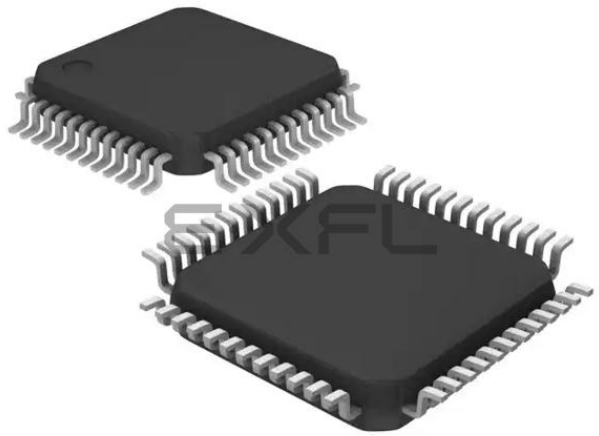

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	ARM7®
Core Size	16/32-Bit
Speed	55MHz
Connectivity	I²C, SPI, SSC, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.65V ~ 1.95V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/at91sam7s32b-au

- Debug Unit (DBGU)
  - 2-wire UART and Support for Debug Communication Channel interrupt, Programmable ICE Access Prevention
  - Mode for General Purpose 2-wire UART Serial Communication
- Periodic Interval Timer (PIT)
  - 20-bit Programmable Counter plus 12-bit Interval Counter
- Windowed Watchdog (WDT)
  - 12-bit key-protected Programmable Counter
  - Provides Reset or Interrupt Signals to the System
  - Counter May Be Stopped While the Processor is in Debug State or in Idle Mode
- Real-time Timer (RTT)
  - 32-bit Free-running Counter with Alarm
  - Runs Off the Internal RC Oscillator
- One Parallel Input/Output Controller (PIOA)
  - Thirty-two (SAM7S512/256/128/64/321/161) or twenty-one (SAM7S32/16) Programmable I/O Lines Multiplexed with up to Two Peripheral I/Os
  - Input Change Interrupt Capability on Each I/O Line
  - Individually Programmable Open-drain, Pull-up resistor and Synchronous Output
- Eleven (SAM7S512/256/128/64/321/161) or Nine (SAM7S32/16) Peripheral DMA Controller (PDC) Channels
- One USB 2.0 Full Speed (12 Mbits per Second) Device Port (Except for the SAM7S32/16).
  - On-chip Transceiver, 328-byte Configurable Integrated FIFOs
- One Synchronous Serial Controller (SSC)
  - Independent Clock and Frame Sync Signals for Each Receiver and Transmitter
  - I²S Analog Interface Support, Time Division Multiplex Support
  - High-speed Continuous Data Stream Capabilities with 32-bit Data Transfer
- Two (SAM7S512/256/128/64/321/161) or One (SAM7S32/16) Universal Synchronous/Asynchronous Receiver Transmitters (USART)
  - Individual Baud Rate Generator, IrDA® Infrared Modulation/Demodulation
  - Support for ISO7816 T0/T1 Smart Card, Hardware Handshaking, RS485 Support
  - Full Modem Line Support on USART1 (SAM7S512/256/128/64/321/161)
- One Master/Slave Serial Peripheral Interface (SPI)
  - 8- to 16-bit Programmable Data Length, Four External Peripheral Chip Selects
- One Three-channel 16-bit Timer/Counter (TC)
  - Three External Clock Input and Two Multi-purpose I/O Pins per Channel (SAM7S512/256/128/64/321/161)
  - One External Clock Input and Two Multi-purpose I/O Pins for the first Two Channels Only (SAM7S32/16)
  - Double PWM Generation, Capture/Waveform Mode, Up/Down Capability
- One Four-channel 16-bit PWM Controller (PWMC)
- One Two-wire Interface (TWI)
  - Master Mode Support Only, All Two-wire Atmel EEPROMs and I²C Compatible Devices Supported (SAM7S512/256/128/64/321/32)
  - Master, Multi-Master and Slave Mode Support, All Two-wire Atmel EEPROMs and I²C Compatible Devices Supported (SAM7S161/16)
- One 8-channel 10-bit Analog-to-Digital Converter, Four Channels Multiplexed with Digital I/Os
- SAM-BA™ Boot Assistant
  - Default Boot program
  - Interface with SAM-BA Graphic User Interface
- IEEE® 1149.1 JTAG Boundary Scan on All Digital Pins
- 5V-tolerant I/Os, including Four High-current Drive I/O lines, Up to 16 mA Each (SAM7S161/16 I/Os Not 5V-tolerant)
- Power Supplies
  - Embedded 1.8V Regulator, Drawing up to 100 mA for the Core and External Components
  - 3.3V or 1.8V VDDIO I/O Lines Power Supply, Independent 3.3V VDDFLASH Flash Power Supply
  - 1.8V VDDCORE Core Power Supply with Brown-out Detector

- **Fully Static Operation: Up to 55 MHz at 1.65V and 85° C Worst Case Conditions**
- **Available in 64-lead LQFP Green or 64-pad QFN Green Package (SAM7S512/256/128/64/321/161) and 48-lead LQFP Green or 48-pad QFN Green Package (SAM7S32/16)**

1. Description

Atmel's SAM7S is a series of low pincount Flash microcontrollers based on the 32-bit ARM RISC processor. It features a high-speed Flash and an SRAM, a large set of peripherals, including a USB 2.0 device (except for the SAM7S32 and SAM7S16), and a complete set of system functions minimizing the number of external components. The device is an ideal migration path for 8-bit microcontroller users looking for additional performance and extended memory.

The embedded Flash memory can be programmed in-system via the JTAG-ICE interface or via a parallel interface on a production programmer prior to mounting. Built-in lock bits and a security bit protect the firmware from accidental overwrite and preserves its confidentiality.

