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### Embedded - Microcontrollers - Application Specific: Tailored Solutions for Precision and Performance

Embedded - Microcontrollers - Application Specific represents a category of microcontrollers designed with unique features and capabilities tailored to specific application needs. Unlike general-purpose microcontrollers, application-specific microcontrollers are optimized for particular tasks, offering enhanced performance, efficiency, and functionality to meet the demands of specialized applications.

### What Are Embedded - Microcontrollers - Application Specific?

Application specific microcontrollers are engineered to

#### Details

Product Status	Obsolete
Applications	Capacitive Sensing
Core Processor	M8C
Program Memory Type	FLASH (16kB)
Controller Series	CY8C20xx6
RAM Size	2K x 8
Interface	I <sup>2</sup> C, SPI
Number of I/O	28
Voltage - Supply	1.71V ~ 5.5V
Operating Temperature	-40°C ~ 85°C
Mounting Type	Surface Mount
Package / Case	32-UFQFN Exposed Pad
Supplier Device Package	32-QFN (5x5)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/cy8c20446h-24lqxi">https://www.e-xfl.com/product-detail/infineon-technologies/cy8c20446h-24lqxi</a>

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## Additional System Resources

System resources provide additional capability, such as configurable USB and I<sup>2</sup>C slave, SPI master/slave communication interface, three 16-bit programmable timers, and various system resets supported by the M8C.

These system resources provide additional capability useful to complete systems. Additional resources include low voltage detection and power on reset. The merits of each system resource are listed here:

- The I<sup>2</sup>C slave/SPI master-slave module provides 50/100/400 kHz communication over two wires. SPI communication over three or four wires runs at speeds of 46.9 kHz to 3 MHz (lower for a slower system clock).
- The I<sup>2</sup>C hardware address recognition feature reduces the already low power consumption by eliminating the need for CPU intervention until a packet addressed to the target device is received.
- The I<sup>2</sup>C enhanced slave interface appears as a 32-byte RAM buffer to the external I<sup>2</sup>C master. Using a simple predefined protocol, the master controls the read and write pointers into the RAM. When this method is enabled, the slave does not stall the bus when receiving data bytes in active mode. For usage details, refer to the application note [I2C Enhanced Slave Operation - AN56007](#).
- Low voltage detection (LVD) interrupts can signal the application of falling voltage levels, while the advanced power-on-reset (POR) circuit eliminates the need for a system supervisor.
- An internal reference provides an absolute reference for capacitive sensing.
- A register-controlled bypass mode allows the user to disable the LDO regulator.

## Getting Started

For in depth information, along with detailed programming details, see the PSoC® [Technical Reference Manual](#).

For up-to-date ordering, packaging, and electrical specification information, see the latest [PSoC device datasheets](#) on the web.

## Application Notes

[Cypress application notes](#) are an excellent introduction to the wide variety of possible PSoC designs.

## Development Kits

[PSoC Development Kits](#) are available online from and through a growing number of regional and global distributors, which include Arrow, Avnet, Digi-Key, Farnell, Future Electronics, and Newark.

## Training

[Free PSoC technical training](#) (on demand, webinars, and workshops), which is available online via [www.cypress.com](http://www.cypress.com), covers a wide variety of topics and skill levels to assist you in your designs.

## CYPros Consultants

Certified PSoC consultants offer everything from technical assistance to completed PSoC designs. To contact or become a PSoC consultant go to the [CYPros Consultants](#) web site.

## Solutions Library

Visit our growing [library of solution focused designs](#). Here you can find various application designs that include firmware and hardware design files that enable you to complete your designs quickly.

## Technical Support

[Technical support](#) – including a searchable Knowledge Base articles and technical forums – is also available online. If you cannot find an answer to your question, call our Technical Support hotline at 1-800-541-4736.

## Designing with PSoC Designer

The development process for the PSoC device differs from that of a traditional fixed-function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and lowering inventory costs. These configurable resources, called PSoC blocks, have the ability to implement a wide variety of user-selectable functions. The PSoC development process is:

1. Select [user modules](#).
2. Configure user modules.
3. Organize and connect.
4. Generate, verify, and debug.

### Select User Modules

PSoC Designer provides a library of prebuilt, pretested hardware peripheral components called “user modules.” User modules make selecting and implementing peripheral devices, both analog and digital, simple.

### Configure User Modules

Each user module that you select establishes the basic register settings that implement the selected function. They also provide parameters and properties that allow you to tailor their precise configuration to your particular application. For example, a PWM User Module configures one or more digital PSoC blocks, one for each eight bits of resolution. Using these parameters, you can establish the pulse width and duty cycle. Configure the parameters and properties to correspond to your chosen application. Enter values directly or by selecting values from drop-down menus. All of the user modules are documented in datasheets that may be viewed directly in PSoC Designer or on the Cypress website. These [user module datasheets](#) explain the internal operation of the user module and provide performance specifications. Each datasheet describes the use of each user module parameter, and other information that you may need to successfully implement your design.

## Organize and Connect

Build signal chains at the chip level by interconnecting user modules to each other and the I/O pins. Perform the selection, configuration, and routing so that you have complete control over all on-chip resources.

## Generate, Verify, and Debug

When you are ready to test the hardware configuration or move on to developing code for the project, perform the “Generate Configuration Files” step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the software for the system. The generated code provides APIs with high-level functions to control and respond to hardware events at run time, and interrupt service routines that you can adapt as needed.

A complete code development environment lets you to develop and customize your applications in C, assembly language, or both.

The last step in the development process takes place inside PSoC Designer's Debugger (accessed by clicking the Connect icon). PSoC Designer downloads the HEX image to the ICE where it runs at full-speed. PSoC Designer debugging capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint, and watch-variable features, the debug interface provides a large trace buffer. It lets you to define complex breakpoint events that include monitoring address and data bus values, memory locations, and external signals.

