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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M7
Core Size	32-Bit Single-Core
Speed	300MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, SSC, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	44
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	384K x 8
Voltage - Supply (Vcc/Vdd)	1.7V ~ 3.6V
Data Converters	A/D 5x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/atsams70j20b-mnt">https://www.e-xfl.com/product-detail/microchip-technology/atsams70j20b-mnt</a>

**Table 8-1. System I/O Configuration Pin List**

CCFG_SYSIO Bit Number	Default Function After Reset	Other Function	Constraints for Normal Start	Configuration
12	ERASE	PB12	Low Level at startup (see <b>Note 1</b> )	In Matrix User Interface Registers (Refer to the <a href="#">19.4.7 CCFG_SYSIO</a> register)
7	TCK/SWCLK	PB7	—	
6	TMS/SWDIO	PB6	—	
5	TDO/TRACESWO	PB5	—	
4	TDI	PB4	—	
—	PA7	XIN32	—	(see <b>Note 2</b> )
—	PA8	XOUT32	—	(see <b>Note 3</b> )
—	PB9	XIN	—	
—	PB8	XOUT	—	

**Note:**

1. If PB12 is used as PIO input in user applications, a low level must be ensured at startup to prevent Flash erase before the user application sets PB12 into PIO mode.
2. Refer to [23.4.2 Slow Clock Generator](#).
3. Refer to [30.5.3 Main Crystal Oscillator](#).

### 8.2.1 Serial Wire Debug Port (SW-DP) Pins

The SW-DP pins SWCLK and SWDIO are commonly provided on a standard 20-pin JTAG connector defined by ARM. For more details about voltage reference and reset state, refer to [Table 4-1](#).

At startup, SW-DP pins are configured in SW-DP mode to allow connection with debugging probe. For more details, refer to [16. Debug and Test Features](#).

SW-DP pins can be used as standard I/Os to provide users more general input/output pins when the debug port is not needed in the end application. Mode selection between SW-DP mode (System IO mode) and general IO mode is performed through the AHB Matrix Special Function Registers (MATRIX\_SFR). Configuration of the pad for pull-up, triggers, debouncing and glitch filters is possible regardless of the mode.

The JTAGSEL pin is used to select the JTAG boundary scan when asserted at a high level. It integrates a permanent pulldown resistor of about 15 kΩ to GND, so that it can be left unconnected for normal operations.

The JTAG Debug Port TDI, TDO, TMS and TCK is inactive. It is provided for Boundary Scan Manufacturing Test purpose only.

### 8.2.2 Embedded Trace Module (ETM) Pins

The Embedded Trace Module (ETM) depends on the Trace Port Interface Unit (TPIU) to export data out of the system.

The TPUI features the following pins:

# SAM E70/S70/V70/V71 Family

## Peripherals

Instance ID	Instance Name	NVIC Interrupt	PMC Clock Control	Description
20	TWIHS1	X	X	Two-wire Interface (I2C-compatible)
21	SPI0	X	X	Serial Peripheral Interface
22	SSC	X	X	Synchronous Serial Controller
23	TC0_CHANNEL0	X	X	16-bit Timer Counter 0, Channel 0
24	TC0_CHANNEL1	X	X	16-bit Timer Counter 0, Channel 1
25	TC0_CHANNEL2	X	X	16-bit Timer Counter 0, Channel 2
26	TC1_CHANNEL0	X	X	16-bit Timer Counter 1, Channel 0
27	TC1_CHANNEL1	X	X	16-bit Timer Counter 1, Channel 1
28	TC1_CHANNEL2	X	X	16-bit Timer Counter 1, Channel 2
29	AFEC0	X	X	Analog Front-End Controller
30	DACC	X	X	Digital-to-Analog Converter
31	PWM0	X	X	Pulse Width Modulation Controller
32	ICM	X	X	Integrity Check Monitor
33	ACC	X	X	Analog Comparator Controller
34	USBHS	X	X	USB Host / Device Controller
35	MCAN0	X	X	CAN IRQ Line 0
36	MCAN0	INT1	–	CAN IRQ Line 1
37	MCAN1	X	X	CAN IRQ Line 0
38	MCAN1	INT1	–	CAN IRQ Line 1
39	GMAC	X	X	Ethernet MAC
35	–	–	–	Reserved
36	–	–	–	Reserved
37	–	–	–	Reserved
38	–	–	–	Reserved
39	–	–	–	Reserved
40	AFEC1	X	X	Analog Front End Controller
41	TWIHS2	X	X	Two-wire Interface
42	SPI1	X	X	Serial Peripheral Interface
43	QSPI	X	X	Quad I/O Serial Peripheral Interface
44	UART2	X	X	Universal Asynchronous Receiver/ Transmitter

