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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	48MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	35
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	3.8K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 14x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f46k20-e-pt

PIC18F2XK20/4XK20

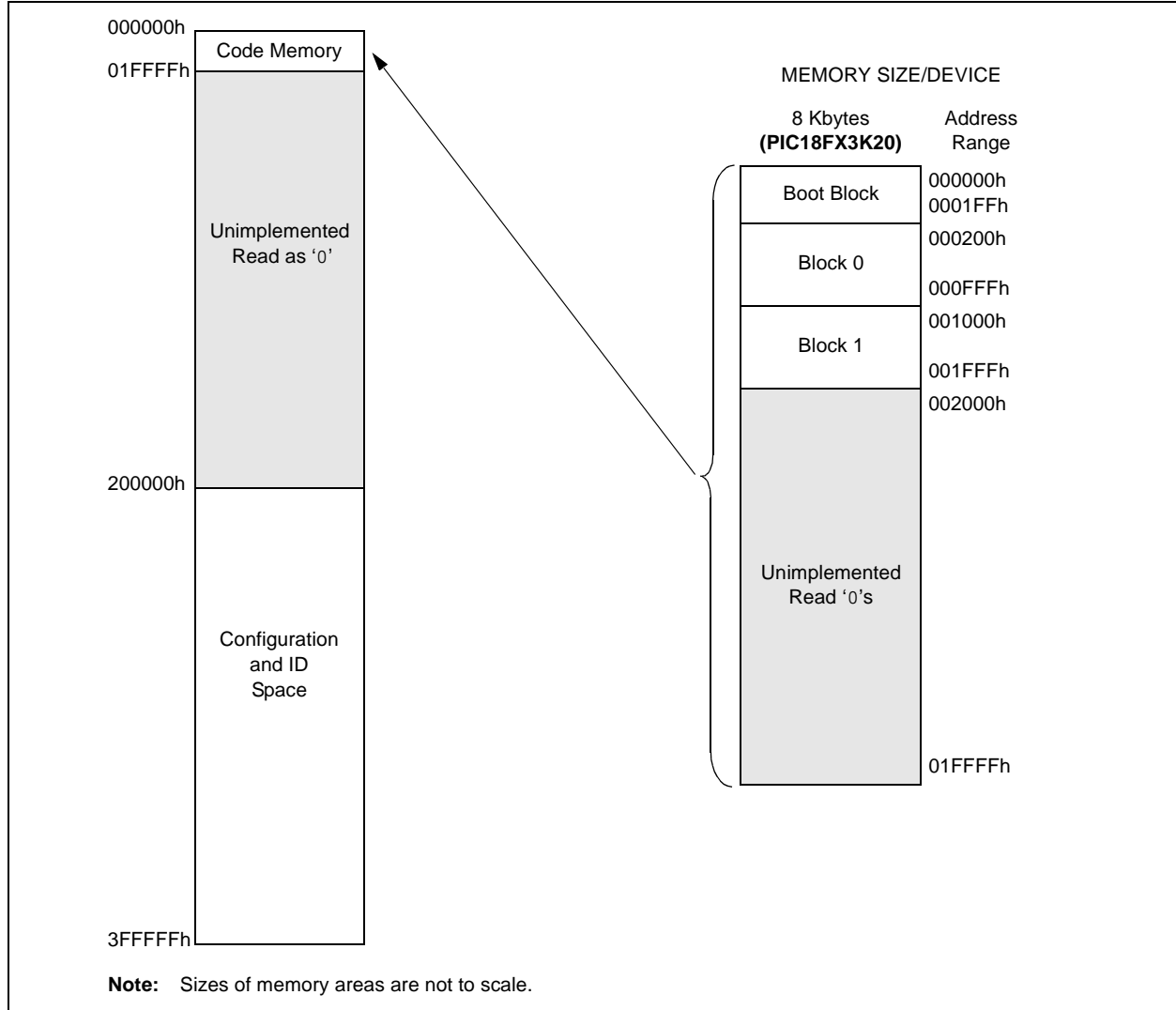
2.3 Memory Maps

For the PIC18FX3K20 devices, the code memory space extends from 0000h to 01FFFh (8 Kbytes) in two 4-Kbyte blocks. Addresses 0000h through 01FFFh, however, define a “Boot Block” region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

TABLE 2-2: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)
PIC18F23K20	000000h-001FFFh (8K)
PIC18F43K20	

FIGURE 2-6: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX3K20 DEVICES



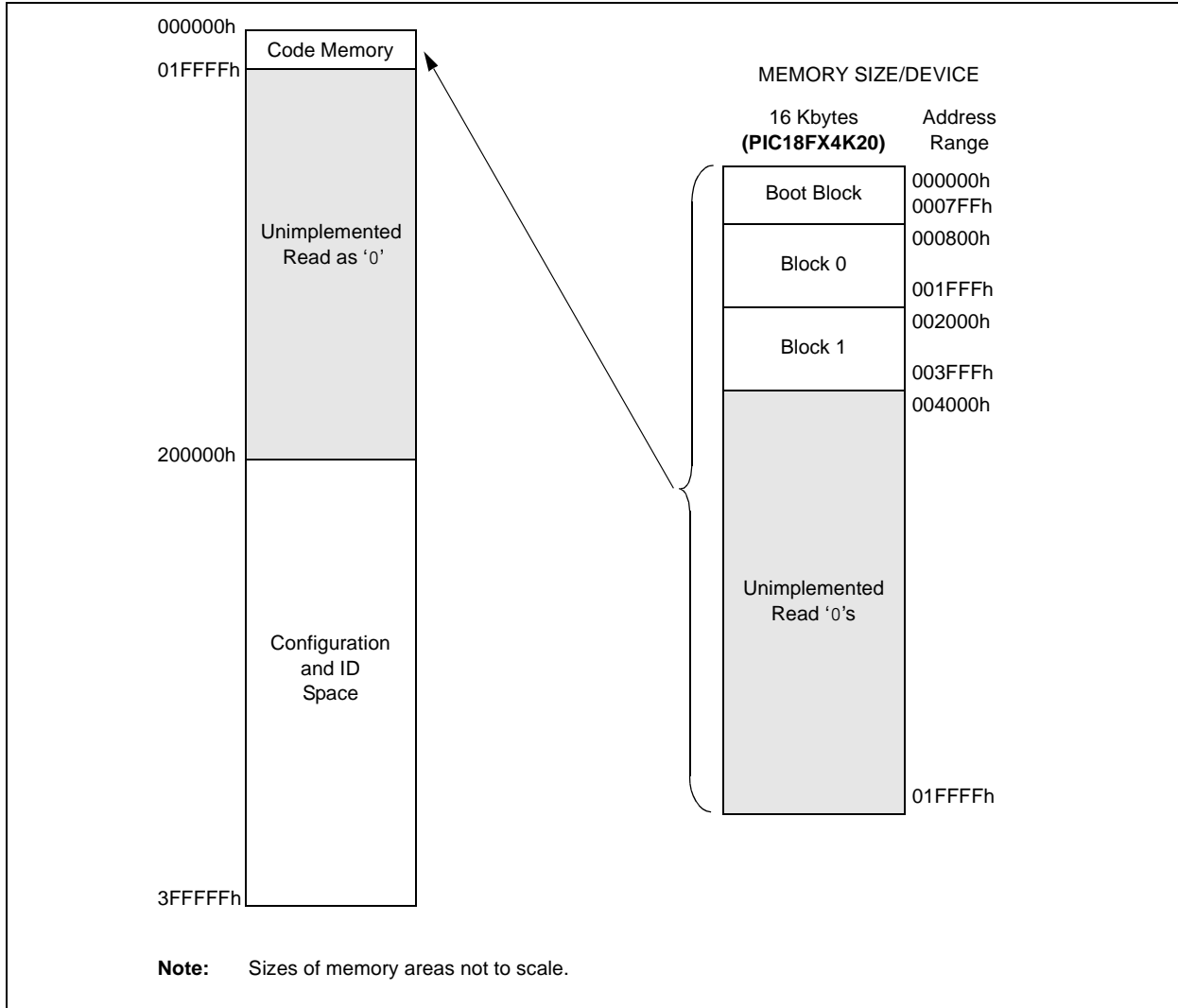
PIC18F2XK20/4XK20

For PIC18FX4K20 devices, the code memory space extends from 000000h to 003FFFh (16 Kbytes) in two 8-Kbyte blocks. Addresses 000000h through 0007FFh, however, define a “Boot Block” region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

