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## Understanding [Embedded - CPLDs \(Complex Programmable Logic Devices\)](#)

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

## Applications of Embedded - CPLDs

### Details

Product Status	Obsolete
Programmable Type	In System Programmable
Delay Time tpd(1) Max	7.5 ns
Voltage Supply - Internal	3V ~ 3.6V
Number of Logic Elements/Blocks	-
Number of Macrocells	192
Number of Gates	-
Number of I/O	96
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	144-BGA
Supplier Device Package	144-FPBGA (13x13)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/lattice-semiconductor/m4a3-192-96-7fac">https://www.e-xfl.com/product-detail/lattice-semiconductor/m4a3-192-96-7fac</a>

**Table 1. ispMACH 4A Device Features**

<b>3.3 V Devices</b>								
<b>Feature</b>	<b>M4A3-32</b>	<b>M4A3-64</b>	<b>M4A3-96</b>	<b>M4A3-128</b>	<b>M4A3-192</b>	<b>M4A3-256</b>	<b>M4A3-384</b>	<b>M4A3-512</b>
Macrocells	32	64	96	128	192	256	384	512
User I/O options	32	32/64	48	64	96	128/160/192	160/192	160/192/256
t <sub>PD</sub> (ns)	5.0	5.5	5.5	5.5	6.0	5.5	6.5	7.5
f <sub>CNT</sub> (MHz)	182	167	167	167	160	167	154	125
t <sub>COS</sub> (ns)	4.0	4.0	4.0	4.0	4.5	4.0	4.5	5.5
t <sub>SS</sub> (ns)	3.0	3.5	3.5	3.5	3.5	3.5	3.5	5.0
Static Power (mA)	20	25/52	40	55	85	110/150	149/155	179
JTAG Compliant	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
PCI Compliant	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes

<b>5 V Devices</b>						
<b>Feature</b>	<b>M4A5-32</b>	<b>M4A5-64</b>	<b>M4A5-96</b>	<b>M4A5-128</b>	<b>M4A5-192</b>	<b>M4A5-256</b>
Macrocells	32	64	96	128	192	256
User I/O options	32	32	48	64	96	128
t <sub>PD</sub> (ns)	5.0	5.5	5.5	5.5	6.0	6.5
f <sub>CNT</sub> (MHz)	182	167	167	167	160	154
t <sub>COS</sub> (ns)	4.0	4.0	4.0	4.0	4.5	5.0
t <sub>SS</sub> (ns)	3.0	3.5	3.5	3.5	3.5	3.5
Static Power (mA)	20	25	40	55	74	110
JTAG Compliant	Yes	Yes	Yes	Yes	Yes	Yes
PCI Compliant	Yes	Yes	Yes	Yes	Yes	Yes

## GENERAL DESCRIPTION

The ispMACH™ 4A family from Lattice offers an exceptionally flexible architecture and delivers a superior Complex Programmable Logic Device (CPLD) solution of easy-to-use silicon products and software tools. The overall benefits for users are a guaranteed and predictable CPLD solution, faster time-to-market, greater flexibility and lower cost. The ispMACH 4A devices offer densities ranging from 32 to 512 macrocells with 100% utilization and 100% pin-out retention. The ispMACH 4A families offer 5-V (M4A5-xxx) and 3.3-V (M4A3-xxx) operation.

ispMACH 4A products are 5-V or 3.3-V in-system programmable through the JTAG (IEEE Std. 1149.1) interface. JTAG boundary scan testing also allows product testability on automated test equipment for device connectivity.

All ispMACH 4A family members deliver First-Time-Fit and easy system integration with pin-out retention after any design change and refit. For both 3.3-V and 5-V operation, ispMACH 4A products can deliver guaranteed fixed timing as fast as 5.0 ns  $t_{PD}$  and 182 MHz  $f_{CNT}$  through the SpeedLocking feature when using up to 20 product terms per output (Table 2).

**Table 2. ispMACH 4A Speed Grades**

Device	Speed Grade							
	-5	-55	-6	-65	-7	-10	-12	-14
M4A3-32	C				C, I	C, I	I	
M4A5-32								
M4A3-64/32		C			C, I	C, I	I	
M4A5-64/32								
M4A3-64/64		C			C, I	C, I	I	
M4A3-96		C			C, I	C, I	I	
M4A5-96								
M4A3-128		C			C, I	C, I	I	
M4A5-128								
M4A3-192			C		C, I	C, I	I	
M4A5-192								
M4A3-256/128		C		C	C, I	C, I	I	
M4A5-256/128				C	C	C, I	I	
M4A3-256/192					C	C, I	I	
M4A3-256/160								
M4A3-384				C		C, I	C, I	I
M4A3-512					C	C, I	C, I	I

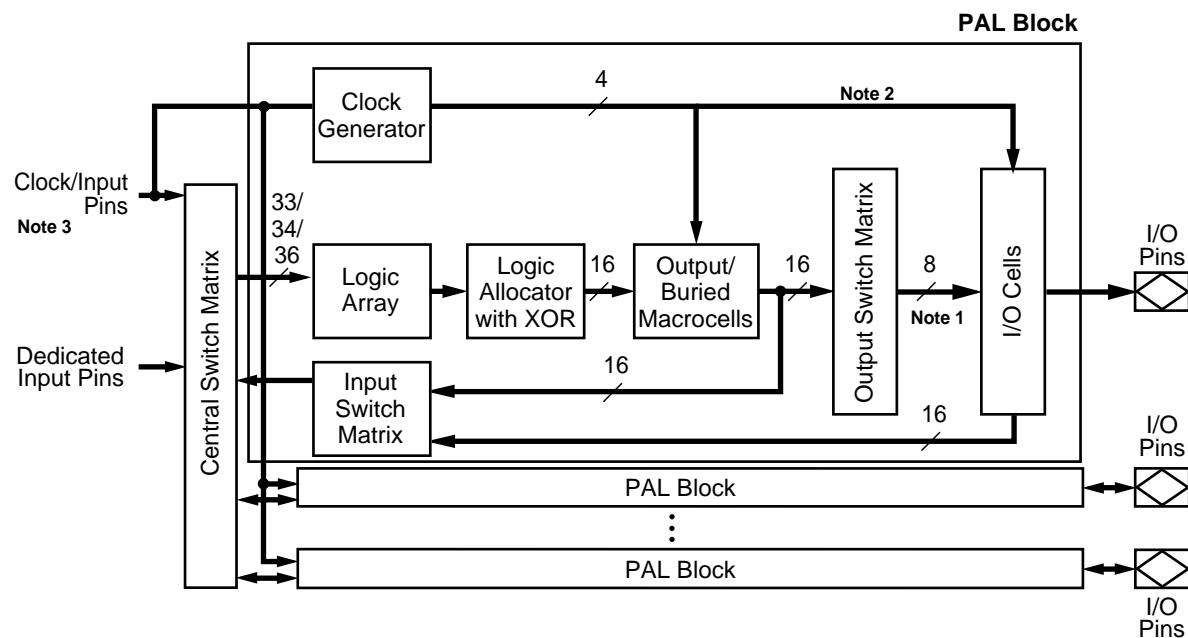
**Note:**

1. C = Commercial    I = Industrial

## FUNCTIONAL DESCRIPTION

The fundamental architecture of ispMACH 4A devices (Figure 1) consists of multiple, optimized PAL® blocks interconnected by a central switch matrix. The central switch matrix allows communication between PAL blocks and routes inputs to the PAL blocks. Together, the PAL blocks and central switch matrix allow the logic designer to create large designs in a single device instead of having to use multiple devices.

The key to being able to make effective use of these devices lies in the interconnect schemes. In the ispMACH 4A architecture, the macrocells are flexibly coupled to the product terms through the logic allocator, and the I/O pins are flexibly coupled to the macrocells due to the output switch matrix. In addition, more input routing options are provided by the input switch matrix. These resources provide the flexibility needed to fit designs efficiently.

