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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I²C, IrDA, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	29
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 11x16b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mk20dn128vlf5">https://www.e-xfl.com/product-detail/nxp-semiconductors/mk20dn128vlf5</a>

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# 1 Ordering parts

## 1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to <http://www.freescale.com> and perform a part number search for the following device numbers: PK20 and MK20 .

# 2 Part identification

## 2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

## 2.2 Format

Part numbers for this device have the following format:

Q K## A M FFF R T PP CC N

## 2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	<ul style="list-style-type: none"> <li>M = Fully qualified, general market flow</li> <li>P = Prequalification</li> </ul>
K##	Kinetis family	<ul style="list-style-type: none"> <li>K20</li> </ul>
A	Key attribute	<ul style="list-style-type: none"> <li>D = Cortex-M4 w/ DSP</li> <li>F = Cortex-M4 w/ DSP and FPU</li> </ul>
M	Flash memory type	<ul style="list-style-type: none"> <li>N = Program flash only</li> <li>X = Program flash and FlexMemory</li> </ul>

*Table continues on the next page...*

## Terminology and guidelines

Field	Description	Values
FFF	Program flash memory size	<ul style="list-style-type: none"> <li>• 32 = 32 KB</li> <li>• 64 = 64 KB</li> <li>• 128 = 128 KB</li> <li>• 256 = 256 KB</li> <li>• 512 = 512 KB</li> <li>• 1M0 = 1 MB</li> </ul>
R	Silicon revision	<ul style="list-style-type: none"> <li>• Z = Initial</li> <li>• (Blank) = Main</li> <li>• A = Revision after main</li> </ul>
T	Temperature range (°C)	<ul style="list-style-type: none"> <li>• V = -40 to 105</li> <li>• C = -40 to 85</li> </ul>
PP	Package identifier	<ul style="list-style-type: none"> <li>• FM = 32 QFN (5 mm x 5 mm)</li> <li>• FT = 48 QFN (7 mm x 7 mm)</li> <li>• LF = 48 LQFP (7 mm x 7 mm)</li> <li>• LH = 64 LQFP (10 mm x 10 mm)</li> <li>• MP = 64 MAPBGA (5 mm x 5 mm)</li> <li>• LK = 80 LQFP (12 mm x 12 mm)</li> <li>• MB = 81 MAPBGA (8 mm x 8 mm)</li> <li>• LL = 100 LQFP (14 mm x 14 mm)</li> <li>• ML = 104 MAPBGA (8 mm x 8 mm)</li> <li>• MC = 121 MAPBGA (8 mm x 8 mm)</li> <li>• LQ = 144 LQFP (20 mm x 20 mm)</li> <li>• MD = 144 MAPBGA (13 mm x 13 mm)</li> <li>• MJ = 256 MAPBGA (17 mm x 17 mm)</li> </ul>
CC	Maximum CPU frequency (MHz)	<ul style="list-style-type: none"> <li>• 5 = 50 MHz</li> <li>• 7 = 72 MHz</li> <li>• 10 = 100 MHz</li> <li>• 12 = 120 MHz</li> <li>• 15 = 150 MHz</li> </ul>
N	Packaging type	<ul style="list-style-type: none"> <li>• R = Tape and reel</li> <li>• (Blank) = Trays</li> </ul>

## 2.4 Example

This is an example part number:

MK20DN32VLF5

## 3 Terminology and guidelines

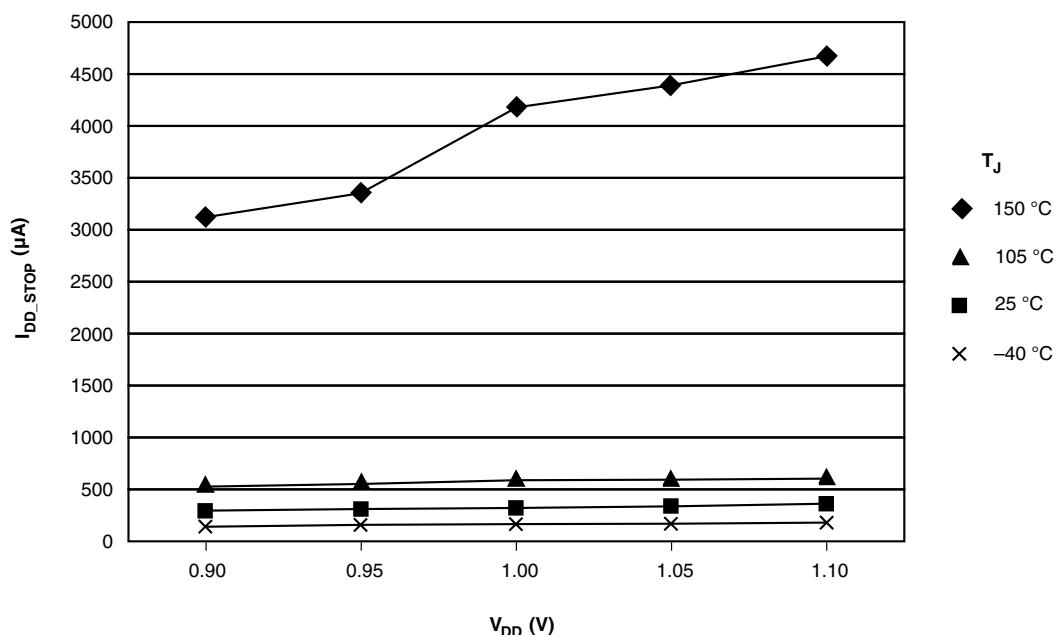
### 3.8.1 Example 1

This is an example of an operating behavior that includes a typical value:

Symbol	Description	Min.	Typ.	Max.	Unit
$I_{WP}$	Digital I/O weak pullup/pulldown current	10	70	130	$\mu\text{A}$

### 3.8.2 Example 2

This is an example of a chart that shows typical values for various voltage and temperature conditions:



## 3.9 Typical value conditions

Typical values assume you meet the following conditions (or other conditions as specified):

Symbol	Description	Value	Unit
$T_A$	Ambient temperature	25	$^{\circ}\text{C}$
$V_{DD}$	3.3 V supply voltage	3.3	V

## 4 Ratings

### 4.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
$T_{STG}$	Storage temperature	-55	150	°C	<a href="#">1</a>
$T_{SDR}$	Solder temperature, lead-free	—	260	°C	<a href="#">2</a>

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

### 4.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level	—	3	—	<a href="#">1</a>

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

### 4.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
$V_{HBM}$	Electrostatic discharge voltage, human body model	-2000	+2000	V	<a href="#">1</a>
$V_{CDM}$	Electrostatic discharge voltage, charged-device model	-500	+500	V	<a href="#">2</a>
$I_{LAT}$	Latch-up current at ambient temperature of 105°C	-100	+100	mA	

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.

### 4.4 Voltage and current operating ratings

Symbol	Description	Min.	Max.	Unit
$V_{DD}$	Digital supply voltage	-0.3	3.8	V

Table continues on the next page...

**Table 5. Power mode transition operating behaviors**

Symbol	Description	Min.	Max.	Unit	Notes
$t_{POR}$	After a POR event, amount of time from the point $V_{DD}$ reaches 1.71 V to execution of the first instruction across the operating temperature range of the chip.	—	300	μs	<a href="#">1</a>
	• VLLS0 → RUN	—	130	μs	
	• VLLS1 → RUN	—	130	μs	
	• VLLS2 → RUN	—	70	μs	
	• VLLS3 → RUN	—	70	μs	
	• LLS → RUN	—	6	μs	
	• VLPS → RUN	—	5.2	μs	
	• STOP → RUN	—	5.2	μs	

1. Normal boot (FTFL\_OPT[LPBOOT]=1)

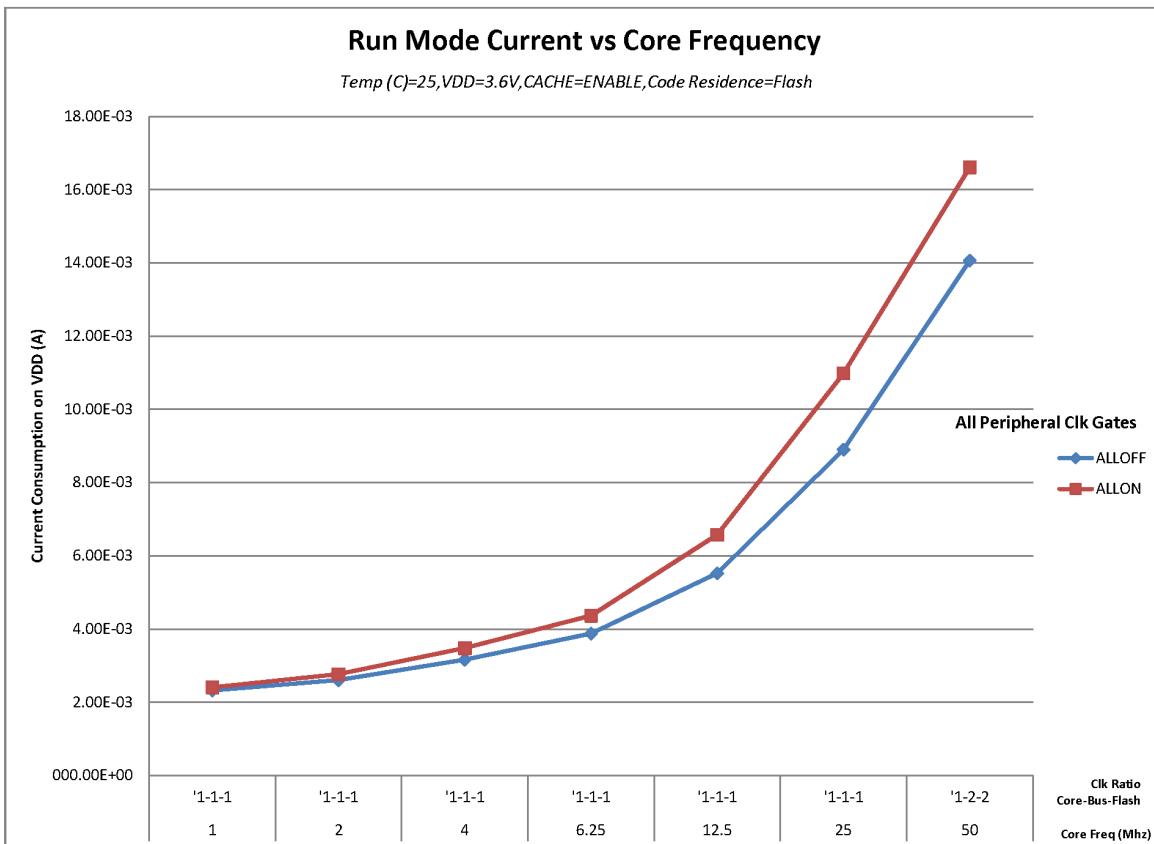
## 5.2.5 Power consumption operating behaviors

**Table 6. Power consumption operating behaviors**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$I_{DDA}$	Analog supply current	—	—	See note	mA	<a href="#">1</a>
$I_{DD\_RUN}$	Run mode current — all peripheral clocks disabled, code executing from flash	—	13.7	15.1	mA	<a href="#">2</a>
	• @ 1.8V	—	13.9	15.3	mA	
	• @ 3.0V					
$I_{DD\_RUN}$	Run mode current — all peripheral clocks enabled, code executing from flash	—	16.1	18.2	mA	<a href="#">3, 4</a>
	• @ 1.8V	—	16.3	17.7	mA	
	• @ 3.0V	—	16.7	18.4	mA	
	• @ 25°C					
	• @ 125°C					
$I_{DD\_WAIT}$	Wait mode high frequency current at 3.0 V — all peripheral clocks disabled	—	7.5	8.4	mA	<a href="#">2</a>
$I_{DD\_WAIT}$	Wait mode reduced frequency current at 3.0 V — all peripheral clocks disabled	—	5.6	6.4	mA	<a href="#">5</a>

Table continues on the next page...

