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Understanding Embedded - Microprocessors

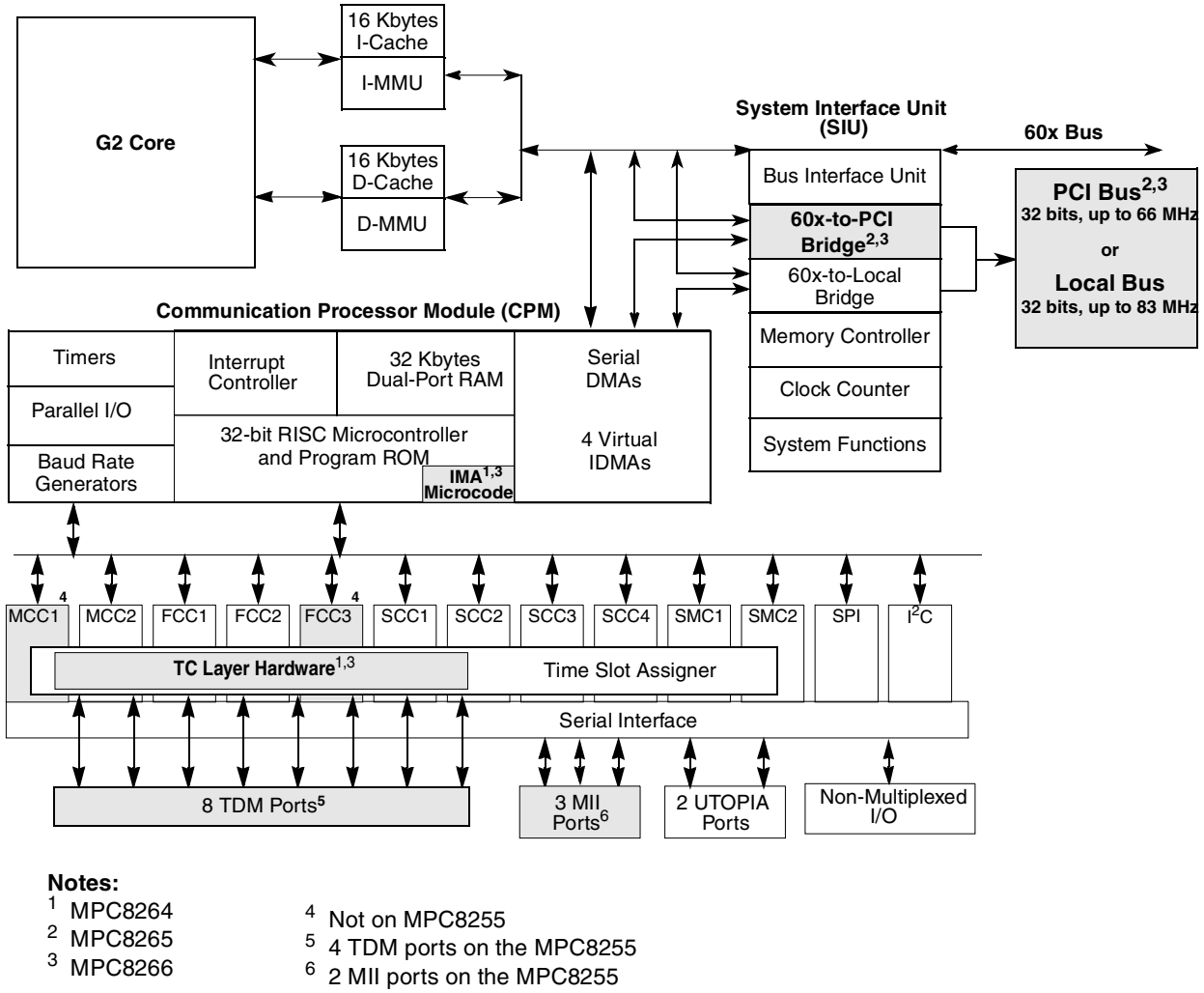
Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Active
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	300MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mpc8260azupjdb

Figure 1 shows the block diagram for the MPC8266, the HiP4 superset device. Shaded portions indicate functionality that is not available on all devices; refer to the notes.



Notes:
1 MPC8264
2 MPC8265
3 MPC8266
4 Not on MPC8255
5 4 TDM ports on the MPC8255
6 2 MII ports on the MPC8255

Figure 1. MPC8266 Block Diagram

1 Features

The major features of the MPC826xA family are as follows:

- Dual-issue integer core
  - A core version of the EC603e microprocessor
  - System core microprocessor supporting frequencies of 150–300 MHz
  - Separate 16-Kbyte data and instruction caches:
    - Four-way set associative
    - Physically addressed
    - LRU replacement algorithm

  - PowerPC architecture-compliant memory management unit (MMU)
  - Common on-chip processor (COP) test interface
  - High-performance (6.6–7.65 SPEC95 benchmark at 300 MHz; 1.68 MIPs/MHz without inlining and 1.90 Dhrystones MIPS/MHz with
  - Supports bus snooping for data cache coherency
  - Floating-point unit (FPU)
- Separate power supply for internal logic and for I/O
- Separate PLLs for G2 core and for the CPM
  - G2 core and CPM can run at different frequencies for power/performance optimization
  - Internal core/bus clock multiplier that provides 1.5:1, 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
  - Internal CPM/bus clock multiplier that provides 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
- 64-bit data and 32-bit address 60x bus
  - Bus supports multiple master designs
  - Supports single- and four-beat burst transfers
  - 64-, 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
  - Supports data parity or ECC and address parity
- 32-bit data and 18-bit address local bus
  - Single-master bus, supports external slaves
  - Eight-beat burst transfers
  - 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
- 60x-to-PCI bridge (MPC8265 and MPC8266 only)
  - Programmable host bridge and agent
  - 32-bit data bus, 66 MHz, 3.3 V
  - Synchronous and asynchronous 60x and PCI clock modes
  - All internal address space available to external PCI host
  - DMA for memory block transfers
  - PCI-to-60x address remapping
- System interface unit (SIU)
  - Clock synthesizer
  - Reset controller
  - Real-time clock (RTC) register
  - Periodic interrupt timer
  - Hardware bus monitor and software watchdog timer
  - IEEE Std. 1149.1™ standard JTAG test access port
- Twelve-bank memory controller
  - Glueless interface to SRAM, page mode SDRAM, DRAM, EPROM, Flash and other user-definable peripherals
  - Byte write enables and selectable parity generation

