



#### Welcome to E-XFL.COM

#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Active
Core Processor	12V1
Core Size	16-Bit
Speed	25MHz
Connectivity	CANbus, IrDA, LINbus, SCI, SPI
Peripherals	LVD, POR, PWM, WDT
Number of I/O	26
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	3.13V ~ 5.5V
Data Converters	A/D 12x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/s9s12g64f1clc

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

PAD9	<ul> <li>48/64 LQFP: The ACMPO signal of the analog comparator is mapped to this pin when used with the ACMP function. If the ACMP output is enabled (ACMPC[ACOPE]=1) the I/O state will be forced to output.</li> <li>48/64/100 LQFP: The ADC analog input channel signal AN9 and the related digital trigger input are mapped to this pin. The ADC function has no effect on the output state. Refer to NOTE/2-172 for input buffer control.</li> <li>48/64/100 LQFP: Pin interrupts can be generated if enabled in digital input or output mode.</li> <li>Signal priority: 48 LQFP: ACMPO &gt; GPO 64/100 LQFP: GPO</li> </ul>
PAD8	<ul> <li>48/64/100 LQFP: The ADC analog input channel signal AN8 and the related digital trigger input are mapped to this pin. The ADC function has no effect on the output state. Refer to NOTE/2-172 for input buffer control.</li> <li>48/64/100 LQFP: Pin interrupts can be generated if enabled in digital input or output mode.</li> <li>Signal priority: 48/64/100 LQFP: GPO</li> </ul>
4	

#### Table 2-16. Port AD Pins AD15-8

<sup>1</sup> AMP output takes precedence over DACU output on shared pin.

#### Table 2-17. Port AD Pins AD7-0

PAD7	<ul> <li>32 LQFP: The inverting input signal ACMPM of the analog comparator is mapped to this pin when used with the ACMP function. The ACMP function has no effect on the output state. Refer to NOTE/2-172 for input buffer control.</li> <li>Except 20 TSSOP: The ADC analog input channel signal AN7 and the related digital trigger input are mapped to this pin. The ADC function has no effect on the output state. Refer to NOTE/2-172 for input buffer control.</li> <li>Except 20 TSSOP: Pin interrupts can be generated if enabled in digital input or output mode.</li> <li>Signal priority: Except 20 TSSOP: GPO</li> </ul>
PAD6	<ul> <li>32 LQFP: The non-inverting input signal ACMPP of the analog comparator is mapped to this pin when used with the ACMP function. The ACMP function has no effect on the output state. Refer to NOTE/2-172 for input buffer control.</li> <li>Except 20 TSSOP: The ADC analog input channel signal AN6 and the related digital trigger input are mapped to this pin. The ADC function has no effect on the output state. Refer to NOTE/2-172 for input buffer control.</li> <li>Except 20 TSSOP: Pin interrupts can be generated if enabled in digital input or output mode.</li> <li>Signal priority: Except 20 TSSOP: GPO</li> </ul>

Port Integration Module (S12GPIMV1)

# 2.4 PIM Ports - Memory Map and Register Definition

This section provides a detailed description of all PIM registers.

## 2.4.1 Memory Map

Table 2-18 shows the memory maps of all groups (for definitions see Table 2-2). Addresses 0x0000 to 0x0007 are only implemented in group G1 otherwise reserved.

Port	Global Address	Register	Access	Reset Value	Section/Page
(A)	0x0000	PORTA—Port A Data Register <sup>1</sup>	R/W	0x00	2.4.3.1/2-197
(B)	0x0001	PORTB—Port B Data Register <sup>1</sup>	R/W	0x00	2.4.3.2/2-197
	0x0002	DDRA—Port A Data Direction Register <sup>1</sup>	R/W	0x00	2.4.3.3/2-198
	0x0003	DDRB—Port B Data Direction Register <sup>1</sup>	R/W	0x00	2.4.3.4/2-199
(C)	0x0004	PORTC—Port C Data Register <sup>1</sup>	R/W	0x00	2.4.3.5/2-199
(D)	0x0005	PORTD—Port D Data Register <sup>1</sup>	R/W	0x00	2.4.3.6/2-200
	0x0006	DDRC—Port C Data Direction Register <sup>1</sup>	R/W	0x00	2.4.3.7/2-201
	0x0007	DDRD—Port D Data Direction Register <sup>1</sup>	R/W	0x00	2.4.3.8/2-201
E	0x0008	PORTE—Port E Data Register	R/W	0x00	
	0x0009	DDRE—Port E Data Direction Register	R/W	0x00	
	0x000A	Non-PIM address range <sup>2</sup>	-	-	-
	: 0x000B				
(A)	0x000C	PUCR—Pull Control Register	R/W	0x50	2.4.3.11/2-203
(B) (C) (D)	0x000D	Reserved	R	0x00	
	0x000E	Non-PIM address range <sup>2</sup>	-	-	-
	: 0x001B				
	0x001C	ECLKCTL—ECLK Control Register	R/W	0xC0	2.4.3.12/2-205
	0x001D	Reserved	R	0x00	
	0x001E	IRQCR—IRQ Control Register	R/W	0x00	2.4.3.13/2-205
	0x001F	Reserved	R	0x00	
	0x0020	Non-PIM address range <sup>2</sup>	-	-	-
	: 0x023F				

