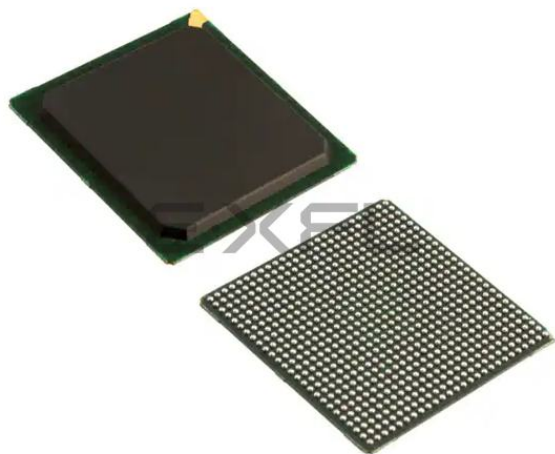




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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	86316
Total RAM Bits	2648064
Number of I/O	425
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	676-BGA
Supplier Device Package	676-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/m2gl090s-1fg676i

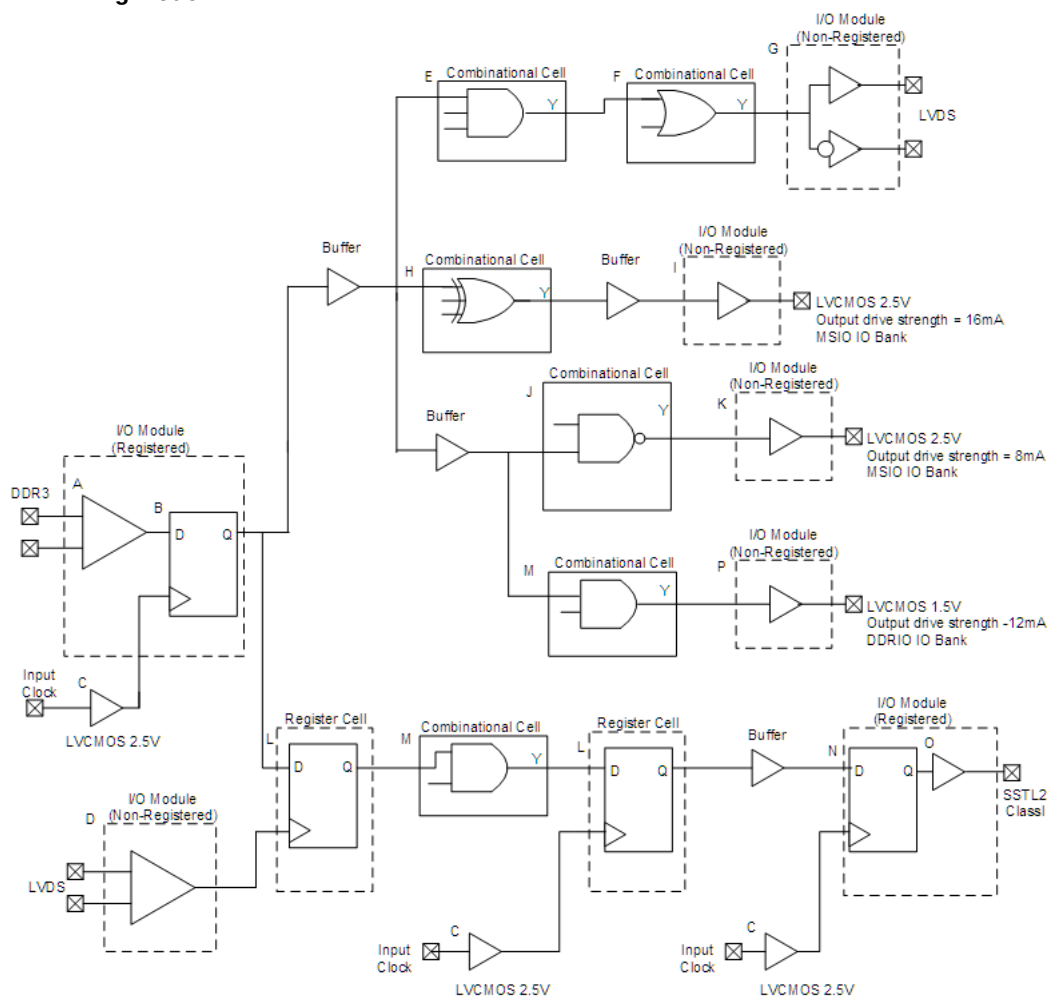
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2.3.4 Timing Model

This section describes timing model and timing parameters.

