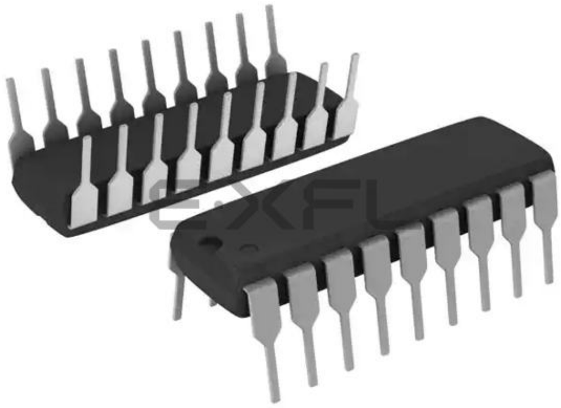

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Discontinued at Digi-Key
Core Processor	Z8
Core Size	8-Bit
Speed	8MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	14
Program Memory Size	1KB (1K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	125 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	External
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86e0408pec1903

FEATURES

- 14 Input/Output Lines
- Six Vectored, Prioritized Interrupts (3 falling edge, 1 rising edge, 2 timers)
- Two Analog Comparators
- Program Options:
  - Low Noise
  - ROM Protect
  - Auto Latch
  - Watch-Dog Timer (WDT)
  - EPROM/Test Mode Disable
- Two Programmable 8-Bit Counter/Timers, Each with 6-Bit Programmable Prescaler
- WDT/ Power-On Reset (POR)
- On-Chip Oscillator that Accepts XTAL, Ceramic Resonance, LC, RC, or External Clock
- Clock-Free WDT Reset
- Low-Power Consumption (50 mw typical)
- Fast Instruction Pointer (1µs @ 12 MHz)
- RAM Bytes (125)

GENERAL DESCRIPTION

Zilog's Z86E04/E08 Microcontrollers (MCU) are One-Time Programmable (OTP) members of Zilog's single-chip Z8® MCU family that allow easy software development, debug, prototyping, and small production runs not economically desirable with masked ROM versions.

For applications demanding powerful I/O capabilities, the Z86E04/E08's dedicated input and output lines are grouped into three ports, and are configurable under software control to provide timing, status signals, or parallel I/O.

Two on-chip counter/timers, with a large number of user selectable modes, offload the system of administering real-time tasks such as counting/timing and I/O data communications.

Note: All Signals with an overline, " ‾ ", are active Low, for example: B/$\overline{W}$ (WORD is active Low); $\overline{B}$/W (BYTE is active Low, only).

Power connections follow conventional descriptions below:

Connection	Circuit	Device
Power	V_{CC}	V_{DD}
Ground	GND	V_{SS}

GENERAL DESCRIPTION (Continued)

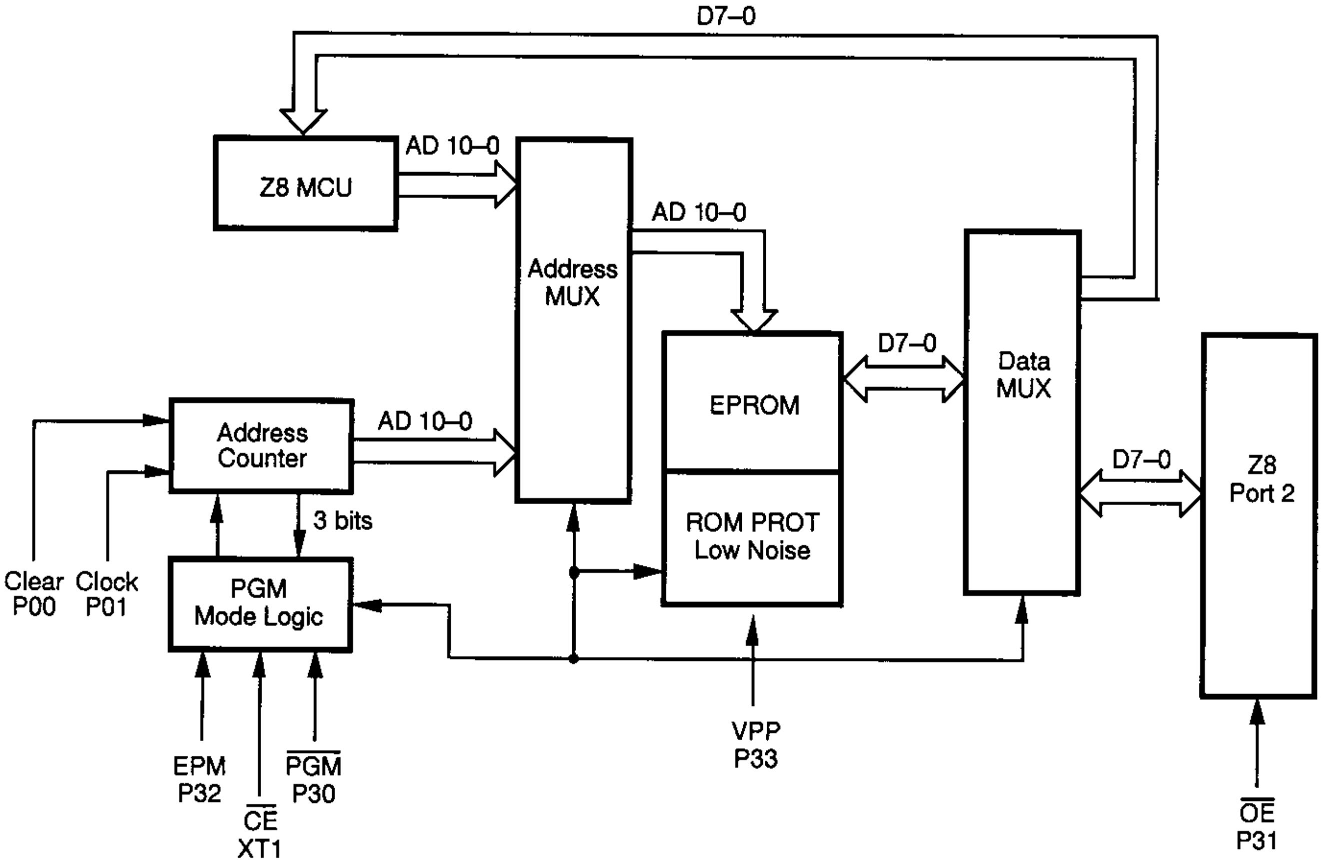


Figure 2. EPROM Programming Mode Block Diagram

ABSOLUTE MAXIMUM RATINGS

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability. Total power dissipation should not exceed 462 mW for the package. Power dissipation is calculated as follows:

Total Power Dissipation = V_{DD} x [I_{DD}–(sum of I_{OH})]
+ sum of [(V_{DD}–V_{OH}) x I_{OH}]
+ sum of (V_{0L} x I_{0L})

Parameter	Min	Max	Units	Note
Ambient Temperature under Bias	–40	+105	C	
Storage Temperature	–65	+150	C	
Voltage on any Pin with Respect to V_{SS}	–0.7	+12	V	1
Voltage on V_{DD} Pin with Respect to V_{SS}	–0.3	+7	V	
Voltage on Pins 7, 8, 9, 10 with Respect to V_{SS}	–0.6	V_{DD}+1	V	2
Total Power Dissipation		1.65	W	
Maximum Allowable Current out of V_{SS}		300	mA	
Maximum Allowable Current into V_{DD}		220	mA	
Maximum Allowable Current into an Input Pin	–600	+600	µA	3
Maximum Allowable Current into an Open-Drain Pin	–600	+600	µA	4
Maximum Allowable Output Current Sinked by Any I/O Pin		25	mA	
Maximum Allowable Output Current Sourced by Any I/O Pin		25	mA	
Total Maximum Output Current Sinked by a Port		60	mA	
Total Maximum Output Current Sourced by a Port		45	mA	

Notes:
1. This applies to all pins except where otherwise noted. Maximum current into pin must be ± 600 µA.
2. There is no input protection diode from pin to V_{DD} (not applicable to EPROM Mode).
3. This excludes Pin 6 and Pin 7.
4. Device pin is not at an output Low state.