- Code execution from flash with cache enabled
- For the ALLOFF curve, all peripheral clocks are disabled except FTFL



**Figure 2. Run mode supply current vs. core frequency**

## Peripheral operating requirements and behaviors

Board type	Symbol	Description	48 LQFP	48 QFN	Unit	Notes
Single-layer (1s)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	58	66	°C/W	1,3
Four-layer (2s2p)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	40	23	°C/W	,
—	$R_{\theta JB}$	Thermal resistance, junction to board	24	11	°C/W	5
—	$R_{\theta JC}$	Thermal resistance, junction to case	18	1.4	°C/W	6
—	$\Psi_{JT}$	Thermal characterization parameter, junction to package top outside center (natural convection)	3	4	°C/W	7

1. Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
2. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)* with the single layer board horizontal. For the LQFP, the board meets the JESD51-3 specification. For the MAPBGA, the board meets the JESD51-9 specification.
3. Determined according to JEDEC Standard JESD51-6, *Integrated Circuits Thermal Test Method Environmental Conditions—Forced Convection (Moving Air)* with the board horizontal.
5. Determined according to JEDEC Standard JESD51-8, *Integrated Circuit Thermal Test Method Environmental Conditions—Junction-to-Board*. Board temperature is measured on the top surface of the board near the package.
6. Determined according to Method 1012.1 of MIL-STD 883, *Test Method Standard, Microcircuits*, with the cold plate temperature used for the case temperature. The value includes the thermal resistance of the interface material between the top of the package and the cold plate.
7. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)*.

## 6 Peripheral operating requirements and behaviors

### 6.1 Core modules

## 6.1.1 JTAG electricals

Table 12. JTAG voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	2.7	5.5	V
J1	TCLK frequency of operation	—	10	MHz
	• JTAG	—	5	
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width	100	—	ns
	• JTAG	200	—	ns
	• CJTAG			ns
J4	TCLK rise and fall times	—	1	ns
J5	TMS input data setup time to TCLK rise	53	—	ns
	• JTAG	112	—	
J6	TDI input data setup time to TCLK rise	8	—	ns
J7	TMS input data hold time after TCLK rise	3.4	—	ns
	• JTAG	3.4	—	
J8	TDI input data hold time after TCLK rise	3.4	—	ns
J9	TCLK low to TMS data valid	—	48	ns
	• JTAG	—	85	
J10	TCLK low to TDO data valid	—	48	ns
J11	Output data hold/invalid time after clock edge <sup>1</sup>	—	3	ns

1. They are common for JTAG and CJTAG. Input transition = 1 ns and Output load = 50pf

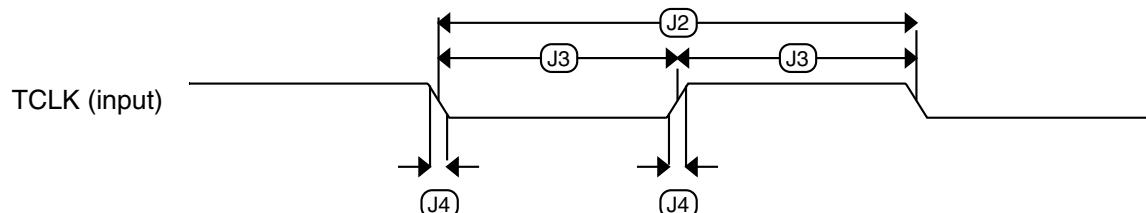


Figure 4. Test clock input timing

**Table 13. MCG specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
J <sub>acc_pll</sub>	PLL accumulated jitter over 1μs (RMS) <ul style="list-style-type: none"> <li>• f<sub>VCO</sub> = 48 MHz</li> <li>• f<sub>VCO</sub> = 100 MHz</li> </ul>	—	1350	—	ps	8
D <sub>lock</sub>	Lock entry frequency tolerance	± 1.49	—	± 2.98	%	
D <sub>unl</sub>	Lock exit frequency tolerance	± 4.47	—	± 5.97	%	
t <sub>pll_lock</sub>	Lock detector detection time	—	—	150 × 10 <sup>-6</sup> + 1075(1/ f <sub>pll_ref</sub> )	s	9

1. This parameter is measured with the internal reference (slow clock) being used as a reference to the FLL (FEI clock mode).
2. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32=0.
3. The resulting system clock frequencies should not exceed their maximum specified values. The DCO frequency deviation ( $\Delta f_{dcos_t}$ ) over voltage and temperature should be considered.
4. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32=1.
5. The resulting clock frequency must not exceed the maximum specified clock frequency of the device.
6. This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bits are changed, or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
7. Excludes any oscillator currents that are also consuming power while PLL is in operation.
8. This specification was obtained using a Freescale developed PCB. PLL jitter is dependent on the noise characteristics of each PCB and results will vary.
9. This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

### 6.3.2 Oscillator electrical specifications

This section provides the electrical characteristics of the module.

#### 6.3.2.1 Oscillator DC electrical specifications

**Table 14. Oscillator DC electrical specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V <sub>DD</sub>	Supply voltage	1.71	—	3.6	V	
I <sub>DDOSC</sub>	Supply current — low-power mode (HGO=0) <ul style="list-style-type: none"> <li>• 32 kHz</li> <li>• 4 MHz</li> <li>• 8 MHz (RANGE=01)</li> <li>• 16 MHz</li> <li>• 24 MHz</li> <li>• 32 MHz</li> </ul>	—	500	—	nA	1
		—	200	—	μA	
		—	300	—	μA	
		—	950	—	μA	
		—	1.2	—	mA	
		—	1.5	—	mA	

Table continues on the next page...

