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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Dectano	
Product Status	Active
Core Processor	ARM® Cortex®-M7
Core Size	32-Bit Single-Core
Speed	300MHz
Connectivity	CANbus, Ethernet, I ² C, IrDA, LINbus, SPI, SSC, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, POR, PWM, WDT
Number of I/O	44
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	384K x 8
Voltage - Supply (Vcc/Vdd)	1.7V ~ 3.6V
Data Converters	A/D 5x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsame70j20b-ant

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Fast Flash Programming Interface (FFPI)

Step	Handshake Sequence	MODE[3:0]	DATA[15:0]
n	Write handshaking	ADDR0	Memory Address LSB
n+1	Write handshaking	ADDR1	Memory Address
n+2	Write handshaking	DATA	*Memory Address++
n+3	Write handshaking	DATA	*Memory Address++

18.3.5.8 Get Version Command

The Get Version (GVE) command retrieves the version of the FFPI interface.

Table 18-15. Get Version Command

Step	Handshake Sequence	MODE[3:0]	DATA[15:0]
1	Write handshaking	CMDE	GVE
2	Read handshaking	DATA	Version

22.4.2 Read Operations

An optimized controller manages embedded Flash reads, thus increasing performance when the processor is running in Thumb-2 mode by means of the 128-bit-wide memory interface.

The Flash memory is accessible through 8-, 16- and 32-bit reads.

As the Flash block size is smaller than the address space reserved for the internal memory area, the embedded Flash wraps around the address space and appears to be repeated within it.

The read operations can be performed with or without wait states. Wait states must be programmed in the field FWS in the Flash Mode register (EEFC_FMR). Defining FWS as 0 enables the single-cycle access of the embedded Flash. For more details, refer to the section "Electrical Characteristics" of this datasheet.

Related Links

- 59. Electrical Characteristics for SAM E70/S70
- 58. Electrical Characteristics for SAM V70/V71

22.4.2.1 Code Read Optimization

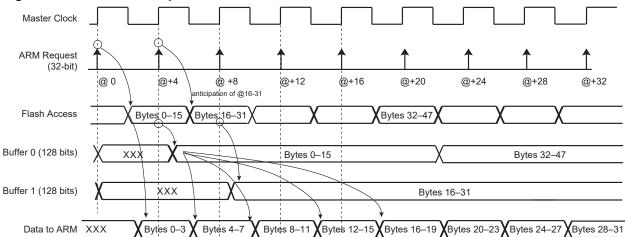
Code read optimization is enabled if the bit EEFC_FMR.SCOD is cleared.

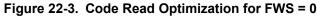
A system of 2 x 128-bit buffers is added in order to optimize sequential code fetch.

Note: Immediate consecutive code read accesses are not mandatory to benefit from this optimization.

The sequential code read optimization is enabled by default. If the bit EEFC_FMR.SCOD is set, these buffers are disabled and the sequential code read is no longer optimized.

Another system of 2 x 128-bit buffers is added in order to optimize loop code fetch. Refer to the "Code Loop Optimization" section for more details.





Note: When FWS is equal to '0', all the accesses are performed in a single-cycle access.

Enhanced Embedded Flash Controller (EEFC)

Symbol	Word Index	Description
FL_ID	0	Flash interface description
FL_SIZE	1	Flash size in bytes
FL_PAGE_SIZE	2	Page size in bytes
FL_NB_PLANE	3	Number of planes
FL_PLANE[0]	4	Number of bytes in the plane
FL_NB_LOCK	4 + FL_NB_PLANE	Number of lock bits. A bit is associated with a lock region. A lock bit is used to prevent write or erase operations in the lock region.
FL_LOCK[0]	4 + FL_NB_PLANE + 1	Number of bytes in the first lock region

Table 22-2. Flash Descriptor Definition

22.4.3.2 Write Commands

DMA write accesses must be 32-bit aligned. If a single byte is to be written in a 32-bit word, the rest of the word must be written with ones.

