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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

| | |
|----------------------------|---|
| Product Status | Active |
| Core Processor | Z8 |
| Core Size | 8-Bit |
| Speed | 12MHz |
| Connectivity | - |
| Peripherals | POR, WDT |
| Number of I/O | 14 |
| Program Memory Size | 1KB (1K x 8) |
| Program Memory Type | OTP |
| EEPROM Size | - |
| RAM Size | 125 x 8 |
| Voltage - Supply (Vcc/Vdd) | 4.5V ~ 5.5V |
| Data Converters | - |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 105°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 18-SOIC (0.295", 7.50mm Width) |
| Supplier Device Package | - |
| Purchase URL | https://www.e-xfl.com/product-detail/zilog/z86e0412seg |

FEATURES

- 14 Input/Output Lines
- Six Vectored, Prioritized Interrupts
(3 falling edge, 1 rising edge, 2 timers)
- Two Analog Comparators
- Program Options:
 - Low Noise
 - ROM Protect
 - Auto Latch
 - Watch-Dog Timer (WDT)
 - EPROM/Test Mode Disable
- Two Programmable 8-Bit Counter/Timers, Each with 6-Bit Programmable Prescaler
- WDT/ Power-On Reset (POR)
- On-Chip Oscillator that Accepts XTAL, Ceramic Resonance, LC, RC, or External Clock
- Clock-Free WDT Reset
- Low-Power Consumption (50 mw typical)
- Fast Instruction Pointer (1 μ s @ 12 MHz)
- RAM Bytes (125)

GENERAL DESCRIPTION

Zilog's Z86E04/E08 Microcontrollers (MCU) are One-Time Programmable (OTP) members of Zilog's single-chip Z8[®] MCU family that allow easy software development, debug, prototyping, and small production runs not economically desirable with masked ROM versions.

For applications demanding powerful I/O capabilities, the Z86E04/E08's dedicated input and output lines are grouped into three ports, and are configurable under software control to provide timing, status signals, or parallel I/O.

Two on-chip counter/timers, with a large number of user selectable modes, offload the system of administering real-time tasks such as counting/timing and I/O data communications.

Note: All Signals with an overline, " $\overline{}$ ", are active Low, for example: $\overline{B/W}$ (WORD is active Low); \overline{B}/W (BYTE is active Low, only).

Power connections follow conventional descriptions below:

| Connection | Circuit | Device |
|------------|-----------------|-----------------|
| Power | V _{CC} | V _{DD} |
| Ground | GND | V _{SS} |

ABSOLUTE MAXIMUM RATINGS

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability. Total power

dissipation should not exceed 462 mW for the package. Power dissipation is calculated as follows:

$$\begin{aligned} \text{Total Power Dissipation} = & V_{DD} \times [I_{DD} - (\text{sum of } I_{OH})] \\ & + \text{sum of } [(V_{DD} - V_{OH}) \times I_{OH}] \\ & + \text{sum of } (V_{OL} \times I_{OL}) \end{aligned}$$

| Parameter | Min | Max | Units | Note |
|---|------|------------|---------------|------|
| Ambient Temperature under Bias | -40 | +105 | C | |
| Storage Temperature | -65 | +150 | C | |
| Voltage on any Pin with Respect to V_{SS} | -0.7 | +12 | V | 1 |
| Voltage on V_{DD} Pin with Respect to V_{SS} | -0.3 | +7 | V | |
| Voltage on Pins 7, 8, 9, 10 with Respect to V_{SS} | -0.6 | $V_{DD}+1$ | V | 2 |
| Total Power Dissipation | | 1.65 | W | |
| Maximum Allowable Current out of V_{SS} | | 300 | mA | |
| Maximum Allowable Current into V_{DD} | | 220 | mA | |
| Maximum Allowable Current into an Input Pin | -600 | +600 | μA | 3 |
| Maximum Allowable Current into an Open-Drain Pin | -600 | +600 | μA | 4 |
| Maximum Allowable Output Current Sunked by Any I/O Pin | | 25 | mA | |
| Maximum Allowable Output Current Sourced by Any I/O Pin | | 25 | mA | |
| Total Maximum Output Current Sunked by a Port | | 60 | mA | |
| Total Maximum Output Current Sourced by a Port | | 45 | mA | |

Notes:

1. This applies to all pins except where otherwise noted. Maximum current into pin must be $\pm 600 \mu\text{A}$.
2. There is no input protection diode from pin to V_{DD} (not applicable to EPROM Mode).
3. This excludes Pin 6 and Pin 7.
4. Device pin is not at an output Low state.

DC ELECTRICAL CHARACTERISTICS (Continued)

| Sym | Parameter | V _{CC} [4] | T _A = -40°C to +105°C | | Typical @ 25°C | Units | Conditions | Notes |
|------------------|---------------------------------|---------------------|----------------------------------|------|-------------------|-------|--|-------|
| | | | Min | Max | | | | |
| I _{CC} | Supply Current | 4.5V | | 11.0 | 6.8 | mA | All Output and I/O Pins Floating @ 2 MHz | 5,7 |
| | | 5.5V | | 11.0 | 6.8 | mA | All Output and I/O Pins Floating @ 2 MHz | 5,7 |
| | | 4.5V | | 15.0 | 8.2 | mA | All Output and I/O Pins Floating @ 8 MHz | 5,7 |
| | | 5.5V | | 15.0 | 8.2 | mA | All Output and I/O Pins Floating @ 8 MHz | 5,7 |
| | | 4.5V | | 20.0 | 12.0 | mA | All Output and I/O Pins Floating @ 12 MHz | 5,7 |
| | | 5.5V | | 20.0 | 12.0 | mA | All Output and I/O Pins Floating @ 12 MHz | 5,7 |
| I _{CC1} | Standby Current | 4.5V | | 5.0 | 2.5 | mA | HALT Mode V _{IN} = 0V, V _{CC} @ 2 MHz | 5,7 |
| | | 5.5V | | 5.0 | 2.5 | mA | HALT Mode V _{IN} = 0V, V _{CC} @ 2 MHz | 5,7 |
| | | 4.5V | | 5.0 | 3.0 | mA | HALT Mode V _{IN} = 0V, V _{CC} @ 8 MHz | 5,7 |
| | | 5.5V | | 5.0 | 3.0 | mA | HALT Mode V _{IN} = 0V, V _{CC} @ 8 MHz | 5,7 |
| | | 4.5V | | 7.0 | 4.0 | mA | HALT Mode V _{IN} = 0V, V _{CC} @ 12 MHz | 5,7 |
| | | 5.5V | | 7.0 | 4.0 | mA | HALT Mode V _{IN} = 0V, V _{CC} @ 12 MHz | 5,7 |
| I _{CC} | Supply Current (Low Noise Mode) | 4.5V | | 11.0 | 6.8 | mA | All Output and I/O Pins Floating @ 1 MHz | 7 |
| | | 5.5V | | 11.0 | 6.8 | mA | All Output and I/O Pins Floating @ 1 MHz | 7 |
| | | 4.5V | | 13.0 | 7.5 | mA | All Output and I/O Pins Floating @ 2 MHz | 7 |
| | | 5.5V | | 13.0 | 7.5 | mA | All Output and I/O Pins Floating @ 2 MHz | 7 |
| | | 4.5V | | 15.0 | 8.2 | mA | All Output and I/O Pins Floating @ 4 MHz | 7 |
| | | 5.5V | | 15.0 | 8.2 | mA | All Output and I/O Pins Floating @ 4 MHz | 7 |

AC ELECTRICAL CHARACTERISTICS

Timing Table (Standard Mode for SCLK/TCLK = XTAL/2)

