



Welcome to E-XFL.COM

#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Active
Core Processor	12V1
Core Size	16-Bit
Speed	25MHz
Connectivity	CANbus, IrDA, LINbus, SCI, SPI
Peripherals	LVD, POR, PWM, WDT
Number of I/O	40
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	3.13V ~ 5.5V
Data Converters	A/D 12x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/s9s12g128f0mlfr

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

	<b>Function</b> <lowestpriorityhighest></lowestpriorityhighest>					Power	Internal Pull Resistor	
Package Pin	Pin	2nd Func.	3rd Func.	4th Func	5th Func	Supply	CTRL	Reset State
1	RESET	_	—	_	_	V <sub>DDX</sub>	PULLUF	þ
2	VDDXR	_	—	_	_	—	_	_
3	VSSX	_	—	—	—	—	_	_
4	PE0 <sup>1</sup>	EXTAL	—	_	_	V <sub>DDX</sub>	PUCR/PDPEE	Down
5	VSS	_	—		_	—	_	_
6	PE1 <sup>1</sup>	XTAL	—	_	_	V <sub>DDX</sub>	PUCR/PDPEE	Down
7	TEST	_	—		_	N.A.	RESET pin	Down
8	PJ0	KWJ0	—		_	V <sub>DDX</sub>	PERJ/PPSJ	Up
9	PJ1	KWJ1	—		_	V <sub>DDX</sub>	PERJ/PPSJ	Up
10	PJ2	KWJ2	—		_	V <sub>DDX</sub>	PERJ/PPSJ	Up
11	PJ3	KWJ3	—	_		V <sub>DDX</sub>	PERJ/PPSJ	Up
12	BKGD	MODC	—		_	V <sub>DDX</sub>	PUCR/BKPUE	Up
13	PP0	KWP0	ETRIG0	API_EXTC LK	PWM0	V <sub>DDX</sub>	PERP/PPSP	Disabled
14	PP1	KWP1	ETRIG1	ECLKX2	PWM1	V <sub>DDX</sub>	PERP/PPSP	Disabled
15	PP2	KWP2	ETRIG2	PWM2	_	V <sub>DDX</sub>	PERP/PPSP	Disabled
16	PP3	KWP3	ETRIG3	PWM3	—	V <sub>DDX</sub>	PERP/PPSP	Disabled
17	PP4	KWP4	PWM4	_	_	V <sub>DDX</sub>	PERP/PPSP	Disabled
18	PP5	KWP5	PWM5		_	V <sub>DDX</sub>	PERP/PPSP	Disabled
19	PT5	IOC5	—	—	—	V <sub>DDX</sub>	PERT/PPST	Disabled
20	PT4	IOC4	—	—	—	V <sub>DDX</sub>	PERT/PPST	Disabled
21	PT3	IOC3	—	_	_	V <sub>DDX</sub>	PERT/PPST	Disabled
22	PT2	IOC2	—	_	_	V <sub>DDX</sub>	PERT/PPST	Disabled
23	PT1	IOC1	IRQ	_	_	V <sub>DDX</sub>	PERT/PPST	Disabled
24	PT0	IOC0	XIRQ	—	—	V <sub>DDX</sub>	PERT/PPST	Disabled
25	PAD0	KWAD0	AN0	—	—	V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
26	PAD8	KWAD8	—	—	—	V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
27	PAD1	KWAD1	AN1	—	—	V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled

Table 1-10. 48-Pin LQFP/QFN Pinout for S12GN16 and S12GN32

MC9S12G Family Reference Manual Rev.1.27

	< 0	Function owestPRIORITYhighest>			Power	Internal P Resisto	ull r
Package Pin	Pin	2nd Func.	3rd Func.	4th Func.	Supply	CTRL	Reset State
57	PAD1	KWAD1	AN1	—	V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
58	PAD9	KWAD9	AN9	—	V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
59	PAD2	KWAD2	AN2	—	V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
60	PAD10	KWAD10	AN10	—	V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
61	PAD3	KWAD3	AN3	—	V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
62	PAD11	KWAD11	AN11		V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
63	PAD4	KWAD4	AN4		V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
64	PAD12	KWAD12	_		V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
65	PAD5	KWAD5	AN5		V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
66	PAD13	KWAD13			V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
67	PAD6	KWAD6	AN6	_	V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
68	PAD14	KWAD14	_		V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
69	PAD7	KWAD7	AN7		V <sub>DDA</sub>	PER1AD/PPS1AD	Disabled
70	PAD15	KWAD15	—	—	V <sub>DDA</sub>	PER0AD/PPS0AD	Disabled
71	PC4	—	—	—	V <sub>DDA</sub>	PUCR/PUPCE	Disabled
72	PC5		_	_	V <sub>DDA</sub>	PUCR/PUPCE	Disabled
73	PC6		—	—	V <sub>DDA</sub>	PUCR/PUPCE	Disabled
74	PC7		_	_	V <sub>DDA</sub>	PUCR/PUPCE	Disabled
75	VRH	—	_		_	_	_
76	VDDA	—	—	—	_	_	_
77	VSSA	—	—	—	_	_	_
78	PD0	—	_	_	V <sub>DDX</sub>	PUCR/PUPDE	Disabled
79	PD1	—	—	—	V <sub>DDX</sub>	PUCR/PUPDE	Disabled
80	PD2	—	_		V <sub>DDX</sub>	PUCR/PUPDE	Disabled
81	PD3	—	—	—	V <sub>DDX</sub>	PUCR/PUPDE	Disabled
82	PS0	RXD0	—	—	V <sub>DDX</sub>	PERS/PPSS	Up
83	PS1	TXD0	—	_	V <sub>DDX</sub>	PERS/PPSS	Up
84	PS2	RXD1	—	_	V <sub>DDX</sub>	PERS/PPSS	Up
85	PS3	TXD1	_		V <sub>DDX</sub>	PERS/PPSS	Up

Table 1-25.	100-Pin LQFP	Pinout for	S12GA96	and S12GA128
-------------	--------------	------------	---------	--------------

MC9S12G Family Reference Manual Rev.1.27

Vector Address <sup>1</sup>	Interrupt Source	CCR Mask	CCR Local Enable f		Wakeup from WAIT
Vector base + \$D2	ADC	l bit	ATDCTL2 (ASCIE)	No	Yes
Vector base + \$D0			Reserved	,	
Vector base + \$CE	Port J	l bit	PIEJ (PIEJ7-PIEJ0)	Yes	Yes
Vector base + \$CC	ACMP	l bit	ACMPC (ACIE)	No	Yes
Vector base + \$CA			Reserved		
Vector base + \$C8	Oscillator status interrupt	atus interrupt I bit CPMUINT (OSCIE)		No	Yes
Vector base + \$C6	PLL lock interrupt	PLL lock interrupt I bit CPMUINT (LOCKIE)		No	Yes
Vector base + \$C4			Reserved		
Vector base + \$C2	SCI2	SCI2 I bit SCI2CR2 (TIE, TCIE, RIE, ILIE)		Yes	Yes
Vector base + \$C0			Reserved		
Vector base + \$BE	SPI1	I bit SPI1CR1 (SPIE, SPTIE)		No	Yes
Vector base + \$BC	SPI2	l bit	SPI2CR1 (SPIE, SPTIE)	No	Yes
Vector base + \$BA	FLASH error	FLASH error I bit		No	No
Vector base + \$B8	FLASH command	l bit	FCNFG (CCIE)	No	Yes
Vector base + \$B6	CAN wake-up	l bit	CANRIER (WUPIE)	Yes	Yes
Vector base + \$B4	CAN errors	l bit	CANRIER (CSCIE, OVRIE)	No	Yes
Vector base + \$B2	CAN receive	l bit	CANRIER (RXFIE)	No	Yes
Vector base + \$B0	CAN transmit		CANTIER (TXEIE[2:0])	No	Yes
Vector base + \$AE to Vector base + \$90			Reserved		
Vector base + \$8E	Port P interrupt I bit PIEP (PIE		PIEP (PIEP7-PIEP0)	Yes	Yes
Vector base+ \$8C			Reserved		
Vector base + \$8A	Low-voltage interrupt (LVI)	l bit	CPMUCTRL (LVIE)	No	Yes
Vector base + \$88	Autonomous periodical interrupt (API)	Autonomous periodical interrupt (API)		Yes	Yes
Vector base + \$86			Reserved		
Vector base + \$84	ADC compare interrupt	I bit	ATDCTL2 (ACMPIE)	No	Yes
Vector base + \$82	Port AD interrupt	l bit	PIE1AD(PIE1AD7-PIE1AD0) PIE0AD(PIE0AD7-PIE0AD0)	Yes	Yes
Vector base + \$80	Spurious interrupt	_	None	-	-

Table 1-35	. Interrupt	Vector	Locations	(Sheet 2 of 2	2)
------------	-------------	--------	-----------	---------------	----

