Infineon Technologies - XMC1402Q064X0128AAXUMA1 Datasheet

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, I²S, POR, PWM, WDT
Number of I/O	48
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 12x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	PG-VQFN-64-6
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/xmc1402q064x0128aaxuma1

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Table of Contents

1.1 Device Overview

The following table lists the available features per device type for the XMC1400 series.

Table 1 Features of XMC1400 Device Types[1)]

Features		XMC1401-Q048	XMC1401-F064	XMC1402-T038	XMC1402-Q040	XMC1402-Q048	XMC1402-Q064	XMC1402-F064	XMC1403-Q040	XMC1403-Q048	XMC1403-Q064	XMC1404-Q048	XMC1404-Q064	XMC1404-F064
CPU frequency		48 MHz												
Operating temperature (ambient)		-40 to 85 °C		-40 to 105 °C										
Operating voltage		1.8 V to 5.5 V												
Flash options (Kbytes)		64, 128	64, 128	32, 64, 128 200	32, 64, 128 200	32, 64, 128 200	64, 128 200	64, 128 200	64, 128 200	64, 128 200	64, 128 200	64, 128 200	64, 128 200	64, 128 200
SRAM (Kbytes)		16	16	16	16	16	16	16	16	16	16	16	16	16
MATH		-	-	1	1	1	1	1	-	-	-	1	1	1
Industrial Control	CCU4	2	2	2	2	2	2	2	2	2	2	2	2	2
	CCU8	-	-	2	2	2	2	2	-	-	-	2	2	2
	POSIF	-	-	1	1	2	2	2	-	-	-	2	2	2
	BCCU	-	-	1	1	1	1	1	-	-	-	1	1	1
Communication	USIC (modules / channels)	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2	2 / 2
	LEDTS	3	3	-	-	-	-	-	-	-	-	3	3	3
	MultiCAN+ (nodes / MOs)	-	-	-	-	-	-	-	2 / 32	2 / 32	2 / 32	2 / 32	2 / 32	2 / 32

Table 2 Synopsis of XMC1400 Device Types (cont'd)

Derivative	Package	Flash Kbytes
XMC1403-Q048X0200	PG-VQFN-48	200
XMC1403-Q064X0064	PG-VQFN-64	64
XMC1403-Q064X0128	PG-VQFN-64	128
XMC1403-Q064X0200	PG-VQFN-64	200
XMC1404-Q048X0064	PG-VQFN-48	64
XMC1404-Q048X0128	PG-VQFN-48	128
XMC1404-Q048X0200	PG-VQFN-48	200
XMC1404-Q064X0064	PG-VQFN-64	64
XMC1404-Q064X0128	PG-VQFN-64	128
XMC1404-Q064X0200	PG-VQFN-64	200
XMC1404-F064X0064	PG-LQFP-64	64
XMC1404-F064X0128	PG-LQFP-64	128
XMC1404-F064X0200	PG-LQFP-64	200

1.4 Chip Identification Number

The Chip Identification Number allows software to identify the marking. It is an 8 words value with the most significant 7 words stored in Flash configuration sector 0 (CS0) at address location : 1000 $0F00_H$ (MSB) - 1000 $0F1B_H$ (LSB). The least significant word and most significant word of the Chip Identification Number are the value of registers DBGROMID and IDCHIP, respectively.

Table 3 XMC1400 Chip Identification Number

Derivative	Value	Marking
XMC1401-Q048F0064	00014082 07CF00FF 1E071FF7 20006000 00000D00 00001000 00011000 10204083_H	AA
XMC1401-Q048F0128	00014082 07CF00FF 1E071FF7 20006000 00000D00 00001000 00021000 10204083_H	AA
XMC1401-F064F0064	000140A2 07CF00FF 1E071FF7 20006000 00000D00 00001000 00011000 10204083_H	AA
XMC1401-F064F0128	000140A2 07CF00FF 1E071FF7 20006000 00000D00 00001000 00021000 10204083_H	AA
XMC1402-T038X0032	00014013 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00009000 10204083_H	AA
XMC1402-T038X0064	00014013 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00011000 10204083_H	AA
XMC1402-T038X0128	00014013 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00021000 10204083_H	AA
XMC1402-T038X0200	00014013 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00033000 10204083_H	AA
XMC1402-Q040X0032	00014043 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00009000 10204083_H	AA
XMC1402-Q040X0064	00014043 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00011000 10204083_H	AA
XMC1402-Q040X0128	00014043 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00021000 10204083_H	AA
XMC1402-Q040X0200	00014043 07FF00FF 1E071FF7 000F900F 00000D00 00001000 00033000 10204083_H	AA
XMC1402-Q048X0032	00014083 07FF00FF 1E071FF7 100F900F 00000D00 00001000 00009000 10204083_H	AA

