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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I <sup>2</sup> C, IrDA, SmartCard, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	53
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	1.85V ~ 3.8V
Data Converters	A/D 8x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg330f512-qfn64

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



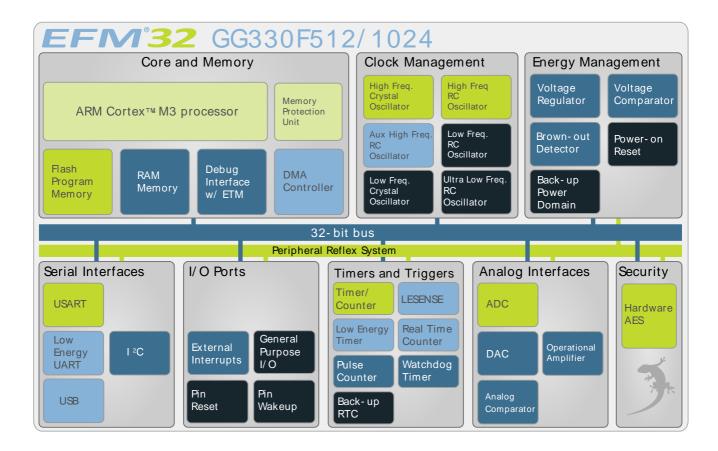
# 2 System Summary

# 2.1 System Introduction

The EFM32 MCUs are the world's most energy friendly microcontrollers. With a unique combination of the powerful 32-bit ARM Cortex-M3, innovative low energy techniques, short wake-up time from energy saving modes, and a wide selection of peripherals, the EFM32GG microcontroller is well suited for any battery operated application as well as other systems requiring high performance and low-energy consumption. This section gives a short introduction to each of the modules in general terms and also shows a summary of the configuration for the EFM32GG330 devices. For a complete feature set and in-depth information on the modules, the reader is referred to the *EFM32GG Reference Manual*.

A block diagram of the EFM32GG330 is shown in Figure 2.1 (p. 3).

Figure 2.1. Block Diagram



#### 2.1.1 ARM Cortex-M3 Core

The ARM Cortex-M3 includes a 32-bit RISC processor which can achieve as much as 1.25 Dhrystone MIPS/MHz. A Memory Protection Unit with support for up to 8 memory segments is included, as well as a Wake-up Interrupt Controller handling interrupts triggered while the CPU is asleep. The EFM32 implementation of the Cortex-M3 is described in detail in *EFM32 Cortex-M3 Reference Manual*.

### 2.1.2 Debug Interface (DBG)

This device includes hardware debug support through a 2-pin serial-wire debug interface and an Embedded Trace Module (ETM) for data/instruction tracing . In addition there is also a 1-wire Serial Wire Viewer pin which can be used to output profiling information, data trace and software-generated messages.



Descriptor-Based Scatter/Gather DMA and supports up to 6 OUT endpoints and 6 IN endpoints, in addition to endpoint 0. The on-chip PHY includes all OTG features, except for the voltage booster for supplying 5V to VBUS when operating as host.

#### 2.1.11 Inter-Integrated Circuit Interface (I2C)

The I<sup>2</sup>C module provides an interface between the MCU and a serial I<sup>2</sup>C-bus. It is capable of acting as both a master and a slave, and supports multi-master buses. Both standard-mode, fast-mode and fast-mode plus speeds are supported, allowing transmission rates all the way from 10 kbit/s up to 1 Mbit/s. Slave arbitration and timeouts are also provided to allow implementation of an SMBus compliant system. The interface provided to software by the I<sup>2</sup>C module, allows both fine-grained control of the transmission process and close to automatic transfers. Automatic recognition of slave addresses is provided in all energy modes.

# 2.1.12 Universal Synchronous/Asynchronous Receiver/Transmitter (US-ART)

The Universal Synchronous Asynchronous serial Receiver and Transmitter (USART) is a very flexible serial I/O module. It supports full duplex asynchronous UART communication as well as RS-485, SPI, MicroWire and 3-wire. It can also interface with ISO7816 SmartCards, IrDA and I2S devices.

#### 2.1.13 Pre-Programmed USB/UART Bootloader

The bootloader presented in application note AN0042 is pre-programmed in the device at factory. The bootloader enables users to program the EFM32 through a UART or a USB CDC class virtual UART without the need for a debugger. The autobaud feature, interface and commands are described further in the application note.

# 2.1.14 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)

The unique LEUART<sup>TM</sup>, the Low Energy UART, is a UART that allows two-way UART communication on a strict power budget. Only a 32.768 kHz clock is needed to allow UART communication up to 9600 baud/s. The LEUART includes all necessary hardware support to make asynchronous serial communication possible with minimum of software intervention and energy consumption.

