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Understanding Embedded - Microprocessors

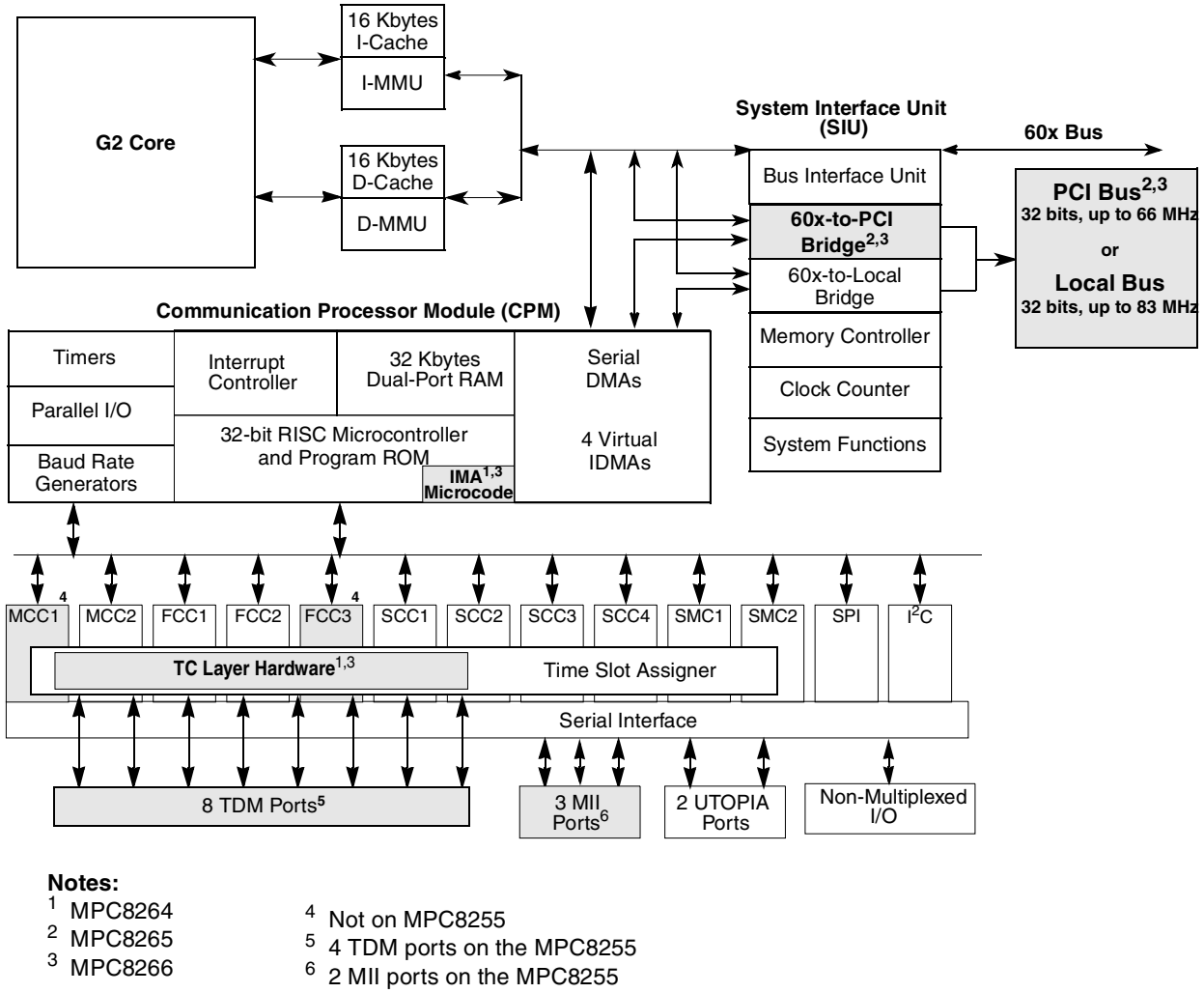
Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	200MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	-40°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/kmpc8264acvvmibb

Figure 1 shows the block diagram for the MPC8266, the HiP4 superset device. Shaded portions indicate functionality that is not available on all devices; refer to the notes.



Notes:
1 MPC8264
2 MPC8265
3 MPC8266
4 Not on MPC8255
5 4 TDM ports on the MPC8255
6 2 MII ports on the MPC8255

Figure 1. MPC8266 Block Diagram

1 Features

The major features of the MPC826xA family are as follows:

- Dual-issue integer core
  - A core version of the EC603e microprocessor
  - System core microprocessor supporting frequencies of 150–300 MHz
  - Separate 16-Kbyte data and instruction caches:
    - Four-way set associative
    - Physically addressed
    - LRU replacement algorithm

  - 32-bit address decodes with programmable bank size
  - Three user programmable machines, general-purpose chip-select machine, and page-mode pipeline SDRAM machine
  - Byte selects for 64 bus width (60x) and byte selects for 32 bus width (local)
  - Dedicated interface logic for SDRAM
- CPU core can be disabled and the device can be used in slave mode to an external core
- Communications processor module (CPM)
  - Embedded 32-bit communications processor (CP) uses a RISC architecture for flexible support for communications protocols
  - Interfaces to G2 core through on-chip 32-Kbyte dual-port RAM and DMA controller
  - Serial DMA channels for receive and transmit on all serial channels
  - Parallel I/O registers with open-drain and interrupt capability
  - Virtual DMA functionality executing memory-to-memory and memory-to-I/O transfers
  - Three fast communications controllers supporting the following protocols (only FCC1 and FCC2 on the MPC8255):
    - 10/100-Mbit Ethernet/IEEE Std. 802.3® CDMA/CS interface through media independent interface (MII)
    - ATM—Full-duplex SAR protocols at 155 Mbps, through UTOPIA interface, AAL5, AAL1, AAL0 protocols, TM 4.0 CBR, VBR, UBR, ABR traffic types, up to 16 K external connections
    - Transparent
    - HDLC—Up to T3 rates (clear channel)
  - Two multichannel controllers (MCCs) (only MCC2 on the MPC8255)
    - Each MCC handles 128 serial, full-duplex, 64-Kbps data channels.Each MCC can be split into four subgroups of 32 channels each.
    - Almost any combination of subgroups can be multiplexed to single or multiple TDM interfaces up to four TDM interfaces per MCC
  - Four serial communications controllers (SCCs) identical to those on the MPC860, supporting the digital portions of the following protocols:
    - Ethernet/IEEE 802.3 CDMA/CS
    - HDLC/SDLC and HDLC bus
    - Universal asynchronous receiver transmitter (UART)
    - Synchronous UART
    - Binary synchronous (BISYNC) communications
    - Transparent
  - Two serial management controllers (SMCs), identical to those of the MPC860
    - Provide management for BRI devices as general circuit interface (GCI) controllers in time-division-multiplexed (TDM) channels