# SAM E70/S70/V70/V71 Family

## Bus Matrix (MATRIX)

Offset	Name	Bit Pos.								
		15:8			M3PR[1:0]				M2PR[1:0]	
		23:16			M5PR[1:0]				M4PR[1:0]	
		31:24			M7PR[1:0]				M6PR[1:0]	
0xAC	MATRIX_PRBS5	7:0			M9PR[1:0]				M8PR[1:0]	
		15:8			M11PR[1:0]				M10PR[1:0]	
		23:16							M12PR[1:0]	
		31:24								
0xB0	MATRIX_PRAS6	7:0			M1PR[1:0]				M0PR[1:0]	
		15:8			M3PR[1:0]				M2PR[1:0]	
		23:16			M5PR[1:0]				M4PR[1:0]	
		31:24			M7PR[1:0]				M6PR[1:0]	
0xB4	MATRIX_PRBS6	7:0			M9PR[1:0]				M8PR[1:0]	
		15:8			M11PR[1:0]				M10PR[1:0]	
		23:16							M12PR[1:0]	
		31:24								
0xB8	MATRIX_PRAS7	7:0			M1PR[1:0]				M0PR[1:0]	
		15:8			M3PR[1:0]				M2PR[1:0]	
		23:16			M5PR[1:0]				M4PR[1:0]	
		31:24			M7PR[1:0]				M6PR[1:0]	
0xBC	MATRIX_PRBS7	7:0			M9PR[1:0]				M8PR[1:0]	
		15:8			M11PR[1:0]				M10PR[1:0]	
		23:16							M12PR[1:0]	
		31:24								
0xC0	MATRIX_PRAS8	7:0			M1PR[1:0]				M0PR[1:0]	
		15:8			M3PR[1:0]				M2PR[1:0]	
		23:16			M5PR[1:0]				M4PR[1:0]	
		31:24			M7PR[1:0]				M6PR[1:0]	
0xC4	MATRIX_PRBS8	7:0			M9PR[1:0]				M8PR[1:0]	
		15:8			M11PR[1:0]				M10PR[1:0]	
		23:16							M12PR[1:0]	
		31:24								
0xC8	Reserved									
...										
0xFF										
0x0100	MATRIX_MRCR	7:0	RCB7	RCB6	RCB5	RCB4	RCB3	RCB2	RCB1	RCB0
		15:8				RCB12	RCB11	RCB10	RCB9	RCB8
		23:16								
		31:24								
0x0104	Reserved									
...										
0x010F										
0x0110	CCFG_CAN0	7:0	Reserved[7:0]							
		15:8								Reserved[8:8]
		23:16	CAN0DMABA[7:0]							
		31:24	CAN0DMABA[15:8]							
0x0114	CCFG_SYSIO	7:0	SYSIO7	SYSIO6	SYSIO5	SYSIO4				

# SAM E70/S70/V70/V71 Family

## Parallel Input/Output Controller (PIO)

### 32.6.1.48 PIO Schmitt Trigger Register

**Name:** PIO\_SCHMITT  
**Offset:** 0x0100  
**Reset:** 0x00000000  
**Property:** Read/Write

Bit	31	30	29	28	27	26	25	24
	SCHMITT31	SCHMITT30	SCHMITT29	SCHMITT28	SCHMITT27	SCHMITT26	SCHMITT25	SCHMITT24
Access								
Reset	0	0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
	SCHMITT23	SCHMITT22	SCHMITT21	SCHMITT20	SCHMITT19	SCHMITT18	SCHMITT17	SCHMITT16
Access								
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
	SCHMITT15	SCHMITT14	SCHMITT13	SCHMITT12	SCHMITT11	SCHMITT10	SCHMITT9	SCHMITT8
Access								
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
	SCHMITT7	SCHMITT6	SCHMITT5	SCHMITT4	SCHMITT3	SCHMITT2	SCHMITT1	SCHMITT0
Access								
Reset	0	0	0	0	0	0	0	0

**Bits 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31 – SCHMITT** PIO Schmitt Trigger Control

Value	Description
0	Schmitt trigger is enabled.
1	Schmitt trigger is disabled.

