Microchip Technology - PIC16LC771T-E/SS Datasheet

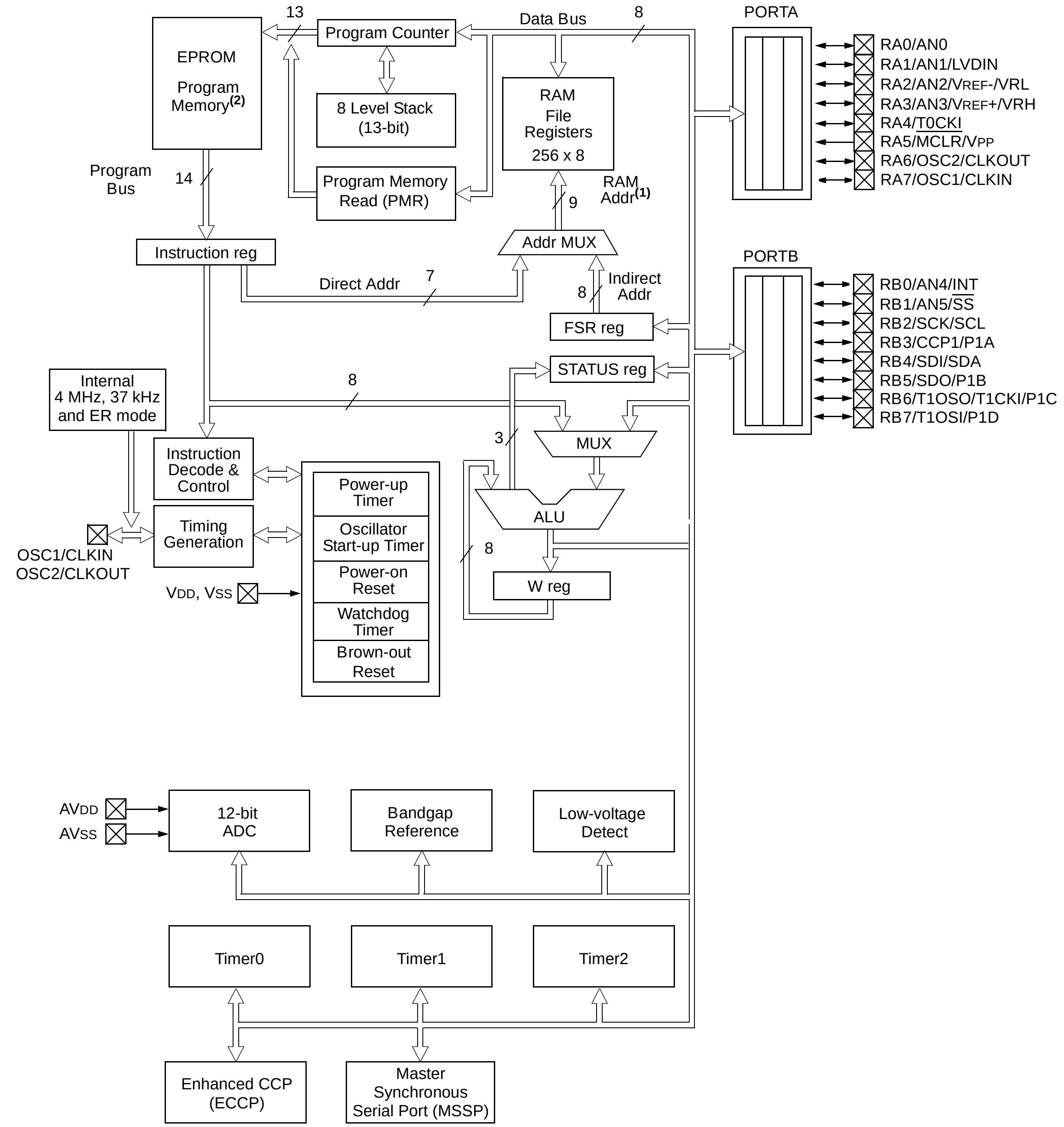
What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	I²C, SPI
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	15
Program Memory Size	7KB (4K x 14)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	2.5V ~ 5.5V
Data Converters	A/D 6x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	20-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lc771t-e-ss

FIGURE 1-2: PIC16C770/771 BLOCK DIAGRAM



Note 1: Higher order bits are from the STATUS register.

2: Program memory for PIC16C770 is 2K x 14. Program memory for PIC16C771 is 4K x 14.

2.2.2.3 INTCON REGISTER

The INTCON Register is a readable and writable register, which contains various enable and flag bits for the TMR0 register overflow, RB Port change and External RB0/INT pin interrupts.

Note:	Interrupt flag bits get set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the global enable bit, GIE (INTCON<7>). User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

REGISTER 2-3: INTERRUPT CONTROL REGISTER (INTCON: 0Bh, 8Bh, 10Bh, 18Bh)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-x
GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF
bit 7							bit 0

bit 7 **GIE:** Global Interrupt Enable bit
1 = Enables all un-masked interrupts
0 = Disables all interrupts

bit 6 **PEIE:** Peripheral Interrupt Enable bit
1 = Enables all un-masked peripheral interrupts
0 = Disables all peripheral interrupts

bit 5 **T0IE:** TMR0 Overflow Interrupt Enable bit
1 = Enables the TMR0 interrupt
0 = Disables the TMR0 interrupt

bit 4 **INTE:** RB0/INT External Interrupt Enable bit
1 = Enables the RB0/INT external interrupt
0 = Disables the RB0/INT external interrupt

bit 3 **RBIE:** RB Port Change Interrupt Enable bit**(1)**
1 = Enables the RB port change interrupt
0 = Disables the RB port change interrupt

bit 2 **T0IF:** TMR0 Overflow Interrupt Flag bit
1 = TMR0 register has overflowed (must be cleared in software)
0 = TMR0 register did not overflow

bit 1 **INTF:** RB0/INT External Interrupt Flag bit
1 = The RB0/INT external interrupt occurred (must be cleared in software)
0 = The RB0/INT external interrupt did not occur

bit 0 **RBIF:** RB Port Change Interrupt Flag bit**(1)**
1 = At least one of the RB<7:0> pins changed state (must be cleared in software)
0 = None of the RB<7:0> pins have changed state

Note 1: Individual RB pin interrupt-on-change can be enabled/disabled from the Interrupt-on-Change PORTB register (IOCB).

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
- n = Value at POR	’1’ = Bit is set	’0’ = Bit is cleared	x = Bit is unknown

2.2.2.5 PIR1 REGISTER

This register contains the individual flag bits for the peripheral interrupts.

Note:	Interrupt flag bits get set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the global enable bit, GIE (INTCON<7>). User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

REGISTER 2-5: PERIPHERAL INTERRUPT REGISTER 1 (PIR1: 0Ch)

U-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	ADIF	—	—	SSPIF	CCP1IF	TMR2IF	TMR1IF
bit 7							bit 0

bit 7 **Unimplemented:** Read as ‘0’.

bit 6 **ADIF:** A/D Converter Interrupt Flag bit
1 = An A/D conversion completed
0 = The A/D conversion is not complete

bit 5-4 **Unimplemented:** Read as ’0’

bit 3 **SSPIF:** Synchronous Serial Port (SSP) Interrupt Flag
1 = The SSP interrupt condition has occurred, and must be cleared in software before returning from the Interrupt Service Routine. The conditions that will set this bit are:
SPI
A transmission/reception has taken place.
I^{2}C Slave / Master
A transmission/reception has taken place.
I^{2}C Master
The initiated START condition was completed by the SSP module.
The initiated STOP condition was completed by the SSP module.
The initiated Restart condition was completed by the SSP module.
The initiated Acknowledge condition was completed by the SSP module.
A START condition occurred while the SSP module was IDLE (Multi-master system).
A STOP condition occurred while the SSP module was IDLE (Multi-master system).
0 = No SSP interrupt condition has occurred.

bit 2 **CCP1IF:** CCP1 Interrupt Flag bit
Capture Mode
1 = A TMR1 register capture occurred (must be cleared in software)
0 = No TMR1 register capture occurred
Compare Mode
1 = A TMR1 register compare match occurred (must be cleared in software)
0 = No TMR1 register compare match occurred
PWM Mode
Unused in this mode

bit 1 **TMR2IF:** TMR2 to PR2 Match Interrupt Flag bit
1 = TMR2 to PR2 match occurred (must be cleared in software)
0 = No TMR2 to PR2 match occurred

bit 0 **TMR1IF:** TMR1 Overflow Interrupt Flag bit
1 = TMR1 register overflowed (must be cleared in software)
0 = TMR1 register did not overflow

