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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	12MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	14
Program Memory Size	1KB (1K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	125 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86e0412pec1903

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

FEATURES

- 14 Input/Output Lines
- Six Vectored, Prioritized Interrupts
 (3 falling edge, 1 rising edge, 2 timers)
- Two Analog Comparators
- Program Options:
 - Low Noise
 - ROM Protect
 - Auto Latch
 - Watch-Dog Timer (WDT)
 - EPROM/Test Mode Disable

- Two Programmable 8-Bit Counter/Timers, Each with
 6-Bit Programmable Prescaler
- WDT/ Power-On Reset (POR)
- On-Chip Oscillator that Accepts XTAL, Ceramic Resonance, LC, RC, or External Clock
- Clock-Free WDT Reset
- Low-Power Consumption (50 mw typical)
- Fast Instruction Pointer (1µs @ 12 MHz)
- RAM Bytes (125)

GENERAL DESCRIPTION

Zilog's Z86E04/E08 Microcontrollers (MCU) are One-Time Programmable (OTP) members of Zilog's single-chip Z8® MCU family that allow easy software development, debug, prototyping, and small production runs not economically desirable with masked ROM versions.

For applications demanding powerful I/O capabilities, the Z86E04/E08's dedicated input and output lines are grouped into three ports, and are configurable under software control to provide timing, status signals, or parallel I/O.

Two on-chip counter/timers, with a large number of user selectable modes, offload the system of administering real-time tasks such as counting/timing and I/O data communications.

Note: All Signals with an overline, "", are active Low, for example: B/W (WORD is active Low); B/W (BYTE is active Low, only).

Power connections follow conventional descriptions below:

Connection	Circuit	Device
Power	V _{cc}	V _{DD}
Ground	GND	V_{SS}

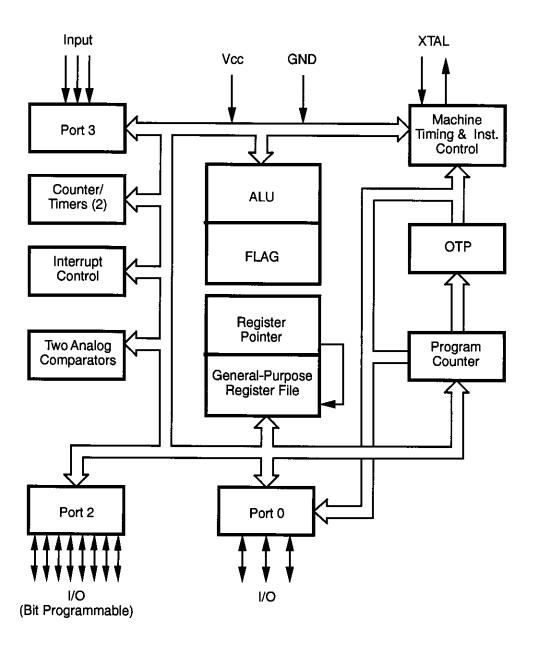


Figure 1. Functional Block Diagram

GENERAL DESCRIPTION (Continued)

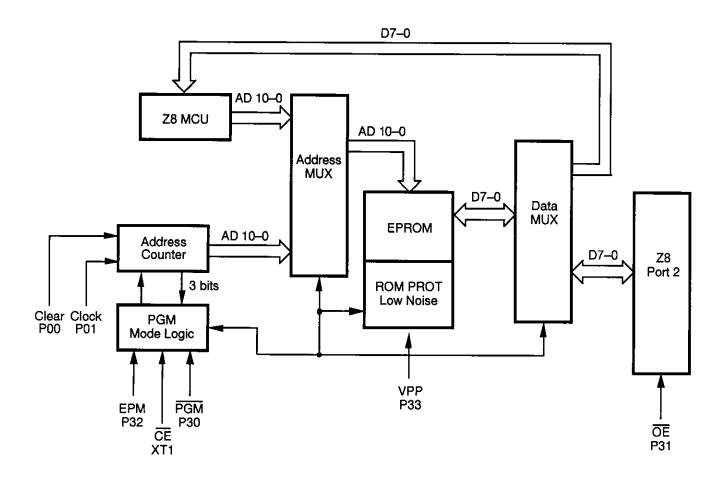


Figure 2. EPROM Programming Mode Block Diagram

PIN DESCRIPTION

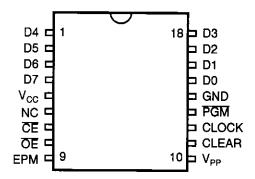


Figure 3. 18-Pin EPROM Mode Configuration

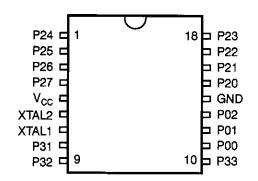


Figure 4. 18-Pin DIP/SOIC Mode Configuration

Table 1. 18-Pin DIP Pin Identification

EPROM	Programmi	ng Mode		
Pin#	Symbol	Function	Direction	
1–4	D4-D7	Data 4, 5, 6, 7	In/Output	
5	V _{cc}	Power Supply		
6	NC	No Connection		
7	CE	Chip Enable	Input	
8	ŌĒ	Output Enable	Input	
9	EPM	EPROM Prog Mode	Input	
10	V _{PP}	Prog Voltage	Input	
11	Clear	Clear Clock	Input	
12	Clock	Address	Input	
13	PGM	Prog Mode	Input	
14	GND	Ground		
15–18	D0-D3	Data 0,1, 2, 3	In/Output	