Several commands are used to program the Flash.

Only 0 values can be programmed using Flash technology; 1 is the erased value. In order to program words in a page, the page must first be erased. Commands are available to erase the full memory plane or a given number of pages. With the EWP and EWPL commands, a page erase is done automatically before a page programming.

After programming, the page (the entire lock region) can be locked to prevent miscellaneous write or erase sequences. The lock bit can be automatically set after page programming using WPL or EWPL commands.

Data to be programmed in the Flash must be written in an internal latch buffer before writing the programming command in EEFC_FCR. Data can be written at their final destination address, as the latch buffer is mapped into the Flash memory address space and wraps around within this Flash address space.

Byte and half-word AHB accesses to the latch buffer are not allowed. Only 32-bit word accesses are supported.

32-bit words must be written continuously, in either ascending or descending order. Writing the latch buffer in a random order is not permitted. This prevents mapping a C-code structure to the latch buffer and accessing the data of the structure in any order. It is instead recommended to fill in a C-code structure in SRAM and copy it in the latch buffer in a continuous order.

Write operations in the latch buffer are performed with the number of wait states programmed for reading the Flash.

The latch buffer is automatically re-initialized, i.e., written with logical '1', after execution of each programming command.

The programming sequence is the following:

- 1. Write the data to be programmed in the latch buffer.
- 2. Write the programming command in EEFC_FCR. This automatically clears the bit EEFC_FSR.FRDY.

26.4.5.1 RSTC Control Register

	Name: Offset: Property:	RSTC_CR 0x00 Write-only						
Bit	31	30	29	28	27	26	25	24
				KEY	[7:0]			
Access	W	W	W	W	W	W	W	W
Reset	0	0	0	0	0	0	0	-
Bit	23	22	21	20	19	18	17	16
Dit	25		21	20	15	10	17	
Access								
Reset								
Reset								
Bit	15	14	13	12	11	10	9	8
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
					EXTRST			PROCRST
Access					W			W
Reset					-			-

Bits 31:24 - KEY[7:0] System Reset Key

Value	Name	Description
0xA5	PASSWD	Writing any other value in this field aborts the write operation.

Bit 3 – EXTRST External Reset

Value	Description
0	No effect.
1	If KEY = 0xA5, asserts the NRST pin.

Bit 0 - PROCRST Processor Reset

Value	Description
0	No effect.
1	If KEY = 0xA5, resets the processor and all the embedded peripherals.

GMAC - Ethernet MAC

.						
Offset	Name	Bit Pos.				
		7:0			DMPVAL[7:0]	
0x06E0	GMAC_ST2ER0	15:8		CO	MPVAL[15:8]	
		23:16				
		31:24				
		7:0			DMPVAL[7:0]	
0x06E4	GMAC_ST2ER1	15:8		CO	MPVAL[15:8]	
		23:16				
		31:24				
		7:0			DMPVAL[7:0]	
0x06E8	GMAC_ST2ER2	15:8		CO	MPVAL[15:8]	
		23:16				
		31:24				
		7:0			DMPVAL[7:0]	
0x06EC	0x06EC GMAC_ST2ER3	15:8		CO	MPVAL[15:8]	
		23:16				
		31:24				
0x06F0						
	Reserved					
0x06FF		7.0				
		7:0			ASKVAL[7:0]	
0x0700	GMAC_ST2CW00	15:8			SKVAL[15:8]	
		23:16			OMPVAL[7:0]	
		31:24		CU	MPVAL[15:8]	
		7:0	OFFSSTRT[0: 0]		OFFSVAL[6:0]	
			5]			OFFSSTRT[1:
0x0704	GMAC_ST2CW10	15:8				1]
		23:16				·,
		31:24				
		7:0		M	ASKVAL[7:0]	
		15:8			SKVAL[15:8]	
0x0708	GMAC_ST2CW01	23:16			DMPVAL[7:0]	
		31:24			MPVAL[15:8]	
		0.1.2.1	OFFSSTRT[0:			
		7:0	0]		OFFSVAL[6:0]	
						OFFSSTRT[1:
0x070C	GMAC_ST2CW11	15:8				1]
		23:16				
		31:24				
		7:0		M	ASKVAL[7:0]	
		15:8			SKVAL[15:8]	
0x0710	GMAC_ST2CW02	23:16			DMPVAL[7:0]	
		31:24			MPVAL[15:8]	
			OFFSSTRT[0:			
0x0714	GMAC_ST2CW12	7:0	0]		OFFSVAL[6:0]	
			1			