TABLE 2-3: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)
PIC18F24K20	000000h-003FFFh (16K)
PIC18F44K20	

FIGURE 2-7: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX4K20 DEVICES



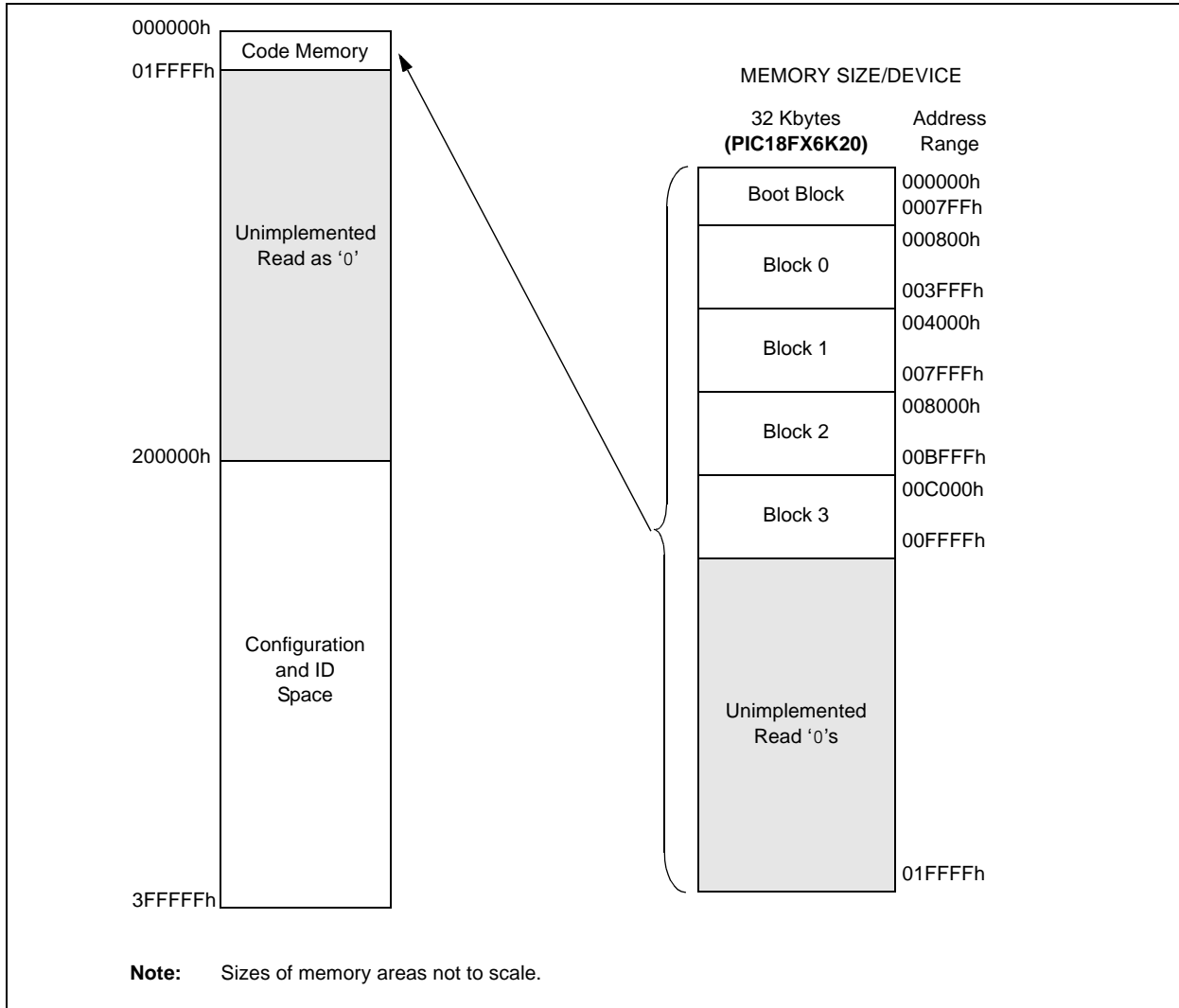
PIC18F2XK20/4XK20

For PIC18FX6K20 devices, the code memory space extends from 000000h to 00FFFFh (64 Kbytes) in four 16-Kbyte blocks. Addresses 000000h through 0007FFh, however, define a “Boot Block” region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

TABLE 2-5: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)
PIC18F26K20	000000h-00FFFFh (64K)
PIC18F46K20	

FIGURE 2-9: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX6K20 DEVICES



In addition to the code memory space, there are three blocks in the configuration and ID space that are accessible to the user through table reads and table writes. Their locations in the memory map are shown in Figure 2-10.

Users may store identification information (ID) in eight ID registers. These ID registers are mapped in addresses 200000h through 200007h. The ID locations read out normally, even after code protection is applied.

Locations 300000h through 30000Dh are reserved for the Configuration bits. These bits select various device options and are described in **Section 5.0 “Configuration Word”**. These Configuration bits read out normally, even after code protection.

Locations 3FFFEh and 3FFFFh are reserved for the device ID bits. These bits may be used by the programmer to identify what device type is being programmed and are described in **Section 5.0 “Configuration Word”**. These device ID bits read out normally, even after code protection.

2.3.1 MEMORY ADDRESS POINTER

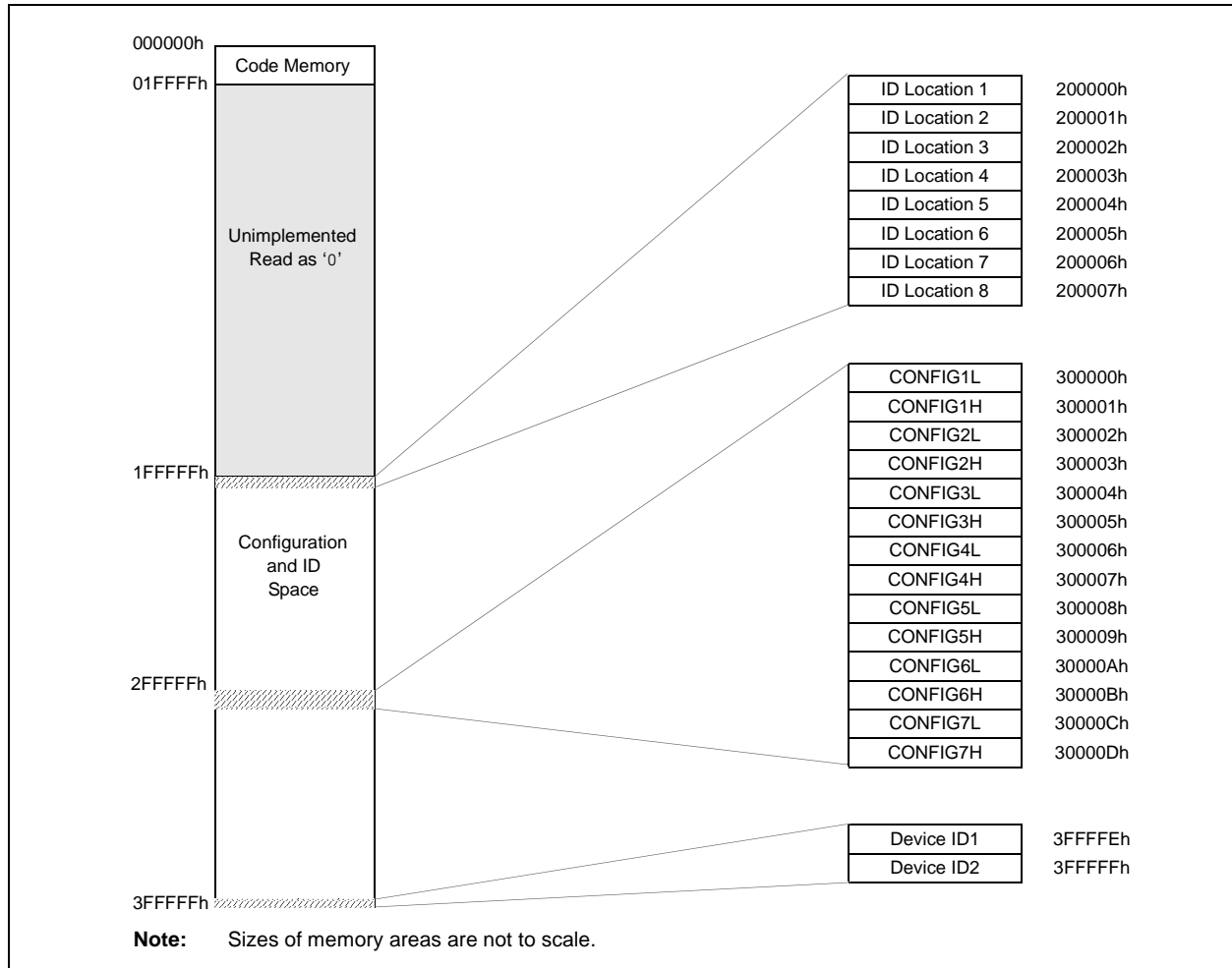
Memory in the address space, 000000h to 3FFFFFFh, is addressed via the Table Pointer register, which is comprised of three Pointer registers:

- TBLPTRU, at RAM address 0FF8h
- TBLPTRH, at RAM address 0FF7h
- TBLPTRL, at RAM address 0FF6h

TBLPTRU	TBLPTRH	TBLPTRL
Addr[21:16]	Addr[15:8]	Addr[7:0]

The 4-bit command, '0000' (core instruction), is used to load the Table Pointer prior to using any read or write operations.

FIGURE 2-10: CONFIGURATION AND ID LOCATIONS FOR PIC18F2XK20/4XK20 DEVICES

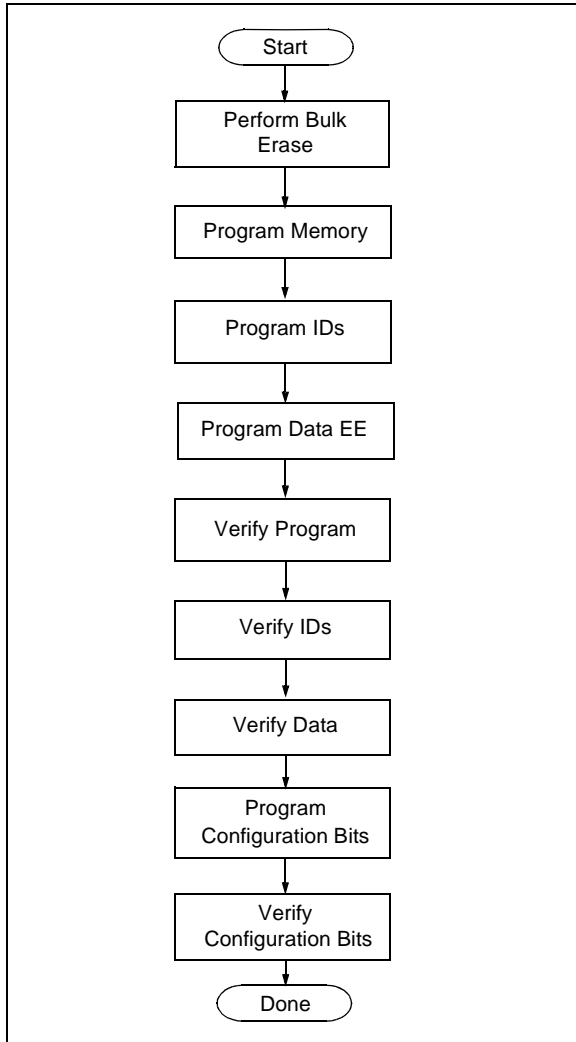


PIC18F2XK20/4XK20

2.4 High-Level Overview of the Programming Process

Figure 2-11 shows the high-level overview of the programming process. First, a Bulk Erase is performed. Next, the code memory, ID locations and data EEPROM are programmed. These memories are then verified to ensure that programming was successful. If no errors are detected, the Configuration bits are then programmed and verified.

FIGURE 2-11: HIGH-LEVEL PROGRAMMING FLOW



2.5 Entering and Exiting High-Voltage ICSP Program/Verify Mode

As shown in Figure 2-12, the High-Voltage ICSP Program/Verify mode is entered by holding PGC and PGD low and then raising $\overline{\text{MCLR}}/\text{VPP}/\text{RE3}$ to $V_{\text{IH}}\text{H}$ (high voltage). Once in this mode, the code memory, data EEPROM, ID locations and Configuration bits can be accessed and programmed in serial fashion. Figure 2-13 shows the exit sequence.

The sequence that enters the device into the Program/Verify mode places all unused I/Os in the high-impedance state.

FIGURE 2-12: ENTERING HIGH-VOLTAGE PROGRAM/VERIFY MODE

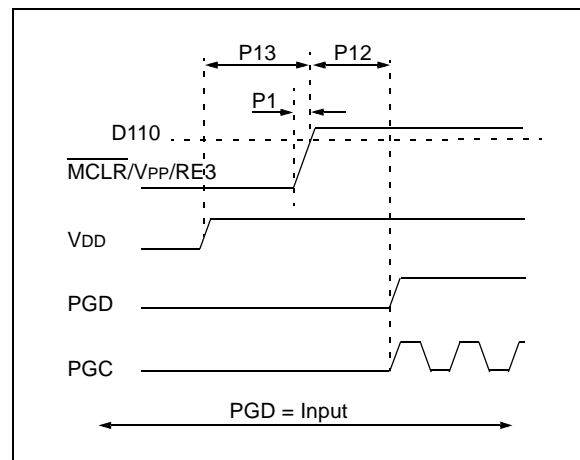
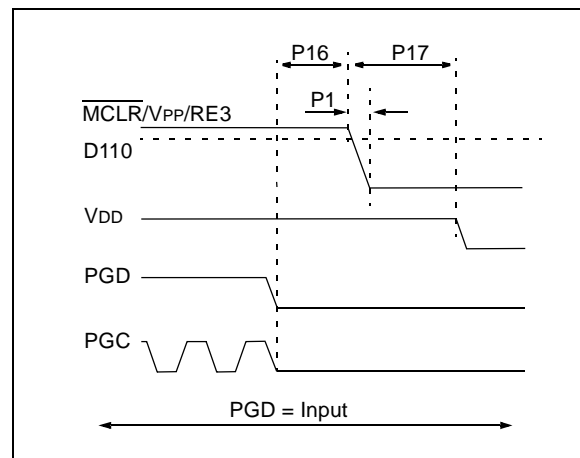


FIGURE 2-13: EXITING HIGH-VOLTAGE PROGRAM/VERIFY MODE



2.6 Entering and Exiting Low-Voltage ICSP Program/Verify Mode

When the LVP Configuration bit is '1' (see **Section 5.3 "Single-Supply ICSP Programming"**), the Low-Voltage ICSP mode is enabled. As shown in Figure 2-14, Low-Voltage ICSP Program/Verify mode is entered by holding PGC and PGD low, placing a logic high on PGM and then raising MCLR/VPP/RE3 to V_{IH} . In this mode, the RB5/PGM pin is dedicated to the programming function and ceases to be a general purpose I/O pin. Figure 2-15 shows the exit sequence.

The sequence that enters the device into the Program/Verify mode places all unused I/Os in the high-impedance state.

