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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	12MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	14
Program Memory Size	1KB (1K x 8)
Program Memory Type	ОТР
EEPROM Size	-
RAM Size	125 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86e0412psc1903

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

### FEATURES

- 14 Input/Output Lines
- Six Vectored, Prioritized Interrupts
   (3 falling edge, 1 rising edge, 2 timers)
- Two Analog Comparators
- Program Options:
  - Low Noise
  - ROM Protect
  - Auto Latch
  - Watch-Dog Timer (WDT)
  - EPROM/Test Mode Disable

- Two Programmable 8-Bit Counter/Timers, Each with 6-Bit Programmable Prescaler
- WDT/ Power-On Reset (POR)
- On-Chip Oscillator that Accepts XTAL, Ceramic Resonance, LC, RC, or External Clock
- Clock-Free WDT Reset
- Low-Power Consumption (50 mw typical)
- Fast Instruction Pointer (1µs @ 12 MHz)
- RAM Bytes (125)

### **GENERAL DESCRIPTION**

Zilog's Z86E04/E08 Microcontrollers (MCU) are One-Time Programmable (OTP) members of Zilog's single-chip Z8<sup>®</sup> MCU family that allow easy software development, debug, prototyping, and small production runs not economically desirable with masked ROM versions.

For applications demanding powerful I/O capabilities, the Z86E04/E08's dedicated input and output lines are grouped into three ports, and are configurable under software control to provide timing, status signals, or parallel I/O.

Two on-chip counter/timers, with a large number of user selectable modes, offload the system of administering real-time tasks such as counting/timing and I/O data communications.

**Note:** All Signals with an overline, " $\overline{}$ ", are active Low, for example: B/W (WORD is active Low); B/W (BYTE is active Low, only).

Power connections follow conventional descriptions below:

Connection	Circuit	Device	
Power	V <sub>cc</sub>	V <sub>DD</sub>	
Ground	GND	V <sub>SS</sub>	

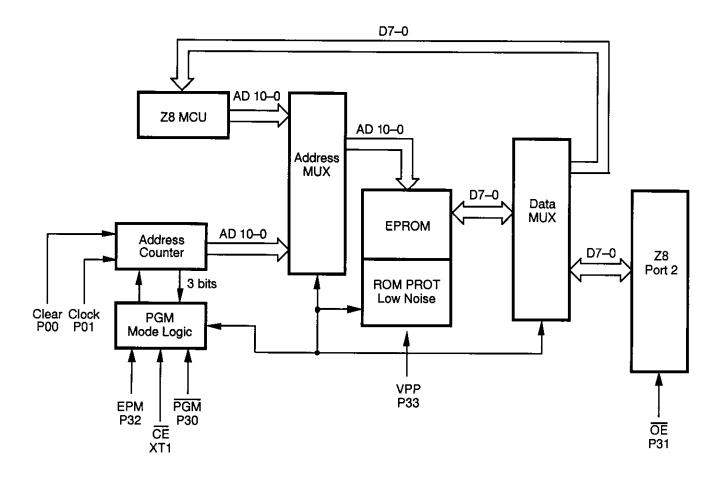


Figure 2. EPROM Programming Mode Block Diagram

## **ABSOLUTE MAXIMUM RATINGS**

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability. Total power dissipation should not exceed 462 mW for the package. Power dissipation is calculated as follows:

Total Power Dissipation =  $V_{DD} \times [I_{DD} - (\text{sum of } I_{OH})]$ + sum of  $[(V_{DD} - V_{OH}) \times I_{OH}]$ + sum of  $(V_{0L} \times I_{0L})$ 

Min	Max	Units	Note
-40	+105	С	
-65	+150	С	
-0.7	+12	V	1
-0.3	+7	V -	
-0.6	V <sub>DD</sub> +1	V	2
	1.65	W	·
	300	mA	
	220	mA	
-600	+600	μA	3
-600	+600	μΑ	4
	25	mA	
	25	mA	
	60	mA	
	45	mA	
	-40 -65 -0.7 -0.3 -0.6	$\begin{array}{c ccc} -40 & \pm 105 \\ -65 & \pm 150 \\ -0.7 & \pm 12 \\ -0.3 & \pm 7 \\ -0.6 & V_{DD} \pm 1 \\ \hline & 1.65 \\ 300 \\ 220 \\ -600 & \pm 600 \\ -600 & \pm 600 \\ 25 \\ 25 \\ 60 \\ \end{array}$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

Notes:

1. This applies to all pins except where otherwise noted. Maximum current into pin must be  $\pm$  600  $\mu$ A.

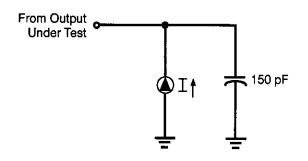
2. There is no input protection diode from pin to V<sub>DD</sub> (not applicable to EPROM Mode).