Standard Temperature

| 15 | | $T_A = 0\text{ }^{\circ}\text{C to } +70\text{ }^{\circ}\text{C}$ | | | | | | | |
|----|--------------|---|----------|-------|------|--------|-----|-------|-------|
| No | Symbol | Parameter | V_{CC} | 8 MHz | | 12 MHz | | Units | Notes |
| | | | | Min | Max | Min | Max | | |
| 1 | TpC | Input Clock Period | 4.5V | 125 | DC | 83 | DC | ns | 1 |
| | | | 5.5V | 125 | DC | 83 | DC | ns | 1 |
| 2 | TrC,TfC | Clock Input Rise and Fall Times | 4.5V | | 25 | | 15 | ns | 1 |
| | | | 5.5V | | 25 | | 15 | ns | 1 |
| 3 | TwC | Input Clock Width | 4.5V | 62 | | 41 | | ns | 1 |
| | | | 5.5V | 62 | | 41 | | ns | 1 |
| 4 | TwTinL | Timer Input Low Width | 4.5V | 100 | | 100 | | ns | 1 |
| | | | 5.5V | 70 | | 70 | | ns | 1 |
| 5 | TwTinH | Timer Input High Width | 4.5V | 5TpC | | 5TpC | | | 1 |
| | | | 5.5V | 5TpC | | 5TpC | | | 1 |
| 6 | TpTin | Timer Input Period | 4.5V | | 8TpC | 8TpC | | | 1 |
| | | | 5.5V | | 8TpC | 8TpC | | | 1 |
| 7 | TrTin, TtTin | Timer Input Rise and Fall Time | 4.5V | | 100 | | 100 | ns | 1 |
| | | | 5.5V | | 100 | | 100 | ns | 1 |
| 8 | TwIL | Int. Request Input Low Time | 4.5V | 70 | | 70 | | ns | 1,2 |
| | | | 5.5V | 70 | | 70 | | ns | 1,2 |
| 9 | TwIH | Int. Request Input High Time | 4.5V | | 5TpC | 5TpC | | | 1,2 |
| | | | 5.5V | | 5TpC | 5TpC | | | 1,2 |
| 10 | Twdt | Watch-Dog Timer Delay Time for Timeout | 4.5V | 12 | | 12 | | ms | 1 |
| | | | 5.5V | 12 | | 12 | | ms | 1 |
| 11 | Tpor | Power-On Reset Time | 4.5V | 20 | 80 | 20 | 80 | ms | 1 |
| | | | 5.5V | 20 | 80 | 20 | 80 | ms | 1 |

Notes:

1. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.
2. Interrupt request through Port 3 (P33–P31).

AC ELECTRICAL CHARACTERISTICS

Timing Table (Standard Mode for SCLK/TCLK = XTAL/2)

Extended Temperature

| T _A = -40 °C to +105 °C | | | | | | | | | |
|------------------------------------|--------------|--|-----------------|------|-----|------|-----|-------|-------|
| 8 MHz | | | | | | | | | |
| 12 MHz | | | | | | | | | |
| No | Symbol | Parameter | V _{CC} | Min | Max | Min | Max | Units | Notes |
| 1 | TpC | Input Clock Period | 4.5V | 125 | DC | 83 | DC | ns | 1 |
| | | | 5.5V | 125 | DC | 83 | DC | ns | 1 |
| 2 | TrC,TfC | Clock Input Rise and Fall Times | 4.5V | | 25 | | 15 | ns | 1 |
| | | | 5.5V | | 25 | | 15 | ns | 1 |
| 3 | TwC | Input Clock Width | 4.5V | | 62 | | 41 | ns | 1 |
| | | | 5.5V | | 62 | | 41 | ns | 1 |
| 4 | TwTinL | Timer Input Low Width | 4.5V | 70 | | 70 | | ns | 1 |
| | | | 5.5V | 70 | | 70 | | ns | 1 |
| 5 | TwTinH | Timer Input High Width | 4.5V | 5TpC | | 5TpC | | | 1 |
| | | | 5.5V | 5TpC | | 5TpC | | | 1 |
| 6 | TpTin | Timer Input Period | 4.5V | 8TpC | | 8TpC | | | 1 |
| | | | 5.5V | 8TpC | | 8TpC | | | 1 |
| 7 | TrTin, TtTin | Timer Input Rise and Fall Time | 4.5V | | 100 | | 100 | ns | 1 |
| | | | 5.5V | | 100 | | 100 | ns | 1 |
| 8 | TwIL | Int. Request Input Low Time | 4.5V | 70 | | 70 | | ns | 1,2 |
| | | | 5.5V | 70 | | 70 | | ns | 1,2 |
| 9 | TwIH | Int. Request Input High Time | 4.5V | 5TpC | | 5TpC | | | 1,2 |
| | | | 5.5V | 5TpC | | 5TpC | | | 1,2 |
| 10 | Twdt | Watch-Dog Timer Delay Time for Timeout | 4.5V | 10 | | 10 | | ms | 1 |
| | | | 5.5V | 10 | | 10 | | ms | 1 |
| 11 | Tpor | Power-On Reset Time | 4.5V | 12 | 100 | 12 | 100 | ms | 1 |
| | | | 5.5V | 12 | 100 | 12 | 100 | ms | 1 |

Notes:

1. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.
2. Interrupt request made through Port 3 (P33–P31).

AC ELECTRICAL CHARACTERISTICS

Low Noise Mode, Standard Temperature

| No | Symbol | Parameter | V _{CC} | T _A = 0 °C to +70 °C | | | | Units | Notes |
|----|-------------------|---|-----------------|---------------------------------|-----|--------|-----|-------|-------|
| | | | | 1 MHz | | 4 MHz | | | |
| | | | | Min | Max | Min | Max | | |
| 1 | TPC | Input Clock Period | 4.5V | 1000 | DC | 250 | DC | ns | 1 |
| | | | 5.5V | 1000 | DC | 250 | DC | ns | 1 |
| 2 | TrC TfC | Clock Input Rise and Fall Times | 4.5V | | 25 | | 25 | ns | 1 |
| | | | 5.5V | | 25 | | 25 | ns | 1 |
| 3 | TwC | Input Clock Width | 4.5V | 500 | | 125 | | ns | 1 |
| | | | 5.5V | 500 | | 125 | | ns | 1 |
| 4. | TwTinL | Timer Input Low Width | 4.5V | 70 | | 70 | | ns | 1 |
| | | | 5.5V | 70 | | 70 | | ns | 1 |
| 5 | TwTinH | Timer Input High Width | 4.5V | 2.5TpC | | 2.5TpC | | | 1 |
| | | | 5.5V | 2.5TpC | | 2.5TpC | | | 1 |
| 6 | TpTin | Timer Input Period | 4.5V | 4TpC | | 4TpC | | | 1 |
| | | | 5.5V | 4TpC | | 4TpC | | | 1 |
| 7 | TrTin, TtTin | Timer Input Rise and Fall Time | 4.5V | | 100 | | 100 | ns | 1 |
| | | | 5.5V | | 100 | | 100 | ns | 1 |
| 8 | TwIL Low Time | Int. Request Input | 4.5V | 70 | | 70 | | ns | 1,2 |
| | | | 5.5V | 70 | | 70 | | ns | 1,2 |
| 9 | TwIH High Time | Int. Request Input | 4.5V | 2.5TpC | | 2.5TpC | | | 1,2 |
| | | | 5.5V | 2.5TpC | | 2.5TpC | | | 1,2 |
| 10 | Twdt | Watch-Dog Timer Delay Time for Timeout | 4.5V | 12 | | 12 | | ms | 1 |
| | | | 5.5V | 12 | | 12 | | ms | 1 |

Notes:

1. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.
2. Interrupt request through Port 3 (P33–P31).

PIN FUNCTIONS (Continued)

XTAL1, XTAL2 *Crystal In, Crystal Out* (time-based input and output, respectively). These pins connect a parallel-resonant crystal, LC, or an external single-phase clock (8 MHz or 12 MHz max) to the on-chip clock oscillator and buffer.

Port 0, P02–P00. Port 0 is a 3-bit bidirectional, Schmitt-triggered CMOS-compatible I/O port. These three I/O lines can be globally configured under software control to be inputs or outputs (Figure 7).

Auto Latch. The Auto Latch puts valid CMOS levels on all CMOS inputs (except P33, P32, P31) that are not externally driven. A valid CMOS level, rather than a floating node, reduces excessive supply current flow in the input buffer. On Power-up and Reset, the Auto Latch will set the ports to an undetermined state of 0 or 1. Default condition is Auto Latches enabled.