— Hot-Swap friendly (supports the Hot Swap Specification as defined by PICMG 2.1 R1.0 August 3, 1998)
— Support for 66 MHz, 3.3 V specification
— 60x-PCI bus core logic which uses a buffer pool to allocate buffers for each port
— Makes use of the local bus signals, so there is no need for additional pins

2 Electrical and Thermal Characteristics

This section provides AC and DC electrical specifications and thermal characteristics for the MPC826xA.

2.1 DC Electrical Characteristics

This section describes the DC electrical characteristics for the MPC826xA. Table 1 shows the maximum electrical ratings.

Table 1. Absolute Maximum Ratings[1]

Rating	Symbol	Value	Unit
Core supply voltage[2]	VDD	–0.3 – 2.5	V
PLL supply voltage[2]	VCCSYN	–0.3 – 2.5	V
I/O supply voltage[3]	VDDH	–0.3 – 4.0	V
Input voltage[4]	VIN	GND(–0.3) – 3.6	V
Junction temperature	T_j	120	°C
Storage temperature range	T_{STG}	(–55) – (+150)	°C

1 Absolute maximum ratings are stress ratings only; functional operation (see Table 2) at the maximums is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage.
2 **Caution:** VDD/VCCSYN must not exceed VDDH by more than 0.4 V at any time, including during power-on reset.
3 **Caution:** VDDH can exceed VDD/VCCSYN by 3.3 V during power on reset by no more than 100 mSec. VDDH should not exceed VDD/VCCSYN by more than 2.5 V during normal operation.
4 **Caution:** VIN must not exceed VDDH by more than 2.5 V at any time, including during power-on reset.

2.4 AC Electrical Characteristics

The following sections include illustrations and tables of clock diagrams, signals, and CPM outputs and inputs for the 66 MHz MPC826xA device. Note that AC timings are based on a 50-p*f* load. Typical output buffer impedances are shown in Table 6.

Table 6. Output Buffer Impedances[1]

Output Buffers	Typical Impedance (Ω)
60x bus	40
Local bus	40
Memory controller	40
Parallel I/O	46
PCI	25

1 These are typical values at 65° C. The impedance may vary by ±25% with process and temperature.

Table 7 lists CPM output characteristics.

Table 7. AC Characteristics for CPM Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp36a	sp37a	FCC outputs—internal clock (NMSI)	6	5.5	1	1
sp36b	sp37b	FCC outputs—external clock (NMSI)	14	12	2	1
sp40	sp41	TDM outputs/SI	25	16	5	4
sp38a	sp39a	SCC/SMC/SPI/I2C outputs—internal clock (NMSI)	19	16	1	0.5
sp38b	sp39b	Ex_SCC/SMC/SPI/I2C outputs—external clock (NMSI)	19	16	2	1
sp42	sp43	TIMER/IDMA outputs	14	11	1	0.5
sp42a	sp43a	PIO outputs	14	11	0.5	0.5

1 Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

Table 8 lists CPM input characteristics.

Table 8. AC Characteristics for CPM Inputs[1]

Spec Number		Characteristic	Setup (ns)		Hold (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp16a	sp17a	FCC inputs—internal clock (NMSI)	10	8	0	0
sp16b	sp17b	FCC inputs—external clock (NMSI)	3	2.5	3	2
sp20	sp21	TDM inputs/SI	15	12	12	10
sp18a	sp19a	SCC/SMC/SPI/I2C inputs—internal clock (NMSI)	20	16	0	0
sp18b	sp19b	SCC/SMC/SPI/I2C inputs—external clock (NMSI)	5	4	5	4
sp22	sp23	PIO/TIMER/IDMA inputs	10	8	3	3

1 Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Note that although the specifications generally reference the rising edge of the clock, the following AC timing diagrams also apply when the falling edge is the active edge.

Figure 3 shows the FCC external clock.

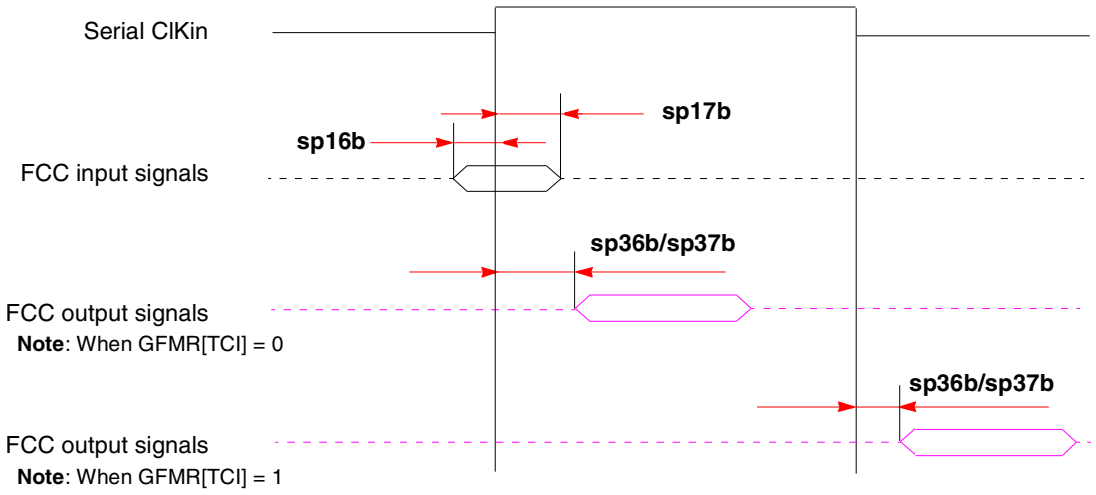
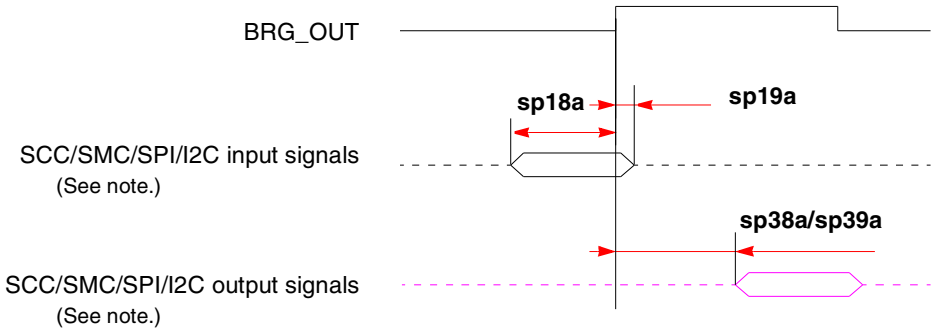