38.8.24 GMAC Type ID Match n Register

	Name: Offset: Reset: Property:	GMAC_TIDM 0xA8 + x*0x04 0x00000000 Read/Write						
Bit	31	30	29	28	27	26	25	24
	ENIDn							
Access	R/W							
Reset	0							
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
				TID[15:8]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
					[7:0]			
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bit 31 – ENIDn Enable Copying of TID Matched Frames

Value	Description
0	TID n is not part of the comparison match.
1	TID n is processed for the comparison match.

Bits 15:0 - TID[15:0] Type ID Match n

For use in comparisons with received frames type ID/length frames.

USB High-Speed Interface (USBHS)

Value	Description
0	Cleared when the HBISOFLUSHIC bit is written to one. This acknowledges the interrupt.
1	Set for High-bandwidth isochronous IN endpoint (with NBTRANS = 2 or 3) at the end of the
	microframe, if less than N transactions have been completed by the USBHS without
	underflow error. This may occur in case of a missing IN token. In this case, the banks are
	flushed out to ensure the data synchronization between the host and the device. This
	triggers a PEP_x interrupt if HBISOFLUSHE = 1.

Bit 3 – HBISOINERRI High Bandwidth Isochronous IN Underflow Error Interrupt

Value	Description
0	Cleared when the HBISOINERRIC bit is written to one. This acknowledges the interrupt.
1	Set for High-bandwidth isochronous IN endpoint (with NBTRANS = 2 or 3) at the end of the
	microframe, if less than N banks were written by the CPU within this microframe. This
	triggers a PEP_x interrupt if HBISOINERRE = 1.

Bit 2 – UNDERFI Underflow Interrupt

This bit is set, for isochronous IN/OUT endpoints, when an underflow error occurs. This triggers a PEP_x interrupt if UNDERFE = 1.

An underflow can occur during IN stage if the host attempts to read from an empty bank. A zero-length packet is then automatically sent by the USBHS.

An underflow can also occur during OUT stage if the host sends a packet while the bank is already full. Typically, the CPU is not fast enough. The packet is lost.

It is cleared by writing a one to the UNDERFIC bit. This acknowledges the interrupt.

Bit 1 – RXOUTI Received OUT Data Interrupt

For control endpoints:

0: Cleared by writing a one to the RXOUTIC bit. This acknowledges the interrupt and frees the bank.

1: Set when the current bank contains a bulk OUT packet (data or status stage). This triggers a PEP_x interrupt if USBHS_DEVEPTIMRx.RXOUTE = 1.

For OUT endpoints:

0: Cleared by writing a one to the RXOUTIC bit. This acknowledges the interrupt, which has no effect on the endpoint FIFO. USBHS_DEVEPTISRx.RXOUTI shall always be cleared before clearing USBHS_DEVEPTIMRx.FIFOCON.

1: Set at the same time as USBHS_DEVEPTIMRx.FIFOCON when the current bank is full. This triggers a PEP_x interrupt if USBHS_DEVEPTIMRx.RXOUTE = 1.

The user reads from the FIFO and clears the USBHS_DEVEPTIMRx.FIFOCON bit to free the bank. If the OUT endpoint is composed of multiple banks, this also switches to the next bank. The USBHS_DEVEPTISRx.RXOUTI and USBHS_DEVEPTIMRx.FIFOCON bits are set/cleared in accordance with the status of the next bank.

