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Understanding Embedded - Microprocessors

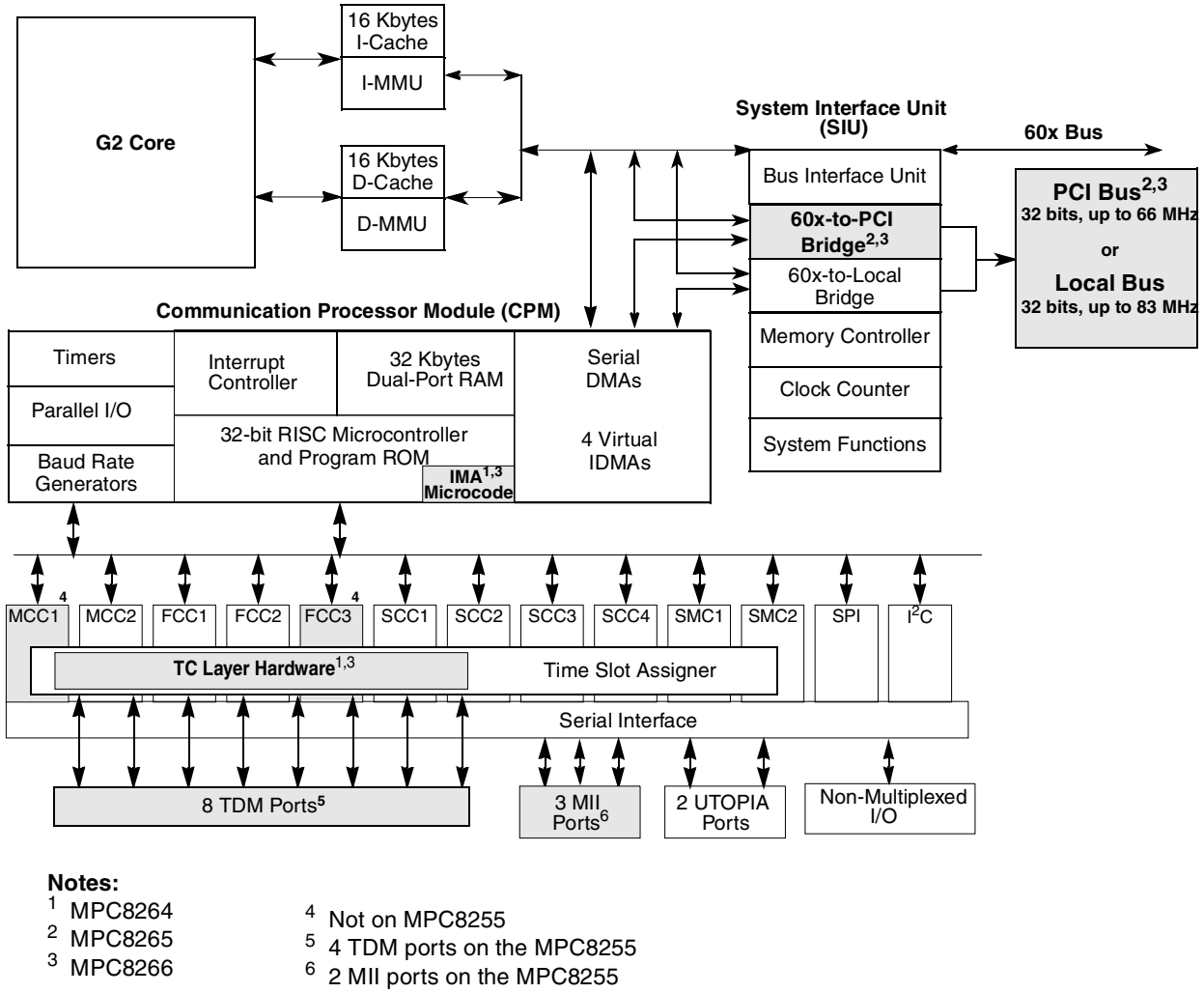
Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	300MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mpc8264avvpjdb

Figure 1 shows the block diagram for the MPC8266, the HiP4 superset device. Shaded portions indicate functionality that is not available on all devices; refer to the notes.



Notes:
1 MPC8264
2 MPC8265
3 MPC8266
4 Not on MPC8255
5 4 TDM ports on the MPC8255
6 2 MII ports on the MPC8255

Figure 1. MPC8266 Block Diagram

1 Features

The major features of the MPC826xA family are as follows:

- Dual-issue integer core
  - A core version of the EC603e microprocessor
  - System core microprocessor supporting frequencies of 150–300 MHz
  - Separate 16-Kbyte data and instruction caches:
    - Four-way set associative
    - Physically addressed
    - LRU replacement algorithm

  - PowerPC architecture-compliant memory management unit (MMU)
  - Common on-chip processor (COP) test interface
  - High-performance (6.6–7.65 SPEC95 benchmark at 300 MHz; 1.68 MIPs/MHz without inlining and 1.90 Dhrystones MIPS/MHz with
  - Supports bus snooping for data cache coherency
  - Floating-point unit (FPU)
- Separate power supply for internal logic and for I/O
- Separate PLLs for G2 core and for the CPM
  - G2 core and CPM can run at different frequencies for power/performance optimization
  - Internal core/bus clock multiplier that provides 1.5:1, 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
  - Internal CPM/bus clock multiplier that provides 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
- 64-bit data and 32-bit address 60x bus
  - Bus supports multiple master designs
  - Supports single- and four-beat burst transfers
  - 64-, 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
  - Supports data parity or ECC and address parity
- 32-bit data and 18-bit address local bus
  - Single-master bus, supports external slaves
  - Eight-beat burst transfers
  - 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
- 60x-to-PCI bridge (MPC8265 and MPC8266 only)
  - Programmable host bridge and agent
  - 32-bit data bus, 66 MHz, 3.3 V
  - Synchronous and asynchronous 60x and PCI clock modes
  - All internal address space available to external PCI host
  - DMA for memory block transfers
  - PCI-to-60x address remapping
- System interface unit (SIU)
  - Clock synthesizer
  - Reset controller
  - Real-time clock (RTC) register
  - Periodic interrupt timer
  - Hardware bus monitor and software watchdog timer
  - IEEE Std. 1149.1™ standard JTAG test access port
- Twelve-bank memory controller
  - Glueless interface to SRAM, page mode SDRAM, DRAM, EPROM, Flash and other user-definable peripherals
  - Byte write enables and selectable parity generation