# 2.1.15 Timer/Counter (TIMER)

The 16-bit general purpose Timer has 3 compare/capture channels for input capture and compare/Pulse-Width Modulation (PWM) output. TIMER0 also includes a Dead-Time Insertion module suitable for motor control applications.

# 2.1.16 Real Time Counter (RTC)

The Real Time Counter (RTC) contains a 24-bit counter and is clocked either by a 32.768 kHz crystal oscillator, or a 32.768 kHz RC oscillator. In addition to energy modes EM0 and EM1, the RTC is also available in EM2. This makes it ideal for keeping track of time since the RTC is enabled in EM2 where most of the device is powered down.

# 2.1.17 Backup Real Time Counter (BURTC)

The Backup Real Time Counter (BURTC) contains a 32-bit counter and is clocked either by a 32.768 kHz crystal oscillator, a 32.768 kHz RC oscillator or a 1 kHz ULFRCO. The BURTC is available in all Energy Modes and it can also run in backup mode, making it operational even if the main power should drain out.



available in energy mode EM2, in addition to EM0 and EM1, making it ideal for sensor monitoring in applications with a strict energy budget.

#### 2.1.26 Backup Power Domain

The backup power domain is a separate power domain containing a Backup Real Time Counter, BURTC, and a set of retention registers, available in all energy modes. This power domain can be configured to automatically change power source to a backup battery when the main power drains out. The backup power domain enables the EFM32GG330 to keep track of time and retain data, even if the main power source should drain out.

#### 2.1.27 Advanced Encryption Standard Accelerator (AES)

The AES accelerator performs AES encryption and decryption with 128-bit or 256-bit keys. Encrypting or decrypting one 128-bit data block takes 52 HFCORECLK cycles with 128-bit keys and 75 HFCORECLK cycles with 256-bit keys. The AES module is an AHB slave which enables efficient access to the data and key registers. All write accesses to the AES module must be 32-bit operations, i.e. 8- or 16-bit operations are not supported.

#### 2.1.28 General Purpose Input/Output (GPIO)

In the EFM32GG330, there are 52 General Purpose Input/Output (GPIO) pins, which are divided into ports with up to 16 pins each. These pins can individually be configured as either an output or input. More advanced configurations like open-drain, filtering and drive strength can also be configured individually for the pins. The GPIO pins can also be overridden by peripheral pin connections, like Timer PWM outputs or USART communication, which can be routed to several locations on the device. The GPIO supports up to 16 asynchronous external pin interrupts, which enables interrupts from any pin on the device. Also, the input value of a pin can be routed through the Peripheral Reflex System to other peripherals.

# 2.2 Configuration Summary

The features of the EFM32GG330 is a subset of the feature set described in the EFM32GG Reference Manual. Table 2.1 (p. 7) describes device specific implementation of the features.

Table 2.1. Configuration Summary

Module	Configuration	Pin Connections
Cortex-M3	Full configuration	NA
DBG	Full configuration	DBG_SWCLK, DBG_SWDIO, DBG_SWO
MSC	Full configuration	NA
DMA	Full configuration	NA
RMU	Full configuration	NA
EMU	Full configuration	NA
CMU	Full configuration	CMU_OUT0, CMU_OUT1
WDOG	Full configuration	NA
PRS	Full configuration	NA
USB	Full configuration	USB_VBUS, USB_VBUSEN, USB_VREGI, USB_VREGO, USB_DM, USB_DMPU, USB_DP, USB_ID



