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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	12
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 8x10b; D/A 1x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	16-VQFN Exposed Pad
Supplier Device Package	16-QFN (4x4)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1704-e-ml">https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1704-e-ml</a>

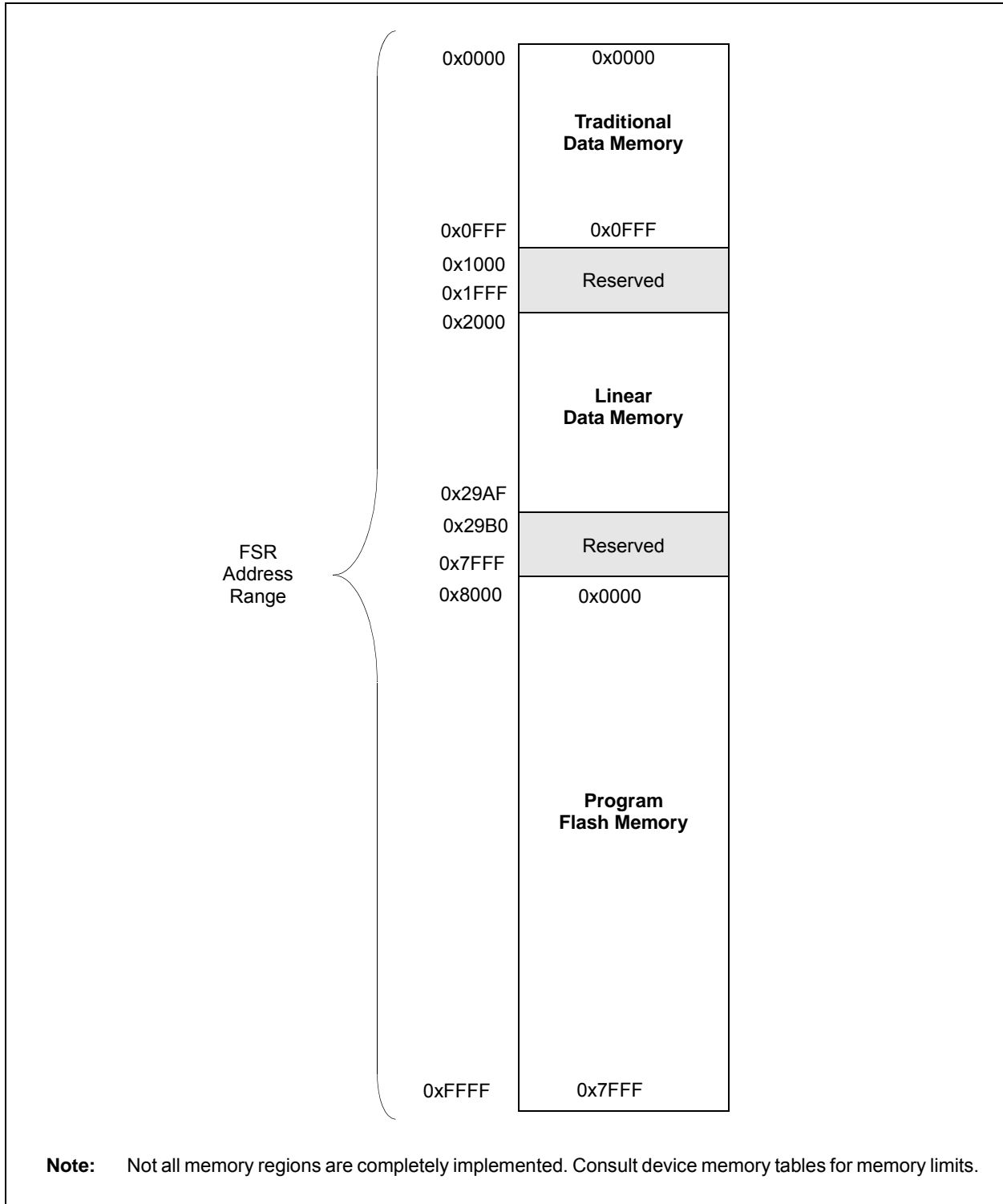
**TABLE 3-10: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
Bank 7											
38Ch	INLVLA	—	—	INLVLA5	INLVLA4	INLVLA3	INLVLA2	INLVLA1	INLVLA0	--11 1111	--11 1111
38Dh	INVLVB <sup>(3)</sup>	INVLVB7	INVLVB6	INVLVB5	INVLVB4	—	—	—	—	1111 ----	1111 ----
38Eh	INLVLC	INLVLC7 <sup>(3)</sup>	INLVLC6 <sup>(3)</sup>	INLVLC5	INLVLC4	INLVLC3	INLVLC2	INLVLC1	INLVLC0	1111 1111	1111 1111
38Fh	—	Unimplemented								—	—
390h	—	Unimplemented								—	—
391h	IOCAP	—	—	IOCAP5	IOCAP4	IOCAP3	IOCAP2	IOCAP1	IOCAP0	--00 0000	--00 0000
392h	IOCAN	—	—	IOCAN5	IOCAN4	IOCAN3	IOCAN2	IOCAN1	IOCAN0	--00 0000	--00 0000
393h	IOCAF	—	—	IOCAF5	IOCAF4	IOCAF3	IOCAF2	IOCAF1	IOCAF0	--00 0000	--00 0000
394h	IOCBP <sup>(3)</sup>	IOCBP7	IOCBP6	IOCBP5	IOCBP4	—	—	—	—	0000 ----	0000 ----
395h	IOCBN <sup>(3)</sup>	IOCBN7	IOCBN6	IOCBN5	IOCBN4	—	—	—	—	0000 ----	0000 ----
396h	IOCBF <sup>(3)</sup>	IOCBF7	IOCBF6	IOCBF5	IOCBF4	—	—	—	—	0000 ----	0000 ----
397h	IOCCP	IOCCP7 <sup>(3)</sup>	IOCCP6 <sup>(3)</sup>	IOCCP5	IOCCP4	IOCCP3	IOCCP2	IIOCCP1	IOCCP0	0000 0000	0000 0000
398h	IOCCN	IOCCN7 <sup>(3)</sup>	IOCCN6 <sup>(3)</sup>	IOCCN5	IOCCN4	IOCCN3	IOCCN2	IIOCCN1	IOCCN0	0000 0000	0000 0000
399h	IOCCF	IOCCF7 <sup>(3)</sup>	IOCCF6 <sup>(3)</sup>	IOCCF5	IOCCF4	IOCCF3	IOCCF2	IIOCCF1	IOCCF0	0000 0000	0000 0000
39Ah 39Fh	—	Unimplemented								—	—
Bank 8											
40Ch — 414h	—	Unimplemented								—	—
415h	TMR4	Holding Register for the Least Significant Byte of the 16-bit TMR4 Register								xxxx xxxx	uuuu uuuu
416h	PR4	Holding Register for the Most Significant Byte of the 16-bit TMR4 Register								xxxx xxxx	uuuu uuuu
417h	T4CON	—	T4OUTPS<3:0>				TMR4ON	T4CKPS<1:0>		-000 0000	-000 0000
418h — 41Bh	—	Unimplemented								—	—
41Ch	TMR6	Holding Register for the Least Significant Byte of the 16-bit TMR6 Register								xxxx xxxx	uuuu uuuu
41Dh	PR6	Holding Register for the Most Significant Byte of the 16-bit TMR6 Register								xxxx xxxx	uuuu uuuu
41Eh	T6CON	—	T6OUTPS<3:0>				TMR6ON	T6CKPS<1:0>		-000 0000	-000 0000
41Fh	—	Unimplemented								—	—
Bank 9											
48Ch to 49Fh	—	Unimplemented								—	—
Bank 10											
50Ch — 510h	—	Unimplemented								—	—
511h	OPA1CON	OPA1EN	OPA1SP	—	OPA1UG	—	—	OPA1PCH<1:0>		00-0 --00	00-0 --00
512h — 514h	—	Unimplemented								—	—
515h	OPA2CON	OPA2EN	OPA2SP	—	OPA2UG	—	—	OPA2PCH<1:0>		00-0 --00	00-0 --00
516h — 51Fh	—	Unimplemented								—	—

