

Welcome to **E-XFL.COM**

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

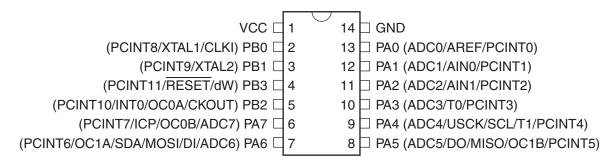
Details	
Product Status	Active
Core Processor	AVR
Core Size	8-Bit
Speed	20MHz
Connectivity	USI
Peripherals	Brown-out Detect/Reset, POR, PWM, Temp Sensor, WDT
Number of I/O	12
Program Memory Size	2KB (1K x 16)
Program Memory Type	FLASH
EEPROM Size	128 x 8
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-WFQFN Exposed Pad
Supplier Device Package	20-QFN-EP (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/attiny24-20mu



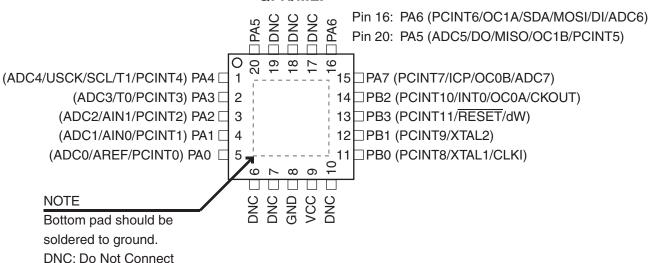
1. Pin Configurations

Figure 1-1. Pinout ATtiny24/44/84

PDIP/SOIC



QFN/MLF



1.1 Pin Descriptions

1.1.1 VCC

Supply voltage.

1.1.2 GND

Ground.

1.1.3 Port B (PB3:PB0)

Port B is a 4-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability except PB3 which has the RESET capability. To use pin PB3 as an I/O pin, instead of RESET pin, program ('0') RSTDISBL fuse. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B also serves the functions of various special features of the ATtiny24/44/84 as listed in Section 10.2 "Alternate Port Functions" on page 58.

1.1.4 **RESET**

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running and provided the reset pin has not been disabled. The minimum pulse length is given in Table 20-4 on page 177. Shorter pulses are not guaranteed to generate a reset.

The reset pin can also be used as a (weak) I/O pin.

1.1.5 Port A (PA7:PA0)

Port A is a 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port A pins that are externally pulled low will source current if the pull-up resistors are activated. The Port A pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port A has alternate functions as analog inputs for the ADC, analog comparator, timer/counter, SPI and pin change interrupt as described in "Alternate Port Functions" on page 58.



The ATtiny24/44/84 provides the following features: 2/4/8K byte of In-System Programmable Flash, 128/256/512 bytes EEPROM, 128/256/512 bytes SRAM, 12 general purpose I/O lines, 32 general purpose working registers, an 8-bit Timer/Counter with two PWM channels, a 16-bit timer/counter with two PWM channels, Internal and External Interrupts, a 8-channel 10-bit ADC, programmable gain stage (1x, 20x) for 12 differential ADC channel pairs, a programmable Watchdog Timer with internal oscillator, internal calibrated oscillator, and four software selectable power saving modes. Idle mode stops the CPU while allowing the SRAM, Timer/Counter, ADC, Analog Comparator, and Interrupt system to continue functioning. ADC Noise Reduction mode minimizes switching noise during ADC conversions by stopping the CPU and all I/O modules except the ADC. In Power-down mode registers keep their contents and all chip functions are disbaled until the next interrupt or hardware reset. In Standby mode, the crystal/resonator oscillator is running while the rest of the device is sleeping, allowing very fast start-up combined with low power consumption.

The device is manufactured using Atmel's high density non-volatile memory technology. The onchip ISP Flash allows the Program memory to be re-programmed in-system through an SPI serial interface, by a conventional non-volatile memory programmer or by an on-chip boot code running on the AVR core.

The ATtiny24/44/84 AVR is supported with a full suite of program and system development tools including: C Compilers, Macro Assemblers, Program Debugger/Simulators and Evaluation kits.





3. About

3.1 Resources

A comprehensive set of drivers, application notes, data sheets and descriptions on development tools are available for download at http://www.atmel.com/avr.