# SAM E70/S70/V70/V71 Family

## DMA Controller (XDMAC)

### 36.6.2.1 Descriptor Structure Microblock Control Member

**Name:** MBR\_UBC

**Property:** Read-only

Bit	31	30	29	28	27	26	25	24
				NVIEW[1:0]		NDEN	NSEN	NDE
Access				R	R	R	R	R
Reset								

Bit	23	22	21	20	19	18	17	16
	UBLEN[23:16]							
Access	R	R	R	R	R	R	R	R
Reset								

Bit	15	14	13	12	11	10	9	8
	UBLEN[15:8]							
Access	R	R	R	R	R	R	R	R
Reset								

Bit	7	6	5	4	3	2	1	0
	UBLEN[7:0]							
Access	R	R	R	R	R	R	R	R
Reset								

#### Bits 28:27 – NVIEW[1:0] Next Descriptor View

Value	Name	Description
0	NDV0	Next Descriptor View 0
1	NDV1	Next Descriptor View 1
2	NDV2	Next Descriptor View 2
3	NDV3	Next Descriptor View 3

#### Bit 26 – NDEN Next Descriptor Destination Update

Value	Description
0	Destination parameters remain unchanged.
1	Destination parameters are updated when the descriptor is retrieved.

#### Bit 25 – NSEN Next Descriptor Source Update

Value	Description
0	Source parameters remain unchanged.
1	Source parameters are updated when the descriptor is retrieved.

#### Bit 24 – NDE Next Descriptor Enable

Value	Description
0	Descriptor fetch is disabled.
1	Descriptor fetch is enabled.

# SAM E70/S70/V70/V71 Family

## DMA Controller (XDMAC)

### 36.9.14 XDMAC Global Channel Read Write Resume Register

**Name:** XDMAC\_GRWR  
**Offset:** 0x34  
**Reset:** –  
**Property:** Write-only

Bit	31	30	29	28	27	26	25	24
Access								
Reset								

Bit	23	22	21	20	19	18	17	16
	RWR23	RWR22	RWR21	RWR20	RWR19	RWR18	RWR17	RWR16
Access	W	W	W	W	W	W	W	W
Reset	–	–	–	–	–	–	–	–

Bit	15	14	13	12	11	10	9	8
	RWR15	RWR14	RWR13	RWR12	RWR11	RWR10	RWR9	RWR8
Access	W	W	W	W	W	W	W	W
Reset	–	–	–	–	–	–	–	–

Bit	7	6	5	4	3	2	1	0
	RWR7	RWR6	RWR5	RWR4	RWR3	RWR2	RWR1	RWR0
Access	W	W	W	W	W	W	W	W
Reset	–	–	–	–	–	–	–	–

**Bits 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23 – RWRx** XDMAC Channel x Read Write Resume

Value	Description
0	No effect.
1	Read and write requests are serviced.

# SAM E70/S70/V70/V71 Family

## DMA Controller (XDMAC)

### 36.9.24 XDMAC Channel x Next Descriptor Address Register [x = 0..23]

**Name:** XDMAC\_CNDA  
**Offset:** 0x68 + n\*0x40 [n=0..23]  
**Reset:** 0x00000000  
**Property:** Read/Write

Bit	31	30	29	28	27	26	25	24
	NDA[29:22]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
	NDA[21:14]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
	NDA[13:6]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
	NDA[5:0]							NDAIF
Access	R/W	R/W	R/W	R/W	R/W	R/W		R/W
Reset	0	0	0	0	0	0		0

#### Bits 31:2 – NDA[29:0] Channel x Next Descriptor Address

The 30-bit width of the NDA field represents the next descriptor address range 31:2. The descriptor is word-aligned and the two least significant register bits 1:0 are ignored.

#### Bit 0 – NDAIF Channel x Next Descriptor Interface

Value	Description
0	The channel descriptor is retrieved through system interface 0.
1	The channel descriptor is retrieved through system interface 1.



# SAM E70/S70/V70/V71 Family

## Image Sensor Interface (ISI)

Value	Name	Description
		Byte 3 B/G(MSB)
3	MODE3	Byte 0 G(LSB)/B Byte 1 R/G(MSB) Byte 2 G(LSB)/B Byte 3 R/G(MSB)

### Bits 29:28 – YCC\_SWAP[1:0] YCrCb Format Swap Mode

Defines the YCC image data.

