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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	8051
Core Size	8-Bit
Speed	40MHz
Connectivity	EBI/EMI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, WDT
Number of I/O	36
Program Memory Size	72KB (72K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	External
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP (0.600", 15.24mm)
Supplier Device Package	40-PDIL
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/sst89e516rd-40-c-pie">https://www.e-xfl.com/product-detail/microchip-technology/sst89e516rd-40-c-pie</a>

**Table 1: Pin Descriptions (Continued) (2 of 3)**

Symbol	Type <sup>1</sup>	Name and Functions
P3[7:0]	I/O with internal pull-up	<b>Port 3:</b> Port 3 is an 8-bit bidirectional I/O port with internal pull-ups. The Port 3 output buffers can drive LS TTL inputs. Port 3 pins are pulled high by the internal pull-ups when “1”s are written to them and can be used as inputs in this state. As inputs, Port 3 pins that are externally pulled low will source current because of the internal pull-ups. Port 3 also receives some control signals and a partial of high-order address bits during the external host mode programming and verification.
P3[0]	I	<b>RXD:</b> Universal Asynchronous Receiver/Transmitter (UART) - Receive input
P3[1]	O	<b>TXD:</b> UART - Transmit output
P3[2]	I	<b>INT0#:</b> External Interrupt 0 Input
P3[3]	I	<b>INT1#:</b> External Interrupt 1 Input
P3[4]	I	<b>T0:</b> External count input to Timer/Counter 0
P3[5]	I	<b>T1:</b> External count input to Timer/Counter 1
P3[6]	O	<b>WR#:</b> External Data Memory Write strobe
P3[7]	O	<b>RD#:</b> External Data Memory Read strobe
PSEN#	I/O	<b>Program Store Enable:</b> PSEN# is the Read strobe to External Program Store. When the device is executing from Internal Program Memory, PSEN# is inactive ( $V_{OH}$ ). When the device is executing code from External Program Memory, PSEN# is activated twice each machine cycle, except when access to External Data Memory while one PSEN# activation is skipped in each machine cycle. A forced high-to-low input transition on the PSEN# pin while the RST input is continually held high for more than ten machine cycles will cause the device to enter External Host mode for programming.
RST	I	<b>Reset:</b> While the oscillator is running, a high logic state on this pin for two machine cycles will reset the device. After a reset, if the PSEN# pin is driven by a high-to-low input transition while the RST input pin is held high, the device will enter the External Host mode, otherwise the device will enter the Normal operation mode.
EA#	I	<b>External Access Enable:</b> EA# must be driven to $V_{IL}$ in order to enable the device to fetch code from the External Program Memory. EA# must be driven to $V_{IH}$ for internal program execution. However, Security lock level 4 will disable EA#, and program execution is only possible from internal program memory. The EA# pin can tolerate a high voltage <sup>2</sup> of 12V.
ALE/ PROG#	I/O	<b>Address Latch Enable:</b> ALE is the output signal for latching the low byte of the address during an access to external memory. This pin is also the programming pulse input (PROG#) for flash programming. Normally the ALE <sup>3</sup> is emitted at a constant rate of 1/6 the crystal frequency <sup>4</sup> and can be used for external timing and clocking. One ALE pulse is skipped during each access to external data memory. However, if AO is set to 1, ALE is disabled.
P4[3:0] <sup>5</sup>	I/O with internal pull-ups	<b>Port 4:</b> Port 4 is an 4-bit bi-directional I/O port with internal pull-ups. The port 4 output buffers can drive LS TTL inputs. Port 4 pins are pulled high by the internal pull-ups when ‘1’s are written to them and can be used as inputs in this state. As inputs, port 4 pins that are externally pulled low will source current because of the internal pull-ups.
P4[0]	I/O	Bit 0 of port 4
P4[1]	I/O	Bit 1 of port 4
P4[2] / INT3#	I/O	Bit 2 of port 4 / INT3# External interrupt 3 input

### SuperFlash Address Registers (SFAH)

Location	7	6	5	4	3	2	1	0	Reset Value
B4H	SuperFlash High Order Byte Address Register								00H

#### Symbol Function

SFAH Mailbox register for interfacing with flash memory block. (High order address register).

### SuperFlash Data Register (SFDT)

Location	7	6	5	4	3	2	1	0	Reset Value
B5H	SuperFlash Data Register								00H

#### Symbol Function

SFDT Mailbox register for interfacing with flash memory block. (Data register).

