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Details

Product Status	Active
Core Processor	8051
Core Size	8-Bit
Speed	50MHz
Connectivity	SMBus (2-Wire/I ² C), SPI, UART/USART
Peripherals	POR, PWM, Temp Sensor, WDT
Number of I/O	17
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	·
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 16x10b; D/A 2x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	20-VFQFN Exposed Pad
Supplier Device Package	20-QFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/c8051f392-a-gm

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Figure 7.3. Precision Temperature Sensor Error vs. Temperature



9.1. Output Code Formatting

The conversion code format differs between Single-ended and Differential modes. The registers ADC0H and ADC0L contain the high and low bytes of the output conversion code from the ADC at the completion of each conversion. Data can be right-justified or left-justified, depending on the setting of the AD0LJST bit (ADC0CN.0). When in Single-ended Mode, conversion codes are represented as 10-bit unsigned integers. Inputs are measured from 0 to VREF x 1023/1024. Example codes are shown below for both right-justified and left-justified data. Unused bits in the ADC0H and ADC0L registers are set to 0.

Input Voltage (Single-Ended)	Right-Justified ADC0H:ADC0L (AD0LJST = 0)	Left-Justified ADC0H:ADC0L (AD0LJST = 1)
VREF x 1023/1024	0x03FF	0xFFC0
VREF x 512/1024	0x0200	0x8000
VREF x 256/1024	0x0100	0x4000
0	0x0000	0x0000

When in Differential Mode, conversion codes are represented as 10-bit signed 2s complement numbers. Inputs are measured from –VREF to VREF x 511/512. Example codes are shown below for both right-justified and left-justified data. For right-justified data, the unused MSBs of ADCOH are a sign-extension of the data word. For left-justified data, the unused LSBs in the ADCOL register are set to 0.

Input Voltage (Differential)	Right-Justified ADC0H:ADC0L (AD0LJST = 0)	Left-Justified ADC0H:ADC0L (AD0LJST = 1)
VREF x 511/512	0x01FF	0x7FC0
VREF x 256/512	0x0100	0x4000
0	0x0000	0x0000
–VREF x 256/512	0xFF00	0xC000
–VREF	0xFE00	0x8000



9.3. Programmable Window Detector

The ADC Programmable Window Detector continuously compares the ADC0 output registers to user-programmed limits, and notifies the system when a desired condition is detected. This is especially effective in an interrupt-driven system, saving code space and CPU bandwidth while delivering faster system response times. The window detector interrupt flag (AD0WINT in register ADC0CN) can also be used in polled mode. The ADC0 Greater-Than (ADC0GTH, ADC0GTL) and Less-Than (ADC0LTH, ADC0LTL) registers hold the comparison values. The window detector flag can be programmed to indicate when measured data is inside or outside of the user-programmed limits, depending on the contents of the ADC0 Less-Than and ADC0 Greater-Than registers.

SFR Definition 9.5. ADC0GTH: ADC0 Greater Than Data High Byte

Bit	7	6	5	4	3	2	1	0
Name	ADC0GTH[7:0]							
Туре	R/W							
Reset	1	1	1	1	1	1	1	1

SFR Address = 0xC4; SFR Page = All Pages

Bit	Name	Function
7:0	ADC0GTH[7:0]	ADC0 Greater-Than Data Word High-Order Bits.

SFR Definition 9.6. ADC0GTL: ADC0 Greater-Than Data Low Byte

Bit	7	6	5	4	3	2	1	0
Name	ADC0GTL[7:0]							
Туре	R/W							
Reset	1	1	1	1	1	1	1	1

SFR Address = 0xC3; SFR Page = All Pages

Bit	Name	Function
7:0	ADC0GTL[7:0]	ADC0 Greater-Than Data Word Low-Order Bits.