STANDARD TEST CONDITIONS

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to Ground. Positive current flows into the referenced pin (Figure 5).

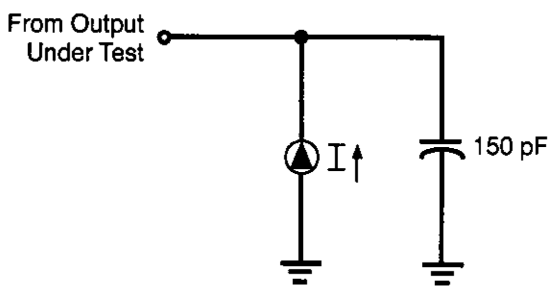


Figure 5. Test Load Diagram

CAPACITANCE

T_A = 25°C, V_{CC} = GND = 0V, f = 1.0 MHz, unmeasured pins returned to GND.

Parameter	Min	Max
Input capacitance	0	10 pF
Output capacitance	0	20 pF
I/O capacitance	0	25 pF

DC ELECTRICAL CHARACTERISTICS (Continued)

Sym	Parameter	V_{CC} [4]	T_A = 0°C to +70°C Min	Max	Typical @ 25°C	Units	Conditions	Notes
I_{CC1}	Standby Current (Low Noise Mode)	4.5V		4.0	2.5	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 1 MHz	7
		5.5V		4.0	2.5	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 1 MHz	7
		4.5V		4.5	2.8	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 2 MHz	7
		5.5V		4.5	2.8	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 2 MHz	7
		4.5V		5.0	3.0	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 4 MHz	7
		5.5V		5.0	3.0	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 4 MHz	7
I_{CC2}	Standby Current	4.5V		10.0	1.0	µA	STOP Mode V_{IN} = 0V, V_{CC} WDT is not Running	7,8
		5.5V		10.0	1.0	µA	STOP Mode V_{IN} = 0V,V_{CC} WDT is not Running	7,8
I_{ALL}	Auto Latch Low Current	4.5V		32.0	16	µA	$0V < V_{IN} < V_{CC}$	
		5.5V		32.0	16	µA	$0V < V_{IN} < V_{CC}$	
I_{ALH}	Auto Latch High Current	4.5V		–16.0	–8.0	µA	$0V < V_{IN} < V_{CC}$	
		5.5V		–16.0	–8.0	µA	$0V < V_{IN} < V_{CC}$	

Notes:
1. Port 2 and Port 0 only
2. V_{SS} = 0V = GND
3. The device operates down to V_{LV} of the specified frequency for V_{LV}. The minimum operational V_{CC} is determined on the value of the voltage V_{LV} at the ambient temperature. The V_{LV} increases as the temperature decreases.
4. V_{CC} = 4.5 to 5.5V, typical values measured at V_{CC} = 5.0V.
   The V_{CC} voltage specification of 5.5 V guarantees 5.0 V ± 0.5V with typical values measured at V_{CC} = 5.0V.
5. Standard Mode (not Low EMI Mode)
6. Z86E08 only
7. All outputs unloaded and all inputs are at V_{CC} or V_{SS} level.
8. If analog comparator is selected, then the comparator inputs must be at V_{CC} level.

DC ELECTRICAL CHARACTERISTICS
Extended Temperature

Sym	Parameter	V_{CC} [4]	T_A = –40°C to +105°C Min	Max	Typical @ 25°C	Units	Conditions	Notes
V_{INMAX}	Max Input Voltage	4.5V		12.0		V	$I_{IN} < 250\ \mu A$	1
		5.5V		12.0		V	$I_{IN} < 250\ \mu A$	1
V_{CH}	Clock Input High Voltage	4.5V	0.8 V_{CC}	V_{CC}+0.3	2.8	V	Driven by External Clock Generator	
		5.5V	0.8 V_{CC}	V_{CC}+0.3	2.8	V	Driven by External Clock Generator	
V_{CL}	Clock Input Low Voltage	4.5V	V_{SS}–0.3	0.2 V_{CC}	1.7	V	Driven by External Clock Generator	
		5.5V	V_{SS}–0.3	0.2 V_{CC}	1.7	V	Driven by External Clock Generator	
V_{IH}	Input High Voltage	4.5V	0.7 V_{CC}	V_{CC}+0.3	2.8	V		
		5.5V	0.7 V_{CC}	V_{CC}+0.3	2.8	V		
V_{IL}	Input Low Voltage	4.5V	V_{SS}–0.3	0.2 V_{CC}	1.5	V		
		5.5V	V_{SS}–0.3	0.2 V_{CC}	1.5	V		
V_{OH}	Output High Voltage	4.5V	V_{CC}–0.4		4.8	V	I_{OH} = –2.0 mA	5
		5.5V	V_{CC}–0.4		4.8	V	I_{OH} = –2.0 mA	5
		4.5V	V_{CC}–0.4			V	Low Noise @ I_{OH} = –0.5 mA	
		5.5V	V_{CC}–0.4			V	Low Noise @ I_{OH} = –0.5 mA	
V_{OL1}	Output Low Voltage	4.5V		0.4	0.1	V	I_{OL} = +4.0 mA	5
		5.5V		0.4	0.1	V	I_{OL} = +4.0 mA	5
		4.5V		0.4	0.1	V	Low Noise @ I_{OL} = 1.0 mA	
		5.5V		0.4	0.1	V	Low Noise @ I_{OL} = 1.0 mA	
V_{OL2}	Output Low Voltage	4.5V		1.0	0.3	V	I_{OL} = +12 mA,	5
		5.5V		1.0	0.3	V	I_{OL} = +12 mA,	5
V_{OFFSET}	Comparator Input Offset Voltage	4.5V		25.0	10.0	mV		
		5.5V		25.0	10.0	mV		
V_{LV}	V_{CC} Low Voltage Auto Reset		1.8	3.8	2.8	V	@ 6 MHz Max. Int. CLK Freq.	3
I_{IL}	Input Leakage (Input Bias Current of Comparator)	4.5V		–1.0	1.0	µA	V_{IN} = 0V, V_{CC}	
		5.5V		–1.0	1.0	µA	V_{IN} = 0V, V_{CC}	
I_{OL}	Output Leakage	4.5V		–1.0	1.0	µA	V_{IN} = 0V, V_{CC}	
		5.5V		–1.0	1.0	µA	V_{IN} = 0V, V_{CC}	
V_{ICR}	Comparator Input Common Mode Voltage Range		0	V_{CC} –1.5		V		

Sym	Parameter	V_{CC} [4]	T_A = –40°C to +105°C Min	Max	Typical @ 25°C	Units	Conditions	Notes
I_{CC1}	Standby Current (Low Noise Mode)	4.5V		4.0	2.5	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 1 MHz	7
		5.5V		4.0	2.5	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 1 MHz	7
		4.5V		4.5	2.8	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 2 MHz	7
		5.5V		4.5	2.8	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 2 MHz	7
		4.5V		5.0	3.0	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 4 MHz	7
		5.5V		5.0	3.0	mA	HALT Mode V_{IN} = 0V, V_{CC} @ 4 MHz	7
I_{CC2}	Standby Current	4.5V		20	1.0	µA	STOP Mode V_{IN} = 0V, V_{CC} WDT is not Running	7,8
		5.5V		20	1.0	µA	STOP Mode V_{IN} = 0V, V_{CC} WDT is not Running	7,8
I_{ALL}	Auto Latch Low Current	4.5V		40	16	µA	$0V < V_{IN} < V_{CC}$	
		5.5V		40	16	µA	$0V < V_{IN} < V_{CC}$	
I_{ALH}	Auto Latch High Current	4.5V		–20.0	–8.0	µA	$0V < V_{IN} < V_{CC}$	
		5.5V		–20.0	–8.0	µA	$0V < V_{IN} < V_{CC}$	

Notes:
1. Port 2 and Port 0 only
2. V_{SS} = 0V = GND
3. The device operates down to V_{LV} of the specified frequency for V_{LV}. The minimum operational V_{CC} is determined on the value of the voltage V_{LV} at the ambient temperature. The V_{LV} increases as the temperature decreases.
4. V_{CC} = 4.5V to 5.5V, typical values measured at V_{CC} = 5.0V
5. Standard Mode (not Low EMI Mode)
6. Z86E08 only
7. All outputs unloaded and all inputs are at V_{CC} or V_{SS} level.
8. If analog comparator is selected, then the comparator inputs must be at V_{CC} level.

