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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	35
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	3.8K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 14x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	40-UFQFN Exposed Pad
Supplier Device Package	40-UQFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f46k20-i-mv

FIGURE 2-1: 28-PIN SDIP, SSOP AND SOIC PIN DIAGRAMS

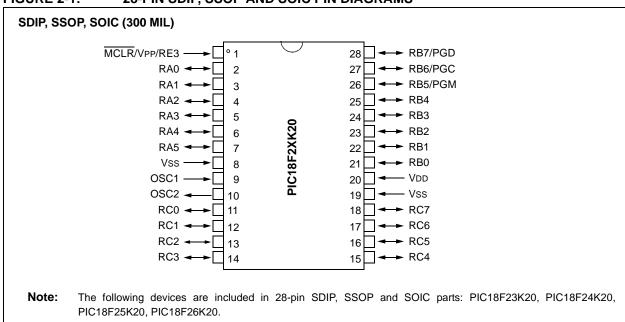
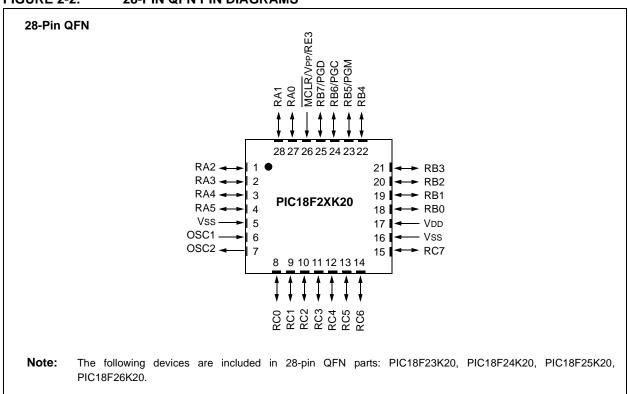


FIGURE 2-2: 28-PIN QFN PIN DIAGRAMS



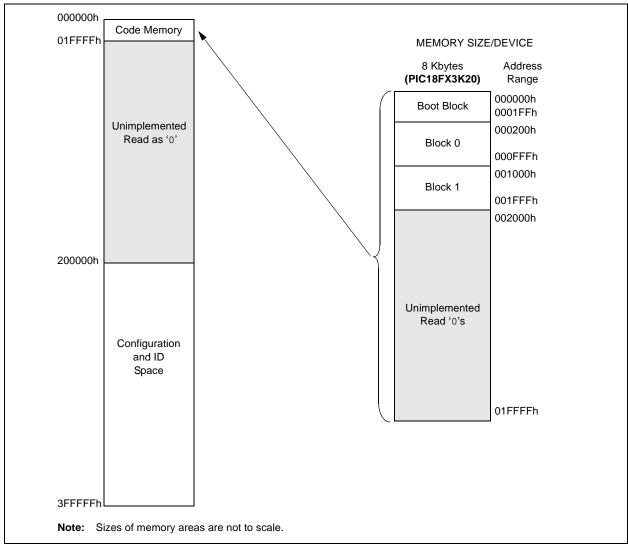
#### 2.3 Memory Maps

For the PIC18FX3K20 devices, the code memory space extends from 0000h to 01FFFh (8 Kbytes) in two 4-Kbyte blocks. Addresses 0000h through 01FFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

TABLE 2-2: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)	
PIC18F23K20	- 000000h-001FFFh (8K)	
PIC18F43K20		

FIGURE 2-6: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX3K20 DEVICES

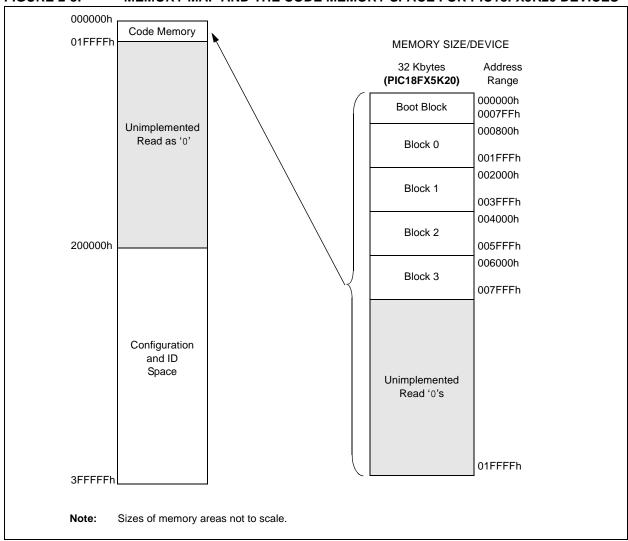


For PIC18FX5K20 devices, the code memory space extends from 000000h to 007FFFh (32 Kbytes) in four 8-Kbyte blocks. Addresses 000000h through 0007FFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

TABLE 2-4: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)	
PIC18F25K20	000000h 007EEEh (22K)	
PIC18F45K20	000000h-007FFFh (32K)	





In addition to the code memory space, there are three blocks in the configuration and ID space that are accessible to the user through table reads and table writes. Their locations in the memory map are shown in Figure 2-10.

Users may store identification information (ID) in eight ID registers. These ID registers are mapped in addresses 200000h through 200007h. The ID locations read out normally, even after code protection is applied.

Locations 300000h through 30000Dh are reserved for the Configuration bits. These bits select various device options and are described in **Section 5.0 "Configuration Word"**. These Configuration bits read out normally, even after code protection.

Locations 3FFFFEh and 3FFFFFh are reserved for the device ID bits. These bits may be used by the programmer to identify what device type is being programmed and are described in **Section 5.0 "Configuration Word"**. These device ID bits read out normally, even after code protection.