Table 2-18. Block Memory Map (0x0000-0x027F)

## 2.4.3.18 Port T Pull Device Enable Register (PERT)



Figure 2-19. Port T Pull Device Enable Register (PERT)

<sup>1</sup> Read: Anytime

Write: Anytime

#### Table 2-38. PERT Register Field Descriptions

Field	Description
7-2 PERT	<b>Port T pull device enable</b> —Enable pull device on input pin This bit controls whether a pull device on the associated port input pin is active. If a pin is used as output this bit has no effect. The polarity is selected by the related polarity select register bit.
	1 Pull device enabled 0 Pull device disabled
1 PERT	<b>Port T pull device enable</b> —Enable pull device on input pin This bit controls whether a pull device on the associated port input pin is active. The polarity is selected by the related polarity select register bit. If this pin is used as IRQ only a pullup device can be enabled.
	1 Pull device enabled 0 Pull device disabled
0 PERT	<b>Port T pull device enable</b> —Enable pull device on input pin This bit controls whether a pull device on the associated port input pin is active. The polarity is selected by the related polarity select register bit. If this pin is used as XIRQ only a pullup device can be enabled.
	1 Pull device enabled 0 Pull device disabled

#### S12S Debug Module (S12SDBGV2)

Bit	Description
0 PC16	<b>Program Counter bit 16</b> — In Normal and Loop1 mode this bit corresponds to program counter bit 16.

#### Table 8-39. PCH Field Descriptions (continued)

## 8.4.5.4 Trace Buffer Organization (Compressed Pure PC mode)

Table 8-40. Trace Buffer Organization Example (Compressed PurePC mode)

Modo	Line Number	2-bits	6-bits	6-bits	6-bits
Mode		Field 3	Field 2	Field 1	Field 0
Compressed Pure PC Mode	Line 1	00	PC1 (Initial 18-bit PC Base Address)		
	Line 2	11	PC4	PC3	PC2
	Line 3	01	0	0	PC5
	Line 4	00	PC6 (New 18-bit PC Base Address)		
	Line 5	10	0	PC8	PC7
	Line 6	00	PC9 (New 18-bit PC Base Address)		

### NOTE

Configured for end aligned triggering in compressed PurePC mode, then after rollover it is possible that the oldest base address is overwritten. In this case all entries between the pointer and the next base address have lost their base address following rollover. For example in Table 8-40 if one line of rollover has occurred, Line 1, PC1, is overwritten with a new entry. Thus the entries on Lines 2 and 3 have lost their base address. For reconstruction of program flow the first base address following the pointer must be used, in the example, Line 4. The pointer points to the oldest entry, Line 2.

### Field3 Bits in Compressed Pure PC Modes

Table 8-41. Compressed Pure PC Mode Field 3 Information Bit Encoding

INF1	INF0	TRACE BUFFER ROW CONTENT
0	0	Base PC address TB[17:0] contains a full PC[17:0] value
0	1	Trace Buffer[5:0] contain incremental PC relative to base address zero value
1	0	Trace Buffer[11:0] contain next 2 incremental PCs relative to base address zero value
1	1	Trace Buffer[17:0] contain next 3 incremental PCs relative to base address zero value

Each time that PC[17:6] differs from the previous base PC[17:6], then a new base address is stored. The base address zero value is the lowest address in the 64 address range

The first line of the trace buffer always gets a base PC address, this applies also on rollover.

Table 10-5	. CPMUCLKS	Descriptions	(continued)
------------	------------	--------------	-------------

Field	Description
1 RTIOSCSEL	<b>RTI Clock Select</b> — RTIOSCSEL selects the clock source to the RTI. Either IRCCLK or OSCCLK. Changing the RTIOSCSEL bit re-starts the RTI time-out period.
	UPOSC= 0 clears the RTIOSCSEL bit.
	1 RTI clock source is OSCCLK.
0	<b>COP Clock Select 0</b> — COPOSCSEL0 and COPOSCSEL1 combined determine the clock source to the COP
COP OSCSEL0	(see also Table 10-6) If COPOSCSEL1 = 1, COPOSCSEL0 has no effect regarding clock select and changing the COPOSCSEL0 bit does not re-start the COP time-out period.
	When COPOSCSEL1=0,COPOSCSEL0 selects the clock source to the COP to be either IRCCLK or OSCCLK. Changing the COPOSCSEL0 bit re-starts the COP time-out period.
	UPOSC= 0 clears the COPOSCSEL0 bit.
	0 COP clock source is IRCCLK.
	1 COP clock source is OSCCLK