Table 2. 18-Pin DIP/SOIC Pin Identification

Standa	rd Mode		
Pin#	Symbol	Function	Direction
1–4	P24-P27	Port 2, Pins 4,5,6,7	In/Output
5	V _{CC}	Power Supply	<u></u>
6	XTAL2	Crystal Osc. Clock	Output
7	XTAL1	Crystal Osc. Clock	Input
8	P31	Port 3, Pin 1, AN1	Input
9	P32	Port 3, Pin 2, AN2	Input
10	P33	Port 3, Pin 3, REF	Input
11–13	P00-P02	Port 0, Pins 0,1,2	In/Output
14	GND	Ground	
15–18	P20-P23	Port 2, Pins 0,1,2,3	In/Output

ABSOLUTE MAXIMUM RATINGS

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability. Total power

dissipation should not exceed 462 mW for the package. Power dissipation is calculated as follows:

Total Power Dissipation = $V_{DD} \times [I_{DD} - (sum of I_{OH})]$ + sum of $[(V_{DD} - V_{OH}) \times I_{OH}]$ + sum of $(V_{0L} \times I_{0L})$

Parameter	Min	Max	Units	Note
Ambient Temperature under Bias	-40	+105	С	
Storage Temperature	-6 5	+150	С	
Voltage on any Pin with Respect to V _{ss}	-0.7	+12	٧	1
Voltage on V _{DD} Pin with Respect to V _{SS}	-0.3	+7	V	
Voltage on Pins 7, 8, 9, 10 with Respect to V _{SS}	-0.6	V _{DD} +1	V	2
Total Power Dissipation		1.65	W	·
Maximum Allowable Current out of V _{SS}	-	300	mA	
Maximum Allowable Current into V _{DD}	- \ W.L	220	mA	
Maximum Allowable Current into an Input Pin	-600	+600	μА	3
Maximum Allowable Current into an Open-Drain Pin	-600	+600	μA	4
Maximum Allowable Output Current Sinked by Any I/O Pin		25	mA	
Maximum Allowable Output Current Sourced by Any I/O Pin		25	mA	
Total Maximum Output Current Sinked by a Port		60	mA	
Total Maximum Output Current Sourced by a Port		45	mA	

- 1. This applies to all pins except where otherwise noted. Maximum current into pin must be \pm 600 μ A.
- 2. There is no input protection diode from pin to V_{DD} (not applicable to EPROM Mode).
- 3. This excludes Pin 6 and Pin 7.
- 4. Device pin is not at an output Low state.

DC ELECTRICAL CHARACTERISTICS

Standard Temperature

			$T_A = 0^{\circ}C$	to +70°C	Typical			
Sym	Parameter	V _{cc} [4]	Min	Max	@ 25°C	Units	Conditions	Notes
VINMAX	Max Input Voltage	4.5V	<u> </u>	12		V	I _{In} <250 μA	1
		5.5V		12		٧	I _{In} <250 μΑ	1
V _{CH}	Clock Input High Voltage	4.5V	0.8 V _{CC}	V _{CC} +0.3	2.8	٧	Driven by External Clock Generator	
		5.5V	0.8 V _{CC}	V _{CC} +0.3	2.8	V	Driven by External Clock Generator	- "
V _{CL}	Clock Input Low Voltage	4.5V	V _{SS} -0.3	0.2 V _{CC}	1.7	V	Driven by External Clock Generator	
		5.5V	V _{SS} -0.3	0.2 V _{CC}	1.7	V	Driven by External Clock Generator	
V _{IH}	Input High Voltage	4.5V	0.7 V _{CC}	V _{CC} +0.3	2.8	V		
		5.5V	$0.7 V_{CC}$	V _{CC} +0.3	2.8	V		
V _{IL}	Input Low Voltage	4.5V	V _{SS} -0.3	0.2 V _{CC}	1.5	V		
		5.5V	V _{SS} -0.3	$0.2\mathrm{V_{CC}}$	1.5	٧		
V _{OH}	Output High Voltage	4.5V	V _{CC} -0.4		4.8	٧	$I_{OH} = -2.0 \text{ mA}$	5
		5.5V	V _{CC} -0.4		4.8	V	I _{OH} = -2.0 mA	5
	•	4.5V	V _{CC} -0.4		4.8	٧	Low Noise @ I _{OH} = -0.5 mA	*** **
	•	5.5V	V _{CC} -0.4		4.8	٧	Low Noise @ I _{OH} = -0.5 mA	
V _{OL1}	Output Low Voltage	4.5V		0.8	0.1	٧	$I_{OL} = +4.0 \text{ mA}$	5
	•	5.5V		0.4	0.1	V	I _{OL} = +4.0 mA	5
	•	4.5V		0.4	0.1	V	Low Noise @ I _{OL} = 1.0 mA	
	•	5.5V	<u>.</u>	0.4	0.1	V	Low Noise @ I _{OL} = 1.0 mA	
V _{OL2}	Output Low Voltage	4.5V		0.8	0.8	٧	I _{OL} = +12 mA,	5
	•	5.5V		0.8	0.8	٧	l _{OL} = +12 mA,	5
VOFFSET	Comparator Input	4.5V		25.0	10.0	mV		
	Offset Voltage	5.5V		25.0	10.0	mV		
V_{LV}	V _{CC} Low Voltage Auto Reset		2.2	3.0	2.8	V	@ 6 MHz Max. Int. CLK Freq.	<u>-</u>
I _{IL}	Input Leakage	4.5V	-1.0	1.0		μА	V _{IN} = 0V, V _{CC}	
	(Input Bias Current of Comparator)	5.5V	-1.0	1.0	·	μА	V _{IN} = 0V, V _{CC}	*****
I _{OL}	Output Leakage	4.5V	-1.0	1.0		μA	V _{IN} = 0V, V _{CC}	
	-	5.5V	-1.0	1.0		μА	V _{IN} = 0V, V _{CC}	
V _{ICR}	Comparator Input Common Mode Voltage Range		0	V _{CC} -1.0		V		