Figure 2 • Timing Model



The following table lists the timing model parameters in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 17 • Timing Model Parameters

Index	Symbol	Description	-1	Unit	For More Information
A	T_{PY}	Propagation delay of DDR3 receiver	1.605	ns	See Table 137 , page 50
B	T_{ICLKQ}	Clock-to-Q of the input data register	0.16	ns	See Table 221 , page 71
	T_{ISUD}	Setup time of the input data register	0.357	ns	See Table 221 , page 71
C	T_{RCKH}	Input high delay for global clock	1.53	ns	See Table 227 , page 78
	T_{RCKL}	Input low delay for global clock	0.897	ns	See Table 227 , page 78
D	T_{PY}	Input propagation delay of LVDS receiver	2.774	ns	See Table 167 , page 56
E	T_{DP}	Propagation delay of a three-input AND gate	0.198	ns	See Table 223 , page 76

2.3.5.7 2.5 V LVCMOS

LVCMOS 2.5 V is a general standard for 2.5 V applications and is supported in IGLOO2 FPGA and SmartFusion2 SoC FPGAs that are in compliance with the JEDEC specification JESD8-5A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 38 • LVCMOS 2.5 V DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	2.375	2.5	2.625	V

Table 39 • LVCMOS 2.5 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V _{IH} (DC)	1.7	2.625	V
DC input logic high (for MSIO I/O bank)	V _{IH} (DC)	1.7	3.45	V
DC input logic low	V _{IL} (DC)	−0.3	0.7	V
Input current high ¹	I _{IH} (DC)			
Input current low ¹	I _{IL} (DC)			

1. See Table 24, page 22.

Table 40 • LVCMOS 2.5 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V _{OH} ¹	V _{DDI} − 0.4	–	V
DC output logic low	V _{OL} ²		0.4	V

1. The VOH/VOL test points selected ensure compliance with LVCMOS 2.5 V JEDEC8-5A requirements.

Table 41 • LVCMOS 2.5 V AC Minimum and Maximum Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D _{MAX}	400	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D _{MAX}	410	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	420	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 42 • LVCMOS 2.5 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	R _{odt_cal}	75, 60, 50, 33, 25, 20	Ω

Table 72 • LVCMOS 1.5 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	2.735	3.218	3.371	3.966	3.618	4.257	6.03	7.095	5.705	6.712	ns
4 mA	Slow	2.426	2.854	2.992	3.521	3.221	3.79	6.738	7.927	6.298	7.41	ns
6 mA	Slow	2.433	2.862	2.81	3.306	3.031	3.566	7.123	8.38	6.596	7.76	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.10 1.2 V LVCMOS

LVCMOS 1.2 is a general standard for 1.2 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-12A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 73 • LVCMOS 1.2 V DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	1.140	1.2	1.26	V

Table 74 • LVCMOS 1.2 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V _{IH} (DC)	0.65 × V _{DDI}	1.26	V
DC input logic high (for MSIO I/O bank)	V _{IH} (DC)	0.65 × V _{DDI}	3.45	V
DC input logic low	V _{IL} (DC)	-0.3	0.35 × V _{DDI}	V
Input current high ¹	I _{IH} (DC)			
Input current low ¹	I _{IL} (DC)			

1. See Table 24, page 22.

Table 75 • LVCMOS 1.2 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V _{OH}	V _{DDI} × 0.75		V
DC output logic low	V _{OL}		V _{DDI} × 0.25	V

Table 76 • LVCMOS 1.2 V Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D _{MAX}	200	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D _{MAX}	120	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	160	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 118 • DDR1/SSTL2 Class II Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.29	2.693	1.988	2.338	1.978	2.326	1.989	2.34	1.979	2.328	ns
Differential	2.418	2.846	2.304	2.711	2.297	2.702	2.131	2.506	2.124	2.499	ns

