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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	Coldfire V1
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	CANbus, I <sup>2</sup> C, SCI, SPI, USB OTG
Peripherals	LVD, PWM, WDT
Number of I/O	51
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 12x12b
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-QFP
Supplier Device Package	64-QFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mcf51jm128vqh

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



<sup>2</sup> Up to 16 pins on Ports A, H, and J are shared with the ColdFire Rapid GPIO module.

## 1.2 Block Diagram

Figure 1 shows the connections between the MCF51JM128 series pins and modules.

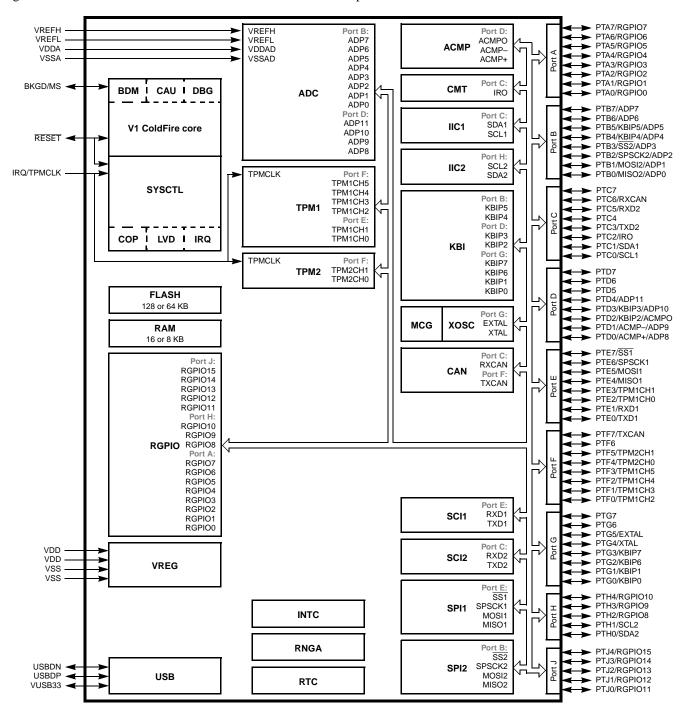


Figure 1. MCF51JM128 Block Diagram

MCF51JM128 ColdFire Microcontroller, Rev. 4



## 1.3 Features

Table 2 describes the functional units of the MCF51JM128 series.

Table 2. MCF51JM128 Series Functional Units

Unit	Function
CF1CORE (V1 ColdFire core)	Executes programs and interrupt handlers
BDM (background debug module)	Provides a single-pin debugging interface (part of the V1 ColdFire core)
DBG (debug)	Provides debugging and emulation capabilities (part of the V1 ColdFire core)
SYSCTL (system control)	Provides LVD, COP, external interrupt request, and so on
FLASH (flash memory)	Provides storage for program code and constants
RAM (random-access memory)	Provides storage for program code, constants, and variables
RGPIO (rapid general-purpose input/output)	Allows I/O port access at CPU clock speeds
VREG (voltage regulator)	Controls power management throughout the device
USBOTG (USB On-The-Go)	Supports the USB On-The-Go dual-role controller
ADC (analog-to-digital converter)	Measures analog voltages at up to 12 bits of resolution
TPM1, TPM2 (timer/pulse-width modulators)	Provide a variety of timing-based features
CF1_INTC (interrupt controller)	Controls and prioritizes all device interrupts
CAU (cryptographic acceleration unit)	Co-processor support for DES, 3DES, AES, MD5, and SHA-1
RNGA (random number generator accelerator)	32-bit random number generator that complies with FIPS-140
RTC (real-time counter)	Provides a constant-time base with optional interrupt
ACMP (analog comparator)	Compares two analog inputs
CMT (carrier modulator timer)	Infrared output used for the Remote Controller
IIC1, IIC2 (inter-integrated circuits)	Supports the standard IIC communications protocol
KBI (keyboard interrupt)	Provides pin interrupt capabilities
MCG (multipurpose clock generator)	Provides clocking options for the device, including a phase-locked loop (PLL) and frequency-locked loop (FLL) for multiplying slower reference clock sources
XOSC (crystal oscillator)	Supports low/high range crystals
CAN (controller area network)	Supports standard CAN communications protocol
SCI1, SCI2 (serial communications interfaces)	Serial communications UARTs that can support RS-232 and LIN protocols
SPI1, SPI2 (serial peripheral interfaces)	Provide a 4-pin synchronous serial interface
	•