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SFR Definition 12.1. REF0CN: Reference Control

Bit	7	6	5	4	3	2	1	0
Name	REFBGS			REGOVR	REFSL	TEMPE	BIASE	REFBE
Туре	R/W	R	R	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xD1; SFR Page = All Pages

Bit	Name	Function
7	REFBGS	Reference Buffer Gain Select.
		This bit selects between 1x and 2x gain for the on-chip voltage ref- erence buffer. 0: 2x Gain 1: 1x Gain
6:5	Unused	Read = 00b; Write = Don't care.
4	REGOVR	Regulator Reference Override.
		This bit "overrides" the REFSL bit, and allows the internal regulator to be used as a reference source.0: The voltage reference source is selected by the REFSL bit.1: The internal regulator is used as the voltage reference.
3	REFSL	Voltage Reference Select.
		This bit selects the ADCs voltage reference. 0: V _{REF} pin used as voltage reference. 1: V _{DD} used as voltage reference.
2	TEMPE	Temperature Sensor Enable Bit.
		0: Internal Temperature Sensor off. 1: Internal Temperature Sensor on.
1	BIASE	Internal Analog Bias Generator Enable Bit.
		0: Internal Bias Generator off. 1: Internal Bias Generator on.
0	REFBE	 On-chip Reference Buffer Enable Bit. 0: On-chip Reference Buffer off. 1: On-chip Reference Buffer on. Internal voltage reference driven on the V_{REF} pin.



Table 15.1. CIP-51 Instruction Set Summary (Continued)

Mnemonic	Description	Bytes	Clock Cycles
XRL direct, #data	Exclusive-OR immediate to direct byte	3	3
CLR A	Clear A	1	1
CPL A	Complement A	1	1
RL A	Rotate A left	1	1
RLC A	Rotate A left through Carry	1	1
RR A	Rotate A right	1	1
RRC A	Rotate A right through Carry	1	1
SWAP A	Swap nibbles of A	1	1
Data Transfer	•	I	
MOV A, Rn	Move Register to A	1	1
MOV A, direct	Move direct byte to A	2	2
MOV A, @Ri	Move indirect RAM to A	1	2
MOV A, #data	Move immediate to A	2	2
MOV Rn, A	Move A to Register	1	1
MOV Rn, direct	Move direct byte to Register	2	2
MOV Rn, #data	Move immediate to Register	2	2
MOV direct, A	Move A to direct byte	2	2
MOV direct, Rn	Move Register to direct byte	2	2
MOV direct, direct	Move direct byte to direct byte	3	3
MOV direct, @Ri	Move indirect RAM to direct byte	2	2
MOV direct, #data	Move immediate to direct byte	3	3
MOV @Ri, A	Move A to indirect RAM	1	2
MOV @Ri, direct	Move direct byte to indirect RAM	2	2
MOV @Ri, #data	Move immediate to indirect RAM	2	2
MOV DPTR, #data16	Load DPTR with 16-bit constant	3	3
MOVC A, @A+DPTR	Move code byte relative DPTR to A	1	3
MOVC A, @A+PC	Move code byte relative PC to A	1	3
MOVX A, @Ri	Move external data (8-bit address) to A	1	3
MOVX @Ri, A	Move A to external data (8-bit address)	1	3
MOVX A, @DPTR	Move external data (16-bit address) to A	1	3
MOVX @DPTR, A	Move A to external data (16-bit address)	1	3
PUSH direct	Push direct byte onto stack	2	2
POP direct	Pop direct byte from stack	2	2
XCH A, Rn	Exchange Register with A	1	1
XCH A, direct	Exchange direct byte with A	2	2
XCH A, @Ri	Exchange indirect RAM with A	1	2
XCHD A, @Ri	Exchange low nibble of indirect RAM with A	1	2
Boolean Manipulation			<u>.</u>
CLR C	Clear Carry	1	1
CLR bit	Clear direct bit	2	2
SETB C	Set Carry	1	1
SETB bit	Set direct bit	2	2
CPL C	Complement Carry	1	1
CPL bit	Complement direct bit	2	2



