #17 US1_CLK #16 US1_CS #15 US1_CTS #14 US1_RTS #13 US3_TX #2 US3_RX #1 US3_CLK #0 US3_CS #31 US3_CTS #30 US3_RTS #29 LEU0_TX #18 LEU0_RX #17 I2C0_SDA #18 I2C0_SCL #17	CMU_CLK1 #4 PRS_CH3 #9 PRS_CH4 #1 PRS_CH5 #0 PRS_CH6 #12 ACMP0_O #18 ACMP1_O #18 LES_CH2
20	PD11	BUSCY BUSDX	TIM0_CC0 #19 TIM0_CC1 #18 TIM0_CC2 #17 TIM0_CDTI0 #16 TIM0_CDTI1 #15 TIM0_CDTI2 #14 TIM1_CC0 #19 TIM1_CC1 #18 TIM1_CC2 #17 TIM1_CC3 #16 WTIM0_CC2 #31 WTIM0_CDTI0 #27 WTIM0_CDTI1 #25 WTIM0_CDTI2 #23 WTIM1_CC0 #19 WTIM1_CC1 #17 WTIM1_CC2 #15 WTIM1_CC3 #13 LE- TIM0_OUT0 #19 LE- TIM0_OUT1 #18 PCNT0_S0IN #19 PCNT0_S1IN #18	US0_TX #19 US0_RX #18 US0_CLK #17 US0_CS #16 US0_CTS #15 US0_RTS #14 US1_TX #19 US1_RX #18 US1_CLK #17 US1_CS #16 US1_CTS #15 US1_RTS #14 US3_TX #3 US3_RX #2 US3_CLK #1 US3_CS #0 US3_CTS #31 US3_RTS #30 LEU0_TX #19 LEU0_RX #18 I2C0_SDA #19 I2C0_SCL #18	PRS_CH3 #10 PRS_CH4 #2 PRS_CH5 #1 PRS_CH6 #13 ACMP0_O #19 ACMP1_O #19 LES_CH3

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
26	PA1	BUSCY BUSDX ADC0_EXTP VDAC0_EXT	TIM0_CC0 #1 TIM0_CC1 #0 TIM0_CC2 #31 TIM0_CDTI0 #30 TIM0_CDTI1 #29 TIM0_CDTI2 #28 TIM1_CC0 #1 TIM1_CC1 #0 TIM1_CC2 #31 TIM1_CC3 #30 WTIM0_CC0 #1 LE- TIM0_OUT0 #1 LE- TIM0_OUT1 #0 PCNT0_S0IN #1 PCNT0_S1IN #0	US0_TX #1 US0_RX #0 US0_CLK #31 US0_CS #30 US0_CTS #29 US0_RTS #28 US1_TX #1 US1_RX #0 US1_CLK #31 US1_CS #30 US1_CTS #29 US1_RTS #28 LEU0_TX #1 LEU0_RX #0 I2C0_SDA #1 I2C0_SCL #0	CMU_CLK0 #0 PRS_CH6 #1 PRS_CH7 #0 PRS_CH8 #10 PRS_CH9 #9 ACMP0_O #1 ACMP1_O #1 LES_CH9
27	PA2	VDAC0_OUT1ALT / OPA1_OUTALT #1 BUSDY BUSCX OPA0_P	TIM0_CC0 #2 TIM0_CC1 #1 TIM0_CC2 #0 TIM0_CDTI0 #31 TIM0_CDTI1 #30 TIM0_CDTI2 #29 TIM1_CC0 #2 TIM1_CC1 #1 TIM1_CC2 #0 TIM1_CC3 #31 WTIM0_CC0 #2 WTIM0_CC1 #0 LE- TIM0_OUT0 #2 LE- TIM0_OUT1 #1 PCNT0_S0IN #2 PCNT0_S1IN #1	US0_TX #2 US0_RX #1 US0_CLK #0 US0_CS #31 US0_CTS #30 US0_RTS #29 US1_TX #2 US1_RX #1 US1_CLK #0 US1_CS #31 US1_CTS #30 US1_RTS #29 LEU0_TX #2 LEU0_RX #1 I2C0_SDA #2 I2C0_SCL #1	PRS_CH6 #2 PRS_CH7 #1 PRS_CH8 #0 PRS_CH9 #10 ACMP0_O #2 ACMP1_O #2 LES_CH10
28	PA3	BUSCY BUSDX VDAC0_OUT0 / OPA0_OUT	TIM0_CC0 #3 TIM0_CC1 #2 TIM0_CC2 #1 TIM0_CDTI0 #0 TIM0_CDTI1 #31 TIM0_CDTI2 #30 TIM1_CC0 #3 TIM1_CC1 #2 TIM1_CC2 #1 TIM1_CC3 #0 WTIM0_CC0 #3 WTIM0_CC1 #1 LE- TIM0_OUT0 #3 LE- TIM0_OUT1 #2 PCNT0_S0IN #3 PCNT0_S1IN #2	US0_TX #3 US0_RX #2 US0_CLK #1 US0_CS #0 US0_CTS #31 US0_RTS #30 US1_TX #3 US1_RX #2 US1_CLK #1 US1_CS #0 US1_CTS #31 US1_RTS #30 LEU0_TX #3 LEU0_RX #2 I2C0_SDA #3 I2C0_SCL #2	PRS_CH6 #3 PRS_CH7 #2 PRS_CH8 #1 PRS_CH9 #0 ACMP0_O #3 ACMP1_O #3 LES_CH11 GPIO_EM4WU8