This bit is inactive (cleared) for IN endpoints.

Bit 0 – TXINI Transmitted IN Data Interrupt For control endpoints:

0: Cleared when TXINIC = 1. This acknowledges the interrupt and sends the packet.

USB High-Speed Interface (USBHS)

39.6.22 Device Endpoint Interrupt Mask Register (Isochronous Endpoints)

Name:	USBHS_DEVEPTIMRx (ISOENPT)
Offset:	0x01C0 + x*0x04 [x=09]
Reset:	0
Property:	Read/Write

This register view is relevant only if EPTYPE = 0x1 in "Device Endpoint x Configuration Register".

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
						RSTDT		EPDISHDMA
Access								
Reset						0		0
Bit	15	14	13	12	11	10	9	8
		FIFOCON	KILLBK	NBUSYBKE		ERRORTRANS	DATAXE	MDATAE
						E		
Access			•	•				
Reset		0	0	0		0	0	0
Bit	7	6	5	4	3	2	1	0
	SHORTPACKE	CRCERRE	OVERFE	HBISOFLUSHE	HBISOINERRE	UNDERFE	RXOUTE	TXINE
	TE							
Access								
Reset	0	0	0	0	0	0	0	0

Bit 18 – RSTDT Reset Data Toggle

This bit is set when USBHS_DEVEPTIERx.RSTDTS = 1. This clears the data toggle sequence, i.e., sets to Data0 the data toggle sequence of the next sent (IN endpoints) or received (OUT endpoints) packet.

This bit is cleared instantaneously.

The user does not have to wait for this bit to be cleared.

Bit 16 - EPDISHDMA Endpoint Interrupts Disable HDMA Request

This bit is set when USBHS_DEVEPTIERx.EPDISHDMAS = 1. This pauses the on-going DMA channel x transfer on any Endpoint x interrupt (PEP_x), whatever the state of the Endpoint x Interrupt Enable bit (PEP_x).

The user then has to acknowledge or to disable the interrupt source (e.g. USBHS_DEVEPTISRx.RXOUTI) or to clear the EPDISHDMA bit (by writing a one to the USBHS_DEVEPTIDRx.EPDISHDMAC bit) in order to complete the DMA transfer.

In Ping-pong mode, if the interrupt is associated to a new system-bank packet (e.g. Bank1) and the current DMA transfer is running on the previous packet (Bank0), then the previous-packet DMA transfer completes normally, but the new-packet DMA transfer does not start (not requested).

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USB High-Speed Interface (USBHS)

Value	Description
0	Cleared when USBHS_HSTPIPIDR.OVERFIEC = 1. This disables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.OVERFIE).
1	Set when USBHS_HSTPIPIER.OVERFIES = 1. This enables the Transmitted IN Data
	interrupt (USBHS HSTPIPIMR.OVERFIE).

Bit 4 – NAKEDE NAKed Interrupt Enable

Value	Description
0	Cleared when USBHS_HSTPIPIDR.NAKEDEC = 1. This disables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.NAKEDE).
1	Set when USBHS_HSTPIPIER.NAKEDES = 1. This enables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.NAKEDE).

Bit 3 – PERRE Pipe Error Interrupt Enable

Value	Description
0	Cleared when USBHS_HSTPIPIDR.PERREC = 1. This disables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.PERRE).
1	Set when USBHS_HSTPIPIER.PERRES = 1. This enables the Transmitted IN Data interrupt (USBHS_HSTPIPIMR.PERRE).

Bit 2 – UNDERFIE Underflow Interrupt Enable

Value	Description
0	Cleared when USBHS_HSTPIPIDR.UNDERFIEC = 1. This disables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.UNDERFIE).
1	Set when USBHS_HSTPIPIER.UNDERFIES = 1. This enables the Transmitted IN Data interrupt (USBHS_HSTPIPIMR.UNDERFIE).