3. This excludes Pin 6 and Pin 7.

4. Device pin is not at an output Low state.

## STANDARD TEST CONDITIONS

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to Ground. Positive current flows into the referenced pin (Figure 5).





### CAPACITANCE

 $T_A = 25^{\circ}C$ ,  $V_{CC} = GND = 0V$ , f = 1.0 MHz, unmeasured pins returned to GND.

Parameter	Min	Max
Input capacitance	0	10 pF
Output capacitance	0	20 pF
I/O capacitance	0	25 pF

## DC ELECTRICAL CHARACTERISTICS Extended Temperature

				40°C to )5°C	Typical			
Sym	Parameter	V <sub>cc</sub> [4]	Min	Max	@ 25°C	Units	Conditions	Notes
VINMAX	Max Input Voltage	4.5V		12.0		V	I <sub>IN</sub> < 250 μA	1
		5.5V		12.0	- 4 .	V	l <sub>IN</sub> < 250 μA	1
V <sub>CH</sub>	Clock Input High Voltage	4.5V	0.8 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V	Driven by External Clock Generator	
		5.5V	0.8 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V	Driven by External Clock Generator	
V <sub>CL</sub>	Clock Input Low Voltage	4.5V	V <sub>SS</sub> 0.3	0.2 V <sub>CC</sub>	1.7	V	Driven by External Clock Generator	
		5.5V	V <sub>SS</sub> –0.3	0.2 V <sub>CC</sub>	1.7	V	Driven by External Clock Generator	
V <sub>IH</sub>	Input High Voltage	4.5V	$0.7  V_{CC}$	V <sub>CC</sub> +0.3	2.8	V		
	_	5.5V	0.7 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V	<u>,</u>	
V <sub>IL</sub>	Input Low Voltage	4.5V	V <sub>ss</sub> –0.3	0.2 V <sub>CC</sub>	1.5	V		
		5.5V	V <sub>ss</sub> -0.3	0.2 V <sub>CC</sub>	1.5	V		I
V <sub>OH</sub>	Output High Voltage	4.5V	V <sub>cc</sub> -0.4		4.8	V	I <sub>OH</sub> = -2.0 mA	5
		5.5V	V <sub>cc</sub> -0.4		4.8	V	I <sub>OH</sub> = -2.0 mA	5
		4.5V	V <sub>cc</sub> -0.4			V	Low Noise @ $I_{OH} = -0.5$ mA	
		5.5V	V <sub>cc</sub> -0.4	<del>.</del>		V	Low Noise @ I <sub>OH</sub> = -0.5 mA	
V <sub>OL1</sub>	Output Low Voltage	4.5V		0.4	0.1	V	I <sub>OL</sub> = +4.0 mA	5
	·	5.5V		0.4	0.1	V	I <sub>OL</sub> = +4.0 mA	5
		4.5V		0.4	0.1	V	Low Noise @ I <sub>OL</sub> = 1.0 mA	
		5.5V		0.4	0.1	V	Low Noise @ I <sub>OL</sub> = 1.0 mA	
V <sub>ol2</sub>	Output Low Voltage	4.5V		1.0	0.3	V	l <sub>oL</sub> = +12 mA,	5
		5.5V		1.0	0.3	V	I <sub>OL</sub> = +12 mA,	5
V <sub>offset</sub>	Comparator Input	4.5V		25.0	10.0	mV		
	Offset Voltage	5.5V		25.0	10.0	mV		
V <sub>LV</sub>	V <sub>CC</sub> Low Voltage Auto Reset		1.8	3.8	2.8	V	@ 6 MHz Max. Int. CLK Freq.	3
կլ	Input Leakage	4.5V		-1.0	1.0	μA	$V_{\rm IN} = 0V, V_{\rm CC}$	
	(Input Bias Current of Comparator)	5.5V		-1.0	1.0	μA	$V_{IN} = 0V, V_{CC}$	
I <sub>OL</sub>	Output Leakage	4.5V		-1.0	1.0	μA	$V_{\rm IN} = 0V, V_{\rm CC}$	
		5.5V		-1.0	1.0	μA	$V_{IN} = 0V, V_{CC}$	
V <sub>ICR</sub>	Comparator Input Common Mode Voltage Range		0	V <sub>CC</sub> –1.5		V		