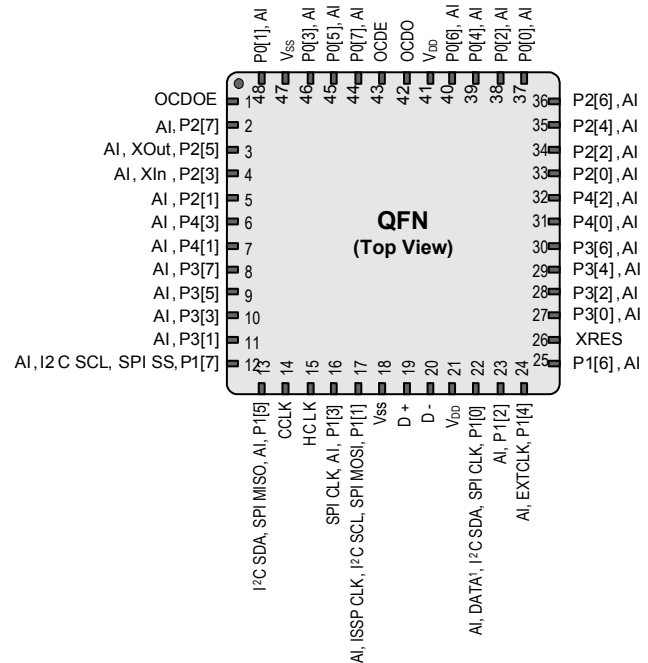
## 48-Pin QFN OCD

The 48-pin QFN part is for the CY8C20066A On-Chip Debug (OCD) PSoC device. Note that this part is only used for in-circuit debugging.<sup>[9]</sup>

**Table 3. Pin Definitions - CY8C20066A PSoC Device** <sup>[10, 11]</sup>

Pin No.	Digital	Analog	Name	Description
1			OCDOE	OCD mode direction pin
2	I/O	I	P2[7]	
3	I/O	I	P2[5]	Crystal output (XOut)
4	I/O	I	P2[3]	Crystal input (XIn)
5	I/O	I	P2[1]	
6	I/O	I	P4[3]	
7	I/O	I	P4[1]	
8	I/O	I	P3[7]	
9	I/O	I	P3[5]	
10	I/O	I	P3[3]	
11	I/O	I	P3[1]	
12	IOHR	I	P1[7]	I <sup>2</sup> C SCL, SPI SS
13	IOHR	I	P1[5]	I <sup>2</sup> C SDA, SPI MISO
14			CCLK	OCD CPU clock output
15			HCLK	OCD high speed clock output
16	IOHR	I	P1[3]	SPI CLK.
17	IOHR	I	P1[1]	ISSP CLK <sup>[12]</sup> , I <sup>2</sup> C SCL, SPI MOSI
18	Power		Vss	Ground connection
19	I/O		D+	USB D+
20	I/O		D-	USB D-
21	Power		V <sub>DD</sub>	Supply voltage
22	IOHR	I	P1[0]	ISSP DATA <sup>[12]</sup> , I <sup>2</sup> C SDA, SPI CLK
23	IOHR	I	P1[2]	
24	IOHR	I	P1[4]	Optional external clock input (EXTCLK)
25	IOHR	I	P1[6]	
26	Input		XRES	Active high external reset with internal pull down
27	I/O	I	P3[0]	
28	I/O	I	P3[2]	
29	I/O	I	P3[4]	
30	I/O	I	P3[6]	
31	I/O	I	P4[0]	
32	I/O	I	P4[2]	
33	I/O	I	P2[0]	
34	I/O	I	P2[2]	
35	I/O	I	P2[4]	
36	I/O	I	P2[6]	

**Figure 4. CY8C20066A PSoC Device**



Pin No.	Digital	Analog	Name	Description
37	IOH	I	P0[0]	
38	IOH	I	P0[2]	
39	IOH	I	P0[4]	
40	IOH	I	P0[6]	
41	Power		V <sub>DD</sub>	Supply voltage
42			OCDO	OCD even data I/O
43			OCDE	OCD odd data output
44	IOH	I	P0[7]	
45	IOH	I	P0[5]	
46	IOH	I	P0[3]	Integrating input
47	Power		V <sub>SS</sub>	Ground connection
48	IOH	I	P0[1]	
CP	Power		V <sub>SS</sub>	Center pad must be connected to ground

**LEGEND** A = Analog, I = Input, O = Output, NC = No Connection H = 5 mA High Output Drive, R = Regulated Output.

### Notes

9. This part is available in limited quantities for In-Circuit Debugging during prototype development. It is not available in production volumes.
10. During power-up or reset event, device P1[1] and P1[0] may disturb the I<sup>2</sup>C bus. Use alternate pins if you encounter any issues.
11. The center pad (CP) on the QFN package must be connected to ground (Vss) for best mechanical, thermal, and electrical performance. If not connected to ground, it must be electrically floated and not connected to any other signal.
12. These are the ISSP pins, which are not High Z at power on reset (POR).

## DC Chip-Level Specifications

The following table lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 6. DC Chip-Level Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$V_{DD}^{[13]}$	Supply voltage	Refer the table <a href="#">DC POR and LVD Specifications on page 17</a>	1.71	–	5.50	V
$I_{DD24}$	Supply current, IMO = 24 MHz	Conditions are $V_{DD} \leq 3.0$ V, $T_A = 25$ °C, CPU = 24 MHz. CapSense running at 12 MHz, no I/O sourcing current	–	3.32	4.00	mA
$I_{DD12}$	Supply current, IMO = 12 MHz	Conditions are $V_{DD} \leq 3.0$ V, $T_A = 25$ °C, CPU = 12 MHz. CapSense running at 12 MHz, no I/O sourcing current	–	1.86	2.60	mA
$I_{DD6}$	Supply current, IMO = 6 MHz	Conditions are $V_{DD} \leq 3.0$ V, $T_A = 25$ °C, CPU = 6 MHz. CapSense running at 6 MHz, no I/O sourcing current	–	1.13	1.80	mA
$I_{SB0}$	Deep sleep current	$V_{DD} \leq 3.0$ V, $T_A = 25$ °C, I/O regulator turned off	–	0.10	0.50	μA
$I_{SB1}$	Standby current with POR, LVD, and sleep timer	$V_{DD} \leq 3.0$ V, $T_A = 25$ °C, I/O regulator turned off	–	1.07	1.50	μA

### Note

13. When  $V_{DD}$  remains in the range from 1.71 V to 1.9 V for more than 50 μsec, the slew rate when moving from the 1.71 V to 1.9 V range to greater than 2 V must be slower than 1 V/500 μsec to avoid triggering POR. The only other restriction on slew rates for any other voltage range or transition is the  $SR_{POWER\_UP}$  parameter.

