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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	Z8
Core Size	8-Bit
Speed	12MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	14
Program Memory Size	2KB (2K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	125 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/zilog/z86e0812peg1866">https://www.e-xfl.com/product-detail/zilog/z86e0812peg1866</a>

## FEATURES

- 14 Input/Output Lines
- Six Vectored, Prioritized Interrupts (3 falling edge, 1 rising edge, 2 timers)
- Two Analog Comparators
- Program Options:
  - Low Noise
  - ROM Protect
  - Auto Latch
  - Watch-Dog Timer (WDT)
  - EPROM/Test Mode Disable
- Two Programmable 8-Bit Counter/Timers, Each with 6-Bit Programmable Prescaler
- WDT/ Power-On Reset (POR)
- On-Chip Oscillator that Accepts XTAL, Ceramic Resonance, LC, RC, or External Clock
- Clock-Free WDT Reset
- Low-Power Consumption (50 mw typical)
- Fast Instruction Pointer (1 $\mu$ s @ 12 MHz)
- RAM Bytes (125)

## GENERAL DESCRIPTION

Zilog's Z86E04/E08 Microcontrollers (MCU) are One-Time Programmable (OTP) members of Zilog's single-chip Z8<sup>®</sup> MCU family that allow easy software development, debug, prototyping, and small production runs not economically desirable with masked ROM versions.

For applications demanding powerful I/O capabilities, the Z86E04/E08's dedicated input and output lines are grouped into three ports, and are configurable under software control to provide timing, status signals, or parallel I/O.

Two on-chip counter/timers, with a large number of user selectable modes, offload the system of administering real-time tasks such as counting/timing and I/O data communications.

**Note:** All Signals with an overline, " $\overline{\phantom{x}}$ ", are active Low, for example:  $\overline{B/W}$  (WORD is active Low);  $\overline{B}/W$  (BYTE is active Low, only).

Power connections follow conventional descriptions below:

Connection	Circuit	Device
Power	V <sub>CC</sub>	V <sub>DD</sub>
Ground	GND	V <sub>SS</sub>

## PIN DESCRIPTION

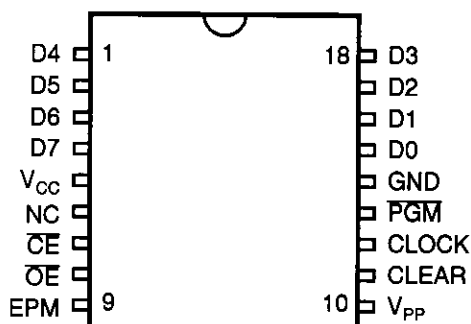


Figure 3. 18-Pin EPROM Mode Configuration

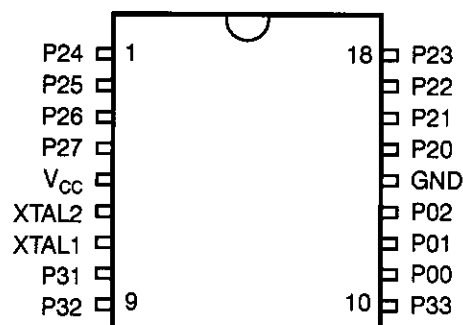


Figure 4. 18-Pin DIP/SOIC Mode Configuration

Table 1. 18-Pin DIP Pin Identification

EPROM Programming Mode			
Pin #	Symbol	Function	Direction
1–4	D4–D7	Data 4, 5, 6, 7	In/Output
5	V <sub>CC</sub>	Power Supply	
6	NC	No Connection	
7	CE	Chip Enable	Input
8	OE	Output Enable	Input
9	EPM	EPROM Prog Mode	Input
10	V <sub>PP</sub>	Prog Voltage	Input
11	Clear	Clear Clock	Input
12	Clock	Address	Input
13	PGM	Prog Mode	Input
14	GND	Ground	
15–18	D0–D3	Data 0,1, 2, 3	In/Output

Table 2. 18-Pin DIP/SOIC Pin Identification

Standard Mode			
Pin #	Symbol	Function	Direction
1–4	P24–P27	Port 2, Pins 4,5,6,7	In/Output
5	V <sub>CC</sub>	Power Supply	
6	XTAL2	Crystal Osc. Clock	Output
7	XTAL1	Crystal Osc. Clock	Input
8	P31	Port 3, Pin 1, AN1	Input
9	P32	Port 3, Pin 2, AN2	Input
10	P33	Port 3, Pin 3, REF	Input
11–13	P00–P02	Port 0, Pins 0,1,2	In/Output
14	GND	Ground	
15–18	P20–P23	Port 2, Pins 0,1,2,3	In/Output

**ABSOLUTE MAXIMUM RATINGS**

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability. Total power

dissipation should not exceed 462 mW for the package. Power dissipation is calculated as follows:

$$\begin{aligned} \text{Total Power Dissipation} = & V_{DD} \times [I_{DD} - (\text{sum of } I_{OH})] \\ & + \text{sum of } [(V_{DD} - V_{OH}) \times I_{OH}] \\ & + \text{sum of } (V_{OL} \times I_{OL}) \end{aligned}$$

Parameter	Min	Max	Units	Note
Ambient Temperature under Bias	-40	+105	C	
Storage Temperature	-65	+150	C	
Voltage on any Pin with Respect to $V_{SS}$	-0.7	+12	V	1
Voltage on $V_{DD}$ Pin with Respect to $V_{SS}$	-0.3	+7	V	
Voltage on Pins 7, 8, 9, 10 with Respect to $V_{SS}$	-0.6	$V_{DD}+1$	V	2
Total Power Dissipation		1.65	W	
Maximum Allowable Current out of $V_{SS}$		300	mA	
Maximum Allowable Current into $V_{DD}$		220	mA	
Maximum Allowable Current into an Input Pin	-600	+600	$\mu\text{A}$	3
Maximum Allowable Current into an Open-Drain Pin	-600	+600	$\mu\text{A}$	4
Maximum Allowable Output Current Sunked by Any I/O Pin		25	mA	
Maximum Allowable Output Current Sourced by Any I/O Pin		25	mA	
Total Maximum Output Current Sunked by a Port		60	mA	
Total Maximum Output Current Sourced by a Port		45	mA	

**Notes:**

1. This applies to all pins except where otherwise noted. Maximum current into pin must be  $\pm 600 \mu\text{A}$ .
2. There is no input protection diode from pin to  $V_{DD}$  (not applicable to EPROM Mode).
3. This excludes Pin 6 and Pin 7.
4. Device pin is not at an output Low state.