  - 32-bit address decodes with programmable bank size
  - Three user programmable machines, general-purpose chip-select machine, and page-mode pipeline SDRAM machine
  - Byte selects for 64 bus width (60x) and byte selects for 32 bus width (local)
  - Dedicated interface logic for SDRAM
- CPU core can be disabled and the device can be used in slave mode to an external core
- Communications processor module (CPM)
  - Embedded 32-bit communications processor (CP) uses a RISC architecture for flexible support for communications protocols
  - Interfaces to G2 core through on-chip 32-Kbyte dual-port RAM and DMA controller
  - Serial DMA channels for receive and transmit on all serial channels
  - Parallel I/O registers with open-drain and interrupt capability
  - Virtual DMA functionality executing memory-to-memory and memory-to-I/O transfers
  - Three fast communications controllers supporting the following protocols (only FCC1 and FCC2 on the MPC8255):
    - 10/100-Mbit Ethernet/IEEE Std. 802.3® CDMA/CS interface through media independent interface (MII)
    - ATM—Full-duplex SAR protocols at 155 Mbps, through UTOPIA interface, AAL5, AAL1, AAL0 protocols, TM 4.0 CBR, VBR, UBR, ABR traffic types, up to 16 K external connections
    - Transparent
    - HDLC—Up to T3 rates (clear channel)
  - Two multichannel controllers (MCCs) (only MCC2 on the MPC8255)
    - Each MCC handles 128 serial, full-duplex, 64-Kbps data channels.Each MCC can be split into four subgroups of 32 channels each.
    - Almost any combination of subgroups can be multiplexed to single or multiple TDM interfaces up to four TDM interfaces per MCC
  - Four serial communications controllers (SCCs) identical to those on the MPC860, supporting the digital portions of the following protocols:
    - Ethernet/IEEE 802.3 CDMA/CS
    - HDLC/SDLC and HDLC bus
    - Universal asynchronous receiver transmitter (UART)
    - Synchronous UART
    - Binary synchronous (BISYNC) communications
    - Transparent
  - Two serial management controllers (SMCs), identical to those of the MPC860
    - Provide management for BRI devices as general circuit interface (GCI) controllers in time-division-multiplexed (TDM) channels

  - Transparent
  - UART (low-speed operation)
- One serial peripheral interface identical to the MPC860 SPI
- One inter-integrated circuit (I^2C) controller (identical to the MPC860 I^2C controller)
  - Microwire compatible
  - Multiple-master, single-master, and slave modes
- Up to eight TDM interfaces (four on the MPC8255)
  - Supports two groups of four TDM channels for a total of eight TDMs
  - 2,048 bytes of SI RAM
  - Bit or byte resolution
  - Independent transmit and receive routing, frame synchronization
  - Supports T1, CEPT, T1/E1, T3/E3, pulse code modulation highway, ISDN basic rate, ISDN primary rate, Freescale interchip digital link (IDL), general circuit interface (GCI), and user-defined TDM serial interfaces
- Eight independent baud rate generators and 20 input clock pins for supplying clocks to FCCs, SCCs, SMCs, and serial channels
- Four independent 16-bit timers that can be interconnected as two 32-bit timers

Additional features of the MPC826xA family are as follows:

- CPM
  - 32-Kbyte dual-port RAM
  - Additional MCC host commands
  - Eight transfer transmission convergence (TC) layers between the TDMs and FCC2 to support inverse multiplexing for ATM capabilities (IMA) (MPC8264 and MPC8266 only)
- CPM multiplexing
  - FCC2 can also be connected to the TC layer.
- TC layer (MPC8264 and MPC8266 only)
  - Each of the 8 TDM channels is routed in hardware to a TC layer block
    - Protocol-specific overhead bits may be discarded or routed to other controllers by the SI
    - Performing ATM TC layer functions (according to ITU-T I.432)
    - Transmit (Tx) updates
      - Cell HEC generation
      - Payload scrambling using self synchronizing scrambler (programmable by the user)
      - Coset generation (programmable by the user)
      - Cell rate by inserting idle/unassigned cells
    - Receive (Rx) updates
      - Cell delineation using bit by bit HEC checking and programmable ALPHA and DELTA parameters for the delineation state machine
      - Payload descrambling using self synchronizing scrambler (programmable by the user)

— Hot-Swap friendly (supports the Hot Swap Specification as defined by PICMG 2.1 R1.0 August 3, 1998)
— Support for 66 MHz, 3.3 V specification
— 60x-PCI bus core logic which uses a buffer pool to allocate buffers for each port
— Makes use of the local bus signals, so there is no need for additional pins

2 Electrical and Thermal Characteristics

This section provides AC and DC electrical specifications and thermal characteristics for the MPC826xA.

2.1 DC Electrical Characteristics

This section describes the DC electrical characteristics for the MPC826xA. Table 1 shows the maximum electrical ratings.

Table 1. Absolute Maximum Ratings[1]

Rating	Symbol	Value	Unit
Core supply voltage[2]	VDD	–0.3 – 2.5	V
PLL supply voltage[2]	VCCSYN	–0.3 – 2.5	V
I/O supply voltage[3]	VDDH	–0.3 – 4.0	V
Input voltage[4]	VIN	GND(–0.3) – 3.6	V
Junction temperature	T_j	120	°C
Storage temperature range	T_{STG}	(–55) – (+150)	°C

1 Absolute maximum ratings are stress ratings only; functional operation (see Table 2) at the maximums is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage.
2 **Caution:** VDD/VCCSYN must not exceed VDDH by more than 0.4 V at any time, including during power-on reset.
3 **Caution:** VDDH can exceed VDD/VCCSYN by 3.3 V during power on reset by no more than 100 mSec. VDDH should not exceed VDD/VCCSYN by more than 2.5 V during normal operation.
4 **Caution:** VIN must not exceed VDDH by more than 2.5 V at any time, including during power-on reset.

Table 2 lists recommended operational voltage conditions.