Value	Name	Description
0	DEFAULT	Byte 0 Cb(i) Byte 1 Y(i) Byte 2 Cr(i) Byte 3 Y(i+1)
1	MODE1	Byte 0 Cr(i) Byte 1 Y(i) Byte 2 Cb(i) Byte 3 Y(i+1)
2	MODE2	Byte 0 Y(i) Byte 1 Cb(i) Byte 2 Y(i+1) Byte 3 Cr(i)
3	MODE3	Byte 0 Y(i) Byte 1 Cr(i) Byte 2 Y(i+1) Byte 3 Cb(i)

### Bits 26:16 – IM\_HSIZE[10:0] Horizontal Size of the Image Sensor [0..2047]

If 8-bit Grayscale mode is enabled, IM\_HSIZE = (Horizontal size/2) - 1.

Else IM\_HSIZE = Horizontal size - 1.

### Bit 15 – COL\_SPACE Color Space for the Image Data

Value	Description
0	YCbCr.
1	RGB.

### Bit 14 – RGB\_SWAP RGB Format Swap Mode

The RGB\_SWAP has no effect when Grayscale mode is enabled.

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## Image Sensor Interface (ISI)

### 37.6.12 ISI Interrupt Enable Register

**Name:** ISI\_IER  
**Offset:** 0x2C  
**Reset:** –  
**Property:** Write-only

Bit	31	30	29	28	27	26	25	24
					FR_OVR	CRC_ERR	C_OVR	P_OVR
Access					W	W	W	W
Reset					–	–	–	–

Bit	23	22	21	20	19	18	17	16
							CXFR_DONE	PXFR_DONE
Access							W	W
Reset							–	–

Bit	15	14	13	12	11	10	9	8
						VSYNC		
Access						W		
Reset						–		

Bit	7	6	5	4	3	2	1	0
						SRST	DIS_DONE	
Access						W	W	
Reset						–	–	

#### Bit 27 – FR\_OVR Frame Rate Overflow Interrupt Enable

Value	Description
0	No effect.
1	Enables the corresponding interrupt.

#### Bit 26 – CRC\_ERR Embedded Synchronization CRC Error Interrupt Enable

Value	Description
0	No effect.
1	Enables the corresponding interrupt.

#### Bit 25 – C\_OVR Codec Datapath Overflow Interrupt Enable

Value	Description
0	No effect.
1	Enables the corresponding interrupt.

#### Bit 24 – P\_OVR Preview Datapath Overflow Interrupt Enable

Value	Description
0	No effect.
1	Enables the corresponding interrupt.

### 38.8.19 GMAC RX Jumbo Frame Max Length Register

**Name:** GMAC\_RJFML

**Offset:** 0x048

**Reset:** 0x00003FFF

**Property:** Read/Write

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
Access								
Reset								
Bit	15	14	13	12	11	10	9	8
			FML[13:8]					
Access			R/W	R/W	R/W	R/W	R/W	R/W
Reset			1	1	1	1	1	1
Bit	7	6	5	4	3	2	1	0
	FML[7:0]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	1	1	1	1	1	1	1	1

**Bits 13:0 – FML[13:0]** Frame Max Length

Rx jumbo frame maximum length.

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## USB High-Speed Interface (USBHS)

Offset	Name	Bit Pos.								
0x016C	USBHS_DEVEPTIC R3 (ISOENPT)	7:0	SHORTPACK ETC	CRCERRIC	OVERFIC	HBISOFLUSH IC	HBISOINERRI C	UNDERFIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x0170	USBHS_DEVEPTIC R4	7:0	SHORTPACK ETC	STALLEDIC	OVERFIC	NAKINIC	NAKOUTIC	RXSTPIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x0170	USBHS_DEVEPTIC R4 (ISOENPT)	7:0	SHORTPACK ETC	CRCERRIC	OVERFIC	HBISOFLUSH IC	HBISOINERRI C	UNDERFIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x0174	USBHS_DEVEPTIC R5	7:0	SHORTPACK ETC	STALLEDIC	OVERFIC	NAKINIC	NAKOUTIC	RXSTPIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x0174	USBHS_DEVEPTIC R5 (ISOENPT)	7:0	SHORTPACK ETC	CRCERRIC	OVERFIC	HBISOFLUSH IC	HBISOINERRI C	UNDERFIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x0178	USBHS_DEVEPTIC R6	7:0	SHORTPACK ETC	STALLEDIC	OVERFIC	NAKINIC	NAKOUTIC	RXSTPIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x0178	USBHS_DEVEPTIC R6 (ISOENPT)	7:0	SHORTPACK ETC	CRCERRIC	OVERFIC	HBISOFLUSH IC	HBISOINERRI C	UNDERFIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x017C	USBHS_DEVEPTIC R7	7:0	SHORTPACK ETC	STALLEDIC	OVERFIC	NAKINIC	NAKOUTIC	RXSTPIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								
0x017C	USBHS_DEVEPTIC R7 (ISOENPT)	7:0	SHORTPACK ETC	CRCERRIC	OVERFIC	HBISOFLUSH IC	HBISOINERRI C	UNDERFIC	RXOUTIC	TXINIC
		15:8								
		23:16								
		31:24								