#### 2.3.1 MEMORY ADDRESS POINTER

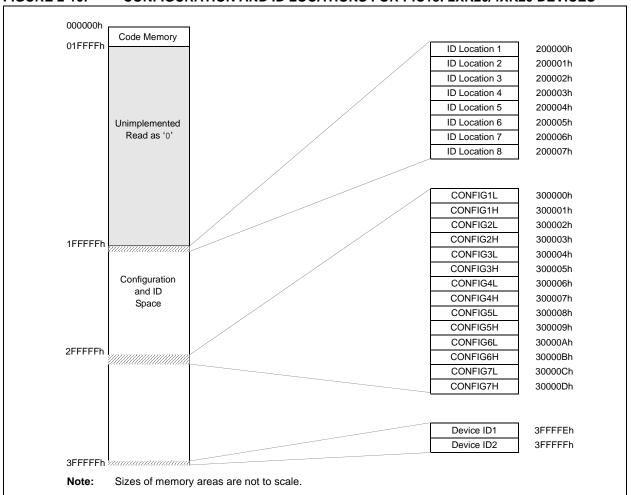
Memory in the address space, 0000000h to 3FFFFFh, is addressed via the Table Pointer register, which is comprised of three Pointer registers:

- · TBLPTRU, at RAM address 0FF8h
- · TBLPTRH, at RAM address 0FF7h
- · TBLPTRL, at RAM address 0FF6h

TBLPTRU	TBLPTRH	TBLPTRL
Addr[21:16]	Addr[15:8]	Addr[7:0]

The 4-bit command, '0000' (core instruction), is used to load the Table Pointer prior to using any read or write operations.

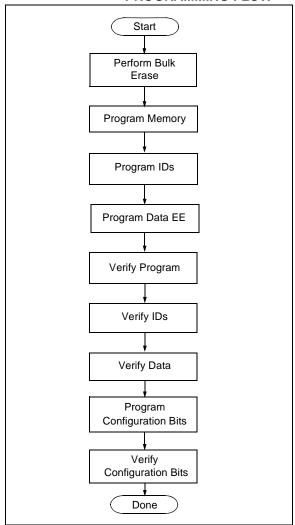
FIGURE 2-10: CONFIGURATION AND ID LOCATIONS FOR PIC18F2XK20/4XK20 DEVICES



#### 2.4 High-Level Overview of the Programming Process

Figure 2-11 shows the high-level overview of the programming process. First, a Bulk Erase is performed. Next, the code memory, ID locations and data EEPROM are programmed. These memories are then verified to ensure that programming was successful. If no errors are detected, the Configuration bits are then programmed and verified.

FIGURE 2-11: HIGH-LEVEL PROGRAMMING FLOW



# 2.5 Entering and Exiting High-Voltage ICSP Program/Verify Mode

As shown in Figure 2-12, the High-Voltage ICSP Program/Verify mode is entered by holding PGC and PGD low and then raising MCLR/VPP/RE3 to VIHH (high voltage). Once in this mode, the code memory, data EEPROM, ID locations and Configuration bits can be accessed and programmed in serial fashion. Figure 2-13 shows the exit sequence.

The sequence that enters the device into the Program/ Verify mode places all unused I/Os in the high-impedance state.

FIGURE 2-12: ENTERING HIGH-VOLTAGE PROGRAM/VERIFY MODE

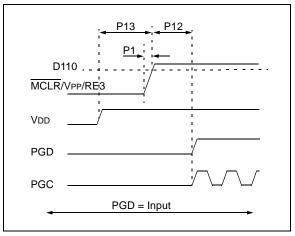
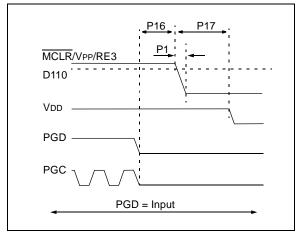


FIGURE 2-13: EXITING HIGH-VOLTAGE PROGRAM/VERIFY MODE



#### 3.0 DEVICE PROGRAMMING

Programming includes the ability to erase or write the various memory regions within the device.

In all cases, except high-voltage ICSP Bulk Erase, the EECON1 register must be configured in order to operate on a particular memory region.

When using the EECON1 register to act on code memory, the EEPGD bit must be set (EECON1<7>=1) and the CFGS bit must be cleared (EECON1<6>=0). The WREN bit must be set (EECON1<2>=1) to enable writes of any sort (e.g., erases) and this must be done prior to initiating a write sequence. The FREE bit must be set (EECON1<4>=1) in order to erase the program space being pointed to by the Table Pointer. The erase or write sequence is initiated by setting the WR bit (EECON1<1>=1). It is strongly recommended that the WREN bit only be set immediately prior to a program or erase.

#### 3.1 ICSP Erase

#### 3.1.1 HIGH-VOLTAGE ICSP BULK ERASE

Erasing code or data EEPROM is accomplished by configuring two Bulk Erase Control registers located at 3C0004h and 3C0005h. Code memory may be erased portions at a time, or the user may erase the entire device in one action. Bulk Erase operations will also clear any code-protect settings associated with the memory block erased. Erase options are detailed in Table 3-1. If data EEPROM is code-protected (CPD = 0), the user must request an erase of data EEPROM (e.g., 0084h as shown in Table 3-1).