Table 2. Recommended Operating Conditions[1]

Rating	Symbol	Value			Unit
Core supply voltage	VDD	1.7 – 1.9[2]	1.7–2.1[3]	1.9 –2.2[4]	V
PLL supply voltage	VCCSYN	1.7 – 1.9[2]	1.7–2.1[3]	1.9–2.2[4]	V
I/O supply voltage	VDDH	3.135 – 3.465			V
Input voltage	VIN	GND (–0.3) – 3.465			V
Junction temperature (maximum)	T_j	105[5]			°C
Ambient temperature	T_A	0–70[5]			°C

1 **Caution:** These are the recommended and tested operating conditions. Proper device operating outside of these conditions is not guaranteed.
2 CPU frequency less than or equal to 200 MHz.
3 CPU frequency greater than 200 MHz but less than 233 MHz.
4 CPU frequency greater than or equal to 233 MHz.
5 Note that for extended temperature parts the range is $(-40)_{T_A} – 105_{T_j}$.

NOTE: Core, PLL, and I/O Supply Voltages

VDDH, VCCSYN, and VDD must track each other and both must vary in the same direction—in the positive direction (+5% and +0.1 Vdc) or in the negative direction (–5% and –0.1 Vdc).

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (either GND or V_{CC}).

Figure 2 shows the undershoot and overshoot voltage of the 60x and local bus memory interface of the MPC8280. Note that in PCI mode the I/O interface is different.

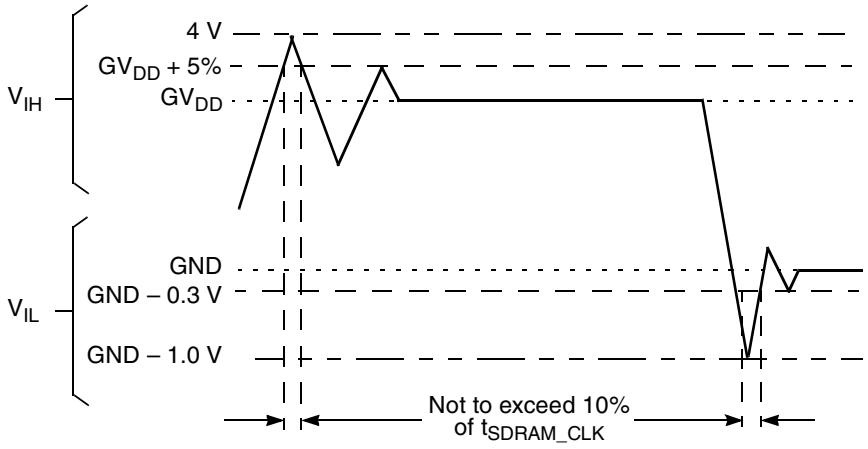


Figure 2. Overshoot/Undershoot Voltage

Table 3. DC Electrical Characteristics[1] (continued)

Characteristic	Symbol	Min	Max	Unit
I_{OL} = 7.0 mA BR BG ABB/IRQ2 TS A[0-31] TT[0-4] TBST TSIZE[0–3] AACK ARTRY DBG DBB/IRQ3 D[0-63] DP(0)/RSRV/EXT_BR2 DP(1)/IRQ1/EXT_BG2 DP(2)/TLBISYNC/IRQ2/EXT_DBG2 DP(3)/IRQ3/EXT_BR3/CKSTP_OUT DP(4)/IRQ4/EXT_BG3/CORE_SREST DP(5)/TBEN/IRQ5/EXT_DBG3 DP(6)/CSE(0)/IRQ6 DP(7)/CSE(1)/IRQ7 PSDVAL TA TEA GBL/IRQ1 CI/BADDR29/IRQ2 WT/BADDR30/IRQ3 L2_HIT/IRQ4 CPU_BG/BADDR31/IRQ5 CPU_DBG CPU_BR IRQ0/NMI_OUT IRQ7/INT_OUT/APE PORESET HRESET SRESET RSTCONF QREQ	V_{OL}	—	0.4	V

Table 3. DC Electrical Characteristics[1] (continued)

Characteristic	Symbol	Min	Max	Unit
I_{OL} = 5.3mA CS[0-9] CS(10)/BCTL1 CS(11)/AP(0) BADDR[27–28] ALE BCTL0 PWE(0:7)/PSDDQM(0:7)/PBS(0:7) PSDA10/PGPL0 PSDWE/PGPL1 POE/PSDRAS/PGPL2 PSDCAS/PGPL3 PGTA/PUPMWAIT/PGPL4/PPBS PSDAMUX/PGPL5 LWE[0–3]LSDDQM[0–3]/LBS[0–3]/PCI_CFG[0–3][3] LSDA10/LGPL0/PCI_MODCKH0[3] LSDWE/LGPL1/PCI_MODCKH1[3] LOE/LSDRAS/LGPL2/PCI_MODCKH2[3] LSDCAS/LGPL3/PCI_MODCKH3[3] LGTA/LUPMWAIT/LGPL4/LPBS LSDAMUX/LGPL5/PCI_MODCK[3] LWR MODCK1/AP(1)/TC(0)/BNKSEL(0) MODCK2/AP(2)/TC(1)/BNKSEL(1) MODCK3/AP(3)/TC(2)/BNKSEL(2)	V_{OL}	—	0.4	V
I_{OL} = 3.2mA L_A14/PAR[3] L_A15/FRAME[3]/SMI L_A16/TRDY[3] L_A17/IRDY[3]/CKSTP_OUT L_A18/STOP[3] L_A19/DEVSEL[3] L_A20/IDSEL[3] L_A21/PERR[3] L_A22/SERR[3] L_A23/REQ0[3] L_A24/REQ1[3]/HSEJSW[3] L_A25/GNT0[3] L_A26/GNT1[3]/HSLED[3] L_A27/GNT2[3]/HSENUM[3] L_A28/RST[3]/CORE_SRESET L_A29/INTA[3] L_A30/REQ2[3] L_A31 LCL_D(0-31)/AD(0-31)[3] LCL_DP(0-3)/C/BE(0-3)[3] PA[0–31] PB[4–31] PC[0–31] PD[4–31] TDO				

1 The default configuration of the CPM pins (PA[0–31], PB[4–31], PC[0–31], PD[4–31]) is input. To prevent excessive DC current, it is recommended to either pull unused pins to GND or VDDH, or to configure them as outputs.

2 The leakage current is measured for nominal VDD, VCCSYN, and VDD.
3 MPC8265 and MPC8266 only.

2.2 Thermal Characteristics

Table 4 describes thermal characteristics.

