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Understanding Embedded - Microprocessors

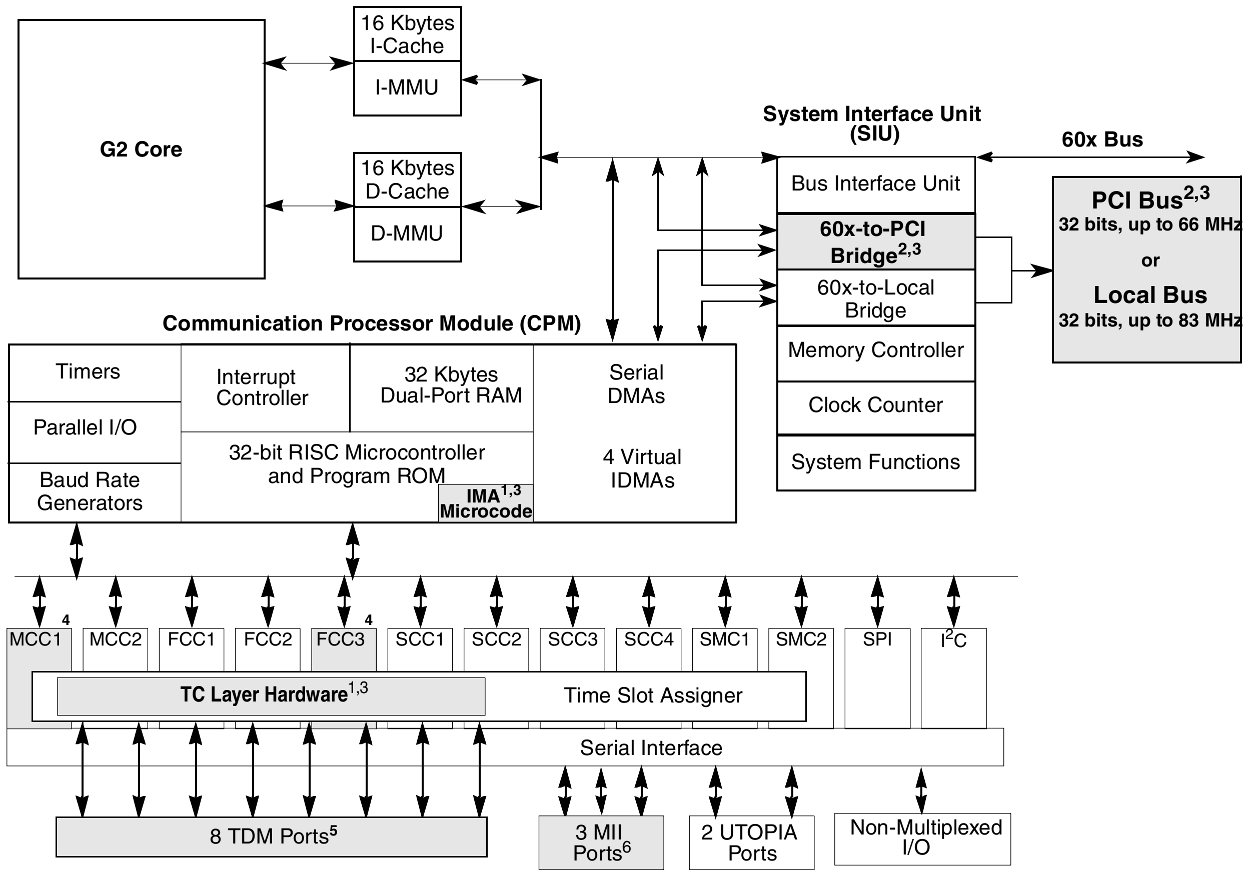
Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	266MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	-40°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mpc8264aczumibb

Figure 1 shows the block diagram for the MPC8266, the HiP4 superset device. Shaded portions indicate functionality that is not available on all devices; refer to the notes.



Notes:

1 MPC8264
2 MPC8265
3 MPC8266
4 Not on MPC8255
5 4 TDM ports on the MPC8255
6 2 MII ports on the MPC8255

Figure 1. MPC8266 Block Diagram

1 Features

The major features of the MPC826xA family are as follows:

- Dual-issue integer core
  - — A core version of the EC603e microprocessor
  - — System core microprocessor supporting frequencies of 150–300 MHz
  - — Separate 16-Kbyte data and instruction caches:
    - – Four-way set associative
    - – Physically addressed
    - – LRU replacement algorithm