**Legend:** x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.  
Shaded locations are unimplemented, read as '0'.

**Note** 1: Unimplemented, read as '1'.  
2: PIC16(L)F1704 only.  
3: PIC16(L)F1708 only.  
4: Unimplemented on PIC16LF1704/8.

**FIGURE 3-8: INDIRECT ADDRESSING**



## 5.12 Determining the Cause of a Reset

Upon any Reset, multiple bits in the STATUS and PCON register are updated to indicate the cause of the Reset. Table 5-3 and Table 5-4 show the Reset conditions of these registers.

**TABLE 5-3: RESET STATUS BITS AND THEIR SIGNIFICANCE**

STKOVF	STKUNF	RWD $\overline{T}$	RMCLR	RI	POR	BOR	TO	PD	Condition
0	0	1	1	1	0	x	1	1	Power-on Reset
0	0	1	1	1	0	x	0	x	Illegal, $\overline{TO}$ is set on $\overline{POR}$
0	0	1	1	1	0	x	x	0	Illegal, $\overline{PD}$ is set on $\overline{POR}$
0	0	u	1	1	u	0	1	1	Brown-out Reset
u	u	0	u	u	u	u	0	u	WDT Reset
u	u	u	u	u	u	u	0	0	WDT Wake-up from Sleep
u	u	u	u	u	u	u	1	0	Interrupt Wake-up from Sleep
u	u	u	0	u	u	u	u	u	$\overline{MCLR}$ Reset during normal operation
u	u	u	0	u	u	u	1	0	$\overline{MCLR}$ Reset during Sleep
u	u	u	u	0	u	u	u	u	RESET Instruction Executed
1	u	u	u	u	u	u	u	u	Stack Overflow Reset (STVREN = 1)
u	1	u	u	u	u	u	u	u	Stack Underflow Reset (STVREN = 1)

**TABLE 5-4: RESET CONDITION FOR SPECIAL REGISTERS**

Condition	Program Counter	STATUS Register	PCON Register
Power-on Reset	0000h	---1 1000	00-- 110x
$\overline{MCLR}$ Reset during normal operation	0000h	---u uuuu	uu-- 0uuu
$\overline{MCLR}$ Reset during Sleep	0000h	---1 0uuu	uu-- 0uuu
WDT Reset	0000h	---0 uuuu	uu-- uuuu
WDT Wake-up from Sleep	PC + 1	---0 0uuu	uu-- uuuu
Brown-out Reset	0000h	---1 1uuu	00-- 11u0
Interrupt Wake-up from Sleep	PC + 1 <sup>(1)</sup>	---1 0uuu	uu-- uuuu
RESET Instruction Executed	0000h	---u uuuu	uu-- u0uu
Stack Overflow Reset (STVREN = 1)	0000h	---u uuuu	1u-- uuuu
Stack Underflow Reset (STVREN = 1)	0000h	---u uuuu	u1-- uuuu

**Legend:** u = unchanged, x = unknown, - = unimplemented bit, reads as '0'.

**Note 1:** When the wake-up is due to an interrupt and Global Enable bit (GIE) is set, the return address is pushed on the stack and PC is loaded with the interrupt vector (0004h) after execution of PC + 1.

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## 5.13 Power Control (PCON) Register

The Power Control (PCON) register contains flag bits to differentiate between a:

- Power-on Reset ( $\overline{\text{POR}}$ )
- Brown-out Reset ( $\overline{\text{BOR}}$ )
- Reset Instruction Reset ( $\overline{\text{RI}}$ )
- MCLR Reset ( $\overline{\text{RMCLR}}$ )
- Watchdog Timer Reset ( $\overline{\text{RWDT}}$ )
- Stack Underflow Reset (STKUNF)
- Stack Overflow Reset (STKOVF)

The PCON register bits are shown in Register 5-2.

## 5.14 Register Definitions: Power Control

**REGISTER 5-2: PCON: POWER CONTROL REGISTER**

R/W/HS-0/q	R/W/HS-0/q	U-0	R/W/HC-1/q	R/W/HC-1/q	R/W/HC-1/q	R/W/HC-q/u	R/W/HC-q/u
STKOVF	STKUNF	—	$\overline{\text{RWDT}}$	$\overline{\text{RMCLR}}$	$\overline{\text{RI}}$	$\overline{\text{POR}}$	$\overline{\text{BOR}}$
bit 7							bit 0

**Legend:**

HC = Bit is cleared by hardware

HS = Bit is set by hardware

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-m/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

q = Value depends on condition

bit 7 **STKOVF:** Stack Overflow Flag bit

1 = A Stack Overflow occurred

0 = A Stack Overflow has not occurred or cleared by firmware

bit 6 **STKUNF:** Stack Underflow Flag bit

1 = A Stack Underflow occurred

0 = A Stack Underflow has not occurred or cleared by firmware

bit 5 **Unimplemented:** Read as '0'

bit 4 **RWDT:** Watchdog Timer Reset Flag bit

1 = A Watchdog Timer Reset has not occurred or set to '1' by firmware

0 = A Watchdog Timer Reset has occurred (cleared by hardware)

bit 3 **RMCLR:** MCLR Reset Flag bit

1 = A  $\overline{\text{MCLR}}$  Reset has not occurred or set to '1' by firmware

0 = A MCLR Reset has occurred (cleared by hardware)

bit 2 **RI:** RESET Instruction Flag bit

1 = A RESET instruction has not been executed or set to '1' by firmware

0 = A RESET instruction has been executed (cleared by hardware)

bit 1 **POR:** Power-on Reset Status bit

1 = No Power-on Reset occurred

0 = A Power-on Reset occurred (must be set in software after a Power-on Reset occurs)

bit 0 **BOR:** Brown-out Reset Status bit

1 = No Brown-out Reset occurred

0 = A Brown-out Reset occurred (must be set in software after a Power-on Reset or Brown-out Reset occurs)

## 6.2.2.5 Internal Oscillator Frequency Selection

The system clock speed can be selected via software using the Internal Oscillator Frequency Select bits IRCF<3:0> of the OSCCON register.