DC ELECTRICAL CHARACTERISTICS (Continued)

		-	T _A = 0°0	C to +70°C	Typical			
Sym	Parameter	V _{cc} [4]	Min	Max	@ 25°C	Units	Conditions	Notes
I _{CC1}	Standby Current	4.5V		4.0	2.5	mA	HALT Mode V _{IN} = 0V,	7
	(Low Noise Mode)						V _{CC} @ 1 MHz	
		5.5V		4.0	2.5	mA	HALT Mode V _{IN} = 0V,	7
							V _{CC} @ 1 MHz	
		4.5V		4.5	2.8	mA	HALT Mode V _{IN} = 0V,	7
							V _{CC} @ 2 MHz	
		5.5V	*****	4.5	2.8	mA	HALT Mode V _{IN} = 0V,	7
							V _{CC} @ 2 MHz	
		4.5V		5.0	3.0	mA	HALT Mode V _{IN} = 0V,	7
							V _{CC} @ 4 MHz	
		5.5V		5.0	3.0	mA	HALT Mode V _{IN} = 0V,	7
							V _{CC} @ 4 MHz	
I_{CC2}	Standby Current	4.5V		10.0	1.0	μΑ	STOP Mode V _{IN} = 0V, V _{CC}	7,8
					· •		WDT is not Running	
		5.5V		10.0	1.0	μА	STOP Mode V _{IN} = 0V,V _{CC}	7,8
							WDT is not Running	
I _{ALL}	Auto Latch Low	4.5V		32.0	16	μА	0V < V _{IN} < V _{CC}	
	Current	5.5V		32.0	16	μА	0V < V _{IN} < V _{CC}	-
I _{ALH}	Auto Latch High	4.5V	mak.	-16.0	-8.0	μА	OV < V _{IN} < V _{CC}	-
	Current	5.5V		-16.0	-8.0	μА	0V < V _{IN} < V _{CC}	

- 1. Port 2 and Port 0 only
- 2. $V_{SS} = 0V = GND$
- 3. The device operates down to V_{LV} of the specified frequency for V_{LV} . The minimum operational V_{CC} is determined on the value of the voltage V_{LV} at the ambient temperature. The V_{LV} increases as the temperature decreases.
- 4. V_{CC} = 4.5 to 5.5V, typical values measured at V_{CC} = 5.0V. The V_{CC} voltage specification of 5.5 V guarantees 5.0 V \pm 0.5V with typical values measured at V_{CC} = 5.0V.
- 5. Standard Mode (not Low EMI Mode)
- 6. Z86E08 only
- 7. All outputs unloaded and all inputs are at $\rm V_{\rm CC}$ or $\rm V_{\rm SS}$ level.
- 8. If analog comparator is selected, then the comparator inputs must be at $V_{\rm CC}$ level.

