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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	12MHz
Connectivity	-
Peripherals	POR, WDT
Number of I/O	14
Program Memory Size	2KB (2K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	125 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	18-SOIC (0.295", 7.50mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86e0812sec1903tr

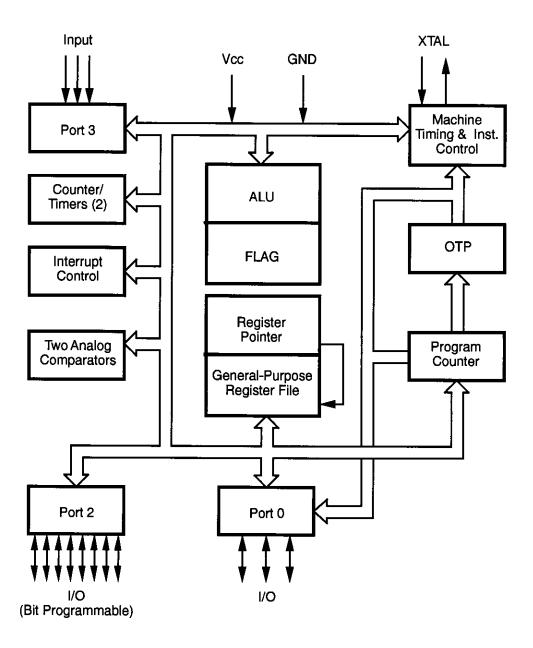


Figure 1. Functional Block Diagram

# **GENERAL DESCRIPTION** (Continued)

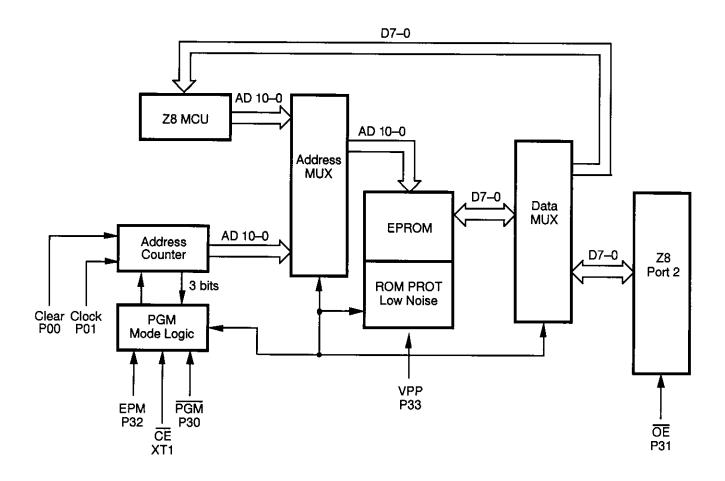


Figure 2. EPROM Programming Mode Block Diagram

### STANDARD TEST CONDITIONS

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to Ground. Positive current flows into the referenced pin (Figure 5).

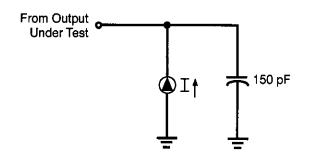


Figure 5. Test Load Diagram

### **CAPACITANCE**

 $T_A = 25$ °C,  $V_{CC} = GND = 0V$ , f = 1.0 MHz, unmeasured pins returned to GND.

Parameter	Min	Max
Input capacitance	0	10 pF
Output capacitance	0	20 pF
I/O capacitance	0	25 pF