### 1.3.1 Feature List

- 32-bit Version 1 ColdFire Central Processor Unit (CPU)
  - Up to 50.33 MHz at 2.7 V 5.5 V
  - Performance (Dhrystone 2.1):
    - 0.94 Dhrystone 2.1 MIPS per MHz when running from internal RAM
    - 0.76 Dhrystone 2.1 MIPS per MHz when running from flash
  - Implements Instruction Set Revision C (ISA\_C)
  - Supports up to 30 peripheral interrupt requests and seven software interrupts
- · On-chip memory
  - Up to 128 KB Flash memory with read/program/erase over full operating voltage and temperature range
  - Up to 16 KB static random access memory (RAM)
  - Security circuitry to prevent unauthorized access to RAM and flash contents
- · Power-saving modes
  - Two low-power stop plus wait modes
  - Peripheral clock enable register can disable clocks to unused modules, thereby reducing currents; this behavior allows clocks to remain enabled to specific perhipherals in Stop3 mode
  - Very lower power real-time counter for use in run, wait, and stop modes with internal and external clock sources
- Four Clock Source Options
  - Oscillator (XOSC) Loop-control Pierce oscillator; crystal or ceramic resonator range of 31.25 kHz to 38.4 kHz or 1 MHz to 16 MHz
  - FLL/PLL controlled by internal or external reference
  - Trimmable internal reference allows 0.2% resolution and 2% deviation
- System protection features
  - Watchdog computer operating properly (COP) reset with option to run from dedicated 1 kHz internal clock source or bus clock
  - Low-voltage detection with reset or interrupt; selectable trip points
  - Illegal opcode and illegal address detection with programmable reset or exception response
  - Flash block protection
- Debug support
  - Single-wire Background debug interface
  - 4 Program Counters plus two address (optional data) breakpoint registers with programmable 1- or 2-level trigger response
  - 64-entry processor status and debug data trace buffer with programmable start/stop conditions
- Universal Serial Bus (USB) On-The-Go dual-role controller
  - Full-speed USB device controller
    - Fully compliant with USB specification 1.1 and 2.0
    - 16 bidirectional endpoints, with double buffering to provide the maximum throughput
    - Supports control, bulk, interrupt, and isochronous endpoints
    - Supports bus-powered capability with low-power consumption
  - Full-speed / low-speed host controller
    - Host mode allows control, bulk, interrupt, and isochronous transfers
  - OTG protocol logic
  - On-chip USB transceiver
  - On-chip 3.3 V USB regulator and pull-up resistors save system cost



#### RTC

- 8-bit modulus counter with binary- or decimal-based prescaler
- External clock source for precise time base, time-of-day, calendar or task scheduling functions
- Free running on-chip low power oscillator (1 kHz) for cyclic wake-up without external components
- Carrier modulator timer (CMT)
  - carrier generator, modulator, and transmitter drive the infrared out (IRO) pin
  - operation in independent high/low time control, baseband, FSK, and direct IRO control modes
- Input/Output
  - 66 GPIOs
  - Eight keyboard interrupt pins with selectable polarity
  - Hysteresis and configurable pull-up device on all input pins; configurable slew rate and drive strength on all output pins
  - 16 bits of Rapid GPIO connected to the processor's local 32-bit platform bus with set, clear, and faster toggle functionality

### 1.4 Part Numbers

**Table 3. Orderable Part Number Summary** 

Freescale Part Number	Description		Package	Temperature
MCF51JM128EVLK	CF51JM128EVLK MCF51JM128 ColdFire Microcontroller with CAU and RNGA Enabled		80 LQFP	−40 to +105 °C
MCF51JM128VLK	MCF51JM128 ColdFire Microcontroller	128 / 16	80 LQFP	-40 to +105 °C
MCF51JM128EVLH	MCF51JM128 ColdFire Microcontroller with CAU and RNGA Enabled	128 / 16	64 LQFP	−40 to +105 °C
MCF51JM128VLH	MCF51JM128 ColdFire Microcontroller	128 / 16	64 LQFP	-40 to +105 °C
MCF51JM128EVQH	MCF51JM128 ColdFire Microcontroller with CAU and RNGA Enabled	128 / 16	64 QFP	−40 to +105 °C
MCF51JM128VQH	MCF51JM128 ColdFire Microcontroller	128 / 16	64 QFP	-40 to +105 °C
MCF51JM128EVLD	MCF51JM128 ColdFire Microcontroller with CAU and RNGA Enabled	128 / 16	44 LQFP	−40 to +105 °C
MCF51JM128VLD	MCF51JM128 ColdFire Microcontroller	128 / 16	44 LQFP	-40 to +105 °C
MCF51JM64EVLK	MCF51JM64 ColdFire Microcontroller with CAU and RNGA Enabled	64 / 16	80 LQFP	−40 to +105 °C
MCF51JM64VLK	MCF51JM64 ColdFire Microcontroller	64 / 16	80 LQFP	-40 to +105 °C
MCF51JM64EVLH	MCF51JM64 ColdFire Microcontroller with CAU and RNGA Enabled	64 / 16	64 LQFP	−40 to +105 °C
MCF51JM64VLH	MCF51JM64 ColdFire Microcontroller	64 / 16	64 LQFP	−40 to +105 °C
MCF51JM64EVQH	MCF51JM64 ColdFire Microcontroller with CAU and RNGA Enabled	64 / 16	64 QFP	−40 to +105 °C
MCF51JM64VQH	MCF51JM64 ColdFire Microcontroller	64 / 16	64 QFP	-40 to +105 °C



Table 4. Pin Assignments by Package and Pin Sharing Priority (continued)