  - PowerPC architecture-compliant memory management unit (MMU)
  - Common on-chip processor (COP) test interface
  - High-performance (6.6–7.65 SPEC95 benchmark at 300 MHz; 1.68 MIPs/MHz without inlining and 1.90 Dhrystones MIPS/MHz with
  - Supports bus snooping for data cache coherency
  - Floating-point unit (FPU)
- Separate power supply for internal logic and for I/O
- Separate PLLs for G2 core and for the CPM
  - G2 core and CPM can run at different frequencies for power/performance optimization
  - Internal core/bus clock multiplier that provides 1.5:1, 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
  - Internal CPM/bus clock multiplier that provides 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
- 64-bit data and 32-bit address 60x bus
  - Bus supports multiple master designs
  - Supports single- and four-beat burst transfers
  - 64-, 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
  - Supports data parity or ECC and address parity
- 32-bit data and 18-bit address local bus
  - Single-master bus, supports external slaves
  - Eight-beat burst transfers
  - 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
- 60x-to-PCI bridge (MPC8265 and MPC8266 only)
  - Programmable host bridge and agent
  - 32-bit data bus, 66 MHz, 3.3 V
  - Synchronous and asynchronous 60x and PCI clock modes
  - All internal address space available to external PCI host
  - DMA for memory block transfers
  - PCI-to-60x address remapping
- System interface unit (SIU)
  - Clock synthesizer
  - Reset controller
  - Real-time clock (RTC) register
  - Periodic interrupt timer
  - Hardware bus monitor and software watchdog timer
  - IEEE Std. 1149.1™ standard JTAG test access port
- Twelve-bank memory controller
  - Glueless interface to SRAM, page mode SDRAM, DRAM, EPROM, Flash and other user-definable peripherals
  - Byte write enables and selectable parity generation

  - Transparent
  - UART (low-speed operation)
- One serial peripheral interface identical to the MPC860 SPI
- One inter-integrated circuit (I^2C) controller (identical to the MPC860 I^2C controller)
  - Microwire compatible
  - Multiple-master, single-master, and slave modes
- Up to eight TDM interfaces (four on the MPC8255)
  - Supports two groups of four TDM channels for a total of eight TDMs
  - 2,048 bytes of SI RAM
  - Bit or byte resolution
  - Independent transmit and receive routing, frame synchronization
  - Supports T1, CEPT, T1/E1, T3/E3, pulse code modulation highway, ISDN basic rate, ISDN primary rate, Freescale interchip digital link (IDL), general circuit interface (GCI), and user-defined TDM serial interfaces
- Eight independent baud rate generators and 20 input clock pins for supplying clocks to FCCs, SCCs, SMCs, and serial channels
- Four independent 16-bit timers that can be interconnected as two 32-bit timers

Additional features of the MPC826xA family are as follows:

- CPM
  - 32-Kbyte dual-port RAM
  - Additional MCC host commands
  - Eight transfer transmission convergence (TC) layers between the TDMs and FCC2 to support inverse multiplexing for ATM capabilities (IMA) (MPC8264 and MPC8266 only)
- CPM multiplexing
  - FCC2 can also be connected to the TC layer.
- TC layer (MPC8264 and MPC8266 only)
  - Each of the 8 TDM channels is routed in hardware to a TC layer block
    - Protocol-specific overhead bits may be discarded or routed to other controllers by the SI
    - Performing ATM TC layer functions (according to ITU-T I.432)
    - Transmit (Tx) updates
      - Cell HEC generation
      - Payload scrambling using self synchronizing scrambler (programmable by the user)
      - Coset generation (programmable by the user)
      - Cell rate by inserting idle/unassigned cells
    - Receive (Rx) updates
      - Cell delineation using bit by bit HEC checking and programmable ALPHA and DELTA parameters for the delineation state machine
      - Payload descrambling using self synchronizing scrambler (programmable by the user)

- Coset removing (programmable by the user)
- Filtering idle/unassigned cells (programmable by the user)
- Performing HEC error detection and single bit error correction (programmable by user)
- Generating loss of cell delineation status/interrupt (LOC/LCD)

— Operates with FCC2 (UTOPIA 8)
— Provides serial loop back mode
— Cell echo mode is provided
— Supports both FCC transmit modes
  – External rate mode—Idle cells are generated by the FCC (microcode) to control data rate.
  – Internal rate mode (sub-rate)—FCC transfers only the data cells using the required data rate. The TC layer generates idle/unassigned cells to maintain the line bit rate.
— Supports TC-layer and PMD-WIRE interface (according to the ATM-Forum af-phy-0063.000)
— Cell counters for performance monitoring
  – 16-bit counters count
    - HEC error cells
    - HEC single bit error and corrected cells
    - Idle/unassigned cells filtered
    - Idle/unassigned cells transmitted
    - Transmitted ATM cells
    - Received ATM cells
  – Maskable interrupt is sent to the host when a counter expires
— Overrun (Rx cell FIFO) and underrun (Tx cell FIFO) condition produces maskable interrupt
— May be operated at E1 and DS-1 rates. In addition, xDSL applications at bit rates up to 10 Mbps are supported