# DC ELECTRICAL CHARACTERISTICS (Continued)

				40°C to )5°C	Typical			
Sym	Parameter	V <sub>cc</sub> [4]	Min	Max	@ 25°C	Units	Conditions	Notes
lcc	Supply Current	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		4.5V		20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
		5.5V		20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
I <sub>CC1</sub>	Standby Current	4.5V		5.0	2.5	mA	HALT Mode $V_{IN} = 0V$ , $V_{CC} @ 2 MHz$	5,7
		5.5V		5.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 2 MHz	5,7
		4.5V	-184	5.0	3.0	mA	HALT Mode $V_{IN} = 0V$ , $V_{CC} @ 8 MHz$	5,7
		5.5V	<del></del>	5.0	3.0	mA	HALT Mode $V_{IN} = 0V$ , $V_{CC} @ 8 MHz$	5,7
		4.5V		7.0	4.0	mA	HALT Mode $V_{iN} = 0V$ , $V_{CC}$ @ 12 MHz	5,7
		5.5V	· ·	7.0	4.0	mA	HALT Mode $V_{IN} = 0V$ , $V_{CC} @ 12 MHz$	5,7
Icc	Supply Current (Low Noise Mode)	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		4.5V		13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		5.5V		13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7

#### Z86E04/E08 CMOS Z8 OTP Microcontrollers

•	<b>_</b>	N/ F/1		C to +105°C	Typical			
Sym	Parameter	V <sub>cc</sub> [4]	Min	Max	@ 25°C	Units	Conditions	Notes
I <sub>CC1</sub>	Standby Current	4.5V		4.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V,	7
	(Low Noise Mode)						V <sub>cc</sub> @1MHz	
		5.5V	-	4.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V,	7
							V <sub>CC</sub> @ 1 MHz	
		4.5V		4.5	2.8	mA	HALT Mode V <sub>IN</sub> = 0V,	7
							V <sub>CC</sub> @ 2 MHz	
		5.5V		4.5	2.8	mA	HALT Mode V <sub>IN</sub> = 0V,	7
							V <sub>CC</sub> @ 2 MHz	
		4.5V		5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V,	7
							V <sub>CC</sub> @ 4 MHz	
		5.5V		5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V,	7
							V <sub>CC</sub> @ 4 MHz	
I <sub>CC2</sub>	Standby Current	4.5V		20	1.0	μA	STOP Mode V <sub>IN</sub> = 0V, V <sub>CC</sub>	7,8
							WDT is not Running	
		5.5V		20	1.0	μA	STOP Mode V <sub>IN</sub> = 0V, V <sub>CC</sub>	7,8
							WDT is not Running	
	Auto Latch Low	4.5V		40	16	μA	$0V < V_{IN} < V_{CC}$	
	Current	5.5V		40	16	μA	$0V < V_{iN} < V_{CC}$	
I <sub>ALH</sub>	Auto Latch High	4.5V		-20.0	-8.0	μA	$0V < V_{IN} < V_{CC}$	
	Current	5.5V		-20.0	-8.0	μA	$0V < V_{IN} < V_{CC}$	
	····							

### Notes:

1. Port 2 and Port 0 only

2.  $V_{SS} = 0V = GND$ 

 The device operates down to V<sub>LV</sub> of the specified frequency for V<sub>LV</sub>. The minimum operational V<sub>CC</sub> is determined on the value of the voltage V<sub>LV</sub> at the ambient temperature. The V<sub>LV</sub> increases as the temperature decreases.