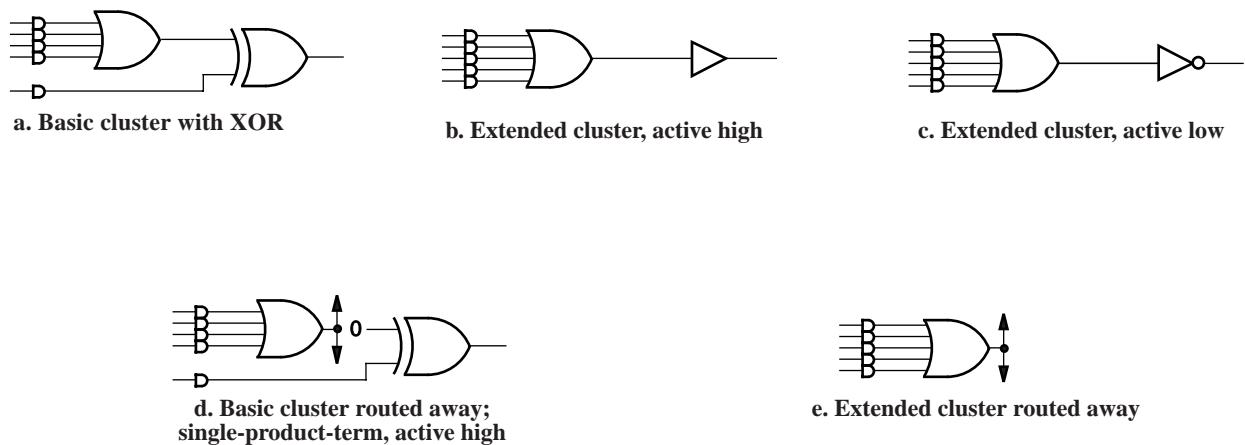


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**Figure 1. ispMACH 4A Block Diagram and PAL Block Structure**

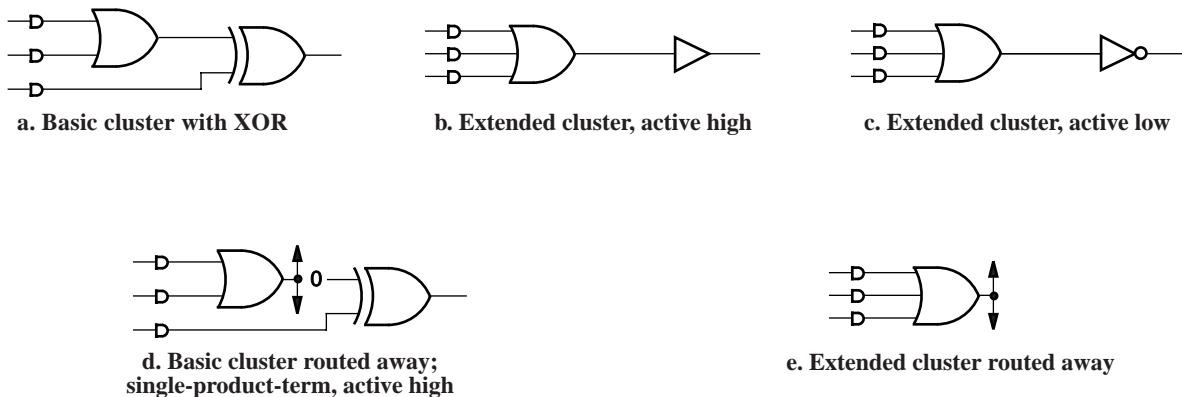
### Notes:

1. 16 for ispMACH 4A devices with 1:1 macrocell-I/O cell ratio (see next page).
2. Block clocks do not go to I/O cells in M4A(3,5)-32/32.
3. M4A(3,5)-192, M4A(3,5)-256, M4A3-384, and M4A3-512 have dedicated clock pins which cannot be used as inputs and do not connect to the central switch matrix.



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**Figure 3. Logic Allocator Configurations: Synchronous Mode**



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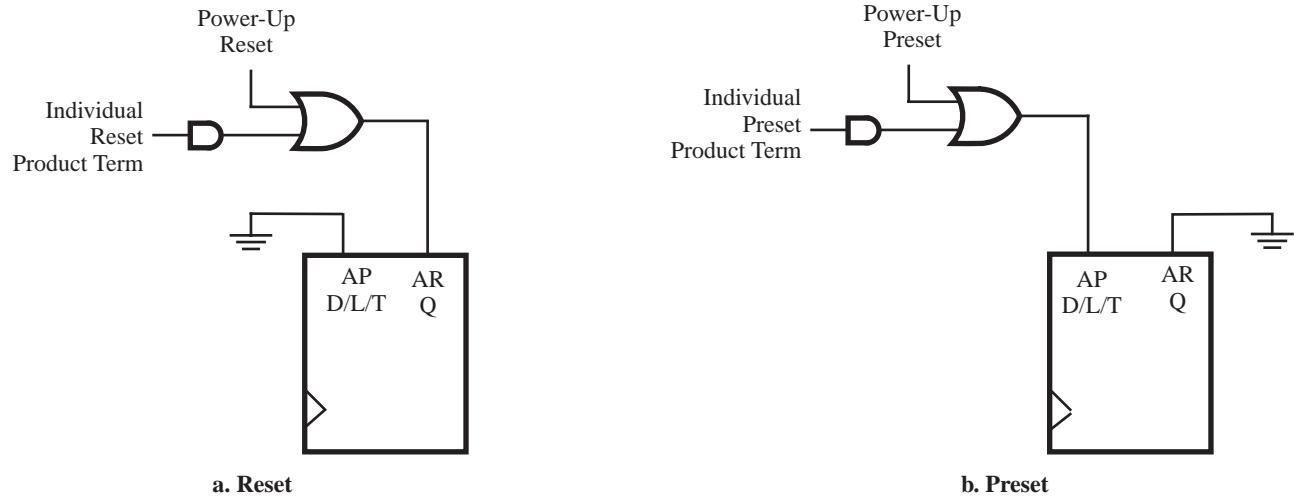
**Figure 4. Logic Allocator Configurations: Asynchronous Mode**

Note that the configuration of the logic allocator has absolutely no impact on the speed of the signal. All configurations have the same delay. This means that designers do not have to decide between optimizing resources or speed; both can be optimized.

If not used in the cluster, the extra product term can act in conjunction with the basic cluster to provide XOR logic for such functions as data comparison, or it can work with the D-, T-type flip-flop to provide for J-K, and S-R register operation. In addition, if the basic cluster is routed to another macrocell, the extra product term is still available for logic. In this case, the first XOR input will be a logic 0. This circuit has the flexibility to route product terms elsewhere without giving up the use of the macrocell.

Product term clusters do not “wrap” around a PAL block. This means that the macrocells at the ends of the block have fewer product terms available.

A reset/preset swapping feature in each macrocell allows for reset and preset to be exchanged, providing flexibility. In asynchronous mode (Figure 8), a single individual product term is provided for initialization. It can be selected to control reset or preset.



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Note that the reset/preset swapping selection feature effects power-up reset as well. The initialization functionality of the flip-flops is illustrated in Table 9. The macrocell sends its data to the output switch matrix and the input switch matrix. The output switch matrix can route this data to an output if so desired. The input switch matrix can send the signal back to the central switch matrix as feedback.

**Table 9. Asynchronous Reset/Preset Operation**

<b>AR</b>	<b>AP</b>	<b>CLK/LE<sup>1</sup></b>	<b>Q+</b>
0	0	X	See Table 8
0	1	X	1
1	0	X	0
1	1	X	0

**Note:**

- ### 1. Transparent latch is unaffected by AR, AP

**Table 11. Output Switch Matrix Combinations for M4A3-256/160 and M4A3-256/192**

<b>Macrocell</b>	<b>Routeable to I/O Cells</b>							
I/08	M8	M9	M10	M11	M12	M13	M14	M15
I/09	M8	M9	M10	M11	M12	M13	M14	M15
I/010	M8	M9	M10	M11	M12	M13	M14	M15
I/011	M8	M9	M10	M11	M12	M13	M14	M15
I/012	M8	M9	M10	M11	M12	M13	M14	M15
I/013	M8	M9	M10	M11	M12	M13	M14	M15
I/014	M8	M9	M10	M11	M12	M13	M14	M15
I/015	M8	M9	M10	M11	M12	M13	M14	M15

**Table 12. Output Switch Matrix Combinations for M4A(3,5)-32/32**

<b>Macrocell</b>	<b>Routeable to I/O Cells</b>
M0, M1, M2, M3, M4, M5, M6, M7	I/00, I/01, I/02, I/03, I/04, I/05, I/06, I/07
M8, M9, M10, M11, M12, M13, M14, M15	I/08, I/09, I/010, I/011, I/012, I/013, I/014, I/015

<b>I/O Cell</b>	<b>Available Macrocells</b>
I/00, I/01, I/02, I/03, I/04, I/05, I/06, I/07	M0, M1, M2, M3, M4, M5, M6, M7
I/08, I/09, I/010, I/011, I/012, I/013, I/014, I/015	M8, M9, M10, M11, M12, M13, M14, M15