Pin		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
29	PA4	VDAC0_OUT1ALT / OPA1_OUTALT #2 BUSDY BUSCX OPA0_N	TIM0_CC0 #4 TIM0_CC1 #3 TIM0_CC2 #2 TIM0_CDTI0 #1 TIM0_CDTI1 #0 TIM0_CDTI2 #31 TIM1_CC0 #4 TIM1_CC1 #3 TIM1_CC2 #2 TIM1_CC3 #1 WTIM0_CC0 #4 WTIM0_CC1 #2 WTIM0_CC2 #0 LE- TIM0_OUT0 #4 LE- TIM0_OUT1 #3 PCNT0_S0IN #4 PCNT0_S1IN #3	US0_TX #4 US0_RX #3 US0_CLK #2 US0_CS #1 US0_CTS #0 US0_RTS #31 US1_TX #4 US1_RX #3 US1_CLK #2 US1_CS #1 US1_CTS #0 US1_RTS #31 LEU0_TX #4 LEU0_RX #3 I2C0_SDA #4 I2C0_SCL #3	PRS_CH6 #4 PRS_CH7 #3 PRS_CH8 #2 PRS_CH9 #1 ACMP0_O #4 ACMP1_O #4 LES_CH12
30	PA5	VDAC0_OUT0ALT / OPA0_OUTALT #0 BUSCY BUSDX	TIM0_CC0 #5 TIM0_CC1 #4 TIM0_CC2 #3 TIM0_CDTI0 #2 TIM0_CDTI1 #1 TIM0_CDTI2 #0 TIM1_CC0 #5 TIM1_CC1 #4 TIM1_CC2 #3 TIM1_CC3 #2 WTIM0_CC0 #5 WTIM0_CC1 #3 WTIM0_CC2 #1 LE- TIM0_OUT0 #5 LE- TIM0_OUT1 #4 PCNT0_S0IN #5 PCNT0_S1IN #4	US0_TX #5 US0_RX #4 US0_CLK #3 US0_CS #2 US0_CTS #1 US0_RTS #0 US1_TX #5 US1_RX #4 US1_CLK #3 US1_CS #2 US1_CTS #1 US1_RTS #0 US2_TX #0 US2_RX #31 US2_CLK #30 US2_CS #29 US2_CTS #28 US2_RTS #27 LEU0_TX #5 LEU0_RX #4 I2C0_SDA #5 I2C0_SCL #4	CMU_CLKI0 #4 PRS_CH6 #5 PRS_CH7 #4 PRS_CH8 #3 PRS_CH9 #2 ACMP0_O #5 ACMP1_O #5 LES_CH13 ETM_TCLK #1
31	PB11	BUSCY BUSDX OPA2_P	TIM0_CC0 #6 TIM0_CC1 #5 TIM0_CC2 #4 TIM0_CDTI0 #3 TIM0_CDTI1 #2 TIM0_CDTI2 #1 TIM1_CC0 #6 TIM1_CC1 #5 TIM1_CC2 #4 TIM1_CC3 #3 WTIM0_CC0 #15 WTIM0_CC1 #13 WTIM0_CC2 #11 WTIM0_CDTI0 #7 WTIM0_CDTI1 #5 WTIM0_CDTI2 #3 LE- TIM0_OUT0 #6 LE- TIM0_OUT1 #5 PCNT0_S0IN #6 PCNT0_S1IN #5	US0_TX #6 US0_RX #5 US0_CLK #4 US0_CS #3 US0_CTS #2 US0_RTS #1 US1_TX #6 US1_RX #5 US1_CLK #4 US1_CS #3 US1_CTS #2 US1_RTS #1 US3_TX #15 US3_RX #14 US3_CLK #13 US3_CS #12 US3_CTS #11 US3_RTS #10 LEU0_TX #6 LEU0_RX #5 I2C0_SDA #6 I2C0_SCL #5	PRS_CH6 #6 PRS_CH7 #5 PRS_CH8 #4 PRS_CH9 #3 ACMP0_O #6 ACMP1_O #6

