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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	XC800
Core Size	8-Bit
Speed	27MHz
Connectivity	CANbus, LINbus, SSI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	40
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3.25K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	PG-LQFP-64-4
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/xc878clm16ffa5vackxuma1

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Summary of Features**Features: (continued)**

- Power-on reset generation
- Brownout detection for core logic supply
- On-chip OSC and PLL for clock generation
 - Loss-of-Clock detection
- Power saving modes
 - slow-down mode
 - idle mode
 - power-down mode with wake-up capability via RXD or EXINT0¹⁾
 - clock gating control to each peripheral
- Programmable 16-bit Watchdog Timer (WDT)
- Five ports
 - Up to 40 pins as digital I/O
 - 8 dedicated analog inputs used as A/D converter input
- 8-channel, 10-bit ADC
- Four 16-bit timers
 - Timer 0 and Timer 1 (T0 and T1)
 - Timer 2 and Timer 21 (T2 and T21)
- Multiplication/Division Unit for arithmetic operations (MDU)
- CORDIC Coprocessor for computation of trigonometric, hyperbolic and linear functions
- MultiCAN with 2 nodes, 32 message objects
- Two Capture/compare units
 - Capture/compare unit 6 for PWM signal generation (CCU6)
 - Timer 2 Capture/compare unit for various digital signal generation (T2CCU)
- Two full-duplex serial interfaces (UART and UART1)
- Synchronous serial channel (SSC)
- On-chip debug support
 - 1 Kbyte of monitor ROM (part of the 8-Kbyte Boot ROM)
 - 64 bytes of monitor RAM
- Packages:
 - PG-LQFP-64
 - PG-VQFN-48
- Temperature range T_A :
 - SAF (-40 to 85 °C)
 - SAX (-40 to 105 °C)
 - SAK (-40 to 125 °C)

1) SAK product variant does not support power-down mode.

Functional Description
3.2.4.7 ADC Registers

The ADC SFRs can be accessed in the standard memory area (RMAP = 0).

Table 11 ADC Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 0										
D1 _H	ADC_PAGE Reset: 00_H Page Register	Bit Field	OP		STNR		0	PAGE		
		Type	w		w		r	rw		
RMAP = 0, PAGE 0										
CA _H	ADC_GLOBCTR Reset: 30_H Global Control Register	Bit Field	ANON	DW	CTC		0			
		Type	rw	rw	rw		r			
CB _H	ADC_GLOBSTR Reset: 00_H Global Status Register	Bit Field	0		CHNR			0	SAMP LE	BUSY
		Type	r		rh			r	rh	rh
CC _H	ADC_PRAR Reset: 00_H Priority and Arbitration Register	Bit Field	ASEN 1	ASEN 0	0	ARBM	CSM1	PRI01	CSM0	PRI00
		Type	rw	rw	r	rw	rw	rw	rw	rw
CD _H	ADC_LCBR Reset: B7_H Limit Check Boundary Register	Bit Field	BOUND1				BOUND0			
		Type	rw				rw			
CE _H	ADC_INPCR0 Reset: 00_H Input Class 0 Register	Bit Field	STC							
		Type	rw							
CF _H	ADC_ETRCR Reset: 00_H External Trigger Control Register	Bit Field	SYNE N1	SYNE N0	ETRSEL1			ETRSEL0		
		Type	rw	rw	rw			rw		
RMAP = 0, PAGE 1										
CA _H	ADC_CHCTR0 Reset: 00_H Channel Control Register 0	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		
CB _H	ADC_CHCTR1 Reset: 00_H Channel Control Register 1	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		
CC _H	ADC_CHCTR2 Reset: 00_H Channel Control Register 2	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		
CD _H	ADC_CHCTR3 Reset: 00_H Channel Control Register 3	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		
CE _H	ADC_CHCTR4 Reset: 00_H Channel Control Register 4	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		
CF _H	ADC_CHCTR5 Reset: 00_H Channel Control Register 5	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		
D2 _H	ADC_CHCTR6 Reset: 00_H Channel Control Register 6	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		
D3 _H	ADC_CHCTR7 Reset: 00_H Channel Control Register 7	Bit Field	0	LCC			0	RESRSEL		
		Type	r	rw			r	rw		