2.3.6.4 Stub-Series Terminated Logic 1.8 V (SSTL18)

SSTL18 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs, and also comply with the reduced and full drive double data rate (DDR2) standard. IGLOO2 and SmartFusion2 SoC FPGA I/Os support both standards for single-ended signaling and differential signaling for SSTL18. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification**Table 119 • SSTL18 DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.71	1.8	1.89	V
Termination voltage	V_{TT}	0.838	0.900	0.964	V
Input reference voltage	V_{REF}	0.838	0.900	0.964	V

Table 120 • SSTL18 DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high	V_{IH} (DC)	$V_{REF} + 0.125$	1.89	V
DC input logic low	V_{IL} (DC)	-0.3	$V_{REF} - 0.125$	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 121 • SSTL18 DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
SSTL18 Class I (DDR2 Reduced Drive)				
DC output logic high	V_{OH}	$V_{TT} + 0.603$		V
DC output logic low	V_{OL}		$V_{TT} - 0.603$	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	6.5		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	-6.5		mA
SSTL18 Class II (DDR2 Full Drive)¹				
DC output logic high	V_{OH}	$V_{TT} + 0.603$		V
DC output logic low	V_{OL}		$V_{TT} - 0.603$	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	13.4		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	-13.4		mA

1. To meet JEDEC Electrical Compliance, use DDR2 Full Drive Transmitter.

Table 122 • SSTL18 DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.3	V

Table 123 • SSTL18 AC Differential Voltage Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF} (AC)	0.5		V
AC differential cross point voltage	V_x (AC)	$0.5 \times V_{DDI} - 0.175$	$0.5 \times V_{DDI} + 0.175$	V

Table 124 • SSTL18 Minimum and Maximum AC Switching Speed (Applicable to DDRIO Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	667	Mbps	AC loading: per JEDEC specification

Table 125 • SSTL18 AC Impedance Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	R_{REF}	20, 42	Ω	Reference resistor = 150 Ω
Effective impedance value (ODT)	R_{TT}	50, 75, 150	Ω	Reference resistor = 150 Ω

Table 126 • SSTL18 AC Test Parameter Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for SSTL18 Class I (T_{DP})	RTT_TEST	50	Ω
Reference resistance for data test path for SSTL18 Class II (T_{DP})	RTT_TEST	25	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.71\text{ V}$

Table 127 • DDR2/SSTL18 Receiver Characteristics for DDRIO I/O Bank with Fixed Code

		T_{PY}		Unit
		-1	-Std	
Pseudo differential	None	1.567	1.844	ns
True differential	None	1.588	1.869	ns

2.3.6.6 Low Power Double Data Rate (LPDDR)

LPDDR reduced and full drive low power double data rate standards are supported in IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 139 • LPDDR DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max
Supply voltage	V_{DDI}	1.71	1.8	1.89
Termination voltage	V_{TT}	0.838	0.900	0.964
Input reference voltage	V_{REF}	0.838	0.900	0.964

Table 140 • LPDDR DC Input Voltage Specification

Parameter	Symbol	Min	Max
DC input logic high	V_{IH} (DC)	$0.7 \times V_{DDI}$	1.89
DC input logic low	V_{IL} (DC)	-0.3	$0.3 \times V_{DDI}$
Input current high ¹	I_{IH} (DC)		
Input current low ¹	I_{IL} (DC)		

1. See Table 24, page 22.

Table 141 • LPDDR DC Output Voltage Specification Reduced Drive

Parameter	Symbol	Min	Max
DC output logic high	V_{OH}	$0.9 \times V_{DDI}$	
DC output logic low	V_{OL}		$0.1 \times V_{DDI}$
Output minimum source DC current	I_{OH} at V_{OH}	0.1	
Output minimum sink current	I_{OL} at V_{OL}	-0.1	

Table 142 • LPDDR DC Output Voltage Specification Full Drive¹

Parameter	Symbol	Min	Max
DC output logic high	V_{OH}	$0.9 \times V_{DDI}$	
DC output logic low	V_{OL}		$0.1 \times V_{DDI}$
Output minimum source DC current	I_{OH} at V_{OH}	0.1	
Output minimum sink current	I_{OL} at V_{OL}	-0.1	

1. To meet JEDEC Electrical Compliance, use LPDDR Full Drive Transmitter.

Table 143 • LPDDR DC Differential Voltage Specification

Parameter	Symbol	Min
DC input differential voltage	V_{ID} (DC)	$0.4 \times V_{DDI}$