## DC ELECTRICAL CHARACTERISTICS (Continued)

Sym	Parameter	V <sub>CC</sub> [4]	T <sub>A</sub> = 0°C to +70°C		Typical @ 25°C	Units	Conditions	Notes
			Min	Max				
I <sub>CC1</sub>	Standby Current (Low Noise Mode)	4.5V		4.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 1 MHz	7
		5.5V		4.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 1 MHz	7
		4.5V		4.5	2.8	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 2 MHz	7
		5.5V		4.5	2.8	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 2 MHz	7
		4.5V		5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 4 MHz	7
		5.5V		5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 4 MHz	7
I <sub>CC2</sub>	Standby Current	4.5V		10.0	1.0	μA	STOP Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> WDT is not Running	7,8
		5.5V		10.0	1.0	μA	STOP Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> WDT is not Running	7,8
I <sub>ALL</sub>	Auto Latch Low Current	4.5V		32.0	16	μA	0V < V <sub>IN</sub> < V <sub>CC</sub>	
		5.5V		32.0	16	μA	0V < V <sub>IN</sub> < V <sub>CC</sub>	
I <sub>ALH</sub>	Auto Latch High Current	4.5V		-16.0	-8.0	μA	0V < V <sub>IN</sub> < V <sub>CC</sub>	
		5.5V		-16.0	-8.0	μA	0V < V <sub>IN</sub> < V <sub>CC</sub>	

## Notes:

- Port 2 and Port 0 only
- V<sub>SS</sub> = 0V = GND
- The device operates down to V<sub>LV</sub> of the specified frequency for V<sub>LV</sub>. The minimum operational V<sub>CC</sub> is determined on the value of the voltage V<sub>LV</sub> at the ambient temperature. The V<sub>LV</sub> increases as the temperature decreases.
- V<sub>CC</sub> = 4.5 to 5.5V, typical values measured at V<sub>CC</sub> = 5.0V.  
The V<sub>CC</sub> voltage specification of 5.5 V guarantees 5.0 V ± 0.5V with typical values measured at V<sub>CC</sub> = 5.0V.
- Standard Mode (not Low EMI Mode)
- Z86E08 only
- All outputs unloaded and all inputs are at V<sub>CC</sub> or V<sub>SS</sub> level.
- If analog comparator is selected, then the comparator inputs must be at V<sub>CC</sub> level.

**DC ELECTRICAL CHARACTERISTICS**

## Extended Temperature

Sym	Parameter	V <sub>CC</sub> [4]	T <sub>A</sub> = -40°C to +105°C		Typical @ 25°C	Units	Conditions	Notes
			Min	Max				
V <sub>INMAX</sub>	Max Input Voltage	4.5V		12.0		V	I <sub>IN</sub> < 250 μA	1
		5.5V		12.0		V	I <sub>IN</sub> < 250 μA	1
V <sub>CH</sub>	Clock Input High Voltage	4.5V	0.8 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V	Driven by External Clock Generator	
		5.5V	0.8 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V	Driven by External Clock Generator	
V <sub>CL</sub>	Clock Input Low Voltage	4.5V	V <sub>SS</sub> -0.3	0.2 V <sub>CC</sub>	1.7	V	Driven by External Clock Generator	
		5.5V	V <sub>SS</sub> -0.3	0.2 V <sub>CC</sub>	1.7	V	Driven by External Clock Generator	
V <sub>IH</sub>	Input High Voltage	4.5V	0.7 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V		
		5.5V	0.7 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V		
V <sub>IL</sub>	Input Low Voltage	4.5V	V <sub>SS</sub> -0.3	0.2 V <sub>CC</sub>	1.5	V		
		5.5V	V <sub>SS</sub> -0.3	0.2 V <sub>CC</sub>	1.5	V		
V <sub>OH</sub>	Output High Voltage	4.5V	V <sub>CC</sub> -0.4		4.8	V	I <sub>OH</sub> = -2.0 mA	5
		5.5V	V <sub>CC</sub> -0.4		4.8	V	I <sub>OH</sub> = -2.0 mA	5
		4.5V	V <sub>CC</sub> -0.4			V	Low Noise @ I <sub>OH</sub> = -0.5 mA	
		5.5V	V <sub>CC</sub> -0.4			V	Low Noise @ I <sub>OH</sub> = -0.5 mA	
V <sub>OL1</sub>	Output Low Voltage	4.5V		0.4	0.1	V	I <sub>OL</sub> = +4.0 mA	5
		5.5V		0.4	0.1	V	I <sub>OL</sub> = +4.0 mA	5
		4.5V		0.4	0.1	V	Low Noise @ I <sub>OL</sub> = 1.0 mA	
		5.5V		0.4	0.1	V	Low Noise @ I <sub>OL</sub> = 1.0 mA	
V <sub>OL2</sub>	Output Low Voltage	4.5V		1.0	0.3	V	I <sub>OL</sub> = +12 mA,	5
		5.5V		1.0	0.3	V	I <sub>OL</sub> = +12 mA,	5
V <sub>OFFSET</sub>	Comparator Input Offset Voltage	4.5V		25.0	10.0	mV		
		5.5V		25.0	10.0	mV		
V <sub>LV</sub>	V <sub>CC</sub> Low Voltage Auto Reset		1.8	3.8	2.8	V	@ 6 MHz Max. Int. CLK Freq.	3
I <sub>IL</sub>	Input Leakage (Input Bias Current of Comparator)	4.5V		-1.0	1.0	μA	V <sub>IN</sub> = 0V, V <sub>CC</sub>	
		5.5V		-1.0	1.0	μA	V <sub>IN</sub> = 0V, V <sub>CC</sub>	
I <sub>OL</sub>	Output Leakage	4.5V		-1.0	1.0	μA	V <sub>IN</sub> = 0V, V <sub>CC</sub>	
		5.5V		-1.0	1.0	μA	V <sub>IN</sub> = 0V, V <sub>CC</sub>	
V <sub>ICR</sub>	Comparator Input Common Mode Voltage Range		0	V <sub>CC</sub> -1.5		V		

## DC ELECTRICAL CHARACTERISTICS (Continued)

Sym	Parameter	V <sub>CC</sub> [4]	T <sub>A</sub> = -40°C to +105°C		Typical @ 25°C	Units	Conditions	Notes
			Min	Max				
I <sub>CC</sub>	Supply Current	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		4.5V		20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
		5.5V		20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
I <sub>CC1</sub>	Standby Current	4.5V		5.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 2 MHz	5,7
		5.5V		5.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 2 MHz	5,7
		4.5V		5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 8 MHz	5,7
		5.5V		5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 8 MHz	5,7
		4.5V		7.0	4.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 12 MHz	5,7
		5.5V		7.0	4.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 12 MHz	5,7
I <sub>CC</sub>	Supply Current (Low Noise Mode)	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		4.5V		13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		5.5V		13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7