• PCI bridge (MPC8265 and MPC8266 only)
— PCI Specification Revision 2.2 compliant and supports frequencies up to 66 MHz
— On-chip arbitration
— Support for PCI to 60x memory and 60x memory to PCI streaming
— PCI Host Bridge or Peripheral capabilities
— Includes 4 DMA channels for the following transfers:
  – PCI-to-60x to 60x-to-PCI
  – 60x-to-PCI to PCI-to-60x
  – PCI-to-60x to PCI-to-60x
  – 60x-to-PCI to 60x-to-PCI
— Includes all of the configuration registers (which are automatically loaded from the EPROM and used to configure the MPC8265) required by the PCI standard as well as message and doorbell registers
— Supports the I_2O standard

Table 3 shows DC electrical characteristics.

Table 3. DC Electrical Characteristics[1]

Characteristic	Symbol	Min	Max	Unit
Input high voltage, all inputs except CLKIN	V_{IH}	2.0	3.465	V
Input low voltage	V_{IL}	GND	0.8	V
CLKIN input high voltage	V_{IHC}	2.4	3.465	V
CLKIN input low voltage	V_{ILC}	GND	0.4	V
Input leakage current, V_{IN} = VDDH[2]	I_{IN}	—	10	µA
Hi-Z (off state) leakage current, V_{IN} = VDDH[2]	I_{OZ}	—	10	µA
Signal low input current, V_{IL} = 0.8 V	I_L	—	1	µA
Signal high input current, V_{IH} = 2.0 V	I_H	—	1	µA
Output high voltage, I_{OH} = –2 mA except XFC, UTOPIA mode, and open drain pins In UTOPIA mode: I_{OH} = –8.0 mA PA[0-31] PB[4-31] PC[0-31] PD[4-31]	V_{OH}	2.4	—	V
In UTOPIA mode: I_{OL} = 8.0 mA PA[0-31] PB[4-31] PC[0-31] PD[4-31]	V_{OL}	—	0.5	V

where K is a constant pertaining to the particular part. K can be determined from equation (3) by measuring P_D (at equilibrium) for a known T_A. Using this value of K, the values of P_D and T_J can be obtained by solving equations (1) and (2) iteratively for any value of T_A.

2.3.1 Layout Practices

Each V_{CC} pin should be provided with a low-impedance path to the board's power supply. Each ground pin should likewise be provided with a low-impedance path to ground. The power supply pins drive distinct groups of logic on chip. The V_{CC} power supply should be bypassed to ground using at least four 0.1 µF by-pass capacitors located as close as possible to the four sides of the package. The capacitor leads and associated printed circuit traces connecting to chip V_{CC} and ground should be kept to less than half an inch per capacitor lead. A four-layer board is recommended, employing two inner layers as V_{CC} and GND planes.

All output pins on the MPC826xA have fast rise and fall times. Printed circuit (PC) trace interconnection length should be minimized in order to minimize overdamped conditions and reflections caused by these fast output switching times. This recommendation particularly applies to the address and data buses. Maximum PC trace lengths of six inches are recommended. Capacitance calculations should consider all device loads as well as parasitic capacitances due to the PC traces. Attention to proper PCB layout and bypassing becomes especially critical in systems with higher capacitive loads because these loads create higher transient currents in the V_{CC} and GND circuits. Pull up all unused inputs or signals that will be inputs during reset. Special care should be taken to minimize the noise levels on the PLL supply pins.

Table 5 provides preliminary, estimated power dissipation for various configurations. Note that suitable thermal management is required for conditions above P_D = 3 W (when the ambient temperature is 70 °C or greater) to ensure the junction temperature does not exceed the maximum specified value. Also note that the I/O power should be included when determining whether to use a heat sink.

Table 5. Estimated Power Dissipation for Various Configurations[1]

Bus (MHz)	CPM Multiplier	Core CPU Multiplier	CPM (MHz)	CPU (MHz)	P_{INT}(W)[2]			
					Vddl 1.8 Volts		Vddl 2.0 Volts	
					Nominal	Maximum	Nominal	Maximum
66.66	2	3	133	200	1.2	2	1.8	2.3
66.66	2.5	3	166	200	1.3	2.1	1.9	2.3
66.66	3	4	200	266	—	—	2.3	2.9
66.66	3	4.5	200	300	—	—	2.4	3.1
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2	3	166	250	—	—	2.2	2.8
83.33	2.5	3.5	208	291	—	—	2.4	3.1

1 Test temperature = room temperature (25° C)

2 $P_{INT} = I_{DD} \times V_{DD}$ Watts

Table 8 lists CPM input characteristics.