Table 4. Thermal Characteristics for 480 TBGA Package

Characteristics	Symbol	Value	Unit	Air Flow
Junction to ambient	θ_{JA}	13[1]	°C/W	NC[2]
		10[1]		1 m/s
		11[3]		NC
		8[3]		1 m/s
Junction to board[4]	θ_{JB}	4	°C/W	—
Junction to case[5]	θ_{JC}	1.1	°C/W	—

1 Assumes a single layer board with no thermal vias
2 Natural convection
3 Assumes a four layer board
4 Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
5 Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).

2.3 Power Considerations

The average chip-junction temperature, T_J, in °C can be obtained from the following:

$$T_J = T_A + (P_D \times \theta_{JA}) \quad (1)$$

where

T_A = ambient temperature °C

θ_{JA} = package thermal resistance, junction to ambient, °C/W

$P_D = P_{INT} + P_{I/O}$

$P_{INT} = I_{DD} \times V_{DD}$ Watts (chip internal power)

$P_{I/O}$ = power dissipation on input and output pins (determined by user)

For most applications $P_{I/O} < 0.3 \times P_{INT}$. If $P_{I/O}$ is neglected, an approximate relationship between P_D and T_J is the following:

$$P_D = K/(T_J + 273° C) \quad (2)$$

Solving equations (1) and (2) for K gives:

$$K = P_D \times (T_A + 273° C) + \theta_{JA} \times P_D^2 \quad (3)$$

2.4 AC Electrical Characteristics

The following sections include illustrations and tables of clock diagrams, signals, and CPM outputs and inputs for the 66 MHz MPC826xA device. Note that AC timings are based on a 50-p*f* load. Typical output buffer impedances are shown in Table 6.

Table 6. Output Buffer Impedances[1]

Output Buffers	Typical Impedance (Ω)
60x bus	40
Local bus	40
Memory controller	40
Parallel I/O	46
PCI	25

1 These are typical values at 65° C. The impedance may vary by ±25% with process and temperature.

Table 7 lists CPM output characteristics.

Table 7. AC Characteristics for CPM Outputs[1]

Spec Number		Characteristic	Max Delay (ns)		Min Delay (ns)	
Max	Min		66 MHz	83 MHz	66 MHz	83 MHz
sp36a	sp37a	FCC outputs—internal clock (NMSI)	6	5.5	1	1
sp36b	sp37b	FCC outputs—external clock (NMSI)	14	12	2	1
sp40	sp41	TDM outputs/SI	25	16	5	4
sp38a	sp39a	SCC/SMC/SPI/I2C outputs—internal clock (NMSI)	19	16	1	0.5
sp38b	sp39b	Ex_SCC/SMC/SPI/I2C outputs—external clock (NMSI)	19	16	2	1
sp42	sp43	TIMER/IDMA outputs	14	11	1	0.5
sp42a	sp43a	PIO outputs	14	11	0.5	0.5

1 Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

Figure 9 shows the interaction of several bus signals.

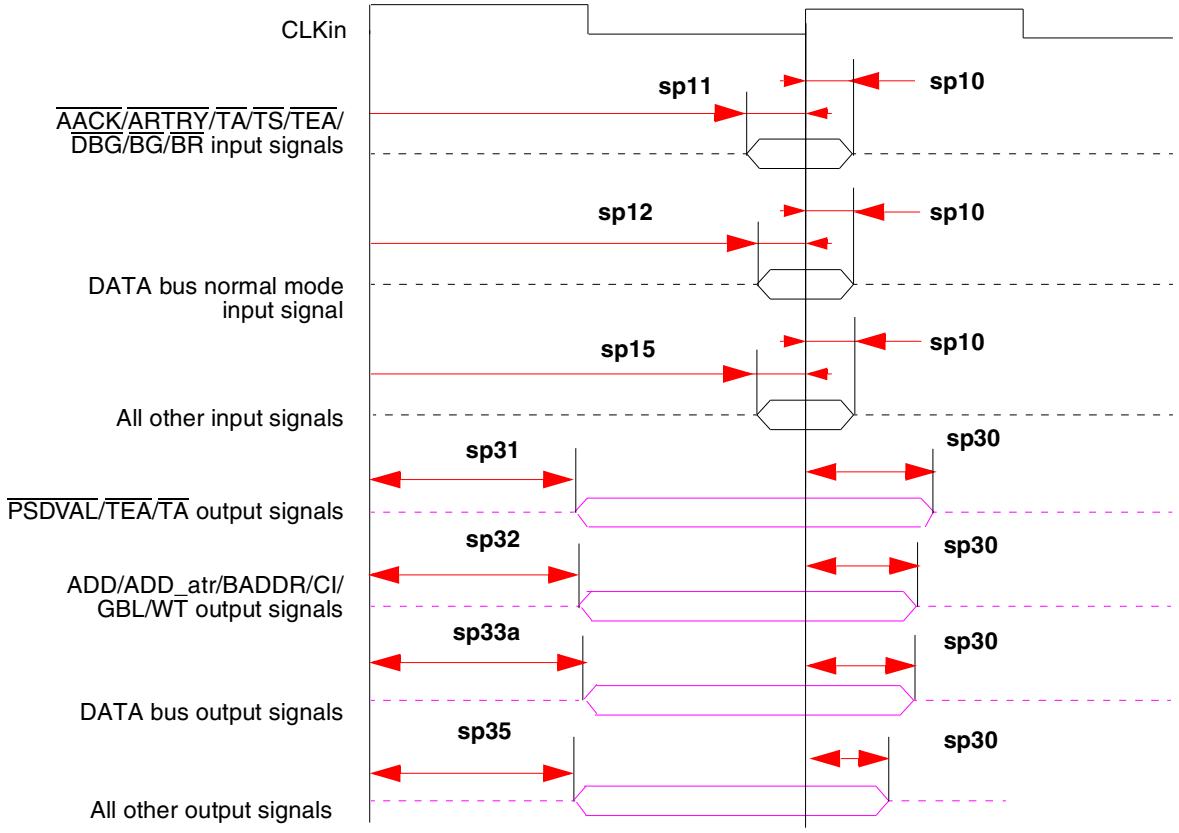


Figure 9. Bus Signals

Figure 10 shows signal behavior for all parity modes (including ECC, RMW parity, and standard parity).