## AC ELECTRICAL CHARACTERISTICS

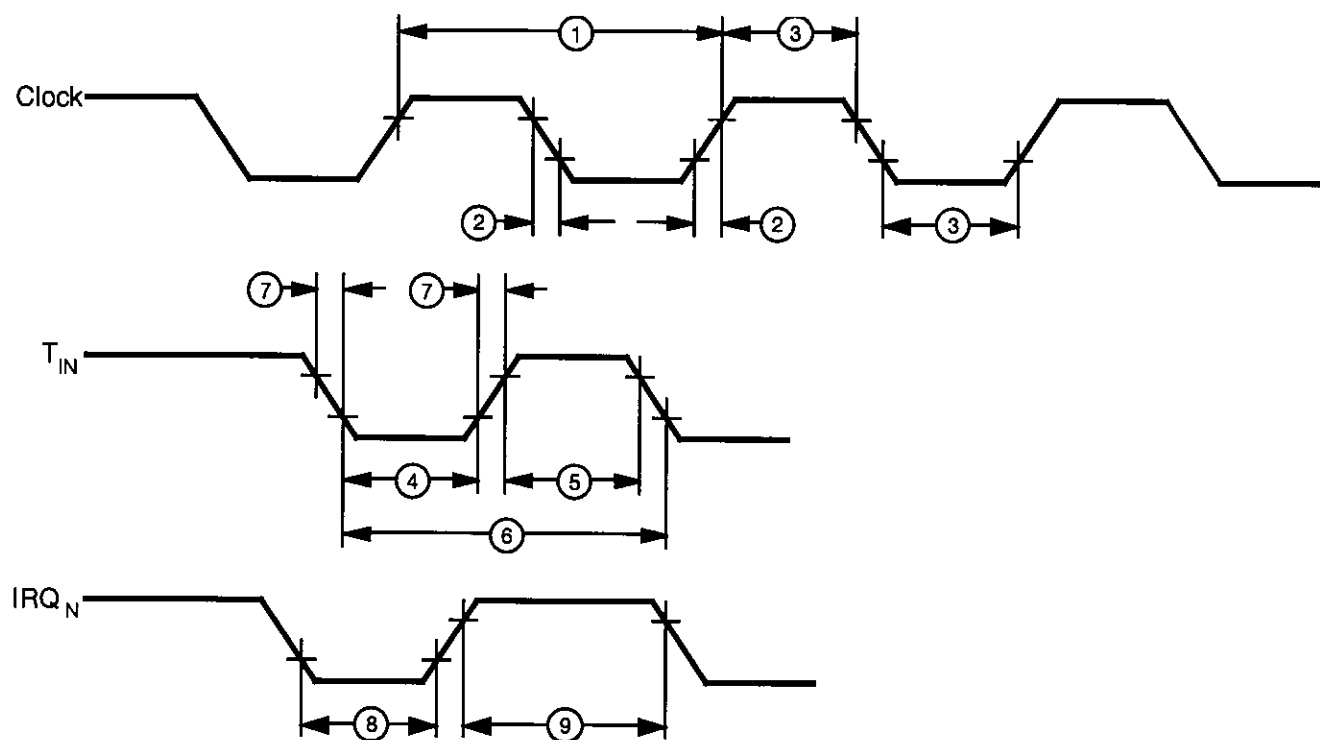


Figure 6. AC Electrical Timing Diagram



**AC ELECTRICAL CHARACTERISTICS**

Timing Table (Standard Mode for SCLK/TCLK = XTAL/2)

Standard Temperature

15		$T_A = 0\text{ }^{\circ}\text{C to } +70\text{ }^{\circ}\text{C}$							
No	Symbol	Parameter	$V_{CC}$	8 MHz		12 MHz		Units	Notes
				Min	Max	Min	Max		
1	TpC	Input Clock Period	4.5V	125	DC	83	DC	ns	1
			5.5V	125	DC	83	DC	ns	1
2	TrC,TfC	Clock Input Rise and Fall Times	4.5V		25		15	ns	1
			5.5V		25		15	ns	1
3	TwC	Input Clock Width	4.5V	62		41		ns	1
			5.5V	62		41		ns	1
4	TwTinL	Timer Input Low Width	4.5V	100		100		ns	1
			5.5V	70		70		ns	1
5	TwTinH	Timer Input High Width	4.5V	5TpC		5TpC			1
			5.5V	5TpC		5TpC			1
6	TpTin	Timer Input Period	4.5V		8TpC	8TpC			1
			5.5V		8TpC	8TpC			1
7	TrTin, TtTin	Timer Input Rise and Fall Time	4.5V		100		100	ns	1
			5.5V		100		100	ns	1
8	TwIL	Int. Request Input Low Time	4.5V	70		70		ns	1,2
			5.5V	70		70		ns	1,2
9	TwIH	Int. Request Input High Time	4.5V		5TpC	5TpC			1,2
			5.5V		5TpC	5TpC			1,2
10	Twdt	Watch-Dog Timer Delay Time for Timeout	4.5V	12		12		ms	1
			5.5V	12		12		ms	1
11	Tpor	Power-On Reset Time	4.5V	20	80	20	80	ms	1
			5.5V	20	80	20	80	ms	1

**Notes:**

1. Timing Reference uses 0.7  $V_{CC}$  for a logic 1 and 0.2  $V_{CC}$  for a logic 0.
2. Interrupt request through Port 3 (P33–P31).

**AC ELECTRICAL CHARACTERISTICS**

Timing Table (Standard Mode for SCLK/TCLK = XTAL/2)

Extended Temperature

No	Symbol	Parameter	V <sub>CC</sub>	T <sub>A</sub> = -40 °C to +105 °C				Units	Notes
				8 MHz		12 MHz			
				Min	Max	Min	Max		
1	TpC	Input Clock Period	4.5V	125	DC	83	DC	ns	1
			5.5V	125	DC	83	DC	ns	1
2	TrC,TfC	Clock Input Rise and Fall Times	4.5V		25		15	ns	1
			5.5V		25		15	ns	1
3	TwC	Input Clock Width	4.5V		62		41	ns	1
			5.5V		62		41	ns	1
4	TwTinL	Timer Input Low Width	4.5V	70		70		ns	1
			5.5V	70		70		ns	1
5	TwTinH	Timer Input High Width	4.5V	5TpC		5TpC			1
			5.5V	5TpC		5TpC			1
6	TpTin	Timer Input Period	4.5V	8TpC		8TpC			1
			5.5V	8TpC		8TpC			1
7	TrTin, TtTin	Timer Input Rise and Fall Time	4.5V		100		100	ns	1
			5.5V		100		100	ns	1
8	TwIL	Int. Request Input Low Time	4.5V	70		70		ns	1,2
			5.5V	70		70		ns	1,2
9	TwIH	Int. Request Input High Time	4.5V	5TpC		5TpC			1,2
			5.5V	5TpC		5TpC			1,2
10	Twdt	Watch-Dog Timer Delay Time for Timeout	4.5V	10		10		ms	1
			5.5V	10		10		ms	1
11	Tpor	Power-On Reset Time	4.5V	12	100	12	100	ms	1
			5.5V	12	100	12	100	ms	1

**Notes:**

1. Timing Reference uses 0.7 V<sub>CC</sub> for a logic 1 and 0.2 V<sub>CC</sub> for a logic 0.
2. Interrupt request made through Port 3 (P33–P31).

## LOW NOISE VERSION

### Low EMI Emission

The Z86E04/E08 can be programmed to operate in a Low EMI Emission Mode by means of a mask ROM bit option. Use of this feature results in:

- All pre-driver slew rates reduced to 10 ns typical.
- Internal SCLK/TCLK operation limited to a maximum of 4 MHz–250 ns cycle time.

- Output drivers have resistances of 500 Ohms (typical).
- Oscillator divide-by-two circuitry eliminated.

The Low EMI Mode is mask-programmable to be selected by the customer at the time the ROM code is submitted.

## PIN FUNCTIONS

### OTP Programming Mode

**D7–D0 Data Bus.** Data can be read from, or written to, the EPROM through this data bus.

**V<sub>CC</sub> Power Supply.** It is typically 5V during EPROM Read Mode and 6.4V during the other modes (Program, Program Verify, and so on).

**$\overline{CE}$  Chip Enable** (active Low). This pin is active during EPROM Read Mode, Program Mode, and Program Verify Mode.

**$\overline{OE}$  Output Enable** (active Low). This pin drives the Data Bus direction. When this pin is Low, the Data Bus is output. When High, the Data Bus is input.

**EPM EPROM Program Mode.** This pin controls the different EPROM Program Modes by applying different voltages.

**V<sub>PP</sub> Program Voltage.** This pin supplies the program voltage.

**Clear Clear** (active High). This pin resets the internal address counter at the High Level.

**Clock Address Clock.** This pin is a clock input. The internal address counter increases by one with one clock cycle.

**PGM Program Mode** (active Low). A Low level at this pin programs the data to the EPROM through the Data Bus.

### Application Precaution

The production test-mode environment may be enabled accidentally during normal operation if **excessive noise** surges above V<sub>CC</sub> occur on the XTAL1 pin.

In addition, processor operation of Z8 OTP devices may be affected by **excessive noise** surges on the V<sub>PP</sub>,  $\overline{CE}$ , EPM,  $\overline{OE}$  pins while the microcontroller is in Standard Mode.