The SAM7S Series system controller includes a reset controller capable of managing the power-on sequence of the microcontroller and the complete system. Correct device operation can be monitored by a built-in brownout detector and a watchdog running off an integrated RC oscillator.

The SAM7S Series are general-purpose microcontrollers. Their integrated USB Device port makes them ideal devices for peripheral applications requiring connectivity to a PC or cellular phone. Their aggressive price point and high level of integration pushes their scope of use far into the cost-sensitive, high-volume consumer market.

1.1 Configuration Summary of the SAM7S512, SAM7S256, SAM7S128, SAM7S64, SAM7S321, SAM7S32, SAM7S161 and SAM7S16

The SAM7S512, SAM7S256, SAM7S128, SAM7S64, SAM7S321, SAM7S32, SAM7S161 and SAM7S16 differ in memory size, peripheral set and package. Table 1-1 summarizes the configuration of the six devices.

Except for the SAM7S32/16, all other SAM7S devices are package and pinout compatible.

Table 1-1. Configuration Summary

SAM7S512	512 Kbytes	Master	dual plane	64 Kbytes	1	2(1) (2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S256	256 Kbytes	Master	single plane	64 Kbytes	1	2(1) (2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S128	128 Kbytes	Master	single plane	32 Kbytes	1	2(1) (2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S64	64 Kbytes	Master	single plane	16 Kbytes	1	2(2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S321	32 Kbytes	Master	single plane	8 Kbytes	1	2(2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S32	32 Kbytes	Master	single plane	8 Kbytes	not present	1	1	9	3(3)	Yes	21	LQFP/ QFN 48
SAM7S161	16 Kbytes	Master/ Slave	single plane	4 Kbytes	1	2(2)	2	11	3	No	32	LQFP
SAM7S16	16 Kbytes	Master/ Slave	single plane	4 Kbytes	not present	1	1	9	3(3)	No	21	LQFP/ QFN 48

Notes: 1. Fractional Baud Rate.
2. Full modem line support on USART1.
3. Only two TC channels are accessible through the PIO.