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
- n = Value at POR	’1’ = Bit is set	’0’ = Bit is cleared	x = Bit is unknown

FIGURE 3-3: BLOCK DIAGRAM OF RA4/T0CKI

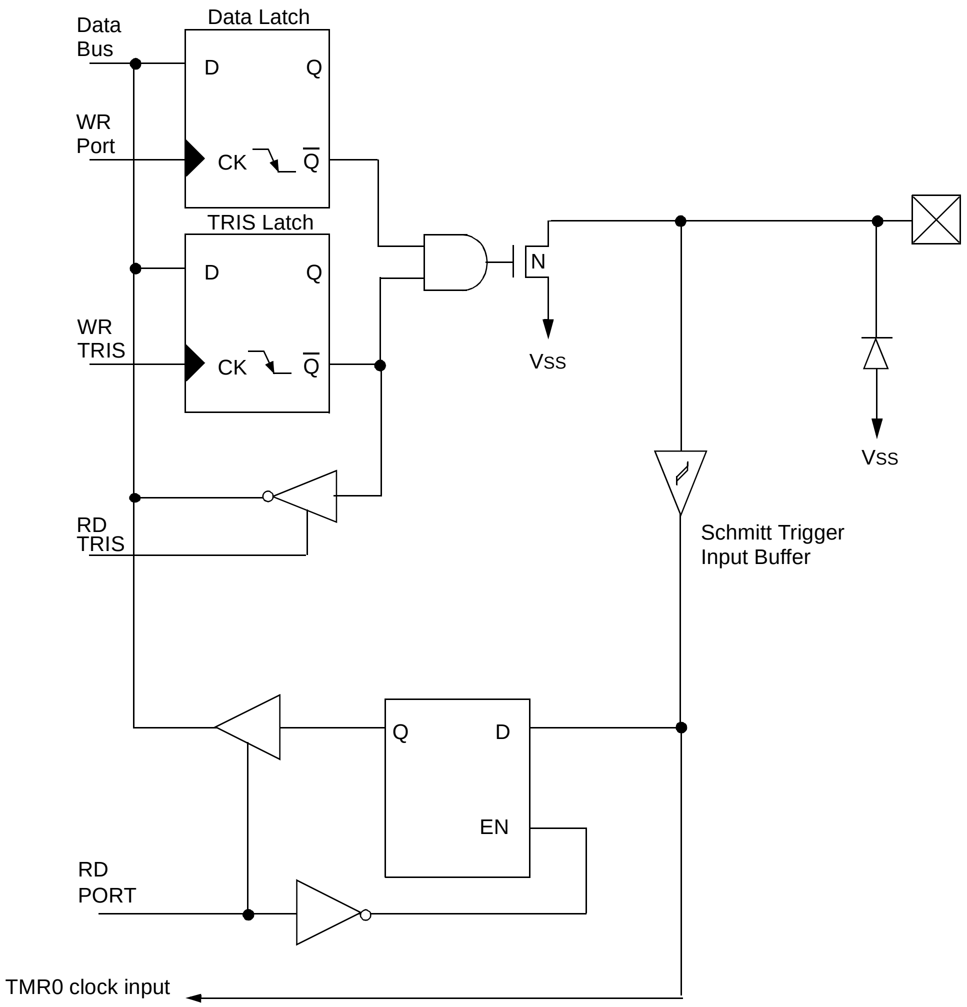


TABLE 3-1: PORTA FUNCTIONS

Name	Function	Input Type	Output Type	Description
RA0/AN0	RA0	ST	CMOS	Bi-directional I/O
	AN0	AN		A/D input
RA1/AN1/LVDIN	RA1	ST	CMOS	Bi-directional I/O
	AN1	AN		A/D input
	LVDIN	AN		LVD input reference
RA2/AN2/VREF-/VRL	RA2	ST	CMOS	Bi-directional I/O
	AN2	AN		A/D input
	VREF-	AN		Negative analog reference input
	VRL		AN	Internal voltage reference low output
RA3/AN3/VREF+/VRH	RA3	ST	CMOS	Bi-directional I/O
	AN3	AN		A/D input
	VREF+	AN		Positive analog reference input
	VRH		AN	Internal voltage reference high output
RA4/T0CKI	RA4	ST	OD	Bi-directional I/O
	T0CKI	ST		TMR0 clock input
RA5/$\overline{\text{MCLR}}$/VPP	RA5	ST		Input port
	$\overline{\text{MCLR}}$	ST		Master clear
	VPP	Power		Programming voltage
RA6/OSC2/CLKOUT	RA6	ST	CMOS	Bi-directional I/O
	OSC2		XTAL	Crystal/resonator
	CLKOUT		CMOS	FOSC/4 output
RA7/OSC1/CLKIN	RA7	ST	CMOS	Bi-directional I/O
	OSC1	XTAL		Crystal/resonator
	CLKIN	ST/AN		External clock input/ER resistor connection

TABLE 3-2: SUMMARY OF REGISTERS ASSOCIATED WITH PORTA

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other RESETS
05h	PORTA	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	`xxxx 0000`	`uuuu 0000`
85h	TRISA	PORTA Data Direction Register								`1111 1111`	`1111 1111`
9Dh	ANSEL	—	—	ANS5	ANS4	ANS3	ANS2	ANS1	ANS0	`--11 1111`	`--11 1111`

Legend: x = unknown, u = unchanged, - = unimplemented locations read as '0'. Shaded cells are not used by PORTA.

3.3 PORTB and the TRISB Register

PORTB is an 8-bit wide bi-directional port. The corresponding data direction register is TRISB. Setting a TRISB bit (=1) will make the corresponding PORTB pin an input (i.e., put the corresponding output driver in a Hi-impedance mode). Clearing a TRISB bit (=0) will make the corresponding PORTB pin an output (i.e., put the contents of the output latch on the selected pin).

EXAMPLE 3-2: Initializing PORTB

```
BCF     STATUS, RP0;
CLRF    PORTB      ; Initialize PORTB by
                   ; clearing output
                   ; data latches
BSF     STATUS, RP0; Select Bank 1
MOVLW   0xCF       ; Value used to
                   ; initialize data
                   ; direction
MOVWF   TRISB      ; Set RB<3:0> as inputs
                   ; RB<5:4> as outputs
                   ; RB<7:6> as inputs
MOVLW   0x30       ; Set RB<1:0> as analog
                     inputs
MOVWF   ANSEL      ;
BCF     STATUS, RP0; Return to Bank 0
```

Each of the PORTB pins has an internal pull-up, which can be individually enabled from the WPUB register. A single global enable bit can turn on/off the enabled pull-ups. Clearing the $\overline{\text{RBPU}}$ bit, (OPTION_REG<7>), enables the weak pull-up resistors. The weak pull-up is automatically turned off when the port pin is configured as an output. The pull-ups are disabled on a Power-on Reset.

Each of the PORTB pins, if configured as input, also has an interrupt-on-change feature, which can be individually selected from the IOCB register. The RBIE bit in the INTCON register functions as a global enable bit to turn on/off the interrupt-on-change feature. The selected inputs are compared to the old value latched on the last read of PORTB. The "mismatch" outputs are OR'ed together to generate the RB Port Change Interrupt with flag bit RBIF (INTCON<0>).