Table 8. AC Characteristics for CPM Inputs[1]

Spec Number		Characteristic	Setup (ns)		Hold (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp16a	sp17a	FCC inputs—internal clock (NMSI)	10	8	0	0
sp16b	sp17b	FCC inputs—external clock (NMSI)	3	2.5	3	2
sp20	sp21	TDM inputs/SI	15	12	12	10
sp18a	sp19a	SCC/SMC/SPI/I2C inputs—internal clock (NMSI)	20	16	0	0
sp18b	sp19b	SCC/SMC/SPI/I2C inputs—external clock (NMSI)	5	4	5	4
sp22	sp23	PIO/TIMER/IDMA inputs	10	8	3	3

1 Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Note that although the specifications generally reference the rising edge of the clock, the following AC timing diagrams also apply when the falling edge is the active edge.

Figure 3 shows the FCC external clock.

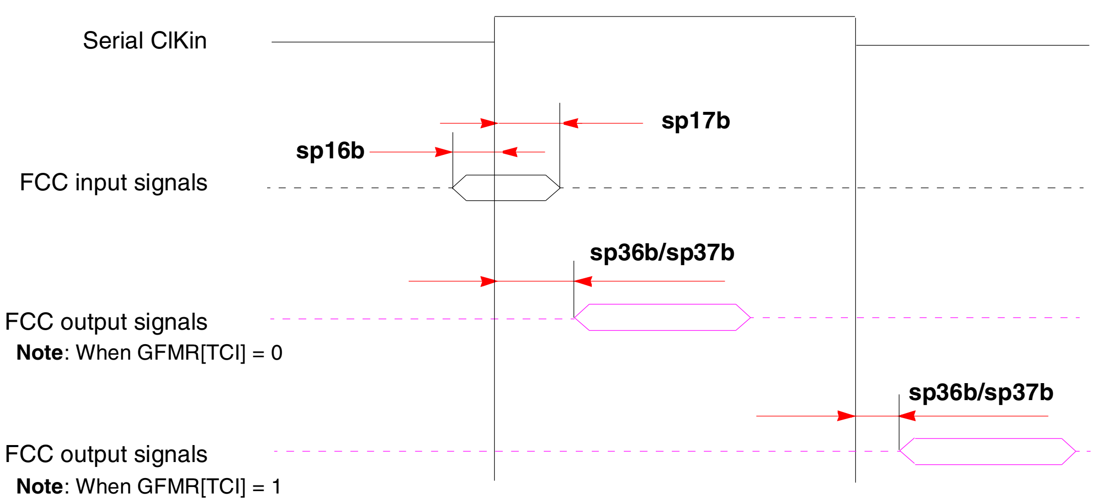
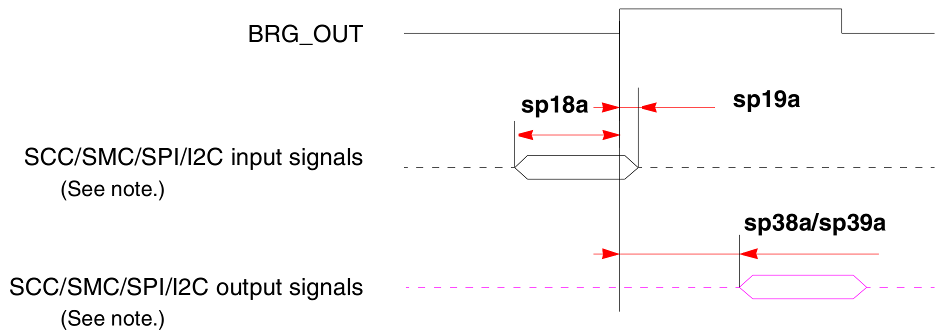


Figure 3. FCC External Clock Diagram

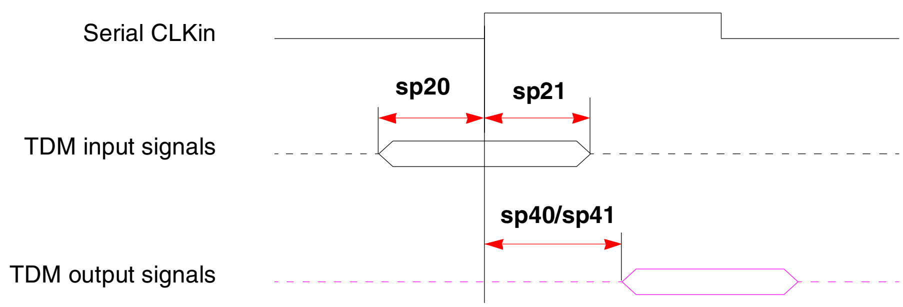
Figure 6 shows the SCC/SMC/SPI/I²C internal clock.