DC ELECTRICAL CHARACTERISTICS

Extended Temperature

		T _A = -40°C to +105°C			Typical			
Sym	Parameter	V _{cc} [4]	Min	Max	@ 25°C	Units	Conditions	Notes
$\overline{V_{\text{INMAX}}}$	Max Input Voltage	4.5V	<u> </u>	12.0		V	I _{IN} < 250 μA	1
		5.5V		12.0	 	V	I _{IN} < 250 μA	1
V _{CH}	Clock Input High Voltage	4.5V	0.8 V _{CC}	V _{CC} +0.3	2.8	V	Driven by External Clock Generator	
		5.5V	0.8 V _{CC}	V _{CC} +0.3	2.8	٧	Driven by External Clock Generator	
V _{CL}	Clock Input Low Voltage	4.5V	V _{SS} -0.3	0.2 V _{CC}	1.7	٧	Driven by External Clock Generator	, - <u>1</u>
		5.5V		0.2 V _{CC}	1.7	V	Driven by External Clock Generator	
V _{IH}	Input High Voltage	4.5V	0.7 V _{cc}	V _{CC} +0.3	2.8	V		
		5.5V	0.7 V _{CC}	V _{CC} +0.3	2.8	٧	**	
V_{IL}	Input Low Voltage	4.5V	V _{ss} –0.3	0.2 V _{CC}	1.5	V		
		5.5V	V _{ss} -0.3	0.2 V _{CC}	1.5	V		
V_{OH}	Output High Voltage	4.5V	V _{CC} -0.4		4.8	V	I _{OH} = -2.0 mA	5
		5.5V	V _{CC} -0.4		4.8	V	I _{OH} = -2.0 mA	5
	-	4.5V	V _{CC} -0.4	<u> </u>		٧	Low Noise @ I _{OH} = -0.5 mA	
		5.5V	V _{CC} -0.4	•	**	V	Low Noise @ I _{OH} = -0.5 mA	
V _{OL1}	Output Low Voltage	4.5V		0.4	0.1	V	$I_{OL} = +4.0 \text{ mA}$	5
	•	5.5V		0.4	0.1	٧	$I_{OL} = +4.0 \text{ mA}$	5
		4.5V		0.4	0.1	٧	Low Noise @ I _{OL} = 1.0 mA	
	•	5.5V		0.4	0.1	V	Low Noise @ I _{OL} = 1.0 mA	
V _{OL2}	Output Low Voitage	4.5V		1.0	0.3	V	I _{OL} = +12 mA,	5
		5.5V		1.0	0.3	V	$I_{OL} = +12 \text{ mA},$	5
V_{OFFSET}	Comparator Input	4.5V		25.0	10.0	mV		
	Offset Voltage	5.5V		25.0	10.0	mV		
V _{LV}	V _{CC} Low Voltage Auto Reset		1.8	3.8	2.8	V	@ 6 MHz Max. Int. CLK Freq.	3
l _{i∟}	Input Leakage	4.5V		-1.0	1.0	μА	$V_{IN} = 0V, V_{CC}$	
	(Input Bias Current of Comparator)	5.5V		-1.0	1.0	μА	$V_{IN} = 0V$, V_{CC}	
I _{OL}	Output Leakage	4.5V		-1.0	1.0	μА	$V_{IN} = 0V_i V_{CC}$	
		5.5V		-1.0	1.0	μA	$V_{IN} = 0V, V_{CC}$	•
V _{ICR}	Comparator Input Common Mode Voltage Range		Ö	V _{CC} –1.5		V		·

DC ELECTRICAL CHARACTERISTICS (Continued)

		T _A = -40°C · +105°C			Typical			
Sym	Parameter	V _{CC} [4]	Min	Max	@ 25°C	Units	Conditions	Notes
Icc	Supply Current	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		4.5V	_	20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
		5.5V		20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
I _{CC1}	Standby Current	4.5V		5.0	2.5	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 2 MHz	5,7
		5.5V		5.0	2.5	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 2 MHz	5,7
		4.5V	-10-	5.0	3.0	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 8 MHz	5,7
		5.5V		5.0	3.0	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 8 MHz	5,7
		4.5V	=	7.0	4.0	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 12 MHz	5,7
		5.5V		7.0	4.0	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 12 MHz	5,7
Icc	Supply Current (Low Noise Mode)	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		4.5V	,	13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		5.5V		13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7

Sym	Parameter	V _{cc} [4]	T _A = -40°C to +105°C Min Max	Typical @ 25°C	Units	Conditions	Notes
I _{CC1}	Standby Current (Low Noise Mode)	4.5V	4.0	2.5	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 1 MHz	7
		5.5V	4.0	2.5	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 1 MHz	7
		4.5V	4.5	2.8	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 2 MHz	7
		5.5V	4.5	2.8	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 2 MHz	7
		4.5V	5.0	3.0	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 4 MHz	7
		5.5V	5.0	3.0	mA	HALT Mode V _{IN} = 0V, V _{CC} @ 4 MHz	7
I _{CC2}	Standby Current	4.5V	20	1.0	μА	STOP Mode $V_{IN} = 0V, V_{CC}$ WDT is not Running	7,8
		5.5V	20	1.0	μА	STOP Mode V _{IN} = 0V, V _{CC} WDT is not Running	7,8
I _{ALL}	Auto Latch Low	4.5V	40	16	μА	OV < V _{IN} < V _{CC}	
	Current	5.5V	40	16	μА	OV < V _{IN} < V _{CC}	
I _{ALH}	Auto Latch High	4.5V	-20.0	-8.0	μА	OV < V _{IN} < V _{CC}	
	Current	5.5V	-20.0	-8.0	μА	0V < V _{IN} < V _{CC}	