**Table 9. 1.71 V to 2.4 V DC GPIO Specifications (continued)**

Symbol	Description	Conditions	Min	Typ	Max	Units
$V_H$	Input hysteresis voltage		–	80	–	mV
$I_{IL}$	Input leakage (absolute value)		–	1	1000	nA
$C_{PIN}$	Capacitive load on pins	Package and pin dependent Temp = 25 °C	0.50	1.70	7	pF

**Table 10. DC Characteristics – USB Interface**

Symbol	Description	Conditions	Min	Typ	Max	Units
Rusbi	USB D+ pull-up resistance	With idle bus	900	–	1575	$\Omega$
Rusba	USB D+ pull-up resistance	While receiving traffic	1425	–	3090	$\Omega$
Vohusb	Static output high		2.8	–	3.6	V
Volusb	Static output low		–	–	0.3	V
Vdi	Differential input sensitivity		0.2	–	–	V
Vcm	Differential input common mode range		0.8	–	2.5	V
Vse	Single-ended receiver threshold		0.8	–	2.0	V
Cin	Transceiver capacitance		–	–	50	pF
Iio	High-Z state data line leakage	On D+ or D- line	–10	–	+10	$\mu$ A
Rps2	PS/2 pull-up resistance		3000	5000	7000	$\Omega$
Rext	External USB series resistor	In series with each USB pin	21.78	22.0	22.22	$\Omega$

### DC Analog Mux Bus Specifications

The following table lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 11. DC Analog Mux Bus Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$R_{SW}$	Switch resistance to common analog bus		–	–	800	$\Omega$
$R_{GND}$	Resistance of initialization switch to $V_{SS}$		–	–	800	$\Omega$

The maximum pin voltage for measuring  $R_{SW}$  and  $R_{GND}$  is 1.8 V

### DC Low Power Comparator Specifications

The following table lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 12. DC Comparator Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$V_{LPC}$	Low power comparator (LPC) common mode	Maximum voltage limited to $V_{DD}$	0.0	–	1.8	V
$I_{LPC}$	LPC supply current		–	10	40	$\mu$ A
$V_{OSLPC}$	LPC voltage offset		–	2.5	30	mV

### Comparator User Module Electrical Specifications

The following table lists the guaranteed maximum and minimum specifications. Unless stated otherwise, the specifications are for the entire device voltage and temperature operating range:  $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ ,  $1.71\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ .

**Table 13. Comparator User Module Electrical Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$T_{\text{COMP}}$	Comparator response time	50-mV overdrive	–	70	100	ns
Offset		Valid from 0.2 V to $V_{DD} - 0.2\text{ V}$	–	2.5	30	mV
Current		Average DC current, 50 mV overdrive	–	20	80	$\mu\text{A}$
PSRR	Supply voltage > 2 V	Power supply rejection ratio	–	80	–	dB
	Supply voltage < 2 V	Power supply rejection ratio	–	40	–	dB
Input Range			0	–	1.5	V

### ADC Electrical Specifications

**Table 14. ADC User Module Electrical Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
<b>Input</b>						
$V_{\text{IN}}$	Input voltage range		0	–	$V_{\text{REFADC}}$	V
$C_{\text{IIN}}$	Input capacitance		–	–	5	pF
$R_{\text{IN}}$	Input resistance	Equivalent switched cap input resistance for 8-, 9-, or 10-bit resolution	$1/(500\text{fF} \times \text{data clock})$	$1/(400\text{fF} \times \text{data clock})$	$1/(300\text{fF} \times \text{data clock})$	$\Omega$
<b>Reference</b>						
$V_{\text{REFADC}}$	ADC reference voltage		1.14	–	1.26	V
<b>Conversion Rate</b>						
$F_{\text{CLK}}$	Data clock	Source is chip's internal main oscillator. See <a href="#">AC Chip-Level Specifications on page 18</a> for accuracy	2.25	–	6	MHz
S8	8-bit sample rate	Data clock set to 6 MHz. Sample Rate = $0.001/(2^{\text{Resolution}}/\text{Data clock})$	–	23.43	–	ksps
S10	10-bit sample rate	Data clock set to 6 MHz. Sample Rate = $0.001/(2^{\text{Resolution}}/\text{Data clock})$	–	5.85	–	ksps
<b>DC Accuracy</b>						
RES	Resolution	Can be set to 8-, 9-, or 10-bit	8	–	10	bits
DNL	Differential nonlinearity		–1	–	+2	LSB
INL	<a href="#">Integral nonlinearity</a>		–2	–	+2	LSB
$E_{\text{OFFSET}}$	Offset error	8-bit resolution	0	3.20	19.20	LSB
		10-bit resolution	0	12.80	76.80	LSB
$E_{\text{GAIN}}$	Gain error	For any resolution	–5	–	+5	%FSR
<b>Power</b>						
$I_{\text{ADC}}$	Operating current		–	2.10	2.60	mA
PSRR	Power supply rejection ratio	PSRR ( $V_{DD} > 3.0\text{ V}$ )	–	24	–	dB
		PSRR ( $V_{DD} < 3.0\text{ V}$ )	–	30	–	dB



**Table 19. AC Characteristics – USB Data Timings**

Symbol	Description	Conditions	Min	Typ	Max	Units
T <sub>DRATE</sub>	Full-speed data rate	Average bit rate	12 – 0.25%	12	12 + 0.25%	MHz
T <sub>JR1</sub>	Receiver jitter tolerance	To next transition	–18.5	–	18.5	ns
T <sub>JR2</sub>	Receiver jitter tolerance	To pair transition	–9	–	9	ns
T <sub>DJ1</sub>	FS driver jitter	To next transition	–3.5	–	3.5	ns
T <sub>DJ2</sub>	FS driver jitter	To pair transition	–4.0	–	4.0	ns
T <sub>FDEOP</sub>	Source jitter for differential transition	To SE0 transition	–2	–	5	ns
T <sub>FEOPT</sub>	Source SE0 interval of EOP		160	–	175	ns
T <sub>FEOPR</sub>	Receiver SE0 interval of EOP		82	–		ns
T <sub>FST</sub>	Width of SE0 interval during differential transition		–	–	14	ns

**Table 20. AC Characteristics – USB Driver**

Symbol	Description	Conditions	Min	Typ	Max	Units
T <sub>FR</sub>	Transition rise time	50 pF	4	–	20	ns
T <sub>FF</sub>	Transition fall time	50 pF	4	–	20	ns
T <sub>FRFM</sub> <sup>[19]</sup>	Rise/fall time matching		90	–	111	%
V <sub>crs</sub>	Output signal crossover voltage		1.30	–	2.00	V

### AC Comparator Specifications

The following table lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 21. AC Low Power Comparator Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
T <sub>LPC</sub>	Comparator response time, 50 mV overdrive	50 mV overdrive does not include offset voltage.	–	–	100	ns

### AC External Clock Specifications

The following table lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 22. AC External Clock Specifications**

