

Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I ² C, IrDA, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I ² S, LVD, POR, PWM, WDT
Number of I/O	29
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	2K x 8
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 11x16b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mk20dx128vlf5

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Table of Contents

1	Orde	ering pa	ırts	3
	1.1	Determ	nining valid orderable parts	3
2	Part	identifi	cation	3
	2.1	Descri	otion	3
	2.2	Format	t	3
	2.3	Fields.		3
	2.4	Examp	le	4
3	Terr	ninolog	y and guidelines	4
	3.1	Definiti	on: Operating requirement	4
	3.2	Definiti	on: Operating behavior	5
	3.3	Definiti	on: Attribute	5
	3.4	Definiti	on: Rating	6
	3.5	Result	of exceeding a rating	6
	3.6	Relatio	nship between ratings and operating	
		require	ments	6
	3.7	Guideli	nes for ratings and operating requirements	7
	3.8	Definiti	on: Typical value	7
	3.9	Typica	value conditions	8
4	Rati	ngs		9
	4.1	Therma	al handling ratings	9
	4.2	Moistu	re handling ratings	9
	4.3	ESD h	andling ratings	9
	4.4	Voltage	e and current operating ratings	9
5	Gen	eral		10
	5.1	AC ele	ctrical characteristics	10
	5.2	Nonsw	itching electrical specifications	11
		5.2.1	Voltage and current operating requirements	11
		5.2.2	LVD and POR operating requirements	11
		5.2.3	Voltage and current operating behaviors	12
		5.2.4	Power mode transition operating behaviors	13
		5.2.5	Power consumption operating behaviors	14
		5.2.6	EMC radiated emissions operating behaviors	18
		5.2.7	Designing with radiated emissions in mind	19
		5.2.8	Capacitance attributes	19
	5.3	Switch	ing specifications	19
		5.3.1	Device clock specifications	19
		5.3.2	General switching specifications	20
	5.4	Therma	al specifications	21

		5.4.1	Thermal operating requirements21
		5.4.2	Thermal attributes21
6	Peri	pheral o	operating requirements and behaviors22
	6.1	Core m	nodules22
		6.1.1	JTAG electricals22
	6.2	System	n modules25
	6.3	Clock r	modules25
		6.3.1	MCG specifications25
		6.3.2	Oscillator electrical specifications27
		6.3.3	32 kHz Oscillator Electrical Characteristics29
	6.4	Memor	ries and memory interfaces
		6.4.1	Flash electrical specifications30
		6.4.2	EzPort Switching Specifications
	6.5	Securit	ty and integrity modules35
	6.6	Analog	J
		6.6.1	ADC electrical specifications35
		6.6.2	CMP and 6-bit DAC electrical specifications40
		6.6.3	Voltage reference electrical specifications43
	6.7	Timers	
	6.8	Comm	unication interfaces44
		6.8.1	USB electrical specifications44
		6.8.2	USB DCD electrical specifications45
		6.8.3	USB VREG electrical specifications45
		6.8.4	DSPI switching specifications (limited voltage
			range)46
		6.8.5	DSPI switching specifications (full voltage range).47
		6.8.6	I2C switching specifications49
		6.8.7	UART switching specifications49
		6.8.8	I2S/SAI Switching Specifications49
	6.9	Humar	n-machine interfaces (HMI)54
		6.9.1	TSI electrical specifications54
7	Dim	ensions	
	7.1	Obtain	ing package dimensions55
8	Pinc	out	
	8.1	K20 Si	gnal Multiplexing and Pin Assignments56
	8.2	K20 Pi	nouts58
9	Rev	ision Hi	story58

General

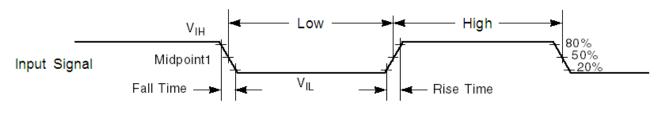
Symbol	Description	Min.	Max.	Unit
I _{DD}	Digital supply current	-	155	mA
V _{DIO}	Digital input voltage (except RESET, EXTAL, and XTAL)	-0.3	V _{DD} + 0.3	V
V _{AIO}	Analog ¹ , RESET, EXTAL, and XTAL input voltage	-0.3	V _{DD} + 0.3	V
Ι _D	Maximum current single pin limit (applies to all port pins)	-25	25	mA
V _{DDA}	Analog supply voltage	V _{DD} – 0.3	V _{DD} + 0.3	V
$V_{USB_{DP}}$	USB_DP input voltage	-0.3	3.63	V
$V_{USB_{DM}}$	USB_DM input voltage	-0.3	3.63	V
VREGIN	USB regulator input	-0.3	6.0	V
V _{BAT}	RTC battery supply voltage	-0.3	3.8	V

1. Analog pins are defined as pins that do not have an associated general purpose I/O port function.

5 General

5.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.



The midpoint is V_{IL} + $(V_{IH} - V_{IL})/2$.