4.  $V_{CC}$  = 4.5V to 5.5V, typical values measured at  $V_{CC}$  = 5.0V

5. Standard Mode (not Low EMI Mode)

6. Z86E08 only

7. All outputs unloaded and all inputs are at  $V_{CC} \mbox{ or } V_{SS}$  level.

8. If analog comparator is selected, then the comparator inputs must be at  $V_{CC}$  level.

# AC ELECTRICAL CHARACTERISTICS

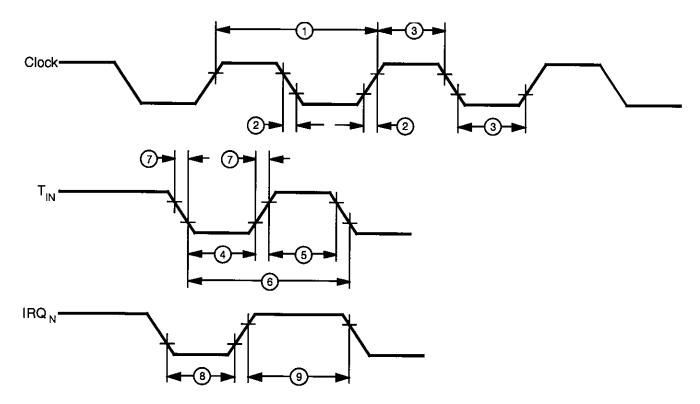


Figure 6. AC Electrical Timing Dlagram

### Low Noise Mode, Extended Temperature

				T۸	= -40 °C	; to +105 °	С		
				1 Ŵ		4 M			
No Syr	Symbol	Parameter	V <sub>cc</sub>	Min	Max	Min	Мах	Units	Notes
1	TPC	Input Clock Period	4.5V	1000	DC	250	DC	ns	1
			5.5V	1000	DC	250	DC	ns	1
2	TrC	Clock Input Rise	4.5V		25		25	ns	1
	TfC	and Fall Times	5.5V		25		25	ns	1
3	TwC	Input Clock Width	4.5V	500		125		ns	1
			5.5V	500		125		ns	1
4.	TwTinL	Timer Input Low Width	4.5V	70		70		ns	1
			5.5V	70		70		ns	1
5	TwTinH	Timer Input High Width	4.5V	2.5TpC		2.5TpC		-	1
			5.5V	2.5TpC		2.5TpC			1
6	TpTin	Timer Input Period	4.5V		4TpC	4TpC	".		1
			5.5V		4TpC	4TpC			1
7	TrTin,	Timer Input Rise	4.5V		100		100	ns	1
	TtTin	and Fall Time	5.5V		100		100	ns	1
8	TwIL	Int. Request Input	4.5V	70		70		ns	1,2
		Low Time	5.5V	70		70		ns	1,2
9	TwiH	Int. Request Input	4.5V	2.5TpC		2.5TpC			1,2
		High Time	5.5V	2.5TpC		2.5TpC			1,2
10	Twdt	Watch-Dog Timer	4.5V	10		10		ms	1
		Delay Time for Timeout	5.5V	10		10		ms	1

#### Notes:

1. Timing Reference uses 0.7  $V_{CC}$  for a logic 1 and 0.2  $V_{CC}$  for a logic 0.

2. Interrupt request through Port 3 (P33-P31).

**Port 2, P27–P20.** Port 2 is an 8-bit, bit programmable, bidirectional, Schmitt-triggered CMOS-compatible I/O port. These eight I/O lines can be configured under software

control to be inputs or outputs, independently. Bits programmed as outputs can be globally programmed as either push-pull or open-drain (Figure 8).

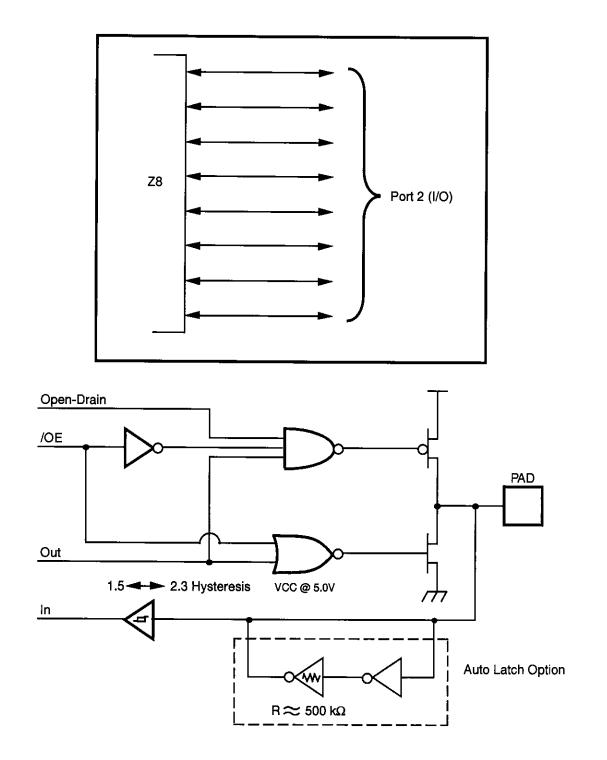


Figure 8. Port 2 Configuration

### PIN FUNCTIONS (Continued)

**Port 3, P33–P31.** Port 3 is a 3-bit, CMOS-compatible port with three fixed input (P33–P31) lines. These three input lines can be configured under software control as digital Schmitt-trigger inputs or analog inputs.

These three input lines are also used as the interrupt sources IRQ0–IRQ3, and as the timer input signal  $T_{\rm IN}$  (Figure 9).

