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Details

Product Status	Obsolete
Core Processor	XC800
Core Size	8-Bit
Speed	27MHz
Connectivity	LINbus, SPI, SSI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	40
Program Memory Size	52KB (52K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3.25K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	PG-LQFP-64-4
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/sax-xc878l-13ffa-5v-aa

XC87x Data Sheet**Revision History: V1.5 2011-03**

Previous Versions: V1.4

Page	Subjects (major changes since last revision)
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Changes from V1.4 2010-08 to V1.5 2011-03

Page 3	A new variant, SAF-XC874CM-13FVA 5V, has been added in Table 2.
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General Device Information

2.3 Pin Configuration

The pin configuration of the XC878, which is based on the PG-LQFP-64, is shown in **Figure 4**, while that of the XC874, which is based on the PG-VQFN-48 package, is shown in **Figure 5**.

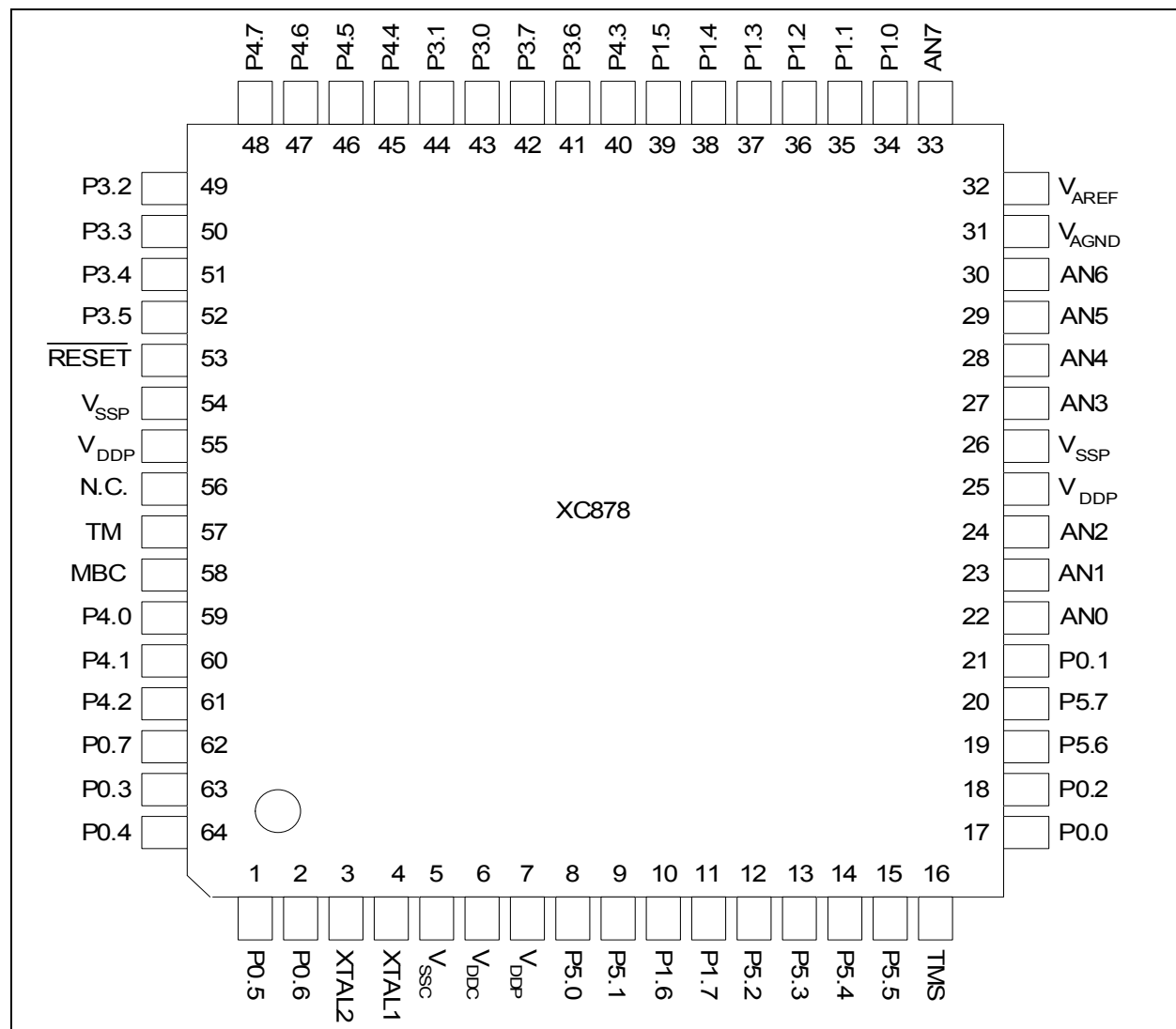


Figure 4 XC878 Pin Configuration, PG-LQFP-64 Package (top view)

General Device Information
Table 3 Pin Definitions and Functions (cont'd)

Symbol	Pin Number (LQFP-64 / VQFN-48)	Type	Reset State	Function
P5.5	15/-		PU	CCPOS2_0 CCU6 Hall Input 2 CTRAP_1 CCU6 Trap Input CC60_3 Input of Capture/Compare channel 0 TDO_1 JTAG Serial Data Output TXD1_2 UART1 Transmit Data Output/ Clock Output T2CC0_2/ External Interrupt Input 3/T2CCU EXINT3_3 Capture/Compare Channel 0 A5 Address Line 5 Output
P5.6	19/-		PU	TCK_1 JTAG Clock Input RXD01_2 UART1 Transmit Data Output T2CC1_2/ External Interrupt Input 4/T2CCU EXINT4_3 Capture/Compare Channel 1 A6 Address Line 6 Output
P5.7	20/-		PU	TDI_1 JTAG Serial Data Input RXD1_2 UART1 Receive Data Input T2CC3_2/ External Interrupt Input 6/T2CCU EXINT6_4 Capture/Compare Channel 3 A7 Address Line 7 Output

Functional Description

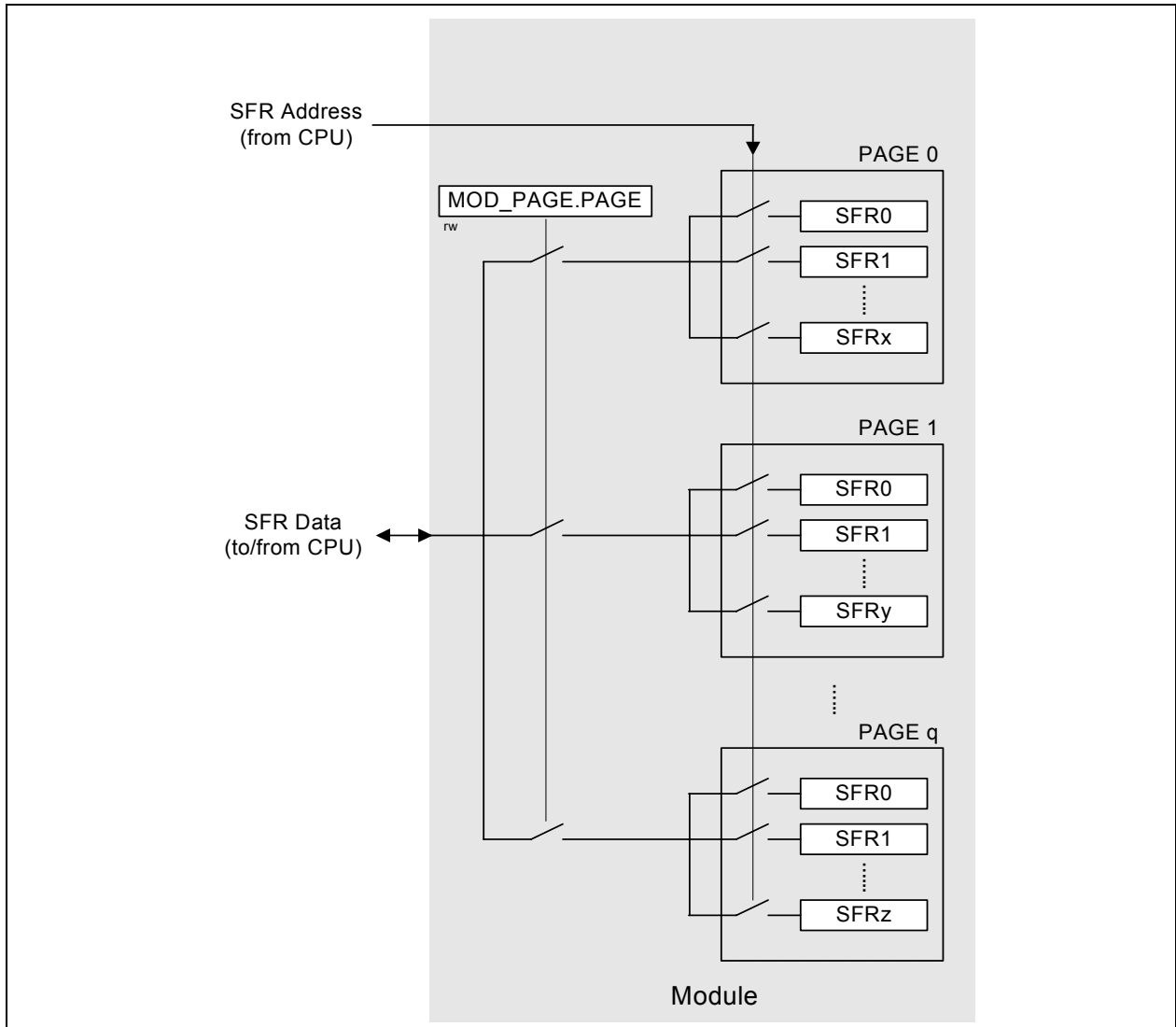


Figure 10 Address Extension by Paging

In order to access a register located in a page different from the actual one, the current page must be exited. This is done by reprogramming the bit field PAGE in the page register. Only then can the desired access be performed.

If an interrupt routine is initiated between the page register access and the module register access, and the interrupt needs to access a register located in another page, the current page setting can be saved, the new one programmed and the old page setting restored. This is possible with the storage fields STx (x = 0 - 3) for the save and restore action of the current page setting. By indicating which storage bit field should be used in parallel with the new page value, a single write operation can:

- Save the contents of PAGE in STx before overwriting with the new value (this is done in the beginning of the interrupt routine to save the current page setting and program the new page number); or

Functional Description
3.2.4.10 CCU6 Registers

The CCU6 SFRs can be accessed in the standard memory area (RMAP = 0).

Table 14 CCU6 Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
A3 _H	CCU6_PAGE Page Register Reset: 00 _H	Bit Field	OP		STNR		0	PAGE		
		Type	w		w		r	rwh		
RMAP = 0, PAGE 0										
9A _H	CCU6_CC63SRL Capture/Compare Shadow Register for Channel CC63 Low Reset: 00 _H	Bit Field	CC63SL							
		Type	rw							
9B _H	CCU6_CC63SRH Capture/Compare Shadow Register for Channel CC63 High Reset: 00 _H	Bit Field	CC63SH							
		Type	rw							
9C _H	CCU6_TCTR4L Timer Control Register 4 Low Reset: 00 _H	Bit Field	T12 STD	T12 STR	0		DT RES	T12 RES	T12R S	T12R R
		Type	w	w	r		w	w	w	w
9D _H	CCU6_TCTR4H Timer Control Register 4 High Reset: 00 _H	Bit Field	T13 STD	T13 STR	0			T13 RES	T13R S	T13R R
		Type	w	w	r			w	w	w
9E _H	CCU6_MCMOUTSL Multi-Channel Mode Output Shadow Register Low Reset: 00 _H	Bit Field	STRM CM	0	MCMPS					
		Type	w	r	rw					
9F _H	CCU6_MCMOUTSH Multi-Channel Mode Output Shadow Register High Reset: 00 _H	Bit Field	STRH P	0	CURHS			EXPHS		
		Type	w	r	rw			rw		
A4 _H	CCU6_ISRL Capture/Compare Interrupt Status Reset Register Low Reset: 00 _H	Bit Field	RT12 PM	RT12 OM	RCC6 2F	RCC6 2R	RCC6 1F	RCC6 1R	RCC6 0F	RCC6 0R
		Type	w	w	w	w	w	w	w	w
A5 _H	CCU6_ISRH Capture/Compare Interrupt Status Reset Register High Reset: 00 _H	Bit Field	RSTR	RIDLE	RWH E	RCHE	0	RTRP F	RT13 PM	RT13 CM
		Type	w	w	w	w	r	w	w	w
A6 _H	CCU6_CMPMODIFL Compare State Modification Register Low Reset: 00 _H	Bit Field	0	MCC6 3S	0			MCC6 2S	MCC6 1S	MCC6 0S
		Type	r	w	r			w	w	w
A7 _H	CCU6_CMPMODIFH Compare State Modification Register High Reset: 00 _H	Bit Field	0	MCC6 3R	0			MCC6 2R	MCC6 1R	MCC6 0R
		Type	r	w	r			w	w	w
FA _H	CCU6_CC60SRL Capture/Compare Shadow Register for Channel CC60 Low Reset: 00 _H	Bit Field	CC60SL							
		Type	rwh							
FB _H	CCU6_CC60SRH Capture/Compare Shadow Register for Channel CC60 High Reset: 00 _H	Bit Field	CC60SH							
		Type	rwh							

Functional Description

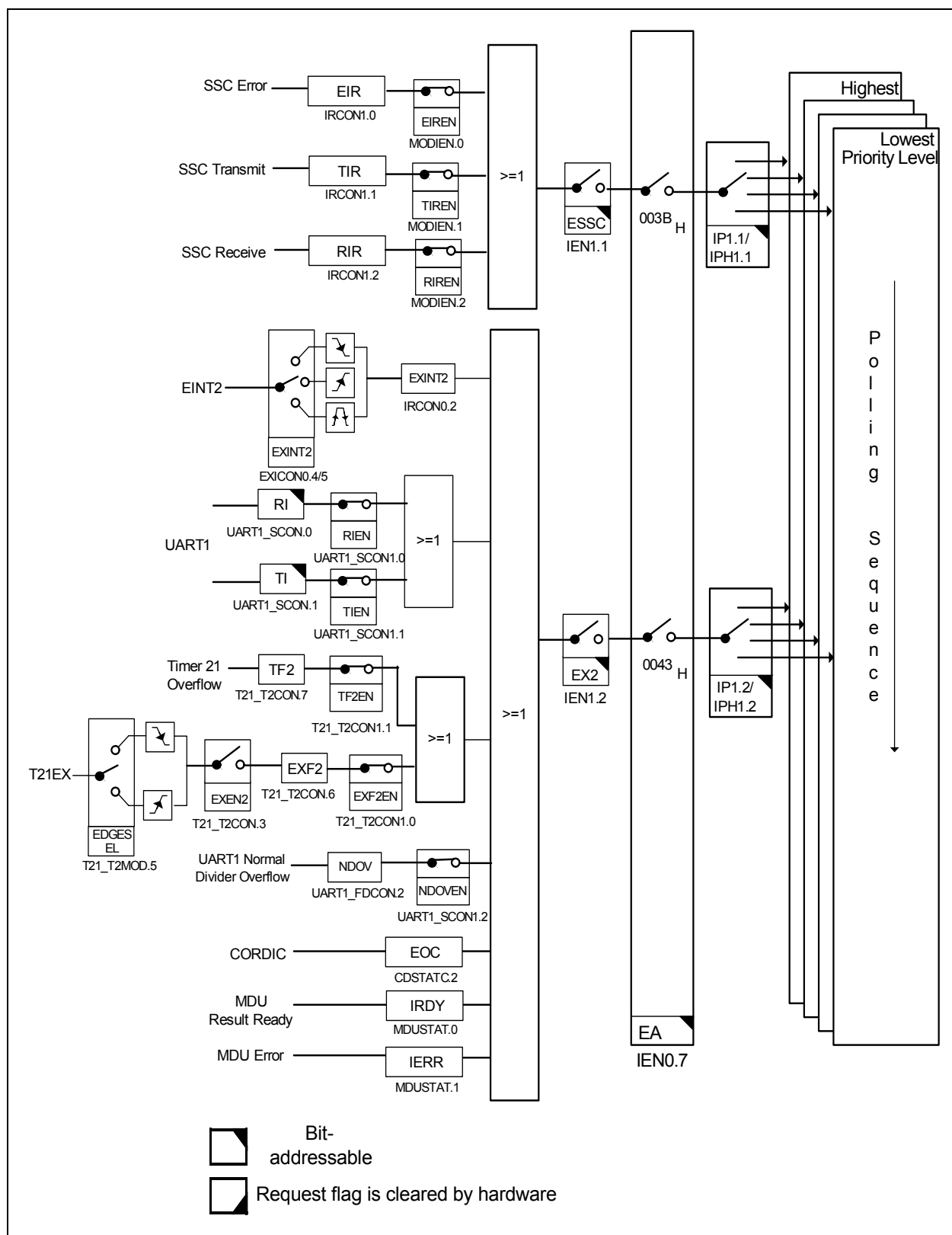


Figure 15 Interrupt Request Sources (Part 3)

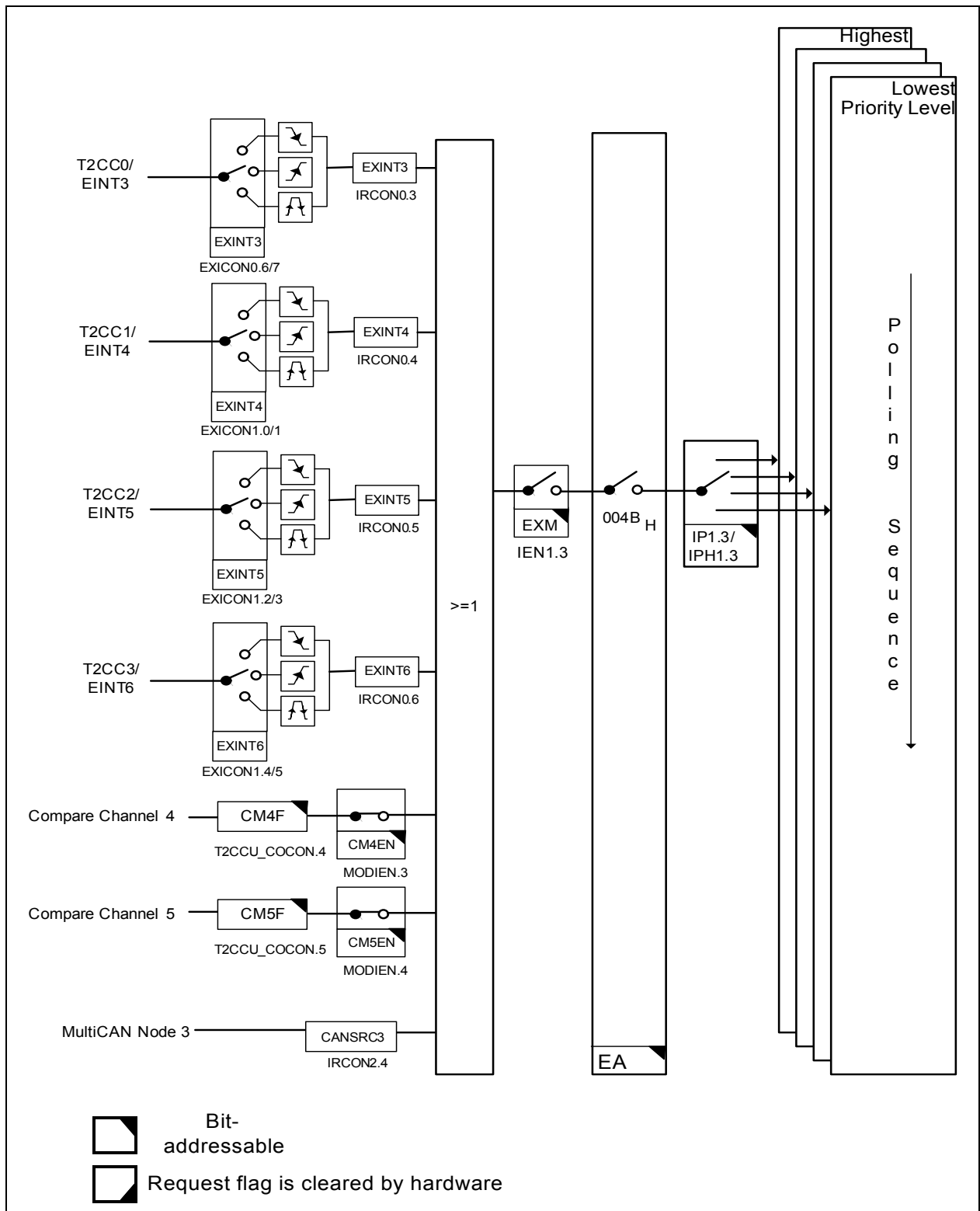


Figure 16 Interrupt Request Sources (Part 4)

Functional Description
Table 22 Interrupt Vector Addresses (cont'd)

Interrupt Source	Vector Address	Assignment for XC87x	Enable Bit	SFR
XINTR6	0033 _H	MultiCAN Nodes 1 and 2	EADC	IEN1
		ADC[1:0]		
XINTR7	003B _H	SSC	ESSC	
XINTR8	0043 _H	External Interrupt 2	EX2	
		T21		
		CORDIC		
		UART1		
		UART1 Fractional Divider (Normal Divider Overflow)		
		MDU[1:0]		
XINTR9	004B _H	External Interrupt 3	EXM	
		External Interrupt 4		
		External Interrupt 5		
		External Interrupt 6		
		T2CCU		
		MultiCAN Node 3		
XINTR10	0053 _H	CCU6 INP0	ECCIP0	
		MultiCAN Node 4		
XINTR11	005B _H	CCU6 INP1	ECCIP1	
		MultiCAN Node 5		
XINTR12	0063 _H	CCU6 INP2	ECCIP2	
		MultiCAN Node 6		
XINTR13	006B _H	CCU6 INP3	ECCIP3	
		MultiCAN Node 7		

3.7 Reset Control

The XC87x has five types of reset: power-on reset, hardware reset, watchdog timer reset, power-down wake-up reset, and brownout reset.

When the XC87x is first powered up, the status of certain pins (see [Table 25](#)) must be defined to ensure proper start operation of the device. At the end of a reset sequence, the sampled values are latched to select the desired boot option, which cannot be modified until the next power-on reset or hardware reset. This guarantees stable conditions during the normal operation of the device.

The second type of reset in XC87x is the hardware reset. This reset function can be used during normal operation or when the chip is in power-down mode. A reset input pin **RESET** is provided for the hardware reset.

The Watchdog Timer (WDT) module is also capable of resetting the device if it detects a malfunction in the system.

Another type of reset that needs to be detected is a reset while the device is in power-down mode (wake-up reset). While the contents of the static RAM are undefined after a power-on reset, they are well defined after a wake-up reset from power-down mode.

3.7.1 Module Reset Behavior

[Table 24](#) lists the functions of the XC87x and the various reset types that affect these functions. The symbol “■” signifies that the particular function is reset to its default state.

Table 24 Effect of Reset on Device Functions

Module/ Function	Wake-Up Reset	Watchdog Reset	Hardware Reset	Power-On Reset	Brownout Reset
CPU Core	■	■	■	■	■
Peripherals	■	■	■	■	■
On-Chip Static RAM	Not affected, Reliable	Not affected, Reliable	Not affected, Reliable	Affected, un- reliable	Affected, un- reliable
Oscillator, PLL	■	Not affected	■	■	■
Port Pins	■	■	■	■	■
EVR	The voltage regulator is switched on	Not affected	Not affected	■	■
FLASH	■	■	■	■	■
NMI	Disabled	Disabled	■	■	■

Functional Description

resistance method. Oscillation measurement with the final target system is strongly recommended to verify the input amplitude at XTAL1 and to determine the actual oscillation allowance (margin negative resistance) for the oscillator-crystal system.

When using an external clock signal, the signal must be connected to XTAL1. XTAL2 is left open (unconnected).

The oscillator can also be used in combination with a ceramic resonator. The final circuitry must also be verified by the resonator vendor. **Figure 21** shows the recommended external oscillator circuitries for both operating modes, external crystal mode and external input clock mode.

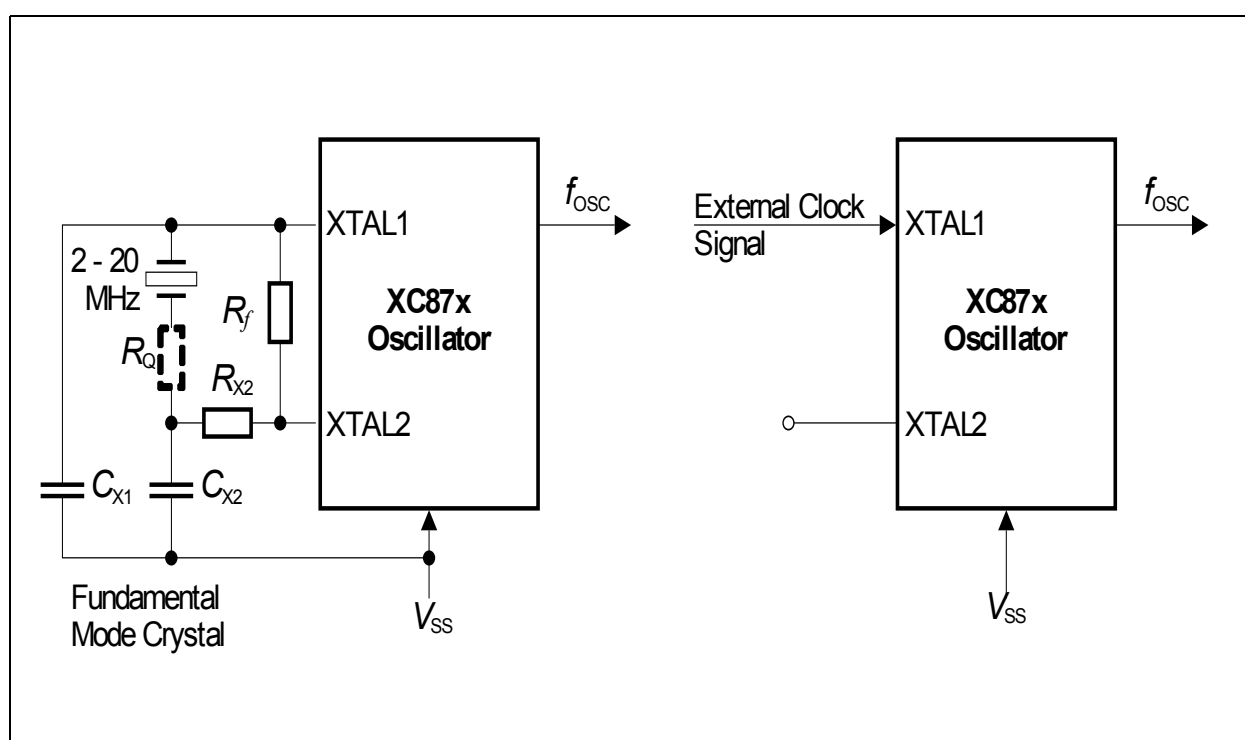


Figure 21 External Oscillator Circuitry

Note: For crystal operation, it is strongly recommended to measure the negative resistance in the final target system (layout) to determine the optimum parameters for the oscillator operation. Please refer to the minimum and maximum values of the negative resistance specified by the crystal supplier.

Functional Description

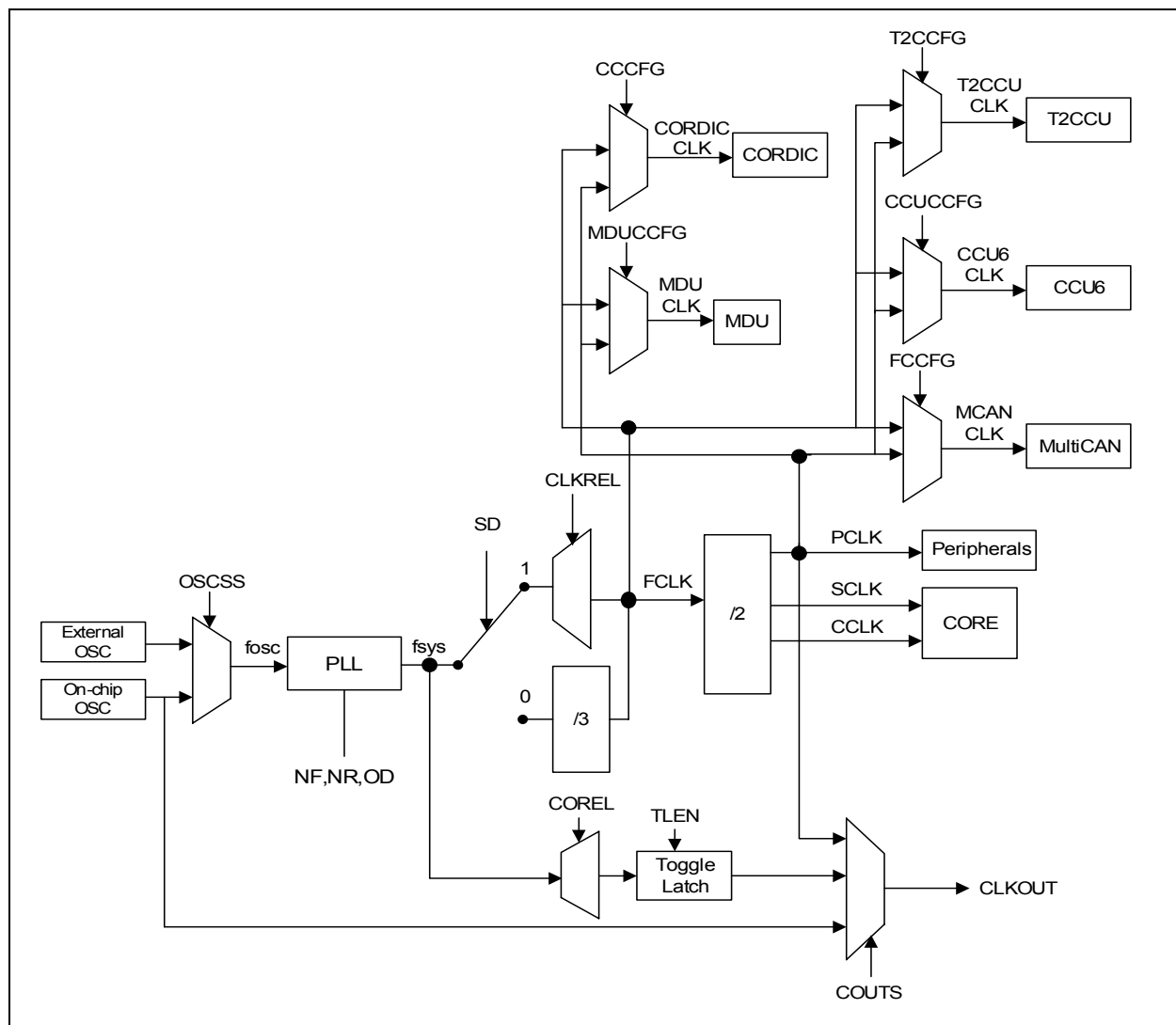


Figure 22 Clock Generation from f_{sys}

Table 32 Deviation Error for UART with Fractional Divider enabled

f_{PCLK}	Prescaling Factor (2BRPRE)	Reload Value (BR_VALUE + 1)	STEP	Deviation Error
24 MHz	1	6 (6 _H)	59 (3B _H)	+0.03 %
12 MHz	1	3 (3 _H)	59 (3B _H)	+0.03 %
8 MHz	1	2 (2 _H)	59 (3B _H)	+0.03 %
6 MHz	1	6 (6 _H)	236 (EC _H)	+0.03 %

3.13.2 Baud Rate Generation using Timer 1

In UART modes 1 and 3 of UART module, Timer 1 can be used for generating the variable baud rates. In theory, this timer could be used in any of its modes. But in practice, it should be set into auto-reload mode (Timer 1 mode 2), with its high byte set to the appropriate value for the required baud rate. The baud rate is determined by the Timer 1 overflow rate and the value of SMOD as follows:

$$\text{Mode 1, 3 baud rate} = \frac{2^{\text{SMOD}} \times f_{PCLK}}{32 \times 2 \times (256 - \text{TH1})} \quad (3.6)$$

3.14 Normal Divider Mode (8-bit Auto-reload Timer)

Setting bit FDM in register FDCON to 1 configures the fractional divider to normal divider mode, while at the same time disables baud rate generation (see [Figure 26](#)). Once the fractional divider is enabled (FDEN = 1), it functions as an 8-bit auto-reload timer (with no relation to baud rate generation) and counts up from the reload value with each input clock pulse. Bit field RESULT in register FDRES represents the timer value, while bit field STEP in register FDSTEP defines the reload value. At each timer overflow, an overflow flag (FDCON.NDOV) will be set and an interrupt request generated. This gives an output clock f_{MOD} that is 1/n of the input clock f_{DIV} , where n is defined by 256 - STEP. The output frequency in normal divider mode is derived as follows:

$$f_{MOD} = f_{DIV} \times \frac{1}{256 - \text{STEP}} \quad (3.7)$$

3.19 Timer 2 Capture/Compare Unit

The T2CCU (Timer 2 Capture/Compare Unit) consists of the standard Timer 2 unit and a Capture/compare unit (CCU). The Capture/Compare Timer (CCT) is part of the CCU. Control is available in the T2CCU to select individually for each of its 16-bit capture/compare channel, either the Timer 2 or the Capture/Compare Timer (CCT) as the time base. Both timers have a resolution of 16 bits. The clock frequency of T2CCU, f_{T2CCU} , could be set at PCLK frequency or 2 times the PCLK frequency.

The T2CCU can be used for various digital signal generation and event capturing like pulse generation, pulse width modulation, pulse width measuring etc. Target applications include various automotive control as well as industrial (frequency generation, digital-to-analog conversion, process control etc.).

T2CCU Features

- Option to select individually for each channel, either Timer 2 or Capture/Compare Timer as time base
- Extremely flexible Capture/Compare Timer count rate by cascading with Timer 2
- Capture/Compare Timer may be 'reset' immediately by triggering overflow event
- 16-bit resolution
- Six compare channels in total
- Four capture channels multiplexed with the compare channels, in total
- Shadow register for each compare register
 - Transfer via software control or on timer overflow.
- Compare Mode 0: Compare output signal changes from the inactive level to active level on compare match. Returns to inactive level on timer overflow.
 - Active level can be defined by register bit for channel groups A and B.
 - Support of 0% to 100% duty cycle in compare mode 0.
- Compare Mode 1: Full control of the software on the compare output signal level, for the next compare match.
- Concurrent Compare Mode with channel 0
- Capture Mode 0: Capture on any external event (rising/falling/both edge) at the 4 pins T2CC0 to T2CC3.
- Capture Mode 1: Capture upon writing to the low byte of the corresponding channel capture register.
- Capture mode 0 or 1 can be established independently on the 4 capture channels.

Electrical Parameters
4.2.4 Power Supply Current

Table 43, **Table 44**, **Table 45** and **Table 46** provide the characteristics of the power supply current in the XC87x.

**Table 43 Power Supply Current Parameters (Operating Conditions apply;
 $V_{DDP} = 5V$ range)**

Parameter	Symbol	Limit Values		Unit	Test Conditions
		typ. ¹⁾	max. ²⁾		
$V_{DDP} = 5V$ Range					
Active Mode	I_{DDP}	37.5	45	mA	³⁾ SAF and SAX variants
		40.5	48	mA	³⁾ SAK variant
Idle Mode	I_{DDP}	29.2	35	mA	⁴⁾ SAF and SAX variants
		32.2	38	mA	⁴⁾ SAK variant
Active Mode with slow-down enabled	I_{DDP}	10	15	mA	⁵⁾ SAF and SAX variants
		13	18	mA	⁵⁾ SAK variant
Idle Mode with slow-down enabled	I_{DDP}	9.2	14	mA	⁶⁾ SAF and SAX variants
		12.2	17	mA	⁶⁾ SAK variant

1) The typical I_{DDP} values are based on preliminary measurements and are to be used as reference only. These values are periodically measured at $T_A = +25\text{ °C}$ and $V_{DDP} = 5.0\text{ V}$.

2) The maximum I_{DDP} values are measured under worst case conditions ($T_A = +105\text{ °C}$ and $V_{DDP} = 5.5\text{ V}$).

3) I_{DDP} (active mode) is measured with: CPU clock and input clock to all peripherals running at 24 MHz with on-chip oscillator of 4 MHz, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

4) I_{DDP} (idle mode) is measured with: CPU clock disabled, watchdog timer disabled, input clock to all peripherals enabled and running at 24 MHz, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

5) I_{DDP} (active mode with slow-down mode) is measured with: CPU clock and input clock to all peripherals running at 1 MHz by setting CLKREL in CMCON to 1000_B, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

6) I_{DDP} (idle mode with slow-down mode) is measured with: CPU clock disabled, watchdog timer disabled, input clock to all peripherals enabled and running at 1 MHz by setting CLKREL in CMCON to 1000_B, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

Electrical Parameters

**Table 45 Power Supply Current Parameters¹⁾ (Operating Conditions apply;
 $V_{DDP} = 3.3V$ range)**

Parameter	Symbol	Limit Values		Unit	Test Conditions
		typ. ²⁾	max. ³⁾		
$V_{DDP} = 3.3V$ Range					
Active Mode	I_{DDP}	35.4	43	mA	⁴⁾
Idle Mode	I_{DDP}	27.6	33	mA	⁵⁾
Active Mode with slow-down enabled	I_{DDP}	8.6	13	mA	⁶⁾
Idle Mode with slow-down enabled	I_{DDP}	8	12	mA	⁷⁾

1) The table is only applicable to SAF and SAX variants.

2) The typical I_{DDP} values are based on preliminary measurements and are to be used as reference only. These values are periodically measured at $T_A = +25\text{ °C}$ and $V_{DDP} = 3.3\text{ V}$.

3) The maximum I_{DDP} values are measured under worst case conditions ($T_A = +105\text{ °C}$ and $V_{DDP} = 3.6\text{ V}$).

4) I_{DDP} (active mode) is measured with: CPU clock and input clock to all peripherals running at 24 MHz with on-chip oscillator of 4 MHz, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

5) I_{DDP} (idle mode) is measured with: CPU clock disabled, watchdog timer disabled, input clock to all peripherals enabled and running at 24 MHz, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

6) I_{DDP} (active mode with slow-down mode) is measured with: CPU clock and input clock to all peripherals running at 1 MHz by setting CLKREL in CMCON to 1000_B, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

7) I_{DDP} (idle mode with slow-down mode) is measured with: CPU clock disabled, watchdog timer disabled, input clock to all peripherals enabled and running at 1 MHz by setting CLKREL in CMCON to 1000_B, $\overline{\text{RESET}} = V_{DDP}$; all other pins are disconnected, no load on ports.

Electrical Parameters

Table 46 Power Down Current¹⁾(Operating Conditions apply; $V_{DDP} = 3.3V$ range)

Parameter	Symbol	Limit Values		Unit	Test Conditions
		typ. ²⁾	max. ³⁾		
$V_{DDP} = 3.3V$ Range					
Power-Down Mode	I_{PDP}	20	80	μA	$T_A = + 25\text{ }^{\circ}C^{4)5)}$
		-	250	μA	$T_A = + 85\text{ }^{\circ}C^{5)6)}$

1) The table is only applicable to SAF and SAX variants.

2) The typical I_{PDP} values are based on preliminary measurements and are to be used as reference only. These values are measured at $V_{DDP} = 3.3\text{ V}$.

3) The maximum I_{PDP} values are measured at $V_{DDP} = 3.6\text{ V}$.

4) I_{PDP} has a maximum value of $450\text{ }\mu A$ at $T_A = + 105\text{ }^{\circ}C$.

5) I_{PDP} is measured with: $\overline{RESET} = V_{DDP}$, $V_{AGND} = V_{SS}$, $RXD/INT0 = V_{DDP}$; rest of the ports are programmed to be input with either internal pull devices enabled or driven externally to ensure no floating inputs.

6) Not subjected to production test, verified by design/characterization.

Electrical Parameters

4.3.4 On-Chip Oscillator Characteristics

Table 49 provides the characteristics of the on-chip oscillator in the XC87x.

Table 49 On-chip Oscillator Characteristics (Operating Conditions apply)

Parameter	Symbol	Limit Values			Unit	Test Conditions
		min.	typ.	max.		
Nominal frequency	f_{NOM} CC	3.88	4	4.12	MHz	under nominal conditions ¹⁾ after IFX-backend trimming
Long term frequency deviation	Δf_{LT} CC	-5	–	5	%	with respect to f_{NOM} , over lifetime and temperature (-40°C to 105°C), for one given device after trimming
Short term frequency deviation	Δf_{ST} CC	-1.0	–	1.0	%	within one LIN message (<10 ms 100 ms)

1) Nominal condition: $V_{\text{DDC}} = 2.5 \text{ V}$, $T_{\text{A}} = +25^{\circ}\text{C}$.

Electrical Parameters

4.3.7 JTAG Timing

Table 53 provides the characteristics of the JTAG timing in the XC87x.

Table 53 TCK Clock Timing (Operating Conditions apply; CL = 50 pF)

Parameter	Symbol		Limits		Unit	Test Conditions
			min	max		
TCK clock period	t_{TCK}	SR	50	-	ns	1)
TCK high time	t_1	SR	20	-	ns	1)
TCK low time	t_2	SR	20	-	ns	1)
TCK clock rise time	t_3	SR	-	4	ns	1)
TCK clock fall time	t_4	SR	-	4	ns	1)

1) Not all parameters are 100% tested, but are verified by design/characterization and test correlation.

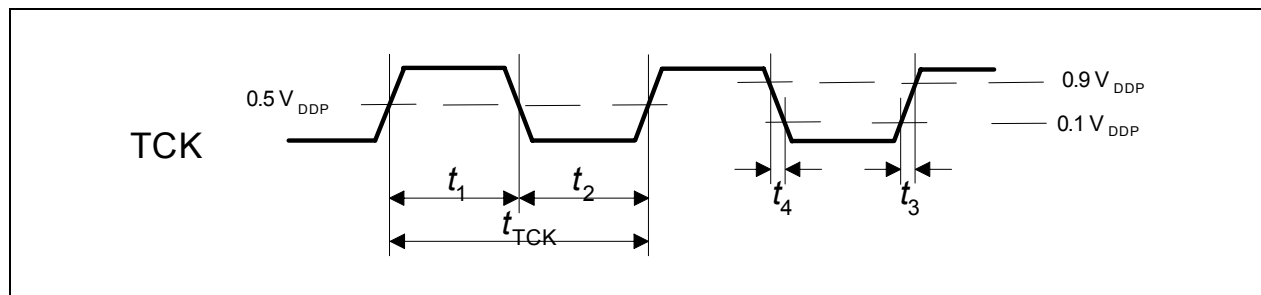






Figure 44 TCK Clock Timing

Table 54 JTAG Timing (Operating Conditions apply; CL = 50 pF)

Parameter	Symbol		Limits		Unit	Test Conditions
			min	max		
TMS setup to TCK 	t_1	SR	8	-	ns	1)
TMS hold to TCK 	t_2	SR	0	-	ns	1)
TDI setup to TCK 	t_1	SR	8	-	ns	1)
TDI hold to TCK 	t_2	SR	4	-	ns	1)
TDO valid output from TCK	t_3	CC	-	24	ns	5V Device ¹⁾
			-	31	ns	3.3V Device ¹⁾