The postscaled output of the 16 MHz HFINTOSC, 500 kHz MFINTOSC, and 31 kHz LFINTOSC connect to a multiplexer (see Figure 6-1). The Internal Oscillator Frequency Select bits IRCF<3:0> of the OSCCON register select the frequency output of the internal oscillators. One of the following frequencies can be selected via software:

- 32 MHz (requires 4x PLL)
- 16 MHz
- 8 MHz
- 4 MHz
- 2 MHz
- 1 MHz
- 500 kHz (default after Reset)
- 250 kHz
- 125 kHz
- 62.5 kHz
- 31.25 kHz
- 31 kHz (LFINTOSC)

**Note:** Following any Reset, the IRCF<3:0> bits of the OSCCON register are set to '0111' and the frequency selection is set to 500 kHz. The user can modify the IRCF bits to select a different frequency.

The IRCF<3:0> bits of the OSCCON register allow duplicate selections for some frequencies. These duplicate choices can offer system design trade-offs. Lower power consumption can be obtained when changing oscillator sources for a given frequency. Faster transition times can be obtained between frequency changes that use the same oscillator source.

## 6.2.2.6 32 MHz Internal Oscillator Frequency Selection

The Internal Oscillator Block can be used with the 4x PLL associated with the External Oscillator Block to produce a 32 MHz internal system clock source. The following settings are required to use the 32 MHz internal clock source:

- The FOSC bits in Configuration Words must be set to use the INTOSC source as the device system clock (FOSC<2:0> = 100).
- The SCS bits in the OSCCON register must be cleared to use the clock determined by FOSC<2:0> in Configuration Words (SCS<1:0> = 00).
- The IRCF bits in the OSCCON register must be set to the 8 MHz HFINTOSC set to use (IRCF<3:0> = 1110).
- The SPLLEN bit in the OSCCON register must be set to enable the 4x PLL, or the PLLEN bit of the Configuration Words must be programmed to a '1'.

**Note:** When using the PLLEN bit of the Configuration Words, the 4x PLL cannot be disabled by software and the SPLLEN option will not be available.

The 4x PLL is not available for use with the internal oscillator when the SCS bits of the OSCCON register are set to '1x'. The SCS bits must be set to '00' to use the 4x PLL with the internal oscillator.

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## REGISTER 7-6: PIR2: PERIPHERAL INTERRUPT REQUEST REGISTER 2

R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
OSFIF	C2IF	C1IF	—	BCL1IF	TMR6IF	TMR4IF	CCP2IF
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

- bit 7 **OSFIF:** Oscillator Fail Interrupt Flag bit  
1 = Interrupt is pending  
0 = Interrupt is not pending
- bit 6 **C2IF:** Comparator C2 Interrupt Flag bit  
1 = Interrupt is pending  
0 = Interrupt is not pending
- bit 5 **C1IF:** Comparator C1 Interrupt Flag bit  
1 = Interrupt is pending  
0 = Interrupt is not pending
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **BCL1IF:** MSSP Bus Collision Interrupt Flag bit  
1 = Interrupt is pending  
0 = Interrupt is not pending
- bit 2 **TMR6IF:** Timer6 to PR6 Interrupt Flag bit  
1 = Interrupt is pending  
0 = Interrupt is not pending
- bit 1 **TMR4IF:** Timer4 to PR4 Interrupt Flag bit  
1 = Interrupt is pending  
0 = Interrupt is not pending
- bit 0 **CCP2IF:** CCP2 Interrupt Flag bit  
1 = Interrupt is pending  
0 = Interrupt is not pending

**Note:** Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE, of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

## 10.2.3 ERASING FLASH PROGRAM MEMORY

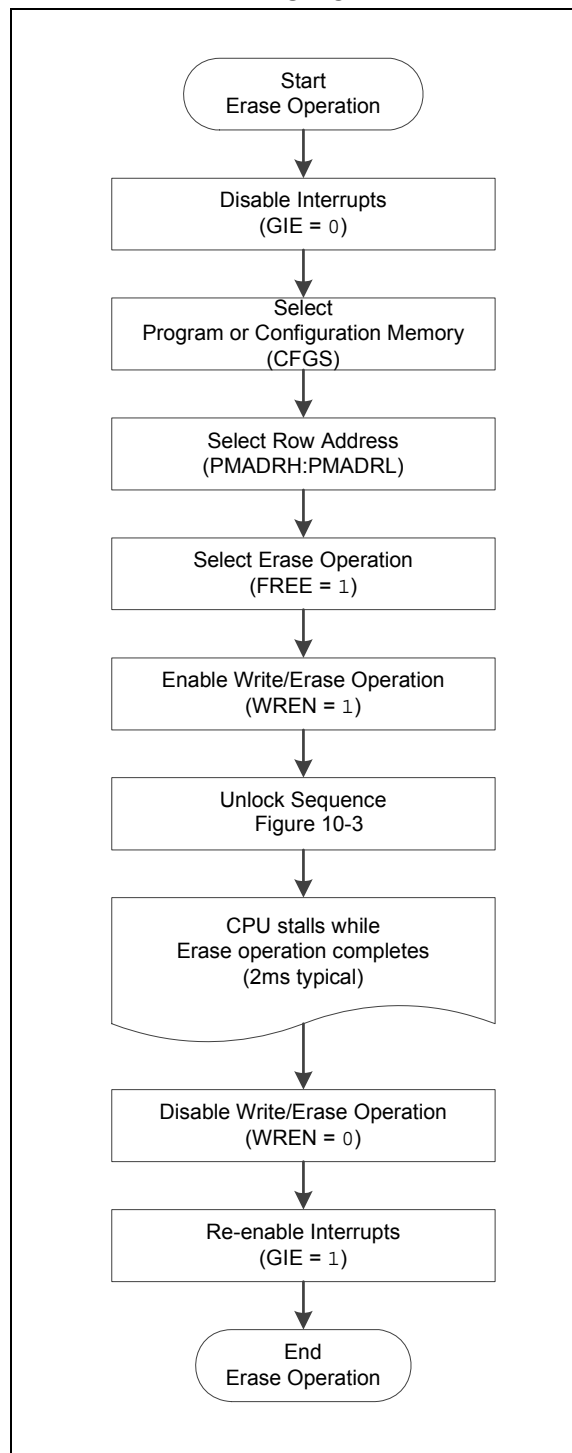
While executing code, program memory can only be erased by rows. To erase a row:

1. Load the PMADRH:PMADRL register pair with any address within the row to be erased.
2. Clear the CFGS bit of the PMCON1 register.
3. Set the FREE and WREN bits of the PMCON1 register.
4. Write 55h, then AAh, to PMCON2 (Flash programming unlock sequence).
5. Set control bit WR of the PMCON1 register to begin the erase operation.

See Example 10-2.

After the “BSF PMCON1, WR” instruction, the processor requires two cycles to set up the erase operation. The user must place two NOP instructions immediately following the WR bit set instruction. The processor will halt internal operations for the typical 2 ms erase time. This is not Sleep mode as the clocks and peripherals will continue to run. After the erase cycle, the processor will resume operation with the third instruction after the PMCON1 write instruction.