  - 32-bit address decodes with programmable bank size
  - Three user programmable machines, general-purpose chip-select machine, and page-mode pipeline SDRAM machine
  - Byte selects for 64 bus width (60x) and byte selects for 32 bus width (local)
  - Dedicated interface logic for SDRAM
- CPU core can be disabled and the device can be used in slave mode to an external core
- Communications processor module (CPM)
  - Embedded 32-bit communications processor (CP) uses a RISC architecture for flexible support for communications protocols
  - Interfaces to G2 core through on-chip 32-Kbyte dual-port RAM and DMA controller
  - Serial DMA channels for receive and transmit on all serial channels
  - Parallel I/O registers with open-drain and interrupt capability
  - Virtual DMA functionality executing memory-to-memory and memory-to-I/O transfers
  - Three fast communications controllers supporting the following protocols (only FCC1 and FCC2 on the MPC8255):
    - 10/100-Mbit Ethernet/IEEE Std. 802.3® CDMA/CS interface through media independent interface (MII)
    - ATM—Full-duplex SAR protocols at 155 Mbps, through UTOPIA interface, AAL5, AAL1, AAL0 protocols, TM 4.0 CBR, VBR, UBR, ABR traffic types, up to 16 K external connections
    - Transparent
    - HDLC—Up to T3 rates (clear channel)
  - Two multichannel controllers (MCCs) (only MCC2 on the MPC8255)
    - Each MCC handles 128 serial, full-duplex, 64-Kbps data channels.Each MCC can be split into four subgroups of 32 channels each.
    - Almost any combination of subgroups can be multiplexed to single or multiple TDM interfaces up to four TDM interfaces per MCC
  - Four serial communications controllers (SCCs) identical to those on the MPC860, supporting the digital portions of the following protocols:
    - Ethernet/IEEE 802.3 CDMA/CS
    - HDLC/SDLC and HDLC bus
    - Universal asynchronous receiver transmitter (UART)
    - Synchronous UART
    - Binary synchronous (BISYNC) communications
    - Transparent
  - Two serial management controllers (SMCs), identical to those of the MPC860
    - Provide management for BRI devices as general circuit interface (GCI) controllers in time-division-multiplexed (TDM) channels

— Hot-Swap friendly (supports the Hot Swap Specification as defined by PICMG 2.1 R1.0 August 3, 1998)
— Support for 66 MHz, 3.3 V specification
— 60x-PCI bus core logic which uses a buffer pool to allocate buffers for each port
— Makes use of the local bus signals, so there is no need for additional pins

2 Electrical and Thermal Characteristics

This section provides AC and DC electrical specifications and thermal characteristics for the MPC826xA.

2.1 DC Electrical Characteristics

This section describes the DC electrical characteristics for the MPC826xA. Table 1 shows the maximum electrical ratings.

Table 1. Absolute Maximum Ratings[1]

Rating	Symbol	Value	Unit
Core supply voltage[2]	VDD	–0.3 – 2.5	V
PLL supply voltage[2]	VCCSYN	–0.3 – 2.5	V
I/O supply voltage[3]	VDDH	–0.3 – 4.0	V
Input voltage[4]	VIN	GND(–0.3) – 3.6	V
Junction temperature	T_j	120	°C
Storage temperature range	T_{STG}	(–55) – (+150)	°C

1 Absolute maximum ratings are stress ratings only; functional operation (see Table 2) at the maximums is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage.
2 **Caution:** VDD/VCCSYN must not exceed VDDH by more than 0.4 V at any time, including during power-on reset.
3 **Caution:** VDDH can exceed VDD/VCCSYN by 3.3 V during power on reset by no more than 100 mSec. VDDH should not exceed VDD/VCCSYN by more than 2.5 V during normal operation.
4 **Caution:** VIN must not exceed VDDH by more than 2.5 V at any time, including during power-on reset.

Table 2 lists recommended operational voltage conditions.

Table 2. Recommended Operating Conditions[1]

Rating	Symbol	Value			Unit
Core supply voltage	VDD	1.7 – 1.9[2]	1.7–2.1[3]	1.9 –2.2[4]	V
PLL supply voltage	VCCSYN	1.7 – 1.9[2]	1.7–2.1[3]	1.9–2.2[4]	V
I/O supply voltage	VDDH	3.135 – 3.465			V
Input voltage	VIN	GND (–0.3) – 3.465			V
Junction temperature (maximum)	T_j	105[5]			°C
Ambient temperature	T_A	0–70[5]			°C

1 **Caution:** These are the recommended and tested operating conditions. Proper device operating outside of these conditions is not guaranteed.
2 CPU frequency less than or equal to 200 MHz.
3 CPU frequency greater than 200 MHz but less than 233 MHz.
4 CPU frequency greater than or equal to 233 MHz.
5 Note that for extended temperature parts the range is $(-40)_{T_A} – 105_{T_j}$.

NOTE: Core, PLL, and I/O Supply Voltages

VDDH, VCCSYN, and VDD must track each other and both must vary in the same direction—in the positive direction (+5% and +0.1 Vdc) or in the negative direction (–5% and –0.1 Vdc).

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (either GND or V_{CC}).

Figure 2 shows the undershoot and overshoot voltage of the 60x and local bus memory interface of the MPC8280. Note that in PCI mode the I/O interface is different.

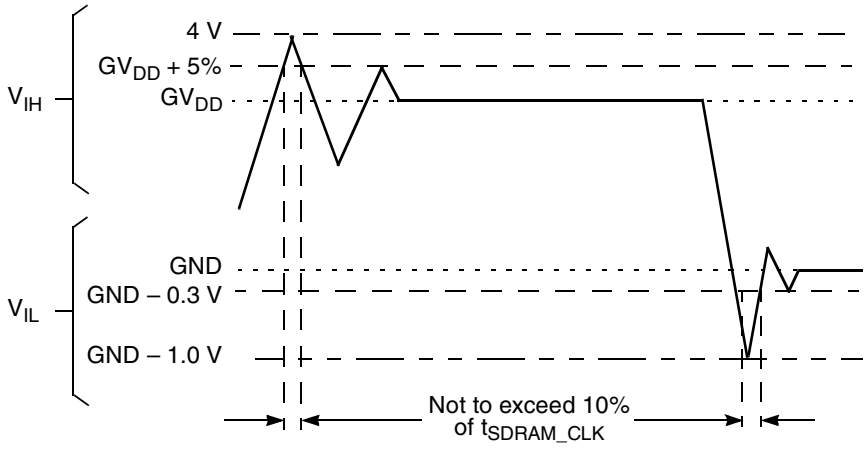


Figure 2. Overshoot/Undershoot Voltage

Table 3. DC Electrical Characteristics[1] (continued)

