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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	200MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/kmpc8265azupibc

  - Transparent
  - UART (low-speed operation)
- One serial peripheral interface identical to the MPC860 SPI
- One inter-integrated circuit (I^2C) controller (identical to the MPC860 I^2C controller)
  - Microwire compatible
  - Multiple-master, single-master, and slave modes
- Up to eight TDM interfaces (four on the MPC8255)
  - Supports two groups of four TDM channels for a total of eight TDMs
  - 2,048 bytes of SI RAM
  - Bit or byte resolution
  - Independent transmit and receive routing, frame synchronization
  - Supports T1, CEPT, T1/E1, T3/E3, pulse code modulation highway, ISDN basic rate, ISDN primary rate, Freescale interchip digital link (IDL), general circuit interface (GCI), and user-defined TDM serial interfaces
- Eight independent baud rate generators and 20 input clock pins for supplying clocks to FCCs, SCCs, SMCs, and serial channels
- Four independent 16-bit timers that can be interconnected as two 32-bit timers

Additional features of the MPC826xA family are as follows:

- CPM
  - 32-Kbyte dual-port RAM
  - Additional MCC host commands
  - Eight transfer transmission convergence (TC) layers between the TDMs and FCC2 to support inverse multiplexing for ATM capabilities (IMA) (MPC8264 and MPC8266 only)
- CPM multiplexing
  - FCC2 can also be connected to the TC layer.
- TC layer (MPC8264 and MPC8266 only)
  - Each of the 8 TDM channels is routed in hardware to a TC layer block
    - Protocol-specific overhead bits may be discarded or routed to other controllers by the SI
    - Performing ATM TC layer functions (according to ITU-T I.432)
    - Transmit (Tx) updates
      - Cell HEC generation
      - Payload scrambling using self synchronizing scrambler (programmable by the user)
      - Coset generation (programmable by the user)
      - Cell rate by inserting idle/unassigned cells
    - Receive (Rx) updates
      - Cell delineation using bit by bit HEC checking and programmable ALPHA and DELTA parameters for the delineation state machine
      - Payload descrambling using self synchronizing scrambler (programmable by the user)

- Coset removing (programmable by the user)
- Filtering idle/unassigned cells (programmable by the user)
- Performing HEC error detection and single bit error correction (programmable by user)
- Generating loss of cell delineation status/interrupt (LOC/LCD)

— Operates with FCC2 (UTOPIA 8)
— Provides serial loop back mode
— Cell echo mode is provided
— Supports both FCC transmit modes
  – External rate mode—Idle cells are generated by the FCC (microcode) to control data rate.
  – Internal rate mode (sub-rate)—FCC transfers only the data cells using the required data rate. The TC layer generates idle/unassigned cells to maintain the line bit rate.
— Supports TC-layer and PMD-WIRE interface (according to the ATM-Forum af-phy-0063.000)
— Cell counters for performance monitoring
  – 16-bit counters count
    - HEC error cells
    - HEC single bit error and corrected cells
    - Idle/unassigned cells filtered
    - Idle/unassigned cells transmitted
    - Transmitted ATM cells
    - Received ATM cells
  – Maskable interrupt is sent to the host when a counter expires
— Overrun (Rx cell FIFO) and underrun (Tx cell FIFO) condition produces maskable interrupt
— May be operated at E1 and DS-1 rates. In addition, xDSL applications at bit rates up to 10 Mbps are supported

- PCI bridge (MPC8265 and MPC8266 only)
  — PCI Specification Revision 2.2 compliant and supports frequencies up to 66 MHz
  — On-chip arbitration
  — Support for PCI to 60x memory and 60x memory to PCI streaming
  — PCI Host Bridge or Peripheral capabilities
  — Includes 4 DMA channels for the following transfers:
    – PCI-to-60x to 60x-to-PCI
    – 60x-to-PCI to PCI-to-60x
    – PCI-to-60x to PCI-to-60x
    – 60x-to-PCI to 60x-to-PCI
  — Includes all of the configuration registers (which are automatically loaded from the EPROM and used to configure the MPC8265) required by the PCI standard as well as message and doorbell registers
  — Supports the I_2O standard

— Hot-Swap friendly (supports the Hot Swap Specification as defined by PICMG 2.1 R1.0 August 3, 1998)
— Support for 66 MHz, 3.3 V specification
— 60x-PCI bus core logic which uses a buffer pool to allocate buffers for each port
— Makes use of the local bus signals, so there is no need for additional pins

2 Electrical and Thermal Characteristics

This section provides AC and DC electrical specifications and thermal characteristics for the MPC826xA.