Table 3 XMC1400 Chip Identification Number (cont'd)

Derivative	Value	Marking
XMC1403-Q064X0200	00014093 07CF00FF 1E071FF7 00B00000 00000D00 00001000 00033000 10204083_H	AA
XMC1404-Q048X0064	00014083 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00011000 10204083_H	AA
XMC1404-Q048X0128	00014083 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00021000 10204083_H	AA
XMC1404-Q048X0200	00014083 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00033000 10204083_H	AA
XMC1404-Q064X0064	00014093 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00011000 10204083_H	AA
XMC1404-Q064X0128	00014093 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00021000 10204083_H	AA
XMC1404-Q064X0200	00014093 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00033000 10204083_H	AA
XMC1404-F064X0064	000140A3 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00011000 10204083_H	AA
XMC1404-F064X0128	000140A3 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00021000 10204083_H	AA
XMC1404-F064X0200	000140A3 07FF00FF 1E071FF7 30BFF00F 00000D00 00001000 00033000 10204083_H	AA

2.2 Pin Configuration and Definition

The following figures summarize all pins, showing their locations on the different packages.

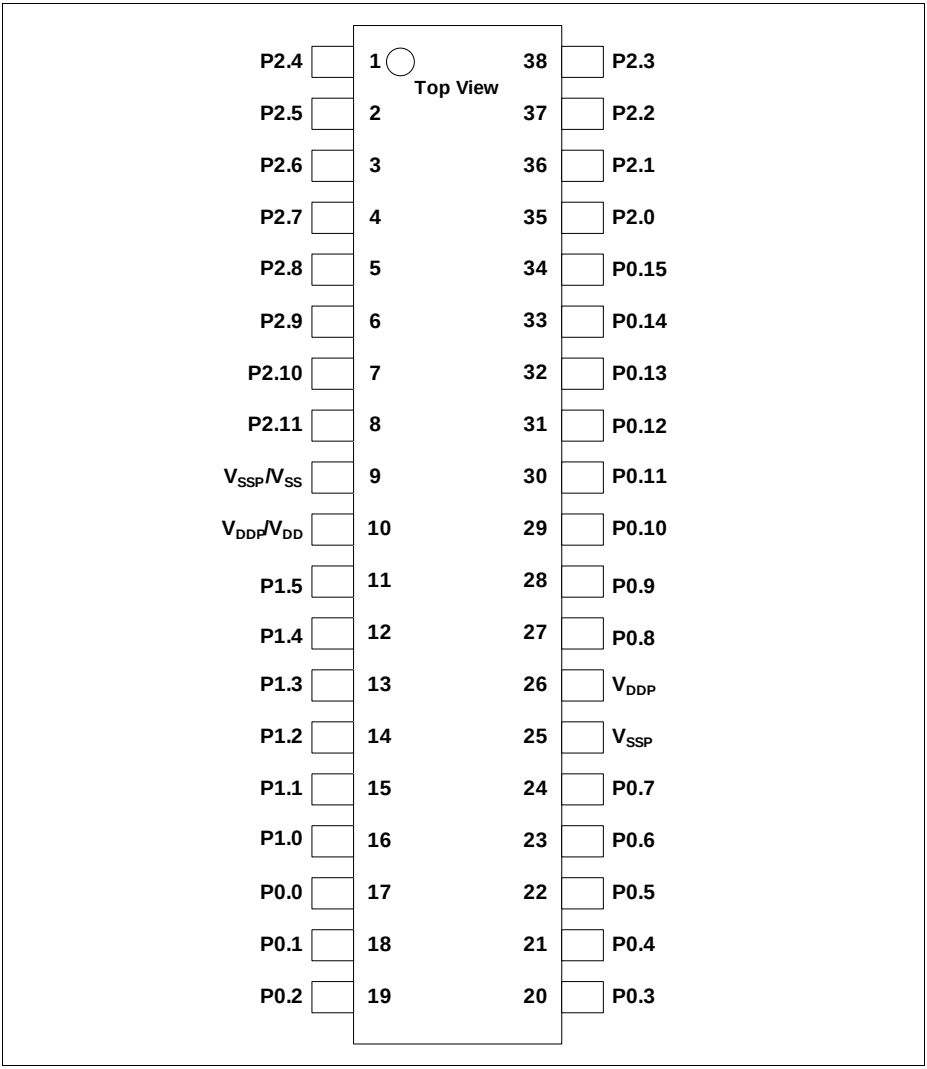


Figure 6 XMC1400 PG-TSSOP-38-9 Pin Configuration (top view)

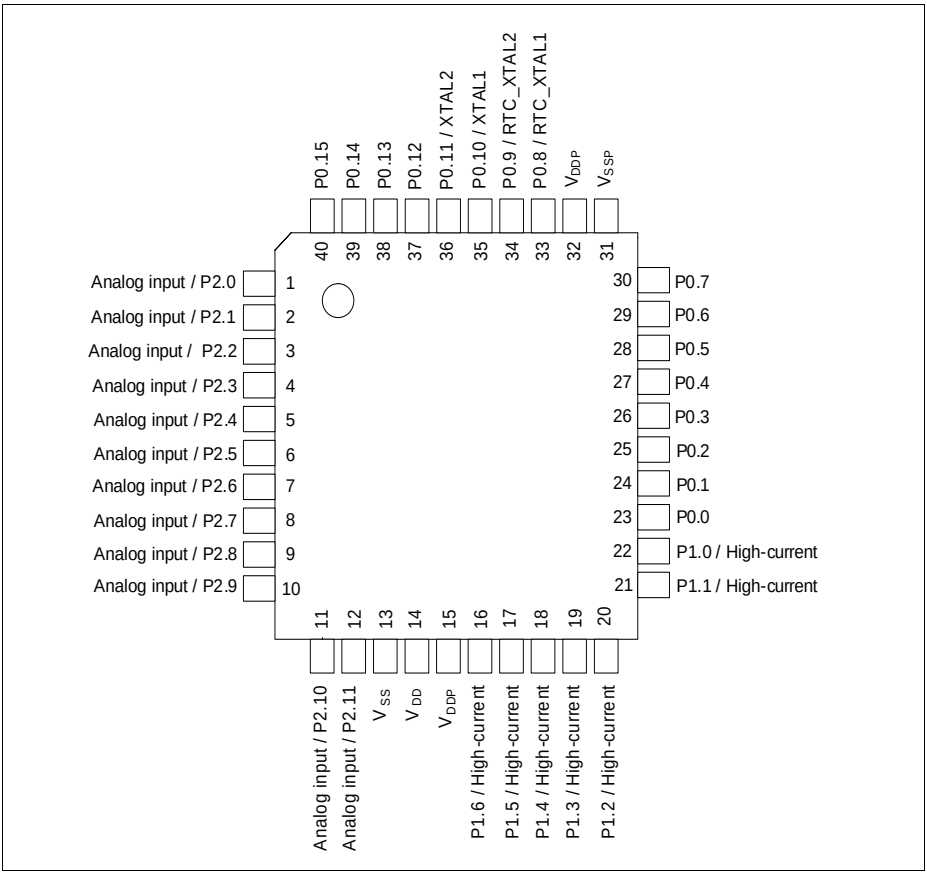


Figure 7 XMC1400 PG-VQFN-40-17 Pin Configuration (top view)