2. Block Diagram

Figure 2-1. SAM7S512/256/128/64/321/161 Block Diagram

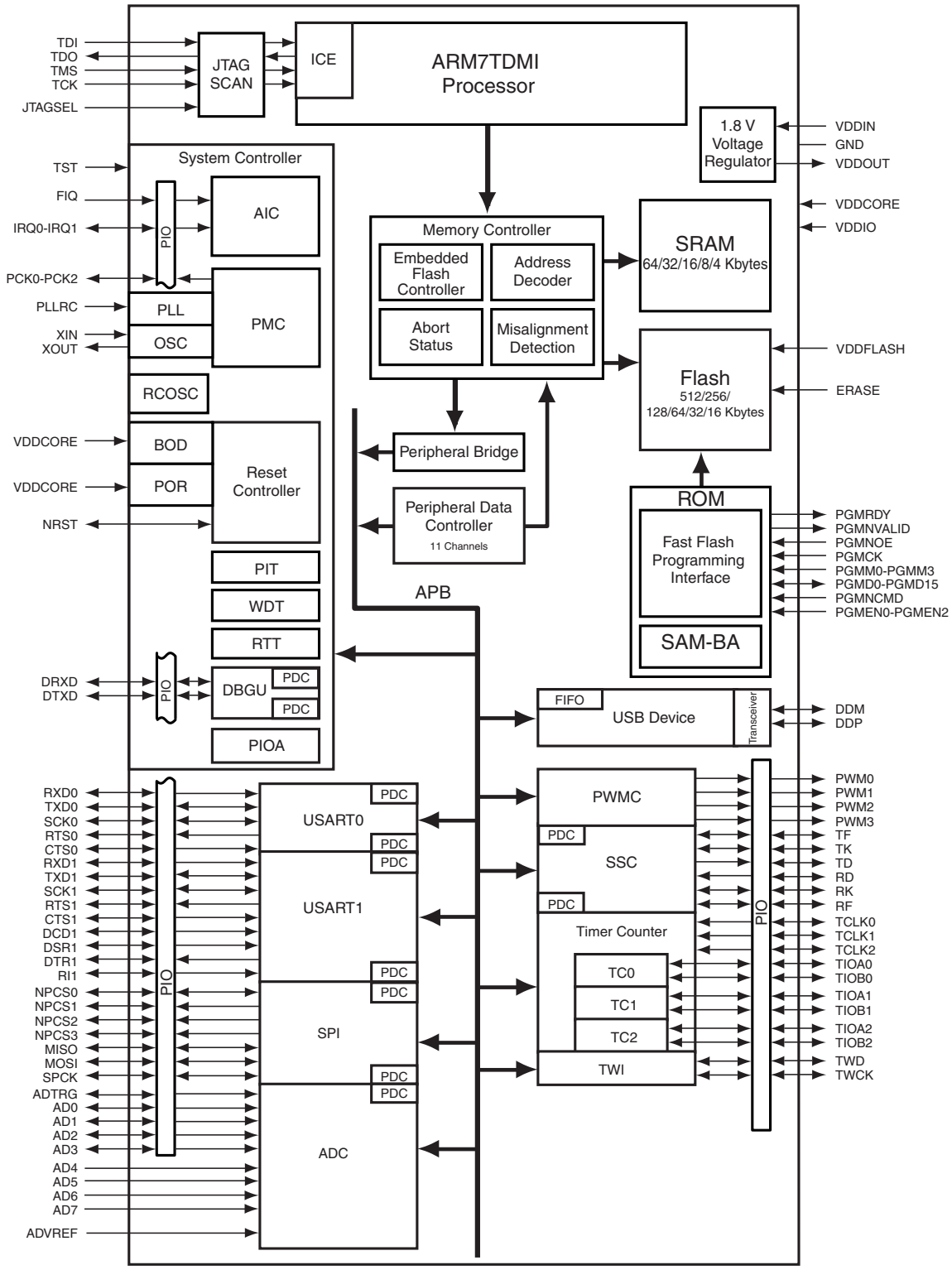
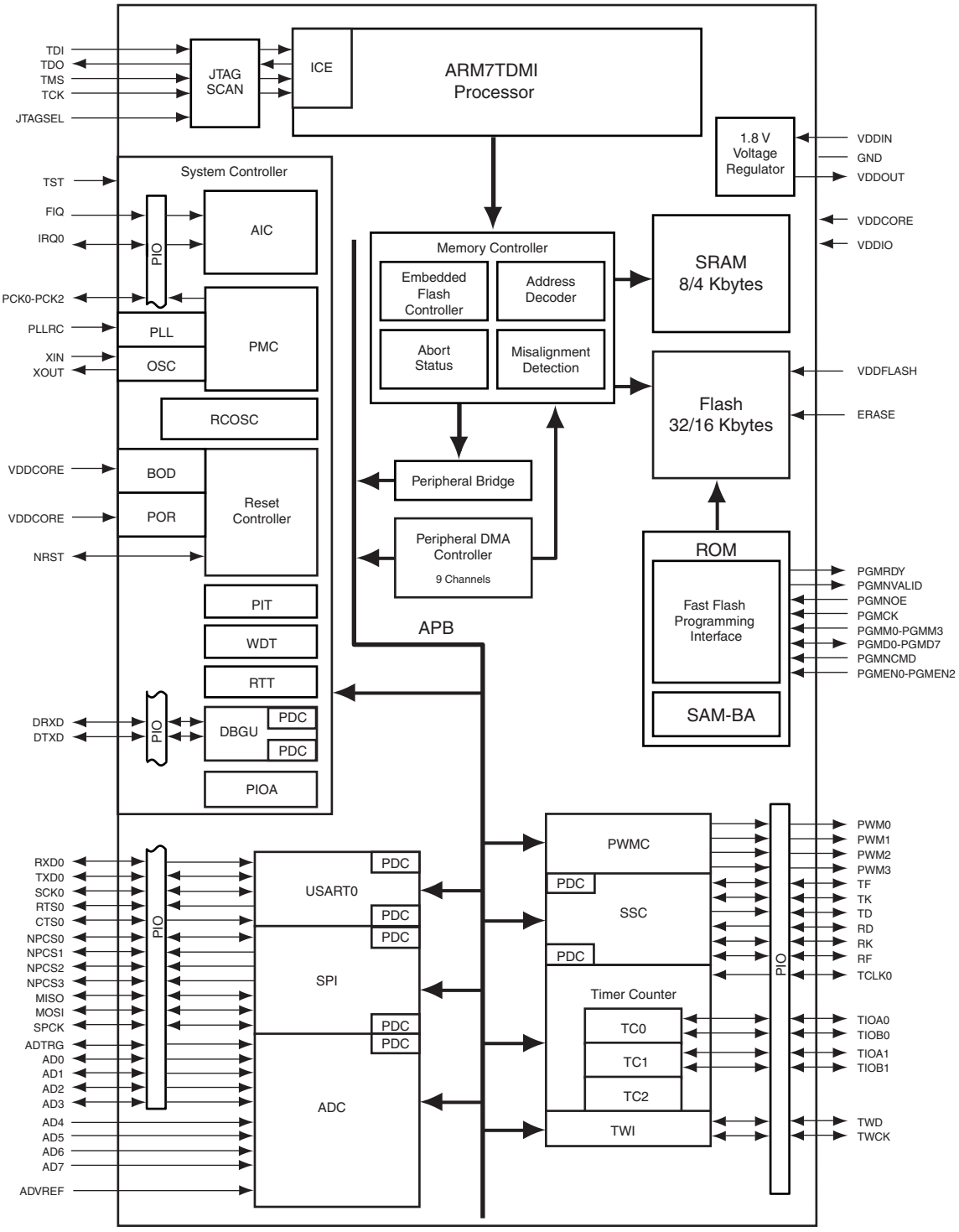


Figure 2-2. SAM7S32/16 Block Diagram



4. Package and Pinout

The SAM7S512/256/128/64/321 are available in a 64-lead LQFP or 64-pad QFN package.

The SAM7S161 is available in a 64-Lead LQFP package.

The SAM7S32/16 are available in a 48-lead LQFP or 48-pad QFN package.

4.1 64-lead LQFP and 64-pad QFN Package Outlines

Figure 4-1 and Figure 4-2 show the orientation of the 64-lead LQFP and the 64-pad QFN package. A detailed mechanical description is given in the section Mechanical Characteristics of the full datasheet.

Figure 4-1. 64-lead LQFP Package (Top View)

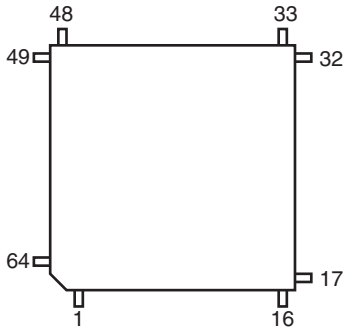
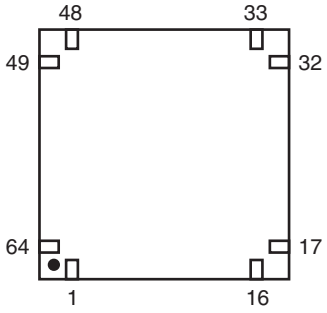


Figure 4-2. 64-pad QFN Package (Top View)



5. Power Considerations

5.1 Power Supplies

The SAM7S Series has six types of power supply pins and integrates a voltage regulator, allowing the device to be supplied with only one voltage. The six power supply pin types are:

- VDDIN pin. It powers the voltage regulator and the ADC; voltage ranges from 3.0V to 3.6V, 3.3V nominal.
- VDDOUT pin. It is the output of the 1.8V voltage regulator.
- VDDIO pin. It powers the I/O lines and the USB transceivers; dual voltage range is supported. Ranges from 3.0V to 3.6V, 3.3V nominal or from 1.65V to 1.95V, 1.8V nominal. Note that supplying less than 3.0V to VDDIO prevents any use of the USB transceivers.
- VDDFLASH pin. It powers a part of the Flash and is required for the Flash to operate correctly; voltage ranges from 3.0V to 3.6V, 3.3V nominal.
- VDDCORE pins. They power the logic of the device; voltage ranges from 1.65V to 1.95V, 1.8V typical. It can be connected to the VDDOUT pin with decoupling capacitor. VDDCORE is required for the device, including its embedded Flash, to operate correctly.

During startup, core supply voltage (VDDCORE) slope must be superior or equal to 6V/ms.

- VDDPLL pin. It powers the oscillator and the PLL. It can be connected directly to the VDDOUT pin.

No separate ground pins are provided for the different power supplies. Only GND pins are provided and should be connected as shortly as possible to the system ground plane.

In order to decrease current consumption, if the voltage regulator and the ADC are not used, VDDIN, ADVREF, AD4, AD5, AD6 and AD7 should be connected to GND. In this case VDDOUT should be left unconnected.

5.2 Power Consumption

The SAM7S Series has a static current of less than 60 µA on VDDCORE at 25°C, including the RC oscillator, the voltage regulator and the power-on reset. When the brown-out detector is activated, 20 µA static current is added.

The dynamic power consumption on VDDCORE is less than 50 mA at full speed when running out of the Flash. Under the same conditions, the power consumption on VDDFLASH does not exceed 10 mA.

5.3 Voltage Regulator

The SAM7S Series embeds a voltage regulator that is managed by the System Controller.

In Normal Mode, the voltage regulator consumes less than 100 µA static current and draws 100 mA of output current.

The voltage regulator also has a Low-power Mode. In this mode, it consumes less than 25 µA static current and draws 1 mA of output current.

Adequate output supply decoupling is mandatory for VDDOUT to reduce ripple and avoid oscillations. The best way to achieve this is to use two capacitors in parallel: one external 470 pF (or 1 nF) NPO capacitor must be connected between VDDOUT and GND as close to the chip as possible. One external 2.2 µF (or 3.3 µF) X7R capacitor must be connected between VDDOUT and GND.

Adequate input supply decoupling is mandatory for VDDIN in order to improve startup stability and reduce source voltage drop. The input decoupling capacitor should be placed close to the chip. For example, two capacitors can be used in parallel: 100 nF NPO and 4.7 µF X7R.

5.4 Typical Powering Schematics

The SAM7S Series supports a 3.3V single supply mode. The internal regulator is connected to the 3.3V source and its output feeds VDDCORE and the VDDPLL. Figure 5-1 shows the power schematics to be used for USB bus-powered systems.

6. I/O Lines Considerations

6.1 JTAG Port Pins

TMS, TDI and TCK are schmitt trigger inputs. TMS and TCK are 5-V tolerant, TDI is not. TMS, TDI and TCK do not integrate a pull-up resistor.

TDO is an output, driven at up to VDDIO, and has no pull-up resistor.

The JTAGSEL pin is used to select the JTAG boundary scan when asserted at a high level. The JTAGSEL pin integrates a permanent pull-down resistor of about 15 kΩ to GND, so that it can be left unconnected for normal operations.

6.2 Test Pin

The TST pin is used for manufacturing test, fast programming mode or SAM-BA Boot Recovery of the SAM7S Series when asserted high. The TST pin integrates a permanent pull-down resistor of about 15 kΩ to GND, so that it can be left unconnected for normal operations.

To enter fast programming mode, the TST pin and the PA0 and PA1 pins should be tied high and PA2 tied to low.

To enter SAM-BA Boot Recovery, the TST pin and the PA0, PA1 and PA2 pins should be tied high for at least 10 seconds. Then a power cycle of the board is mandatory.

Driving the TST pin at a high level while PA0 or PA1 is driven at 0 leads to unpredictable results.

6.3 Reset Pin

The NRST pin is bidirectional with an open drain output buffer. It is handled by the on-chip reset controller and can be driven low to provide a reset signal to the external components or asserted low externally to reset the microcontroller. There is no constraint on the length of the reset pulse, and the reset controller can guarantee a minimum pulse length. This allows connection of a simple push-button on the pin NRST as system user reset, and the use of the signal NRST to reset all the components of the system.

The NRST pin integrates a permanent pull-up resistor to VDDIO.

6.4 ERASE Pin

The ERASE pin is used to re-initialize the Flash content and some of its NVM bits. It integrates a permanent pull-down resistor of about 15 kΩ to GND, so that it can be left unconnected for normal operations.

6.5 PIO Controller A Lines

- All the I/O lines PA0 to PA31on SAM7S512/256/128/64/321 (PA0 to PA20 on SAM7S32) are 5V-tolerant and all integrate a programmable pull-up resistor.
- All the I/O lines PA0 to PA31 on SAM7S161 (PA0 to PA20 on SAM7S16) are **not** 5V-tolerant and all integrate a programmable pull-up resistor.

Programming of this pull-up resistor is performed independently for each I/O line through the PIO controllers.

5V-tolerant means that the I/O lines can drive voltage level according to VDDIO, but can be driven with a voltage of up to 5.5V. However, driving an I/O line with a voltage over VDDIO while the programmable pull-up resistor is enabled will create a current path through the pull-up resistor from the I/O line to VDDIO. Care should be taken, in particular at reset, as all the I/O lines default to input with the pull-up resistor enabled at reset.