#### Table 10-6. COPOSCSEL1, COPOSCSEL0 clock source select description

COPOSCSEL1	COPOSCSEL0	COP clock source
0	0	IRCCLK
0	1	OSCCLK
1	x	ACLK

## 10.3.2.7 S12CPMU PLL Control Register (CPMUPLL)

This register controls the PLL functionality.

0x003A



#### Figure 10-10. S12CPMU PLL Control Register (CPMUPLL)

Read: Anytime

Write: Anytime if PROT=0 (CPMUPROT register) and PLLSEL=1 (CPMUCLKS register). Else write has no effect.

#### NOTE

Write to this register clears the LOCK and UPOSC status bits.

#### MC9S12G Family Reference Manual Rev.1.27

	Figure 10-33. Enabling the External Oscillator
ena	ble external Oscillator by writing OSCE bit to one.
OSCE	
EXTAL	
	UPOSC flag is set upon successful start of oscillation
OSCCLK	
	select OSCCLK <sub>a</sub> as Core/Bus Clock by writing PLLSEL to zero
PLLSEL	
Core Clock	- based on PLLCLK based on OSCCLK

## 10.4.6 System Clock Configurations

## 10.4.6.1 PLL Engaged Internal Mode (PEI)

This mode is the default mode after System Reset or Power-On Reset.

The Bus clock is based on the PLLCLK, the reference clock for the PLL is internally generated (IRC1M). The PLL is configured to 50 MHz VCOCLK with POSTDIV set to 0x03. If locked (LOCK=1) this results in a PLLCLK of 12.5 MHz and a Bus clock of 6.25 MHz. The PLL can be re-configured to other bus frequencies.

The clock sources for COP and RTI can be based on the internal reference clock generator (IRC1M) or the RC-Oscillator (ACLK).

## 10.4.6.2 PLL Engaged External Mode (PEE)

In this mode, the Bus clock is based on the PLLCLK as well (like PEI). The reference clock for the PLL is based on the external oscillator.

The clock sources for COP and RTI can be based on the internal reference clock generator or on the external oscillator clock or the RC-Oscillator (ACLK).

This mode can be entered from default mode PEI by performing the following steps:

- 1. Configure the PLL for desired bus frequency.
- 2. Enable the external oscillator (OSCE bit).
- 3. Wait for oscillator to start-up and the PLL being locked (LOCK = 1) and (UPOSC = 1).

<sup>1</sup>If only AN0 should be converted use MULT=0.

## 12.3.2.2 ATD Control Register 1 (ATDCTL1)

Writes to this register will abort current conversion sequence.

Module Base + 0x0001



Figure 12-4. ATD Control Register 1 (ATDCTL1)

Read: Anytime

Write: Anytime

Table 12-3		Field	Descriptions
Table 12-3.	AIDUILI	гіеіа	Descriptions

Field	Description
7 ETRIGSEL	<b>External Trigger Source Select</b> — This bit selects the external trigger source to be either one of the AD channels or one of the ETRIG3-0 inputs. See device specification for availability and connectivity of ETRIG3-0 inputs. If a particular ETRIG3-0 input option is not available, writing a 1 to ETRISEL only sets the bit but has no effect, this means that one of the AD channels (selected by ETRIGCH3-0) is configured as the source for external trigger. The coding is summarized in Table 12-5.
6–5 SRES[1:0]	<b>A/D Resolution Select</b> — These bits select the resolution of A/D conversion results. See Table 12-4 for coding.
4 SMP_DIS	<ul> <li>Discharge Before Sampling Bit</li> <li>No discharge before sampling.</li> <li>The internal sample capacitor is discharged before sampling the channel. This adds 2 ATD clock cycles to the sampling time. This can help to detect an open circuit instead of measuring the previous sampled channel.</li> </ul>
3–0 ETRIGCH[3:0]	<b>External Trigger Channel Select</b> — These bits select one of the AD channels or one of the ETRIG3-0 inputs as source for the external trigger. The coding is summarized in Table 12-5.

SRES1	SRES0	A/D Resolution
0	0	8-bit data
0	1	10-bit data
1	0	12-bit data
1	1	Reserved

# 14.1.2 Modes of Operation

## 14.1.2.1 Conversion Modes

There is software programmable selection between performing **single** or **continuous conversion** on a **single channel** or **multiple channels**.