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
LES_ALTEX0	0: PA8								LESENSE alternate excite output 0.
LES_ALTEX1	0: PA9								LESENSE alternate excite output 1.
LES_ALTEX2	0: PJ14								LESENSE alternate excite output 2.
LES_ALTEX3	0: PJ15								LESENSE alternate excite output 3.
LES_ALTEX4	0: PI0								LESENSE alternate excite output 4.
LES_ALTEX5	0: PI1								LESENSE alternate excite output 5.
LES_ALTEX6	0: PI2								LESENSE alternate excite output 6.
LES_ALTEX7	0: PI3								LESENSE alternate excite output 7.
LES_CH0	0: PD8								LESENSE channel 0.
LES_CH1	0: PD9								LESENSE channel 1.
LES_CH2	0: PD10								LESENSE channel 2.
LES_CH3	0: PD11								LESENSE channel 3.
LES_CH4	0: PD12								LESENSE channel 4.

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
LEU0_RX	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	LEUART0 Receive input.
LEU0_TX	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	LEUART0 Transmit output. Also used as receive input in half duplex communication.
LFXTAL_N	0: PB14								Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	0: PB15								Low Frequency Crystal (typically 32.768 kHz) positive pin.
OPA0_N	0: PA4								Operational Amplifier 0 external negative input.
OPA0_P	0: PA2								Operational Amplifier 0 external positive input.
OPA1_N	0: PD15								Operational Amplifier 1 external negative input.
OPA1_P	0: PD13								Operational Amplifier 1 external positive input.
OPA2_N	0: PB13								Operational Amplifier 2 external negative input.
OPA2_OUT	0: PB12								Operational Amplifier 2 output.
OPA2_OUTALT	0: PB9 1: PB10								Operational Amplifier 2 alternative output.
OPA2_P	0: PB11								Operational Amplifier 2 external positive input.



Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
PCNT0_S0IN	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	Pulse Counter PCNT0 input number 0.
PCNT0_S1IN	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	Pulse Counter PCNT0 input number 1.
PCNT1_S0IN	0: PA6 1: PA7 2: PA8 3: PA9	4: PI2 5: PI3 6: PB6 7: PB7	8: PB8 9: PB9 10: PB10 11: PJ14	12: PJ15 13: PC0 14: PC1 15: PC2	16: PC3 17: PC4 18: PC5 19: PF6	20: PF7 21: PF8 22: PF9 23: PF10	24: PF11 25: PF12 26: PF13 27: PF14	28: PF15 29: PK0 30: PK1 31: PK2	Pulse Counter PCNT1 input number 0.
PCNT1_S1IN	0: PA7 1: PA8 2: PA9 3: PI2	4: PI3 5: PB6 6: PB7 7: PB8	8: PB9 9: PB10 10: PJ14 11: PJ15	12: PC0 13: PC1 14: PC2 15: PC3	16: PC4 17: PC5 18: PF6 19: PF7	20: PF8 21: PF9 22: PF10 23: PF11	24: PF12 25: PF13 26: PF14 27: PF15	28: PK0 29: PK1 30: PK2 31: PA6	Pulse Counter PCNT1 input number 1.
PCNT2_S0IN	0: PA6 1: PA7 2: PA8 3: PA9	4: PI2 5: PI3 6: PB6 7: PB7	8: PB8 9: PB9 10: PB10 11: PJ14	12: PJ15 13: PC0 14: PC1 15: PC2	16: PC3 17: PC4 18: PC5 19: PC10	20: PC11 21: PF8 22: PF9 23: PF10	24: PF11 25: PF12 26: PF13 27: PF14	28: PF15 29: PK0 30: PK1 31: PK2	Pulse Counter PCNT2 input number 0.
PCNT2_S1IN	0: PA7 1: PA8 2: PA9 3: PI2	4: PI3 5: PB6 6: PB7 7: PB8	8: PB9 9: PB10 10: PJ14 11: PJ15	12: PC0 13: PC1 14: PC2 15: PC3	16: PC4 17: PC5 18: PC10 19: PC11	20: PF8 21: PF9 22: PF10 23: PF11	24: PF12 25: PF13 26: PF14 27: PF15	28: PK0 29: PK1 30: PK2 31: PA6	Pulse Counter PCNT2 input number 1.
PRS_CH0	0: PF0 1: PF1 2: PF2 3: PF3	4: PF4 5: PF5 6: PF6 7: PF7	8: PC6 9: PC7 10: PC8 11: PC9	12: PC10 13: PC11					Peripheral Reflex System PRS, channel 0.
PRS_CH1	0: PF1 1: PF2 2: PF3 3: PF4	4: PF5 5: PF6 6: PF7 7: PF0							Peripheral Reflex System PRS, channel 1.
PRS_CH2	0: PF2 1: PF3 2: PF4 3: PF5	4: PF6 5: PF7 6: PF0 7: PF1							Peripheral Reflex System PRS, channel 2.
PRS_CH3	0: PF3 1: PF4 2: PF5 3: PF6	4: PF7 5: PF0 6: PF1 7: PF2	8: PD9 9: PD10 10: PD11 11: PD12	12: PD13 13: PD14 14: PD15					Peripheral Reflex System PRS, channel 3.
PRS_CH4	0: PD9 1: PD10 2: PD11 3: PD12	4: PD13 5: PD14 6: PD15							Peripheral Reflex System PRS, channel 4.
PRS_CH5	0: PD10 1: PD11 2: PD12 3: PD13	4: PD14 5: PD15 6: PD9							Peripheral Reflex System PRS, channel 5.
PRS_CH6	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PD9	12: PD10 13: PD11 14: PD12 15: PD13	16: PD14 17: PD15				Peripheral Reflex System PRS, channel 6.