FIGURE 2-14: ENTERING LOW-VOLTAGE PROGRAM/VERIFY MODE

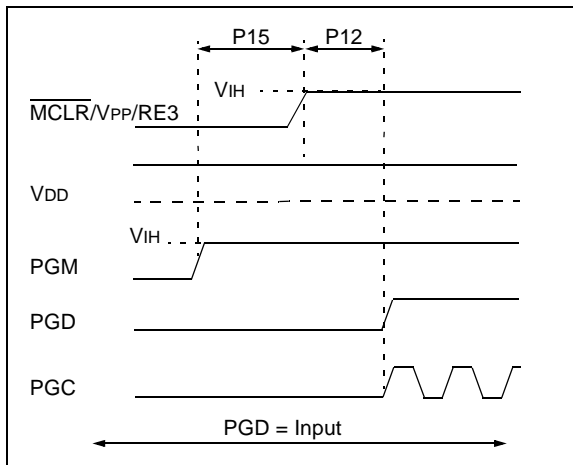
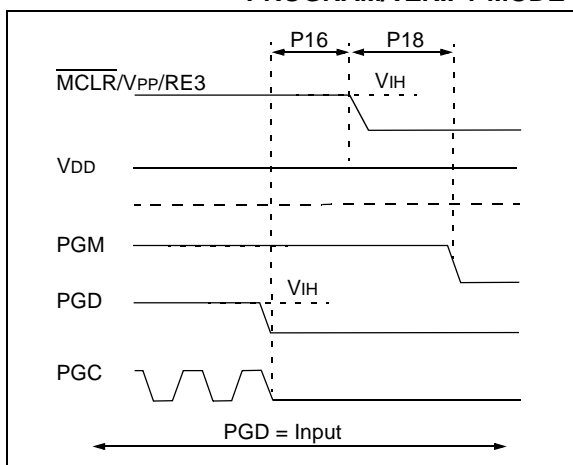


FIGURE 2-15: EXITING LOW-VOLTAGE PROGRAM/VERIFY MODE



2.7 Serial Program/Verify Operation

The PGC pin is used as a clock input pin and the PGD pin is used for entering command bits and data input/output during serial operation. Commands and data are transmitted on the rising edge of PGC, latched on the falling edge of PGC and are Least Significant bit (LSb) first.

2.7.1 4-BIT COMMANDS

All instructions are 20 bits, consisting of a leading 4-bit command followed by a 16-bit operand, which depends on the type of command being executed. To input a command, PGC is cycled four times. The commands needed for programming and verification are shown in Table 2-6.

Depending on the 4-bit command, the 16-bit operand represents 16 bits of input data or 8 bits of input data and 8 bits of output data.

Throughout this specification, commands and data are presented as illustrated in Table 2-7. The 4-bit command is shown Most Significant bit (MSb) first. The command operand, or "Data Payload", is shown <MSB><LSB>. Figure 2-16 demonstrates how to serially present a 20-bit command/operand to the device.

2.7.2 CORE INSTRUCTION

The core instruction passes a 16-bit instruction to the CPU core for execution. This is needed to set up registers as appropriate for use with other commands.

TABLE 2-6: COMMANDS FOR PROGRAMMING

Description	4-Bit Command
Core Instruction (Shift in 16-bit instruction)	0000
Shift out TABLAT register	0010
Table Read	1000
Table Read, post-increment	1001
Table Read, post-decrement	1010
Table Read, pre-increment	1011
Table Write	1100
Table Write, post-increment by 2	1101
Table Write, start programming, post-increment by 2	1110
Table Write, start programming	1111

PIC18F2XK20/4XK20

TABLE 2-7: SAMPLE COMMAND SEQUENCE

4-Bit Command	Data Payload	Core Instruction
1101	3C 40	Table Write, post-increment by 2

FIGURE 2-16: TABLE WRITE, POST-INCREMENT TIMING DIAGRAM (1101)

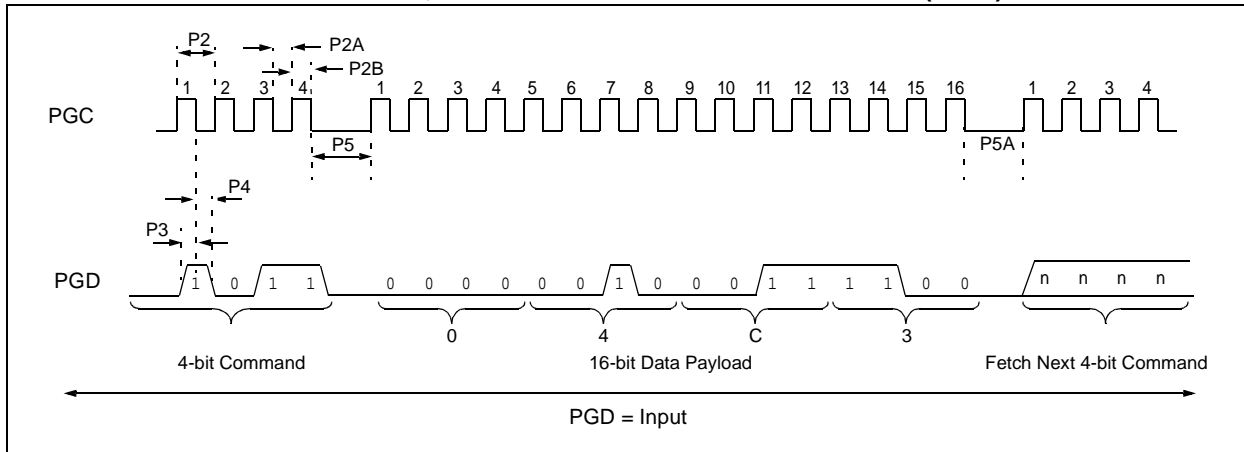


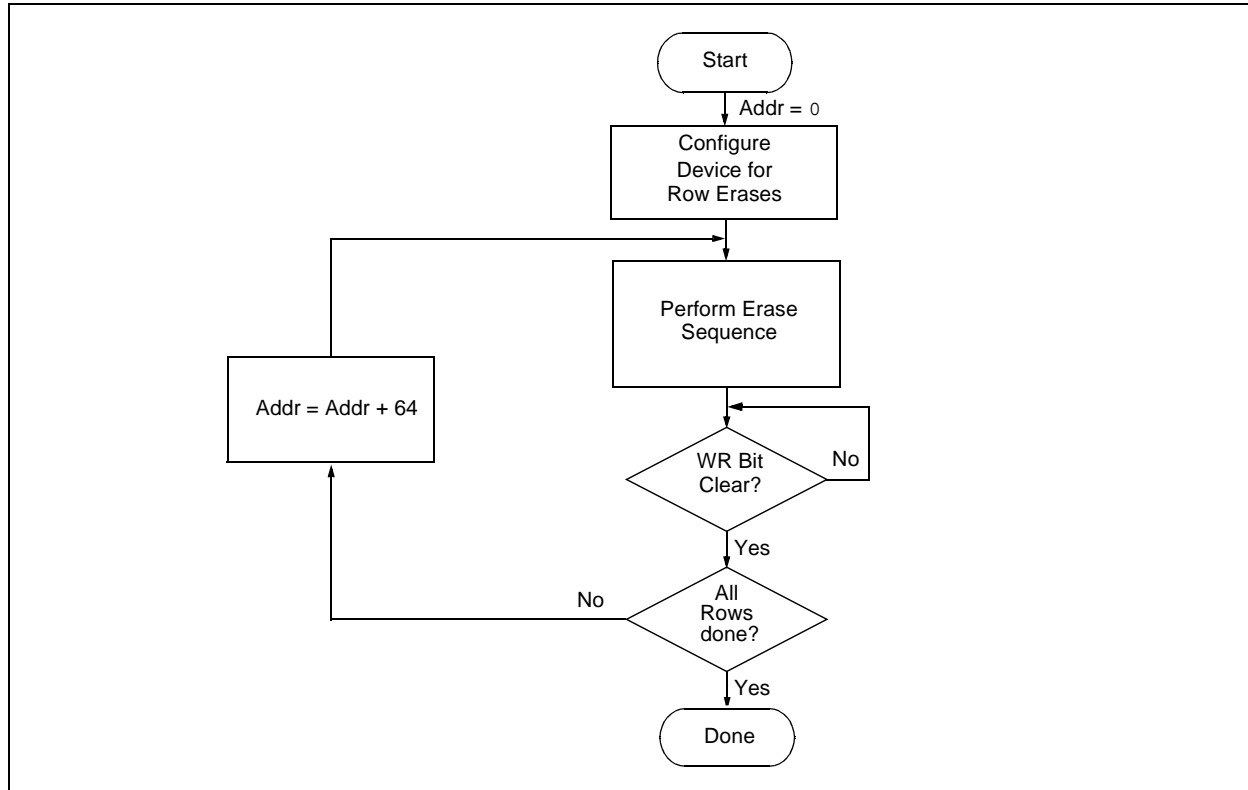
TABLE 3-3: ERASE CODE MEMORY CODE SEQUENCE