## 14.1.2.2 MCU Operating Modes

### • Stop Mode

Entering Stop Mode aborts any conversion sequence in progress and if a sequence was aborted restarts it after exiting stop mode. This has the same effect/consequences as starting a conversion sequence with write to ATDCTL5. So after exiting from stop mode with a previously aborted sequence all flags are cleared etc.

### • Wait Mode

ADC12B12C behaves same in Run and Wait Mode. For reduced power consumption continuous conversions should be aborted before entering Wait mode.

#### • Freeze Mode

In Freeze Mode the ADC12B12C will either continue or finish or stop converting according to the FRZ1 and FRZ0 bits. This is useful for debugging and emulation.

Table 20-4	. SCICR1	Field	Descriptions
------------	----------	-------	--------------

Field	Description
7 LOOPS	<ul> <li>Loop Select Bit — LOOPS enables loop operation. In loop operation, the RXD pin is disconnected from the SCI and the transmitter output is internally connected to the receiver input. Both the transmitter and the receiver must be enabled to use the loop function.</li> <li>0 Normal operation enabled</li> <li>1 Loop operation enabled</li> <li>The receiver input is determined by the RSRC bit.</li> </ul>
6 SCISWAI	<ul> <li>SCI Stop in Wait Mode Bit — SCISWAI disables the SCI in wait mode.</li> <li>SCI enabled in wait mode</li> <li>SCI disabled in wait mode</li> </ul>
5 RSRC	<ul> <li>Receiver Source Bit — When LOOPS = 1, the RSRC bit determines the source for the receiver shift register input. See Table 20-5.</li> <li>0 Receiver input internally connected to transmitter output</li> <li>1 Receiver input connected externally to transmitter</li> </ul>
4 M	<ul> <li>Data Format Mode Bit — MODE determines whether data characters are eight or nine bits long.</li> <li>0 One start bit, eight data bits, one stop bit</li> <li>1 One start bit, nine data bits, one stop bit</li> </ul>
3 WAKE	<ul> <li>Wakeup Condition Bit — WAKE determines which condition wakes up the SCI: a logic 1 (address mark) in the most significant bit position of a received data character or an idle condition on the RXD pin.</li> <li>Idle line wakeup</li> <li>Address mark wakeup</li> </ul>
2 ILT	<ul> <li>Idle Line Type Bit — ILT determines when the receiver starts counting logic 1s as idle character bits. The counting begins either after the start bit or after the stop bit. If the count begins after the start bit, then a string of logic 1s preceding the stop bit may cause false recognition of an idle character. Beginning the count after the stop bit avoids false idle character recognition, but requires properly synchronized transmissions.</li> <li>Idle character bit count begins after stop bit</li> </ul>
1 PE	<ul> <li>Parity Enable Bit — PE enables the parity function. When enabled, the parity function inserts a parity bit in the most significant bit position.</li> <li>0 Parity function disabled</li> <li>1 Parity function enabled</li> </ul>
0 PT	<ul> <li>Parity Type Bit — PT determines whether the SCI generates and checks for even parity or odd parity. With even parity, an even number of 1s clears the parity bit and an odd number of 1s sets the parity bit. With odd parity, an odd number of 1s clears the parity bit and an even number of 1s sets the parity bit.</li> <li>0 Even parity</li> <li>1 Odd parity</li> </ul>

#### Table 20-5. Loop Functions

LOOPS	RSRC	Function
0	х	Normal operation
1	0	Loop mode with transmitter output internally connected to receiver input
1	1	Single-wire mode with TXD pin connected to receiver input

# 20.4.4 Baud Rate Generation

A 13-bit modulus counter in the baud rate generator derives the baud rate for both the receiver and the transmitter. The value from 0 to 8191 written to the SBR12:SBR0 bits determines the bus clock divisor. The SBR bits are in the SCI baud rate registers (SCIBDH and SCIBDL). The baud rate clock is synchronized with the bus clock and drives the receiver. The baud rate clock divided by 16 drives the transmitter. The receiver has an acquisition rate of 16 samples per bit time.

Baud rate generation is subject to one source of error:

• Integer division of the bus clock may not give the exact target frequency.

Table 20-16 lists some examples of achieving target baud rates with a bus clock frequency of 25 MHz.