### 6.4.1.2 Flash timing specifications — commands

**Table 19. Flash command timing specifications**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{rd1blk32k}$	Read 1s Block execution time <ul style="list-style-type: none"> <li>• 32 KB data flash</li> <li>• 128 KB program flash</li> </ul>	—	—	0.5	ms	
$t_{rd1blk128k}$		—	—	1.7	ms	
$t_{rd1sec1k}$	Read 1s Section execution time (flash sector)	—	—	60	$\mu s$	<b>1</b>
$t_{pgmchk}$	Program Check execution time	—	—	45	$\mu s$	<b>1</b>
$t_{rdrsrc}$	Read Resource execution time	—	—	30	$\mu s$	<b>1</b>
$t_{pgm4}$	Program Longword execution time	—	65	145	$\mu s$	
$t_{ersblk32k}$	Erase Flash Block execution time <ul style="list-style-type: none"> <li>• 32 KB data flash</li> <li>• 128 KB program flash</li> </ul>	—	55	465	ms	<b>2</b>
$t_{ersblk128k}$		—	61	495	ms	
$t_{ersscr}$	Erase Flash Sector execution time	—	14	114	ms	<b>2</b>
$t_{pgmsec512}$	Program Section execution time <ul style="list-style-type: none"> <li>• 512 B flash</li> <li>• 1 KB flash</li> </ul>	—	4.7	—	ms	
$t_{pgmsec1k}$		—	9.3	—	ms	
$t_{rd1all}$	Read 1s All Blocks execution time	—	—	1.8	ms	
$t_{rdonce}$	Read Once execution time	—	—	25	$\mu s$	<b>1</b>
$t_{pgmonce}$	Program Once execution time	—	65	—	$\mu s$	
$t_{ersall}$	Erase All Blocks execution time	—	115	1000	ms	<b>2</b>
$t_{vfkey}$	Verify Backdoor Access Key execution time	—	—	30	$\mu s$	<b>1</b>
$t_{pgmpart32k}$	Program Partition for EEPROM execution time <ul style="list-style-type: none"> <li>• 32 KB FlexNVM</li> </ul>	—	70	—	ms	
$t_{setramff}$	Set FlexRAM Function execution time: <ul style="list-style-type: none"> <li>• Control Code 0xFF</li> </ul>	—	50	—	$\mu s$	
$t_{setram8k}$	<ul style="list-style-type: none"> <li>• 8 KB EEPROM backup</li> </ul>	—	0.3	0.5	ms	
$t_{setram32k}$	<ul style="list-style-type: none"> <li>• 32 KB EEPROM backup</li> </ul>	—	0.7	1.0	ms	
Byte-write to FlexRAM for EEPROM operation						
$t_{eewr8bers}$	Byte-write to erased FlexRAM location execution time	—	175	260	$\mu s$	<b>3</b>
$t_{eewr8b8k}$	Byte-write to FlexRAM execution time: <ul style="list-style-type: none"> <li>• 8 KB EEPROM backup</li> </ul>	—	340	1700	$\mu s$	
$t_{eewr8b16k}$	<ul style="list-style-type: none"> <li>• 16 KB EEPROM backup</li> </ul>	—	385	1800	$\mu s$	
$t_{eewr8b32k}$	<ul style="list-style-type: none"> <li>• 32 KB EEPROM backup</li> </ul>	—	475	2000	$\mu s$	

Table continues on the next page...

**Table 19. Flash command timing specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
Word-write to FlexRAM for EEPROM operation						
$t_{eewr16bers}$	Word-write to erased FlexRAM location execution time	—	175	260	μs	
$t_{eewr16b8k}$	Word-write to FlexRAM execution time:	—	340	1700	μs	
$t_{eewr16b16k}$	• 8 KB EEPROM backup	—	385	1800	μs	
$t_{eewr16b32k}$	• 16 KB EEPROM backup	—	475	2000	μs	
Longword-write to FlexRAM for EEPROM operation						
$t_{eewr32bers}$	Longword-write to erased FlexRAM location execution time	—	360	540	μs	
$t_{eewr32b8k}$	Longword-write to FlexRAM execution time:	—	545	1950	μs	
$t_{eewr32b16k}$	• 8 KB EEPROM backup	—	630	2050	μs	
$t_{eewr32b32k}$	• 16 KB EEPROM backup	—	810	2250	μs	

- Assumes 25MHz flash clock frequency.
- Maximum times for erase parameters based on expectations at cycling end-of-life.
- For byte-writes to an erased FlexRAM location, the aligned word containing the byte must be erased.

#### 6.4.1.3 Flash high voltage current behaviors

**Table 20. Flash high voltage current behaviors**

Symbol	Description	Min.	Typ.	Max.	Unit
$I_{DD\_PGM}$	Average current adder during high voltage flash programming operation	—	2.5	6.0	mA
$I_{DD\_ERS}$	Average current adder during high voltage flash erase operation	—	1.5	4.0	mA