### SuperFlash Status Register (SFST) (Read Only Register)

Location	7	6	5	4	3	2	1	0	Reset Value
B6H	SB1_i	SB2_i	SB3_i	-	EDC_i	FLASH_BU SY	-	-	xxxxx0xxb

#### Symbol Function

SB1\_i Security Bit 1 status (inverse of SB1 bit)

SB2\_i Security Bit 2 status (inverse of SB2 bit)

SB3\_i Security Bit 3 status (inverse of SB3 bit)

Please refer to Table 25 for security lock options.

EDC\_i Double Clock Status

0: 12 clocks per machine cycle

1: 6 clocks per machine cycle

FLASH\_BUSY Flash operation completion polling bit.

0: Device has fully completed the last IAP command.

1: Device is busy with flash operation.

### Auxiliary Register (AUXR)

Location	7	6	5	4	3	2	1	0	Reset Value
8EH	-	-	-	-	-	-	EXTRA M	AO	xxxxxx00b

#### Symbol Function

EXTRAM Internal/External RAM access

0: Internal Expanded RAM access within range of 00H to 2FFH using MOVX @Ri / @DPTR.  
Beyond 300H, the MCU always accesses external data memory.

For details, refer to Section , “Expanded Data RAM Addressing” .

1: External data memory access.

AO Disable/Enable ALE

0: ALE is emitted at a constant rate of 1/3 the oscillator frequency in 6 clock mode, 1/6 f<sub>OSC</sub> in 12 clock mode.

1: ALE is active only during a MOVX or MOVC instruction.

### Auxiliary Register 1 (AUXR1)

Location	7	6	5	4	3	2	1	0	Reset Value
A2H	-	-	-	-	GF2	0	-	DPS	xxxx00x0b

#### Symbol Function

GF2 General purpose user-defined flag.

DPS DPTR registers select bit.

0: DPTR0 is selected.

1: DPTR1 is selected.

### Watchdog Timer Control Register (WDTC)

Location	7	6	5	4	3	2	1	0	Reset Value
C0H	-	-	-	WDOUT	WDRE	WDTS	WDT	SWDT	xxx00000b

#### Symbol Function

WDOUT Watchdog output enable.

0: Watchdog reset will not be exported on Reset pin.

1: Watchdog reset if enabled by WDRE, will assert Reset pin for 32 clocks.

WDRE Watchdog timer reset enable.

0: Disable watchdog timer reset.

1: Enable watchdog timer reset.

WDTS Watchdog timer reset flag.

0: External hardware reset or power-on reset clears the flag.

Flag can also be cleared by writing a 1.

Flag survives if chip reset happened because of watchdog timer overflow.

1: Hardware sets the flag on watchdog overflow.

WDT Watchdog timer refresh.

0: Hardware resets the bit when refresh is done.

1: Software sets the bit to force a watchdog timer refresh.

SWDT Start watchdog timer.

0: Stop WDT.

1: Start WDT.

### SPI Data Register (SPDR)

Location	7	6	5	4	3	2	1	0	Reset Value
86H	SPDR[7:0]								00H

### Power Control Register (PCON)

Location	7	6	5	4	3	2	1	0	Reset Value
87H	SMOD1	SMOD0	BOF	POF	GF1	GF0	PD	IDL	00010000b

#### Symbol Function

SMOD1	Double Baud rate bit. If SMOD1 = 1, Timer 1 is used to generate the baud rate, and the serial port is used in modes 1, 2, and 3.
SMOD0	FE/SM0 Selection bit. 0: SCON[7] = SM0 1: SCON[7] = FE,
BOF	Brown-out detection status bit, this bit will not be affected by any other reset. BOF should be cleared by software. Power-on reset will also clear the BOF bit. 0: No brown-out. 1: Brown-out occurred
POF	Power-on reset status bit, this bit will not be affected by any other reset. POF should be cleared by software. 0: No Power-on reset. 1: Power-on reset occurred
GF1	General-purpose flag bit.
GF0	General-purpose flag bit.
PD	Power-down bit, this bit is cleared by hardware after exiting from power-down mode. 0: Power-down mode is not activated. 1: Activates Power-down mode.
IDL	Idle mode bit, this bit is cleared by hardware after exiting from idle mode. 0: Idle mode is not activated. 1: Activates idle mode.