### When IREN = 0 then,

SCI baud rate = SCI bus clock / (16 \* SCIBR[12:0])

Bits SBR[12:0]	Receiver Clock (Hz)	Transmitter Clock (Hz)	Target Baud Rate	Error (%)
41	609,756.1	38,109.8	38,400	.76
81	308,642.0	19,290.1	19,200	.47
163	153,374.2	9585.9	9,600	.16
326	76,687.1	4792.9	4,800	.15
651	38,402.5	2400.2	2,400	.01
1302	19,201.2	1200.1	1,200	.01
2604	9600.6	600.0	600	.00
5208	4800.0	300.0	300	.00

#### Table 20-16. Baud Rates (Example: Bus Clock = 25 MHz)

## 22.3.2.12 Timer Input Capture/Output Compare Registers High and Low 0– 5(TCxH and TCxL)



	7	6	5	4	3	2	1	0	
R W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
Reset	0	0	0	0	0	0	0	0	



<sup>1</sup> This register is available only when the corresponding channel exists and is reserved if that channel does not exist. Writes to a reserved register have no functional effect. Reads from a reserved register return zeroes.

Depending on the TIOS bit for the corresponding channel, these registers are used to latch the value of the free-running counter when a defined transition is sensed by the corresponding input capture edge detector or to trigger an output action for output compare.

#### Read: Anytime

Write: Anytime for output compare function.Writes to these registers have no meaning or effect during input capture. All timer input capture/output compare registers are reset to 0x0000.

### NOTE

Read/Write access in byte mode for high byte should take place before low byte otherwise it will give a different result.

#### 32 KByte Flash Module (S12FTMRG32K1V1)

Register	Error Bit	Error Condition
		Set if CCOBIX[2:0] != 010 at command launch
		Set if command not available in current mode (see Table 25-27)
	ACCERR	Set if an invalid global address [17:0] is supplied
		Set if a misaligned word address is supplied (global address [0] != 0)
FSTAT		Set if the requested section breaches the end of the EEPROM block
	FPVIOL	None
	MGSTAT1	Set if any errors have been encountered during the read or if blank check failed.
	MGSTAT0	Set if any non-correctable errors have been encountered during the read or if blank check failed.

Table 25-61. Erase Verify EEPROM Section Command Error Handling

## 25.4.6.15 Program EEPROM Command

The Program EEPROM operation programs one to four previously erased words in the EEPROM block. The Program EEPROM operation will confirm that the targeted location(s) were successfully programmed upon completion.

### CAUTION

A Flash word must be in the erased state before being programmed. Cumulative programming of bits within a Flash word is not allowed.

 Table 25-62. Program EEPROM Command FCCOB Requirements

CCOBIX[2:0]	FCCOB Parameters		
000	0x11	Global address [17:16] to identify the EEPROM block	
001	Global address [15:0] of word to be programmed		
010	Word 0 program value		
011	Word 1 program value, if desired		
100	Word 2 program value, if desired		
101	Word 3 program value, if desired		

Upon clearing CCIF to launch the Program EEPROM command, the user-supplied words will be transferred to the Memory Controller and be programmed if the area is unprotected. The CCOBIX index value at Program EEPROM command launch determines how many words will be programmed in the EEPROM block. The CCIF flag is set when the operation has completed.

#### 32 KByte Flash Module (S12FTMRG32K1V1)

The user code stored in the P-Flash memory must have a method of receiving the backdoor keys from an external stimulus. This external stimulus would typically be through one of the on-chip serial ports.

If the KEYEN[1:0] bits are in the enabled state (see Section 25.3.2.2), the MCU can be unsecured by the backdoor key access sequence described below:

- 1. Follow the command sequence for the Verify Backdoor Access Key command as explained in Section 25.4.6.11
- 2. If the Verify Backdoor Access Key command is successful, the MCU is unsecured and the SEC[1:0] bits in the FSEC register are forced to the unsecure state of 10

The Verify Backdoor Access Key command is monitored by the Memory Controller and an illegal key will prohibit future use of the Verify Backdoor Access Key command. A reset of the MCU is the only method to re-enable the Verify Backdoor Access Key command. The security as defined in the Flash security byte (0x3\_FF0F) is not changed by using the Verify Backdoor Access Key command sequence. The backdoor keys stored in addresses 0x3\_FF00-0x3\_FF07 are unaffected by the Verify Backdoor Access Key command sequence. The Verify Backdoor Access Key command sequence has no effect on the program and erase protections defined in the Flash protection register, FPROT.

After the backdoor keys have been correctly matched, the MCU will be unsecured. After the MCU is unsecured, the sector containing the Flash security byte can be erased and the Flash security byte can be reprogrammed to the unsecure state, if desired. In the unsecure state, the user has full control of the contents of the backdoor keys by programming addresses 0x3\_FF00-0x3\_FF07 in the Flash configuration field.