2.1 DC Electrical Characteristics

This section describes the DC electrical characteristics for the MPC826xA. Table 1 shows the maximum electrical ratings.

Table 1. Absolute Maximum Ratings[1]

Rating	Symbol	Value	Unit
Core supply voltage[2]	VDD	–0.3 – 2.5	V
PLL supply voltage[2]	VCCSYN	–0.3 – 2.5	V
I/O supply voltage[3]	VDDH	–0.3 – 4.0	V
Input voltage[4]	VIN	GND(–0.3) – 3.6	V
Junction temperature	T_j	120	°C
Storage temperature range	T_{STG}	(–55) – (+150)	°C

1 Absolute maximum ratings are stress ratings only; functional operation (see Table 2) at the maximums is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage.
2 **Caution:** VDD/VCCSYN must not exceed VDDH by more than 0.4 V at any time, including during power-on reset.
3 **Caution:** VDDH can exceed VDD/VCCSYN by 3.3 V during power on reset by no more than 100 mSec. VDDH should not exceed VDD/VCCSYN by more than 2.5 V during normal operation.
4 **Caution:** VIN must not exceed VDDH by more than 2.5 V at any time, including during power-on reset.

where K is a constant pertaining to the particular part. K can be determined from equation (3) by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving equations (1) and (2) iteratively for any value of T_A.

2.3.1 Layout Practices

Each V_{CC} pin should be provided with a low-impedance path to the board's power supply. Each ground pin should likewise be provided with a low-impedance path to ground. The power supply pins drive distinct groups of logic on chip. The V_{CC} power supply should be bypassed to ground using at least four 0.1 µF by-pass capacitors located as close as possible to the four sides of the package. The capacitor leads and associated printed circuit traces connecting to chip V_{CC} and ground should be kept to less than half an inch per capacitor lead. A four-layer board is recommended, employing two inner layers as V_{CC} and GND planes.

All output pins on the MPC826xA have fast rise and fall times. Printed circuit (PC) trace interconnection length should be minimized in order to minimize overdamped conditions and reflections caused by these fast output switching times. This recommendation particularly applies to the address and data buses. Maximum PC trace lengths of six inches are recommended. Capacitance calculations should consider all device loads as well as parasitic capacitances due to the PC traces. Attention to proper PCB layout and bypassing becomes especially critical in systems with higher capacitive loads because these loads create higher transient currents in the V_{CC} and GND circuits. Pull up all unused inputs or signals that will be inputs during reset. Special care should be taken to minimize the noise levels on the PLL supply pins.

Table 5 provides preliminary, estimated power dissipation for various configurations. Note that suitable thermal management is required for conditions above P_D = 3 W (when the ambient temperature is 70 °C or greater) to ensure the junction temperature does not exceed the maximum specified value. Also note that the I/O power should be included when determining whether to use a heat sink.

Table 5. Estimated Power Dissipation for Various Configurations[1]

Bus (MHz)	CPM Multiplier	Core CPU Multiplier	CPM (MHz)	CPU (MHz)	P_{INT}(W)[2]			
					Vddl 1.8 Volts		Vddl 2.0 Volts	
					Nominal	Maximum	Nominal	Maximum
66.66	2	3	133	200	1.2	2	1.8	2.3
66.66	2.5	3	166	200	1.3	2.1	1.9	2.3
66.66	3	4	200	266	—	—	2.3	2.9
66.66	3	4.5	200	300	—	—	2.4	3.1
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2.5	3.5	208	291	—	—	2.4	3.1

1 Test temperature = room temperature (25° C)

2 $P_{INT} = I_{DD} \times V_{DD}$ Watts

Table 8 lists CPM input characteristics.