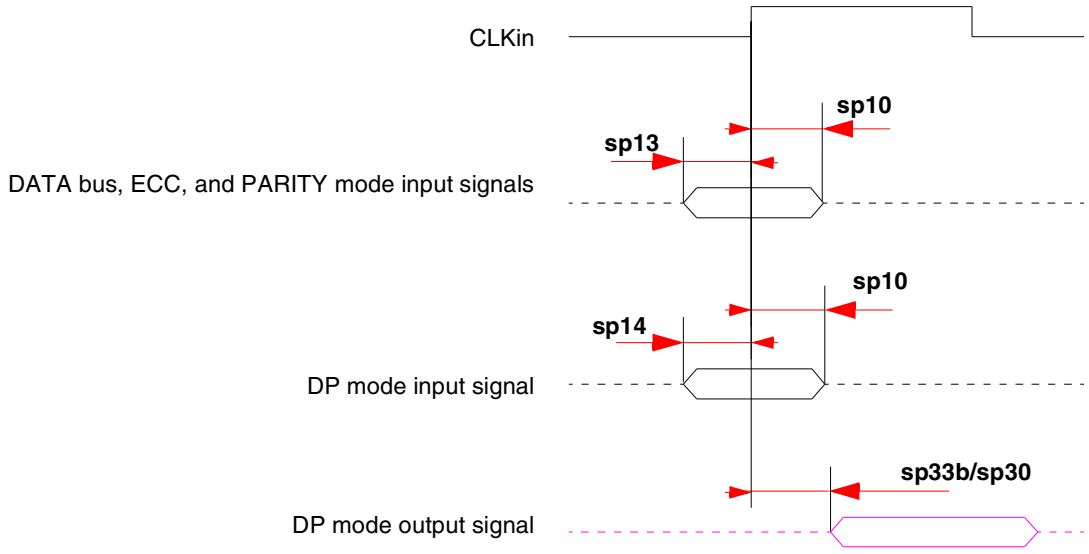


Figure 10. Parity Mode Diagram

Figure 11 shows signal behavior in MEMC mode.

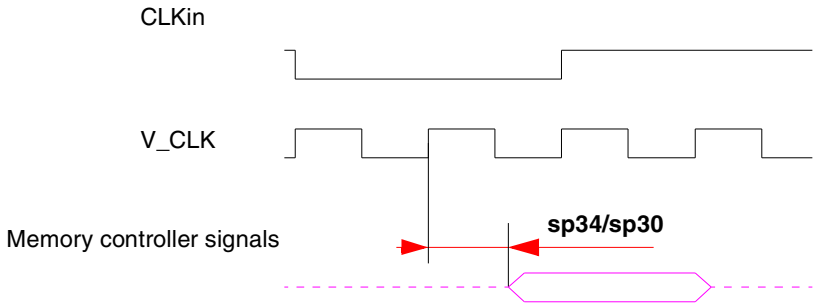


Figure 11. MEMC Mode Diagram

NOTE

Generally, all MPC826xA bus and system output signals are driven from the rising edge of the input clock (CLKin). Memory controller signals, however, trigger on four points within a CLKin cycle. Each cycle is divided by four internal ticks: T1, T2, T3, and T4. T1 always occurs at the rising edge, and T3 at the falling edge, of CLKin. However, the spacing of T2 and T4 depends on the PLL clock ratio selected, as shown in Table 11.

Table 11. Tick Spacing for Memory Controller Signals

PLL Clock Ratio	Tick Spacing (T1 Occurs at the Rising Edge of CLKin)		
	T2	T3	T4
1:2, 1:3, 1:4, 1:5, 1:6	1/4 CLKin	1/2 CLKin	3/4 CLKin
1:2.5	3/10 CLKin	1/2 CLKin	8/10 CLKin
1:3.5	4/14 CLKin	1/2 CLKin	11/14 CLKin

Figure 12 is a graphical representation of Table 11.

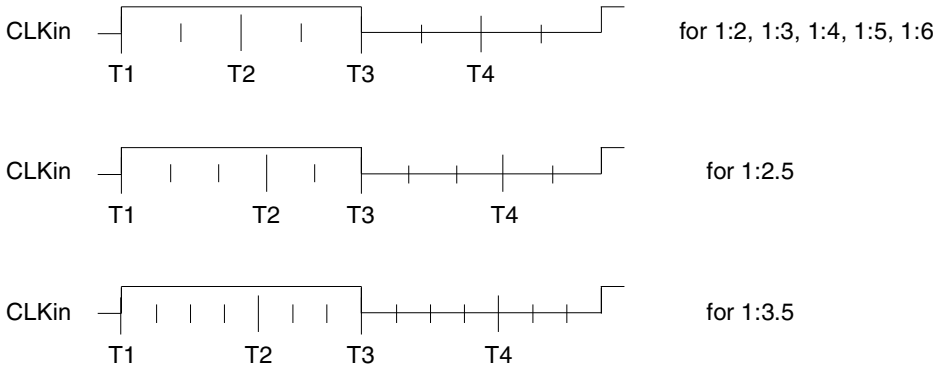


Figure 12. Internal Tick Spacing for Memory Controller Signals

Table 12 lists the JTAG timings.

Table 12. JTAG Timings[1]

Parameter	Symbol[2]	Min	Max	Unit	Notes
JTAG external clock frequency of operation	f_{JTG}	0	25	MHz	—
JTAG external clock cycle time	t_{JTG}	40	—	ns	—
JTAG external clock pulse width measured at 1.4V	t_{JTKHKL}	20	—	ns	—
JTAG external clock rise and fall times	t_{JTGR} and t_{JTGF}	0	5	ns	6
TRST assert time	t_{TRST}	25	—	ns	3, 6
Input setup times Boundary-scan data TMS, TDI	 t_{JTDVKH} t_{JTIVKH}	 4 4	 — —	 ns ns	 4, 7 4, 7
Input hold times Boundary-scan data TMS, TDI	 t_{JTDXKH} t_{JTIXKH}	 10 10	 — —	 ns ns	 4, 7 4, 7
Output valid times Boundary-scan data TDO	 t_{JTKLDV} t_{JTKLOV}	 — —	 25 25	 ns ns	 5, 7 5. 7
Output hold times Boundary-scan data TDO	 t_{JTKLDX} t_{JTKLOX}	 1 1	 — —	 ns ns	 5, 7 5, 7
JTAG external clock to output high impedance Boundary-scan data TDO	 t_{JTKLDZ} t_{JTKLOZ}	 1 1	 25 25	 ns ns	 5, 6 5, 6

1 All outputs are measured from the midpoint voltage of the falling/rising edge of t_{TCLK} to the midpoint of the signal in question. The output timings are measured at the pins. All output timings assume a purely resistive 50-Ω load. Time-of-flight delays must be added for trace lengths, vias, and connectors in the system.