Characteristic	Symbol	Min	Max	Unit
I_{OL} = 5.3mA CS[0-9] CS(10)/BCTL1 CS(11)/AP(0) BADDR[27–28] ALE BCTL0 PWE(0:7)/PSDDQM(0:7)/PBS(0:7) PSDA10/PGPL0 PSDWE/PGPL1 POE/PSDRAS/PGPL2 PSDCAS/PGPL3 PGTA/PUPMWAIT/PGPL4/PPBS PSDAMUX/PGPL5 LWE[0–3]LSDDQM[0–3]/LBS[0–3]/PCI_CFG[0–3][3] LSDA10/LGPL0/PCI_MODCKH0[3] LSDWE/LGPL1/PCI_MODCKH1[3] LOE/LSDRAS/LGPL2/PCI_MODCKH2[3] LSDCAS/LGPL3/PCI_MODCKH3[3] LGTA/LUPMWAIT/LGPL4/LPBS LSDAMUX/LGPL5/PCI_MODCK[3] LWR MODCK1/AP(1)/TC(0)/BNKSEL(0) MODCK2/AP(2)/TC(1)/BNKSEL(1) MODCK3/AP(3)/TC(2)/BNKSEL(2)	V_{OL}	—	0.4	V
I_{OL} = 3.2mA L_A14/PAR[3] L_A15/FRAME[3]/SMI L_A16/TRDY[3] L_A17/IRDY[3]/CKSTP_OUT L_A18/STOP[3] L_A19/DEVSEL[3] L_A20/IDSEL[3] L_A21/PERR[3] L_A22/SERR[3] L_A23/REQ0[3] L_A24/REQ1[3]/HSEJSW[3] L_A25/GNT0[3] L_A26/GNT1[3]/HSLED[3] L_A27/GNT2[3]/HSENUM[3] L_A28/RST[3]/CORE_SRESET L_A29/INTA[3] L_A30/REQ2[3] L_A31 LCL_D(0-31)/AD(0-31)[3] LCL_DP(0-3)/C/BE(0-3)[3] PA[0–31] PB[4–31] PC[0–31] PD[4–31] TDO				

1 The default configuration of the CPM pins (PA[0–31], PB[4–31], PC[0–31], PD[4–31]) is input. To prevent excessive DC current, it is recommended to either pull unused pins to GND or VDDH, or to configure them as outputs.

2.4 AC Electrical Characteristics

The following sections include illustrations and tables of clock diagrams, signals, and CPM outputs and inputs for the 66 MHz MPC826xA device. Note that AC timings are based on a 50-p*f* load. Typical output buffer impedances are shown in Table 6.

Table 6. Output Buffer Impedances[1]

Output Buffers	Typical Impedance (Ω)
60x bus	40
Local bus	40
Memory controller	40
Parallel I/O	46
PCI	25

1 These are typical values at 65° C. The impedance may vary by ±25% with process and temperature.

Table 7 lists CPM output characteristics.

Table 7. AC Characteristics for CPM Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp36a	sp37a	FCC outputs—internal clock (NMSI)	6	5.5	1	1
sp36b	sp37b	FCC outputs—external clock (NMSI)	14	12	2	1
sp40	sp41	TDM outputs/SI	25	16	5	4
sp38a	sp39a	SCC/SMC/SPI/I2C outputs—internal clock (NMSI)	19	16	1	0.5
sp38b	sp39b	Ex_SCC/SMC/SPI/I2C outputs—external clock (NMSI)	19	16	2	1
sp42	sp43	TIMER/IDMA outputs	14	11	1	0.5
sp42a	sp43a	PIO outputs	14	11	0.5	0.5

1 Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

Figure 4 shows the FCC internal clock.

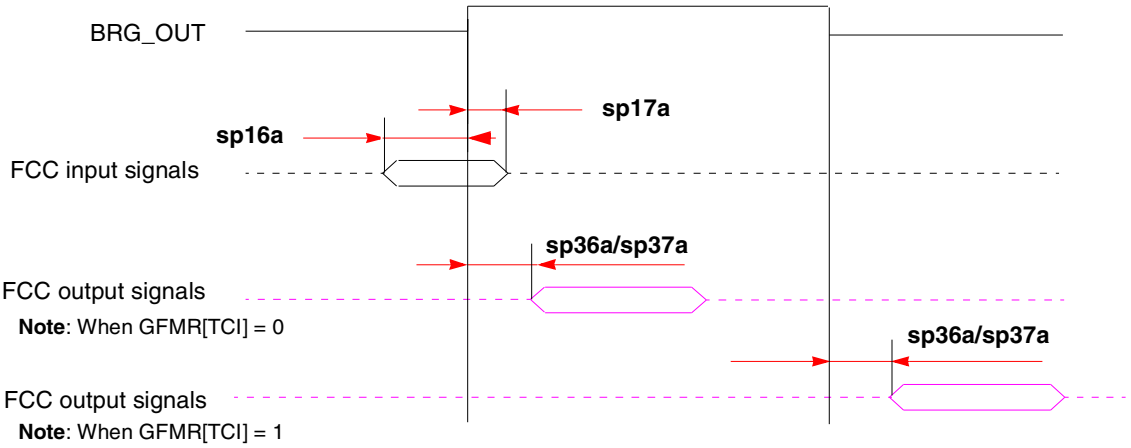
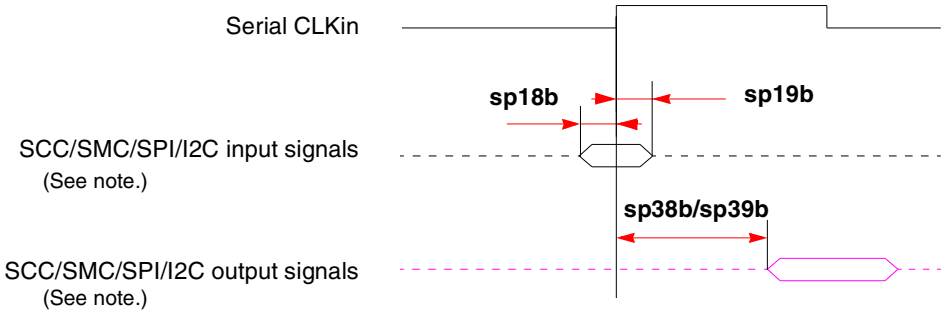