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
TIM1_CC2	0: PA2 1: PA3 2: PA4 3: PA5	4: PB11 5: PB12 6: PB13 7: PB14	8: PB15 9: PC6 10: PC7 11: PC8	12: PC9 13: PC10 14: PC11 15: PD9	16: PD10 17: PD11 18: PD12 19: PD13	20: PD14 21: PD15 22: PF0 23: PF1	24: PF2 25: PF3 26: PF4 27: PF5	28: PF6 29: PF7 30: PA0 31: PA1	Timer 1 Capture Compare input / output channel 2.
TIM1_CC3	0: PA3 1: PA4 2: PA5 3: PB11	4: PB12 5: PB13 6: PB14 7: PB15	8: PC6 9: PC7 10: PC8 11: PC9	12: PC10 13: PC11 14: PD9 15: PD10	16: PD11 17: PD12 18: PD13 19: PD14	20: PD15 21: PF0 22: PF1 23: PF2	24: PF3 25: PF4 26: PF5 27: PF6	28: PF7 29: PA0 30: PA1 31: PA2	Timer 1 Capture Compare input / output channel 3.
US0_CLK	0: PA2 1: PA3 2: PA4 3: PA5	4: PB11 5: PB12 6: PB13 7: PB14	8: PB15 9: PC6 10: PC7 11: PC8	12: PC9 13: PC10 14: PC11 15: PD9	16: PD10 17: PD11 18: PD12 19: PD13	20: PD14 21: PD15 22: PF0 23: PF1	24: PF2 25: PF3 26: PF4 27: PF5	28: PF6 29: PF7 30: PA0 31: PA1	USART0 clock input / output.
US0_CS	0: PA3 1: PA4 2: PA5 3: PB11	4: PB12 5: PB13 6: PB14 7: PB15	8: PC6 9: PC7 10: PC8 11: PC9	12: PC10 13: PC11 14: PD9 15: PD10	16: PD11 17: PD12 18: PD13 19: PD14	20: PD15 21: PF0 22: PF1 23: PF2	24: PF3 25: PF4 26: PF5 27: PF6	28: PF7 29: PA0 30: PA1 31: PA2	USART0 chip select input / output.
US0_CTS	0: PA4 1: PA5 2: PB11 3: PB12	4: PB13 5: PB14 6: PB15 7: PC6	8: PC7 9: PC8 10: PC9 11: PC10	12: PC11 13: PD9 14: PD10 15: PD11	16: PD12 17: PD13 18: PD14 19: PD15	20: PF0 21: PF1 22: PF2 23: PF3	24: PF4 25: PF5 26: PF6 27: PF7	28: PA0 29: PA1 30: PA2 31: PA3	USART0 Clear To Send hardware flow control input.
US0_RTS	0: PA5 1: PB11 2: PB12 3: PB13	4: PB14 5: PB15 6: PC6 7: PC7	8: PC8 9: PC9 10: PC10 11: PC11	12: PD9 13: PD10 14: PD11 15: PD12	16: PD13 17: PD14 18: PD15 19: PF0	20: PF1 21: PF2 22: PF3 23: PF4	24: PF5 25: PF6 26: PF7 27: PA0	28: PA1 29: PA2 30: PA3 31: PA4	USART0 Request To Send hardware flow control output.
US0_RX	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	USART0 Asynchronous Receive.  USART0 Synchronous mode Master Input / Slave Output (MISO).
US0_TX	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	USART0 Asynchronous Transmit. Also used as receive input in half duplex communication.  USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	0: PA2 1: PA3 2: PA4 3: PA5	4: PB11 5: PB12 6: PB13 7: PB14	8: PB15 9: PC6 10: PC7 11: PC8	12: PC9 13: PC10 14: PC11 15: PD9	16: PD10 17: PD11 18: PD12 19: PD13	20: PD14 21: PD15 22: PF0 23: PF1	24: PF2 25: PF3 26: PF4 27: PF5	28: PF6 29: PF7 30: PA0 31: PA1	USART1 clock input / output.
US1_CS	0: PA3 1: PA4 2: PA5 3: PB11	4: PB12 5: PB13 6: PB14 7: PB15	8: PC6 9: PC7 10: PC8 11: PC9	12: PC10 13: PC11 14: PD9 15: PD10	16: PD11 17: PD12 18: PD13 19: PD14	20: PD15 21: PF0 22: PF1 23: PF2	24: PF3 25: PF4 26: PF5 27: PF6	28: PF7 29: PA0 30: PA1 31: PA2	USART1 chip select input / output.
US1_CTS	0: PA4 1: PA5 2: PB11 3: PB12	4: PB13 5: PB14 6: PB15 7: PC6	8: PC7 9: PC8 10: PC9 11: PC10	12: PC11 13: PD9 14: PD10 15: PD11	16: PD12 17: PD13 18: PD14 19: PD15	20: PF0 21: PF1 22: PF2 23: PF3	24: PF4 25: PF5 26: PF6 27: PF7	28: PA0 29: PA1 30: PA2 31: PA3	USART1 Clear To Send hardware flow control input.

Port	Bus	CH31	CH30	CH29	CH28	CH27	CH26	CH25	CH24	CH23	CH22	CH21	CH20	CH19	CH18	CH17	CH16	CH15	CH14	CH13	CH12	CH11	CH10	CH9	CH8	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0	
VDAC0_OUT1 / OPA1_OUT																																		
APORT4Y	BUSDY		PB14		PB12		PB10		PB8		PB6								PA6			PA4		PA2		PA0		PD14		PD12		PD10		PD8
APORT3Y	BUSCY	PB15		PB13		PB11		PB9		PB7								PA7		PA5		PA3			PA1		PD15		PD13		PD11		PD9	
APORT2Y	BUSBY		PF14		PF12		PF10		PF8		PF6		PF4		PF2		PF0							PC10		PC8		PC6		PC4		PC2		PC0
APORT1Y	BUSAY	PF15		PF13		PF11		PF9		PF7		PF5		PF3		PF1							PC11		PC9		PC7		PC5		PC3		PC1	

