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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

| Product Status             | Active   |
|----------------------------|--|
| Core Processor             | AVR  |
| Core Size                  | 8-Bit  |
| Speed                      | 10MHz  |
| Connectivity               | I <sup>2</sup> C, SPI, UART/USART  |
| Peripherals                | Brown-out Detect/Reset, POR, PWM, WDT                                      |
| Number of I/O              | 23   |
| Program Memory Size        | 8KB (4K x 16)  |
| Program Memory Type        | FLASH  |
| EEPROM Size                | 512 x 8  |
| RAM Size                   | 1K x 8   |
| Voltage - Supply (Vcc/Vdd) | 1.8V ~ 5.5V  |
| Data Converters            | A/D 8x10b  |
| Oscillator Type            | Internal   |
| Operating Temperature      | -40°C ~ 85°C (TA)  |
| Mounting Type              | Surface Mount  |
| Package / Case             | 32-VFQFN Exposed Pad   |
| Supplier Device Package    | 32-VQFN (5x5)  |
| Purchase URL               | https://www.e-xfl.com/product-detail/microchip-technology/atmega88pv-10mur |

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

- Peripheral Features
  - Two 8-bit Timer/Counters with Separate Prescaler and Compare Mode
  - One 16-bit Timer/Counter with Separate Prescaler, Compare Mode, and Capture Mode
  - Real Time Counter with Separate Oscillator
  - Six PWM Channels
  - 8-channel 10-bit ADC in TQFP and QFN/MLF package
    - Temperature Measurement
  - 6-channel 10-bit ADC in PDIP Package
    - Temperature Measurement
  - Two Master/Slave SPI Serial Interface
  - One Programmable Serial USART
  - One Byte-oriented 2-wire Serial Interface (Philips I<sup>2</sup>C compatible)
  - Programmable Watchdog Timer with Separate On-chip Oscillator
  - One On-chip Analog Comparator
  - Interrupt and Wake-up on Pin Change
- Special Microcontroller Features
  - Power-on Reset and Programmable Brown-out Detection
  - Internal Calibrated Oscillator
  - External and Internal Interrupt Sources
  - Six Sleep Modes: Idle, ADC Noise Reduction, Power-save, Power-down, Standby, and Extended Standby
- I/O and Packages
  - 23 Programmable I/O Lines
  - 28-pin PDIP, 32-lead TQFP, 28-pad QFN/MLF and 32-pad QFN/MLF
- Operating Voltage:
  - 2.7 5.5V for ATmega48P/88P/168P
  - 1.8 5.5V for ATmega48PV/88PV/168PV
- Temperature Range:
  - -40°C to 85°C
- Speed Grade:
  - ATmega48P/88P/168P: 0 10MHz @ 2.7V 5.5V, 0 20MHz @ 4.5V 5.5V
  - ATmega48PV/88PV/168PV: 0 4MHz @ 1.8V 5.5V, 0 10MHz @ 2.7V 5.5V
- Power Consumption at 1MHz, 1.8V, 25°C
  - Active Mode: 0.3mA
  - Power-down Mode: 0.1µA
  - Power-save Mode: 0.8µA (Including 32kHz RTC)



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### 1. Description

The Atmel AVR<sup>®</sup> core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in a single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega48P/PV /88P/PV /168P/PV provides the following features: 4K/8K/16Kbytes of In-System Programmable Flash with Read-While-Write capabilities, 256/512/512bytes EEPROM, 512/1K/1Kbytes SRAM, 23 general purpose I/O lines, 32 general purpose working registers, Real Time Counter (RTC), three flexible Timer/Counters with compare modes and PWM, 1 serial programmable USARTs, 1 byte-oriented 2-wire Serial Interface (I2C), a 6-channel 10-bit ADC (8 channels in TQFP and QFN/MLF packages), a programmable Watchdog Timer with internal Oscillator, an SPI serial port, and six software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or hardware reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except asynchronous timer and ADC to minimize switching noise during ADC conversions. In Standby mode, the crystal/resonator oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low power consumption. In Extended Standby mode, both the main oscillator and the asynchronous timer continue to run.