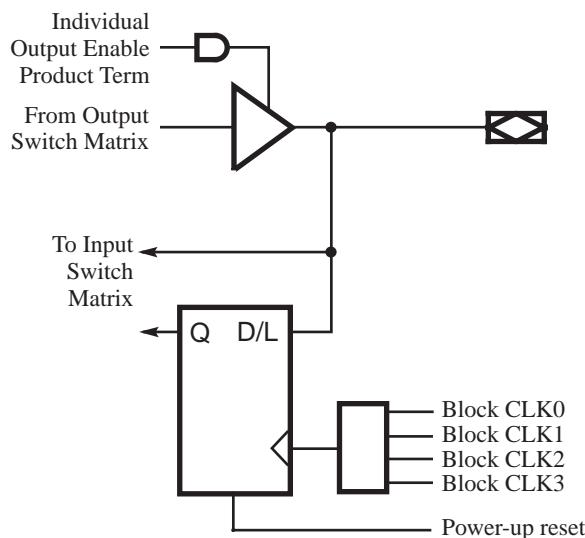
**Table 13. Output Switch Matrix Combinations for M4A3-64/64**

<b>Macrocell</b>	<b>Routeable to I/O Cells</b>
M0, M1	I/00, I/01, I/010, I/011, I/012, I/013, I/014, I/015
M2, M3	I/00, I/01, I/02, I/03, I/012, I/013, I/014, I/015
M4, M5	I/00, I/01, I/02, I/03, I/04, I/05, I/014, I/015
M6, M7	I/00, I/01, I/02, I/03, I/04, I/05, I/06, I/07
M8, M9	I/02, I/03, I/04, I/05, I/06, I/07, I/08, I/09
M10, M11	I/04, I/05, I/06, I/07, I/08, I/09, I/010, I/011
M12, M13	I/06, I/07, I/08, I/09, I/010, I/011, I/012, I/013
M14, M15	I/08, I/09, I/010, I/011, I/012, I/013, I/014, I/015

<b>I/O Cell</b>	<b>Available Macrocells</b>
I/00, I/01	M0, M1, M2, M3, M4, M5, M6, M7
I/02, I/03	M2, M3, M4, M5, M6, M7, M8, M9
I/04, I/05	M4, M5, M6, M7, M8, M9, M10, M11
I/06, I/07	M6, M7, M8, M9, M10, M11, M12, M13
I/08, I/09	M8, M9, M10, M11, M12, M13, M14, M15
I/010, I/011	M0, M1, M10, M11, M12, M13, M14, M15
I/012, I/013	M0, M1, M2, M3, M12, M13, M14, M15
I/014, I/015	M0, M1, M2, M3, M4, M5, M14, M15

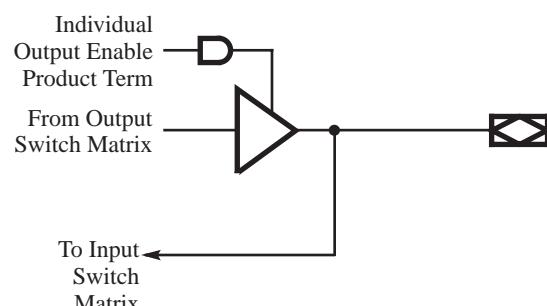
## I/O Cell

The I/O cell (Figures 10 and 11) simply consists of a programmable output enable, a feedback path, and flip-flop (except ispMACH 4A devices with 1:1 macrocell-I/O cell ratio). An individual output enable product term is provided for each I/O cell. The feedback signal drives the input switch matrix.



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**Figure 10. I/O Cell for ispMACH 4A Devices with 2:1 Macrocell-I/O Cell Ratio**



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**Figure 11. I/O Cell for ispMACH 4A Devices with 1:1 Macrocell-I/O Cell Ratio**

The I/O cell (Figure 10) contains a flip-flop, which provides the capability for storing the input in a D-type register or latch. The clock can be any of the PAL block clocks. Both the direct and registered versions of the input are sent to the input switch matrix. This allows for such functions as “time-domain-multiplexed” data comparison, where the first data value is stored, and then the second data value is put on the I/O pin and compared with the previous stored value.

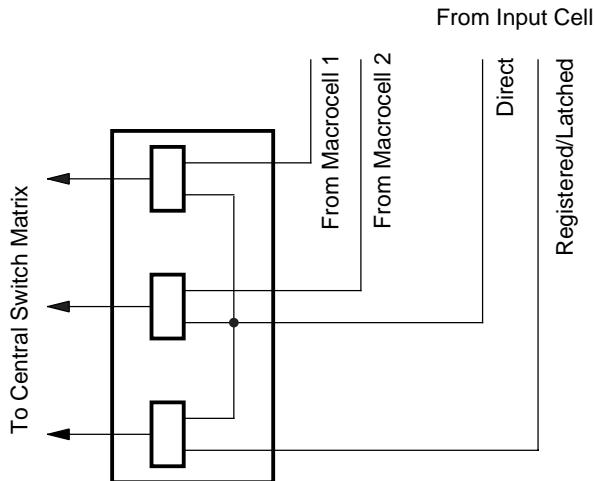
Note that the flip-flop used in the ispMACH 4A I/O cell is independent of the flip-flops in the macrocells. It powers up to a logic low.

### **Zero-Hold-Time Input Register**

The ispMACH 4A devices have a zero-hold-time (ZHT) fuse which controls the time delay associated with loading data into all I/O cell registers and latches. When programmed, the ZHT fuse increases the data path setup delays to input storage elements, matching equivalent delays in the clock path. When the fuse is erased, the setup time to the input storage element is minimized. This feature facilitates doing worst-case designs for which data is loaded from sources which have low (or zero) minimum output propagation delays from clock edges.

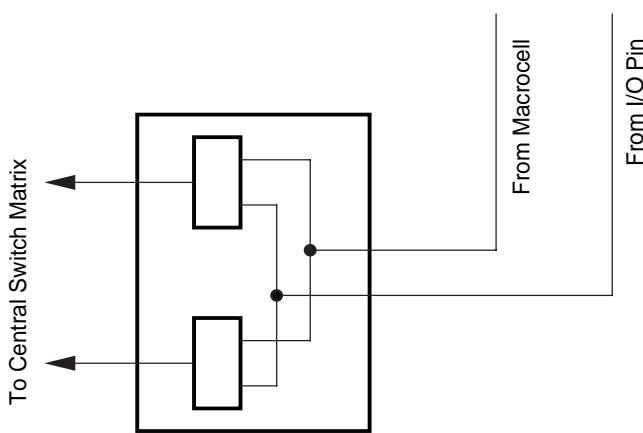
## Input Switch Matrix

The input switch matrix (Figures 12 and 13) optimizes routing of inputs to the central switch matrix. Without the input switch matrix, each input and feedback signal has only one way to enter the central switch matrix. The input switch matrix provides additional ways for these signals to enter the central switch matrix.



17466G-002

**Figure 12. ispMACH 4A with 2:1 Macrocell-I/O Cell Ratio - Input Switch Matrix**



17466G-003

**Figure 13. ispMACH 4A with 1:1 Macrocell-I/O Cell Ratio - Input Switch Matrix**

## IEEE 1149.1-COMPLIANT BOUNDARY SCAN TESTABILITY

All ispMACH 4A devices have boundary scan cells and are compliant to the IEEE 1149.1 standard. This allows functional testing of the circuit board on which the device is mounted through a serial scan path that can access all critical logic nodes. Internal registers are linked internally, allowing test data to be shifted in and loaded directly onto test nodes, or test node data to be captured and shifted out for verification. In addition, these devices can be linked into a board-level serial scan path for more complete board-level testing.

## IEEE 1149.1-COMPLIANT IN-SYSTEM PROGRAMMING

Programming devices in-system provides a number of significant benefits including: rapid prototyping, lower inventory levels, higher quality, and the ability to make in-field modifications. All ispMACH 4A devices provide In-System Programming (ISP) capability through their Boundary ScanTest Access Ports. This capability has been implemented in a manner that ensures that the port remains compliant to the IEEE 1149.1 standard. By using IEEE 1149.1 as the communication interface through which ISP is achieved, customers get the benefit of a standard, well-defined interface.

ispMACH 4A devices can be programmed across the commercial temperature and voltage range. The PC-based ispVM™ software facilitates in-system programming of ispMACH 4A devices. ispVM takes the JEDEC file output produced by the design implementation software, along with information about the JTAG chain, and creates a set of vectors that are used to drive the JTAG chain. ispVM software can use these vectors to drive a JTAG chain via the parallel port of a PC. Alternatively, ispVM software can output files in formats understood by common automated test equipment. This equipment can then be used to program ispMACH 4A devices during the testing of a circuit board.