## 25.5.2 Unsecuring the MCU in Special Single Chip Mode using BDM

A secured MCU can be unsecured in special single chip mode by using the following method to erase the P-Flash and EEPROM memory:

- 1. Reset the MCU into special single chip mode
- 2. Delay while the BDM executes the Erase Verify All Blocks command write sequence to check if the P-Flash and EEPROM memories are erased
- 3. Send BDM commands to disable protection in the P-Flash and EEPROM memory
- 4. Execute the Erase All Blocks command write sequence to erase the P-Flash and EEPROM memory. Alternatively the Unsecure Flash command can be executed, if so the steps 5 and 6 below are skeeped.
- 5. After the CCIF flag sets to indicate that the Erase All Blocks operation has completed, reset the MCU into special single chip mode
- 6. Delay while the BDM executes the Erase Verify All Blocks command write sequence to verify that the P-Flash and EEPROM memory are erased

If the P-Flash and EEPROM memory are verified as erased, the MCU will be unsecured. All BDM commands will now be enabled and the Flash security byte may be programmed to the unsecure state by continuing with the following steps:

7. Send BDM commands to execute the Program P-Flash command write sequence to program the Flash security byte to the unsecured state

# 26.4.6 Flash Command Description

This section provides details of all available Flash commands launched by a command write sequence. The ACCERR bit in the FSTAT register will be set during the command write sequence if any of the following illegal steps are performed, causing the command not to be processed by the Memory Controller:

- Starting any command write sequence that programs or erases Flash memory before initializing the FCLKDIV register
- Writing an invalid command as part of the command write sequence
- For additional possible errors, refer to the error handling table provided for each command

If a Flash block is read during execution of an algorithm (CCIF = 0) on that same block, the read operation will return invalid data if both flags SFDIF and DFDIF are set. If the SFDIF or DFDIF flags were not previously set when the invalid read operation occurred, both the SFDIF and DFDIF flags will be set.

If the ACCERR or FPVIOL bits are set in the FSTAT register, the user must clear these bits before starting any command write sequence (see Section 26.3.2.7).

## CAUTION

A Flash word or phrase must be in the erased state before being programmed. Cumulative programming of bits within a Flash word or phrase is not allowed.

## 26.4.6.1 Erase Verify All Blocks Command

The Erase Verify All Blocks command will verify that all P-Flash and EEPROM blocks have been erased.

Table 26-31. Erase Verify All Blocks Command FCCOB Requirements

CCOBIX[2:0]	FCCOB Parameters	
000	0x01	Not required

Upon clearing CCIF to launch the Erase Verify All Blocks command, the Memory Controller will verify that the entire Flash memory space is erased. The CCIF flag will set after the Erase Verify All Blocks operation has completed. If all blocks are not erased, it means blank check failed, both MGSTAT bits will be set.

 Table 26-32. Erase Verify All Blocks Command Error Handling

Register	Error Bit	Error Condition	
FSTAT	ACCERR	Set if CCOBIX[2:0] != 000 at command launch	
	FPVIOL	None	
	MGSTAT1	Set if any errors have been encountered during the reador if blank check failed .	
	MGSTAT0	Set if any non-correctable errors have been encountered during the read or if blank check failed.	

# 28.4.6 Flash Command Description

This section provides details of all available Flash commands launched by a command write sequence. The ACCERR bit in the FSTAT register will be set during the command write sequence if any of the following illegal steps are performed, causing the command not to be processed by the Memory Controller:

- Starting any command write sequence that programs or erases Flash memory before initializing the FCLKDIV register
- Writing an invalid command as part of the command write sequence
- For additional possible errors, refer to the error handling table provided for each command

If a Flash block is read during execution of an algorithm (CCIF = 0) on that same block, the read operation will return invalid data if both flags SFDIF and DFDIF are set. If the SFDIF or DFDIF flags were not previously set when the invalid read operation occurred, both the SFDIF and DFDIF flags will be set.

If the ACCERR or FPVIOL bits are set in the FSTAT register, the user must clear these bits before starting any command write sequence (see Section 28.3.2.7).

### CAUTION

A Flash word or phrase must be in the erased state before being programmed. Cumulative programming of bits within a Flash word or phrase is not allowed.

## 28.4.6.1 Erase Verify All Blocks Command

The Erase Verify All Blocks command will verify that all P-Flash and EEPROM blocks have been erased.

Table 28-31. Erase Verify All Blocks Command FCCOB Requirements

CCOBIX[2:0]	FCCOB Parameters		
000	0x01	Not required	

Upon clearing CCIF to launch the Erase Verify All Blocks command, the Memory Controller will verify that the entire Flash memory space is erased. The CCIF flag will set after the Erase Verify All Blocks operation has completed. If all blocks are not erased, it means blank check failed, both MGSTAT bits will be set.