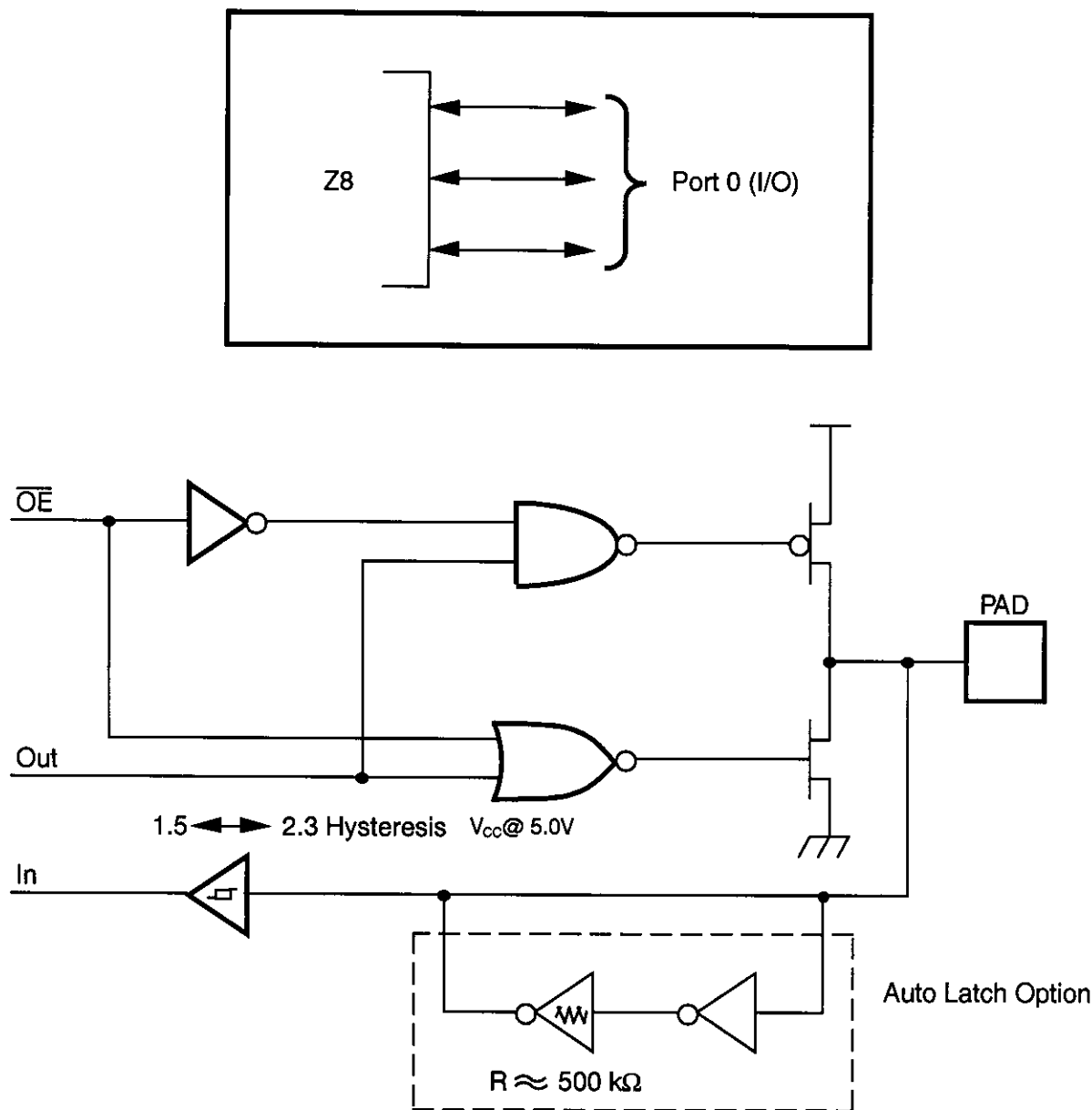


Figure 7. Port 0 Configuration

PIN FUNCTIONS (Continued)

Port 3, P33–P31. Port 3 is a 3-bit, CMOS-compatible port with three fixed input (P33–P31) lines. These three input lines can be configured under software control as digital Schmitt-trigger inputs or analog inputs.

These three input lines are also used as the interrupt sources IRQ0–IRQ3, and as the timer input signal T_{IN} (Figure 9).

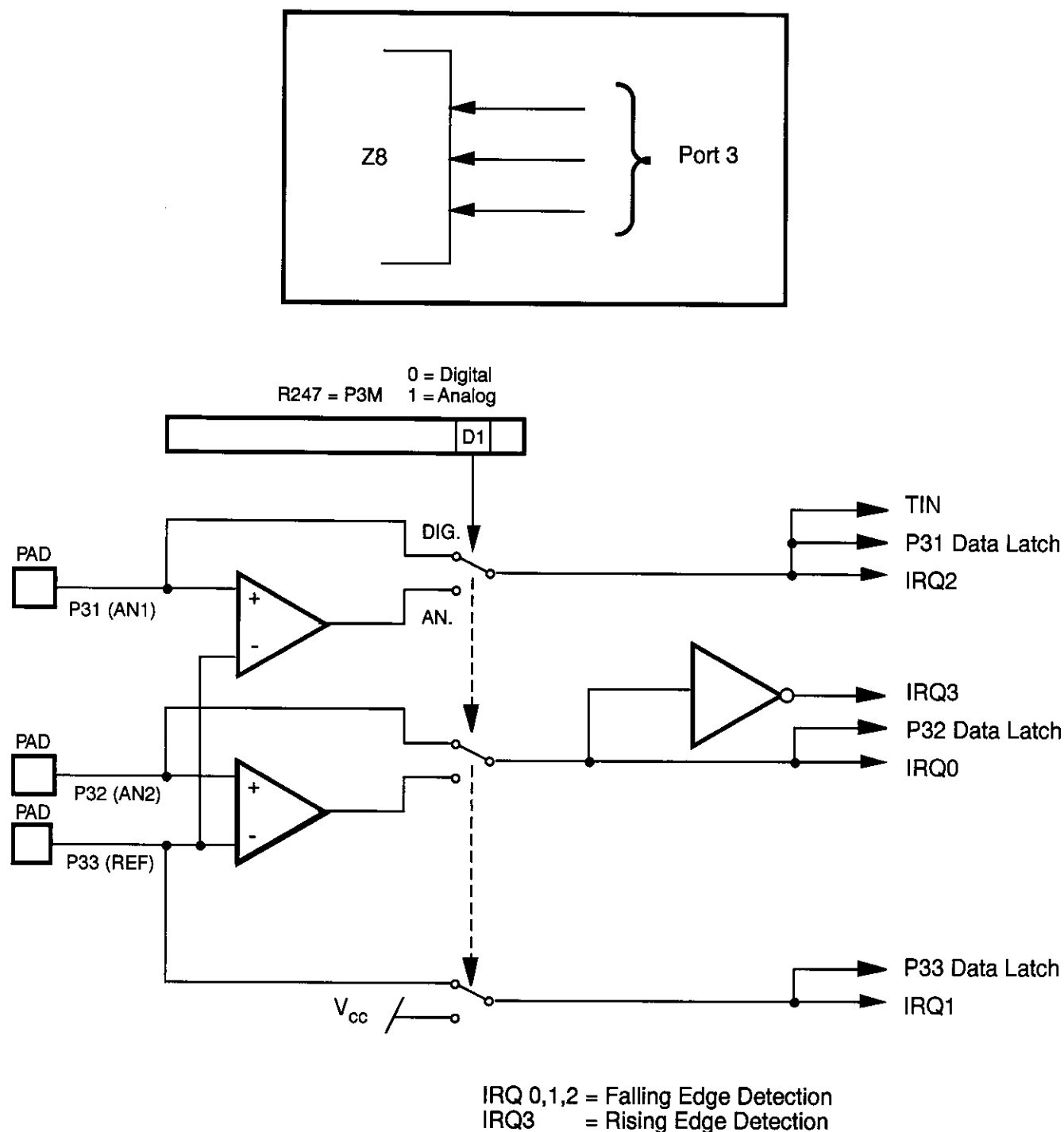


Figure 9. Port 3 Configuration

Program Memory. The Z86E04/E08 addresses up to 1K/2KB of Internal Program Memory (Figure 11). The first 12 bytes of program memory are reserved for the interrupt vectors. These locations contain six 16-bit vectors that correspond to the six available interrupts. Bytes 0–1024/2048 are on-chip one-time programmable ROM.