Note: There are four possible timing conditions for SCC and SPI:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 6. SCC/SMC/SPI/I²C Internal Clock Diagram

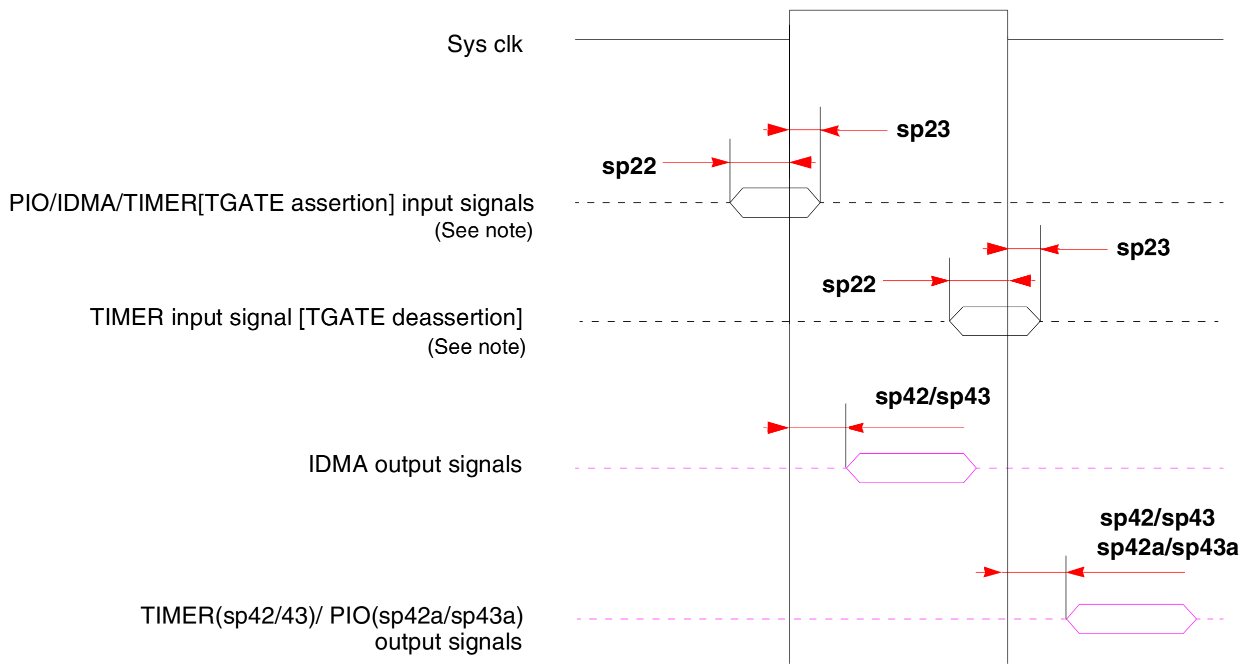
Figure 7 shows TDM input and output signals.



Note: There are four possible TDM timing conditions:
1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 7. TDM Signal Diagram

Figure 8 shows PIO, timer, and DMA signals.



Note: TGATE is asserted on the rising edge of the clock; it is deasserted on the falling edge.

Figure 8. PIO, Timer, and DMA Signal Diagram

Table 10 lists SIU input characteristics.

Table 9. AC Characteristics for SIU Inputs[1]

Spec Number		Characteristic	Setup (ns)		Hold (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp11	sp10	$\overline{\text{AACK}}$/$\overline{\text{ARTRY}}$/$\overline{\text{TA}}$/$\overline{\text{TS}}$/$\overline{\text{TEA}}$/$\overline{\text{DBG}}$/$\overline{\text{BG}}$/$\overline{\text{BR}}$	6	5	0.5	0.5
sp12	sp10	Data bus in normal mode	5	4	0.5	0.5
sp13	sp10	Data bus in ECC and PARITY modes	8	6	0.5	0.5
sp14	sp10	DP pins	7	6	0.5	0.5
sp15	sp10	All other pins	5	4	0.5	0.5

1 Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Table 10 lists SIU output characteristics.

Table 10. AC Characteristics for SIU Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp31	sp30	$\overline{PSDVAL}/\overline{TEA}/\overline{TA}$	7	6	0.5	0.5
sp32	sp30	ADD/ADD_atr./BADDR/CI/GBL/WT	8	6.5	0.5	0.5
sp33a	sp30	Data bus	6.5	6.5	0.5	0.5
sp33b	sp30	DP	8	7	0.5	0.5
sp34	sp30	Memory controller signals/ALE	6	5	0.5	0.5
sp35	sp30	All other signals	6	5.5	0.5	0.5

1 Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

NOTE

Activating data pipelining (setting BR*x*[DR] in the memory controller) improves the AC timing. When data pipelining is activated, sp12 can be used for data bus setup even when ECC or PARITY are used. Also, sp33a can be used as the AC specification for DP signals.

Figure 11 shows signal behavior in MEMC mode.