Figure 4. FCC Internal Clock Diagram

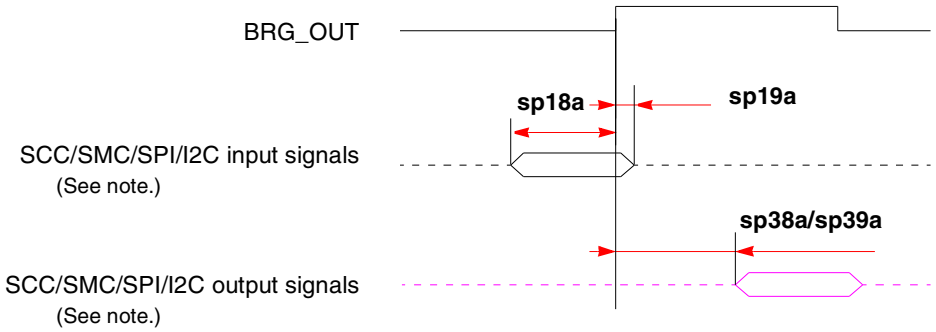
Figure 5 shows the SCC/SMC/SPI/I^2C external clock.



Note: There are four possible timing conditions for SCC and SPI:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 5. SCC/SMC/SPI/I^2C External Clock Diagram

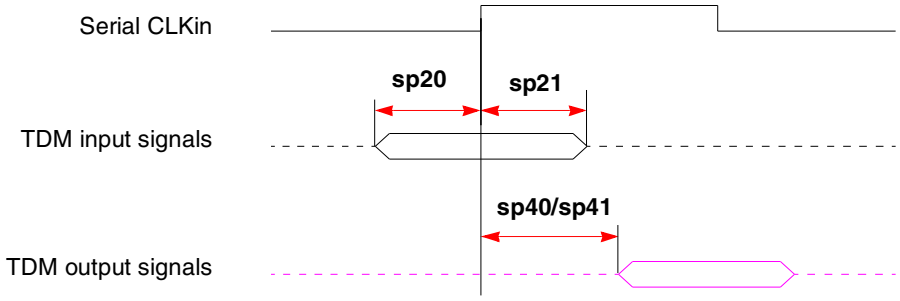
Figure 6 shows the SCC/SMC/SPI/I^{2}C internal clock.



Note: There are four possible timing conditions for SCC and SPI:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 6. SCC/SMC/SPI/I^{2}C Internal Clock Diagram

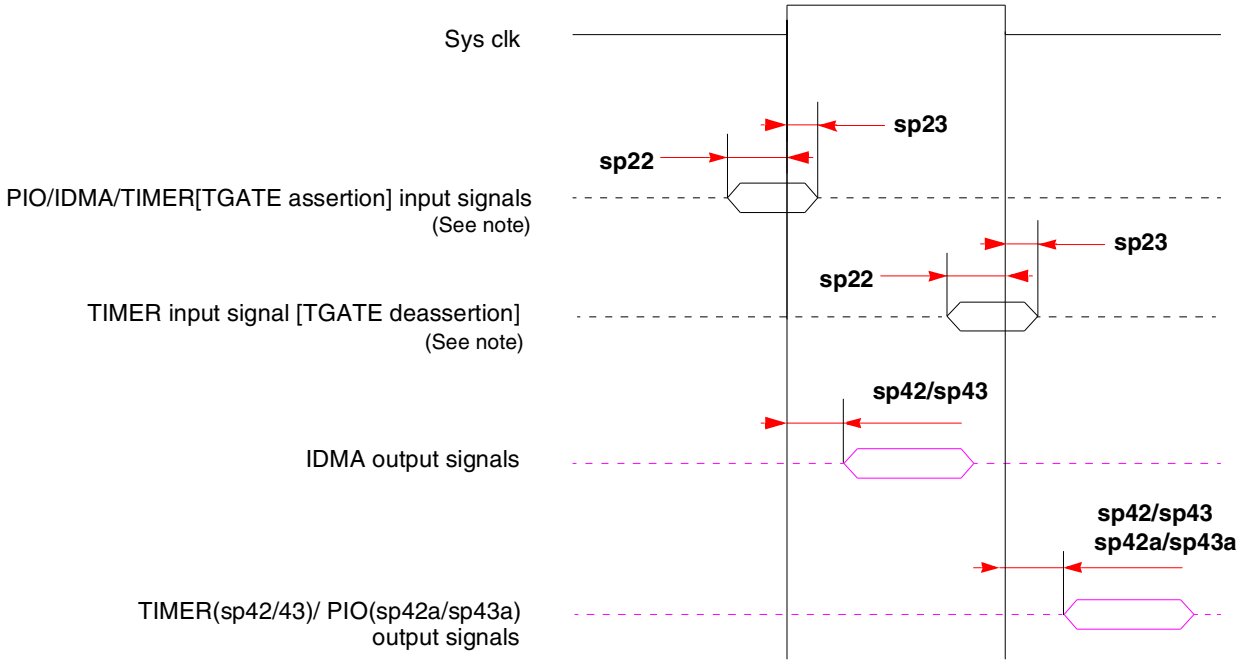
Figure 7 shows TDM input and output signals.



Note: There are four possible TDM timing conditions:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 7. TDM Signal Diagram

Figure 8 shows PIO, timer, and DMA signals.



Note: TGATE is asserted on the rising edge of the clock; it is deasserted on the falling edge.

Figure 8. PIO, Timer, and DMA Signal Diagram

Table 10 lists SIU input characteristics.

Table 9. AC Characteristics for SIU Inputs[1]

Spec Number		Characteristic	Setup (ns)		Hold (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp11	sp10	$\overline{\text{AACK}}/\overline{\text{ARTRY}}/\overline{\text{TA}}/\overline{\text{TS}}/\overline{\text{TEA}}/\overline{\text{DBG}}/\overline{\text{BG}}/\overline{\text{BR}}$	6	5	0.5	0.5
sp12	sp10	Data bus in normal mode	5	4	0.5	0.5
sp13	sp10	Data bus in ECC and PARITY modes	8	6	0.5	0.5
sp14	sp10	DP pins	7	6	0.5	0.5
sp15	sp10	All other pins	5	4	0.5	0.5

1 Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Figure 9 shows the interaction of several bus signals.