4-bit Command	Data Payload	Core Instruction
Step 1: Direct access to code memory and enable writes.		
0000	8E A6	BSF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
0000	84 A6	BSF EECON1, WREN
Step 2: Point to first row in code memory.		
0000	6A F8	CLRF TBLPTRU
0000	6A F7	CLRF TBLPTRH
0000	6A F6	CLRF TBLPTRL
Step 3: Enable erase and erase single row.		
0000	88 A6	BSF EECON1, FREE
0000	82 A6	BSF EECON1, WR
0000	00 00	NOP
0000	00 00	NOP Erase starts on the 4th clock of this instruction
Step 4: Poll WR bit. Repeat until bit is clear.		
0000	50 A6	MOVF EECON1, W, 0
0000	6E F5	MOVWF TABLAT
0000	00 00	NOP
0010	<MSB><LSB>	Shift out data ⁽¹⁾
Step 5: Hold PGC low for time P10.		
Step 6: Repeat step 3 with Address Pointer incremented by 64 until all rows are erased.		
Step 7: Disable writes.		
0000	94 A6	BCF EECON1, WREN

Note 1: See Figure 4-4 for details on shift out data timing.

PIC18F2XK20/4XK20

FIGURE 3-3: SINGLE ROW ERASE CODE MEMORY FLOW



3.2 Code Memory Programming

Programming code memory is accomplished by first loading data into the write buffer and then initiating a programming sequence. The write and erase buffer sizes shown in Table 3-4 can be mapped to any location of the same size beginning at 000000h. The actual memory write sequence takes the contents of this buffer and programs the proper amount of code memory that contains the Table Pointer.

The programming duration is externally timed and is controlled by PGC. After a Start Programming command is issued (4-bit command, '1111'), a NOP is issued, where the 4th PGC is held high for the duration of the programming time, P9.

After PGC is brought low, the programming sequence is terminated. PGC must be held low for the time specified by parameter P10 to allow high-voltage discharge of the memory array.

The code sequence to program a PIC18F2XK20/4XK20 device is shown in Table 3-5. The flowchart shown in Figure 3-4 depicts the logic necessary to completely write a PIC18F2XK20/4XK20 device. The timing diagram that details the Start Programming command and parameters P9 and P10 is shown in Figure 3-5.

Note: The TBLPTR register must point to the same region when initiating the programming sequence as it did when the write buffers were loaded.

TABLE 3-4: WRITE AND ERASE BUFFER SIZES

Devices (Arranged by Family)	Write Buffer Size (bytes)	Erase Size (bytes)
PIC18F26K20, PIC18F46K20	64	64
PIC18F24K20, PIC18F25K20, PIC18F44K20, PIC18F45K20	32	64
PIC18F23K20, PIC18F43K20	16	64

TABLE 3-5: WRITE CODE MEMORY CODE SEQUENCE

4-bit Command	Data Payload	Core Instruction
Step 1: Direct access to code memory.		
0000	8E A6	BSF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
0000	84 A6	BSF EECON1, WREN
Step 2: Point to row to write.		
0000	0E <Addr[21:16]>	MOVLW <Addr[21:16]>
0000	6E F8	MOVWF TBLPTRU
0000	0E <Addr[15:8]>	MOVLW <Addr[15:8]>
0000	6E F7	MOVWF TBLPTRH
0000	0E <Addr[7:0]>	MOVLW <Addr[7:0]>
0000	6E F6	MOVWF TBLPTRL
Step 3: Load write buffer. Repeat for all but the last two bytes.		
1101	<MSB><LSB>	Write 2 bytes and post-increment address by 2.
Step 4: Load write buffer for last two bytes and start programming.		
1111	<MSB><LSB>	Write 2 bytes and start programming.
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.
To continue writing data, repeat steps 2 through 4, where the Address Pointer is incremented by 2 at each iteration of the loop.		

PIC18F2XK20/4XK20

FIGURE 3-4: PROGRAM CODE MEMORY FLOW

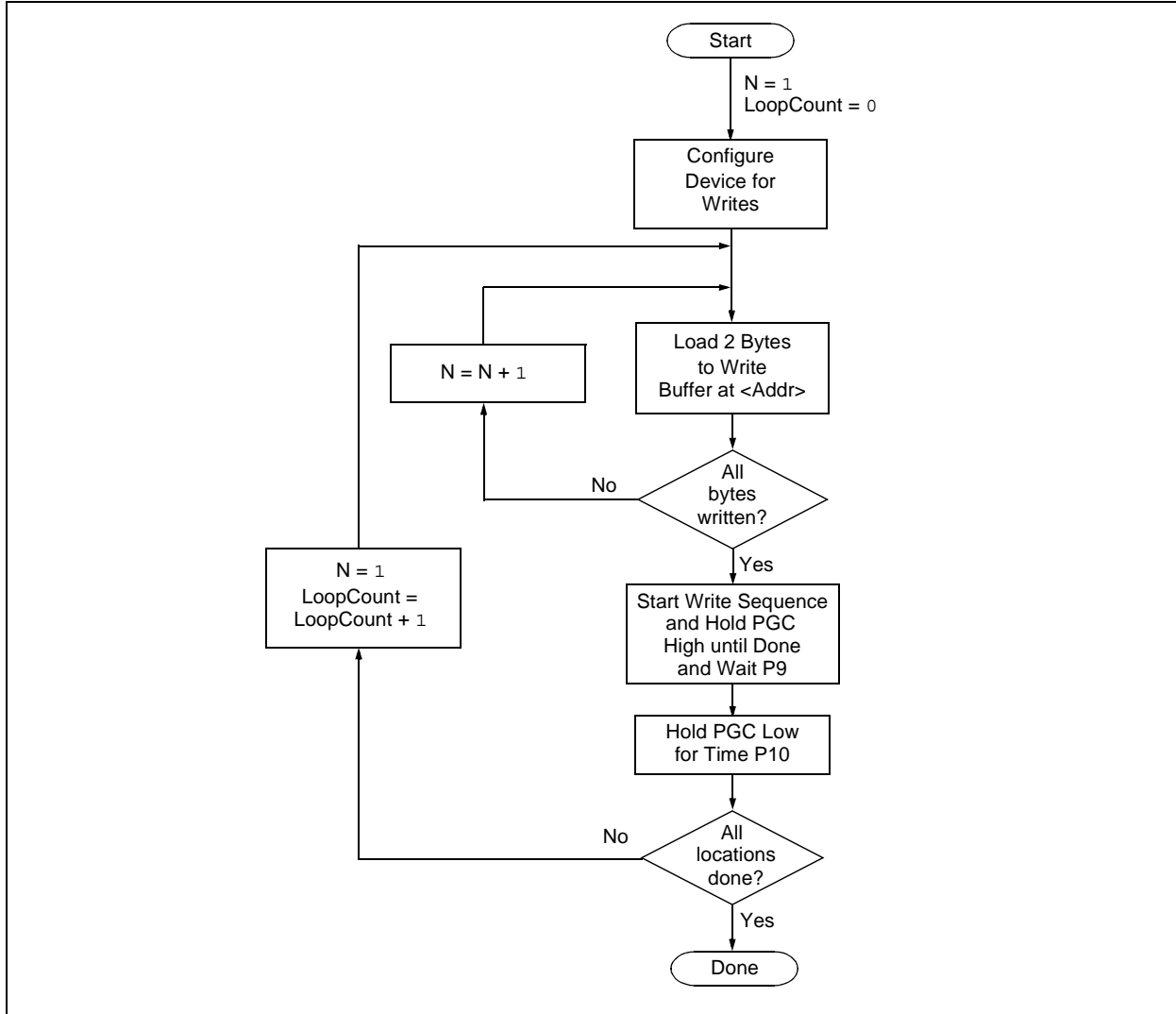


FIGURE 3-5: TABLE WRITE AND START PROGRAMMING INSTRUCTION TIMING DIAGRAM (1111)