<sup>1</sup>16 bits vector address based <sup>2</sup>Only available if the 8 channel timer module is instantiated on the device <sup>3</sup>Only available if the 8 channel timer module is instantiated on the device

## 2.3.1 Pin BKGD

#### Table 2-5. Pin BKGD

BKGD	The BKGD pin is associated with the BDM module in all packages. During reset, the BKGD pin is used     as MODC input

### 2.3.2 Pins PA7-0

Table 2-6. Port A Pins PA7-0

PA7-PA0	These pins feature general-purpose I/O functionality only.
---------	--

### 2.3.3 Pins PB7-0

#### Table 2-7. Port B Pins PB7-0

PB7-PB6	These pins feature general-purpose I/O functionality only.
PB5	<ul> <li>100 LQFP: The XIRQ signal is mapped to this pin when used with the XIRQ interrupt function. The interrupt is enabled by clearing the X mask bit in the CPU Condition Code register. The I/O state of the pin is forced to input level upon the first clearing of the X bit and held in this state even if the bit is set again. A STOP or WAIT recovery with the X bit set (refer to CPU12/CPU12X Reference Manual) is not available.</li> <li>Signal priority: 100 LQFP: XIRQ &gt; GPO</li> </ul>
PB4	<ul> <li>100 LQFP: The IRQ signal is mapped to this pin when used with the IRQ interrupt function. If enabled (IRQEN=1) the I/O state of the pin is forced to be an input.</li> <li>Signal priority: 100 LQFP: IRQ &gt; GPO</li> </ul>
PB3	This pin features general-purpose I/O functionality only.
PB2	<ul> <li>100 LQFP: The ECLKX2 signal is mapped to this pin when used with the external clock function. The enabled ECLKX2 signal forces the I/O state to an output.</li> <li>Signal priority: 100 LQFP: ECLKX2 &gt; GPO</li> </ul>
PB1	<ul> <li>100 LQFP: The API_EXTCLK signal is mapped to this pin when used with the external clock function. If the Autonomous Periodic Interrupt clock is enabled and routed here the I/O state is forced to output.</li> <li>Signal priority: 100 LQFP: API_EXTCLK &gt; GPO</li> </ul>
PB0	<ul> <li>100 LQFP: The ECLK signal is mapped to this pin when used with the external clock function. The enabled ECLK signal forces the I/O state to an output.</li> <li>Signal priority: 100 LQFP: ECLK &gt; GPO</li> </ul>

### 2.3.4 Pins PC7-0

### NOTE

• When using AMPM1, AMPP1 or DACU1 please refer to section 2.6.1, "Initialization".

## 5.4.3 Unimplemented and Reserved Address Ranges

The S12GMMC is capable of mapping up 240K of flash, up to 4K of EEPROM and up to 11K of RAM into the global memory map. Smaller devices of the S12G-family do not utilize all of the available address space. Address ranges which are not associated with one of the on-chip memories fall into two categories: Unimplemented addresses and reserved addresses.

Unimplemented addresses are not mapped to any of the on-chip memories. The S12GMMC is aware that accesses to these address location have no destination and triggers a system reset (illegal address reset) whenever they are attempted by the CPU. The BDM is not able to trigger illegal address resets.

Reserved addresses are associated with a memory block on the device, even though the memory block does not contain the resources to fill the address space. The S12GMMC is not aware that the associated memory does not physically exist. It does not trigger an illegal address reset when accesses to reserved locations are attempted.



Table 5-8 shows the global address ranges of all members of the S12G-family.

Table 5-8. Global Address Ranges

ETRIGSEL	ETRIGCH3	ETRIGCH2	ETRIGCH1	ETRIGCH0	External trigger source is
0	0	0	0	0	AN0
0	0	0	0	1	AN1
0	0	0	1	0	AN2
0	0	0	1	1	AN3
0	0	1	0	0	AN4
0	0	1	0	1	AN5
0	0	1	1	0	AN6
0	0	1	1	1	AN7
0	1	0	0	0	AN8
0	1	0	0	1	AN9
0	1	0	1	0	AN10
0	1	0	1	1	AN11
0	1	1	0	0	AN11
0	1	1	0	1	AN11
0	1	1	1	0	AN11
0	1	1	1	1	AN11
1	0	0	0	0	ETRIG0 <sup>1</sup>
1	0	0	0	1	ETRIG1 <sup>1</sup>
1	0	0	1	0	ETRIG2 <sup>1</sup>
1	0	0	1	1	ETRIG3 <sup>1</sup>
1	0	1	Х	Х	Reserved
1	1	Х	Х	Х	Reserved

Table 14-5. External Trigger Channel Select Coding

<sup>1</sup> Only if ETRIG3-0 input option is available (see device specification), else ETRISEL is ignored, that means external trigger source is still on one of the AD channels selected by ETRIGCH3-0

## 14.3.2.3 ATD Control Register 2 (ATDCTL2)

Writes to this register will abort current conversion sequence.