- 1. Port 2 and Port 0 only
- 2. $V_{SS} = 0V = GND$
- 3. The device operates down to V_{LV} of the specified frequency for V_{LV} . The minimum operational V_{CC} is determined on the value of the voltage V_{LV} at the ambient temperature. The V_{LV} increases as the temperature decreases.
- 4. V_{CC} = 4.5V to 5.5V, typical values measured at V_{CC} = 5.0V
- 5. Standard Mode (not Low EMI Mode)
- 6. Z86E08 only
- 7. All outputs unloaded and all inputs are at V_{CC} or V_{SS} level.
- 8. If analog comparator is selected, then the comparator inputs must be at V_{CC} level.

AC ELECTRICAL CHARACTERISTICS

Low Noise Mode, Standard Temperature

				Т	_= 0 °C t	o +70 °C			
				1 M		4 M	Hz		
No	Symbol	Parameter	v_{cc}	Min	Max	Min	Max	Units	Notes
1	TPC	Input Clock Period	4.5V	1000	DC	250	DC	ns	1
		-	5.5V	1000	DC	250	DC	ns	1
2	TrC	Clock Input Rise	4.5V		25		25	ns	1
	TfC	and Fall Times	5.5V		25	,	25	ns	1
3	TwC	Input Clock Width	4.5V	500		125		ns	1
		-	5.5V	500		125		ns	1
4.	TwTinL	Timer Input Low Width	4.5V	70	•	70		ns	1
		-	5.5V	70		70		ns	1
5	TwTinH	Timer Input High Width	4.5V	2.5TpC		2.5TpC			1
		-	5.5V	2.5TpC		2.5TpC		.,	1
6	TpTin	Timer Input Period	4.5V	4TpC		4TpC			1
		-	5.5V	4TpC		4TpC			1
7	TrTin,	Timer Input Rise	4.5V	· ·	100		100	ns	1
	TtTin	and Fall Time	5.5V		100		100	ns	1
8	TwiL	Int. Request Input	4.5V	70		70	_	ns	1,2
	Low Time	•	5.5V	70		70		ns	1,2
9	TwiH	Int. Request Input	4.5V	2.5TpC		2.5TpC			1,2
	High Time	•	5.5V	2.5TpC		2.5TpC	 -		1,2
10	Twdt	Watch-Dog Timer	4.5V	12		12		ms	1
		Delay Time for Timeout	5.5V	12		12		ms	1

- Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.
 Interrupt request through Port 3 (P33–P31).

AC ELECTRICAL CHARACTERISTICS (Continued)

Low Noise Mode, Extended Temperature

				T _A = -40 °C to +105 °C							
				1 MHz		4 MHz					
No	Symbol	Parameter	V _{cc}	Min	Max	Min	Max	Units	Notes		
1	TPC	Input Clock Period	4.5V	1000	DC	250	DC	ns	1		
			5.5V	1000	DC	250	DC	ns	1		
2	TrC	Clock Input Rise	4.5V		25		25	ns	1		
	TfC	and Fall Times	5.5V		25	-	25	ns	1		
3	TwC	Input Clock Width	4.5V	500		125		ns	1		
			5.5V	500		125		ns	1		
4.	TwTinL	Timer Input Low Width	4.5V	70		70		ns	1		
			5.5V	70		70		ns	1		
5	TwTinH	Timer Input High Width	4.5V	2.5TpC		2.5TpC	 -		1		
			5.5V	2.5TpC	•	2.5TpC			1		
6	TpTin	Timer Input Period	4.5V		4TpC	4TpC			1		
			5.5V		4TpC	4TpC			1		
7	TrTin,	Timer Input Rise	4.5V		100	•	100	ns	1		
	TtTin	and Fall Time	5.5V		100		100	ns	1		
8	TwlL	Int. Request Input	4.5V	70		70		ns	1,2		
		Low Time	5.5V	70		70		ns	1,2		
9	TWIH	Int. Request Input	4.5V	2.5TpC		2.5TpC			1,2		
		High Time	5.5V	2.5TpC		2.5TpC			1,2		
10	Twdt	Watch-Dog Timer	4.5V	10		10		ms	1		
		Delay Time for Timeout	5.5V	10		10		ms	1		

^{1.} Timing Reference uses 0.7 $\rm V_{CC}$ for a logic 1 and 0.2 $\rm V_{CC}$ for a logic 0.

^{2.} Interrupt request through Port 3 (P33-P31).