SFR Definition 15.6. PSW: Program Status Word

Bit	7	6	5	4	3	2	1	0
Name	CY	AC	F0	RS[1:0]	OV	F1	PARITY
Туре	R/W	R/W	R/W	R/	W	R/W	R/W	R
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xD0; SFR Page = All Pages; Bit-Addressable

Bit	Name	Function
7	CY	Carry Flag. This bit is set when the last arithmetic operation resulted in a carry (addition) or a borrow (subtraction). It is cleared to logic 0 by all other arithmetic operations.
6	AC	Auxiliary Carry Flag.
		This bit is set when the last arithmetic operation resulted in a carry into (addition) or a borrow from (subtraction) the high order nibble. It is cleared to logic 0 by all other arithmetic operations.
5	F0	User Flag 0.
		This is a bit-addressable, general purpose flag for use under soft- ware control.
4:3	RS[1:0]	Register Bank Select.
		These bits select which register bank is used during register accesses. 00: Bank 0, Addresses 0x00-0x07 01: Bank 1, Addresses 0x08-0x0F 10: Bank 2, Addresses 0x10-0x17 11: Bank 3, Addresses 0x18-0x1F
2	OV	Overflow Flag.
		 This bit is set to 1 under the following circumstances: An ADD, ADDC, or SUBB instruction causes a sign-change overflow. A MUL instruction results in an overflow (result is greater than 255). A DIV instruction causes a divide-by-zero condition. The OV bit is cleared to 0 by the ADD, ADDC, SUBB, MUL, and DIV instructions in all other cases.
1	F1	User Flag 1.
		This is a bit-addressable, general purpose flag for use under soft- ware control.
0	PARITY	Parity Flag.
		This bit is set to logic 1 if the sum of the eight bits in the accumula- tor is odd and cleared if the sum is even.



20. Interrupts

The C8051F39x/37x includes an extended interrupt system supporting multiple interrupt sources with four priority levels. The allocation of interrupt sources between on-chip peripherals and external input pins varies according to the specific version of the device. Each interrupt source has one or more associated interrupt-pending flag(s) located in an SFR. When a peripheral or external source meets a valid interrupt condition, the associated interrupt-pending flag is set to logic 1.

If interrupts are enabled for the source, an interrupt request is generated when the interrupt-pending flag is set. As soon as execution of the current instruction is complete, the CPU generates an LCALL to a predetermined address to begin execution of an interrupt service routine (ISR). Each ISR must end with an RETI instruction, which returns program execution to the next instruction that would have been executed if the interrupt request had not occurred. If interrupts are not enabled, the interrupt-pending flag is ignored by the hardware and program execution continues as normal. (The interrupt-pending flag is set to logic 1 regard-less of the interrupt's enable/disable state.)

Each interrupt source can be individually enabled or disabled through the use of an associated interrupt enable bit in an SFR (IE, EIE1, and EIE2). However, interrupts must first be globally enabled by setting the EA bit (IE.7) to logic 1 before the individual interrupt enables are recognized. Setting the EA bit to logic 0 disables all interrupt sources regardless of the individual interrupt-enable settings.

Note: Any instruction that clears a bit to disable an interrupt should be immediately followed by an instruction that has two or more opcode bytes. Using EA (global interrupt enable) as an example:

```
// in 'C':
EA = 0; // clear EA bit.
EA = 0; // this is a dummy instruction with two-byte opcode.
; in assembly:
CLR EA ; clear EA bit.
CLR EA ; this is a dummy instruction with two-byte opcode.
```

For example, if an interrupt is posted during the execution phase of a "CLR EA" opcode (or any instruction which clears a bit to disable an interrupt source), and the instruction is followed by a single-cycle instruction, the interrupt may be taken. However, a read of the enable bit will return a '0' inside the interrupt service routine. When the bit-clearing opcode is followed by a multi-cycle instruction, the interrupt will not be taken.