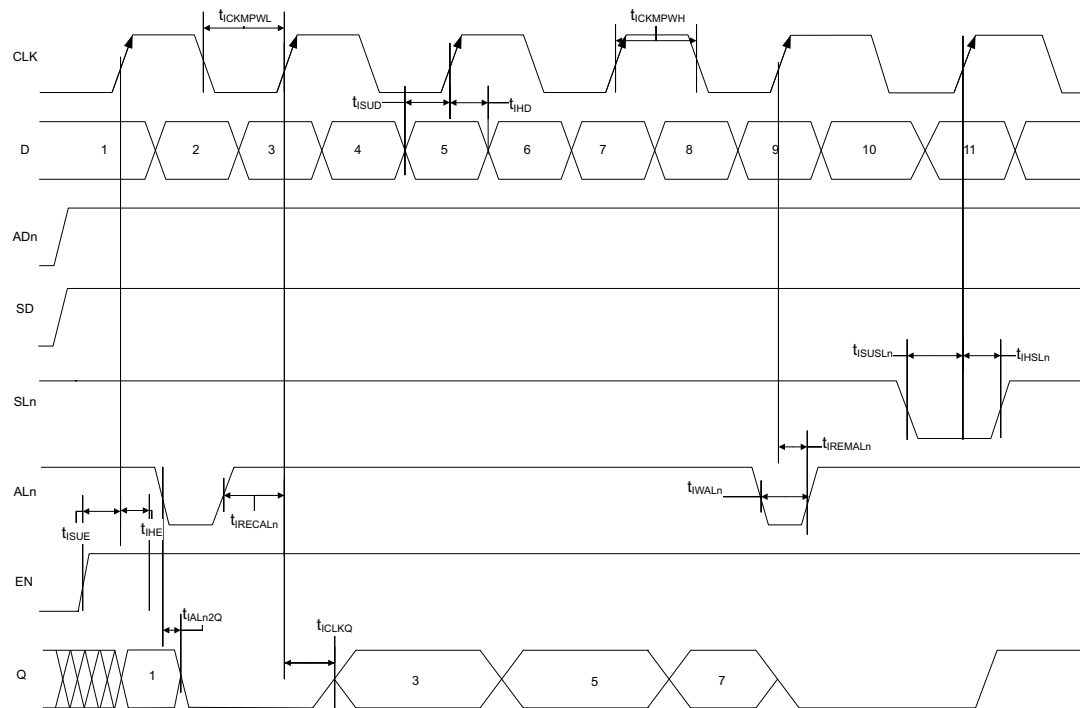
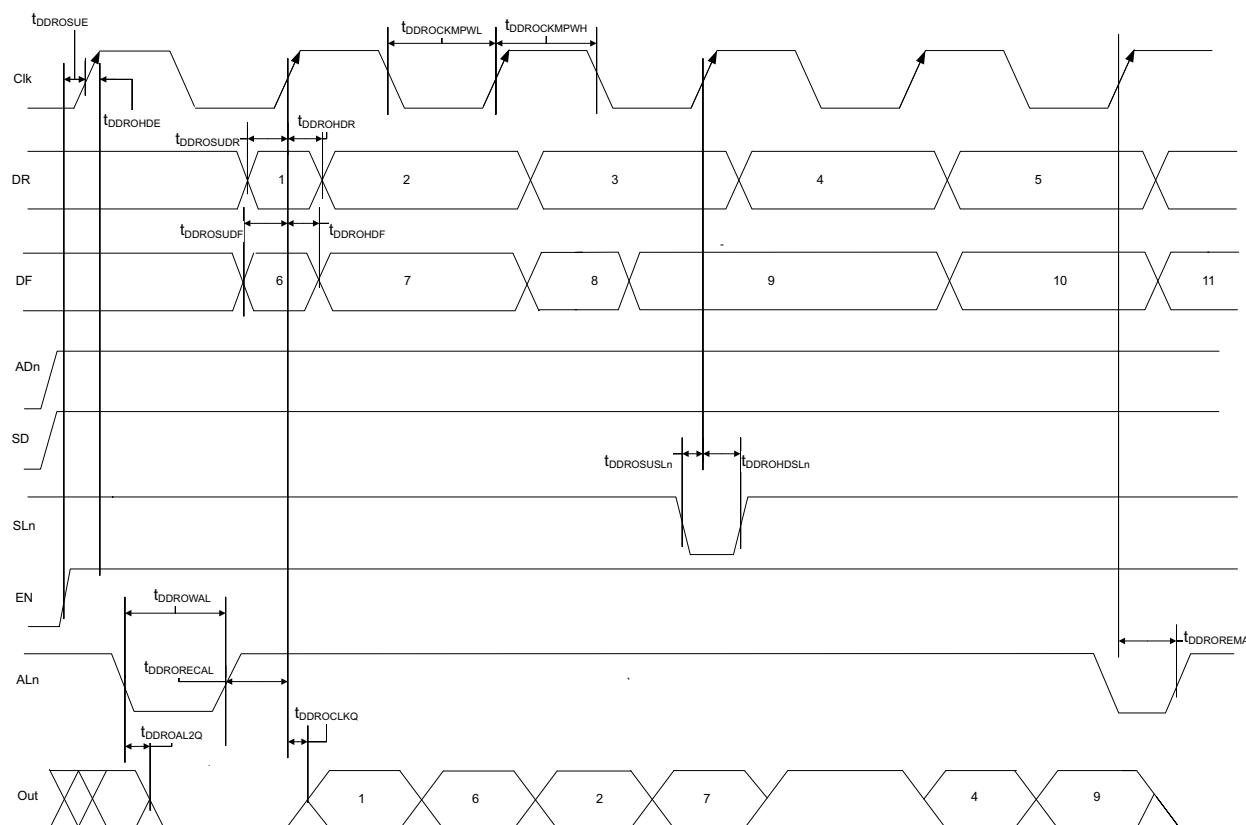
Figure 7 • I/O Register Input Timing Diagram