## PCI COMPLIANT

ispMACH 4A devices in the -5/-55/-6/-65/-7/-10/-12 speed grades are compliant with the *PCI Local Bus Specification* version 2.1, published by the PCI Special Interest Group (SIG). The 5-V devices are fully PCI-compliant. The 3.3-V devices are mostly compliant but do not meet the PCI condition to clamp the inputs as they rise above  $V_{CC}$  because of their 5-V input tolerant feature.

## SAFE FOR MIXED SUPPLY VOLTAGE SYSTEM DESIGNS

Both the 3.3-V and 5-V  $V_{CC}$  ispMACH 4A devices are safe for mixed supply voltage system designs. The 5-V devices will not overdrive 3.3-V devices above the output voltage of 3.3 V, while they accept inputs from other 3.3-V devices. The 3.3-V device will accept inputs up to 5.5 V. Both the 5-V and 3.3-V versions have the same high-speed performance and provide easy-to-use mixed-voltage design capability.

## PULL UP OR BUS-FRIENDLY INPUTS AND I/Os

All ispMACH 4A devices have inputs and I/Os which feature the Bus-Friendly circuitry incorporating two inverters in series which loop back to the input. This double inversion weakly holds the input at its last driven logic state. While it is good design practice to tie unused pins to a known state, the Bus-Friendly input structure pulls pins away from the input threshold voltage where noise can cause high-frequency switching. At power-up, the Bus-Friendly latches are reset to a logic level “1.” For the circuit diagram, please refer to the document entitled *MACH Endurance Characteristics* on the Lattice Data Book CD-ROM or Lattice web site.

All ispMACH 4A devices have a programmable bit that configures all inputs and I/Os with either pull-up or Bus-Friendly characteristics. If the device is configured in pull-up mode, all inputs and I/O pins are

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weakly pulled up. For the circuit diagram, please refer to the document entitled *MACH Endurance Characteristics* on the Lattice Data Book CD-ROM or Lattice web site.

## POWER MANAGEMENT

Each individual PAL block in ispMACH 4A devices features a programmable low-power mode, which results in power savings of up to 50%. The signal speed paths in the low-power PAL block will be slower than those in the non-low-power PAL block. This feature allows speed critical paths to run at maximum frequency while the rest of the signal paths operate in the low-power mode.

## PROGRAMMABLE SLEW RATE

Each ispMACH 4A device I/O has an individually programmable output slew rate control bit. Each output can be individually configured for the higher speed transition (3 V/ns) or for the lower noise transition (1 V/ns). For high-speed designs with long, unterminated traces, the slow-slew rate will introduce fewer reflections, less noise, and keep ground bounce to a minimum. For designs with short traces or well terminated lines, the fast slew rate can be used to achieve the highest speed. The slew rate is adjusted independent of power.

## POWER-UP RESET/SET

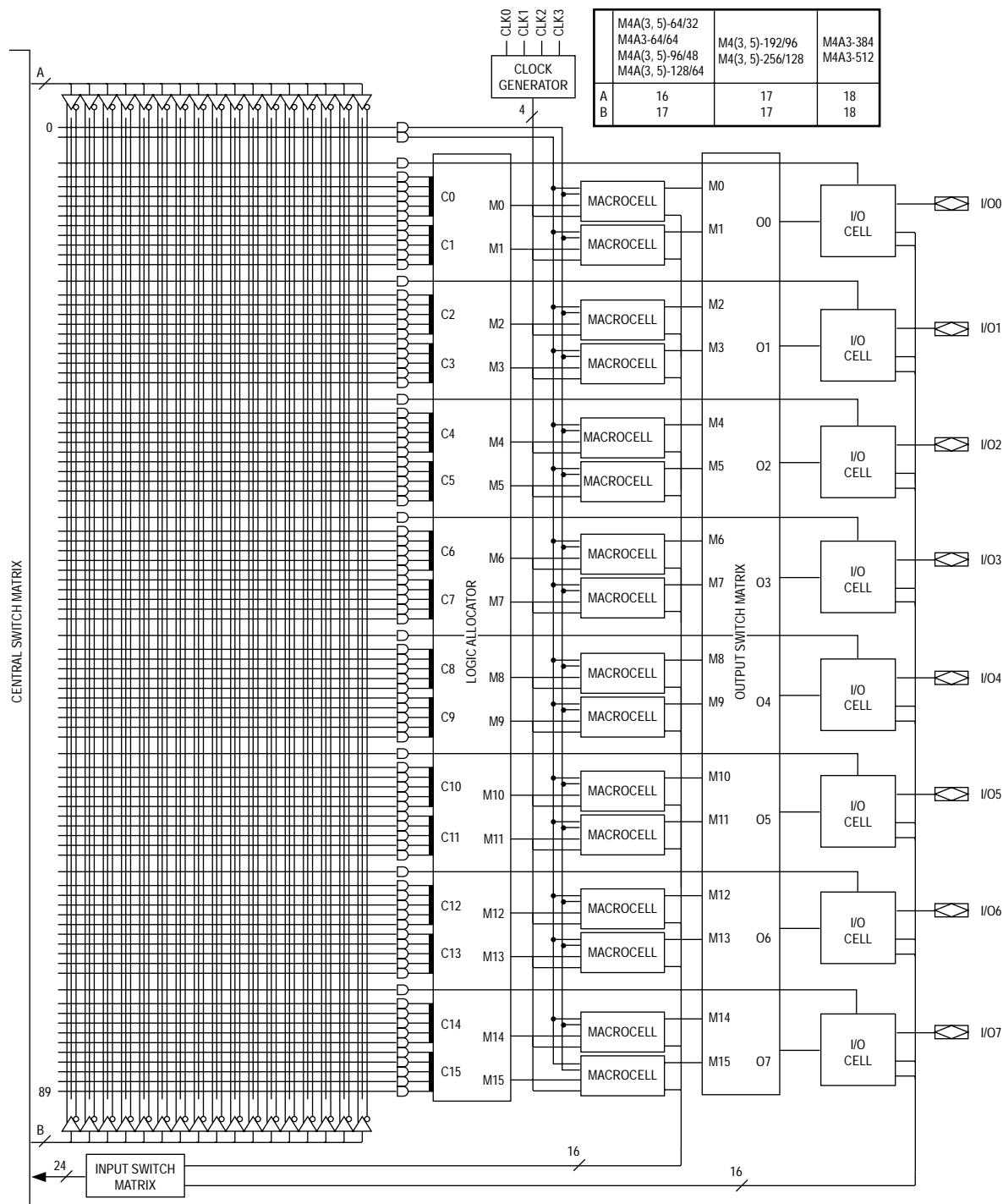
All flip-flops power up to a known state for predictable system initialization. If a macrocell is configured to SET on a signal from the control generator, then that macrocell will be SET during device power-up. If a macrocell is configured to RESET on a signal from the control generator or is not configured for set/reset, then that macrocell will RESET on power-up. To guarantee initialization values, the V<sub>CC</sub> rise must be monotonic, and the clock must be inactive until the reset delay time has elapsed.

## SECURITY BIT

A programmable security bit is provided on the ispMACH 4A devices as a deterrent to unauthorized copying of the array configuration patterns. Once programmed, this bit defeats readback of the programmed pattern by a device programmer, securing proprietary designs from competitors. Programming and verification are also defeated by the security bit. The bit can only be reset by erasing the entire device.