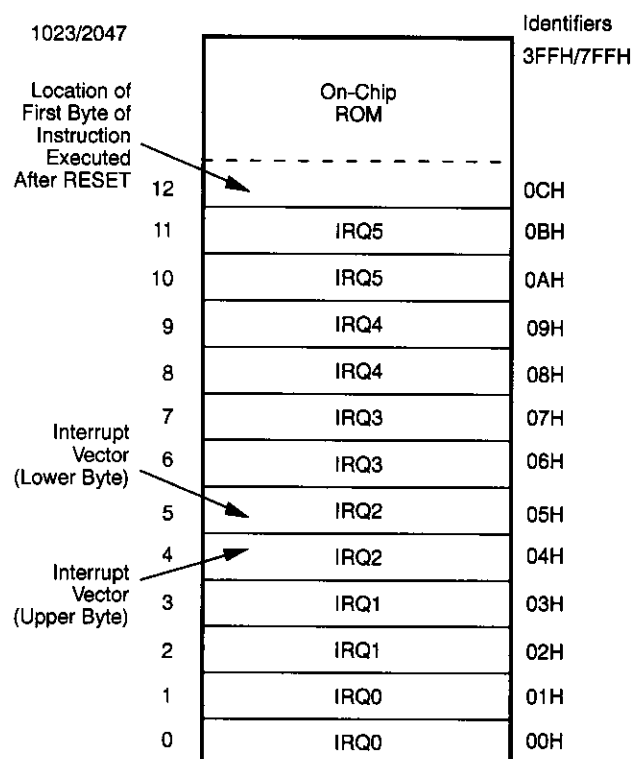
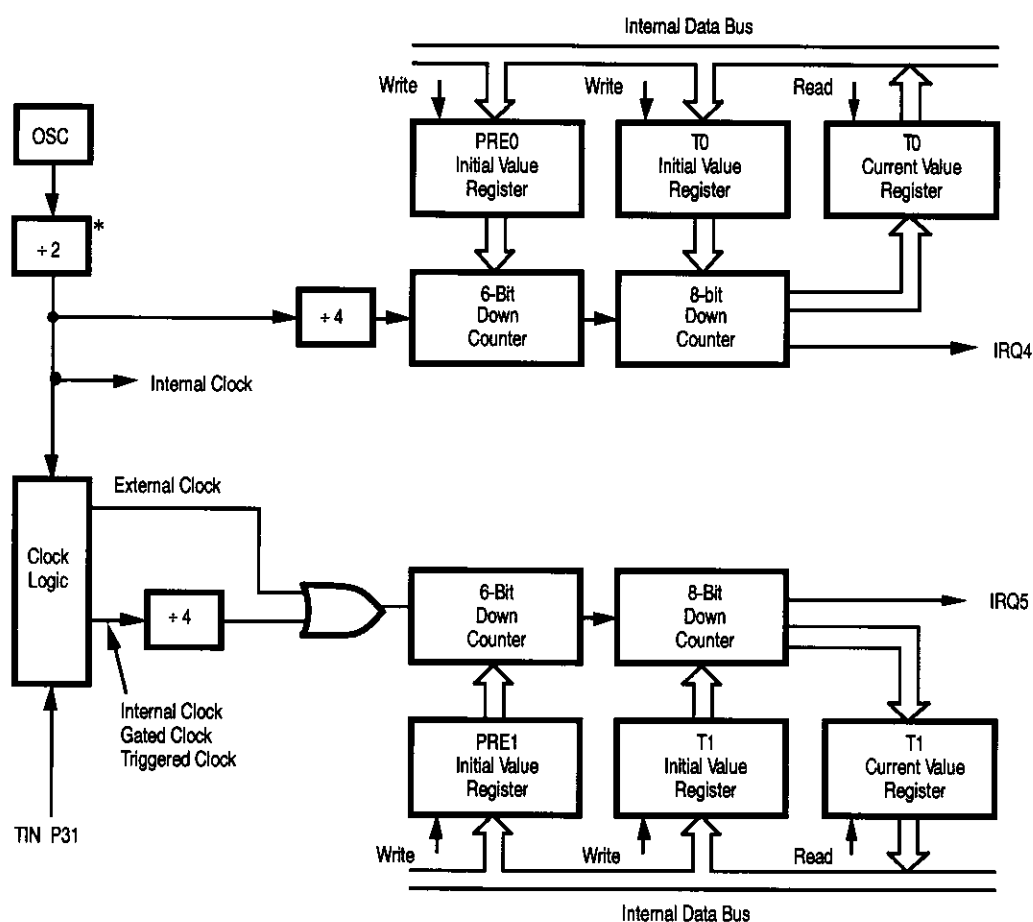


Figure 11. Program Memory Map

Register File. The Register File consists of three I/O port registers, 124 general-purpose registers, and 14 control and status registers R0–R3, R4–R127 and R241–R255, respectively (Figure 12). General-purpose registers occupy the 04H to 7FH address space. I/O ports are mapped as per the existing CMOS Z8.

| Location | Identifiers |
|-----------|---------------------------------|
| 255 (FFH) | Stack Pointer (Bits 7-0) SPL |
| 254 (FE) | General-Purpose Register GPR |
| 253 (FD) | Register Pointer RP |
| 252 (FC) | Program Control Flags FLAGS |
| 251 (FB) | Interrupt Mask Register IMR |
| 250 (FA) | Interrupt Request Register IRQ |
| 249 (F9) | Interrupt Priority Register IPR |
| 248 (F8) | Ports 0-1 Mode P01M |
| 247 (F7) | Port 3 Mode P3M |
| 246 (F6) | Port 2 Mode P2M |
| 245 (F5) | T0 Prescaler PRE0 |
| 244 (F4) | Timer/Counter 0 T0 |
| 243 (F3) | T1 Prescaler PRE1 |
| 242 (F2) | Timer/Counter 1 T1 |
| 241 (F1H) | Timer Mode TMR |
| 128 | Not Implemented |
| 127 (7FH) | General-Purpose Registers |
| 4 | |
| 3 | Port 3 P3 |
| 2 | Port 2 P2 |
| 1 | Reserved P1 |
| 0 (00H) | Port 0 P0 |

Figure 12. Register File



* Note: By passed, if Low EMI Mode is selected.

Figure 14. Counter/Timers Block Diagram

FUNCTIONAL DESCRIPTION (Continued)

Interrupts. The Z8 has six interrupts from six different sources. These interrupts are maskable and prioritized (Figure 15). The sources are divided as follows: the falling edge of P31 (AN1), P32 (AN2), P33 (REF), the rising edge of P32 (AN2), and two counter/timers. The Interrupt Mask Register globally or individually enables or disables the six interrupt requests (Table 4).

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder that is controlled by the Interrupt Priority register. All Z8 interrupts are vectored through locations in program memory. When an Interrupt machine cycle is activated, an Interrupt Request is granted. This disables all subsequent interrupts, saves the Program Counter and Status Flags, and then branches to the program memory vector location reserved for that interrupt. This memory location and the next byte contain the 16-bit starting address of the interrupt service routine for that particular interrupt request.

To accommodate polled interrupt systems, interrupt inputs are masked and the interrupt request register is polled to determine which of the interrupt requests needs service.

Note: User must select any Z86E08 mode in Zilog's C12 ICEBOX™ emulator. The rising edge interrupt is not supported on the CCP emulator (a hardware/software workaround must be employed).