**FIGURE 10-4: FLASH PROGRAM MEMORY ERASE FLOWCHART**





# PIC16(L)F1704/8

## REGISTER 11-12: ANSELB: PORTB ANALOG SELECT REGISTER

U-0	U-0	R/W-1/1	R/W-1/1	U-0	U-0	U-0	U-0
—	—	ANSB5	ANSB4	—	—	—	—
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **Unimplemented:** Read as '0'

bit 5-4 **ANSB<5:4>:** Analog Select between Analog or Digital Function on pins RB<5:4>, respectively  
0 = Digital I/O. Pin is assigned to port or digital special function.  
1 = Analog input. Pin is assigned as analog input<sup>(1)</sup>. Digital input buffer disabled.

bit 3-0 **Unimplemented:** Read as '0'

**Note 1:** When setting a pin to an analog input, the corresponding TRIS bit must be set to Input mode in order to allow external control of the voltage on the pin.

## REGISTER 11-13: WPUB: WEAK PULL-UP PORTB REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	U-0	U-0	U-0	U-0
WPUB7	WPUB6	WPUB5	WPUB4	—	—	—	—
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-4 **WPUB<7:4>:** Weak Pull-up Register bits  
1 = Pull-up enabled  
0 = Pull-up disabled

bit 3-0 **Unimplemented:** Read as '0'

**Note 1:** Global WPUEN bit of the OPTION\_REG register must be cleared for individual pull-ups to be enabled.  
**2:** The weak pull-up device is automatically disabled if the pin is configured as an output.

## 17.2 Register Definitions: PWM Control

### REGISTER 17-1: PWMxCON: PWM CONTROL REGISTER

R/W-0/0	U-0	R-0/0	R/W-0/0	U-0	U-0	U-0	U-0
PWMxEN	—	PWMxOUT	PWMxPOL	—	—	—	—
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7 **PWMxEN:** PWM Module Enable bit

1 = PWM module is enabled

0 = PWM module is disabled

bit 6 **Unimplemented:** Read as '0'

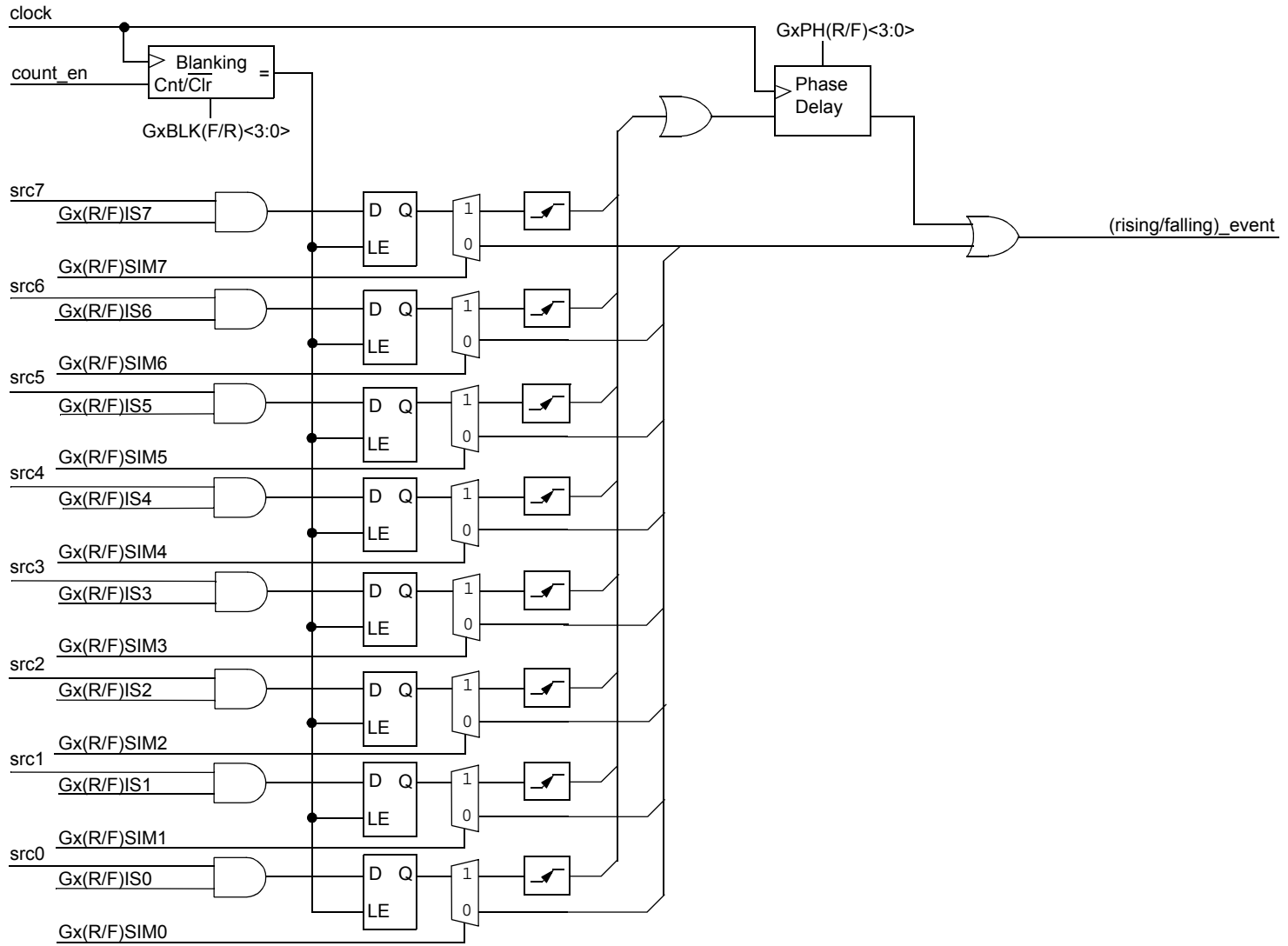
bit 5 **PWMxOUT:** PWM module output level when bit is read.

bit 4 **PWMxPOL:** PWMx Output Polarity Select bit

1 = PWM output is active-low.

0 = PWM output is active-high.

bit 3-0 **Unimplemented:** Read as '0'

**FIGURE 18-7: COG (RISING/FALLING) INPUT BLOCK**

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## 18.13 Register Definitions: COG Control

### REGISTER 18-1: COGxCON0: COG CONTROL REGISTER 0

R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
GxEN	GxLD	—	GxCS<1:0>		GxMD<2:0>		
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

q = Value depends on condition

bit 7 **GxEN:** COGx Enable bit

1 = Module is enabled

0 = Module is disabled

bit 6 **GxLD:** COGx Load Buffers bit

1 = Phase, blanking, and dead-band buffers to be loaded with register values on next input events

0 = Register to buffer transfer is complete

bit 5 **Unimplemented:** Read as '0'

bit 4-3 **GxCS<1:0>:** COGx Clock Selection bits

11 = Reserved. Do not use.

10 = COG\_clock is HFINTOSC (stays active during Sleep)

01 = COG\_clock is Fosc

00 = COG\_clock is Fosc/4

bit 2-0 **GxMD<2:0>:** COGx Mode Selection bits

11x = Reserved. Do not use.