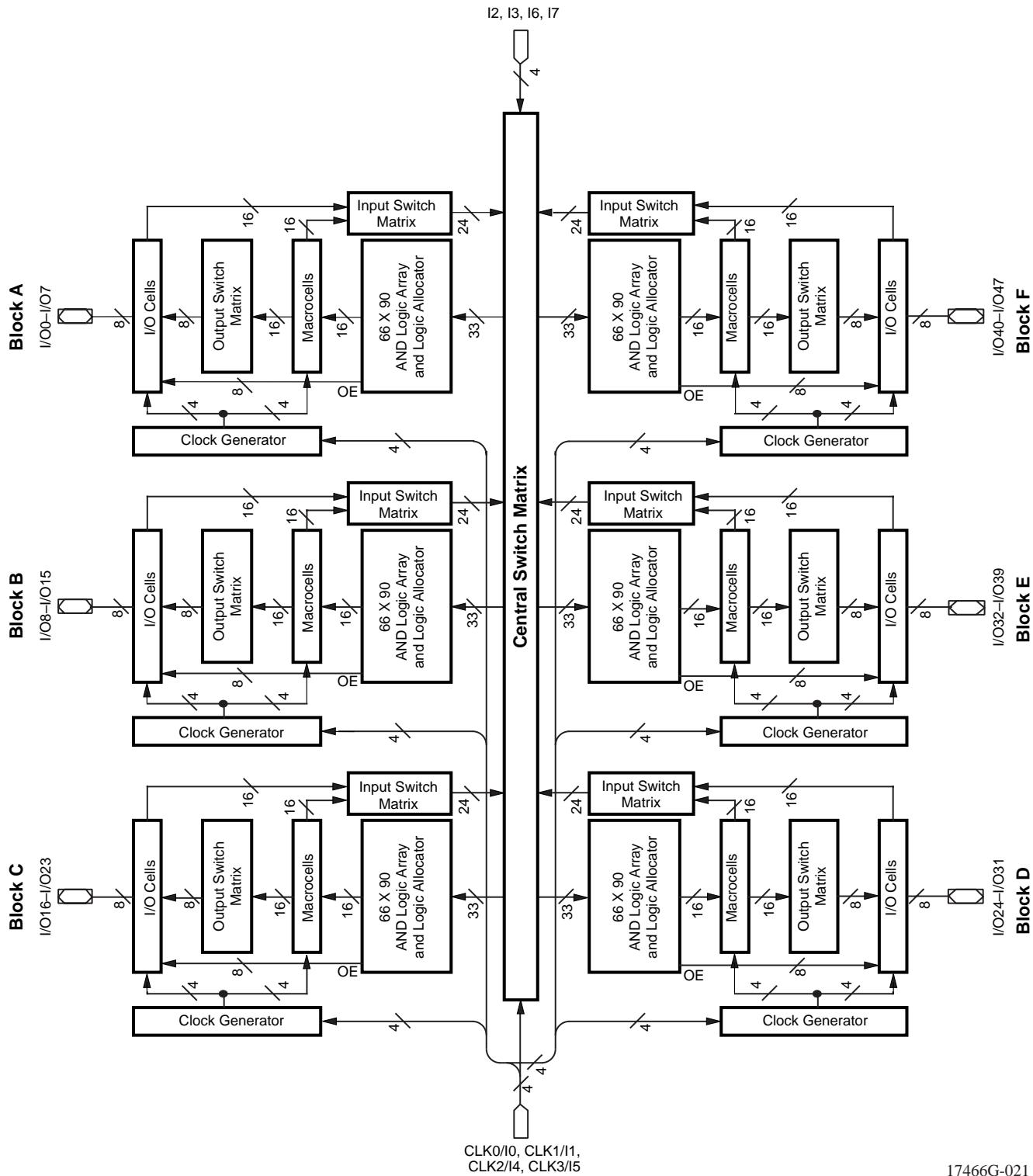
## HOT SOCKETING

ispMACH 4A devices are well-suited for those applications that require hot socketing capability. Hot socketing a device requires that the device, when powered down, can tolerate active signals on the I/Os and inputs without being damaged. Additionally, it requires that the effects of the powered-down MACH devices be minimal on active signals.



**Figure 16. PAL Block for ispMACH 4A with 2:1 Macrocell - I/O Cell Ratio**

## BLOCK DIAGRAM – M4A(3,5)-96/48



CLK0/I0, CLK1/I1,  
CLK2/I4, CLK3/I5

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## ABSOLUTE MAXIMUM RATINGS

### M4A5

Storage Temperature.....	-65°C to +150°C
Ambient Temperature with Power Applied.....	-55°C to +100°C
Device Junction Temperature.....	+130°C
Supply Voltage with Respect to Ground .....	-0.5 V to +7.0 V
DC Input Voltage .....	-0.5 V to $V_{CC}$ + 0.5 V
Static Discharge Voltage.....	2000 V
Latchup Current ( $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$ ) .....	200 mA
<i>Stresses above those listed under Absolute Maximum Ratings may cause permanent device failure. Functionality at or above these limits is not implied. Exposure to Absolute Maximum Ratings for extended periods may affect device reliability.</i>	

## OPERATING RANGES

### Commercial (C) Devices

Ambient Temperature ( $T_A$ )	
Operating in Free Air.....	0°C to +70°C
Supply Voltage ( $V_{CC}$ ) with Respect to Ground.....	+4.75 V to +5.25 V

### Industrial (I) Devices

Ambient Temperature ( $T_A$ )	
Operating in Free Air.....	-40°C to +85°C
Supply Voltage ( $V_{CC}$ ) with Respect to Ground.....	+4.50 V to +5.5 V
<i>Operating ranges define those limits between which the functionality of the device is guaranteed.</i>	

## 5-V DC CHARACTERISTICS OVER OPERATING RANGES

Parameter Symbol	Parameter Description	Test Conditions	Min	Typ	Max	Unit
$V_{OH}$	Output HIGH Voltage	$I_{OH} = -3.2 \text{ mA}$ , $V_{CC} = \text{Min}$ , $V_{IN} = V_{IH}$ or $V_{IL}$	2.4			V
		$I_{OH} = -100 \mu\text{A}$ , $V_{CC} = \text{Max}$ , $V_{IN} = V_{IH}$ or $V_{IL}$		3.3	3.6	V
$V_{OL}$	Output LOW Voltage	$I_{OL} = 24 \text{ mA}$ , $V_{CC} = \text{Min}$ , $V_{IN} = V_{IH}$ or $V_{IL}$ (Note 1)			0.5	V
$V_{IH}$	Input HIGH Voltage	Guaranteed Input Logical HIGH Voltage for all Inputs (Note 2)	2.0			V
$V_{IL}$	Input LOW Voltage	Guaranteed Input Logical LOW Voltage for all Inputs (Note 2)			0.8	V
$I_{IH}$	Input HIGH Leakage Current	$V_{IN} = 5.25 \text{ V}$ , $V_{CC} = \text{Max}$ (Note 3)			10	$\mu\text{A}$
$I_{IL}$	Input LOW Leakage Current	$V_{IN} = 0 \text{ V}$ , $V_{CC} = \text{Max}$ (Note 3)			-10	$\mu\text{A}$
$I_{OZH}$	Off-State Output Leakage Current HIGH	$V_{OUT} = 5.25 \text{ V}$ , $V_{CC} = \text{Max}$ , $V_{IN} = V_{IH}$ or $V_{IL}$ (Note 3)			10	$\mu\text{A}$
$I_{OZL}$	Off-State Output Leakage Current LOW	$V_{OUT} = 0 \text{ V}$ , $V_{CC} = \text{Max}$ , $V_{IN} = V_{IH}$ or $V_{IL}$ (Note 3)			-10	$\mu\text{A}$
$I_{SC}$	Output Short-Circuit Current	$V_{OUT} = 0.5 \text{ V}$ , $V_{CC} = \text{Max}$ (Note 4)	-30		-160	mA

### Notes:

1. Total  $I_{OL}$  for one PAL block should not exceed 64 mA.
2. These are absolute values with respect to device ground, and all overshoots due to system or tester noise are included.
3. I/O pin leakage is the worst case of  $I_{IL}$  and  $I_{OZL}$  (or  $I_{IH}$  and  $I_{OZH}$ ).
4. Not more than one output should be shorted at a time and duration of the short-circuit should not exceed one second.  $V_{OUT} = 0.5 \text{ V}$  has been chosen to avoid test problems caused by tester ground degradation.

## ispMACH 4A TIMING PARAMETERS OVER OPERATING RANGES<sup>1</sup>

		-5		-55		-6		-65		-7		-10		-12		-14		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
<b>Frequency:</b>																		
$f_{MAXS}$	External feedback, D-type, Min of $1/(t_{WLS} + t_{WHS})$ or $1/(t_{SS} + t_{COS})$	143		133		125		118		95.2		87.0		74.1		60.6		MHz
	External feedback, T-type, Min of $1/(t_{WLS} + t_{WHS})$ or $1/(t_{SS} + t_{COS})$	125		125		118		111		87.0		80.0		69.0		57.1		MHz
	Internal feedback ( $f_{CNT}$ ), D-type, Min of $1/(t_{WLS} + t_{WHS})$ or $1/(t_{SS} + t_{COS})$	182		167		160		154		125		118		95.0		74.1		MHz
	Internal feedback ( $f_{CNT}$ ), T-type, Min of $1/(t_{WLS} + t_{WHS})$ or $1/(t_{SS} + t_{COS})$	154		154		148		143		111		105		87.0		69.0		MHz
	No feedback <sup>2</sup> , Min of $1/(t_{WLS} + t_{WHS})$ , $1/(t_{SS} + t_{HS})$ or $1/(t_{SST} + t_{HS})$	250		250		200		200		154		125		100		83.3		MHz
$f_{MAXA}$	External feedback, D-type, Min of $1/(t_{WLA} + t_{WHA})$ or $1/(t_{SA} + t_{COA})$	111		111		108		100		83.3		66.7		55.6		43.5		MHz
	External feedback, T-type, Min of $1/(t_{WLA} + t_{WHA})$ or $1/(t_{SAT} + t_{COA})$	105		105		102		95.2		76.9		62.5		52.6		41.7		MHz
	Internal feedback ( $f_{CNTA}$ ), D-type, Min of $1/(t_{WLA} + t_{WHA})$ or $1/(t_{SA} + t_{COA})$	133		133		125		125		105		83.3		66.7		50.0		MHz
	Internal feedback ( $f_{CNTA}$ ), T-type, Min of $1/(t_{WLA} + t_{WHA})$ or $1/(t_{SAT} + t_{COA})$	125		125		125		118		95.2		76.9		62.5		47.6		MHz
	No feedback <sup>2</sup> , Min of $1/(t_{WLA} + t_{WHA})$ , $1/(t_{SA} + t_{HA})$ or $1/(t_{SAT} + t_{HA})$	167		167		143		143		125		100		62.5		55.6		MHz
$f_{MAXI}$	Maximum input register frequency, Min of $1/(t_{WIRH} + t_{WIRL})$ or $1/(t_{SIRS} + t_{HIRS})$	167		167		143		143		125		100		83.3		83.3		MHz