Table 10 Hardware I/O Controlled Functions

Function	Outputs	Outputs	Inputs	Inputs	Pull Control	Pull Control	Pull Control	Pull Control
	HWO0	HWO1	HWI0	HWI1	HW0_PD	HW0_PU	HW1_PD	HW1_PU
P4.4	LEDTS2. EXTENDED0		LEDTS2.TSIN0	LEDTS2.TSIN0	Reserved for LEDTS Scheme A: pull-down disabled always	Reserved for LEDTS Scheme A: pull-down enabled always	Reserved for LEDTS Scheme B: pull-up enabled and pull-down disabled, and vice versa	
P4.5	LEDTS2. EXTENDED1		LEDTS2.TSIN1	LEDTS2.TSIN1				
P4.6	LEDTS2. EXTENDED2		LEDTS2.TSIN2	LEDTS2.TSIN2				
P4.7	LEDTS2. EXTENDED3		LEDTS2.TSIN3	LEDTS2.TSIN3				
P4.8	LEDTS2. EXTENDED4		LEDTS2.TSIN4	LEDTS2.TSIN4				
P4.9	LEDTS2. EXTENDED5		LEDTS2.TSIN5	LEDTS2.TSIN5				
P4.10	LEDTS2. EXTENDED6		LEDTS2.TSIN6	LEDTS2.TSIN6				
P4.11	LEDTS2. EXTENDED7		LEDTS2.TSIN7	LEDTS2.TSIN7				

3.2.3 Out of Range Comparator (ORC) Characteristics

The Out-of-Range Comparator (ORC) triggers on analog input voltages (V_{AIN}) above V_{DDP} on selected input pins (ORCx.AIN) and generates a service request trigger (ORCx.OUT).

Note: These parameters are not subject to production test, but verified by design and/or characterization.

Table 18 Out of Range Comparator (ORC) Characteristics (Operating Conditions apply; V_{DDP} = 3.0 V - 5.5 V; C_L = 0.25pF)

Parameter	Symbol		Values			Unit	Note / Test Condition
			Min.	Typ.	Max.		
DC Switching Level	V_{ODC}	CC	–	–	180	mV	$V_{AIN} \geq V_{DDP} + V_{ODC}$
Hysteresis	V_{OHYS}	CC	15	–	54	mV	
Always detected Overvoltage Pulse	t_{OPDD}	CC	103	–	–	ns	$V_{AIN} \geq V_{DDP}$ + 150 mV
			88	–	–	ns	$V_{AIN} \geq V_{DDP}$ + 350 mV
Never detected Overvoltage Pulse	t_{OPDN}	CC	–	–	21	ns	$V_{AIN} \geq V_{DDP}$ + 150 mV
			–	–	11	ns	$V_{AIN} \geq V_{DDP}$ + 350 mV
Detection Delay	t_{ODD}	CC	39	–	132	ns	$V_{AIN} \geq V_{DDP}$ + 150 mV
			31	–	121	ns	$V_{AIN} \geq V_{DDP}$ + 350 mV
Release Delay	t_{ORD}	CC	44	–	240	ns	$V_{AIN} \leq V_{DDP}$; V_{DDP} = 5 V
			57	–	340	ns	$V_{AIN} \leq V_{DDP}$; V_{DDP} = 3.3 V
Enable Delay	t_{OED}	CC	–	–	300	ns	ORCCTRL.ENORCx = 1

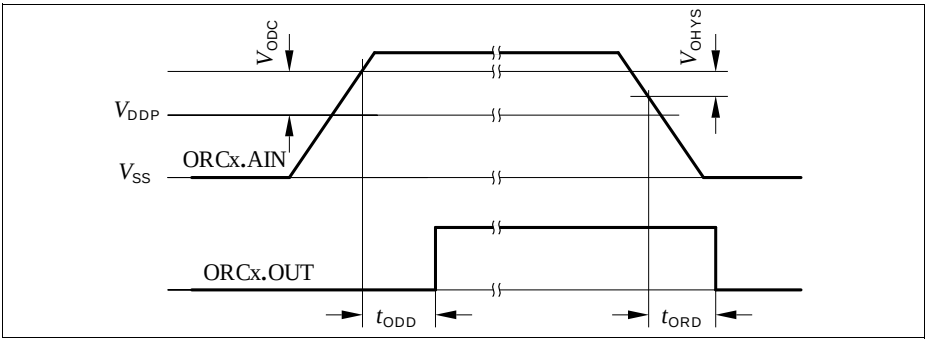


Figure 13 ORCx.OUT Trigger Generation

Table 21 OSC_XTAL Parameters

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Input frequency	f_{OSC} SR	4	–	48	MHz	Direct Input Mode
		4	–	20	MHz	External Crystal Mode
Oscillator start-up time[1)2)]	t_{OSCS} CC	–	–	10	ms	
Input voltage at XTAL1	V_{IX} SR	-0.3	–	1.5	V	External Crystal Mode
		-0.3	–	5.5	V	Direct Input Mode
Input amplitude (peak-to-peak) at XTAL1[2)3)]	V_{PPX} SR	0.6	–	1.7	V	External Crystal Mode

1) t_{OSCS} is defined from the moment the oscillator is enabled wih SCU_ANAOSCHPCTRL.MODE until the oscillations reach an amplitude at XTAL1 of 0.9 * V_{PPX}.