Figure 1. Input signal measurement reference

All digital I/O switching characteristics assume:

- 1. output pins
 - have C_L=30pF loads,
 - are configured for fast slew rate (PORTx_PCRn[SRE]=0), and
 - are configured for high drive strength (PORTx_PCRn[DSE]=1)
- 2. input pins
 - have their passive filter disabled (PORTx_PCRn[PFE]=0)

5.2 Nonswitching electrical specifications

5.2.1 Voltage and current operating requirements

Table 1. Voltage and current operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V _{DD}	Supply voltage	1.71	3.6	V	
V _{DDA}	Analog supply voltage	1.71	3.6	V	
V _{DD} – V _{DDA}	V _{DD} -to-V _{DDA} differential voltage	-0.1	0.1	V	
$V_{SS} - V_{SSA}$	V _{SS} -to-V _{SSA} differential voltage	-0.1	0.1	V	
V _{BAT}	RTC battery supply voltage	1.71	3.6	V	
V _{IH}	Input high voltage				
	• 2.7 V \leq V _{DD} \leq 3.6 V	$0.7 \times V_{DD}$	—	V	
	• $1.7 \text{ V} \le \text{V}_{\text{DD}} \le 2.7 \text{ V}$	$0.75 \times V_{DD}$	—	V	
V _{IL}	Input low voltage				
	• $2.7 \text{ V} \le \text{V}_{\text{DD}} \le 3.6 \text{ V}$	_	$0.35 \times V_{DD}$	V	
	• $1.7 \text{ V} \le \text{V}_{\text{DD}} \le 2.7 \text{ V}$	_	$0.3 \times V_{DD}$	V	
V _{HYS}	Input hysteresis	$0.06 \times V_{DD}$	—	V	
I _{ICIO}	I/O pin DC injection current — single pin				1
	 V_{IN} < V_{SS}-0.3V (Negative current injection) 			mA	
	 V_{IN} > V_{DD}+0.3V (Positive current injection) 	-3	—		
		—	+3		
I _{ICcont}	Contiguous pin DC injection current —regional limit, includes sum of negative injection currents or sum of positive injection currents of 16 contiguous pins				
	Negative current injection	-25	—	mA	
	Positive current injection	—	+25		
V _{RAM}	V _{DD} voltage required to retain RAM	1.2	_	V	
V _{RFVBAT}	V _{BAT} voltage required to retain the VBAT register file	V _{POR_VBAT}		V	

All analog pins are internally clamped to V_{SS} and V_{DD} through ESD protection diodes. If V_{IN} is greater than V_{AIO_MIN} (=V_{SS}-0.3V) and V_{IN} is less than V_{AIO_MAX}(=V_{DD}+0.3V) is observed, then there is no need to provide current limiting resistors at the pads. If these limits cannot be observed then a current limiting resistor is required. The negative DC injection current limiting resistor is calculated as R=(V_{AIO_MIN}-V_{IN})/II_{IC}I. The positive injection current limiting resistor is calculated as R=(V_{IN}-V_{AIO_MAX})/II_{IC}I. Select the larger of these two calculated resistances.

Symbol	Description	Min.	Max.	Unit	Notes
t _{POR}	After a POR event, amount of time from the point V_{DD} reaches 1.71 V to execution of the first instruction across the operating temperature range of the chip.	_	300	μs	1
	• VLLS0 → RUN	_	130	μs	
	• VLLS1 → RUN	—	130	μs	
	• VLLS2 → RUN	_	70	μs	
	• VLLS3 → RUN	—	70	μs	
	• LLS → RUN	_	6	μs	
	VLPS → RUN	_	5.2	μs	
	• STOP → RUN	_	5.2	μs	

Table 5. Power mode transition operating behaviors

1. Normal boot (FTFL_OPT[LPBOOT]=1)

5.2.5 Power consumption operating behaviors

Table 6. Power consumption operating behaviors

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
I _{DDA}	Analog supply current	—	—	See note	mA	1
I _{DD_RUN}	Run mode current — all peripheral clocks disabled, code executing from flash • @ 1.8V • @ 3.0V		13.7 13.9	15.1 15.3	mA mA	2
I _{DD_RUN}	Run mode current — all peripheral clocks enabled, code executing from flash • @ 1.8V	_	16.1	18.2	mA	3, 4
	 @ 3.0V @ 25°C @ 125°C 	_	16.3 16.7	17.7 18.4	mA mA	
I _{DD_WAIT}	Wait mode high frequency current at 3.0 V — all peripheral clocks disabled	_	7.5	8.4	mA	2
I _{DD_WAIT}	Wait mode reduced frequency current at 3.0 V — all peripheral clocks disabled	—	5.6	6.4	mA	5

Table continues on the next page...