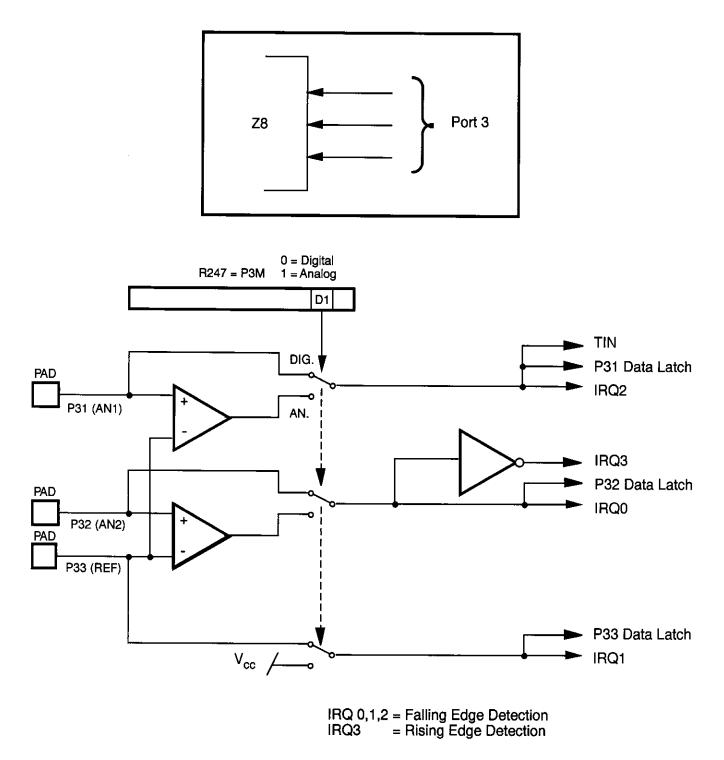


Figure 9. Port 3 Configuration

**Comparator Inputs.** Two analog comparators are added to input of Port 3, P31, and P32, for interface flexibility. The comparators reference voltage P33 (REF) is common to both comparators.

Typical applications for the on-board comparators; Zero crossing detection, A/D conversion, voltage scaling, and threshold detection. In Analog Mode, P33 input functions serve as a reference voltage to the comparators.

The dual comparator (common inverting terminal) features a single power supply which discontinues power in STOP

Mode. The common voltage range is 0-4 V when the V<sub>CC</sub> is 5.0V; the power supply and common mode rejection ratios are 90 dB and 60 dB, respectively.

Interrupts are generated on either edge of Comparator 2's output, or on the falling edge of Comparator 1's output. The comparator output is used for interrupt generation, Port 3 data inputs, or  $T_{\rm IN}$  through P31. Alternatively, the comparators can be disabled, freeing the reference input (P33) for use as IRQ1 and/or P33 input.

## FUNCTIONAL DESCRIPTION

The following special functions have been incorporated into the Z8 devices to enhance the standard Z8 core architecture to provide the user with increased design flexibility.

**RESET**. This function is accomplished by means of a Power-On Reset or a Watch-Dog Timer Reset. Upon power-up, the Power-On Reset circuit waits for  $T_{POR}$  ms, plus 18 clock cycles, then starts program execution at address 000C (Hex) (Figure 10). The Z8 control registers' reset value is shown in Table 3.

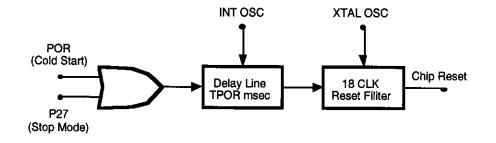


Figure 10. Internal Reset Configuration

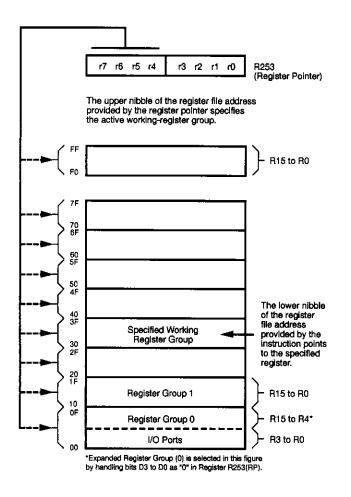
**Power-On Reset (POR).** A timer circuit clocked by a dedicated on-board RC oscillator is used for a POR timer function. The POR time allows  $V_{CC}$  and the oscillator circuit to stabilize before instruction execution begins. The POR timer circuit is a one-shot timer triggered by one of the four following conditions:

Watch-Dog Timer Reset. The WDT is a retriggerable one-shot timer that resets the Z8 if it reaches its terminal count. The WDT is initially enabled by executing the WDT instruction and is retriggered on subsequent execution of the WDT instruction. The timer circuit is driven by an onboard RC oscillator.