2) The external oscillator circuitry must be optimized by the customer and checked for negative resistance and amplitude as recommended and specified by crystal suppliers.

3) If the shaper unit is enabled and not bypassed.

3.2.7 Power Supply Current

The total power supply current defined below consists of a leakage and a switching component.

Application relevant values are typically lower than those given in the following tables, and depend on the customer's system operating conditions (e.g. thermal connection or used application configurations).

Note: These parameters are not subject to production test, but verified by design and/or characterization.

Table 23 Power Supply parameter table; V_{DDP} = 5V

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.[1]	Max.		
Active mode current Peripherals enabled f_{MCLK} / f_{PCLK} in MHz[2]	I_{DDPAE} CC	–	14.1	20	mA	48 / 96
		–	9.8	–	mA	24 / 48
		–	7.8	–	mA	16 / 32
		–	6.4	–	mA	8 / 16
		–	4.4	–	mA	1 / 1
Active mode current Peripherals disabled f_{MCLK} / f_{PCLK} in MHz[3]	I_{DDPAD} CC	–	6.2		mA	48 / 96
		–	4.6	–	mA	24 / 48
		–	3.6	–	mA	16 / 32
		–	3.1	–	mA	8 / 16
		–	1.8	–	mA	1 / 1
Active mode current Code execution from RAM Flash is powered down f_{MCLK} / f_{PCLK} in MHz	I_{DDPAR} CC	–	9.6	–	mA	48 / 96
Sleep mode current Peripherals clock enabled f_{MCLK} / f_{PCLK} in MHz[4]	I_{DDPSE} CC	–	11.0	–	mA	48 / 96
		–	7.6	–	mA	24 / 48
		–	6.4	–	mA	16 / 32
		–	5.3	–	mA	8 / 16
		–	4.2	–	mA	1 / 1

Table 24 provides the active current consumption of some modules operating at 5 V power supply at 25 °C. The typical values shown are used as a reference guide on the current consumption when these modules are enabled.

Table 24 Typical Active Current parameter table

Active Current Consumption	Symbol	Limit Values	Unit	Test Condition
		Typ.		
Baseload current	I_{CPUDDC}	4.14	mA	Modules including Core, SCU, PORT, memories, ANATOP[1)]
VADC and SHS	I_{ADCDDC}	3.73	mA	Set CGATCLR0.VADC to 1[2)]
USICx	$I_{USIC0DDC}$	1.35	mA	Set CGATCLR0.USIC0 to 1[3)]
CCU4x	$I_{CCU40DDC}$	0.99	mA	Set CGATCLR0.CCU40 to 1[4)]
CCU8x	$I_{CCU80DDC}$	1.00	mA	Set CGATCLR0.CCU80 to 1[5)]
POSIFx	$I_{PIF0DDC}$	1.05	mA	Set CGATCLR0.POSIF0 to 1[6)]
LEDTSx	$I_{LTSxDDC}$	1.14	mA	Set CGATCLR0.LEDTSx to 1[7)]
BCCU0	$I_{BCCU0DDC}$	0.29	mA	Set CGATCLR0.BCCU0 to 1[8)]
MATH	$I_{MATHDDC}$	0.50	mA	Set CGATCLR0.MATH to 1[9)]
WDT	I_{WDTDDC}	0.03	mA	Set CGATCLR0.WDT to 1[10)]
RTC	I_{RTCDDC}	0.01	mA	Set CGATCLR0.RTC to 1[11)]
MultiCAN	$I_{MCANDDC}$	1.38	mA	Set CGATCLR0.MCAN0 to 1[12)]

1) Baseload current is measured with device running in user mode, MCLK=PCLK=48 MHz, with an endless loop in the flash memory. The clock to the modules stated in CGATSTAT0 are gated.