# DC ELECTRICAL CHARACTERISTICS

Standard Temperature

			$T_A = 0^{\circ}C$	to +70°C	Typical			
Sym	Parameter	V <sub>cc</sub> [4]	Min	Max	@ 25°C	Units	Conditions	Notes
VINMAX	Max Input Voltage	4.5V	<u> </u>	12		V	I <sub>In</sub> <250 μA	1
		5.5V		12		٧	I <sub>In</sub> <250 μΑ	1
V <sub>CH</sub>	Clock Input High Voltage	4.5V	0.8 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	٧	Driven by External Clock Generator	
		5.5V	0.8 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V	Driven by External Clock Generator	- "
V <sub>CL</sub>	Clock Input Low Voltage	4.5V	V <sub>SS</sub> -0.3	0.2 V <sub>CC</sub>	1.7	V	Driven by External Clock Generator	
		5.5V	V <sub>SS</sub> -0.3	0.2 V <sub>CC</sub>	1.7	V	Driven by External Clock Generator	
V <sub>IH</sub>	Input High Voltage	4.5V	0.7 V <sub>CC</sub>	V <sub>CC</sub> +0.3	2.8	V		
<del></del>		5.5V	$0.7  V_{CC}$	V <sub>CC</sub> +0.3	2.8	V		
V <sub>IL</sub>	Input Low Voltage	4.5V	V <sub>SS</sub> -0.3	0.2 V <sub>CC</sub>	1.5	V		
		5.5V	V <sub>SS</sub> -0.3	$0.2\mathrm{V_{CC}}$	1.5	٧		
V <sub>OH</sub>	Output High Voltage	4.5V	V <sub>CC</sub> -0.4		4.8	V	$I_{OH} = -2.0 \text{ mA}$	5
		5.5V	V <sub>CC</sub> -0.4		4.8	V	I <sub>OH</sub> = -2.0 mA	5
		4.5V	V <sub>CC</sub> -0.4		4.8	٧	Low Noise @ I <sub>OH</sub> = -0.5 mA	*** **
		5.5V	V <sub>CC</sub> -0.4		4.8	٧	Low Noise @ I <sub>OH</sub> = -0.5 mA	
V <sub>OL1</sub>	Output Low Voltage	4.5V		0.8	0.1	٧	$I_{OL} = +4.0 \text{ mA}$	5
	•	5.5V		0.4	0.1	V	I <sub>OL</sub> = +4.0 mA	5
	•	4.5V		0.4	0.1	V	Low Noise @ I <sub>OL</sub> = 1.0 mA	
	•	5.5V	<u>.</u>	0.4	0.1	V	Low Noise @ I <sub>OL</sub> = 1.0 mA	
V <sub>OL2</sub>	Output Low Voltage	4.5V		0.8	0.8	٧	I <sub>OL</sub> = +12 mA,	5
	•	5.5V	-,	0.8	0.8	٧	l <sub>OL</sub> = +12 mA,	5
VOFFSET	Comparator Input	4.5V		25.0	10.0	mV		
	Offset Voltage	5.5V		25.0	10.0	mV		
$V_{LV}$	V <sub>CC</sub> Low Voltage Auto Reset		2.2	3.0	2.8	V	@ 6 MHz Max. Int. CLK Freq.	<u>-</u>
I <sub>IL</sub>	Input Leakage	4.5V	-1.0	1.0		μА	V <sub>IN</sub> = 0V, V <sub>CC</sub>	
	(Input Bias Current of Comparator)	5.5V	-1.0	1.0	· ·	μА	V <sub>IN</sub> = 0V, V <sub>CC</sub>	· · · · · · · · · · · · · · · · · · ·
I <sub>OL</sub>	Output Leakage	4.5V	-1.0	1.0		μА	V <sub>IN</sub> = 0V, V <sub>CC</sub>	
	•	5.5V	-1.0	1.0		μА	$V_{IN} = 0V, V_{CC}$	
V <sub>ICR</sub>	Comparator Input Common Mode Voltage Range		0	V <sub>CC</sub> -1.0		V		

# DC ELECTRICAL CHARACTERISTICS (Continued)

			• • • • • • • • • • • • • • • • • • • •	40°C to 5°C	Typical			
Sym	Parameter	V <sub>CC</sub> [4]	Min	Max	@ 25°C	Units	Conditions	Notes
Icc	Supply Current	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 2 MHz	5,7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 8 MHz	5,7
		4.5V	_	20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
		5.5V		20.0	12.0	mA	All Output and I/O Pins Floating @ 12 MHz	5,7
I <sub>CC1</sub> Sta	Standby Current	4.5V		5.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 2 MHz	5,7
		5.5V		5.0	2.5	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 2 MHz	5,7
		4.5V	-10-	5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 8 MHz	5,7
		5.5V		5.0	3.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 8 MHz	5,7
		4.5V	<del>-, ,</del>	7.0	4.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 12 MHz	5,7
		5.5V		7.0	4.0	mA	HALT Mode V <sub>IN</sub> = 0V, V <sub>CC</sub> @ 12 MHz	5,7
Icc	Supply Current (Low Noise Mode)	4.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		5.5V		11.0	6.8	mA	All Output and I/O Pins Floating @ 1 MHz	7
		4.5V	,	13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		5.5V		13.0	7.5	mA	All Output and I/O Pins Floating @ 2 MHz	7
		4.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7
		5.5V		15.0	8.2	mA	All Output and I/O Pins Floating @ 4 MHz	7