2 The symbols used for timing specifications herein follow the pattern of $t_{\text{(first two letters of functional block)(signal)(state)(reference)(state)}}$ for inputs and $t_{\text{((first two letters of functional block)(reference)(state)(signal)(state)}}$ for outputs. For example, t_{JTDVKH} symbolizes JTAG device timing (JT) with respect to the time data input signals (D) reaching the valid state (V) relative to the t_{JTG} clock reference (K) going to the high (H) state or setup time. Also, t_{JTDXKH} symbolizes JTAG timing (JT) with respect to the time data input signals (D) went invalid (X) relative to the t_{JTG} clock reference (K) going to the high (H) state. Note that, in general, the clock reference symbol representation is based on three letters representing the clock of a particular functional. For rise and fall times, the latter convention is used with the appropriate letter: R (rise) or F (fall).

3 TRST is an asynchronous level sensitive signal. The setup time is for test purposes only.

4 Non-JTAG signal input timing with respect to t_{TCLK}.

5 Non-JTAG signal output timing with respect to t_{TCLK}.

6 Guaranteed by design.

7 Guaranteed by design and device characterization.

NOTE

The UPM machine outputs change on the internal tick determined by the memory controller programming; the AC specifications are relative to the internal tick. Note that SDRAM and GPCM machine outputs change on CLKin's rising edge.

3 Clock Configuration Modes

To configure the main PLL multiplication factor and the core, CPM, and 60x bus frequencies, the MODCK[1–3] pins are sampled while $\overline{\text{HRESET}}$ is asserted. Table 13 lists the eight basic configuration modes. Table 14 lists the other modes that are available by using the configuration pin ($\overline{\text{RSTCONF}}$) and driving four bits from hardware configuration word on the data bus.

Note that the MPC8265 and the MPC8266 have two additional clocking modes—PCI agent and PCI host. Refer to Section 3.2, “PCI Mode” on page 26 for information.

NOTE

Clock configurations change only after $\overline{\text{POR}}$ is asserted.

3.1 Local Bus Mode

Table 13 describes default clock modes for the MPC826xA.

Table 13. Clock Default Modes

MODCK[1–3]	Input Clock Frequency	CPM Multiplication Factor	CPM Frequency	Core Multiplication Factor	Core Frequency
000	33 MHz	3	100 MHz	4	133 MHz
001	33 MHz	3	100 MHz	5	166 MHz
010	33 MHz	4	133 MHz	4	133 MHz
011	33 MHz	4	133 MHz	5	166 MHz
100	66 MHz	2	133 MHz	2.5	166 MHz
101	66 MHz	2	133 MHz	3	200 MHz
110	66 MHz	2.5	166 MHz	2.5	166 MHz
111	66 MHz	2.5	166 MHz	3	200 MHz

Table 14 describes all possible clock configurations when using the hard reset configuration sequence. Note that basic modes are shown in boldface type. The frequencies listed are for the purpose of illustration only. Users must select a mode and input bus frequency so that the resulting configuration does not exceed the frequency rating of the user’s device.

Table 14. Clock Configuration Modes[1]

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0001_000	33 MHz	2	66 MHz	4	133 MHz
0001_001	33 MHz	2	66 MHz	5	166 MHz
0001_010	33 MHz	2	66 MHz	6	200 MHz
0001_011	33 MHz	2	66 MHz	7	233 MHz
0001_100	33 MHz	2	66 MHz	8	266 MHz

Table 14. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3]	CPM Multiplication Factor[2]	CPM Frequency[2]	Core Multiplication Factor[2]	Core Frequency[2]
0001_101	33 MHz	3	100 MHz	4	133 MHz
0001_110	33 MHz	3	100 MHz	5	166 MHz
0001_111	33 MHz	3	100 MHz	6	200 MHz
0010_000	33 MHz	3	100 MHz	7	233 MHz
0010_001	33 MHz	3	100 MHz	8	266 MHz
0010_010	**33 MHz**	**4**	**133 MHz**	**4**	**133 MHz**
0010_011	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**
0010_100	33 MHz	4	133 MHz	6	200 MHz
0010_101	33 MHz	4	133 MHz	7	233 MHz
0010_110	33 MHz	4	133 MHz	8	266 MHz
0010_111	33 MHz	5	166 MHz	4	133 MHz
0011_000	33 MHz	5	166 MHz	5	166 MHz
0011_001	33 MHz	5	166 MHz	6	200 MHz
0011_010	33 MHz	5	166 MHz	7	233 MHz
0011_011	33 MHz	5	166 MHz	8	266 MHz
0011_100	33 MHz	6	200 MHz	4	133 MHz
0011_101	33 MHz	6	200 MHz	5	166 MHz
0011_110	33 MHz	6	200 MHz	6	200 MHz
0011_111	33 MHz	6	200 MHz	7	233 MHz
0100_000	33 MHz	6	200 MHz	8	266 MHz
0100_001	Reserved				
0100_010					
0100_011					
0100_100					
0100_101					
0100_110					

Table 18. Clock Default Configurations in PCI Agent Mode (MODCK_HI = 0000) (continued)

MODCK[1–3][1]	Input Clock Frequency (PCI)[2]	CPM Multiplication Factor[2]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
100	66/33 MHz	3/6	200 MHz	3	240 MHz	2.5	80 MHz
101	66/33 MHz	3/6	200 MHz	3.5	280 MHz	2.5	80 MHz
110	66/33 MHz	4/8	266 MHz	3.5	300 MHz	3	88 MHz
111	66/33 MHz	4/8	266 MHz	3	300 MHz	2.5	100 MHz

1 Assumes MODCK_HI = 0000.
2 The frequency depends on the value of PCI_MODCK. If PCI_MODCK is high (logic ‘1’), the PCI frequency is divided by 2 (33 instead of 66 MHz, etc.) and the CPM multiplication factor is multiplied by 2. Refer to Table 15.
3 Core frequency = (60x bus frequency)(core multiplication factor)
4 Bus frequency = CPM frequency/bus division factor

Table 19 describes all possible clock configurations when using the MPC8265 or the MPC8266’s internal PCI bridge in agent mode.