#### 6.4.1.4 Reliability specifications

**Table 21. NVM reliability specifications**

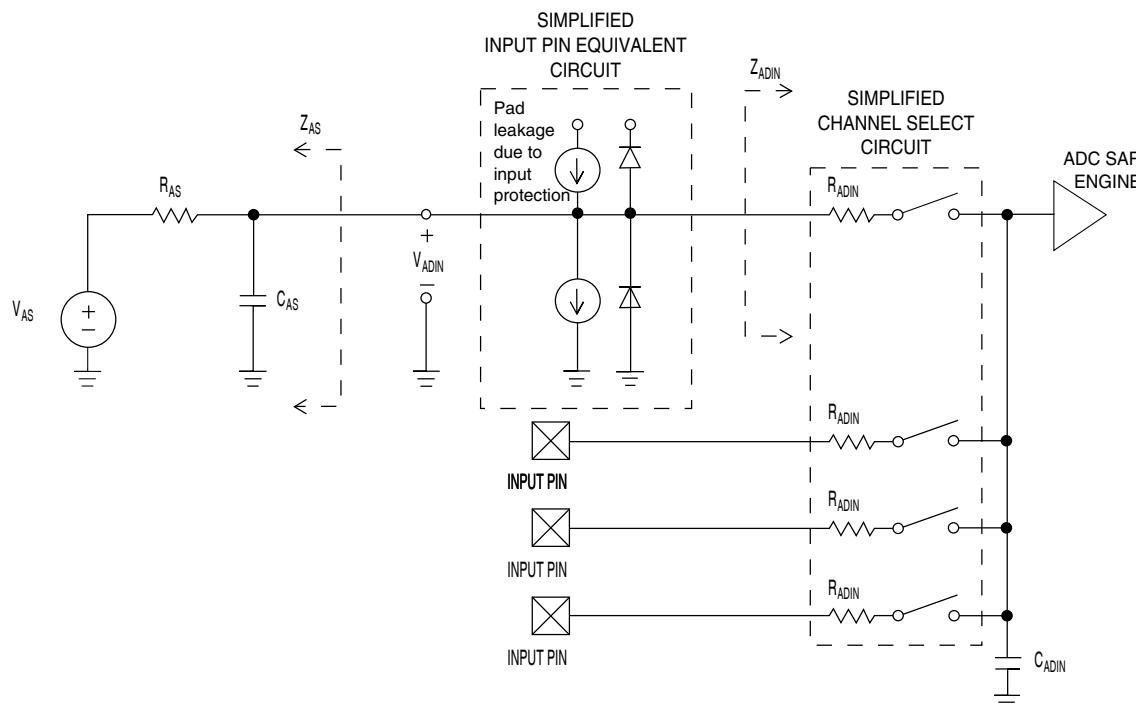
Symbol	Description	Min.	Typ.	Max.	Unit	Notes
Program Flash						
$t_{nvmretp10k}$	Data retention after up to 10 K cycles	5	50	—	years	
$t_{nvmretp1k}$	Data retention after up to 1 K cycles	20	100	—	years	
$n_{nvmcycp}$	Cycling endurance	10 K	50 K	—	cycles	<sup>2</sup>
Data Flash						
$t_{nvmretd10k}$	Data retention after up to 10 K cycles	5	50	—	years	

Table continues on the next page...

**Table 23. 16-bit ADC operating conditions (continued)**

Symbol	Description	Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
C <sub>rate</sub>	ADC conversion rate	16 bit modes No ADC hardware averaging Continuous conversions enabled, subsequent conversion time	37.037	—	461.467	Ksps	5

1. Typical values assume V<sub>DDA</sub> = 3.0 V, Temp = 25°C, f<sub>ADCK</sub> = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. DC potential difference.
3. This resistance is external to MCU. The analog source resistance should be kept as low as possible in order to achieve the best results. The results in this datasheet were derived from a system which has <8 Ω analog source resistance. The R<sub>AS</sub>/C<sub>AS</sub> time constant should be kept to <1ns.
4. To use the maximum ADC conversion clock frequency, the ADHSC bit should be set and the ADLPC bit should be clear.
5. For guidelines and examples of conversion rate calculation, download the ADC calculator tool: [http://cache.freescale.com/files/soft\\_dev\\_tools/software/app\\_software/converters/ADC\\_CALCULATOR\\_CNV.zip?fpst=1](http://cache.freescale.com/files/soft_dev_tools/software/app_software/converters/ADC_CALCULATOR_CNV.zip?fpst=1)

**Figure 10. ADC input impedance equivalency diagram**

### 6.6.1.2 16-bit ADC electrical characteristics

**Table 24. 16-bit ADC characteristics (V<sub>REFH</sub> = V<sub>DDA</sub>, V<sub>REFL</sub> = V<sub>SSA</sub>)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
I <sub>DDA_ADC</sub>	Supply current		0.215	—	1.7	mA	3

*Table continues on the next page...*

**Table 24. 16-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Symbol	Description	Conditions <sup>1</sup>	Min.	Typ. <sup>2</sup>	Max.	Unit	Notes
$f_{ADACK}$	ADC asynchronous clock source	<ul style="list-style-type: none"> <li>• ADLPC=1, ADHSC=0</li> <li>• ADLPC=1, ADHSC=1</li> <li>• ADLPC=0, ADHSC=0</li> <li>• ADLPC=0, ADHSC=1</li> </ul>	1.2 3.0 2.4 4.4	2.4 4.0 5.2 6.2	3.9 7.3 6.1 9.5	MHz MHz MHz MHz	$t_{ADACK} = 1/f_{ADACK}$
	Sample Time	See Reference Manual chapter for sample times					
TUE	Total unadjusted error	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	$\pm 4$ $\pm 1.4$	$\pm 6.8$ $\pm 2.1$	LSB <sup>4</sup>	5
DNL	Differential non-linearity	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	$\pm 0.7$ $\pm 0.2$	-1.1 to +1.9 -0.3 to 0.5	LSB <sup>4</sup>	5
INL	Integral non-linearity	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	$\pm 1.0$ $\pm 0.5$	-2.7 to +1.9 -0.7 to +0.5	LSB <sup>4</sup>	5
$E_{FS}$	Full-scale error	<ul style="list-style-type: none"> <li>• 12 bit modes</li> <li>• &lt;12 bit modes</li> </ul>	— —	-4 -1.4	-5.4 -1.8	LSB <sup>4</sup>	$V_{ADIN} = V_{DDA}$ 5
$E_Q$	Quantization error	<ul style="list-style-type: none"> <li>• 16 bit modes</li> <li>• ≤13 bit modes</li> </ul>	— —	-1 to 0 —	— $\pm 0.5$	LSB <sup>4</sup>	
ENOB	Effective number of bits	16 bit differential mode <ul style="list-style-type: none"> <li>• Avg=32</li> <li>• Avg=4</li> </ul> 16 bit single-ended mode <ul style="list-style-type: none"> <li>• Avg=32</li> <li>• Avg=4</li> </ul>	12.8 11.9 12.2 11.4	14.5 13.8 13.9 13.1	— — — —	bits bits bits bits	6
SINAD	Signal-to-noise plus distortion	See ENOB	$6.02 \times ENOB + 1.76$			dB	
THD	Total harmonic distortion	16 bit differential mode <ul style="list-style-type: none"> <li>• Avg=32</li> </ul> 16 bit single-ended mode <ul style="list-style-type: none"> <li>• Avg=32</li> </ul>	— —	-94 -85	— —	dB dB	7

Table continues on the next page...