 Table 28-32. Erase Verify All Blocks Command Error Handling

Register	Error Bit	Error Condition	
	ACCERR	Set if CCOBIX[2:0] != 000 at command launch	
	FPVIOL	None	
FSTAT	MGSTAT1	Set if any errors have been encountered during the read <sup>1</sup> or if blank check failed .	
	MGSTAT0	Set if any non-correctable errors have been encountered during the read <sup>1</sup> o blank check failed.	

<sup>1</sup> As found in the memory map for FTMRG96K1.

Register	Error Bit	Error Condition	
FSTAT	ACCERR	Set if CCOBIX[2:0] != 001 at command launch	
		Set if command not available in current mode (see Table 29-27)	
		Set if an invalid FlashBlockSelectionCode[1:0] is supplied (See Table 29-34)	
		Set if an invalid margin level setting is supplied	
	FPVIOL	None	
	MGSTAT1	None	
	MGSTAT0	None	

Table 29-59. Set Field Margin Level Command Error Handling

## CAUTION

Field margin levels must only be used during verify of the initial factory programming.

## NOTE

Field margin levels can be used to check that Flash memory contents have adequate margin for data retention at the normal level setting. If unexpected results are encountered when checking Flash memory contents at field margin levels, the Flash memory contents should be erased and reprogrammed.

## 29.4.6.14 Erase Verify EEPROM Section Command

The Erase Verify EEPROM Section command will verify that a section of code in the EEPROM is erased. The Erase Verify EEPROM Section command defines the starting point of the data to be verified and the number of words.

CCOBIX[2:0]	FCCOB Parameters		
000	0x10	Global address [17:16] to identify the EEPROM block	
001	Global address [15:0] of t	he first word to be verified	
010	Number of words to be verified		

Table 29-60. Erase Verify EEPROM Section Command FCCOB Requirements

Upon clearing CCIF to launch the Erase Verify EEPROM Section command, the Memory Controller will verify the selected section of EEPROM memory is erased. The CCIF flag will set after the Erase Verify EEPROM Section operation has completed. If the section is not erased, it means blank check failed, both MGSTAT bits will be set.

## 30.3.2.11 Flash Common Command Object Register (FCCOB)

The FCCOB is an array of six words addressed via the CCOBIX index found in the FCCOBIX register. Byte wide reads and writes are allowed to the FCCOB register.



## 30.3.2.11.1 FCCOB - NVM Command Mode

NVM command mode uses the indexed FCCOB register to provide a command code and its relevant parameters to the Memory Controller. The user first sets up all required FCCOB fields and then initiates the command's execution by writing a 1 to the CCIF bit in the FSTAT register (a 1 written by the user clears the CCIF command completion flag to 0). When the user clears the CCIF bit in the FSTAT register all FCCOB parameter fields are locked and cannot be changed by the user until the command completes (as evidenced by the Memory Controller returning CCIF to 1). Some commands return information to the FCCOB register array.

The generic format for the FCCOB parameter fields in NVM command mode is shown in Table 30-24. The return values are available for reading after the CCIF flag in the FSTAT register has been returned to 1 by the Memory Controller. Writes to the unimplemented parameter fields (CCOBIX = 110 and CCOBIX = 111) are ignored with reads from these fields returning 0x0000.

Table 30-24 shows the generic Flash command format. The high byte of the first word in the CCOB array contains the command code, followed by the parameters for this specific Flash command. For details on the FCCOB settings required by each command, see the Flash command descriptions in Section 30.4.6.

СС	OBIX[2:0]	Byte	FCCOB Parameter Fields (NVM Command Mode)	
HI		HI	FCMD[7:0] defining Flash command	
	000	LO	6'h0, Global address [17:16]	
	001	HI	Global address [15:8]	
001	LO	Global address [7:0]		

Table 30-24. FCCOB - NVM Command Mode (Typical Usage)

### NOTE

Vector addresses and their relative interrupt priority are determined at the MCU level.

## 30.4.7.1 Description of Flash Interrupt Operation

The Flash module uses the CCIF flag in combination with the CCIE interrupt enable bit to generate the Flash command interrupt request. The Flash module uses the DFDIF and SFDIF flags in combination with the DFDIE and SFDIE interrupt enable bits to generate the Flash error interrupt request. For a detailed description of the register bits involved, refer to Section 30.3.2.5, "Flash Configuration Register (FCNFG)", Section 30.3.2.6, "Flash Error Configuration Register (FERCNFG)", Section 30.3.2.7, "Flash Status Register (FSTAT)", and Section 30.3.2.8, "Flash Error Status Register (FERSTAT)".

The logic used for generating the Flash module interrupts is shown in Figure 30-27.



Figure 30-27. Flash Module Interrupts Implementation

## 30.4.8 Wait Mode

The Flash module is not affected if the MCU enters wait mode. The Flash module can recover the MCU from wait via the CCIF interrupt (see Section 30.4.7, "Interrupts").