### 39.6.28 Device DMA Channel x Address Register

**Name:** USBHS\_DEVDMAADDRESSx  
**Offset:** 0x0304 + x\*0x10 [x=0..6]  
**Reset:** 0  
**Property:** Read/Write

Bit	31	30	29	28	27	26	25	24
	BUFF_ADD[31:24]							
Access								
Reset	0	0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
	BUFF_ADD[23:16]							
Access								
Reset	0	0	0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
	BUFF_ADD[15:8]							
Access								
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
	BUFF_ADD[7:0]							
Access								
Reset	0	0	0	0	0	0	0	0

#### Bits 31:0 – BUFF\_ADD[31:0] Buffer Address

This field determines the AHB bus starting address of a DMA channel transfer.

Channel start and end addresses may be aligned on any byte boundary.

The firmware can write this field only when the USBHS\_DEVDMASTATUS.CHANN\_ENB bit is clear.

This field is updated at the end of the address phase of the current access to the AHB bus. It is incremented by the access byte width. The access width is 4 bytes (or less) at packet start or end, if the start or end address is not aligned on a word boundary.

The packet start address is either the channel start address or the next channel address to be accessed in the channel buffer. The packet end address is either the channel end address or the latest channel address accessed in the channel buffer.

The channel start address is written by software or loaded from the descriptor. The channel end address is either determined by the end of buffer or the USB device, or by the USB end of transfer if the USBHS\_DEVDMACONTROLx.END\_TR\_EN bit is set.

# SAM E70/S70/V70/V71 Family

## Serial Peripheral Interface (SPI)

- The SPCK pin is driven by the transmitter to synchronize the receiver.
- The NPCS0 pin becomes an input, and is used as a slave select signal (NSS)
- The NPCS1 to NPCS3 pins are not driven and can be used for other purposes.

The data transfers are identically programmable for both modes of operation. The baud rate generator is activated only in Master mode.

### 41.7.2 Data Transfer

Four combinations of polarity and phase are available for data transfers. The clock polarity is programmed with the CPOL bit in the SPI Chip Select registers (SPI\_CSRx). The clock phase is programmed with the NCPHA bit. These two parameters determine the edges of the clock signal on which data is driven and sampled. Each of the two parameters has two possible states, resulting in four possible combinations that are incompatible with one another. Consequently, a master/slave pair must use the same parameter pair values to communicate. If multiple slaves are connected and require different configurations, the master must reconfigure itself each time it needs to communicate with a different slave.

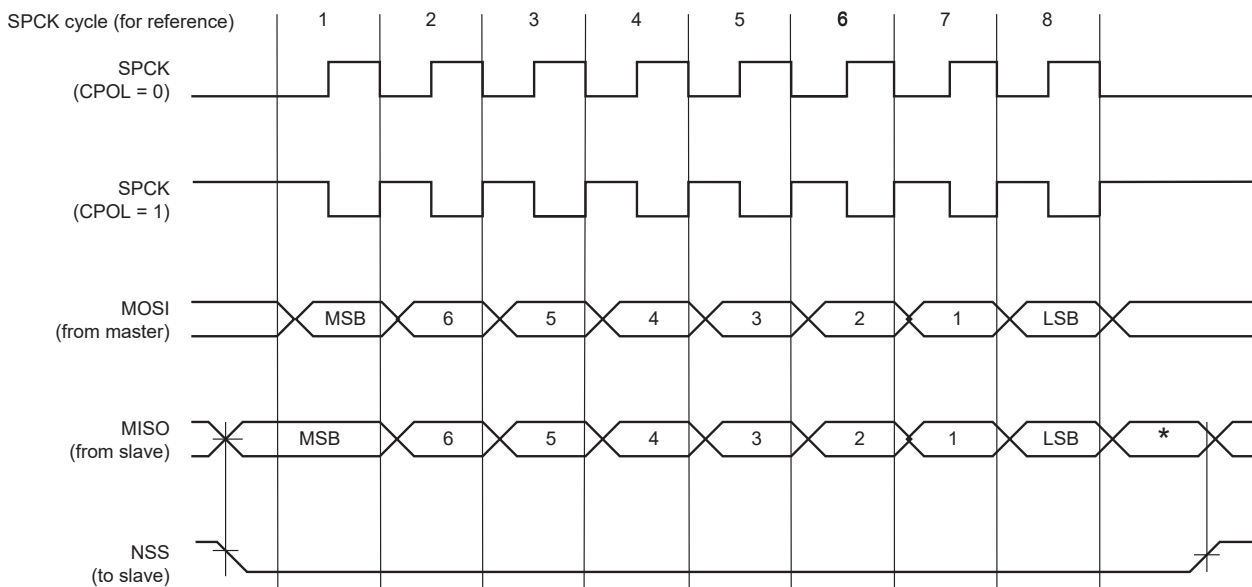
The table below shows the four modes and corresponding parameter settings.

**Table 41-2. SPI Bus Protocol Modes**

SPI Mode	CPOL	NCPHA	Shift SPCK Edge	Capture SPCK Edge	SPCK Inactive Level
0	0	1	Falling	Rising	Low
1	0	0	Rising	Falling	Low
2	1	1	Rising	Falling	High
3	1	0	Falling	Rising	High

The following figures show examples of data transfers.

**Figure 41-3. SPI Transfer Format (NCPHA = 1, 8 bits per transfer)**



\* Not defined.

# SAM E70/S70/V70/V71 Family

## Synchronous Serial Controller (SSC)

### Bit 9 – CP1 Compare 1

Value	Description
0	A compare 1 has not occurred since the last read of the Status Register.
1	A compare 1 has occurred since the last read of the Status Register.

### Bit 8 – CP0 Compare 0

Value	Description
0	A compare 0 has not occurred since the last read of the Status Register.
1	A compare 0 has occurred since the last read of the Status Register.

### Bit 5 – OVRUN Receive Overrun

Value	Description
0	No data has been loaded in SSC_RHR while previous data has not been read since the last read of the Status Register.
1	Data has been loaded in SSC_RHR while previous data has not yet been read since the last read of the Status Register.

### Bit 4 – RXRDY Receive Ready

Value	Description
0	SSC_RHR is empty.
1	Data has been received and loaded in SSC_RHR.

### Bit 1 – TXEMPTY Transmit Empty

Value	Description
0	Data remains in SSC_THR or is currently transmitted from TSR.
1	Last data written in SSC_THR has been loaded in TSR and last data loaded in TSR has been transmitted.

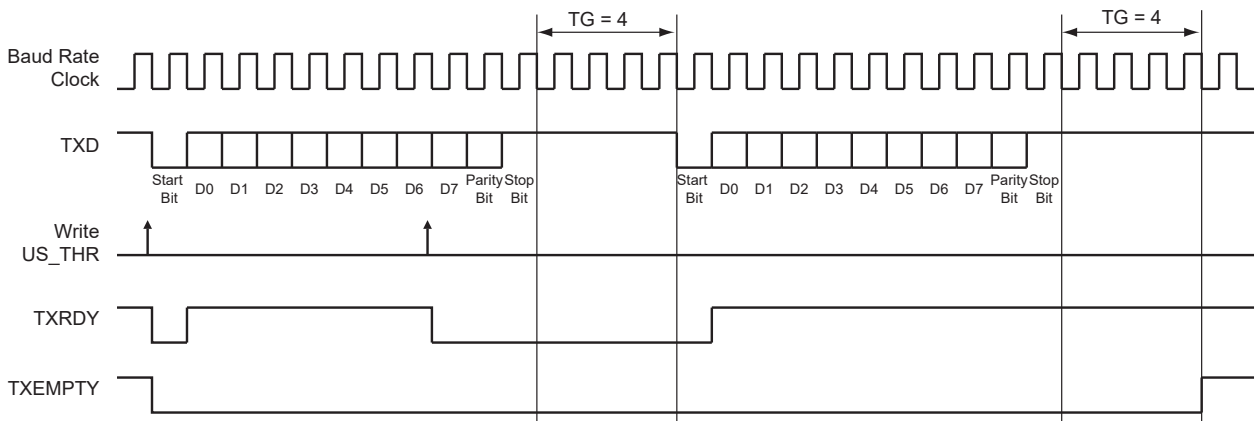
### Bit 0 – TXRDY Transmit Ready

Value	Description
0	Data has been loaded in SSC_THR and is waiting to be loaded in the transmit shift register (TSR).
1	SSC_THR is empty.