# **3.4 Current Consumption**

Table 3.3. Current Consumption

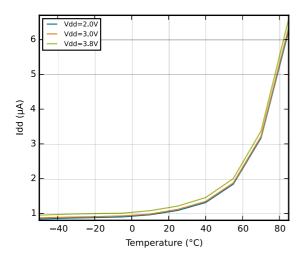
Symbol	Parameter	Condition	Min	Тур	Max	Unit
		48 MHz HFXO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		219	240	μΑ/ MHz
		28 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		205	225	μΑ/ MHz
	EM0 current. No prescaling. Run-	21 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		206	229	μΑ/ MHz
I <sub>EM0</sub>	ning prime num- ber calculation code from flash. (Produc-	14 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		209	232	μΑ/ MHz
	tion test condition = 14MHz)	11 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		211	234	μΑ/ MHz
		6.6 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		215	242	μΑ/ MHz
		1.2 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		243	327	μΑ/ MHz
		48 MHz HFXO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		80	90	μΑ/ MHz
		28 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		80	90	μΑ/ MHz
		21 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		81	91	μΑ/ MHz
I <sub>EM1</sub>	EM1 current (Production test condition = 14MHz)	14 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		83	99	μΑ/ MHz
		11 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		85	100	μΑ/ MHz
		6.6 MHz HFRCO, all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		90	102	μΑ/ MHz
		1.2 MHz HFRCO. all peripheral clocks disabled, V <sub>DD</sub> = 3.0 V		122	152	μΑ/ MHz
	EM2 ourrent	EM2 current with RTC prescaled to 1 Hz, 32.768 kHz LFRCO, V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C		1.11	1.9 <sup>1</sup>	μΑ
I <sub>EM2</sub> EI	EM2 current	EM2 current with RTC prescaled to 1 Hz, 32.768 kHz LFRCO, V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =85°C		8.81	21.5 <sup>1</sup>	μА
l=	EM3 current	V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C		0.81	1.5 <sup>1</sup>	μΑ
I <sub>EM3</sub>	LIVIO CUITETIL	V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =85°C		8.2 <sup>1</sup>	20.3 <sup>1</sup>	μΑ
leva	EM4 current	V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C		0.02	0.08	μΑ
I <sub>EM4</sub>	LIVIT OUTICITE	V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =85°C		0.5	2.5	μΑ

Only one RAM block enabled. The RAM block size is 32 kB.



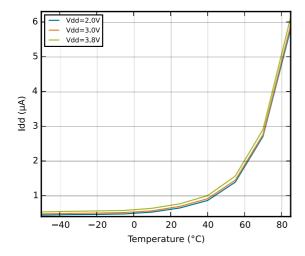
# 3.4.1 EM2 Current Consumption

Figure 3.1. EM2 current consumption. RTC<sup>1</sup> prescaled to 1 Hz, 32.768 kHz LFRCO.



### 3.4.2 EM3 Current Consumption

Figure 3.2. EM3 current consumption.

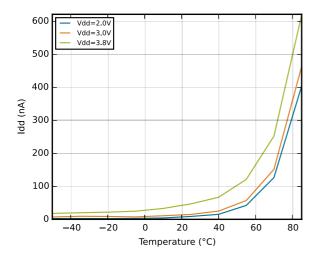


<sup>&</sup>lt;sup>1</sup>Using backup RTC.



#### 3.4.3 EM4 Current Consumption

Figure 3.3. EM4 current consumption.



# 3.5 Transition between Energy Modes

The transition times are measured from the trigger to the first clock edge in the CPU.

Table 3.4. Energy Modes Transitions

Symbol	Parameter	Min	Тур	Max	Unit
t <sub>EM10</sub>	Transition time from EM1 to EM0		0		HF- CORE- CLK cycles
t <sub>EM20</sub>	Transition time from EM2 to EM0		2		μs
t <sub>EM30</sub>	Transition time from EM3 to EM0		2		μs
t <sub>EM40</sub>	Transition time from EM4 to EM0		163		μs

# 3.6 Power Management

The EFM32GG requires the AVDD\_x, VDD\_DREG and IOVDD\_x pins to be connected together (with optional filter) at the PCB level. For practical schematic recommendations, please see the application note, "AN0002 EFM32 Hardware Design Considerations".