Table 221 • Input DDR Propagation Delays (continued)

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
T _{DDRIWAL}	Asynchronous load minimum pulse width for input DDR	F, F	0.304	0.357	ns
T _{DDRICKMPWH}	Clock minimum pulse width high for input DDR	B, B	0.075	0.088	ns
T _{DDRICKMPWL}	Clock minimum pulse width low for input DDR	B, B	0.159	0.187	ns

Figure 13 • Output DDR Timing Diagram**2.3.9.5 Timing Characteristics**

The following table lists the output DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 222 • Output DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDROCLKQ}$	Clock-to-out of DDR for output DDR	E, G	0.263	0.309	ns
$T_{DDROSUDF}$	Data_F data setup for output DDR	F, E	0.143	0.168	ns
$T_{DDROSUDR}$	Data_R data setup for output DDR	A, E	0.19	0.223	ns
$T_{DDROHDF}$	Data_F data hold for output DDR	F, E	0	0	ns
$T_{DDROHDR}$	Data_R data hold for output DDR	A, E	0	0	ns
$T_{DDROSUE}$	Enable setup for input DDR	B, E	0.419	0.493	ns
T_{DDROHE}	Enable hold for input DDR	B, E	0	0	ns
$T_{DDROSUSLn}$	Synchronous load setup for input DDR	D, E	0.196	0.231	ns
$T_{DDROHSLn}$	Synchronous load hold for input DDR	D, E	0	0	ns
$T_{DDROAL2Q}$	Asynchronous load-to-out for output DDR	C, G	0.528	0.621	ns
$T_{DDRORECAL}$	Asynchronous load removal time for output DDR	C, E	0	0	ns
$T_{DDRORECAL}$	Asynchronous load recovery time for output DDR	C, E	0.034	0.04	ns

2.3.10.2 Timing Characteristics

The following table lists the combinatorial cell propagation delays in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

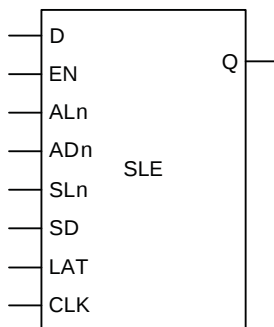
Table 223 • Combinatorial Cell Propagation Delays

