Welcome to E-XFL.COM

Understanding Embedded - Microprocessors

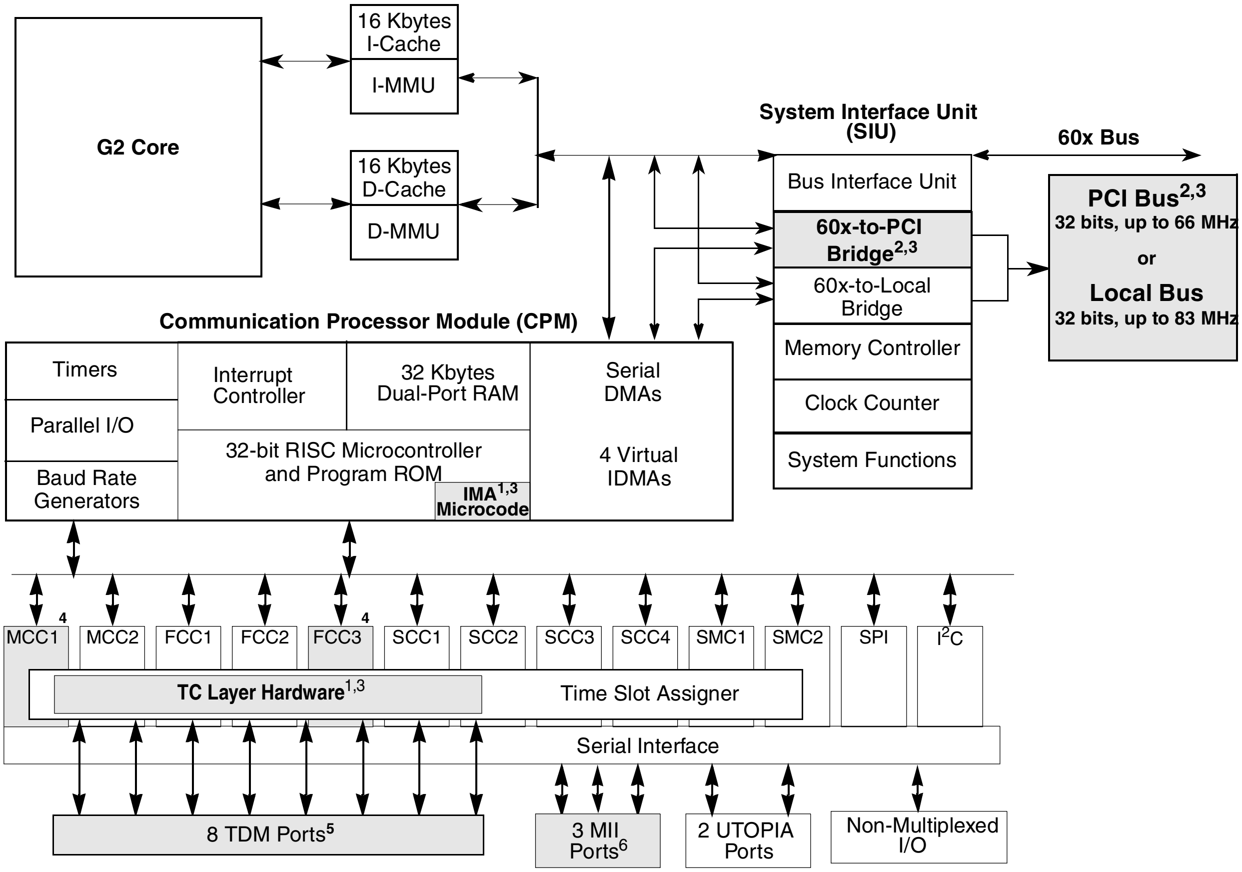
Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	200MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	-40°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/kmpc8260acvvmibb

Figure 1 shows the block diagram for the MPC8266, the HiP4 superset device. Shaded portions indicate functionality that is not available on all devices; refer to the notes.



Notes:

[1] MPC8264
[2] MPC8265
[3] MPC8266
[4] Not on MPC8255
[5] 4 TDM ports on the MPC8255
[6] 2 MII ports on the MPC8255

Figure 1. MPC8266 Block Diagram

1 Features

The major features of the MPC826xA family are as follows:

- Dual-issue integer core
  - — A core version of the EC603e microprocessor
  - — System core microprocessor supporting frequencies of 150–300 MHz
  - — Separate 16-Kbyte data and instruction caches:
    - – Four-way set associative
    - – Physically addressed
    - – LRU replacement algorithm

    - Transparent
    - UART (low-speed operation)
  - One serial peripheral interface identical to the MPC860 SPI
  - One inter-integrated circuit (I^2C) controller (identical to the MPC860 I^2C controller)
    - Microwire compatible
    - Multiple-master, single-master, and slave modes
  - Up to eight TDM interfaces (four on the MPC8255)
    - Supports two groups of four TDM channels for a total of eight TDMs
    - 2,048 bytes of SI RAM
    - Bit or byte resolution
    - Independent transmit and receive routing, frame synchronization
    - Supports T1, CEPT, T1/E1, T3/E3, pulse code modulation highway, ISDN basic rate, ISDN primary rate, Freescale interchip digital link (IDL), general circuit interface (GCI), and user-defined TDM serial interfaces
  - Eight independent baud rate generators and 20 input clock pins for supplying clocks to FCCs, SCCs, SMCs, and serial channels
  - Four independent 16-bit timers that can be interconnected as two 32-bit timers

Additional features of the MPC826xA family are as follows:

- CPM
  - 32-Kbyte dual-port RAM
  - Additional MCC host commands
  - Eight transfer transmission convergence (TC) layers between the TDMs and FCC2 to support inverse multiplexing for ATM capabilities (IMA) (MPC8264 and MPC8266 only)
- CPM multiplexing
  - FCC2 can also be connected to the TC layer.
- TC layer (MPC8264 and MPC8266 only)
  - Each of the 8 TDM channels is routed in hardware to a TC layer block
    - Protocol-specific overhead bits may be discarded or routed to other controllers by the SI
    - Performing ATM TC layer functions (according to ITU-T I.432)
    - Transmit (Tx) updates
      - Cell HEC generation
      - Payload scrambling using self synchronizing scrambler (programmable by the user)
      - Coset generation (programmable by the user)
      - Cell rate by inserting idle/unassigned cells
    - Receive (Rx) updates
      - Cell delineation using bit by bit HEC checking and programmable ALPHA and DELTA parameters for the delineation state machine
      - Payload descrambling using self synchronizing scrambler (programmable by the user)

- Hot-Swap friendly (supports the Hot Swap Specification as defined by PICMG 2.1 R1.0 August 3, 1998)
- Support for 66 MHz, 3.3 V specification
- 60x-PCI bus core logic which uses a buffer pool to allocate buffers for each port
- Makes use of the local bus signals, so there is no need for additional pins

2 Electrical and Thermal Characteristics

This section provides AC and DC electrical specifications and thermal characteristics for the MPC826xA.

2.1 DC Electrical Characteristics

This section describes the DC electrical characteristics for the MPC826xA. Table 1 shows the maximum electrical ratings.

Table 1. Absolute Maximum Ratings[1]

Rating	Symbol	Value	Unit
Core supply voltage[2]	VDD	–0.3 – 2.5	V
PLL supply voltage[2]	VCCSYN	–0.3 – 2.5	V
I/O supply voltage[3]	VDDH	–0.3 – 4.0	V
Input voltage[4]	VIN	GND(–0.3) – 3.6	V
Junction temperature	T_j	120	°C
Storage temperature range	T_{STG}	(–55) – (+150)	°C

[1] Absolute maximum ratings are stress ratings only; functional operation (see Table 2) at the maximums is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage.

[2] **Caution:** VDD/VCCSYN must not exceed VDDH by more than 0.4 V at any time, including during power-on reset.

[3] **Caution:** VDDH can exceed VDD/VCCSYN by 3.3 V during power on reset by no more than 100 mSec. VDDH should not exceed VDD/VCCSYN by more than 2.5 V during normal operation.

[4] **Caution:** VIN must not exceed VDDH by more than 2.5 V at any time, including during power-on reset.

Table 2 lists recommended operational voltage conditions.

Table 2. Recommended Operating Conditions[1]

Rating	Symbol	Value			Unit
Core supply voltage	VDD	1.7 – 1.9[2]	1.7–2.1[3]	1.9 –2.2[4]	V
PLL supply voltage	VCCSYN	1.7 – 1.9[2]	1.7–2.1[3]	1.9–2.2[4]	V
I/O supply voltage	VDDH	3.135 – 3.465			V
Input voltage	VIN	GND (–0.3) – 3.465			V
Junction temperature (maximum)	T_j	105[5]			°C
Ambient temperature	T_A	0–70[5]			°C

[1] **Caution:** These are the recommended and tested operating conditions. Proper device operating outside of these conditions is not guaranteed.

[2] CPU frequency less than or equal to 200 MHz.

[3] CPU frequency greater than 200 MHz but less than 233 MHz.

[4] CPU frequency greater than or equal to 233 MHz.

[5] Note that for extended temperature parts the range is $(-40)_{T_A} - 105_{T_j}$.

NOTE: Core, PLL, and I/O Supply Voltages

> VDDH, VCCSYN, and VDD must track each other and both must vary in the same direction—in the positive direction (+5% and +0.1 Vdc) or in the negative direction (–5% and –0.1 Vdc).

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (either GND or V_{CC}).

Figure 2 shows the undershoot and overshoot voltage of the 60x and local bus memory interface of the MPC8280. Note that in PCI mode the I/O interface is different.

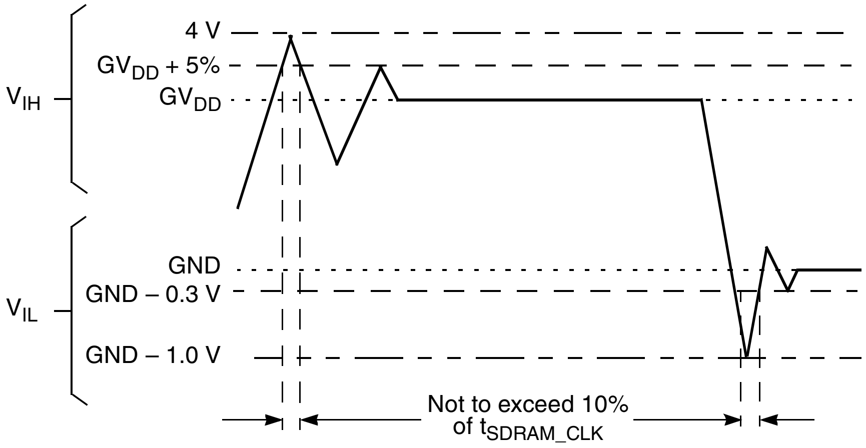


Figure 2. Overshoot/Undershoot Voltage

[2] The leakage current is measured for nominal VDD, VCCSYN, and VDD.
[3] MPC8265 and MPC8266 only.