AC ELECTRICAL CHARACTERISTICS

Low Noise Mode, Standard Temperature

				T_A= 0 °C to +70 °C					
				1 MHz		4 MHz			
No	**Symbol**	**Parameter**	V_{CC}	**Min**	**Max**	**Min**	**Max**	**Units**	**Notes**
1	TPC	Input Clock Period	4.5V	1000	DC	250	DC	ns	1
			5.5V	1000	DC	250	DC	ns	1
2	TrC TfC	Clock Input Rise and Fall Times	4.5V		25		25	ns	1
			5.5V		25		25	ns	1
3	TwC	Input Clock Width	4.5V	500		125		ns	1
			5.5V	500		125		ns	1
4.	TwTinL	Timer Input Low Width	4.5V	70		70		ns	1
			5.5V	70		70		ns	1
5	TwTinH	Timer Input High Width	4.5V	2.5TpC		2.5TpC			1
			5.5V	2.5TpC		2.5TpC			1
6	TpTin	Timer Input Period	4.5V	4TpC		4TpC			1
			5.5V	4TpC		4TpC			1
7	TrTin, TtTin	Timer Input Rise and Fall Time	4.5V		100		100	ns	1
			5.5V		100		100	ns	1
8	TwIL Low Time	Int. Request Input	4.5V	70		70		ns	1,2
			5.5V	70		70		ns	1,2
9	TwIH High Time	Int. Request Input	4.5V	2.5TpC		2.5TpC			1,2
			5.5V	2.5TpC		2.5TpC			1,2
10	Twdt	Watch-Dog Timer Delay Time for Timeout	4.5V	12		12		ms	1
			5.5V	12		12		ms	1

Notes:

1. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.
2. Interrupt request through Port 3 (P33–P31).

PIN FUNCTIONS (Continued)

XTAL1, XTAL2 *Crystal In, Crystal Out* (time-based input and output, respectively). These pins connect a parallel-resonant crystal, LC, or an external single-phase clock (8 MHz or 12 MHz max) to the on-chip clock oscillator and buffer.

Port 0, P02–P00. Port 0 is a 3-bit bidirectional, Schmitt-triggered CMOS-compatible I/O port. These three I/O lines can be globally configured under software control to be inputs or outputs (Figure 7).

Auto Latch. The Auto Latch puts valid CMOS levels on all CMOS inputs (except P33, P32, P31) that are not externally driven. A valid CMOS level, rather than a floating node, reduces excessive supply current flow in the input buffer. On Power-up and Reset, the Auto Latch will set the ports to an undetermined state of 0 or 1. Default condition is Auto Latches enabled.

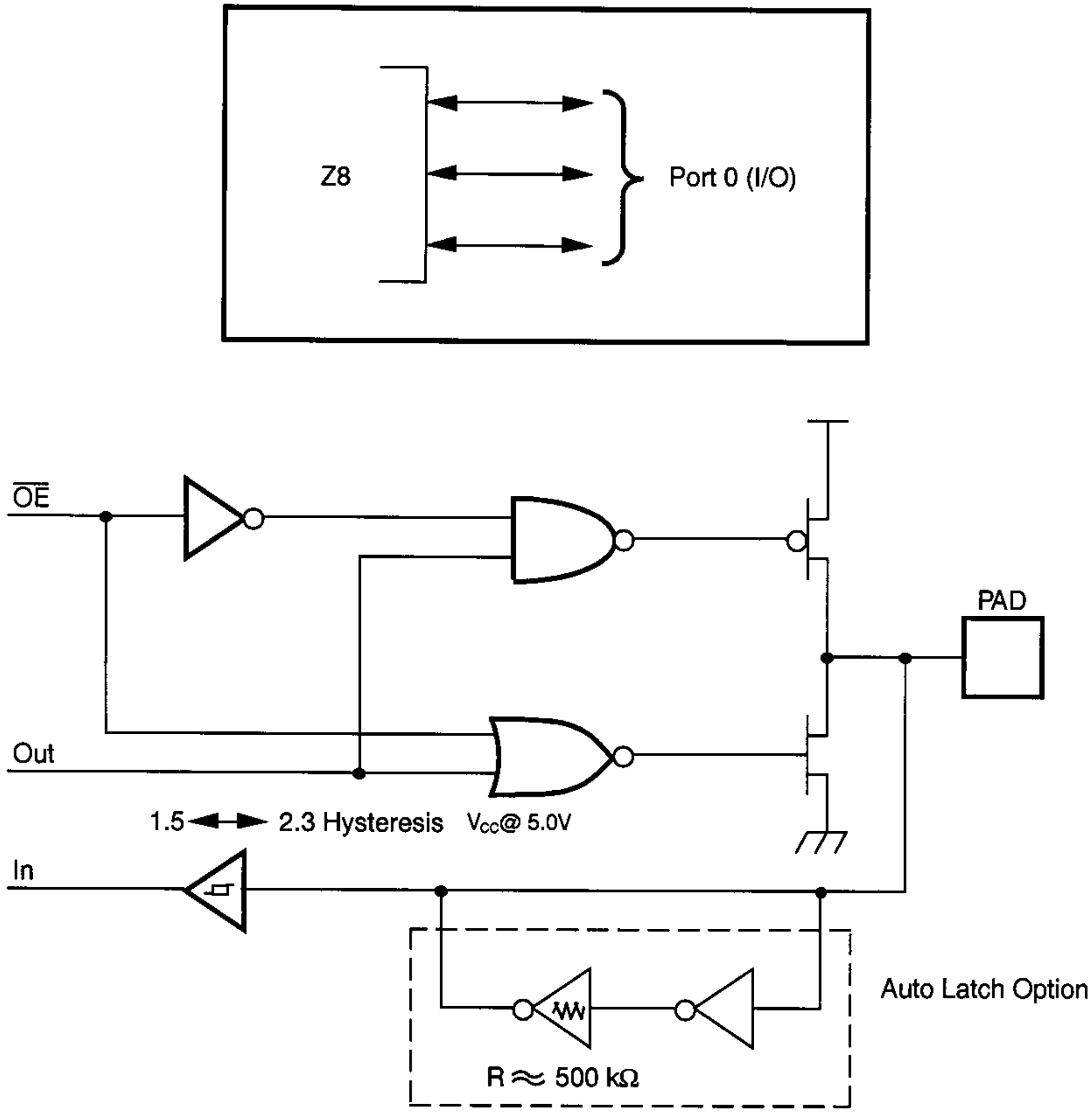


Figure 7. Port 0 Configuration

Port 2, P27–P20. Port 2 is an 8-bit, bit programmable, bi-directional, Schmitt-triggered CMOS-compatible I/O port. These eight I/O lines can be configured under software control to be inputs or outputs, independently. Bits programmed as outputs can be globally programmed as either push-pull or open-drain (Figure 8).