6.6 I/O Line Drive Levels

The PIO lines PA0 to PA3 are high-drive current capable. Each of these I/O lines can drive up to 16 mA permanently.

The remaining I/O lines can draw only 8 mA.

However, the total current drawn by all the I/O lines cannot exceed 150 mA (100 mA for SAM7S32/16).

7. Processor and Architecture

7.1 ARM7TDMI Processor

- RISC processor based on ARMv4T Von Neumann architecture
  - Runs at up to 55 MHz, providing 0.9 MIPS/MHz
- Two instruction sets
  - ARM® high-performance 32-bit instruction set
  - Thumb® high code density 16-bit instruction set
- Three-stage pipeline architecture
  - Instruction Fetch (F)
  - Instruction Decode (D)
  - Execute (E)

7.2 Debug and Test Features

- Integrated EmbeddedICE™ (embedded in-circuit emulator)
  - Two watchpoint units
  - Test access port accessible through a JTAG protocol
  - Debug communication channel
- Debug Unit
  - Two-pin UART
  - Debug communication channel interrupt handling
  - Chip ID Register
- IEEE1149.1 JTAG Boundary-scan on all digital pins

7.3 Memory Controller

- Bus Arbiter
  - Handles requests from the ARM7TDMI and the Peripheral DMA Controller
- Address decoder provides selection signals for
  - Three internal 1 Mbyte memory areas
  - One 256 Mbyte embedded peripheral area
- Abort Status Registers
  - Source, Type and all parameters of the access leading to an abort are saved
  - Facilitates debug by detection of bad pointers
- Misalignment Detector
  - Alignment checking of all data accesses
  - Abort generation in case of misalignment
- Remap Command
  - Remaps the SRAM in place of the embedded non-volatile memory
  - Allows handling of dynamic exception vectors
- Embedded Flash Controller
  - Embedded Flash interface, up to three programmable wait states
  - Prefetch buffer, buffering and anticipating the 16-bit requests, reducing the required wait states
  - Key-protected program, erase and lock/unlock sequencer
  - Single command for erasing, programming and locking operations
  - Interrupt generation in case of forbidden operation

- Fast access time, 30 MHz single-cycle access in Worst Case conditions
- Page programming time: 6 ms, including page auto-erase
- Page programming without auto-erase: 3 ms
- Full chip erase time: 15 ms
- 10,000 write cycles, 10-year data retention capability
- 16 lock bits, protecting 16 sectors of 32 pages
- Protection Mode to secure contents of the Flash