Module Base + 0x0002





Read: Anytime

Write: Anytime

Analog-to-Digital Converter (ADC12B12CV2)

## 14.3.2.4 ATD Control Register 3 (ATDCTL3)

Writes to this register will abort current conversion sequence.

Module Base + 0x0003



### Figure 14-6. ATD Control Register 3 (ATDCTL3)

Read: Anytime

Write: Anytime

Field	Description
7 DJM	<ul> <li>Result Register Data Justification — Result data format is always unsigned. This bit controls justification of conversion data in the result registers.</li> <li>0 Left justified data in the result registers.</li> <li>1 Right justified data in the result registers.</li> <li>Table 14-9 gives example ATD results for an input signal range between 0 and 5.12 Volts.</li> </ul>
6–3 S8C, S4C, S2C, S1C	<b>Conversion Sequence Length</b> — These bits control the number of conversions per sequence. Table 14-10 shows all combinations. At reset, S4C is set to 1 (sequence length is 4). This is to maintain software continuity to HC12 family.
2 FIFO	<b>Result Register FIFO Mode</b> — If this bit is zero (non-FIFO mode), the A/D conversion results map into the result registers based on the conversion sequence; the result of the first conversion appears in the first result register (ATDDR0), the second result in the second result register (ATDDR1), and so on.
	If this bit is one (FIFO mode) the conversion counter is not reset at the beginning or end of a conversion sequence; sequential conversion results are placed in consecutive result registers. In a continuously scanning conversion sequence, the result register counter will wrap around when it reaches the end of the result register file. The conversion counter value (CC3-0 in ATDSTAT0) can be used to determine where in the result register file, the current conversion result will be placed.
	Aborting a conversion or starting a new conversion clears the conversion counter even if FIFO=1. So the first result of a new conversion sequence, started by writing to ATDCTL5, will always be place in the first result register (ATDDDR0). Intended usage of FIFO mode is continuos conversion (SCAN=1) or triggered conversion (ETRIG=1).
	Which result registers hold valid data can be tracked using the conversion complete flags. Fast flag clear mode may be useful in a particular application to track valid data.
	If this bit is one, automatic compare of result registers is always disabled, that is ADC12B12C will behave as if ACMPIE and all CPME[ <i>n</i> ] were zero. 0 Conversion results are placed in the corresponding result register up to the selected sequence length. 1 Conversion results are placed in consecutive result registers (wrap around at end).
1–0 FRZ[1:0]	<b>Background Debug Freeze Enable</b> — When debugging an application, it is useful in many cases to have the ATD pause when a breakpoint (Freeze Mode) is encountered. These 2 bits determine how the ATD will respond to a breakpoint as shown in Table 14-11. Leakage onto the storage node and comparator reference capacitors may compromise the accuracy of an immediately frozen conversion depending on the length of the freeze period.

#### Table 14-8. ATDCTL3 Field Descriptions

## 14.3.2.7 ATD Status Register 0 (ATDSTAT0)

This register contains the Sequence Complete Flag, overrun flags for external trigger and FIFO mode, and the conversion counter.

Module Base + 0x0006



Figure 14-9. ATD Status Register 0 (ATDSTAT0)

Read: Anytime

Write: Anytime (No effect on (CC3, CC2, CC1, CC0))

Table 14-10. AIDSTATU FIEld Descriptions	Table 14-16.	ATDSTAT0	Field [	Descriptions
--	--------------	----------	---------	--------------