# AC ELECTRICAL CHARACTERISTICS (Continued)

Low Noise Mode, Extended Temperature

				T,	= -40 °C	to +105 °	C		
				1 M		4 M			
No	Symbol	Parameter	V <sub>cc</sub>	Min	Max	Min	Max	Units	Notes
1	TPC	Input Clock Period	4.5V	1000	DC	250	DC	ns	1
			5.5V	1000	DC	250	DC	ns	1
2	TrC	Clock Input Rise	4.5V	+	25		25	ns	1
	TfC	and Fall Times	5.5V		25		25	ns	1
3	TwC	Input Clock Width	4.5V	500		125		ns	1
			5.5V	500		125		ns	1
4.	TwTinL	Timer Input Low Width	4.5V	70		70		ns	1
			5.5V	70		70		ns	1
5	TwTinH	Timer Input High Width	4.5V	2.5TpC		2.5TpC	<del></del> -		1
			5.5V	2.5TpC	•	2.5TpC			1
6	TpTin	Timer Input Period	4.5V		4TpC	4TpC			1
			5.5V		4TpC	4TpC			1
7	TrTin,	Timer Input Rise	4.5V		100	•	100	ns	1
	TtTin	and Fall Time	5.5V		100		100	ns	1
8	TwlL	Int. Request Input	4.5V	70		70		ns	1,2
		Low Time	5.5V	70		70		ns	1,2
9	TwiH	Int. Request Input	4.5V	2.5TpC		2.5TpC	, <u>, , , , , , , , , , , , , , , , ,</u>		1,2
		High Time	5.5V	2.5TpC		2.5TpC			1,2
10	Twdt	Watch-Dog Timer	4.5V	10		10		ms	
	Delay Time for Timeout	5.5V	10		10		ms	1	

#### Notes:

<sup>1.</sup> Timing Reference uses 0.7  $\rm V_{CC}$  for a logic 1 and 0.2  $\rm V_{CC}$  for a logic 0.

<sup>2.</sup> Interrupt request through Port 3 (P33-P31).

### PIN FUNCTIONS (Continued)

**XTAL1, XTAL2** Crystal In, Crystal Out (time-based input and output, respectively). These pins connect a parallel-resonant crystal, LC, or an external single-phase clock (8 MHz or 12 MHz max) to the on-chip clock oscillator and buffer.

**Port 0, P02—P00.** Port 0 is a 3-bit bidirectional, Schmitt-triggered CMOS-compatible I/O port. These three I/O lines can be globally configured under software control to be inputs or outputs (Figure 7).

**Auto Latch.** The Auto Latch puts valid CMOS levels on all CMOS inputs (except P33, P32, P31) that are not externally driven. A valid CMOS level, rather than a floating node, reduces excessive supply current flow in the input buffer. On Power-up and Reset, the Auto Latch will set the ports to an undetermined state of 0 or 1. Default condition is Auto Latches enabled.

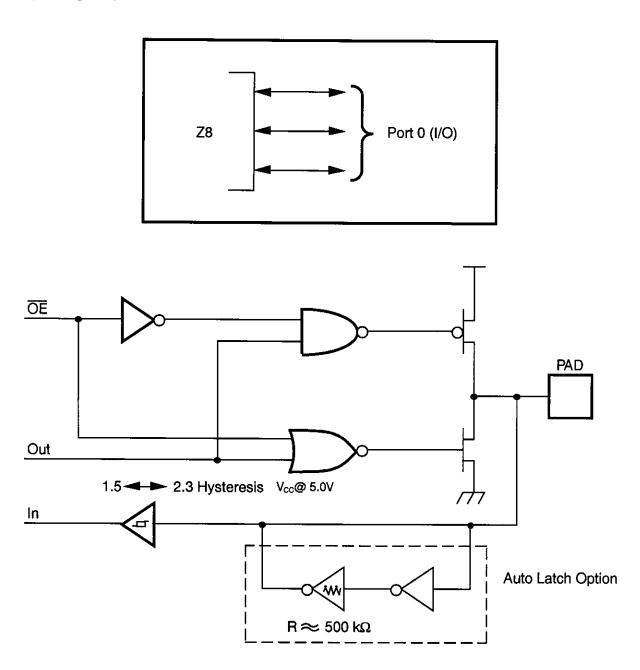


Figure 7. Port 0 Configuration

Port 2, P27-P20. Port 2 is an 8-bit, bit programmable, bidirectional, Schmitt-triggered CMOS-compatible I/O port. These eight I/O lines can be configured under software

control to be inputs or outputs, independently. Bits programmed as outputs can be globally programmed as either push-pull or open-drain (Figure 8).