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
I _{DD_VLPR}	Very-low-power run mode current at 3.0 V — all peripheral clocks disabled	_	867		μA	6
I _{DD_VLPR}	Very-low-power run mode current at 3.0 V — all peripheral clocks enabled	_	1.1	_	mA	7
I _{DD_VLPW}	Very-low-power wait mode current at 3.0 V	_	509	—	μA	8
I _{DD_STOP}	Stop mode current at 3.0 V					
	● @ -40 to 25°C	—	310	426	μA	
	• @ 70°C	—	384	458	μA	
	• @ 105°C	—	629	1100	μA	
I _{DD_VLPS}	Very-low-power stop mode current at 3.0 V					
	● @ -40 to 25°C	—	3.5	22.6	μA	
	• @ 70°C	—	20.7	52.9	μA	
	• @ 105°C	—	85	220	μA	
I _{DD_LLS}	Low leakage stop mode current at 3.0 V					
	● @ -40 to 25°C	—	2.1	3.7	μA	
	• @ 70°C	—	7.7	43.1	μA	
	• @ 105°C	—	32.2	68	μA	
I _{DD_VLLS3}	Very low-leakage stop mode 3 current at 3.0 V					
	● @ -40 to 25°C	—	1.5	2.9	μA	
	• @ 70°C	—	4.8	22.5	μA	
	• @ 105°C	—	20	37.8	μA	
I _{DD_VLLS2}	Very low-leakage stop mode 2 current at 3.0 V					
	● @ -40 to 25°C	—	1.4	2.8	μA	
	• @ 70°C	—	4.1	19.2	μA	
	• @ 105°C	—	17.3	32.4	μA	
I _{DD_VLLS1}	Very low-leakage stop mode 1 current at 3.0 V					
	• @ -40 to 25°C	—	0.678	1.3	μA	
	• @ 70°C	—	2.8	13.6	μA	
	• @ 105°C	—	13.6	24.5	μA	
I _{DD_VLLS0}	Very low-leakage stop mode 0 current at 3.0 V with POR detect circuit enabled					
	 @ −40 to 25°C 	—	0.367	1.0	μΑ	
	• @ 70°C	—	2.4	13.3	μΑ	
	• @ 105°C		13.2	24.1	μA	

 Table 6. Power consumption operating behaviors (continued)

Table continues on the next page...



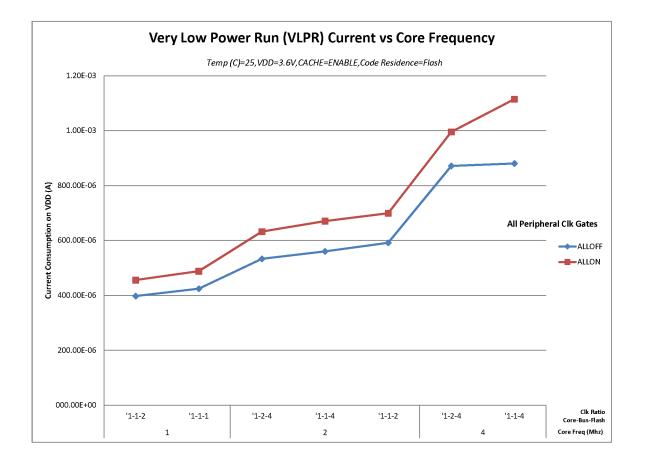


Figure 3. VLPR mode supply current vs. core frequency

5.2.6 EMC radiated emissions operating behaviors Table 7. EMC radiated emissions operating behaviors for 64LQFP

Symbol	Description	Frequency band (MHz)	Тур.	Unit	Notes
V _{RE1}	Radiated emissions voltage, band 1	0.15–50	19	dBµV	1,2
V _{RE2}	Radiated emissions voltage, band 2	50–150	21	dBµV	
V _{RE3}	Radiated emissions voltage, band 3	150–500	19	dBµV	
V _{RE4}	Radiated emissions voltage, band 4	500–1000	11	dBµV	
V _{RE_IEC}	IEC level	0.15–1000	L	_	2, 3

 Determined according to IEC Standard 61967-1, Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 1: General Conditions and Definitions and IEC Standard 61967-2, Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 2: Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method. Measurements were made while the microcontroller was running basic application code. The reported

emission level is the value of the maximum measured emission, rounded up to the next whole number, from among the measured orientations in each frequency range.

- 2. $V_{DD} = 3.3 \text{ V}, \text{ T}_{A} = 25 \text{ °C}, \text{ } f_{OSC} = 12 \text{ MHz} \text{ (crystal)}, \text{ } f_{SYS} = 48 \text{ MHz}, \text{ } f_{BUS} = 48 \text{ MHz}$
- 3. Specified according to Annex D of IEC Standard 61967-2, Measurement of Radiated Emissions TEM Cell and Wideband TEM Cell Method

5.2.7 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

- 1. Go to http://www.freescale.com.
- 2. Perform a keyword search for "EMC design."

5.2.8 Capacitance attributes

Table 8. Capacitance attributes

Symbol	Description	Min.	Max.	Unit
C _{IN_A}	Input capacitance: analog pins	_	7	pF
C _{IN_D}	Input capacitance: digital pins	—	7	pF

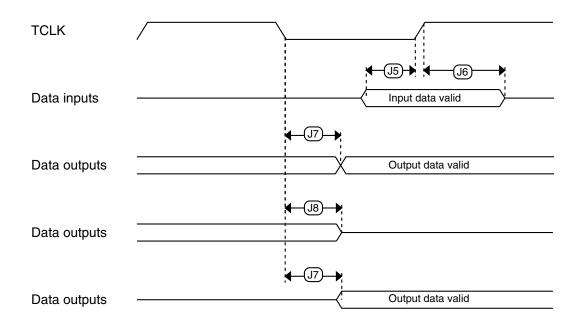
5.3 Switching specifications

5.3.1 Device clock specifications

Table 9. Device clock specifications

Symbol	Description	Min.	Max.	Unit	Notes
	Normal run mode	9		•	
f _{SYS}	System and core clock		50	MHz	
f _{SYS_USB}	System and core clock when Full Speed USB in operation	20	_	MHz	
f _{BUS}	Bus clock		50	MHz	
f _{FLASH}	Flash clock		25	MHz	
f _{LPTMR}	LPTMR clock		25	MHz	
	VLPR mode ¹				
f _{SYS}	System and core clock	_	4	MHz	
f _{BUS}	Bus clock	_	4	MHz	

Table continues on the next page ...





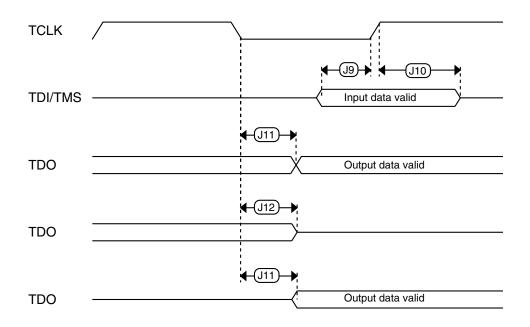
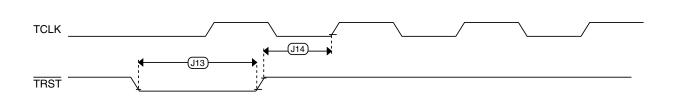


Figure 6. Test Access Port timing





6.2 System modules

There are no specifications necessary for the device's system modules.

6.3 Clock modules

6.3.1 MCG specifications

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
f _{ints_ft}	Internal reference frequency (slow clock) — factory trimmed at nominal VDD and 25 °C	_	32.768	_	kHz	
f _{ints_t}	Internal reference frequency (slow clock) — user trimmed	31.25	_	39.0625	kHz	
$\Delta_{fdco_res_t}$	Resolution of trimmed average DCO output frequency at fixed voltage and temperature — using SCTRIM and SCFTRIM	_	± 0.3	± 0.6	%f _{dco}	1
Δf_{dco_t}	Total deviation of trimmed average DCO output frequency over voltage and temperature	_	+0.5/-0.7	± 3	%f _{dco}	1
Δf_{dco_t}	Total deviation of trimmed average DCO output frequency over fixed voltage and temperature range of 0–70°C	_	± 0.3	_	%f _{dco}	1
f _{intf_ft}	Internal reference frequency (fast clock) — factory trimmed at nominal VDD and 25°C	_	4	_	MHz	
f _{intf_t}	Internal reference frequency (fast clock) — user trimmed at nominal VDD and 25 °C	3		5	MHz	
f _{loc_low}	Loss of external clock minimum frequency — RANGE = 00	(3/5) x f _{ints_t}	_	—	kHz	
${\sf f}_{\sf loc_high}$	Loss of external clock minimum frequency — RANGE = 01, 10, or 11	(16/5) x f _{ints_t}	_	_	kHz	
	FL					

Table 13. MCG specifications

Table continues on the next page...

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
I _{DDOSC}	Supply current — high gain mode (HGO=1)					1
	• 32 kHz	—	25	_	μA	
	• 4 MHz	—	400	_	μΑ	
	• 8 MHz (RANGE=01)	—	500	—	μA	
	• 16 MHz	—	2.5	—	mA	
	• 24 MHz	—	3	_	mA	
	• 32 MHz	—	4	_	mA	
C _x	EXTAL load capacitance	_		_		2, 3
Cy	XTAL load capacitance					2, 3
R _F	Feedback resistor — low-frequency, low-power mode (HGO=0)	—	_	_	MΩ	2, 4
	Feedback resistor — low-frequency, high-gain mode (HGO=1)	_	10	_	MΩ	
	Feedback resistor — high-frequency, low-power mode (HGO=0)	—	_	_	MΩ	
	Feedback resistor — high-frequency, high-gain mode (HGO=1)	—	1		MΩ	
R _S	Series resistor — low-frequency, low-power mode (HGO=0)	—	_		kΩ	
	Series resistor — low-frequency, high-gain mode (HGO=1)	—	200		kΩ	
	Series resistor — high-frequency, low-power mode (HGO=0)	—	_		kΩ	
	Series resistor — high-frequency, high-gain mode (HGO=1)					
		_	0	_	kΩ	
V _{pp} ⁵	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, low-power mode (HGO=0)	_	0.6	_	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, high-gain mode (HGO=1)	_	V _{DD}	_	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, low-power mode (HGO=0)	_	0.6	_	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, high-gain mode (HGO=1)	_	V _{DD}	_	V	

Table 14. Oscillator DC electrical specifications (continued)

1. V_{DD} =3.3 V, Temperature =25 °C

2. See crystal or resonator manufacturer's recommendation

- 3. C_x, C_y can be provided by using either the integrated capacitors or by using external components.
- 4. When low power mode is selected, R_F is integrated and must not be attached externally.

S	ymbol	Description	Min.	Тур.	Max.	Unit
(C _{para}	Parasitical capacitance of EXTAL32 and XTAL32	_	5	7	pF
	V _{pp} ¹	Peak-to-peak amplitude of oscillation	_	0.6	_	V

Table 16. 32kHz oscillator DC electrical specifications (continued)

1. When a crystal is being used with the 32 kHz oscillator, the EXTAL32 and XTAL32 pins should only be connected to required oscillator components and must not be connected to any other devices.

6.3.3.2 32kHz oscillator frequency specifications Table 17. 32kHz oscillator frequency specifications

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
f _{osc_lo}	Oscillator crystal	—	32.768	—	kHz	
t _{start}	Crystal start-up time	_	1000	_	ms	1
f _{ec_extal32}	Externally provided input clock frequency	_	32.768	_	kHz	2
V _{ec_extal32}	Externally provided input clock amplitude	700	_	V _{BAT}	mV	2, 3

1. Proper PC board layout procedures must be followed to achieve specifications.

2. This specification is for an externally supplied clock driven to EXTAL32 and does not apply to any other clock input. The oscillator remains enabled and XTAL32 must be left unconnected.

The parameter specified is a peak-to-peak value and V_{IH} and V_{IL} specifications do not apply. The voltage of the applied clock must be within the range of V_{SS} to V_{BAT}.

6.4 Memories and memory interfaces

6.4.1 Flash electrical specifications

This section describes the electrical characteristics of the flash memory module.

6.4.1.1 Flash timing specifications — program and erase

The following specifications represent the amount of time the internal charge pumps are active and do not include command overhead.

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
t _{hvpgm4}	Longword Program high-voltage time	_	7.5	18	μs	
t _{hversscr}	Sector Erase high-voltage time	_	13	113	ms	1
t _{hversblk32k}	Erase Block high-voltage time for 32 KB	_	52	452	ms	1
t _{hversblk128k}	Erase Block high-voltage time for 128 KB	_	52	452	ms	1

 Table 18.
 NVM program/erase timing specifications

1. Maximum time based on expectations at cycling end-of-life.

6.4.1.2 Flash timing specifications — commands Table 19. Flash command timing specifications

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
	Read 1s Block execution time					
t _{rd1blk32k}	32 KB data flash	_	—	0.5	ms	
t _{rd1blk128k}	128 KB program flash	_		1.7	ms	
t _{rd1sec1k}	Read 1s Section execution time (flash sector)			60	μs	1
t _{pgmchk}	Program Check execution time	_	_	45	μs	1
t _{rdrsrc}	Read Resource execution time			30	μs	1
t _{pgm4}	Program Longword execution time	_	65	145	μs	
	Erase Flash Block execution time					2
t _{ersblk32k}	32 KB data flash	_	55	465	ms	
t _{ersblk128k}	128 KB program flash	_	61	495	ms	
t _{ersscr}	Erase Flash Sector execution time		14	114	ms	2
	Program Section execution time					
t _{pgmsec512}	• 512 B flash	_	4.7	_	ms	
t _{pgmsec1k}	• 1 KB flash	_	9.3	_	ms	
t _{rd1all}	Read 1s All Blocks execution time			1.8	ms	
t _{rdonce}	Read Once execution time			25	μs	1
t _{pgmonce}	Program Once execution time	—	65	—	μs	
t _{ersall}	Erase All Blocks execution time	—	115	1000	ms	2
t _{vfykey}	Verify Backdoor Access Key execution time	_	_	30	μs	1
	Program Partition for EEPROM execution time					
t _{pgmpart32k}	• 32 KB FlexNVM	_	70	_	ms	
	Set FlexRAM Function execution time:					
t _{setramff}	Control Code 0xFF	_	50	_	μs	
t _{setram8k}	8 KB EEPROM backup	_	0.3	0.5	ms	
t _{setram32k}	32 KB EEPROM backup	_	0.7	1.0	ms	
	Byte-write to FlexRAM	for EEPROM	l operation	I		
t _{eewr8bers}	Byte-write to erased FlexRAM location execution time		175	260	μs	3
	Byte-write to FlexRAM execution time:					
t _{eewr8b8k}	8 KB EEPROM backup	_	340	1700	μs	
t _{eewr8b16k}	16 KB EEPROM backup	_	385	1800	μs	
t _{eewr8b32k}	32 KB EEPROM backup	_	475	2000	μs	

Table continues on the next page ...

Symbol	Description	Min.	Тур.	Max.	Unit	Notes
	Word-write to FlexRAM	for EEPRON	A operation			
t _{eewr16bers}	Word-write to erased FlexRAM location execution time	_	175	260	μs	
	Word-write to FlexRAM execution time:					
t _{eewr16b8k}	8 KB EEPROM backup	_	340	1700	μs	
t _{eewr16b16k}	16 KB EEPROM backup	_	385	1800	μs	
t _{eewr16b32k}	32 KB EEPROM backup	_	475	2000	μs	
	Longword-write to FlexRA	M for EEPR	OM operation	ו		
t _{eewr32bers}	Longword-write to erased FlexRAM location execution time	_	360	540	μs	
	Longword-write to FlexRAM execution time:					
t _{eewr32b8k}	8 KB EEPROM backup	_	545	1950	μs	
t _{eewr32b16k}	16 KB EEPROM backup	_	630	2050	μs	
t _{eewr32b32k}	32 KB EEPROM backup	_	810	2250	μs	

Table 19. Flash command timing specifications (continued)