- Power-bad to power-good status
- Stop-Mode Recovery
- WDT time-out
- WDH time-out

The Z8 instructions can access registers directly or indirectly through an 8-bit address field. This allows short 4-bit register addressing using the Register Pointer.

In the 4-bit mode, the register file is divided into eight working register groups, each occupying 16 continuous locations. The Register Pointer (Figure 13) addresses the starting location of the active working-register group.





**Stack Pointer.** The Z8 has an 8-bit Stack Pointer (R255) used for the internal stack that resides within the 124 general-purpose registers.

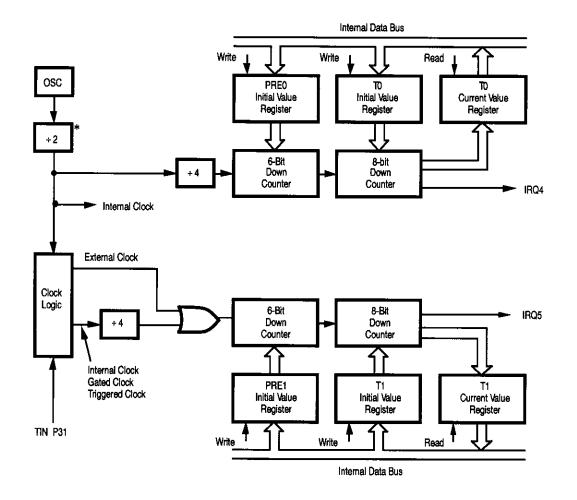
**General-Purpose Registers (GPR).** These registers are undefined after the device is powered up. The registers keep their last value after any reset, as long as the reset occurs in the  $V_{CC}$  voltage-specified operating range. Note: Register R254 has been designated as a general-purpose register and is set to 00 Hex after any reset or Stop-Mode Recovery.

**Counter/Timer.** There are two 8-bit programmable counter/timers (T0 and T1), each driven by its own 6-bit programmable prescaler. The T1 prescaler is driven by internal or external clock sources; however, the T0 can be driven by the internal clock source only (Figure 14).

The 6-bit prescalers divide the input frequency of the clock source by any integer number from 1 to 64. Each prescaler drives its counter, which decrements the value (1 to 256) that has been loaded into the counter. When both counter and prescaler reach the end of count, a timer interrupt request IRQ4 (T0) or IRQ5 (T1) is generated.

The counter can be programmed to start, stop, restart to continue, or restart from the initial value. The counters are also programmed to stop upon reaching zero (Single-Pass Mode) or to automatically reload the initial value and continue counting (Modulo-N Continuous Mode).

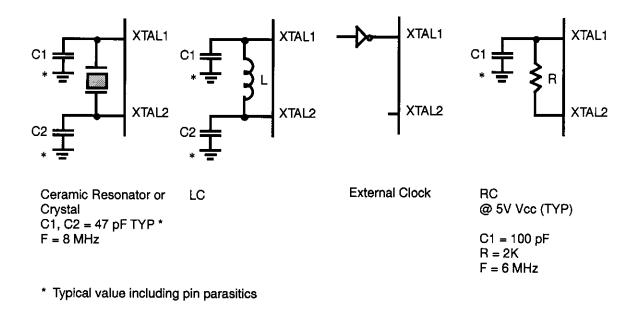
The counters, but not the prescalers, are read at any time without disturbing their value or count mode. The clock source for T1 is user-definable and is either the internal microprocessor clock divided by four, or an external signal input through Port 3. The Timer Mode register configures the external timer input (P31) as an external clock, a trigger input that is retriggerable or non-retriggerable, or used as a gate input for the internal clock.



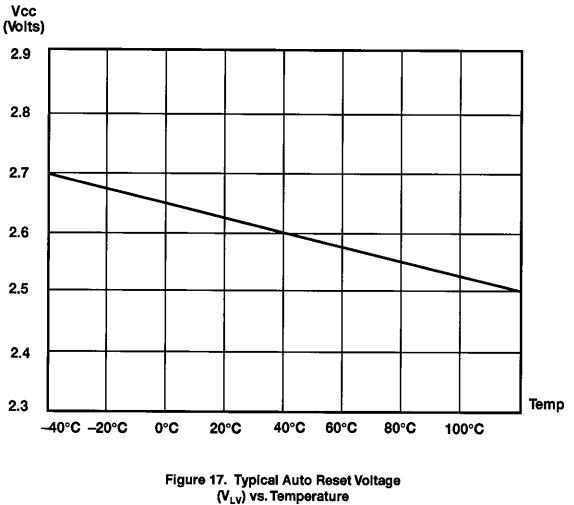
\* Note: By passed, if Low EMI Mode is selected.