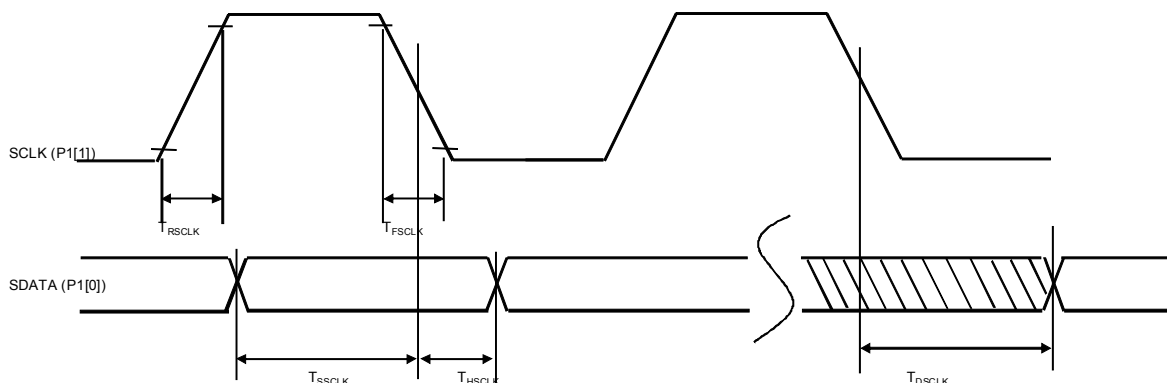
Symbol	Description	Conditions	Min	Typ	Max	Units
F <sub>OSCEXT</sub>	Frequency (external oscillator frequency)		0.75	–	25.20	MHz
	High period		20.60	–	5300	ns
	Low period		20.60	–	–	ns
	Power-up IMO to switch		150	–	–	μs

#### Note

19. T<sub>FRFM</sub> is not met under all conditions. There is a corner case at lower supply voltages, such as those under 3.3 V. This condition does not affect USB communications. Signal integrity tests show an excellent eye diagram at 3.15 V.

## AC Programming Specifications

Figure 7. AC Waveform



The following table lists the guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 23. AC Programming Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$T_{RCLK}$	Rise time of SCLK		1	–	20	ns
$T_{FCLK}$	Fall time of SCLK		1	–	20	ns
$T_{SSCLK}$	Data Setup time to falling edge of SCLK		40	–	–	ns
$T_{HSCLK}$	Data Hold time from falling edge of SCLK		40	–	–	ns
$F_{SCLK}$	Frequency of SCLK		0	–	8	MHz
$T_{ERASEB}$	Flash erase time (Block)		–	–	18	ms
$T_{WRITE}$	Flash block write time		–	–	25	ms
$T_{DSCLK}$	Data out delay from falling edge of SCLK	$3.6 < V_{DD}$	–	–	60	ns
$T_{DSCLK3}$	Data out delay from falling edge of SCLK	$3.0 \leq V_{DD} \leq 3.6$	–	–	85	ns
$T_{DSCLK2}$	Data out delay from falling edge of SCLK	$1.71 \leq V_{DD} \leq 3.0$	–	–	130	ns
$T_{XRST3}$	External reset pulse width after power-up	Required to enter programming mode when coming out of sleep	300	–	–	$\mu$ s
$T_{XRES}$	XRES Pulse Length		300	–	–	$\mu$ s
$T_{VDDWAIT}$	$V_{DD}$ stable to wait-and-poll hold off		0.1	–	1	ms
$T_{VDDXRES}$	$V_{DD}$ stable to XRES assertion delay		14.27	–	–	ms
$T_{POLL}$	SDATA high pulse time		0.01	–	200	ms
$T_{ACQ}$	“Key window” time after a $V_{DD}$ ramp acquire event, based on 256 ILO clocks.		3.20	–	19.60	ms
$T_{XRESINI}$	“Key window” time after an XRES event, based on eight ILO clocks		98	–	615	$\mu$ s

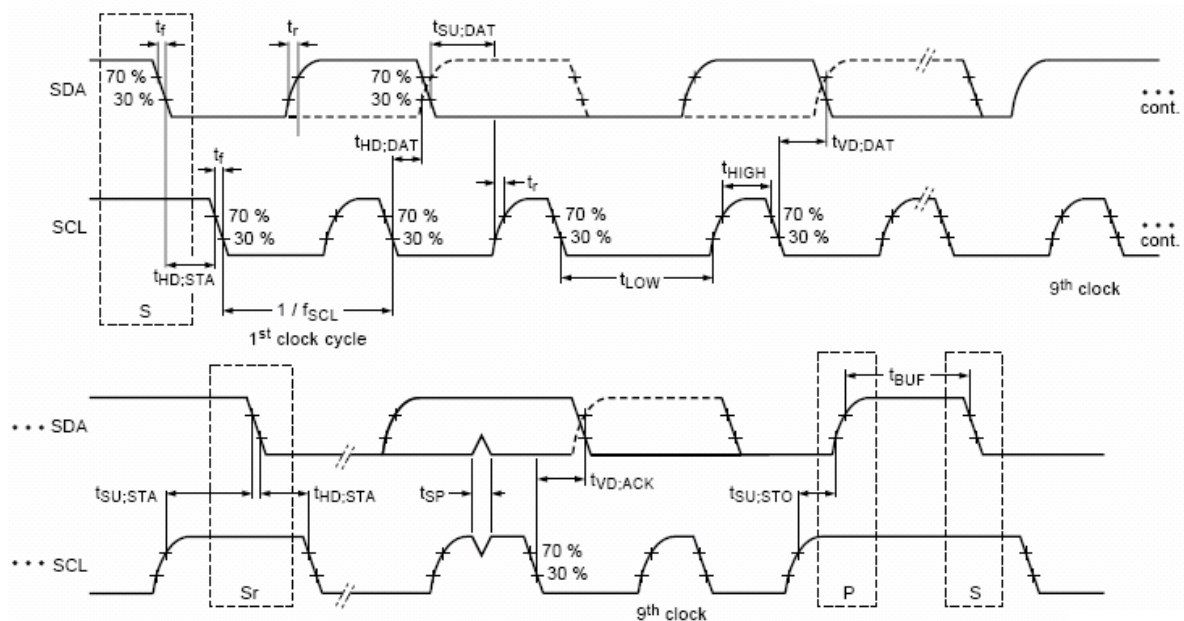
## AC I<sup>2</sup>C Specifications

The following table lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 24. AC Characteristics of the I<sup>2</sup>C SDA and SCL Pins**