2.2 Thermal Characteristics

Table 4 describes thermal characteristics.

Table 4. Thermal Characteristics for 480 TBGA Package

Characteristics	Symbol	Value	Unit	Air Flow
Junction to ambient	θ_{JA}	13[1]	°C/W	NC[2]
		10[1]		1 m/s
		11[3]		NC
		8[3]		1 m/s
Junction to board[4]	θ_{JB}	4	°C/W	—
Junction to case[5]	θ_{JC}	1.1	°C/W	—

[1] Assumes a single layer board with no thermal vias
[2] Natural convection
[3] Assumes a four layer board
[4] Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
[5] Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).

2.3 Power Considerations

The average chip-junction temperature, T_J, in °C can be obtained from the following:

$$T_J = T_A + (P_D \times \theta_{JA}) \qquad (1)$$

where

T_A = ambient temperature °C

θ_{JA} = package thermal resistance, junction to ambient, °C/W

$P_D = P_{INT} + P_{I/O}$

$P_{INT} = I_{DD} \times V_{DD}$ Watts (chip internal power)

$P_{I/O}$ = power dissipation on input and output pins (determined by user)

For most applications $P_{I/O} < 0.3 \times P_{INT}$. If $P_{I/O}$ is neglected, an approximate relationship between P_D and T_J is the following:

$$P_D = K/(T_J + 273^\circ\ C) \qquad (2)$$

Solving equations (1) and (2) for K gives:

$$K = P_D \times (T_A + 273^\circ\ C) + \theta_{JA} \times P_D^2 \qquad (3)$$

where K is a constant pertaining to the particular part. K can be determined from equation (3) by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving equations (1) and (2) iteratively for any value of T_A.

2.3.1 Layout Practices

Each V_{CC} pin should be provided with a low-impedance path to the board's power supply. Each ground pin should likewise be provided with a low-impedance path to ground. The power supply pins drive distinct groups of logic on chip. The V_{CC} power supply should be bypassed to ground using at least four 0.1 µF by-pass capacitors located as close as possible to the four sides of the package. The capacitor leads and associated printed circuit traces connecting to chip V_{CC} and ground should be kept to less than half an inch per capacitor lead. A four-layer board is recommended, employing two inner layers as V_{CC} and GND planes.

All output pins on the MPC826xA have fast rise and fall times. Printed circuit (PC) trace interconnection length should be minimized in order to minimize overdamped conditions and reflections caused by these fast output switching times. This recommendation particularly applies to the address and data buses. Maximum PC trace lengths of six inches are recommended. Capacitance calculations should consider all device loads as well as parasitic capacitances due to the PC traces. Attention to proper PCB layout and bypassing becomes especially critical in systems with higher capacitive loads because these loads create higher transient currents in the V_{CC} and GND circuits. Pull up all unused inputs or signals that will be inputs during reset. Special care should be taken to minimize the noise levels on the PLL supply pins.

Table 5 provides preliminary, estimated power dissipation for various configurations. Note that suitable thermal management is required for conditions above P_D = 3 W (when the ambient temperature is 70 °C or greater) to ensure the junction temperature does not exceed the maximum specified value. Also note that the I/O power should be included when determining whether to use a heat sink.

Table 5. Estimated Power Dissipation for Various Configurations[1]

Bus (MHz)	CPM Multiplier	Core CPU Multiplier	CPM (MHz)	CPU (MHz)	P_{INT}(W)[2]			
					Vddl 1.8 Volts		Vddl 2.0 Volts	
					Nominal	Maximum	Nominal	Maximum
66.66	2	3	133	200	1.2	2	1.8	2.3
66.66	2.5	3	166	200	1.3	2.1	1.9	2.3
66.66	3	4	200	266	—	—	2.3	2.9
66.66	3	4.5	200	300	—	—	2.4	3.1
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2.5	3.5	208	291	—	—	2.4	3.1

[1] Test temperature = room temperature (25° C)

[2] $P_{INT} = I_{DD} \times V_{DD}$ Watts

Table 8 lists CPM input characteristics.

Table 8. AC Characteristics for CPM Inputs[1]

Spec Number		Characteristic	Setup (ns)		Hold (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp16a	sp17a	FCC inputs—internal clock (NMSI)	10	8	0	0
sp16b	sp17b	FCC inputs—external clock (NMSI)	3	2.5	3	2
sp20	sp21	TDM inputs/SI	15	12	12	10
sp18a	sp19a	SCC/SMC/SPI/I2C inputs—internal clock (NMSI)	20	16	0	0
sp18b	sp19b	SCC/SMC/SPI/I2C inputs—external clock (NMSI)	5	4	5	4
sp22	sp23	PIO/TIMER/IDMA inputs	10	8	3	3

[1] Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Note that although the specifications generally reference the rising edge of the clock, the following AC timing diagrams also apply when the falling edge is the active edge.

Figure 3 shows the FCC external clock.