Table 4. Interrupt Types, Sources, and Vectors

| Name | Source | Vector Location | Comments |
|------|----------|-----------------|------------------|
| IRQ0 | AN2(P32) | 0,1 | External (F)Edge |
| IRQ1 | REF(P33) | 2,3 | External (F)Edge |
| IRQ2 | AN1(P31) | 4,5 | External (F)Edge |
| IRQ3 | AN2(P32) | 6,7 | External (R)Edge |
| IRQ4 | T0 | 8,9 | Internal |
| IRQ5 | T1 | 10,11 | Internal |

Notes:

F = Falling edge triggered

R = Rising edge triggered

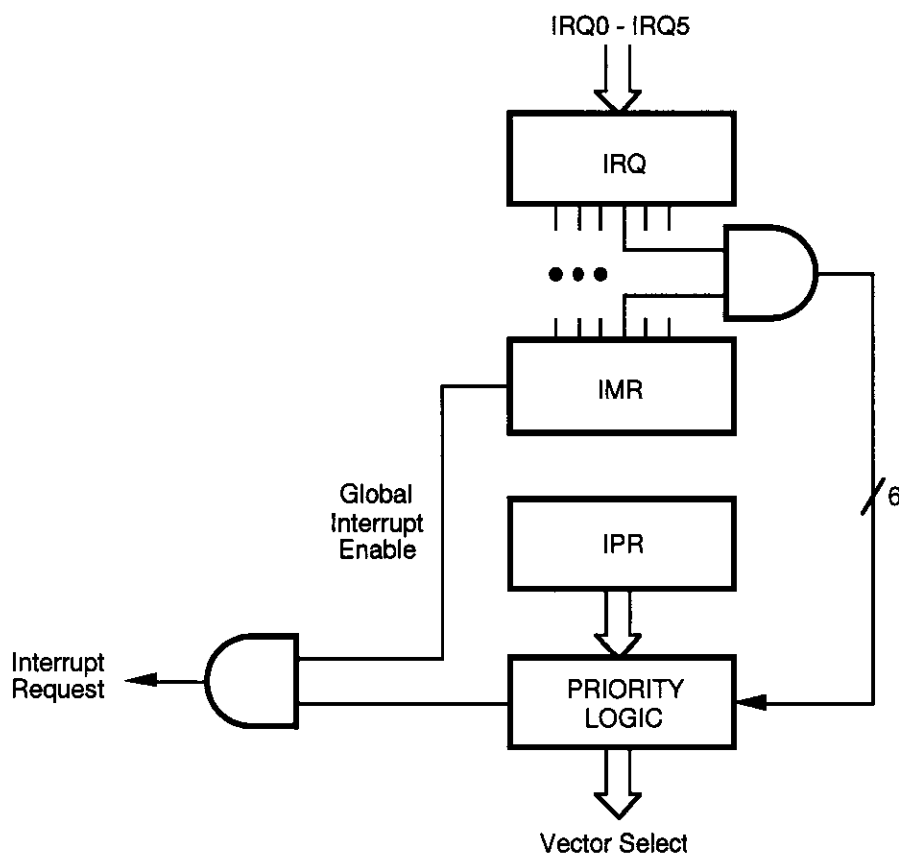


Figure 15. Interrupt Block Diagram

Low EMI Emission

The Z8 can be programmed to operate in a low EMI Emission (Low Noise) Mode by means of an EPROM programmable bit option. Use of this feature results in:

- Less than 1 mA consumed during HALT Mode.
- All drivers slew rates reduced to 10 ns (typical).
- Internal SCLK/TCLK = XTAL operation limited to a maximum of 4 MHz–250 ns cycle time.
- Output drivers have resistances of 500 ohms (typical).
- Oscillator divide-by-two circuitry eliminated.

In addition to V_{DD} and GND (V_{SS}), the Z8 changes all its pin functions in the EPROM Mode. XTAL2 has no function, XTAL1 functions as \overline{CE} , P31 functions as \overline{OE} , P32 functions as EPM, P33 functions as V_{PP} , and P02 functions as PGM.

ROM Protect. ROM Protect fully protects the Z8 ROM code from being read externally. When ROM Protect is selected, the instructions LDC and LDCI are supported (Z86E04/E08 and Z86C04/C08 do not support the instructions of LDE and LDEI). When the device is programmed for ROM Protect, the Low Noise feature will not automatically be enabled.

Please note that when using the device in a noisy environment, it is suggested that the voltages on the EPM and \overline{CE} pins be clamped to V_{CC} through a diode to V_{CC} to prevent accidentally entering the OTP Mode. The V_{PP} requires both a diode and a 100 pF capacitor.

Auto Latch Disable. Auto Latch Disable option bit when programmed will globally disable all Auto Latches.

WDT Enable. The WDT Enable option bit, when programmed, will have the hardware enabled Permanent WDT enabled after exiting reset and can not be stopped in Halt or Stop Mode.

EPROM/Test Mode Disable. The EPROM/Test Mode Disable option bit, when programmed, will disable the EPROM Mode and the Factory Test Mode. Reading, verifying, and programming the Z8 will be disabled. To fully verify that this mode is disabled, the device must be power cycled.

User Modes. Table 7 shows the programming voltage of each mode.

Table 7. OTP Programming Table

| Programming Modes | V_{PP} | EPM | \overline{CE} | \overline{OE} | PGM | ADDR | DATA | V_{CC}^* |
|--------------------|----------|----------|-----------------|-----------------|----------|------|------|------------|
| EPROM READ | NU | V_H | V_{IL} | V_{IL} | V_{IH} | ADDR | Out | 5.0V |
| PROGRAM | V_H | V_{IH} | V_{IL} | V_{IH} | V_{IL} | ADDR | In | 6.4V |
| PROGRAM VERIFY | V_H | V_{IH} | V_{IL} | V_{IL} | V_{IH} | ADDR | Out | 6.4V |
| EPROM PROTECT | V_H | V_H | V_H | V_{IH} | V_{IL} | NU | NU | 6.4V |
| LOW NOISE SELECT | V_H | V_{IH} | V_H | V_{IH} | V_{IL} | NU | NU | 6.4V |
| AUTO LATCH DISABLE | V_H | V_{IH} | V_H | V_{IL} | V_{IL} | NU | NU | 6.4V |
| WDT ENABLE | V_H | V_{IL} | V_H | V_{IH} | V_{IL} | NU | NU | 6.4V |
| EPROM/TEST MODE | V_H | V_{IL} | V_H | V_{IL} | V_{IL} | NU | NU | 6.4V |

Notes:

1. $V_H = 12.75V \pm 0.25 V_{DC}$.
2. V_{IH} = As per specific Z8 DC specification.
3. V_{IL} = As per specific Z8 DC specification.
4. X = Not used, but must be set to V_H or V_{IH} level.
5. NU = Not used, but must be set to either V_{IH} or V_{IL} level.
6. I_{PP} during programming = 40 mA maximum.
7. I_{CC} during programming, verify, or read = 40 mA maximum.
8. * V_{CC} has a tolerance of $\pm 0.25V$.

FUNCTIONAL DESCRIPTION (Continued)