This interrupt can wake the device from SLEEP. The user, in the interrupt service routine, can clear the interrupt in the following manner:

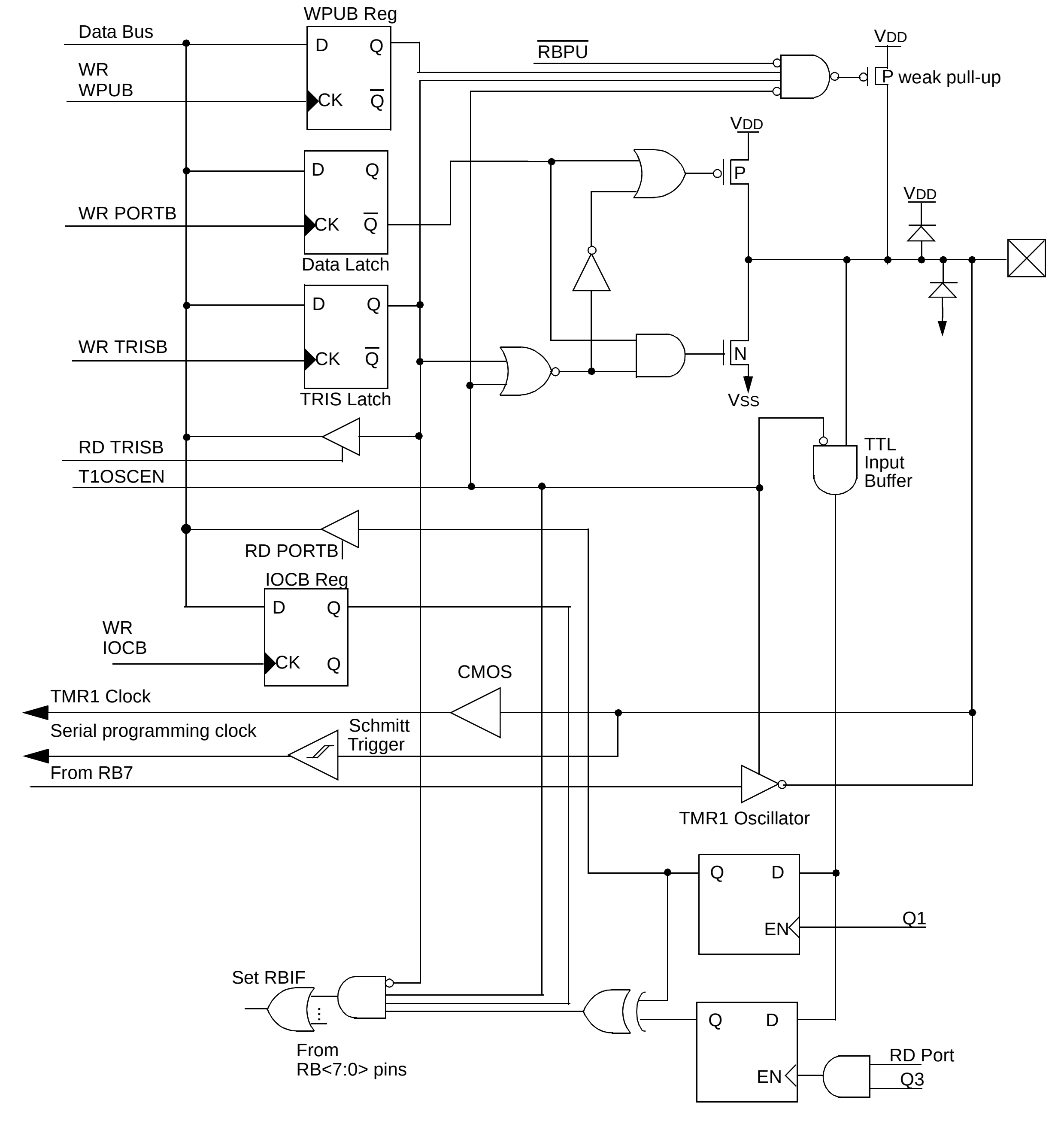
a) Any read or write of PORTB. This will end the mismatch condition.

a) Clear flag bit RBIF.

A mismatch condition will continue to set flag bit RBIF. Reading PORTB will end the mismatch condition and allow flag bit RBIF to be cleared.

The interrupt-on-change feature is recommended for wake-up on key depression operation and operations where PORTB is only used for the interrupt-on-change feature. Polling of PORTB is not recommended while using the interrupt-on-change feature.

FIGURE 3-9: BLOCK DIAGRAM OF RB6/T1OSO/T1CKI/P1C



Note: The TMR1 oscillator enable (T1OSCEN = 1) overrides the RB6 I/O port and P1C functions.

6.2 Timer1 Oscillator

A crystal oscillator circuit is built in between pins T1OSI (input) and T1OSO (amplifier output). It is enabled by setting control bit T1OSCEN (T1CON<3>). The oscillator is a low power oscillator rated up to 200 kHz. It will continue to run during SLEEP. It is primarily intended for a 32 kHz crystal. Table 6-1 shows the capacitor selection for the Timer1 oscillator.

The Timer1 oscillator is identical to the LP oscillator. The user must provide a software time delay to ensure proper oscillator start-up.

TABLE 6-1: CAPACITOR SELECTION FOR THE TIMER1 OSCILLATOR

Osc Type	Freq	C1	C2
LP	32 kHz	33 pF	33 pF
	100 kHz	15 pF	15 pF
	200 kHz	15 pF	15 pF
These values are for design guidance only.			
Note 1: Higher capacitance increases the stability of oscillator but also increases the start-up time. **2:** Since each resonator/crystal has its own characteristics, the user should consult the resonator/crystal manufacturer for appropriate values of external components.			

6.3 Timer1 Interrupt

The TMR1 Register pair (TMR1H:TMR1L) increments from 0000h to FFFFh and rolls over to 0000h. The TMR1 Interrupt, if enabled, is generated on overflow which is latched in interrupt flag bit TMR1IF (PIR1<0>). This interrupt can be enabled/disabled by setting/clearing TMR1 interrupt enable bit TMR1IE (PIE1<0>).

6.4 Resetting Timer1 using a CCP Trigger Output

If the ECCP module is configured in Compare mode to generate a “special event trigger" (CCP1M<3:0> = `1011`), this signal will reset Timer1 and start an A/D conversion (if the A/D module is enabled).

> **Note:** The special event triggers from the CCP1 module will not set interrupt flag bit TMR1IF (PIR1<0>).

Timer1 must be configured for either timer or Synchronized Counter mode to take advantage of this feature. If Timer1 is running in Asynchronous Counter mode, this RESET operation may not work.

In the event that a write to Timer1 coincides with a special event trigger from ECCP, the write will take precedence.

In this mode of operation, the CCPR1H:CCPR1L registers pair effectively becomes the period register for Timer1.

TABLE 6-2: REGISTERS ASSOCIATED WITH TIMER1 AS A TIMER/COUNTER

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other RESETS
0Bh,8Bh, 10Bh,18Bh	INTCON	GIE	PEIE	T0IE	INTE	RBIE	T0IF	INTF	RBIF	0000 000x	0000 000u
0Ch	PIR1	—	ADIF	—	—	SSPIF	CCP1IF	TMR2IF	TMR1IF	-0-- 0000	-0-- 0000
8Ch	PIE1	—	ADIE	—	—	SSPIE	CCP1IE	TMR2IE	TMR1IE	-0-- 0000	-0-- 0000
0Eh	TMR1L	Holding register for the Least Significant Byte of the 16-bit TMR1 register								xxxx xxxx	uuuu uuuu
0Fh	TMR1H	Holding register for the Most Significant Byte of the 16-bit TMR1 register								xxxx xxxx	uuuu uuuu
10h	T1CON	—	—	T1CKPS1	T1CKPS0	T1OSCEN	$\overline{\text{T1SYNC}}$	TMR1CS	TMR1ON	--00 0000	--uu uuuu

Legend: x = unknown, u = unchanged, - = unimplemented read as '0'. Shaded cells are not used by the Timer1 module.

7.0 TIMER2 MODULE

The Timer2 module timer has the following features:

- 8-bit timer (TMR2 register)
- 8-bit period register (PR2)
- Readable and writable (Both registers)
- Software programmable prescaler (1:1, 1:4, 1:16)
- Software programmable postscaler (1:1 to 1:16)
- Interrupt on TMR2 match of PR2
- SSP module optional use of TMR2 output to generate clock shift

Timer2 has a control register, shown in Register 7-1. Timer2 can be shut off by clearing control bit TMR2ON (T2CON<2>) to minimize power consumption.

Figure 7-1 is a simplified block diagram of the Timer2 module.

Additional information on timer modules is available in the PIC Mid-Range MCU Family Reference Manual, (DS33023).

7.1 Timer2 Operation

Timer2 can be used as the PWM time-base for PWM mode of the ECCP module.

The TMR2 register is readable and writable, and is cleared on any device RESET.

The input clock (FOSC/4) has a prescale option of 1:1, 1:4 or 1:16, selected by control bits T2CKPS<1:0> (T2CON<1:0>).

The match output of TMR2 goes through a 4-bit postscaler (which gives a 1:1 to 1:16 scaling inclusive) to generate a TMR2 interrupt (latched in flag bit TMR2IF, (PIR1<1>)).