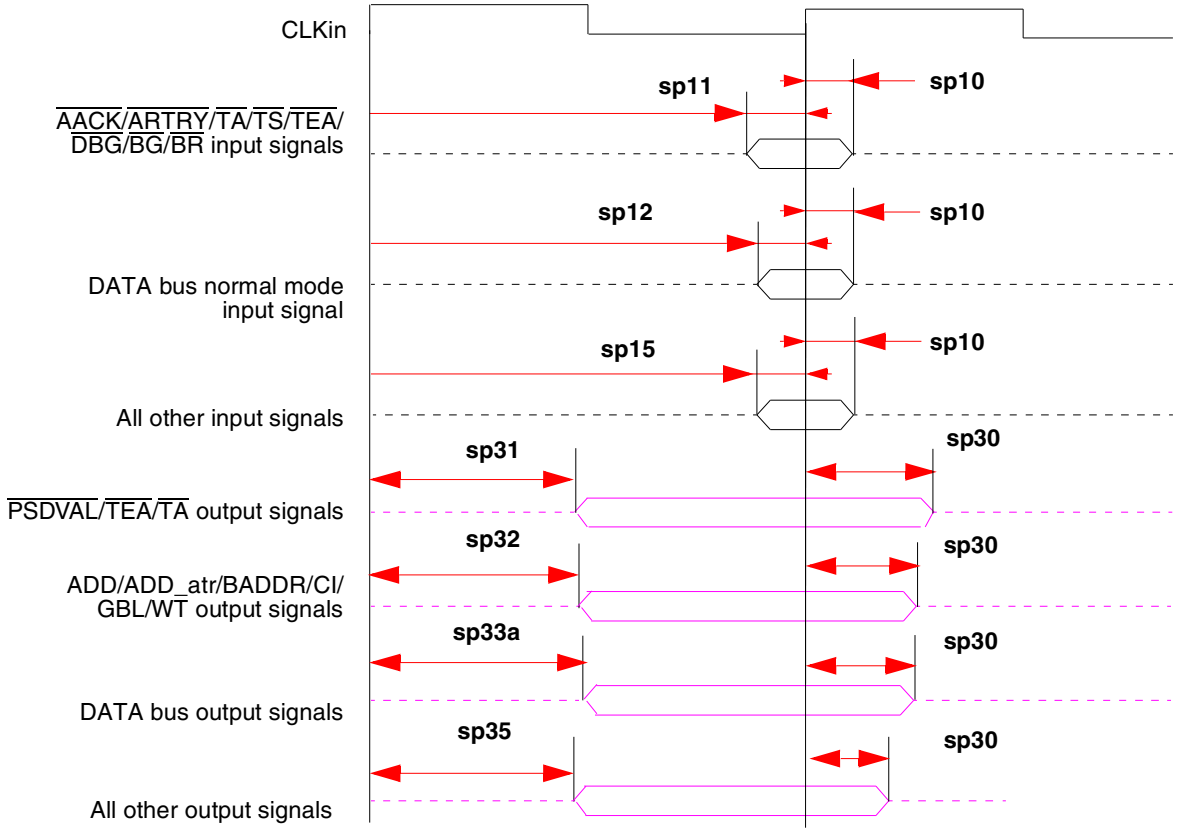


Figure 9. Bus Signals

Figure 10 shows signal behavior for all parity modes (including ECC, RMW parity, and standard parity).

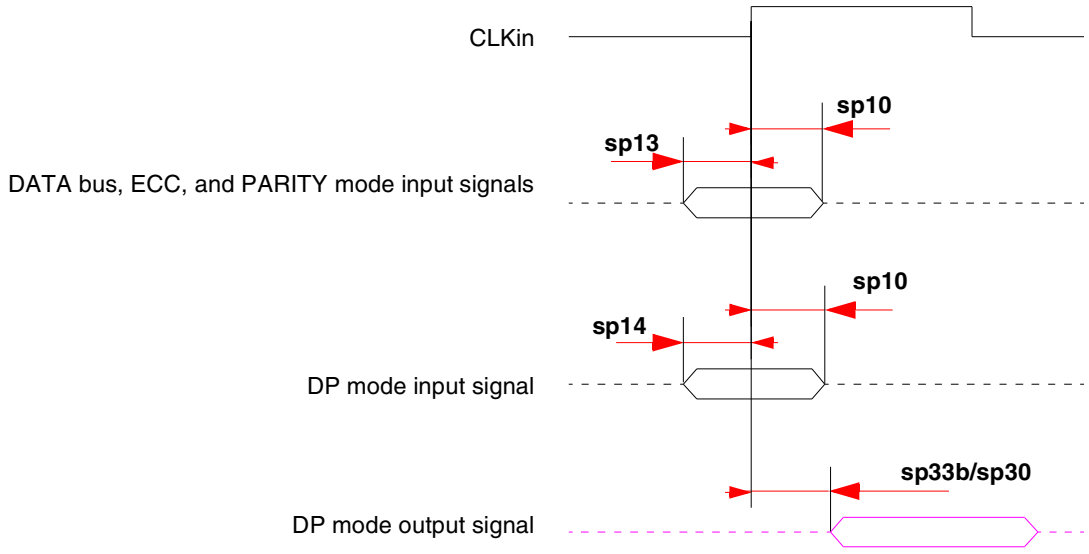


Figure 10. Parity Mode Diagram

Figure 11 shows signal behavior in MEMC mode.

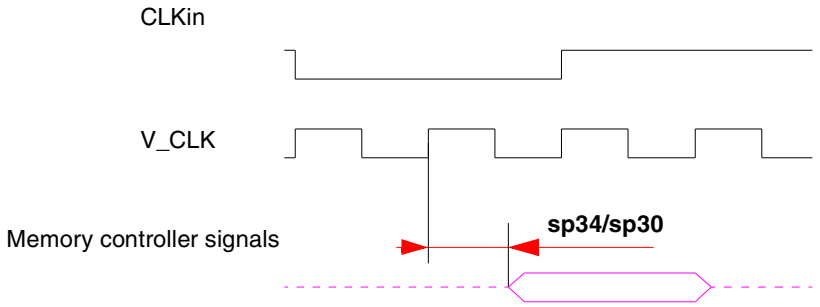


Figure 11. MEMC Mode Diagram

NOTE

Generally, all MPC826xA bus and system output signals are driven from the rising edge of the input clock (CLKin). Memory controller signals, however, trigger on four points within a CLKin cycle. Each cycle is divided by four internal ticks: T1, T2, T3, and T4. T1 always occurs at the rising edge, and T3 at the falling edge, of CLKin. However, the spacing of T2 and T4 depends on the PLL clock ratio selected, as shown in Table 11.