Recommendations for dampening voltage surges in both test and OTP Mode include the following:

- Using a clamping diode to V<sub>CC</sub>.
- Adding a capacitor to the affected pin.

**Note:** Programming the EPROM/Test Mode Disable option will prevent accidental entry into EPROM Mode or Test Mode.

## FUNCTIONAL DESCRIPTION (Continued)

The Z8 instructions can access registers directly or indirectly through an 8-bit address field. This allows short 4-bit register addressing using the Register Pointer.

In the 4-bit mode, the register file is divided into eight working register groups, each occupying 16 continuous locations. The Register Pointer (Figure 13) addresses the starting location of the active working-register group.

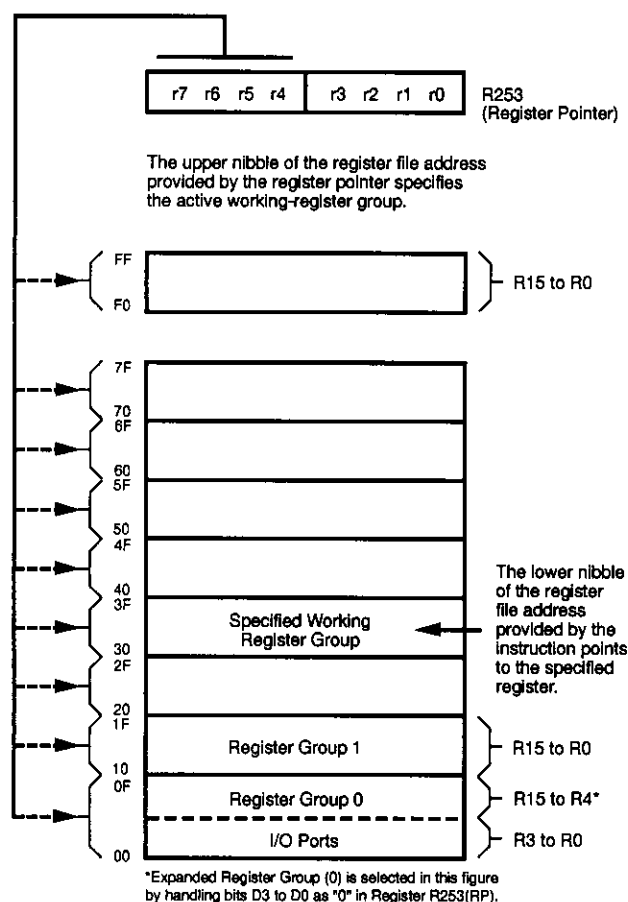


Figure 13. Register Pointer

**Stack Pointer.** The Z8 has an 8-bit Stack Pointer (R255) used for the internal stack that resides within the 124 general-purpose registers.

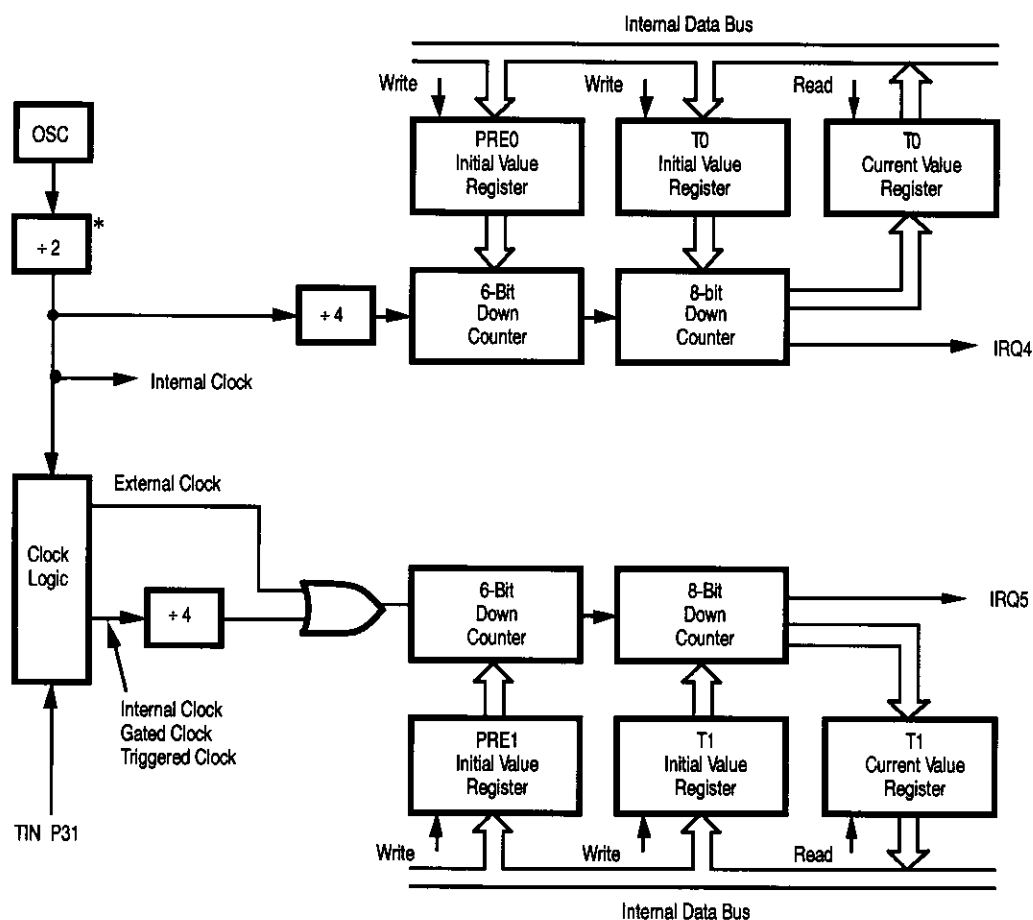
**General-Purpose Registers (GPR).** These registers are undefined after the device is powered up. The registers keep their last value after any reset, as long as the reset occurs in the  $V_{CC}$  voltage-specified operating range. **Note:** Register R254 has been designated as a general-purpose register and is set to 00 Hex after any reset or Stop-Mode Recovery.

**Counter/Timer.** There are two 8-bit programmable counter/timers (T0 and T1), each driven by its own 6-bit programmable prescaler. The T1 prescaler is driven by internal or external clock sources; however, the T0 can be driven by the internal clock source only (Figure 14).

The 6-bit prescalers divide the input frequency of the clock source by any integer number from 1 to 64. Each prescaler drives its counter, which decrements the value (1 to 256) that has been loaded into the counter. When both counter and prescaler reach the end of count, a timer interrupt request IRQ4 (T0) or IRQ5 (T1) is generated.

The counter can be programmed to start, stop, restart to continue, or restart from the initial value. The counters are also programmed to stop upon reaching zero (Single-Pass Mode) or to automatically reload the initial value and continue counting (Modulo-N Continuous Mode).

The counters, but not the prescalers, are read at any time without disturbing their value or count mode. The clock source for T1 is user-definable and is either the internal microprocessor clock divided by four, or an external signal input through Port 3. The Timer Mode register configures the external timer input (P31) as an external clock, a trigger input that is retriggerable or non-retriggerable, or used as a gate input for the internal clock.