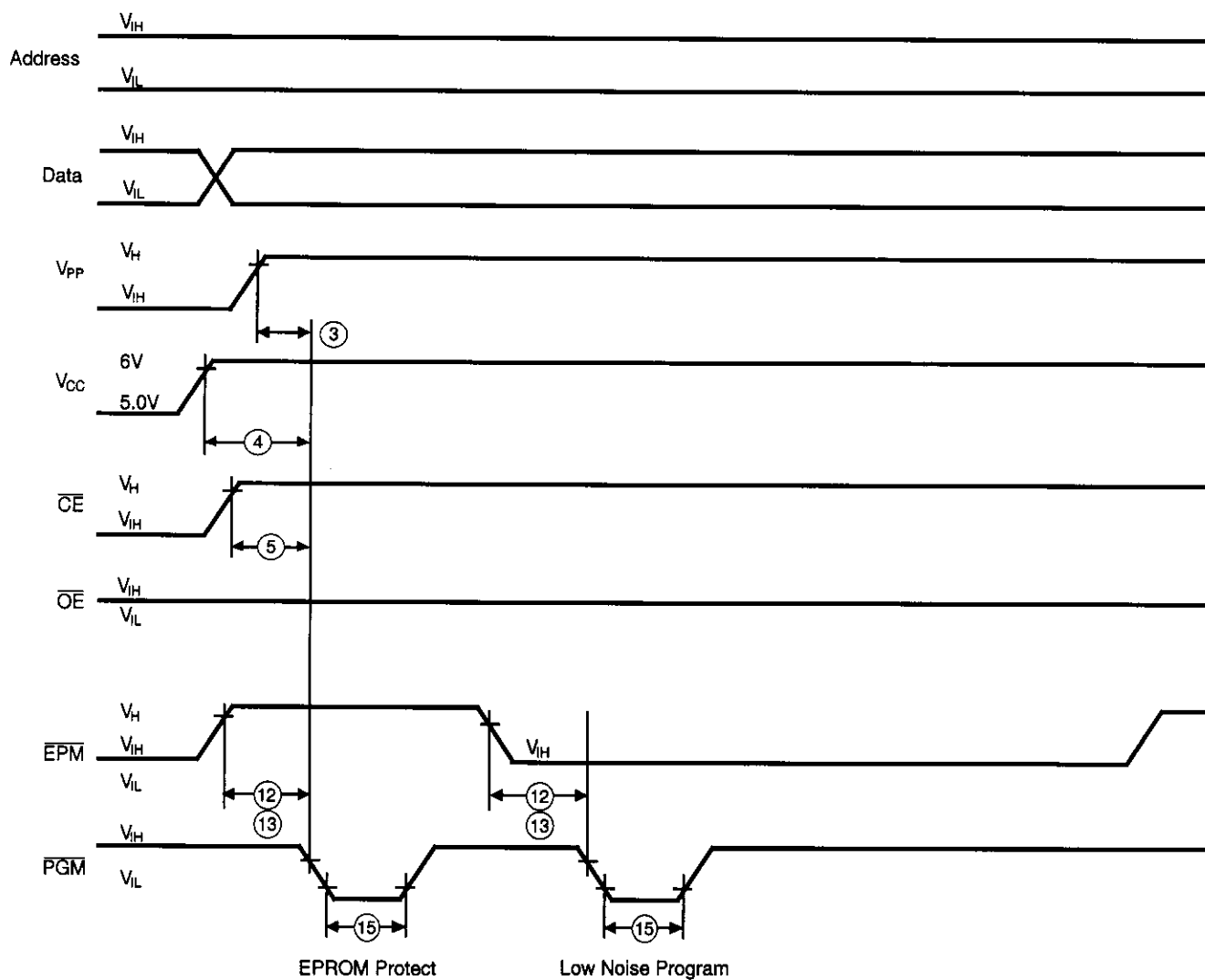
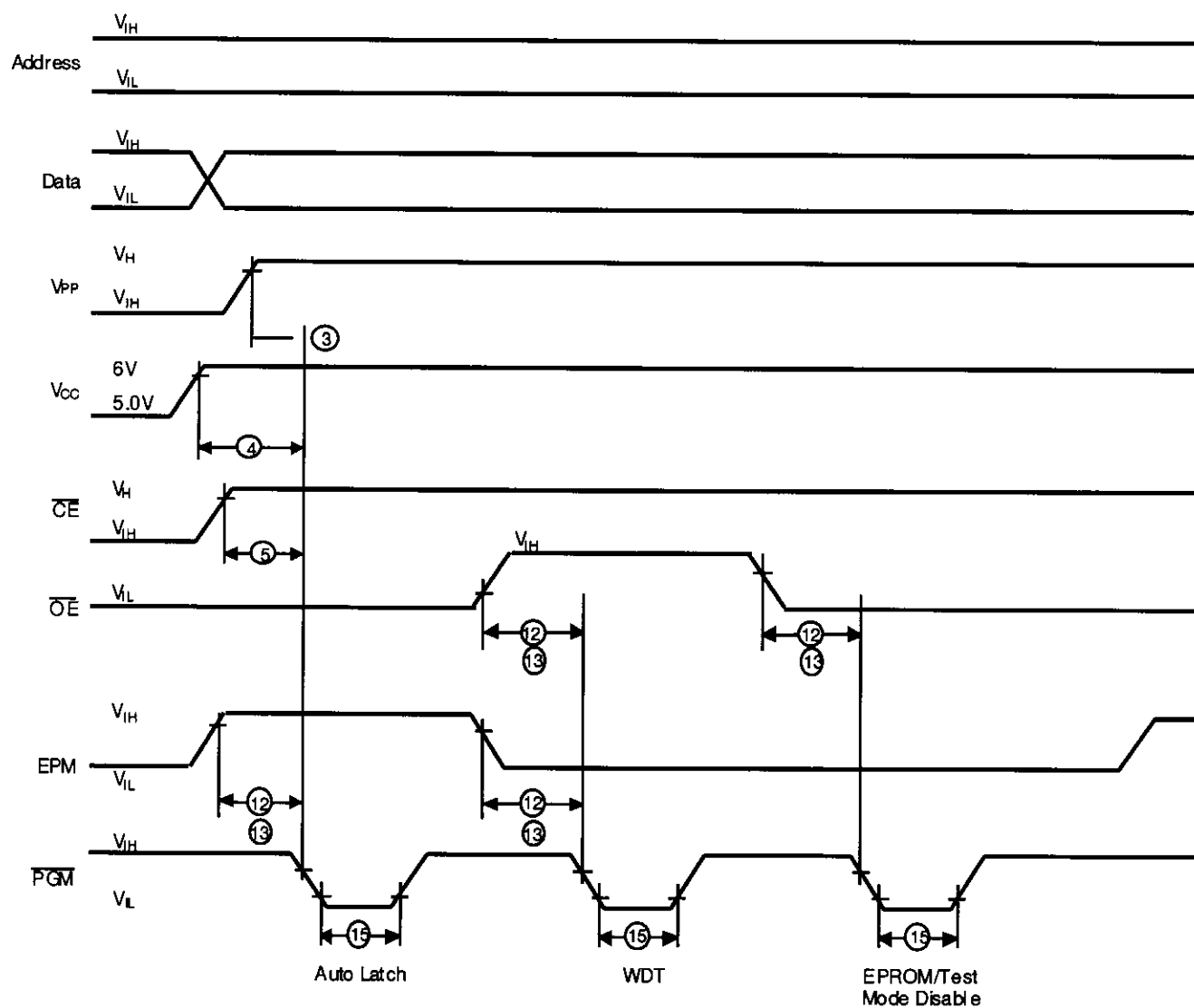


Figure 21. Z86E04/E08 Programming Options Waveform
(EPROM Protect and Low Noise Program)



**Figure 22. Z86E04/E08 Programming Options Waveform
(Auto Latch Disable, Permanent WDT Enable and
EPROM/Test Mode Disable)**

FUNCTIONAL DESCRIPTION (Continued)

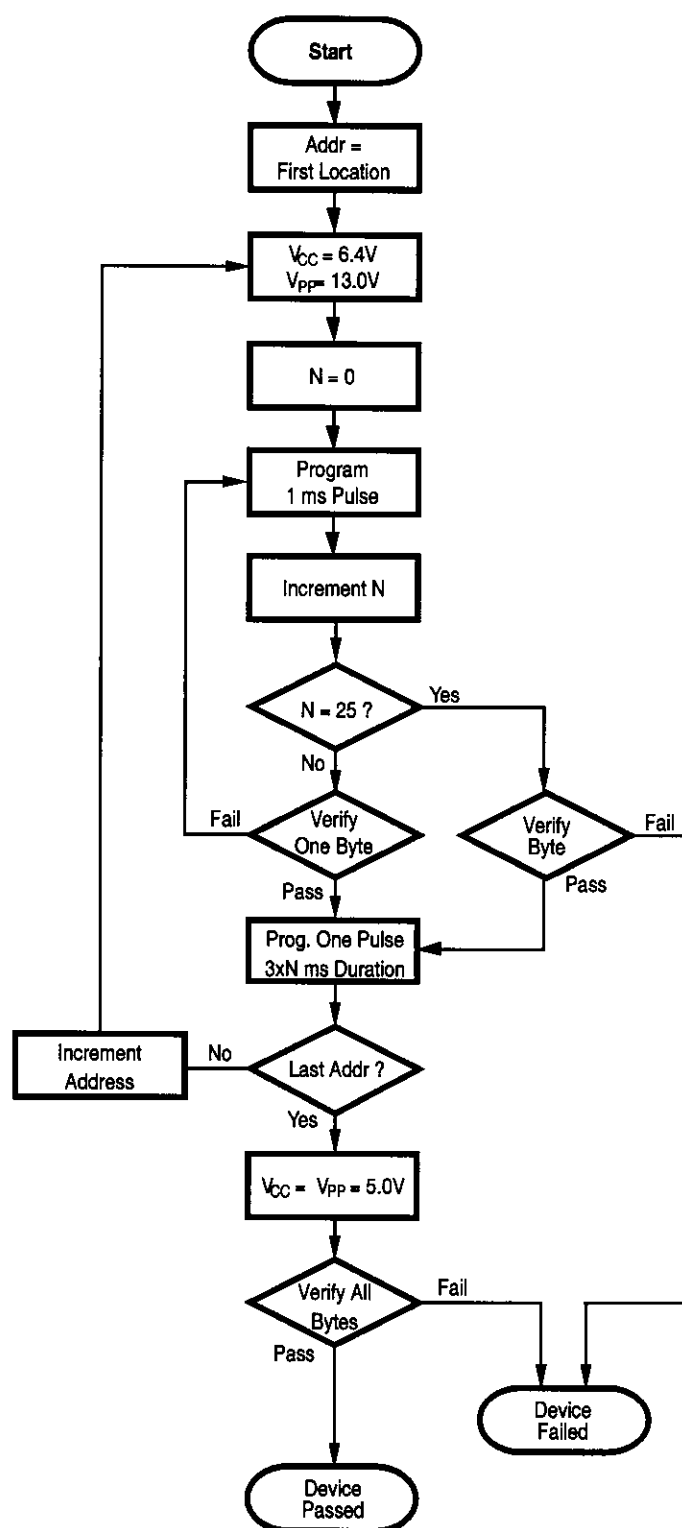
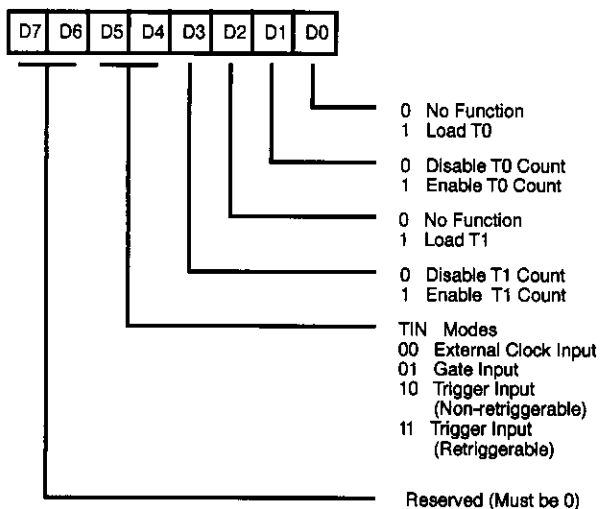