LOW NOISE VERSION

Low EMI Emission

The Z86E04/E08 can be programmed to operate in a Low EMI Emission Mode by means of a mask ROM bit option. Use of this feature results in:

- All pre-driver slew rates reduced to 10 ns typical.
- Internal SCLK/TCLK operation limited to a maximum of 4 MHz-250 ns cycle time.
- Output drivers have resistances of 500 Ohms (typical).
- Oscillator divide-by-two circuitry eliminated.

The Low EMI Mode is mask-programmable to be selected by the customer at the time the ROM code is submitted.

PIN FUNCTIONS

OTP Programming Mode

D7–D0 Data Bus. Data can be read from, or written to, the EPROM through this data bus.

 $V_{\rm CC}$ Power Supply. It is typically 5V during EPROM Read Mode and 6.4V during the other modes (Program, Program Verify, and so on).

CE Chip Enable (active Low). This pin is active during EPROM Read Mode, Program Mode, and Program Verify Mode.

OE Output Enable (active Low). This pin drives the Data Bus direction. When this pin is Low, the Data Bus is output. When High, the Data Bus is input.

EPM *EPROM Program Mode.* This pin controls the different EPROM Program Modes by applying different voltages.

 \mathbf{V}_{PP} Program Voltage. This pin supplies the program voltage.

Clear Clear (active High). This pin resets the internal address counter at the High Level.

Clock Address Clock. This pin is a clock input. The internal address counter increases by one with one clock cycle.

PGM Program Mode (active Low). A Low level at this pin programs the data to the EPROM through the Data Bus.

Application Precaution

The production test-mode environment may be enabled accidentally during normal operation if *excessive noise* surges above V_{CC} occur on the XTAL1 pin.

In addition, processor operation of Z8 OTP devices may be affected by *excessive noise* surges on the V_{pp} , \overline{CE} , EPM, \overline{OE} pins while the microcontroller is in Standard Mode.

Recommendations for dampening voltage surges in both test and OTP Mode include the following:

- Using a clamping diode to V_{CC}.
- Adding a capacitor to the affected pin.

Note: Programming the EPROM/Test Mode Disable option will prevent accidental entry into EPROM Mode or Test Mode.

Comparator Inputs. Two analog comparators are added to input of Port 3, P31, and P32, for interface flexibility. The comparators reference voltage P33 (REF) is common to both comparators.

Typical applications for the on-board comparators; Zero crossing detection, A/D conversion, voltage scaling, and threshold detection. In Analog Mode, P33 input functions serve as a reference voltage to the comparators.

The dual comparator (common inverting terminal) features a single power supply which discontinues power in STOP

Mode. The common voltage range is 0–4 V when the $V_{\rm CC}$ is 5.0V; the power supply and common mode rejection ratios are 90 dB and 60 dB, respectively.

Interrupts are generated on either edge of Comparator 2's output, or on the falling edge of Comparator 1's output. The comparator output is used for interrupt generation, Port 3 data inputs, or T_{IN} through P31. Alternatively, the comparators can be disabled, freeing the reference input (P33) for use as IRQ1 and/or P33 input.

FUNCTIONAL DESCRIPTION

The following special functions have been incorporated into the Z8 devices to enhance the standard Z8 core architecture to provide the user with increased design flexibility.

RESET. This function is accomplished by means of a Power-On Reset or a Watch-Dog Timer Reset. Upon power-up, the Power-On Reset circuit waits for T_{POR} ms, plus 18 clock cycles, then starts program execution at address 000C (Hex) (Figure 10). The Z8 control registers' reset value is shown in Table 3.

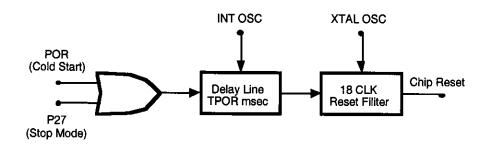
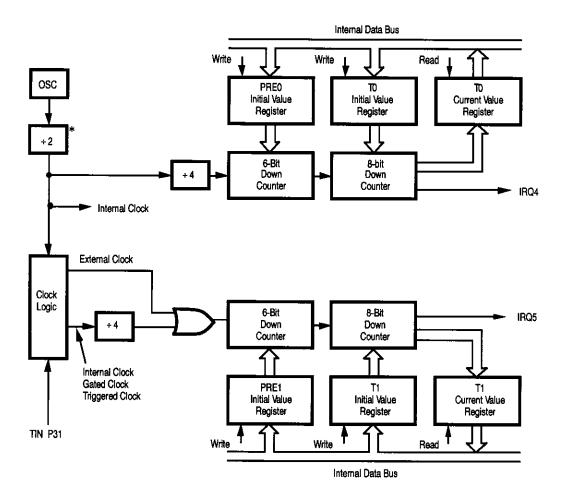


Figure 10. Internal Reset Configuration

Power-On Reset (POR). A timer circuit clocked by a dedicated on-board RC oscillator is used for a POR timer function. The POR time allows $V_{\rm CC}$ and the oscillator circuit to stabilize before instruction execution begins. The POR timer circuit is a one-shot timer triggered by one of the four following conditions:

- Power-bad to power-good status
- Stop-Mode Recovery
- WDT time-out
- WDH time-out

Watch-Dog Timer Reset. The WDT is a retriggerable one-shot timer that resets the Z8 if it reaches its terminal count. The WDT is initially enabled by executing the WDT instruction and is retriggered on subsequent execution of the WDT instruction. The timer circuit is driven by an on-board RC oscillator.