Table 8. AC Characteristics for CPM Inputs[1]

Spec Number		Characteristic	Setup (ns)		Hold (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp16a	sp17a	FCC inputs—internal clock (NMSI)	10	8	0	0
sp16b	sp17b	FCC inputs—external clock (NMSI)	3	2.5	3	2
sp20	sp21	TDM inputs/SI	15	12	12	10
sp18a	sp19a	SCC/SMC/SPI/I2C inputs—internal clock (NMSI)	20	16	0	0
sp18b	sp19b	SCC/SMC/SPI/I2C inputs—external clock (NMSI)	5	4	5	4
sp22	sp23	PIO/TIMER/IDMA inputs	10	8	3	3

[1] Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Note that although the specifications generally reference the rising edge of the clock, the following AC timing diagrams also apply when the falling edge is the active edge.

Figure 3 shows the FCC external clock.

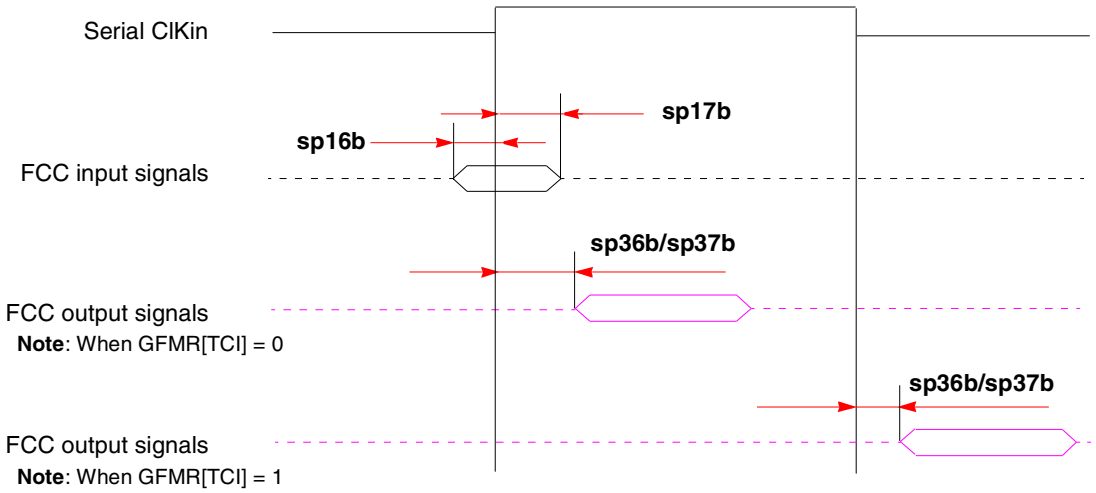


Figure 3. FCC External Clock Diagram

Figure 4 shows the FCC internal clock.

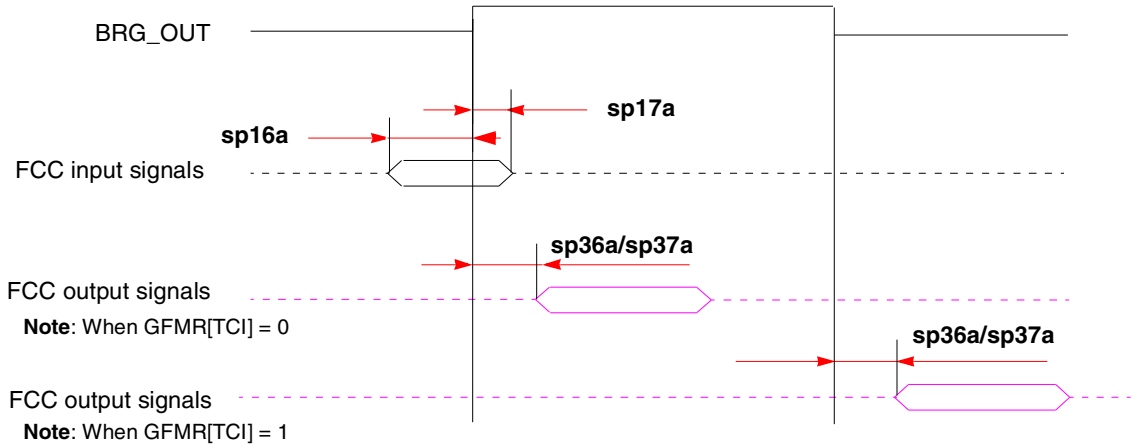
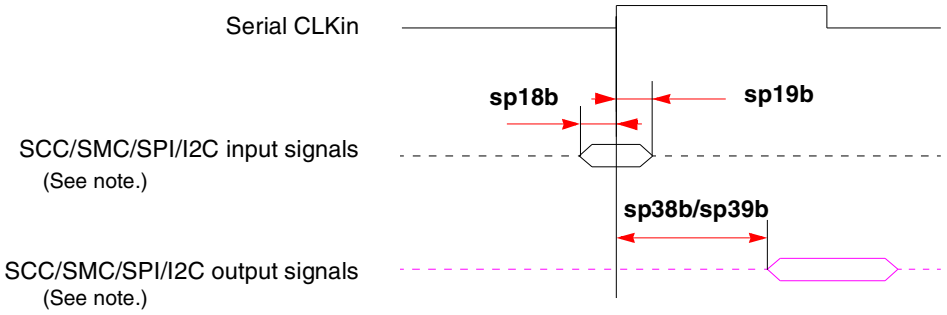