The prescaler and postscaler counters are cleared when any of the following occurs:

- a write to the TMR2 register
- a write to the T2CON register
- any device RESET (Power-on Reset, $\overline{\text{MCLR}}$ Reset, Watchdog Timer Reset, or Brown-out Reset)

TMR2 is not cleared when T2CON is written.

REGISTER 7-1: TIMER2 CONTROL REGISTER (T2CON1: 12h)

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	TOUTPS3	TOUTPS2	TOUTPS1	TOUTPS0	TMR2ON	T2CKPS1	T2CKPS0
bit 7							bit 0

bit 7 **Unimplemented:** Read as '0'

bit 6-3 **TOUTPS<3:0>:** Timer2 Output Postscale Select bits
`0000` = 1:1 Postscale
`0001` = 1:2 Postscale
•
•
•
`1111` = 1:16 Postscale

bit 2 **TMR2ON:** Timer2 On bit
`1` = Timer2 is on
`0` = Timer2 is off

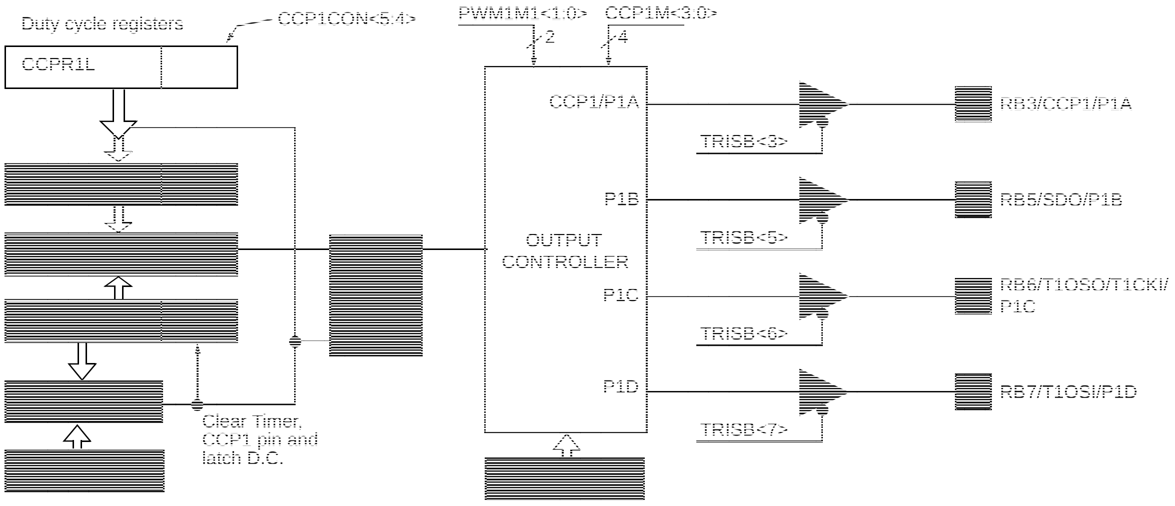
bit 1-0 **T2CKPS<1:0>:** Timer2 Clock Prescale Select bits
`00` = Prescaler is 1
`01` = Prescaler is 4
`1x` = Prescaler is 16

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
- n = Value at POR	’1’ = Bit is set	’0’ = Bit is cleared	x = Bit is unknown

8.3 PWM Mode

In Pulse Width Modulation (PWM) mode, the ECCP module produces up to a 10-bit resolution PWM output. Figure 8-3 shows the simplified PWM block diagram.

FIGURE 8-3: SIMPLIFIED PWM BLOCK DIAGRAM



Note: 8 bit timer TMR2 is concatenated with 2 bit internal Q clock or 2 bits of the prescaler to create 10 bit time base.

8.3.1 PWM PERIOD

The PWM period is specified by writing to the PR2 register. The PWM period can be calculated using the following formula:

$$\text{PWM PERIOD} = [(\text{PR2}) + 1] \cdot 4 \cdot T_{OSC} \cdot (\text{TMR2 PRESCALE VALUE})$$

PWM frequency is defined as 1 / [PWM period].

When TMR2 is equal to PR2, the following three events occur on the next increment cycle:

- TMR2 is cleared
- The CCP1 pin is set (exception: if PWM duty cycle = 0%, the CCP1 pin will not be set)
- The PWM duty cycle is latched from CCPR1L into CCPR1H

Note:	The Timer2 postscaler (see Section 7.0) is not used in the determination of the PWM frequency. The postscaler could be used to have a servo update rate at a different frequency than the PWM output.

9.2.3 GENERAL CALL ADDRESS SUPPORT

The addressing procedure for the I^{2}C bus is such that the first byte after the START condition usually determines which device will be the slave addressed by the master. The exception is the general call address, which can address all devices. When this address is used, all devices should, in theory, respond with an Acknowledge.

The general call address is one of eight addresses reserved for specific purposes by the I^{2}C protocol. It consists of all 0's with R/$\overline{W}$ = 0

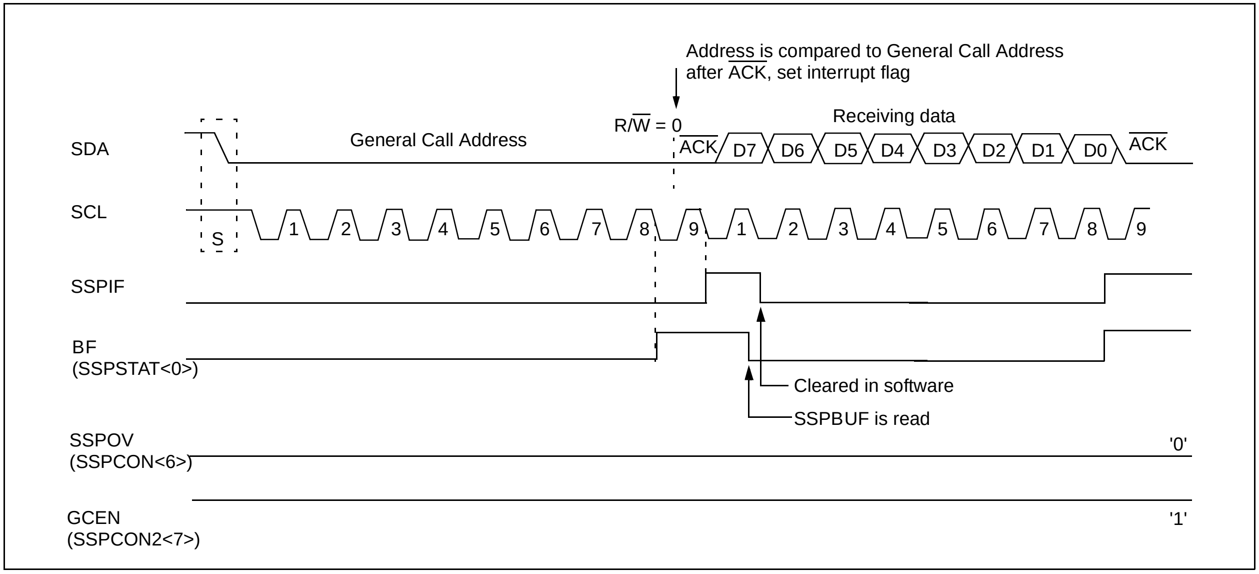
The general call address is recognized when the General Call Enable bit (GCEN) is set (SSPCON2<7> is set). Following a START bit detect, eight bits are shifted into the SSPSR, and the address is compared against SSPADD. It is also compared to the general call address, fixed in hardware.

If the general call address matches, the SSPSR is transferred to the SSPBUF, the BF flag is set (eighth bit), and on the falling edge of the ninth bit ($\overline{ACK}$ bit), the SSPIF flag is set.

When the interrupt is serviced, the source for the interrupt can be checked by reading the contents of the SSPBUF to determine if the address was device specific or a general call address.

If the general call address is sampled with GCEN set and the slave configured in 10-bit Address mode, the second half of the address is not necessary. The UA bit will not be set and the slave will begin receiving data after the Acknowledge (Figure 9-12).

FIGURE 9-12: SLAVE MODE GENERAL CALL ADDRESS SEQUENCE (7- OR 10-BIT MODE)



9.2.17.3 BUS COLLISION DURING A STOP CONDITION

Bus collision occurs during a STOP condition if:

a) After the SDA pin has been de-asserted and allowed to float high, SDA is sampled low after the BRG has timed out.

b) After the SCL pin is de-asserted, SCL is sampled low before SDA goes high.