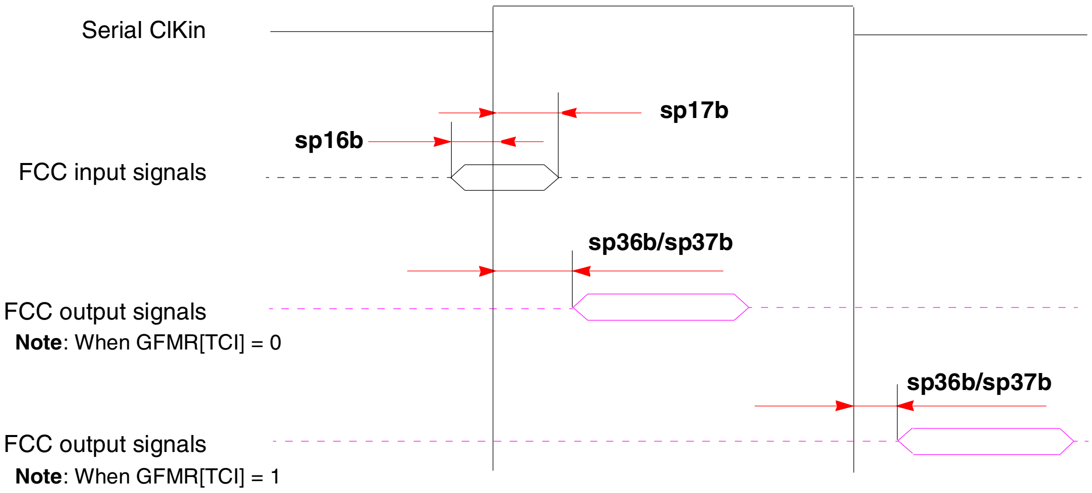


Figure 3. FCC External Clock Diagram

Table 10 lists SIU output characteristics.

Table 10. AC Characteristics for SIU Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp31	sp30	$\overline{\text{PSDVAL}}$/$\overline{\text{TEA}}$/$\overline{\text{TA}}$	7	6	0.5	0.5
sp32	sp30	ADD/ADD_atr./BADDR/CI/GBL/WT	8	6.5	0.5	0.5
sp33a	sp30	Data bus	6.5	6.5	0.5	0.5
sp33b	sp30	DP	8	7	0.5	0.5
sp34	sp30	Memory controller signals/ALE	6	5	0.5	0.5
sp35	sp30	All other signals	6	5.5	0.5	0.5

[1] Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

NOTE

Activating data pipelining (setting BR*x*[DR] in the memory controller) improves the AC timing. When data pipelining is activated, sp12 can be used for data bus setup even when ECC or PARITY are used. Also, sp33a can be used as the AC specification for DP signals.

Figure 11 shows signal behavior in MEMC mode.

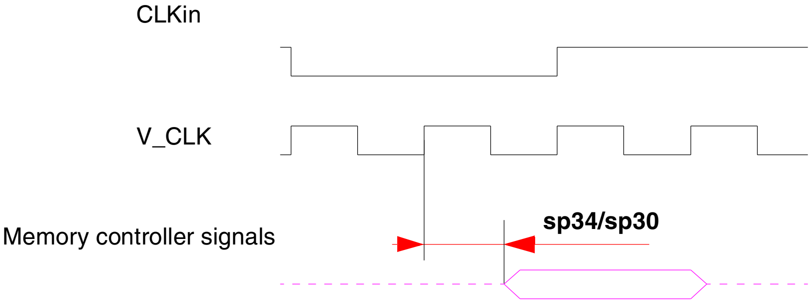


Figure 11. MEMC Mode Diagram

NOTE

Generally, all MPC826xA bus and system output signals are driven from the rising edge of the input clock (CLKin). Memory controller signals, however, trigger on four points within a CLKin cycle. Each cycle is divided by four internal ticks: T1, T2, T3, and T4. T1 always occurs at the rising edge, and T3 at the falling edge, of CLKin. However, the spacing of T2 and T4 depends on the PLL clock ratio selected, as shown in Table 11.

Table 11. Tick Spacing for Memory Controller Signals

PLL Clock Ratio	Tick Spacing (T1 Occurs at the Rising Edge of CLKin)		
	T2	T3	T4
1:2, 1:3, 1:4, 1:5, 1:6	1/4 CLKin	1/2 CLKin	3/4 CLKin
1:2.5	3/10 CLKin	1/2 CLKin	8/10 CLKin
1:3.5	4/14 CLKin	1/2 CLKin	11/14 CLKin

Figure 12 is a graphical representation of Table 11.

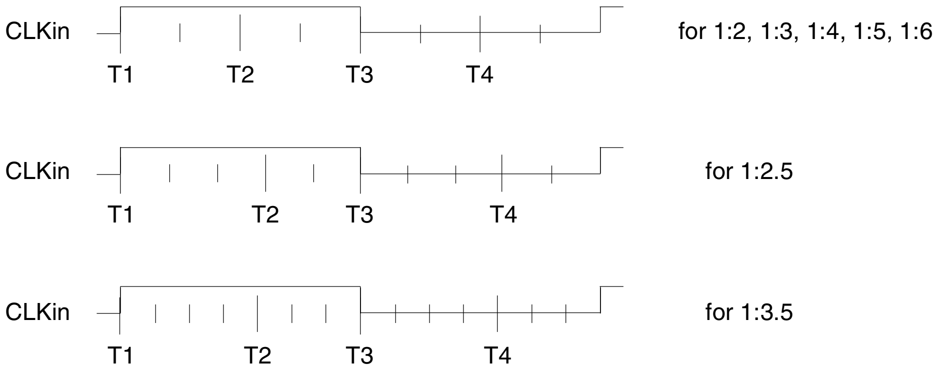


Figure 12. Internal Tick Spacing for Memory Controller Signals

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0001_101	33 MHz	3	100 MHz	4	133 MHz
0001_110	33 MHz	3	100 MHz	5	166 MHz
0001_111	33 MHz	3	100 MHz	6	200 MHz
0010_000	33 MHz	3	100 MHz	7	233 MHz
0010_001	33 MHz	3	100 MHz	8	266 MHz
0010_010	**33 MHz**	**4**	**133 MHz**	**4**	**133 MHz**
0010_011	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**
0010_100	33 MHz	4	133 MHz	6	200 MHz
0010_101	33 MHz	4	133 MHz	7	233 MHz
0010_110	33 MHz	4	133 MHz	8	266 MHz
0010_111	33 MHz	5	166 MHz	4	133 MHz
0011_000	33 MHz	5	166 MHz	5	166 MHz
0011_001	33 MHz	5	166 MHz	6	200 MHz
0011_010	33 MHz	5	166 MHz	7	233 MHz
0011_011	33 MHz	5	166 MHz	8	266 MHz
0011_100	33 MHz	6	200 MHz	4	133 MHz
0011_101	33 MHz	6	200 MHz	5	166 MHz
0011_110	33 MHz	6	200 MHz	6	200 MHz
0011_111	33 MHz	6	200 MHz	7	233 MHz
0100_000	33 MHz	6	200 MHz	8	266 MHz
0100_001	Reserved				
0100_010					
0100_011					
0100_100					
0100_101					
0100_110					

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
1000_001	66 MHz	3.5	233 MHz	3	200 MHz
1000_010	66 MHz	3.5	233 MHz	3.5	233 MHz
1000_011	66 MHz	3.5	233 MHz	4	266 MHz
1000_100	66 MHz	3.5	233 MHz	4.5	300 MHz

[1] Because of speed dependencies, not all of the possible configurations in Table 14 are applicable.

[2] The user should choose the input clock frequency and the multiplication factors such that the frequency of the CPU is equal to or greater than 150 MHz and the CPM ranges between 66–233 MHz.

[3] Input clock frequency is given only for the purpose of reference. The user should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user's part.

3.2 PCI Mode

The MPC8265 and the MPC8266 have three clocking modes: local, PCI host, and PCI agent. The clocking mode is set according to three input pins—PCI_MODE, PCI_CFG[0], PCI_MODCK—as shown in Table 15.

Table 15. MPC8265 and MPC8266 Clocking Modes

Pins			Clocking Mode	PCI Clock Frequency Range (MHZ)
PCI_MODE	PCI_CFG[0]	PCI_MODCK		
1	—	—	Local bus	—
0	0	0	PCI host	50–66
0	0	1		25–50
0	1	0	PCI agent	50–66
0	1	1		25–50

In addition, note the following:

NOTE: PCI_MODCK

In PCI mode only, PCI_MODCK comes from the LGPL5 pin and MODCK_H[0–3] comes from {LGPL0, LGPL1, LGPL2, LGPL3}.

NOTE: Tval (Output Hold)

The minimum Tval = 2 when PCI_MODCK = 1, and the minimum Tval = 1 when PCI_MODCK = 0. Therefore, designers should use clock configurations that fit this condition to achieve PCI-compliant AC timing.

NOTE

Clock configurations change only after $\overline{\text{POR}}$ is asserted.

3.2.1 PCI Host Mode

The frequencies listed in Table 16 and Table 17 are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user’s device.

Table 16. Clock Default Configurations in PCI Host Mode (MODCK_HI = 0000)

MODCK[1–3][1]	Input Clock Frequency (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
000	66 MHz	2	133 MHz	2.5	166 MHz	2/4	66/33 MHz
001	66 MHz	2	133 MHz	3	200 MHz	2/4	66/33 MHz
010	66 MHz	2.5	166 MHz	3	200 MHz	3/6	55/28 MHz
011	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
100	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
101	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
110	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
111	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz

[1] Assumes MODCK_HI = 0000.

[2] The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic ‘1’), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) Refer to Table 15.

Table 17 describes all possible clock configurations when using the MPC8265’s or the MPC8266’s internal PCI bridge in host mode.

Table 17. Clock Configuration Modes in PCI Host Mode

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0001_000	33 MHz	3	100 MHz	5	166 MHz	3/6	33/16 MHz
0001_001	33 MHz	3	100 MHz	6	200 MHz	3/6	33/16 MHz
0001_010	33 MHz	3	100 MHz	7	233 MHz	3/6	33/16 MHz
0001_011	33 MHz	3	100 MHz	8	266 MHz	3/6	33/16 MHz
0010_000	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**	**4/8**	**33/16 MHz**
0010_001	33 MHz	4	133 MHz	6	200 MHz	4/8	33/16 MHz
0010_010	33 MHz	4	133 MHz	7	233 MHz	4/8	33/16 MHz
0010_011	33 MHz	4	133 MHz	8	266 MHz	4/8	33/16 MHz
0011_000[3]	33 MHz	5	166 MHz	5	166 MHz	5	**33 MHz**
0011_001[3]	33 MHz	5	166 MHz	6	200 MHz	5	33 MHz
0011_010[3]	33 MHz	5	166 MHz	7	233 MHz	5	33 MHz

Table 17. Clock Configuration Modes in PCI Host Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0011_011[3]	33 MHz	5	166 MHz	8	266 MHz	5	33 MHz
0100_000[3]	33 MHz	6	200 MHz	5	166 MHz	6	33 MHz
0100_001[3]	33 MHz	6	200 MHz	6	200 MHz	6	33 MHz
0100_010[3]	33 MHz	6	200 MHz	7	233 MHz	6	33 MHz
0100_011[3]	33 MHz	6	200 MHz	8	266 MHz	6	33 MHz
0101_000	**66 MHz**	**2**	**133 MHz**	**2.5**	**166 MHz**	**2/4**	**66/33 MHz**
0101_001	**66 MHz**	**2**	**133 MHz**	**3**	**200 MHz**	**2**/4	**66**/33 **MHz**
0101_010	66 MHz	2	133 MHz	3.5	233 MHz	2/4	66/33 MHz
0101_011	66 MHz	2	133 MHz	4	266 MHz	2/4	66/33 MHz
0101_100	66 MHz	2	133 MHz	4.5	300 MHz	2/4	66/33 MHz
0110_000	**66 MHz**	**2.5**	**166 MHz**	**2.5**	**166 MHz**	3/6	**55/28 MHz**
0110_001	**66 MHz**	**2.5**	**166 MHz**	**3**	**200 MHz**	3/6	55/28 MHz
0110_010	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
0110_011	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
0110_100	66 MHz	2.5	166 MHz	4.5	300 MHz	3/6	55/28 MHz
0111_000	66 MHz	3	200 MHz	2.5	166 MHz	3/6	66/33 MHz
0111_001	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
0111_010	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
0111_011	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz
0111_100	66 MHz	3	200 MHz	4.5	300 MHz	3/6	66/33 MHz
1000_000	66 MHz	3	200 MHz	2.5	166 MHz	4/8	50/25 MHz
1000_001	66 MHz	3	200 MHz	3	200 MHz	4/8	50/25 MHz
1000_010	66 MHz	3	200 MHz	3.5	233 MHz	4/8	50/25 MHz
1000_011	66 MHz	3	200 MHz	4	266 MHz	4/8	50/25 MHz
1000_100	66 MHz	3	200 MHz	4.5	300 MHz	4/8	50/25 MHz
1001_000	66 MHz	3.5	233 MHz	2.5	166 MHz	4/8	58/29 MHz
1001_001	66 MHz	3.5	233 MHz	3	200 MHz	4/8	58/29 MHz

Table 17. Clock Configuration Modes in PCI Host Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
1001_010	66 MHz	3.5	233 MHz	3.5	233 MHz	4/8	58/29 MHz
1001_011	66 MHz	3.5	233 MHz	4	266 MHz	4/8	58/29 MHz
1001_100	66 MHz	3.5	233 MHz	4.5	300 MHz	4/8	58/29 MHz
1010_000	100 MHz	2	200 MHz	2	200 MHz	3/6	66/33 MHz
1010_001	100 MHz	2	200 MHz	2.5	250 MHz	3/6	66/33 MHz
1010_010	100 MHz	2	200 MHz	3	300 MHz	3/6	66/33 MHz
1010_011	100 MHz	2	200 MHz	3.5	350 MHz	3/6	66/33 MHz
1010_100	100 MHz	2	200 MHz	4	400 MHz	3/6	66/33 MHz
1011_000	100 MHz	2.5	250 MHz	2	200 MHz	4/8	62/31 MHz
1011_001	100 MHz	2.5	250 MHz	2.5	250 MHz	4/8	62/31MHz
1011_010	100 MHz	2.5	250 MHz	3	300 MHz	4/8	62/31 MHz
1011_011	100 MHz	2.5	250 MHz	3.5	350 MHz	4/8	62/31 MHz
1011_100	100 MHz	2.5	250 MHz	4	400 MHz	4/8	62/31 MHz

[1] Input clock frequency is given only for the purpose of reference. User should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user’s part.

[2] The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic ‘1’), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.). Refer to Table 15.

[3] In this mode, PCI_MODCK must be “0”.

3.2.2 PCI Agent Mode

The frequencies listed in Table 18 and Table 19 are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user’s device.

Table 18. Clock Default Configurations in PCI Agent Mode (MODCK_HI = 0000)

MODCK[1–3][1]	Input Clock Frequency (PCI)[2]	CPM Multiplication Factor[2]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
000	66/33 MHz	2/4	133 MHz	2.5	166 MHz	2	66 MHz
001	66/33 MHz	2/4	133 MHz	3	200 MHz	2	66 MHz
010	66/33 MHz	3/6	200 MHz	3	200 MHz	3	66 MHz
011	66/33 MHz	3/6	200 MHz	4	266 MHz	3	66 MHz

Table 21. Pinout List (continued)

Pin Name	Ball
D32	E18
D33	B17
D34	A15
D35	A12
D36	D11
D37	C8
D38	E7
D39	A3
D40	D18
D41	A17
D42	A14
D43	B12
D44	A10
D45	D8
D46	B6
D47	C4
D48	C18
D49	E16
D50	B14
D51	C12
D52	B10
D53	A7
D54	C6
D55	D5
D56	B18
D57	B16
D58	E14
D59	D12
D60	C10
D61	E8
D62	D6
D63	C2
DP0/$\overline{\mathrm{RSRV}}$/$\overline{\mathrm{EXT\_BR2}}$	B22
$\overline{\mathrm{IRQ1}}$/DP1/$\overline{\mathrm{EXT\_BG2}}$	A22
$\overline{\mathrm{IRQ2}}$/DP2/$\overline{\mathrm{TLBISYNC}}$/$\overline{\mathrm{EXT\_DBG2}}$	E21

Table 21. Pinout List (continued)

Pin Name	Ball
IRQ3/DP3/CKSTP_OUT/EXT_BR3	D21
IRQ4/DP4/CORE_SRESET/EXT_BG3	C21
IRQ5/DP5/TBEN/EXT_DBG3	B21
IRQ6/DP6/CSE0	A21
IRQ7/DP7/CSE1	E20
PSDVAL	V3
TA	C22
TEA	V5
GBL/IRQ1	W1
CI/BADDR29/IRQ2	U2
WT/BADDR30/IRQ3	U3
L2_HIT/IRQ4	Y4
CPU_BG/BADDR31/IRQ5	U4
CPU_DBG	R2
CPU_BR	Y3
CS0	F25
CS1	C29
CS2	E27
CS3	E28
CS4	F26
CS5	F27
CS6	F28
CS7	G25
CS8	D29
CS9	E29
CS10/BCTL1	F29
CS11/AP0	G28
BADDR27	T5
BADDR28	U1
ALE	T2
BCTL0	A27
PWE0/PSDDQM0/PBS0	C25
PWE1/PSDDQM1/PBS1	E24
PWE2/PSDDQM2/PBS2	D24
PWE3/PSDDQM3/PBS3	C24

Table 21. Pinout List (continued)

Pin Name	Ball
L_A28/$\overline{\text{RST}}$[1]/$\overline{\text{CORE\_SRESET}}$	AB29
L_A29/$\overline{\text{INTA}}$[1]	AB28
L_A30/$\overline{\text{REQ2}}$[1]	P25
L_A31/DLLOUT[1]	AB27
LCL_D0/AD0[1]	H29
LCL_D1/AD1[1]	J29
LCL_D2/AD2[1]	J28
LCL_D3/AD3[1]	J27
LCL_D4/AD4[1]	J26
LCL_D5/AD5[1]	J25
LCL_D6/AD6[1]	K25
LCL_D7/AD7[1]	L29
LCL_D8/AD8[1]	L27
LCL_D9/AD9[1]	L26
LCL_D10/AD10[1]	L25
LCL_D11/AD11[1]	M29
LCL_D12/AD12[1]	M28
LCL_D13/AD13[1]	M27
LCL_D14/AD14[1]	M26
LCL_D15/AD15[1]	N29
LCL_D16/AD16[1]	T25
LCL_D17/AD17[1]	U27
LCL_D18/AD18[1]	U26
LCL_D19/AD19[1]	U25
LCL_D20/AD20[1]	V29
LCL_D21/AD21[1]	V28
LCL_D22/AD22[1]	V27
LCL_D23/AD23[1]	V26
LCL_D24/AD24[1]	W27
LCL_D25/AD25[1]	W26
LCL_D26/AD26[1]	W25
LCL_D27/AD27[1]	Y29
LCL_D28/AD28[1]	Y28
LCL_D29/AD29[1]	Y25
LCL_D30/AD30[1]	AA29

Table 21. Pinout List (continued)

Pin Name	Ball
LCL_D31/AD31[1]	AA28
LCL_DP0/C0[1]/BE0[1]	L28
LCL_DP1/C1[1]/BE1[1]	N28
LCL_DP2/C2[1]/BE2[1]	T28
LCL_DP3/C3[1]/BE3[1]	W28
IRQ0/NMI_OUT	T1
IRQ7/INT_OUT/APE	D1
TRST	AH3
TCK	AG5
TMS	AJ3
TDI	AE6
TDO	AF5
TRIS	AB4
PORESET	AG6
HRESET	AH5
SRESET	AF6
QREQ	AA3
RSTCONF	AJ4
MODCK1/AP1/TC0/BNKSEL0	W2
MODCK2/AP2/TC1/BNKSEL1	W3
MODCK3/AP3/TC2/BNKSEL2	W4
XFC	AB2
CLKIN1	AH4
PA0/RESTART1/DREQ3/FCC2_UTM_TXADDR2	AC29[2]
PA1/REJECT1/FCC2_UTM_TXADDR1/DONE3	AC25[2]
PA2/CLK20/FCC2_UTM_TXADDR0/DACK3	AE28[2]
PA3/CLK19/FCC2_UTM_RXADDR0/DACK4/L1RXD1A2	AG29[2]
PA4/REJECT2/FCC2_UTM_RXADDR1/DONE4	AG28[2]
PA5/RESTART2/DREQ4/FCC2_UTM_RXADDR2	AG26[2]
PA6/L1RSYNCA1	AE24[2]
PA7/SMSYN2/L1TSYNCA1/L1GNTA1	AH25[2]
PA8/SMRXD2/L1RXD0A1/L1RXDA1	AF23[2]
PA9/SMTXD2/L1TXD0A1	AH23[2]
PA10/FCC1_UT8_RXD0/FCC1_UT16_RXD8/MSNUM5	AE22[2]
PA11/FCC1_UT8_RXD1/FCC1_UT16_RXD9/MSNUM4	AH22[2]

Table 21. Pinout List (continued)

Pin Name	Ball
PA12/FCC1_UT8_RXD2/FCC1_UT16_RXD10/MSNUM3	AJ21[2]
PA13/FCC1_UT8_RXD3/FCC1_UT16_RXD11/MSNUM2	AH20[2]
PA14/FCC1_UT8_RXD4/FCC1_UT16_RXD12/FCC1_RXD3	AG19[2]
PA15/FCC1_UT8_RXD5/FCC1_UT16_RXD13/FCC1_RXD2	AF18[2]
PA16/FCC1_UT8_RXD6/FCC1_UT16_RXD14/FCC1_RXD1	AF17[2]
PA17/FCC1_UT8_RXD7/FCC1_UT16_RXD15/FCC1_RXD0/FCC1_RXD	AE16[2]
PA18/FCC1_UT8_TXD7/FCC1_UT16_TXD15/FCC1_TXD0/FCC1_TXD	AJ16[2]
PA19/FCC1_UT8_TXD6/FCC1_UT16_TXD14/FCC1_TXD1	AG15[2]
PA20/FCC1_UT8_TXD5/FCC1_UT16_TXD13/FCC1_TXD2	AJ13[2]
PA21/FCC1_UT8_TXD4/FCC1_UT16_TXD12/FCC1_TXD3	AE13[2]
PA22/FCC1_UT8_TXD3/FCC1_UT16_TXD11	AF12[2]
PA23/FCC1_UT8_TXD2/FCC1_UT16_TXD10	AG11[2]
PA24/FCC1_UT8_TXD1/FCC1_UT16_TXD9/MSNUM1	AH9[2]
PA25/FCC1_UT8_TXD0/FCC1_UT16_TXD8/MSNUM0	AJ8[2]
PA26/FCC1_UTM_RXCLAV/FCC1_UTS_RXCLAV/FCC1_MII_RX_ER	AH7[2]
PA27/FCC1_UT_RXSOC/FCC1_MII_RX_DV	AF7[2]
PA28/FCC1_UTM_RXENB/FCC1_UTS_RXENB/FCC1_MII_TX_EN	AD5[2]
PA29/FCC1_UT_TXSOC/FCC1_MII_TX_ER	AF1[2]
PA30/FCC1_UTM_TXCLAV/FCC1_UTS_TXCLAV/FCC1_MII_CRS/ FCC1_RTS	AD3[2]
PA31/FCC1_UTM_TXENB/FCC1_UTS_TXENB/FCC1_MII_COL	AB5[2]
PB4/FCC3_TXD3/FCC2_UT8_RXD0/L1RSYNCA2/FCC3_RTS	AD28[2]
PB5/FCC3_TXD2/FCC2_UT8_RXD1/L1TSYNCA2/L1GNTA2	AD26[2]
PB6/FCC3_TXD1/FCC2_UT8_RXD2/L1RXDA2/L1RXD0A2	AD25[2]
PB7/FCC3_TXD0/FCC3_TXD/FCC2_UT8_RXD3/L1TXDA2/L1TXD0A2	AE26[2]
PB8/FCC2_UT8_TXD3/FCC3_RXD0/FCC3_RXD/TXD3/L1RSYNCD1	AH27[2]
PB9/FCC2_UT8_TXD2/FCC3_RXD1/L1TXD2A2/L1TSYNCD1/L1GNTD1	AG24[2]
PB10/FCC2_UT8_TXD1/FCC3_RXD2/L1RXDD1	AH24[2]
PB11/FCC3_RXD3/FCC2_UT8_TXD0/L1TXDD1	AJ24[2]
PB12/FCC3_MII_CRS/L1CLKOB1/L1RSYNCC1/TXD2	AG22[2]
PB13/FCC3_MII_COL/L1RQB1/L1TSYNCC1/L1GNTC1/L1TXD1A2	AH21[2]
PB14/FCC3_MII_TX_EN/RXD3/L1RXDC1	AG20[2]
PB15/FCC3_MII_TX_ER/RXD2/L1TXDC1	AF19[2]
PB16/FCC3_MII_RX_ER/L1CLKOA1/CLK18	AJ18[2]
PB17/FCC3_MII_RX_DV/L1RQA1/CLK17	AJ17[2]

6 Ordering Information

Figure 16 provides an example of the Freescale part numbering nomenclature for the MPC826xA. In addition to the processor frequency, the part numbering scheme also consists of a part modifier that indicates any enhancement(s) in the part from the original production design. Each part number also contains a revision code that refers to the die mask revision number and is specified in the part numbering scheme for identification purposes only. For more information, contact your local Freescale sales office.

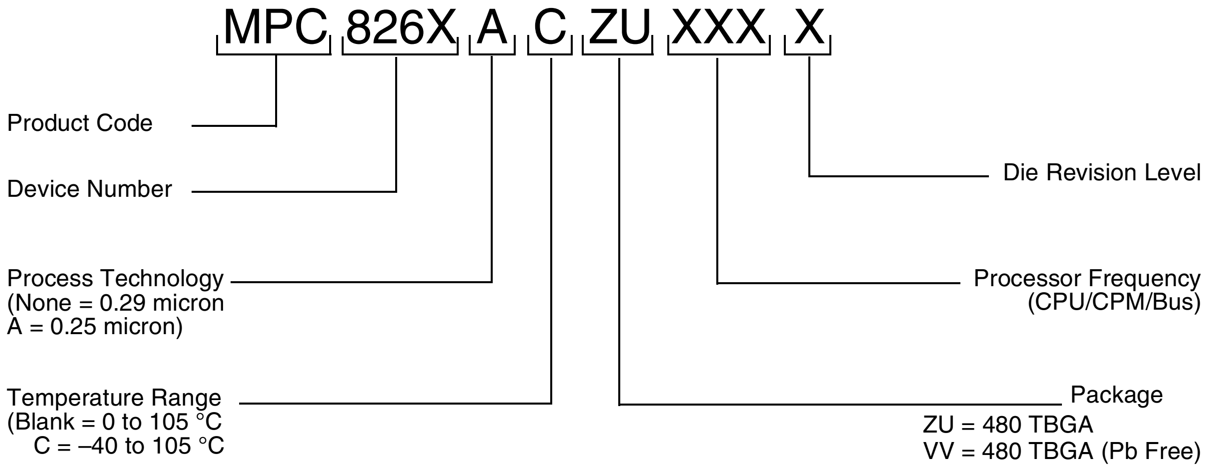


Figure 16. Freescale Part Number Key

7 Document Revision History

Table 23 lists significant changes in each revision of this document.

Table 23. Document Revision History

Revision	Date	Substantive Changes
2	06/2009	• Updated package values in Figure 16.
1.1	02/2006	• Addition of Table 12.
1.0	9/2005	• Document template update