Atmel offers the QTouch<sup>®</sup> library for embedding capacitive touch buttons, sliders and wheels functionality into AVR microcontrollers. The patented charge-transfer signal acquisition offers robust sensing and includes fully debounced reporting of touch keys and includes Adjacent Key Suppression<sup>®</sup> (AKS<sup>™</sup>) technology for unambiguous detection of key events. The easy-to-use QTouch Suite toolchain allows you to explore, develop and debug your own touch applications.

The device is manufactured using Atmel's high density non-volatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed In-System through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core. The Boot program can use any interface to download the application program in the Application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega48P/PV /88P/PV /168P/PV is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

The ATmega48P/PV /88P/PV /168P/PV is supported with a full suite of program and system development tools including: C Compilers, Macro Assemblers, Program Debugger/Simulators, In-Circuit Emulators, and Evaluation kits.



# 2. Configuration Summary

| Features  | ATmega48P/PV /88P/PV /168P/PV |
|---|-------------------------------|
| Pin Count                                       | 28/32                         |
| Flash (Bytes)                                   | 4K/8K/16K                     |
| SRAM (Bytes)                                    | 512/1K/1K                     |
| EEPROM (Bytes)                                  | 256/512/512                   |
| Interrupt Vector Size (instruction word/vector) | 1/1/2                         |
| General Purpose I/O Lines                       | 23                            |
| SPI   | 2                             |
| TWI (I <sup>2</sup> C)                          | 1                             |
| USART   | 1                             |
| ADC   | 10-bit 15kSPS                 |
| ADC Channels                                    | 8                             |
| 8-bit Timer/Counters                            | 2                             |
| 16-bit Timer/Counters                           | 1                             |

ATmega88P/PV and ATmega168P/PV support a real Read-While-Write Self-Programming mechanism. There is a separate Boot Loader Section, and the SPM instruction can only execute from there. In ATmega48P/PV, there is no Read-While-Write support and no separate Boot Loader Section. The SPM instruction can execute from the entire Flash.



### 3. Ordering Information

### 3.1. ATmega48P/PV

| Speed [MHz] <sup>(3)</sup> | Power Supply [V] | Ordering Code <sup>(2)</sup>  | Package <sup>(1)</sup>                                 | Operational Range             |  |  |
|----------------------------|------------------|---|--|-------------------------------|--|--|
| 10                         | 1.8 - 5.5        | ATmega48PV-10AU<br>ATmega48PV-10AUR <sup>(4)</sup><br>ATmega48PV-10MMU<br>ATmega48PV-10MMUR <sup>(4)</sup><br>ATmega48PV-10MU<br>ATmega48PV-10MUR <sup>(4)</sup><br>ATmega48PV-10PU | 32A<br>32A<br>28M1<br>28M1<br>32M1-A<br>32M1-A<br>28P3 | Industrial<br>(-40°C to 85°C) |  |  |
| 20                         | 2.7 - 5.5        | ATmega48P-20AU<br>ATmega48P-20AUR <sup>(4)</sup><br>ATmega48P-20MMU<br>ATmega48P-20MMUR <sup>(4)</sup><br>ATmega48P-20MU<br>ATmega48P-20MUR <sup>(4)</sup><br>ATmega48P-20PU        | 32A<br>32A<br>28M1<br>28M1<br>32M1-A<br>32M1-A<br>28P3 |                               |  |  |

#### Note:

- 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
- 2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
- 3. Please refer to Speed Grades for Speed vs. V<sub>CC</sub>
- 4. Tape & Reel.

| Package | е Туре  |
|---------|---|
| 28M1    | 28-pad, 4 x 4 x 1.0 body, Lead Pitch 0.45mm Quad Flat No-Lead/Micro Lead Frame Package (QFN/ MLF) |
| 28P3    | 28-lead, 0.300" Wide, Plastic Dual Inline Package (PDIP)  |
| 32M1-A  | 32-pad, 5 x 5 x 1.0 body, Lead Pitch 0.50mm Quad Flat No-Lead/Micro Lead Frame Package (QFN/ MLF) |
| 32A     | 32-lead, Thin (1.0mm) Plastic Quad Flat Package (TQFP)  |