1. Assumes 25MHz flash clock frequency.

2. Maximum times for erase parameters based on expectations at cycling end-of-life.

3. For byte-writes to an erased FlexRAM location, the aligned word containing the byte must be erased.

6.4.1.3 Flash high voltage current behaviors Table 20. Flash high voltage current behaviors

Symbol	Description	Min.	Тур.	Max.	Unit
I _{DD_PGM}	Average current adder during high voltage flash programming operation		2.5	6.0	mA
I _{DD_ERS}	Average current adder during high voltage flash erase operation	_	1.5	4.0	mA

6.4.1.4 Reliability specifications

Table 21. NVM reliability specifications

Symbol	Description	Min.	Typ. ¹	Max.	Unit	Notes
Program Flash						
t _{nvmretp10k}	Data retention after up to 10 K cycles	5	50	_	years	
t _{nvmretp1k}	Data retention after up to 1 K cycles	20	100	_	years	
n _{nvmcycp}	Cycling endurance	10 K	50 K	_	cycles	2
Data Flash						
t _{nvmretd10k}	Data retention after up to 10 K cycles	5	50	_	years	

Table continues on the next page ...

Symbol	Description	Min.	Typ. ¹	Max.	Unit	Notes
t _{nvmretd1k}	Data retention after up to 1 K cycles	20	100	_	years	
n _{nvmcycd}	Cycling endurance	10 K	50 K	_	cycles	2
	FlexRAM as	s EEPROM				
t _{nvmretee100}	Data retention up to 100% of write endurance	5	50	_	years	
t _{nvmretee10}	Data retention up to 10% of write endurance	20	100	_	years	
	Write endurance					3
n _{nvmwree16}	EEPROM backup to FlexRAM ratio = 16	35 K	175 K	—	writes	
n _{nvmwree128}	 EEPROM backup to FlexRAM ratio = 128 	315 K	1.6 M	—	writes	
n _{nvmwree512}	 EEPROM backup to FlexRAM ratio = 512 	1.27 M	6.4 M	—	writes	
n _{nvmwree4k}	EEPROM backup to FlexRAM ratio = 4096	10 M	50 M	—	writes	
n _{nvmwree8k}	EEPROM backup to FlexRAM ratio = 8192	20 M	100 M	—	writes	

Table 21. NVM reliability specifications (continued)

 Typical data retention values are based on measured response accelerated at high temperature and derated to a constant 25°C use profile. Engineering Bulletin EB618 does not apply to this technology. Typical endurance defined in Engineering Bulletin EB619.

2. Cycling endurance represents number of program/erase cycles at -40°C \leq T_j \leq 125°C.

3. Write endurance represents the number of writes to each FlexRAM location at -40°C ≤Tj ≤ 125°C influenced by the cycling endurance of the FlexNVM (same value as data flash) and the allocated EEPROM backup. Minimum and typical values assume all byte-writes to FlexRAM.

6.4.1.5 Write endurance to FlexRAM for EEPROM

When the FlexNVM partition code is not set to full data flash, the EEPROM data set size can be set to any of several non-zero values.

The bytes not assigned to data flash via the FlexNVM partition code are used by the flash memory module to obtain an effective endurance increase for the EEPROM data. The built-in EEPROM record management system raises the number of program/erase cycles that can be attained prior to device wear-out by cycling the EEPROM data through a larger EEPROM NVM storage space.

While different partitions of the FlexNVM are available, the intention is that a single choice for the FlexNVM partition code and EEPROM data set size is used throughout the entire lifetime of a given application. The EEPROM endurance equation and graph shown below assume that only one configuration is ever used.

Writes_FlexRAM =
$$\frac{\text{EEPROM} - 2 \times \text{EEESIZE}}{\text{EEESIZE}} \times \text{Write}_\text{efficiency} \times n_{\text{nvmcycd}}$$

where

• Writes_FlexRAM — minimum number of writes to each FlexRAM location

Symbol	Description	Conditions ¹	Min.	Typ. ²	Max.	Unit	Notes
SFDR	Spurious free dynamic range	16 bit differential modeAvg=3216 bit single-ended mode	82 78	95 90	_	dB dB	7
E _{IL}	Input leakage error	• Avg=32		I _{In} × R _{AS}		mV	I _{In} = leakage
							current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	-40°C to 105°C	_	1.715	_	mV/°C	
V _{TEMP25}	Temp sensor voltage	25°C	—	719	_	mV	

Table 24. 16-bit ADC characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$) (continued)

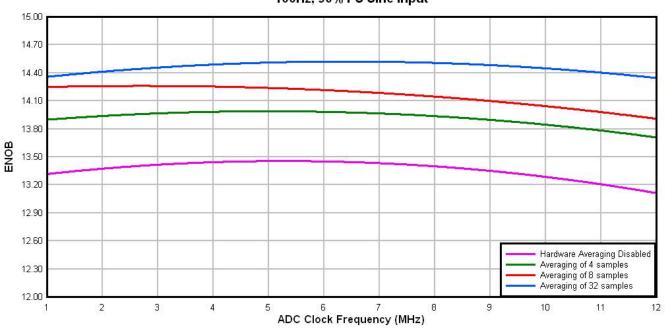
1. All accuracy numbers assume the ADC is calibrated with $V_{REFH} = V_{DDA}$

Typical values assume V_{DDA} = 3.0 V, Temp = 25°C, f_{ADCK} = 2.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

 The ADC supply current depends on the ADC conversion clock speed, conversion rate and the ADLPC bit (low power). For lowest power operation the ADLPC bit should be set, the HSC bit should be clear with 1MHz ADC conversion clock speed.

