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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Active
Core Processor	AVR
Core Size	8-Bit
Speed	10MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	23
Program Memory Size	4KB (2K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-VFQFN Exposed Pad
Supplier Device Package	32-VQFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega48pv-10mu

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

- Peripheral Features
  - Two 8-bit Timer/Counters with Separate Prescaler and Compare Mode
  - One 16-bit Timer/Counter with Separate Prescaler, Compare Mode, and Capture Mode
  - Real Time Counter with Separate Oscillator
  - Six PWM Channels
  - 8-channel 10-bit ADC in TQFP and QFN/MLF package
    - Temperature Measurement
  - 6-channel 10-bit ADC in PDIP Package
    - Temperature Measurement
  - Two Master/Slave SPI Serial Interface
  - One Programmable Serial USART
  - One Byte-oriented 2-wire Serial Interface (Philips I<sup>2</sup>C compatible)
  - Programmable Watchdog Timer with Separate On-chip Oscillator
  - One On-chip Analog Comparator
  - Interrupt and Wake-up on Pin Change
- Special Microcontroller Features
  - Power-on Reset and Programmable Brown-out Detection
  - Internal Calibrated Oscillator
  - External and Internal Interrupt Sources
  - Six Sleep Modes: Idle, ADC Noise Reduction, Power-save, Power-down, Standby, and Extended Standby
- I/O and Packages
  - 23 Programmable I/O Lines
  - 28-pin PDIP, 32-lead TQFP, 28-pad QFN/MLF and 32-pad QFN/MLF
- Operating Voltage:
  - 2.7 5.5V for ATmega48P/88P/168P
  - 1.8 5.5V for ATmega48PV/88PV/168PV
- Temperature Range:
  - -40°C to 85°C
- Speed Grade:
  - ATmega48P/88P/168P: 0 10MHz @ 2.7V 5.5V, 0 20MHz @ 4.5V 5.5V
  - ATmega48PV/88PV/168PV: 0 4MHz @ 1.8V 5.5V, 0 10MHz @ 2.7V 5.5V
- Power Consumption at 1MHz, 1.8V, 25°C
  - Active Mode: 0.3mA
  - Power-down Mode: 0.1µA
  - Power-save Mode: 0.8µA (Including 32kHz RTC)



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# 2. Configuration Summary

Features	ATmega48P/PV /88P/PV /168P/PV
Pin Count	28/32
Flash (Bytes)	4K/8K/16K
SRAM (Bytes)	512/1K/1K
EEPROM (Bytes)	256/512/512
Interrupt Vector Size (instruction word/vector)	1/1/2
General Purpose I/O Lines	23
SPI	2
TWI (I <sup>2</sup> C)	1
USART	1
ADC	10-bit 15kSPS
ADC Channels	8
8-bit Timer/Counters	2
16-bit Timer/Counters	1

ATmega88P/PV and ATmega168P/PV support a real Read-While-Write Self-Programming mechanism. There is a separate Boot Loader Section, and the SPM instruction can only execute from there. In ATmega48P/PV, there is no Read-While-Write support and no separate Boot Loader Section. The SPM instruction can execute from the entire Flash.



### 3. Ordering Information

### 3.1. ATmega48P/PV

Speed [MHz] <sup>(3)</sup>	Power Supply [V]	Ordering Code <sup>(2)</sup>	Package <sup>(1)</sup>	Operational Range		
10	1.8 - 5.5	ATmega48PV-10AU ATmega48PV-10AUR <sup>(4)</sup> ATmega48PV-10MMU ATmega48PV-10MMUR <sup>(4)</sup> ATmega48PV-10MU ATmega48PV-10MUR <sup>(4)</sup> ATmega48PV-10PU	32A 32A 28M1 28M1 32M1-A 32M1-A 28P3	Industrial (-40°C to 85°C)		
20	2.7 - 5.5	ATmega48P-20AU ATmega48P-20AUR <sup>(4)</sup> ATmega48P-20MMU ATmega48P-20MMUR <sup>(4)</sup> ATmega48P-20MU ATmega48P-20MUR <sup>(4)</sup> ATmega48P-20PU	32A 32A 28M1 28M1 32M1-A 32M1-A 28P3			

#### Note:

- 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
- 2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
- 3. Please refer to Speed Grades for Speed vs. V<sub>CC</sub>
- 4. Tape & Reel.