101 = COG outputs operate in Push-Pull mode

100 = COG outputs operate in Half-Bridge mode

011 = COG outputs operate in Reverse Full-Bridge mode

010 = COG outputs operate in Forward Full-Bridge mode

001 = COG outputs operate in synchronous steered PWM mode

000 = COG outputs operate in steered PWM mode

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## REGISTER 19-2: CLCxPOL: SIGNAL POLARITY CONTROL REGISTER

R/W-0/0	U-0	U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
LCxPOL	—	—	—	LCxG4POL	LCxG3POL	LCxG2POL	LCxG1POL
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

- bit 7      **LCxPOL:** LCOU<sub>T</sub> Polarity Control bit  
1 = The output of the logic cell is inverted  
0 = The output of the logic cell is not inverted
- bit 6-4    **Unimplemented:** Read as '0'
- bit 3      **LCxG4POL:** Gate 4 Output Polarity Control bit  
1 = The output of gate 4 is inverted when applied to the logic cell  
0 = The output of gate 4 is not inverted
- bit 2      **LCxG3POL:** Gate 3 Output Polarity Control bit  
1 = The output of gate 3 is inverted when applied to the logic cell  
0 = The output of gate 3 is not inverted
- bit 1      **LCxG2POL:** Gate 2 Output Polarity Control bit  
1 = The output of gate 2 is inverted when applied to the logic cell  
0 = The output of gate 2 is not inverted
- bit 0      **LCxG1POL:** Gate 1 Output Polarity Control bit  
1 = The output of gate 1 is inverted when applied to the logic cell  
0 = The output of gate 1 is not inverted

## 20.3 Register Definitions: ADC Control

### REGISTER 20-1: ADCON0: ADC CONTROL REGISTER 0

U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	CHS<4:0>					GO/DONE	ADON
bit 7							bit 0

#### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7 **Unimplemented:** Read as '0'

bit 6-2 **CHS<4:0>:** Analog Channel Select bits

11111 = FVR\_Buffer1 Output<sup>(2)</sup>  
 11110 = DAC\_output<sup>(1)</sup>  
 11101 = Temperature Indicator<sup>(3)</sup>  
 11100 = Reserved. No channel connected  
 11011 = Reserved. No channel connected.  
 .  
 .  
 .  
 01100 = Reserved. No channel connected.  
 01011 = AN11  
 01010 = AN10  
 01001 = AN9  
 01000 = AN8  
 00111 = AN7  
 00110 = AN6  
 00101 = AN5  
 00100 = AN4  
 00011 = AN3  
 00010 = AN2  
 00001 = AN1  
 00000 = AN0

bit 1 **GO/DONE:** ADC Conversion Status bit

1 = ADC conversion cycle in progress. Setting this bit starts an ADC conversion cycle.  
 This bit is automatically cleared by hardware when the ADC conversion has completed.  
 0 = ADC conversion completed/not in progress

bit 0 **ADON:** ADC Enable bit

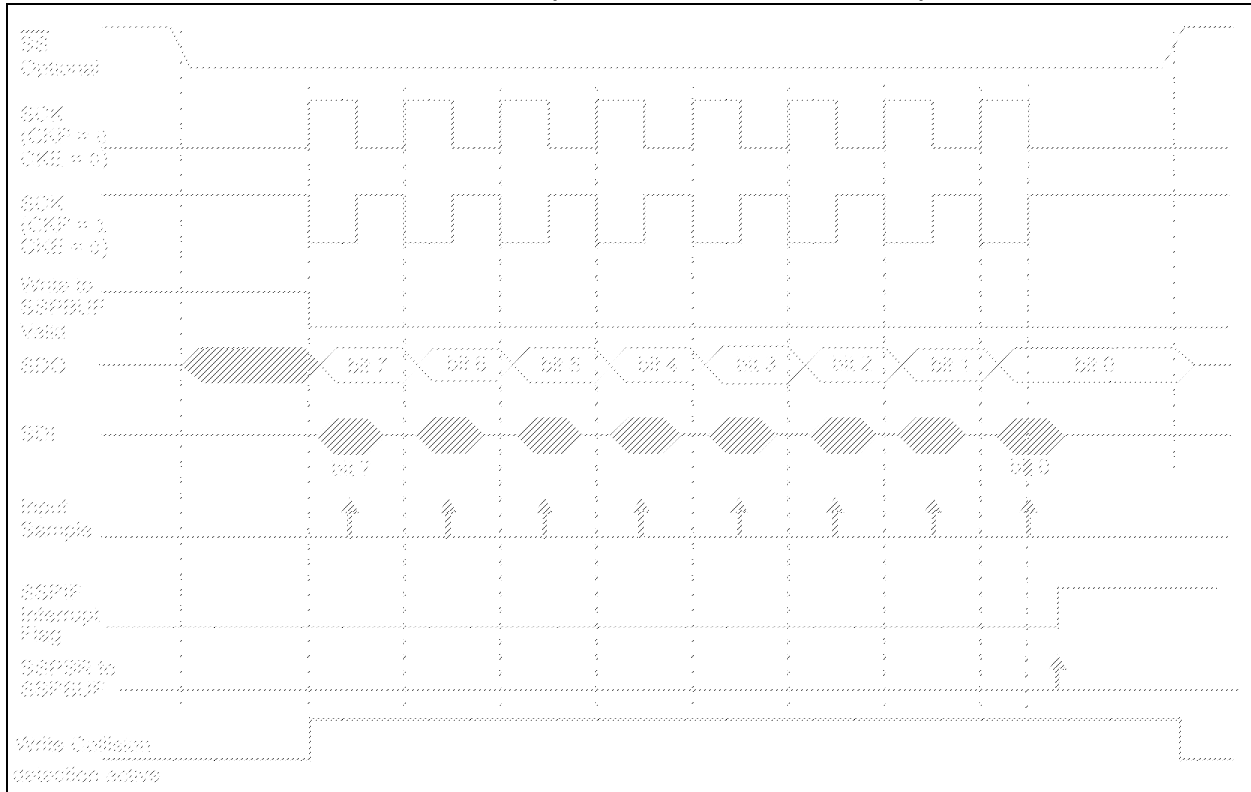
1 = ADC is enabled  
 0 = ADC is disabled and consumes no operating current

