Infineon Technologies - XC87816FFI5VACFXUMA1 Datasheet

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	XC800
Core Size	8-Bit
Speed	27MHz
Connectivity	SPI, SSI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	40
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3.25K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	PG-LQFP-64-4
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/xc87816ffi5vacfxuma1

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Table 2 Device Profile (cont'd)

Sales Type	Device Type	Program Memory (Kbytes)	Power Supply (V)	Temp-erature (°C)	Quality Profile
SAF-XC878CM-13FFI 3V3	Flash	52	3.3	-40 to 85	Industrial
SAF-XC878-16FFI 3V3	Flash	64	3.3	-40 to 85	Industrial
SAF-XC878M-16FFI 3V3	Flash	64	3.3	-40 to 85	Industrial
SAF-XC878CM-16FFI 3V3	Flash	64	3.3	-40 to 85	Industrial
SAF-XC878-13FFA 5V	Flash	52	5.0	-40 to 85	Automotive
SAF-XC878CM-13FFA 5V	Flash	52	5.0	-40 to 85	Automotive
SAF-XC878LM-13FFA 5V	Flash	52	5.0	-40 to 85	Automotive
SAF-XC878CLM-13FFA 5V	Flash	52	5.0	-40 to 85	Automotive
SAF-XC878-16FFA 5V	Flash	64	5.0	-40 to 85	Automotive
SAF-XC878CM-16FFA 5V	Flash	64	5.0	-40 to 85	Automotive
SAF-XC878LM-16FFA 5V	Flash	64	5.0	-40 to 85	Automotive
SAF-XC878CLM-16FFA 5V	Flash	64	5.0	-40 to 85	Automotive
SAX-XC878-13FFA 5V	Flash	52	5.0	-40 to 105	Automotive
SAX-XC878CM-13FFA 5V	Flash	52	5.0	-40 to 105	Automotive
SAX-XC878LM-13FFA 5V	Flash	52	5.0	-40 to 105	Automotive
SAX-XC878CLM-13FFA 5V	Flash	52	5.0	-40 to 105	Automotive
SAX-XC878-16FFA 5V	Flash	64	5.0	-40 to 105	Automotive
SAX-XC878CM-16FFA 5V	Flash	64	5.0	-40 to 105	Automotive
SAX-XC878LM-16FFA 5V	Flash	64	5.0	-40 to 105	Automotive
SAX-XC878CLM-16FFA 5V	Flash	64	5.0	-40 to 105	Automotive
SAK-XC878-13FFA 5V	Flash	52	5.0	-40 to 125	Automotive
SAK-XC878CM-13FFA 5V	Flash	52	5.0	-40 to 125	Automotive
SAK-XC878LM-13FFA 5V	Flash	52	5.0	-40 to 125	Automotive
SAK-XC878CLM-13FFA 5V	Flash	52	5.0	-40 to 125	Automotive
SAK-XC878-16FFA 5V	Flash	64	5.0	-40 to 125	Automotive
SAK-XC878CM-16FFA 5V	Flash	64	5.0	-40 to 125	Automotive
SAK-XC878LM-16FFA 5V	Flash	64	5.0	-40 to 125	Automotive
SAK-XC878CLM-16FFA 5V	Flash	64	5.0	-40 to 125	Automotive
SAF-XC874LM-16FVA 5V	Flash	64	5.0	-40 to 85	Automotive

Table 2 Device Profile (cont'd)

Sales Type	Device Type	Program Memory (Kbytes)	Power Supply (V)	Temp-erature (°C)	Quality Profile
SAF-XC874CM-16FVA 5V	Flash	64	5.0	-40 to 85	Automotive
SAF-XC874CM-13FVA 5V	Flash	52	5.0	-40 to 85	Automotive
SAK-XC874LM-16FVA 5V	Flash	64	5.0	-40 to 125	Automotive
SAK-XC874CM-16FVA 5V	Flash	64	5.0	-40 to 125	Automotive
SAK-XC874-16FVA 5V	Flash	64	5.0	-40 to 125	Automotive
SAK-XC874LM-13FVA 5V	Flash	52	5.0	-40 to 125	Automotive
SAK-XC874CM-13FVA 5V	Flash	52	5.0	-40 to 125	Automotive
SAK-XC874-13FVA 5V	Flash	52	5.0	-40 to 125	Automotive

As this document refers to all the derivatives, some description may not apply to a specific product. For simplicity, all versions are referred to by the term XC87x throughout this document.

Ordering Information

The ordering code for Infineon Technologies microcontrollers provides an exact reference to the required product. This ordering code identifies:

- The derivative itself, i.e. its function set, the temperature range, and the supply voltage
- The package and the type of delivery

For the available ordering codes for the XC87x, please refer to your responsible sales representative or your local distributor.

2.4 Pin Definitions and Functions

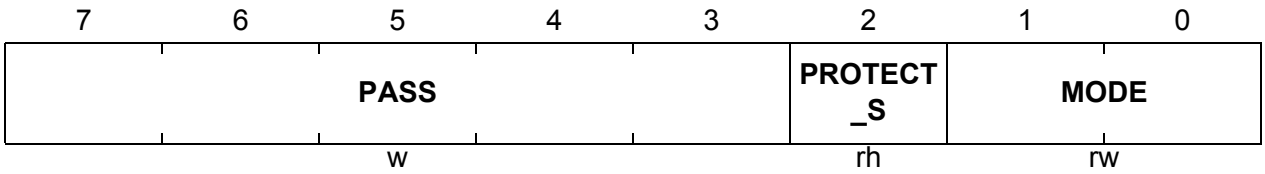
The functions and default states of the XC87x external pins are provided in **Table 3**.