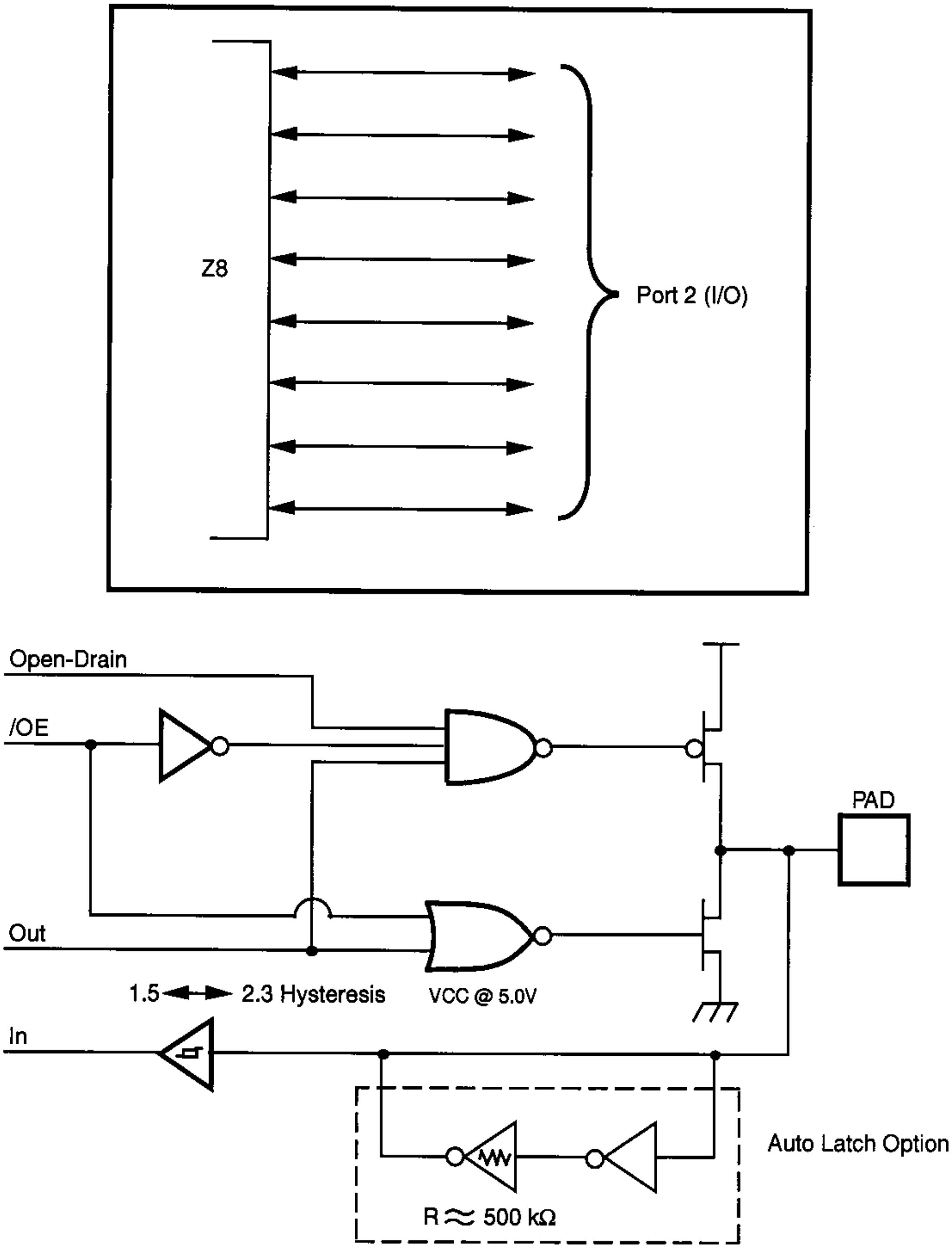


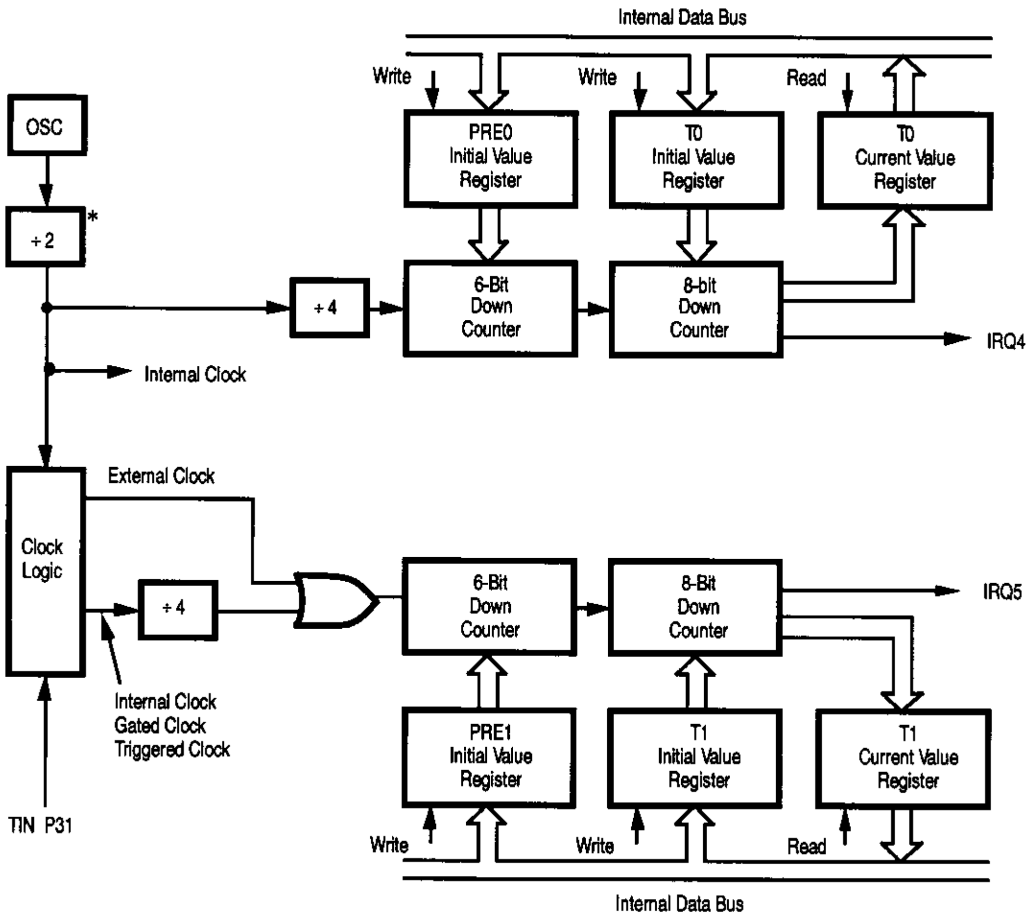
Figure 8. Port 2 Configuration

FUNCTIONAL DESCRIPTION (Continued)

Table 3. Control Registers

		Reset Condition								
Addr.	**Reg.**	**D7**	**D6**	**D5**	**D4**	**D3**	**D2**	**D1**	**D0**	**Comments**
FF	SPL	0	0	0	0	0	0	0	0	
FD	RP	0	0	0	0	0	0	0	0	
FC	FLAGS	U	U	U	U	U	U	U	U	
FB	IMR	0	U	U	U	U	U	U	U	
FA	IRQ	U	U	0	0	0	0	0	0	IRQ3 is used for positive edge detection
F9	IPR	U	U	U	U	U	U	U	U	
F8*	P01M	U	U	U	0	U	U	0	1	
F7*	P3M	U	U	U	U	U	U	0	0	
F6*	P2M	1	1	1	1	1	1	1	1	Inputs after reset
F5	PRE0	U	U	U	U	U	U	U	0	
F4	T0	U	U	U	U	U	U	U	U	
F3	PRE1	U	U	U	U	U	U	0	0	
F2	T1	U	U	U	U	U	U	U	U	
F1	TMR	0	0	0	0	0	0	0	0	

Note: *Registers are not reset after a STOP-Mode Recovery using P27 pin. A subsequent reset will cause these control registers to be reconfigured as shown in Table 4 and the user must avoid bus contention on the port pins or it may affect device reliability.