Combinatorial Cell	Equation	Symbol	–1	–Std	Unit
INV	$Y = !A$	T_{PD}	0.1	0.118	ns
AND2	$Y = A \cdot B$	T_{PD}	0.164	0.193	ns
NAND2	$Y = !(A \cdot B)$	T_{PD}	0.147	0.173	ns
OR2	$Y = A + B$	T_{PD}	0.164	0.193	ns
NOR2	$Y = !(A + B)$	T_{PD}	0.147	0.173	ns
XOR2	$Y = A \oplus B$	T_{PD}	0.164	0.193	ns
XOR3	$Y = A \oplus B \oplus C$	T_{PD}	0.225	0.265	ns
AND3	$Y = A \cdot B \cdot C$	T_{PD}	0.209	0.246	ns
AND4	$Y = A \cdot B \cdot C \cdot D$	T_{PD}	0.287	0.338	ns

2.3.10.3 Sequential Module

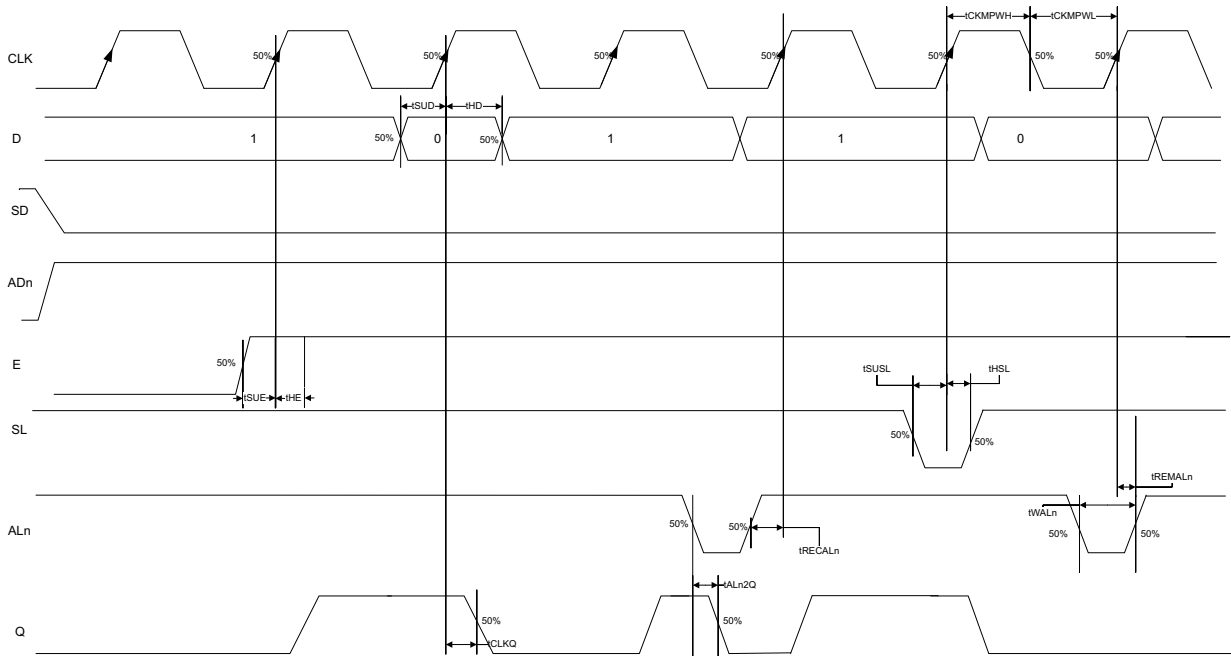
IGLOO2 and SmartFusion2 SoC FPGAs offer a separate flip-flop which can be used independently from the LUT. The flip-flop can be configured as a register or a latch and has a data input and optional enable, synchronous load (clear or preset), and asynchronous load (clear or preset).

Figure 15 • Sequential Module



The following figure shows a configuration with SD = 0 (synchronous clear) and ADn = 1 (asynchronous clear) for a flip-flop (LAT = 0).