The STOP condition begins with SDA asserted low. When SDA is sampled low, the SCL pin is allowed to float. When the pin is sampled high (clock arbitration), the baud rate generator is loaded with SSPADD<6:0> and counts down to ‘0’. After the BRG times out SDA is sampled. If SDA is sampled low, a bus collision has occurred. This is due to another master attempting to drive a data '0' (Figure 9-29). If the SCL pin is sampled low before SDA is allowed to float high, a bus collision occurs. This is another case of another master attempting to drive a data '0' (Figure 9-30).

FIGURE 9-29: BUS COLLISION DURING A STOP CONDITION (CASE 1)

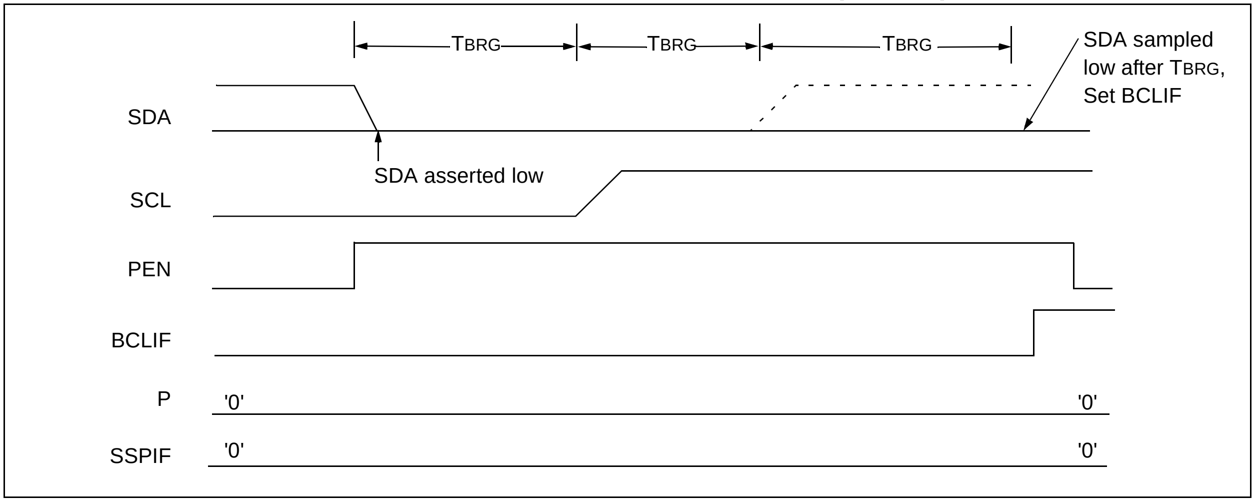
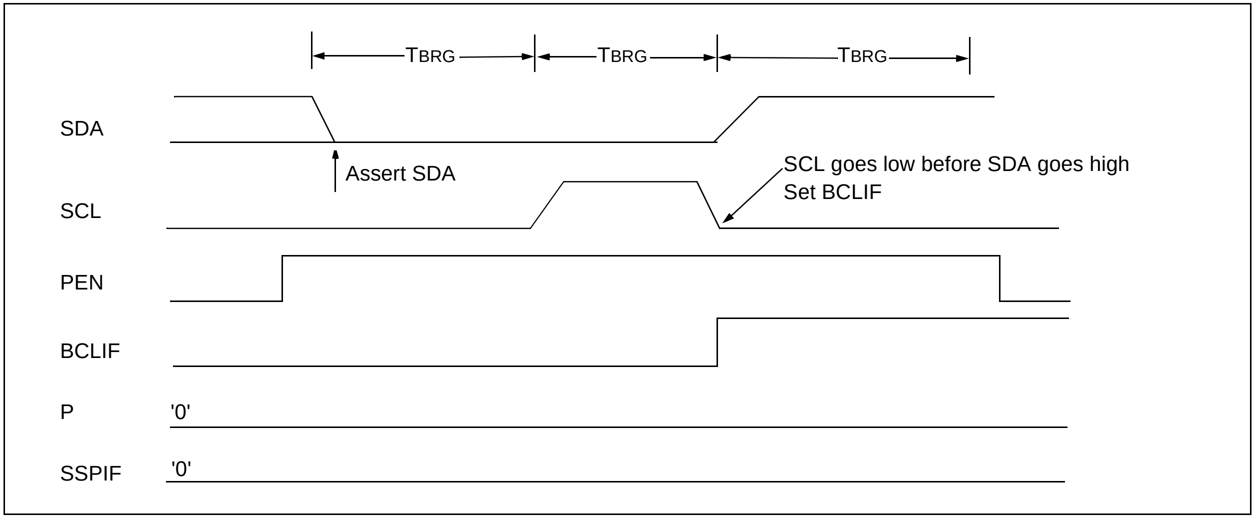


FIGURE 9-30: BUS COLLISION DURING A STOP CONDITION (CASE 2)



10.3 Low Voltage Detect (LVD)

This module is used to generate an interrupt when the supply voltage falls below a specified “trip” voltage. This module operates completely under software control. This allows a user to power the module on and off to periodically monitor the supply voltage, and thus minimize total current consumption.

The LVD module is enabled by setting the LVDEN bit in the LVDCON register. The “trip point” voltage is the minimum supply voltage level at which the device can operate before the LVD module asserts an interrupt. When the supply voltage is equal to or less than the trip point, the module will generate an interrupt signal setting interrupt flag bit LVDIF. If interrupt enable bit LVDIE was set, then an interrupt is generated. The LVD interrupt can wake the device from SLEEP. The "trip point" voltage is software programmable to any one of 16 values, five of which are reserved (See Figure 10-1). The trip point is selected by programming the LV<3:0> bits (LVDCON<3:0>).

Note:	The LVDIF bit can not be cleared until the supply voltage rises above the LVD trip point. If interrupts are enabled, clear the LVDIE bit once the first LVD interrupt occurs to prevent reentering the interrupt service routine immediately after exiting the ISR.

Once the LV bits have been programmed for the specified trip voltage, the low-voltage detect circuitry is then enabled by setting the LVDEN (LVDCON<4>) bit.

If the bandgap reference voltage is previously unused by either the brown-out circuitry or the voltage reference circuitry, then the bandgap circuit requires a time to start-up and become stable before a low voltage condition can be reliably detected. The low-voltage interrupt flag is prevented from being set until the bandgap has reached a stable reference voltage.

When the bandgap is stable the BGST (LVDCON<5>) bit is set indicating that the low-voltage interrupt flag bit is released to be set if V_{DD} is equal to or less than the LVD trip point.

10.3.1 EXTERNAL ANALOG VOLTAGE INPUT

The LVD module has an additional feature that allows the user to supply the trip voltage to the module from an external source. This mode is enabled when LV<3:0> = `1111`. When these bits are set the comparator input is multiplexed from an external input pin (RA1/AN1/LVDIN).

12.3 RESET

The PIC16C717/770/771 devices have several different RESETS. These RESETS are grouped into two classifications; power-up and non-power-up. The power-up type RESETS are the Power-on and Brown-out Resets which assume the device VDD was below its normal operating range for the device's configuration. The non power-up type RESETS assume normal operating limits were maintained before/during and after the RESET.

- Power-on Reset (POR)
- Programmable Brown-out Reset (PBOR)
- $\overline{\text{MCLR}}$ Reset during normal operation
- $\overline{\text{MCLR}}$ Reset during SLEEP
- WDT Reset (during normal operation)

Some registers are not affected in any RESET condition. Their status is unknown on a Power-up Reset and unchanged in any other RESET. Most other registers are placed into an initialized state upon RESET, however they are not affected by a WDT Reset during SLEEP, because this is considered a WDT Wake-up, which is viewed as the resumption of normal operation.

Several status bits have been provided to indicate which RESET occurred (see Table 12-4). See Table 12-6 for a full description of RESET states of all registers.

A simplified block diagram of the On-Chip Reset circuit is shown in Figure 12-4.

These devices have a $\overline{\text{MCLR}}$ noise filter in the $\overline{\text{MCLR}}$ Reset path. The filter will detect and ignore small pulses.

It should be noted that a WDT Reset does not drive $\overline{\text{MCLR}}$ pin low.