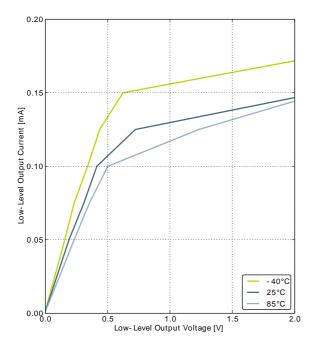


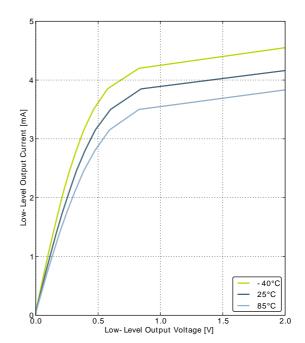
#### Table 3.5. Power Management

Symbol	Parameter	Condition	Min	Тур	Max	Unit
\ /	BOD threshold on	ЕМО	1.74		1.96	V
V <sub>BODextthr</sub> -	falling external sup- ply voltage	EM2	1.74		1.98	V
V <sub>BODintthr</sub> -	BOD threshold on falling internally regulated supply voltage		1.57		1.70	V
V <sub>BODextthr+</sub>	BOD threshold on rising external supply voltage			1.85	1.98	V
V <sub>PORthr+</sub>	Power-on Reset (POR) threshold on rising external sup- ply voltage				1.98	V
t <sub>RESET</sub>	Delay from reset is released until program execution starts	Applies to Power-on Reset, Brown-out Reset and pin reset.		163		μs
C <sub>DECOUPLE</sub>	Voltage regulator decoupling capacitor.	X5R capacitor recommended. Apply between DECOUPLE pin and GROUND		1		μF
C <sub>USB_VREGO</sub>	USB voltage regulator out decoupling capacitor.	X5R capacitor recommended. Apply between USB_VREGO pin and GROUND		1		μF
C <sub>USB_VREGI</sub>	USB voltage regulator in decoupling capacitor.	X5R capacitor recommended. Apply between USB_VREGI pin and GROUND		4.7		μF



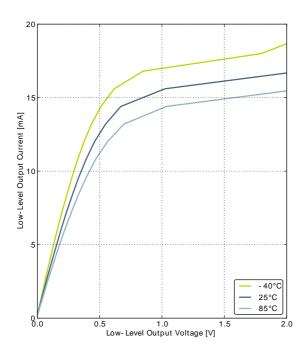
Figure 3.4. Typical Low-Level Output Current, 2V Supply Voltage

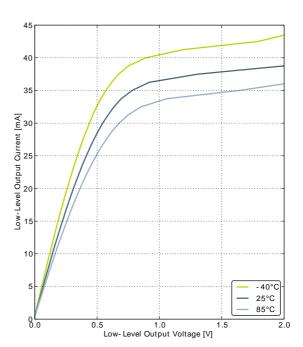




GPIO\_Px\_CTRL DRIVEMODE = LOWEST





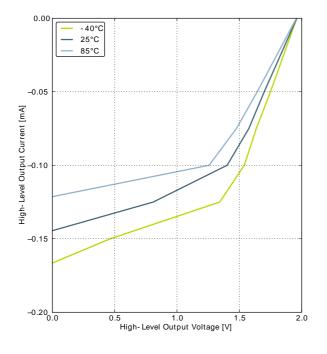


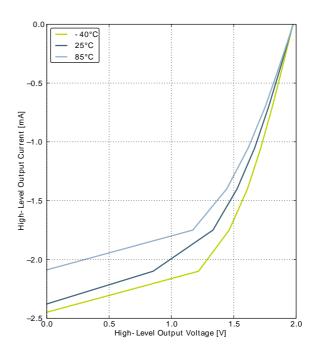
GPIO\_Px\_CTRL DRIVEMODE = STANDARD

GPIO\_Px\_CTRL DRIVEMODE = HIGH



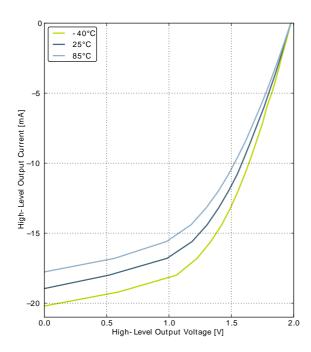
Figure 3.5. Typical High-Level Output Current, 2V Supply Voltage

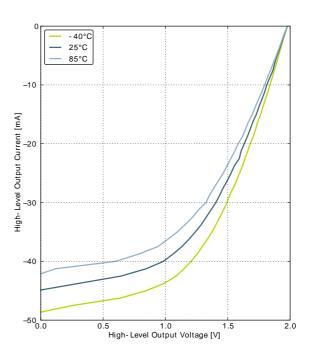




GPIO\_Px\_CTRL DRIVEMODE = LOWEST

GPIO\_Px\_CTRL DRIVEMODE = LOW





GPIO\_Px\_CTRL DRIVEMODE = STANDARD

GPIO\_Px\_CTRL DRIVEMODE = HIGH



#### 3.9 Oscillators

#### 3.9.1 LFXO

Table 3.8. LFXO

Symbol	Parameter	Condition	Min	Тур	Max	Unit
f <sub>LFXO</sub>	Supported nominal crystal frequency			32.768		kHz
ESR <sub>LFXO</sub>	Supported crystal equivalent series resistance (ESR)			30	120	kOhm
C <sub>LFXOL</sub>	Supported crystal external load range		X <sup>1</sup>		25	pF
DC <sub>LFXO</sub>	Duty cycle		48	50	53.5	%
I <sub>LFXO</sub>	Current consumption for core and buffer after startup.	ESR=30 kOhm, C <sub>L</sub> =10 pF, LFXOBOOST in CMU_CTRL is 1		190		nA
t <sub>LFXO</sub>	Start- up time.	ESR=30 kOhm, C <sub>L</sub> =10 pF, 40% - 60% duty cycle has been reached, LFXOBOOST in CMU_CTRL is 1		400		ms

<sup>&</sup>lt;sup>1</sup>See Minimum Load Capacitance (C<sub>LFXOL</sub>) Requirement For Safe Crystal Startup in energyAware Designer in Simplicity Studio

For safe startup of a given crystal, the Configurator tool in Simplicity Studio contains a tool to help users configure both load capacitance and software settings for using the LFXO. For details regarding the crystal configuration, the reader is referred to application note "AN0016 EFM32 Oscillator Design Consideration".