Figure 3. FCC External Clock Diagram

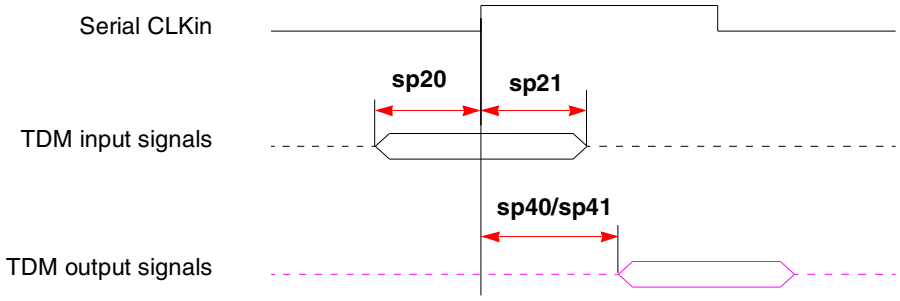
Figure 6 shows the SCC/SMC/SPI/I^{2}C internal clock.



Note: There are four possible timing conditions for SCC and SPI:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 6. SCC/SMC/SPI/I^{2}C Internal Clock Diagram

Figure 7 shows TDM input and output signals.



Note: There are four possible TDM timing conditions:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 7. TDM Signal Diagram

Figure 9 shows the interaction of several bus signals.

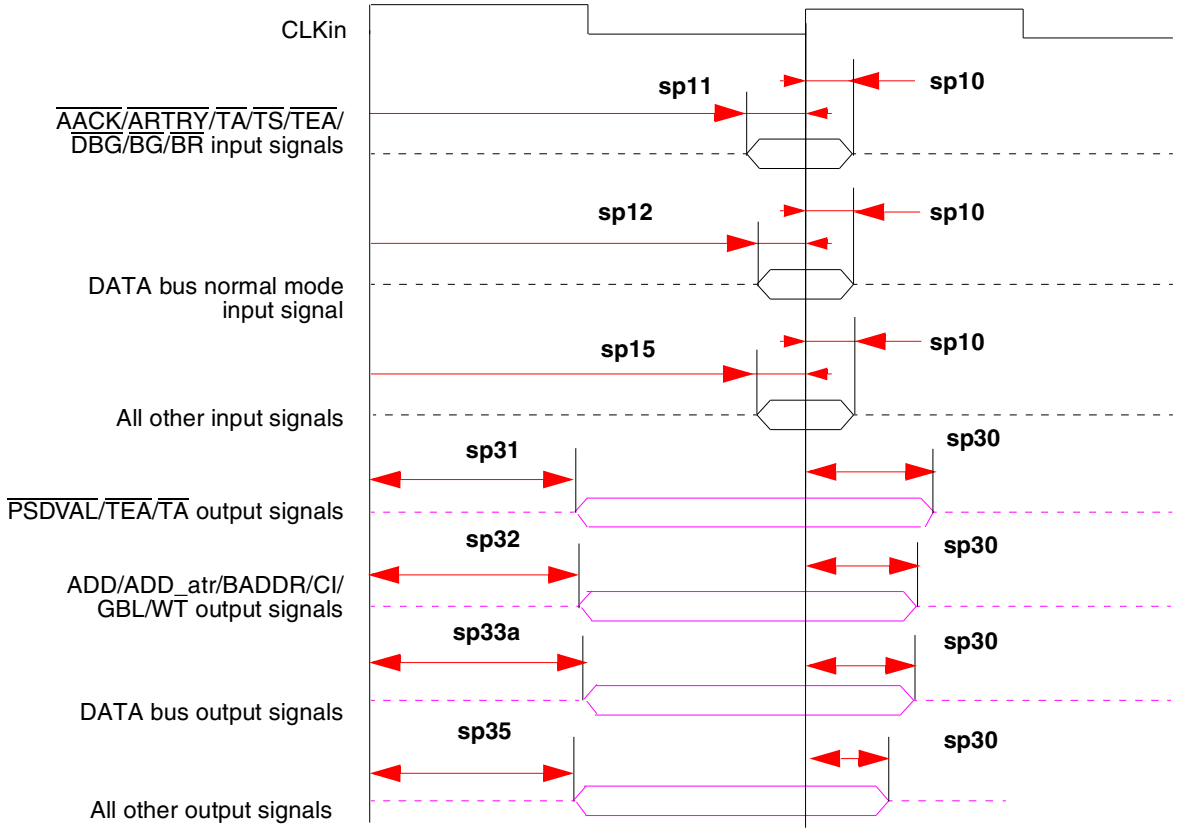


Figure 9. Bus Signals

Figure 10 shows signal behavior for all parity modes (including ECC, RMW parity, and standard parity).