TABLE 3-1: BULK ERASE OPTIONS

TABLE O 1. BOLK LIVIOL OF HORO				
Description	Data (3C0005h:3C0004h)			
Chip Erase	0F8Fh			
Erase User ID	0088h			
Erase Data EEPROM	0084h			
Erase Boot Block	0081h			
Erase Config Bits	0082h			
Erase Code EEPROM Block 0	0180h			
Erase Code EEPROM Block 1	0280h			
Erase Code EEPROM Block 2	0480h			
Erase Code EEPROM Block 3	0880h			

The actual Bulk Erase function is a self-timed operation. Once the erase has started (falling edge of the 4th PGC after the NOP command), serial execution will cease until the erase completes (parameter P11). During this time, PGC may continue to toggle but PGD must be held low.

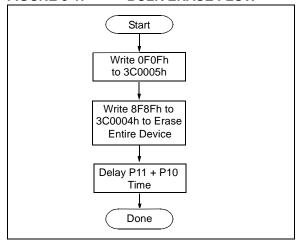
The code sequence to erase the entire device is shown in Table 3-2 and the flowchart is shown in Figure 3-1.

A Bulk Erase is the only way to reprogram code-protect bits from an "on" state to an "off" state.

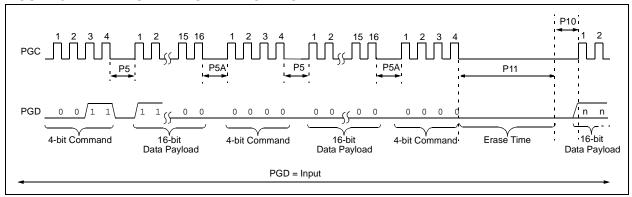
TABLE 3-2: BULK ERASE COMMAND SEQUENCE

4-Bit Command	Data Payload	Core Instruction
0000	0E 3C	MOVLW 3Ch
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPTRH
0000	0E 05	MOVLW 05h
0000	6E F6	MOVWF TBLPTRL
1100	0F 0F	Write OFh to 3C0005h
0000	0E 3C	MOVLW 3Ch
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPTRH
0000	0E 04	MOVLW 04h
0000	6E F6	MOVWF TBLPTRL
1100	8F 8F	Write 8F8Fh TO 3C0004h to erase entire device.
0000	00 00	NOP
0000	00 00	Hold PGD low until erase completes.

FIGURE 3-1: BULK ERASE FLOW



#### FIGURE 3-2: **BULK ERASE TIMING DIAGRAM**



#### LOW-VOLTAGE ICSP BULK ERASE 3.1.2

When using low-voltage ICSP, the part must be supplied by the voltage specified in parameter D111 if a Bulk Erase is to be executed. All other Bulk Erase details as described above apply.

If it is determined that a program memory erase must be performed at a supply voltage below the Bulk Erase limit, refer to the erase methodology described in Section 3.1.3 "ICSP Row Erase" and Section 3.2.1 "Modifying Code Memory".

If it is determined that a data EEPROM erase must be performed at a supply voltage below the Bulk Erase limit, follow the methodology described in Section 3.3 "Data EEPROM Programming" and write '1's to the array.

#### 3.1.3 **ICSP ROW ERASE**

Regardless of whether high or low-voltage ICSP is used, it is possible to erase one row (64 bytes of data), provided the block is not code or write-protected. Rows are located at static boundaries beginning at program memory address 000000h, extending to the internal program memory limit (see Section 2.3 "Memory Maps").

The Row Erase duration is self-timed. After the WR bit in EECON1 is set, two NOPs are issued. Erase starts upon the 4th PGC of the second NOP. It ends when the WR bit is cleared by hardware.

The code sequence to Row Erase a PIC18F2XK20/ 4XK20 device is shown in Table 3-3. The flowchart shown in Figure 3-3 depicts the logic necessary to completely erase a PIC18F2XK20/4XK20 device. The timing diagram for Row Erase is identical to the data EEPROM write timing shown in Figure 3-7.

Note: The TBLPTR register can point at any byte within the row intended for erase.

#### 3.2 Code Memory Programming

Programming code memory is accomplished by first loading data into the write buffer and then initiating a programming sequence. The write and erase buffer sizes shown in Table 3-4 can be mapped to any location of the same size beginning at 000000h. The actual memory write sequence takes the contents of this buffer and programs the proper amount of code memory that contains the Table Pointer.

The programming duration is externally timed and is controlled by PGC. After a Start Programming command is issued (4-bit command, '1111'), a  $\mathtt{NOP}$  is issued, where the 4th PGC is held high for the duration of the programming time, P9.

After PGC is brought low, the programming sequence is terminated. PGC must be held low for the time specified by parameter P10 to allow high-voltage discharge of the memory array.

The code sequence to program a PIC18F2XK20/4XK20 device is shown in Table 3-5. The flowchart shown in Figure 3-4 depicts the logic necessary to completely write a PIC18F2XK20/4XK20 device. The timing diagram that details the Start Programming command and parameters P9 and P10 is shown in Figure 3-5.

**Note:** The TBLPTR register must point to the same region when initiating the programming sequence as it did when the write buffers were loaded.