Figure 4. FCC Internal Clock Diagram

Figure 5 shows the SCC/SMC/SPI/I^{2}C external clock.

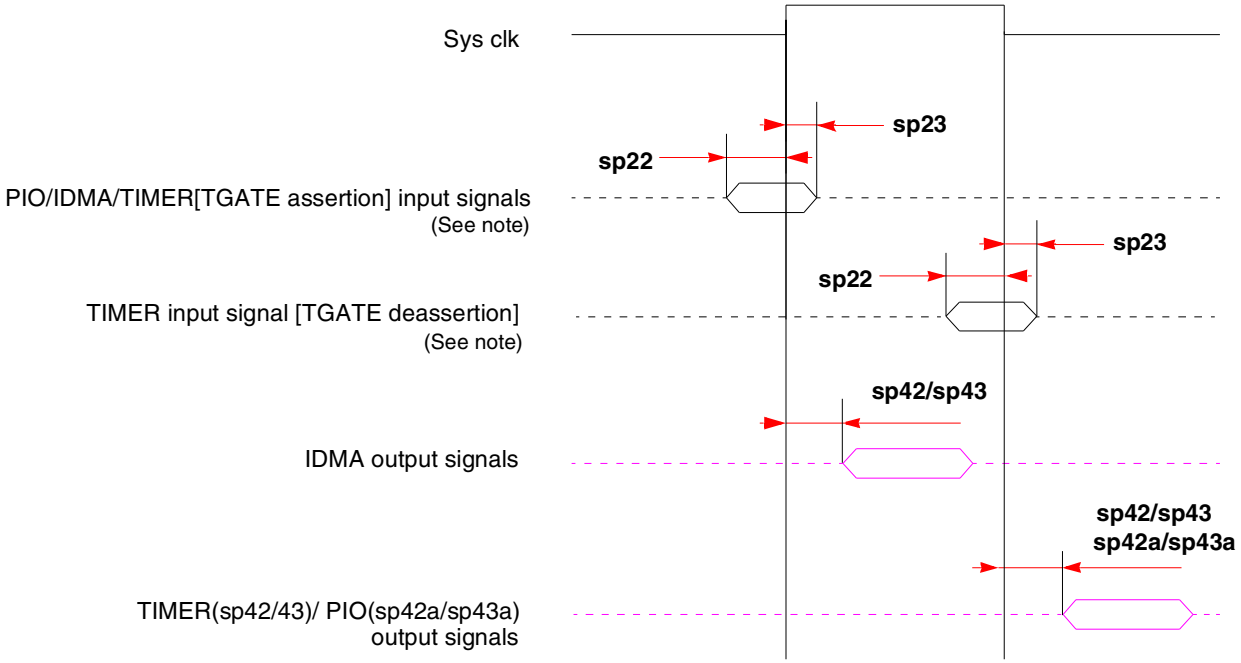


Note: There are four possible timing conditions for SCC and SPI:

1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 5. SCC/SMC/SPI/I^{2}C External Clock Diagram

Figure 8 shows PIO, timer, and DMA signals.



Note: TGATE is asserted on the rising edge of the clock; it is deasserted on the falling edge.

Figure 8. PIO, Timer, and DMA Signal Diagram

Table 10 lists SIU input characteristics.