Some interrupt-pending flags are automatically cleared by the hardware when the CPU vectors to the ISR. However, most are not cleared by the hardware and must be cleared by software before returning from the ISR. If an interrupt-pending flag remains set after the CPU completes the return-from-interrupt (RETI) instruction, a new interrupt request will be generated immediately and the CPU will re-enter the ISR after the completion of the next instruction.



20.2. Interrupt Register Descriptions

The SFRs used to enable the interrupt sources and set their priority level are described in this section. Refer to the data sheet section associated with a particular on-chip peripheral for information regarding valid interrupt conditions for the peripheral and the behavior of its interrupt-pending flag(s).

SFR Definition 20.1. IE: Interrupt Enable

Bit	7	6	5	4	3	2	1	0
Name	EA	ESPI0	ET2	ES0	ET1	EX1	ET0	EX0
Туре	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xA8; SFR Page = All Pages; Bit-Addressable

Bit	Name	Function
7	EA	 Enable All Interrupts. Globally enables/disables all interrupts. It overrides individual interrupt mask settings. 0: Disable all interrupt sources. 1: Enable each interrupt according to its individual mask setting.
6	ESPI0	Enable Serial Peripheral Interface (SPI0) Interrupt. This bit sets the masking of the SPI0 interrupts. 0: Disable all SPI0 interrupts. 1: Enable interrupt requests generated by SPI0.
5	ET2	 Enable Timer 2 Interrupt. This bit sets the masking of the Timer 2 interrupt. 0: Disable Timer 2 interrupt. 1: Enable interrupt requests generated by the TF2L or TF2H flags.
4	ES0	Enable UART0 Interrupt. This bit sets the masking of the UART0 interrupt. 0: Disable UART0 interrupt. 1: Enable UART0 interrupt.
3	ET1	Enable Timer 1 Interrupt.This bit sets the masking of the Timer 1 interrupt.0: Disable all Timer 1 interrupt.1: Enable interrupt requests generated by the TF1 flag.
2	EX1	Enable External Interrupt 1. This bit sets the masking of External Interrupt 1. 0: Disable external interrupt 1. 1: Enable interrupt requests generated by the /INT1 input.
1	ET0	Enable Timer 0 Interrupt. This bit sets the masking of the Timer 0 interrupt. 0: Disable all Timer 0 interrupt. 1: Enable interrupt requests generated by the TF0 flag.
0	EX0	Enable External Interrupt 0. This bit sets the masking of External Interrupt 0. 0: Disable external interrupt 0. 1: Enable interrupt requests generated by the INTO input.



SFR Definition 20.3. IPH: Interrupt Priority High

Bit	7	6	5	4	3	2	1	0
Name		PHSPI0	PHT2	PHS0	PHT1	PHX1	PHT0	PHX0
Туре	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	1	0	0	0	0	0	0	0

SFR Address = 0x84; SFR Page = All Pages; Bit-Addressable

Bit	Name	Function
7	Unused	Read = 1, Write = Don't Care.
6	PHSPI0	Serial Peripheral Interface (SPI0) Interrupt Priority Control MSB.
		This bit sets the MSB of the priority field for the SPI0 interrupt.
5	PHT2	Timer 2 Interrupt Priority Control MSB.
		This bit sets the MSB of the priority field for the Timer 2 interrupt.
4	PHS0	UART0 Interrupt Priority Control MSB.
		This bit sets the MSB of the priority field for the UART0 interrupt.
3	PHT1	Timer 1 Interrupt Priority Control MSB.
		This bit sets the MSB of the priority field for the Timer 1 interrupt.
2	PHX1	External Interrupt 1 Priority Control MSB.
		This bit sets the MSB of the priority field for the External Interrupt 1 inter-
		rupt.
1	PHT0	Timer 0 Interrupt Priority Control MSB.
		This bit sets the MSB of the priority field for the Timer 0 interrupt.
0	PHX0	External Interrupt 0 Priority Control MSB.
		This bit sets the MSB of the priority field for the External Interrupt 0 inter- rupt.