**Note 1:** See **Section 22.0 “8-Bit Digital-to-Analog Converter (DAC1) Module”** for more information.

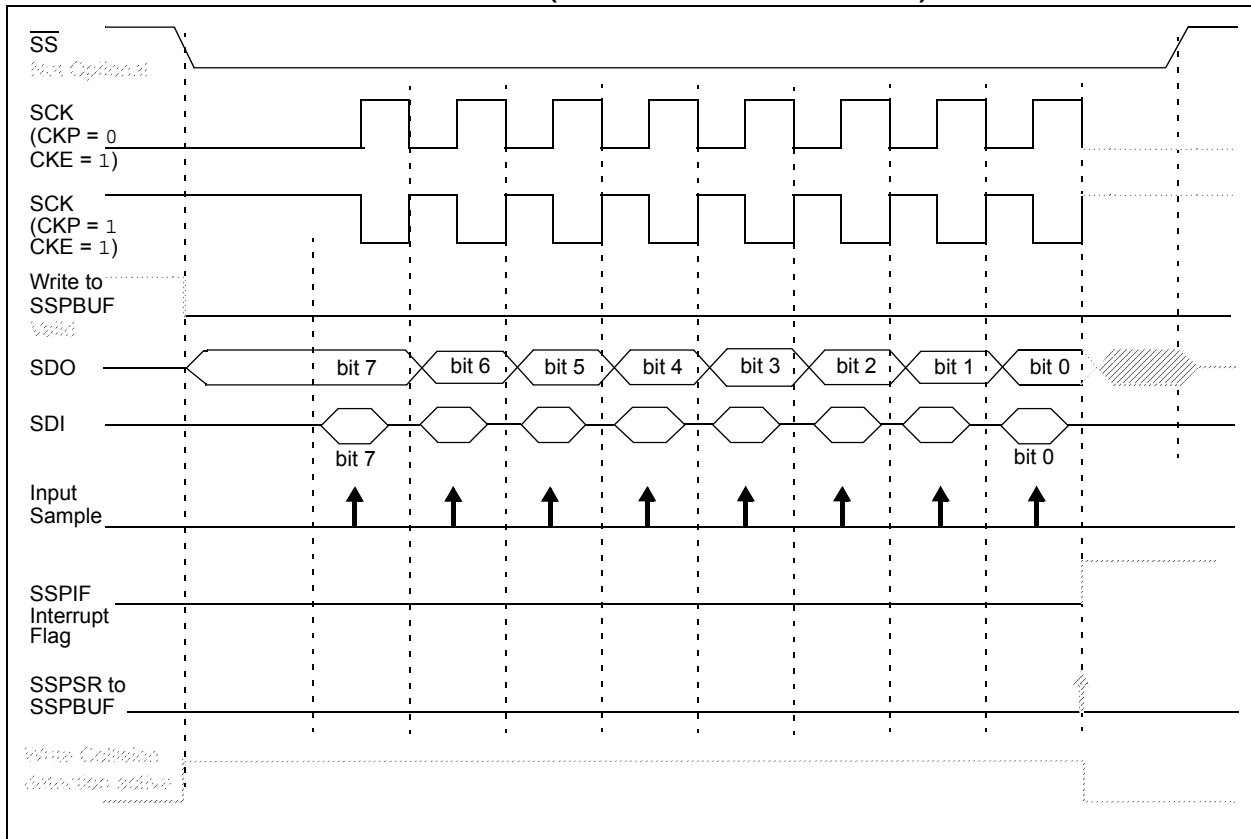
**2:** See **Section 14.0 “Fixed Voltage Reference (FVR)”** for more information.

**3:** See **Section 15.0 “Temperature Indicator Module”** for more information.

**FIGURE 28-9: SPI MODE WAVEFORM (SLAVE MODE WITH CKE = 0)**



**FIGURE 28-10: SPI MODE WAVEFORM (SLAVE MODE WITH CKE = 1)**



# PIC16(L)F1704/8

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## REGISTER 28-2: SSP1CON1: SSP CONTROL REGISTER 1 (CONTINUED)

bit 3-0      **SSPM<3:0>**: Synchronous Serial Port Mode Select bits

- 1111 = I<sup>2</sup>C Slave mode, 10-bit address with Start and Stop bit interrupts enabled
- 1110 = I<sup>2</sup>C Slave mode, 7-bit address with Start and Stop bit interrupts enabled
- 1101 = Reserved
- 1100 = Reserved
- 1011 = I<sup>2</sup>C firmware controlled Master mode (slave idle)
- 1010 = SPI Master mode, clock =  $F_{osc}/(4 * (SSPADD+1))$ <sup>(5)</sup>
- 1001 = Reserved
- 1000 = I<sup>2</sup>C Master mode, clock =  $F_{osc} / (4 * (SSPADD+1))$ <sup>(4)</sup>
- 0111 = I<sup>2</sup>C Slave mode, 10-bit address
- 0110 = I<sup>2</sup>C Slave mode, 7-bit address
- 0101 = SPI Slave mode, clock = SCK pin,  $\overline{SS}$  pin control disabled,  $\overline{SS}$  can be used as I/O pin
- 0100 = SPI Slave mode, clock = SCK pin,  $\overline{SS}$  pin control enabled
- 0011 = SPI Master mode, clock = T2\_match/2
- 0010 = SPI Master mode, clock =  $F_{osc}/64$
- 0001 = SPI Master mode, clock =  $F_{osc}/16$
- 0000 = SPI Master mode, clock =  $F_{osc}/4$

- Note 1:** In Master mode, the overflow bit is not set since each new reception (and transmission) is initiated by writing to the SSPBUF register.
- 2:** When enabled, these pins must be properly configured as input or output. Use SSPSSPPS, SSPCLKPPS, SSPDATPPS, and RxyPPS to select the pins.
- 3:** When enabled, the SDA and SCL pins must be configured as inputs. Use SSPCLKPPS, SSPDATPPS, and RxyPPS to select the pins.
- 4:** SSPADD values of 0, 1 or 2 are not supported for I<sup>2</sup>C mode.
- 5:** SSPADD value of '0' is not supported. Use SSPM = 0000 instead.



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FIGURE 29-7: AUTO-WAKE-UP BIT (WUE) TIMING DURING NORMAL OPERATION

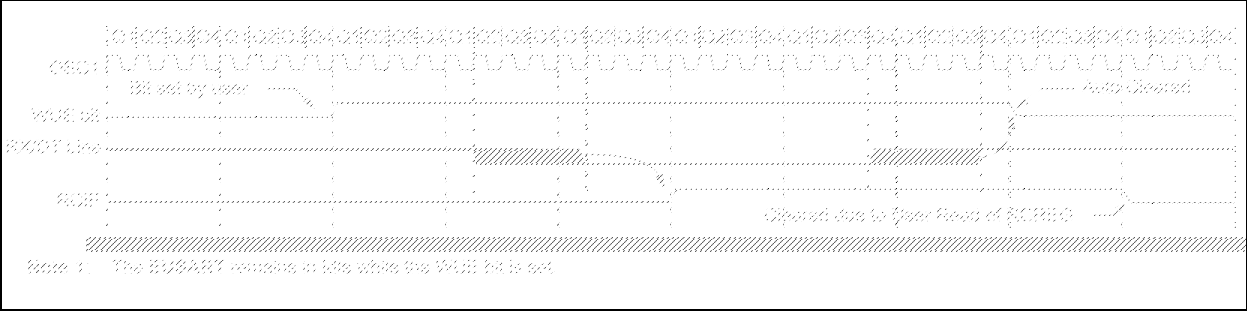
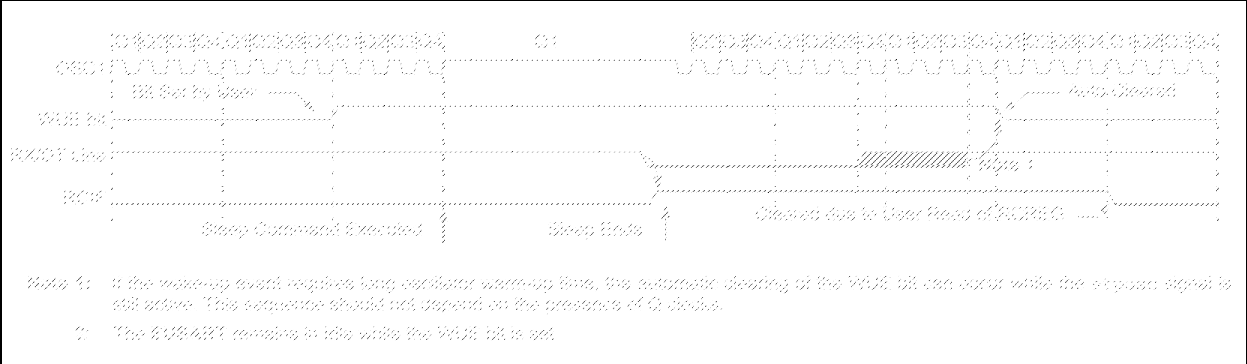