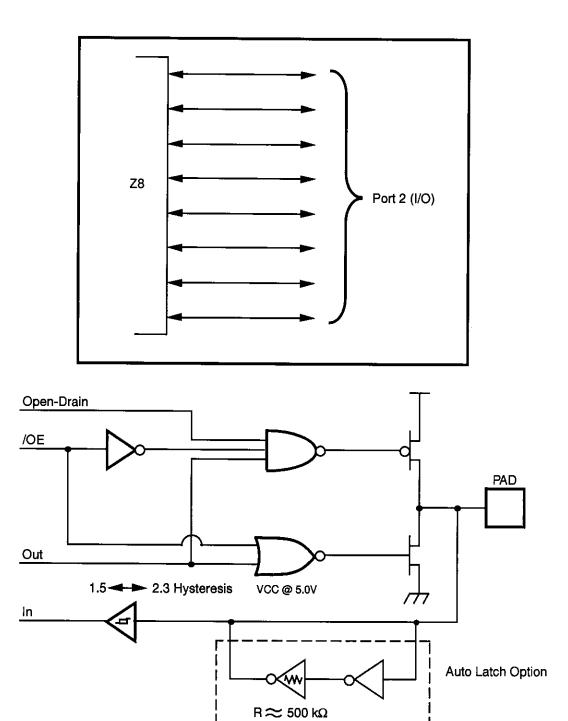
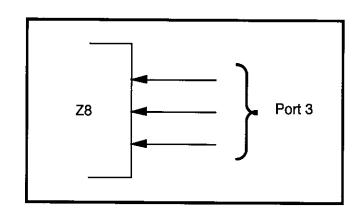


Figure 8. Port 2 Configuration

## **PIN FUNCTIONS** (Continued)

Port 3, P33–P31. Port 3 is a 3-bit, CMOS-compatible port with three fixed input (P33–P31) lines. These three input lines can be configured under software control as digital Schmitt-trigger inputs or analog inputs.

These three input lines are also used as the interrupt sources IRQ0–IRQ3, and as the timer input signal  $T_{\text{IN}}$  (Figure 9).



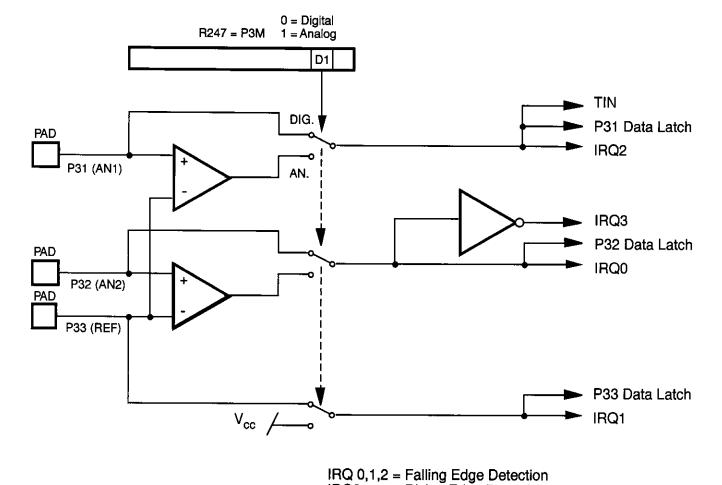


Figure 9. Port 3 Configuration

= Rising Edge Detection

IRQ3

**Program Memory.** The Z86E04/E08 addresses up to 1K/2KB of Internal Program Memory (Figure 11). The first 12 bytes of program memory are reserved for the interrupt vectors. These locations contain six 16-bit vectors that correspond to the six available interrupts. Bytes 0–1024/2048 are on-chip one-time programmable ROM.

Identifiers 1023/2047 3FFH/7FFH Location of On-Chip First Byte of ROM Instruction Executed After RESET 12 0CH IRQ5 0BH 11 10 IRQ5 0AH IRQ4 9 09H IRQ4 8 08H 7 **IRQ3** 07H Interrupt Vector 6 06H IRQ3 (Lower Byte) IRQ2 5 05H 04H IRQ2 Interrupt Vector 3 IRQ1 03H (Upper Byte) IRQ1 2 02H 1 IRQ0 01H 0 00H IRQ0

Figure 11. Program Memory Map

Register File. The Register File consists of three I/O port registers, 124 general-purpose registers, and 14 control and status registers R0–R3, R4–R127 and R241–R255, respectively (Figure 12). General-purpose registers occupy the 04H to 7FH address space. I/O ports are mapped as per the existing CMOS Z8.