- 16 Kbytes of Fast SRAM
  - Single-cycle access at full speed

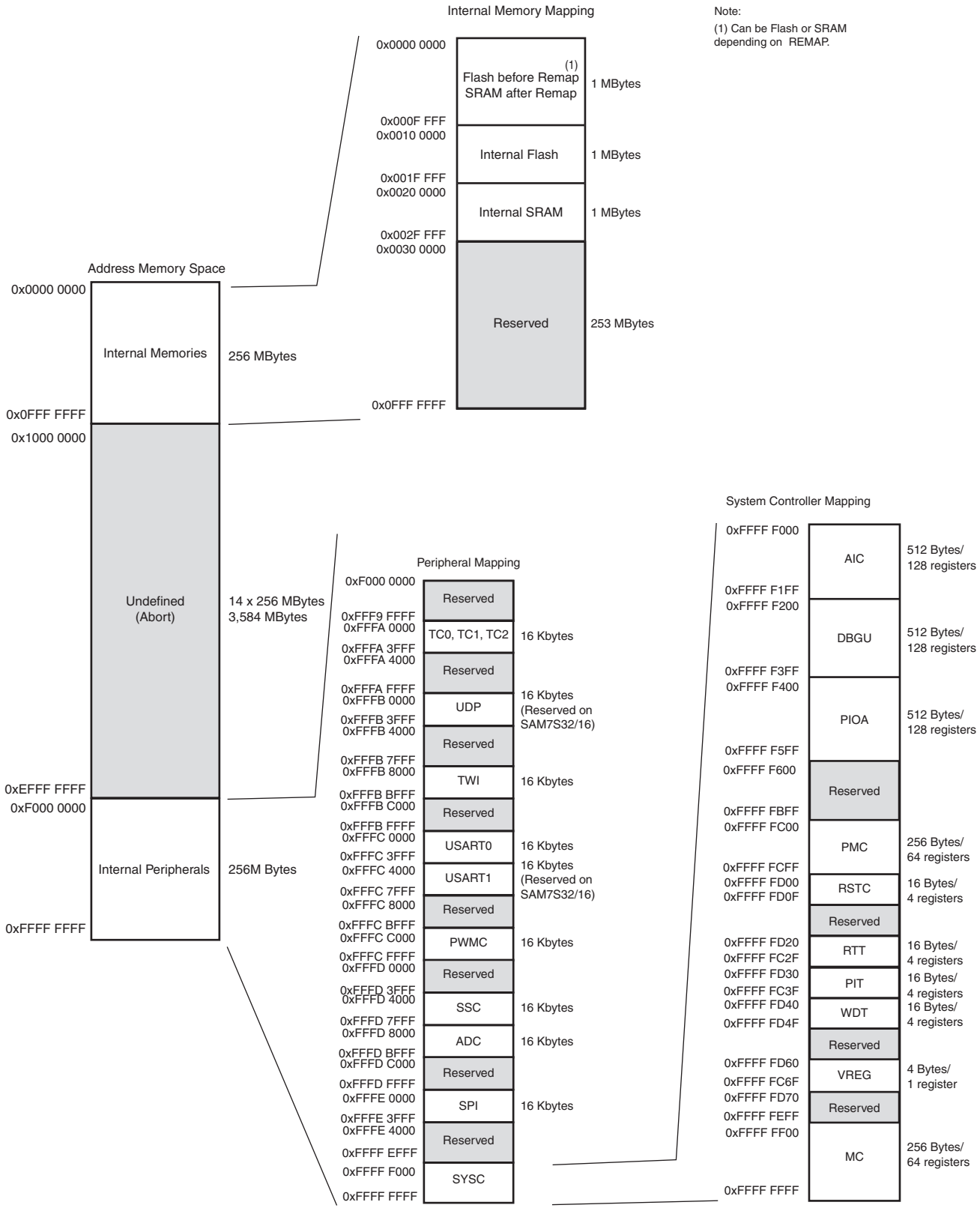
8.5 SAM7S321/32

- 32 Kbytes of Flash Memory, single plane
  - 256 pages of 128 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 8 lock bits, protecting 8 sectors of 32 pages
  - Protection Mode to secure contents of the Flash
- 8 Kbytes of Fast SRAM
  - Single-cycle access at full speed

8.6 SAM7S161/16

- 16 Kbytes of Flash Memory, single plane
  - 256 pages of 64 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 8 lock bits, protecting 8 sectors of 32 pages
  - Protection Mode to secure contents of the Flash
- 4 Kbytes of Fast SRAM
  - Single-cycle access at full speed

Figure 8-1. SAM SAM7S512/256/128/64/321/32/161/16 Memory Mapping



8.8.6 Calibration Bits

Eight NVM bits are used to calibrate the brownout detector and the voltage regulator. These bits are factory configured and cannot be changed by the user. The ERASE pin has no effect on the calibration bits.

8.9 Fast Flash Programming Interface

The Fast Flash Programming Interface allows programming the device through either a serial JTAG interface or through a multiplexed fully-handshaked parallel port. It allows gang-programming with market-standard industrial programmers.

The FFPI supports read, page program, page erase, full erase, lock, unlock and protect commands.

The Fast Flash Programming Interface is enabled and the Fast Programming Mode is entered when the TST pin and the PA0 and PA1 pins are all tied high and PA2 is tied low.

8.10 SAM-BA Boot Assistant

The SAM-BA® Boot Recovery restores the SAM-BA Boot in the first two sectors of the on-chip Flash memory. The SAM-BA Boot recovery is performed when the TST pin and the PA0, PA1 and PA2 pins are all tied high for 10 seconds. Then, a power cycle of the board is mandatory.

The SAM-BA Boot Assistant is a default Boot Program that provides an easy way to program in situ the on-chip Flash memory.

The SAM-BA Boot Assistant supports serial communication through the DBGU or through the USB Device Port. (The SAM7S32/16 have no USB Device Port.)

- Communication through the DBGU supports a wide range of crystals from 3 to 20 MHz via software auto-detection.
- Communication through the USB Device Port is limited to an 18.432 MHz crystal. (

The SAM-BA Boot provides an interface with SAM-BA Graphic User Interface (GUI).

9. System Controller

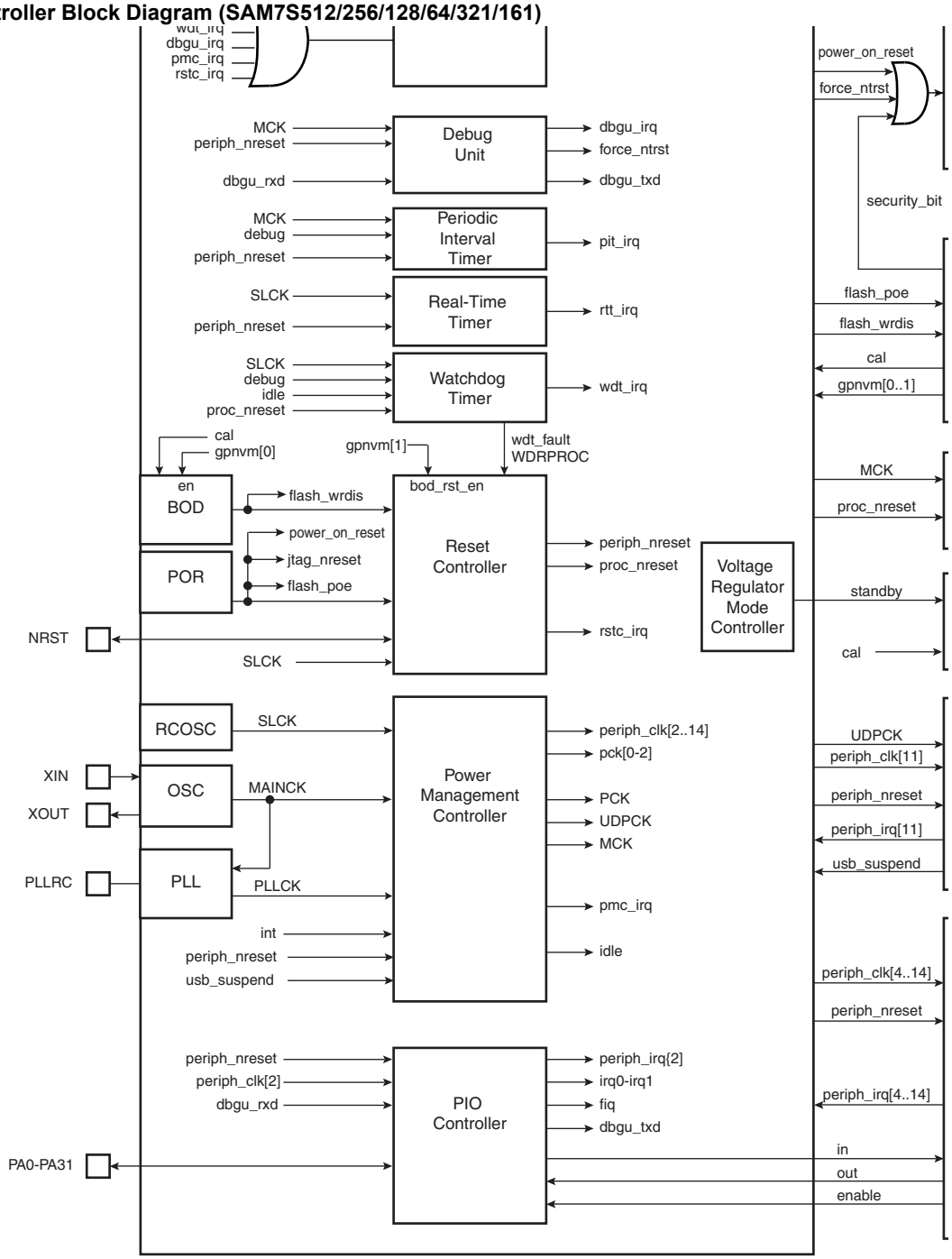
The System Controller manages all vital blocks of the microcontroller: interrupts, clocks, power, time, debug and reset.