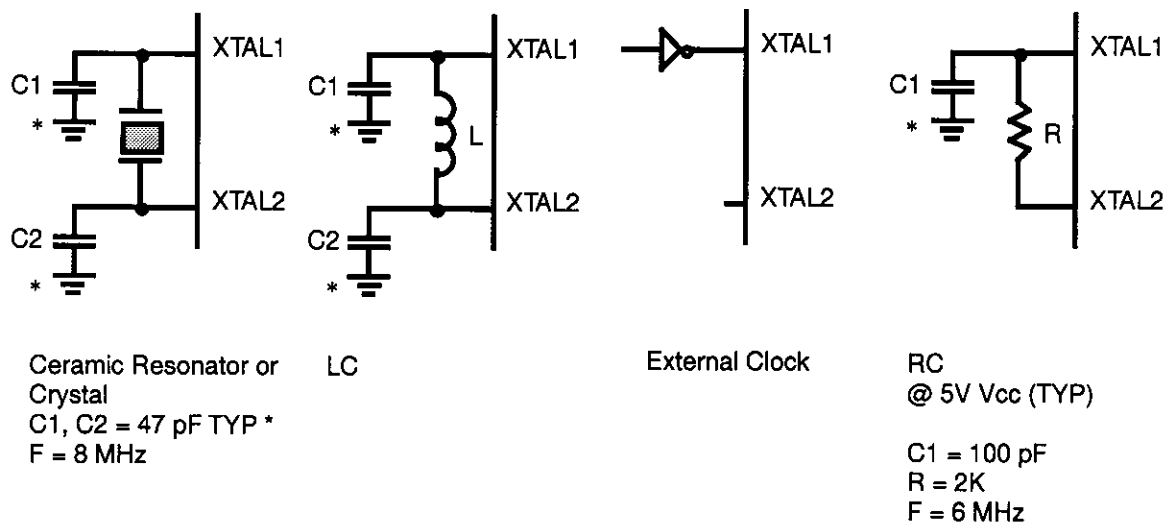


\* **Note:** By passed, if Low EMI Mode is selected.

**Figure 14. Counter/Timers Block Diagram**

**Clock.** The Z8 on-chip oscillator has a high-gain, parallel-resonant amplifier for connection to a crystal, LC, RC, ceramic resonator, or any suitable external clock source (XTAL1 = INPUT, XTAL2 = OUTPUT). The crystal should be AT cut, up to 12 MHz max., with a series resistance (RS) of less than or equal to 100 Ohms.

The crystal should be connected across XTAL1 and XTAL2 using the vendors crystal recommended capacitors from each pin directly to device ground pin 14 (Figure 16). Note that the crystal capacitor loads should be connected to  $V_{SS}$ , Pin 14 to reduce Ground noise injection.



\* Typical value including pin parasitics

**Figure 16. Oscillator Configuration**

**HALT Mode.** This instruction turns off the internal CPU clock but not the crystal oscillation. The counter/timers and external interrupts IRQ0, IRQ1, IRQ2 and IRQ3 remain active. The device is recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after the HALT.

**Note:** On the C12 ICEBOX, the IRQ3 does not wake the device out of HALT Mode.

**STOP Mode.** This instruction turns off the internal clock and external crystal oscillation and reduces the standby current to 10  $\mu$ A. The STOP Mode is released by a RESET through a Stop-Mode Recovery (pin P27). A Low input condition on P27 releases the STOP Mode. Program execution begins at location 000C(Hex). However, when P27 is used to release the STOP Mode, the I/O port Mode registers are not reconfigured to their default power-on conditions. This prevents any I/O, configured as output when the STOP instruction was executed, from glitching to an unknown state. To use the P27 release approach with STOP Mode, use the following instruction:

```
LD          P2M, #1XXX XXXXB
NOP
STOP
```

X = Dependent on user's application.

**Note:** A low level detected on P27 pin will take the device out of STOP Mode even if configured as an output.

In order to enter STOP or HALT Mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, the user executes a NOP (opcode=FFH) immediately before the appropriate SLEEP instruction, such as:

```
FF      NOP      ; clear the pipeline
6F      STOP     ; enter STOP Mode
        or
FF      NOP      ; clear the pipeline
7F      HALT     ; enter HALT Mode
```

**Watch-Dog Timer (WDT).** The Watch-Dog Timer is enabled by instruction WDT. When the WDT is enabled, it cannot be stopped by the instruction. With the WDT instruction, the WDT is refreshed when it is enabled within every 1 Twdt period; otherwise, the controller resets itself. The WDT instruction affects the flags accordingly; Z=1, S=0, V=0.

WDT = 5F (Hex)

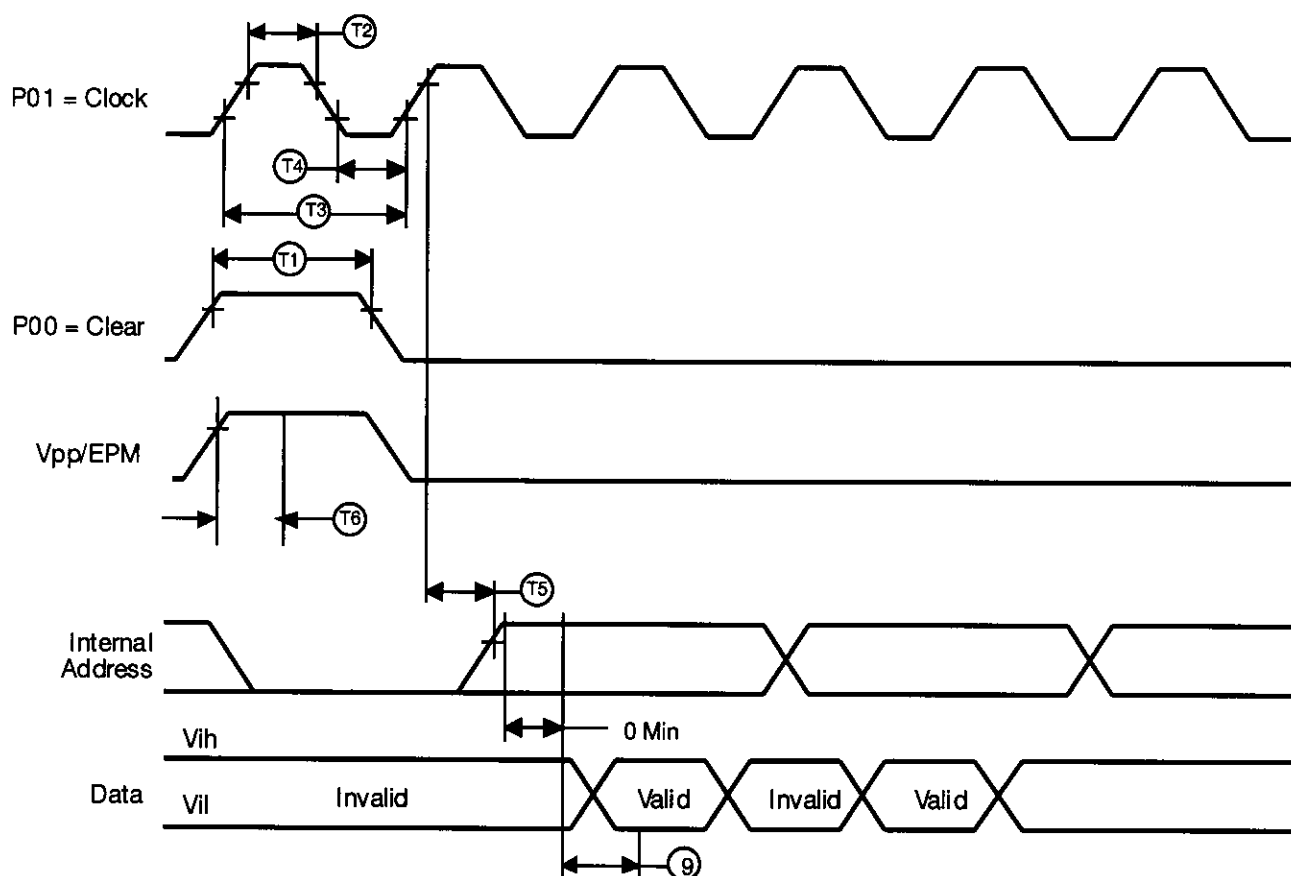
**Opcode WDT (5FH).** The first time Opcode 5FH is executed, the WDT is enabled and subsequent execution clears the WDT counter. This must be done at least every  $T_{WDT}$ ; otherwise, the WDT times out and generates a reset. The generated reset is the same as a power-on reset of  $T_{POR}$ , plus 18 XTAL clock cycles. The software enabled WDT does not run in STOP Mode.