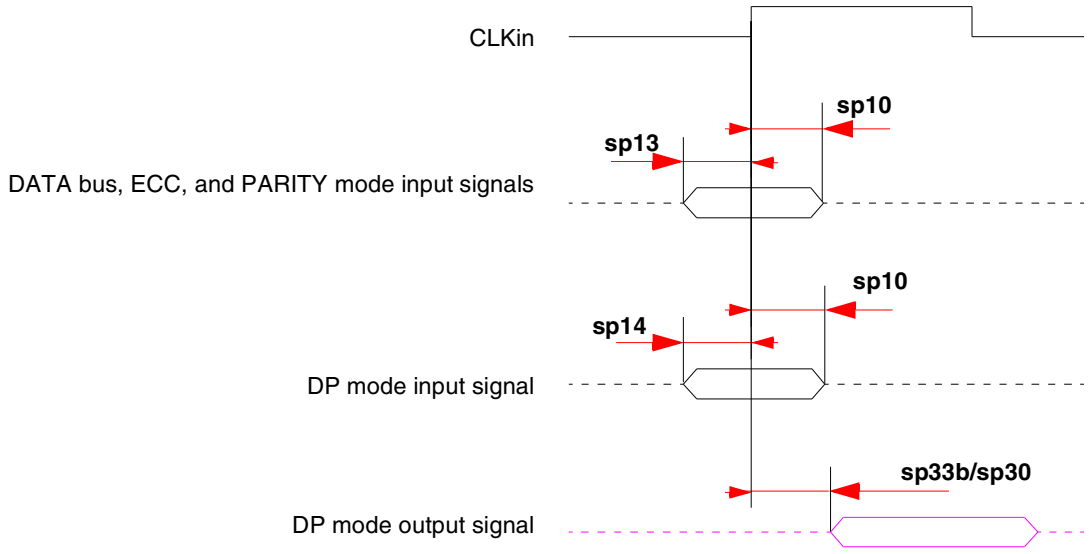


Figure 10. Parity Mode Diagram

Table 12 lists the JTAG timings.

Table 12. JTAG Timings[1]

Parameter	Symbol[2]	Min	Max	Unit	Notes
JTAG external clock frequency of operation	f_{JTG}	0	25	MHz	—
JTAG external clock cycle time	t_{JTG}	40	—	ns	—
JTAG external clock pulse width measured at 1.4V	t_{JTKHKL}	20	—	ns	—
JTAG external clock rise and fall times	t_{JTGR} and t_{JTGF}	0	5	ns	6
TRST assert time	t_{TRST}	25	—	ns	3, 6
Input setup times Boundary-scan data TMS, TDI	 t_{JTDVKH} t_{JTIVKH}	 4 4	 — —	 ns ns	 4, 7 4, 7
Input hold times Boundary-scan data TMS, TDI	 t_{JTDXKH} t_{JTIXKH}	 10 10	 — —	 ns ns	 4, 7 4, 7
Output valid times Boundary-scan data TDO	 t_{JTKLDV} t_{JTKLOV}	 — —	 25 25	 ns ns	 5, 7 5. 7
Output hold times Boundary-scan data TDO	 t_{JTKLDX} t_{JTKLOX}	 1 1	 — —	 ns ns	 5, 7 5, 7
JTAG external clock to output high impedance Boundary-scan data TDO	 t_{JTKLDZ} t_{JTKLOZ}	 1 1	 25 25	 ns ns	 5, 6 5, 6

1 All outputs are measured from the midpoint voltage of the falling/rising edge of t_{TCLK} to the midpoint of the signal in question. The output timings are measured at the pins. All output timings assume a purely resistive 50-Ω load. Time-of-flight delays must be added for trace lengths, vias, and connectors in the system.

2 The symbols used for timing specifications herein follow the pattern of $t_{\text{(first two letters of functional block)(signal)(state)(reference)(state)}}$ for inputs and $t_{\text{((first two letters of functional block)(reference)(state)(signal)(state)}}$ for outputs. For example, t_{JTDVKH} symbolizes JTAG device timing (JT) with respect to the time data input signals (D) reaching the valid state (V) relative to the t_{JTG} clock reference (K) going to the high (H) state or setup time. Also, t_{JTDXKH} symbolizes JTAG timing (JT) with respect to the time data input signals (D) went invalid (X) relative to the t_{JTG} clock reference (K) going to the high (H) state. Note that, in general, the clock reference symbol representation is based on three letters representing the clock of a particular functional. For rise and fall times, the latter convention is used with the appropriate letter: R (rise) or F (fall).

3 TRST is an asynchronous level sensitive signal. The setup time is for test purposes only.

4 Non-JTAG signal input timing with respect to t_{TCLK}.

5 Non-JTAG signal output timing with respect to t_{TCLK}.

6 Guaranteed by design.

7 Guaranteed by design and device characterization.

NOTE

The UPM machine outputs change on the internal tick determined by the memory controller programming; the AC specifications are relative to the internal tick. Note that SDRAM and GPCM machine outputs change on CLKin's rising edge.

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
1000_001	66 MHz	3.5	233 MHz	3	200 MHz
1000_010	66 MHz	3.5	233 MHz	3.5	233 MHz
1000_011	66 MHz	3.5	233 MHz	4	266 MHz
1000_100	66 MHz	3.5	233 MHz	4.5	300 MHz

1 Because of speed dependencies, not all of the possible configurations in Table 14 are applicable.
2 The user should choose the input clock frequency and the multiplication factors such that the frequency of the CPU is equal to or greater than 150 MHz and the CPM ranges between 66–233 MHz.
3 Input clock frequency is given only for the purpose of reference. The user should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user's part.

3.2 PCI Mode

The MPC8265 and the MPC8266 have three clocking modes: local, PCI host, and PCI agent. The clocking mode is set according to three input pins—PCI_MODE, PCI_CFG[0], PCI_MODCK—as shown in Table 15.

Table 15. MPC8265 and MPC8266 Clocking Modes

Pins			Clocking Mode	PCI Clock Frequency Range (MHZ)
PCI_MODE	PCI_CFG[0]	PCI_MODCK		
1	—	—	Local bus	—
0	0	0	PCI host	50–66
0	0	1		25–50
0	1	0	PCI agent	50–66
0	1	1		25–50

In addition, note the following:

NOTE: PCI_MODCK

In PCI mode only, PCI_MODCK comes from the LGPL5 pin and MODCK_H[0–3] comes from {LGPL0, LGPL1, LGPL2, LGPL3}.