* **Note**: By passed, if Low EMI Mode is selected.

Figure 14. Counter/Timers Block Diagram

FUNCTIONAL DESCRIPTION (Continued)

Interrupts. The Z8 has six interrupts from six different sources. These interrupts are maskable and prioritized (Figure 15). The sources are divided as follows: the falling edge of P31 (AN1), P32 (AN2), P33 (REF), the rising edge of P32 (AN2), and two counter/timers. The Interrupt Mask Register globally or individually enables or disables the six interrupt requests (Table 4).

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder that is controlled by the Interrupt Priority register. All Z8 interrupts are vectored through locations in program memory. When an Interrupt machine cycle is activated, an Interrupt Request is granted. This disables all subsequent interrupts, saves the Program Counter and Status Flags, and then branches to the program memory vector location reserved for that interrupt. This memory location and the next byte contain the 16-bit starting address of the interrupt service routine for that particular interrupt request.

To accommodate polled interrupt systems, interrupt inputs are masked and the interrupt request register is polled to determine which of the interrupt requests needs service.

Note: User must select any Z86E08 mode in Zilog's C12 ICEBOX™ emulator. The rising edge interrupt is not supported on the CCP emulator (a hardware/software workaround must be employed).

Table 4. Interrupt Types, Sources, and Vectors

Name	Source	Vector Location	Comments
IRQ0	AN2(P32)	0,1	External (F)Edge
IRQ1	REF(P33)	2,3	External (F)Edge
IRQ2	AN1(P31)	4,5	External (F)Edge
IRQ3	AN2(P32)	6,7	External (R)Edge
IRQ4	T0	8,9	Internal
IRQ5	T1	10,11	Internal

Notes:
F = Falling edge triggered
R = Rising edge triggered

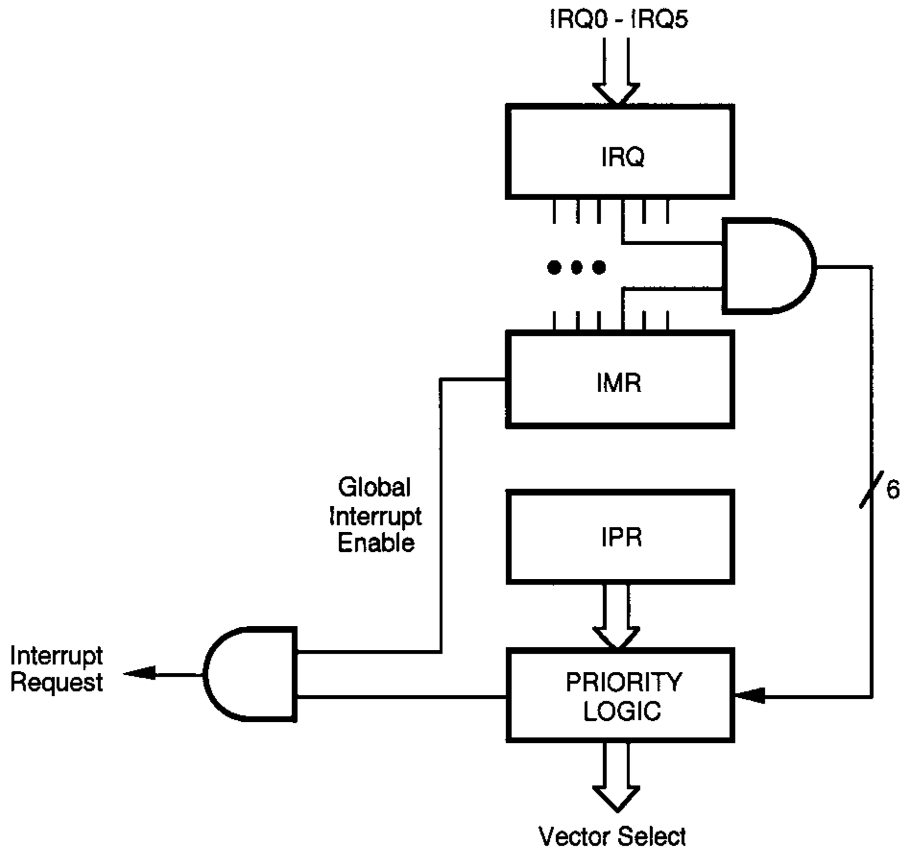


Figure 15. Interrupt Block Diagram

FUNCTIONAL DESCRIPTION (Continued)

Table 5. Typical Frequency vs. RC Values
V_{CC} = 5.0V @ 25°C

Resistor (R)	33 pFd A(Hz)	33 pFd B(Hz)	56 pFd A(Hz)	56 pFd B(Hz)	100 pFd A(Hz)	100 pFd B(Hz)	0.00 1μFd A(Hz)	0.00 1μFd B(Hz)
1.0M	33K	31K	20K	20K	12K	11K	1.4K	1.4K
560K	56K	52K	34K	32K	20K	19K	2.5K	2.4K
220K	144K	130K	84K	78K	48K	45K	6K	6K
100K	315K	270K	182K	164K	100K	95K	12K	12K
56K	552K	480K	330K	300K	185K	170K	23K	22K
20K	1.4M	1M	884K	740K	500K	450K	65K	61K
10K	2.6M	2M	1.6M	1.3M	980K	820K	130K	123K
5K	4.4M	3M	2.8M	2M	1.7K	1.3M	245K	225K
2K	8M	5M	6M	4M	3.8K	2.7M	600K	536K
1K	12M	7M	8.8M	6M	6.3K	4.2M	1.0M	950K

Notes:
A = STD Mode Frequency.
B = Low EMI Mode Frequency.

Table 6. Typical Frequency vs. RC Values
V_{CC} = 3.3V @ 25°C

Resistor (R)	33 pFd A(Hz)	33 pFd B(Hz)	56 pFd A(Hz)	56 pFd B(Hz)	100 pFd A(Hz)	100 pFd B(Hz)	0.00 1μFd A(Hz)	0.00 1μFd B(Hz)
1.0M	18K	18K	12K	12K	7.4K	7.7K	1K	1K
560K	30K	30K	20K	20K	12K	12K	1.6K	1.6K
220K	70K	70K	47K	47K	30K	30K	4K	4K
100K	150K	148K	97K	96K	60K	60K	8K	8K
56K	268K	250K	176K	170K	100K	100K	15K	15K
20K	690M	600K	463K	416K	286K	266K	40K	40K
10K	1.2M	1M	860K	730K	540K	480K	80K	76K
5K	2M	1.7M	1.5M	1.2M	950K	820K	151K	138K
2K	4.6M	3M	3.3M	2.4M	2.2M	1.6M	360K	316K
1K	7M	4.6M	5M	3.6M	3.6K	2.6M	660K	565K

Notes:
A = STD Mode Frequency.
B = Low EMI Mode Frequency.