Figure 14. Counter/Timers Block Diagram

**Clock.** The Z8 on-chip oscillator has a high-gain, parallelresonant amplifier for connection to a crystal, LC, RC, ceramic resonator, or any suitable external clock source (XTAL1 = INPUT, XTAL2 = OUTPUT). The crystal should be AT cut, up to 12 MHz max., with a series resistance (RS) of less than or equal to 100 Ohms. The crystal should be connected across XTAL1 and XTAL2 using the vendors crystal recommended capacitors from each pin directly to device ground pin 14 (Figure 16). Note that the crystal capacitor loads should be connected to  $V_{SS}$ , Pin 14 to reduce Ground noise injection.







#### Z86E04/E08 CMOS Z8 OTP Microcontrollers

### Low EMI Emission

The Z8 can be programmed to operate in a low EMI Emission (Low Noise) Mode by means of an EPROM programmable bit option. Use of this feature results in:

- Less than 1 mA consumed during HALT Mode.
- All drivers slew rates reduced to 10 ns (typical).
- Internal SCLK/TCLK = XTAL operation limited to a maximum of 4 MHz-250 ns cycle time.
- Output drivers have resistances of 500 ohms (typical).
- Oscillator divide-by-two circuitry eliminated.

In addition to V<sub>DD</sub> and GND (V<sub>SS</sub>), the Z8 changes all its pin functions in the EPROM Mode. XTAL2 has no function, XTAL1 functions as  $\overline{CE}$ , P31 functions as  $\overline{OE}$ , P32 functions as EPM, P33 functions as V<sub>PP</sub>, and P02 functions as PGM.

**ROM Protect.** ROM Protect fully protects the Z8 ROM code from being read externally. When ROM Protect is selected, the instructions LDC and LDCI **are supported** (Z86E04/E08 and Z86C04/C08 do not support the instructions of LDE and LDEI). When the device is programmed for ROM Protect, the Low Noise feature will not automatically be enabled.

Please note that when using the device in a noisy environment, it is suggested that the voltages on the EPM and  $\overline{CE}$  pins be clamped to V<sub>CC</sub> through a diode to V<sub>CC</sub> to prevent accidentally entering the OTP Mode. The V<sub>PP</sub> requires both a diode and a 100 pF capacitor.

Auto Latch Disable. Auto Latch Disable option bit when programmed will globally disable all Auto Latches.

**WDT Enable.** The WDT Enable option bit, when programmed, will have the hardware enabled Permanent WDT enabled after exiting reset and can not be stopped in Halt or Stop Mode.

**EPROM/Test Mode Disable.** The EPROM/Test Mode Disable option bit, when programmed, will disable the EPROM Mode and the Factory Test Mode. Reading, verifying, and programming the Z8 will be disabled. To fully verify that this mode is disabled, the device must be power cycled.

**User Modes.** Table 7 shows the programming voltage of each mode.

Programming Modes	$V_{_{PP}}$	EPM	CE	ŌĒ	PGM	ADDR	DATA	V <sub>cc</sub> *
EPROM READ	NU	V <sub>H</sub>	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IH</sub>	ADDR	Out	5.0V
PROGRAM	V <sub>H</sub>	V <sub>IH</sub>	V <sub>IL</sub>	VIH	V <sub>IL</sub>	ADDR	In	6.4V
PROGRAM VERIFY	V <sub>H</sub>	ViH	V <sub>IL</sub>	VIL	V <sub>IH</sub>	ADDR	Out	6.4V
EPROM PROTECT	V <sub>H</sub>	V <sub>H</sub>	V <sub>H</sub>	VIH	V <sub>IL</sub>	NU	NU	6.4V
LOW NOISE SELECT	V <sub>H</sub>	V <sub>IH</sub>	V <sub>H</sub>	VIH	V <sub>IL</sub>	NU	NU	6.4V
AUTO LATCH DISABLE	V <sub>H</sub>	VIH	V <sub>H</sub>	V <sub>IL</sub>	V <sub>IL</sub>	NU	NU	6.4V
WDT ENABLE	V <sub>H</sub>	V <sub>IL</sub>	V <sub>H</sub>	VIH	VIL	NU	NU	6.4V
EPROM/TEST MODE	V <sub>H</sub>	V <sub>IL</sub>	V <sub>H</sub>	V <sub>IL</sub>	V <sub>IL</sub>	NU	NU	6.4V

### Table 7. OTP Programming Table

#### Notes:

- 1.  $V_{H} = 12.75V \pm 0.25 V_{DC}$ .
- 2.  $V_{IH}$  = As per specific Z8 DC specification.
- 3. V<sub>IL</sub>= As per specific Z8 DC specification.
- 4. X = Not used, but must be set to  $V_H$  or  $V_{IH}$  level.
- 5. NU = Not used, but must be set to either  $V_{IH}$  or  $V_{IL}$  level.
- 6.  $I_{PP}$  during programming = 40 mA maximum.
- 7.  $I_{CC}$  during programming, verify, or read = 40 mA maximum.
- 8. \*  $V_{CC}$  has a tolerance of ±0.25V.