3.2 Code Examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C compiler documentation for more details.

For I/O Registers located in the extended I/O map, "IN", "OUT", "SBIS", "SBIC", "CBI", and "SBI" instructions must be replaced with instructions that allow access to extended I/O. Typically, this means "LDS" and "STS" combined with "SBRS", "SBRC", "SBR", and "CBR". Note that not all AVR devices include an extended I/O map.

3.3 Data Retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C or 100 years at 25°C.

3.4 Disclaimer

Typical values contained in this datasheet are based on simulations and characterization of other AVR microcontrollers manufactured on the same process technology.

4. Register Summary

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page	
0x3F (0x5F)	SREG	I	Т	Н	S	V	N	Z	С	Page 8	
0x3E (0x5E)	SPH	-	_	_	_	_		SP9	SP8	Page 11	
0x3D (0x5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	Page 11	
0x3C (0x5C)	OCR0B			Timer/	Counter0 - Outp	out Compare Rec	gister B			Page 85	
0x3B (0x5B)	GIMSK	-	INT0	PCIE1	PCIE0	_	_	-	-	Page 51	
0x3A (0x5A	GIFR	-	INTF0	PCIF1	PCIF0	-	-	-	-	Page 52	
0x39 (0x59)	TIMSK0	_	-	_	_	_	OCIE0B	OCIE0A	TOIE0	Page 85	
0x38 (0x58)	TIFR0		-	-	-	-	OCF0B	OCF0A	TOV0	Page 85	
0x37 (0x57)	SPMCSR	-	-	RSIG	СТРВ	RFLB	PGWRT	PGERS	SPMEN	Page 157	
0x36 (0x56)	OCR0A		•			out Compare Rec				Page 84	
0x35 (0x55)	MCUCR	BODS	PUD	SE	SM1	SM0	BODSE	ISC01	ISC00	Pages 36, 51, and 67	
0x34 (0x54)	MCUSR	-	-	_	-	WDRF	BORF	EXTRF	PORF	Page 45	
0x33 (0x53)	TCCR0B	FOC0A	FOC0B	_	-	WGM02	CS02	CS01	CS00	Page 83	
0x32 (0x52)	TCNT0	0417	041.0	0415		Counter0	0410			Page 84	
0x31 (0x51)	OSCCAL	CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0	Page 30	
0x30 (0x50)	TCCR0A	COM0A1	COM0A0	COM0B1	COM0B0	_		WGM01	WGM00	Page 80	
0x2F (0x4F) 0x2E (0x4E)	TCCR1A TCCR1B	COM1A1 ICNC1	COM1A0 ICES1	COM1B1	COM1B0 WGM13	WGM12	CS12	WGM11 CS11	WGM10 CS10	Page 108 Page 110	
0x2D (0x4D)	TCNT1H	ICNCT	ICEST			nter Register Hig		CSTI	0310	Page 112	
0x2C (0x4C)	TCNT1L					nter Register Lo	•			Page 112	
0x2B (0x4B)	OCR1AH					are Register A F				Page 112	
0x2A (0x4A)	OCR1AL					are Register A L	<u> </u>			Page 112	
0x29 (0x49)	OCR1BH					are Register B F				Page 112	
0x28 (0x48)	OCR1BL					are Register B L	• •			Page 112	
0x27 (0x47)	DWDR					R[7:0]				Page 152	
0x26 (0x46)	CLKPR	CLKPCE	-	_	-	CLKPS3	CLKPS2	CLKPS1	CLKPS0	Page 31	
0x25 (0x45)	ICR1H			Timer/Co	unter1 - Input C	apture Register	High Byte	•	•	Page 113	