2) Active current is measured with: module enabled, MCLK=48 MHz, running in auto-scan conversion mode

3) Active current is measured with: module enabled, each of the 2 USIC channels sending alternate messages at 57.6 kbaud every 200 ms

4) Active current is measured with: module enabled, MCLK=PCLK=48 MHz, 1 CCU4 slice for PWM switching at 20kHz with duty cycle varying at 10%-90%, 1 CCU4 slice in capture mode for reading period and duty cycle

5) Active current is measured with: module enabled, MCLK=PCLK=48 MHz, 3 CCU8 slices with PWM frequency at 20kHz and a period match interrupt used to toggle duty cycle between 10% and 90%

6) Active current is measured with: module enabled, MCLK=48 MHz, PCLK=96 MHz, hall sensor mode

7) Active current is measured with: module enabled, MCLK=48 MHz, 1 LED column, 6 LED/TS lines, Pad Scheme A with large pad hysteresis config, time slice duration = 1.048 ms

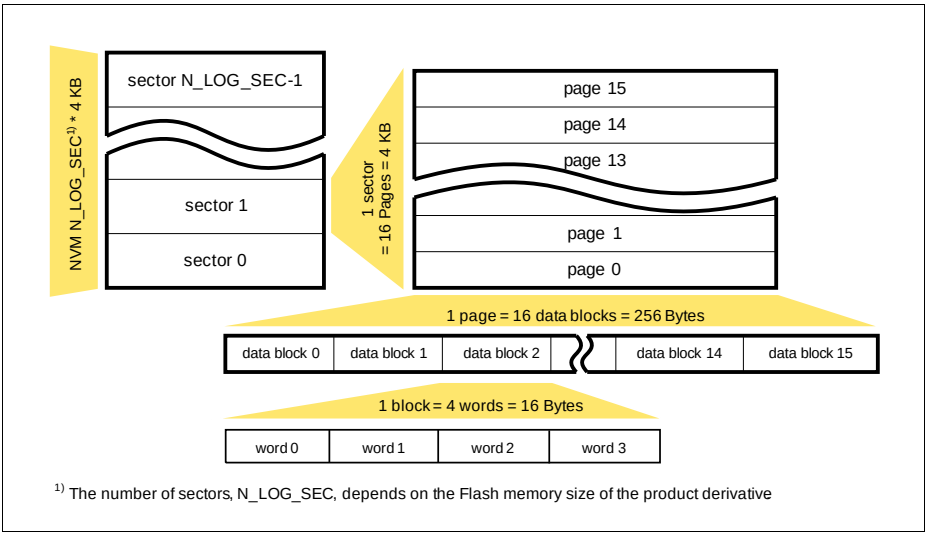
8) Active current is measured with: module enabled, MCLK=48 MHz, PCLK=96MHz, FCLK=0.8 MHz, Normal mode (BCCU clock = FCLK/4), 4 BCCU Channels with packers enabled and 1 Dimming Engine, change color or dim every 1s

9) Active current is measured with: module enabled, MCLK=48 MHz, PCLK=96 MHz, tangent calculation in while loop; CORDIC circular rotation, no keep, autostart; 32-by-32 bit signed DIV, autostart, DVS right shift by 11

10) Active current is measured with: module enabled, MCLK=48 MHz, time-out mode; WLB = 0, WUB = 0x00008000; WDT serviced every 1 s

11) Active current is measured with: module enabled, MCLK=48 MHz, Periodic interrupt enabled

12) Active current is measured with: module enabled, MCLK=48 MHz, running at 20 MHz baudrate generator, 1 node activated, 1 transmit and 1 receive object active.



[1] The number of sectors, N_LOG_SEC, depends on the Flash memory size of the product derivative

Figure 19 Logical Structure of the Flash

3.3.4 Serial Wire Debug Port (SW-DP) Timing

The following parameters are applicable for communication through the SW-DP interface.

Note: These parameters are not subject to production test, but verified by design and/or characterization.

Table 29 SWD Interface Timing Parameters(Operating Conditions apply)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
SWDCLK high time	t_1 SR	50	–	500000	ns	–
SWDCLK low time	t_2 SR	50	–	500000	ns	–
SWDIO input setup to SWDCLK rising edge	t_3 SR	10	–	–	ns	–
SWDIO input hold after SWDCLK rising edge	t_4 SR	10	–	–	ns	–
SWDIO output valid time after SWDCLK rising edge	t_5 CC	–	–	68	ns	C_L = 50 pF
		–	–	62	ns	C_L = 30 pF
SWDIO output hold time from SWDCLK rising edge	t_6 CC	4	–	–	ns	

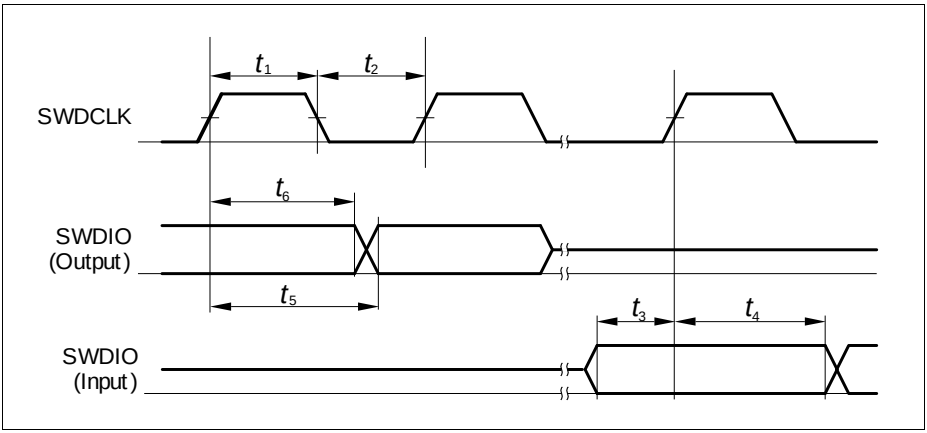


Figure 24 SWD Timing

3.3.5 SPD Timing Requirements

The optimum SPD decision time between 0_B and 1_B is 0.75 µs. With this value the system has maximum robustness against frequency deviations of the sampling clock on tool and on device side. However it is not always possible to exactly match this value with the given constraints for the sample clock. For instance for a oversampling rate of 4, the sample clock will be 8 MHz and in this case the closest possible effective decision time is 5.5 clock cycles (0.69 µs).

Table 30 Optimum Number of Sample Clocks for SPD

Sample Freq.	Sampling Factor	Sample Clocks 0_B	Sample Clocks 1_B	Effective Decision Time[1)]	Remark
8 MHz	4	1 to 5	6 to 12	0.69 µs	The other closest option (0.81 µs) for the effective decision time is less robust.

1) Nominal sample frequency period multiplied with 0.5 + (max. number of 0_B sample clocks)

For a balanced distribution of the timing robustness of SPD between tool and device, the timing requirements for the tool are:

- Frequency deviation of the sample clock is +/- 5%
- Effective decision time is between 0.69 µs and 0.75 µs (calculated with nominal sample frequency)

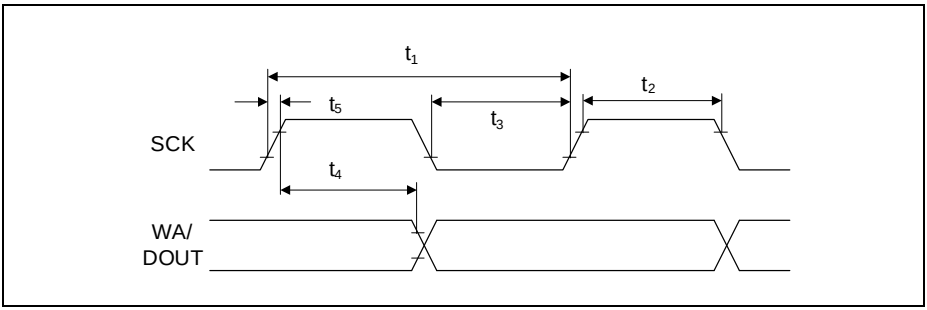


Figure 27 USIC IIS Master Transmitter Timing

Table 36 USIC IIS Slave Receiver Timing

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Clock period	t_6 SR	$4/f_{MCLK}$	-	-	ns	
Clock HIGH	t_7 SR	0.35 x t_{6min}	-	-	ns	
Clock Low	t_8 SR	0.35 x t_{6min}	-	-	ns	
Set-up time	t_9 SR	0.3 x t_{6min}	-	-	ns	
Hold time	t_{10} SR	15	-	-	ns	