## 7.2 BGA125 PCB Land Pattern

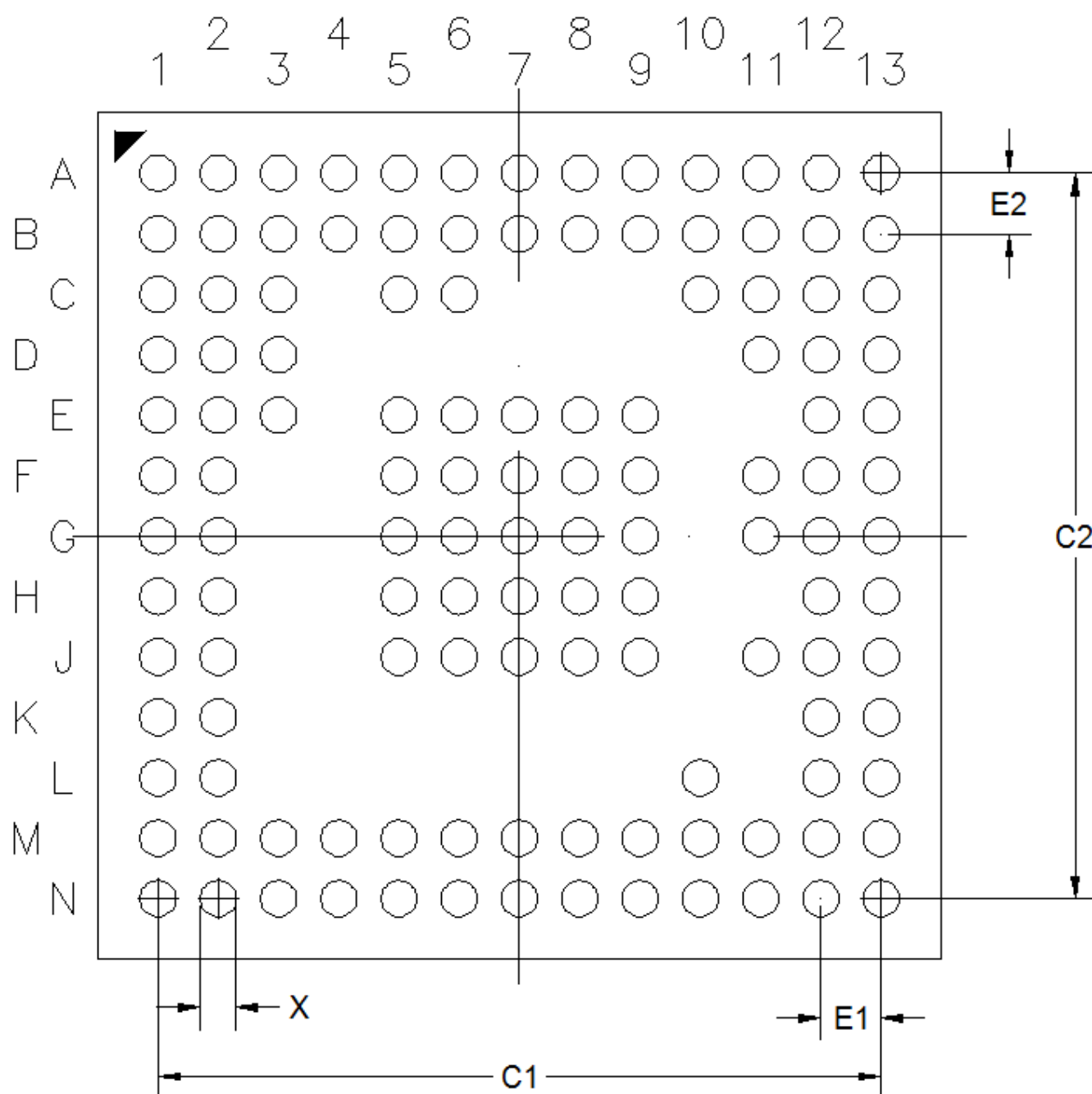


Figure 7.2. BGA125 PCB Land Pattern Drawing

### 8.3 QFN48 Package Marking



Figure 8.3. QFN48 Package Marking

The package marking consists of:

- P P P P P P P P P P – The part number designation.
- T T T T T T – A trace or manufacturing code. The first letter is the device revision.
- Y Y – The last 2 digits of the assembly year.
- W W – The 2-digit workweek when the device was assembled.