0x24 (0x44)	ICR1L			Timer/Co	ounter1 - Input C	apture Register	Low Byte			Page 113	
0x23 (0x43)	GTCCR	TSM	-	_	-	-	_	-	PSR10	Page 116	
0x22 (0x42)	TCCR1C	FOC1A	FOC1B	_	-	-	-	_	-	Page 111	
0x21 (0x41)	WDTCSR	WDIF	WDIE	WDP3	WDCE	WDE	WDP2	WDP1	WDP0	Page 45	
0x20 (0x40)	PCMSK1	-	_	_	-	PCINT11	PCINT10	PCINT9	PCINT8	Page 52	
0x1F (0x3F)	EEARH	-	-	-	-	-	-	_	EEAR8	Page 20	
0x1E (0x3E)	EEARL	EEAR7	EEAR6	EEAR5	EEAR4	EEAR3	EEAR2	EEAR1	EEAR0	Page 21	
0x1D (0x3D)	EEDR			T		ata Register		T	T	Page 21	
0x1C (0x3C)	EECR	-	-	EEPM1	EEPM0	EERIE	EEMPE	EEPE	EERE	Page 21	
0x1B (0x3B)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	Page 67	
0x1A (0x3A)	DDRA PINA	DDA7 PINA7	DDA6 PINA6	DDA5 PINA5	DDA4 PINA4	DDA3 PINA3	DDA2 PINA2	DDA1 PINA1	DDA0 PINA0	Page 67	
0x19 (0x39) 0x18 (0x38)	PORTB	FINA/	FINAO	CANIT	FINA4	PORTB3	PORTB2	PORTB1	PORTB0	Page 68 Page 68	
0x17 (0x37)	DDRB	_	_	_	_	DDB3	DDB2	DDB1	DDB0	Page 68	
0x16 (0x36)	PINB	_		_	_	PINB3	PINB2	PINB1	PINB0	Page 68	
0x15 (0x35)	GPIOR2				General Purpos	se I/O Register 2		1 11101	1 11450	Page 23	
0x14 (0x34)	GPIOR1					se I/O Register 1				Page 23	
0x13 (0x33)	GPIOR0					pose I/O Register 0				Page 23	
0x12 (0x32)	PCMSK0	PCINT7	PCINT6	PCINT5	PCINT4	PCINT3	PCINT2	PCINT1	PCINT0	Page 53	
0x11 (0x31))	Reserved					-		•	•		
0x10 (0x30)	USIBR		USI Buffer Register						Page 125		
0x0F (0x2F)	USIDR					Register				Page 124	
0x0E (0x2E)	USISR	USISIF	USIOIF	USIPF	USIDC	USICNT3	USICNT2	USICNT1	USICNT0	Page 125	
0x0D (0x2D)	USICR	USISIE	USIOIE	USIWM1	USIWM0	USICS1	USICS0	USICLK	USITC	Page 126	
0x0C (0x2C)	TIMSK1	-	-	ICIE1	-	-	OCIE1B	OCIE1A	TOIE1	Page 113	
0x0B (0x2B)	TIFR1	-	_	ICF1	-	-	OCF1B	OCF1A	TOV1	Page 114	
0x0A (0x2A)	Reserved					-					
0x09 (0x29)	Reserved					-					
0x08 (0x28)	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	Page 130	
0x07 (0x27)	ADMUX	REFS1	REFS0	MUX5	MUX4	MUX3	MUX2	MUX1	MUX0	Page 145	
0x06 (0x26)	ADCSRA	ADEN ADSC ADATE ADIF ADIE ADPS2 ADPS1 ADPS0						Page 147			
0x05 (0x25)	ADCH	ADC Data Register High Byte						Page 149			
0x04 (0x24)	ADCL		40			gister Low Byte	4===:	1	1 4===:	Page 149	
0x03 (0x23)	ADCSRB	BIN	ACME	_	ADLAR	_	ADTS2	ADTS1	ADTS0	Page 131, Page 149	
0x02 (0x22)	Reserved	AD075	ADOCD	ADOED	ADO/5	AD000	ADOCD	ADOCE	ADOCD	Dage 404 D- 450	
0x01 (0x21)	DIDR0	ADC7D	ADC6D	ADC5D	ADC4D	ADC3D	ADC2D	ADC1D	ADC0D	Page 131, Page 150	
0x00 (0x20)	PRR	_	-	_	_	PRTIM1	PRTIM0	PRUSI	PRADC	Page 37	