Location		Identifiers
255 (FFH)	Stack Pointer (Bits 7-0)	SPL
254 (FE)	General-Purpose Register	GPR
253 (FD)	Register Pointer	RP
252 (FC)	Program Control Flags	FLAGS
251 (FB)	Interrupt Mask Register	IMR
250 (FA)	Interrupt Request Register	IRQ
249 (F9)	Interrupt Priority Register	IPR
248 (F8)	Ports 0-1 Mode	P01M
247 (F7)	Port 3 Mode	РЗМ
246 (F6)	Port 2 Mode	P2M
245 (F5)	TO Prescaler	PRE0
244 (F4)	Timer/Counter 0	<b>τ</b> ο
243 (F3)	T1 Prescaler	PRE1
242 (F2)	Timer/Counter 1	T1
241 (F1H)	Timer Mode	TMR
128	Not Implemented	
127 (7FH)	General-Purpose Registers	
4		
3	Port 3	P3
2	Port 2	P2
1	Reserved	P1
0 (00H)	Port 0	P0

Figure 12. Register File

Interrupts. The Z8 has six interrupts from six different sources. These interrupts are maskable and prioritized (Figure 15). The sources are divided as follows: the falling edge of P31 (AN1), P32 (AN2), P33 (REF), the rising edge of P32 (AN2), and two counter/timers. The Interrupt Mask Register globally or individually enables or disables the six interrupt requests (Table 4).

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder that is controlled by the Interrupt Priority register. All Z8 interrupts are vectored through locations in program memory. When an Interrupt machine cycle is activated, an Interrupt Request is granted. This disables all subsequent interrupts, saves the Program Counter and Status Flags, and then branches to the program memory vector location reserved for that interrupt. This memory location and the next byte contain the 16-bit starting address of the interrupt service routine for that particular interrupt request.

To accommodate polled interrupt systems, interrupt inputs are masked and the interrupt request register is polled to determine which of the interrupt requests needs service.

Note: User must select any Z86E08 mode in Zilog's C12 ICEBOX<sup>™</sup> emulator. The rising edge interrupt is not supported on the CCP emulator (a hardware/software workaround must be employed).

Table 4. Interrupt Types, Sources, and Vectors

Name	Source	Vector Location	Comments
IRQ0	AN2(P32)	0,1	External (F)Edge
IRQ1	REF(P33)	2,3	External (F)Edge
IRQ2	AN1(P31)	4,5	External (F)Edge
IRQ3	AN2(P32)	6,7	External (R)Edge
IRQ4	TO	8,9	Internal
IRQ5	T1	10,11	Internal

#### Notes:

F = Falling edge triggered

R = Rising edge triggered

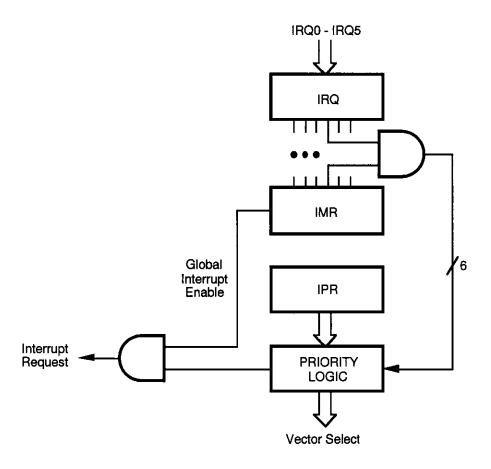
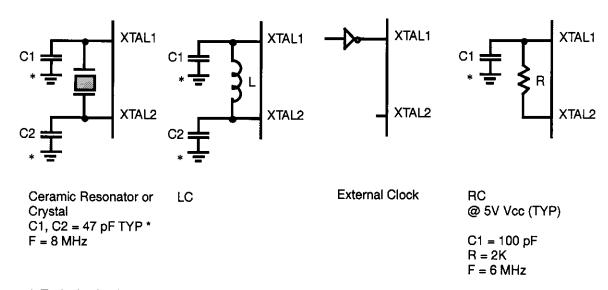


Figure 15. Interrupt Block Dlagram

Clock. The Z8 on-chip oscillator has a high-gain, parallel-resonant amplifier for connection to a crystal, LC, RC, ceramic resonator, or any suitable external clock source (XTAL1 = INPUT, XTAL2 = OUTPUT). The crystal should be AT cut, up to 12 MHz max., with a series resistance (RS) of less than or equal to 100 Ohms.

The crystal should be connected across XTAL1 and XTAL2 using the vendors crystal recommended capacitors from each pin directly to device ground pin 14 (Figure 16). Note that the crystal capacitor loads should be connected to  $V_{\rm SS}$ , Pin 14 to reduce Ground noise injection.