Table 19. Clock Configuration Modes in PCI Agent Mode

MODCK_H – MODCK[1–3]	Input Clock Frequency (PCI)[1,2]	CPM Multiplication Factor[1]	CPM Frequency	Core Multiplication Factor	Core Frequency[3]	Bus Division Factor	60x Bus Frequency[4]
0001_001	66/33 MHz	2/4	133 MHz	5	166 MHz	4	33 MHz
0001_010	66/33 MHz	2/4	133 MHz	6	200 MHz	4	33 MHz
0001_011	66/33 MHz	2/4	133 MHz	7	233 MHz	4	33 MHz
0001_100	66/33 MHz	2/4	133 MHz	8	266 MHz	4	33 MHz
0010_001	50/25 MHz	3/6	**150 MHz**	3	180 MHz	2.5	**60 MHz**
0010_010	50/25 MHz	3/6	**150 MHz**	3.5	210 MHz	2.5	**60 MHz**
0010_011	50/25 MHz	3/6	**150 MHz**	4	240 MHz	2.5	**60 MHz**
0010_100	50/25 MHz	3/6	**150 MHz**	4.5	270 MHz	2.5	**60 MHz**
0011_000	66/33 MHz	2/4	**133 MHz**	2.5	110MHz	3	44 MHz
0011_001	66/33 MHz	2/4	**133 MHz**	3	132 MHz	3	44 MHz
0011_010	66/33 MHz	2/4	**133 MHz**	3.5	154 MHz	3	**44 MHz**
0011_011	66/33 MHz	2/4	**133 MHz**	4	176MHz	3	**44 MHz**
0011_100	66/33 MHz	2/4	**133 MHz**	4.5	198 MHz	3	**44 MHz**
0100_000	66/33 MHz	3/6	200 MHz	2.5	166 MHz	**3**	66 MHz
0100_001	66/33 MHz	3/6	**200 MHz**	3	200 MHz	**3**	**66 MHz**
0100_010	66/33 MHz	3/6	**200 MHz**	3.5	233 MHz	**3**	**66 MHz**
0100_011	66/33 MHz	3/6	**200 MHz**	4	266 MHz	**3**	**66 MHz**

Figure 14 shows the side profile of the TBGA package to indicate the direction of the top surface view.

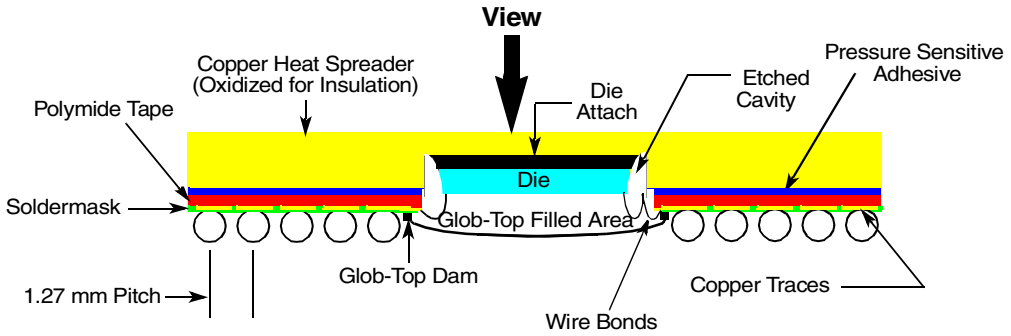


Figure 14. Side View of the TBGA Package

Table 21 shows the pinout list of the MPC826xA. Table 20 defines conventions and acronyms used in Table 21.

Symbols used in Table 21 are described in Table 20.

Table 20. Symbol Legend

Symbol	Meaning
OVERBAR	Signals with overbars, such as $\overline{TA}$, are active low.
UTM	Indicates that a signal is part of the UTOPIA master interface.
UTS	Indicates that a signal is part of the UTOPIA slave interface.
UT8	Indicates that a signal is part of the 8-bit UTOPIA interface.
UT16	Indicates that a signal is part of the 16-bit UTOPIA interface.
MII	Indicates that a signal is part of the media independent interface.

Table 21. Pinout List

Pin Name	Ball
BR	W5
BG	F4
ABB/IRQ2	E2
TS	E3
A0	G1
A1	H5
A2	H2
A3	H1
A4	J5
A5	J4
A6	J3
A7	J2

Table 21. Pinout List (continued)

Pin Name	Ball
A8	J1
A9	K4
A10	K3
A11	K2
A12	K1
A13	L5
A14	L4
A15	L3
A16	L2
A17	L1
A18	M5
A19	N5
A20	N4
A21	N3
A22	N2
A23	N1
A24	P4
A25	P3
A26	P2
A27	P1
A28	R1
A29	R3
A30	R5
A31	R4
TT0	F1
TT1	G4
TT2	G3
TT3	G2
TT4	F2
TBST	D3
TSIZ0	C1
TSIZ1	E4
TSIZ2	D2
TSIZ3	F5
AACK	F3

Table 21. Pinout List (continued)