Symbol	Description	Standard Mode		Fast Mode		Units
		Min	Max	Min	Max	
$f_{SCL}$	SCL clock frequency	0	100	0	400	kHz
$t_{HD;STA}$	Hold time (repeated) START condition. After this period, the first clock pulse is generated.	4.0	—	0.6	—	$\mu$ s
$t_{LOW}$	LOW period of the SCL clock	4.7	—	1.3	—	$\mu$ s
$t_{HIGH}$	HIGH period of the SCL clock	4.0	—	0.6	—	$\mu$ s
$t_{SU;STA}$	Setup time for a repeated START condition	4.7	—	0.6	—	$\mu$ s
$t_{HD;DAT}$	Data hold time	0	3.45	0	0.9	$\mu$ s
$t_{SU;DAT}$	Data setup time	250	—	100 <sup>[20]</sup>	—	ns
$t_{SU;STO}$	Setup time for STOP condition	4.0	—	0.6	—	$\mu$ s
$t_{BUF}$	Bus-free time between a STOP and START condition	4.7	—	1.3	—	$\mu$ s
$t_{SP}$	Pulse width of spikes are suppressed by the input filter.	—	—	0	50	ns

**Figure 8. Definition for Timing for Fast/Standard Mode on the I<sup>2</sup>C Bus**

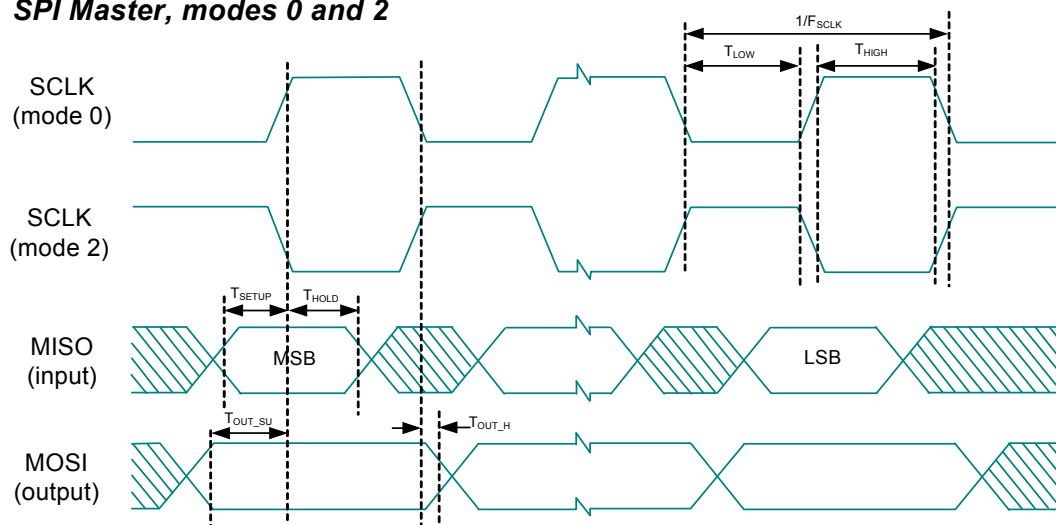


### Note

20. A Fast-Mode I<sup>2</sup>C-bus device can be used in a Standard Mode I<sup>2</sup>C-bus system, but the requirement  $t_{SU;DAT} \geq 250$  ns must then be met. This automatically be the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line  $t_{rmax} + t_{SU;DAT} = 1000 + 250 = 1250$  ns (according to the Standard-Mode I<sup>2</sup>C-bus specification) before the SCL line is released.

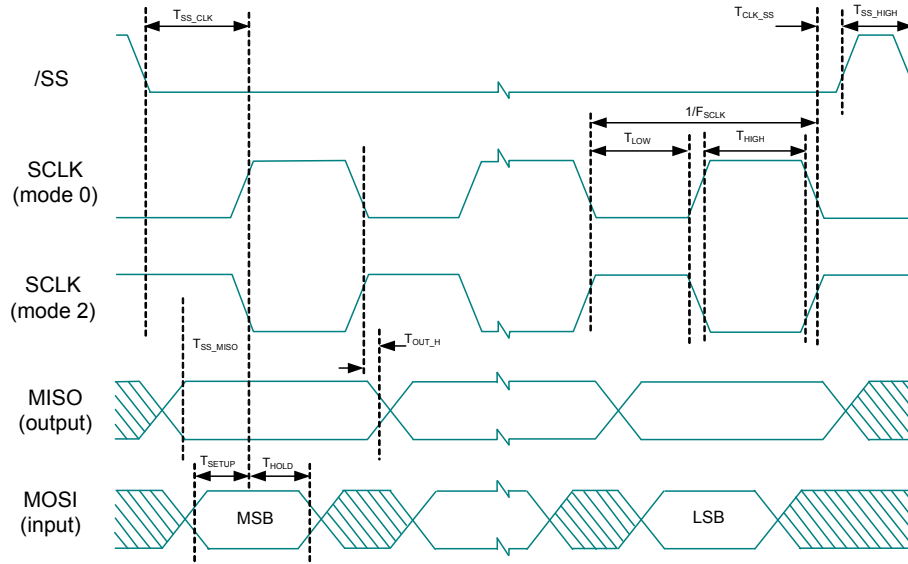
**Table 25. SPI Master AC Specifications**

Symbol	Description	Conditions	Min	Typ	Max	Units
$F_{SCLK}$	SCLK clock frequency	$V_{DD} \geq 2.4\text{ V}$ $V_{DD} < 2.4\text{ V}$	— —	— —	6 3	MHz
DC	SCLK duty cycle		—	50	—	%
$T_{SETUP}$	MISO to SCLK setup time	$V_{DD} \geq 2.4\text{ V}$ $V_{DD} < 2.4\text{ V}$	60 100	— —	— —	ns
$T_{HOLD}$	SCLK to MISO hold time		40	—	—	ns
$T_{OUT\_VAL}$	SCLK to MOSI valid time		—	—	40	ns
$T_{OUT\_H}$	MOSI high time		40	—	—	ns