Package	Package Type								
28M1	28-pad, 4 x 4 x 1.0 body, Lead Pitch 0.45mm Quad Flat No-Lead/Micro Lead Frame Package (QFN/ MLF)								
28P3	28-lead, 0.300" Wide, Plastic Dual Inline Package (PDIP)								
32M1-A	32-pad, 5 x 5 x 1.0 body, Lead Pitch 0.50mm Quad Flat No-Lead/Micro Lead Frame Package (QFN/ MLF)								
32A	32-lead, Thin (1.0mm) Plastic Quad Flat Package (TQFP)								



### 3.3. ATmega168P/PV

Speed [MHz] <sup>(3)</sup>	Power Supply [V]	Ordering Code <sup>(2)</sup>	Package <sup>(1)</sup>	Operational Range	
10	1.8 - 5.5	ATmega168PV-10AU ATmega168PV-10AUR <sup>(4)</sup> ATmega168PV-10MU ATmega168PV-10MUR <sup>(4)</sup> ATmega168PV-10PU	32A 32A 32M1-A 32M1-A 28P3	Industrial (-40°C to 85°C)	
20	2.7 - 5.5	ATmega168P-20AUR <sup>(4)</sup> ATmega168P-20MUR <sup>(4)</sup> ATmega168P-20AU ATmega168P-20MU ATmega168P-20PU	32A 32M1-A 32A 32M1-A 28P3		

#### Note:

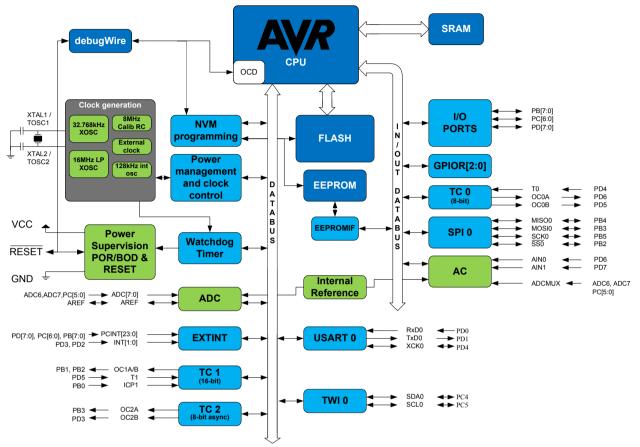
- 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
- 2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
- 3. Please refer to Speed Grades for Speed vs.  $V_{CC}$
- 4. Tape & Reel.

Package	Package Type								
28P3	28-lead, 0.300" Wide, Plastic Dual Inline Package (PDIP)								
32M1-A	32-pad, 5 x 5 x 1.0 body, Lead Pitch 0.50mm Quad Flat No-Lead/Micro Lead Frame Package (QFN/ MLF)								
32A	32-lead, Thin (1.0mm) Plastic Quad Flat Package (TQFP)								