<sup>\*</sup> Typical value including pin parasitics

Figure 16. Oscillator Configuration

Table 5. Typical Frequency vs. RC Values V<sub>CC</sub> = 5.0V @ 25°C

Load Capacitor								
	33	pFd	56 pFd		100	100 pFd		1μFd
Resistor (R)	A(Hz)	B(Hz)	A(Hz)	B(Hz)	A(Hz)	B(Hz)	A(Hz)	B(Hz)
1.0M	33K	31K	20K	20K	12K	11K	1.4K	1.4K
560K	56K	52K	34K	32K	20K	19K	2.5K	2.4K
220K	144K	130K	84K	78K	48K	45K	6K	6K
100K	315K	270K	182K	164K	100K	95K	12K	12K
56K	552K	480K	330K	300K	185K	170K	23K	22K
20K	1.4M	1M	884K	740K	500K	450K	65K	61K
10K	2.6M	2M	1.6M	1.3M	980K	820K	130K	123K
5K	4.4M	3M	2.8M	2M	1.7K	1.3M	245K	225K
2K	8M	5M	6M	4M	3.8K	2.7M	600K	536K
1K	12M	7M	8.8M	6M	6.3K	4.2M	1.0M	950K

Notes:

A = STD Mode Frequency. B = Low EMI Mode Frequency.

Table 6. Typical Frequency vs. RC Values V<sub>cc</sub> = 3.3V @ 25°C

Load Capacitor									
Resistor (R)	33	pFd	56 pFd		100	pFd	0.00 1μFd		
	A(Hz)	B(Hz)	A(Hz)	B(Hz)	A(Hz)	B(Hz)	A(Hz)	B(Hz)	
1.0M	18K	18K	12K	12K	7.4K	7.7K	1K	1K	
560K	30K	30K	20K	20K	12K	12K	1.6K	1.6K	
220K	70K	70K	47K	47K	30K	30K	4K	4K	
100K	150K	148K	97K	96K	60K	60K	8K	8K	
56K	268K	250K	176K	170K	100K	100K	15K	15K	
20K	690M	600K	463K	416K	286K	266K	40K	40K	
10K	1.2M	1M	860K	730K	540K	480K	80K	76K	
5K	2M	1.7M	1.5M	1.2M	950K	820K	151K	138K	
2K	4.6M	3M	3.3M	2.4M	2.2M	1.6M	360K	316K	
1K	7M	4.6M	5M	3.6M	3.6K	2.6M	660K	565K	

Notes:

A = STD Mode Frequency.

B = Low EMI Mode Frequency.

HALT Mode. This instruction turns off the internal CPU clock but not the crystal oscillation. The counter/timers and external interrupts IRQ0, IRQ1, IRQ2 and IRQ3 remain active. The device is recovered by interrupts, either externally or internally generated. An interrupt request must be executed (enabled) to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after the HALT.

**Note:** On the C12 ICEBOX, the IRQ3 does not wake the device out of HALT Mode.

STOP Mode. This instruction turns off the internal clock and external crystal oscillation and reduces the standby current to 10  $\mu\text{A}$ . The STOP Mode is released by a RESET through a Stop-Mode Recovery (pin P27). A Low input condition on P27 releases the STOP Mode. Program execution begins at location 000C(Hex). However, when P27 is used to release the STOP Mode, the I/O port Mode registers are not reconfigured to their default power-on conditions. This prevents any I/O, configured as output when the STOP instruction was executed, from glitching to an unknown state. To use the P27 release approach with STOP Mode, use the following instruction:

LD

P2M, #1XXX XXXXB

NOP STOP

X = Dependent on user's application.

**Note:** A low level detected on P27 pin will take the device out of STOP Mode even if configured as an output.

In order to enter STOP or HALT Mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, the user executes a NOP (opcode=FFH) immediately before the appropriate SLEEP instruction, such as:

FF 6F NOP STOP ; clear the pipeline ; enter STOP Mode

~

FF 7**F**  NOP HALT ; clear the pipeline

; enter HALT Mode

**Watch-Dog Timer** (WDT). The Watch-Dog Timer is enabled by instruction WDT. When the WDT is enabled, it cannot be stopped by the instruction. With the WDT instruction, the WDT is refreshed when it is enabled within every 1 Twdt period; otherwise, the controller resets itself, The WDT instruction affects the flags accordingly; Z=1, S=0, V=0.

WDT = 5F (Hex)

**Opcode WDT** (5FH). The first time Opcode 5FH is executed, the WDT is enabled and subsequent execution clears the WDT counter. This must be done at least every  $T_{WDT}$ ; otherwise, the WDT times out and generates a reset. The generated reset is the same as a power-on reset of  $T_{POR}$ , plus 18 XTAL clock cycles. The software enabled WDT does not run in STOP Mode.

**Opcode WDH** (4FH). When this instruction is executed it enables the WDT during HALT. If not, the WDT stops when entering HALT. This instruction does not clear the counters, it just makes it possible to have the WDT running during HALT Mode. A WDH instruction executed without executing WDT (5FH) has no effect.

Permanent WDT. Selecting the hardware enabled Permanent WDT option, will automatically enable the WDT upon exiting reset. The permanent WDT will always run in HALT Mode and STOP Mode, and it cannot be disabled.