Table 3 Pin Definitions and Functions

Symbol	Pin Number (LQFP-64 / VQFN-48)	Type	Reset State	Function
P0		I/O		**Port 0** Port 0 is an 8-bit bidirectional general purpose I/O port. It can be used as alternate functions for the JTAG, CCU6, UART, UART1, T2CCU, Timer 21, MultiCAN, SSC and External Bus Interface. *Note: External Bus Interface is not available in XC874.*
P0.0	17/12		Hi-Z	TCK_0 JTAG Clock Input T12HR_1 CCU6 Timer 12 Hardware Run Input CC61_1 Input/Output of Capture/Compare channel 1 CLKOUT_0 Clock Output RXDO_1 UART Transmit Data Output
P0.1	21/14		Hi-Z	TDI_0 JTAG Serial Data Input T13HR_1 CCU6 Timer 13 Hardware Run Input RXD_1 UART Receive Data Input RXDC1_0 MultiCAN Node 1 Receiver Input COUT61_1 Output of Capture/Compare channel 1 EXF2_1 Timer 2 External Flag Output
P0.2	18/13		PU	$\overline{\text{CTRAP\_2}}$ CCU6 Trap Input TDO_0 JTAG Serial Data Output TXD_1 UART Transmit Data Output/Clock Output TXDC1_0 MultiCAN Node 1 Transmitter Output

3.2.3.1 Password Register

PASSWD
Password Register **Reset Value: 07_H**



Field	Bits	Type	Description
MODE	[1:0]	rw	**Bit Protection Scheme Control Bits** 00 Scheme disabled - direct access to the protected bits is allowed. 11 Scheme enabled - the bit field PASS has to be written with the passwords to open and close the access to protected bits. (default) Others:Scheme Enabled. These two bits cannot be written directly. To change the value between 11_B and 00_B, the bit field PASS must be written with 11000_B; only then, will the MODE[1:0] be registered.
PROTECT_S	2	rh	**Bit Protection Signal Status Bit** This bit shows the status of the protection. 0 Software is able to write to all protected bits. 1 Software is unable to write to any protected bits.
PASS	[7:3]	w	**Password Bits** The Bit Protection Scheme only recognizes three patterns. 11000_B Enables writing of the bit field MODE. 10011_B Opens access to writing of all protected bits. 10101_B Closes access to writing of all protected bits

Table 12 T2CCU Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
$C5_H$	**T2CCU_CCTH Reset: 00_H** T2CCU Capture/Compare Timer Register High	Bit Field	CCT							
		Type	rwh							
$C6_H$	**T2CCU_CCTCON Reset: 00_H** T2CCU CaptureCcompare Timer Control Register	Bit Field	CCTPRE				CCTOVF	CCTOVEN	TIMSYN	CCTST
		Type	rw				rwh	rw	rw	rw
RMAP = 0, PAGE 2										
$C0_H$	**T2CCU_COSHDWReset: 00_H** T2CCU Capture/compare Enable Register	Bit Field	ENSHDW	TXOV	COOUT5	COOUT4	COOUT3	COOUT2	COOUT1	COOUT0
		Type	rwh	rwh	rwh	rwh	rwh	rwh	rwh	rwh
$C1_H$	**T2CCU_CC0L Reset: 00_H** T2CCU Capture/Compare Register 0 Low	Bit Field	CCVALL							
		Type	rwh							
$C2_H$	**T2CCU_CC0H Reset: 00_H** T2CCU Capture/compare Register 0 High	Bit Field	CCVALH							
		Type	rwh							
$C3_H$	**T2CCU_CC1L Reset: 00_H** T2CCU Capture/compare Register 1 Low	Bit Field	CCVALL							
		Type	rwh							
$C4_H$	**T2CCU_CC1H Reset: 00_H** T2CCU Capture/compare Register 1 High	Bit Field	CCVALH							
		Type	rwh							
$C5_H$	**T2CCU_CC2L Reset: 00_H** T2CCU Capture/compare Register 2 Low	Bit Field	CCVALL							
		Type	rwh							
$C6_H$	**T2CCU_CC2H Reset: 00_H** T2CCU Capture/compare Register 2 High	Bit Field	CCVALH							
		Type	rwh							
RMAP = 0, PAGE 3										
$C0_H$	**T2CCU_COCON Reset: 00_H** T2CCU Compare Control Register	Bit Field	CCM5	CCM4	CM5F	CM4F	POLB	POLA	COMOD	
		Type	rw	rw	rwh	rwh	rw	rw	rw	
$C1_H$	**T2CCU_CC3L Reset: 00_H** T2CCU Capture/compare Register 3 Low	Bit Field	CCVALL							
		Type	rwh							
$C2_H$	**T2CCU_CC3H Reset: 00_H** T2CCU Capture/compare Register 3 High	Bit Field	CCVALH							
		Type	rwh							
$C3_H$	**T2CCU_CC4L Reset: 00_H** T2CCU Capture/compare Register 4 Low	Bit Field	CCVALL							
		Type	rwh							
$C4_H$	**T2CCU_CC4H Reset: 00_H** T2CCU Capture/compare Register 4 High	Bit Field	CCVALH							
		Type	rwh							
$C5_H$	**T2CCU_CC5L Reset: 00_H** T2CCU Capture/compare Register 5 Low	Bit Field	CCVALL							
		Type	rwh							
$C6_H$	**T2CCU_CC5H Reset: 00_H** T2CCU Capture/compare Register 5 High	Bit Field	CCVALH							
		Type	rwh							

3.2.4.10 CCU6 Registers

The CCU6 SFRs can be accessed in the standard memory area (RMAP = 0).