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24.1. Power-On Reset

During power-up, the device is held in a reset state and the \overline{RST} pin is driven low until V_{DD} settles above V_{RST}. A delay occurs before the device is released from reset; the delay decreases as the V_{DD} ramp time increases (V_{DD} ramp time is defined as how fast V_{DD} ramps from 0 V to V_{RST}). Figure 24.2. plots the power-on and V_{DD} monitor reset timing. The maximum V_{DD} ramp time is 1 ms; slower ramp times may cause the device to be released from reset before V_{DD} reaches the V_{RST} level. For ramp times less than 1 ms, the power-on reset delay (T_{PORDelay}) is typically less than 0.3 ms.

On exit from a power-on reset, the PORSF flag (RSTSRC.1) is set by hardware to logic 1. When PORSF is set, all of the other reset flags in the RSTSRC Register are indeterminate (PORSF is cleared by all other resets). Since all resets cause program execution to begin at the same location (0x0000) software can read the PORSF flag to determine if a power-up was the cause of reset. The content of internal data memory should be assumed to be undefined after a power-on reset. The V_{DD} monitor is enabled following a power-on reset.



Figure 24.2. Power-On and V_{DD} Monitor Reset Timing



24.2. Power-Fail Reset / V_{DD} Monitor

When a power-down transition or power irregularity causes V_{DD} to drop below V_{RST} , the power supply monitor will drive the \overline{RST} pin low and hold the CIP-51 in a reset state (see Figure 24.2). When V_{DD} returns to a level above V_{RST} , the CIP-51 will be released from the reset state. Note that even though internal data memory contents are not altered by the power-fail reset, it is impossible to determine if V_{DD} dropped below the level required for data retention. If the PORSF flag reads '1', the data may no longer be valid. The V_{DD} monitor is enabled after power-on resets. Its defined state (enabled/disabled) is not altered by any other reset source. For example, if the V_{DD} monitor is disabled by code and a software reset is performed, the V_{DD} monitor will still be disabled after the reset.

Important Note: If the V_{DD} monitor is being turned on from a disabled state, it should be enabled before it is selected as a reset source. Selecting the V_{DD} monitor as a reset source before it is enabled and stabilized may cause a system reset. In some applications, this reset may be undesirable. If this is not desirable in the application, a delay should be introduced between enabling the monitor and selecting it as a reset source. The procedure for enabling the V_{DD} monitor and configuring it as a reset source from a disabled state is shown below:

- 1. Enable the V_{DD} monitor (VDMEN bit in VDM0CN = '1').
- 2. If necessary, wait for the V_{DD} monitor to stabilize.
- 3. Select the V_{DD} monitor as a reset source (PORSF bit in RSTSRC = '1').

See Figure 24.2 for V_{DD} monitor timing; note that the power-on-reset delay is not incurred after a V_{DD} monitor reset. See Section "7. Electrical Characteristics" on page 32 for complete electrical characteristics of the V_{DD} monitor.



SFR Definition 27.6. P1MAT: Port 1 Match Register

Bit	7	6	5	4	3	2	1	0
Name	P1MAT[7:0]							
Туре	R/W							
Reset	1	1 1 1 1 1 1 1 1						

SFR Address = 0xED; SFR Page = All Pages

Bit	Name	Function
7:0	P1MAT[7:0]	Port 1 Match Value.
		Match comparison value used on Port 1 for bits in P1MASK which are set to '1'. 0: P1.n pin logic value is compared with logic LOW. 1: P1.n pin logic value is compared with logic HIGH.

27.6. Special Function Registers for Accessing and Configuring Port I/O

All Port I/O are accessed through corresponding special function registers (SFRs) that are both byte addressable and bit addressable. When writing to a Port, the value written to the SFR is latched to maintain the output data value at each pin. When reading, the logic levels of the Port's input pins are returned regardless of the XBRn settings (i.e., even when the pin is assigned to another signal by the Crossbar, the Port register can always read its corresponding Port I/O pin). The exception to this is the execution of the read-modify-write instructions that target a Port Latch register as the destination. The read-modify-write instructions when operating on a Port SFR are the following: ANL, ORL, XRL, JBC, CPL, INC, DEC, DJNZ and MOV, CLR or SETB, when the destination is an individual bit in a Port SFR. For these instructions, the value of the latch register (not the pin) is read, modified, and written back to the SFR.