**Notes:**

- See "Switching Test Circuit" document on the Literature Download page of the Lattice web site.
- This parameter does not apply to flip-flops in the emulated mode since the feedback path is required for emulation.

## CAPACITANCE<sup>1</sup>

Parameter Symbol	Parameter Description	Test Conditions		Typ	Unit
$C_{IN}$	Input capacitance	$V_{IN}=2.0\text{ V}$	3.3 V or 5 V, 25°C, 1 MHz	6	pF
$C_{I/O}$	Output capacitance	$V_{OUT}=2.0\text{ V}$	3.3 V or 5 V, 25°C, 1 MHz	8	pF

**Note:**

- These parameters are not 100% tested, but are calculated at initial characterization and at any time the design is modified where this parameter may be affected.

## I<sub>CC</sub> vs. FREQUENCY

These curves represent the typical power consumption for a particular device at system frequency. The selected “typical” pattern is a 16-bit up-down counter. This pattern fills the device and exercises every macrocell. Maximum frequency shown uses internal feedback and a D-type register. Power-Speed are optimized to obtain the highest counter frequency and the lowest power. The highest frequency (LSBs) is placed in common PAL blocks, which are set to high power. The lowest frequency signals (MSBs) are placed in a common PAL block and set to lowest power.

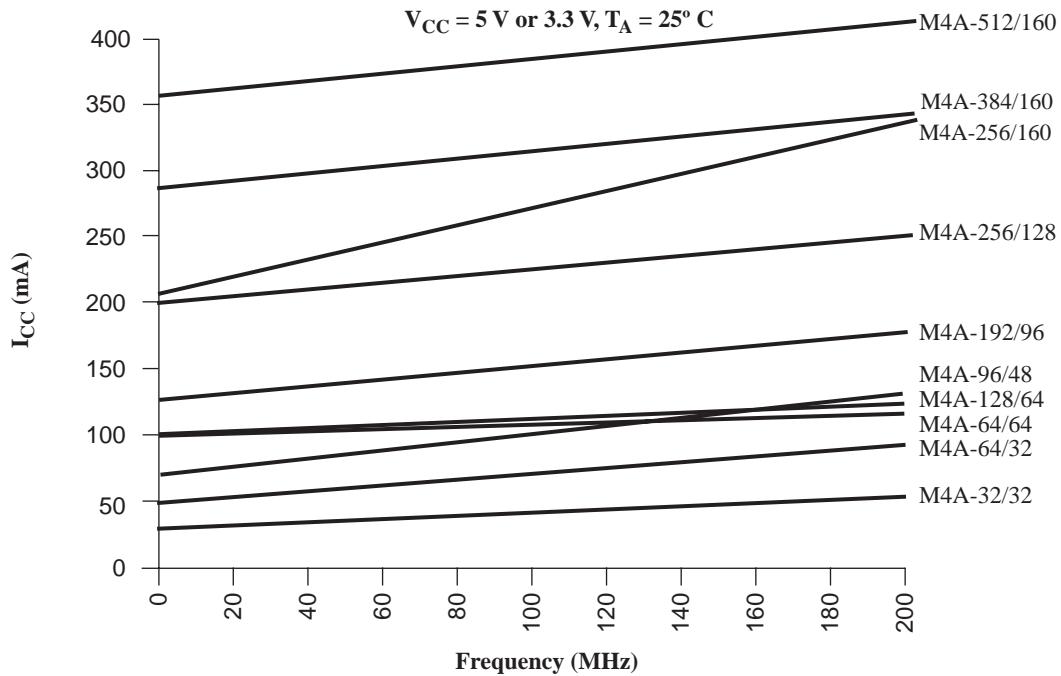


Figure 19. ispMACH 4A I<sub>CC</sub> Curves at High Speed Mode

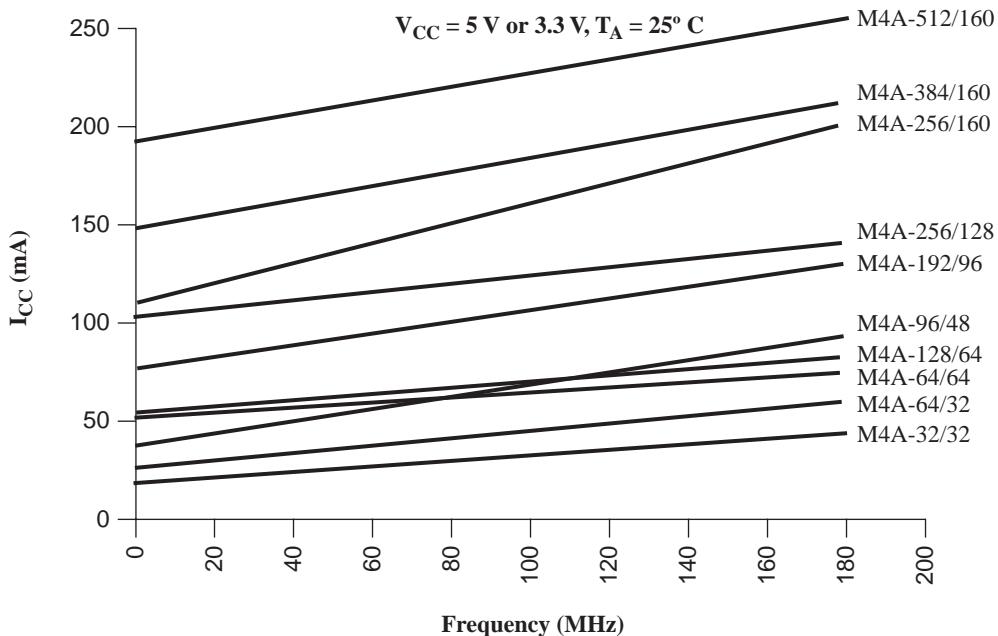
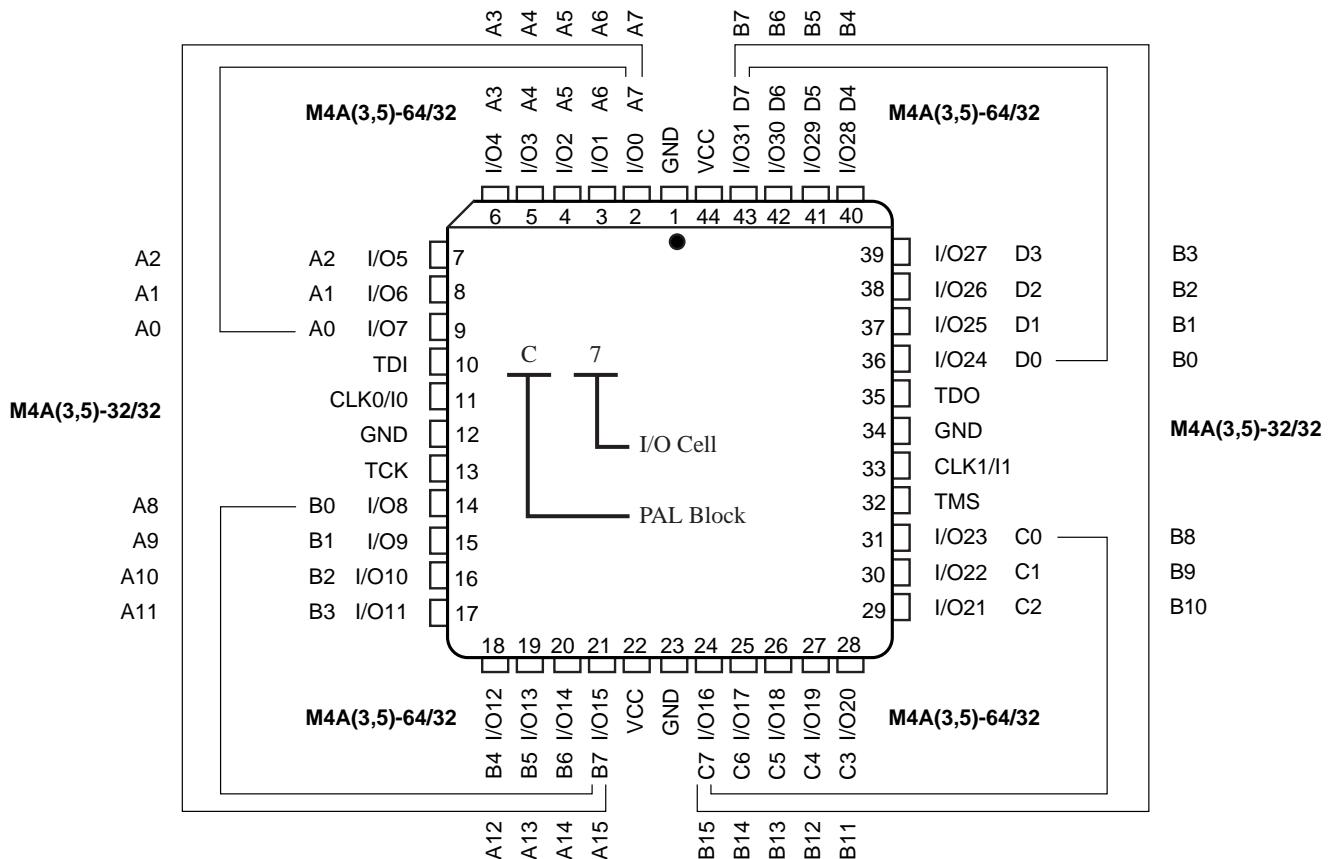


Figure 20. ispMACH 4A I<sub>CC</sub> Curves at Low Power Mode

## 44-PIN PLCC CONNECTION DIAGRAM (M4A(3,5)-32/32 AND M4A(3,5)-64/32)

## Top View

44-Pin PLCC



17466G-026

## PIN DESIGNATIONS

CLK/I = Clock or Input

GND = Ground

I/O = Input/Output

$V_{CC}$  = Supply Voltage

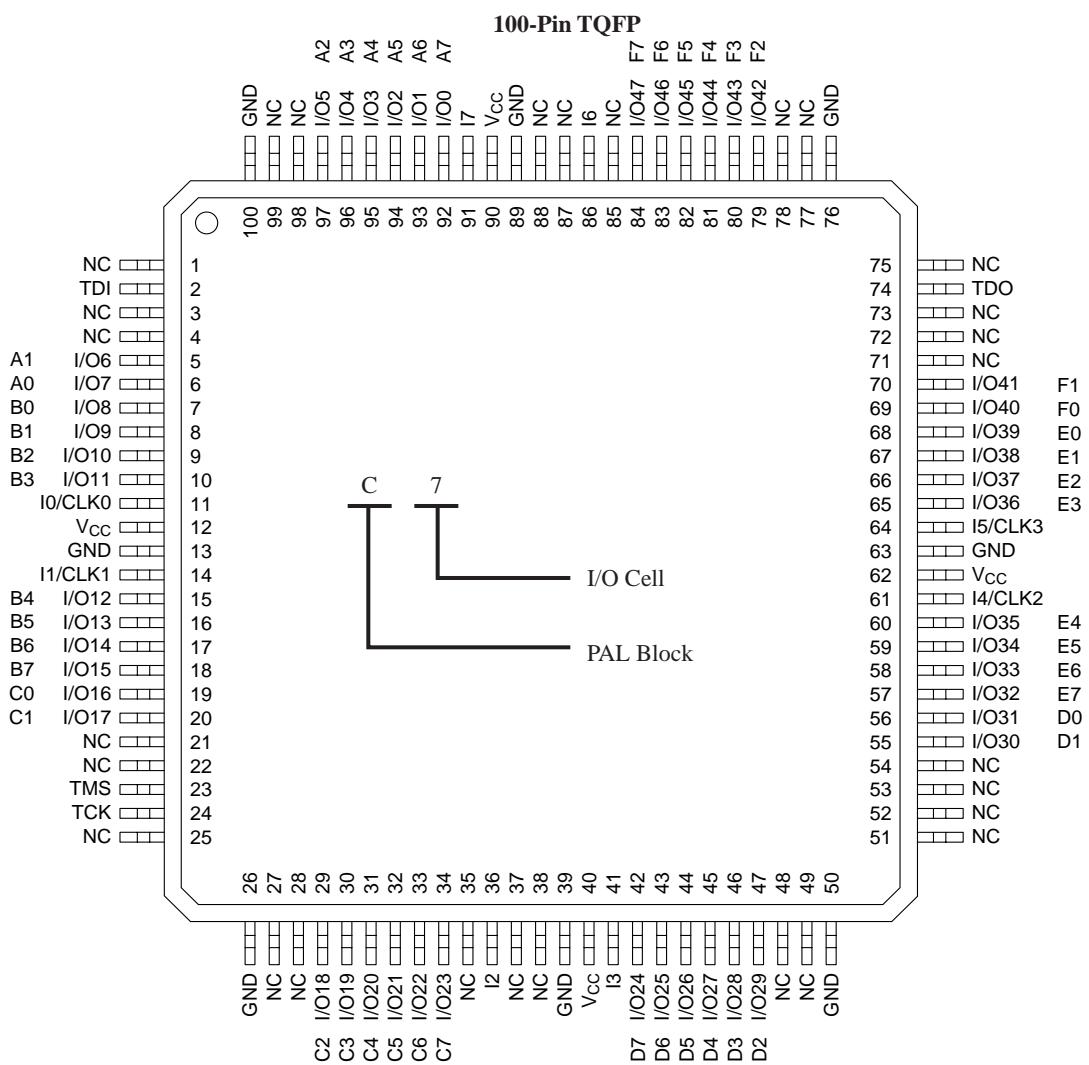
TDI = Test Data In

TCK = Test Clock

TMS = Test Mode Set

## 100-PIN TQFP CONNECTION DIAGRAM (M4A(3,5)-96/48)

## Top View



17466G-029

## PIN DESIGNATIONS

CLK/I = Clock or Input

GND = Ground

I = Input

I/O = Input/Output

$V_{CC}$  = Supply Voltage

NC = No Connect

TDI = Test Data In

TCK = Test Clock

TMS = Test Mode

TDO = Test Data Out

## 100-BALL caBGA CONNECTION DIAGRAM (M4A3-128/64)

### Bottom View

100-Ball caBGA

	10	9	8	7	6	5	4	3	2	1	
A	GND	I/O63 H7	I/O60 H4	I/O57 H1	GND	GND	I/O1 A1	I/O4 A4	I/O7 A7	GND	A
B	TRST	GND	I/O61 H5	I5	VCC	I/O0 A0	I/O6 A6	GND	TDI	I/O15 B7	B
C	I/O53 G5	TDO	I/O62 H6	I/O58 H2	I/O56 H0	I/O2 A2	GND	I/O14 B6	I/O13 B5	I/O12 B4	C
D	I/O50 G2	I/O55 G7	GND	I/O59 H3	I/O3 A3	I/O5 A5	I/O11 B3	I/O10 B2	CLK0/I0	I/O9 B1	D
E	CLK3/I4	I/O49 G1	I/O51 G3	I/O54 G6	VCC	I/O16 C0	I/O20 C4	I/O8 B0	VCC	GND	E
F	GND	VCC	I/O40 F0	I/O52 G4	I/O48 G0	VCC	I/O22 C6	I/O19 C3	I/O17 C1	CLK1/I1	F
G	I/O41 F1	CLK2/I3	I/O42 F2	I/O43 F3	I/O37 E5	I/O35 E3	I/O27 D3	GND	I/O23 C7	I/O18 C2	G
H	I/O44 F4	I/O45 F5	I/O46 F6	GND	I/O34 E2	I/O24 D0	I/O26 D2	I/O30 D6	TCK	I/O21 C5	H
J	I/O47 F7	ENABLE	GND	I/O38 E6	I/O32 E0	VCC	I2	I/O29 D5	GND	TMS	J
K	GND	I/O39 E7	I/O36 E4	I/O33 E1	GND	GND	I/O25 D1	I/O28 D4	I/O31 D7	GND	K