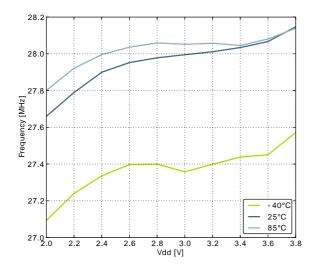
#### 3.9.2 HFXO

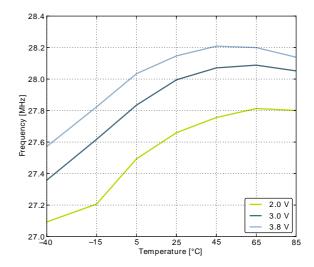
Table 3.9. HFXO

Symbol	Parameter	Condition	Min	Тур	Max	Unit
f <sub>HFXO</sub>	Supported nominal crystal Frequency		4		48	MHz
	Supported crystal	Crystal frequency 48 MHz			50	Ohm
ESR <sub>HFXO</sub>	equivalent series re-	Crystal frequency 32 MHz		30	60	Ohm
	sistance (ESR)	Crystal frequency 4 MHz		400	1500	Ohm
g <sub>mHFXO</sub>	The transconductance of the HFXO input transistor at crystal startup	HFXOBOOST in CMU_CTRL equals 0b11	20			mS
C <sub>HFXOL</sub>	Supported crystal external load range		5		25	pF
l	Current consump-	4 MHz: ESR=400 Ohm, C <sub>L</sub> =20 pF, HFXOBOOST in CMU_CTRL equals 0b11		85		μА
I <sub>HFXO</sub>	startup	32 MHz: ESR=30 Ohm, C <sub>L</sub> =10 pF, HFXOBOOST in CMU_CTRL equals 0b11		165		μΑ
t <sub>HFXO</sub>	Startup time	32 MHz: ESR=30 Ohm, C <sub>L</sub> =10 pF, HFXOBOOST in CMU_CTRL equals 0b11		400		μs



Figure 3.16. Calibrated HFRCO 28 MHz Band Frequency vs Supply Voltage and Temperature





#### 3.9.5 AUXHFRCO

Table 3.12. AUXHFRCO

Symbol	Parameter	Condition	Min	Тур	Max	Unit
		28 MHz frequency band	27.5	28.0	28.5	MHz
		21 MHz frequency band	20.6	21.0	21.4	MHz
ļ	Oscillation frequen-	14 MHz frequency band	13.7	14.0	14.3	MHz
† <sub>AUXHFRCO</sub>	cy, V <sub>DD</sub> = 3.0 V, T <sub>AMB</sub> =25°C	11 MHz frequency band	10.8	11.0	11.2	MHz
		7 MHz frequency band	6.48 <sup>1</sup>	6.60 <sup>1</sup>	6.72 <sup>1</sup>	MHz
		1 MHz frequency band	1.15 <sup>2</sup>	1.20 <sup>2</sup>	1.25 <sup>2</sup>	MHz
t <sub>AUXHFRCO_settlir</sub>	<sub>g</sub> Settling time after start-up	f <sub>AUXHFRCO</sub> = 14 MHz		0.6		Cycles
DC <sub>AUXHFRCO</sub>	Duty cycle	f <sub>AUXHFRCO</sub> = 14 MHz	48.5	50	51	%
TUNESTEP <sub>AUX</sub> HFRCO	Frequency step for LSB change in TUNING value			0.3 <sup>3</sup>		%

<sup>&</sup>lt;sup>1</sup>For devices with prod. rev. < 19, Typ = 7MHz and Min/Max values not applicable.

<sup>&</sup>lt;sup>2</sup>For devices with prod. rev. < 19, Typ = 1MHz and Min/Max values not applicable.

<sup>&</sup>lt;sup>3</sup>The TUNING field in the CMU\_AUXHFRCOCTRL register may be used to adjust the AUXHFRCO frequency. There is enough adjustment range to ensure that the frequency bands above 7 MHz will always have some overlap across supply voltage and temperature. By using a stable frequency reference such as the LFXO or HFXO, a firmware calibration routine can vary the TUNING bits and the frequency band to maintain the AUXHFRCO frequency at any arbitrary value between 7 MHz and 28 MHz across operating conditions.