Table 14 CCU6 Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
$A3_H$	**CCU6_PAGE** **Reset: 00_H** Page Register	Bit Field	OP		STNR		0	PAGE		
		Type	w		w		r	rwh		
RMAP = 0, PAGE 0										
$9A_H$	**CCU6_CC63SRL** **Reset: 00_H** Capture/Compare Shadow Register for Channel CC63 Low	Bit Field	CC63SL							
		Type	rw							
$9B_H$	**CCU6_CC63SRH** **Reset: 00_H** Capture/Compare Shadow Register for Channel CC63 High	Bit Field	CC63SH							
		Type	rw							
$9C_H$	**CCU6_TCTR4L** **Reset: 00_H** Timer Control Register 4 Low	Bit Field	T12 STD	T12 STR	0		DT RES	T12 RES	T12R S	T12R R
		Type	w	w	r		w	w	w	w
$9D_H$	**CCU6_TCTR4H** **Reset: 00_H** Timer Control Register 4 High	Bit Field	T13 STD	T13 STR	0			T13 RES	T13R S	T13R R
		Type	w	w	r			w	w	w
$9E_H$	**CCU6_MCMOUTSL** **Reset: 00_H** Multi-Channel Mode Output Shadow Register Low	Bit Field	STRM CM	0	MCMPS					
		Type	w	r	rw					
$9F_H$	**CCU6_MCMOUTSH** **Reset: 00_H** Multi-Channel Mode Output Shadow Register High	Bit Field	STRH P	0	CURHS			EXPHS		
		Type	w	r	rw			rw		
$A4_H$	**CCU6_ISRL** **Reset: 00_H** Capture/Compare Interrupt Status Reset Register Low	Bit Field	RT12 PM	RT12 OM	RCC6 2F	RCC6 2R	RCC6 1F	RCC6 1R	RCC6 0F	RCC6 0R
		Type	w	w	w	w	w	w	w	w
$A5_H$	**CCU6_ISRH** **Reset: 00_H** Capture/Compare Interrupt Status Reset Register High	Bit Field	RSTR	RIDLE	RWH E	RCHE	0	RTRP F	RT13 PM	RT13 CM
		Type	w	w	w	w	r	w	w	w
$A6_H$	**CCU6_CMPMODIFL** **Reset: 00_H** Compare State Modification Register Low	Bit Field	0	MCC6 3S	0			MCC6 2S	MCC6 1S	MCC6 0S
		Type	r	w	r			w	w	w
$A7_H$	**CCU6_CMPMODIFH** **Reset: 00_H** Compare State Modification Register High	Bit Field	0	MCC6 3R	0			MCC6 2R	MCC6 1R	MCC6 0R
		Type	r	w	r			w	w	w
FA_H	**CCU6_CC60SRL** **Reset: 00_H** Capture/Compare Shadow Register for Channel CC60 Low	Bit Field	CC60SL							
		Type	rwh							
FB_H	**CCU6_CC60SRH** **Reset: 00_H** Capture/Compare Shadow Register for Channel CC60 High	Bit Field	CC60SH							
		Type	rwh							

3.2.4.11 UART1 Registers

The UART1 SFRs can be accessed in the mapped memory area (RMAP = 1).

Table 15 UART1 Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 1										
$C8_H$	**SCON** **Reset: 00_H** Serial Channel Control Register	Bit Field	SM0	SM1	SM2	REN	TB8	RB8	TI	RI
		Type	rw	rw	rw	rw	rw	rwh	rwh	rwh
$C9_H$	**SBUF** **Reset: 00_H** Serial Data Buffer Register	Bit Field	VAL							
		Type	rwh							
CA_H	**BCON** **Reset: 00_H** Baud Rate Control Register	Bit Field	0				BRPRE			R
		Type	r				rw			rw
CB_H	**BG** **Reset: 00_H** Baud Rate Timer/Reload Register	Bit Field	BR_VALUE							
		Type	rwh							
CC_H	**FDCON** **Reset: 00_H** Fractional Divider Control Register	Bit Field	0					NDOV	FDM	FDEN
		Type	r					rwh	rw	rw
CD_H	**FDSTEP** **Reset: 00_H** Fractional Divider Reload Register	Bit Field	STEP							
		Type	rw							
CE_H	**FDRES** **Reset: 00_H** Fractional Divider Result Register	Bit Field	RESULT							
		Type	rh							
CF_H	**SCON1** **Reset: 07_H** Serial Channel Control Register 1	Bit Field	0					NDOV EN	TIEN	RIEN
		Type	r					rw	rw	rw

3.2.4.12 SSC Registers

The SSC SFRs can be accessed in the standard memory area (RMAP = 0).

Table 16 SSC Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
$A9_H$	**SSC_PISEL** **Reset: 00_H** Port Input Select Register	Bit Field	0					CIS	SIS	MIS
		Type	r					rw	rw	rw
AA_H	**SSC_CONL** **Reset: 00_H** Control Register Low Programming Mode	Bit Field	LB	PO	PH	HB	BM			
		Type	rw	rw	rw	rw	rw			
AA_H	**SSC_CONL** **Reset: 00_H** Control Register Low Operating Mode	Bit Field	0				BC			
		Type	r				rh			
AB_H	**SSC_CONH** **Reset: 00_H** Control Register High Programming Mode	Bit Field	EN	MS	0	AREN	BEN	PEN	REN	TEN
		Type	rw	rw	r	rw	rw	rw	rw	rw

Table 20 and Table 21 shows the Flash data retention and endurance targets for Industrial profile and Automotive profile respectively.

Table 20 Flash Data Retention and Endurance for Industrial Profile (Operating Conditions apply)

Retention	Endurance[1)2)]	Size	Remarks
Program Flash			
15 years	1000 cycles	up to 60 Kbytes	
Data Flash			
15 years	1000 cycles	4 Kbytes	
10 years	10,000 cycles	4 Kbytes	
5 years	30,000 cycles	4 Kbytes	
1 year	100,000 cycles	4 Kbytes	SAF and SAX variant
	80,000 cycles		SAK variant

1) In Program Flash, one cycle refers to the programming of all pages in the flash bank and a mass erase.

2) In Data Flash, one cycle refers to the programming of all wordlines in a page and a page erase.

Table 21 Flash Data Retention and Endurance for Automotive Profile (Operating Conditions apply)

Retention	Endurance[1)2)]	Size	Remarks
Program Flash			
15 years	1000 cycles	up to 60 Kbytes	
Data Flash			
15 years	1000 cycles	4 Kbytes	
5 years	10,000 cycles	1 Kbytes	
2 years	15,000 cycles	512 Bytes	
2 years	30,000 cycles	256 Bytes	
1 year	100,000 cycles	128 Bytes	

1) In Program Flash, one cycle refers to the programming of all pages in the flash bank and a mass erase.

2) In Data Flash, one cycle refers to the programming of all wordlines in a page and a page erase.

3.12 CORDIC Coprocessor

The CORDIC Coprocessor provides CPU with hardware support for the solving of circular (trigonometric), linear (multiply-add, divide-add) and hyperbolic functions.