Bit 1 – TXOUTE Transmitted OUT Data Interrupt Enable

Value	Description
0	Cleared when USBHS_HSTPIPIDR.TXOUTEC = 1. This disables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.TXOUTE).
1	Set when USBHS_HSTPIPIER.TXOUTES = 1. This enables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.TXOUTE).

Bit 0 – RXINE Received IN Data Interrupt Enable

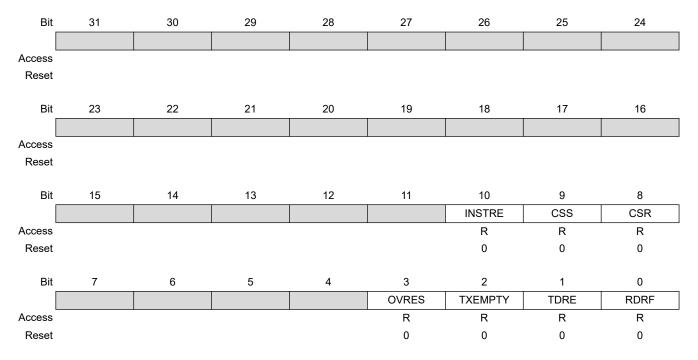
Value	Description
0	Cleared when USBHS_HSTPIPIDR.RXINEC = 1. This disables the Transmitted IN Data
	interrupt (USBHS_HSTPIPIMR.RXINE).
1	Set when USBHS_HSTPIPIER.RXINES = 1. This enables the Transmitted IN Data interrupt
	(USBHS_HSTPIPIMR.RXINE).

42.7.8 QSPI Interrupt Mask Register

Name:	QSPI_IMR
Offset:	0x1C
Reset:	0x00000000
Property:	Read-only

The following configuration values are valid for all listed bit names of this register:

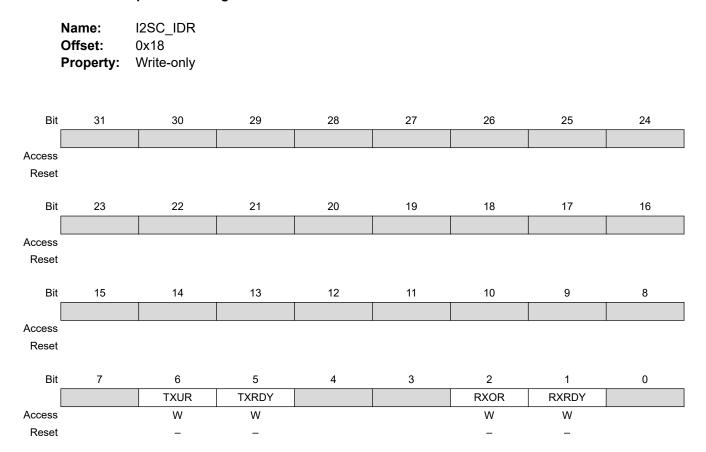
- 0: The corresponding interrupt is not enabled.
- 1: The corresponding interrupt is enabled.



Bit 10 - INSTRE Instruction End Interrupt Mask

- Bit 9 CSS Chip Select Status Interrupt Mask
- Bit 8 CSR Chip Select Rise Interrupt Mask
- Bit 3 OVRES Overrun Error Interrupt Mask
- Bit 2 TXEMPTY Transmission Registers Empty Mask
- **Bit 1 TDRE** Transmit Data Register Empty Interrupt Mask
- Bit 0 RDRF Receive Data Register Full Interrupt Mask

Inter-IC Sound Controller (I2SC)



45.8.7 I2SC Interrupt Disable Register

Bit 6 – TXUR Transmit Underflow Interrupt Disable

Value	Description
0	Writing a '0' to this bit has no effect.
1	Writing a '1' to this bit clears the corresponding bit in I2SC_IMR.

Bit 5 – TXRDY Transmit Ready Interrupt Disable

Value	Description
0	Writing a '0' to this bit has no effect.
1	Writing a '1' to this bit clears the corresponding bit in I2SC_IMR.

Bit 2 – RXOR Receiver Overrun Interrupt Disable

Value	Description					
0	Writing a '0' to this bit has no effect.					
1	Writing a '1' to this bit clears the corresponding bit in I2SC_IMR.					

Bit 1 – RXRDY Receiver Ready Interrupt Disable

Value	Description					
0	Writing a '0' to this bit has no effect.					
1	Writing a '1' to this bit clears the corresponding bit in I2SC_IMR.					

Universal Synchronous Asynchronous Receiver Transc...

46.7.19 USART Channel Status Register (LIN_MODE)

Name:	US_CSR (LIN_MODE)
Offset:	0x0014
Reset:	0x0
Property:	Read-only

This configuration is relevant only if USART_MODE = 0xA or 0xB in the USART Mode Register.

Bit	31	30	29	28	27	26	25	24
	LINHTE	LINSTE	LINSNRE	LINCE	LINIPE	LINISFE	LINBE	
Access		•			•	•	•	
Reset	0	0	0	0	0	0	0	
Bit	23	22	21	20	19	18	17	16
	LINBLS							
Access								
Reset	0							
Bit	15	14	13	12	11	10	9	8
	LINTC	LINID	LINBK				TXEMPTY	TIMEOUT
Access								
Reset	0	0	0				0	0
Bit	7	6	5	4	3	2	1	0
	PARE	FRAME	OVRE				TXRDY	RXRDY
Access								
Reset	0	0	0				0	0

Bit 31 – LINHTE LIN Header Timeout Error (cleared by writing a one to bit US_CR.RSTSTA)

Value	Description					
0	No LIN header timeout error has been detected since the last RSTSTA.					
1	A LIN header timeout error has been detected since the last RSTSTA.					

Bit 30 – LINSTE LIN Synch Tolerance Error (cleared by writing a one to bit US_CR.RSTSTA)

Value	Description				
0	No LIN synch tolerance error has been detected since the last RSTSTA.				
1	A LIN synch tolerance error has been detected since the last RSTSTA.				

Bit 29 – LINSNRE LIN Slave Not Responding Error (cleared by writing a one to bit US_CR.RSTSTA)

Value	Description
0	No LIN slave not responding error has been detected since the last RSTSTA.
1	A LIN slave not responding error has been detected since the last RSTSTA.

Bit 28 – LINCE LIN Checksum Error (cleared by writing a one to bit US_CR.RSTSTA)

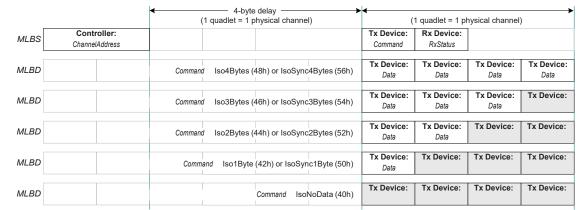


Figure 48-13. MediaLB Isochronous Data Structure

The isochronous flow for a Tx Device is illustrated in Figure 48-14. The data transfer blocks (slanted rectangle shapes) occur only during a physical channel (PCn) associated with the logical channel defined by a single ChannelAddress. Similar to the synchronous flow, isochronous data immediately starts transmitting. When data exists from the application, the IsoSync?Bytes commands are used to indicate the start of a block, which provides alignment information to the Rx Device. The Iso?Bytes commands indicate the middle of a block of data. The definition of block for isochronous data is outside the scope of this document. For physical channels that transfer less than four bytes, the Rx Device must only use/ store the number of valid bytes, and ignore the unused portion.