Table 11. Tick Spacing for Memory Controller Signals

PLL Clock Ratio	Tick Spacing (T1 Occurs at the Rising Edge of CLKin)		
	T2	T3	T4
1:2, 1:3, 1:4, 1:5, 1:6	1/4 CLKin	1/2 CLKin	3/4 CLKin
1:2.5	3/10 CLKin	1/2 CLKin	8/10 CLKin
1:3.5	4/14 CLKin	1/2 CLKin	11/14 CLKin

Figure 12 is a graphical representation of Table 11.

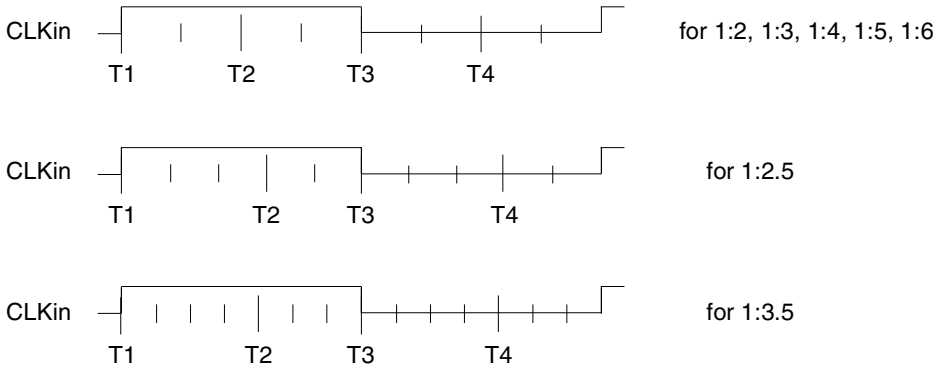


Figure 12. Internal Tick Spacing for Memory Controller Signals

3 Clock Configuration Modes

To configure the main PLL multiplication factor and the core, CPM, and 60x bus frequencies, the MODCK[1–3] pins are sampled while $\overline{\text{HRESET}}$ is asserted. Table 13 lists the eight basic configuration modes. Table 14 lists the other modes that are available by using the configuration pin ($\overline{\text{RSTCONF}}$) and driving four bits from hardware configuration word on the data bus.

Note that the MPC8265 and the MPC8266 have two additional clocking modes—PCI agent and PCI host. Refer to Section 3.2, “PCI Mode” on page 26 for information.

NOTE

Clock configurations change only after $\overline{\text{POR}}$ is asserted.

3.1 Local Bus Mode

Table 13 describes default clock modes for the MPC826xA.

Table 13. Clock Default Modes

MODCK[1–3]	Input Clock Frequency	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency
000	33 MHz	3	100 MHz	4	133 MHz
001	33 MHz	3	100 MHz	5	166 MHz
010	33 MHz	4	133 MHz	4	133 MHz
011	33 MHz	4	133 MHz	5	166 MHz
100	66 MHz	2	133 MHz	2.5	166 MHz
101	66 MHz	2	133 MHz	3	200 MHz
110	66 MHz	2.5	166 MHz	2.5	166 MHz
111	66 MHz	2.5	166 MHz	3	200 MHz

Table 14 describes all possible clock configurations when using the hard reset configuration sequence. Note that basic modes are shown in boldface type. The frequencies listed are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user’s device.

Table 14. Clock Configuration Modes[1]

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0001_000	33 MHz	2	66 MHz	4	133 MHz
0001_001	33 MHz	2	66 MHz	5	166 MHz
0001_010	33 MHz	2	66 MHz	6	200 MHz
0001_011	33 MHz	2	66 MHz	7	233 MHz
0001_100	33 MHz	2	66 MHz	8	266 MHz

Table 17. Clock Configuration Modes in PCI Host Mode (continued)

MODCK_H – MODCK[1–3]	Input Clock Frequency[1] (Bus)	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency	PCI Division Factor[2]	PCI Frequency[2]
1001_010	66 MHz	3.5	233 MHz	3.5	233 MHz	4/8	58/29 MHz
1001_011	66 MHz	3.5	233 MHz	4	266 MHz	4/8	58/29 MHz
1001_100	66 MHz	3.5	233 MHz	4.5	300 MHz	4/8	58/29 MHz
1010_000	100 MHz	2	200 MHz	2	200 MHz	3/6	66/33 MHz
1010_001	100 MHz	2	200 MHz	2.5	250 MHz	3/6	66/33 MHz
1010_010	100 MHz	2	200 MHz	3	300 MHz	3/6	66/33 MHz
1010_011	100 MHz	2	200 MHz	3.5	350 MHz	3/6	66/33 MHz
1010_100	100 MHz	2	200 MHz	4	400 MHz	3/6	66/33 MHz
1011_000	100 MHz	2.5	250 MHz	2	200 MHz	4/8	62/31 MHz
1011_001	100 MHz	2.5	250 MHz	2.5	250 MHz	4/8	62/31MHz
1011_010	100 MHz	2.5	250 MHz	3	300 MHz	4/8	62/31 MHz
1011_011	100 MHz	2.5	250 MHz	3.5	350 MHz	4/8	62/31 MHz
1011_100	100 MHz	2.5	250 MHz	4	400 MHz	4/8	62/31 MHz

1 Input clock frequency is given only for the purpose of reference. User should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user's part.

2 The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic '1'), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.). Refer to Table 15.

3 In this mode, PCI_MODCK must be "0".

3.2.2 PCI Agent Mode

The frequencies listed in Table 18 and Table 19 are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user's device.

Table 18. Clock Default Configurations in PCI Agent Mode (MODCK_HI = 0000)

MODCK[1–3][1]	Input Clock Frequency (PCI)[2]	CPM Multiplication Factor[2]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
000	66/33 MHz	2/4	133 MHz	2.5	166 MHz	2	66 MHz
001	66/33 MHz	2/4	133 MHz	3	200 MHz	2	66 MHz
010	66/33 MHz	3/6	200 MHz	3	200 MHz	3	66 MHz
011	66/33 MHz	3/6	200 MHz	4	266 MHz	3	66 MHz

Figure 14 shows the side profile of the TBGA package to indicate the direction of the top surface view.

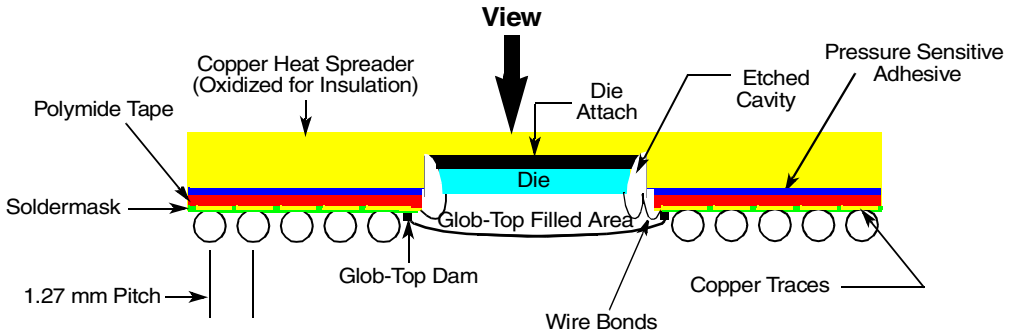


Figure 14. Side View of the TBGA Package

Table 21 shows the pinout list of the MPC826xA. Table 20 defines conventions and acronyms used in Table 21.

Symbols used in Table 21 are described in Table 20.

Table 20. Symbol Legend

Symbol	Meaning
OVERBAR	Signals with overbars, such as $\overline{TA}$, are active low.
UTM	Indicates that a signal is part of the UTOPIA master interface.
UTS	Indicates that a signal is part of the UTOPIA slave interface.
UT8	Indicates that a signal is part of the 8-bit UTOPIA interface.
UT16	Indicates that a signal is part of the 16-bit UTOPIA interface.
MII	Indicates that a signal is part of the media independent interface.

Table 21. Pinout List

Pin Name	Ball
BR	W5
BG	F4
ABB/IRQ2	E2
TS	E3
A0	G1
A1	H5
A2	H2
A3	H1
A4	J5
A5	J4
A6	J3
A7	J2

Table 21. Pinout List (continued)

Pin Name	Ball
ARTRY	E1
DBG	V1
DBB/IRQ3	V2
D0	B20
D1	A18
D2	A16
D3	A13
D4	E12
D5	D9
D6	A6
D7	B5
D8	A20
D9	E17
D10	B15
D11	B13
D12	A11
D13	E9
D14	B7
D15	B4
D16	D19
D17	D17
D18	D15
D19	C13
D20	B11
D21	A8
D22	A5
D23	C5
D24	C19
D25	C17
D26	C15
D27	D13
D28	C11
D29	B8
D30	A4
D31	E6

Table 21. Pinout List (continued)

Pin Name	Ball
LCL_D31/AD31[1]	AA28
LCL_DP0/C0[1]/$\overline{\text{BE0}}$[1]	L28
LCL_DP1/C1[1]/$\overline{\text{BE1}}$[1]	N28
LCL_DP2/C2[1]/$\overline{\text{BE2}}$[1]	T28
LCL_DP3/C3[1]/$\overline{\text{BE3}}$[1]	W28
IRQ0/NMI_OUT	T1
IRQ7/INT_OUT/APE	D1
TRST	AH3
TCK	AG5
TMS	AJ3
TDI	AE6
TDO	AF5
TRIS	AB4
PORESET	AG6
HRESET	AH5
SRESET	AF6
QREQ	AA3
RSTCONF	AJ4
MODCK1/AP1/TC0/BNKSEL0	W2
MODCK2/AP2/TC1/BNKSEL1	W3
MODCK3/AP3/TC2/BNKSEL2	W4
XFC	AB2
CLKIN1	AH4
PA0/$\overline{\text{RESTART1}}$/DREQ3/FCC2_UTM_TXADDR2	AC29[2]
PA1/$\overline{\text{REJECT1}}$/FCC2_UTM_TXADDR1/$\overline{\text{DONE3}}$	AC25[2]
PA2/CLK20/FCC2_UTM_TXADDR0/$\overline{\text{DACK3}}$	AE28[2]
PA3/CLK19/FCC2_UTM_RXADDR0/$\overline{\text{DACK4}}$/L1RXD1A2	AG29[2]
PA4/$\overline{\text{REJECT2}}$/FCC2_UTM_RXADDR1/$\overline{\text{DONE4}}$	AG28[2]
PA5/$\overline{\text{RESTART2}}$/DREQ4/FCC2_UTM_RXADDR2	AG26[2]
PA6/L1RSYNCA1	AE24[2]
PA7/SMSYN2/L1TSYNCA1/L1GNTA1	AH25[2]
PA8/SMRXD2/L1RXD0A1/L1RXDA1	AF23[2]
PA9/SMTXD2/L1TXD0A1	AH23[2]
PA10/FCC1_UT8_RXD0/FCC1_UT16_RXD8/MSNUM5	AE22[2]
PA11/FCC1_UT8_RXD1/FCC1_UT16_RXD9/MSNUM4	AH22[2]

Table 21. Pinout List (continued)

Pin Name	Ball
PB18/FCC2_UT8_RXD4/FCC2_RXD3/L1CLKOD2/L1RXD2A2	AE14[2]
PB19/FCC2_UT8_RXD5/FCC2_RXD2/L1RQD2/L1RXD3A2	AF13[2]
PB20/FCC2_UT8_RXD6/FCC2_RXD1/L1RSYNCD2/L1TXD1A1	AG12[2]
PB21/FCC2_UT8_RXD7/FCC2_RXD0/FCC2_RXD/L1TSYNCD2/L1GNTD2/ L1TXD2A1	AH11[2]
PB22/FCC2_UT8_TXD7/FCC2_TXD0/FCC2_TXD/L1RXD1A1/L1RXDD2	AH16[2]
PB23/FCC2_UT8_TXD6/FCC2_TXD1/L1RXD2A1/L1TXDD2	AE15[2]
PB24/FCC2_UT8_TXD5/FCC2_TXD2/L1RXD3A1/L1RSYNCC2	AJ9[2]
PB25/FCC2_UT8_TXD4/FCC2_TXD3/L1TSYNCC2/L1GNTC2/L1TXD3A1	AE9[2]
PB26/FCC2_MII_CRS/FCC2_UT8_TXD1/L1RXDC2	AJ7[2]
PB27/FCC2_MII_COL/FCC2_UT8_TXD0/L1TXDC2	AH6[2]
PB28/FCC2_MII_RX_ER/$\overline{\text{FCC2\_RTS}}$/L1TSYNCB2/L1GNTB2/TXD1	AE3[2]
PB29/FCC2_UTM_RXCLAV/FCC2_UTS_RXCLAV/L1RSYNCB2/ FCC2_MII_TX_EN	AE2[2]
PB30/FCC2_MII_RX_DV/FCC2_UT_TXSOC/L1RXDB2	AC5[2]
PB31/FCC2_MII_TX_ER/FCC2_UT_RXSOC/L1TXDB2	AC4[2]
PC0/DREQ1/BRGO7/$\overline{\text{SMSYN2}}$/L1CLKOA2	AB26[2]
PC1/DREQ2/BRGO6/$\overline{\text{L1RQA2}}$	AD29[2]
PC2/$\overline{\text{FCC3\_CD}}$/FCC2_UT8_TXD3/$\overline{\text{DONE2}}$	AE29[2]
PC3/$\overline{\text{FCC3\_CTS}}$/FCC2_UT8_TXD2/$\overline{\text{DACK2}}$/$\overline{\text{CTS4}}$	AE27[2]
PC4/$\overline{\text{FCC2\_UTM\_RXENB}}$/$\overline{\text{FCC2\_UTS\_RXENB}}$/SI2_L1ST4/$\overline{\text{FCC2\_CD}}$	AF27[2]
PC5/FCC2_UTM_TXCLAV/FCC2_UTS_TXCLAV/SI2_L1ST3/$\overline{\text{FCC2\_CTS}}$	AF24[2]
PC6/$\overline{\text{FCC1\_CD}}$/L1CLKOC1/FCC1_UTM_RXADDR2/FCC1_UTS_RXADDR/ FCC1_UTM_RXCLAV1	AJ26[2]
PC7/$\overline{\text{FCC1\_CTS}}$/$\overline{\text{L1RQC1}}$/FCC1_UTM_TXADDR2/FCC1_UTS_TXADDR2/ FCC1_UTM_TXCLAV1	AJ25[2]
PC8/$\overline{\text{CD4}}$/RENA4/FCC1_UT16_TXD0/SI2_L1ST2/$\overline{\text{CTS3}}$	AF22[2]
PC9/$\overline{\text{CTS4}}$/CLSN4/FCC1_UT16_TXD1/SI2_L1ST1/L1TSYNCA2/L1GNTA2	AE21[2]
PC10/$\overline{\text{CD3}}$/RENA3/FCC1_UT16_TXD2/SI1_L1ST4/FCC2_UT8_RXD3	AF20[2]
PC11/$\overline{\text{CTS3}}$/CLSN3/L1CLKOD1/L1TXD3A2/FCC2_UT8_RXD2	AE19[2]
PC12/$\overline{\text{CD2}}$/RENA2/SI1_L1ST3/FCC1_UTM_RXADDR1/ FCC1_UTS_RXADDR1	AE18[2]
PC13/$\overline{\text{CTS2}}$/CLSN2/$\overline{\text{L1RQD1}}$/FCC1_UTM_TXADDR1/ FCC1_UTS_TXADDR1	AH18[2]
PC14/$\overline{\text{CD1}}$/RENA1/FCC1_UTM_RXADDR0/FCC1_UTS_RXADDR0	AH17[2]
PC15/$\overline{\text{CTS1}}$/CLSN1/SMTXD2/FCC1_UTM_TXADDR0/ FCC1_UTS_TXADDR0	AG16[2]

Table 21. Pinout List (continued)

Pin Name	Ball
PD21/TXD4/FCC1_UT16_RXD3/L1RXD0A2/L1RXDA2	AH13[2]
PD22/RXD4/FCC1_UT16_TXD5/L1TXD0A2/L1TXDA2	AJ12[2]
PD23/$\overline{\text{RTS3}}$/TENA3/FCC1_UT16_RXD4/L1RSYNCD1	AE12[2]
PD24/TXD3/FCC1_UT16_RXD5/L1RXDD1	AF10[2]
PD25/RXD3/FCC1_UT16_TXD6/L1TXDD1	AG9[2]
PD26/$\overline{\text{RTS2}}$/TENA2/FCC1_UT16_RXD6/L1RSYNCC1	AH8[2]
PD27/TXD2/FCC1_UT16_RXD7/L1RXDC1	AG7[2]
PD28/RXD2/FCC1_UT16_TXD7/L1TXDC1	AE4[2]
PD29/$\overline{\text{RTS1}}$/TENA1/FCC1_UTM_RXADDR3/FCC1_UTS_RXADDR3/ FCC1_UTM_RXCLAV2/FCC2_UTM_RXADDR4	AG1[2]
PD30/$\overline{\text{FCC2\_UTM\_TXENB}}$/$\overline{\text{FCC2\_UTS\_TXENB}}$/TXD1	AD4[2]
PD31/RXD1	AD2[2]
VCCSYN	AB3
VCCSYN1	B9
GNDSYN	AB1
CLKIN2[1,3]	AE11
SPARE4[4]	U5
$\overline{\text{PCI\_MODE}}$[1,5]	AF25
SPARE6[4]	V4
THERMAL0[6]	AA1
THERMAL1[6]	AG4
I/O power	AG21, AG14, AG8, AJ1, AJ2, AH1, AH2, AG3, AF4, AE5, AC27, Y27, T27, P27, K26, G27, AE25, AF26, AG27, AH28, AH29, AJ28, AJ29, C7, C14, C16, C20, C23, E10, A28, A29, B28, B29, C27, D26, E25, H3, M4, T3, AA4, A1, A2, B1, B2, C3, D4, E5
Core Power	U28, U29, K28, K29, A9, A19, B19, M1, M2, Y1, Y2, AC1, AC2, AH19, AJ19, AH10, AJ10, AJ5
Ground	AA5, AF21, AF14, AF8, AE7, AF11, AE17, AE23, AC26, AB25, Y26, V25, T26, R25, P26, M25, K27, H25, G26, D7, D10, D14, D16, D20, D23, C9, E11, E13, E15, E19, E22, B3, G5, H4, K5, M3, P5, T4, Y5, AA2, AC3

1 MPC8265 and MPC8266 only.

2 The default configuration of the CPM pins (PA[0–31], PB[4–31], PC[0–31], PD[4–31]) is input. To prevent excessive DC current, it is recommended to either pull unused pins to GND or VDDH, or to configure them as outputs.

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Document Number: MPC8260AEC
Rev. 2.0
06/2009

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