Features

- Modes of operation
  - Supports all CORDIC operating modes for solving circular (trigonometric), linear (multiply-add, divide-add) and hyperbolic functions
  - Integrated look-up tables (LUTs) for all operating modes
- Circular vectoring mode: Extended support for values of initial X and Y data up to full range of $[-2^{15},(2^{15}-1)]$ for solving angle and magnitude
- Circular rotation mode: Extended support for values of initial Z data up to full range of $[-2^{15},(2^{15}-1)]$, representing angles in the range $[-\pi,((2^{15}-1)/2^{15})\pi]$ for solving trigonometry
- Implementation-dependent operational frequency of up to 80 MHz
- Gated clock input to support disabling of module
- 16-bit accessible data width
  - 24-bit kernel data width plus 2 overflow bits for X and Y each
  - 20-bit kernel data width plus 1 overflow bit for Z
  - With KEEP bit to retain the last value in the kernel register for a new calculation
- 16 iterations per calculation: Approximately 41 clock-cycles or less, from set of start (ST) bit to set of end-of-calculation flag, excluding time taken for write and read access of data bytes.
- Twos complement data processing
  - Only exception: X result data with user selectable option for unsigned result
- X and Y data generally accepted as integer or rational number; X and Y must be of the same data form
- Entries of LUTs are 20-bit signed integers
  - Entries of atan and atanh LUTs are integer representations (S19) of angles with the scaling such that $[-2^{15},(2^{15}-1)]$ represents the range $[-\pi,((2^{15}-1)/2^{15})\pi]$
  - Accessible Z result data for circular and hyperbolic functions is integer in data form of S15
- Emulated LUT for linear function
  - Data form is 1 integer bit and 15-bit fractional part (1.15)
  - Accessible Z result data for linear function is rational number with fixed data form of S4.11 (signed 4Q16)
- Truncation Error
  - The result of a CORDIC calculation may return an approximation due to truncation of LSBs
  - Good accuracy of the CORDIC calculated result data, especially in circular mode
- Interrupt
  - On completion of a calculation

fractional divider) for generating a wide range of baud rates based on its input clock f_{PCLK}, see **Figure 26**.

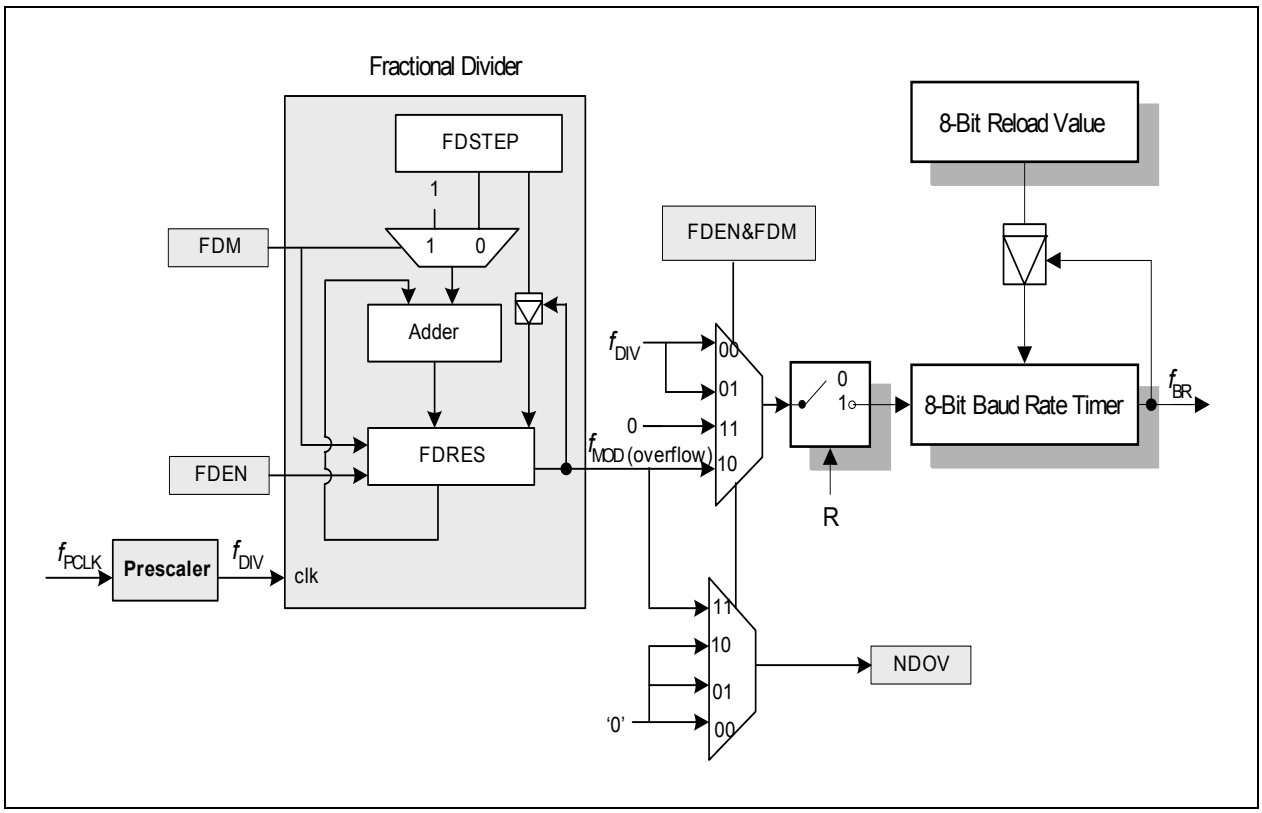


Figure 26 Baud-rate Generator Circuitry

The baud rate timer is a count-down timer and is clocked by either the output of the fractional divider (f_{MOD}) if the fractional divider is enabled (FDCON.FDEN = 1), or the output of the prescaler (f_{DIV}) if the fractional divider is disabled (FDEN = 0). For baud rate generation, the fractional divider must be configured to fractional divider mode (FDCON.FDM = 0). This allows the baud rate control run bit BCON.R to be used to start or stop the baud rate timer. At each timer underflow, the timer is reloaded with the 8-bit reload value in register BG and one clock pulse is generated for the serial channel.

Enabling the fractional divider in normal divider mode (FDEN = 1 and FDM = 1) stops the baud rate timer and nullifies the effect of bit BCON.R. See **Section 3.14**.

The baud rate (f_{BR}) value is dependent on the following parameters:

- Input clock f_{PCLK}
- Prescaling factor (2^{BRPRE}) defined by bit field BRPRE in register BCON
- Fractional divider (STEP/256) defined by register FDSTEP
  (to be considered only if fractional divider is enabled and operating in fractional divider mode)
- 8-bit reload value (BR_VALUE) for the baud rate timer defined by register BG

Table 32 Deviation Error for UART with Fractional Divider enabled

f_{PCLK}	Prescaling Factor (2BRPRE)	Reload Value (BR_VALUE + 1)	STEP	Deviation Error
24 MHz	1	6 (6_H)	59 ($3B_H$)	+0.03 %
12 MHz	1	3 (3_H)	59 ($3B_H$)	+0.03 %
8 MHz	1	2 (2_H)	59 ($3B_H$)	+0.03 %
6 MHz	1	6 (6_H)	236 (EC_H)	+0.03 %

3.13.2 Baud Rate Generation using Timer 1

In UART modes 1 and 3 of UART module, Timer 1 can be used for generating the variable baud rates. In theory, this timer could be used in any of its modes. But in practice, it should be set into auto-reload mode (Timer 1 mode 2), with its high byte set to the appropriate value for the required baud rate. The baud rate is determined by the Timer 1 overflow rate and the value of SMOD as follows:

$$\text{Mode 1, 3 baud rate} = \frac{2^{SMOD} \times f_{PCLK}}{32 \times 2 \times (256 - TH1)} \tag{3.6}$$

3.14 Normal Divider Mode (8-bit Auto-reload Timer)

Setting bit FDM in register FDCON to 1 configures the fractional divider to normal divider mode, while at the same time disables baud rate generation (see **Figure 26**). Once the fractional divider is enabled (FDEN = 1), it functions as an 8-bit auto-reload timer (with no relation to baud rate generation) and counts up from the reload value with each input clock pulse. Bit field RESULT in register FDRES represents the timer value, while bit field STEP in register FDSTEP defines the reload value. At each timer overflow, an overflow flag (FDCON.NDOV) will be set and an interrupt request generated. This gives an output clock f_{MOD} that is 1/n of the input clock f_{DIV}, where n is defined by 256 - STEP.

The output frequency in normal divider mode is derived as follows:

$$f_{MOD} = f_{DIV} \times \frac{1}{256 - STEP} \tag{3.7}$$

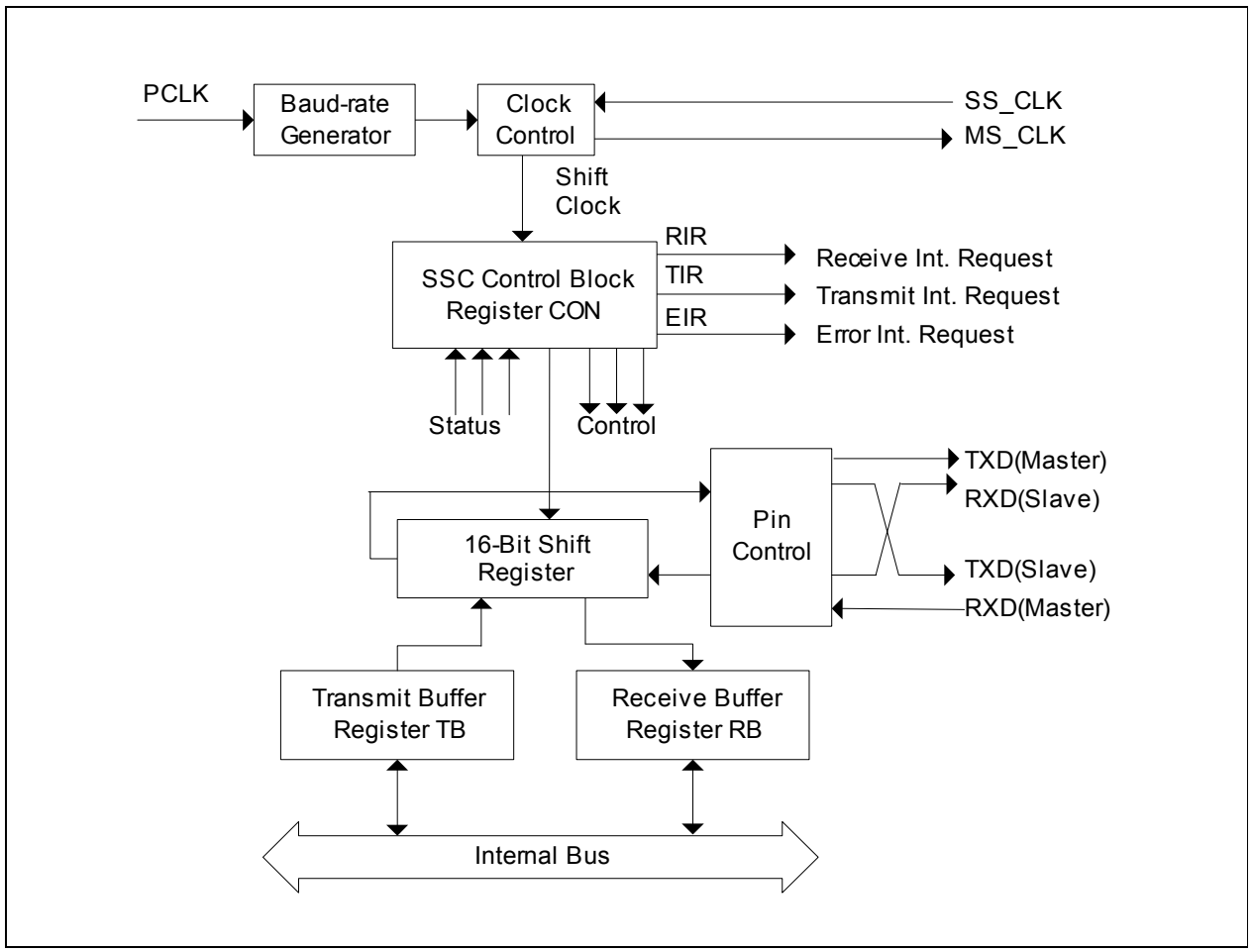


Figure 28 SSC Block Diagram

3.21 Controller Area Network (MultiCAN)

The MultiCAN module contains two Full-CAN nodes operating independently or exchanging data and remote frames via a gateway function. Transmission and reception of CAN frames is handled in accordance to CAN specification V2.0 B active. Each CAN node can receive and transmit standard frames with 11-bit identifiers as well as extended frames with 29-bit identifiers.