### 3.3. ATmega168P/PV

| Speed [MHz] <sup>(3)</sup> | Power Supply [V] | Ordering Code <sup>(2)</sup>   | Package <sup>(1)</sup>                 | Operational Range             |  |
|----------------------------|------------------|--|--|-------------------------------|--|
| 10                         | 1.8 - 5.5        | ATmega168PV-10AU<br>ATmega168PV-10AUR <sup>(4)</sup><br>ATmega168PV-10MU<br>ATmega168PV-10MUR <sup>(4)</sup><br>ATmega168PV-10PU | 32A<br>32A<br>32M1-A<br>32M1-A<br>28P3 | Industrial<br>(-40°C to 85°C) |  |
| 20                         | 2.7 - 5.5        | ATmega168P-20AUR <sup>(4)</sup><br>ATmega168P-20MUR <sup>(4)</sup><br>ATmega168P-20AU<br>ATmega168P-20MU<br>ATmega168P-20PU      | 32A<br>32M1-A<br>32A<br>32M1-A<br>28P3 |                               |  |

#### Note:

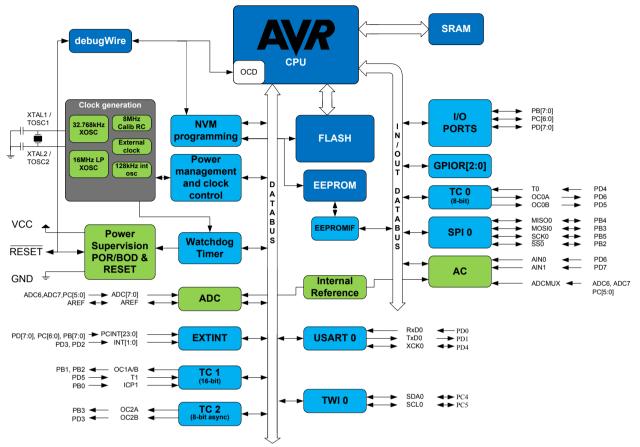
- 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
- 2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
- 3. Please refer to Speed Grades for Speed vs.  $V_{CC}$
- 4. Tape & Reel.

| Package | э Туре  |
|---------|---|
| 28P3    | 28-lead, 0.300" Wide, Plastic Dual Inline Package (PDIP)  |
| 32M1-A  | 32-pad, 5 x 5 x 1.0 body, Lead Pitch 0.50mm Quad Flat No-Lead/Micro Lead Frame Package (QFN/ MLF) |
| 32A     | 32-lead, Thin (1.0mm) Plastic Quad Flat Package (TQFP)  |



# 4. Block Diagram

Figure 4-1. Block Diagram





### 5. Pin Configurations

### 5.1. Pin-out

Figure 5-1. 28-pin PDIP

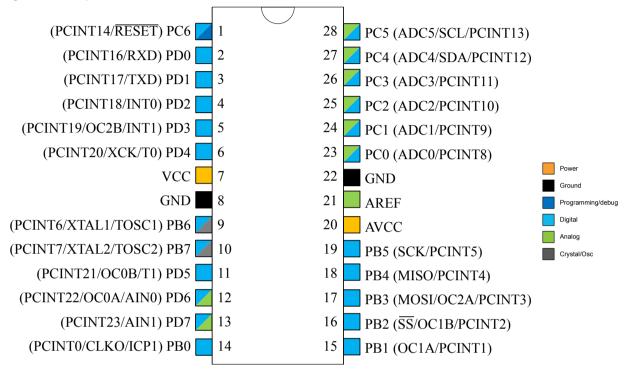
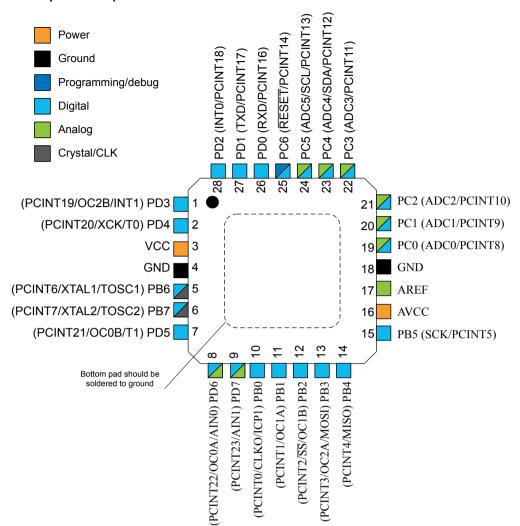