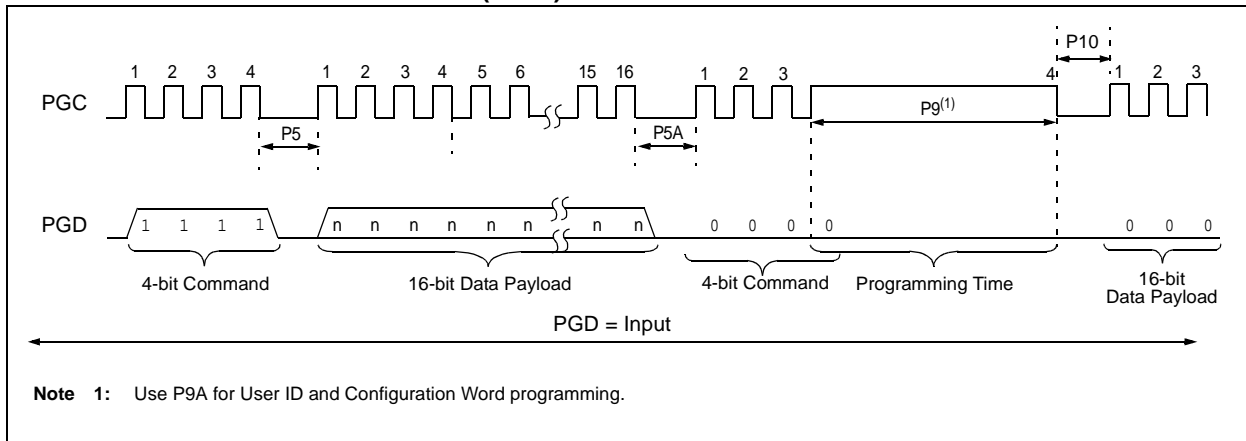


TABLE 3-7: PROGRAMMING DATA MEMORY

4-bit Command	Data Payload	Core Instruction
Step 1: Direct access to data EEPROM.		
0000	9E A6	BCF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
Step 2: Set the data EEPROM Address Pointer.		
0000	0E <Addr>	MOVLW <Addr>
0000	6E A9	MOVWF EEADR
0000	0E <AddrH>	MOVLW <AddrH>
0000	6E AA	MOVWF EEADRH
Step 3: Load the data to be written.		
0000	0E <Data>	MOVLW <Data>
0000	6E A8	MOVWF EEDATA
Step 4: Enable memory writes.		
0000	84 A6	BSF EECON1, WREN
Step 5: Initiate write.		
0000	82 A6	BSF EECON1, WR
0000	00 00	NOP
0000	00 00	NOP ;write starts on 4th clock of this instruction
Step 6: Poll WR bit, repeat until the bit is clear.		
0000	50 A6	MOVF EECON1, W, 0
0000	6E F5	MOVWF TABLAT
0000	00 00	NOP
0010	<MSB><LSB>	Shift out data ⁽¹⁾
Step 7: Hold PGC low for time P10.		
Step 8: Disable writes.		
0000	94 A6	BCF EECON1, WREN
Repeat steps 2 through 8 to write more data.		

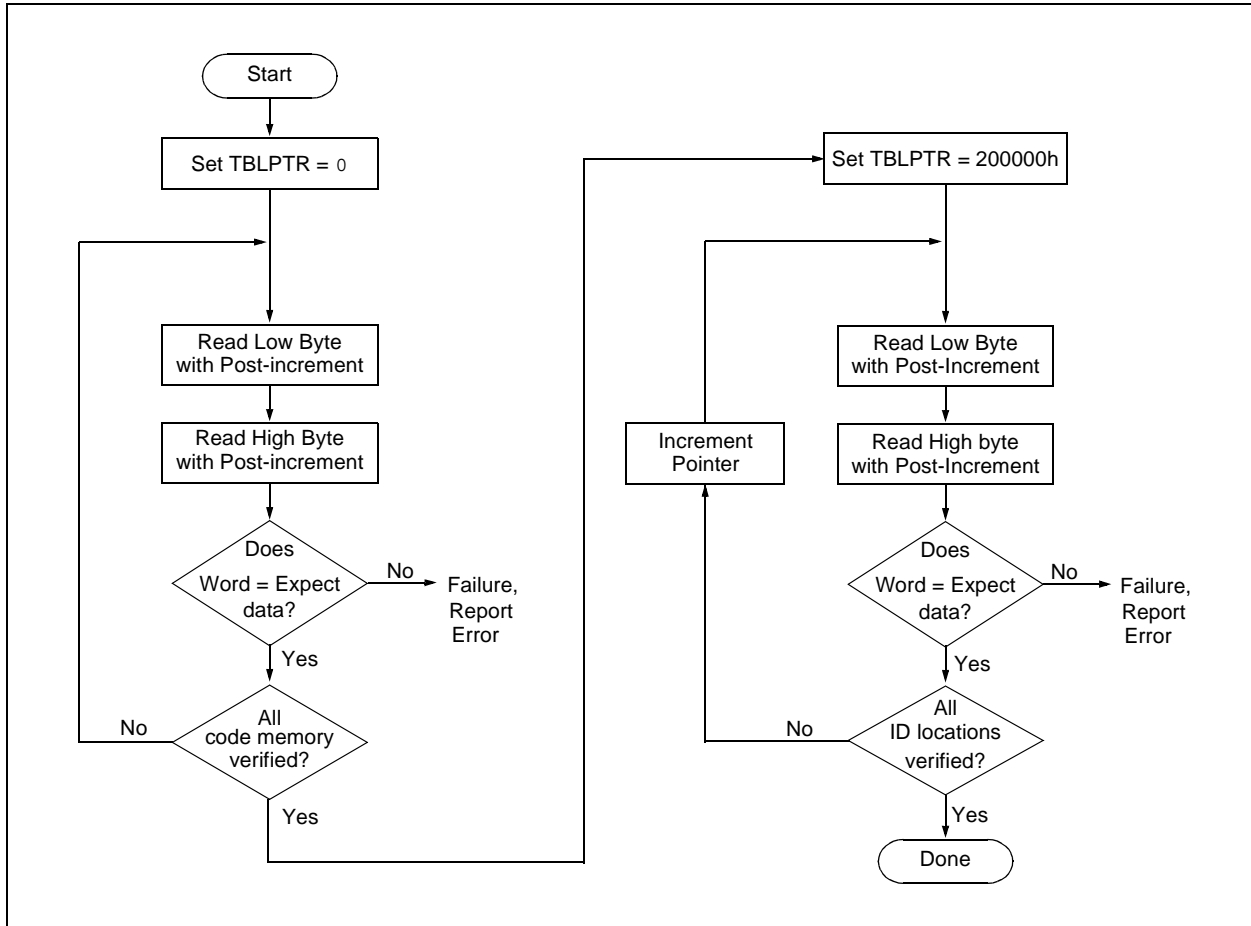
Note 1: See Figure 4-4 for details on shift out data timing.

4.2 Verify Code Memory and ID Locations

The verify step involves reading back the code memory space and comparing it against the copy held in the programmer's buffer. Memory reads occur a single byte at a time, so two bytes must be read to compare against the word in the programmer's buffer. Refer to **Section 4.1 "Read Code Memory, ID Locations and Configuration Bits"** for implementation details of reading code memory.