**Opcode WDH (4FH).** When this instruction is executed it enables the WDT during HALT. If not, the WDT stops when entering HALT. This instruction does not clear the counters, it just makes it possible to have the WDT running during HALT Mode. A WDH instruction executed without executing WDT (5FH) has no effect.

**Permanent WDT.** Selecting the hardware enabled Permanent WDT option, will automatically enable the WDT upon exiting reset. The permanent WDT will always run in HALT Mode and STOP Mode, and it cannot be disabled.

**Auto Reset Voltage ( $V_{LV}$ ).** The Z8 has an auto-reset built-in. The auto-reset circuit resets the Z8 when it detects the  $V_{CC}$  below  $V_{LV}$ .

Figure 17 shows the Auto Reset Voltage versus temperature. If the  $V_{CC}$  drops below the VCC operating voltage range, the Z8 will function down to the  $V_{LV}$  unless the internal clock frequency is higher than the specified maximum  $V_{LV}$  frequency.



Legend:	
T1 Reset Clock Width	30 ns Min
T2 Input Clock High	100 ns Min
T3 Input Clock Period	200 ns Min
T4 Input Clock Low	100 ns Min
T5 Clock to Address Counter Out Delay	15 ns Max
T6 Epm/Vpp Set up Time	40 $\mu$ s Min

Figure 18. Z86E04/E08 Address Counter Waveform



# FUNCTIONAL DESCRIPTION (Continued)

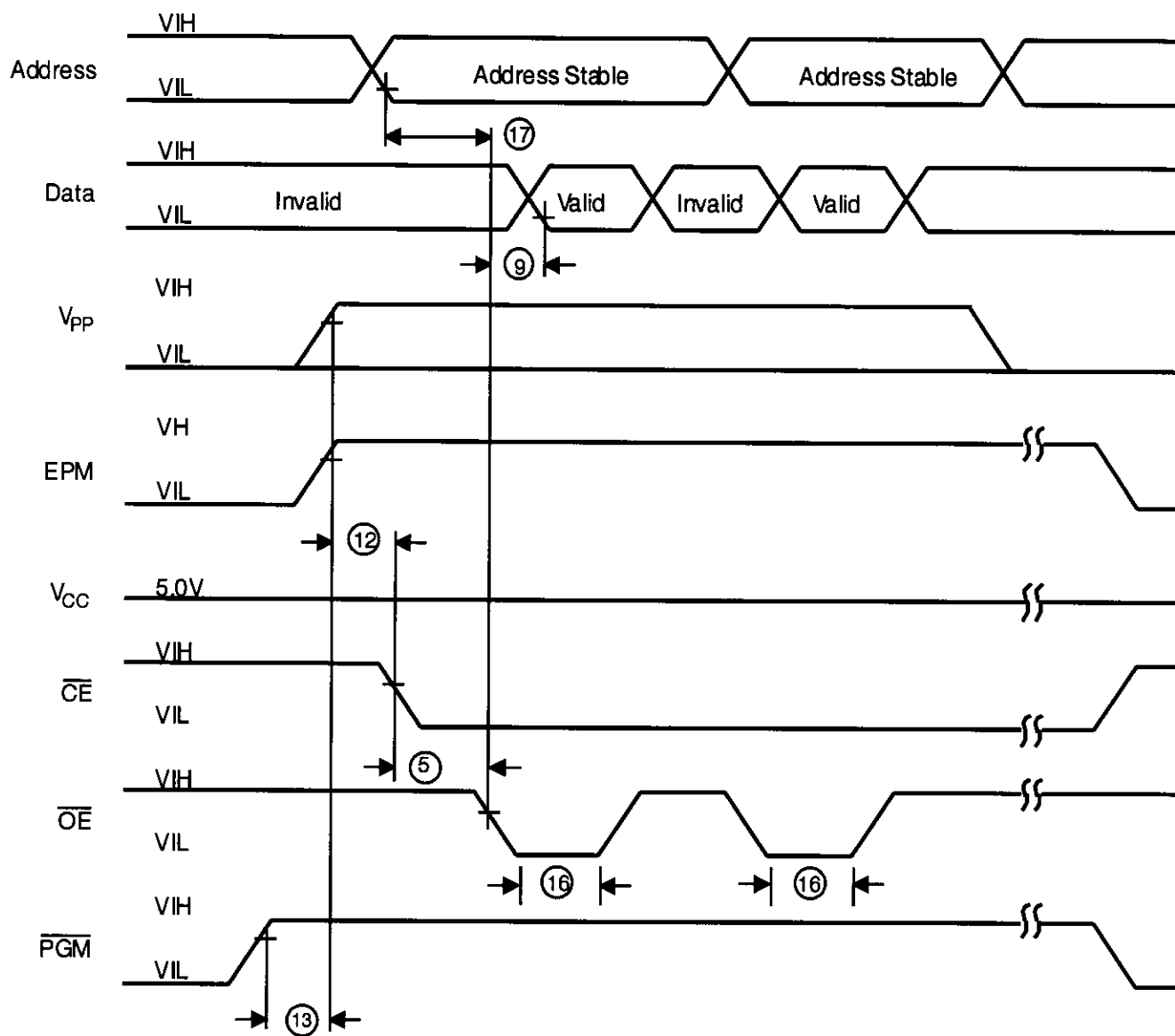


Figure 19. Z86E04/E08 Programming Waveform  
(EPROM Read)