Both CAN nodes share a common set of message objects, where each message object may be individually allocated to one of the CAN nodes. Besides serving as a storage container for incoming and outgoing frames, message objects may be combined to build gateways between the CAN nodes or to setup a FIFO buffer.

The message objects are organized in double chained lists, where each CAN node has it's own list of message objects. A CAN node stores frames only into message objects that are allocated to the list of the CAN node. It only transmits messages from objects of this list. A powerful, command driven list controller performs all list operations.

The bit timings for the CAN nodes are derived from the peripheral clock (f_{CAN}) and are programmable up to a data rate of 1 MBaud. A pair of receive and transmit pins connects each CAN node to a bus transceiver.

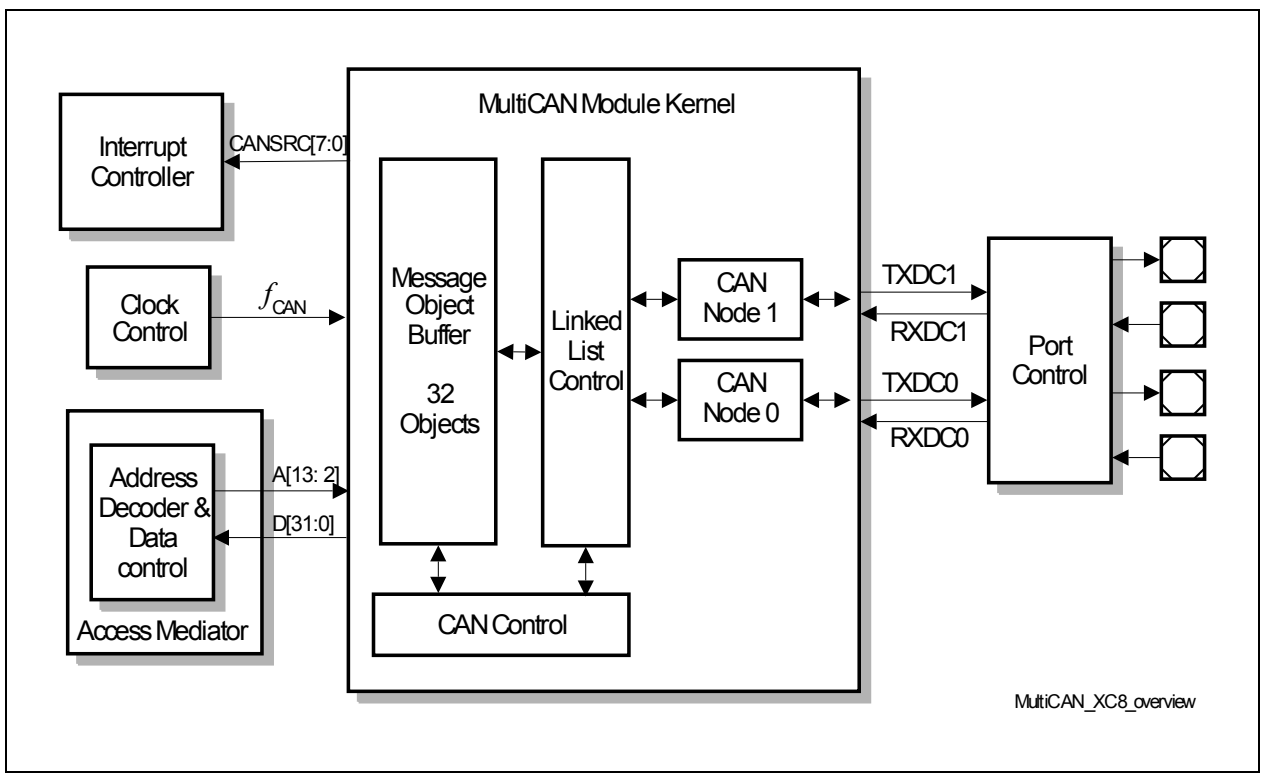


Figure 30 Overview of the MultiCAN

Features

- Compliant to ISO 11898.

- CAN functionality according to CAN specification V2.0 B active.
- Dedicated control registers are provided for each CAN node.
- A data transfer rate up to 1 MBaud is supported.
- Flexible and powerful message transfer control and error handling capabilities are implemented.
- Advanced CAN bus bit timing analysis and baud rate detection can be performed for each CAN node via the frame counter.
- Full-CAN functionality: A set of 32 message objects can be individually
  - allocated (assigned) to any CAN node
  - configured as transmit or receive object
  - setup to handle frames with 11-bit or 29-bit identifier
  - counted or assigned a timestamp via a frame counter
  - configured to remote monitoring mode
- Advanced Acceptance Filtering:
  - Each message object provides an individual acceptance mask to filter incoming frames.
  - A message object can be configured to accept only standard or only extended frames or to accept both standard and extended frames.
  - Message objects can be grouped into 4 priority classes.
  - The selection of the message to be transmitted first can be performed on the basis of frame identifier, IDE bit and RTR bit according to CAN arbitration rules.
- Advanced Message Object Functionality:
  - Message Objects can be combined to build FIFO message buffers of arbitrary size, which is only limited by the total number of message objects.
  - Message objects can be linked to form a gateway to automatically transfer frames between 2 different CAN buses. A single gateway can link any two CAN nodes. An arbitrary number of gateways may be defined.
- Advanced Data Management:
  - The Message objects are organized in double chained lists.
  - List reorganizations may be performed any time, even during full operation of the CAN nodes.
  - A powerful, command driven list controller manages the organization of the list structure and ensures consistency of the list.
  - Message FIFOs are based on the list structure and can easily be scaled in size during CAN operation.
  - Static Allocation Commands offer compatibility with TwinCAN applications, which are not list based.
- Advanced Interrupt Handling:
  - Up to 8 interrupt output lines are available. Most interrupt requests can be individually routed to one of the 8 interrupt output lines.
  - Message postprocessing notifications can be flexibly aggregated into a dedicated register field of 64 notification bits.

Table 40 Input/Output Characteristics (Operating Conditions apply) (cont'd)

Parameter	Symbol		Limit Values		Unit	Test Conditions
			min.	max.		
Voltage on any pin during V_{DDP} power off	V_{PO}	SR	–	0.3	V	6)
Maximum current per pin (excluding V_{DDP} and V_{SS})	I_M SR	SR	–	8	mA	
Maximum current for all pins (excluding V_{DDP} and V_{SS})	$\Sigma\|I_M\|$	SR	–	150	mA	
Maximum current into V_{DDP}	I_{MVDDP}	SR	–	200	mA	5)
Maximum current out of V_{SS}	I_{MVSS}	SR	–	200	mA	5)

1) DS = 0 refers to the pin having a weak drive strength which is programmable via Px_DS register.

2) DS = 1 refers to the pin having a strong drive strength which is programmable via Px_DS register.

3) Not subjected to production test, verified by design/characterization. Hysteresis is implemented to avoid meta stable states and switching due to internal ground bounce. It cannot be guaranteed that it suppresses switching due to external system noise.

4) An additional error current (I_{INJ}) will flow if an overload current flows through an adjacent pin. TMS pin and $\overline{\text{RESET}}$ pin have internal pull devices and are not included in the input leakage current characteristic.

5) Not subjected to production test, verified by design/characterization.

6) Not subjected to production test, verified by design/characterization. However, for applications with strict low power-down current requirements, it is mandatory that no active voltage source is supplied at any GPIO pin when V_{DDP} is powered off.

7) P0.1 has a minimum input hysteresis of 0.25V.

Table 42 ADC Characteristics (Operating Conditions apply; V_{DDP} = 5V Range)

Parameter	Symbol		Limit Values			Unit	Test Conditions/ Remarks
			min.	typ .	max.		
Input resistance of the reference input	R_{AREF}	CC	–	1	2	kΩ	1)
Input resistance of the selected analog channel	R_{AIN}	CC	–	1	3	kΩ	1)

1) Not subjected to production test, verified by design/characterization.

2) This value includes the maximum oscillator deviation.

3) This represents an equivalent switched capacitance. This capacitance is not switched to the reference voltage at once. Instead of this, smaller capacitances are successively switched to the reference voltage.

4) The sampling capacity of the conversion C-Network is pre-charged to V_{AREF}/2 before connecting the input to the C-Network. Because of the parasitic elements, the voltage measured at ANx is lower than V_{AREF}/2.

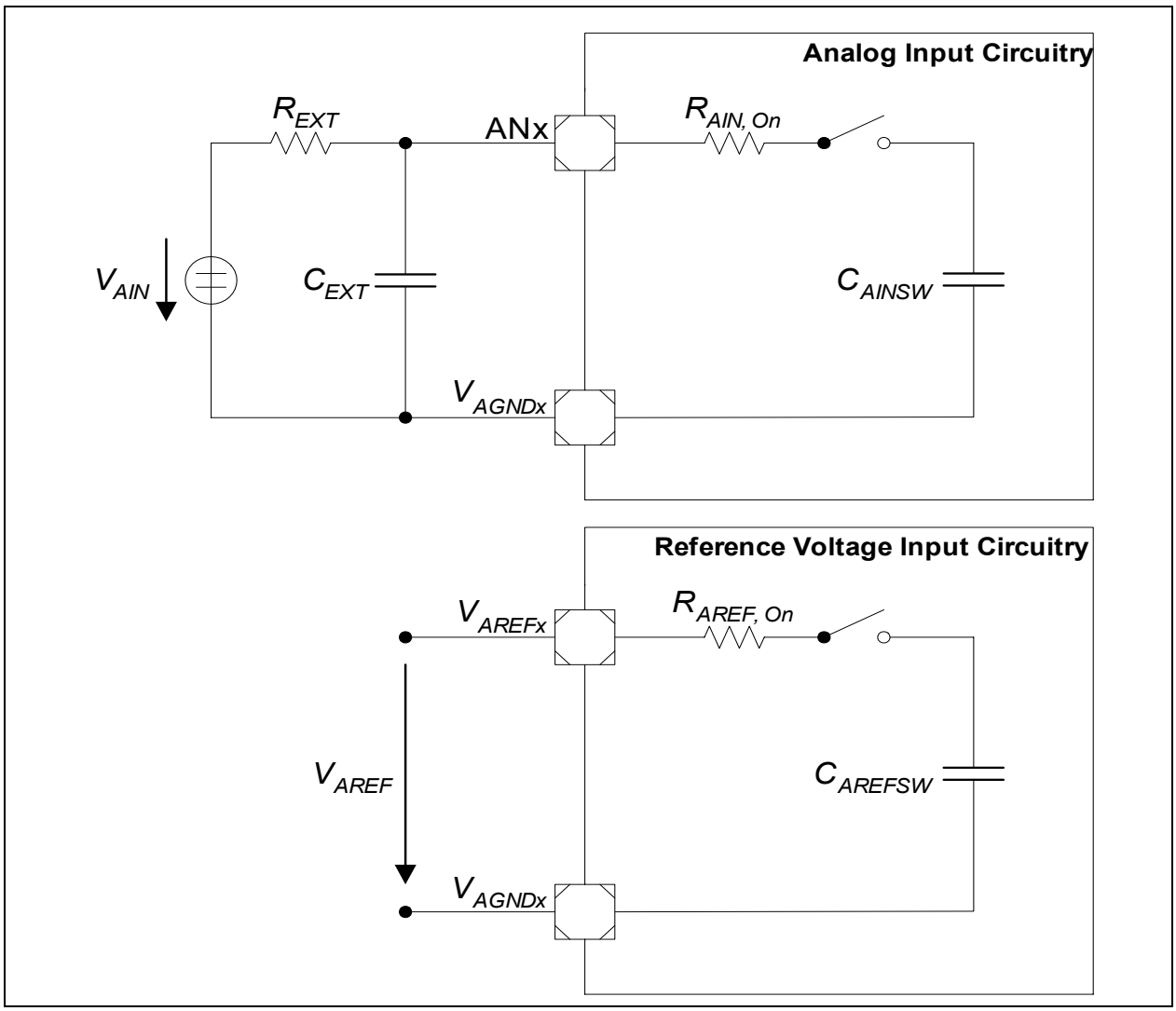


Figure 35 ADC Input Circuits

4.2.3.1 ADC Conversion Timing

Conversion time, $t_C = t_{ADC} \times (1 + r \times (3 + n + STC))$, where

r = CTC + 2 for CTC = 00_B, 01_B or 10_B,

r = 32 for CTC = 11_B,

CTC = Conversion Time Control (GLOBCTR.CTC),

STC = Sample Time Control (INPCR0.STC),

n = 8 or 10 (for 8-bit and 10-bit conversion respectively),

$t_{ADC} = 1 / f_{ADC}$

Table 44 Power Down Current[1](Operating Conditions apply; V_{DDP} = 5V range)

Parameter	Symbol	Limit Values		Unit	Test Conditions
		typ.[2]	max.[3]		
V_{DDP} = 5V Range					
Power-Down Mode	I_{PDP}	20	80	µA	T_A = + 25 °C[4][5]
		-	250	µA	T_A = + 85 °C[5][6]

1) The table is only applicable to SAF and SAX variants. SAK variant does not support power-down mode

2) The typical I_{PDP} values are based on preliminary measurements and are to be used as reference only. These values are measured at V_{DDP} = 5.0 V.