^{*} Note: By passed, if Low EMI Mode is selected.

Figure 14. Counter/Timers Block Diagram

HALT Mode. This instruction turns off the internal CPU clock but not the crystal oscillation. The counter/timers and external interrupts IRQ0, IRQ1, IRQ2 and IRQ3 remain active. The device is recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after the HALT.

Note: On the C12 ICEBOX, the IRQ3 does not wake the device out of HALT Mode.

STOP Mode. This instruction turns off the internal clock and external crystal oscillation and reduces the standby current to 10 μA . The STOP Mode is released by a RESET through a Stop-Mode Recovery (pin P27). A Low input condition on P27 releases the STOP Mode. Program execution begins at location 000C(Hex). However, when P27 is used to release the STOP Mode, the I/O port Mode registers are not reconfigured to their default power-on conditions. This prevents any I/O, configured as output when the STOP instruction was executed, from glitching to an unknown state. To use the P27 release approach with STOP Mode, use the following instruction:

LD

P2M, #1XXX XXXXB

NOP STOP

X = Dependent on user's application.

Note: A low level detected on P27 pin will take the device out of STOP Mode even if configured as an output.

In order to enter STOP or HALT Mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, the user executes a NOP (opcode=FFH) immediately before the appropriate SLEEP instruction, such as:

FF 6F NOP STOP ; clear the pipeline ; enter STOP Mode

~

FF 7**F** NOP HALT ; clear the pipeline

; enter HALT Mode

Watch-Dog Timer (WDT). The Watch-Dog Timer is enabled by instruction WDT. When the WDT is enabled, it cannot be stopped by the instruction. With the WDT instruction, the WDT is refreshed when it is enabled within every 1 Twdt period; otherwise, the controller resets itself, The WDT instruction affects the flags accordingly; Z=1, S=0, V=0.

WDT = 5F (Hex)

Opcode WDT (5FH). The first time Opcode 5FH is executed, the WDT is enabled and subsequent execution clears the WDT counter. This must be done at least every T_{WDT} ; otherwise, the WDT times out and generates a reset. The generated reset is the same as a power-on reset of T_{POR} , plus 18 XTAL clock cycles. The software enabled WDT does not run in STOP Mode.

Opcode WDH (4FH). When this instruction is executed it enables the WDT during HALT. If not, the WDT stops when entering HALT. This instruction does not clear the counters, it just makes it possible to have the WDT running during HALT Mode. A WDH instruction executed without executing WDT (5FH) has no effect.

Permanent WDT. Selecting the hardware enabled Permanent WDT option, will automatically enable the WDT upon exiting reset. The permanent WDT will always run in HALT Mode and STOP Mode, and it cannot be disabled.

Auto Reset Voltage (V_{LV}). The Z8 has an auto-reset builtin. The auto-reset circuit resets the Z8 when it detects the V_{CC} below V_{LV} .

Figure 17 shows the Auto Reset Voltage versus temperature. If the V_{CC} drops below the VCC operating voltage range, the Z8 will function down to the V_{LV} unless the internal clock frequency is higher than the specified maximum V_{LV} frequency.

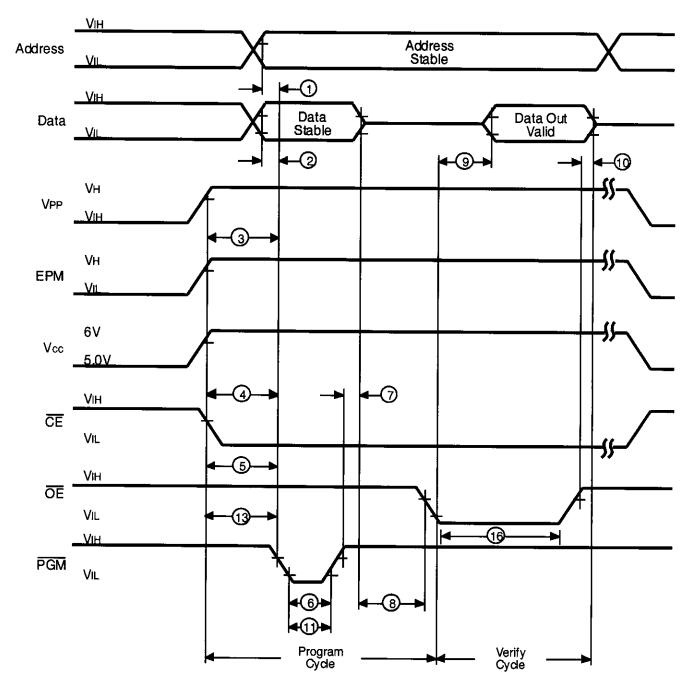


Figure 20. Z86E04/E08 Programming Waveform (Program and Verify)