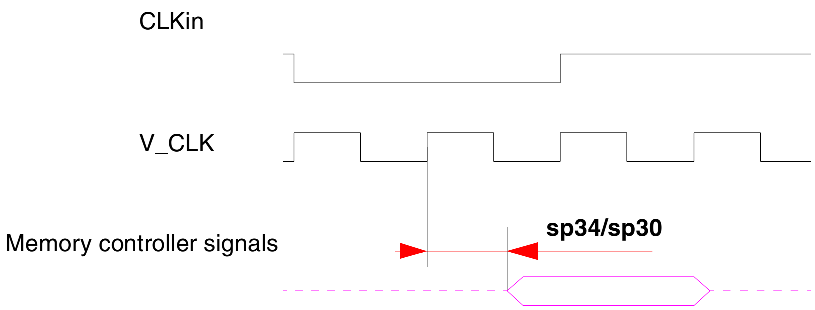


Figure 11. MEMC Mode Diagram

NOTE

Generally, all MPC826xA bus and system output signals are driven from the rising edge of the input clock (CLKin). Memory controller signals, however, trigger on four points within a CLKin cycle. Each cycle is divided by four internal ticks: T1, T2, T3, and T4. T1 always occurs at the rising edge, and T3 at the falling edge, of CLKin. However, the spacing of T2 and T4 depends on the PLL clock ratio selected, as shown in Table 11.

Table 11. Tick Spacing for Memory Controller Signals

PLL Clock Ratio	Tick Spacing (T1 Occurs at the Rising Edge of CLKin)		
	T2	**T3**	**T4**
1:2, 1:3, 1:4, 1:5, 1:6	1/4 CLKin	1/2 CLKin	3/4 CLKin
1:2.5	3/10 CLKin	1/2 CLKin	8/10 CLKin
1:3.5	4/14 CLKin	1/2 CLKin	11/14 CLKin

Figure 12 is a graphical representation of Table 11.

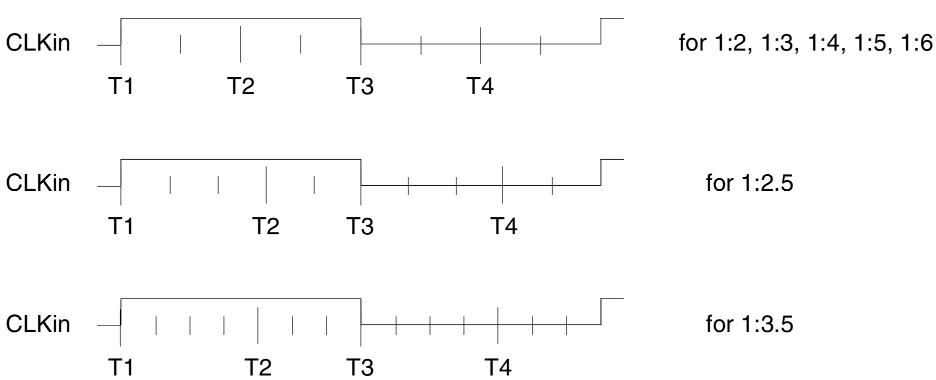


Figure 12. Internal Tick Spacing for Memory Controller Signals

3 Clock Configuration Modes

To configure the main PLL multiplication factor and the core, CPM, and 60x bus frequencies, the MODCK[1–3] pins are sampled while $\overline{\text{HRESET}}$ is asserted. Table 13 lists the eight basic configuration modes. Table 14 lists the other modes that are available by using the configuration pin ($\overline{\text{RSTCONF}}$) and driving four bits from hardware configuration word on the data bus.

Note that the MPC8265 and the MPC8266 have two additional clocking modes—PCI agent and PCI host. Refer to Section 3.2, "PCI Mode" on page 26 for information.

NOTE

Clock configurations change only after $\overline{\text{POR}}$ is asserted.

3.1 Local Bus Mode

Table 13 describes default clock modes for the MPC826xA.

Table 13. Clock Default Modes

MODCK[1–3]	Input Clock Frequency	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency
000	33 MHz	3	100 MHz	4	133 MHz
001	33 MHz	3	100 MHz	5	166 MHz
010	33 MHz	4	133 MHz	4	133 MHz
011	33 MHz	4	133 MHz	5	166 MHz
100	66 MHz	2	133 MHz	2.5	166 MHz
101	66 MHz	2	133 MHz	3	200 MHz
110	66 MHz	2.5	166 MHz	2.5	166 MHz
111	66 MHz	2.5	166 MHz	3	200 MHz

Table 14 describes all possible clock configurations when using the hard reset configuration sequence. Note that basic modes are shown in boldface type. The frequencies listed are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user's device.