Table 9. AC Characteristics for SIU Inputs[1]

Spec Number		Characteristic	Setup (ns)		Hold (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp11	sp10	$\overline{\text{AACK}}/\overline{\text{ARTRY}}/\overline{\text{TA}}/\overline{\text{TS}}/\overline{\text{TEA}}/\overline{\text{DBG}}/\overline{\text{BG}}/\overline{\text{BR}}$	6	5	0.5	0.5
sp12	sp10	Data bus in normal mode	5	4	0.5	0.5
sp13	sp10	Data bus in ECC and PARITY modes	8	6	0.5	0.5
sp14	sp10	DP pins	7	6	0.5	0.5
sp15	sp10	All other pins	5	4	0.5	0.5

[1] Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Table 10 lists SIU output characteristics.

Table 10. AC Characteristics for SIU Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp31	sp30	$\overline{\text{PSDVAL}}/\overline{\text{TEA}}/\overline{\text{TA}}$	7	6	0.5	0.5
sp32	sp30	ADD/ADD_atr./BADDR/CI/GBL/WT	8	6.5	0.5	0.5
sp33a	sp30	Data bus	6.5	6.5	0.5	0.5
sp33b	sp30	DP	8	7	0.5	0.5
sp34	sp30	Memory controller signals/ALE	6	5	0.5	0.5
sp35	sp30	All other signals	6	5.5	0.5	0.5

[1] Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

NOTE

Activating data pipelining (setting BR*x*[DR] in the memory controller) improves the AC timing. When data pipelining is activated, sp12 can be used for data bus setup even when ECC or PARITY are used. Also, sp33a can be used as the AC specification for DP signals.

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0100_111	Reserved				
0101_000					
0101_001					
0101_010					
0101_011					
0101_100					
0101_101	66 MHz	2	133 MHz	2	133 MHz
0101_110	**66 MHz**	**2**	**133 MHz**	**2.5**	**166 MHz**
0101_111	**66 MHz**	**2**	**133 MHz**	**3**	**200 MHz**
0110_000	66 MHz	2	133 MHz	3.5	233 MHz
0110_001	66 MHz	2	133 MHz	4	266 MHz
0110_010	66 MHz	2	133 MHz	4.5	300 MHz
0110_011	66 MHz	2.5	166 MHz	2	133 MHz
0110_100	**66 MHz**	**2.5**	**166 MHz**	**2.5**	**166 MHz**
0110_101	**66 MHz**	**2.5**	**166 MHz**	**3**	**200 MHz**
0110_110	66 MHz	2.5	166 MHz	3.5	233 MHz
0110_111	66 MHz	2.5	166 MHz	4	266 MHz
0111_000	66 MHz	2.5	166 MHz	4.5	300 MHz
0111_001	66 MHz	3	200 MHz	2	133 MHz
0111_010	66 MHz	3	200 MHz	2.5	166 MHz
0111_011	66 MHz	3	200 MHz	3	200 MHz
0111_100	66 MHz	3	200 MHz	3.5	233 MHz
0111_101	66 MHz	3	200 MHz	4	266 MHz
0111_110	66 MHz	3	200 MHz	4.5	300 MHz
0111_111	66 MHz	3.5	233 MHz	2	133 MHz
1000_000	66 MHz	3.5	233 MHz	2.5	166 MHz

3.2.1 PCI Host Mode

The frequencies listed in Table 16 and Table 17 are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user's device.

Table 16. Clock Default Configurations in PCI Host Mode (MODCK_HI = 0000)

MODCK[1–3][1]	Input Clock Frequency (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
000	66 MHz	2	133 MHz	2.5	166 MHz	2/4	66/33 MHz
001	66 MHz	2	133 MHz	3	200 MHz	2/4	66/33 MHz
010	66 MHz	2.5	166 MHz	3	200 MHz	3/6	55/28 MHz
011	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
100	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
101	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
110	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
111	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz

1 Assumes MODCK_HI = 0000.
2 The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic '1'), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) Refer to Table 15.

Table 17 describes all possible clock configurations when using the MPC8265's or the MPC8266's internal PCI bridge in host mode.