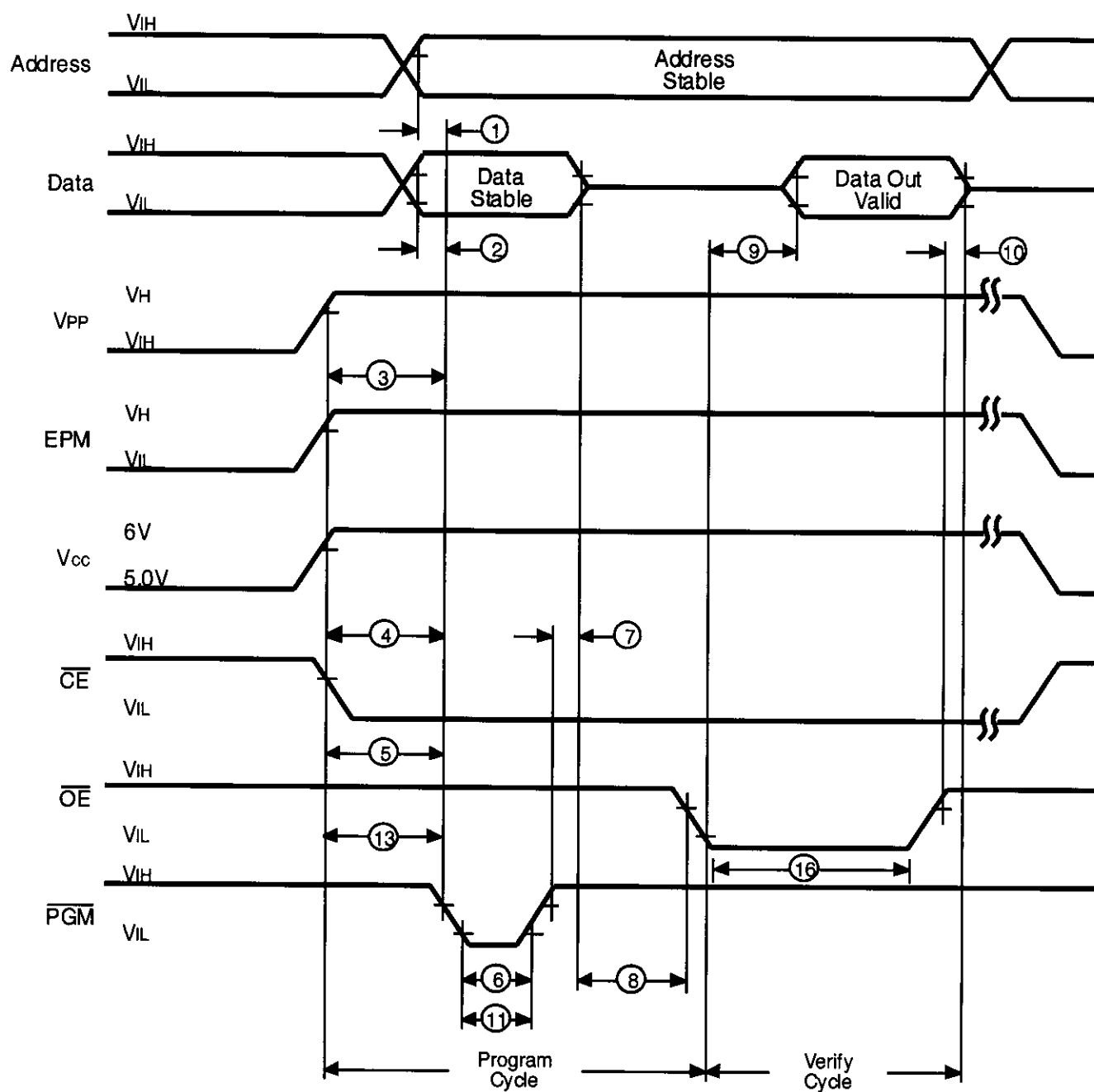


Figure 20. Z86E04/E08 Programming Waveform  
(Program and Verify)

# FUNCTIONAL DESCRIPTION (Continued)

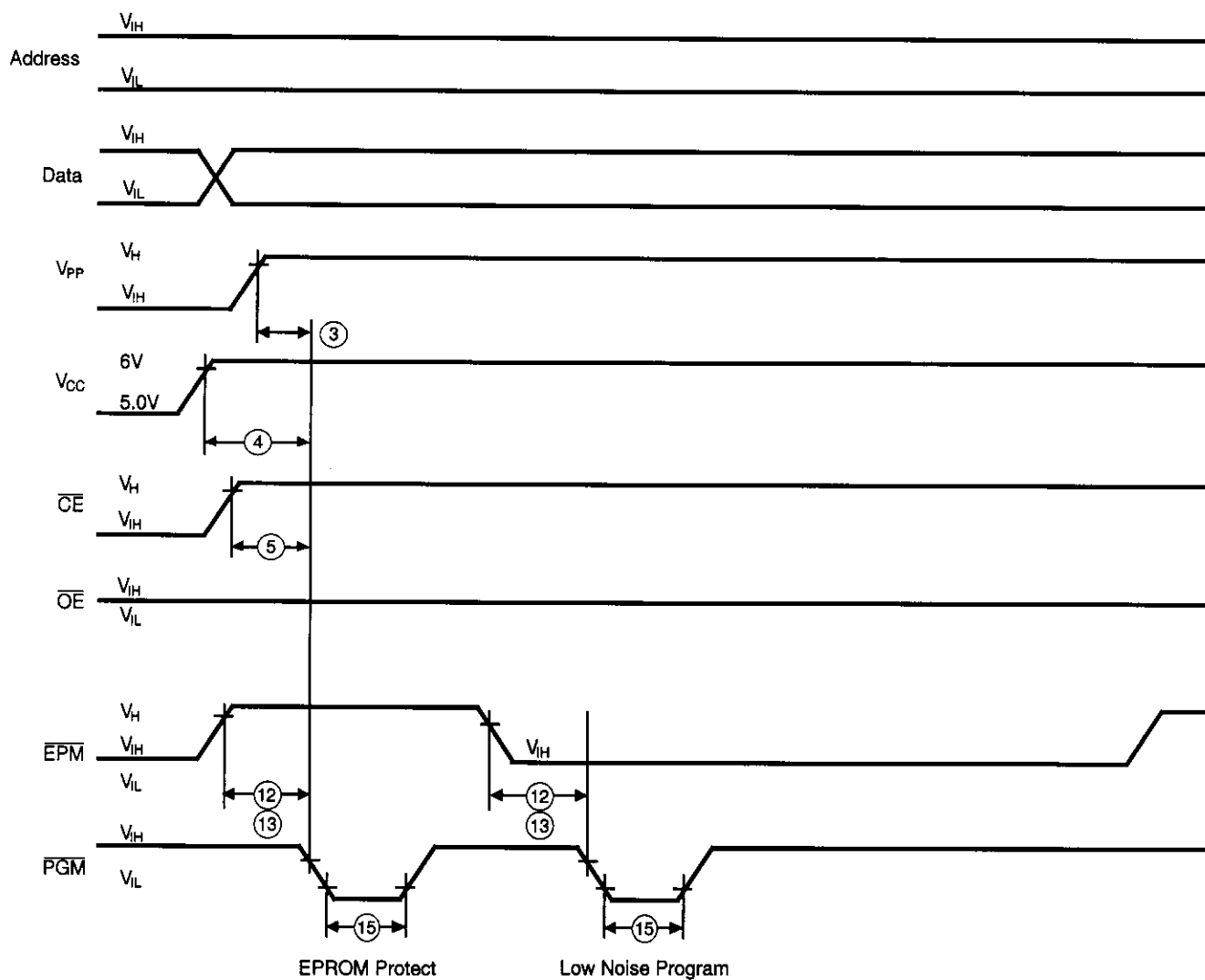
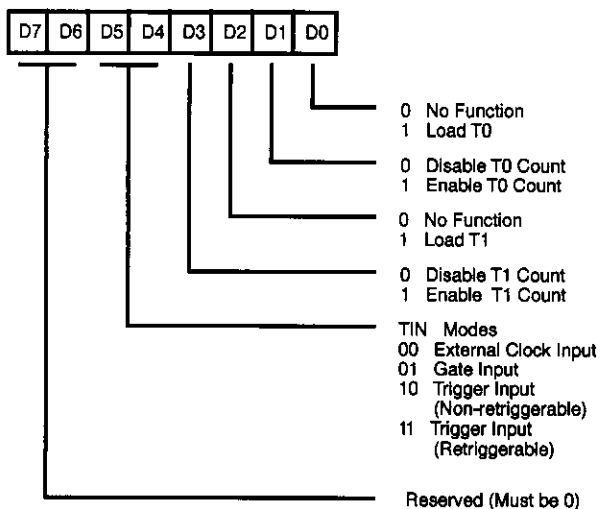