NOTE: Tval (Output Hold)

The minimum Tval = 2 when PCI_MODCK = 1, and the minimum Tval = 1 when PCI_MODCK = 0. Therefore, designers should use clock configurations that fit this condition to achieve PCI-compliant AC timing.

NOTE

Clock configurations change only after $\overline{\text{POR}}$ is asserted.

3.2.1 PCI Host Mode

The frequencies listed in Table 16 and Table 17 are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user's device.

Table 16. Clock Default Configurations in PCI Host Mode (MODCK_HI = 0000)

MODCK[1–3][1]	Input Clock Frequency (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
000	66 MHz	2	133 MHz	2.5	166 MHz	2/4	66/33 MHz
001	66 MHz	2	133 MHz	3	200 MHz	2/4	66/33 MHz
010	66 MHz	2.5	166 MHz	3	200 MHz	3/6	55/28 MHz
011	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
100	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
101	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
110	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
111	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz

1 Assumes MODCK_HI = 0000.

2 The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic '1'), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) Refer to Table 15.

Table 17 describes all possible clock configurations when using the MPC8265's or the MPC8266's internal PCI bridge in host mode.

Table 17. Clock Configuration Modes in PCI Host Mode

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0001_000	33 MHz	3	100 MHz	5	166 MHz	3/6	33/16 MHz
0001_001	33 MHz	3	100 MHz	6	200 MHz	3/6	33/16 MHz
0001_010	33 MHz	3	100 MHz	7	233 MHz	3/6	33/16 MHz
0001_011	33 MHz	3	100 MHz	8	266 MHz	3/6	33/16 MHz
0010_000	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**	**4/8**	**33**/16 **MHz**
0010_001	33 MHz	4	133 MHz	6	200 MHz	4/8	33/16 MHz
0010_010	33 MHz	4	133 MHz	7	233 MHz	4/8	33/16 MHz
0010_011	33 MHz	4	133 MHz	8	266 MHz	4/8	33/16 MHz
0011_000[3]	33 MHz	5	166 MHz	5	166 MHz	5	**33 MHz**
0011_001[3]	33 MHz	5	166 MHz	6	200 MHz	5	33 MHz
0011_010[3]	33 MHz	5	166 MHz	7	233 MHz	5	33 MHz

Table 17. Clock Configuration Modes in PCI Host Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0011_011[3]	33 MHz	5	166 MHz	8	266 MHz	5	33 MHz
0100_000[3]	33 MHz	6	200 MHz	5	166 MHz	6	33 MHz
0100_001[3]	33 MHz	6	200 MHz	6	200 MHz	6	33 MHz
0100_010[3]	33 MHz	6	200 MHz	7	233 MHz	6	33 MHz
0100_011[3]	33 MHz	6	200 MHz	8	266 MHz	6	33 MHz
0101_000	**66 MHz**	**2**	**133 MHz**	**2.5**	**166 MHz**	**2/4**	**66/33 MHz**
0101_001	**66 MHz**	**2**	**133 MHz**	**3**	**200 MHz**	**2**/4	**66**/33 **MHz**
0101_010	66 MHz	2	133 MHz	3.5	233 MHz	2/4	66/33 MHz
0101_011	66 MHz	2	133 MHz	4	266 MHz	2/4	66/33 MHz
0101_100	66 MHz	2	133 MHz	4.5	300 MHz	2/4	66/33 MHz
0110_000	**66 MHz**	**2.5**	**166 MHz**	**2.5**	**166 MHz**	3/6	**55/28 MHz**
0110_001	**66 MHz**	**2.5**	**166 MHz**	**3**	**200 MHz**	3/6	55/28 MHz
0110_010	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
0110_011	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
0110_100	66 MHz	2.5	166 MHz	4.5	300 MHz	3/6	55/28 MHz
0111_000	66 MHz	3	200 MHz	2.5	166 MHz	3/6	66/33 MHz
0111_001	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
0111_010	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
0111_011	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz
0111_100	66 MHz	3	200 MHz	4.5	300 MHz	3/6	66/33 MHz
1000_000	66 MHz	3	200 MHz	2.5	166 MHz	4/8	50/25 MHz
1000_001	66 MHz	3	200 MHz	3	200 MHz	4/8	50/25 MHz
1000_010	66 MHz	3	200 MHz	3.5	233 MHz	4/8	50/25 MHz
1000_011	66 MHz	3	200 MHz	4	266 MHz	4/8	50/25 MHz
1000_100	66 MHz	3	200 MHz	4.5	300 MHz	4/8	50/25 MHz
1001_000	66 MHz	3.5	233 MHz	2.5	166 MHz	4/8	58/29 MHz
1001_001	66 MHz	3.5	233 MHz	3	200 MHz	4/8	58/29 MHz

Table 17. Clock Configuration Modes in PCI Host Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
1001_010	66 MHz	3.5	233 MHz	3.5	233 MHz	4/8	58/29 MHz
1001_011	66 MHz	3.5	233 MHz	4	266 MHz	4/8	58/29 MHz
1001_100	66 MHz	3.5	233 MHz	4.5	300 MHz	4/8	58/29 MHz
1010_000	100 MHz	2	200 MHz	2	200 MHz	3/6	66/33 MHz
1010_001	100 MHz	2	200 MHz	2.5	250 MHz	3/6	66/33 MHz
1010_010	100 MHz	2	200 MHz	3	300 MHz	3/6	66/33 MHz
1010_011	100 MHz	2	200 MHz	3.5	350 MHz	3/6	66/33 MHz
1010_100	100 MHz	2	200 MHz	4	400 MHz	3/6	66/33 MHz
1011_000	100 MHz	2.5	250 MHz	2	200 MHz	4/8	62/31 MHz
1011_001	100 MHz	2.5	250 MHz	2.5	250 MHz	4/8	62/31MHz
1011_010	100 MHz	2.5	250 MHz	3	300 MHz	4/8	62/31 MHz
1011_011	100 MHz	2.5	250 MHz	3.5	350 MHz	4/8	62/31 MHz
1011_100	100 MHz	2.5	250 MHz	4	400 MHz	4/8	62/31 MHz

1 Input clock frequency is given only for the purpose of reference. User should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user's part.