FIGURE 12-4: SIMPLIFIED BLOCK DIAGRAM OF ON-CHIP RESET CIRCUIT

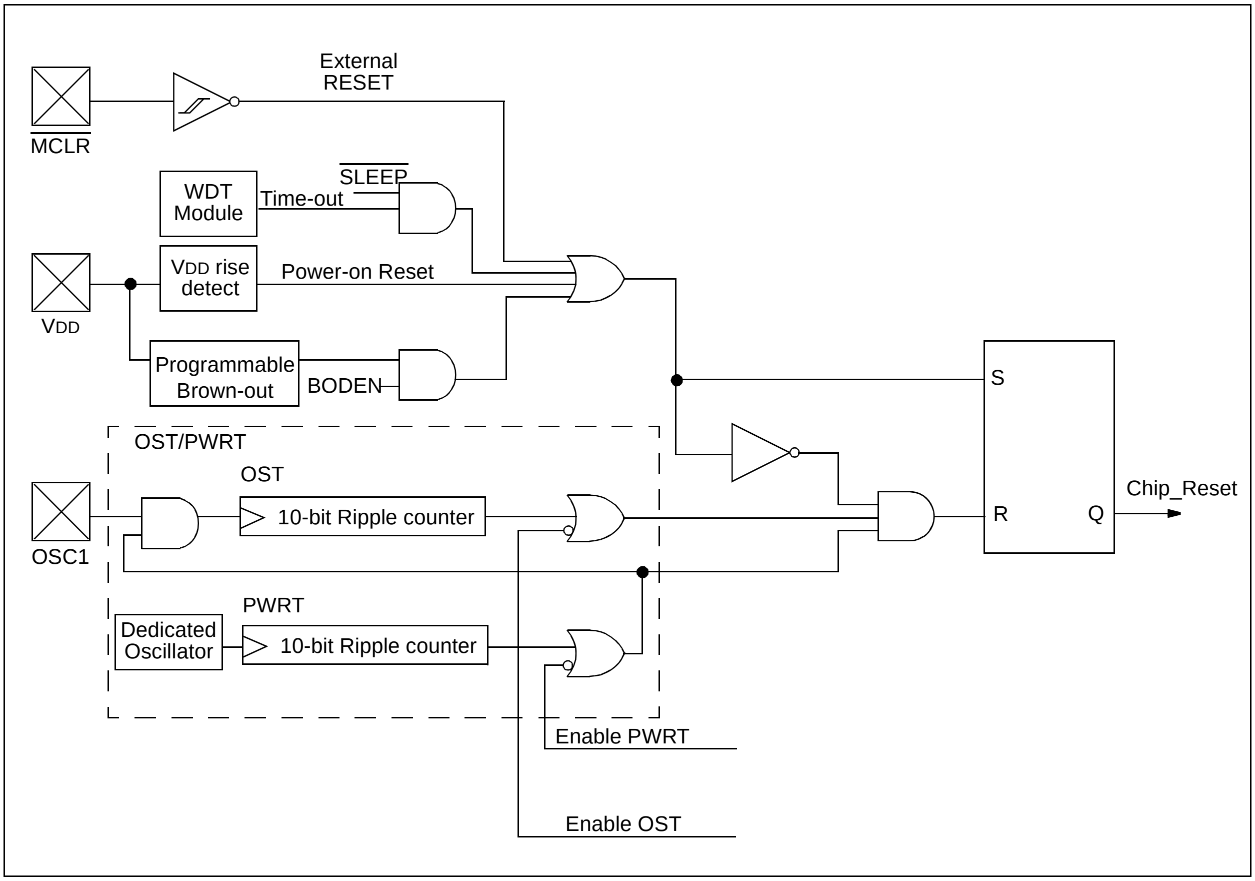


TABLE 12-6: INITIALIZATION CONDITIONS FOR ALL REGISTERS (CONTINUED)

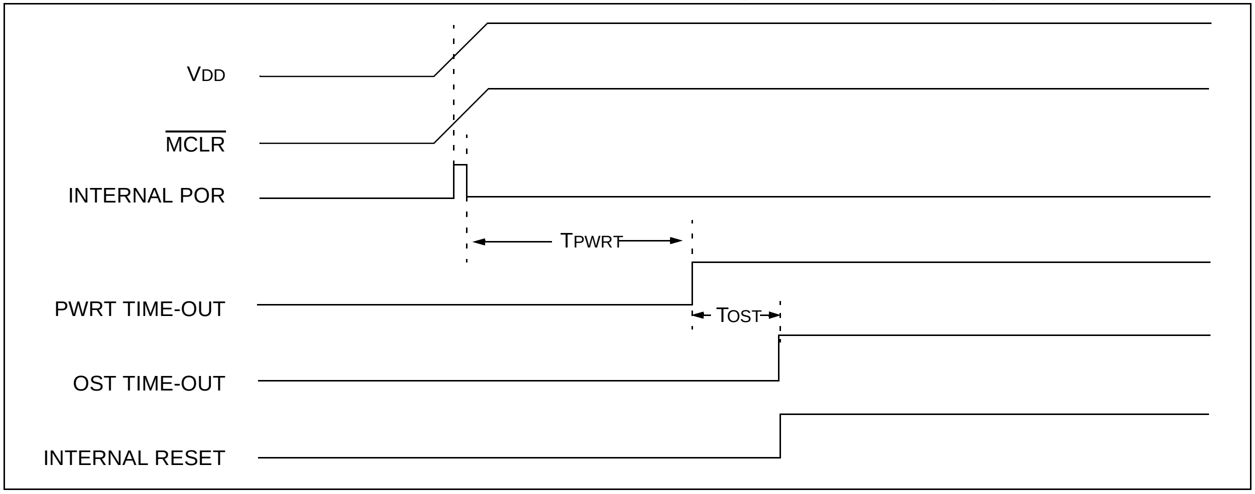
Register	Power-on Reset or Brown-out Reset	$\overline{\text{MCLR}}$ Reset or WDT Reset	Wake-up via WDT or Interrupt
P1DEL	0000 0000	0000 0000	uuuu uuuu
REFCON	0000 ----	0000 ----	uuuu ----
LVDCON	--00 0101	--00 0101	--uu uuuu
ANSEL	--11 1111	--11 1111	--uu uuuu
ADRESL	xxxx xxxx	uuuu uuuu	uuuu uuuu
ADCON1	0000 0000	0000 0000	uuuu uuuu
PMDATL	xxxx xxxx	uuuu uuuu	uuuu uuuu
PMADRL	xxxx xxxx	uuuu uuuu	uuuu uuuu
PMDATH	--xx xxxx	--uu uuuu	--uu uuuu
PMADRH	---- xxxx	---- uuuu	---- uuuu
PMCON1	1--- ---0	1--- ---0	1--- ---0

Legend: u = unchanged, x = unknown, - = unimplemented bit, read as '0', q = value depends on condition

Note 1: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

2: See Table 12-5 for RESET value for specific condition.

FIGURE 12-6: TIME-OUT SEQUENCE ON POWER-UP ($\overline{\text{MCLR}}$ TIED TO VDD)



12.12 Watchdog Timer (WDT)

The Watchdog Timer is a free running on-chip RC oscillator, which does not require any external components. This oscillator is independent from the processor clock. If enabled, the WDT will run even if the main clock of the device has been stopped, for example, by execution of a `SLEEP` instruction.