Table 14. Clock Configuration Modes[1]

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0001_000	33 MHz	2	66 MHz	4	133 MHz
0001_001	33 MHz	2	66 MHz	5	166 MHz
0001_010	33 MHz	2	66 MHz	6	200 MHz
0001_011	33 MHz	2	66 MHz	7	233 MHz
0001_100	33 MHz	2	66 MHz	8	266 MHz

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0001_101	33 MHz	3	100 MHz	4	133 MHz
0001_110	33 MHz	3	100 MHz	5	166 MHz
0001_111	33 MHz	3	100 MHz	6	200 MHz
0010_000	33 MHz	3	100 MHz	7	233 MHz
0010_001	33 MHz	3	100 MHz	8	266 MHz
0010_010	**33 MHz**	**4**	**133 MHz**	**4**	**133 MHz**
0010_011	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**
0010_100	33 MHz	4	133 MHz	6	200 MHz
0010_101	33 MHz	4	133 MHz	7	233 MHz
0010_110	33 MHz	4	133 MHz	8	266 MHz
0010_111	33 MHz	5	166 MHz	4	133 MHz
0011_000	33 MHz	5	166 MHz	5	166 MHz
0011_001	33 MHz	5	166 MHz	6	200 MHz
0011_010	33 MHz	5	166 MHz	7	233 MHz
0011_011	33 MHz	5	166 MHz	8	266 MHz
0011_100	33 MHz	6	200 MHz	4	133 MHz
0011_101	33 MHz	6	200 MHz	5	166 MHz
0011_110	33 MHz	6	200 MHz	6	200 MHz
0011_111	33 MHz	6	200 MHz	7	233 MHz
0100_000	33 MHz	6	200 MHz	8	266 MHz
0100_001	Reserved				
0100_010					
0100_011					
0100_100					
0100_101					
0100_110					

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0100_111	Reserved				
0101_000					
0101_001					
0101_010					
0101_011					
0101_100					
0101_101	66 MHz	2	133 MHz	2	133 MHz
0101_110	**66 MHz**	**2**	**133 MHz**	**2.5**	**166 MHz**
0101_111	**66 MHz**	**2**	**133 MHz**	**3**	**200 MHz**
0110_000	66 MHz	2	133 MHz	3.5	233 MHz
0110_001	66 MHz	2	133 MHz	4	266 MHz
0110_010	66 MHz	2	133 MHz	4.5	300 MHz
0110_011	66 MHz	2.5	166 MHz	2	133 MHz
0110_100	**66 MHz**	**2.5**	**166 MHz**	**2.5**	**166 MHz**
0110_101	**66 MHz**	**2.5**	**166 MHz**	**3**	**200 MHz**
0110_110	66 MHz	2.5	166 MHz	3.5	233 MHz
0110_111	66 MHz	2.5	166 MHz	4	266 MHz
0111_000	66 MHz	2.5	166 MHz	4.5	300 MHz
0111_001	66 MHz	3	200 MHz	2	133 MHz
0111_010	66 MHz	3	200 MHz	2.5	166 MHz
0111_011	66 MHz	3	200 MHz	3	200 MHz
0111_100	66 MHz	3	200 MHz	3.5	233 MHz
0111_101	66 MHz	3	200 MHz	4	266 MHz
0111_110	66 MHz	3	200 MHz	4.5	300 MHz
0111_111	66 MHz	3.5	233 MHz	2	133 MHz
1000_000	66 MHz	3.5	233 MHz	2.5	166 MHz

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
1000_001	66 MHz	3.5	233 MHz	3	200 MHz
1000_010	66 MHz	3.5	233 MHz	3.5	233 MHz
1000_011	66 MHz	3.5	233 MHz	4	266 MHz
1000_100	66 MHz	3.5	233 MHz	4.5	300 MHz

[1] Because of speed dependencies, not all of the possible configurations in Table 14 are applicable.
[2] The user should choose the input clock frequency and the multiplication factors such that the frequency of the CPU is equal to or greater than 150 MHz and the CPM ranges between 66–233 MHz.
[3] Input clock frequency is given only for the purpose of reference. The user should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user's part.

3.2 PCI Mode

The MPC8265 and the MPC8266 have three clocking modes: local, PCI host, and PCI agent. The clocking mode is set according to three input pins—PCI_MODE, PCI_CFG[0], PCI_MODCK—as shown in Table 15.

Table 15. MPC8265 and MPC8266 Clocking Modes

Pins			Clocking Mode	PCI Clock Frequency Range (MHZ)
PCI_MODE	PCI_CFG[0]	PCI_MODCK		
1	—	—	Local bus	—
0	0	0	PCI host	50–66
0	0	1		25–50
0	1	0	PCI agent	50–66
0	1	1		25–50

In addition, note the following:

NOTE: PCI_MODCK

In PCI mode only, PCI_MODCK comes from the LGPL5 pin and MODCK_H[0–3] comes from {LGPL0, LGPL1, LGPL2, LGPL3}.