Each Port has a corresponding PnSKIP register which allows its individual Port pins to be assigned to digital functions or skipped by the Crossbar. All Port pins used for analog functions, GPIO, or dedicated digital functions such as the EMIF should have their PnSKIP bit set to '1'.

The Port input mode of the I/O pins is defined using the Port Input Mode registers (PnMDIN). Each Port cell can be configured for analog or digital I/O. This selection is required even for the digital resources selected in the XBRn registers, and is not automatic. The only exception to this is P2.4, which can only be used for digital I/O.

The output driver characteristics of the I/O pins are defined using the Port Output Mode registers (PnMD-OUT). Each Port Output driver can be configured as either open drain or push-pull. This selection is required even for the digital resources selected in the XBRn registers, and is not automatic. The only exception to this is the SMBus (SDA, SCL) pins, which are configured as open-drain regardless of the PnMDOUT settings.



29.1. Enhanced Baud Rate Generation

The UART0 baud rate is generated by Timer 1 in 8-bit auto-reload mode. The TX clock is generated by TL1; the RX clock is generated by a copy of TL1 (shown as RX Timer in Figure 29.2), which is not useraccessible. Both TX and RX Timer overflows are divided by two to generate the TX and RX baud rates. The RX Timer runs when Timer 1 is enabled, and uses the same reload value (TH1). However, an RX Timer reload is forced when a START condition is detected on the RX pin. This allows a receive to begin any time a START is detected, independent of the TX Timer state.



Figure 29.2. UART0 Baud Rate Logic

Timer 1 should be configured for Mode 2, 8-bit auto-reload (see Section "31.1.3. Mode 2: 8-bit Counter/ Timer with Auto-Reload" on page 247). The Timer 1 reload value should be set so that overflows will occur at two times the desired UART baud rate frequency. Note that Timer 1 may be clocked by one of six sources: SYSCLK, SYSCLK/4, SYSCLK/12, SYSCLK/48, the external oscillator clock/8, or an external input T1. For any given Timer 1 clock source, the UART0 baud rate is determined by Equation 29.1-A and Equation 29.1-B.

A) UartBaudRate =
$$\frac{1}{2} \times T1_Overflow_Rate$$

B) T1_Overflow_Rate = $\frac{T1_{CLK}}{256 - TH1}$

Equation 29.1. UART0 Baud Rate

Where $T1_{CLK}$ is the frequency of the clock supplied to Timer 1, and T1H is the high byte of Timer 1 (reload value). Timer 1 clock frequency is selected as described in Section "31. Timers" on page 242. A quick reference for typical baud rates and system clock frequencies is given in Table 29.1 through Table 29.2. The internal oscillator may still generate the system clock when the external oscillator is driving Timer 1.



SFR Definition 31.1. CKCON: Clock Control

Bit	7	6	5	4	3	2	1	0
Name	ТЗМН	T3ML	T2MH	T2ML	T1M	TOM	SCA	.[1:0]
Туре	R/W	R/W	R/W	R/W	R/W	R/W	R/	W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x8E; SFR Page = All Pages