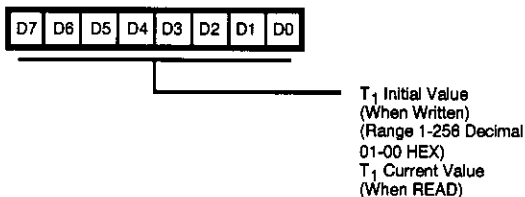
Figure 21. Z86E04/E08 Programming Options Waveform  
(EPROM Protect and Low Noise Program)

## Z8 CONTROL REGISTERS

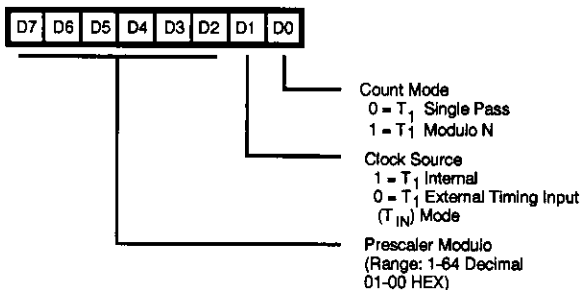
R241 TMR

Figure 24. Timer Mode Register (F1<sub>H</sub>: Read/Write)

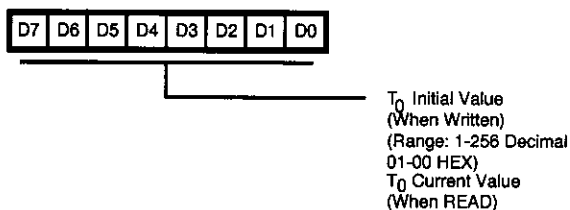
R242 T1

Figure 25. Counter Timer 1 Register (F2<sub>H</sub>: Read/Write)

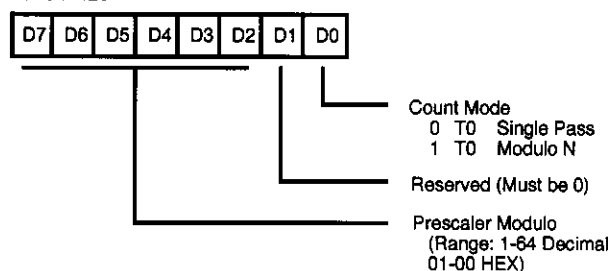
R243 PRE1

Figure 26. Prescaler 1 Register (F3<sub>H</sub>: Write Only)

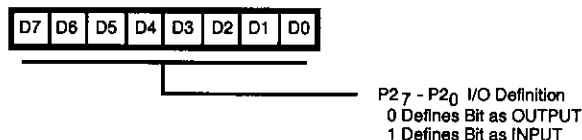
R244 T0

Figure 27. Counter/Timer 0 Register (F4<sub>H</sub>: Read/Write)

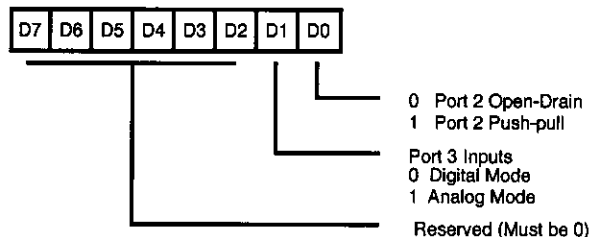
R245 PRE0

Figure 28. Prescaler 0 Register (F5<sub>H</sub>: Write Only)

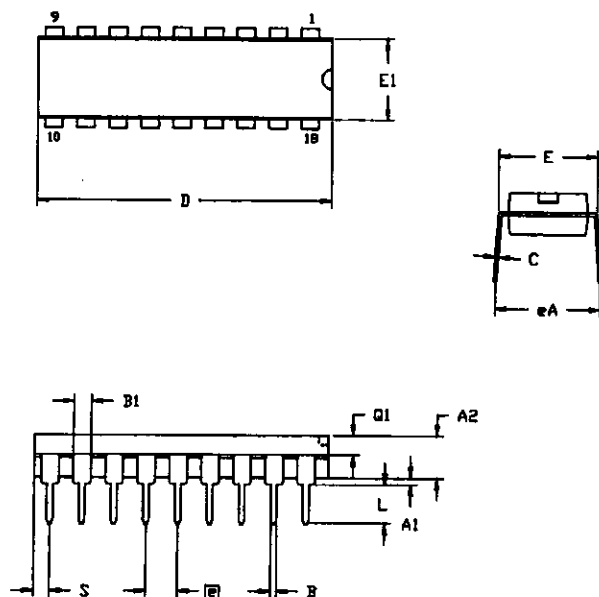
R246 P2M

Figure 29. Port 2 Mode Register (F6<sub>H</sub>: Write Only)

R247 P3M

Figure 30. Port 3 Mode Register (F7<sub>H</sub>: Write Only)

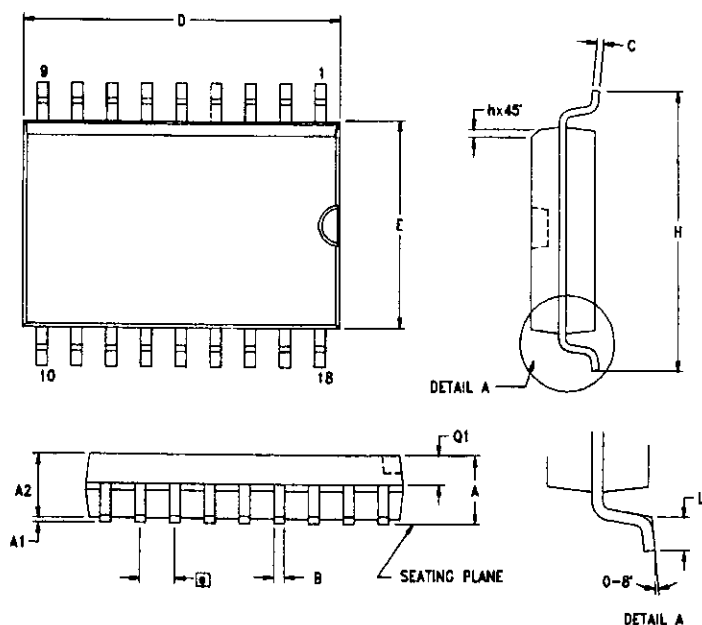
## PACKAGE INFORMATION



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A1	0.51	0.81	.020	.032
A2	3.25	3.43	.128	.135
B	0.38	0.53	.015	.021
B1	1.14	1.65	.045	.065
C	0.23	0.38	.009	.015
D	22.35	23.37	.880	.920
E	7.62	8.13	.300	.320
E1	6.22	6.48	.245	.255
□	2.54 TYP		.100 TYP	
eA	7.87	8.89	.310	.350
L	3.18	3.81	.125	.150
Q1	1.52	1.65	.060	.065
S	0.89	1.65	.035	.065

CONTROLLING DIMENSIONS : INCH

18-Pin DIP Package Diagram



SYMBOL	MILLIMETER		INCH	
	MIN	MAX	MIN	MAX
A	2.40	2.65	0.094	0.104
A1	0.10	0.30	0.004	0.012
A2	2.24	2.44	0.088	0.096
B	0.36	0.46	0.014	0.018
C	0.23	0.30	0.009	0.012
D	11.40	11.75	0.449	0.463
E	7.40	7.60	0.291	0.299
□	1.27 TYP		0.050 TYP	
H	10.00	10.65	0.394	0.419
h	0.30	0.50	0.012	0.020
L	0.60	1.00	0.024	0.039
Q1	0.97	1.07	0.038	0.042

CONTROLLING DIMENSIONS : MM  
LEADS ARE COPLANAR WITHIN .004 INCH.

18-Pin SOIC Package Diagram