## 30.4.9 Stop Mode

If a Flash command is active (CCIF = 0) when the MCU requests stop mode, the current Flash operation will be completed before the MCU is allowed to enter stop mode.

#### 192 KByte Flash Module (S12FTMRG192K2V1)

reprogrammed to the unsecure state, if desired. In the unsecure state, the user has full control of the contents of the backdoor keys by programming addresses 0x3\_FF00-0x3\_FF07 in the Flash configuration field.

## 30.5.2 Unsecuring the MCU in Special Single Chip Mode using BDM

A secured MCU can be unsecured in special single chip mode by using the following method to erase the P-Flash and EEPROM memory:

- 1. Reset the MCU into special single chip mode
- 2. Delay while the BDM executes the Erase Verify All Blocks command write sequence to check if the P-Flash and EEPROM memories are erased
- 3. Send BDM commands to disable protection in the P-Flash and EEPROM memory
- 4. Execute the Erase All Blocks command write sequence to erase the P-Flash and EEPROM memory. Alternatively the Unsecure Flash command can be executed, if so the steps 5 and 6 below are skeeped.
- 5. After the CCIF flag sets to indicate that the Erase All Blocks operation has completed, reset the MCU into special single chip mode
- 6. Delay while the BDM executes the Erase Verify All Blocks command write sequence to verify that the P-Flash and EEPROM memory are erased

If the P-Flash and EEPROM memory are verified as erased, the MCU will be unsecured. All BDM commands will now be enabled and the Flash security byte may be programmed to the unsecure state by continuing with the following steps:

- 7. Send BDM commands to execute the Program P-Flash command write sequence to program the Flash security byte to the unsecured state
- 8. Reset the MCU

## 30.5.3 Mode and Security Effects on Flash Command Availability

The availability of Flash module commands depends on the MCU operating mode and security state as shown in Table 30-27.

## 30.6 Initialization

On each system reset the flash module executes an initialization sequence which establishes initial values for the Flash Block Configuration Parameters, the FPROT and EEPROT protection registers, and the FOPT and FSEC registers. The initialization routine reverts to built-in default values that leave the module in a fully protected and secured state if errors are encountered during execution of the reset sequence. If a double bit fault is detected during the reset sequence, both MGSTAT bits in the FSTAT register will be set.

CCIF is cleared throughout the initialization sequence. The Flash module holds off all CPU access for a portion of the initialization sequence. Flash reads are allowed once the hold is removed. Completion of the initialization sequence is marked by setting CCIF high which enables user commands.

## 31.4.4.3 Valid Flash Module Commands

Table 31-27 present the valid Flash commands, as enabled by the combination of the functional MCU mode (Normal SingleChip NS, Special Singlechip SS) with the MCU security state (Unsecured, Secured).

Special Singlechip mode is selected by input mmc\_ss\_mode\_ts2 asserted. MCU Secured state is selected by input mmc\_secure input asserted.

FOND	<b>0</b>	Unsecured		Secured	
FCMD	Command	NS <sup>1</sup>	SS <sup>2</sup>	NS <sup>3</sup>	SS <sup>4</sup>
0x01	Erase Verify All Blocks	*	*	*	*
0x02	Erase Verify Block	*	*	*	*
0x03	Erase Verify P-Flash Section	*	*	*	
0x04	Read Once	*	*	*	
0x06	Program P-Flash	*	*	*	
0x07	Program Once	*	*	*	
0x08	Erase All Blocks		*		*
0x09	Erase Flash Block	*	*	*	
0x0A	Erase P-Flash Sector	*	*	*	
0x0B	Unsecure Flash		*		*
0x0C	Verify Backdoor Access Key	*		*	
0x0D	Set User Margin Level	*	*	*	
0x0E	Set Field Margin Level		*		
0x10	Erase Verify EEPROM Section	*	*	*	
0x11	Program EEPROM	*	*	*	
0x12	Erase EEPROM Sector	*	*	*	

Table 31-27. Flash Commands by Mode and Security State

<sup>1</sup> Unsecured Normal Single Chip mode

<sup>2</sup> Unsecured Special Single Chip mode.

<sup>3</sup> Secured Normal Single Chip mode.

<sup>4</sup> Secured Special Single Chip mode.

## 31.4.4.4 P-Flash Commands

Table 31-28 summarizes the valid P-Flash commands along with the effects of the commands on the P-Flash block and other resources within the Flash module.

FCMD	Command	Function on P-Flash Memory
0x01	Erase Verify All Blocks	Verify that all P-Flash (and EEPROM) blocks are erased.

 Table 31-28. P-Flash Commands