Figure 5-2. 28-pin MLF Top View





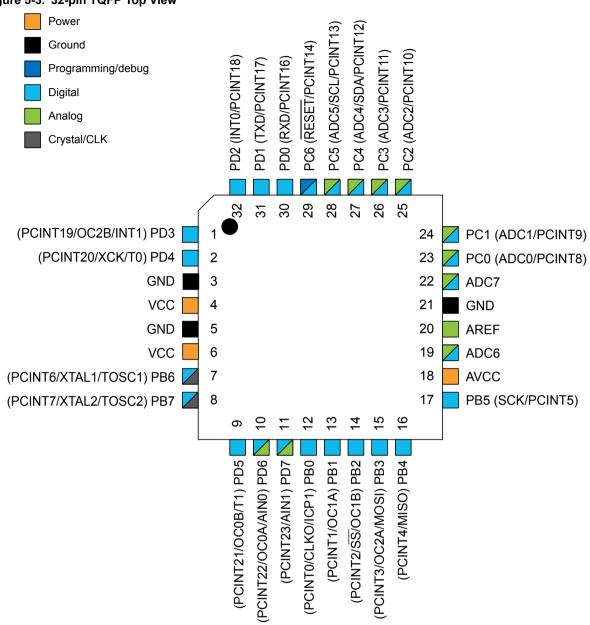


Figure 5-3. 32-pin TQFP Top View

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Depending on the clock selection fuse settings, PB7 can be used as output from the inverting Oscillator amplifier.

If the Internal Calibrated RC Oscillator is used as chip clock source, PB[7:6] is used as TOSC[2:1] input for the Asynchronous Timer/Counter2 if the AS2 bit in ASSR is set.

#### 5.2.4. Port C (PC[5:0])

Port C is a 7-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The PC[5:0] output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.

#### 5.2.5. PC6/RESET

If the RSTDISBL Fuse is programmed, PC6 is used as an I/O pin. Note that the electrical characteristics of PC6 differ from those of the other pins of Port C.

If the RSTDISBL Fuse is unprogrammed, PC6 is used as a Reset input. A low level on this pin for longer than the minimum pulse length will generate a Reset, even if the clock is not running. Shorter pulses are not guaranteed to generate a Reset.

The various special features of Port C are elaborated in the Alternate Functions of Port C section.

#### 5.2.6. Port D (PD[7:0])

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

### 5.2.7. AV<sub>CC</sub>

 $AV_{CC}$  is the supply voltage pin for the A/D Converter, PC[3:0], and PE[3:2]. It should be externally connected to  $V_{CC}$ , even if the ADC is not used. If the ADC is used, it should be connected to  $V_{CC}$  through a low-pass filter. Note that PC[6:4] use digital supply voltage,  $V_{CC}$ .

#### 5.2.8. AREF

AREF is the analog reference pin for the A/D Converter.

#### 5.2.9. ADC[7:6] (TQFP and VFQFN Package Only)

In the TQFP and VFQFN package, ADC[7:6] serve as analog inputs to the A/D converter. These pins are powered from the analog supply and serve as 10-bit ADC channels.



# 6. I/O Multiplexing

Each pin is by default controlled by the PORT as a general purpose I/O and alternatively it can be assigned to one of the peripheral functions.

The following table describes the peripheral signals multiplexed to the PORT I/O pins.