FUNCTIONAL DESCRIPTION (Continued)

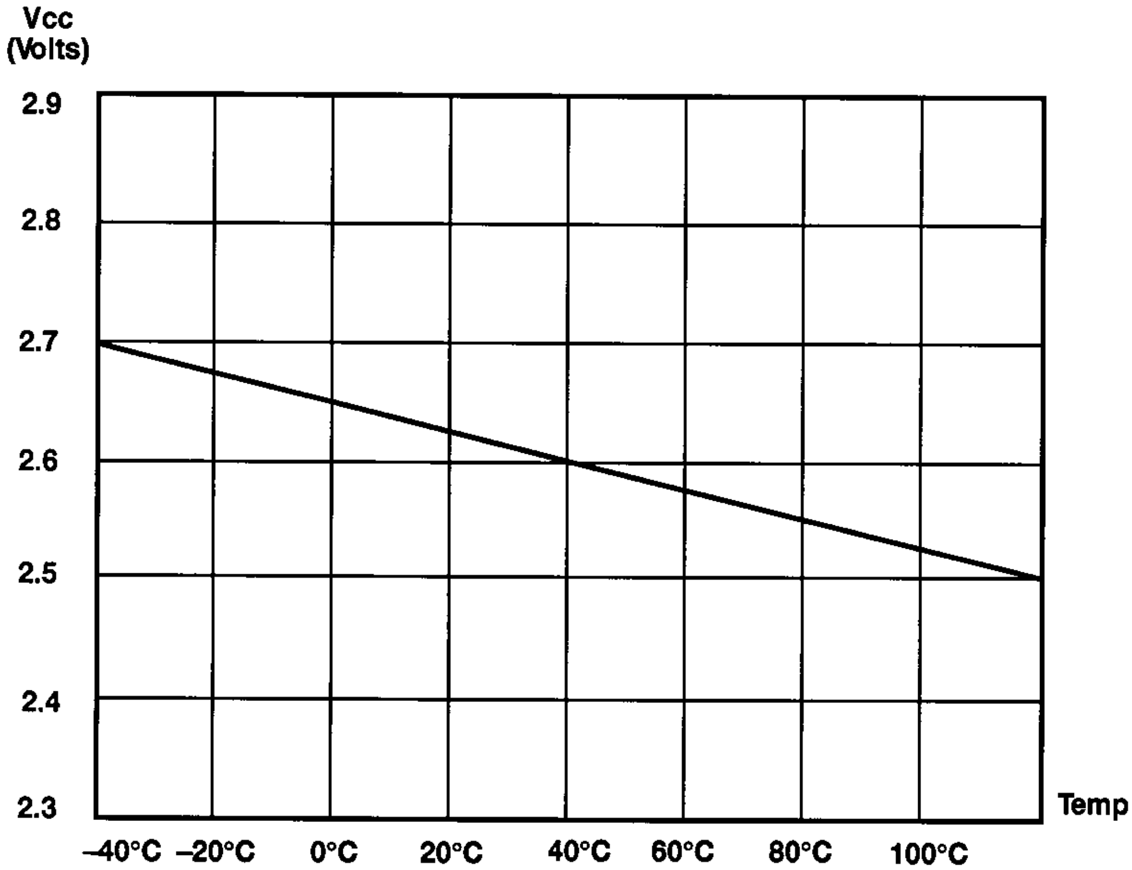
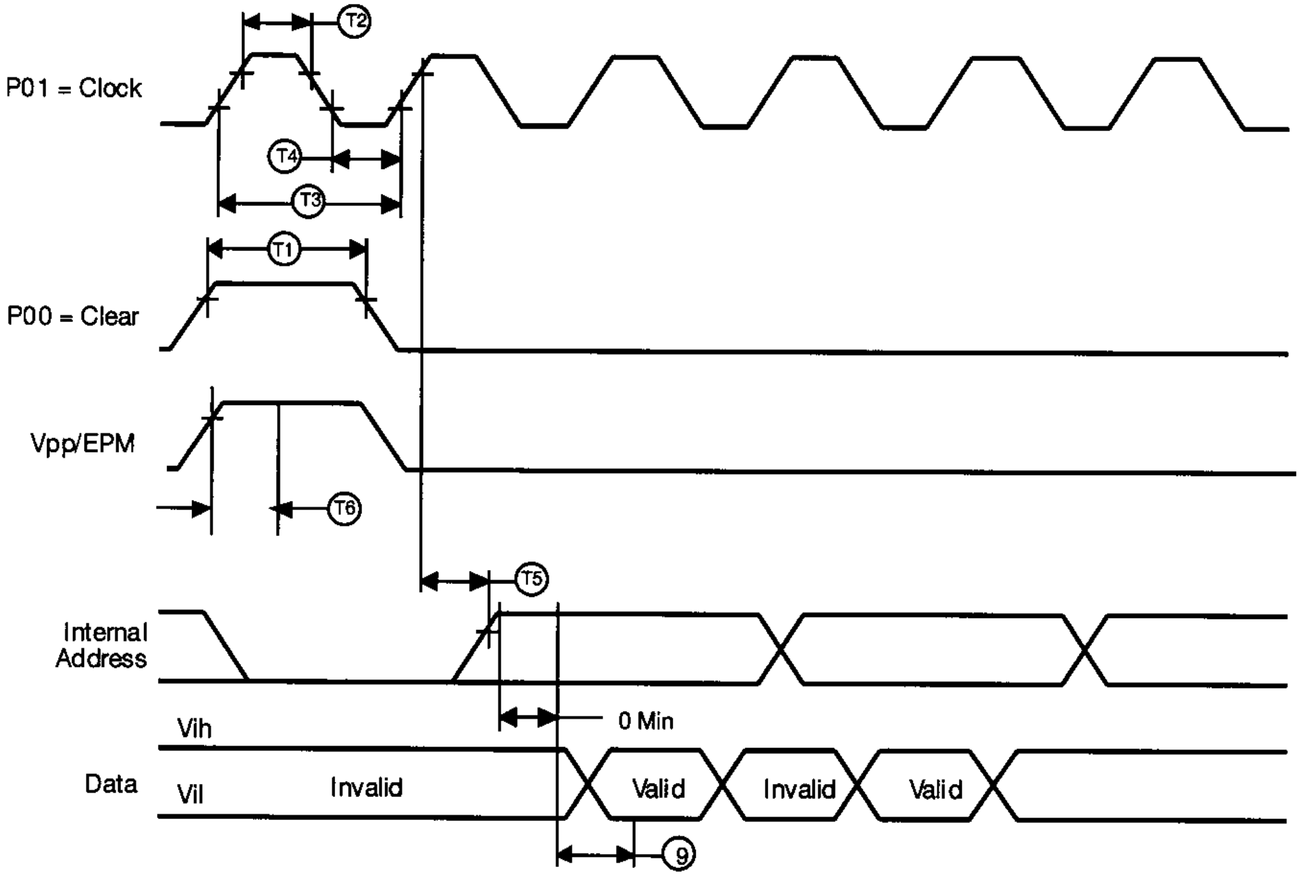


Figure 17. Typical Auto Reset Voltage (V_{LV}) vs. Temperature



Legend:	
T1 Reset Clock Width	30 ns Min
T2 Input Clock High	100 ns Min
T3 Input Clock Period	200 ns Min
T4 Input Clock Low	100 ns Min
T5 Clock to Address Counter Out Delay	15 ns Max
T6 Epm/Vpp Set up Time	40 µs Min