2 The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic '1'), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.). Refer to Table 15.

3 In this mode, PCI_MODCK must be "0".

3.2.2 PCI Agent Mode

The frequencies listed in Table 18 and Table 19 are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user's device.

Table 18. Clock Default Configurations in PCI Agent Mode (MODCK_HI = 0000)

MODCK[1–3][1]	Input Clock Frequency (PCI)[2]	CPM Multiplication Factor[2]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
000	66/33 MHz	2/4	133 MHz	2.5	166 MHz	2	66 MHz
001	66/33 MHz	2/4	133 MHz	3	200 MHz	2	66 MHz
010	66/33 MHz	3/6	200 MHz	3	200 MHz	3	66 MHz
011	66/33 MHz	3/6	200 MHz	4	266 MHz	3	66 MHz

Table 19. Clock Configuration Modes in PCI Agent Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency (PCI)[1,2]	CPM Multiplication Factor[1]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
1010_001	66/33 MHz	4/8	266 MHz	3	266 MHz	3	88 MHz
1010_010	66/33 MHz	4/8	266 MHz	3.5	300 MHz	3	88 MHz
1010_011	66/33 MHz	4/8	266 MHz	4	350 MHz	3	88 MHz
1010_100	66/33 MHz	4/8	266 MHz	4.5	400 MHz	3	88 MHz
1011_000	66/33 MHz	4/8	266 MHz	2	212MHz	2.5	106 MHz
1011_001	66/33 MHz	4/8	266 MHz	2.5	265 MHz	2.5	106 MHz
1011_010	66/33 MHz	4/8	266 MHz	3	318 MHz	2.5	106 MHz
1011_011	66/33 MHz	4/8	266 MHz	3.5	371 MHz	2.5	106 MHz
1011_100	66/33 MHz	4/8	266 MHz	4	424 MHz	2.5	106 MHz

1 The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic ‘1’), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) and the CPM multiplication factor is multiplied by 2. Refer to Table 15.

2 Input clock frequency is given only for the purpose of reference. User should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user’s part.

3 Core frequency = (60x bus frequency)(core multiplication factor)

4 Bus frequency = CPM frequency/bus division factor

5 In this mode, PCI_MODCK must be “1”.

Table 21. Pinout List (continued)

Pin Name	Ball
ARTRY	E1
DBG	V1
DBB/IRQ3	V2
D0	B20
D1	A18
D2	A16
D3	A13
D4	E12
D5	D9
D6	A6
D7	B5
D8	A20
D9	E17
D10	B15
D11	B13
D12	A11
D13	E9
D14	B7
D15	B4
D16	D19
D17	D17
D18	D15
D19	C13
D20	B11
D21	A8
D22	A5
D23	C5
D24	C19
D25	C17
D26	C15
D27	D13
D28	C11
D29	B8
D30	A4
D31	E6

Table 21. Pinout List (continued)

Pin Name	Ball
D32	E18
D33	B17
D34	A15
D35	A12
D36	D11
D37	C8
D38	E7
D39	A3
D40	D18
D41	A17
D42	A14
D43	B12
D44	A10
D45	D8
D46	B6
D47	C4
D48	C18
D49	E16
D50	B14
D51	C12
D52	B10
D53	A7
D54	C6
D55	D5
D56	B18
D57	B16
D58	E14
D59	D12
D60	C10
D61	E8
D62	D6
D63	C2
DP0/$\overline{\text{RSRV}}$/$\overline{\text{EXT\_BR2}}$	B22
$\overline{\text{IRQ1}}$/DP1/$\overline{\text{EXT\_BG2}}$	A22
$\overline{\text{IRQ2}}$/DP2/$\overline{\text{TLBISYNC}}$/$\overline{\text{EXT\_DBG2}}$	E21

Table 21. Pinout List (continued)

Pin Name	Ball
LCL_D31/AD31[1]	AA28
LCL_DP0/C0[1]/$\overline{\text{BE0}}$[1]	L28
LCL_DP1/C1[1]/$\overline{\text{BE1}}$[1]	N28
LCL_DP2/C2[1]/$\overline{\text{BE2}}$[1]	T28
LCL_DP3/C3[1]/$\overline{\text{BE3}}$[1]	W28
IRQ0/NMI_OUT	T1
IRQ7/INT_OUT/APE	D1
TRST	AH3
TCK	AG5
TMS	AJ3
TDI	AE6
TDO	AF5
TRIS	AB4
PORESET	AG6
HRESET	AH5
SRESET	AF6
QREQ	AA3
RSTCONF	AJ4
MODCK1/AP1/TC0/BNKSEL0	W2
MODCK2/AP2/TC1/BNKSEL1	W3
MODCK3/AP3/TC2/BNKSEL2	W4
XFC	AB2
CLKIN1	AH4
PA0/$\overline{\text{RESTART1}}$/DREQ3/FCC2_UTM_TXADDR2	AC29[2]
PA1/$\overline{\text{REJECT1}}$/FCC2_UTM_TXADDR1/$\overline{\text{DONE3}}$	AC25[2]
PA2/CLK20/FCC2_UTM_TXADDR0/$\overline{\text{DACK3}}$	AE28[2]
PA3/CLK19/FCC2_UTM_RXADDR0/$\overline{\text{DACK4}}$/L1RXD1A2	AG29[2]
PA4/$\overline{\text{REJECT2}}$/FCC2_UTM_RXADDR1/$\overline{\text{DONE4}}$	AG28[2]
PA5/$\overline{\text{RESTART2}}$/DREQ4/FCC2_UTM_RXADDR2	AG26[2]
PA6/L1RSYNCA1	AE24[2]
PA7/SMSYN2/L1TSYNCA1/L1GNTA1	AH25[2]
PA8/SMRXD2/L1RXD0A1/L1RXDA1	AF23[2]
PA9/SMTXD2/L1TXD0A1	AH23[2]
PA10/FCC1_UT8_RXD0/FCC1_UT16_RXD8/MSNUM5	AE22[2]
PA11/FCC1_UT8_RXD1/FCC1_UT16_RXD9/MSNUM4	AH22[2]