Functional Description
Table 11 ADC Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
CB _H	ADC_RCR1 Reset: 00_H Result Control Register 1	Bit Field	VFCT R	WFR	0	IEN	0			DRCT R
		Type	rw	rw	r	rw	r			rw
CC _H	ADC_RCR2 Reset: 00_H Result Control Register 2	Bit Field	VFCT R	WFR	0	IEN	0			DRCT R
		Type	rw	rw	r	rw	r			rw
CD _H	ADC_RCR3 Reset: 00_H Result Control Register 3	Bit Field	VFCT R	WFR	0	IEN	0			DRCT R
		Type	rw	rw	r	rw	r			rw
CE _H	ADC_VFCR Reset: 00_H Valid Flag Clear Register	Bit Field	0				VFC3	VFC2	VFC1	VFC0
		Type	r				w	w	w	w
RMAP = 0, PAGE 5										
CA _H	ADC_CHINFR Reset: 00_H Channel Interrupt Flag Register	Bit Field	CHINF 7	CHINF 6	CHINF 5	CHINF 4	CHINF 3	CHINF 2	CHINF 1	CHINF 0
		Type	rh	rh	rh	rh	rh	rh	rh	rh
CB _H	ADC_CHINCR Reset: 00_H Channel Interrupt Clear Register	Bit Field	CHINC 7	CHINC 6	CHINC 5	CHINC 4	CHINC 3	CHINC 2	CHINC 1	CHINC 0
		Type	w	w	w	w	w	w	w	w
CC _H	ADC_CHINSR Reset: 00_H Channel Interrupt Set Register	Bit Field	CHINS 7	CHINS 6	CHINS 5	CHINS 4	CHINS 3	CHINS 2	CHINS 1	CHINS 0
		Type	w	w	w	w	w	w	w	w
CD _H	ADC_CHINPR Reset: 00_H Channel Interrupt Node Pointer Register	Bit Field	CHINP 7	CHINP 6	CHINP 5	CHINP 4	CHINP 3	CHINP 2	CHINP 1	CHINP 0
		Type	rw	rw	rw	rw	rw	rw	rw	rw
CE _H	ADC_EVINFR Reset: 00_H Event Interrupt Flag Register	Bit Field	EVINF 7	EVINF 6	EVINF 5	EVINF 4	0		EVINF 1	EVINF 0
		Type	rh	rh	rh	rh	r		rh	rh
CF _H	ADC_EVINCR Reset: 00_H Event Interrupt Clear Flag Register	Bit Field	EVINC 7	EVINC 6	EVINC 5	EVINC 4	0		EVINC 1	EVINC 0
		Type	w	w	w	w	r		w	w
D2 _H	ADC_EVINSR Reset: 00_H Event Interrupt Set Flag Register	Bit Field	EVINS 7	EVINS 6	EVINS 5	EVINS 4	0		EVINS 1	EVINS 0
		Type	w	w	w	w	r		w	w
D3 _H	ADC_EVINPR Reset: 00_H Event Interrupt Node Pointer Register	Bit Field	EVINP 7	EVINP 6	EVINP 5	EVINP 4	0		EVINP 1	EVINP 0
		Type	rw	rw	rw	rw	r		rw	rw
RMAP = 0, PAGE 6										
CA _H	ADC_CRCR1 Reset: 00_H Conversion Request Control Register 1	Bit Field	CH7	CH6	CH5	CH4	0			
		Type	rwh	rwh	rwh	rwh	r			
CB _H	ADC_CRPR1 Reset: 00_H Conversion Request Pending Register 1	Bit Field	CHP7	CHP6	CHP5	CHP4	0			
		Type	rwh	rwh	rwh	rwh	r			

Functional Description
Table 14 CCU6 Register Overview (cont'd)

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
FC _H	CCU6_CC61SRL Reset: 00_H Capture/Compare Shadow Register for Channel CC61 Low	Bit Field	CC61SL							
		Type	rwh							
FD _H	CCU6_CC61SRH Reset: 00_H Capture/Compare Shadow Register for Channel CC61 High	Bit Field	CC61SH							
		Type	rwh							
FE _H	CCU6_CC62SRL Reset: 00_H Capture/Compare Shadow Register for Channel CC62 Low	Bit Field	CC62SL							
		Type	rwh							
FF _H	CCU6_CC62SRH Reset: 00_H Capture/Compare Shadow Register for Channel CC62 High	Bit Field	CC62SH							
		Type	rwh							
RMAP = 0, PAGE 1										
9A _H	CCU6_CC63RL Reset: 00_H Capture/Compare Register for Channel CC63 Low	Bit Field	CC63VL							
		Type	rh							
9B _H	CCU6_CC63RH Reset: 00_H Capture/Compare Register for Channel CC63 High	Bit Field	CC63VH							
		Type	rh							
9C _H	CCU6_T12PRL Reset: 00_H Timer T12 Period Register Low	Bit Field	T12PVL							
		Type	rwh							
9D _H	CCU6_T12PRH Reset: 00_H Timer T12 Period Register High	Bit Field	T12PVH							
		Type	rwh							
9E _H	CCU6_T13PRL Reset: 00_H Timer T13 Period Register Low	Bit Field	T13PVL							
		Type	rwh							
9F _H	CCU6_T13PRH Reset: 00_H Timer T13 Period Register High	Bit Field	T13PVH							
		Type	rwh							
A4 _H	CCU6_T12DTCL Reset: 00_H Dead-Time Control Register for Timer T12 Low	Bit Field	DTM							
		Type	rw							
A5 _H	CCU6_T12DTCH Reset: 00_H Dead-Time Control Register for Timer T12 High	Bit Field	0	DTR2	DTR1	DTR0	0	DTE2	DTE1	DTE0
		Type	r	rh	rh	rh	r	rw	rw	rw
A6 _H	CCU6_TCTR0L Reset: 00_H Timer Control Register 0 Low	Bit Field	CTM	CDIR	STE1 2	T12R	T12 PRE	T12CLK		
		Type	rw	rh	rh	rh	rw	rw		
A7 _H	CCU6_TCTR0H Reset: 00_H Timer Control Register 0 High	Bit Field	0		STE1 3	T13R	T13 PRE	T13CLK		
		Type	r		rh	rh	rw	rw		
FA _H	CCU6_CC60RL Reset: 00_H Capture/Compare Register for Channel CC60 Low	Bit Field	CC60VL							
		Type	rh							
FB _H	CCU6_CC60RH Reset: 00_H Capture/Compare Register for Channel CC60 High	Bit Field	CC60VH							
		Type	rh							
FC _H	CCU6_CC61RL Reset: 00_H Capture/Compare Register for Channel CC61 Low	Bit Field	CC61VL							
		Type	rh							

Functional Description

Table 18 OCDS Register Overview

Addr	Register Name	Bit	7	6	5	4	3	2	1	0
RMAP = 1										
E9 _H	MMCR2 Reset: 8U_H Monitor Mode Control 2 Register	Bit Field	STMO DE	EXBC	DSUS P	MBCO N	ALTDI	MMEP	MMOD E	JENA
		Type	rw	rw	rw	rwh	rw	rwh	rh	rh
EA _H	MEXTCR Reset: 0U_H Memory Extension Control Register	Bit Field	0				BANKBPx			
		Type	r				rw			
EB _H	MMWR1 Reset: 00_H Monitor Work Register 1	Bit Field	MMWR1							
		Type	rw							
EC _H	MMWR2 Reset: 00_H Monitor Work Register 2	Bit Field	MMWR2							
		Type	rw							
F1 _H	MMCR Reset: 00_H Monitor Mode Control Register	Bit Field	MEXIT _P	MEXIT	0	MSTE P	MRAM S_P	MRAM S	TRF	RRF
		Type	w	rwh	r	rw	w	rwh	rh	rh
F2 _H	MMSR Reset: 00_H Monitor Mode Status Register	Bit Field	MBCA M	MBCIN	EXBF	SWBF	HWB3 F	HWB2 F	HWB1 F	HWB0 F
		Type	rw	rwh	rwh	rwh	rwh	rwh	rwh	rwh
F3 _H	MMBPCR Reset: 00_H Breakpoints Control Register	Bit Field	SWBC	HWB3C		HWB2C		HWB1 C	HWB0C	
		Type	rw	rw		rw		rw	rw	
F4 _H	MMICR Reset: 00_H Monitor Mode Interrupt Control Register	Bit Field	DVEC T	DRET R	COMR ST	MSTS EL	MMUI E_P	MMUI E	RRIE_ P	RRIE
		Type	rwh	rwh	rwh	rh	w	rw	w	rw
F5 _H	MMDR Reset: 00_H Monitor Mode Data Transfer Register Receive	Bit Field	MMRR							
		Type	rh							
F6 _H	HWBPSR Reset: 00_H Hardware Breakpoints Select Register	Bit Field	0			BPSEL _P	BPSEL			
		Type	r			w	rw			
F7 _H	HWBPDR Reset: 00_H Hardware Breakpoints Data Register	Bit Field	HWBPxx							
		Type	rw							

Functional Description

Table 20 and **Table 21** shows the Flash data retention and endurance targets for Industrial profile and Automotive profile respectively.

**Table 20 Flash Data Retention and Endurance for Industrial Profile
(Operating Conditions apply)**

Retention	Endurance ¹⁾²⁾	Size	Remarks
Program Flash			
15 years	1000 cycles	up to 60 Kbytes	
Data Flash			
15 years	1000 cycles	4 Kbytes	
10 years	10,000 cycles	4 Kbytes	
5 years	30,000 cycles	4 Kbytes	
1 year	100,000 cycles	4 Kbytes	SAF and SAX variant
	80,000 cycles		SAK variant

1) In Program Flash, one cycle refers to the programming of all pages in the flash bank and a mass erase.

2) In Data Flash, one cycle refers to the programming of all wordlines in a page and a page erase.

**Table 21 Flash Data Retention and Endurance for Automotive Profile
(Operating Conditions apply)**

Retention	Endurance ¹⁾²⁾	Size	Remarks
Program Flash			
15 years	1000 cycles	up to 60 Kbytes	
Data Flash			
15 years	1000 cycles	4 Kbytes	
5 years	10,000 cycles	1 Kbytes	
2 years	15,000 cycles	512 Bytes	
2 years	30,000 cycles	256 Bytes	
1 year	100,000 cycles	128 Bytes	

1) In Program Flash, one cycle refers to the programming of all pages in the flash bank and a mass erase.

2) In Data Flash, one cycle refers to the programming of all wordlines in a page and a page erase.

Functional Description
Table 22 Interrupt Vector Addresses (cont'd)

Interrupt Source	Vector Address	Assignment for XC87x	Enable Bit	SFR
XINTR6	0033 _H	MultiCAN Nodes 1 and 2	EADC	IEN1
		ADC[1:0]		
XINTR7	003B _H	SSC	ESSC	
XINTR8	0043 _H	External Interrupt 2	EX2	
		T21		
		CORDIC		
		UART1		
		UART1 Fractional Divider (Normal Divider Overflow)		
		MDU[1:0]		
XINTR9	004B _H	External Interrupt 3	EXM	
		External Interrupt 4		
		External Interrupt 5		
		External Interrupt 6		
		T2CCU		
		MultiCAN Node 3		
XINTR10	0053 _H	CCU6 INP0	ECCIP0	
		MultiCAN Node 4		
XINTR11	005B _H	CCU6 INP1	ECCIP1	
		MultiCAN Node 5		
XINTR12	0063 _H	CCU6 INP2	ECCIP2	
		MultiCAN Node 6		
XINTR13	006B _H	CCU6 INP3	ECCIP3	
		MultiCAN Node 7		

3.8.2 Clock Management

The CGU generates all clock signals required within the microcontroller from a single clock, f_{sys} . During normal system operation, the typical frequencies of the different modules are as follow:

- CPU clock: CCLK, SCLK = 24 MHz
- MultiCAN clock : MCANCLK = 24 or 48 MHz
- MDU clock : MDUCLK = 24 or 48 MHz
- CORDIC clock : CORDICCLK = 24 or 48 MHz
- CCU6 clock : CCU6CLK = 24 or 48 MHz
- T2CCU clock : T2CCUCLK = 24 or 48 MHz
- Peripheral clock: PCLK = 24 MHz

In addition, different clock frequencies can be output to pin CLKOUT (P0.0 or P0.7). The clock output frequency, which is derived from the clock output divider (bit COREL), can further be divided by 2 using toggle latch (bit TLEN is set to 1). The resulting output frequency has a 50% duty cycle. **Figure 22** shows the clock distribution of the XC87x.

Functional Description

3.11 Multiplication/Division Unit

The Multiplication/Division Unit (MDU) provides fast 16-bit multiplication, 16-bit and 32-bit division as well as shift and normalize features. It has been integrated to support the XC87x Core in real-time control applications, which require fast mathematical computations.

Features

- Fast signed/unsigned 16-bit multiplication
- Fast signed/unsigned 32-bit divide by 16-bit and 16-bit divide by 16-bit operations
- 32-bit unsigned normalize operation
- 32-bit arithmetic/logical shift operations

Table 29 specifies the number of clock cycles used for calculation in various operations.

Table 29 MDU Operation Characteristics

Operation	Result	Remainder	No. of Clock Cycles used for calculation
Signed 32-bit/16-bit	32-bit	16-bit	33
Signed 16-bit/16bit	16-bit	16-bit	17
Signed 16-bit x 16-bit	32-bit	-	16
Unsigned 32-bit/16-bit	32-bit	16-bit	32
Unsigned 16-bit/16-bit	16-bit	16-bit	16
Unsigned 16-bit x 16-bit	32-bit	-	16
32-bit normalize	-	-	No. of shifts + 1 (Max. 32)
32-bit shift L/R	-	-	No. of shifts + 1 (Max. 32)

Functional Description

- Interrupt enabling and corresponding flag

3.13 UART and UART1

The XC87x provides two Universal Asynchronous Receiver/Transmitter (UART and UART1) modules for full-duplex asynchronous reception/transmission. Both are also receive-buffered, i.e., they can commence reception of a second byte before a previously received byte has been read from the receive register. However, if the first byte still has not been read by the time reception of the second byte is complete, one of the bytes will be lost.

Features

- Full-duplex asynchronous modes
 - 8-bit or 9-bit data frames, LSB first
 - Fixed or variable baud rate
- Receive buffered
- Multiprocessor communication
- Interrupt generation on the completion of a data transmission or reception

The UART modules can operate in the four modes shown in [Table 30](#).

Table 30 UART Modes

Operating Mode	Baud Rate
Mode 0: 8-bit shift register	$f_{PCLK}/2$
Mode 1: 8-bit shift UART	Variable
Mode 2: 9-bit shift UART	$f_{PCLK}/32$ or $f_{PCLK}/64^{1)}$
Mode 3: 9-bit shift UART	Variable

1) For UART1 module, the baud rate is fixed at $f_{PCLK}/64$.

There are several ways to generate the baud rate clock for the serial port, depending on the mode in which it is operating. In mode 0, the baud rate for the transfer is fixed at $f_{PCLK}/2$. In mode 2, the baud rate is generated internally based on the UART input clock and can be configured to either $f_{PCLK}/32$ or $f_{PCLK}/64$. For UART1 module, only $f_{PCLK}/64$ is available. The variable baud rate is set by the underflow rate on the dedicated baud-rate generator. For UART module, the variable baud rate alternatively can be set by the overflow rate on Timer 1.

3.13.1 Baud-Rate Generator

Both UART modules have their own dedicated baud-rate generator, which is based on a programmable 8-bit reload value, and includes divider stages (i.e., prescaler and

3.16 High-Speed Synchronous Serial Interface

The High-Speed Synchronous Serial Interface (SSC) supports full-duplex and half-duplex synchronous communication. The serial clock signal can be generated by the SSC internally (master mode), using its own 16-bit baud-rate generator, or can be received from an external master (slave mode). Data width, shift direction, clock polarity and phase are programmable. This allows communication with SPI-compatible devices or devices using other synchronous serial interfaces.

Features

- Master and slave mode operation
 - Full-duplex or half-duplex operation
- Transmit and receive buffered
- Flexible data format
 - Programmable number of data bits: 2 to 8 bits
 - Programmable shift direction: LSB or MSB shift first
 - Programmable clock polarity: idle low or high state for the shift clock
 - Programmable clock/data phase: data shift with leading or trailing edge of the shift clock
- Variable baud rate
- Compatible with Serial Peripheral Interface (SPI)
- Interrupt generation
 - On a transmitter empty condition
 - On a receiver full condition
 - On an error condition (receive, phase, baud rate, transmit error)

Data is transmitted or received on lines TXD and RXD, which are normally connected to the pins MTSR (Master Transmit/Slave Receive) and MRST (Master Receive/Slave Transmit). The clock signal is output via line MS_CLK (Master Serial Shift Clock) or input via line SS_CLK (Slave Serial Shift Clock). Both lines are normally connected to the pin SCLK. Transmission and reception of data are double-buffered.

Figure 28 shows the block diagram of the SSC.

Functional Description

3.17 Timer 0 and Timer 1

Timer 0 and Timer 1 can function as both timers or counters. When functioning as a timer, Timer 0 and Timer 1 are incremented every machine cycle, i.e. every 2 input clocks (or 2 PCLKs). When functioning as a counter, Timer 0 and Timer 1 are incremented in response to a 1-to-0 transition (falling edge) at their respective external input pins, T0 or T1.

Timer 0 and 1 are fully compatible and can be configured in four different operating modes for use in a variety of applications, see [Table 33](#). In modes 0, 1 and 2, the two timers operate independently, but in mode 3, their functions are specialized.

Table 33 Timer 0 and Timer 1 Modes

Mode	Operation
0	13-bit timer The timer is essentially an 8-bit counter with a divide-by-32 prescaler. This mode is included solely for compatibility with Intel 8048 devices.
1	16-bit timer The timer registers, TLx and THx, are concatenated to form a 16-bit counter.
2	8-bit timer with auto-reload The timer register TLx is reloaded with a user-defined 8-bit value in THx upon overflow.
3	Timer 0 operates as two 8-bit timers The timer registers, TL0 and TH0, operate as two separate 8-bit counters. Timer 1 is halted and retains its count even if enabled.

Functional Description

- Synchronization phase (t_{SYN})
- Sample phase (t_{S})
- Conversion phase
- Write result phase (t_{WR})

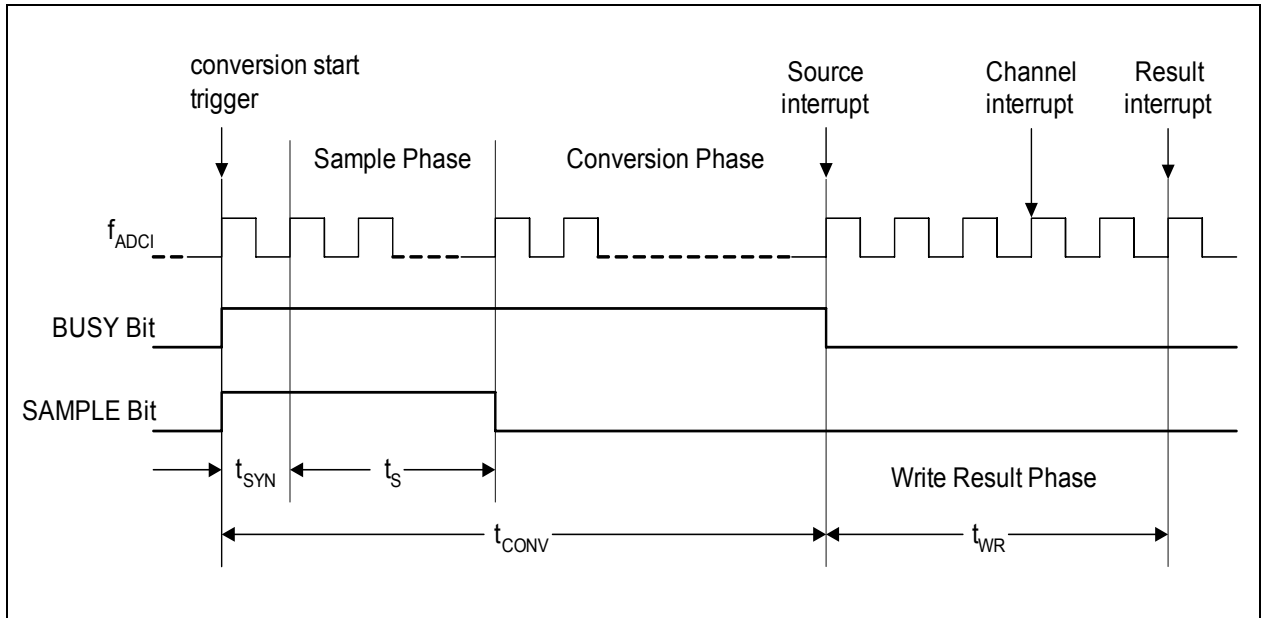


Figure 32 ADC Conversion Timing

4.3 AC Parameters

The electrical characteristics of the AC Parameters are detailed in this section.

4.3.1 Testing Waveforms

The testing waveforms for rise/fall time, output delay and output high impedance are shown in [Figure 36](#), [Figure 37](#) and [Figure 38](#).

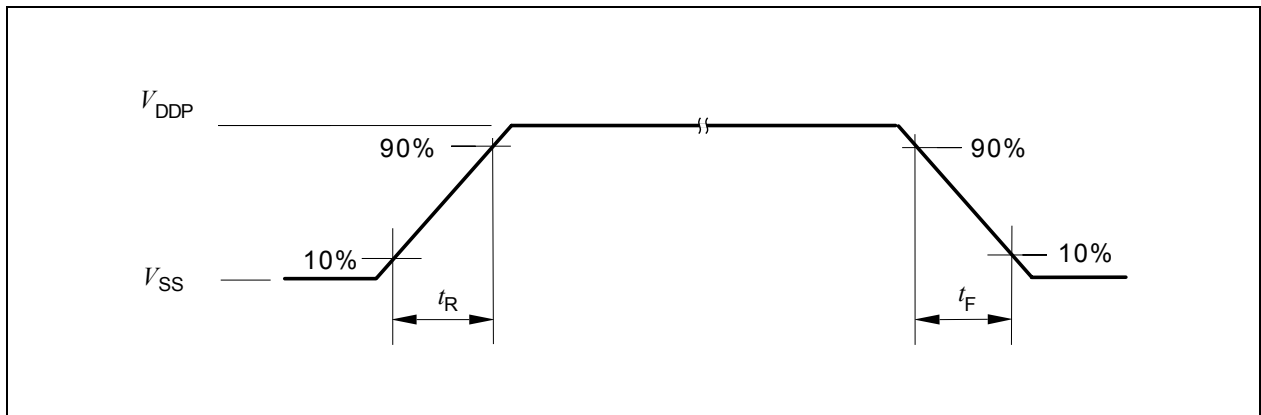


Figure 36 Rise/Fall Time Parameters

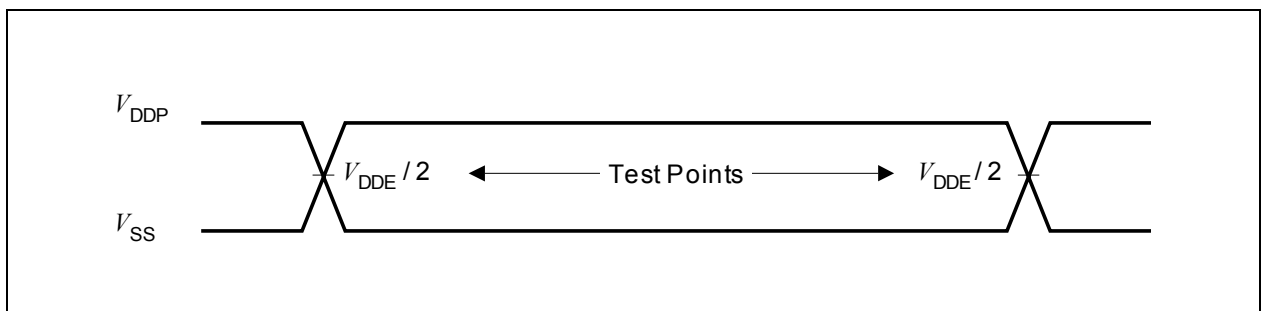


Figure 37 Testing Waveform, Output Delay

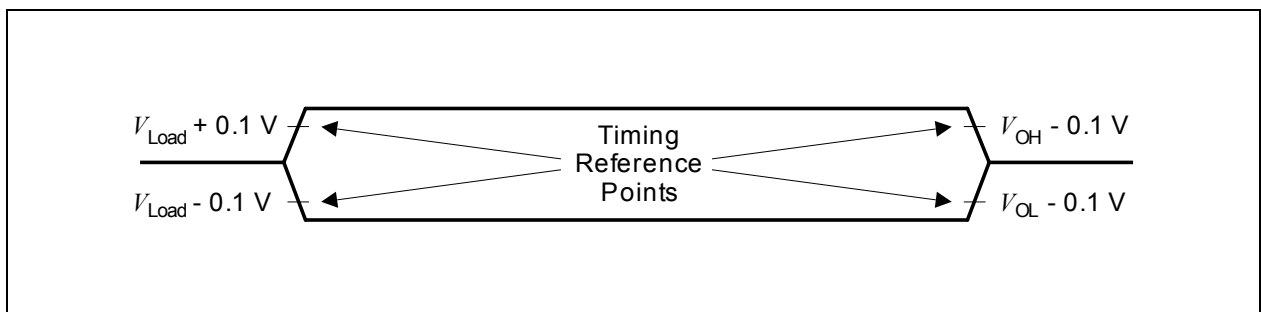


Figure 38 Testing Waveform, Output High Impedance

Electrical Parameters

Table 51 shows the timing of the external data memory write cycle.

Table 51 External Data Memory Write Timing¹⁾ (Operating Conditions apply)

Parameter	Symbol		Limit Values		Unit	Test Conditions
			Min.	Max.		
$\overline{\text{WR}}$ pulse width	t_1	CC	$f_{\text{CCLK}} - 10$	-	ns	2)
Address valid to $\overline{\text{WR}}$	t_2	CC	$2 \cdot f_{\text{CCLK}} - 7$	-	ns	2)
Data valid to $\overline{\text{WR}}$ transition	t_3	SR	$f_{\text{CCLK}} - 5$	-	ns	2)
Data setup before $\overline{\text{WR}}$	t_4	SR	$9 \cdot f_{\text{CCLK}} - 13$	-	ns	2)
Data hold after $\overline{\text{WR}}$	t_5	SR	$6 \cdot f_{\text{CCLK}} - 3$	-	ns	2)

1) External Bus Interface is not available in XC874.

2) Not all parameters are 100% tested, but are verified by design/characterization and test correlation.

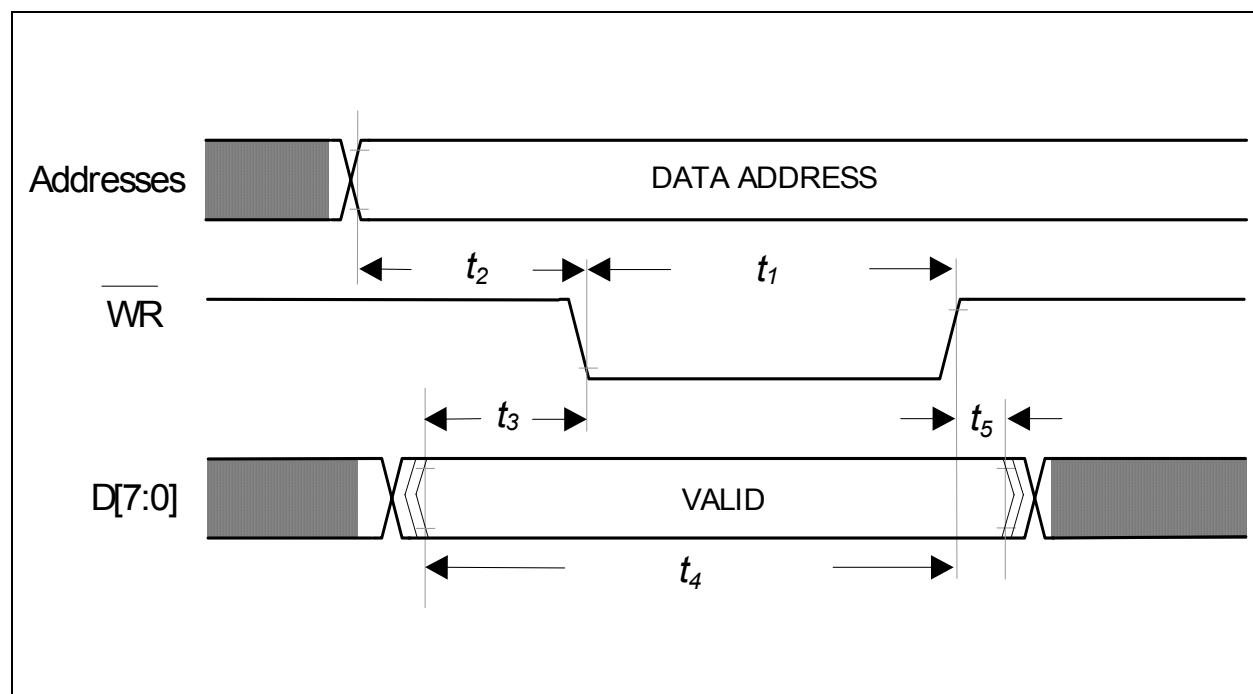


Figure 42 External Data Memory Write Cycle

5 Package and Quality Declaration

Chapter 5 provides the information of the XC87x package and reliability section.

5.1 Package Parameters

Table 56 provides the thermal characteristics of the package used in XC878 and XC874.