The System Controller peripherals are all mapped to the highest 4 Kbytes of address space, between addresses 0xFFFF F000 and 0xFFFF FFFF.

Figure 9-1 on page 26 and Figure 9-2 on page 27 show the product specific System Controller Block Diagrams.

Figure 8-1 on page 20 shows the mapping of the of the User Interface of the System Controller peripherals. Note that the memory controller configuration user interface is also mapped within this address space.

Figure 9-1. System Controller Block Diagram (SAM7S512/256/128/64/321/161)



9.9 PIO Controller

- One PIO Controller, controlling 32 I/O lines (21 for SAM7S32/16)
- Fully programmable through set/clear registers
- Multiplexing of two peripheral functions per I/O line
- For each I/O line (whether assigned to a peripheral or used as general-purpose I/O)
  - Input change interrupt
  - Half a clock period glitch filter
  - Multi-drive option enables driving in open drain
  - Programmable pull-up on each I/O line
  - Pin data status register, supplies visibility of the level on the pin at any time
- Synchronous output, provides Set and Clear of several I/O lines in a single write

9.10 Voltage Regulator Controller

The aim of this controller is to select the Power Mode of the Voltage Regulator between Normal Mode (bit 0 is cleared) or Standby Mode (bit 0 is set).

10.4 PIO Controller A Multiplexing

Table 10-3. Multiplexing on PIO Controller A (SAM7S512/256/128/64/321/161)

PA0	PWM0	TIOA0	High-Drive		
PA1	PWM1	TIOB0	High-Drive		
PA2	PWM2	SCK0	High-Drive		
PA3	TWD	NPCS3	High-Drive		
PA4	TWCK	TCLK0			
PA5	RXD0	NPCS3			
PA6	TXD0	PCK0			
PA7	RTS0	PWM3			
PA8	CTS0	ADTRG			
PA9	DRXD	NPCS1			
PA10	DTXD	NPCS2			
PA11	NPCS0	PWM0			
PA12	MISO	PWM1			
PA13	MOSI	PWM2			
PA14	SPCK	PWM3			
PA15	TF	TIOA1			
PA16	TK	TIOB1			
PA17	TD	PCK1	AD0		
PA18	RD	PCK2	AD1		
PA19	RK	FIQ	AD2		
PA20	RF	IRQ0	AD3		
PA21	RXD1	PCK1			
PA22	TXD1	NPCS3			
PA23	SCK1	PWM0			
PA24	RTS1	PWM1			
PA25	CTS1	PWM2			
PA26	DCD1	TIOA2			
PA27	DTR1	TIOB2			
PA28	DSR1	TCLK1			
PA29	RI1	TCLK2			
PA30	IRQ1	NPCS2			
PA31	NPCS1	PCK2			

10.8 Serial Synchronous Controller

- Provides serial synchronous communication links used in audio and telecom applications
- Contains an independent receiver and transmitter and a common clock divider
- Offers a configurable frame sync and data length
- Receiver and transmitter can be programmed to start automatically or on detection of different event on the frame sync signal
- Receiver and transmitter include a data signal, a clock signal and a frame synchronization signal

10.9 Timer Counter

- Three 16-bit Timer Counter Channels
  - Two output compare or one input capture per channel (except for SAM7S32/16 which have only two channels connected to the PIO)
- Wide range of functions including:
  - Frequency measurement
  - Event counting
  - Interval measurement
  - Pulse generation
  - Delay timing
  - Pulse Width Modulation
  - Up/down capabilities
- Each channel is user-configurable and contains:
  - Three external clock inputs (The SAM7S32/16 have one)
  - Five internal clock inputs, as defined in Table 10-5

Table 10-5. Timer Counter Clocks Assignment

TIMER_CLOCK1	MCK/2
TIMER_CLOCK2	MCK/8
TIMER_CLOCK3	MCK/32
TIMER_CLOCK4	MCK/128
TIMER_CLOCK5	MCK/1024

  - Two multi-purpose input/output signals
  - Two global registers that act on all three TC channels

10.10 PWM Controller

- Four channels, one 16-bit counter per channel
- Common clock generator, providing thirteen different clocks
  - One Modulo n counter providing eleven clocks
  - Two independent linear dividers working on modulo n counter outputs
- Independent channel programming
  - Independent enable/disable commands
  - Independent clock selection
  - Independent period and duty cycle, with double buffering
  - Programmable selection of the output waveform polarity

- Programmable center or left aligned output waveform

10.11 USB Device Port (Does not pertain to SAM7S32/16)

- USB V2.0 full-speed compliant, 12 Mbits per second.
- Embedded USB V2.0 full-speed transceiver
- Embedded 328-byte dual-port RAM for endpoints
- Four endpoints
  - Endpoint 0: 8 bytes
  - Endpoint 1 and 2: 64 bytes ping-pong
  - Endpoint 3: 64 bytes
  - Ping-pong Mode (two memory banks) for isochronous and bulk endpoints
- Suspend/resume logic