10      9      8      7      6      5      4      3      2      1

### PIN DESIGNATIONS

CLK	= Clock
GND	= Ground
I	= Input
I/O	= Input/Output
N/C	= No Connect
VCC	= Supply Voltage
TDI	= Test Data In
TCK	= Test Clock
TMS	= Test Mode Select
TDO	= Test Data Out
TRST	= Test Reset
ENABLE	= Program

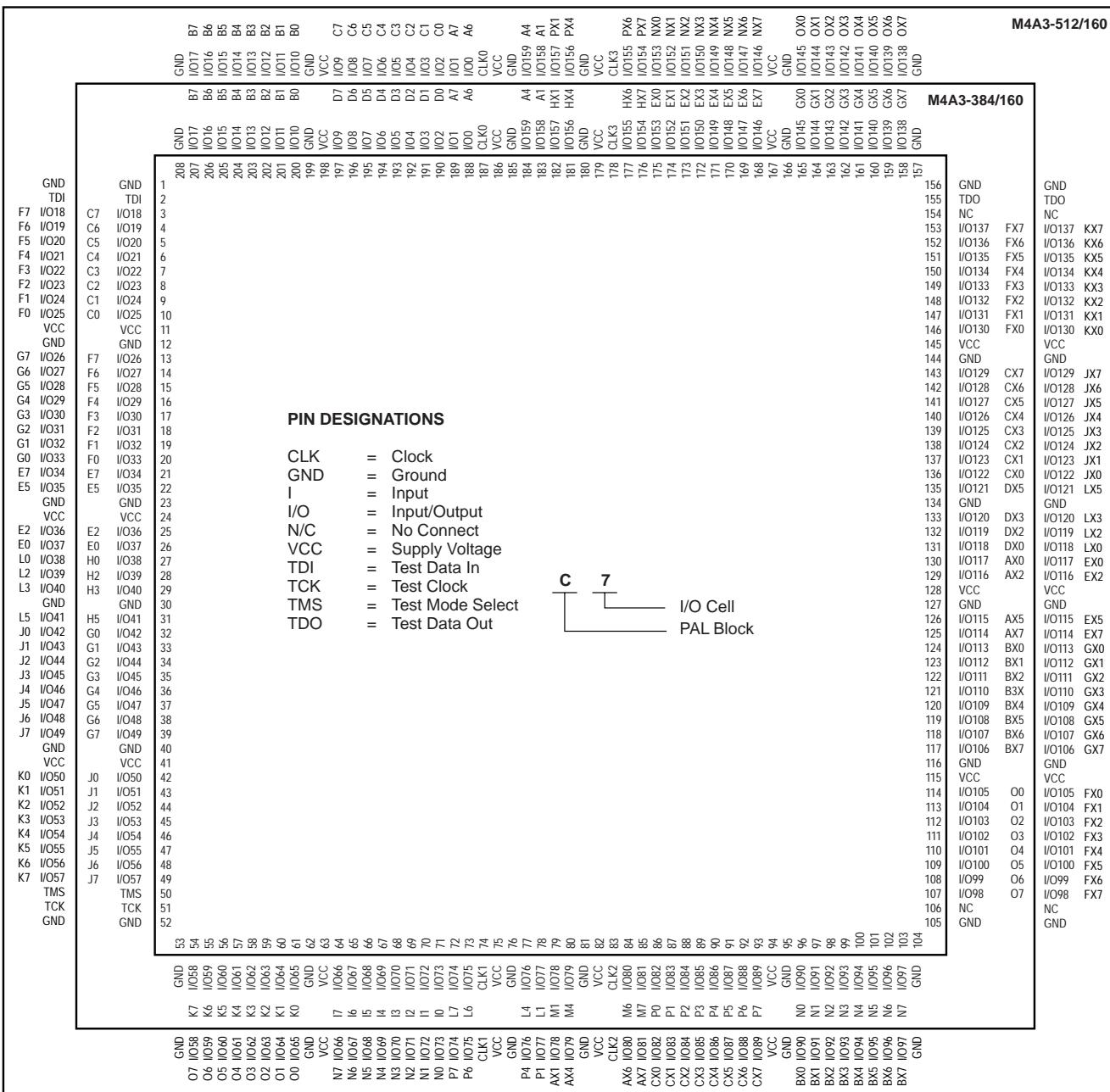


17466G-100cabga

## 208-PIN PQFP CONNECTION DIAGRAM (M4A3-384/160 AND M4A3-512/160)

### Top View

208-Pin PQFP



17466Ga-044

## 256-BALL fpBGA CONNECTION DIAGRAM (M4A3-256/128)

### Bottom View

256-Ball fpBGA

	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
A	TRST	I/O117 O5	I/O116 O4	I/O113 O1	I/O126 P6	I/O124 P4	I12	NC	NC	NC	CLK0	I/O1 A1	I/O5 A5	I/O7 A7	I/O10 B2	I/O12 B4 <th>A</th>	A
B	I/O110 N6	I/O111 N7	I/O118 O6	I/O115 O3	I/O127 P7	I/O125 P5	I/O120 P0	NC	NC	NC	I1	I/O2 A2	I/O8 B0	I/O11 B3	I/O13 B5	NC	B
C	I/O108 N4	I/O109 N5	NC	I/O119 O7	I/O114 O2	I/O122 P2	I/O123 P3	NC	NC	I0	I/O4 A4	I/O6 A6	I/O15 B7	I/O14 B6	TDI	I/O23 C7	C
D	NC	I/O104 N0	TDO	GND	GND	VCC	GND	VCC	GND	GND	VCC	GND	VCC	I/O9 B1	I/O22 C6	I/O21 C5	D
E	I/O102 M6	NC	I/O107 N3	VCC	I/O105 N1	I/O106 N2	I13	CLK3	NC	NC	I/O0 A0	NC	GND	I/O20 C4	I/O19 C3	I/O31 D7	E
F	I/O98 M2	I/O103 M7	I/O101 M5	GND	I/O100 M4	I/O99 M3	I/O112 O0	I/O121 P1	NC	NC	I/O3 A3	I/O18 C2	VCC	I/O16 C0	I/O30 D6	I/O29 D5	F
G	NC	I/O96 M0	I11	VCC	NC	I/O97 M1	VCC	GND	VCC	I/O17 C1	I/O28 D4	GND	I/O26 D2	I/O25 D1	I2	G	
H	I/O88 L0	I10	I9	GND	I/O89 L1	I/O90 L2	GND	VCC	VCC	GND	I/O27 D3	I/O24 D0	VCC	NC	NC	NC	H
J	I/O91 L3	I/O92 L4	I/O93 L5	GND	I/O95 L7	I/O94 L6	GND	VCC	VCC	GND	I3	NC	GND	NC	NC	NC	J
K	NC	NC	NC	VCC	NC	NC	VCC	GND	GND	VCC	NC	NC	VCC	I4	NC	I/O32 E0	K
L	NC	NC	I/O80 K0	GND	I/O83 K3	NC	NC	NC	I/O59 H3	I/O61 H5	NC	NC	GND	I/O35 E3	I/O36 E4	I/O33 E1	L
M	I/O81 K1	I/O82 K2	I/O84 K4	GND	I/O67 I3	I/O65 I1	NC	NC	I/O58 H2	I/O48 G0	I/O51 G3	NC	VCC	I/O44 F4	I/O39 E7	I/O34 E2	M
N	I/O85 K5	I/O86 K6	ENABLE	VCC	GND	VCC	GND	VCC	GND	GND	VCC	GND	GND	TCK	I/O40 F0	I/O37 E5	N
P	I/O87 K7	I/O77 J5	I/O78 J6	I/O79 J7	I/O68 I4	I/O66 I2	NC	NC	NC	I6	I/O63 H7	I/O52 G4	I/O55 G7	TMS	I/O41 F1	I/O38 E6	P
R	I/O76 J4	I/O75 J3	I/O72 J0	I/O71 I7	I/O64 I0	I7	NC	NC	NC	I/O56 H0	I/O60 H4	I/O49 G1	I/O53 G5	I/O47 F7	I/O43 F3	I/O42 F2	R
T	I/O74 J2	I/O73 J1	I/O70 I6	I/O69 I5	I8	CLK2	NC	NC	CLK1	I5	I/O57 H1	I/O62 H6	I/O50 G2	I/O54 G6	I/O46 F6	I/O45 F5	T
	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	

### PIN DESIGNATIONS

CLK = Clock  
 GND = Ground  
 I = Input  
 I/O = Input/Output  
 N/C = No Connect  
 VCC = Supply Voltage  
 TDI = Test Data In  
 TCK = Test Clock  
 TMS = Test Mode Select  
 TDO = Test Data Out  
 TRST = Test Reset  
 ENABLE = Program



m4a3.256.128\_256bga