MPC8260

Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details

Product Status	Obsolete
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	300MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/kmpc8260azupjdb

— 32-bit address decodes with programmable bank size

— Three user programmable machines, general-purpose chip-select machine, and page-mode pipeline SDRAM machine

— Byte selects for 64 bus width (60x) and byte selects for 32 bus width (local)

— Dedicated interface logic for SDRAM

- CPU core can be disabled and the device can be used in slave mode to an external core

- Communications processor module (CPM)

  — Embedded 32-bit communications processor (CP) uses a RISC architecture for flexible support for communications protocols

  — Interfaces to G2 core through on-chip 32-Kbyte dual-port RAM and DMA controller

  — Serial DMA channels for receive and transmit on all serial channels

  — Parallel I/O registers with open-drain and interrupt capability

  — Virtual DMA functionality executing memory-to-memory and memory-to-I/O transfers

  — Three fast communications controllers supporting the following protocols (only FCC1 and FCC2 on the MPC8255):

    – 10/100-Mbit Ethernet/IEEE Std. 802.3® CDMA/CS interface through media independent interface (MII)

    – ATM—Full-duplex SAR protocols at 155 Mbps, through UTOPIA interface, AAL5, AAL1, AAL0 protocols, TM 4.0 CBR, VBR, UBR, ABR traffic types, up to 16 K external connections

    – Transparent

    – HDLC—Up to T3 rates (clear channel)

  — Two multichannel controllers (MCCs) (only MCC2 on the MPC8255)

    – Each MCC handles 128 serial, full-duplex, 64-Kbps data channels.Each MCC can be split into four subgroups of 32 channels each.

    – Almost any combination of subgroups can be multiplexed to single or multiple TDM interfaces up to four TDM interfaces per MCC

  — Four serial communications controllers (SCCs) identical to those on the MPC860, supporting the digital portions of the following protocols:

    – Ethernet/IEEE 802.3 CDMA/CS

    – HDLC/SDLC and HDLC bus

    – Universal asynchronous receiver transmitter (UART)

    – Synchronous UART

    – Binary synchronous (BISYNC) communications

    – Transparent

  — Two serial management controllers (SMCs), identical to those of the MPC860

    – Provide management for BRI devices as general circuit interface (GCI) controllers in time-division-multiplexed (TDM) channels

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- – Transparent
- – UART (low-speed operation)
— One serial peripheral interface identical to the MPC860 SPI
— One inter-integrated circuit (I^2C) controller (identical to the MPC860 I^2C controller)
  - – Microwire compatible
  - – Multiple-master, single-master, and slave modes
— Up to eight TDM interfaces (four on the MPC8255)
  - – Supports two groups of four TDM channels for a total of eight TDMs
  - – 2,048 bytes of SI RAM
  - – Bit or byte resolution
  - – Independent transmit and receive routing, frame synchronization
  - – Supports T1, CEPT, T1/E1, T3/E3, pulse code modulation highway, ISDN basic rate, ISDN primary rate, Freescale interchip digital link (IDL), general circuit interface (GCI), and user-defined TDM serial interfaces
— Eight independent baud rate generators and 20 input clock pins for supplying clocks to FCCs, SCCs, SMCs, and serial channels
— Four independent 16-bit timers that can be interconnected as two 32-bit timers

Additional features of the MPC826xA family are as follows:

- • CPM
  - — 32-Kbyte dual-port RAM
  - — Additional MCC host commands
  - — Eight transfer transmission convergence (TC) layers between the TDMs and FCC2 to support inverse multiplexing for ATM capabilities (IMA) (MPC8264 and MPC8266 only)
- • CPM multiplexing
  - — FCC2 can also be connected to the TC layer.
- • TC layer (MPC8264 and MPC8266 only)
  - — Each of the 8 TDM channels is routed in hardware to a TC layer block
    - – Protocol-specific overhead bits may be discarded or routed to other controllers by the SI
    - – Performing ATM TC layer functions (according to ITU-T I.432)
    - – Transmit (Tx) updates
      - - Cell HEC generation
      - - Payload scrambling using self synchronizing scrambler (programmable by the user)
      - - Coset generation (programmable by the user)
      - - Cell rate by inserting idle/unassigned cells
    - – Receive (Rx) updates
      - - Cell delineation using bit by bit HEC checking and programmable ALPHA and DELTA parameters for the delineation state machine
      - - Payload descrambling using self synchronizing scrambler (programmable by the user)

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— Hot-Swap friendly (supports the Hot Swap Specification as defined by PICMG 2.1 R1.0 August 3, 1998)

— Support for 66 MHz, 3.3 V specification

— 60x-PCI bus core logic which uses a buffer pool to allocate buffers for each port

— Makes use of the local bus signals, so there is no need for additional pins

2 Electrical and Thermal Characteristics

This section provides AC and DC electrical specifications and thermal characteristics for the MPC826xA.

2.1 DC Electrical Characteristics

This section describes the DC electrical characteristics for the MPC826xA. Table 1 shows the maximum electrical ratings.