Field	Description
7 SCF	Sequence Complete Flag — This flag is set upon completion of a conversion sequence. If conversion sequences are continuously performed (SCAN=1), the flag is set after each one is completed. This flag is cleared when one of the following occurs: <ul> <li>A) Write "1" to SCF</li> <li>B) Write to ATDCTL5 (a new conversion sequence is started)</li> <li>C) If AFFC=1 and a result register is read</li> <li>Conversion sequence has completed</li> </ul>
5 ETORF	<ul> <li>External Trigger Overrun Flag — While in edge sensitive mode (ETRIGLE=0), if additional active edges are detected while a conversion sequence is in process the overrun flag is set. This flag is cleared when one of the following occurs: <ul> <li>A) Write "1" to ETORF</li> <li>B) Write to ATDCTL0,1,2,3,4, ATDCMPE or ATDCMPHT (a conversion sequence is aborted)</li> <li>C) Write to ATDCTL5 (a new conversion sequence is started)</li> </ul> </li> <li>0 No External trigger overrun error has occurred</li> <li>1 External trigger overrun error has occurred</li> </ul>
4 FIFOR	Result Register Overrun Flag — This bit indicates that a result register has been written to before its associated conversion complete flag (CCF) has been cleared. This flag is most useful when using the FIFO mode because the flag potentially indicates that result registers are out of sync with the input channels. However, it is also practical for non-FIFO modes, and indicates that a result register has been overwritten before it has been read (i.e. the old data has been lost). This flag is cleared when one of the following occurs: <ul> <li>A) Write "1" to FIFOR</li> <li>B) Write to ATDCTL0,1,2,3,4, ATDCMPE or ATDCMPHT (a conversion sequence is aborted)</li> <li>C) Write to ATDCTL5 (a new conversion sequence is started)</li> </ul> <li>No overrun has occurred</li> <li>1 Overrun condition exists (result register has been written while associated CCFx flag was still set)</li>

### 15.3.2.12.2 Right Justified Result Data (DJM=1)



#### Figure 15-15. Right justified ATD conversion result register (ATDDRn)

Table 15-22 shows how depending on the A/D resolution the conversion result is transferred to the ATD result registers for right justified data. Compare is always done using all 12 bits of both the conversion result and the compare value in ATDDRn.

A/D resolution	DJM	conversion result mapping to ATDDR <i>n</i>
8-bit data	1	Result-Bit[7:0] = result, Result-Bit[11:8]=0000
10-bit data	1	Result-Bit[9:0] = result, Result-Bit[11:10]=00

Table 15-22. Conversion result mapping to ATDDRn

# 16.1.3 Block Diagram





MC9S12G Family Reference Manual Rev.1.27

## 20.1.2 Features

The SCI includes these distinctive features:

- Full-duplex or single-wire operation
- Standard mark/space non-return-to-zero (NRZ) format
- Selectable IrDA 1.4 return-to-zero-inverted (RZI) format with programmable pulse widths
- 13-bit baud rate selection
- Programmable 8-bit or 9-bit data format
- Separately enabled transmitter and receiver
- Programmable polarity for transmitter and receiver
- Programmable transmitter output parity
- Two receiver wakeup methods:
  - Idle line wakeup
  - Address mark wakeup
- Interrupt-driven operation with eight flags:
  - Transmitter empty
  - Transmission complete
  - Receiver full
  - Idle receiver input
  - Receiver overrun
  - Noise error
  - Framing error
  - Parity error
  - Receive wakeup on active edge
  - Transmit collision detect supporting LIN
  - Break Detect supporting LIN
- Receiver framing error detection
- Hardware parity checking
- 1/16 bit-time noise detection

## 20.1.3 Modes of Operation

The SCI functions the same in normal, special, and emulation modes. It has two low power modes, wait and stop modes.

- Run mode
- Wait mode
- Stop mode

Field	Description
7 RSEDGIE	Receive Input Active Edge Interrupt Enable — RXEDGIE enables the receive input active edge interrupt flag,         RXEDGIF, to generate interrupt requests.         0       RXEDGIF interrupt requests disabled         1       RXEDGIF interrupt requests enabled
1 BERRIE	<ul> <li>Bit Error Interrupt Enable — BERRIE enables the bit error interrupt flag, BERRIF, to generate interrupt requests.</li> <li>0 BERRIF interrupt requests disabled</li> <li>1 BERRIF interrupt requests enabled</li> </ul>
0 BKDIE	<ul> <li>Break Detect Interrupt Enable — BKDIE enables the break detect interrupt flag, BKDIF, to generate interrupt requests.</li> <li>0 BKDIF interrupt requests disabled</li> <li>1 BKDIF interrupt requests enabled</li> </ul>