Symbol	Parameter	Condition	Min	Тур	Max	Unit
C <sub>ADCIN</sub>	Input capacitance			2		pF
R <sub>ADCIN</sub>	Input ON resistance		1			MOhm
R <sub>ADCFILT</sub>	Input RC filter resistance			10		kOhm
C <sub>ADCFILT</sub>	Input RC filter/de- coupling capaci- tance			250		fF
f <sub>ADCCLK</sub>	ADC Clock Frequency				13	MHz
		6 bit	7			ADC- CLK Cycles
t <sub>ADCCONV</sub>	Conversion time	8 bit	11			ADC- CLK Cycles
		12 bit	13			ADC- CLK Cycles
t <sub>ADCACQ</sub>	Acquisition time	Programmable	1		256	ADC- CLK Cycles
t <sub>ADCACQVDD3</sub>	Required acquisition time for VDD/3 reference		2			μs
	Startup time of ref- erence generator and ADC core in NORMAL mode			5		μs
t <sub>ADCSTART</sub>	Startup time of ref- erence generator and ADC core in KEEPADCWARM mode			1		μs
		1 MSamples/s, 12 bit, single ended, internal 1.25V refer- ence		59		dB
		1 MSamples/s, 12 bit, single ended, internal 2.5V reference		63		dB
		1 MSamples/s, 12 bit, single ended, V <sub>DD</sub> reference		65		dB
SNR <sub>ADC</sub>	Signal to Noise Ratio (SNR)	1 MSamples/s, 12 bit, differential, internal 1.25V reference		60		dB
	ao (OIVIC)	1 MSamples/s, 12 bit, differential, internal 2.5V reference		65		dB
		1 MSamples/s, 12 bit, differential, 5V reference		54		dB
		1 MSamples/s, 12 bit, differential, V <sub>DD</sub> reference		67		dB
		1 MSamples/s, 12 bit, differential, 2xV <sub>DD</sub> reference		69		dB



Symbol	Parameter	Condition	Min	Тур	Max	Unit
		200 kSamples/s, 12 bit, single ended, internal 1.25V reference		62		dB
		200 kSamples/s, 12 bit, single ended, internal 2.5V reference		63		dB
		200 kSamples/s, 12 bit, single ended, V <sub>DD</sub> reference		67		dB
		200 kSamples/s, 12 bit, differential, internal 1.25V reference		63		dB
		200 kSamples/s, 12 bit, differential, internal 2.5V reference		66		dB
		200 kSamples/s, 12 bit, differential, 5V reference		66		dB
		200 kSamples/s, 12 bit, differential, V <sub>DD</sub> reference	63	66		dB
		200 kSamples/s, 12 bit, differential, 2xV <sub>DD</sub> reference		70		dB
		1 MSamples/s, 12 bit, single ended, internal 1.25V refer- ence		58		dB
		1 MSamples/s, 12 bit, single ended, internal 2.5V reference		62		dB
		1 MSamples/s, 12 bit, single ended, V <sub>DD</sub> reference		64		dB
		1 MSamples/s, 12 bit, differential, internal 1.25V reference		60		dB
		1 MSamples/s, 12 bit, differential, internal 2.5V reference		64		dB
		1 MSamples/s, 12 bit, differential, 5V reference		54		dB
		1 MSamples/s, 12 bit, differential, V <sub>DD</sub> reference		66		dB
SINAD <sub>ADC</sub>	SIgnal-to-Noise And Distortion-ratio (SINAD)	1 MSamples/s, 12 bit, differential, 2xV <sub>DD</sub> reference		68		dB
	(3.1.1.2)	200 kSamples/s, 12 bit, single ended, internal 1.25V reference		61		dB
		200 kSamples/s, 12 bit, single ended, internal 2.5V reference		65		dB
		200 kSamples/s, 12 bit, single ended, V <sub>DD</sub> reference		66		dB
		200 kSamples/s, 12 bit, differential, internal 1.25V reference		63		dB
		200 kSamples/s, 12 bit, differential, internal 2.5V reference		66		dB
		200 kSamples/s, 12 bit, differential, 5V reference		66		dB
		200 kSamples/s, 12 bit, differential, V <sub>DD</sub> reference	62	65		dB