The Table Pointer must be manually set to 200000h (base address of the ID locations) once the code memory has been verified. The post-increment feature of the table read 4-bit command can not be used to increment the Table Pointer beyond the code memory space. In a 64-Kbyte device, for example, a post-increment read of address FFFFh will wrap the Table Pointer back to 000000h, rather than point to unimplemented address 010000h.

FIGURE 4-2: VERIFY CODE MEMORY FLOW



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4.3 Verify Configuration Bits

A configuration address may be read and output on PGD via the 4-bit command, '1001'. Configuration data is read and written in a byte-wise fashion, so it is not necessary to merge two bytes into a word prior to a compare. The result may then be immediately compared to the appropriate configuration data in the programmer's memory for verification. Refer to **Section 4.1 "Read Code Memory, ID Locations and Configuration Bits"** for implementation details of reading configuration data.

4.4 Read Data EEPROM Memory

Data EEPROM is accessed one byte at a time via an Address Pointer (register pair EEADRH:EEADR) and a data latch (EEDATA). Data EEPROM is read by loading EEADRH:EEADR with the desired memory location and initiating a memory read by appropriately configuring the EECON1 register. The data will be loaded into EEDATA, where it may be serially output on PGD via the 4-bit command, '0010' (Shift Out Data Holding register). A delay of P6 must be introduced after the falling edge of the 8th PGC of the operand to allow PGD to transition from an input to an output. During this time, PGC must be held low (see Figure 4-4).

The command sequence to read a single byte of data is shown in Table 4-2.

FIGURE 4-3: READ DATA EEPROM FLOW

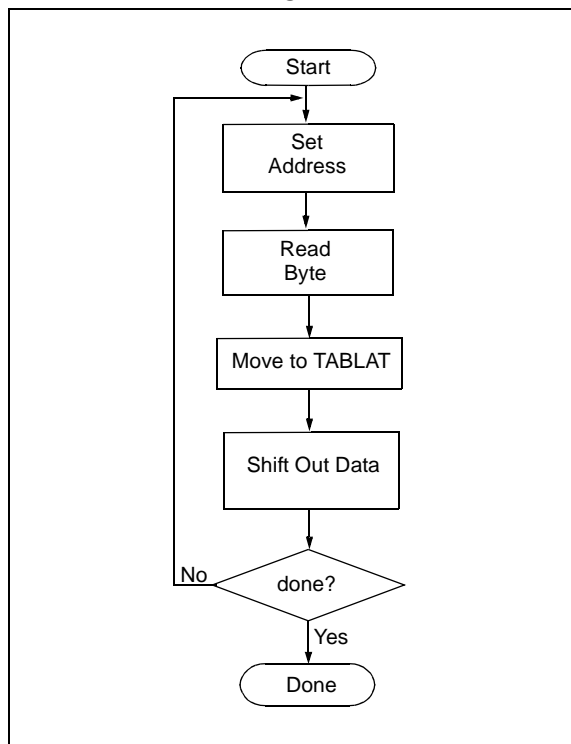


TABLE 4-2: READ DATA EEPROM MEMORY

4-bit Command	Data Payload	Core Instruction
Step 1: Direct access to data EEPROM.		
0000	9E A6	BCF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
Step 2: Set the data EEPROM Address Pointer.		
0000	0E <Addr>	MOVLW <Addr>
0000	6E A9	MOVWF EEADR
0000	0E <AddrH>	MOVLW <AddrH>
0000	6E AA	MOVWF EEADRH
Step 3: Initiate a memory read.		
0000	80 A6	BSF EECON1, RD
Step 4: Load data into the Serial Data Holding register.		
0000	50 A8	MOVF EEDATA, W, 0
0000	6E F5	MOVWF TABLAT
0000	00 00	NOP
0010	<MSB><LSB>	Shift Out Data ⁽¹⁾

Note 1: The <LSB> is undefined. The <MSB> is the data.

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5.0 CONFIGURATION WORD

The PIC18F2XK20/4XK20 devices have several Configuration Words. These bits can be set or cleared to select various device configurations. All other memory areas should be programmed and verified prior to setting Configuration Words. These bits may be read out normally, even after read or code protection. See Table 5-1 for a list of Configuration bits and device IDs and Table 5-3 for the Configuration bit descriptions.

5.1 User ID Locations

A user may store identification information (ID) in eight ID locations mapped in 200000h:200007h. It is recommended that the Most Significant nibble of each ID be Fh. In doing so, if the user code inadvertently tries to execute from the ID space, the ID data will execute as a NOP.

5.2 Device ID Word

The device ID word for the PIC18F2XK20/4XK20 devices is located at 3FFFFEh:3FFFFFh. These bits may be used by the programmer to identify what device type is being programmed and read out normally, even after code or read protection. See Table 5-2 for a complete list of device ID values.

FIGURE 5-1: READ DEVICE ID WORD FLOW

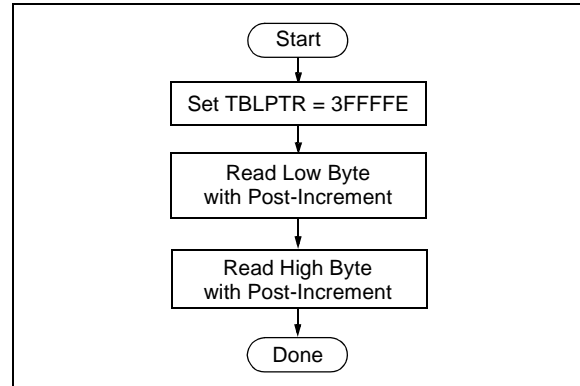


TABLE 5-1: CONFIGURATION BITS AND DEVICE IDs

File Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default/ Unprogrammed Value	
300001h	CONFIG1H	IESO	FCMEN	—	—	FOSC3	FOSC2	FOSC1	FOSC0	00-- 0111
300002h	CONFIG2L	—	—	—	BORV1	BORV0	BOREN1	BOREN0	PWRTEN	---1 1111
300003h	CONFIG2H	—	—	—	WDTPS3	WDTPS2	WDTPS1	WDTPS0	WDTEN	---1 1111
300005h	CONFIG3H	MCLRE	—	—	—	HFOFST	LPT1OSC	PBADEN	CCP2MX	1--- 1011
300006h	CONFIG4L	DEBUG	XINST	—	—	—	LVP	—	STVREN	10-- -1-1
300008h	CONFIG5L	—	—	—	—	CP3 ⁽¹⁾	CP2 ⁽¹⁾	CP1	CP0	---- 1111
300009h	CONFIG5H	CPD	CPB	—	—	—	—	—	—	11-- ----
30000Ah	CONFIG6L	—	—	—	—	WRT3 ⁽¹⁾	WRT2 ⁽¹⁾	WRT1	WRT0	---- 1111
30000Bh	CONFIG6H	WRD	WRTB	WRTC	—	—	—	—	—	111- ----
30000Ch	CONFIG7L	—	—	—	—	EBTR3 ⁽¹⁾	EBTR2 ⁽¹⁾	EBTR1	EBTR0	---- 1111
30000Dh	CONFIG7H	—	EBTRB	—	—	—	—	—	—	-1-- ----
3FFFFEh	DEVID1 ⁽²⁾	DEV2	DEV1	DEV0	REV4	REV3	REV2	REV1	REV0	See Table 5-2
3FFFFFh	DEVID2 ⁽²⁾	DEV10	DEV9	DEV8	DEV7	DEV6	DEV5	DEV4	DEV3	See Table 5-2

Legend: x = unknown, u = unchanged, — = unimplemented. Shaded cells are unimplemented, read as '0'.

Note 1: These bits are only implemented on specific devices. Refer to **Section 2.3 “Memory Maps”** to determine which bits apply based on available memory.

2: DEVID registers are read-only and cannot be programmed by the user.