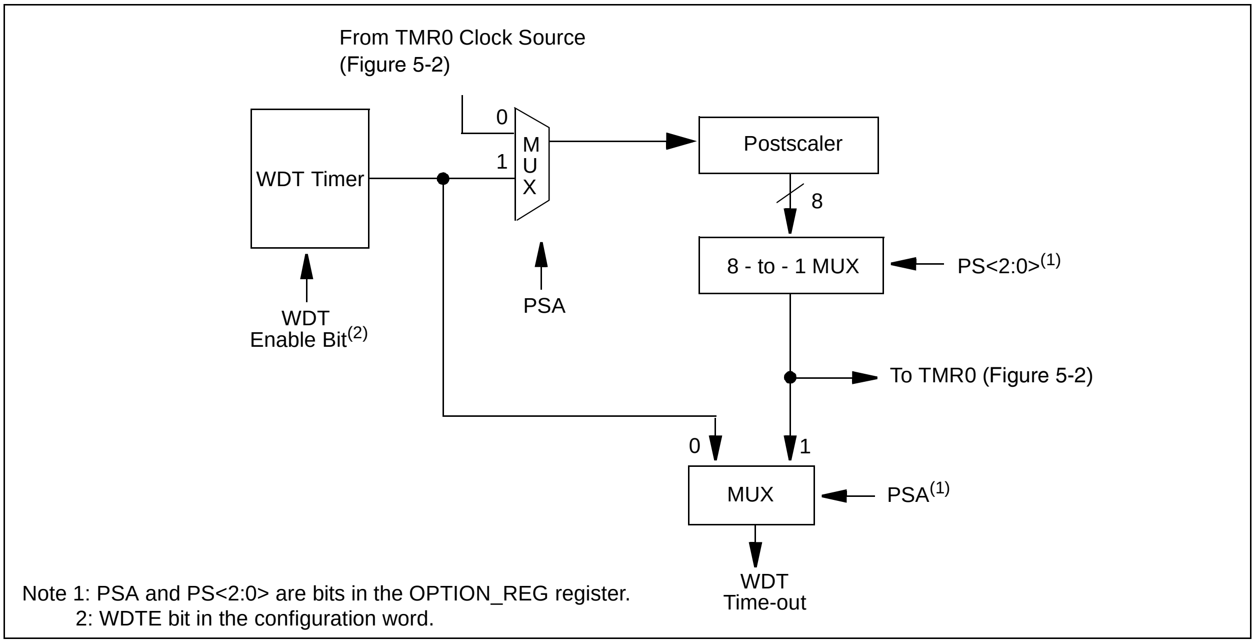
During normal operation, a WDT time-out generates a device RESET (Watchdog Timer Reset). If the device is in SLEEP mode, a WDT time-out causes the device to wake-up and continue with normal operation (Watchdog Timer Wake-up). The $\overline{\text{TO}}$ bit in the STATUS register will be cleared upon a Watchdog Timer time-out.

The WDT can be permanently disabled by programming the configuration bit WDTE to ’0’ (Section 12.1).

WDT time-out period values may be found in Table 15-4. Values for the WDT prescaler may be assigned using the OPTION_REG register.

Note:	The `SLEEP` instruction clears the WDT and the postscaler, if assigned to the WDT, restarting the WDT period.

FIGURE 12-11: WATCHDOG TIMER BLOCK DIAGRAM



Note 1: PSA and PS<2:0> are bits in the OPTION_REG register.
2: WDTE bit in the configuration word.

TABLE 12-7: SUMMARY OF WATCHDOG TIMER REGISTERS

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
2007h	Config. bits[1]	—	BODEN	MCLRE	$\overline{\text{PWRTE}}$	WDTE	FOSC2	FOSC1	FOSC0
81h,181h	OPTION_REG	$\overline{\text{RBPU}}$	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0

Legend: Shaded cells are not used by the Watchdog Timer.
Note 1: See Register 12-1 for the full description of the configuration word bits.

TABLE 13-2: PIC16CXXX INSTRUCTION SET

Mnemonic, Operands		Description	Cycles	14-Bit Opcode				Status Affected	Notes
				MSb			LSb		
BYTE-ORIENTED FILE REGISTER OPERATIONS									
ADDWF	**f, d**	Add W and f	1	`00`	`0111`	`dfff`	`ffff`	C,DC,Z	1,2
ANDWF	**f, d**	AND W with f	1	`00`	`0101`	`dfff`	`ffff`	Z	1,2
CLRF	**f**	Clear f	1	`00`	`0001`	`lfff`	`ffff`	Z	2
CLRW	**-**	Clear W	1	`00`	`0001`	`0000`	`0011`	Z	
COMF	**f, d**	Complement f	1	`00`	`1001`	`dfff`	`ffff`	Z	1,2
DECF	**f, d**	Decrement f	1	`00`	`0011`	`dfff`	`ffff`	Z	1,2
DECFSZ	**f, d**	Decrement f, Skip if 0	1(2)	`00`	`1011`	`dfff`	`ffff`		1,2,3
INCF	**f, d**	Increment f	1	`00`	`1010`	`dfff`	`ffff`	Z	1,2
INCFSZ	**f, d**	Increment f, Skip if 0	1(2)	`00`	`1111`	`dfff`	`ffff`		1,2,3
IORWF	**f, d**	Inclusive OR W with f	1	`00`	`0100`	`dfff`	`ffff`	Z	1,2
MOVF	**f, d**	Move f	1	`00`	`1000`	`dfff`	`ffff`	Z	1,2
MOVWF	**f**	Move W to f	1	`00`	`0000`	`lfff`	`ffff`		
NOP	**-**	No Operation	1	`00`	`0000`	`0xx0`	`0000`		
RLF	**f, d**	Rotate Left f through Carry	1	`00`	`1101`	`dfff`	`ffff`	C	1,2
RRF	**f, d**	Rotate Right f through Carry	1	`00`	`1100`	`dfff`	`ffff`	C	1,2
SUBWF	**f, d**	Subtract W from f	1	`00`	`0010`	`dfff`	`ffff`	C,DC,Z	1,2
SWAPF	**f, d**	Swap nybbles in f	1	`00`	`1110`	`dfff`	`ffff`		1,2
XORWF	**f, d**	Exclusive OR W with f	1	`00`	`0110`	`dfff`	`ffff`	Z	1,2
BIT-ORIENTED FILE REGISTER OPERATIONS									
BCF	**f, b**	Bit Clear f	1	`01`	`00bb`	`bfff`	`ffff`		1,2
BSF	**f, b**	Bit Set f	1	`01`	`01bb`	`bfff`	`ffff`		1,2
BTFSC	**f, b**	Bit Test f, Skip if Clear	1 (2)	`01`	`10bb`	`bfff`	`ffff`		3
BTFSS	**f, b**	Bit Test f, Skip if Set	1 (2)	`01`	`11bb`	`bfff`	`ffff`		3
LITERAL AND CONTROL OPERATIONS									
ADDLW	**k**	Add literal and W	1	`11`	`111x`	`kkkk`	`kkkk`	C,DC,Z	
ANDLW	**k**	AND literal with W	1	`11`	`1001`	`kkkk`	`kkkk`	Z	
CALL	**k**	Call subroutine	2	`10`	`0kkk`	`kkkk`	`kkkk`		
CLRWDT	**-**	Clear Watchdog Timer	1	`00`	`0000`	`0110`	`0100`	$\overline{TO}$,$\overline{PD}$	
GOTO	**k**	Go to address	2	`10`	`1kkk`	`kkkk`	`kkkk`		
IORLW	**k**	Inclusive OR literal with W	1	`11`	`1000`	`kkkk`	`kkkk`	Z	
MOVLW	**k**	Move literal to W	1	`11`	`00xx`	`kkkk`	`kkkk`		
RETFIE	**-**	Return from interrupt	2	`00`	`0000`	`0000`	`1001`		
RETLW	**k**	Return with literal in W	2	`11`	`01xx`	`kkkk`	`kkkk`		
RETURN	**-**	Return from Subroutine	2	`00`	`0000`	`0000`	`1000`		
SLEEP	**-**	Go into Standby mode	1	`00`	`0000`	`0110`	`0011`	$\overline{TO}$,$\overline{PD}$	
SUBLW	**k**	Subtract W from literal	1	`11`	`110x`	`kkkk`	`kkkk`	C,DC,Z	
XORLW	**k**	Exclusive OR literal with W	1	`11`	`1010`	`kkkk`	`kkkk`	Z	

Note 1: When an I/O register is modified as a function of itself (e.g., `MOVF PORTB, 1`), the value used will be that value present on the pins themselves. For example, if the data latch is '1' for a pin configured as input and is driven low by an external device, the data will be written back with a '0'.

2: If this instruction is executed on the TMR0 register (and, where applicable, d = 1), the prescaler will be cleared if assigned to the Timer0 Module.

3: If Program Counter (PC) is modified or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a `NOP`.