**Figure 9. SPI Master Mode 0 and 2**
**SPI Master, modes 0 and 2**


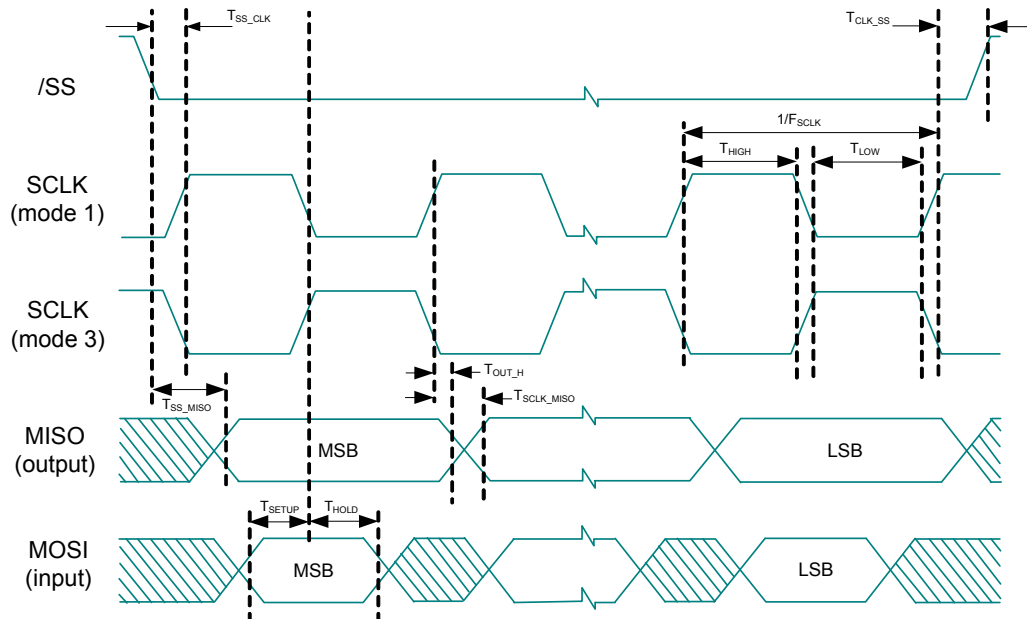
**Figure 11. SPI Slave Mode 0 and 2**

***SPI Slave, modes 0 and 2***



**Figure 12. SPI Slave Mode 1 and 3**

***SPI Slave, modes 1 and 3***

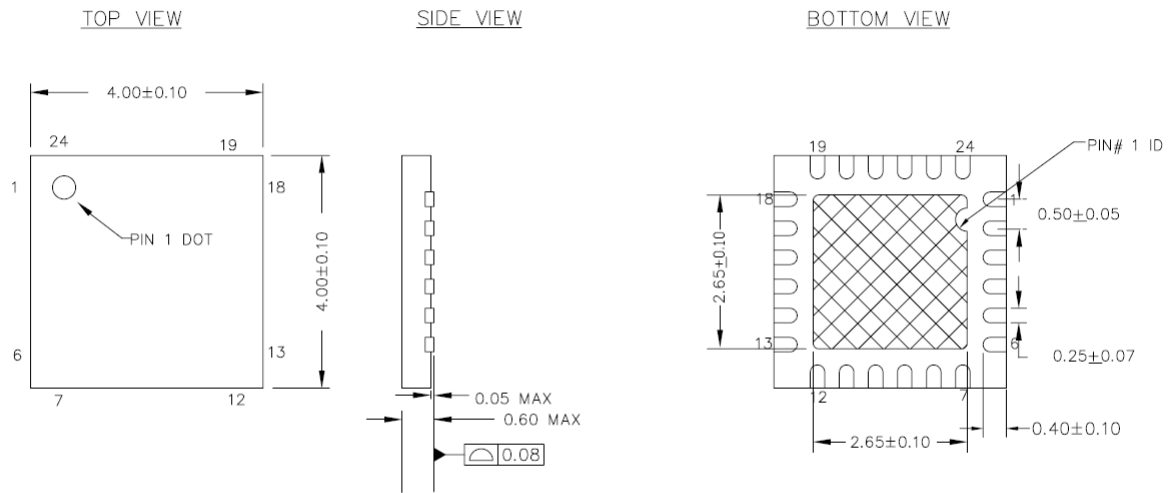


## Packaging Information


This section illustrates the packaging specifications for the CY8C20336H/CY8C20446H PSoC device, along with the thermal impedances for each package.

**Important Note** Emulation tools may require a larger area on the target PCB than the chip's footprint. For a detailed description of the emulation tools' dimensions, refer to the document titled *PSoC Emulator Pod Dimensions* at <http://www.cypress.com/design/MR10161>.

**Figure 13. 24-Pin ( $4 \times 4 \times 0.55$  mm) QFN**

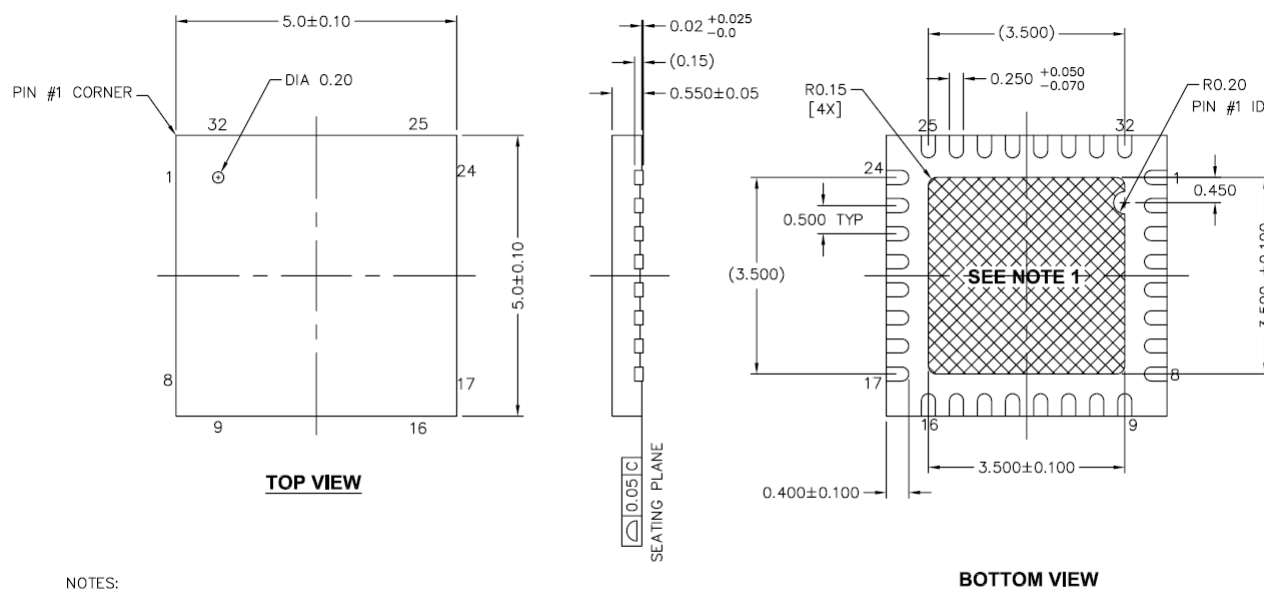


### NOTES :


1.  HATCH IS SOLDERABLE EXPOSED METAL.
2. REFERENCE JEDEC # MO-248
3. PACKAGE WEIGHT :  $29 \pm 3$  mg
4. ALL DIMENSIONS ARE IN MILLIMETERS