**Auto Reset Voltage** ( $V_{LV}$ ). The Z8 has an auto-reset builtin. The auto-reset circuit resets the Z8 when it detects the  $V_{CC}$  below  $V_{LV}$ .

Figure 17 shows the Auto Reset Voltage versus temperature. If the  $V_{CC}$  drops below the VCC operating voltage range, the Z8 will function down to the  $V_{LV}$  unless the internal clock frequency is higher than the specified maximum  $V_{LV}$  frequency.

Internal Address Counter. The address of Z8 is generated internally with a counter clocked through pin P01 (Clock). Each clock signal increases the address by one and the "high" level of pin P00 (Clear) will reset the address to zero. Figure 18 shows the setup time of the serial address input.

**Programming Waveform.** Figures 19, 20, 21 and 22 show the programming waveforms of each mode. Table 8 shows the timing of programming waveforms.

**Programming Algorithm.** Figure 23 shows the flow chart of the Z8 programming algorithm.

**Table 8. Timing of Programming Waveforms** 

Parameters	Name	Min	Max	Units
1	Address Setup Time	2		μs
2	Data Setup Time	2		μs
3	V <sub>PP</sub> Setup	2		μs
4	V <sub>cc</sub> Setup Time	2		μs
5	Chip Enable Setup Time	2	··	μS
6	Program Pulse Width	0.95		ms
7	Data Hold Time	2	,	μS
8	OE Setup Time	2		μЅ
9	Data Access Time	188		ns
10	Data Output Float Time		100	ns
11	Overprogram Pulse Width	2.85		ms
12	EPM Setup Time	2		μS
13	PGM Setup Time	2		μs
14	Address to OE Setup Time	2		μs
15	Option Program Pulse Width	78		ms
16	OE Width	250	, ··· <u>L. L.</u>	ns
17	Address Valid to OE Low	125	-··-	ns

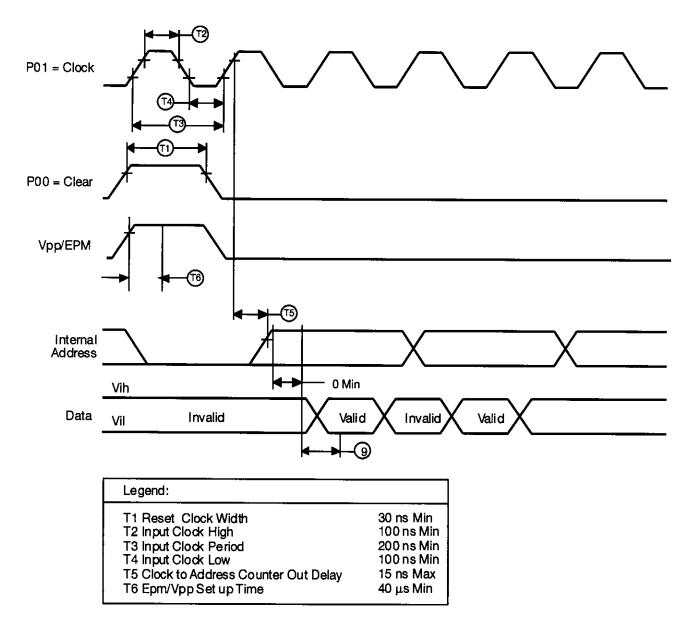


Figure 18. Z86E04/E08 Address Counter Waveform

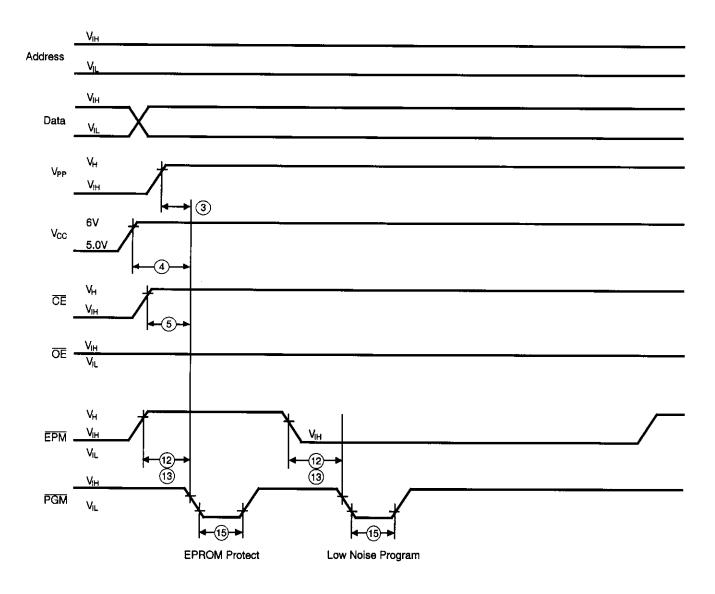


Figure 21. Z86E04/E08 Programming Options Waveform (EPROM Protect and Low Noise Program)