Pin Name	Ball
PB18/FCC2_UT8_RXD4/FCC2_RXD3/L1CLKOD2/L1RXD2A2	AE14[2]
PB19/FCC2_UT8_RXD5/FCC2_RXD2/L1RQD2/L1RXD3A2	AF13[2]
PB20/FCC2_UT8_RXD6/FCC2_RXD1/L1RSYNCD2/L1TXD1A1	AG12[2]
PB21/FCC2_UT8_RXD7/FCC2_RXD0/FCC2_RXD/L1TSYNCD2/L1GNTD2/ L1TXD2A1	AH11[2]
PB22/FCC2_UT8_TXD7/FCC2_TXD0/FCC2_TXD/L1RXD1A1/L1RXDD2	AH16[2]
PB23/FCC2_UT8_TXD6/FCC2_TXD1/L1RXD2A1/L1TXDD2	AE15[2]
PB24/FCC2_UT8_TXD5/FCC2_TXD2/L1RXD3A1/L1RSYNCC2	AJ9[2]
PB25/FCC2_UT8_TXD4/FCC2_TXD3/L1TSYNCC2/L1GNTC2/L1TXD3A1	AE9[2]
PB26/FCC2_MII_CRS/FCC2_UT8_TXD1/L1RXDC2	AJ7[2]
PB27/FCC2_MII_COL/FCC2_UT8_TXD0/L1TXDC2	AH6[2]
PB28/FCC2_MII_RX_ER/$\overline{\text{FCC2\_RTS}}$/L1TSYNCB2/L1GNTB2/TXD1	AE3[2]
PB29/FCC2_UTM_RXCLAV/FCC2_UTS_RXCLAV/L1RSYNCB2/ FCC2_MII_TX_EN	AE2[2]
PB30/FCC2_MII_RX_DV/FCC2_UT_TXSOC/L1RXDB2	AC5[2]
PB31/FCC2_MII_TX_ER/FCC2_UT_RXSOC/L1TXDB2	AC4[2]
PC0/DREQ1/BRGO7/$\overline{\text{SMSYN2}}$/L1CLKOA2	AB26[2]
PC1/DREQ2/BRGO6/$\overline{\text{L1RQA2}}$	AD29[2]
PC2/$\overline{\text{FCC3\_CD}}$/FCC2_UT8_TXD3/$\overline{\text{DONE2}}$	AE29[2]
PC3/$\overline{\text{FCC3\_CTS}}$/FCC2_UT8_TXD2/$\overline{\text{DACK2}}$/$\overline{\text{CTS4}}$	AE27[2]
PC4/$\overline{\text{FCC2\_UTM\_RXENB}}$/$\overline{\text{FCC2\_UTS\_RXENB}}$/SI2_L1ST4/$\overline{\text{FCC2\_CD}}$	AF27[2]
PC5/FCC2_UTM_TXCLAV/FCC2_UTS_TXCLAV/SI2_L1ST3/$\overline{\text{FCC2\_CTS}}$	AF24[2]
PC6/$\overline{\text{FCC1\_CD}}$/L1CLKOC1/FCC1_UTM_RXADDR2/FCC1_UTS_RXADDR/ FCC1_UTM_RXCLAV1	AJ26[2]
PC7/$\overline{\text{FCC1\_CTS}}$/$\overline{\text{L1RQC1}}$/FCC1_UTM_TXADDR2/FCC1_UTS_TXADDR2/ FCC1_UTM_TXCLAV1	AJ25[2]
PC8/$\overline{\text{CD4}}$/RENA4/FCC1_UT16_TXD0/SI2_L1ST2/$\overline{\text{CTS3}}$	AF22[2]
PC9/$\overline{\text{CTS4}}$/CLSN4/FCC1_UT16_TXD1/SI2_L1ST1/L1TSYNCA2/L1GNTA2	AE21[2]
PC10/$\overline{\text{CD3}}$/RENA3/FCC1_UT16_TXD2/SI1_L1ST4/FCC2_UT8_RXD3	AF20[2]
PC11/$\overline{\text{CTS3}}$/CLSN3/L1CLKOD1/L1TXD3A2/FCC2_UT8_RXD2	AE19[2]
PC12/$\overline{\text{CD2}}$/RENA2/SI1_L1ST3/FCC1_UTM_RXADDR1/ FCC1_UTS_RXADDR1	AE18[2]
PC13/$\overline{\text{CTS2}}$/CLSN2/$\overline{\text{L1RQD1}}$/FCC1_UTM_TXADDR1/ FCC1_UTS_TXADDR1	AH18[2]
PC14/$\overline{\text{CD1}}$/RENA1/FCC1_UTM_RXADDR0/FCC1_UTS_RXADDR0	AH17[2]
PC15/$\overline{\text{CTS1}}$/CLSN1/SMTXD2/FCC1_UTM_TXADDR0/ FCC1_UTS_TXADDR0	AG16[2]

6 Ordering Information

Figure 16 provides an example of the Freescale part numbering nomenclature for the MPC826xA. In addition to the processor frequency, the part numbering scheme also consists of a part modifier that indicates any enhancement(s) in the part from the original production design. Each part number also contains a revision code that refers to the die mask revision number and is specified in the part numbering scheme for identification purposes only. For more information, contact your local Freescale sales office.

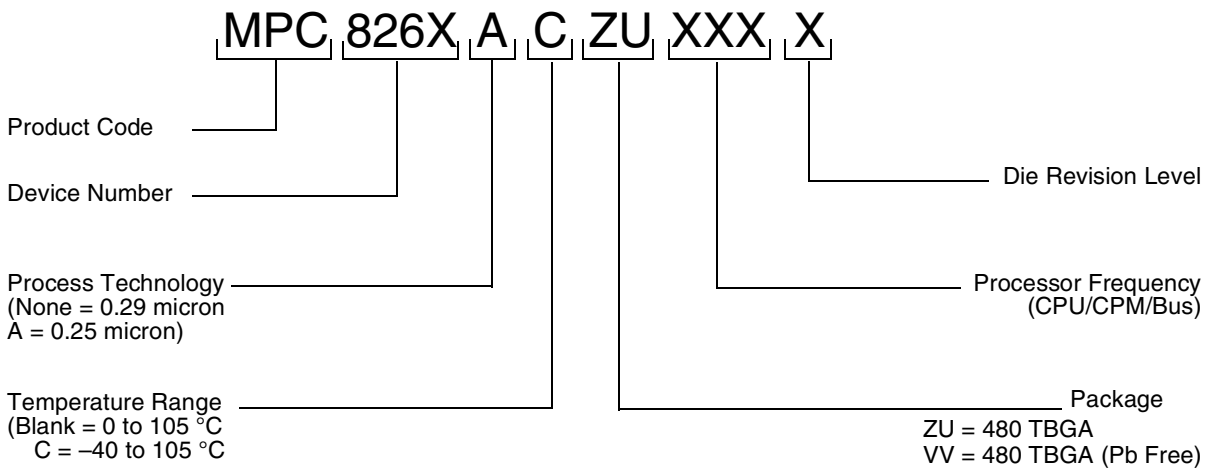


Figure 16. Freescale Part Number Key

7 Document Revision History

Table 23 lists significant changes in each revision of this document.

Table 23. Document Revision History

Revision	Date	Substantive Changes
2	06/2009	• Updated package values in Figure 16.
1.1	02/2006	• Addition of Table 12.
1.0	9/2005	• Document template update