Table 17. Clock Configuration Modes in PCI Host Mode

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0001_000	33 MHz	3	100 MHz	5	166 MHz	3/6	33/16 MHz
0001_001	33 MHz	3	100 MHz	6	200 MHz	3/6	33/16 MHz
0001_010	33 MHz	3	100 MHz	7	233 MHz	3/6	33/16 MHz
0001_011	33 MHz	3	100 MHz	8	266 MHz	3/6	33/16 MHz
0010_000	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**	**4/8**	**33**/16 **MHz**
0010_001	33 MHz	4	133 MHz	6	200 MHz	4/8	33/16 MHz
0010_010	33 MHz	4	133 MHz	7	233 MHz	4/8	33/16 MHz
0010_011	33 MHz	4	133 MHz	8	266 MHz	4/8	33/16 MHz
0011_000[3]	33 MHz	5	166 MHz	5	166 MHz	5	**33 MHz**
0011_001[3]	33 MHz	5	166 MHz	6	200 MHz	5	33 MHz
0011_010[3]	33 MHz	5	166 MHz	7	233 MHz	5	33 MHz

Table 17. Clock Configuration Modes in PCI Host Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
0011_011[3]	33 MHz	5	166 MHz	8	266 MHz	5	33 MHz
0100_000[3]	33 MHz	6	200 MHz	5	166 MHz	6	33 MHz
0100_001[3]	33 MHz	6	200 MHz	6	200 MHz	6	33 MHz
0100_010[3]	33 MHz	6	200 MHz	7	233 MHz	6	33 MHz
0100_011[3]	33 MHz	6	200 MHz	8	266 MHz	6	33 MHz
0101_000	**66 MHz**	**2**	**133 MHz**	**2.5**	**166 MHz**	**2/4**	**66/33 MHz**
0101_001	**66 MHz**	**2**	**133 MHz**	**3**	**200 MHz**	**2**/4	**66**/33 **MHz**
0101_010	66 MHz	2	133 MHz	3.5	233 MHz	2/4	66/33 MHz
0101_011	66 MHz	2	133 MHz	4	266 MHz	2/4	66/33 MHz
0101_100	66 MHz	2	133 MHz	4.5	300 MHz	2/4	66/33 MHz
0110_000	**66 MHz**	**2.5**	**166 MHz**	**2.5**	**166 MHz**	3/6	**55/28 MHz**
0110_001	**66 MHz**	**2.5**	**166 MHz**	**3**	**200 MHz**	3/6	55/28 MHz
0110_010	66 MHz	2.5	166 MHz	3.5	233 MHz	3/6	55/28 MHz
0110_011	66 MHz	2.5	166 MHz	4	266 MHz	3/6	55/28 MHz
0110_100	66 MHz	2.5	166 MHz	4.5	300 MHz	3/6	55/28 MHz
0111_000	66 MHz	3	200 MHz	2.5	166 MHz	3/6	66/33 MHz
0111_001	66 MHz	3	200 MHz	3	200 MHz	3/6	66/33 MHz
0111_010	66 MHz	3	200 MHz	3.5	233 MHz	3/6	66/33 MHz
0111_011	66 MHz	3	200 MHz	4	266 MHz	3/6	66/33 MHz
0111_100	66 MHz	3	200 MHz	4.5	300 MHz	3/6	66/33 MHz
1000_000	66 MHz	3	200 MHz	2.5	166 MHz	4/8	50/25 MHz
1000_001	66 MHz	3	200 MHz	3	200 MHz	4/8	50/25 MHz
1000_010	66 MHz	3	200 MHz	3.5	233 MHz	4/8	50/25 MHz
1000_011	66 MHz	3	200 MHz	4	266 MHz	4/8	50/25 MHz
1000_100	66 MHz	3	200 MHz	4.5	300 MHz	4/8	50/25 MHz
1001_000	66 MHz	3.5	233 MHz	2.5	166 MHz	4/8	58/29 MHz
1001_001	66 MHz	3.5	233 MHz	3	200 MHz	4/8	58/29 MHz

Table 18. Clock Default Configurations in PCI Agent Mode (MODCK_HI = 0000) (continued)

MODCK[1–3][1]	Input Clock Frequency (PCI)[2]	CPM Multiplication Factor[2]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
100	66/33 MHz	3/6	200 MHz	3	240 MHz	2.5	80 MHz
101	66/33 MHz	3/6	200 MHz	3.5	280 MHz	2.5	80 MHz
110	66/33 MHz	4/8	266 MHz	3.5	300 MHz	3	88 MHz
111	66/33 MHz	4/8	266 MHz	3	300 MHz	2.5	100 MHz

1 Assumes MODCK_HI = 0000.
2 The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic '1'), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) and the CPM multiplication factor is multiplied by 2. Refer to Table 15.
3 Core frequency = (60x bus frequency)(core multiplication factor)
4 Bus frequency = CPM frequency/bus division factor

Table 19 describes all possible clock configurations when using the MPC8265 or the MPC8266's internal PCI bridge in agent mode.