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## Universal Synchronous Asynchronous Receiver Transc...

**Figure 46-22. Timeguard Operations**



The following table indicates the maximum length of a timeguard period that the transmitter can handle depending on the baud rate.

**Table 46-7. Maximum Timeguard Length Depending on Baud Rate**

Baud Rate (bit/s)	Bit Time ( $\mu$ s)	Timeguard (ms)
1,200	833	212.50
9,600	104	26.56
14,400	69.4	17.71
19,200	52.1	13.28
28,800	34.7	8.85
38,400	26	6.63
56,000	17.9	4.55
57,600	17.4	4.43
115,200	8.7	2.21

### 46.6.3.11 Receiver Timeout

The Receiver Timeout provides support in handling variable-length frames. This feature detects an idle condition on the RXD line. When a timeout is detected, US\_CSR.TIMEOUT rises and can generate an interrupt, thus indicating to the driver an end of frame.

The timeout delay period (during which the receiver waits for a new character) is programmed in the TO field of the Receiver Timeout register (US\_RTOR). If TO is written to '0', the Receiver Timeout is disabled and no timeout is detected. US\_CSR.TIMEOUT remains at '0'. Otherwise, the receiver loads a 16-bit counter with the value programmed in US\_RTOR.TO. This counter is decremented at each bit period and reloaded each time a new character is received. If the counter reaches 0, TIMEOUT rises. Then, the user can either:

- Stop the counter clock until a new character is received. This is performed by writing a '1' to US\_CR.STTTO. In this case, the idle state on RXD before a new character is received will not provide a timeout. This prevents having to handle an interrupt before a character is received and allows waiting for the next idle state on RXD after a frame is received.



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**Bit 9 – TXEMPTY** TXEMPTY Interrupt Enable

**Bit 8 – TIMEOUT** Timeout Interrupt Enable

**Bit 7 – PARE** Parity Error Interrupt Enable

**Bit 6 – FRAME** Framing Error Interrupt Enable

**Bit 5 – OVRE** Overrun Error Interrupt Enable

**Bit 2 – RXBRK** Receiver Break Interrupt Enable

**Bit 1 – TXRDY** TXRDY Interrupt Enable

**Bit 0 – RXRDY** RXRDY Interrupt Enable

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## Controller Area Network (MCAN)

### 49.6.35 MCAN Tx Buffer Configuration

**Name:** MCAN\_TXBC  
**Offset:** 0xC0  
**Reset:** 0x00000000  
**Property:** Read/Write

This register can only be written if the bits CCE and INIT are set in [MCAN CC Control Register](#).

The sum of TFQS and NDTB may not exceed 32. There is no check for erroneous configurations. The Tx Buffers section in the Message RAM starts with the dedicated Tx Buffers.

Bit	31	30	29	28	27	26	25	24
		TFQM	TFQS[5:0]					
Access		R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset		0	0	0	0	0	0	0
Bit	23	22	21	20	19	18	17	16
			NDTB[5:0]					
Access			R/W	R/W	R/W	R/W	R/W	R/W
Reset			0	0	0	0	0	0
Bit	15	14	13	12	11	10	9	8
	TBSA[13:6]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0
Bit	7	6	5	4	3	2	1	0
	TBSA[5:0]							
Access	R/W	R/W	R/W	R/W	R/W	R/W		
Reset	0	0	0	0	0	0		

#### Bit 30 – TFQM Tx FIFO/Queue Mode

Value	Description
0	Tx FIFO operation.
1	Tx Queue operation.

#### Bits 29:24 – TFQS[5:0] Transmit FIFO/Queue Size

Value	Description
0	No Tx FIFO/Queue.
1–32	Number of Tx Buffers used for Tx FIFO/Queue.
>32	Values greater than 32 are interpreted as 32.

#### Bits 21:16 – NDTB[5:0] Number of Dedicated Transmit Buffers

Value	Description
0	No dedicated Tx Buffers.
1–32	Number of dedicated Tx Buffers.
>32	Values greater than 32 are interpreted as 32.

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## Timer Counter (TC)

Value	Description
0	No effect.
1	Enables the interrupt when a rising edge occurs on IDX input.