FIGURE 15-21: SPI SLAVE MODE TIMING (CKE = 1)

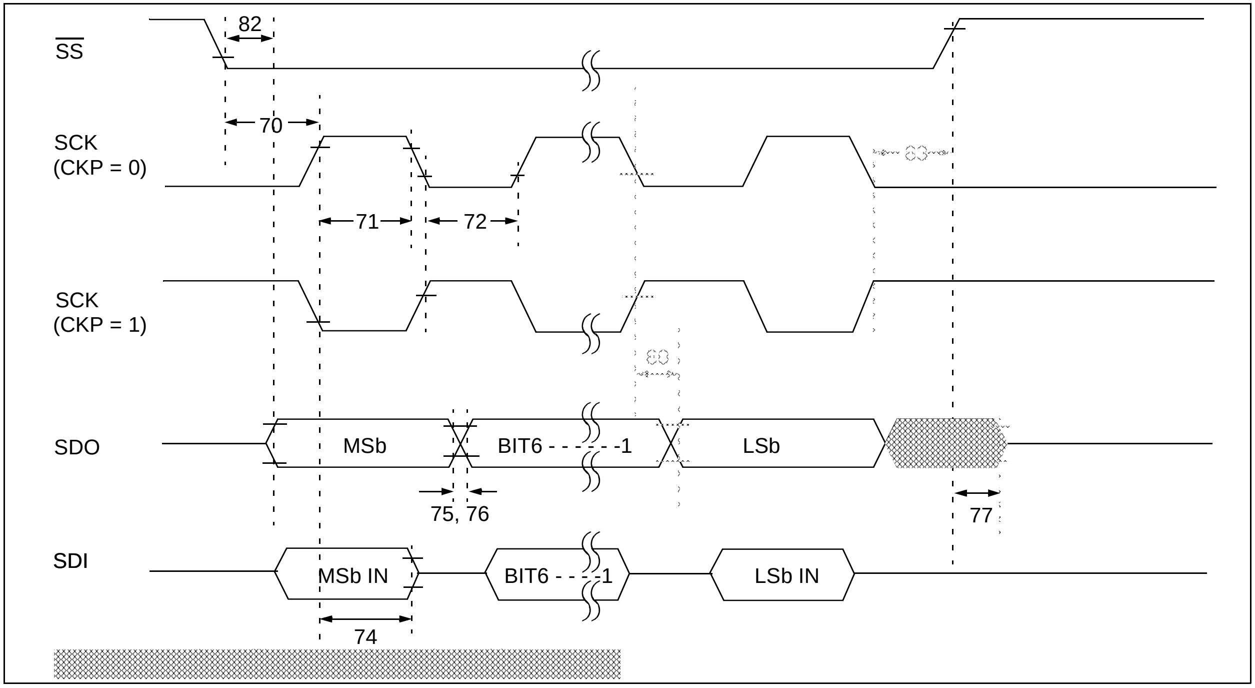


TABLE 15-20: SPI SLAVE MODE REQUIREMENTS (CKE = 1)

Param. No.	Symbol	Characteristic		Min	Typ†	Max	Units	Conditions
70*	TssL2scH, TssL2scL	$\overline{\text{SS}}$↓ to SCK↓ or SCK↑ input		TCY	—	—	ns	
71*	TscH	SCK input high time (Slave mode)	Continuous	1.25TCY + 30	—	—	ns	
71A*			Single Byte	40	—	—	ns	**Note 1**
72*	TscL	SCK input low time (Slave mode)	Continuous	1.25TCY + 30	—	—	ns	
72A*			Single Byte	40	—	—	ns	**Note 1**
73A*	TB2B	Last clock edge of Byte1 to the 1st clock edge of Byte2		1.5TCY + 40	—	—	ns	**Note 1**
74*	TscH2diL, TscL2diL	Hold time of SDI data input to SCK edge		100	—	—	ns	
75*	TdoR	SDO data output rise time	PIC16**C**XXX	—	10	25	ns	
			PIC16**LC**XXX		20	45	ns	
76*	TdoF	SDO data output fall time		—	10	25	ns	
77*	TssH2doZ	$\overline{\text{SS}}$↑ to SDO output hi-impedance		10	—	50	ns	
78*	TscR	SCK output rise time (Master mode)	PIC16**C**XXX	—	10	25	ns	
			PIC16**LC**XXX	—	20	45	ns	
79*	TscF	SCK output fall time (Master mode)		—	10	25	ns	
80*	TscH2doV, TscL2doV	SDO data output valid after SCK edge	PIC16**C**XXX	—	—	50	ns	
			PIC16**LC**XXX	—	—	100	ns	
82*	TssL2doV	SDO data output valid after $\overline{\text{SS}}$↓ edge	PIC16**C**XXX	—	—	50	ns	
			PIC16**LC**XXX	—	—	100	ns	
83*	TscH2ssH, TscL2ssH	$\overline{\text{SS}}$ ↑ after SCK edge		1.5TCY + 40	—	—	ns	

* These parameters are characterized but not tested.

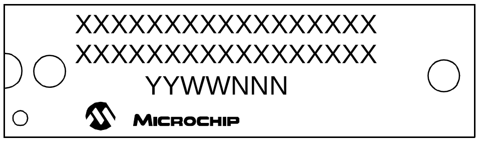
† Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Specification 73A is only required if specifications 71A and 72A are used.

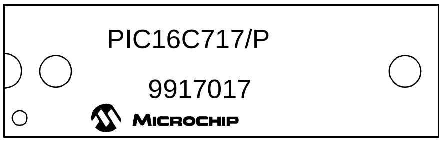
17.0 PACKAGING INFORMATION

17.1 Package Marking Information

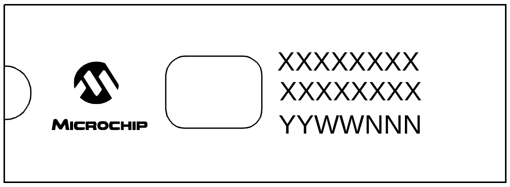
18-Lead PDIP



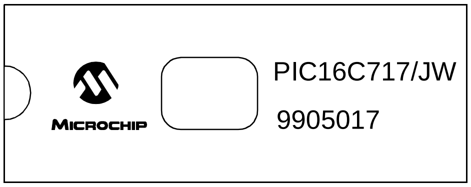
Example



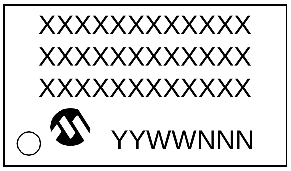
18-Lead CERDIP Windowed



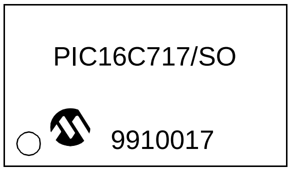
Example



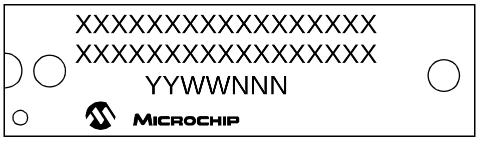
18-Lead SOIC



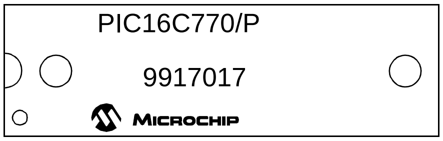
Example



20-Lead PDIP



Example

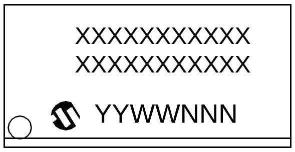


Legend:	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week ‘01’)
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package.

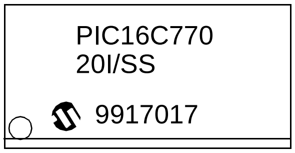
Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

17.1 Package Marking Information (Cont'd)

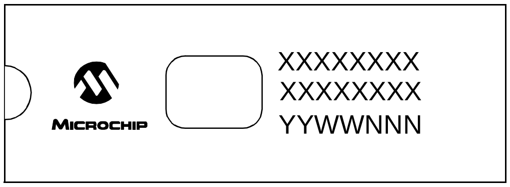
20-Lead SSOP



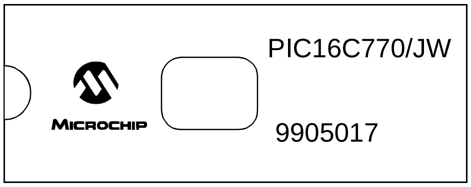
Example



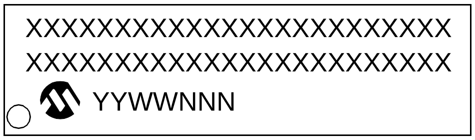
20-Lead CERDIP Windowed



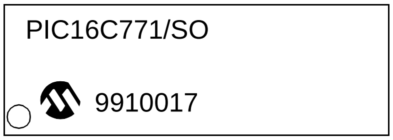
Example



20-Lead SOIC



Example


PIC16C771/SO
9910017