001-13937 \*E

Figure 14. 32-Pin ( $5 \times 5 \times 0.55$  mm) QFN

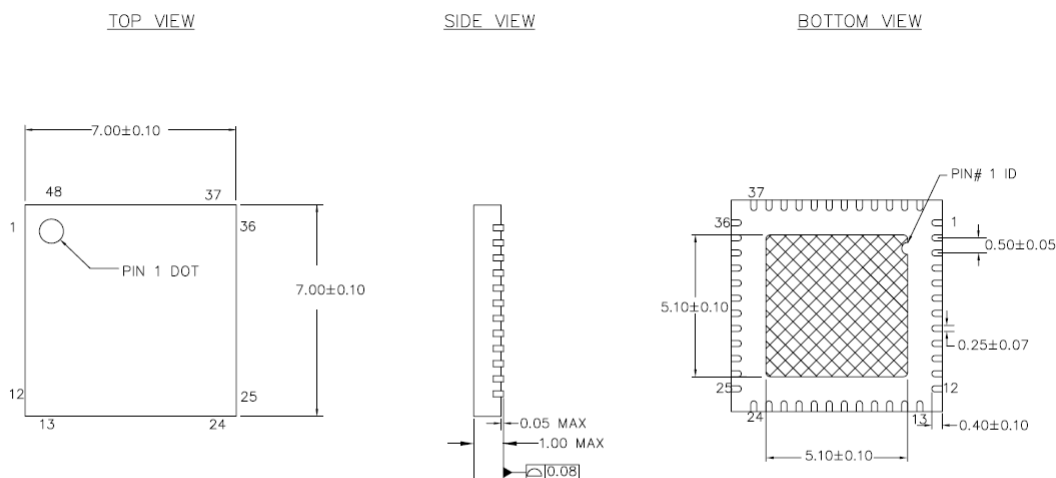


NOTES:


1.  HATCH AREA IS SOLDERABLE EXPOSED PAD
2. BASED ON REF JEDEC # MO-248
3. PACKAGE WEIGHT: 0.0388g
4. DIMENSIONS ARE IN MILLIMETERS

001-42168 \*E

Figure 15. 48-Pin ( $7 \times 7 \times 1.0$  mm) QFN



NOTES:

1.  HATCH AREA IS SOLDERABLE EXPOSED METAL.
2. REFERENCE JEDEC#: MO-220
3. PACKAGE WEIGHT:  $13 \pm 1$  mg
4. ALL DIMENSIONS ARE IN MILLIMETERS

001-13191 \*G

Important Notes

- For information on the preferred dimensions for mounting QFN packages, see the following Application Note at [http://www.amkor.com/products/notes\\_papers/MLFAppNote.pdf](http://www.amkor.com/products/notes_papers/MLFAppNote.pdf).
- Pinned vias for thermal conduction are not required for the low power PSoC device.

## Thermal Impedances

**Table 27. Thermal Impedances per Package**

Package	Typical $\theta_{JA}$ <sup>[21]</sup>
24-QFN <sup>[22]</sup>	20.90 °C/W
32-QFN <sup>[22]</sup>	19.51 °C/W
48-QFN <sup>[22]</sup>	17.68 °C/W

## Capacitance on Crystal Pins

**Table 28. Typical Package Capacitance on Crystal Pins**

Package	Package Capacitance
32-pin QFN	3.2 pF
48-pin QFN	3.3 pF

## Solder Reflow Peak Temperature

This table lists the minimum solder reflow peak temperature to achieve good solderability.

**Table 29. Solder Reflow Peak Temperature**

Package	Maximum Peak Temperature	Time at Maximum Peak Temperature
24-pin QFN	260 °C	30 s
32-pin QFN	260 °C	30 s
48-pin QFN	260 °C	30 s

### Notes

21.  $T_J = T_A + \text{Power} \times \theta_{JA}$ .

22. To achieve the thermal impedance specified for the QFN package, the center thermal pad must be soldered to the PCB ground plane.

23. Higher temperatures may be required based on the solder melting point. Typical temperatures for solder are  $220 \pm 5$  °C with Sn-Pb or  $245 \pm 5$  °C with Sn-Ag-Cu paste. Refer to the solder manufacturer specifications.



## Development Tool Selection

### Software

#### *PSoC Designer*

At the core of the PSoC development software suite is PSoC Designer. Utilized by thousands of PSoC developers, this robust software has been facilitating PSoC designs for over half a decade. PSoC Designer is available free of charge at <http://www.cypress.com>.

#### *PSoC Programmer*

Flexible enough to be used on the bench in development, yet suitable for factory programming, PSoC Programmer works either as a standalone programming application or it can operate directly from PSoC Designer. PSoC Programmer software is compatible with both PSoC ICE-Cube In-Circuit Emulator and PSoC MiniProg. PSoC Programmer is available free of charge at <http://www.cypress.com>.

### Development Kits

All development kits are sold at the Cypress Online Store.

#### *CY3215-DK Basic Development Kit*

The **CY3215-DK** is for prototyping and development with PSoC Designer. This kit supports in-circuit emulation and the software interface enables users to run, halt, and single step the processor and view the content of specific memory locations. PSoC Designer supports the advance emulation features also. The kit includes:

- PSoC Designer software CD
- ICE-Cube In-Circuit Emulator
- ICE Flex-Pod for CY8C29x66A family
- Cat-5 adapter
- Mini-Eval programming board
- 110 ~ 240-V power supply, Euro-Plug adapter
- iMAGEcraft C Compiler (Registration required)
- ISSP cable
- USB 2.0 cable and Blue Cat-5 cable
- Two CY8C29466A-24PXI 28-PDIP chip samples

### Evaluation Tools

All evaluation tools are sold at the Cypress Online Store.

#### *CY3210-MiniProg1*

The **CY3210-MiniProg1** kit enables the user to program PSoC devices via the MiniProg1 programming unit. The MiniProg is a small, compact prototyping programmer that connects to the PC via a provided USB 2.0 cable. The kit includes:

- MiniProg Programming Unit
- MiniEval Socket Programming and Evaluation Board
- 28-pin CY8C29466A-24PXI PDIP PSoC Device Sample
- 28-pin CY8C27443A-24PXI PDIP PSoC Device Sample
- PSoC Designer Software CD
- Getting Started Guide
- USB 2.0 Cable

#### *CY3210-PSoCEval1*

The **CY3210-PSoCEval1** kit features an evaluation board and the MiniProg1 programming unit. The evaluation board includes an LCD module, potentiometer, LEDs, and plenty of bread-boarding space to meet all of your evaluation needs. The kit includes:

- Evaluation Board with LCD Module
- MiniProg Programming Unit
- 28-pin CY8C29466A-24PXI PDIP PSoC Device Sample (2)
- PSoC Designer Software CD
- Getting Started Guide
- USB 2.0 Cable

#### *CY3280-20x66 Universal CapSense Controller*

The **CY3280-20X66 CapSense Controller Kit** is designed for easy prototyping and debug of CY8C20xx6A CapSense Family designs with pre-defined control circuitry and plug-in hardware. Programming hardware and an I2C-to-USB bridge are included for tuning and data acquisition.

The kit includes:

- CY3280-20x66 CapSense Controller board
- CY3240-I2USB bridge
- CY3210 MiniProg1 Programmer
- USB 2.0 retractable cable
- CY3280-20x66 Kit CD

## Device Programmers

All device programmers are purchased from the Cypress Online Store.

### CY3216 Modular Programmer

The **CY3216 Modular Programmer kit** features a modular programmer and the MiniProg1 programming unit. The modular programmer includes three programming module cards and supports multiple Cypress products. The kit includes:

- Modular Programmer Base
- Three Programming Module Cards
- MiniProg Programming Unit
- PSoC Designer Software CD

- Getting Started Guide

- USB 2.0 Cable

### CY3207ISSP In-System Serial Programmer (ISSP)

The **CY3207ISSP** is a production programmer. It includes protection circuitry and an industrial case that is more robust than the MiniProg in a production programming environment. Note that CY3207ISSP needs special software and is not compatible with PSoC Programmer. The kit includes:

- CY3207 Programmer Unit
- PSoC ISSP Software CD
- 110 ~ 240 V Power Supply, Euro-Plug Adapter
- USB 2.0 Cable

## Accessories (Emulation and Programming)

**Table 30. Emulation and Programming Accessories**

Part Number	Pin Package	Flex-Pod Kit <sup>[24]</sup>	Foot Kit <sup>[25]</sup>	Adapter <sup>[26]</sup>
CY8C20336H-24LQXI	24-pin QFN	CY3250-20366QFN	CY3250-24QFN-FK	See note 24
CY8C20446H-24LQXI	32-pin QFN	CY3250-20466QFN	CY3250-32QFN-FK	See note 26

## Third Party Tools

Several tools have been specially designed by the following third-party vendors to accompany PSoC devices during development and production. Specific details for each of these tools can be found at <http://www.cypress.com> under Documentation > Evaluation Boards.

## Build a PSoC Emulator into Your Board

For details on how to emulate your circuit before going to volume production using an on-chip debug (OCD) non-production PSoC device, refer Application Note "Debugging - Build a PSoC Emulator into Your Board - AN2323" at <http://www.cypress.com/?rID2748>.

## Notes

24. Flex-Pod kit includes a practice flex-pod and a practice PCB, in addition to two flex-pods.

25. Foot kit includes surface mount feet that can be soldered to the target PCB.

26. Programming adapter converts non-DIP package to DIP footprint. Specific details and ordering information for each of the adapters can be found at <http://www.emulation.com>.

27. Dual-function digital I/O pins also connect to the common analog mux.

28. This part is available in limited quantities for in-circuit debugging during prototype development. It is not available in production volumes.

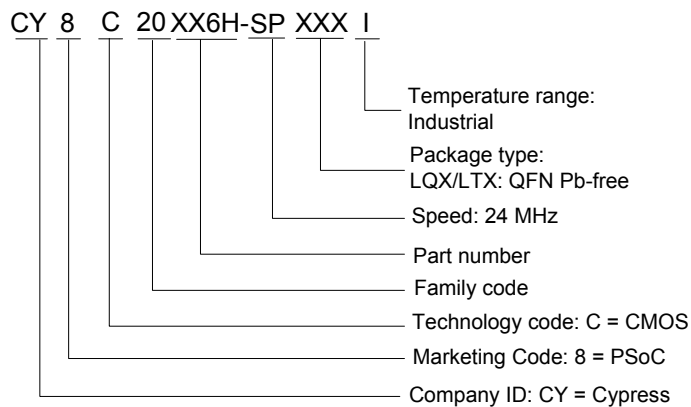
## Ordering Information

The following table lists the CY8C20336H/CY8C20446H PSoC devices' key package features and ordering codes.

**Table 31. PSoC Device Key Features and Ordering Information**

Package	Ordering Code	Flash (KB)	SRAM (KB)	CapSense Blocks	Digital I/O Pins	Analog Inputs <sup>[27]</sup>	XRES Pin	USB
24-pin (4 × 4 × 0.6mm) QFN	CY8C20336H-24LQXI	8	1	1	20	20	Yes	No
32 pin (5 × 5 × 0.6 mm) QFN	CY8C20446H-24LQXI	16	2	1	28	28	Yes	No
48 pin (7 × 7 mm) QFN (OCD) <sup>[28]</sup>	CY8C20066A-24LTXI	32	2	1	36	36	Yes	Yes

## Ordering Code Definitions



## Glossary

<b>Crosspoint connection</b>	Connection between any GPIO combination via analog multiplexer bus.
<b>Differential non-linearity</b>	Ideally, any two adjacent digital codes correspond to output analog voltages that are exactly one LSB apart. Differential non-linearity is a measure of the worst case deviation from the ideal 1 LSB step.
<b>Hold time</b>	Hold time is the time following a clock event during which the data input to a latch or flip-flop must remain stable in order to guarantee that the latched data is correct.
<b>I<sup>2</sup>C</b>	It is a serial multi-master bus used to connect low speed peripherals to MCU.
<b>Integral nonlinearity</b>	It is a term describing the maximum deviation between the ideal output of a DAC/ADC and the actual output level.
<b>Latch up current</b>	Current at which the latch up test is conducted according to JESD78 standard (at 125 °C)
<b>Power supply rejection ratio (PSRR)</b>	The PSRR is defined as the ratio of the change in supply voltage to the corresponding change in output voltage of the device.
<b>Scan</b>	The conversion of all sensor capacitances to digital values.
<b>Setup time</b>	Period required to prepare a device, machine, process, or system for it to be ready to function.
<b>Signal-to-noise ratio</b>	The ratio between a capacitive finger signal and system noise.
<b>SPI</b>	Serial peripheral interface is a synchronous serial data link standard.

## Reference Documents

- Technical reference manual for [CY8C20xx6](#) devices
- In-system Serial Programming (ISSP) protocol for 20xx6 – [AN2026C](#)
- Host Sourced Serial Programming for 20xx6 devices – [AN59389](#)

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