**Table 31. USB VREG electrical specifications  
(continued)**

Symbol	Description	Min.	Typ. <sup>1</sup>	Max.	Unit	Notes
C <sub>OUT</sub>	External output capacitor	1.76	2.2	8.16	μF	
ESR	External output capacitor equivalent series resistance	1	—	100	mΩ	
I <sub>LIM</sub>	Short circuit current	—	290	—	mA	

1. Typical values assume VREGIN = 5.0 V, Temp = 25 °C unless otherwise stated.  
 2. Operating in pass-through mode: regulator output voltage equal to the input voltage minus a drop proportional to I<sub>Load</sub>.

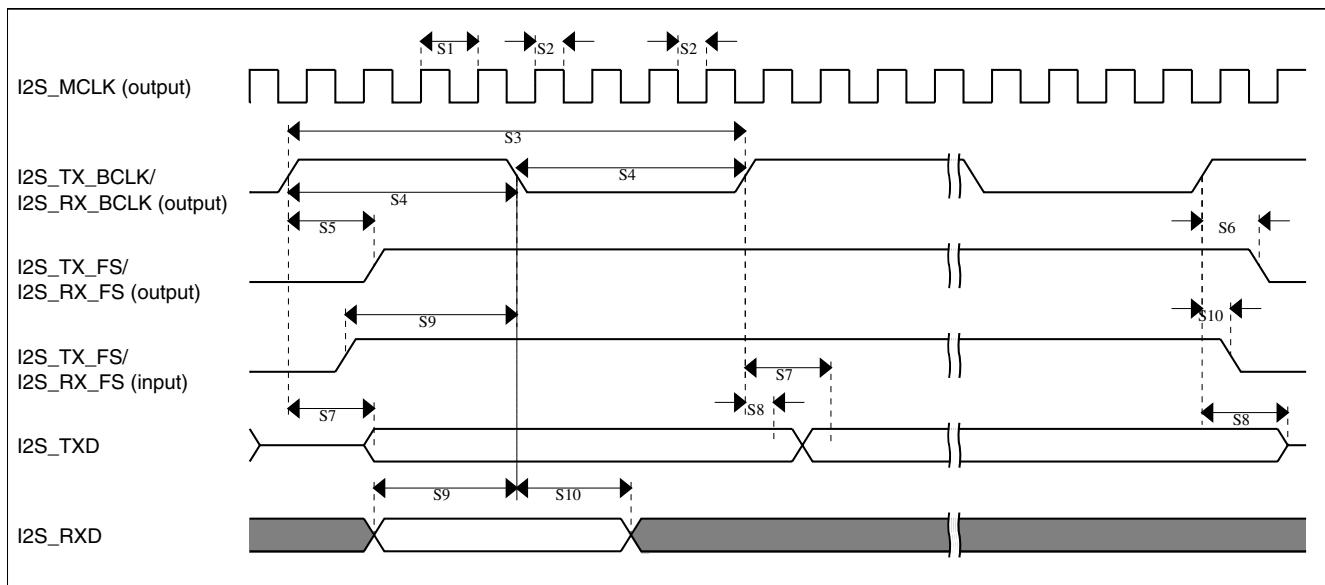
## 6.8.4 DSPI switching specifications (limited voltage range)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provide DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

**Table 32. Master mode DSPI timing (limited voltage range)**

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	25	MHz	
DS1	DSPI_SCK output cycle time	2 x t <sub>BUS</sub>	—	ns	
DS2	DSPI_SCK output high/low time	(t <sub>SCK</sub> /2) – 2	(t <sub>SCK</sub> /2) + 2	ns	
DS3	DSPI_PCS <sub>n</sub> valid to DSPI_SCK delay	(t <sub>BUS</sub> x 2) – 2	—	ns	<sup>1</sup>
DS4	DSPI_SCK to DSPI_PCS <sub>n</sub> invalid delay	(t <sub>BUS</sub> x 2) – 2	—	ns	<sup>2</sup>
DS5	DSPI_SCK to DSPI_SOUT valid	—	8	ns	
DS6	DSPI_SCK to DSPI_SOUT invalid	0	—	ns	
DS7	DSPI_SIN to DSPI_SCK input setup	14	—	ns	
DS8	DSPI_SCK to DSPI_SIN input hold	0	—	ns	

1. The delay is programmable in SPIx\_CTARn[PSSCK] and SPIx\_CTARn[CSSCK].  
 2. The delay is programmable in SPIx\_CTARn[PASC] and SPIx\_CTARn[ASC].