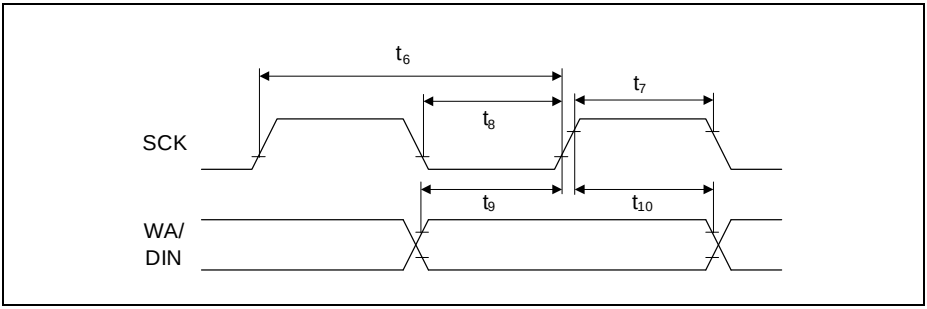


Figure 28 USIC IIS Slave Receiver Timing

4.2 Package Outlines

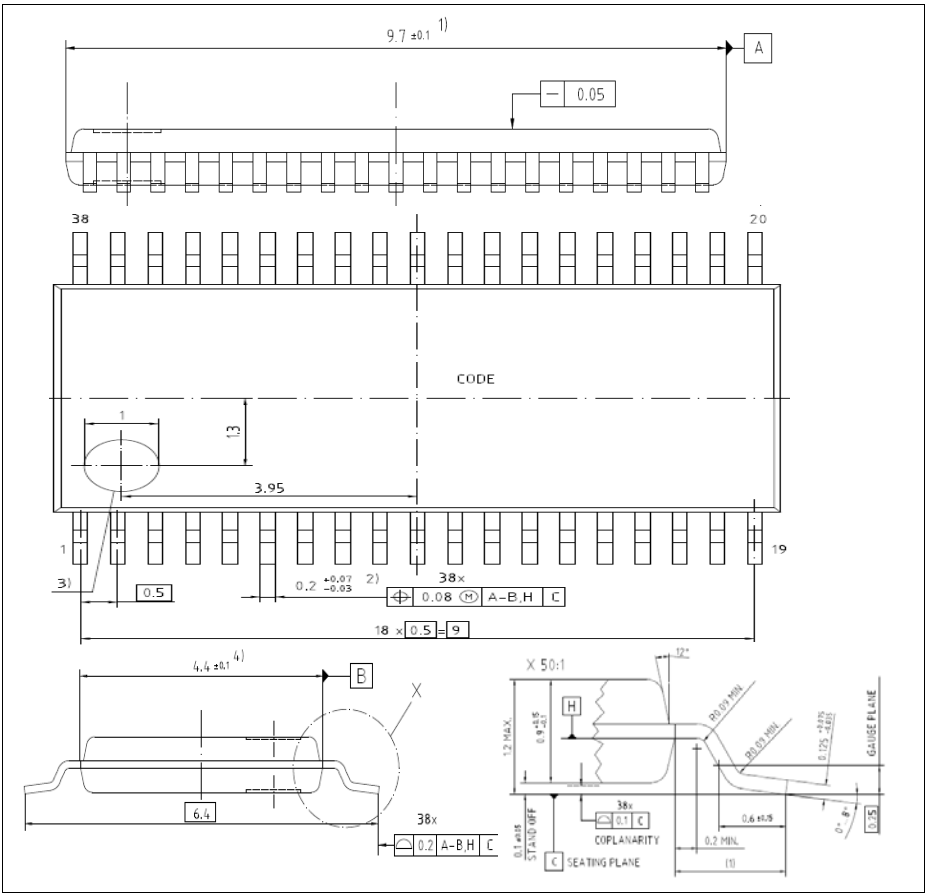


Figure 29 PG-TSSOP-38-9

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