Note:

- 1. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
- 2. I/O Registers within the address range 0x00 0x1F are directly bit-accessible using the SBI and CBI instructions. In these registers, the value of single bits can be checked by using the SBIS and SBIC instructions.
- 3. Some of the Status Flags are cleared by writing a logical one to them. Note that, unlike most other AVRs, the CBI and SBI instructions will only operation the specified bit, and can therefore be used on registers containing such Status Flags. The CBI and SBI instructions work with registers 0x00 to 0x1F only.



Mnemonics	Operands	Description	Operation	Flags	#Clocks
ROR	Rd	Rotate Right Through Carry	$Rd(7)\leftarrow C,Rd(n)\leftarrow Rd(n+1),C\leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=06$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(30)←Rd(74),Rd(74)←Rd(30)	None	1
BSET	s	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	s	Flag Clear	SREG(s) ← 0	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	Т	1
BLD	Rd, b	Bit load from T to Register	Rd(b) ← T	None	1
SEC		Set Carry	C ← 1	С	1
CLC		Clear Carry	C ← 0	С	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	I ← 1	1	1
CLI		Global Interrupt Disable	1←0	l i	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	T	1
CLT		Clear T in SREG	T ← 0	T	1
SEH		Set Half Carry Flag in SREG	H ← 1	Н	1
CLH		Clear Half Carry Flag in SREG	H ← 0	Н	1
DATA TRANSFER I	NETRICTIONS	Clear Hall Carry Hag III Cried	11 — 0	1 ''	
MOV	Rd, Rr	Move Between Registers	Dd . Dr	None	1
		,	Rd ← Rr Rd+1:Rd ← Rr+1:Rr	None	
MOVW	Rd, Rr	Copy Register Word		None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X), X \leftarrow X + 1$	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1$, $Rd \leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect	Rd ← (Y)	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1$, $Rd \leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, $Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Rd, k	Load Direct from SRAM	Rd ← (k)	None	2
ST	X, Rr	Store Indirect	$(X) \leftarrow Rr$	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	$(X) \leftarrow Rr, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1$, $(X) \leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1$, $(Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	$(Y + q) \leftarrow Rr$	None	2
ST	Z, Rr	Store Indirect	(Z) ← Rr	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	$(Z) \leftarrow Rr, Z \leftarrow Z + 1$	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, $(Z) \leftarrow Rr$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$(Z + q) \leftarrow Rr$	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	R0 ← (Z)	None	3
LPM	Rd, Z	Load Program Memory	Rd ← (Z)	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	3
SPM		Store Program Memory	(z) ← R1:R0	None	
IN	Rd, P	In Port	Rd ← P	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	Rd ← STACK	None	2
MCU CONTROL INS		. Sp. Togistor from Stack	1	110110	
NOP		No Operation		None	1
SLEEP			(see specific descr. for Sleep function)		1
		Sleep Watchdog Roset		None	
WDR		Watchdog Reset	(see specific descr. for WDR/Timer)	None	1 N/A
BREAK	1	Break	For On-chip Debug Only	None	N/A



6.2 ATtiny44

Speed (MHz)	Power Supply	Ordering Code ⁽¹⁾	Package ⁽²⁾	Operational Range
10	1.8 - 5.5V	ATtiny44V-10SSU ATtiny44V-10SSUR ATtiny44V-10PU ATtiny44V-10MU ATtiny44V-10MUR	14S1 14S1 14P3 20M1 20M1	Industrial (-40°C to +85°C) ⁽³⁾
20	2.7 - 5.5 V	ATtiny44-20SSU ATtiny44-20SSUR ATtiny44-20PU ATtiny44-20MU ATtiny44-20MUR	14S1 14S1 14P3 20M1 20M1	Industrial (-40°C to +85°C) ⁽³⁾

Notes: 1. Code indicators:

- U: matte tin

- R: tape & reel

- 2. All packages are Pb-free, halide-free and fully green and they comply with the European directive for Restriction of Hazard-ous Substances (RoHS).
- 3. These devices can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

Package Type						
14-lead, 0.150" Wide Body, Plastic Gull Wing Small Outline Package (SOIC)						
14P3	14-lead, 0.300" Wide, Plastic Dual Inline Package (PDIP)					
20M1	20-pad, 4 x 4 x 0.8 mm Body, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)					

6.3 ATtiny84

Speed (MHz)	Power Supply	Ordering Code ⁽¹⁾	Package ⁽²⁾	Operational Range
10	1.8 - 5.5V	ATtiny84V-10SSU ATtiny84V-10SSUR ATtiny84V-10PU ATtiny84V-10MU ATtiny84V-10MUR	14S1 14S1 14P3 20M1 20M1	Industrial (-40°C to +85°C) ⁽³⁾
20	2.7 - 5.5V	ATtiny84-20SSU ATtiny84-20SSUR ATtiny84-20PU ATtiny84-20MU ATtiny84-20MUR	14S1 14S1 14P3 20M1 20M1	Industrial (-40°C to +85°C) ⁽³⁾

Notes: 1. Code indicators:

- U: matte tin

- R: tape & reel

- 2. All packages are Pb-free, halide-free and fully green and they comply with the European directive for Restriction of Hazard-ous Substances (RoHS).
- 3. These devices can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