Table 1. Absolute Maximum Ratings[1]

Rating	Symbol	Value	Unit
Core supply voltage[2]	VDD	–0.3 – 2.5	V
PLL supply voltage[2]	VCCSYN	–0.3 – 2.5	V
I/O supply voltage[3]	VDDH	–0.3 – 4.0	V
Input voltage[4]	VIN	GND(–0.3) – 3.6	V
Junction temperature	T_j	120	°C
Storage temperature range	T_{STG}	(–55) – (+150)	°C

[1] Absolute maximum ratings are stress ratings only; functional operation (see Table 2) at the maximums is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage.

[2] **Caution:** VDD/VCCSYN must not exceed VDDH by more than 0.4 V at any time, including during power-on reset.

[3] **Caution:** VDDH can exceed VDD/VCCSYN by 3.3 V during power on reset by no more than 100 mSec. VDDH should not exceed VDD/VCCSYN by more than 2.5 V during normal operation.

[4] **Caution:** VIN must not exceed VDDH by more than 2.5 V at any time, including during power-on reset.

where K is a constant pertaining to the particular part. K can be determined from equation (3) by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving equations (1) and (2) iteratively for any value of T_A.

2.3.1 Layout Practices

Each V_{CC} pin should be provided with a low-impedance path to the board's power supply. Each ground pin should likewise be provided with a low-impedance path to ground. The power supply pins drive distinct groups of logic on chip. The V_{CC} power supply should be bypassed to ground using at least four 0.1 µF by-pass capacitors located as close as possible to the four sides of the package. The capacitor leads and associated printed circuit traces connecting to chip V_{CC} and ground should be kept to less than half an inch per capacitor lead. A four-layer board is recommended, employing two inner layers as V_{CC} and GND planes.

All output pins on the MPC826xA have fast rise and fall times. Printed circuit (PC) trace interconnection length should be minimized in order to minimize overdamped conditions and reflections caused by these fast output switching times. This recommendation particularly applies to the address and data buses. Maximum PC trace lengths of six inches are recommended. Capacitance calculations should consider all device loads as well as parasitic capacitances due to the PC traces. Attention to proper PCB layout and bypassing becomes especially critical in systems with higher capacitive loads because these loads create higher transient currents in the V_{CC} and GND circuits. Pull up all unused inputs or signals that will be inputs during reset. Special care should be taken to minimize the noise levels on the PLL supply pins.

Table 5 provides preliminary, estimated power dissipation for various configurations. Note that suitable thermal management is required for conditions above $P_D = 3$ W (when the ambient temperature is 70 °C or greater) to ensure the junction temperature does not exceed the maximum specified value. Also note that the I/O power should be included when determining whether to use a heat sink.

Table 5. Estimated Power Dissipation for Various Configurations[1]

| Bus (MHz) | CPM Multiplier | Core CPU Multiplier | CPM (MHz) | CPU (MHz) | P_{INT}(W)[2] | | | |
| | | | | | Vddl 1.8 Volts | | Vddl 2.0 Volts | |
					Nominal	Maximum	Nominal	Maximum
66.66	2	3	133	200	1.2	2	1.8	2.3
66.66	2.5	3	166	200	1.3	2.1	1.9	2.3
66.66	3	4	200	266	—	—	2.3	2.9
66.66	3	4.5	200	300	—	—	2.4	3.1
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2.5	3.5	208	291	—	—	2.4	3.1

[1] Test temperature = room temperature (25° C)

[2] $P_{INT} = I_{DD}$ x V_{DD} Watts

2.4 AC Electrical Characteristics

The following sections include illustrations and tables of clock diagrams, signals, and CPM outputs and inputs for the 66 MHz MPC826xA device. Note that AC timings are based on a 50-p*f* load. Typical output buffer impedances are shown in Table 6.

Table 6. Output Buffer Impedances[1]

Output Buffers	Typical Impedance (Ω)
60x bus	40
Local bus	40
Memory controller	40
Parallel I/O	46
PCI	25

[1] These are typical values at 65° C. The impedance may vary by ±25% with process and temperature.

Table 7 lists CPM output characteristics.

Table 7. AC Characteristics for CPM Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp36a	sp37a	FCC outputs—internal clock (NMSI)	6	5.5	1	1
sp36b	sp37b	FCC outputs—external clock (NMSI)	14	12	2	1
sp40	sp41	TDM outputs/SI	25	16	5	4
sp38a	sp39a	SCC/SMC/SPI/I2C outputs—internal clock (NMSI)	19	16	1	0.5
sp38b	sp39b	Ex_SCC/SMC/SPI/I2C outputs—external clock (NMSI)	19	16	2	1
sp42	sp43	TIMER/IDMA outputs	14	11	1	0.5
sp42a	sp43a	PIO outputs	14	11	0.5	0.5

[1] Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

Figure 4 shows the FCC internal clock.

Figure 4. FCC Internal Clock Diagram

Figure 5 shows the SCC/SMC/SPI/I^{2}C external clock.