Table 21. Pinout List (continued)

Pin Name	Ball
PD21/TXD4/FCC1_UT16_RXD3/L1RXD0A2/L1RXDA2	AH13[2]
PD22/RXD4/FCC1_UT16_TXD5/L1TXD0A2/L1TXDA2	AJ12[2]
PD23/$\overline{\text{RTS3}}$/TENA3/FCC1_UT16_RXD4/L1RSYNCD1	AE12[2]
PD24/TXD3/FCC1_UT16_RXD5/L1RXDD1	AF10[2]
PD25/RXD3/FCC1_UT16_TXD6/L1TXDD1	AG9[2]
PD26/$\overline{\text{RTS2}}$/TENA2/FCC1_UT16_RXD6/L1RSYNCC1	AH8[2]
PD27/TXD2/FCC1_UT16_RXD7/L1RXDC1	AG7[2]
PD28/RXD2/FCC1_UT16_TXD7/L1TXDC1	AE4[2]
PD29/$\overline{\text{RTS1}}$/TENA1/FCC1_UTM_RXADDR3/FCC1_UTS_RXADDR3/ FCC1_UTM_RXCLAV2/FCC2_UTM_RXADDR4	AG1[2]
PD30/$\overline{\text{FCC2\_UTM\_TXENB}}$/$\overline{\text{FCC2\_UTS\_TXENB}}$/TXD1	AD4[2]
PD31/RXD1	AD2[2]
VCCSYN	AB3
VCCSYN1	B9
GNDSYN	AB1
CLKIN2[1,3]	AE11
SPARE4[4]	U5
$\overline{\text{PCI\_MODE}}$[1,5]	AF25
SPARE6[4]	V4
THERMAL0[6]	AA1
THERMAL1[6]	AG4
I/O power	AG21, AG14, AG8, AJ1, AJ2, AH1, AH2, AG3, AF4, AE5, AC27, Y27, T27, P27, K26, G27, AE25, AF26, AG27, AH28, AH29, AJ28, AJ29, C7, C14, C16, C20, C23, E10, A28, A29, B28, B29, C27, D26, E25, H3, M4, T3, AA4, A1, A2, B1, B2, C3, D4, E5
Core Power	U28, U29, K28, K29, A9, A19, B19, M1, M2, Y1, Y2, AC1, AC2, AH19, AJ19, AH10, AJ10, AJ5
Ground	AA5, AF21, AF14, AF8, AE7, AF11, AE17, AE23, AC26, AB25, Y26, V25, T26, R25, P26, M25, K27, H25, G26, D7, D10, D14, D16, D20, D23, C9, E11, E13, E15, E19, E22, B3, G5, H4, K5, M3, P5, T4, Y5, AA2, AC3

1 MPC8265 and MPC8266 only.

2 The default configuration of the CPM pins (PA[0–31], PB[4–31], PC[0–31], PD[4–31]) is input. To prevent excessive DC current, it is recommended to either pull unused pins to GND or VDDH, or to configure them as outputs.

3 On PCI devices (MPC8265 and MPC8266) this pin should be used as CLKIN2. On non-PCI devices (MPC8260A and MPC8264) this is a spare pin that must be pulled down or left floating.
4 Must be pulled down or left floating.
5 On PCI devices (MPC8265 and MPC8266) this pin should be asserted if the PCI function is desired or pulled up or left floating if PCI is not desired. On non-PCI devices (MPC8260A and MPC8264) this is a spare pin that must be pulled up or left floating.
6 For information on how to use this pin, refer to *MPC8260 PowerQUICC II Thermal Resistor Guide* available at www.freescale.com.

5 Package Description

The following sections provide the package parameters and mechanical dimensions for the MPC826xA.

5.1 Package Parameters

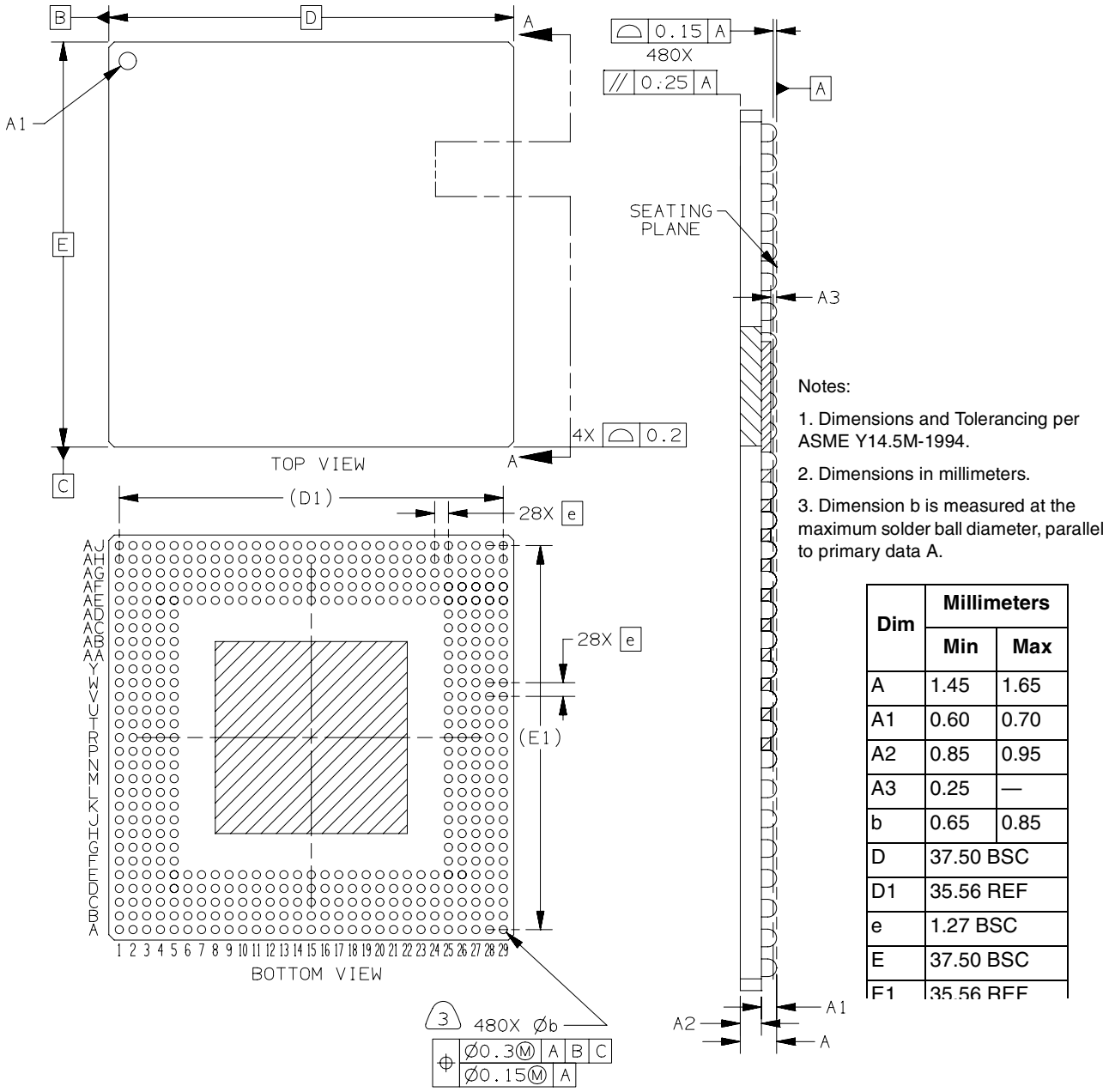
Package parameters are provided in Table 22. The package type is a 37.5 × 37.5 mm, 480-lead TBGA.

Table 22. Package Parameters

Parameter	Value
Package Outline	37.5 × 37.5 mm
Interconnects	480 (29 × 29 ball array)
Pitch	1.27 mm
Nominal unmounted package height	1.55 mm

5.2 Mechanical Dimensions

Figure 15 provides the mechanical dimensions and bottom surface nomenclature of the 480 TBGA package.



Notes:

1. Dimensions and Tolerancing per ASME Y14.5M-1994.
2. Dimensions in millimeters.
3. Dimension b is measured at the maximum solder ball diameter, parallel to primary data A.

Dim	Millimeters	
	Min	Max
A	1.45	1.65
A1	0.60	0.70
A2	0.85	0.95
A3	0.25	—
b	0.65	0.85
D	37.50 BSC	
D1	35.56 REF	
e	1.27 BSC	
E	37.50 BSC	
E1	35.56 REF	

Figure 15. Mechanical Dimensions and Bottom Surface Nomenclature

Table 23. Document Revision History (continued)

Revision	Date	Substantive Changes
0.9	8/2003	• Note: In revision 0.3, sp30 (Table 10) was changed. This change was not previously recorded in this "Document Revision History" Table. • Removal of "HiP4 PowerQUICC II Documentation" table. These supplemental specifications have been replaced by revision 1 of the *MPC8260 PowerQUICC II™ Family Reference Manual*. • Figure 1 and Section 1, "Features": Addition of MPC8255 notes • Addition of Figure 2 • Addition of VCCSYN to "Note: Core, PLL, and I/O Supply Voltages" following Table 2 • Addition of note 1 to Table 3 • Table 4: Changes to θ_{JA} and θ_{JB} and θ_{JC}. • Addition of notes or modifications to Figure 6, Figure 7, and Figure 8 • Table 9: Change of sp10. • Addition of Table 15. • Addition of note 2 to Table 21 • Table 21: Addition of FCC2 Rx and Tx [3,4] to CPM pins PD7, PD18, PD19, and PD29. Also, the addition of SPICLK to PC19. They are documented correctly in the parallel I/O ports chapter in the *MPC8260 PowerQUICC II™ Family Reference Manual* but had previously been omitted from Table 21.
0.8	1/2003	• Table 2: Modification to supply voltage ranges reflected in notes 2, 3, and 4. • Table 4: Addition of θ_{JB} and θ_{JC}. • Table 7, Figure 8: Addition of sp42a/sp43a. • Figure 3, Figure 4: Addition of note for FCC output. • Figure 5, Figure 6, Figure 7: Addition of notes. • Table 14, Table 17, and Table 19: Removal of PLL bypass mode from clock tables.
0.7	5/2002	• Section 1, "Features": minimum supported core frequency of 150 MHz • Section 1, "Features": updated performance values (under "Dual-issue integer core") • Table 2: Note 2 (changes in italics): "...*less* than or equal to *233* MHz, *166* MHz CPM..." • Table 2: Addition of note 3.
0.6	3/2002	• Table 21: Modified notes to pins AE11 and AF25.
0.5	3/2002	• Table 21: Modified notes to pins AE11 and AF25. • Table 21: Addition of note to pins AA1 and AG4 (Therm0 and Therm1).
0.4	2/2002	• Note 2 for Table 2 (changes in italics): "...greater than *or equal to 266* MHz, *200* MHz CPM..." • Table 19: Core and bus frequency values for the following ranges of MODCK_HMODCK: 0011_000 to 0011_100 and 1011_000 to 1011_1000 • Table 21: Notes added to pins at AE11, AF25, U5, and V4.
0.3	11/2001	• Table 1: note 3 • Section 2.1: Removal of "Warning" recommending use of bootstrap diodes. They are not needed. • Table 9: Change to sp12. • Table 10: Change to sp32. • Note 2 for Table 16 and Table 17 • Addition of note at beginning of Section 3.2 • Note 1 for Table 18 and Table 19 • Table 21: Additions to B27, C28, D25, D27, E26, G29, H26–28, N25, P29, AF25, AA25, AB27
0.2	11/2001	• Revision of Table 5, "Power Dissipation" • Modifications to Figure 9, Table 2,Table 10, Table 11, and Table 18 • Modification to pinout diagram, Figure 13 • Additional revisions to text and figures throughout
0.1	8/2001	• Table 8: Change to sp20/sp21.
0	—	Initial version