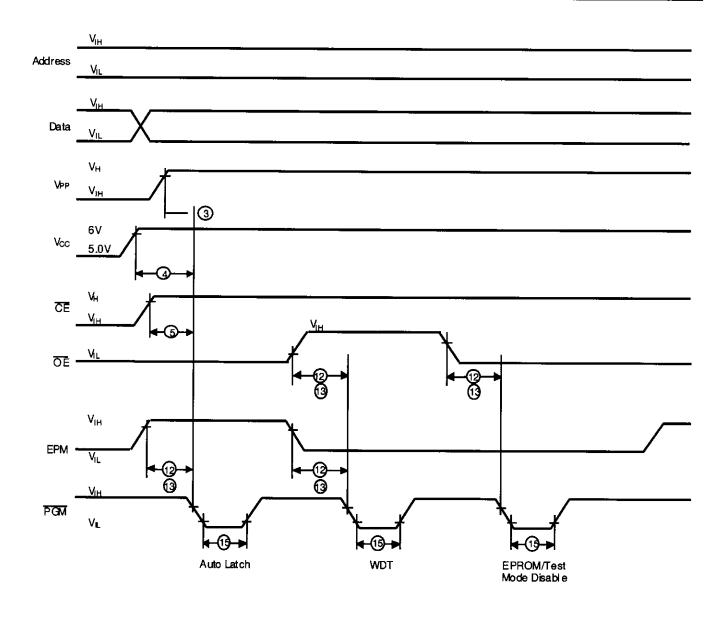


Figure 22. Z86E04/E08 Programming Options Waveform (Auto Latch Disable, Permanent WDT Enable and EPROM/Test Mode Disable)

FUNCTIONAL DESCRIPTION (Continued)

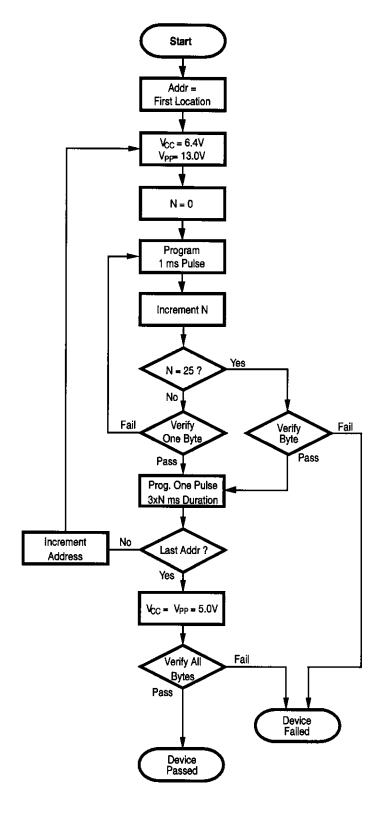


Figure 23. Z86E04/E08 Programming Algorithm

Z8 CONTROL REGISTERS

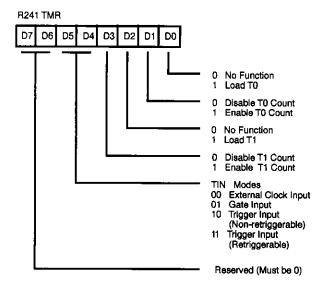


Figure 24. Timer Mode Register (F1_H: Read/Write)

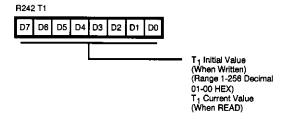


Figure 25. Counter Timer 1 Register (F2_H: Read/Write)

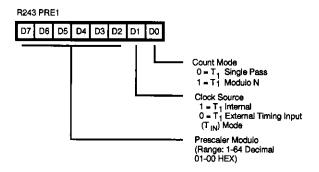


Figure 26. Prescaler 1 Register (F3_H: Write Only)

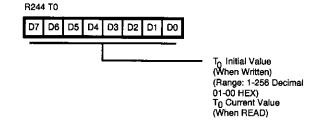


Figure 27. Counter/Timer 0 Register (F4_H: Read/Write)

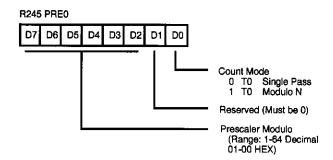


Figure 28. Prescaler 0 Register (F5_H: Write Only)

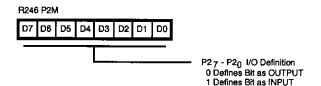


Figure 29. Port 2 Mode Register (F6_H: Write Only)

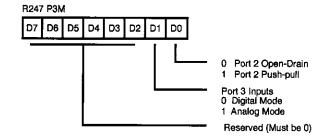


Figure 30. Port 3 Mode Register (F7_H: Write Only)