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TABLE 5-3: PIC18F2XK20/4XK20 BIT DESCRIPTIONS

Bit Name	Configuration Words	Description
IESO	CONFIG1H	Internal External Switchover bit 1 = Internal External Switchover mode enabled 0 = Internal External Switchover mode disabled
FCMEN	CONFIG1H	Fail-Safe Clock Monitor Enable bit 1 = Fail-Safe Clock Monitor enabled 0 = Fail-Safe Clock Monitor disabled
FOSC<3:0>	CONFIG1H	Oscillator Selection bits 11xx = External RC oscillator, CLKOUT function on RA6 101x = External RC oscillator, CLKOUT function on RA6 1001 = HFINTOSC, CLKOUT function on RA6, port function on RA7 1000 = HFINTOSC, port function on RA6, port function on RA7 0111 = External RC oscillator, port function on RA6 0110 = HS oscillator, PLL enabled (clock frequency = 4 x FOSC1) 0101 = EC oscillator, port function on RA6 0100 = EC oscillator, CLKOUT function on RA6 0011 = External RC oscillator, CLKOUT function on RA6 0010 = HS oscillator 0001 = XT oscillator 0000 = LP oscillator
BORV<1:0>	CONFIG2L	Brown-out Reset Voltage bits 11 = VBOR set to 1.8V 10 = VBOR set to 2.2V 01 = VBOR set to 2.7V 00 = VBOR set to 3.0V
BOREN<1:0>	CONFIG2L	Brown-out Reset Enable bits 11 = Brown-out Reset enabled in hardware only (SBOREN is disabled) 10 = Brown-out Reset enabled in hardware only and disabled in Sleep mode (SBOREN is disabled) 01 = Brown-out Reset enabled and controlled by software (SBOREN is enabled) 00 = Brown-out Reset disabled in hardware and software
PWRTEN	CONFIG2L	Power-up Timer Enable bit 1 = PWRT disabled 0 = PWRT enabled
WDPS<3:0>	CONFIG2H	Watchdog Timer Postscaler Select bits 1111 = 1:32,768 1110 = 1:16,384 1101 = 1:8,192 1100 = 1:4,096 1011 = 1:2,048 1010 = 1:1,024 1001 = 1:512 1000 = 1:256 0111 = 1:128 0110 = 1:64 0101 = 1:32 0100 = 1:16 0011 = 1:8 0010 = 1:4 0001 = 1:2 0000 = 1:1

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5.3 Single-Supply ICSP Programming

The LVP bit in Configuration register, CONFIG4L, enables Single-Supply (Low-Voltage) ICSP Programming. The LVP bit defaults to a '1' (enabled) from the factory.

If Single-Supply Programming mode is not used, the LVP bit can be programmed to a '0' and RB5/PGM becomes a digital I/O pin. However, the LVP bit may only be programmed by entering the High-Voltage ICSP mode, where MCLR/VPP/RE3 is raised to V_{IH} . Once the LVP bit is programmed to a '0', only the High-Voltage ICSP mode is available and only the High-Voltage ICSP mode can be used to program the device.

Note 1: The High-Voltage ICSP mode is always available, regardless of the state of the LVP bit, by applying V_{IH} to the MCLR/VPP/RE3 pin.

2: While in Low-Voltage ICSP mode, the RB5 pin can no longer be used as a general purpose I/O.

5.4 Embedding Configuration Word Information in the HEX File

To allow portability of code, a PIC18F2XK20/4XK20 programmer is required to read the Configuration Word locations from the hex file. If Configuration Word information is not present in the hex file, then a simple warning message should be issued. Similarly, while saving a hex file, all Configuration Word information must be included. An option to not include the Configuration Word information may be provided. When embedding Configuration Word information in the hex file, it should start at address 300000h.

Microchip Technology Inc. feels strongly that this feature is important for the benefit of the end customer.

5.5 Embedding Data EEPROM Information In the HEX File

To allow portability of code, a PIC18F2XK20/4XK20 programmer is required to read the data EEPROM information from the hex file. If data EEPROM information is not present, a simple warning message should be issued. Similarly, when saving a hex file, all data EEPROM information must be included. An option to not include the data EEPROM information may be provided. When embedding data EEPROM information in the hex file, it should start at address F00000h.

Microchip Technology Inc. believes that this feature is important for the benefit of the end customer.

5.6 Checksum Computation

The checksum is calculated by summing the following:

- The contents of all code memory locations
- The Configuration Word, appropriately masked
- ID locations (Only if any portion of program memory is code-protected)

The Least Significant 16 bits of this sum are the checksum.

Code protection limits access to program memory by both external programmer (code-protect) and code execution (table read protect). The ID locations, when included in a code protected checksum, contain the checksum of an unprotected part. The unprotected checksum is distributed: one nibble per ID location. Each nibble is right justified.

Table 5-4 describes how to calculate the checksum for each device.

Note: The checksum calculation differs depending on the code-protect setting. Since the code memory locations read out differently depending on the code-protect setting, the table describes how to manipulate the actual code memory values to simulate the values that would be read from a protected device. When calculating a checksum by reading a device, the entire code memory can simply be read and summed. The Configuration Word and ID locations can always be read.

PIC18F2XK20/4XK20

TABLE 5-4: CHECKSUM COMPUTATION

Device	Code-Protect	Checksum	Blank Value	0xAA at 0 and Max Address
PIC18FX3K20	None	SUM[0000:01FF]+SUM[0200:0FFF]+SUM[1000:1FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)	E33Eh	E294h
	Boot Block	SUM[0200:0FFF]+SUM[1000:1FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	E520h	E4C6h
	Boot/Block 0	SUM[1000:1FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	F31Fh	F2C5h
	All	(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	031Dh	0318h
PIC18FX4K20	None	SUM[0000:07FF]+SUM[0800:1FFF]+SUM[2000:3FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)	C33Eh	C294h
	Boot Block	SUM[0800:1FFF]+SUM[2000:3FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	CB1Eh	CAC4h
	Boot/Block 0	SUM[2000:3FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	E31Dh	E2C3h
	All	(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	031Bh	0316h

Legend:

<u>Item</u>	<u>Description</u>
CONFIGx	= Configuration Word
SUM[a:b]	= Sum of locations, a to b inclusive
SUM_ID	= Byte-wise sum of lower four bits of all customer ID locations
+	= Addition
&	= Bit-wise AND

PIC18F2XK20/4XK20

TABLE 5-4: CHECKSUM COMPUTATION (CONTINUED)

Device	Code-Protect	Checksum	Blank Value	0xAA at 0 and Max Address
PIC18FX6K20	None	SUM[0000:07FF]+SUM[0800:3FFF]+SUM[4000:7FFF]+SUM[8000:BFFF]+SUM[C000:FFFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 0Fh)+(CONFIG5H & C0h)+(CONFIG6L & 0Fh)+(CONFIG6H & E0h)+(CONFIG7L & 0Fh)+(CONFIG7H & 40h)	0362h	02B8h
	Boot Block	SUM[0800:3FFF]+SUM[4000:7FFF]+SUM[8000:BFFF]+SUM[C000:FFF F]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 0Fh)+(CONFIG5H & C0h)+(CONFIG6L & 0Fh)+(CONFIG6H & E0h)+(CONFIG7L & 0Fh)+(CONFIG7H & 40h)+SUM_ID	0B2Dh	0AE2h
	Boot/Block 0/Block 1	SUM[3000:BFFF]+SUM[C000:FFFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 0Fh)+(CONFIG5H & C0h)+(CONFIG6L & 0Fh)+(CONFIG6H & E0h)+(CONFIG7L & 0Fh)+(CONFIG7H & 40h)+SUM_ID	832Ah	82DFh
	All	(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 0Fh)+(CONFIG5H & C0h)+(CONFIG6L & 0Fh)+(CONFIG6H & E0h)+(CONFIG7L & 0Fh)+(CONFIG7H & 40h)+SUM_ID	031Eh	0328h

Legend: Item Description
 CONFIGx = Configuration Word
 SUM[a:b] = Sum of locations, a to b inclusive
 SUM_ID = Byte-wise sum of lower four bits of all customer ID locations
 + = Addition
 & = Bit-wise AND

PIC18F2XK20/4XK20

NOTES: