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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

E·XFI

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	39
Program Memory Size	32KB (11K x 24)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-UFQFN Exposed Pad
Supplier Device Package	48-UQFN (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24f32ka304-i-mv

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT MICROCONTROLLERS

2.1 Basic Connection Requirements

Getting started with the PIC24FV32KA304 family of 16-bit microcontrollers requires attention to a minimal set of device pin connections before proceeding with development.

The following pins must always be connected:

- All VDD and Vss pins (see Section 2.2 "Power Supply Pins")
- All AVDD and AVss pins, regardless of whether or not the analog device features are used (see Section 2.2 "Power Supply Pins")
- MCLR pin (see Section 2.3 "Master Clear (MCLR) Pin")
- VCAP pins (see Section 2.4 "Voltage Regulator Pin (VCAP)")

These pins must also be connected if they are being used in the end application:

- PGECx/PGEDx pins used for In-Circuit Serial Programming[™] (ICSP[™]) and debugging purposes (see **Section 2.5 "ICSP Pins"**)
- OSCI and OSCO pins when an external oscillator source is used

(see Section 2.6 "External Oscillator Pins")

Additionally, the following pins may be required:

• VREF+/VREF- pins are used when external voltage reference for analog modules is implemented

Note: The AVDD and AVss pins must always be connected, regardless of whether any of the analog modules are being used.

The minimum mandatory connections are shown in Figure 2-1.

FIGURE 2-1: RECOMMENDED

MINIMUM CONNECTIONS



Key (all values are recommendations):

C1 through C6: 0.1 $\mu\text{F},$ 20V ceramic

C7: 10 µF, 16V tantalum or ceramic

R1: 10 kΩ

R2: 100Ω to 470Ω

- Note 1: See Section 2.4 "Voltage Regulator Pin (VCAP)" for explanation of VCAP pin connections.
 - 2: The example shown is for a PIC24F device with five VDD/Vss and AVDD/AVss pairs. Other devices may have more or less pairs; adjust the number of decoupling capacitors appropriately.

^{3:} Some PIC24F K parts do not have a regulator.

	-																	
File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUF0	0300		ADC1BUF0 xxx											XXXX				
ADC1BUF1	0302		ADC1BUF1 xx										XXXX					
ADC1BUF2	0304		ADC1BUF2 xx:										XXXX					
ADC1BUF3	0306		ADC1BUF3 x										XXXX					
ADC1BUF4	0308		ADC1BUF4 xx									XXXX						
ADC1BUF5	030A		ADC1BUF5 xxx:									XXXX						
ADC1BUF6	030C		ADC1BUF6 xxxx															
ADC1BUF7	030E		ADC1BUF7 xxxx															
ADC1BUF8	0310								ADC1BUF	3								XXXX
ADC1BUF9	0312								ADC1BUF	9								XXXX
ADC1BUF10	0314		ADC1BUF10 xxx									XXXX						
ADC1BUF11	0316								ADC1BUF1	1								XXXX
ADC1BUF12	0318								ADC1BUF1	2								XXXX
ADC1BUF13	031A								ADC1BUF1	3								XXXX
ADC1BUF14	031C								ADC1BUF1	4								XXXX
ADC1BUF15	031E								ADC1BUF1	5								XXXX
ADC1BUF16	0320								ADC1BUF1	6								XXXX
ADC1BUF17	0322								ADC1BUF1	7								XXXX
AD1CON1	0340	ADON	_	ADSIDL	_	—	MODE12	FORM1	FORM0	SSRC3	SSRC2	SSRC1	SSRC0	_	ASAM	SAMP	DONE	0000
AD1CON2	0342	PVCFG1	PVCFG0	NVCFG0	OFFCAL	BUFREGEN	CSCNA	_	_	BUFS	SMPI4	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS	0000
AD1CON3	0344	ADRC	EXTSAM	_	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0	ADCS7	ADCS6	ADCS5	ADCS4	ADCS3	ADCS2	ADCS1	ADCS0	0000
AD1CHS	0348	CH0NB2	CH0NB1	CH0NB0	CH0SB4	CH0SB3	CH0SB2	CH0SB1	CH0SB0	CH0NA2	CH0NA1	CH0NA0	CH0SA4	CH0SA3	CH0SA2	CH0SA1	CH0SA0	0000
AD1CSSH	034E	_	CSSL30	CSSL29	CSSL28	CSSL27	CSSL26	_	_	_	_	—		_	_	CSSL17	CSSL16	0000
AD1CSSL	0350	CSSL15	CSSL14	CSSL13	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8	CSSL7	CSSL6	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0	0000
AD1CON5	0354	ASEN	LPEN	CTMUREQ	BGREQ	r	_	ASINT1	ASINT0	_	_	—		WM1	WM0	CM1	CM0	0000
AD1CHITH	0356	_	_	—	_	_	—	_			—		_	_	—	CHH17	CHH16	0000
AD1CHITL	0358	CHH15	CHH14	CHH13	CHH12	CHH11	CHH10	CHH9	CHH8	CHH7	CHH6	CHH5	CHH4	CHH3	CHH2	CHH1	CHH0	0000

TABLE 4-16: A/D REGISTER MAP

Legend: — = unimplemented, read as '0'; r = reserved. Reset values are shown in hexadecimal.

4.3.3 READING DATA FROM PROGRAM MEMORY USING PROGRAM SPACE VISIBILITY

The upper 32 Kbytes of data space may optionally be mapped into a 16K word page (in PIC24FV16KA3XX devices) and a 32K word page (in PIC24FV32KA3XX devices) of the program space. This provides transparent access of stored constant data from the data space without the need to use special instructions (i.e., TBLRDL/H).

Program space access through the data space occurs if the MSb of the data space EA is '1' and PSV is enabled by setting the PSV bit in the CPU Control (CORCON<2>) register. The location of the program memory space to be mapped into the data space is determined by the Program Space Visibility Page Address (PSVPAG) register. This 8-bit register defines any one of 256 possible pages of 16K words in program space. In effect, PSVPAG functions as the upper 8 bits of the program memory address, with the 15 bits of the EA functioning as the lower bits.

By incrementing the PC by 2 for each program memory word, the lower 15 bits of data space addresses directly map to the lower 15 bits in the corresponding program space addresses.

Data reads from this area add an additional cycle to the instruction being executed, since two program memory fetches are required.

Although each data space address, 8000h and higher, maps directly into a corresponding program memory address (see Figure 4-7), only the lower 16 bits of the 24-bit program word are used to contain the data. The upper 8 bits of any program space location used as data should be programmed with '1111 1111' or '0000 0000' to force a NOP. This prevents possible issues should the area of code ever be accidentally executed.

Note:	PSV access is temporarily disabled during
	table reads/writes.

For operations that use PSV and are executed outside a REPEAT loop, the MOV and MOV. D instructions will require one instruction cycle in addition to the specified execution time. All other instructions will require two instruction cycles in addition to the specified execution time.

For operations that use PSV, which are executed inside a REPEAT loop, there will be some instances that require two instruction cycles in addition to the specified execution time of the instruction:

- · Execution in the first iteration
- · Execution in the last iteration
- Execution prior to exiting the loop due to an interrupt
- Execution upon re-entering the loop after an interrupt is serviced

Any other iteration of the REPEAT loop will allow the instruction accessing data, using PSV, to execute in a single cycle.



FIGURE 4-7: PROGRAM SPACE VISIBILITY OPERATION

REGISTER 8-13: IEC2: INTERRUPT ENABLE CONTROL REGISTER 2

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
	—	—	—	—		—	—	
bit 15							bit 8	
U-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	
	—	IC3IE	—	_	—	SPI2IE	SPF2IE	
bit 7							bit 0	
Legend:								
R = Readable bit W = Writable B		bit	U = Unimplem	nented bit, read	l as '0'			
-n = Value at POR		'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unknown		
bit 15-6	Unimplemen	ted: Read as '	D'					
bit 5	IC3IE: Input C	Capture Channe	el 3 Interrupt E	nable bit				
	1 = Interrupt r	request is enab	led					
	0 = Interrupt r	request is not e	nabled					
bit 4-2	Unimplemen	ted: Read as ') '					
bit 1	SPI2IE: SPI2	Event Interrup	t Enable bit					
	1 = Interrupt request is enabled							
	0 = Interrupt r	request is not e	nabled					
bit 0	SPF2IE: SPI2	2 Fault Interrup	t Enable bit					
	1 = Interrupt r	equest is enab	led					
			ام م ام ا م					

0 = Interrupt request is not enabled

REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER (CONTINUED)

bit 7	CLKLOCK: Clock Selection Lock Enabled bit	
	If FSCM is enabled (FCKSM1 = <u>1):</u>	
	1 = Clock and PLL selections are locked	
	0 = Clock and PLL selections are not locked and may be modified by setting the OSWEN bit	
	If FSCM is disabled (FCKSM1 = 0):	
	Clock and PLL selections are never locked and may be modified by setting the OSWEN bit.	
bit 6	Unimplemented: Read as '0'	
bit 5	LOCK: PLL Lock Status bit ⁽²⁾	
	1 = PLL module is in lock or PLL module start-up timer is satisfied	
	0 = PLL module is out of lock, PLL start-up timer is running or PLL is disabled	
bit 4	Unimplemented: Read as '0'	
bit 3	CF: Clock Fail Detect bit	
	1 = FSCM has detected a clock failure	
	0 = No clock failure has been detected	
bit 2	SOSCDRV: Secondary Oscillator Drive Strength bit ⁽³⁾	
	1 = High-power SOSC circuit is selected	
	0 = Low/high-power select is done via the SOSCSRC Configuration bit	
bit 1	SOSCEN: 32 kHz Secondary Oscillator (SOSC) Enable bit	
	1 = Enables the secondary oscillator	
	0 = Disables the secondary oscillator	
bit 0	OSWEN: Oscillator Switch Enable bit	
	1 = Initiates an oscillator switch to the clock source specified by the NOSC<2:0> bits	
	0 = Oscillator switch is complete	
Note 1:	Reset values for these bits are determined by the FNOSCx Configuration bits.	

- 2: This bit also resets to '0' during any valid clock switch or whenever a non-PLL Clock mode is selected.
 - **3:** When SOSC is selected to run from a digital clock input, rather than an external crystal (SOSCSRC = 0), this bit has no effect.

18.2 Transmitting in 8-Bit Data Mode

- 1. Set up the UARTx:
 - a) Write appropriate values for data, parity and Stop bits.
 - b) Write appropriate baud rate value to the UxBRG register.
 - c) Set up transmit and receive interrupt enable and priority bits.
- 2. Enable the UARTx.
- 3. Set the UTXEN bit (causes a transmit interrupt, two cycles after being set).
- 4. Write the data byte to the lower byte of the UxTXREG word. The value will be immediately transferred to the Transmit Shift Register (TSR) and the serial bit stream will start shifting out with the next rising edge of the baud clock.
- Alternately, the data byte may be transferred while UTXEN = 0 and then, the user may set UTXEN. This will cause the serial bit stream to begin immediately, because the baud clock will start from a cleared state.
- 6. A transmit interrupt will be generated as per interrupt control bit, UTXISELx.

18.3 Transmitting in 9-Bit Data Mode

- 1. Set up the UARTx (as described in **Section 18.2** "**Transmitting in 8-Bit Data Mode**").
- 2. Enable the UARTx.
- 3. Set the UTXEN bit (causes a transmit interrupt, two cycles after being set).
- 4. Write UxTXREG as a 16-bit value only.
- 5. A word write to UxTXREG triggers the transfer of the 9-bit data to the TSR. The serial bit stream will start shifting out with the first rising edge of the baud clock.
- 6. A transmit interrupt will be generated as per the setting of control bit, UTXISELx.

18.4 Break and Sync Transmit Sequence

The following sequence will send a message frame header made up of a Break, followed by an auto-baud Sync byte.

- 1. Configure the UARTx for the desired mode.
- 2. Set UTXEN and UTXBRK this sets up the Break character.
- 3. Load the UxTXREG with a dummy character to initiate transmission (value is ignored).
- 4. Write '55h' to UxTXREG loads the Sync character into the transmit FIFO.
- 5. After the Break has been sent, the UTXBRK bit is reset by hardware. The Sync character now transmits.

18.5 Receiving in 8-Bit or 9-Bit Data Mode

- 1. Set up the UARTx (as described in Section 18.2 "Transmitting in 8-Bit Data Mode").
- 2. Enable the UARTx.
- 3. A receive interrupt will be generated when one or more data characters have been received, as per interrupt control bit, URXISELx.
- 4. Read the OERR bit to determine if an overrun error has occurred. The OERR bit must be reset in software.
- 5. Read UxRXREG.

The act of reading the UxRXREG character will move the next character to the top of the receive FIFO, including a new set of PERR and FERR values.

18.6 Operation of UxCTS and UxRTS Control Pins

UARTx Clear-to-Send (UxCTS) and Request-to-Send (UxRTS) are the two hardware-controlled pins that are associated with the UARTx module. These two pins allow the UARTx to operate in Simplex and Flow Control modes. They are implemented to control the transmission and reception between the Data Terminal Equipment (DTE). The UEN<1:0> bits in the UxMODE register configure these pins.

18.7 Infrared Support

The UARTx module provides two types of infrared UARTx support: one is the IrDA clock output to support an external IrDA encoder and decoder device (legacy module support), and the other is the full implementation of the IrDA encoder and decoder.

As the IrDA modes require a 16x baud clock, they will only work when the BRGH bit (UxMODE<3>) is '0'.

18.7.1 EXTERNAL IrDA SUPPORT – IrDA CLOCK OUTPUT

To support external IrDA encoder and decoder devices, the UxBCLK pin (same as the UxRTS pin) can be configured to generate the 16x baud clock. When UEN<1:0> = 11, the UxBCLK pin will output the 16x baud clock if the UARTx module is enabled; it can be used to support the IrDA codec chip.

18.7.2 BUILT-IN IrDA ENCODER AND DECODER

The UARTx has full implementation of the IrDA encoder and decoder as part of the UARTx module. The built-in IrDA encoder and decoder functionality is enabled using the IREN bit (UxMODE<12>). When enabled (IREN = 1), the receive pin (UxRX) acts as the input from the infrared receiver. The transmit pin (UxTX) acts as the output to the infrared transmitter.

20.1.3 DATA SHIFT DIRECTION

The LENDIAN bit (CRCCON1<3>) is used to control the shift direction. By default, the CRC will shift data through the engine, MSb first. Setting LENDIAN (= 1) causes the CRC to shift data, LSb first. This setting allows better integration with various communication schemes and removes the overhead of reversing the bit order in software. Note that this only changes the direction of the data that is shifted into the engine. The result of the CRC calculation will still be a normal CRC result, not a reverse CRC result.

20.1.4 INTERRUPT OPERATION

The module generates an interrupt that is configurable by the user for either of two conditions. If CRCISEL is '0', an interrupt is generated when the VWORD<4:0> bits make a transition from a value of '1' to '0'. If CRCISEL is '1', an interrupt will be generated after the CRC operation finishes and the module sets the CRCGO bit to '0'. Manually setting CRCGO to '0' will not generate an interrupt.

20.1.5 TYPICAL OPERATION

To use the module for a typical CRC calculation:

- 1. Set the CRCEN bit to enable the module.
- 2. Configure the module for the desired operation:
 - a) Program the desired polynomial using the CRCXORL and CRCXORH registers, and the PLEN<4:0> bits.
 - b) Configure the data width and shift direction using the DWIDTHx and LENDIAN bits.
 - c) Select the desired interrupt mode using the CRCISEL bit.
- 3. Preload the FIFO by writing to the CRCDATL and CRCDATH registers until the CRCFUL bit is set or no data is left.
- 4. Clear old results by writing 00h to CRCWDATL and CRCWDATH. CRCWDAT can also be left unchanged to resume a previously halted calculation.
- 5. Set the CRCGO bit to start calculation.
- 6. Write the remaining data into the FIFO as space becomes available.
- When the calculation completes, CRCGO is automatically cleared. An interrupt will be generated if CRCISEL = 1.
- 8. Read CRCWDATL and CRCWDATH for the result of the calculation.

20.2 Registers

There are eight registers associated with the module:

- CRCCON1
- CRCCON2
- CRCXORL
- CRCXORH
- CRCDATL
- CRCDATH
- CRCWDATL
- CRCWDATH

The CRCCON1 and CRCCON2 registers (Register 20-1 and Register 20-2) control the operation of the module, and configure the various settings. The CRCXOR registers (Register 20-3 and Register 20-4) select the polynomial terms to be used in the CRC equation. The CRCDAT and CRCWDAT registers are each register pairs that serve as buffers for the double-word, input data and CRC processed output, respectively.

REGISTER 20-3: CRCXORL: CRC XOR POLYNOMIAL REGISTER, LOW BYTE

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
X15	X14	X13	X12	X11	X10	X9	X8		
bit 15							bit 8		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0		
X7	X6	X5	X4	X3	X2	X1	—		
bit 7							bit 0		
Legend:									
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'					
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit i				x = Bit is unkr	nown				

bit 15-1 X<15:1>: XOR of Polynomial Term Xⁿ Enable bits

bit 0 Unimplemented: Read as '0'

REGISTER 20-4: CRCXORH: CRC XOR POLYNOMIAL REGISTER, HIGH BYTE

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
X31	X30	X29	X28	X27	X26	X25	X24			
bit 15		•		•			bit 8			
	5444.0			54446		D 444 A	B 844 A			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
X23	X22	X21	X20	X19	X18	X17	X16			
bit 7							bit 0			
Logond:										
Legenu.	1.11									
R = Readable bit W = Writable bit		DIT	U = Unimplemented bit, read as '0'							
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = B		x = Bit is unkr	nown							

bit 15-0 X<31:16>: XOR of Polynomial Term Xⁿ Enable bits

	-		-					
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
CH0NB2	2 CH0NB1	CH0NB0	CH0SB4	CH0SB3	CH0SB2	CH0SB1	CH0SB0	
bit 15							bit 8	
P/M/-0	P/M/-0		P/M/-0				P///_0	
CHONA:	CH0NA1	CHONA0	CH0SA4	CH0SA3	CH0SA2	CH0SA1	CH0SA0	
bit 7			01100/11	01100/10	01100/12	01100/11	bit 0	
Legend:								
R = Reada	able bit	W = Writable I	oit	U = Unimplen	nented bit, read	l as '0'		
-n = Value	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown	
bit 15-13 CH0NB<2:0>: Sample B Channel 0 Negative Input Select bits 111 = AN6 ⁽¹⁾ 110 = AN5 ⁽²⁾ 101 = AN4 100 = AN3 011 = AN2 010 = AN1 001 = AN0 000 = AVSS bit 12-8 CH0SB<4:0>: S/H Amplifier Positive Input Select for MLX B Multiplever Setting bits								
DIL 12-0	11111 = Unir 11111 = AVD 11101 = AVS 11100 = Upp 11011 = Low 11001 = Inter 11001 = No of 10001 = No of 10000 = No of 01111 = AN1 01101 = AN1 01101 = AN1 01011 = AN1 01010 = AN1 01010 = AN2 01000 = AN8 00111 = AN5 00100 = AN4 00111 = AN3 00010 = AN2 00001 = AN1 00001 = AN2 00001 = AN1	nplemented, do D S er guardband ra er guardband ra rnal Band Gap I D = Unimplement channels are co channels are co channels are co channels are co f 4 3 2 1 0 (1) (1) (2)	ail (0.785 * Voi ail (0.215 * Voi Reference (VB nted, do not us nnected, all in nnected, all in	D) D) G)(3) Be puts are floating puts are floating	g (used for CTN g (used for CTN	MU) MU temperature	e sensor input)	
bit 7-5	CH0NA<2:0> The same def	: Sample A Cha finitions as for C	annel 0 Negati CHONB<2:0>.	ve Input Select	bits			
bit 4-0	CH0SA<4:0> The same def	: Sample A Cha finitions as for C	annel 0 Positiv CHONA<4:0>.	e Input Select b	oits			
Note 1: 2:	This is implement This is implement	ed on 44-pin de ed on 28-pin ar	evices only. 1d 44-pin devic	ces only.				

REGISTER 22-5: AD1CHS: A/D SAMPLE SELECT REGISTER

REGISTER 22-8:	AD1CSSH: A/D INPUT SCAN SELECT REGISTER (HIGH WORD) ⁽¹⁾	
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U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0		
_	CSS30	CSS29	CSS28	CSS27	CSS26		—		
bit 15							bit 8		
U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0		
—	—	—		—	—	CSS17	CSS16		
bit 7							bit 0		
Legend:									
R = Readable	bit	W = Writable I	oit	U = Unimplemented bit, read as '0'					
-n = Value at POR '1' = Bit is set			'0' = Bit is clea	ared	x = Bit is unknown				
bit 15	bit 15 Unimplemented: Read as '0'								

- bit 14-10CSS<30:26>: A/D Input Scan Selection bits
1 = Includes corresponding channel for input scan
0 = Skips channel for input scanbit 9-2Unimplemented: Read as '0'bit 1-0CSS<17:16>: A/D Input Scan Selection bits
 - 1 = Includes corresponding channel for input scan
 - 0 = Skips channel for input scan
- **Note 1:** Unimplemented channels are read as '0'. Do not select unimplemented channels for sampling as indeterminate results may be produced.

REGISTER 22-9: AD1CSSL: A/D INPUT SCAN SELECT REGISTER (LOW WORD)⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSS15	CSS14	CSS13	CSS12	CSS11	CSS10	CSS9	CSS8
bit 15		•	•		<u> </u>		bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSS7	CSS6	CSS5	CSS4	CSS3	CSS2	CSS1	CSS0
bit 7		•	•		<u> </u>		bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 C

CSS<15:0>: A/D Input Scan Selection bits

- 1 = Includes corresponding ANx input for scan
- 0 = Skips channel for input scan

Note 1: Unimplemented channels are read as '0'. Do not select unimplemented channels for sampling as indeterminate results may be produced.

REGISTER 23-1: CMxCON: COMPARATOR x CONTROL REGISTERS (CONTINUED)

bit 4	CREF: Comparator x Reference Select bits (non-inverting input)
	1 = Non-inverting input connects to the internal CVREF voltage
	0 = Non-inverting input connects to the CxINA pin
bit 3-2	Unimplemented: Read as '0'
bit 1-0	CCH<1:0>: Comparator x Channel Select bits
	11 = Inverting input of the comparator connects to VBG
	10 = Inverting input of the comparator connects to the CxIND pin
	01 = Inverting input of the comparator connects to the CxINC pin

00 = Inverting input of the comparator connects to the CxINB pin

REGISTER 23-2: CMSTAT: COMPARATOR x MODULE STATUS REGISTER

R/W-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
CMIDL	—	—	—	—	C3EVT	C2EVT	C1EVT
bit 15 bit 8							

U-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
—	—	—	—	—	C3OUT	C2OUT	C1OUT
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15	 CMIDL: Comparator x Stop in Idle Mode bit 1 = Comparator interrupts are disabled in Idle mode; enabled comparators remain operational 0 = Continues operation of all enabled comparators in Idle mode
bit 14-11	Unimplemented: Read as '0'
bit 10	C3EVT: Comparator 3 Event Status bit (read-only)
	Shows the current event status of Comparator 3 (CM3CON<9>).
bit 9	C2EVT: Comparator 2 Event Status bit (read-only)
	Shows the current event status of Comparator 2 (CM2CON<9>).
bit 8	C1EVT: Comparator 1 Event Status bit (read-only)
	Shows the current event status of Comparator 1 (CM1CON<9>).
bit 7-3	Unimplemented: Read as '0'
bit 2	C3OUT: Comparator 3 Output Status bit (read-only)
	Shows the current output of Comparator 3 (CM3CON<8>).
bit 1	C2OUT: Comparator 2 Output Status bit (read-only)
	Shows the current output of Comparator 2 (CM2CON<8>).
bit 0	C1OUT: Comparator 1 Output Status bit (read-only)
	Shows the current output of Comparator 1 (CM1CON<8>).

REGISTER 25-2: CTMUCON2: CTMU CONTROL REGISTER 2 (CONTINUED)

- bit 6 EDG2POL: Edge 2 Polarity Select bit 1 = Edge 2 is programmed for a positive edge 0 = Edge 2 is programmed for a negative edge bit 5-2 EDG2SEL<3:0>: Edge 2 Source Select bits 1111 = Edge 2 source is Comparator 3 output 1110 = Edge 2 source is Comparator 2 output 1101 = Edge 2 source is Comparator 1 output 1100 = Unimplemented; do not use 1011 = Edge 2 source is IC3 1010 = Edge 2 source is IC2 1001 = Edge 2 source is IC1 1000 = Edge 2 source is CTED13⁽²⁾ 0111 = Edge 2 source is CTED12^(1,2) 0110 = Edge 2 source is CTED11^(1,2) 0101 = Edge 2 source is CTED10 0100 = Edge 2 source is CTED9 0011 = Edge 2 source is CTED1 0010 = Edge 2 source is CTED2 0001 = Edge 2 source is OC1 0000 = Edge 2 source is Timer1
- bit 1-0 Unimplemented: Read as '0'
- Note 1: Edge sources, CTED11 and CTED12, are not available on PIC24FV32KA302 devices.
 - 2: Edge sources, CTED3, CTED11, CTED12 and CTED13, are not available on PIC24FV32KA301 devices.

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0
bit 15	•	•			•		bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
							<u> </u>
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable I	oit	U = Unimplem	nented bit, read	1 as '0'	
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	Iown
bit 15-10 ITRIM<5:0>: Current Source Trim bits 011111 = Maximum positive change from nominal current 011110 000001 = Minimum positive change from nominal current 000000 = Nominal current output specified by IRNG<1:0> 111111 = Minimum negative change from nominal current 100010 100001 = Maximum negative change from nominal current							
bit 9-8	IRNG<1:0>: Current Source Range Select bits 11 = 100 × Base Current 10 = 10 × Base Current 01 = Base Current Level (0.55 μA nominal) 00 = 1000 × Base Current Unimplemented: Read as '0'						

REGISTER 25-3: CTMUICON: CTMU CURRENT CONTROL REGISTER

FIGURE 29-16: UARTX BAUD RATE GENERATOR OUTPUT TIMING



FIGURE 29-17: UARTX START BIT EDGE DETECTION



TABLE 29-35: UARTx TIMING REQUIREMENTS

		$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Symbol	Characteristics	Min	Тур	Max	Units		
TLW	UxBCLK High Time	20	Tcy/2	_	ns		
THW	UxBCLK Low Time	20	(TCY * UXBRG) + TCY/2	—	ns		
TBLD	UxBCLK Falling Edge Delay from UxTX	-50	—	50	ns		
Твнр	UxBCLK Rising Edge Delay from UxTX	Tcy/2 – 50	—	Tcy/2 + 50	ns		
Тwak	Minimum Low on UxRX Line to Cause Wake-up	—	1	—	μS		
Тстѕ	Minimum Low on UxCTS Line to Start Transmission	Тсу	_	_	ns		
TSETUP	Start bit Falling Edge to System Clock Rising Edge Setup Time	3	—	—	ns		
TSTDELAY	Maximum Delay in the Detection of the Start bit Falling Edge	—	—	TCY + TSETUP	ns		

30.0 DC AND AC CHARACTERISTICS GRAPHS AND TABLES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore, outside the warranted range.

Data for VDD levels greater than 3.3V are applicable to PIC24FV32KA304 family devices only.

30.1 Characteristcs for Industrial Temperature Devices (-40°C to +85°C)



Frequency (MHz)

18

22

26

30

FIGURE 30-2: TYPICAL AND MAXIMUM IDD vs. Fosc (EC MODE, 1.95 kHz TO 1 MHz, +25°C)



2

6

10

14

30.2 Characteristics for Extended Temperature Devices (-40°C to +125°C)

Note: Data for VDD levels greater than 3.3V are applicable to PIC24FV32KA304 family devices only.

FIGURE 30-40: TYPICAL AND MAXIMUM lidle vs. Vdd (FRC MODE)

libLE (mA)				
		VDD		

FIGURE 30-41: TYPICAL AND MAXIMUM lidle vs. TEMPERATURE (FRC MODE)

liple (mA)	
	Temperature (°C)

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging





	Units	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX	
Number of Pins	N		28		
Pitch	е		1.27 BSC		
Overall Height	A	-	-	2.65	
Molded Package Thickness	A2	2.05	-	-	
Standoff §	A1	0.10	-	0.30	
Overall Width	E		10.30 BSC		
Molded Package Width	7.50 BSC				
Overall Length	D		17.90 BSC		
Chamfer (Optional)	h	0.25	-	0.75	
Foot Length	L	0.40	-	1.27	
Footprint	L1		1.40 REF		
Lead Angle	Θ	0°	-	-	
Foot Angle	φ	0°	-	8°	
Lead Thickness	С	0.18	-	0.33	
Lead Width	b	0.31	-	0.51	
Mold Draft Angle Top	α	5°	-	15°	
Mold Draft Angle Bottom	β	5°	-	15°	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.
- 5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2

28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	E		0.65 BSC	
Optional Center Pad Width	W2			4.25
Optional Center Pad Length	T2			4.25
Contact Pad Spacing	C1		5.70	
Contact Pad Spacing	C2		5.70	
Contact Pad Width (X28)	X1			0.37
Contact Pad Length (X28)	Y1			1.00
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2105A

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	E	E 0.65 BSC		
Optional Center Pad Width	W2			6.60
Optional Center Pad Length	T2			6.60
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.85
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2103B

48-Lead Ultra Thin Plastic Quad Flat, No Lead Package (MV) - 6x6 mm Body [UQFN] With 0.40 mm Contact Length





Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.40 BSC		
Optional Center Pad Width	W2			4.45
Optional Center Pad Length	T2			4.45
Contact Pad Spacing	C1		6.00	
Contact Pad Spacing	C2		6.00	
Contact Pad Width (X28)	X1			0.20
Contact Pad Length (X28)	Y1			0.80
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2153A