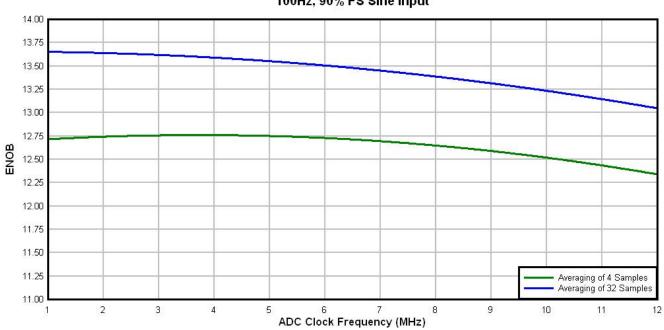
- 4. 1 LSB = $(V_{REFH} V_{REFL})/2^N$
- 5. ADC conversion clock <16MHz, Max hardware averaging (AVGE = %1, AVGS = %11)
- 6. Input data is 100 Hz sine wave. ADC conversion clock <12MHz.
- 7. Input data is 1 kHz sine wave. ADC conversion clock <12MHz.

Peripheral operating requirements and behaviors



Typical ADC 16-bit Differential ENOB vs ADC Clock 100Hz, 90% FS Sine Input





Typical ADC 16-bit Single-Ended ENOB vs ADC Clock 100Hz, 90% FS Sine Input

Figure 12. Typical ENOB vs. ADC_CLK for 16-bit single-ended mode

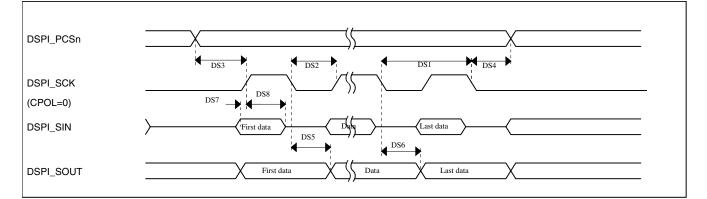


Figure 15. DSPI classic SPI timing — master mode

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
	Frequency of operation		12.5	MHz
DS9	DSPI_SCK input cycle time	4 x t _{BUS}	—	ns
DS10	DSPI_SCK input high/low time	(t _{SCK} /2) – 2	(t _{SCK} /2) + 2	ns
DS11	DSPI_SCK to DSPI_SOUT valid	_	20	ns
DS12	DSPI_SCK to DSPI_SOUT invalid	0	—	ns
DS13	DSPI_SIN to DSPI_SCK input setup	2	_	ns
DS14	DSPI_SCK to DSPI_SIN input hold	7	—	ns
DS15	DSPI_SS active to DSPI_SOUT driven	—	14	ns
DS16	DSPI_SS inactive to DSPI_SOUT not driven	—	14	ns

Table 33. Slave mode DSPI timing (limited voltage range)

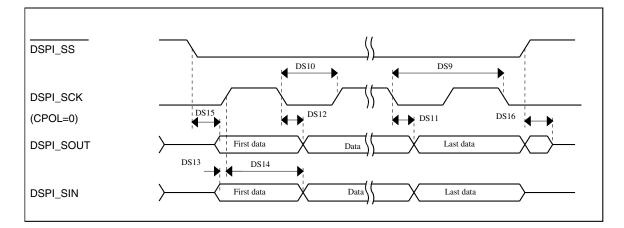


Figure 16. DSPI classic SPI timing — slave mode

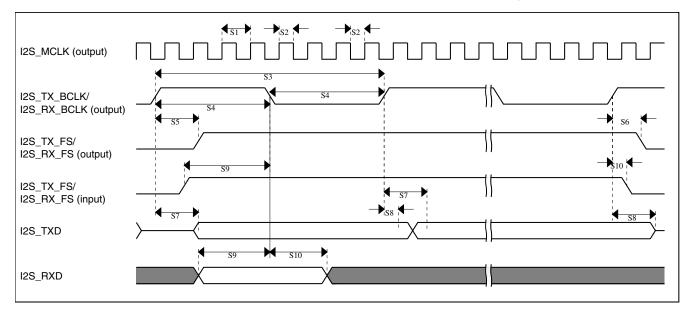


Figure 19. I2S/SAI timing — master modes

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S11	I2S_TX_BCLK/I2S_RX_BCLK cycle time (input)	80	—	ns
S12	I2S_TX_BCLK/I2S_RX_BCLK pulse width high/low (input)	45%	55%	MCLK period
S13	I2S_TX_FS/I2S_RX_FS input setup before I2S_TX_BCLK/I2S_RX_BCLK	10	—	ns
S14	I2S_TX_FS/I2S_RX_FS input hold after I2S_TX_BCLK/I2S_RX_BCLK	2	—	ns
S15	I2S_TX_BCLK to I2S_TXD/I2S_TX_FS output valid	—	29	ns
S16	I2S_TX_BCLK to I2S_TXD/I2S_TX_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_RX_BCLK	10	—	ns
S18	I2S_RXD hold after I2S_RX_BCLK	2	—	ns
S19	I2S_TX_FS input assertion to I2S_TXD output valid ¹	—	21	ns