Bit	Name	Function
7	ТЗМН	 Timer 3 High Byte Clock Select. Selects the clock supplied to the Timer 3 high byte (split 8-bit timer mode only). 0: Timer 3 high byte uses the clock defined by the T3XCLK bit in TMR3CN. 1: Timer 3 high byte uses the system clock.
6	T3ML	 Timer 3 Low Byte Clock Select. Selects the clock supplied to Timer 3. Selects the clock supplied to the lower 8-bit timer in split 8-bit timer mode. 0: Timer 3 low byte uses the clock defined by the T3XCLK bit in TMR3CN. 1: Timer 3 low byte uses the system clock.
5	T2MH	Timer 2 High Byte Clock Select.Selects the clock supplied to the Timer 2 high byte (split 8-bit timer mode only).0: Timer 2 high byte uses the clock defined by the T2XCLK bit in TMR2CN.1: Timer 2 high byte uses the system clock.
4	T2ML	 Timer 2 Low Byte Clock Select. Selects the clock supplied to Timer 2. If Timer 2 is configured in split 8-bit timer mode, this bit selects the clock supplied to the lower 8-bit timer. 0: Timer 2 low byte uses the clock defined by the T2XCLK bit in TMR2CN. 1: Timer 2 low byte uses the system clock.
3	T1	Timer 1 Clock Select.Selects the clock source supplied to Timer 1. Ignored when C/T1 is set to 1.0: Timer 1 uses the clock defined by the prescale bits SCA[1:0].1: Timer 1 uses the system clock.
2	TO	Timer 0 Clock Select.Selects the clock source supplied to Timer 0. Ignored when C/T0 is set to 1.0: Counter/Timer 0 uses the clock defined by the prescale bits SCA[1:0].1: Counter/Timer 0 uses the system clock.
1:0	SCA[1:0]	Timer 0/1 Prescale Bits.These bits control the Timer 0/1 Clock Prescaler:00: System clock divided by 1201: System clock divided by 410: System clock divided by 4811: External clock divided by 8 (synchronized with the system clock)



SFR Definition 31.2. CKCON1: Clock Control 1

Bit	7	6	5	4	3	2	1	0
Name					T5MH	T5ML	T4MH	T4ML
Туре	R	R	R	R	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xF4; SFR Page = All Pages

Bit	Name	Function
7:4	Unused	Read = 0000b; Write = don't care
3	T5MH	Timer 5 High Byte Clock Select.
		Selects the clock supplied to the Timer 5 high byte (split 8-bit timer mode only). 0: Timer 5 high byte uses the clock defined by the T5XCLK bit in TMR5CN.
2	T5MI	
2	I JIME	Selects the clock supplied to Timer 5. Selects the clock supplied to the lower 8-bit timer in split 8-bit timer mode.
		0: Timer 5 low byte uses the clock defined by the T5XCLK bit in TMR5CN.
		1: Timer 5 low byte uses the system clock.
1	T4MH	Timer 4 High Byte Clock Select.
		Selects the clock supplied to the Timer 4 high byte (split 8-bit timer mode only).
		0: Timer 4 high byte uses the clock defined by the T4XCLK bit in TMR4CN.
		1: Timer 4 high byte uses the system clock.
0	T4ML	Timer 4 Low Byte Clock Select.
		Selects the clock supplied to Timer 4. If Timer 4 is configured in split 8-bit timer mode, this bit selects the clock supplied to the lower 8-bit timer.
		0: Timer 4 low byte uses the clock defined by the T4XCLK bit in TMR4CN.
		1: Timer 4 low byte uses the system clock.



31.2.2. 8-bit Timers with Auto-Reload

When T2SPLIT is set, Timer 2 operates as two 8-bit timers (TMR2H and TMR2L). Both 8-bit timers operate in auto-reload mode as shown in Figure 31.5. TMR2RLL holds the reload value for TMR2L; TMR2RLH holds the reload value for TMR2H. The TR2 bit in TMR2CN handles the run control for TMR2H. TMR2L is always running when configured for 8-bit Mode.