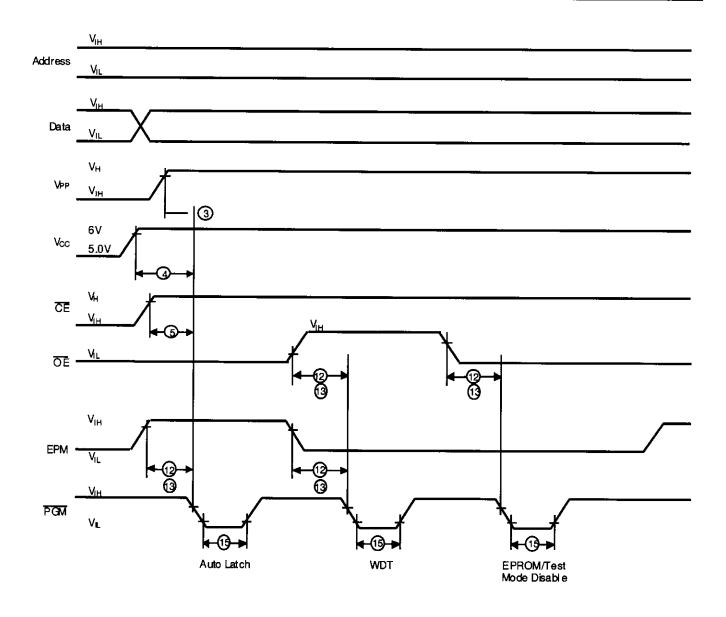


Figure 22. Z86E04/E08 Programming Options Waveform (Auto Latch Disable, Permanent WDT Enable and EPROM/Test Mode Disable)

# **Z8 CONTROL REGISTERS** (Continued)

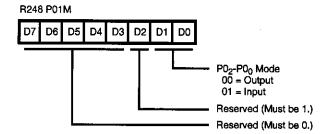


Figure 31. Port 0 and 1 Mode Register (F8<sub>H</sub>: Write Only)

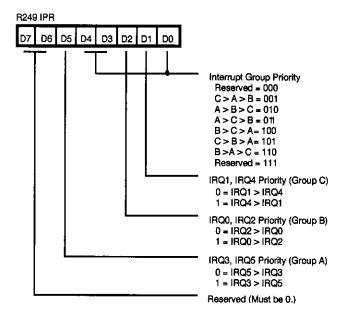


Figure 32. Interrupt Priority Register (F9<sub>H</sub>: Write Only)

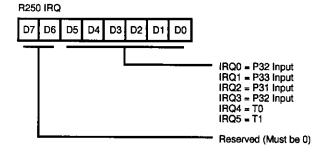


Figure 33. Interrupt Request Register (FA<sub>H</sub>: Read/Write)

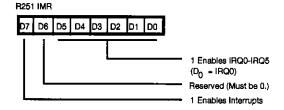


Figure 34. Interrupt Mask Register (FB<sub>H</sub>: Read/Write)

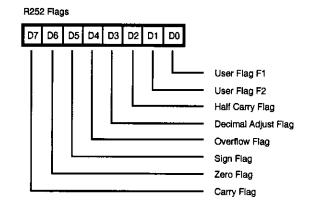


Figure 35. Flag Register (FC<sub>H</sub>: Read/Write)

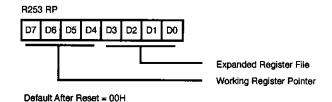


Figure 36. Register Pointer (FD<sub>H</sub>: Read/Write)

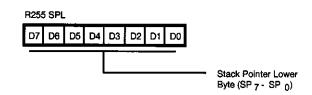


Figure 37. Stack Pointer (FF<sub>H</sub>: Read/Write)

## ORDERING INFORMATION

Z86E04

Z86E08

### **Standard Temperature**

### **Standard Temperature**

	_
18-Pin DIP	•

18-Pin SOIC

18-Pin DIP

18-Pin SOIC

Z86E0412PSC

Z86E0412SSC

Z86E0812PSC

Z86E0812SSC

Z86E0412PEC

Z86E0412SEC

Z86E0812PEC

Z86E0812SEC

For fast results, contact your local Zilog sales office for assistance in ordering the part(s) desired.

### Codes

Preferred Package P = Plastic DIP

Speeds 12 =12 MHz

**Longer Lead Time** 

S = SOIC

Environmental
C = Plastic Standard

**Preferred Temperature** 

 $S = 0^{\circ}C$  to  $+70^{\circ}C$ 

E = -40°C to +105°C