Table 37. I2S/SAI slave mode timing

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear

8 Pinout

8.1 K20 Signal Multiplexing and Pin Assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

48 LQFP -QFN	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
1	VDD	VDD	VDD								
2	VSS	VSS	VSS								
3	USB0_DP	USB0_DP	USB0_DP								
4	USB0_DM	USB0_DM	USB0_DM								
5	VOUT33	VOUT33	VOUT33								
6	VREGIN	VREGIN	VREGIN								
7	ADC0_DP0	ADC0_DP0	ADC0_DP0								
8	ADC0_DM0	ADC0_DM0	ADC0_DM0								
9	VDDA	VDDA	VDDA								
10	VREFH	VREFH	VREFH								
11	VREFL	VREFL	VREFL								
12	VSSA	VSSA	VSSA								
13	VREF_OUT/ CMP1_IN5/ CMP0_IN5	VREF_OUT/ CMP1_IN5/ CMP0_IN5	VREF_OUT/ CMP1_IN5/ CMP0_IN5								
14	XTAL32	XTAL32	XTAL32								
15	EXTAL32	EXTAL32	EXTAL32								
16	VBAT	VBAT	VBAT								
17	PTAO	JTAG_TCLK/ SWD_CLK/ EZP_CLK	TSI0_CH1	PTA0	UARTO_CTS_ b/ UARTO_COL_b	FTM0_CH5				JTAG_TCLK/ SWD_CLK	EZP_CLK
18	PTA1	JTAG_TDI/ EZP_DI	TSI0_CH2	PTA1	UARTO_RX	FTM0_CH6				JTAG_TDI	EZP_DI
19	PTA2	JTAG_TDO/ TRACE_SWO/ EZP_DO	TSI0_CH3	PTA2	UARTO_TX	FTM0_CH7				JTAG_TDO/ TRACE_SWO	EZP_DO
20	PTA3	JTAG_TMS/ SWD_DIO	TSI0_CH4	PTA3	UART0_RTS_b	FTM0_CH0				JTAG_TMS/ SWD_DIO	
21	PTA4/ LLWU_P3	NMI_b/ EZP_CS_b	TSI0_CH5	PTA4/ LLWU_P3		FTM0_CH1				NMI_b	EZP_CS_b
22	VDD	VDD	VDD								
23	VSS	VSS	VSS								

How to Reach Us:

Home Page: www.freescale.com

Web Support: http://www.freescale.com/support

USA/Europe or Locations Not Listed:

Freescale Semiconductor Technical Information Center, EL516 2100 East Elliot Road Tempe, Arizona 85284 +1-800-521-6274 or +1-480-768-2130 www.freescale.com/support

Europe, Middle East, and Africa:

Freescale Halbleiter Deutschland GmbH Technical Information Center Schatzbogen 7 81829 Muenchen, Germany +44 1296 380 456 (English) +46 8 52200080 (English) +49 89 92103 559 (German) +33 1 69 35 48 48 (French) www.freescale.com/support

Japan:

Freescale Semiconductor Japan Ltd. Headquarters ARCO Tower 15F 1-8-1, Shimo-Meguro, Meguro-ku, Tokyo 153-0064 Japan 0120 191014 or +81 3 5437 9125 support.japan@freescale.com

Asia/Pacific:

Freescale Semiconductor China Ltd. Exchange Building 23F No. 118 Jianguo Road Chaoyang District Beijing 100022 China +86 10 5879 8000 support.asia@freescale.com Information in this document is provided solely to enable system and software implementers to use Freescale Semiconductors products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits or integrated circuits based on the information in this document.

Freescale Semiconductor reserves the right to make changes without further notice to any products herein. Freescale Semiconductor makes no warranty, representation, or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale Semiconductor assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any liability, including without limitation consequential or incidental damages. "Typical" parameters that may be provided in Freescale Semiconductor data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals", must be validated for each customer application by customer's technical experts. Freescale Semiconductor does not convey any license under its patent rights nor the rights of others. Freescale Semiconductor products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which failure of the Freescale Semiconductor product could create a situation where personal injury or death may occur. Should Buyer purchase or use Freescale Semiconductor products for any such unintended or unauthorized application, Buyer shall indemnify Freescale Semiconductor and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claims alleges that Freescale Semiconductor was negligent regarding the design or manufacture of the part.

RoHS-compliant and/or Pb-free versions of Freescale products have the functionality and electrical characteristics as their non-RoHS-complaint and/or non-Pb-free counterparts. For further information, see http://www.freescale.com or contact your Freescale sales representative.

For information on Freescale's Environmental Products program, go to http://www.freescale.com/epp.

 $\label{eq:FreescaleTM} Freescale TM and the Freescale logo are trademarks of Freescale Semiconductor, Inc. All other product or service names are the property of their respective owners.$

© 2011–2012 Freescale Semiconductor, Inc.





Document Number: K20P48M50SF0 Rev. 4 5/2012