FIGURE 29-8: AUTO-WAKE-UP BIT (WUE) TIMINGS DURING SLEEP



## MOVWI Move W to INDFn

**Syntax:** [ *label* ] MOVWI ++FSRn  
[ *label* ] MOVWI --FSRn  
[ *label* ] MOVWI FSRn++  
[ *label* ] MOVWI FSRn--  
[ *label* ] MOVWI k[FSRn]

**Operands:** n ∈ [0,1]  
mm ∈ [00,01, 10, 11]  
-32 ≤ k ≤ 31

**Operation:** W → INDFn  
Effective address is determined by

- FSR + 1 (preincrement)
- FSR - 1 (predecrement)
- FSR + k (relative offset)

After the Move, the FSR value will be either:

- FSR + 1 (all increments)
- FSR - 1 (all decrements)

Unchanged

**Status Affected:** None

Mode	Syntax	mm
Preincrement	++FSRn	00
Predecrement	--FSRn	01
Postincrement	FSRn++	10
Postdecrement	FSRn--	11

**Description:** This instruction is used to move data between W and one of the indirect registers (INDFn). Before/after this move, the pointer (FSRn) is updated by pre/post incrementing/decrementing it.

**Note:** The INDFn registers are not physical registers. Any instruction that accesses an INDFn register actually accesses the register at the address specified by the FSRn.

FSRn is limited to the range 0000h-FFFFh. Incrementing/decrementing it beyond these bounds will cause it to wrap-around.

The increment/decrement operation on FSRn WILL NOT affect any Status bits.

## NOP No Operation

**Syntax:** [ *label* ] NOP

**Operands:** None

**Operation:** No operation

**Status Affected:** None

**Description:** No operation.

**Words:** 1

**Cycles:** 1

**Example:** NOP

## OPTION Load OPTION\_REG Register with W

**Syntax:** [ *label* ] OPTION

**Operands:** None

**Operation:** (W) → OPTION\_REG

**Status Affected:** None

**Description:** Move data from W register to OPTION\_REG register.

**Words:** 1

**Cycles:** 1

**Example:** OPTION

Before Instruction  
OPTION\_REG = 0xFF  
W = 0x4F

After Instruction  
OPTION\_REG = 0x4F  
W = 0x4F

## RESET Software Reset

**Syntax:** [ *label* ] RESET

**Operands:** None

**Operation:** Execute a device Reset. Resets the  $\overline{RI}$  flag of the PCON register.

**Status Affected:** None

**Description:** This instruction provides a way to execute a hardware Reset by software.

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**TABLE 32-4: I/O PORTS**

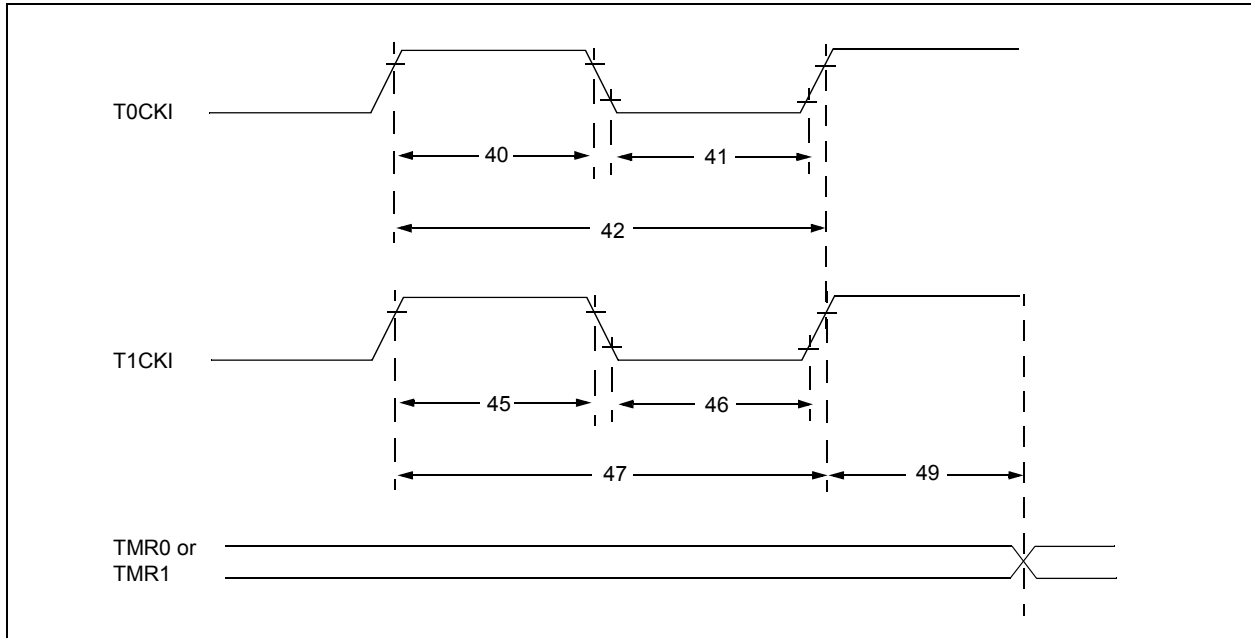
Standard Operating Conditions (unless otherwise stated)							
Param. No.	Sym.	Characteristic	Min.	Typ.†	Max.	Units	Conditions
D034 D034A D035  D036 D036A	V <sub>IL</sub>	<b>Input Low Voltage</b>					
		I/O PORT:					
		with TTL buffer	—	—	0.8	V	4.5V ≤ V <sub>DD</sub> ≤ 5.5V
			—	—	0.15 V <sub>DD</sub>	V	1.8V ≤ V <sub>DD</sub> ≤ 4.5V
		with Schmitt Trigger buffer	—	—	0.2 V <sub>DD</sub>	V	2.0V ≤ V <sub>DD</sub> ≤ 5.5V
		with I <sup>2</sup> C levels	—	—	0.3 V <sub>DD</sub>	V	
		with SMBus levels	—	—	0.8	V	2.7V ≤ V <sub>DD</sub> ≤ 5.5V
D040 D040A  D041  D042 D043A D043B	V <sub>IH</sub>	MCLR, OSC1 (RC mode)	—	—	0.2 V <sub>DD</sub>	V	(Note 1)
		OSC1 (HS mode)	—	—	0.3 V <sub>DD</sub>	V	
		<b>Input High Voltage</b>					
		I/O ports:					
		with TTL buffer	2.0	—	—	V	4.5V ≤ V <sub>DD</sub> ≤ 5.5V
			0.25 V <sub>DD</sub> + 0.8	—	—	V	1.8V ≤ V <sub>DD</sub> ≤ 4.5V
		with Schmitt Trigger buffer	0.8 V <sub>DD</sub>	—	—	V	2.0V ≤ V <sub>DD</sub> ≤ 5.5V
D060  D061	I <sub>IL</sub>	with I <sup>2</sup> C levels	0.7 V <sub>DD</sub>	—	—	V	
		with SMBus levels	2.1	—	—	V	2.7V ≤ V <sub>DD</sub> ≤ 5.5V
		MCLR	0.8 V <sub>DD</sub>	—	—	V	
		OSC1 (HS mode)	0.7 V <sub>DD</sub>	—	—	V	
		OSC1 (RC oscillator)	0.9 V <sub>DD</sub>	—	—	V	V <sub>DD</sub> > 2.0V (Note 1)
D060  D061	I <sub>IL</sub>	<b>Input Leakage Current<sup>(2)</sup></b>					
		I/O Ports	—	± 5	± 125	nA	V <sub>SS</sub> ≤ V <sub>PIN</sub> ≤ V <sub>DD</sub> , Pin at high-impedance, 85°C
			—	± 5	± 1000	nA	V <sub>SS</sub> ≤ V <sub>PIN</sub> ≤ V <sub>DD</sub> , Pin at high-impedance, 125°C
D070*	I <sub>PUR</sub>	MCLR <sup>(3)</sup>	—	± 5	± 200	nA	V <sub>SS</sub> ≤ V <sub>PIN</sub> ≤ V <sub>DD</sub> , Pin at high-impedance, 85°C
		<b>Weak Pull-up Current</b>					
D080	V <sub>OL</sub>		25	100	200	μA	V <sub>DD</sub> = 3.3V, V <sub>PIN</sub> = V <sub>SS</sub>
D080	V <sub>OL</sub>	<b>Output Low Voltage<sup>(4)</sup></b>					
		I/O ports	—	—	0.6	V	I <sub>OL</sub> = 8 mA, V <sub>DD</sub> = 5V I <sub>OL</sub> = 6 mA, V <sub>DD</sub> = 3.3V I <sub>OL</sub> = 1.8 mA, V <sub>DD</sub> = 1.8V
D090	V <sub>OH</sub>	<b>Output High Voltage<sup>(4)</sup></b>					
		I/O ports	V <sub>DD</sub> – 0.7	—	—	V	I <sub>OH</sub> = –3.5 mA, V <sub>DD</sub> = 5V I <sub>OH</sub> = –3 mA, V <sub>DD</sub> = 3.3V I <sub>OH</sub> = –1 mA, V <sub>DD</sub> = 1.8V
D101*	COSC2	<b>Capacitive Loading Specs on Output Pins</b>					
		OSC2 pin	—	—	15	pF	In XT, HS and LP modes when external clock is used to drive OSC1
D101A*	C <sub>IO</sub>	All I/O pins	—	—	50	pF	