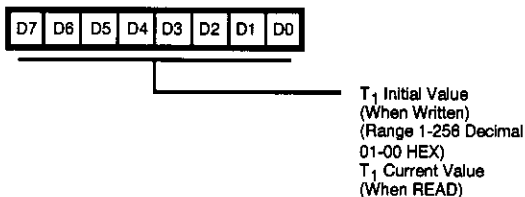
Figure 23. Z86E04/E08 Programming Algorithm

Z8 CONTROL REGISTERS

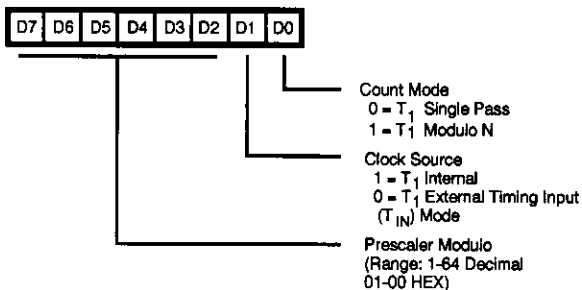
R241 TMR

Figure 24. Timer Mode Register (F1_H: Read/Write)

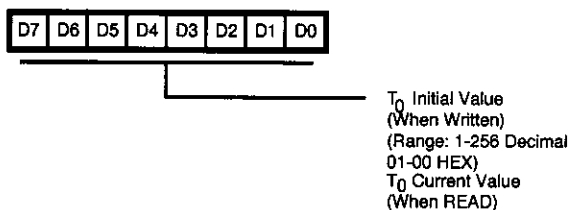
R242 T1

Figure 25. Counter Timer 1 Register (F2_H: Read/Write)

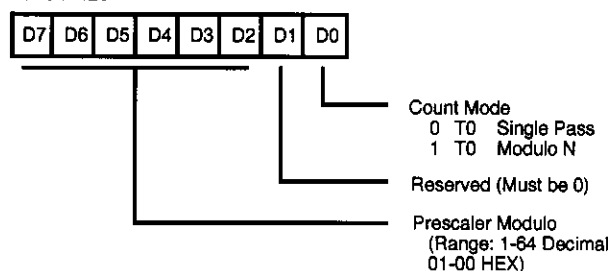
R243 PRE1

Figure 26. Prescaler 1 Register (F3_H: Write Only)

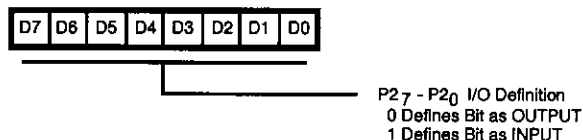
R244 T0

Figure 27. Counter/Timer 0 Register (F4_H: Read/Write)

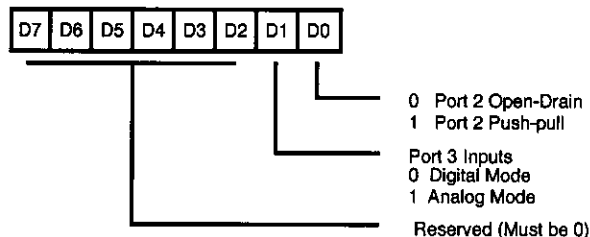
R245 PRE0

Figure 28. Prescaler 0 Register (F5_H: Write Only)

R246 P2M

Figure 29. Port 2 Mode Register (F6_H: Write Only)

R247 P3M

Figure 30. Port 3 Mode Register (F7_H: Write Only)

Z8 CONTROL REGISTERS (Continued)

R248 P01M

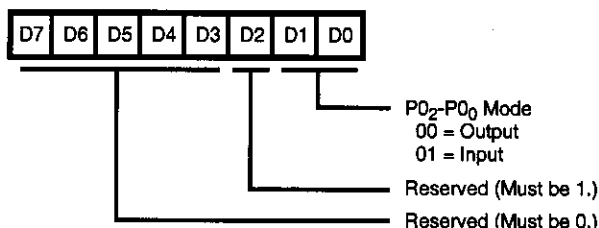


Figure 31. Port 0 and 1 Mode Register
(F8_H: Write Only)

R249 IPR

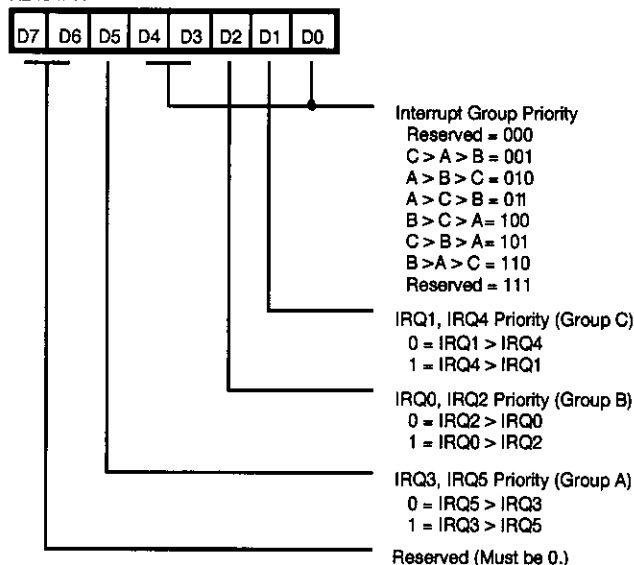


Figure 32. Interrupt Priority Register
(F9_H: Write Only)

R250 IRQ

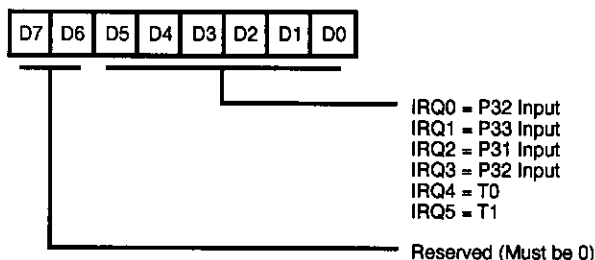


Figure 33. Interrupt Request Register
(FA_H: Read/Write)

R251 IMR

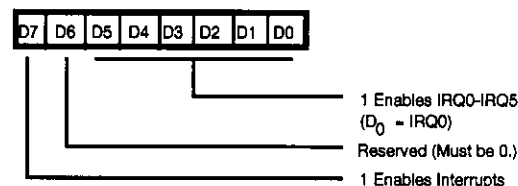


Figure 34. Interrupt Mask Register
(FB_H: Read/Write)