The isochronous flow for an Rx Device is illustrated in Figure 48-15. The NoData command indicates that the channel is not setup yet. Once an isochronous channel is setup, the Rx Device continually receives the channel data, similar to synchronous data. The only two valid responses for an isochronous channel are ReceiverBusy, and the default bus state of ReceiverReady. Although Rx Devices can respond with ReceiverBusy, its use should be minimized, since Tx Devices may not be able to store much isochronous data that gets backed up due to the ReceiverBusy responses. If any Rx Device uses ReceiverBusy, then only one Rx Device is allowed. If all targeted Rx Devices do not drive RxStatus (default ReceiverReady response), then the isochronous stream can support multiple Rx Devices (broadcast).

48.7.16 MIF Data 1 Register

Name:	MLB_MDAT1			
Offset:	0x0C4			
Reset:	0x00000000			
Property:	Read/Write			

Bit	31	30	29	28	27	26	25	24
				DATA	[31:24]			
Access								
Reset	0	0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
				DATA	[23:16]			
Access								
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
				DATA	[15:8]			
Access								
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
				DAT	A [7:0]			
Access								
Reset	0	0	0	0	0	0	0	0

Bits 31:0 – DATA[31:0] CRT Data CTR data - bits[63:32] of 128-bit entry

48.7.29 AHB Channel Mask 1 Register

Name:	MLB_ACMR1			
Offset:	0x3DC			
Reset:	0x00000000			
Property:	Read/Write			

Bit	31	30	29	28	27	26	25	24
				CHM	[31:24]			
Access								
Reset	0	0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
				CHM	[23:16]			
Access								
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
				CHM	l[15:8]			
Access								
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
				CHN	/ [7:0]			
Access								
Reset	0	0	0	0	0	0	0	0

Bits 31:0 – CHM[31:0] Bitwise Channel Mask Bits 63 to 32 CHM[n] = 1 indicates that channel n can generate an interrupt.

Controller Area Network (MCAN)

Bit 0 - RF0N Receive FIFO 0 New Message

Value	Description				
0	No new message written to Receive FIFO 0.				
1	New message written to Receive FIFO 0.				

Pulse Width Modulation Controller (PWM)

51.7.3 PWM Disable Register

Name:PWM_DISOffset:0x08Reset:-Property:Write-only

This register can only be written if bits WPSWS1 and WPHWS1 are cleared in the PWM Write Protection Status Register.

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
Access						-		
Reset								
Bit	7	6	5	4	3	2	1	0
					CHID3	CHID2	CHID1	CHID0
Access					W	W	W	W
Reset					0	0	0	-

Bits 0, 1, 2, 3 – CHIDx Channel ID

Value	Description
0	No effect.
1	Disable PWM output for channel x.

54.4 Signal Description

Table 54-1. ACC Signal Description

Pin Name	Description	Туре
AFE0_AD[5:0]	External analog data inputs	Input
AFE1_AD[1:0]		
TS	On-chip temperature sensor	Input
VREFP	AFE and DAC voltage reference	Input
DAC0, DAC1	On-chip DAC outputs	Input

54.5 **Product Dependencies**

54.5.1 I/O Lines

The analog input pins are multiplexed with digital functions (PIO) on the IO line. By writing the SELMINUS and SELPLUS fields in the ACC Mode Register (ACC_MR), the associated IO lines are set to Analog mode.

54.5.2 Power Management

The ACC is clocked through the Power Management Controller (PMC), thus the programmer must first configure the PMC to enable the ACC clock.

Note that the voltage regulator must be activated to use the analog comparator.

54.5.3 Interrupt Sources

The ACC has an interrupt line connected to the Interrupt Controller (IC). In order to handle interrupts, the Interrupt Controller must be programmed before configuring the ACC.

54.5.4 Fault Output

The ACC has the FAULT output connected to the FAULT input of PWM. See Fault Mode and the implementation of the PWM in the product.

54.6 Functional Description

54.6.1 Description

The Analog Comparator Controller (ACC) controls the analog comparator settings and performs postprocessing of the analog comparator output.

When the analog comparator settings are modified, the output of the analog cell may be invalid. The ACC masks the output for the invalid period.