10.12 Analog-to-digital Converter

- 8-channel ADC
- 10-bit 384 Ksamples/sec. or 8-bit 583 Ksamples/sec. Successive Approximation Register ADC
- ±2 LSB Integral Non Linearity, ±1 LSB Differential Non Linearity
- Integrated 8-to-1 multiplexer, offering eight independent 3.3V analog inputs
- External voltage reference for better accuracy on low voltage inputs
- Individual enable and disable of each channel
- Multiple trigger source
  - Hardware or software trigger
  - External trigger pin
  - Timer Counter 0 to 2 outputs TIOA0 to TIOA2 trigger
- Sleep Mode and conversion sequencer
  - Automatic wakeup on trigger and back to sleep mode after conversions of all enabled channels
- Four of eight analog inputs shared with digital signals

Table 11-1. 48-lead LQFP Package Dimensions (in mm)

Symbol						
A	–	–	1.60	–	–	0.063
A1	0.05	–	0.15	0.002	–	0.006
A2	1.35	1.40	1.45	0.053	0.055	0.057
D	9.00 BSC			0.354 BSC		
D1	7.00 BSC			0.276 BSC		
E	9.00 BSC			0.354 BSC		
E1	7.00 BSC			0.276 BSC		
R2	0.08	–	0.20	0.003	–	0.008
R1	0.08	–	–	0.003	–	–
q	0°	3.5°	7°	0°	3.5°	7°
θ_1	0°	–	–	0°	–	–
θ_2	11°	12°	13°	11°	12°	13°
θ_3	11°	12°	13°	11°	12°	13°
c	0.09	–	0.20	0.004	–	0.008
L	0.45	0.60	0.75	0.018	0.024	0.030
L1	1.00 REF			0.039 REF		
S	0.20	–	–	0.008	–	–
b	0.17	0.20	0.27	0.007	0.008	0.011
e	0.50 BSC.			0.020 BSC.		
D2	5.50			0.217		
E2	5.50			0.217		
Tolerances of Form and Position						
aaa	0.20			0.008		
bbb	0.20			0.008		
ccc	0.08			0.003		
ddd	0.08			0.003		

Table 11-3. 48-pad QFN Package Dimensions (in mm)

Symbol						
A	–	–	090	–	–	0.035
A1	–	–	0.050	–	–	0.002
A2	–	0.65	0.70	–	0.026	0.028
A3	0.20 REF			0.008 REF		
b	0.18	0.20	0.23	0.007	0.008	0.009
D	7.00 bsc			0.276 bsc		
D2	5.45	5.60	5.75	0.215	0.220	0.226
E	7.00 bsc			0.276 bsc		
E2	5.45	5.60	5.75	0.215	0.220	0.226
L	0.35	0.40	0.45	0.014	0.016	0.018
e	0.50 bsc			0.020 bsc		
R	0.09	–	–	0.004	–	–
Tolerances of Form and Position						
aaa	0.10			0.004		
bbb	0.10			0.004		
ccc	0.05			0.002		

Revision History

6175AS	First issue - Unqualified on Intranet Corresponds to 6175A full datasheet approval loop. Qualified on Intranet.	
6175BS	Section 8. “Memories” on page 18 updated: 2 ms => 3 ms, 10 ms => 15 ms, 4 ms => 6 ms	CSR05-529
6175CS	Section 12. ”SAM7S Ordering Information” AT91SAM7S321 changed in Table 12-1 on page 47	#2342
6175DS	“Features” , Table 1-1, “Configuration Summary,” on page 3, Section 4. ”Package and Pinout” Section 12. ”SAM7S Ordering Information” QFN package information added	#2444
6175ES	Section 10.11 on page 39 USB Device port, Ping-pong Mode includes Isochronous endpoints. “Features” on page 1, and global: AT91SAM7S512 added to series. Reference to Manchester Encoder removed from USART. Section 8. ”Memories” Reformatted Memories, Consolidated Memory Mapping in Figure 8-1 on page 20 Section 10. ”Peripherals” Reordered sub sections. Section 11. ”Package Drawings” QFN, LQFP package drawings added. “ice_nreset” signals changed to” power_on_reset” in System Controller block diagrams, Figure 9-1 on page 26 and Figure 9-2 on page 27. Section 4. ”Package and Pinout” LQFP and QFN Package Outlines replace Mechanical Overview. Section 10.1 ”User Interface”, User peripherals are mapped between 0xF000 0000 and 0xFFFF EFFF. SYSIRQ changed to SYSC in “Peripheral Identifiers” Table 10-1 and Table 10-2	specs #2748 #2832 (DBGU IP) rfo review
6175FS	AT91SAM7S161 and AT91SAM7S16 added to product family **Features:** Timer Counter, on page 2 product specific information rewritten, Table 1-1, “Configuration Summary,” on page 3, footnote explains TC on AT91SAM7S32/16 has only two channels accessible via PIO, and in Section 10.9 ”Timer Counter”, precisions added to “compare and capture” output/input. Section 10.6 ”Two-wire Interface”, updated reference to I^2C compatibility, internal address registers, slave addressing, Modes for AT91SAM7S161/16 “One Two-wire Interface (TWI)” on page 2, updated in Features Section 10.12 ”Analog-to-digital Converter”, updated Successive Approximation Register ADC and the INL, DNL ± values of LSB. Section 8.8.3 ”Lock Regions”, locked-region’s erase or program command updated Section 9.5 ”Debug Unit”, Chip ID updated. Section 6. ”I/O Lines Considerations”, JTAG Port Pin, Test Pin, Erase Pin, updated.	BDs 4208 rfo review 4325 5063