\* These parameters are characterized but not tested.

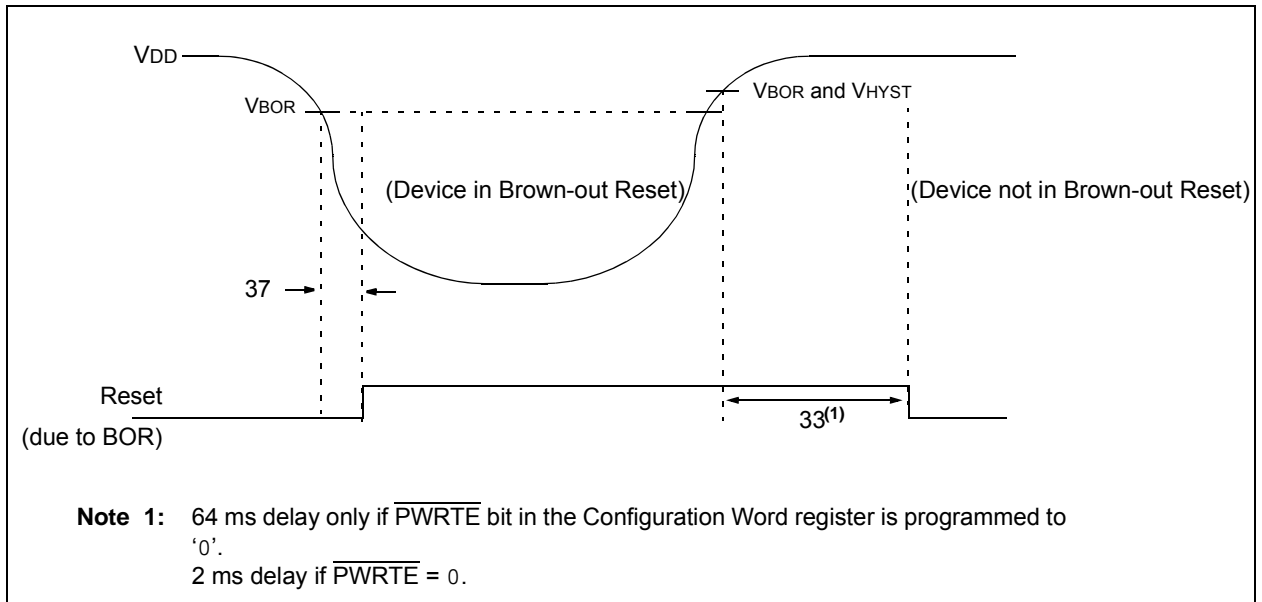
† Data in "Typ." column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note** 1: In RC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended to use an external clock in RC mode.
- 2: Negative current is defined as current sourced by the pin.
- 3: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
- 4: Including OSC2 in CLKOUT mode.

**FIGURE 32-9: TIMER0 AND TIMER1 EXTERNAL CLOCK TIMINGS**



**FIGURE 32-10: BROWN-OUT RESET TIMING AND CHARACTERISTICS**



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**TABLE 32-12: TIMER0 AND TIMER1 EXTERNAL CLOCK REQUIREMENTS**

Standard Operating Conditions (unless otherwise stated)								
Param. No.	Sym.	Characteristic		Min.	Typ.†	Max.	Units	Conditions
40*	Tt0H	T0CKI High Pulse Width	No Prescaler	$0.5 T_{CY} + 20$	—	—	ns	
			With Prescaler	10	—	—	ns	
41*	Tt0L	T0CKI Low Pulse Width	No Prescaler	$0.5 T_{CY} + 20$	—	—	ns	
			With Prescaler	10	—	—	ns	
42*	Tt0P	T0CKI Period		Greater of: 20 or $(T_{CY} + 40) * N$	—	—	ns	N = prescale value (2, 4, ..., 256)
45*	Tt1H	T1CKI High Time	Synchronous, No Prescaler	$0.5 T_{CY} + 20$	—	—	ns	
			Synchronous, with Prescaler	15	—	—	ns	
			Asynchronous	30	—	—	ns	
46*	Tt1L	T1CKI Low Time	Synchronous, No Prescaler	$0.5 T_{CY} + 20$	—	—	ns	
			Synchronous, with Prescaler	15	—	—	ns	
			Asynchronous	30	—	—	ns	
47*	Tt1P	T1CKI Input Period	Synchronous	Greater of: 30 or $(T_{CY} + 40) * N$	—	—	ns	
			Asynchronous	60	—	—	ns	
48	Ft1	Timer1 Oscillator Input Frequency Range (oscillator enabled by setting bit T1OSCEN)		32.4	32.768	33.1	kHz	
49*	TCKEZTMR1	Delay from External Clock Edge to Timer Increment		2 TOSC	—	7 TOSC	—	Timers in Sync mode

\* These parameters are characterized but not tested.

† Data in "Typ." column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.