Each 8-bit timer may be configured to use SYSCLK, SYSCLK divided by 12, or the external oscillator clock source divided by 8. The Timer 2 Clock Select bits (T2MH and T2ML in CKCON) select either SYSCLK or the clock defined by the Timer 2 External Clock Select bit (T2XCLK in TMR2CN), as follows:

T2MH	T2XCLK	TMR2H Clock Source
0	0	SYSCLK / 12
0	1	External Clock / 8
1	Х	SYSCLK

T2ML	T2XCLK	TMR2L Clock Source
0	0	SYSCLK / 12
0	1	External Clock / 8
1	Х	SYSCLK

The TF2H bit is set when TMR2H overflows from 0xFF to 0x00; the TF2L bit is set when TMR2L overflows from 0xFF to 0x00. When Timer 2 interrupts are enabled (IE.5), an interrupt is generated each time TMR2H overflows. If Timer 2 interrupts are enabled and TF2LEN (TMR2CN.5) is set, an interrupt is generated each time either TMR2L or TMR2H overflows. When TF2LEN is enabled, software must check the TF2H and TF2L flags to determine the source of the Timer 2 interrupt. The TF2H and TF2L interrupt flags are not cleared by hardware and must be manually cleared by software.



Figure 31.5. Timer 2 8-Bit Mode Block Diagram



31.3.2. 8-bit Timers with Auto-Reload

When T3SPLIT is set, Timer 3 operates as two 8-bit timers (TMR3H and TMR3L). Both 8-bit timers operate in auto-reload mode as shown in Figure 31.8. TMR3RLL holds the reload value for TMR3L; TMR3RLH holds the reload value for TMR3H. The TR3 bit in TMR3CN handles the run control for TMR3H. TMR3L is always running when configured for 8-bit Mode.

Each 8-bit timer may be configured to use SYSCLK, SYSCLK divided by 12, the external oscillator clock source divided by 8, or the internal Low-frequency Oscillator. The Timer 3 Clock Select bits (T3MH and T3ML in CKCON) select either SYSCLK or the clock defined by the Timer 3 External Clock Select bits (T3XCLK[1:0] in TMR3CN), as follows:

ТЗМН	T3XCLK[1:0]	TMR3H Clock Source
0	00	SYSCLK / 12
0	01	External Clock / 8
0	10	Reserved
0	11	Internal LFO
1	Х	SYSCLK

T3ML	T3XCLK[1:0]	TMR3L Clock Source
0	00	SYSCLK / 12
0	01	External Clock / 8
0	10	Reserved
0	11	Internal LFO
1	Х	SYSCLK

The TF3H bit is set when TMR3H overflows from 0xFF to 0x00; the TF3L bit is set when TMR3L overflows from 0xFF to 0x00. When Timer 3 interrupts are enabled, an interrupt is generated each time TMR3H overflows. If Timer 3 interrupts are enabled and TF3LEN (TMR3CN.5) is set, an interrupt is generated each time either TMR3L or TMR3H overflows. When TF3LEN is enabled, software must check the TF3H and TF3L flags to determine the source of the Timer 3 interrupt. The TF3H and TF3L interrupt flags are not cleared by hardware and must be manually cleared by software.



Figure 31.8. Timer 3 8-Bit Mode Block Diagram



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32.3.1. Edge-triggered Capture Mode

In this mode, a valid transition on the CEXn pin causes the PCA to capture the value of the PCA counter/ timer and load it into the corresponding module's 16-bit capture/compare register (PCA0CPLn and PCA0CPHn). The CAPPn and CAPNn bits in the PCA0CPMn register are used to select the type of transition that triggers the capture: low-to-high transition (positive edge), high-to-low transition (negative edge), or either transition (positive or negative edge). When a capture occurs, the Capture/Compare Flag (CCFn) in PCA0CN is set to logic 1. An interrupt request is generated if the CCFn interrupt for that module is enabled. The CCFn bit is not automatically cleared by hardware when the CPU vectors to the interrupt service routine, and must be cleared by software. If both CAPPn and CAPNn bits are set to logic 1, then the state of the Port pin associated with CEXn can be read directly to determine whether a rising-edge or falling-edge caused the capture.



Figure 32.4. PCA Capture Mode Diagram

Note: The CEXn input signal must remain high or low for at least 2 system clock cycles to be recognized by the hardware.