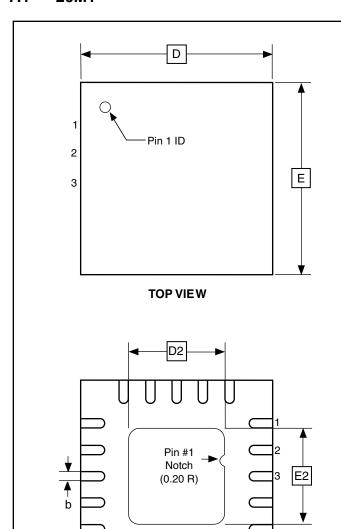
Package Type						
14-lead, 0.150" Wide Body, Plastic Gull Wing Small Outline Package (SOIC)						
14P3	14-lead, 0.300" Wide, Plastic Dual Inline Package (PDIP)					
20M1	20-pad, 4 x 4 x 0.8 mm Body, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)					





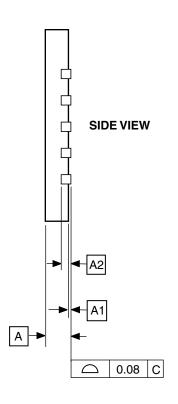
7. Packaging Information

7.1 20M1



←e

Note: Reference JEDEC Standard MO-220, Fig. 1 (SAW Singulation) WGGD-5.



COMMON DIMENSIONS (Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	0.70	0.75	0.80	
A1	-	0.01	0.05	
A2				
b	0.18	0.23	0.30	
D				
D2	2.45	2.60	2.75	
E				
E2	2.45	2.60	2.75	
е				
L	0.35	0.40	0.55	

10/27/04

2325 Orchard Parkway San Jose, CA 95131 **TITLE 20M1**, 20-pad, 4 x 4 x 0.8 mm Body, Lead Pitch 0.50 mm, 2.6 mm Exposed Pad, Micro Lead Frame Package (MLF)

DRAWING NO. REV. 20M1 A

BOTTOM VIEW

8. Errata

The revision letters in this section refer to the revision of the corresponding ATtiny24/44/84 device.

8.1 **ATtiny24**

8.1.1 Rev. D – E

No known errata.

8.1.2 Rev. C

- Reading EEPROM when system clock frequency is below 900 kHz may not work
- Reading EEPROM when system clock frequency is below 900 kHz may not work
 Reading data from the EEPROM at system clock frequency below 900 kHz may result in
 wrong data read.

Problem Fix/Work around

Avoid using the EEPROM at clock frequency below 900 kHz.

8.1.3 Rev. B

- EEPROM read from application code does not work in Lock Bit Mode 3
- Reading EEPROM when system clock frequency is below 900 kHz may not work
- 1. EEPROM read from application code does not work in Lock Bit Mode 3

When the Memory Lock Bits LB2 and LB1 are programmed to mode 3, EEPROM read does not work from the application code.

Problem Fix/Work around

Do not set Lock Bit Protection Mode 3 when the application code needs to read from EEPROM.

2. Reading EEPROM when system clock frequency is below 900 kHz may not work

Reading data from the EEPROM at system clock frequency below 900 kHz may result in wrong data read.

Problem Fix/Work around

Avoid using the EEPROM at clock frequency below 900 kHz.

8.1.4 Rev. A

Not sampled.





8.2 **ATtiny44**

8.2.1 Rev. B – D

No known errata.

8.2.2 Rev. A

- Reading EEPROM when system clock frequency is below 900 kHz may not work
- 1. Reading EEPROM when system clock frequency is below 900 kHz may not work
 Reading data from the EEPROM at system clock frequency below 900 kHz may result in
 wrong data read.

Problem Fix/Work around

Avoid using the EEPROM at clock frequency below 900 kHz.

8.3 ATtiny84

8.3.1 Rev. A – B

No known errata.





9. Datasheet Revision History

Please note that the referring page numbers refer to the complete document.

9.1 Rev K. - 10/10

- 1. Added note for Internal 1.1V Reference in Table 16-4 on page 146.
- 2. Added tape & reel in Section 24. "Ordering Information" on page 217.
- 3. Updated last page.

9.2 Rev J. - 08/10

- 1. Updated Section 6.4 "Clock Output Buffer" on page 30, changed CLKO to CKOUT.
- 2. Removed text "Not recommended for new design" from cover page.