Figure 16 • Sequential Module Timing Diagram



2.3.10.3.1 Timing Characteristics

The following table lists the register delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 224 • Register Delays

Parameter	Symbol	-1	-Std	Unit
Clock-to-Q of the core register	T_{CLKQ}	0.108	0.127	ns
Data setup time for the core register	T_{SUD}	0.254	0.298	ns
Data hold time for the core register	T_{HD}	0	0	ns
Enable setup time for the core register	T_{SUE}	0.335	0.394	ns
Enable hold time for the core register	T_{HE}	0	0	ns
Synchronous load setup time for the core register	T_{SUSL}	0.335	0.394	ns
Synchronous load hold time for the core register	T_{HSL}	0	0	ns
Asynchronous Clear-to-Q of the core register (ADn = 1)	T_{ALN2Q}	0.473	0.556	ns
Asynchronous preset-to-Q of the core register (ADn = 0)		0.451	0.531	ns
Asynchronous load removal time for the core register	T_{RECALN}	0	0	ns
Asynchronous load recovery time for the core register	T_{RECALN}	0.353	0.415	ns
Asynchronous load minimum pulse width for the core register	T_{WALN}	0.266	0.313	ns
Clock minimum pulse width high for the core register	T_{CKMPWH}	0.065	0.077	ns
Clock minimum pulse width low for the core register	T_{CKMPWL}	0.139	0.164	ns

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 16K × 1 in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 235 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 16K × 1

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.32		0.377	ns
Read access time without pipeline register	T_{CLK2Q}		2.269		2.669	ns
Access time with feed-through write timing			1.51		1.777	ns
Address setup time	T_{ADDRSU}	0.626		0.737		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.322		0.378		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.51		1.777	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.53		0.624		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.547		1.82	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.454		0.534		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

Table 239 • μ SRAM (RAM128x9) in 128 × 9 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 128 × 8 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 240 • μ SRAM (RAM128x8) in 128 × 8 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns

Table 240 • μ SRAM (RAM128x8) in 128 × 8 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

Table 259 • 2 Step IAP Programming (Fabric Only)

M2S/M2GL Device	Image size		Authenticate	Program	Verify	Unit
	Bytes					
005	302672	4		39	6	Sec
010	568784	7		45	12	Sec
025	1223504	14		55	23	Sec
050	2424832	29		74	40	Sec
060	2418896	39		83	50	Sec
090	3645968	60		106	73	Sec
150	6139184	100		154	120	Sec

Table 260 • 2 Step IAP Programming (eNVM Only)

M2S/M2GL Device	Image size		Authenticate	Program	Verify	Unit
	Bytes					
005	137536	2		59	5	Sec
010	274816	4		98	11	Sec
025	274816	4		100	10	Sec
050	2,78,528	3		107	9	Sec
060	268480	5		98	22	Sec
090	544496	10		174	43	Sec
150	544496	10		175	44	Sec

Table 261 • 2 Step IAP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size		Authenticate	Program	Verify	Unit
	Bytes					
005	439296	6		78	11	Sec
010	842688	11		122	21	Sec
025	1497408	19		135	32	Sec
050	2695168	32		158	48	Sec
060	2686464	43		159	70	Sec
090	4190208	68		258	115	Sec
150	6682768	109		308	162	Sec

The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 270 • Math Block with Input Register Used and Output in Bypass Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input register setup time	T_{MISU}	0.149		0.176		ns
Input register hold time	T_{MIHD}	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	–0.012		–0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	–0.005		–0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	T_{MICQ}		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 271 • Math Block with Input and Output in Bypass Mode

Parameter	Symbol	–1	–Std	Unit
		Max	Max	
Input to output delay	T_{MIQ}	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 272 • eNVM Read Performance

Symbol	Description	Operating Temperature Range						Unit
		–1	–Std	–1	–Std	–1	–Std	
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 273 • eNVM Page Programming

Symbol	Description	Operating Temperature Range						Unit
		–1	–Std	–1	–Std	–1	–Std	
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

2.3.16 SRAM PUF

For more details on static random-access memory (SRAM) physical unclonable functions (PUF) services, see [AC434: Using SRAM PUF System Service in SmartFusion2 Application Note](#).