Table 56 Thermal Characteristics of the Packages

Parameter	Symbol		Limit Values		Unit	Notes
			Min.	Max.		
PG-LQFP-64-4 (XC878)						
Thermal resistance junction case ¹⁾	R_{TJC}	CC	-	13.8	K/W	-
Thermal resistance junction lead ¹⁾	R_{TJL}	CC	-	34.6	K/W	-
PG-VQFN-48-22 (XC874)						
Thermal resistance junction case ¹⁾	R_{TJC}	CC	-	16.6	K/W	-
Thermal resistance junction lead ¹⁾	R_{TJL}	CC	-	30.7	K/W	-

1) The thermal resistances between the case and the ambient (R_{TCA}), the lead and the ambient (R_{TLA}) are to be combined with the thermal resistances between the junction and the case (R_{TJC}), the junction and the lead (R_{TJL}) given above, in order to calculate the total thermal resistance between the junction and the ambient (R_{TJA}). The thermal resistances between the case and the ambient (R_{TCA}), the lead and the ambient (R_{TLA}) depend on the external system (PCB, case) characteristics, and are under user responsibility.

The junction temperature can be calculated using the following equation: $T_J = T_A + R_{TJA} \times P_D$, where the R_{TJA} is the total thermal resistance between the junction and the ambient. This total junction ambient resistance R_{TJA} can be obtained from the upper four partial thermal resistances, by

- simply adding only the two thermal resistances (junction lead and lead ambient), or
- by taking all four resistances into account, depending on the precision needed.

5.2 Package Outline

Figure 47 shows the package outlines of the XC878.

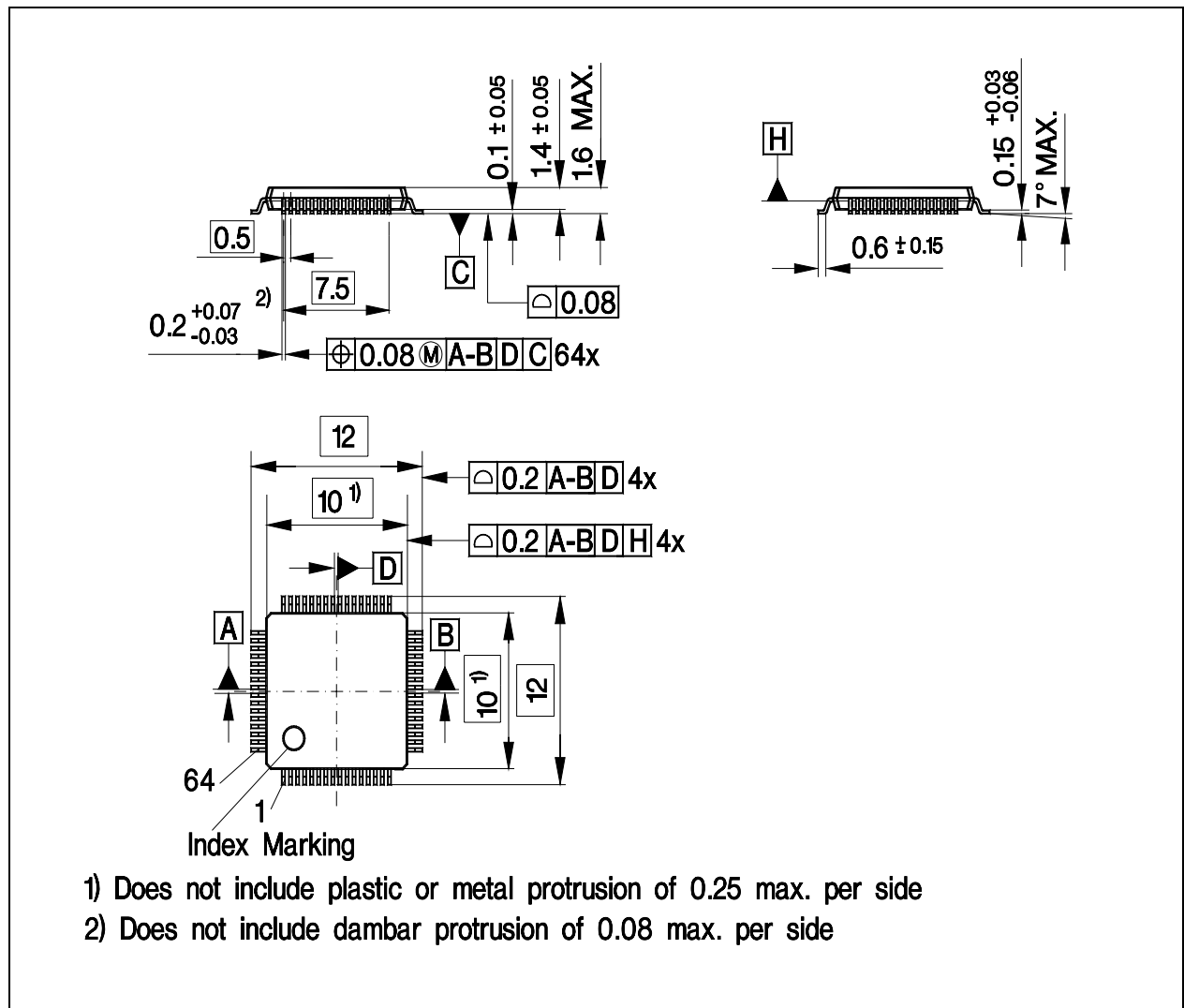


Figure 47 PG-LQFP-64-4 Package Outline

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