A comparison flag is triggered by an event on the output of the analog comparator and an interrupt is generated. The event on the analog comparator output can be selected among falling edge, rising edge or any edge.

The ACC registers are listed in the Register Summary.

Advanced Encryption Standard (AES)

	Name: Offset: Reset: Property:	AES_ISR 0x1C 0x00000000 Read-only						
Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
								TAGRDY
Access		ŀ						R
Reset								0
Bit	15	14	13	12	11	10	9	8
		URA	T[3:0]					URAD
Access	R	R	R	R				R
Reset	0	0	0	0				0
Bit	7	6	5	4	3	2	1	0
								DATRDY
Access								R
Reset								0

57.5.6 AES Interrupt Status Register

Bit 16 – TAGRDY GCM Tag Ready

Value	Description
0	GCM Tag is not valid.
1	GCM Tag generation is complete (cleared by reading GCM Tag, starting another processing or when writing a new key).

Bits 15:12 – URAT[3:0] Unspecified Register Access (cleared by writing SWRST in AES_CR) Only the last Unspecified Register Access Type is available through the URAT field.

Value	Name	Description
0	IDR_WR_PROCESSING	Input Data register written during the data processing when
		SMOD = 2 mode.
1	ODR_RD_PROCESSING	Output Data register read during the data processing.
2	MR_WR_PROCESSING	Mode register written during the data processing.
3	ODR_RD_SUBKGEN	Output Data register read during the sub-keys generation.
4	MR_WR_SUBKGEN	Mode register written during the sub-keys generation.
5	WOR_RD_ACCESS	Write-only register read access.

Bit 8 – URAD Unspecified Register Access Detection Status (cleared by writing SWRST in AES_CR)

Schematic Checklist

Signal Name	Recommended Pin Connection	Description
		Decoupling/filtering capacitors must be added to improve startup stability and reduce source voltage drop.
		Supply ripple must not exceed 20 mVrms for 10 kHz to 20 MHz range.
		Awarning Powerup and powerdown sequences given in the "Power Considerations" chapter must be respected.
VDDPLL	Decoupling/filtering capacitors ferrite beads (100 nF and 470 Ohm @ 100 MHz) ^{(1) (2)}	Powers the PLLA and the fast RC oscillator. The VDDPLL power supply pin draws small current, but it is noise sensitive. Care must be taken in VDDPLL power supply routing, decoupling and also on bypass capacitors.
		Supply ripple must not exceed 20 mVrms for 10 kHz to 10 MHz range and 10 mVrms for higher frequencies.
VDDUTMIC	Decoupling/filtering capacitors ferrite beads (100 nF and 470 Ohm @ 100 MHz) ^{(1) (2)}	Powers the USB transceiver core. Must always be connected even if the USB is not used.
		Decoupling/filtering capacitors/ferrite beads must be added to improve startup stability and reduce source voltage drop.
		Supply ripple must not exceed 10 mVrms for 10 kHz to 10 MHz range.
GND	Voltage Regulator, Core Chip and Peripheral I/O lines ground	GND pins are common to VDDIN, VDDCORE and VDDIO pins. GND pins should be connected as shortly as possible to the
		system ground plane.
GNDUTMI	UDPHS and UHPHS UTMI+ Core and interface ground	GNDUTMI pins are common to VDDUTMII and VDDUTMIC pins. GNDUTMI pins should be connected as shortly as possible to the system ground plane.
GNDPLL	PLLA cell and Main Oscillator ground	GNDPLL pin is provided for VDDPLL pin. GNDPLL pin should be connected as shortly as possible to the system ground plane.
GNDANA	Analog ground	GNDANA pins are common to AFE, DAC and ACC supplied by VDDIN pin. GNDANA pins should be connected as shortly as possible to the system ground plane.
GNDPLLUSB	USB PLL ground	GNDPLLUSB pin is provided for VDDPLLUSB pin. GNDPLLUSB pin should be connected as shortly as possible to the system ground plane.