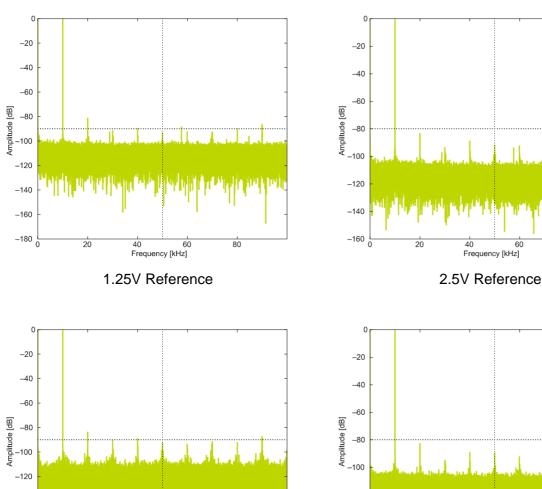


-140

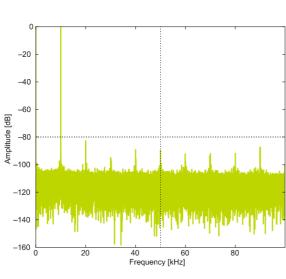
-160 -180

# 3.10.1 Typical performance

Figure 3.19. ADC Frequency Spectrum, Vdd = 3V, Temp = 25°C



2XVDDVSS Reference



**VDD** Reference

-20 - -40 - -60 - -60 - -100 - -120 - -140 - -160 0 20 40 60 80 Frequency [kHz]

**5VDIFF Reference** 



# 3.18 Digital Peripherals

#### Table 3.24. Digital Peripherals

Symbol	Parameter	Condition	Min	Тур	Max	Unit
I <sub>USART</sub>	USART current	USART idle current, clock enabled			μΑ/ MHz	
I <sub>UART</sub>	UART current	UART idle current, clock enabled		3.4		μΑ/ MHz
I <sub>LEUART</sub>	LEUART current	LEUART idle current, clock enabled		140		nA
I <sub>I2C</sub>	I2C current	I2C idle current, clock enabled		6.1		μΑ/ MHz
I <sub>TIMER</sub>	TIMER current	TIMER_0 idle current, clock enabled		6.9		μΑ/ MHz
I <sub>LETIMER</sub>	LETIMER current	LETIMER idle current, clock enabled		119		nA
I <sub>PCNT</sub>	PCNT current	PCNT idle current, clock enabled		54		nA
I <sub>RTC</sub>	RTC current	RTC idle current, clock enabled		54		nA
I <sub>AES</sub>	AES current	AES idle current, clock enabled		3.2		μΑ/ MHz
I <sub>GPIO</sub>	GPIO current	GPIO idle current, clock enabled			μΑ/ MHz	
I <sub>PRS</sub>	PRS current	PRS idle current			μΑ/ MHz	
I <sub>DMA</sub>	DMA current	Clock enable	able 11.0			



Alternate			LOC	ATION				
Functionality	0	1	2	3	4	5	6	Description
PCNT2_S1IN	PD1	PE9						Pulse Counter PCNT2 input number 1.
PRS_CH0	PA0							Peripheral Reflex System PRS, channel 0.
PRS_CH1	PA1							Peripheral Reflex System PRS, channel 1.
PRS_CH2	PC0	PF5						Peripheral Reflex System PRS, channel 2.
PRS_CH3	PC1	PE8						Peripheral Reflex System PRS, channel 3.
TIM0_CC0	PA0	PA0		PD1	PA0	PF0		Timer 0 Capture Compare input / output channel 0.
TIM0_CC1	PA1	PA1		PD2	PC0	PF1		Timer 0 Capture Compare input / output channel 1.
TIM0_CC2	PA2	PA2		PD3	PC1	PF2		Timer 0 Capture Compare input / output channel 2.
TIM0_CDTI0	PA3				PC2			Timer 0 Complimentary Deat Time Insertion channel 0.
TIM0_CDTI1	PA4				PC3			Timer 0 Complimentary Deat Time Insertion channel 1.
TIM0_CDTI2	PA5		PF5		PC4	PF5		Timer 0 Complimentary Deat Time Insertion channel 2.
TIM1_CC0		PE10		PB7	PD6			Timer 1 Capture Compare input / output channel 0.
TIM1_CC1		PE11		PB8	PD7			Timer 1 Capture Compare input / output channel 1.
TIM1_CC2		PE12		PB11				Timer 1 Capture Compare input / output channel 2.
TIM2_CC0	PA8		PC8					Timer 2 Capture Compare input / output channel 0.
TIM2_CC1	PA9		PC9					Timer 2 Capture Compare input / output channel 1.
TIM2_CC2	PA10		PC10					Timer 2 Capture Compare input / output channel 2.
TIM3_CC0	PE14							Timer 3 Capture Compare input / output channel 0.
TIM3_CC1	PE15							Timer 3 Capture Compare input / output channel 1.
TIM3_CC2	PA15							Timer 3 Capture Compare input / output channel 2.
US0_CLK	PE12		PC9		PB13	PB13		USART0 clock input / output.
US0_CS	PE13		PC8		PB14	PB14		USART0 chip select input / output.
								USART0 Asynchronous Receive.
US0_RX	PE11		PC10	PE12	PB8	PC1		USART0 Synchronous mode Master Input / Slave Output (MISO).
US0_TX	PE10		PC11	PE13	PB7	PC0		USART0 Asynchronous Transmit. Also used as receive in put in half duplex communication.
000_1X	1 210		1011	1 213		1 00		USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	PB7	PD2	PF0					USART1 clock input / output.
US1_CS	PB8	PD3	PF1					USART1 chip select input / output.
								USART1 Asynchronous Receive.
US1_RX	PC1	PD1	PD6					USART1 Synchronous mode Master Input / Slave Output (MISO).
IIS1 TV	PC0	BDO	PD7					USART1 Asynchronous Transmit. Also used as receive in put in half duplex communication.
US1_TX	PC0	PD0	PD7					USART1 Synchronous mode Master Output / Slave Inpu (MOSI).
US2_CLK	PC4							USART2 clock input / output.
US2_CS	PC5							USART2 chip select input / output.
								USART2 Asynchronous Receive.
US2_RX	PC3							USART2 Synchronous mode Master Input / Slave Output (MISO).
US2_TX	PC2							USART2 Asynchronous Transmit.Also used as receive in put in half duplex communication.