Internal Address Counter. The address of Z8 is generated internally with a counter clocked through pin P01 (Clock). Each clock signal increases the address by one and the "high" level of pin P00 (Clear) will reset the address to zero. Figure 18 shows the setup time of the serial address input. **Programming Waveform.** Figures 19, 20, 21 and 22 show the programming waveforms of each mode. Table 8 shows the timing of programming waveforms.

**Programming Algorithm.** Figure 23 shows the flow chart of the Z8 programming algorithm.

Parameters	Name	Min	Max	Units
1	Address Setup Time	2	·	μs
2	Data Setup Time	2		μs
3	V <sub>PP</sub> Setup	2		μs
4	V <sub>cc</sub> Setup Time	2		μs
5	Chip Enable Setup Time	2	·····	μs
6	Program Pulse Width	0.95		ms
7	Data Hold Time	2		μs
8	OE Setup Time	2		μs
9	Data Access Time	188		ns
10	Data Output Float Time		100	ns
11	Overprogram Pulse Width	2.85		ms
12	EPM Setup Time	2		μs
13	PGM Setup Time	2		μs
14	Address to OE Setup Time	2		μs
15	Option Program Pulse Width	78		ms
16	OE Width	250		ns
17	Address Valid to OE Low	125		กร

### Table 8. Timing of Programming Waveforms

Zilog

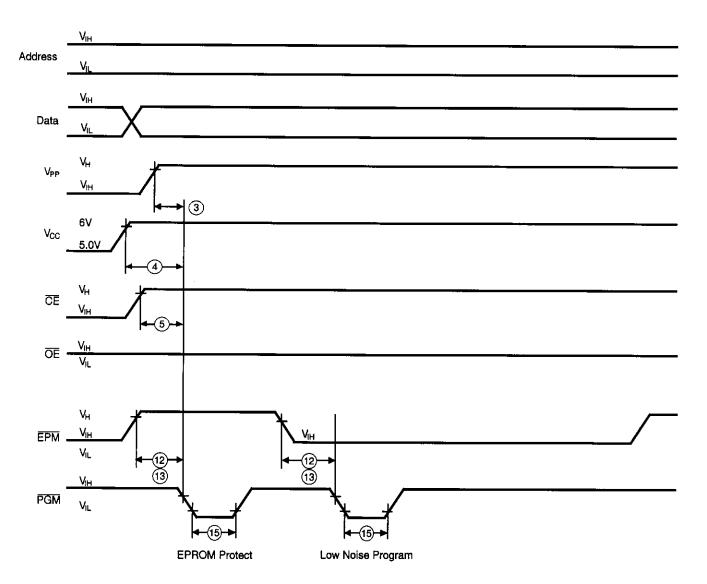


Figure 21. Z86E04/E08 Programming Options Waveform (EPROM Protect and Low Noise Program) Zilog

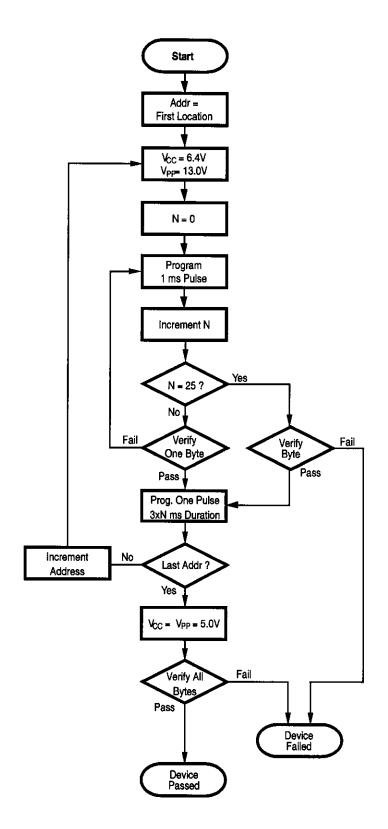


Figure 23. Z86E04/E08 Programming Algorithm