R252 Flags

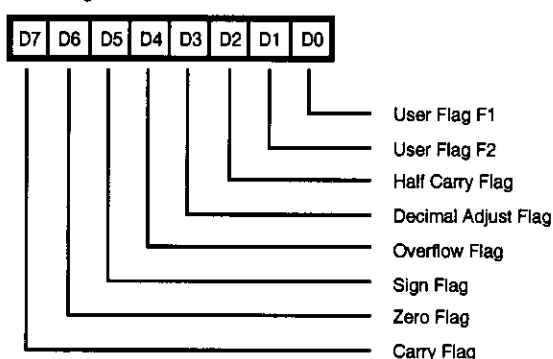


Figure 35. Flag Register
(FC_H: Read/Write)

R253 RP

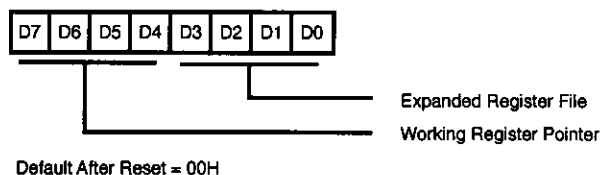


Figure 36. Register Pointer
(FD_H: Read/Write)

R255 SPL

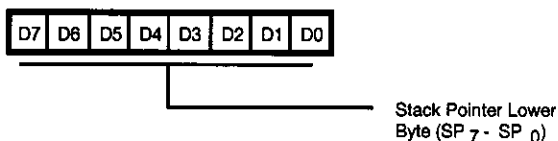
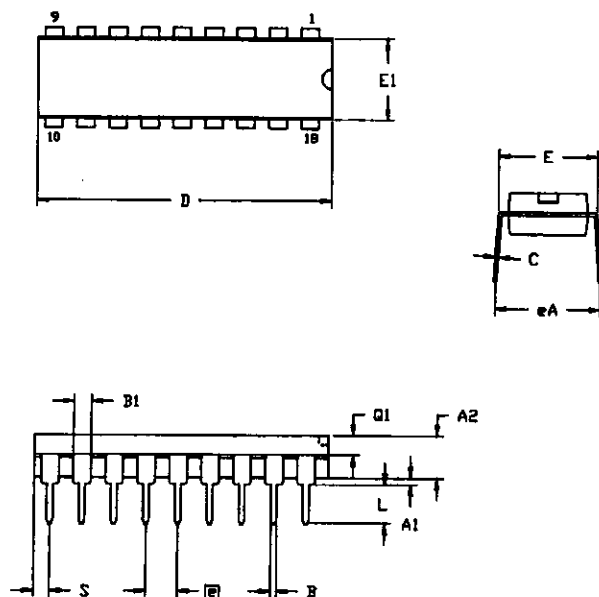


Figure 37. Stack Pointer
(FF_H: Read/Write)

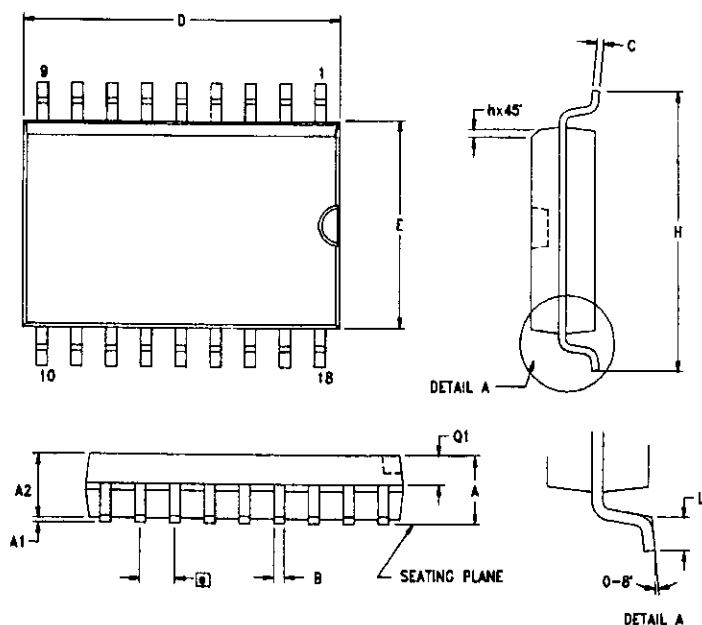
PACKAGE INFORMATION



| SYMBOL | MILLIMETER | | INCH | |
|--------|------------|-------|----------|------|
| | MIN | MAX | MIN | MAX |
| A1 | 0.51 | 0.81 | .020 | .032 |
| A2 | 3.25 | 3.43 | .128 | .135 |
| B | 0.38 | 0.53 | .015 | .021 |
| B1 | 1.14 | 1.65 | .045 | .065 |
| C | 0.23 | 0.38 | .009 | .015 |
| D | 22.35 | 23.37 | .880 | .920 |
| E | 7.62 | 8.13 | .300 | .320 |
| E1 | 6.22 | 6.48 | .245 | .255 |
| □ | 2.54 TYP | | .100 TYP | |
| eA | 7.87 | 8.89 | .310 | .350 |
| L | 3.18 | 3.81 | .125 | .150 |
| Q1 | 1.52 | 1.65 | .060 | .065 |
| S | 0.89 | 1.65 | .035 | .065 |

CONTROLLING DIMENSIONS : INCH

18-Pin DIP Package Diagram



| SYMBOL | MILLIMETER | | INCH | |
|--------|------------|-------|-----------|-------|
| | MIN | MAX | MIN | MAX |
| A | 2.40 | 2.65 | 0.094 | 0.104 |
| A1 | 0.10 | 0.30 | 0.004 | 0.012 |
| A2 | 2.24 | 2.44 | 0.088 | 0.096 |
| B | 0.36 | 0.46 | 0.014 | 0.018 |
| C | 0.23 | 0.30 | 0.009 | 0.012 |
| D | 11.40 | 11.75 | 0.449 | 0.463 |
| E | 7.40 | 7.60 | 0.291 | 0.299 |
| □ | 1.27 TYP | | 0.050 TYP | |
| H | 10.00 | 10.65 | 0.394 | 0.419 |
| h | 0.30 | 0.50 | 0.012 | 0.020 |
| L | 0.60 | 1.00 | 0.024 | 0.039 |
| Q1 | 0.97 | 1.07 | 0.038 | 0.042 |

CONTROLLING DIMENSIONS : MM
LEADS ARE COPLANAR WITHIN .004 INCH.

18-Pin SOIC Package Diagram

ORDERING INFORMATION

Z86E04

Standard Temperature

| 18-Pin DIP | 18-Pin SOIC |
|-------------|-------------|
| Z86E0412PSC | Z86E0412SSC |
| Z86E0412PEC | Z86E0412SEC |

Z86E08

Standard Temperature

| 18-Pin DIP | 18-Pin SOIC |
|-------------|-------------|
| Z86E0812PSC | Z86E0812SSC |
| Z86E0812PEC | Z86E0812SEC |

For fast results, contact your local Zilog sales office for assistance in ordering the part(s) desired.

Codes

Preferred Package

P = Plastic DIP

Speeds

12 = 12 MHz

Longer Lead Time

S = SOIC

Environmental

C = Plastic Standard

Preferred Temperature

S = 0°C to +70°C

E = -40°C to +105°C

Example:

Z 86E04 12 P S C is a Z86E04, 12 MHz, DIP, 0°C to +70°C, Plastic Standard Flow

The diagram illustrates the structure of the part number 'Z 86E04 12 P S C' with lines connecting each segment to its description:

- Z**: Zilog Prefix
- 86E04**: Product Number
- 12**: Speed
- P**: Package
- S**: Temperature
- C**: Environmental Flow

Pre-Characterization Product:

The product represented by this CPS is newly introduced and Zilog has not completed the full characterization of the product. The CPS states what Zilog knows about this product at this time, but additional features or nonconformance with some aspects of the CPS may be

found, either by Zilog or its customers in the course of further application and characterization work. In addition, Zilog cautions that delivery may be uncertain at times, due to start-up yield issues.

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