Figure 18. Z86E04/E08 Address Counter Waveform

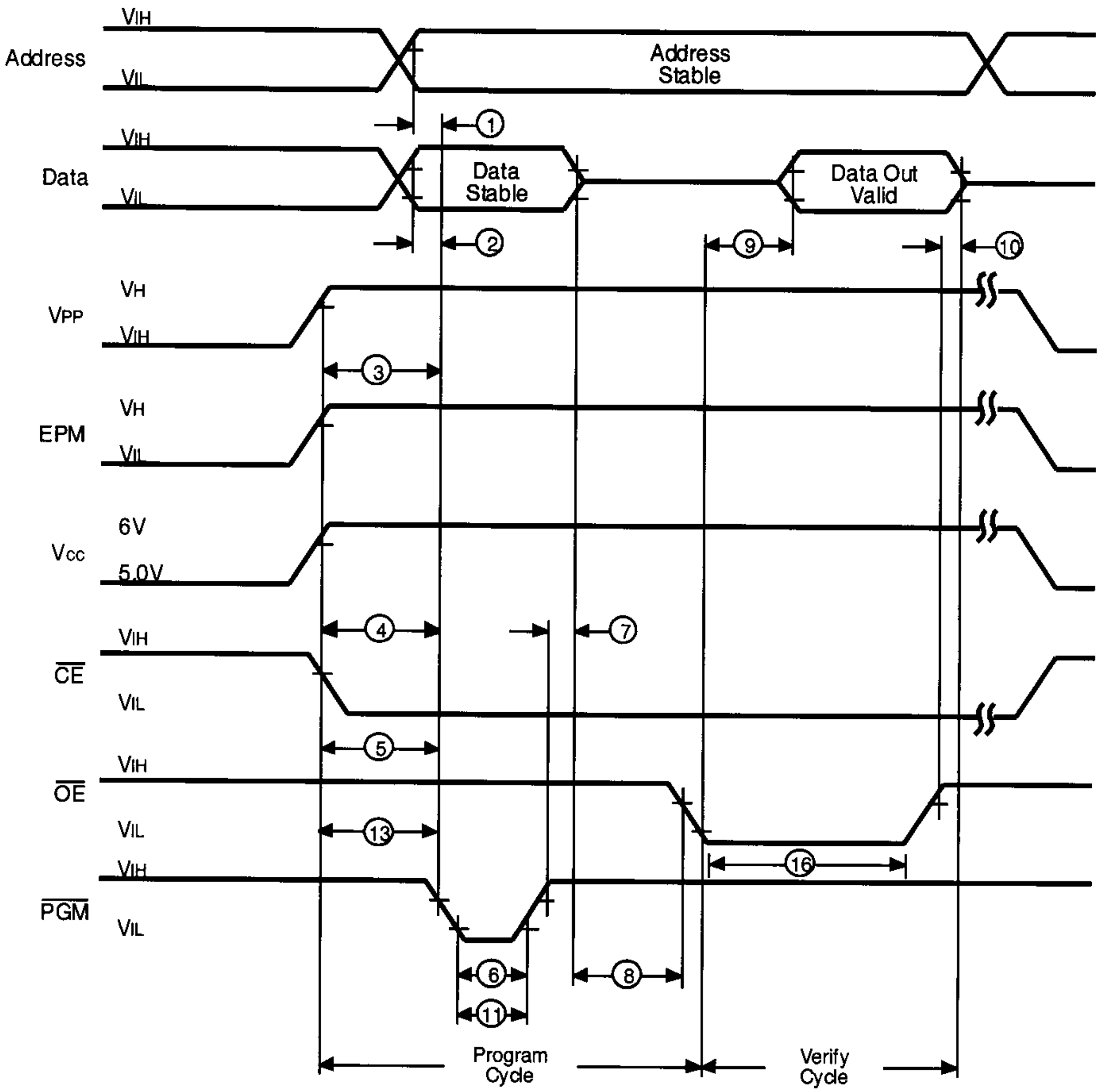


Figure 20. Z86E04/E08 Programming Waveform (Program and Verify)

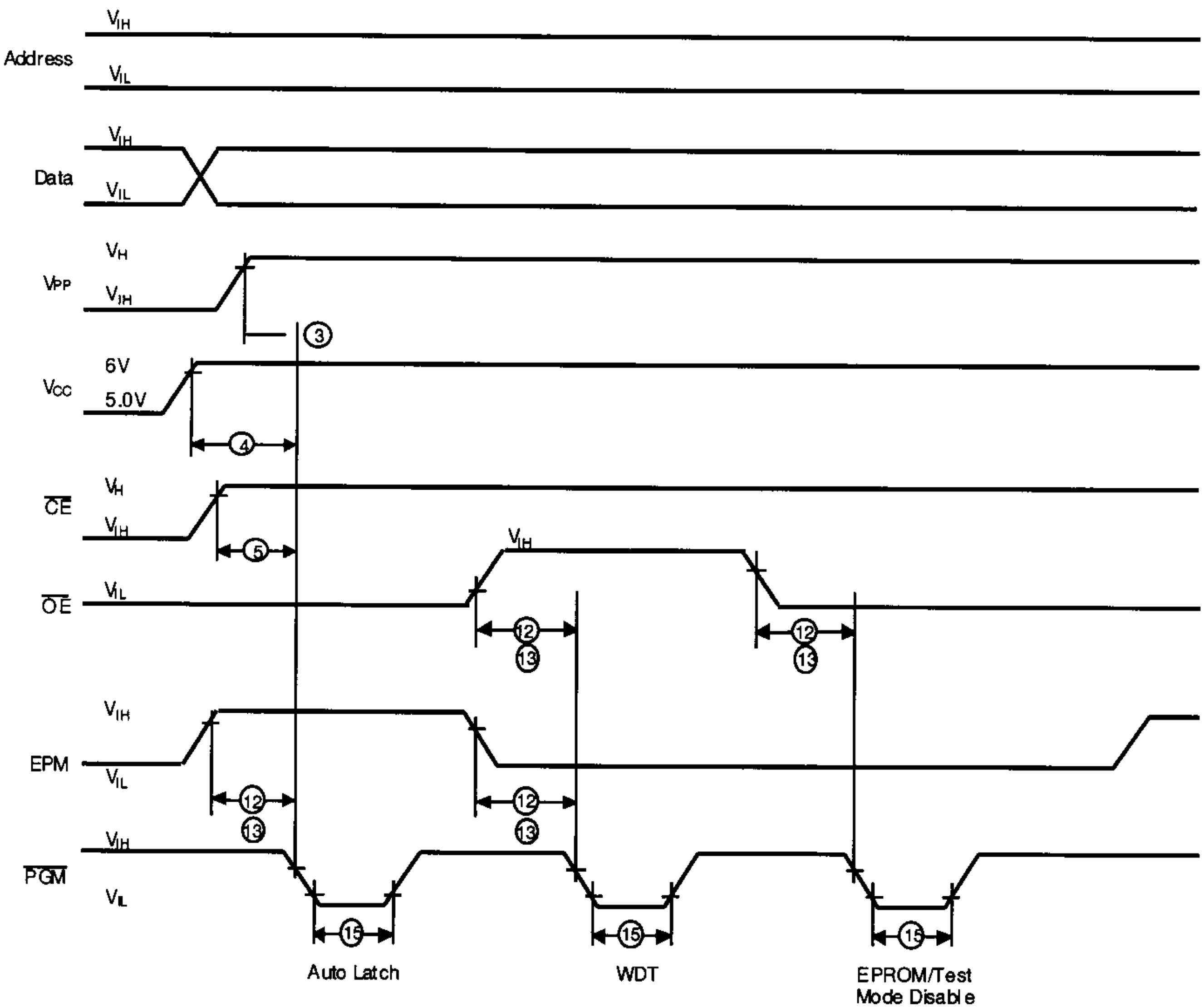


Figure 22. Z86E04/E08 Programming Options Waveform (Auto Latch Disable, Permanent WDT Enable and EPROM/Test Mode Disable)

FUNCTIONAL DESCRIPTION (Continued)