9.3 Rev I. - 06/10

- 1. Removed "Preliminary" from cover page.
- 2. Updated notes in Table 19-16, "High-voltage Serial Programming Instruction Set for ATtiny24/44/84," on page 171.
- 3. Added clarification before Table 6-8, "Capacitance for the Low-Frequency Crystal Oscillator," on page 28.
- 4. Updated some table notes in Section 20. "Electrical Characteristics" on page 174.

9.4 Rev H. 10/09

- 1. Updated document template. Re-arranged some sections.
- 2. Updated "Low-Frequency Crystal Oscillator" with the Table 6-8 on page 28
- 3. Updated Tables:
 - "Active Clock Domains and Wake-up Sources in Different Sleep Modes" on page 33
 - "DC Characteristics" on page 174
 - "Register Summary" on page 213
- 4. Updated Register Description:
 - "ADMUX ADC Multiplexer Selection Register" on page 145
- 5. Signature Imprint Reading Instructions updated in "Reading Device Signature Imprint Table from Firmware" on page 156.
- 6. Updated Section:
 - Step 1. on page 164
- 7. Added Table:
 - "Analog Comparator Characteristics" on page 179
- 8. Updated Figure:
 - "Active Supply Current vs. frequency (1 20 MHz)" on page 187
- 9. Updated Figure 21-30 on page 201 and Figure 21-33 on page 202 under "Pin Threshold and Hysteresis".
- 10. Changed ATtiny24/44 device status to "Not Recommended for New Designs. Use: ATtiny24A/44A".

9.5 Rev G. 01/08

- 1. Updated sections:
 - "Features" on page 1
 - "RESET" on page 3
 - "Overview" on page 4
 - "About" on page 6
 - "SPH and SPL Stack Pointer Register" on page 11
 - "Atomic Byte Programming" on page 17
 - "Write" on page 17
 - "Clock Sources" on page 25
 - "Default Clock Source" on page 30
 - "Sleep Modes" on page 33
 - "Software BOD Disable" on page 34
 - "External Interrupts" on page 49
 - "USIBR USI Data Buffer" on page 125
 - "USIDR USI Data Register" on page 124
 - "DIDR0 Digital Input Disable Register 0" on page 131
 - "Features" on page 132
 - "Prescaling and Conversion Timing" on page 135
 - "Temperature Measurement" on page 144
 - "ADMUX ADC Multiplexer Selection Register" on page 145
 - "Limitations of debugWIRE" on page 152
 - "Reading Lock, Fuse and Signature Data from Software" on page 155
 - "Device Signature Imprint Table" on page 161
 - "Enter High-voltage Serial Programming Mode" on page 168
 - "Absolute Maximum Ratings*" on page 174
 - "DC Characteristics" on page 174
 - "Speed" on page 175
 - "Clock Characteristics" on page 176
 - "Accuracy of Calibrated Internal RC Oscillator" on page 176
 - "System and Reset Characteristics" on page 177
 - "Supply Current of I/O Modules" on page 185
 - "ATtiny24" on page 223
 - "ATtiny44" on page 224
 - "ATtiny84" on page 225
- 2. Updated bit definitions in sections:
 - "MCUCR MCU Control Register" on page 36
 - "MCUCR MCU Control Register" on page 51
 - "MCUCR MCU Control Register" on page 67
 - "PINA Port A Input Pins" on page 68





- "SPMCSR Store Program Memory Control and Status Register" on page 157
- "Register Summary" on page 213