**Figure 19. I2S/SAI timing — master modes****Table 37. I2S/SAI slave mode timing**

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S11	I2S_TX_BCLK/I2S_RX_BCLK cycle time (input)	80	—	ns
S12	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low (input)	45%	55%	MCLK period
S13	I2S_TX_FS/I2S_RX_FS input setup before I2S_TX_BCLK/I2S_RX_BCLK	10	—	ns
S14	I2S_TX_FS/I2S_RX_FS input hold after I2S_TX_BCLK/I2S_RX_BCLK	2	—	ns
S15	I2S_TX_BCLK to I2S_TxD/I2S_TX_FS output valid	—	29	ns
S16	I2S_TX_BCLK to I2S_TxD/I2S_TX_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_RX_BCLK	10	—	ns
S18	I2S_RXD hold after I2S_RX_BCLK	2	—	ns
S19	I2S_TX_FS input assertion to I2S_TxD output valid <sup>1</sup>	—	21	ns

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear

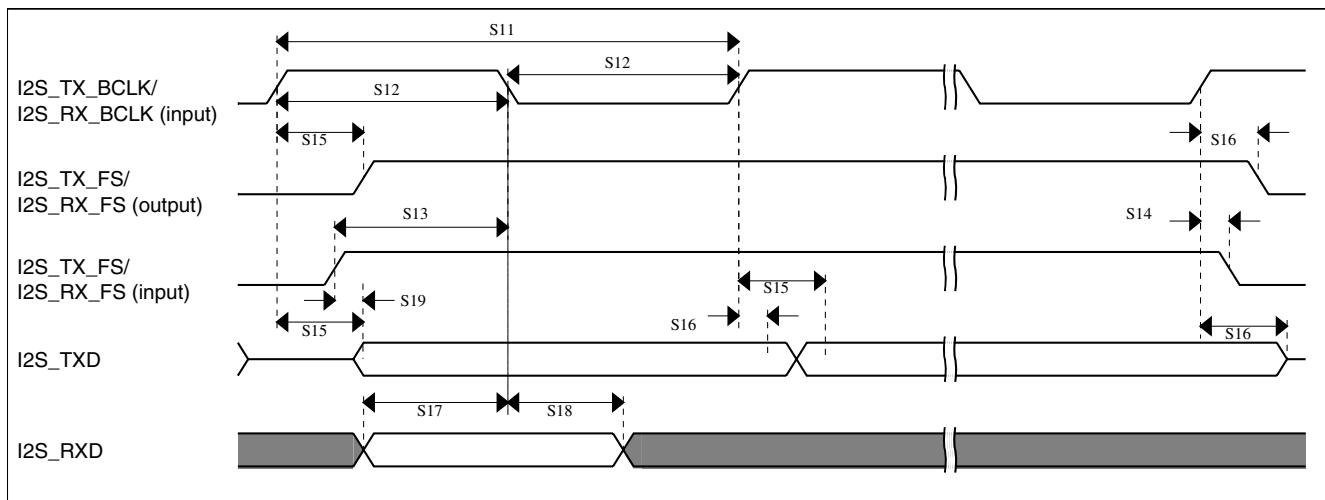


Figure 22. I2S/SAI timing — slave modes

## 6.9 Human-machine interfaces (HMI)

### 6.9.1 TSI electrical specifications

Table 40. TSI electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$V_{DDTSI}$	Operating voltage	1.71	—	3.6	V	
$C_{ELE}$	Target electrode capacitance range	1	20	500	pF	1
$f_{REFmax}$	Reference oscillator frequency	—	8	15	MHz	2, 3
$f_{ELEmax}$	Electrode oscillator frequency	—	1	1.8	MHz	2, 4
$C_{REF}$	Internal reference capacitor	—	1	—	pF	
$V_{\Delta}$	Oscillator delta voltage	—	500	—	mV	2, 5
$I_{REF}$	Reference oscillator current source base current <ul style="list-style-type: none"> <li>• 2 <math>\mu</math>A setting (REFCHRG = 0)</li> <li>• 32 <math>\mu</math>A setting (REFCHRG = 15)</li> </ul>	—	2	3	$\mu$ A	2, 6
$I_{ELE}$	Electrode oscillator current source base current <ul style="list-style-type: none"> <li>• 2 <math>\mu</math>A setting (EXTCHRG = 0)</li> <li>• 32 <math>\mu</math>A setting (EXTCHRG = 15)</li> </ul>	—	36	50	$\mu$ A	2, 7
Pres5	Electrode capacitance measurement precision	—	8.3333	38400	fF/count	8
Pres20	Electrode capacitance measurement precision	—	8.3333	38400	fF/count	9
Pres100	Electrode capacitance measurement precision	—	8.3333	38400	fF/count	10
MaxSens	Maximum sensitivity	0.008	1.46	—	fF/count	11
Res	Resolution	—	—	16	bits	

Table continues on the next page...

**Table 40. TSI electrical specifications (continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
T <sub>Con20</sub>	Response time @ 20 pF	8	15	25	μs	12
I <sub>TSI_RUN</sub>	Current added in run mode	—	55	—	μA	
I <sub>TSI_LP</sub>	Low power mode current adder	—	1.3	2.5	μA	13

1. The TSI module is functional with capacitance values outside this range. However, optimal performance is not guaranteed.
2. Fixed external capacitance of 20 pF.
3. REFCHRG = 2, EXTCHRG=0.
4. REFCHRG = 0, EXTCHRG = 10.
5. V<sub>DD</sub> = 3.0 V.
6. The programmable current source value is generated by multiplying the SCANC[REFCHRG] value and the base current.
7. The programmable current source value is generated by multiplying the SCANC[EXTCHRG] value and the base current.
8. Measured with a 5 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 8; Iext = 16.
9. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 2; Iext = 16.
10. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 16, NSCN = 3; Iext = 16.
11. Sensitivity defines the minimum capacitance change when a single count from the TSI module changes. Sensitivity depends on the configuration used. The documented values are provided as examples calculated for a specific configuration of operating conditions using the following equation: (C<sub>ref</sub> \* I<sub>ext</sub>)/(I<sub>ref</sub> \* PS \* NSCN)

The typical value is calculated with the following configuration:

I<sub>ext</sub> = 6 μA (EXTCHRG = 2), PS = 128, NSCN = 2, I<sub>ref</sub> = 16 μA (REFCHRG = 7), C<sub>ref</sub> = 1.0 pF

The minimum value is calculated with the following configuration:

I<sub>ext</sub> = 2 μA (EXTCHRG = 0), PS = 128, NSCN = 32, I<sub>ref</sub> = 32 μA (REFCHRG = 15), C<sub>ref</sub> = 0.5 pF

The highest possible sensitivity is the minimum value because it represents the smallest possible capacitance that can be measured by a single count.