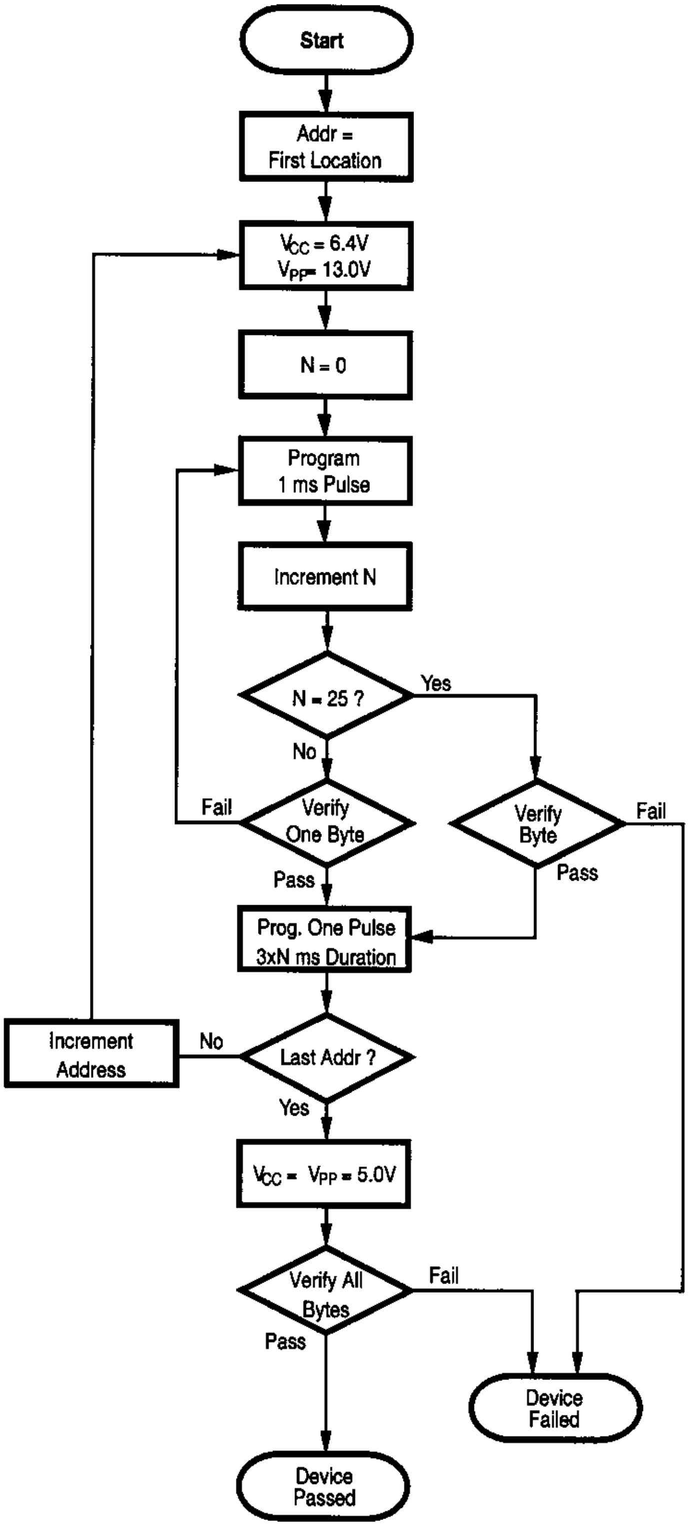


Figure 23. Z86E04/E08 Programming Algorithm

Z8 CONTROL REGISTERS

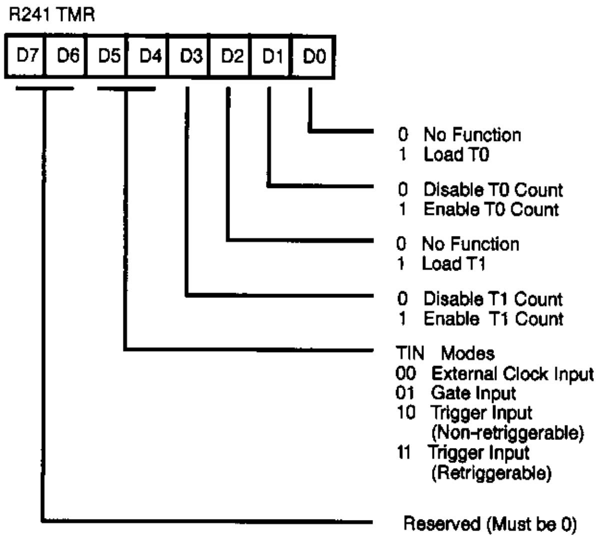


Figure 24. Timer Mode Register (F1$_H$: Read/Write)

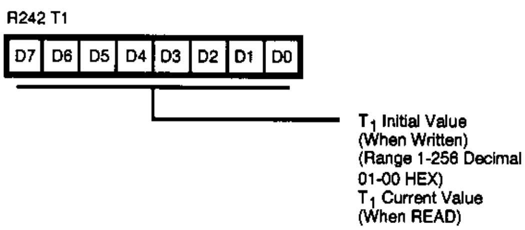


Figure 25. Counter Timer 1 Register (F2$_H$: Read/Write)

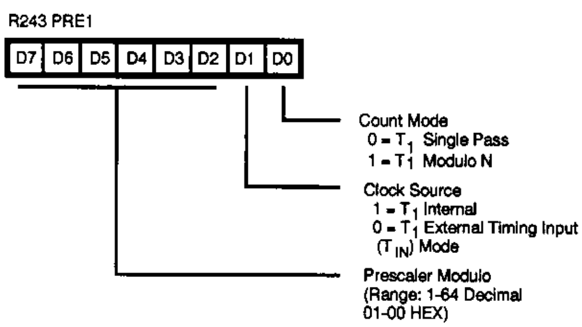


Figure 26. Prescaler 1 Register (F3$_H$: Write Only)

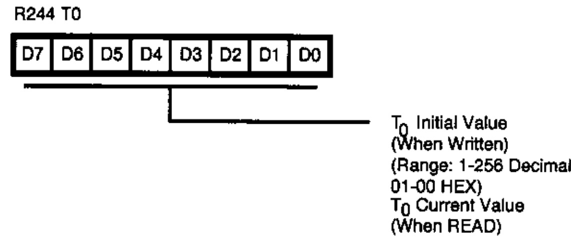


Figure 27. Counter/Timer 0 Register (F4$_H$: Read/Write)

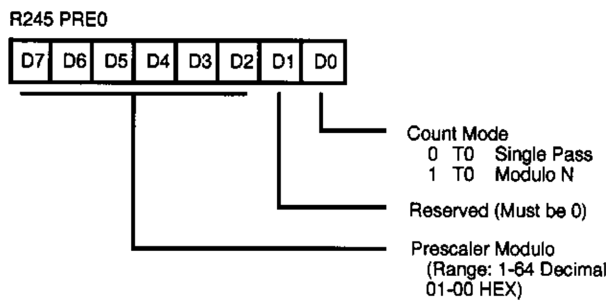


Figure 28. Prescaler 0 Register (F5$_H$: Write Only)

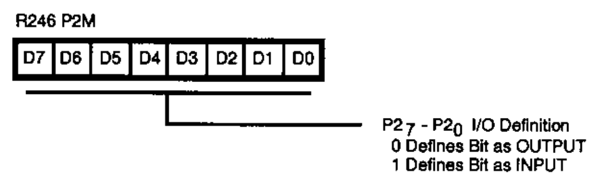


Figure 29. Port 2 Mode Register (F6$_H$: Write Only)

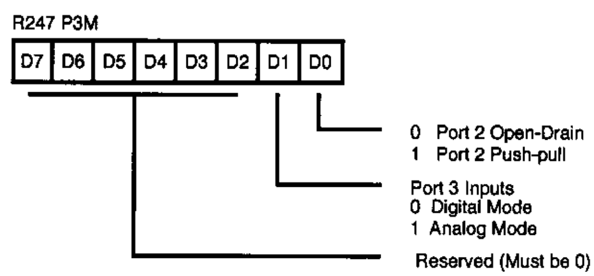


Figure 30. Port 3 Mode Register (F7$_H$: Write Only)