3) The maximum I_{PDP} values are measured at V_{DDP} = 5.5 V.

4) I_{PDP} has a maximum value of 450 µA at T_A = + 105 °C.

5) I_{PDP} is measured with: $\overline{\text{RESET}}$ = V_{DDP}, V_{AGND}= V_{SS}, RXD/INT0 = V_{DDP}; rest of the ports are programmed to be input with either internal pull devices enabled or driven externally to ensure no floating inputs.

6) Not subjected to production test, verified by design/characterization.

4.3 AC Parameters

The electrical characteristics of the AC Parameters are detailed in this section.

4.3.1 Testing Waveforms

The testing waveforms for rise/fall time, output delay and output high impedance are shown in **Figure 36**, **Figure 37** and **Figure 38**.

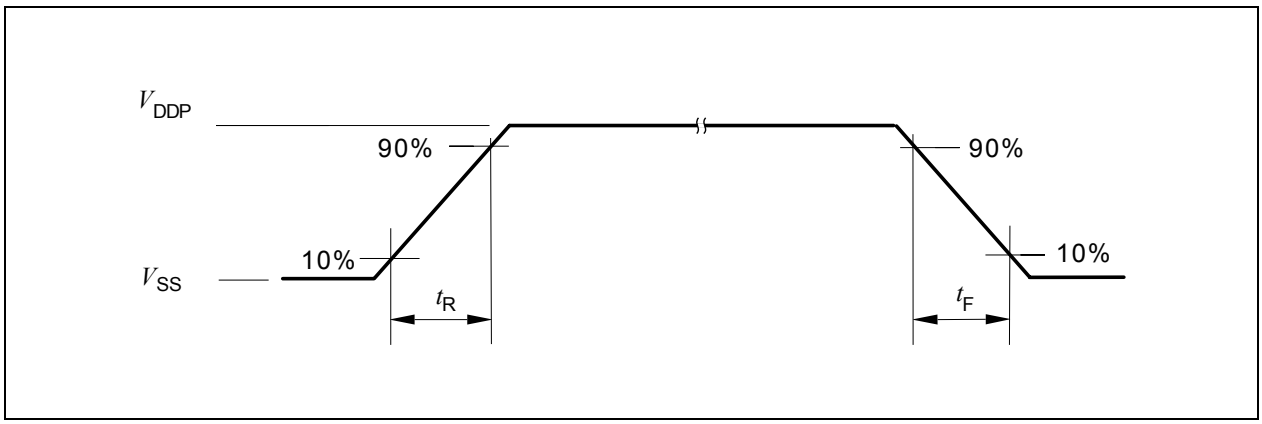


Figure 36 Rise/Fall Time Parameters

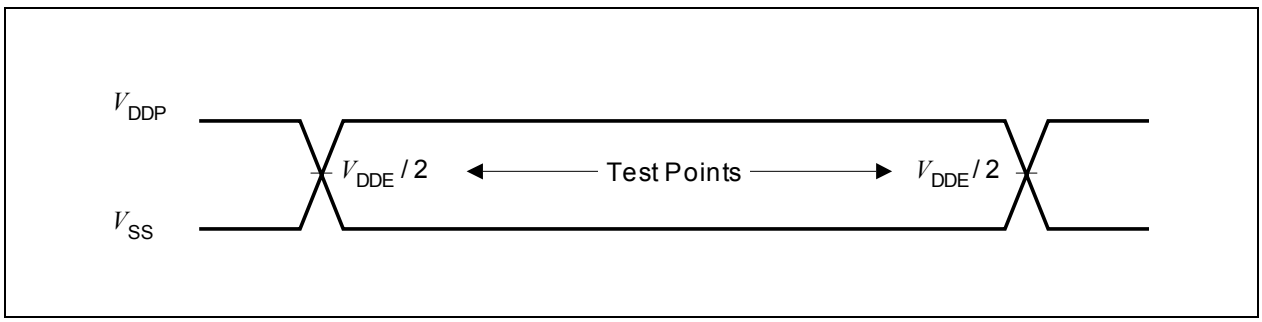


Figure 37 Testing Waveform, Output Delay

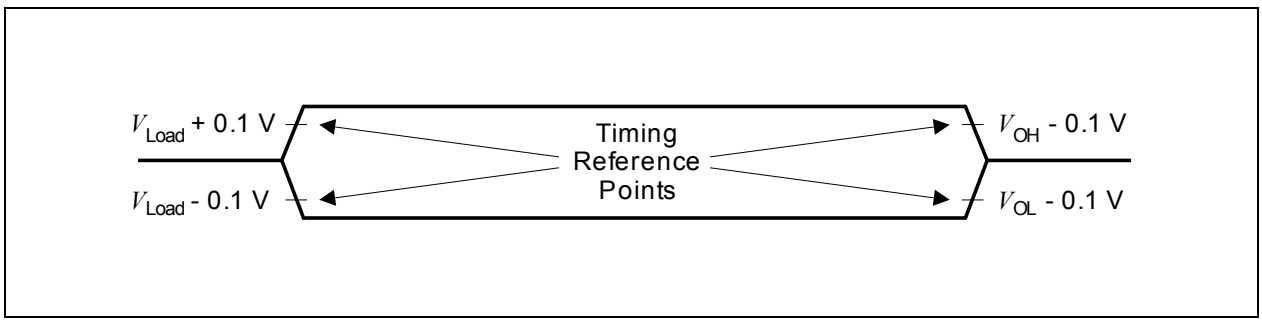


Figure 38 Testing Waveform, Output High Impedance