3. Updated Figures:

- "Reset Logic" on page 39
- "Watchdog Reset During Operation" on page 42
- "Compare Match Output Unit, Schematic (non-PWM Mode)" on page 95
- "Analog to Digital Converter Block Schematic" on page 133
- "ADC Timing Diagram, Free Running Conversion" on page 137
- "Analog Input Circuitry" on page 140
- "High-voltage Serial Programming" on page 167
- "Serial Programming Timing" on page 183
- "High-voltage Serial Programming Timing" on page 184
- "Active Supply Current vs. Low Frequency (0.1 1.0 MHz)" on page 186
- "Active Supply Current vs. frequency (1 20 MHz)" on page 187
- "Active Supply Current vs. V_{CC} (Internal RC Oscillator, 8 MHz)" on page 187
- "Active Supply Current vs. V_{CC} (Internal RC Oscillator, 1 MHz)" on page 188
- "Active Supply Current vs. V_{CC} (Internal RC Oscillator, 128 kHz)" on page 188
- "Idle Supply Current vs. Low Frequency (0.1 1.0 MHz)" on page 189
- "Idle Supply Current vs. Frequency (1 20 MHz)" on page 189
- "Idle Supply Current vs. V_{CC} (Internal RC Oscillator, 8 MHz)" on page 190
- "Idle Supply Current vs. V_{CC} (Internal RC Oscillator, 1 MHz)" on page 190
- "Idle Supply Current vs. V_{CC} (Internal RC Oscillator, 128 kHz)" on page 191
- "Power-down Supply Current vs. V_{CC} (Watchdog Timer Disabled)" on page 191
- "Power-down Supply Current vs. V_{CC} (Watchdog Timer Enabled)" on page 192
- "Reset Pin Input Hysteresis vs. V_{CC}" on page 202
- "Reset Pin Input Hysteresis vs. V_{CC} (Reset Pin Used as I/O)" on page 203
- "Watchdog Oscillator Frequency vs. V_{CC}" on page 205
- "Watchdog Oscillator Frequency vs. Temperature" on page 205
- "Calibrated 8 MHz RC Oscillator Frequency vs. V_{CC}" on page 206
- "Calibrated 8 MHz RC oscillator Frequency vs. Temperature" on page 206
- "ADC Current vs. V_{CC}" on page 207
- "Programming Current vs. V_{CC} (ATtiny24)" on page 209
- "Programming Current vs. V_{CC} (ATtiny44)" on page 209
- "Programming Current vs. V_{CC} (ATtiny84)" on page 210

4. Added Figures:

- "Reset Pin Output Voltage vs. Sink Current ($V_{CC} = 3V$)" on page 198
- "Reset Pin Output Voltage vs. Sink Current (V_{CC} = 5V)" on page 198
- "Reset Pin Output Voltage vs. Source Current ($V_{CC} = 3V$)" on page 199
- "Reset Pin Output Voltage vs. Source Current (V_{CC} = 5V)" on page 199

5. Updated Tables:

"Device Clocking Options Select" on page 25

- "Start-up Times for the Crystal Oscillator Clock Selection" on page 29
- "Start-up Times for the Internal Calibrated RC Oscillator Clock Selection" on page 27
- "Start-up Times for the External Clock Selection" on page 26
- "Start-up Times for the 128 kHz Internal Oscillator" on page 27
- "Active Clock Domains and Wake-up Sources in Different Sleep Modes" on page 33
- "Watchdog Timer Prescale Select" on page 47
- "Reset and Interrupt Vectors" on page 48
- "Overriding Signals for Alternate Functions in PA7:PA5" on page 63
- "Overriding Signals for Alternate Functions in PA4:PA2" on page 64
- "Overriding Signals for Alternate Functions in PA1:PA0" on page 64
- "Port B Pins Alternate Functions" on page 65
- "Overriding Signals for Alternate Functions in PB3:PB2" on page 66
- "Overriding Signals for Alternate Functions in PB1:PB0" on page 67
- "Waveform Generation Modes" on page 110
- "ADC Conversion Time" on page 138
- "Temperature vs. Sensor Output Voltage (Typical Case)" on page 144
- "DC Characteristics. $T_A = -40$ "C to +85 "C" on page 174
- "Calibration Accuracy of Internal RC Oscillator" on page 176
- "Reset, Brown-out, and Internal Voltage Characteristics" on page 177
- "VBOT vs. BODLEVEL Fuse Coding" on page 179
- "ADC Characteristics, Single Ended Channels. T = -40°C to +85°C" on page 180
- "ADC Characteristics, Differential Channels (Bipolar Mode), $T_A = -40$ °C to +85°C" on page 182
- "Serial Programming Characteristics, T_A = -40°C to +85°C, V_{CC} = 1.8 5.5V (Unless Otherwise Noted)" on page 183
- "High-voltage Serial Programming Characteristics T_A = 25°C, V_{CC} = 5V (Unless otherwise noted)" on page 184
- 6. Updated code examples in sections:
 - "Write" on page 17
 - "SPI Master Operation Example" on page 119
- 7. Updated "Ordering Information" in:
 - "ATtiny84" on page 219

9.6 Rev F. 02/07

- Updated Figure 1-1 on page 2, Figure 8-7 on page 43, Figure 20-6 on page 184.
- 2. Updated Table 9-1 on page 48, Table 10-7 on page 65, Table 11-2 on page 80, Table 11-3 on page 81, Table 11-5 on page 81, Table 11-6 on page 82, Table 11-7 on page 82, Table 11-8 on page 83, Table 20-11 on page 182, Table 20-13 on page 184.
- 3. Updated table references in "TCCR0A Timer/Counter Control Register A" on page 80.
- 4. Updated Port B, Bit 0 functions in "Alternate Functions of Port B" on page 65.
- 5. Updated WDTCR bit name to WDTCSR in assembly code examples.