## 4. Block Diagram

Figure 4-1. Block Diagram

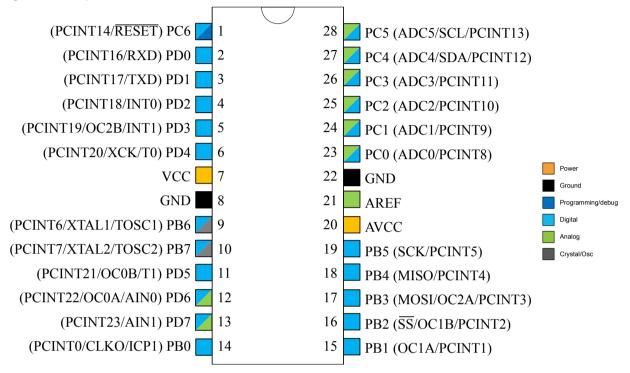




### 5. Pin Configurations

#### 5.1. Pin-out

Figure 5-1. 28-pin PDIP





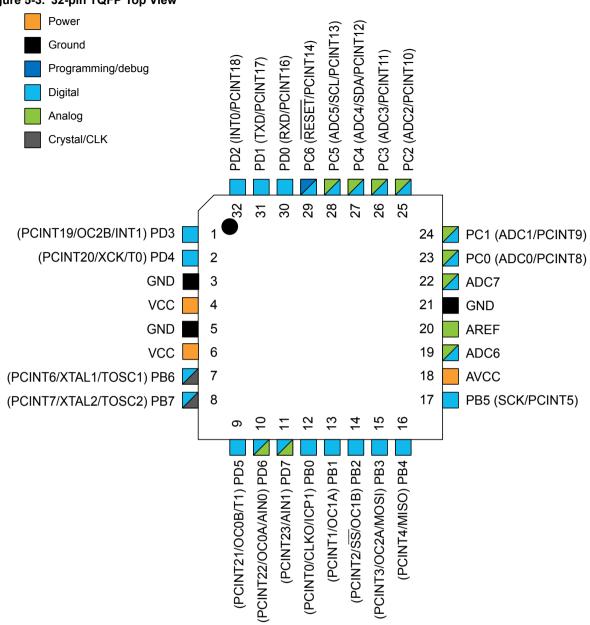
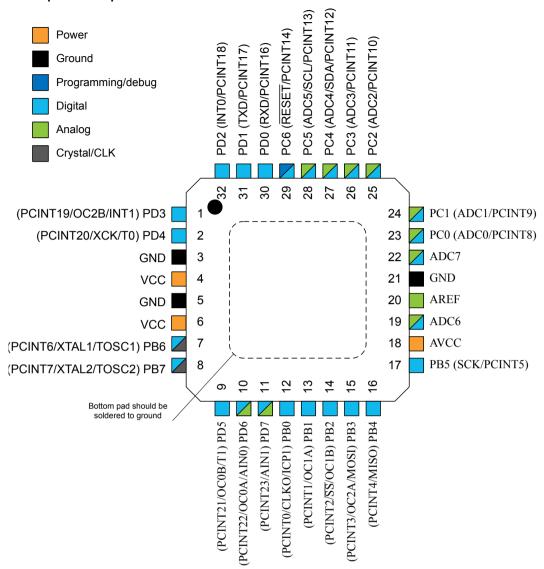


Figure 5-3. 32-pin TQFP Top View

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Figure 5-4. 32-pin MLF Top View



### 5.2. Pin Descriptions

#### 5.2.1. VCC

Digital supply voltage.

### 5.2.2. GND

Ground.

#### 5.2.3. Port B (PB[7:0]) XTAL1/XTAL2/TOSC1/TOSC2

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Depending on the clock selection fuse settings, PB6 can be used as input to the inverting Oscillator amplifier and input to the internal clock operating circuit.



### 6. I/O Multiplexing

Each pin is by default controlled by the PORT as a general purpose I/O and alternatively it can be assigned to one of the peripheral functions.

The following table describes the peripheral signals multiplexed to the PORT I/O pins.

(32-pin MLF/TQFP) Pin#	(28-pin MLF) Pin#	(28-pin PIPD) Pin#	PAD	EXTINT	PCINT	ADC/AC	osc	T/C #0	T/C #1	USART 0	I2C 0	SPI 0
1	1	5	PD[3]	INT1	PCINT19			OC2B				
2	2	6	PD[4]		PCINT20			Т0		XCK0		
4	3	7	VCC									
3	4	8	GND									
6	-	-	VCC									
5	-	-	GND									
7	5	9	PB[6]		PCINT6		XTAL1/ TOSC1					
8	6	10	PB[7]		PCINT7		XTAL2/ TOSC2					
9	7	11	PD[5]		PCINT21			OC0B	T1			
10	8	12	PD[6]		PCINT22	AIN0		OC0A				
11	9	13	PD[7]		PCINT23	AIN1						
12	10	14	PB[0]		PCINT0		CLKO	ICP1				
13	11	15	PB[1]		PCINT1			OC1A				
14	12	16	PB[2]		PCINT2			OC1B				<del>SS0</del>
15	13	17	PB[3]		PCINT3			OC2A				MOSI0
16	14	18	PB[4]		PCINT4							MISO0
17	15	19	PB[5]		PCINT5							SCK0
18	16	20	AVCC									
19	-	-	ADC6			ADC6						
20	17	21	AREF									
21	18	22	GND									
22	-	-	ADC7			ADC7						
23	19	13	PC[0]		PCINT8	ADC0						
24	20	24	PC[1]		PCINT9	ADC1						
25	21	25	PC[2]		PCINT10	ADC2						
26	22	26	PC[3]		PCINT11	ADC3						
27	23	27	PC[4]		PCINT12	ADC4					SDA0	
28	24	28	PC[5]		PCINT13	ADC5					SCL0	
29	25	1	PC[6]/ RESET		PCINT14							