The following table lists the SRAM PUF in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 274 • SRAM PUF

Service	PUF Off		PUF On		Unit
	Typ	Max	Typ	Max	
Create activation code	709.1	746.4	754.4	762.5	ms
Delete activation code	1329.3	1399.3	1414.1	1429.3	ms
Create intrinsic keycode	656.6	691.1	698.5	706.0	ms
Create extrinsic keycode	656.6	691.1	698.5	706.0	ms
Get number of keys	1.3	1.4	1.4	1.4	ms
Export (Kc0, Kc1)	998.0	1050.5	1061.7	1073.1	ms
Export 2 keycodes	2020.2	2126.5	2149.2	2172.3	ms
Export 4 keycodes	3065.7	3227.0	3261.3	3296.4	ms
Export 8 keycodes	5101.0	5369.5	5426.6	5485.0	ms
Export 16 keycodes	9212.1	9697.0	9800.1	9905.5	ms
Import (Kc0, Kc1)	39.7	41.8	42.2	42.7	ms
Import 2 keycodes	50.1	52.7	53.3	53.9	ms
Import 4 keycodes	60.6	63.8	64.5	65.2	ms
Import 8 keycodes	80.9	85.1	86.1	87.0	ms
Import 16 keycodes	123.8	130.4	131.7	133.2	ms
Delete keycode	552.5	581.6	587.8	594.1	ms
Fetch key	31.4	33.0	33.4	33.7	ms
Fetch ecc key	20.0	21.1	21.3	21.5	ms
Get seed	2.0	2.1	2.2	2.2	ms

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

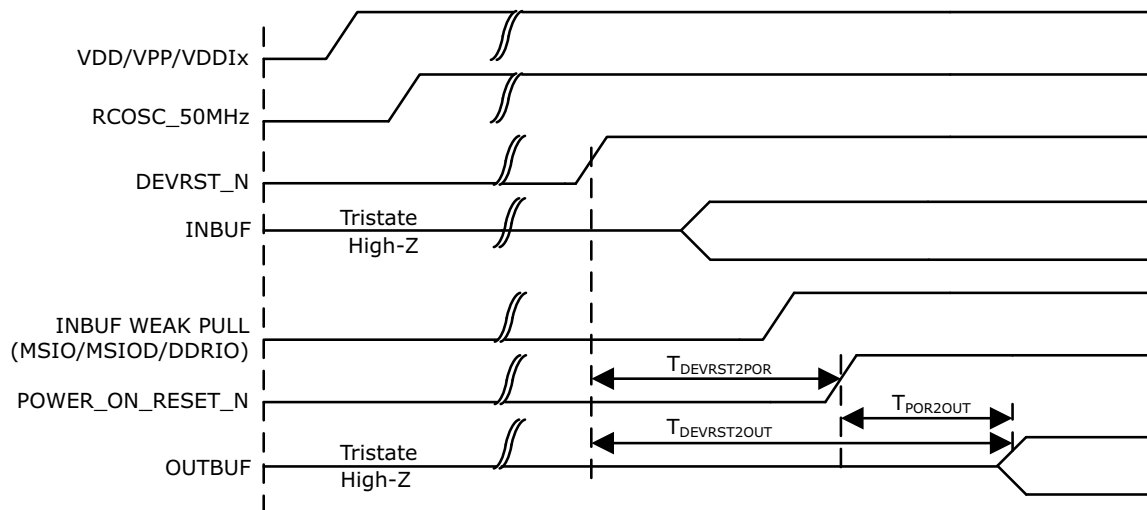
Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

Figure 20 • DEVRST_N to Functional Timing Diagram for IGLOO2

2.3.27 Flash*Freeze Timing Characteristics

The following table lists the Flash*Freeze entry and exit times in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 293 • Flash*Freeze Entry and Exit Times

Parameter	Symbol	Entry/Exit Timing FCLK = 100MHz		Entry/Exit Timing FCLK = 3 MHz		Unit	Conditions
		005, 010, 025, 060, 090, and 150	050	All Devices			
Entry time	TFF_ENTRY	160	150	320		μs	eNVM and MSS/HPMS PLL = ON
		215	200	430		μs	eNVM and MSS/HPMS PLL= OFF
Exit time with respect to the MSS PLL Lock	TFF_EXIT	100	100	140		μs	eNVM and MSS/HPMS PLL = ON during F*F
		136	120	190		μs	eNVM = ON and MSS/HPMS PLL = OFF during F*F and MSS/HPMS PLL turned back on at exit
		200	200	285		μs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
		200	200	285		μs	eNVM = OFF and MSS/HPMS PLL = ON during F*F and eNVM turned back on at exit