TABLE 3-4: WRITE AND ERASE BUFFER SIZES

Devices (Arranged by Family)	Write Buffer Size (bytes)	Erase Size (bytes)
PIC18F26K20, PIC18F46K20	64	64
PIC18F24K20, PIC18F25K20, PIC18F44K20, PIC18F45K20	32	64
PIC18F23K20, PIC18F43K20	16	64

TABLE 3-5: WRITE CODE MEMORY CODE SEQUENCE

4-bit Command	Data Payload	Core Instruction	
Step 1: Direct a	ccess to code memor	y.	
0000 0000 0000	8E A6 9C A6 84 A6	BSF EECON1, EEPGD BCF EECON1, CFGS BSF EECON1, WREN	
Step 2: Point to	row to write.		
0000 0000 0000 0000 0000	0E <addr[21:16]> 6E F8 0E <addr[15:8]> 6E F7 0E <addr[7:0]> 6E F6</addr[7:0]></addr[15:8]></addr[21:16]>	MOVLW <addr[21:16]> MOVWF TBLPTRU MOVLW <addr[15:8]> MOVWF TBLPTRH MOVLW <addr[7:0]> MOVWF TBLPTRL</addr[7:0]></addr[15:8]></addr[21:16]>	
Step 3: Load wr	Step 3: Load write buffer. Repeat for all but the last two bytes.		
1101	<msb><lsb></lsb></msb>	Write 2 bytes and post-increment address by 2.	
Step 4: Load wr	Step 4: Load write buffer for last two bytes and start programming.		
1111 0000	<msb><lsb> 00 00</lsb></msb>	Write 2 bytes and start programming. NOP - hold PGC high for time P9 and low for time P10.	
To continue writing data, repeat steps 2 through 4, where the Address Pointer is incremented by 2 at each iteration o the loop.			

#### 3.2.1 MODIFYING CODE MEMORY

The previous programming example assumed that the device has been Bulk Erased prior to programming (see **Section 3.1.1** "**High-Voltage ICSP Bulk Erase**"). It may be the case, however, that the user wishes to modify only a section of an already programmed device.

The appropriate number of bytes required for the erase buffer must be read out of code memory (as described in **Section 4.2 "Verify Code Memory and ID Locations"**) and buffered. Modifications can be made on this buffer. Then, the block of code memory that was read out must be erased and rewritten with the modified data.

The WREN bit must be set if the WR bit in EECON1 is used to initiate a write sequence.

TABLE 3-6: MODIFYING CODE MEMORY

TABLE 3-6:	MODIFYING CODE	MEMORY
4-bit Command	Data Payload	Core Instruction
Step 1: Direct acc	cess to code memory.	
0000	8E A6	BSF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
Step 2: Read cod	e memory into buffer (Section	on 4.1 "Read Code Memory, ID Locations and Configuration Bits").
Step 3: Set the Ta	able Pointer for the block to I	be erased.
0000	0E <addr[21:16]></addr[21:16]>	MOVLW <addr[21:16]></addr[21:16]>
0000	6E F8	MOVWF TBLPTRU
0000	0E <addr[8:15]></addr[8:15]>	MOVLW <addr[8:15]></addr[8:15]>
0000	6E F7	MOVWF TBLPTRH
0000	0E <addr[7:0]></addr[7:0]>	MOVLW <addr[7:0]></addr[7:0]>
0000	6E F6	MOVWF TBLPTRL
Step 4: Enable m	emory writes and setup an e	prase.
0000	84 A6	BSF EECON1, WREN
0000	88 A6	BSF EECON1, FREE
Step 5: Initiate era	ase.	
0000	88 A6	BSF EECON1, FREE
0000	82 A6	BSF EECON1, WR
0000	00 00	NOP
0000	00 00	NOP Erase starts on the 4th clock of this instruction
Step 6: Poll WR b	oit. Repeat until bit is clear.	
0000	50 A6	MOVF EECON1, W, 0
0000	6E F5	MOVWF TABLAT
0000	00 00	NOP
0000	<msb><lsb></lsb></msb>	Shift out data <sup>(1)</sup>
Step 7: Load write	e buffer. The correct bytes w	rill be selected based on the Table Pointer.
0000	0E <addr[21:16]></addr[21:16]>	MOVLW <addr[21:16]></addr[21:16]>
0000	6E F8	MOVWF TBLPTRU
0000	0E <addr[8:15]></addr[8:15]>	MOVLW <addr[8:15]></addr[8:15]>
0000	6E F7	MOVWF TBLPTRH
0000	0E <addr[7:0]></addr[7:0]>	MOVLW <addr[7:0]></addr[7:0]>
0000	6E F6	MOVWF TBLPTRL
1101	<msb><lsb></lsb></msb>	Write 2 bytes and post-increment address by 2.
•	•	
•	•	Repeat as many times as necessary to fill the write buffer
•	•	Write 2 bytes and start programming.
1111	<msb><lsb></lsb></msb>	NOP - hold PGC high for time P9 and low for time P10.
0000	00 00	
To continue modif	fying data, reneat Stens 2 th	rough 6, where the Address Pointer is incremented by the appropriate number of bytes

To continue modifying data, repeat Steps 2 through 6, where the Address Pointer is incremented by the appropriate number of bytes (see Table 3-4) at each iteration of the loop. The write cycle must be repeated enough times to completely rewrite the contents of the erase buffer.

0.000 00	0.000 0.000			
Step 8: Disable writes.				
0000	94 A6	BCF	EECON1, WREN	

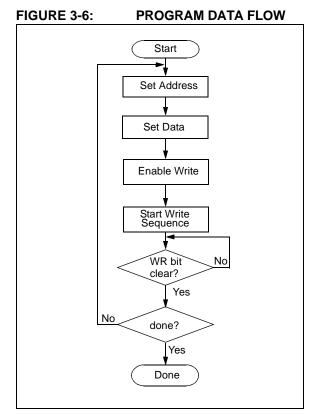
#### 3.3 Data EEPROM Programming

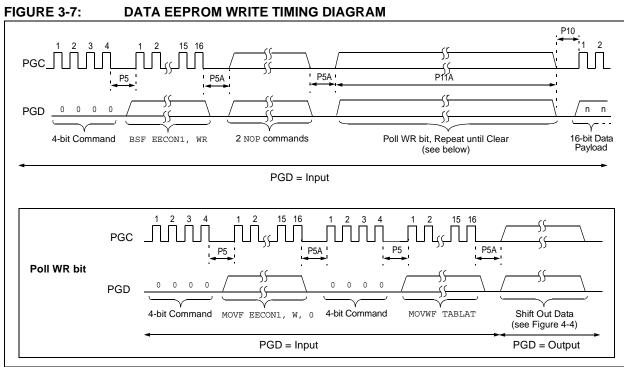
Data EEPROM is accessed one byte at a time via an Address Pointer (register pair EEADRH:EEADR) and a data latch (EEDATA). Data EEPROM is written by loading EEADRH:EEADR with the desired memory location, EEDATA with the data to be written and initiating a memory write by appropriately configuring the EECON1 register. A byte write automatically erases the location and writes the new data (erase-before-write).

When using the EECON1 register to perform a data EEPROM write, both the EEPGD and CFGS bits must be cleared (EECON1<7:6> = 00). The WREN bit must be set (EECON1<2> = 1) to enable writes of any sort and this must be done prior to initiating a write sequence. The write sequence is initiated by setting the WR bit (EECON1<1> = 1).

The write begins on the falling edge of the 24th PGC after the WR bit is set. It ends when the WR bit is cleared by hardware.

After the programming sequence terminates, PGC must be held low for the time specified by parameter P10 to allow high-voltage discharge of the memory array.





#### 4.0 READING THE DEVICE

# 4.1 Read Code Memory, ID Locations and Configuration Bits

Code memory is accessed one byte at a time via the 4-bit command, '1001' (table read, post-increment). The contents of memory pointed to by the Table Pointer (TBLPTRU:TBLPTRH:TBLPTRL) are serially output on PGD.

The 4-bit command is shifted in LSb first. The read is executed during the next 8 clocks, then shifted out on PGD during the last 8 clocks, LSb to MSb. A delay of P6 must be introduced after the falling edge of the 8th

PGC of the operand to allow PGD to transition from an input to an output. During this time, PGC must be held low (see Figure 4-1). This operation also increments the Table Pointer by one, pointing to the next byte in code memory for the next read.

This technique will work to read any memory in the 000000h to 3FFFFFh address space, so it also applies to the reading of the ID and Configuration registers.

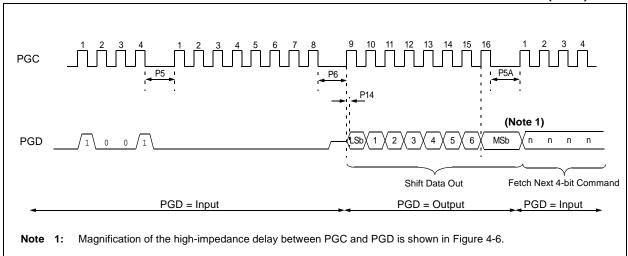
When table read protection is enabled, the first read access to a protected block should be discarded and the read repeated to retrieve valid data. Subsequent reads of the same block can be performed normally.

TABLE 4-1: READ CODE MEMORY SEQUENCE

4-bit Command	Data Payload	Core Instruction		
Step 1: Set Tabl	e Pointer			
0000	0E <addr[21:16]></addr[21:16]>	MOVLW Addr[21:16]		
0000	6E F8	MOVWF TBLPTRU		
0000	0E <addr[15:8]></addr[15:8]>	MOVLW <addr[15:8]></addr[15:8]>		
0000	6E F7	MOVWF TBLPTRH		
0000	0E <addr[7:0]></addr[7:0]>	MOVLW <addr[7:0]></addr[7:0]>		
0000	6E F6	MOVWF TBLPTRL		
Step 2: Read m	Step 2: Read memory and then shift out on PGD, LSb to MSb			
1001	00 00	TBLRD *+		

Note:

### FIGURE 4-1: TABLE READ POST-INCREMENT INSTRUCTION TIMING DIAGRAM (1001)

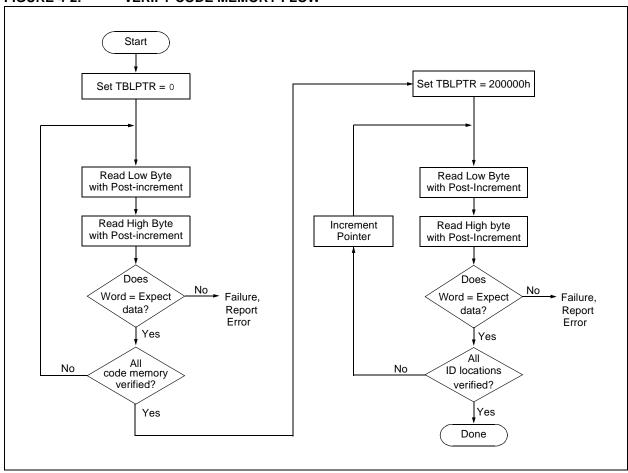


#### 4.2 Verify Code Memory and ID Locations

The verify step involves reading back the code memory space and comparing it against the copy held in the programmer's buffer. Memory reads occur a single byte at a time, so two bytes must be read to compare against the word in the programmer's buffer. Refer to Section 4.1 "Read Code Memory, ID Locations and Configuration Bits" for implementation details of reading code memory.

The Table Pointer must be manually set to 200000h (base address of the ID locations) once the code memory has been verified. The post-increment feature of the table read 4-bit command can not be used to increment the Table Pointer beyond the code memory space. In a 64-Kbyte device, for example, a post-increment read of address FFFFh will wrap the Table Pointer back to 000000h, rather than point to unimplemented address 010000h.

FIGURE 4-2: VERIFY CODE MEMORY FLOW



#### 4.3 Verify Configuration Bits

A configuration address may be read and output on PGD via the 4-bit command, '1001'. Configuration data is read and written in a byte-wise fashion, so it is not necessary to merge two bytes into a word prior to a compare. The result may then be immediately compared to the appropriate configuration data in the programmer's memory for verification. Refer to Section 4.1 "Read Code Memory, ID Locations and Configuration Bits" for implementation details of reading configuration data.

#### 4.4 Read Data EEPROM Memory

Data EEPROM is accessed one byte at a time via an Address Pointer (register pair EEADRH:EEADR) and a data latch (EEDATA). Data EEPROM is read by loading EEADRH:EEADR with the desired memory location and initiating a memory read by appropriately configuring the EECON1 register. The data will be loaded into EEDATA, where it may be serially output on PGD via the 4-bit command, '0010' (Shift Out Data Holding register). A delay of P6 must be introduced after the falling edge of the 8th PGC of the operand to allow PGD to transition from an input to an output. During this time, PGC must be held low (see Figure 4-4).

The command sequence to read a single byte of data is shown in Table 4-2.

FIGURE 4-3: READ DATA EEPROM FLOW

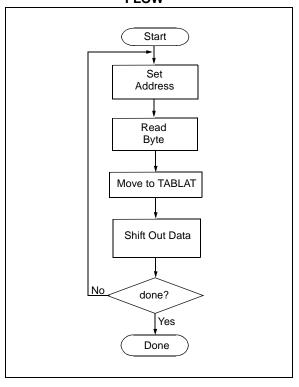


TABLE 4-2: READ DATA EEPROM MEMORY

4-bit Command	Data Payload	Core Instruction
Step 1: Direct acc	ess to data EEPROM.	
0000	9E A6	BCF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
Step 2: Set the da	ta EEPROM Address Point	er.
0000	0E <addr></addr>	MOVLW <addr></addr>
0000	6E A9	MOVWF EEADR
0000	OE <addrh></addrh>	MOVLW <addrh></addrh>
0000	6E AA	MOVWF EEADRH
Step 3: Initiate a memory read.		
0000	80 A6	BSF EECON1, RD
Step 4: Load data into the Serial Data Holding register.		
0000	50 A8	MOVF EEDATA, W, O
0000	6E F5	MOVWF TABLAT
0000	00 00	NOP
0010	<msb><lsb></lsb></msb>	Shift Out Data <sup>(1)</sup>

Note 1: The <LSB> is undefined. The <MSB> is the data.

TABLE 5-2: DEVICE ID VALUE

Device	Device ID Value			
Device	DEVID2	DEVID1		
PIC18F23K20	20h	111x xxxx		
PIC18F24K20	20h	101x xxxx		
PIC18F25K20	20h	011x xxxx		
PIC18F26K20	20h	001x xxxx		
PIC18F43K20	20h	110x xxxx		
PIC18F44K20	20h	100x xxxx		
PIC18F45K20	20h	010x xxxx		
PIC18F46K20	20h	000x xxxx		

**Note:** The 'x's in DEVID1 contain the device revision code.

TABLE 5-3: PIC18F2XK20/4XK20 BIT DESCRIPTIONS

Bit Name	Configuration Words	Description
IESO	CONFIG1H	Internal External Switchover bit  1 = Internal External Switchover mode enabled  0 = Internal External Switchover mode disabled
FCMEN	CONFIG1H	Fail-Safe Clock Monitor Enable bit  1 = Fail-Safe Clock Monitor enabled  0 = Fail-Safe Clock Monitor disabled
FOSC<3:0>	CONFIG1H	Oscillator Selection bits  11xx = External RC oscillator, CLKOUT function on RA6  101x = External RC oscillator, CLKOUT function on RA6  1001 = HFINTOSC, CLKOUT function on RA6, port function on RA7  1000 = HFINTOSC, port function on RA6, port function on RA7  0111 = External RC oscillator, port function on RA6  0110 = HS oscillator, PLL enabled (clock frequency = 4 x FOSC1)  0101 = EC oscillator, port function on RA6  0100 = EC oscillator, CLKOUT function on RA6  0011 = External RC oscillator, CLKOUT function on RA6  0010 = HS oscillator  0001 = XT oscillator  0000 = LP oscillator
BORV<1:0>	CONFIG2L	Brown-out Reset Voltage bits  11 = VBOR set to 1.8V  10 = VBOR set to 2.2V  01 = VBOR set to 2.7V  00 = VBOR set to 3.0V
BOREN<1:0>	CONFIG2L	Brown-out Reset Enable bits  11 = Brown-out Reset enabled in hardware only (SBOREN is disabled)  10 = Brown-out Reset enabled in hardware only and disabled in Sleep mode (SBOREN is disabled)  01 = Brown-out Reset enabled and controlled by software (SBOREN is enabled)  00 = Brown-out Reset disabled in hardware and software
PWRTEN	CONFIG2L	Power-up Timer Enable bit  1 = PWRT disabled  0 = PWRT enabled
WDPS<3:0>	CONFIG2H	Watchdog Timer Postscaler Select bits  1111 = 1:32,768  1110 = 1:16,384  1101 = 1:8,192  1100 = 1:4,096  1011 = 1:2,048  1010 = 1:512  1000 = 1:256  0111 = 1:128  0110 = 1:64  0101 = 1:32  0100 = 1:16  0011 = 1:8  0010 = 1:4  0001 = 1:2  0000 = 1:1

.

PIC18F2XK20/4XK20 BIT DESCRIPTIONS (CONTINUED) **TABLE 5-3:** 

Bit Name	Configuration Words	Description
CP3	CONFIG5L	Code Protection bits (Block 3 code memory area)  1 = Block 3 is not code-protected  0 = Block 3 is code-protected
CP2	CONFIG5L	Code Protection bits (Block 2 code memory area)  1 = Block 2 is not code-protected  0 = Block 2 is code-protected
CP1	CONFIG5L	Code Protection bits (Block 1 code memory area)  1 = Block 1 is not code-protected  0 = Block 1 is code-protected
CP0	CONFIG5L	Code Protection bits (Block 0 code memory area)  1 = Block 0 is not code-protected  0 = Block 0 is code-protected
CPD	CONFIG5H	Code Protection bits (Data EEPROM)  1 = Data EEPROM is not code-protected  0 = Data EEPROM is code-protected
СРВ	CONFIG5H	Code Protection bits (Boot Block memory area)  1 = Boot Block is not code-protected  0 = Boot Block is code-protected
WRT3	CONFIG6L	Write Protection bits (Block 3 code memory area)  1 = Block 3 is not write-protected  0 = Block 3 is write-protected
WRT2	CONFIG6L	Write Protection bits (Block 2 code memory area)  1 = Block 2 is not write-protected  0 = Block 2 is write-protected
WRT1	CONFIG6L	Write Protection bits (Block 1 code memory area)  1 = Block 1 is not write-protected  0 = Block 1 is write-protected
WRT0	CONFIG6L	Write Protection bits (Block 0 code memory area)  1 = Block 0 is not write-protected  0 = Block 0 is write-protected
WRTD	CONFIG6H	Write Protection bit (Data EEPROM)  1 = Data EEPROM is not write-protected  0 = Data EEPROM is write-protected
WRTB	CONFIG6H	Write Protection bit (Boot Block memory area)  1 = Boot Block is not write-protected  0 = Boot Block is write-protected
WRTC	CONFIG6H	Write Protection bit (Configuration registers)  1 = Configuration registers are not write-protected  0 = Configuration registers are write-protected

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TABLE 5-4: CHECKSUM COMPUTATION

Device	Code- Protect	Checksum	Blank Value	0xAA at 0 and Max Address
	None	SUM[0000:01FF]+SUM[0200:0FFF]+SUM[1000:1FFF]+ (CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+ (CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+ (CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+ (CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+ (CONFIG7L & 03h)+(CONFIG7H & 40h)	E33Eh	E294h
PIC18FX3K20	Boot Block	SUM[0200:0FFF]+SUM[1000:1FFF]+(CONFIG1L & 00h)+ (CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+ (CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+ (CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+ (CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+ (CONFIG7H & 40h)+SUM_ID	E520h	E4C6h
	Boot/ Block 0	SUM[1000:1FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+ (CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+ (CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+ (CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+ (CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	F31Fh	F2C5h
	All	(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+ (CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+ (CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+ (CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+ (CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	031Dh	0318h
	None	SUM[0000:07FF]+SUM[0800:1FFF]+SUM[2000:3FFF]+ (CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+ (CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+ (CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+ (CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+ (CONFIG7L & 03h)+(CONFIG7H & 40h)	C33Eh	C294h
PIC18FX4K20	Boot Block	SUM[0800:1FFF]+SUM[2000:3FFF]+(CONFIG1L & 00h)+ (CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+ (CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+ (CONFIG4H & 00h)+(CONFIG5L & 03h)+(CONFIG5H & C0h)+ (CONFIG6L & 03h)+(CONFIG6H & E0h)+(CONFIG7L & 03h)+ (CONFIG7H & 40h)+SUM_ID	CB1Eh	CAC4h
	Boot/ Block 0	SUM[2000:3FFF]+(CONFIG1L & 00h)+(CONFIG1H & CFh)+ (CONFIG2L & 1Fh)+(CONFIG2H & 1F)+(CONFIG3L & 00h)+ (CONFIG3H & 8Fh)+(CONFIG4L & C5h)+(CONFIG4H & 00h)+ (CONFIG5L & 03h)+(CONFIG5H & C0h)+(CONFIG6L & 03h)+ (CONFIG6H & E0h)+(CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	E31Dh	E2C3h
Legend: Item	All	(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+ (CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+ (CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 03h)+ (CONFIG5H & C0h)+(CONFIG6L & 03h)+(CONFIG6H & E0h)+ (CONFIG7L & 03h)+(CONFIG7H & 40h)+SUM_ID	031Bh	0316h

Legend: <u>Item</u> <u>Description</u>

CONFIGx = Configuration Word

SUM[a:b] = Sum of locations, a to b inclusive

SUM\_ID = Byte-wise sum of lower four bits of all customer ID locations

+ = Addition & = Bit-wise AND

TABLE 5-4: CHECKSUM COMPUTATION (CONTINUED)

Device	Code- Protect	Checksum	Blank Value	0xAA at 0 and Max Address
PIC18FX5K20	None	SUM[0000:07FF]+SUM[0800:1FFF]+SUM[2000:3FFF]+ SUM[4000:5FFF]+SUM[6000:7FFF]+(CONFIG1L & 00h)+ (CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+ (CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+ (CONFIG4H & 00h)+(CONFIG5L & 0Fh)+(CONFIG5H & C0h)+ (CONFIG6L & 0Fh)+(CONFIG6H & E0h)+(CONFIG7L & 0Fh)+ (CONFIG7H & 40h)	8362h	82B8h
	Boot Block	SUM[0800:1FFF]+SUM[2000:3FFF]+SUM[4000:5FFF]+SUM[6000:7FFF]+SUM[0800:1FFF]+SUM[6000:7FFF]+SUM[0800:1FFF]+SUM[0800:3FFF]+SUM[4000:5FFF]+SUM[6000:7FFF]+SUM[0800:1FFF]+SUM[08	8B35h	8AEAh
	Boot/ Block 0/ Block 1	SUM[4000:5FFF]+SUM[6000:7FFF]+(CONFIG1L & 00h)+ (CONFIG1H & CFh)+(CONFIG2L & 1Fh)+(CONFIG2H & 1F)+ (CONFIG3L & 00h)+(CONFIG3H & 8Fh)+(CONFIG4L & C5h)+ (CONFIG4H & 00h)+(CONFIG5L & 0Fh)+(CONFIG5H & C0h)+ (CONFIG6L & 0Fh)+(CONFIG6H & E0h)+(CONFIG7L & 0Fh)+ (CONFIG7H & 40h)+SUM_ID		C2E7h
	All	(CONFIG1L & 00h)+(CONFIG1H & CFh)+(CONFIG2L & 1Fh)+ (CONFIG2H & 1F)+(CONFIG3L & 00h)+(CONFIG3H & 8Fh)+ (CONFIG4L & C5h)+(CONFIG4H & 00h)+(CONFIG5L & 0Fh)+ (CONFIG5H & C0h)+(CONFIG6L & 0Fh)+(CONFIG6H & E0h)+ (CONFIG7L & 0Fh)+(CONFIG7H & 40h)+SUM_ID	0326h	0330h

 Legend:
 Item
 Description

CONFIGx = Configuration Word

SUM[a:b] = Sum of locations, a to b inclusive

SUM\_ID = Byte-wise sum of lower four bits of all customer ID locations

+ = Addition & = Bit-wise AND

### 6.0 AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/ VERIFY TEST MODE

**Standard Operating Conditions** 

Operating Temperature: 25°C is recommended

Operating Temperature: 25°C is recommended						
Param No.	Sym.	Characteristic	Min.	Max.	Units	Conditions
D110	VIHH	High-Voltage Programming Voltage on MCLR/VPP/RE3	VDD + 4.5	9	V	
D110A	VIHL	Low-Voltage Programming Voltage on MCLR/VPP/RE3	1.80	3.60	V	
D111	Vdd	Supply Voltage During Programming	1.80	3.60	V	Row Erase/Write
			2.7	3.60	V	Bulk Erase operations
D112	IPP	Programming Current on MCLR/VPP/RE3	_	300	μΑ	
D113	IDDP	Supply Current During Programming	_	10	mA	
D031	VIL	Input Low Voltage	Vss	0.2 VDD	V	
D041	ViH	Input High Voltage	0.8 VDD	Vdd	V	
D080	Vol	Output Low Voltage	_	0.6	V	IOL = X.X mA @ 2.7V
D090	Vон	Output High Voltage	VDD - 0.7	_	V	IOH = -Y.Y mA @ 2.7V
D012	Сю	Capacitive Loading on I/O pin (PGD)	_	50	pF	To meet AC specifications
P1	TR	MCLR/VPP/RE3 Rise Time to enter Program/Verify mode	_	1.0	μS	(Note 1)
P2	TPGC	Serial Clock (PGC) Period	100		ns	VDD = 3.6V
			1	_	μS	VDD = 1.8V
P2A	TPGCL	Serial Clock (PGC) Low Time	40	_	ns	VDD = 3.6V
			400	_	ns	VDD = 1.8V
P2B	TPGCH	Serial Clock (PGC) High Time	40	_	ns	VDD = 3.6V
			400	_	ns	VDD = 1.8V
P3	TSET1	Input Data Setup Time to Serial Clock ↓	15	_	ns	
P4	THLD1	Input Data Hold Time from PGC $\downarrow$	15	_	ns	
P5	TDLY1	Delay between 4-bit Command and Command Operand	40	_	ns	
P5A	TDLY1A	Delay between 4-bit Command Operand and next 4-bit Command	40	_	ns	
P6	TDLY2	Delay between Last PGC ↓ of Command Byte to First PGC ↑ of Read of Data Word	20	_	ns	
P9	TDLY5	PGC High Time (minimum programming time)	1	_	ms	Externally Timed
P9A	TDLY5A	PGC High Time	5		ms	Configuration Word programming time
P10	TDLY6	PGC Low Time after Programming (high-voltage discharge time)	200	_	μS	
P11	TDLY7	Delay to allow Self-Timed Data Write or Bulk Erase to occur	5	_	ms	
P11A	TDRWT	Data Write Polling Time	4	_	ms	
			•	•		

**Note 1:** Do not allow excess time when transitioning MCLR between VIL and VIHH; this can cause spurious program executions to occur. The maximum transition time is:

<sup>1</sup> TCY + TPWRT (if enabled) + 1024 ToSC (for LP, HS, HS/PLL and XT modes only) + 2 ms (for HS/PLL mode only) + 1.5  $\mu$ s (for EC mode only) where TCY is the instruction cycle time, TPWRT is the Power-up Timer period and ToSC is the oscillator period. For specific values, refer to the Electrical Characteristics section of the device data sheet for the particular device.



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