Pin	Num	ber	< Lov	vest <b>Priority</b> > h	Highest
80	64	44	Port Pin	Alt 1	Alt 2
49	41	_	PTB7	ADP7	_
50	42	29	PTD0	ADP8	ACMP+
51	43	30	PTD1	ADP9	ACMP-
52	44	31	_	_	VDDA
53	45		_	_	VREFH
54	46	32	_	_	VREFL
55	47		_	_	VSSA
56	48	33	PTD2	KBIP2	ACMPO
57		_	PTJ0	RGPIO11	_
58	_	_	PTJ1	RGPIO12	_
59		_	PTJ2	RGPIO13	_
60		_	PTJ3	RGPIO14	_
61		_	PTJ4	RGPIO15	_
62	49	_	PTD3	KBIP3	ADP10
63	50	_	PTD4	ADP11	_
64	51	_	PTD5	_	_
65	52	_	PTD6	_	_
66	53	_	PTD7	_	_
67	54	34	PTG2	KBIP6	_
68	55	35	PTG3	KBIP7	_
69	56	36	_	BKGD	MS
70	57	37	PTG4	XTAL	
71	58	38	PTG5	EXTAL	
72	59	39	_	_	VSS
73	_	_	_	_	VDD
74	_	_	PTG6	_	_
75	_	_	PTG7	_	_
76	60	40	PTC0	SCL1	_
77	61	41	PTC1	SDA1	_
78	62	42	PTC2	IRO	_
79	63	43	PTC3	TXD2	_
80	64	44	PTC5	RXD2	_



**Table 6. Absolute Maximum Ratings** 

Rating	Symbol	Value	Unit
Supply voltage	$V_{DD}$	-0.3 to + 5.8	V
Input voltage	V <sub>In</sub>	$-0.3$ to $V_{DD} + 0.3$	V
Instantaneous maximum current Single pin limit (applies to all port pins) <sup>1</sup> , <sup>2</sup> , <sup>3</sup>	I <sub>D</sub>	± 25	mA
Maximum current into V <sub>DD</sub>	I <sub>DD</sub>	120	mA
Storage temperature	T <sub>stg</sub>	-55 to +150	°C
Maximum junction temperature	T <sub>J</sub>	150	°C

Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V<sub>DD</sub>) and negative (V<sub>SS</sub>) clamp voltages, then use the larger of the two resistance values.

### 2.3 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and it is user-determined rather than being controlled by the MCU design. To take  $P_{I/O}$  into account in power calculations, determine the difference between actual pin voltage and  $V_{SS}$  or  $V_{DD}$  and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and  $V_{SS}$  or  $V_{DD}$  is small.

**Table 7. Thermal Characteristics** 

Rating		Symbol	Value	Unit
Operating temperature range (packaged)		T <sub>A</sub>	-40 to +105	°C
Thermal resistance 1,2,3,4				
80-pin LQFP				
	1s		52	
	2s2p		40	
64-pin LQFP				
	1s		65	
	2s2p	$\theta_{\sf JA}$	47	°C/W
64-pin QFP				
	1s		54	
	2s2p		40	
44-pin LQFP				
	1s		69	
	2s2p		48	

Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.

 $<sup>^{2}</sup>$  All functional non-supply pins are internally clamped to  $V_{SS}$  and  $V_{DD}$ .

Power supply must maintain regulation within operating V<sub>DD</sub> range during instantaneous and operating maximum current conditions. If positive injection current (V<sub>In</sub> > V<sub>DD</sub>) is greater than I<sub>DD</sub>, the injection current may flow out of V<sub>DD</sub> and could result in external power supply going out of regulation. Ensure external V<sub>DD</sub> load shunt current is greater than maximum injection current. This is the greatest risk when the MCU is not consuming power. Examples: if no system clock is present or if the clock rate is low, which would reduce overall power consumption.

Junction to Ambient Natural Convection



Table 9. ESD and Latch-Up Protection Characteristics

Num	Rating	Symbol	Min	Max	Unit
1	Human Body Model (HBM)	$V_{HBM}$	+/- 2000	1	V
2	Charge Device Model (CDM)	V <sub>CDM</sub>	+/- 500	_	V
3	Latch-up Current at T <sub>A</sub> = 105°C	I <sub>LAT</sub>	+/- 100	_	mA

## 2.5 DC Characteristics

This section includes information about power supply requirements, I/O pin characteristics, and power supply current in various operating modes.

**Table 10. DC Characteristics** 

Num	С	Parameter	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1		Operating voltage <sup>2</sup>		2.7	_	5.5	V
	0	Output high voltage — Low Drive (PTxDSn = 0) 5 V, I <sub>Load</sub> = -4 mA 3 V, I <sub>Load</sub> = -2 mA 5 V, I <sub>Load</sub> = -2 mA 3 V, I <sub>Load</sub> = -1 mA	V	V <sub>DD</sub> - 1.5 V <sub>DD</sub> - 1.5 V <sub>DD</sub> - 0.8 V <sub>DD</sub> - 0.8			
2	Р	Output high voltage — High Drive (PTxDSn = 1) 5 V, I <sub>Load</sub> = -15 mA 3 V, I <sub>Load</sub> = -8 mA 5 V, I <sub>Load</sub> = -8 mA 3 V, I <sub>Load</sub> = -4 mA	V <sub>ОН</sub>	$V_{DD} - 1.5$ $V_{DD} - 1.5$ $V_{DD} - 0.8$ $V_{DD} - 0.8$		1111	V
3	Р	Output low voltage — Low Drive (PTxDSn = 0) 5 V, I <sub>Load</sub> = 4mA 3 V, I <sub>Load</sub> = 2 mA 5 V, I <sub>Load</sub> = 2 mA 3 V, I <sub>Load</sub> = 1 mA	V <sub>OL</sub>		_ _ _ _	1.5 1.5 0.8 0.8	V
		Output low voltage — High Drive (PTxDSn = 1) 5 V, I <sub>Load</sub> = 15 mA 3 V, I <sub>Load</sub> = 8 mA 5 V, I <sub>Load</sub> = 8 mA 3 V, I <sub>Load</sub> = 4 mA			_ _ _ _	1.5 1.5 0.8 0.8	
4	P	Output high current — Max total I <sub>OH</sub> for all ports 5V 3V	I <sub>OHT</sub>			100 60	mA
5	Р	Output low current — Max total I <sub>OL</sub> for all ports 5V 3V	I <sub>OLT</sub>	_ _	_	100 60	mA
6	Р	Input high voltage; all digital inputs					
		$V_{DD} = 5V$ $V_{DD} = 3V$	V <sub>IH</sub>	3.25 2.10	_ _	_ _	V



## 2.7 Analog Comparator (ACMP) Electricals

**Table 12. Analog Comparator Electrical Specifications** 

Num	С	Rating	Symbol	Min	Typical	Max	Unit
1		Supply voltage	$V_{DD}$	2.7	_	5.5	V
2		Supply current (active)	I <sub>DDAC</sub>	_	20	35	μΑ
3		Analog input voltage	V <sub>AIN</sub>	V <sub>SS</sub> - 0.3	_	$V_{DD}$	V
4		Analog input offset voltage	V <sub>AIO</sub>		20	40	mV
5		Analog Comparator hysteresis	V <sub>H</sub>	3.0	6.0	20.0	mV
6		Analog input leakage current	I <sub>ALKG</sub>			1.0	μА
7		Analog Comparator initialization delay	t <sub>AINIT</sub>	_		1.0	μS
8		Bandgap Voltage Reference Factory trimmed at V <sub>DD</sub> = 3.0 V, Temp = 25°C	$V_{BG}$	1.19	1.20	1.21	V

## 2.8 ADC Characteristics

Table 13. 5 Volt 12-bit ADC Operating Conditions

Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
Absolute	V <sub>DDA</sub>	2.7	_	5.5	V	
Delta to V <sub>DD</sub> (V <sub>DD</sub> -V <sub>DDA</sub> ) <sup>2</sup>	$\Delta V_{DDA}$	-100	0	+100	mV	
Delta to V <sub>SS</sub> (V <sub>SS</sub> -V <sub>SSA</sub> ) <sup>2</sup>	ΔV <sub>SSA</sub>	-100	0	+100	mV	
	V <sub>REFH</sub>	2.7	$V_{DDA}$	$V_{DDA}$	V	
	V <sub>REFL</sub>	V <sub>SSA</sub>	$V_{SSA}$	V <sub>SSA</sub>	V	
	V <sub>ADIN</sub>	V <sub>REFL</sub>	_	V <sub>REFH</sub>	V	
	C <sub>ADIN</sub>	_	4.5	5.5	pF	
	R <sub>ADIN</sub>	_	3	5	kΩ	
12 bit mode f <sub>ADCK</sub> > 4MHz f <sub>ADCK</sub> < 4MHz	R <sub>AS</sub>	_	_	2 5	kΩ	External to MCU
10 bit mode f <sub>ADCK</sub> > 4MHz f <sub>ADCK</sub> < 4MHz		_	_	5 10		
8 bit mode (all valid f <sub>ADCK</sub> )	1	_	_	10		
High Speed (ADLPC=0)	f <sub>ADCK</sub>	0.4	_	8.0	MHz	
Low Power (ADLPC=1)	1	0.4	_	4.0		
	Absolute  Delta to V <sub>DD</sub> (V <sub>DD</sub> -V <sub>DDA</sub> ) <sup>2</sup> Delta to V <sub>SS</sub> (V <sub>SS</sub> -V <sub>SSA</sub> ) <sup>2</sup> 12 bit mode  f <sub>ADCK</sub> > 4MHz f <sub>ADCK</sub> < 4MHz  10 bit mode f <sub>ADCK</sub> > 4MHz f <sub>ADCK</sub> < 4MHz  8 bit mode (all valid f <sub>ADCK</sub> )  High Speed (ADLPC=0)	Absolute $V_{DDA}$ Delta to $V_{DD}$ ( $V_{DD}$ - $V_{DDA}$ ) <sup>2</sup> $\Delta V_{DDA}$ Delta to $V_{SS}$ ( $V_{SS}$ - $V_{SSA}$ ) <sup>2</sup> $\Delta V_{SSA}$ $V_{REFH}$ $V_{ADIN}$ Cadin  12 bit mode $f_{ADCK} > 4MHz$ $f_{ADCK} < 4MHz$ 10 bit mode $f_{ADCK} > 4MHz$ $f_{ADCK} < 4MHz$ 8 bit mode (all valid $f_{ADCK}$ )  High Speed (ADLPC=0) $f_{ADCK}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$

Typical values assume V<sub>DDA</sub> = 5.0V, Temp = 25°C, f<sub>ADCK</sub>=1.0MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>&</sup>lt;sup>2</sup> DC potential difference.



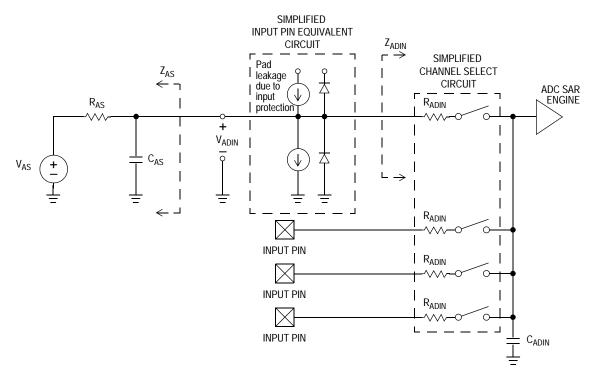


Figure 9. ADC Input Impedance Equivalency Diagram

Table 14. 5 Volt 12-bit ADC Characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ )

Characteristic	Conditions	С	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
Supply Current ADLPC=1 ADLSMP=1 ADCO=1		Т	I <sub>DDAD</sub>		133		μА	
Supply Current ADLPC=1 ADLSMP=0 ADCO=1		Т	I <sub>DDAD</sub>	_	218	_	μА	
Supply Current ADLPC=0 ADLSMP=1 ADCO=1		Т	I <sub>DDAD</sub>	_	327	_	μА	
Supply Current ADLPC=0 ADLSMP=0 ADCO=1		Р	I <sub>DDAD</sub>		0.582	1	mA	
Supply Current	Stop, Reset, Module Off		I <sub>DDAD</sub>	_	0.011	1	μА	
ADC	High Speed (ADLPC=0)	Т	f <sub>ADACK</sub>	2	3.3	5	MHz	t <sub>ADACK</sub> =
Asynchronous Clock Source	Low Power (ADLPC=1)			1.25	2	3.3		1/f <sub>ADACK</sub>



## 2.10 MCG Specifications

**Table 16. MCG Frequency Specifications (Temperature Range = −40 to 125°C Ambient)** 

Num	С	Rat	Symbol	Min	Typical <sup>1</sup>	Max	Unit	
1	Р	Internal reference frequenc = 5 V and temperature = 25	f <sub>int_ft</sub>	_	32.768	_	kHz	
2	Р	Average internal reference	frequency – untrimmed	f <sub>int_ut</sub>	31.25	_	39.0625	kHz
3	Т	Internal reference startup ti	me	t <sub>irefst</sub>	_	60	100	μS
	Р	DCO output frequency	Low range (DRS=00)		16	_	20	
4	Р	range - untrimmed <sup>2</sup>	Mid range (DRS=01)	f <sub>dco_ut</sub>	32	_	40	MHz
	Р		High range (DRS=10)		48	_	60	
	Р	DCO output frequency <sup>2</sup>	Low range (DRS=00)		_	19.92	_	
5	Р	Reference =32768Hz	Mid range (DRS=01)	f <sub>dco_DMX32</sub>	_	39.85	_	MHz
	Р	and DMX32 = 1	High range (DRS=10)		_	59.77	_	
6	D	Resolution of trimmed DCC voltage and temperature (u		$\Delta f_{dco\_res\_t}$	_	±0.1	±0.2	%f <sub>dco</sub>
7	D	Resolution of trimmed DCC voltage and temperature (n		Δf <sub>dco_res_t</sub>	_	±0.2	±0.4	%f <sub>dco</sub>
8	D	Total deviation of trimmed DCO output frequency over voltage and temperature		$\Delta f_{dco\_t}$	_	0.5 -1.0	±2	%f <sub>dco</sub>
9	D	Total deviation of trimmed DCO output frequency over fixed voltage and temperature range of 0 – 70 °C		$\Delta f_{dco\_t}$	_	±0.5	±1	%f <sub>dco</sub>
10	D	FLL acquisition time <sup>3</sup>		t <sub>fll_acquire</sub>	_	_	1	ms
11	D	PLL acquisition time <sup>4</sup>		t <sub>pll_acquire</sub>	_	_	1	ms
12	D	Long term Jitter of DCO ou 2ms interval) <sup>5</sup>	tput clock (averaged over	C <sub>Jitter</sub>	_	0.02	0.2	%f <sub>dco</sub>
13	D	VCO operating frequency		f <sub>vco</sub>	7.0	_	55.0	MHz
14	D	Jitter of PLL output clock m	easured over 625 ns <sup>6</sup>	f <sub>pll_jitter_625ns</sub>	_	0.566 <sup>5</sup>	_	%f <sub>pll</sub>
15	D	Lock entry frequency tolera	nce <sup>7</sup>	D <sub>lock</sub>	±1.49	_	±2.98	%
16	D	Lock exit frequency toleran	ce <sup>8</sup>	D <sub>unl</sub>	±4.47	_	±5.97	%
17	D	Lock time — FLL		t <sub>fil_lock</sub>	_	l	t <sub>fll_acquire+</sub> 1075(1/fint_t )	s
18	D	Lock time — PLL		t <sub>pll_lock</sub>	_	_	t <sub>pll_acquire+</sub> 1075(1/ <sup>f</sup> pll_r ef)	s
19	D	Loss of external clock minir = 0	mum frequency – RANGE	f <sub>loc_low</sub>	(3/5) x f <sub>int</sub>	_	_	kHz
4								

<sup>&</sup>lt;sup>1</sup> Data in Typical column was characterized at 5.0 V, 25C or is typical recommended value

<sup>&</sup>lt;sup>2</sup> The resulting bus clock frequency should not exceed the maximum specified bus clock frequency of the device.

This specification applies to any time the FLL reference source or reference divider is changed, trim value changed or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

<sup>&</sup>lt;sup>4</sup> This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.



- Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f<sub>BUS</sub>. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V<sub>DD</sub> and V<sub>SS</sub> and variation in crystal oscillator frequency increase the C<sub>Jitter</sub> percentage for a given interval.
- 6 625 ns represents 5 time quanta for CAN applications, under worst case conditions of 8 MHz CAN bus clock, 1 Mbps CAN bus speed, and 8 time quanta per bit for bit time settings. 5 time quanta is the minimum time between a synchronization edge and the sample point of a bit using 8 time quanta per bit.
- Below D<sub>lock</sub> minimum, the MCG is guaranteed to enter lock. Above D<sub>lock</sub> maximum, the MCG will not enter lock. But if the MCG is already in lock, then the MCG may stay in lock.
- <sup>8</sup> Below D<sub>unl</sub> minimum, the MCG will not exit lock if already in lock. Above D<sub>unl</sub> maximum, the MCG is guaranteed to exit lock.

### 2.11 AC Characteristics

This section describes ac timing characteristics for each peripheral system.

## 2.11.1 Control Timing

**Table 17. Control Timing** 

Num	С	Parameter	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1		Bus frequency (t <sub>cyc</sub> = 1/f <sub>Bus</sub> )	f <sub>Bus</sub>	dc	_	24	MHz
2		Internal low-power oscillator period	t <sub>LPO</sub>	700		1300	μS
3		External reset pulse width <sup>2</sup> (t <sub>cyc</sub> = 1/f <sub>Self_reset</sub> )	t <sub>extrst</sub>	100		_	ns
4		Reset low drive	t <sub>rstdrv</sub>	66 x t <sub>cyc</sub>		_	ns
5		Active background debug mode latch setup time	t <sub>MSSU</sub>	500		_	ns
6		Active background debug mode latch hold time	t <sub>MSH</sub>	100		_	ns
7		IRQ pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>3</sup>	t <sub>ILIH,</sub> t <sub>IHIL</sub>	100 1.5 x t <sub>cyc</sub>	_	_	ns
8		KBIPx pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>3</sup>	t <sub>ILIH,</sub> t <sub>IHIL</sub>	100 1.5 x t <sub>cyc</sub>	_	_	ns
9		Port rise and fall time (load = 50 pF) <sup>4</sup> Slew rate control disabled (PTxSE = 0) High drive Slew rate control enabled (PTxSE = 1) High drive Slew rate control disabled (PTxSE = 0) Low drive Slew rate control enabled (PTxSE = 1) Low drive	<sup>t</sup> Rise <sup>, t</sup> Fall		11 35 40 75		ns

Typical values are based on characterization data at V<sub>DD</sub> = 5.0V, 25°C unless otherwise stated.

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<sup>&</sup>lt;sup>2</sup> This is the shortest pulse guaranteed to be recognized as a reset pin request. Shorter pulses are not guaranteed to override reset requests from internal sources.

<sup>&</sup>lt;sup>3</sup> This is the minimum pulse width guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

 $<sup>^4</sup>$  Timing is shown with respect to 20%  $\rm V_{DD}$  and 80%  $\rm V_{DD}$  levels. Temperature range –40°C to 105°C.



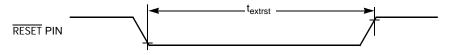


Figure 10. Reset Timing

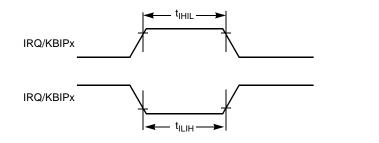


Figure 11. IRQ/KBIPx Timing

## 2.11.2 Timer/PWM (TPM) Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

**Table 18. TPM Input Timing** 

NUM	С	Function	Symbol	Min	Max	Unit
1	_	External clock frequency	f <sub>TPMext</sub>	dc	f <sub>Bus</sub> /4	MHz
2	_	External clock period	t <sub>TPMext</sub>	4	_	t <sub>cyc</sub>
3	D	External clock high time	t <sub>clkh</sub>	1.5	_	t <sub>cyc</sub>
4	D	External clock low time	t <sub>clkl</sub>	1.5	_	t <sub>cyc</sub>
5	D	Input capture pulse width	t <sub>ICPW</sub>	1.5	_	t <sub>cyc</sub>

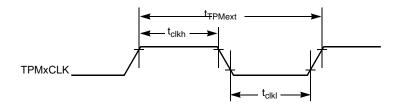
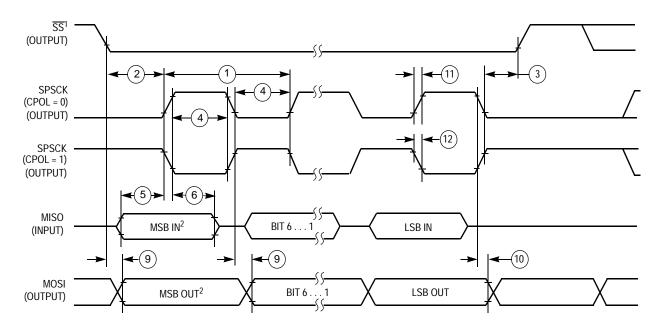


Figure 12. Timer External Clock

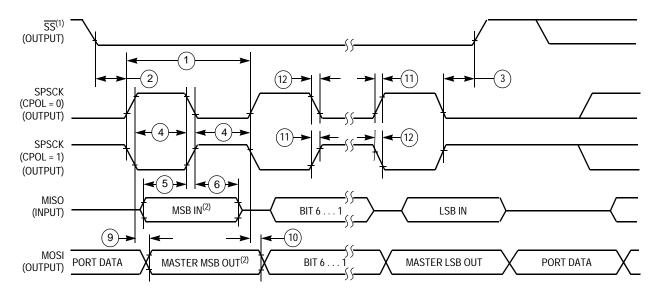




#### NOTES:

- 1.  $\overline{SS}$  output mode (DDS7 = 1, SSOE = 1).
- 2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 14. SPI Master Timing (CPHA = 0)



#### NOTES:

- 1.  $\overline{SS}$  output mode (DDS7 = 1, SSOE = 1).
- 2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 15. SPI Master Timing (CPHA = 1)



## 2.13 Flash Specifications

This section provides details about program/erase times and program-erase endurance for the Flash memory.

Program and erase operations do not require any special power sources other than the normal V<sub>DD</sub> supply.

**Table 21. Flash Characteristics** 

Num	С	Characteristic	Symbol	Min	Typ <sup>1</sup>	Max	Unit
1		Supply voltage for program/erase	V <sub>prog/erase</sub>	2.7		5.5	V
2		Supply voltage for read operation	V <sub>Read</sub>	2.7		5.5	V
3		Internal FCLK frequency <sup>2</sup>	f <sub>FCLK</sub>	150		200	kHz
4		Internal FCLK period (1/FCLK)	t <sub>Fcyc</sub>	5		6.67	μS
5		Byte program time (random location) <sup>(2)</sup>	t <sub>prog</sub>	9		t <sub>Fcyc</sub>	
6		Byte program time (burst mode) <sup>(2)</sup>	t <sub>Burst</sub>	4		t <sub>Fcyc</sub>	
7		Page erase time <sup>3</sup>	t <sub>Page</sub>	4000		t <sub>Fcyc</sub>	
8		Mass erase time <sup>(2)</sup>	t <sub>Mass</sub>	20,000		t <sub>Fcyc</sub>	
9	С	Program/erase endurance <sup>4</sup> T <sub>L</sub> to T <sub>H</sub> = -40°C to + 105°C T = 25°C		10,000	 100,000	_	cycles
10		Data retention <sup>5</sup>	t <sub>D_ret</sub>	15	100	_	years

<sup>&</sup>lt;sup>1</sup> Typical values are based on characterization data at V<sub>DD</sub> = 5.0 V, 25°C unless otherwise stated.

## 2.14 USB Electricals

The USB electricals for the USBOTG module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit http://www.usb.org.

If the Freescale USBOTG implementation requires additional or deviant electrical characteristics, this space would be used to communicate that information.

<sup>&</sup>lt;sup>2</sup> The frequency of this clock is controlled by a software setting.

These values are hardware state machine controlled. User code does not need to count cycles. This information supplied for calculating approximate time to program and erase.

<sup>&</sup>lt;sup>4</sup> Typical endurance for Flash was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale Semiconductor defines typical endurance, please refer to Engineering Bulletin EB619/D, *Typical Endurance for Nonvolatile Memory.* 

Typical data retention values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25°C using the Arrhenius equation. For additional information on how Freescale Semiconductor defines typical data retention, please refer to Engineering Bulletin EB618/D, Typical Data Retention for Nonvolatile Memory.

0.5

35



	Symbol	Unit	Min	Тур	Max
Regulator operating voltage	V <sub>regin</sub>	V	3.9	_	5.5
Vreg output	V <sub>regout</sub>	V	3	3.3	3.6
Vusb33 input with internal Vreg disabled	V <sub>usb33in</sub>	V	3	3.3	3.6

 $I_{VRQ}$ 

mΑ

Table 22. Internal USB 3.3V Voltage Regulator Characteristics

### 2.15 EMC Performance

**VREG Quiescent Current** 

Electromagnetic compatibility (EMC) performance is highly dependant on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 for advice and guidance specifically targeted at optimizing EMC performance.

### 2.15.1 Radiated Emissions

Microcontroller radiated RF emissions are measured from 150 kHz to 1 GHz using the TEM/GTEM Cell method in accordance with the IEC 61967-2 and SAE J1752/3 standards. The measurement is performed with the microcontroller installed on a custom EMC evaluation board while running specialized EMC test software. The radiated emissions from the microcontroller are measured in a TEM cell in two package orientations (North and East). For more detailed information concerning the evaluation results, conditions and setup, please refer to the EMC Evaluation Report for this device.

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# **3 Mechanical Outline Drawings**

## 3.1 80-pin LQFP

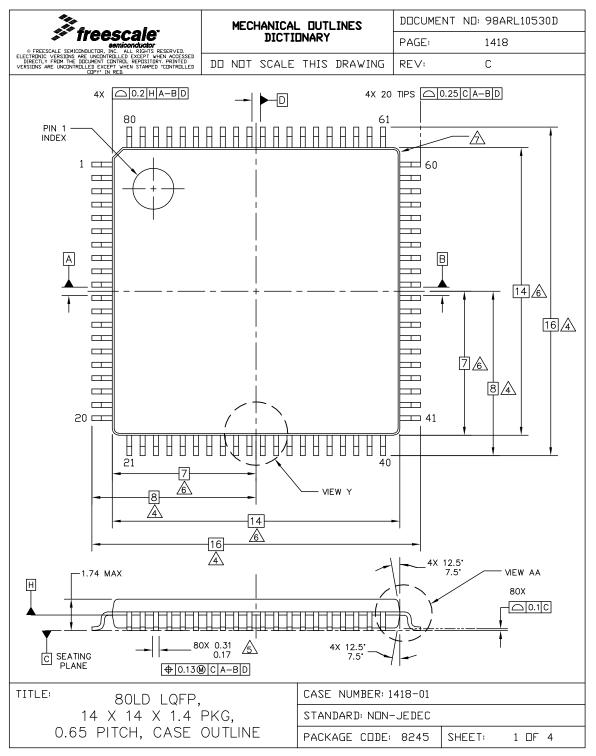


Figure 18. 80-pin LQFP Diagram - I

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## 3.2 64-pin LQFP

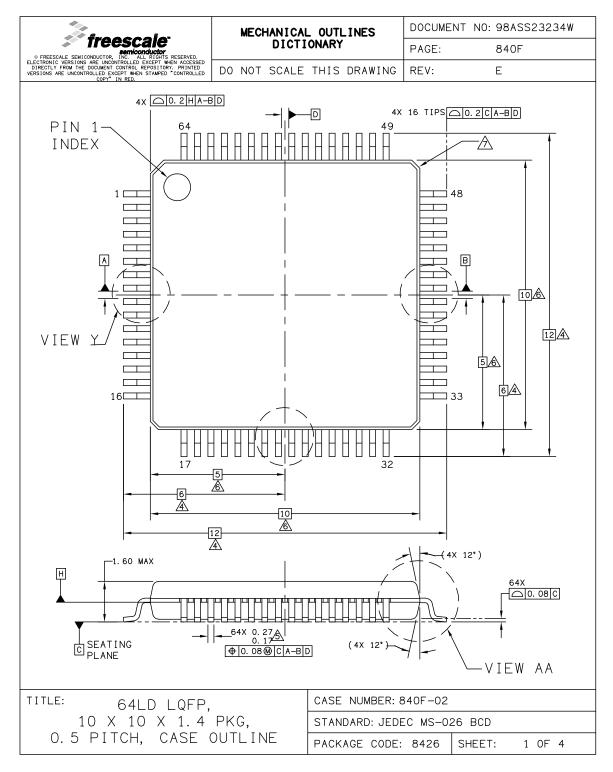


Figure 21. 64-pin LQFP Diagram - I



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#### NOTES:

- 1. DIMENSIONS ARE IN MILLIMETERS.
- 2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
- 3. DATUMS A, B AND D TO BE DETERMINED AT DATUM PLANE H.
- $\stackrel{\textstyle \wedge}{\triangle}$  dimensions to be determined at seating plane c.
- THIS DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE UPPER LIMIT BY MORE THAN 0.08 mm AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD SHALL NOT BE LESS THAN 0.07 mm.
- THIS DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 mm PER SIDE. THIS DIMENSION IS MAXIMUM PLASTIC BODY SIZE DIMENSION INCLUDING MOLD MISMATCH.
- A EXACT SHAPE OF EACH CORNER IS OPTIONAL.
- A THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.1 mm AND 0.25 mm FROM THE LEAD TIP.

TITLE: 64LD LQFP,
10 X 10 X 1. 4 PKG,
0. 5 PITCH, CASE OUTLINE

CASE NUMBER: 840F-02

STANDARD: JEDEC MS-026 BCD

PACKAGE CODE: 8426 SHEET: 3

Figure 23. 64-pin LQFP Diagram - III



### **Revision History**

# 4 Revision History

This section lists major changes between versions of the MCF51JM128 Data Sheet document.

**Table 23. Changes Between Revisions** 

Revision	Description
1	Updated features list Updated the figures Typical Low-side Drive (sink) characteristics – High Drive (PTxDSn = 1), Typical Low-side Drive (sink) characteristics – Low Drive (PTxDSn = 0), and Typical High-side Drive (source) characteristics – High Drive (PTxDSn = 1) Added the figure Typical High-side Drive (source) characteristics – Low Drive (PTxDSn = 0) Updated the table Supply Current Characteristics Updated the table Oscillator Electrical Specifications (Temperature Range = –40 to 105xC Ambient) Updated the table SPI Electrical Characteristic, DC Characteristics
2	Updated the table Orderable Part Number Summary, DC Characteristics, and Supply Current Characteristics
3	Updated the table Orderable Part Number Summary, MCG Characteristics, SPI Characteristics, and Supply Current Characteristics Changed V <sub>DDAD</sub> to V <sub>DDA</sub> , V <sub>SSAD</sub> to V <sub>SSA</sub> Updated the table Device comparison
4	Added "RAM retention voltage" parameter in "DC Characteristics" table, alongwith a table note.  Added "Temp sensor voltage" parameter in "5 Volt 12-bit ADC Characteristics (V <sub>REFH</sub> = V <sub>DDA</sub> , V <sub>REFL</sub> = V <sub>SSA</sub> )" table.  Added "Temp sensor slope" parameter in 5 Volt 12-bit ADC Characteristics (V <sub>REFH</sub> = V <sub>DDA</sub> , V <sub>REFL</sub> = V <sub>SSA</sub> ) table. Also, corrected unit of "Temp sensor voltage" parameter in 5 Volt 12-bit ADC Characteristics (V <sub>REFH</sub> = V <sub>DDA</sub> , V <sub>REFL</sub> = V <sub>SSA</sub> ) table.



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