12. Time to do one complete measurement of the electrode. Sensitivity resolution of 0.0133 pF, PS = 0, NSCN = 0, 1 electrode, EXTCHRG = 7.
13. REFCHRG=0, EXTCHRG=4, PS=7, NSCN=0F, LPSCNITV=F, LPO is selected (1 kHz), and fixed external capacitance of 20 pF. Data is captured with an average of 7 periods window.

## 7 Dimensions

### 7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to <http://www.freescale.com> and perform a keyword search for the drawing's document number:

If you want the drawing for this package	Then use this document number
48-pin LQFP	98ASH00962A
48-pin QFN	98ARH99048A

## 8.2 K20 Pinouts

The below figure shows the pinout diagram for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

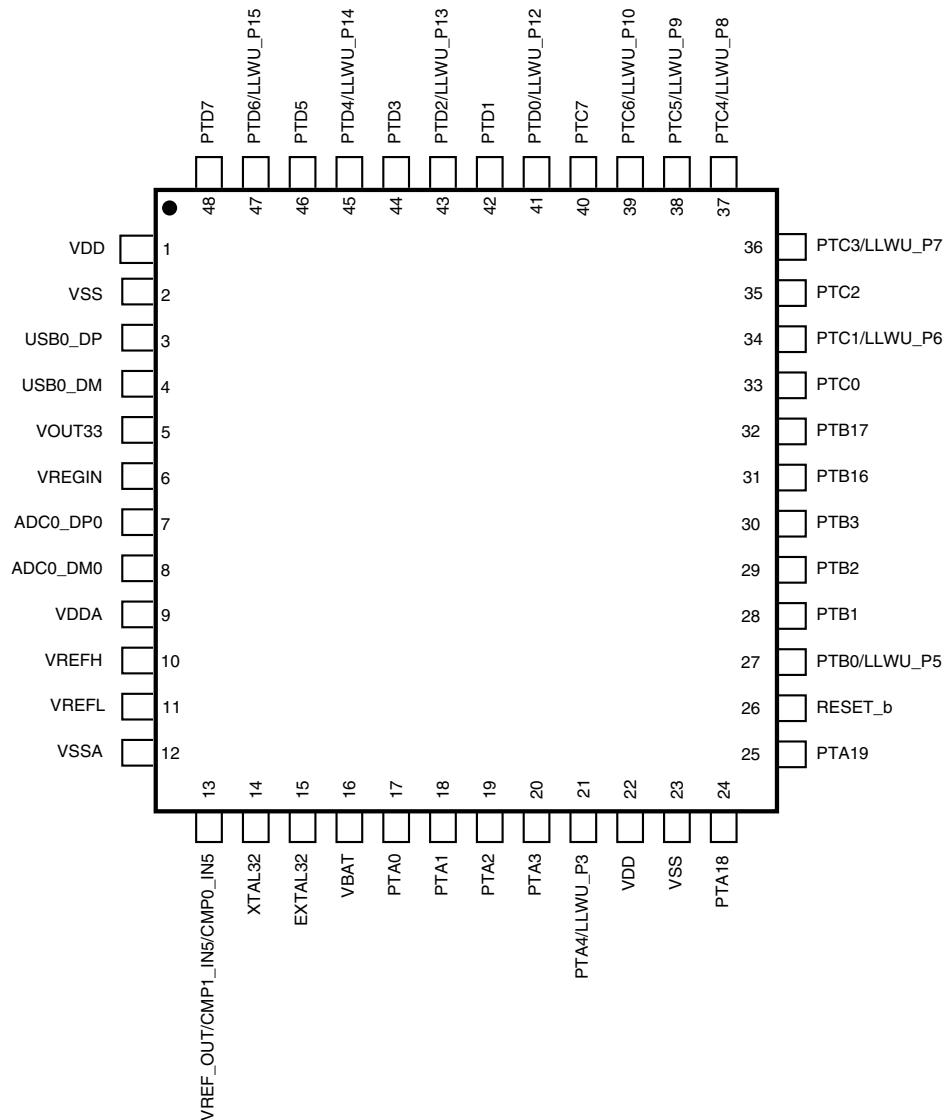


Figure 23. K20 48 LQFP/QFN Pinout Diagram

## 9 Revision History

The following table provides a revision history for this document.

**Table 41. Revision History**

<b>Rev. No.</b>	<b>Date</b>	<b>Substantial Changes</b>
2	2/2012	Initial public release
3	4/2012	<ul style="list-style-type: none"> <li>• Replaced TBDs throughout.</li> <li>• Updated "Power mode transition operating behaviors" table.</li> <li>• Updated "Power consumption operating behaviors" table.</li> <li>• For "Diagram: Typical IDD_RUN operating behavior" section, added "VLPR mode supply current vs. core frequency" figure.</li> <li>• Updated "EMC radiated emissions operating behaviors" section.</li> <li>• Updated "Thermal operating requirements" section.</li> <li>• Updated "MCG specifications" table.</li> <li>• Updated "VREF full-range operating behaviors" table.</li> <li>• Updated "I2S/SAI Switching Specifications" section.</li> <li>• Updated "TSI electrical specifications" table.</li> </ul>
4	5/2012	<ul style="list-style-type: none"> <li>• For the "32kHz oscillator frequency specifications", added specifications for an externally driven clock.</li> <li>• Renamed section "Flash current and power specifications" to section "Flash high voltage current behaviors" and improved the specifications.</li> <li>• For the "VREF full-range operating behaviors" table, removed the Ac (aging coefficient) specification.</li> <li>• Corrected the following DSPI switching specifications: tightened DS5, DS6, and DS7; relaxed DS11 and DS13.</li> <li>• For the "TSI electrical specifications", changed and clarified the example calculations for the MaxSens specification.</li> </ul>