| (32-pin<br>MLF/TQFP)<br>Pin# | (28-pin<br>MLF) Pin# | (28-pin<br>PIPD) Pin# | PAD             | EXTINT | PCINT   | ADC/AC | osc             | T/C #0 | T/C<br>#1 | USART 0 | 12C 0 | SPI 0      |
|------------------------------|----------------------|-----------------------|-----------------|--------|---------|--------|-----------------|--------|-----------|---------|-------|------------|
| 1                            | 1                    | 5                     | PD[3]           | INT1   | PCINT19 |        |                 | OC2B   |           |         |       |            |
| 2                            | 2                    | 6                     | PD[4]           |        | PCINT20 |        |                 | Т0     |           | XCK0    |       |            |
| 4                            | 3                    | 7                     | VCC             |        |         |        |                 |        |           |         |       |            |
| 3                            | 4                    | 8                     | GND             |        |         |        |                 |        |           |         |       |            |
| 6                            | -                    | -                     | VCC             |        |         |        |                 |        |           |         |       |            |
| 5                            | -                    | -                     | GND             |        |         |        |                 |        |           |         |       |            |
| 7                            | 5                    | 9                     | PB[6]           |        | PCINT6  |        | XTAL1/<br>TOSC1 |        |           |         |       |            |
| 8                            | 6                    | 10                    | PB[7]           |        | PCINT7  |        | XTAL2/<br>TOSC2 |        |           |         |       |            |
| 9                            | 7                    | 11                    | PD[5]           |        | PCINT21 |        |                 | OC0B   | T1        |         |       |            |
| 10                           | 8                    | 12                    | PD[6]           |        | PCINT22 | AIN0   |                 | OC0A   |           |         |       |            |
| 11                           | 9                    | 13                    | PD[7]           |        | PCINT23 | AIN1   |                 |        |           |         |       |            |
| 12                           | 10                   | 14                    | PB[0]           |        | PCINT0  |        | CLKO            | ICP1   |           |         |       |            |
| 13                           | 11                   | 15                    | PB[1]           |        | PCINT1  |        |                 | OC1A   |           |         |       |            |
| 14                           | 12                   | 16                    | PB[2]           |        | PCINT2  |        |                 | OC1B   |           |         |       | <u>SS0</u> |
| 15                           | 13                   | 17                    | PB[3]           |        | PCINT3  |        |                 | OC2A   |           |         |       | MOSI0      |
| 16                           | 14                   | 18                    | PB[4]           |        | PCINT4  |        |                 |        |           |         |       | MISO0      |
| 17                           | 15                   | 19                    | PB[5]           |        | PCINT5  |        |                 |        |           |         |       | SCK0       |
| 18                           | 16                   | 20                    | AVCC            |        |         |        |                 |        |           |         |       |            |
| 19                           | -                    | -                     | ADC6            |        |         | ADC6   |                 |        |           |         |       |            |
| 20                           | 17                   | 21                    | AREF            |        |         |        |                 |        |           |         |       |            |
| 21                           | 18                   | 22                    | GND             |        |         |        |                 |        |           |         |       |            |
| 22                           | -                    | -                     | ADC7            |        |         | ADC7   |                 |        |           |         |       |            |
| 23                           | 19                   | 13                    | PC[0]           |        | PCINT8  | ADC0   |                 |        |           |         |       |            |
| 24                           | 20                   | 24                    | PC[1]           |        | PCINT9  | ADC1   |                 |        |           |         |       |            |
| 25                           | 21                   | 25                    | PC[2]           |        | PCINT10 | ADC2   |                 |        |           |         |       |            |
| 26                           | 22                   | 26                    | PC[3]           |        | PCINT11 | ADC3   |                 |        |           |         |       |            |
| 27                           | 23                   | 27                    | PC[4]           |        | PCINT12 | ADC4   |                 |        |           |         | SDA0  |            |
| 28                           | 24                   | 28                    | PC[5]           |        | PCINT13 | ADC5   |                 |        |           |         | SCL0  |            |
| 29                           | 25                   | 1                     | PC[6]/<br>RESET |        | PCINT14 |        |                 |        |           |         |       |            |

#### Table 6-1. PORT Function Multiplexing



| (32-pin<br>MLF/TQFP)<br>Pin# | (28-pin<br>MLF) Pin# | (28-pin<br>PIPD) Pin# | PAD   | EXTINT | PCINT   | ADC/AC | OSC | T/C #0 | T/C<br>#1 | USART 0 | 12C 0 | SPI 0 |
|------------------------------|----------------------|-----------------------|-------|--------|---------|--------|-----|--------|-----------|---------|-------|-------|
| 30                           | 26                   | 2                     | PD[0] |        | PCINT16 |        |     |        |           | RXD0    |       |       |
| 31                           | 27                   | 3                     | PD[1] |        | PCINT17 |        |     |        |           | TXD0    |       |       |
| 32                           | 28                   | 4                     | PD[2] | INT0   | PCINT18 |        |     |        |           |         |       |       |



# 7. Resources

A comprehensive set of development tools, application notes, and datasheets are available for download on http://www.atmel.com/avr.



# 8. Data Retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C.



### 9. About Code Examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Confirm with the C compiler documentation for more details.

For I/O Registers located in extended I/O map, "IN", "OUT", "SBIS", "SBIC", "CBI", and "SBI" instructions must be replaced with instructions that allow access to extended I/O. Typically "LDS" and "STS" combined with "SBRS", "SBRC", "SBR", and "CBR".



### 10. Capacitive Touch Sensing

### 10.1. QTouch Library

The Atmel<sup>®</sup> QTouch<sup>®</sup> Library provides a simple to use solution to realize touch sensitive interfaces on most Atmel AVR<sup>®</sup> microcontrollers. The QTouch Library includes support for the Atmel QTouch and Atmel QMatrix<sup>®</sup> acquisition methods.

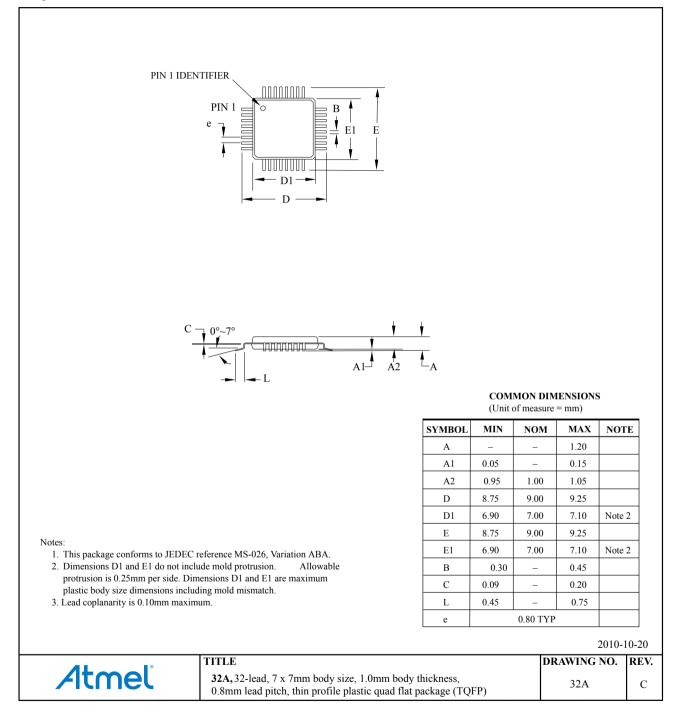
Touch sensing can be added to any application by linking the appropriate Atmel QTouch Library for the AVR Microcontroller. This is done by using a simple set of APIs to define the touch channels and sensors, and then calling the touch sensing API's to retrieve the channel information and determine the touch sensor states.

The QTouch Library is FREE and downloadable from the Atmel website at the following location: http:// www.atmel.com/technologies/touch/. For implementation details and other information, refer to the Atmel QTouch Library User Guide - also available for download from the Atmel website.



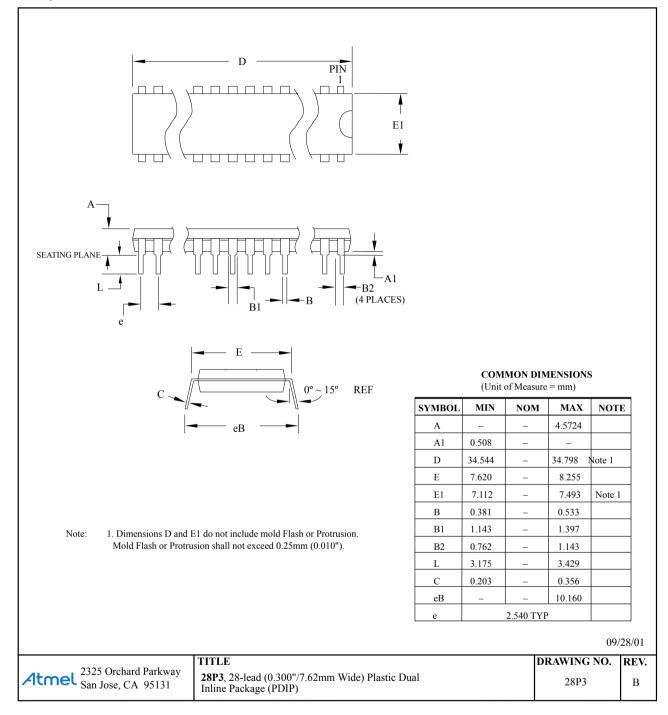
## 11. Packaging Information

### 11.1. 32-pin 32A





### 11.4. 28-pin 28P3



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