Note: There are four possible timing conditions for SCC and SPI:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.
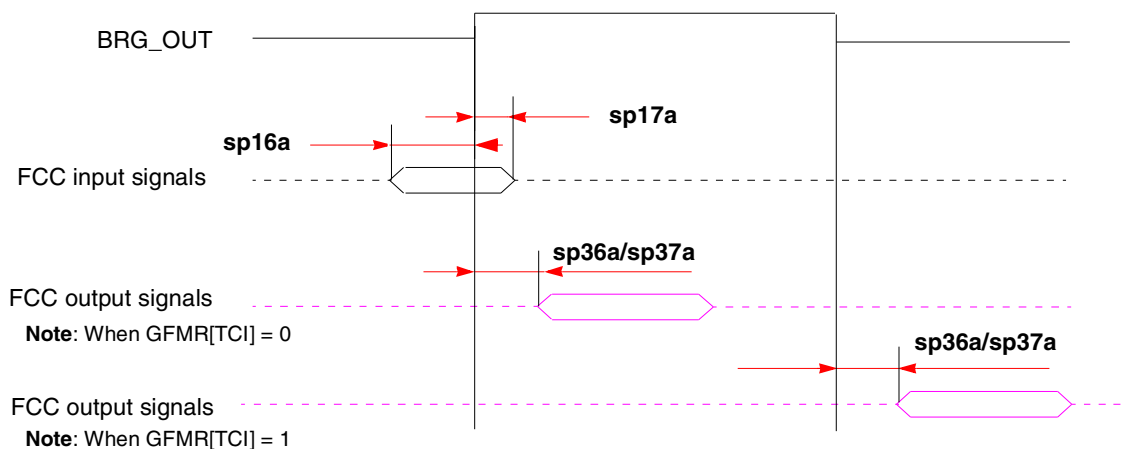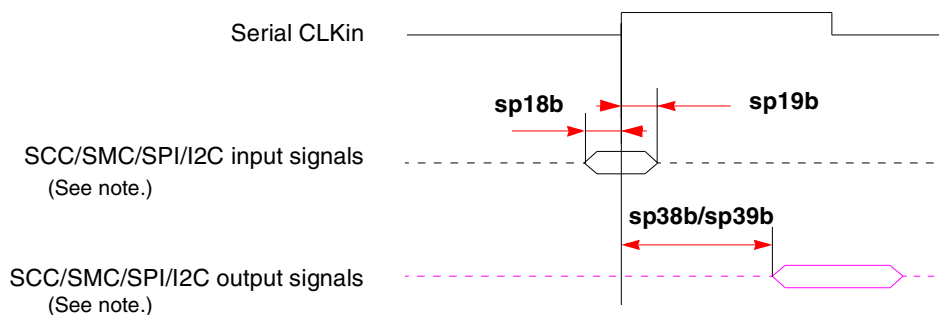
Figure 5. SCC/SMC/SPI/I^{2}C External Clock Diagram

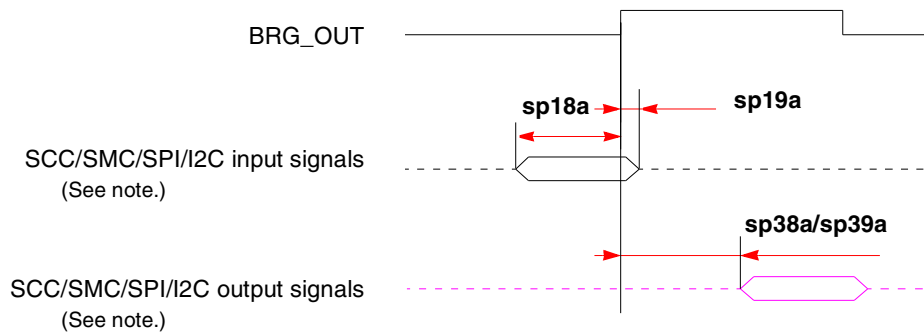Figure 6 shows the SCC/SMC/SPI/I^{2}C internal clock.

Note: There are four possible timing conditions for SCC and SPI:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 6. SCC/SMC/SPI/I^{2}C Internal Clock Diagram

Figure 7 shows TDM input and output signals.

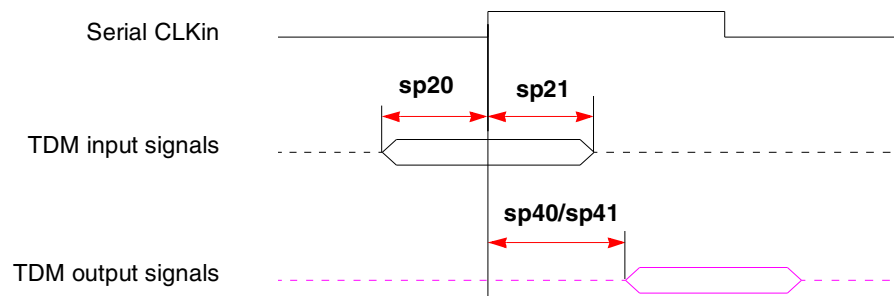**Note**: There are four possible TDM timing conditions:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 7. TDM Signal Diagram

Table 10 lists SIU output characteristics.

Table 10. AC Characteristics for SIU Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp31	sp30	PSDVAL/TEA/TA	7	6	0.5	0.5
sp32	sp30	ADD/ADD_atr./BADDR/CI/GBL/WT	8	6.5	0.5	0.5
sp33a	sp30	Data bus	6.5	6.5	0.5	0.5
sp33b	sp30	DP	8	7	0.5	0.5
sp34	sp30	Memory controller signals/ALE	6	5	0.5	0.5
sp35	sp30	All other signals	6	5.5	0.5	0.5

[1] Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

NOTE

Activating data pipelining (setting BRx[DR] in the memory controller) improves the AC timing. When data pipelining is activated, sp12 can be used for data bus setup even when ECC or PARITY are used. Also, sp33a can be used as the AC specification for DP signals.

Figure 11 shows signal behavior in MEMC mode.
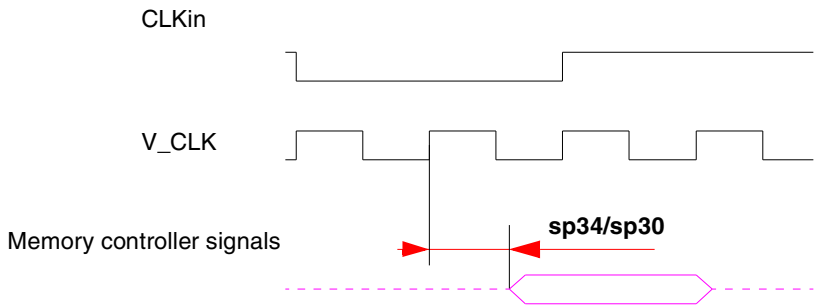
Figure 11. MEMC Mode Diagram

NOTE

Generally, all MPC826xA bus and system output signals are driven from the rising edge of the input clock (CLKin). Memory controller signals, however, trigger on four points within a CLKin cycle. Each cycle is divided by four internal ticks: T1, T2, T3, and T4. T1 always occurs at the rising edge, and T3 at the falling edge, of CLKin. However, the spacing of T2 and T4 depends on the PLL clock ratio selected, as shown in Table 11.

Table 11. Tick Spacing for Memory Controller Signals

PLL Clock Ratio	Tick Spacing (T1 Occurs at the Rising Edge of CLKin)		
	T2	T3	T4
1:2, 1:3, 1:4, 1:5, 1:6	1/4 CLKin	1/2 CLKin	3/4 CLKin
1:2.5	3/10 CLKin	1/2 CLKin	8/10 CLKin
1:3.5	4/14 CLKin	1/2 CLKin	11/14 CLKin

Figure 12 is a graphical representation of Table 11.

Figure 12. Internal Tick Spacing for Memory Controller Signals

Table 12 lists the JTAG timings.

Table 12. JTAG Timings[1]

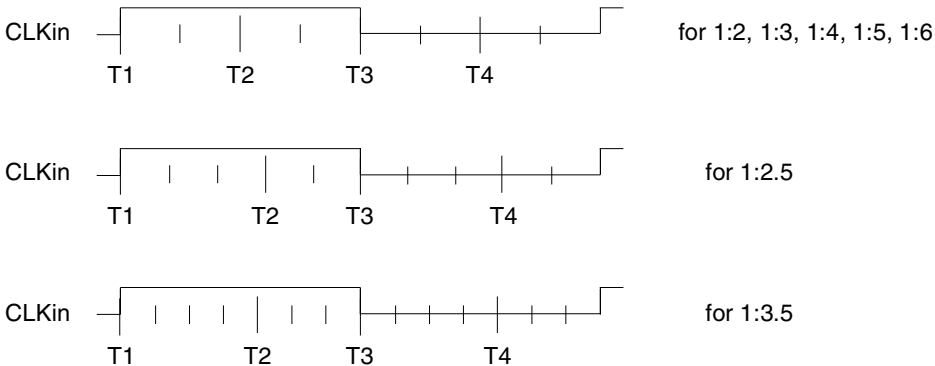| Parameter	Symbol[2]	Min	Max	Unit	Notes
JTAG external clock frequency of operation	f_{JTG}	0	25	MHz	—
JTAG external clock cycle time	t_{JTG}	40	—	ns	—
JTAG external clock pulse width measured at 1.4V	t_{JTKHKL}	20	—	ns	—
JTAG external clock rise and fall times	t_{JTGR} and t_{JTGF}	0	5	ns	6
TRST assert time	t_{TRST}	25	—	ns	3, 6
Input setup times Boundary-scan data	t_{JTDVKH}	4	—	ns	4, 7
TMS, TDI	t_{JTIVKH}	4	—	ns	4, 7
Input hold times Boundary-scan data	t_{JTDXKH}	10	—	ns	4, 7
TMS, TDI	t_{JTIXKH}	10	—	ns	4, 7
Output valid times Boundary-scan data	t_{JTKLDV}	—	25	ns	5, 7
TDO	t_{JTKLOV}	—	25	ns	5. 7
Output hold times Boundary-scan data	t_{JTKLDX}	1	—	ns	5, 7
TDO	t_{JTKLOX}	1	—	ns	5, 7
JTAG external clock to output high impedance Boundary-scan data	t_{JTKLDZ}	1	25	ns	5, 6
TDO	t_{JTKLOZ}	1	25	ns	5, 6

[1] All outputs are measured from the midpoint voltage of the falling/rising edge of t_{TCLK} to the midpoint of the signal in question. The output timings are measured at the pins. All output timings assume a purely resistive 50-Ω load. Time-of-flight delays must be added for trace lengths, vias, and connectors in the system.

[2] The symbols used for timing specifications herein follow the pattern of $t_{(first\ two\ letters\ of\ functional\ block)(signal)(state)(reference)(state)}$ for inputs and $t_{((first\ two\ letters\ of\ functional\ block)(reference)(state)(signal)(state)}$ for outputs. For example, t_{JTDVKH} symbolizes JTAG device timing (JT) with respect to the time data input signals (D) reaching the valid state (V) relative to the t_{JTG} clock reference (K) going to the high (H) state or setup time. Also, t_{JTDXKH} symbolizes JTAG timing (JT) with respect to the time data input signals (D) went invalid (X) relative to the t_{JTG} clock reference (K) going to the high (H) state. Note that, in general, the clock reference symbol representation is based on three letters representing the clock of a particular functional. For rise and fall times, the latter convention is used with the appropriate letter: R (rise) or F (fall).

[3] TRST is an asynchronous level sensitive signal. The setup time is for test purposes only.

[4] Non-JTAG signal input timing with respect to t_{TCLK}.

[5] Non-JTAG signal output timing with respect to t_{TCLK}.

[6] Guaranteed by design.

[7] Guaranteed by design and device characterization.

NOTE

The UPM machine outputs change on the internal tick determined by the memory controller programming; the AC specifications are relative to the internal tick. Note that SDRAM and GPCM machine outputs change on CLKin's rising edge.

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0001_101	33 MHz	3	100 MHz	4	133 MHz
0001_110	33 MHz	3	100 MHz	5	166 MHz
0001_111	33 MHz	3	100 MHz	6	200 MHz
0010_000	33 MHz	3	100 MHz	7	233 MHz
0010_001	33 MHz	3	100 MHz	8	266 MHz
0010_010	**33 MHz**	**4**	**133 MHz**	**4**	**133 MHz**
0010_011	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**
0010_100	33 MHz	4	133 MHz	6	200 MHz
0010_101	33 MHz	4	133 MHz	7	233 MHz
0010_110	33 MHz	4	133 MHz	8	266 MHz
0010_111	33 MHz	5	166 MHz	4	133 MHz
0011_000	33 MHz	5	166 MHz	5	166 MHz
0011_001	33 MHz	5	166 MHz	6	200 MHz
0011_010	33 MHz	5	166 MHz	7	233 MHz
0011_011	33 MHz	5	166 MHz	8	266 MHz
0011_100	33 MHz	6	200 MHz	4	133 MHz
0011_101	33 MHz	6	200 MHz	5	166 MHz
0011_110	33 MHz	6	200 MHz	6	200 MHz
0011_111	33 MHz	6	200 MHz	7	233 MHz
0100_000	33 MHz	6	200 MHz	8	266 MHz
0100_001	Reserved				
0100_010					
0100_011					
0100_100					
0100_101					
0100_110					

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Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0100_111	Reserved				
0101_000					
0101_001					
0101_010					
0101_011					
0101_100					
0101_101	66 MHz	2	133 MHz	2	133 MHz
0101_110	**66 MHz**	**2**	**133 MHz**	**2.5**	**166 MHz**
0101_111	**66 MHz**	**2**	**133 MHz**	**3**	**200 MHz**
0110_000	66 MHz	2	133 MHz	3.5	233 MHz
0110_001	66 MHz	2	133 MHz	4	266 MHz
0110_010	66 MHz	2	133 MHz	4.5	300 MHz
0110_011	66 MHz	2.5	166 MHz	2	133 MHz
0110_100	**66 MHz**	**2.5**	**166 MHz**	**2.5**	**166 MHz**
0110_101	**66 MHz**	**2.5**	**166 MHz**	**3**	**200 MHz**
0110_110	66 MHz	2.5	166 MHz	3.5	233 MHz
0110_111	66 MHz	2.5	166 MHz	4	266 MHz
0111_000	66 MHz	2.5	166 MHz	4.5	300 MHz
0111_001	66 MHz	3	200 MHz	2	133 MHz
0111_010	66 MHz	3	200 MHz	2.5	166 MHz
0111_011	66 MHz	3	200 MHz	3	200 MHz
0111_100	66 MHz	3	200 MHz	3.5	233 MHz
0111_101	66 MHz	3	200 MHz	4	266 MHz
0111_110	66 MHz	3	200 MHz	4.5	300 MHz
0111_111	66 MHz	3.5	233 MHz	2	133 MHz
1000_000	66 MHz	3.5	233 MHz	2.5	166 MHz

3.2.1 PCI Host Mode

The frequencies listed in Table 16 and Table 17 are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user's device.

Table 16. Clock Default Configurations in PCI Host Mode (MODCK_HI = 0000)

MODCK[1–3][1]	Input Clock Frequency (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
000	66 MHz	2	133 MHz	2.5	166 MHz	2/4	66/33 MHz
001	66 MHz	2	133 MHz	3	200 MHz	2/4	66/33 MHz
010	66 MHz	2.5	166 MHz	3	200 MHz	3/6	55/28 MHz
011	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
100	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
101	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
110	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
111	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz

[1] Assumes MODCK_HI = 0000.

[2] The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic '1'), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) Refer to Table 15.

Table 17 describes all possible clock configurations when using the MPC8265's or the MPC8266's internal PCI bridge in host mode.

Table 17. Clock Configuration Modes in PCI Host Mode

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0001_000	33 MHz	3	100 MHz	5	166 MHz	3/6	33/16 MHz
0001_001	33 MHz	3	100 MHz	6	200 MHz	3/6	33/16 MHz
0001_010	33 MHz	3	100 MHz	7	233 MHz	3/6	33/16 MHz
0001_011	33 MHz	3	100 MHz	8	266 MHz	3/6	33/16 MHz
0010_000	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**	**4/8**	**33**/16 **MHz**
0010_001	33 MHz	4	133 MHz	6	200 MHz	4/8	33/16 MHz
0010_010	33 MHz	4	133 MHz	7	233 MHz	4/8	33/16 MHz
0010_011	33 MHz	4	133 MHz	8	266 MHz	4/8	33/16 MHz
0011_000[3]	33 MHz	5	166 MHz	5	166 MHz	5	**33 MHz**
0011_001[3]	33 MHz	5	166 MHz	6	200 MHz	5	33 MHz
0011_010[3]	33 MHz	5	166 MHz	7	233 MHz	5	33 MHz

Table 17. Clock Configuration Modes in PCI Host Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0011_011[3]	33 MHz	5	166 MHz	8	266 MHz	5	33 MHz
0100_000[3]	33 MHz	6	200 MHz	5	166 MHz	6	33 MHz
0100_001[3]	33 MHz	6	200 MHz	6	200 MHz	6	33 MHz
0100_010[3]	33 MHz	6	200 MHz	7	233 MHz	6	33 MHz
0100_011[3]	33 MHz	6	200 MHz	8	266 MHz	6	33 MHz
0101_000	**66 MHz**	**2**	**133 MHz**	**2.5**	**166 MHz**	**2/4**	**66/33 MHz**
0101_001	**66 MHz**	**2**	**133 MHz**	**3**	**200 MHz**	**2/4**	**66**/33 **MHz**
0101_010	66 MHz	2	133 MHz	3.5	233 MHz	2/4	66/33 MHz
0101_011	66 MHz	2	133 MHz	4	266 MHz	2/4	66/33 MHz
0101_100	66 MHz	2	133 MHz	4.5	300 MHz	2/4	66/33 MHz
0110_000	**66 MHz**	**2.5**	**166 MHz**	**2.5**	**166 MHz**	**3/6**	**55/28 MHz**
0110_001	**66 MHz**	**2.5**	**166 MHz**	**3**	**200 MHz**	**3/6**	55/28 MHz
0110_010	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
0110_011	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
0110_100	66 MHz	2.5	166 MHz	4.5	300 MHz	3/6	55/28 MHz
0111_000	66 MHz	3	200 MHz	2.5	166 MHz	3/6	66/33 MHz
0111_001	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
0111_010	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
0111_011	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz
0111_100	66 MHz	3	200 MHz	4.5	300 MHz	3/6	66/33 MHz
1000_000	66 MHz	3	200 MHz	2.5	166 MHz	4/8	50/25 MHz
1000_001	66 MHz	3	200 MHz	3	200 MHz	4/8	50/25 MHz
1000_010	66 MHz	3	200 MHz	3.5	233 MHz	4/8	50/25 MHz
1000_011	66 MHz	3	200 MHz	4	266 MHz	4/8	50/25 MHz
1000_100	66 MHz	3	200 MHz	4.5	300 MHz	4/8	50/25 MHz
1001_000	66 MHz	3.5	233 MHz	2.5	166 MHz	4/8	58/29 MHz
1001_001	66 MHz	3.5	233 MHz	3	200 MHz	4/8	58/29 MHz

Table 19. Clock Configuration Modes in PCI Agent Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency (PCI)[1,2]	CPM Multiplication Factor[1]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
1010_001	66/33 MHz	4/8	266 MHz	3	266 MHz	3	88 MHz
1010_010	66/33 MHz	4/8	266 MHz	3.5	300 MHz	3	88 MHz
1010_011	66/33 MHz	4/8	266 MHz	4	350 MHz	3	88 MHz
1010_100	66/33 MHz	4/8	266 MHz	4.5	400 MHz	3	88 MHz
1011_000	66/33 MHz	4/8	266 MHz	2	212MHz	2.5	106 MHz
1011_001	66/33 MHz	4/8	266 MHz	2.5	265 MHz	2.5	106 MHz
1011_010	66/33 MHz	4/8	266 MHz	3	318 MHz	2.5	106 MHz
1011_011	66/33 MHz	4/8	266 MHz	3.5	371 MHz	2.5	106 MHz
1011_100	66/33 MHz	4/8	266 MHz	4	424 MHz	2.5	106 MHz

[1] The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic '1'), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) and the CPM multiplication factor is multiplied by 2. Refer to Table 15.

[2] Input clock frequency is given only for the purpose of reference. User should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user's part.

[3] Core frequency = (60x bus frequency)(core multiplication factor)

[4] Bus frequency = CPM frequency/bus division factor

[5] In this mode, PCI_MODCK must be "1".

Figure 14 shows the side profile of the TBGA package to indicate the direction of the top surface view.
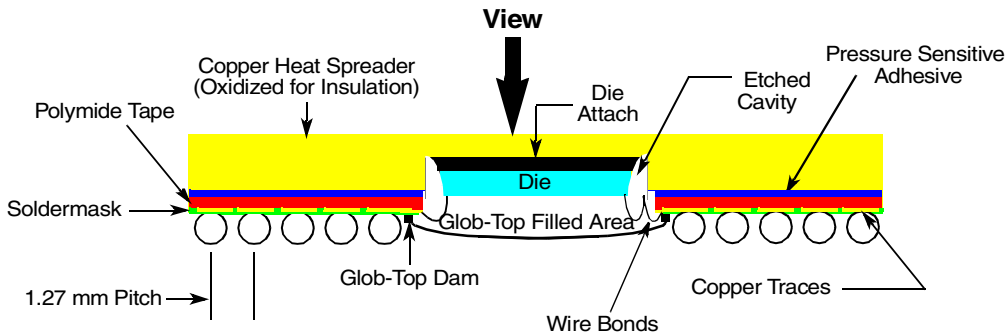
Figure 14. Side View of the TBGA Package

Table 21 shows the pinout list of the MPC826xA. Table 20 defines conventions and acronyms used in Table 21.

Symbols used in Table 21 are described in Table 20.

Table 20. Symbol Legend

Symbol	Meaning
OVERBAR	Signals with overbars, such as $\overline{\text{TA}}$, are active low.
UTM	Indicates that a signal is part of the UTOPIA master interface.
UTS	Indicates that a signal is part of the UTOPIA slave interface.
UT8	Indicates that a signal is part of the 8-bit UTOPIA interface.
UT16	Indicates that a signal is part of the 16-bit UTOPIA interface.
MII	Indicates that a signal is part of the media independent interface.

Table 21. Pinout List

Pin Name	Ball
BR	W5
BG	F4
ABB/IRQ2	E2
TS	E3
A0	G1
A1	H5
A2	H2
A3	H1
A4	J5
A5	J4
A6	J3
A7	J2

Table 21. Pinout List (continued)

Pin Name	Ball
D32	E18
D33	B17
D34	A15
D35	A12
D36	D11
D37	C8
D38	E7
D39	A3
D40	D18
D41	A17
D42	A14
D43	B12
D44	A10
D45	D8
D46	B6
D47	C4
D48	C18
D49	E16
D50	B14
D51	C12
D52	B10
D53	A7
D54	C6
D55	D5
D56	B18
D57	B16
D58	E14
D59	D12
D60	C10
D61	E8
D62	D6
D63	C2
DP0/$\overline{\text{RSRV}}$/$\overline{\text{EXT\_BR2}}$	B22
$\overline{\text{IRQ1}}$/DP1/$\overline{\text{EXT\_BG2}}$	A22
$\overline{\text{IRQ2}}$/DP2/TLBISYNC/$\overline{\text{EXT\_DBG2}}$	E21

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Table 21. Pinout List (continued)

Pin Name	Ball
$\overline{\text{IRQ3}}$/DP3/$\overline{\text{CKSTP\_OUT}}$/$\overline{\text{EXT\_BR3}}$	D21
$\overline{\text{IRQ4}}$/DP4/$\overline{\text{CORE\_SRESET}}$/$\overline{\text{EXT\_BG3}}$	C21
$\overline{\text{IRQ5}}$/DP5/$\overline{\text{TBEN}}$/$\overline{\text{EXT\_DBG3}}$	B21
$\overline{\text{IRQ6}}$/DP6/CSE0	A21
$\overline{\text{IRQ7}}$/DP7/CSE1	E20
PSDVAL	V3
TA	C22
TEA	V5
GBL/IRQ1	W1
$\overline{\text{CI}}$/BADDR29/$\overline{\text{IRQ2}}$	U2
$\overline{\text{WT}}$/BADDR30/$\overline{\text{IRQ3}}$	U3
L2_HIT/IRQ4	Y4
$\overline{\text{CPU\_BG}}$/BADDR31/$\overline{\text{IRQ5}}$	U4
CPU_DBG	R2
CPU_BR	Y3
CS0	F25
CS1	C29
CS2	E27
CS3	E28
CS4	F26
CS5	F27
CS6	F28
CS7	G25
CS8	D29
CS9	E29
$\overline{\text{CS10}}$/BCTL1	F29
$\overline{\text{CS11}}$/AP0	G28
BADDR27	T5
BADDR28	U1
ALE	T2
BCTL0	A27
PWE0/PSDDQM0/PBS0	C25
PWE1/PSDDQM1/PBS1	E24
PWE2/PSDDQM2/PBS2	D24
PWE3/PSDDQM3/PBS3	C24

Table 21. Pinout List (continued)

Pin Name	Ball
PWE4/PSDDQM4/PBS4	B26
PWE5/PSDDQM5/PBS5	A26
PWE6/PSDDQM6/PBS6	B25
PWE7/PSDDQM7/PBS7	A25
PSDA10/PGPL0	E23
$\overline{\text{PSDWE}}$/PGPL1	B24
$\overline{\text{POE}}$/$\overline{\text{PSDRAS}}$/PGPL2	A24
$\overline{\text{PSDCAS}}$/PGPL3	B23
$\overline{\text{PGTA}}$/PUPMWAIT/PGPL4/$\overline{\text{PPBS}}$	A23
PSDAMUX/PGPL5	D22
LWE0/LSDDQM0/$\overline{\text{LBS0}}$/PCI_CFG0[1]	H28
LWE1/LSDDQM1/LBS1/PCI_CFG1[1]	H27
LWE2/LSDDQM2/LBS2/PCI_CFG2[1]	H26
LWE3/LSDDQM3/LBS3/PCI_CFG3[1]	G29
LSDA10/LGPL0/PCI_MODCKH0[1]	D27
$\overline{\text{LSDWE}}$/LGPL1/PCI_MODCKH1[1]	C28
$\overline{\text{LOE}}$/$\overline{\text{LSDRAS}}$/LGPL2/PCI_MODCKH2[1]	E26
$\overline{\text{LSDCAS}}$/LGPL3/PCI_MODCKH3[1]	D25
$\overline{\text{LGTA}}$/LUPMWAIT/LGPL4/$\overline{\text{LPBS}}$	C26
LGPL5/LSDAMUX/PCI_MODCK[1]	B27
LWR	D28
L_A14/PAR[1]	N27
L_A15/$\overline{\text{FRAME}}$[1]/$\overline{\text{SMI}}$	T29
L_A16/$\overline{\text{TRDY}}$[1]	R27
L_A17/$\overline{\text{IRDY}}$[1]/$\overline{\text{CKSTP\_OUT}}$	R26
L_A18/$\overline{\text{STOP}}$[1]	R29
L_A19/$\overline{\text{DEVSEL}}$[1]	R28
L_A20/IDSEL[1]	W29
L_A21/$\overline{\text{PERR}}$[1]	P28
L_A22/$\overline{\text{SERR}}$[1]	N26
L_A23/$\overline{\text{REQ0}}$[1]	AA27
L_A24/$\overline{\text{REQ1}}$[1]/HSEJSW[1]	P29
L_A25/$\overline{\text{GNT0}}$[1]	AA26
L_A26/$\overline{\text{GNT1}}$[1]/HSLED[1]	N25
L_A27/$\overline{\text{GNT2}}$[1]/$\overline{\text{HSENUM}}$[1]	AA25

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6 Ordering Information

Figure 16 provides an example of the Freescale part numbering nomenclature for the MPC826xA. In addition to the processor frequency, the part numbering scheme also consists of a part modifier that indicates any enhancement(s) in the part from the original production design. Each part number also contains a revision code that refers to the die mask revision number and is specified in the part numbering scheme for identification purposes only. For more information, contact your local Freescale sales office.
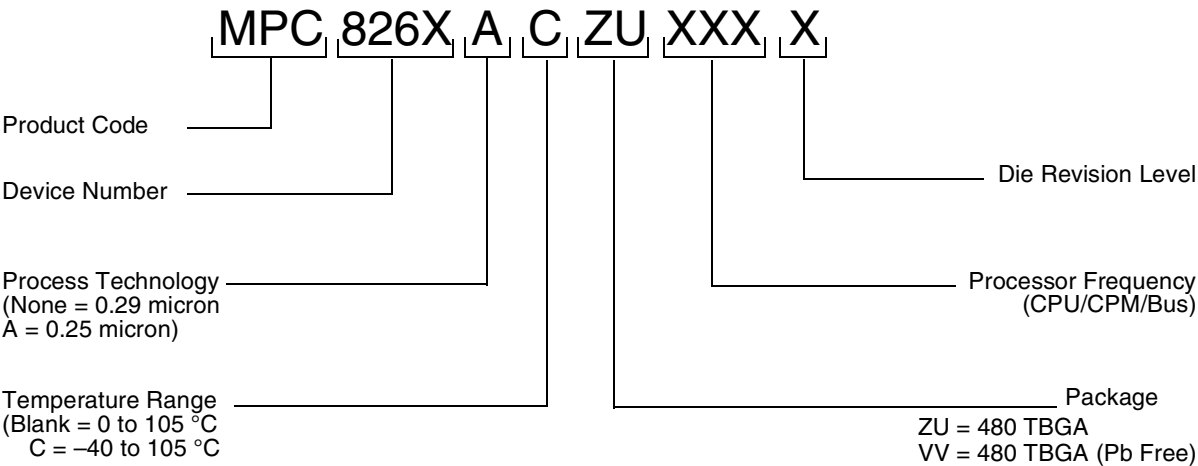
MPC 826X A C ZU XXX X

Product Code

Device Number

Process Technology
(None = 0.29 micron
A = 0.25 micron)

Temperature Range
(Blank = 0 to 105 °C
C = –40 to 105 °C)

Die Revision Level

Processor Frequency
(CPU/CPM/Bus)

Package
ZU = 480 TBGA
VV = 480 TBGA (Pb Free)

Figure 16. Freescale Part Number Key

7 Document Revision History

Table 23 lists significant changes in each revision of this document.

Table 23. Document Revision History

Revision	Date	Substantive Changes
2	06/2009	• Updated package values in Figure 16.
1.1	02/2006	• Addition of Table 12.
1.0	9/2005	• Document template update