### 20.3.2.5 SCI Alternative Control Register 2 (SCIACR2)



#### Figure 20-8. SCI Alternative Control Register 2 (SCIACR2)

Read: Anytime, if AMAP = 1

Write: Anytime, if AMAP = 1

#### Table 20-8. SCIACR2 Field Descriptions

Field	Description
2:1 BERRM[1:0]	<b>Bit Error Mode</b> — Those two bits determines the functionality of the bit error detect feature. See Table 20-9.
0 BKDFE	<ul> <li>Break Detect Feature Enable — BKDFE enables the break detect circuitry.</li> <li>0 Break detect circuit disabled</li> <li>1 Break detect circuit enabled</li> </ul>

#### Table 20-9. Bit Error Mode Coding

BERRM1	BERRM0	Function
0	0	Bit error detect circuit is disabled
0	1	Receive input sampling occurs during the 9th time tick of a transmitted bit (refer to Figure 20-19)
1	0	Receive input sampling occurs during the 13th time tick of a transmitted bit (refer to Figure 20-19)

#### MC9S12G Family Reference Manual Rev.1.27

RWU bit remains set and the receiver remains on standby until another idle character appears on the RXD pin.

Idle line wakeup requires that messages be separated by at least one idle character and that no message contains idle characters.

The idle character that wakes a receiver does not set the receiver idle bit, IDLE, or the receive data register full flag, RDRF.

The idle line type bit, ILT, determines whether the receiver begins counting logic 1s as idle character bits after the start bit or after the stop bit. ILT is in SCI control register 1 (SCICR1).

### 20.4.6.6.2 Address Mark Wakeup (WAKE = 1)

In this wakeup method, a logic 1 in the most significant bit (MSB) position of a frame clears the RWU bit and wakes up the SCI. The logic 1 in the MSB position marks a frame as an address frame that contains addressing information. All receivers evaluate the addressing information, and the receivers for which the message is addressed process the frames that follow. Any receiver for which a message is not addressed can set its RWU bit and return to the standby state. The RWU bit remains set and the receiver remains on standby until another address frame appears on the RXD pin.

The logic 1 MSB of an address frame clears the receiver's RWU bit before the stop bit is received and sets the RDRF flag.

Address mark wakeup allows messages to contain idle characters but requires that the MSB be reserved for use in address frames.

### NOTE

With the WAKE bit clear, setting the RWU bit after the RXD pin has been idle can cause the receiver to wake up immediately.

## 20.4.7 Single-Wire Operation

Normally, the SCI uses two pins for transmitting and receiving. In single-wire operation, the RXD pin is disconnected from the SCI. The SCI uses the TXD pin for both receiving and transmitting.



Figure 20-30. Single-Wire Operation (LOOPS = 1, RSRC = 1)

Enable single-wire operation by setting the LOOPS bit and the receiver source bit, RSRC, in SCI control register 1 (SCICR1). Setting the LOOPS bit disables the path from the RXD pin to the receiver. Setting the RSRC bit connects the TXD pin to the receiver. Both the transmitter and receiver must be enabled (TE = 1 and RE = 1). The TXDIR bit (SCISR2[1]) determines whether the TXD pin is going to be used as an input (TXDIR = 0) or an output (TXDIR = 1) in this mode of operation.

#### 64 KByte Flash Module (S12FTMRG64K1V1)

FCMD	Command	Function on P-Flash Memory
0x02	Erase Verify Block	Verify that a P-Flash block is erased.
0x03	Erase Verify P-Flash Section	Verify that a given number of words starting at the address provided are erased.
0x04	Read Once	Read a dedicated 64 byte field in the nonvolatile information register in P-Flash block that was previously programmed using the Program Once command.
0x06	Program P-Flash	Program a phrase in a P-Flash block.
0x07	Program Once	Program a dedicated 64 byte field in the nonvolatile information register in P-Flash block that is allowed to be programmed only once.
0x08	Erase All Blocks	Erase all P-Flash (and EEPROM) blocks. An erase of all Flash blocks is only possible when the FPLDIS, FPHDIS, and FPOPEN bits in the FPROT register and the DPOPEN bit in the EEPROT register are set prior to launching the command.
0x09	Erase Flash Block	Erase a P-Flash (or EEPROM) block. An erase of the full P-Flash block is only possible when FPLDIS, FPHDIS and FPOPEN bits in the FPROT register are set prior to launching the command.
0x0A	Erase P-Flash Sector	Erase all bytes in a P-Flash sector.
0x0B	Unsecure Flash	Supports a method of releasing MCU security by erasing all P-Flash (and EEPROM) blocks and verifying that all P-Flash (and EEPROM) blocks are erased.
0x0C	Verify Backdoor Access Key	Supports a method of releasing MCU security by verifying a set of security keys.
0x0D	Set User Margin Level	Specifies a user margin read level for all P-Flash blocks.
0x0E	Set Field Margin Level	Specifies a field margin read level for all P-Flash blocks (special modes only).

#### Table 27-28. P-Flash Commands

### 27.4.4.5 EEPROM Commands

Table 27-29 summarizes the valid EEPROM commands along with the effects of the commands on the EEPROM block.

Table 27-29	. EEPROM	Commands
-------------	----------	----------

FCMD	Command	Function on EEPROM Memory
0x01	Erase Verify All Blocks	Verify that all EEPROM (and P-Flash) blocks are erased.
0x02	Erase Verify Block	Verify that the EEPROM block is erased.

Register	Error Bit	Error Condition
	ACCERR	Set if CCOBIX[2:0] != 001 at command launch
		Set if command not available in current mode (see Table 27-27)
		Set if an invalid global address [17:16] is supplied see Table 27-3)
FSTAT		Set if a misaligned phrase address is supplied (global address [2:0] != 000)
	FPVIOL	Set if the selected P-Flash sector is protected
	MGSTAT1	Set if any errors have been encountered during the verify operation
	MGSTAT0	Set if any non-correctable errors have been encountered during the verify operation

Table 27-49. Erase P-Flash Sector Command Error Handling

### 27.4.6.10 Unsecure Flash Command

The Unsecure Flash command will erase the entire P-Flash and EEPROM memory space and, if the erase is successful, will release security.

Table 27-50. Unsecure Flash Command FCCOB Requirements

CCOBIX[2:0]	FCCOB P	arameters
000	0x0B	Not required

Upon clearing CCIF to launch the Unsecure Flash command, the Memory Controller will erase the entire P-Flash and EEPROM memory space and verify that it is erased. If the Memory Controller verifies that the entire Flash memory space was properly erased, security will be released. If the erase verify is not successful, the Unsecure Flash operation sets MGSTAT1 and terminates without changing the security state. During the execution of this command (CCIF=0) the user must not write to any Flash module register. The CCIF flag is set after the Unsecure Flash operation has completed.

Register	Error Bit	Error Condition
	ACCERR	Set if CCOBIX[2:0] != 000 at command launch
		Set if command not available in current mode (see Table 27-27)
FSTAT	FPVIOL	Set if any area of the P-Flash or EEPROM memory is protected
	MGSTAT1	Set if any errors have been encountered during the verify operation
	MGSTAT0	Set if any non-correctable errors have been encountered during the verify operation

Table 27-51. Unsecure Flash Command Error Handling

### 27.4.6.11 Verify Backdoor Access Key Command

The Verify Backdoor Access Key command will only execute if it is enabled by the KEYEN bits in the FSEC register (see Table 27-10). The Verify Backdoor Access Key command releases security if user-supplied keys match those stored in the Flash security bytes of the Flash configuration field (see



All assigned bits in the FERCNFG register are readable and writable.

#### Table 28-14. FERCNFG Field Descriptions

Field	Description
1 DFDIE	<ul> <li>Double Bit Fault Detect Interrupt Enable — The DFDIE bit controls interrupt generation when a double bit fault is detected during a Flash block read operation.</li> <li>0 DFDIF interrupt disabled</li> <li>1 An interrupt will be requested whenever the DFDIF flag is set (see Section 28.3.2.8)</li> </ul>
0 SFDIE	<ul> <li>Single Bit Fault Detect Interrupt Enable — The SFDIE bit controls interrupt generation when a single bit fault is detected during a Flash block read operation.</li> <li>0 SFDIF interrupt disabled whenever the SFDIF flag is set (see Section 28.3.2.8)</li> <li>1 An interrupt will be requested whenever the SFDIF flag is set (see Section 28.3.2.8)</li> </ul>

### 28.3.2.7 Flash Status Register (FSTAT)

The FSTAT register reports the operational status of the Flash module.

Offset Module Base + 0x0006



Figure 28-11. Flash Status Register (FSTAT)

<sup>1</sup> Reset value can deviate from the value shown if a double bit fault is detected during the reset sequence (see Section 28.6).

CCIF, ACCERR, and FPVIOL bits are readable and writable, MGBUSY and MGSTAT bits are readable but not writable, while remaining bits read 0 and are not writable.

### NOTE

Vector addresses and their relative interrupt priority are determined at the MCU level.

### 30.4.7.1 Description of Flash Interrupt Operation

The Flash module uses the CCIF flag in combination with the CCIE interrupt enable bit to generate the Flash command interrupt request. The Flash module uses the DFDIF and SFDIF flags in combination with the DFDIE and SFDIE interrupt enable bits to generate the Flash error interrupt request. For a detailed description of the register bits involved, refer to Section 30.3.2.5, "Flash Configuration Register (FCNFG)", Section 30.3.2.6, "Flash Error Configuration Register (FERCNFG)", Section 30.3.2.7, "Flash Status Register (FSTAT)", and Section 30.3.2.8, "Flash Error Status Register (FERSTAT)".

The logic used for generating the Flash module interrupts is shown in Figure 30-27.



Figure 30-27. Flash Module Interrupts Implementation

### 30.4.8 Wait Mode

The Flash module is not affected if the MCU enters wait mode. The Flash module can recover the MCU from wait via the CCIF interrupt (see Section 30.4.7, "Interrupts").

### 30.4.9 Stop Mode

If a Flash command is active (CCIF = 0) when the MCU requests stop mode, the current Flash operation will be completed before the MCU is allowed to enter stop mode.

# Chapter 31 240 KByte Flash Module (S12FTMRG240K2V1)

Revision Number	Revision Date	Sections Affected	Description of Changes
V01.06	23 Jun 2010	31.4.6.2/31-115 9 31.4.6.12/31-11 66 31.4.6.13/31-11 67	Updated description of the commands RD1BLK, MLOADU and MLOADF
V01.07	20 aug 2010	31.4.6.2/31-115 9 31.4.6.12/31-11 66 31.4.6.13/31-11 67	Updated description of the commands RD1BLK, MLOADU and MLOADF
Rev.1.27	31 Jan 2011	31.3.2.9/31-114 2	Updated description of protection on Section 31.3.2.9

#### Table 31-1. Revision History

## 31.1 Introduction

The FTMRG240K2 module implements the following:

- 240Kbytes of P-Flash (Program Flash) memory
- 4Kbytes of EEPROM memory

The Flash memory is ideal for single-supply applications allowing for field reprogramming without requiring external high voltage sources for program or erase operations. The Flash module includes a memory controller that executes commands to modify Flash memory contents. The user interface to the memory controller consists of the indexed Flash Common Command Object (FCCOB) register which is written to with the command, global address, data, and any required command parameters. The memory controller must complete the execution of a command before the FCCOB register can be written to with a new command.

### CAUTION

A Flash word or phrase must be in the erased state before being programmed. Cumulative programming of bits within a Flash word or phrase is not allowed.



Figure 31-1. FTMRG240K2 Block Diagram

# 31.2 External Signal Description

The Flash module contains no signals that connect off-chip.

# A.10 Electrical Characteristics for the Oscillator (XOSCLCP)

Table A-44. XOSCLCP Characteristics (Junction Temperature From –40°C To +150°C)

Conditions are shown in Table A-4 unless otherwise noted									
Num	С	Rating	Symbol	Min	Тур Мах		Unit		
1	С	Nominal crystal or resonator frequency	f <sub>OSC</sub>	4.0		16	MHz		
2	Ρ	Startup Current	iosc	100			μA		
3a	С	Oscillator start-up time (4MHz) <sup>1</sup>	t <sub>UPOSC</sub>		2	10	ms		
3b	С	Oscillator start-up time (8MHz) <sup>1</sup>	t <sub>UPOSC</sub>	_	1.6	8	ms		
3c	С	Oscillator start-up time (16MHz) <sup>1</sup>	t <sub>UPOSC</sub>	—	1	5	ms		
4	Ρ	Clock Monitor Failure Assert Frequency	f <sub>CMFA</sub>	200	450	1200	KHz		
5	D	Input Capacitance (EXTAL, XTAL pins)	C <sub>IN</sub>		7		pF		
6	С	EXTAL Pin Input Hysteresis	V <sub>HYS,EXTA</sub> L	_	120		mV		
7	с	EXTAL Pin oscillation amplitude (loop controlled Pierce) all mask sets except for 2N75C and 2N55V	V <sub>PP,EXTAL</sub>		1.0		V		
8	D	EXTAL Pin oscillation required amplitude <sup>2</sup> (loop controlled Pierce) all mask sets except for 2N75C and 2N55V	V <sub>PP,EXTAL</sub>	0.8	_	1.5	V		

<sup>1</sup> These values apply for carefully designed PCB layouts with capacitors that match the crystal/resonator requirements.

<sup>2</sup> Needs to be measured at room temperature on the application board using a probe with very low (<=5pF) input capacitance.