#### Table 6-1. PORT Function Multiplexing



(32-pin MLF/TQFP) Pin#	(28-pin MLF) Pin#	(28-pin PIPD) Pin#	PAD	EXTINT	PCINT	ADC/AC	OSC	T/C #0	T/C #1	USART 0	12C 0	SPI 0
30	26	2	PD[0]		PCINT16					RXD0		
31	27	3	PD[1]		PCINT17					TXD0		
32	28	4	PD[2]	INT0	PCINT18							



## 7. Resources

A comprehensive set of development tools, application notes, and datasheets are available for download on http://www.atmel.com/avr.



### 8. Data Retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C.



### 9. About Code Examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Confirm with the C compiler documentation for more details.

For I/O Registers located in extended I/O map, "IN", "OUT", "SBIS", "SBIC", "CBI", and "SBI" instructions must be replaced with instructions that allow access to extended I/O. Typically "LDS" and "STS" combined with "SBRS", "SBRC", "SBR", and "CBR".



### 10. Capacitive Touch Sensing

#### 10.1. QTouch Library

The Atmel<sup>®</sup> QTouch<sup>®</sup> Library provides a simple to use solution to realize touch sensitive interfaces on most Atmel AVR<sup>®</sup> microcontrollers. The QTouch Library includes support for the Atmel QTouch and Atmel QMatrix<sup>®</sup> acquisition methods.

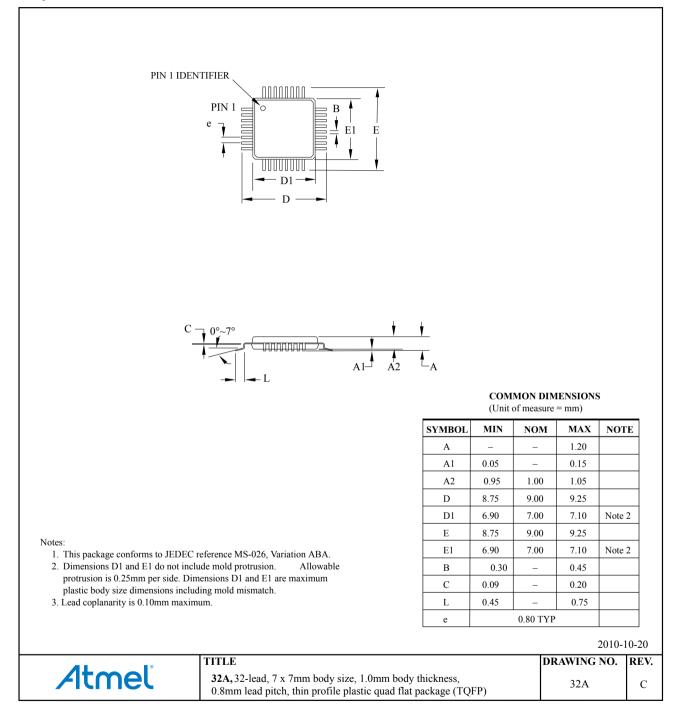
Touch sensing can be added to any application by linking the appropriate Atmel QTouch Library for the AVR Microcontroller. This is done by using a simple set of APIs to define the touch channels and sensors, and then calling the touch sensing API's to retrieve the channel information and determine the touch sensor states.

The QTouch Library is FREE and downloadable from the Atmel website at the following location: http:// www.atmel.com/technologies/touch/. For implementation details and other information, refer to the Atmel QTouch Library User Guide - also available for download from the Atmel website.



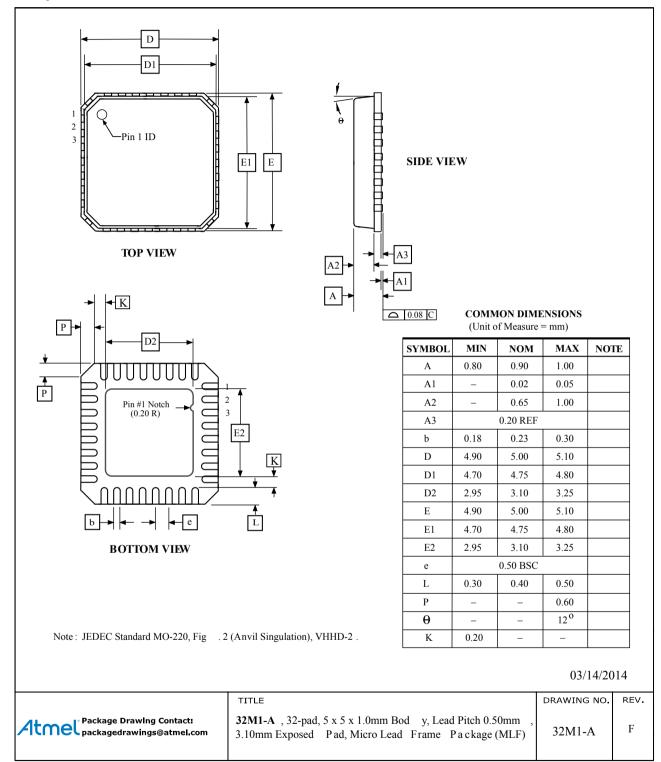
### 11. Packaging Information

#### 11.1. 32-pin 32A



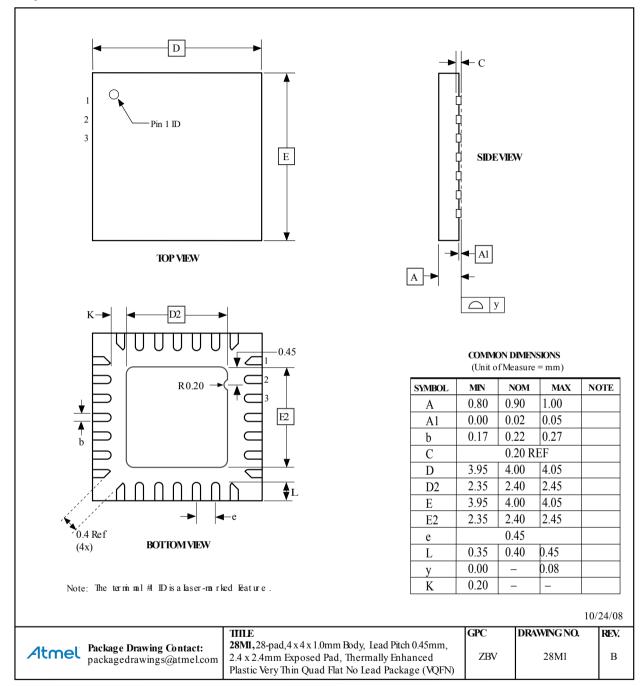


#### 11.2. 32-pin 32M1-A



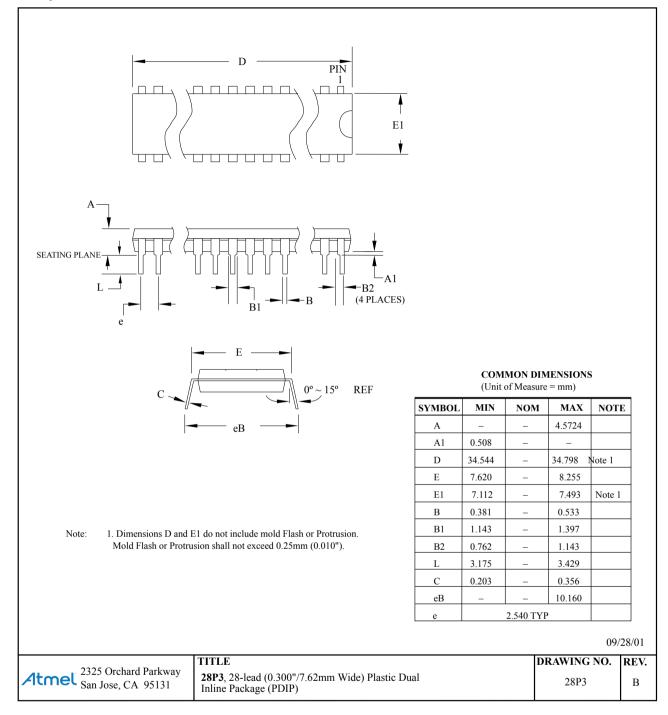


#### 28-pin 28M1 11.3.





#### 11.4. 28-pin 28P3



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Atmel Corporation 1600 Technology Driv

1600 Technology Drive, San Jose, CA 95110 USA

T: (+1)(408) 441.0311

F: (+1)(408) 436.4200

www.atmel.com

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