Table 19. Clock Configuration Modes in PCI Agent Mode

MODCK_H – MODCK[1–3]	Input Clock Frequency (PCI)[1,2]	CPM Multiplication Factor[1]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
0001_001	66/33 MHz	2/4	133 MHz	5	166 MHz	4	33 MHz
0001_010	66/33 MHz	2/4	133 MHz	6	200 MHz	4	33 MHz
0001_011	66/33 MHz	2/4	133 MHz	7	233 MHz	4	33 MHz
0001_100	66/33 MHz	2/4	133 MHz	8	266 MHz	4	33 MHz
0010_001	50/25 MHz	3/6	**150 MHz**	3	180 MHz	2.5	**60 MHz**
0010_010	50/25 MHz	3/6	**150 MHz**	3.5	210 MHz	2.5	**60 MHz**
0010_011	50/25 MHz	3/6	**150 MHz**	4	240 MHz	2.5	**60 MHz**
0010_100	50/25 MHz	3/6	**150 MHz**	4.5	270 MHz	2.5	**60 MHz**
0011_000	66/33 MHz	2/4	**133 MHz**	2.5	110MHz	3	44 MHz
0011_001	66/33 MHz	2/4	**133 MHz**	3	132 MHz	3	44 MHz
0011_010	66/33 MHz	2/4	**133 MHz**	3.5	154 MHz	3	**44 MHz**
0011_011	66/33 MHz	2/4	**133 MHz**	4	176MHz	3	**44 MHz**
0011_100	66/33 MHz	2/4	**133 MHz**	4.5	198 MHz	3	**44 MHz**
0100_000	66/33 MHz	3/6	200 MHz	2.5	166 MHz	**3**	66 MHz
0100_001	66/33 MHz	3/6	**200 MHz**	3	200 MHz	**3**	**66 MHz**
0100_010	66/33 MHz	3/6	**200 MHz**	3.5	233 MHz	**3**	**66 MHz**
0100_011	66/33 MHz	3/6	**200 MHz**	4	266 MHz	**3**	**66 MHz**

4 Pinout

This section provides the pin assignments and pinout list for the MPC826xA.

4.1 Pin Assignments

Figure 13 shows the pinout of the MPC826xA's 480 TBGA package as viewed from the top surface.

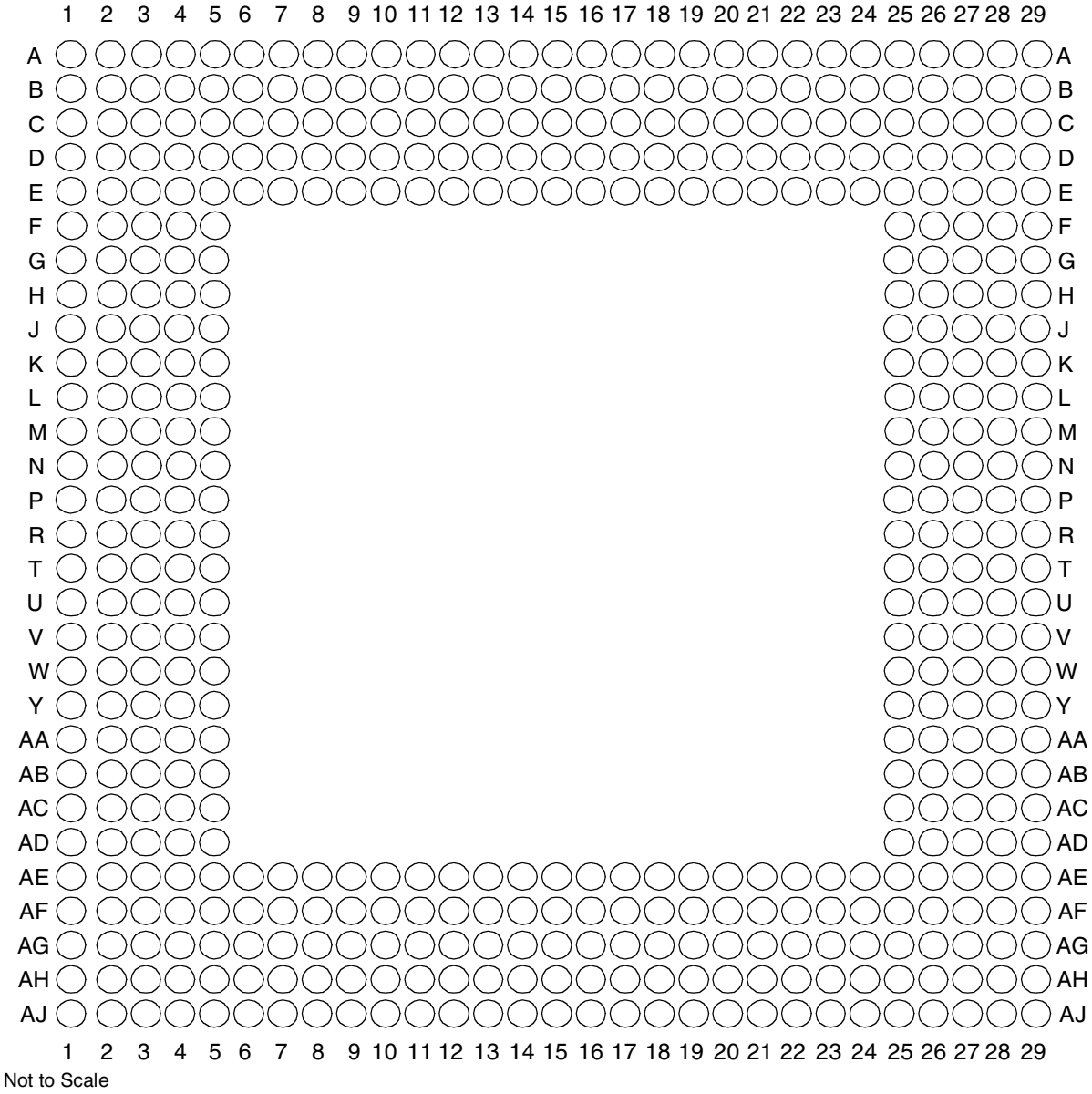


Figure 13. Pinout of the 480 TBGA Package as Viewed from the Top Surface

Figure 14 shows the side profile of the TBGA package to indicate the direction of the top surface view.

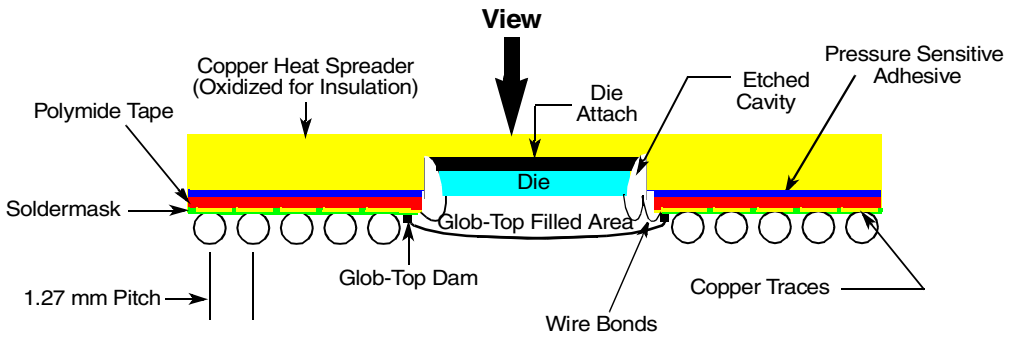


Figure 14. Side View of the TBGA Package

Table 21 shows the pinout list of the MPC826xA. Table 20 defines conventions and acronyms used in Table 21.

Symbols used in Table 21 are described in Table 20.

Table 20. Symbol Legend

Symbol	Meaning
OVERBAR	Signals with overbars, such as $\overline{TA}$, are active low.
UTM	Indicates that a signal is part of the UTOPIA master interface.
UTS	Indicates that a signal is part of the UTOPIA slave interface.
UT8	Indicates that a signal is part of the 8-bit UTOPIA interface.
UT16	Indicates that a signal is part of the 16-bit UTOPIA interface.
MII	Indicates that a signal is part of the media independent interface.

Table 21. Pinout List

Pin Name	Ball
BR	W5
BG	F4
ABB/IRQ2	E2
TS	E3
A0	G1
A1	H5
A2	H2
A3	H1
A4	J5
A5	J4
A6	J3
A7	J2