- 6. Updated bit5 name in "TIFR1 Timer/Counter Interrupt Flag Register 1" on page 114.
- 7. Updated bit5 in "TIFR1 Timer/Counter Interrupt Flag Register 1" on page 114.
- 8. Updated "SPI Master Operation Example" on page 119.
- 9. Updated step 5 in "Enter High-voltage Serial Programming Mode" on page 168.

9.7 Rev E. 09/06

- 1. All characterization data moved to "Electrical Characteristics" on page 174.
- 2. All Register Descriptions gathered up in separate sections at the end of each chapter.
- 3. Updated "System Control and Reset" on page 39.
- 4. Updated Table 11-3 on page 81, Table 11-6 on page 82, Table 11-8 on page 83, Table 12-3 on page 109 and Table 12-5 on page 110.
- 5. Updated "Fast PWM Mode" on page 97.
- 6. Updated Figure 12-7 on page 98 and Figure 16-1 on page 133.
- 7. Updated "Analog Comparator Multiplexed Input" on page 129.
- 8. Added note in Table 19-12 on page 165.
- 9. Updated "Electrical Characteristics" on page 174.
- 10. Updated "Typical Characteristics" on page 185.

9.8 Rev D. 08/06

- 1. Updated "Calibrated Internal 8 MHz Oscillator" on page 26.
- 2. Updated "OSCCAL Oscillator Calibration Register" on page 30.
- 3. Added Table 20-2 on page 176.
- 4. Updated code examples in "SPI Master Operation Example" on page 119.
- 5. Updated code examples in "SPI Slave Operation Example" on page 121.
- 6. Updated "Signature Bytes" on page 162.

9.9 Rev C. 07/06

- 1. Updated Features in "USI Universal Serial Interface" on page 117.
- 2. Added "Clock speed considerations" on page 123.
- 3. Updated Bit description in "ADMUX ADC Multiplexer Selection Register" on page 145.
- Added note to Table 18-1 on page 157.

9.10 Rev B. 05/06

- 1. Updated "Default Clock Source" on page 30
- 2. Updated "Power Reduction Register" on page 35.
- 3. Updated Table 20-4 on page 177, Table 9-4 on page 42, Table 16-3 on page 145, Table 19-5 on page 161, Table 19-12 on page 165, Table 19-16 on page 171, Table 20-11 on page 182.
- 4. Updated Features in "Analog to Digital Converter" on page 132.
- 5. Updated Operation in "Analog to Digital Converter" on page 132.
- 6. Updated "Temperature Measurement" on page 144.

- 7. Updated DC Characteristics in "Electrical Characteristics" on page 174.
- 8. Updated "Typical Characteristics" on page 185.
- 9. Updated "Errata" on page 223.

9.11 Rev A. 12/05

Initial revision.





Headquarters

Atmel Corporation

2325 Orchard Parkway San Jose, CA 95131 USA

Tel: (+1)(408) 441-0311 Fax: (+1)(408) 487-2600

International

Atmel Asia Limited

Unit 01-5 & 16, 19F BEA Tower, Millennium City 5 418 Kwun Tong Road Kwun Tong, Kowloon HONG KONG

Tel: (+852) 2245-6100 Fax: (+852) 2722-1369 Atmel Munich GmbH

Business Campus Parkring 4 D-85748 Garching b. Munich **GERMANY**

Tel: (+49) 89-31970-0 Fax: (+49) 89-3194621 Atmel Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033 **JAPAN**

Tel: (+81)(3) 3523-3551 Fax: (+81)(3) 3523-7581

Product Contact

Web Site

www.atmel.com

Technical Support

avr@atmel.com

Sales Contact

www.atmel.com/contacts

Literature Requests www.atmel.com/literature

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDITIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDEN-TAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

© 2010 Atmel Corporation. All rights reserved.

Atmel®, logo and combinations thereof, and others are registered trademarks or trademarks of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.