NOTE: Tval (Output Hold)

The minimum Tval = 2 when PCI_MODCK = 1, and the minimum Tval = 1 when PCI_MODCK = 0. Therefore, designers should use clock configurations that fit this condition to achieve PCI-compliant AC timing.

NOTE

Clock configurations change only after $\overline{\text{POR}}$ is asserted.

Table 21. Pinout List (continued)

Pin Name	Ball
A8	J1
A9	K4
A10	K3
A11	K2
A12	K1
A13	L5
A14	L4
A15	L3
A16	L2
A17	L1
A18	M5
A19	N5
A20	N4
A21	N3
A22	N2
A23	N1
A24	P4
A25	P3
A26	P2
A27	P1
A28	R1
A29	R3
A30	R5
A31	R4
TT0	F1
TT1	G4
TT2	G3
TT3	G2
TT4	F2
TBST	D3
TSIZ0	C1
TSIZ1	E4
TSIZ2	D2
TSIZ3	F5
AACK	F3

Table 21. Pinout List (continued)

Pin Name	Ball
ARTRY	E1
DBG	V1
DBB/IRQ3	V2
D0	B20
D1	A18
D2	A16
D3	A13
D4	E12
D5	D9
D6	A6
D7	B5
D8	A20
D9	E17
D10	B15
D11	B13
D12	A11
D13	E9
D14	B7
D15	B4
D16	D19
D17	D17
D18	D15
D19	C13
D20	B11
D21	A8
D22	A5
D23	C5
D24	C19
D25	C17
D26	C15
D27	D13
D28	C11
D29	B8
D30	A4
D31	E6

Table 21. Pinout List (continued)

Pin Name	Ball
D32	E18
D33	B17
D34	A15
D35	A12
D36	D11
D37	C8
D38	E7
D39	A3
D40	D18
D41	A17
D42	A14
D43	B12
D44	A10
D45	D8
D46	B6
D47	C4
D48	C18
D49	E16
D50	B14
D51	C12
D52	B10
D53	A7
D54	C6
D55	D5
D56	B18
D57	B16
D58	E14
D59	D12
D60	C10
D61	E8
D62	D6
D63	C2
DP0/$\overline{\text{RSRV}}$/$\overline{\text{EXT\_BR2}}$	B22
$\overline{\text{IRQ1}}$/DP1/$\overline{\text{EXT\_BG2}}$	A22
$\overline{\text{IRQ2}}$/DP2/$\overline{\text{TLBISYNC}}$/$\overline{\text{EXT\_DBG2}}$	E21

Table 21. Pinout List (continued)

Pin Name	Ball
PWE4/PSDDQM4/PBS4	B26
PWE5/PSDDQM5/PBS5	A26
PWE6/PSDDQM6/PBS6	B25
PWE7/PSDDQM7/PBS7	A25
PSDA10/PGPL0	E23
PSDWE/PGPL1	B24
POE/PSDRAS/PGPL2	A24
PSDCAS/PGPL3	B23
PGTA/PUPMWAIT/PGPL4/PPBS	A23
PSDAMUX/PGPL5	D22
LWE0/LSDDQM0/LBS0/PCI_CFG0[1]	H28
LWE1/LSDDQM1/LBS1/PCI_CFG1[1]	H27
LWE2/LSDDQM2/LBS2/PCI_CFG2[1]	H26
LWE3/LSDDQM3/LBS3/PCI_CFG3[1]	G29
LSDA10/LGPL0/PCI_MODCKH0[1]	D27
LSDWE/LGPL1/PCI_MODCKH1[1]	C28
LOE/LSDRAS/LGPL2/PCI_MODCKH2[1]	E26
LSDCAS/LGPL3/PCI_MODCKH3[1]	D25
LGTA/LUPMWAIT/LGPL4/LPBS	C26
LGPL5/LSDAMUX/PCI_MODCK[1]	B27
LWR	D28
L_A14/PAR[1]	N27
L_A15/FRAME[1]/SMI	T29
L_A16/TRDY[1]	R27
L_A17/IRDY[1]/CKSTP_OUT	R26
L_A18/STOP[1]	R29
L_A19/DEVSEL[1]	R28
L_A20/IDSEL[1]	W29
L_A21/PERR[1]	P28
L_A22/SERR[1]	N26
L_A23/REQ0[1]	AA27
L_A24/REQ1[1]/HSEJSW[1]	P29
L_A25/GNT0[1]	AA26
L_A26/GNT1[1]/HSLED[1]	N25
L_A27/GNT2[1]/HSENUM[1]	AA25

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Document Number: MPC8260AEC
Rev. 2.0
06/2009