# **5 PCB Layout and Soldering**

# **5.1 Recommended PCB Layout**

Figure 5.1. QFN64 PCB Land Pattern

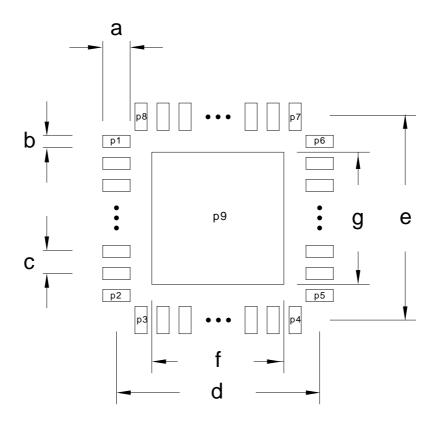


Table 5.1. QFN64 PCB Land Pattern Dimensions (Dimensions in mm)

Symbol	Dim. (mm)	Symbol	Pin number	Symbol	Pin number
а	0.85	P1	1	P8	64
b	0.30	P2	16	P9	65
С	0.50	P3	17	-	-
d	8.90	P4	32	-	-
е	8.90	P5	33	-	-
f	7.20	P6	48	-	-
g	7.20	P7	49	-	-



#### **7.5 Revision 1.10**

June 28th, 2013

Updated power requirements in the Power Management section.

Removed minimum load capacitance figure and table. Added reference to application note.

Other minor corrections.

#### 7.6 Revision 1.00

September 11th, 2012

Updated the HFRCO 1 MHz band typical value to 1.2 MHz.

Updated the HFRCO 7 MHz band typical value to 6.6 MHz.

Other minor corrections.

#### **7.7 Revision 0.98**

May 25th, 2012

Corrected EM3 current consumption in the Electrical Characteristics section.

#### 7.8 Revision 0.96

February 28th, 2012

Added reference to errata document.

Corrected QFN64 package drawing.

Updated PCB land pattern, solder mask and stencil design.

#### **7.9 Revision 0.95**

September 28th, 2011

Flash configuration for Giant Gecko is now 1024KB or 512KB. For flash sizes below 512KB, see the Leopard Gecko Family.

Corrected operating voltage from 1.8 V to 1.85 V.

Added rising POR level to Electrical Characteristics section.

Updated Minimum Load Capacitance (C<sub>LFXOL</sub>) Requirement For Safe Crystal Startup.

Added Gain error drift and Offset error drift to ADC table.

Added Opamp pinout overview.

Added reference to errata document.

Corrected QFN64 package drawing.

Updated PCB land pattern, solder mask and stencil design.



#### 7.10 Revision 0.91

March 21th, 2011

Added new alternative locations for SWO.

Added new USB Pin to pinout table.

Corrected slew rate data for Opamps.

#### 7.11 Revision 0.90

February 4th, 2011

Initial preliminary release.



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