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## Pulse Width Modulation Controller (PWM)

### 51.7.50 PWM Leading-Edge Blanking Register

**Name:** PWM\_LEBRx  
**Offset:** 0x0430 + x\*0x20 [x=0..1]  
**Reset:** 0x00000000  
**Property:** Read/Write

Bit	31	30	29	28	27	26	25	24
Access								
Reset								
Bit	23	22	21	20	19	18	17	16
					PWMHREN	PWMHFEN	PWMLREN	PWMLFEN
Access					R/W	R/W	R/W	R/W
Reset					0	0	0	0
Bit	15	14	13	12	11	10	9	8
Access								
Reset								
Bit	7	6	5	4	3	2	1	0
		LEBDELAY[6:0]						
Access		R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset		0	0	0	0	0	0	0

#### Bit 19 – PWMHREN PWMH Rising Edge Enable

Leading-edge blanking is enabled on PWMHx output rising edge.

Value	Description
0	Leading-edge blanking is disabled on PWMHx output rising edge.
1	Leading-edge blanking is enabled on PWMHx output rising edge.

#### Bit 18 – PWMHFEN PWMH Falling Edge Enable

Value	Description
0	Leading-edge blanking is disabled on PWMHx output falling edge.
1	Leading-edge blanking is enabled on PWMHx output falling edge.

#### Bit 17 – PWMLREN PWML Rising Edge Enable

Value	Description
0	Leading-edge blanking is disabled on PWMLx output rising edge.
1	Leading-edge blanking is enabled on PWMLx output rising edge.

#### Bit 16 – PWMLFEN PWML Falling Edge Enable

### 53.6.4.4 Bypass Mode

Bypass mode disables the DAC output buffer and thus minimizes power consumption. This mode can be used to generate slow varying signals. Refer to the DAC Characteristics in the section “Electrical Characteristics” of this datasheet.

To enter this mode, Free-running mode must be selected and the DACC\_ACR.IBCTLCHx field configured in Bypass mode.

#### Related Links

[58. Electrical Characteristics for SAM V70/V71](#)

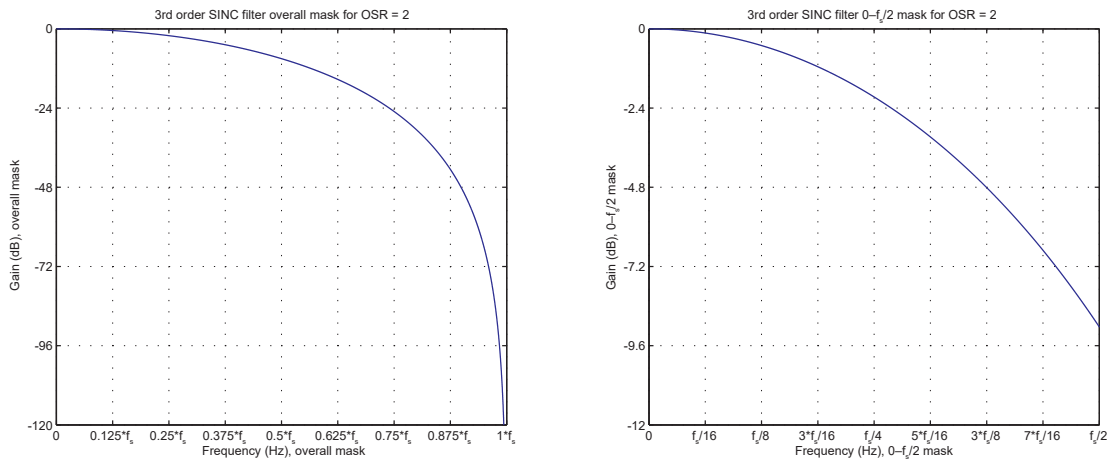
### 53.6.4.5 Interpolation Mode

The DACC integrates interpolation filters that allow OSR of 2×, 4×, 8×, 16× or 32×. This mode can be used only if Trigger mode is enabled and value in the field OSRx is not '0'. The OSR of the interpolator is configured in the OSRx field in the [DACC Trigger Register](#) (DACC\_TRIGR).

The data is sampled once every OSR trigger event and then recomputed at the trigger sample rate using a third-order SINC filter. This reduces the number of accesses to the DACC and increases the signal-to-noise ratio (SNR) of the converted output signal.

The figures below show the spectral mask of the SINC filter depending on the selected OSR.  $f_s$  is the sampling frequency of the input signal which corresponds to the trigger frequency divided by OSR.

**Figure 53-5. Interpolator Spectral Mask for OSR = 2**



**Figure 53-6. Interpolator Spectral Mask for OSR = 4**