### Serial Port Control Register (SCON)

Location	7	6	5	4	3	2	1	0	Reset Value
98H	SM0/FE	SM1	SM2	REN	TB8	RB8	TI	RI	00000000b

#### Symbol Function

FE	Set SMOD0 = 1 to access FE bit. 0: No framing error 1: Framing Error. Set by receiver when an invalid stop bit is detected. This bit needs to be cleared by software.
SM0	SMOD0 = 0 to access SM0 bit. Serial Port Mode Bit 0
SM1	Serial Port Mode Bit 1

SM0	SM1	Mode	Description	Baud Rate <sup>1</sup>
0	0	0	Shift Register	$f_{osc}/6$ (6 clock mode) or $f_{osc}/12$ (12 clock mode)
0	1	1	8-bit UART	Variable
1	0	2	9-bit UART	$f_{osc}/32$ or $f_{osc}/16$ (6 clock mode) or $f_{osc}/64$ or $f_{osc}/32$ (12 clock mode)
1	1	3	9-bit UART	Variable

1.  $f_{osc}$  = oscillator frequency

SM2	Enables the Automatic Address Recognition feature in Modes 2 or 3. If SM2 = 1 then RI will not be set unless the received 9th data bit (RB8) is 1, indicating an address, and the received byte is a given or broadcast address. In Mode 1, if SM2 = 1 then RI will not be activated unless a valid stop bit was received. In Mode 0, SM2 should be 0.
REN	Enables serial reception. 0: to disable reception. 1: to enable reception.
TB8	The 9th data bit that will be transmitted in Modes 2 and 3. Set or clear by software as desired.
RB8	In Modes 2 and 3, the 9th data bit that was received. In Mode 1, if SM2 = 0, RB8 is the stop bit that was received. In Mode 0, RB8 is not used.
TI	Transmit interrupt flag. Set by hardware at the end of the 8th bit time in Mode 0, or at the beginning of the stop bit in the other modes, in any serial transmission, Must be cleared by software.
RI	Receive interrupt flag. Set by hardware at the end of the 8th bit time in Mode 0, or halfway through the stop bit time in the other modes, in any serial reception (except see SM2). Must be cleared by software.

## Flash Memory Programming

The device internal flash memory can be programmed or erased using In-Application Programming (IAP) mode

### Product Identification

The Read-ID command accesses the Signature Bytes that identify the device and the manufacturer as SST. External programmers primarily use these Signature Bytes in the selection of programming algorithms.

**Table 12:** Product Identification

	Address	Data
Manufacturer's ID	30H	BFH
Device ID		
SST89E516RD2/RD	31H	93H
SST89V516RD2/RD	31H	92H

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### In-Application Programming Mode

The device offers either 72 KByte of in-application programmable flash memory. During in-application programming, the CPU of the microcontroller enters IAP mode. The two blocks of flash memory allow the CPU to execute user code from one block, while the other is being erased or reprogrammed concurrently. The CPU may also fetch code from an external memory while all internal flash is being reprogrammed. The mailbox registers (SFST, SFCM, SFAL, SFAH, SFDT and SFCF) located in the special function register (SFR), control and monitor the device's erase and program process.

Table 14 outline the commands and their associated mailbox register settings.

### In-Application Programming Mode Clock Source

During IAP mode, both the CPU core and the flash controller unit are driven off the external clock. However, an internal oscillator will provide timing references for Program and Erase operations. The internal oscillator is only turned on when required, and is turned off as soon as the flash operation is completed.

### Memory Bank Selection for In-Application Programming Mode

With the addressing range limited to 16 bit, only 64 KByte of program address space is "visible" at any one time. As shown in Table 13, the bank selection (the configuration of EA# and SFCF[1:0]), allows Block 1 memory to be overlaid on the lowest 8 KByte of Block 0 memory, making Block 1 reachable. The same concept is employed to allow both Block 0 and Block 1 flash to be accessible to IAP operations. Code from a block that is not visible may not be used as a source to program another address. However, a block that is not "visible" may be programmed by code from the other block through mailbox registers.

The device allows IAP code in one block of memory to program the other block of memory, but may not program any location in the same block. If an IAP operation originates physically from Block 0, the target of this operation is implicitly defined to be in Block 1. If the IAP operation originates physically from

Block 1, then the target address is implicitly defined to be in Block 0. If the IAP operation originates from external program space, then, the target will depend on the address and the state of bank selection.

### IAP Enable Bit

The IAP enable bit, SFCF[6], enables in-application programming mode. Until this bit is set, all flash programming IAP commands will be ignored.

**Table 13:** IAP Address Resolution

EA#	SFCF[1:0]	Address of IAP Inst.	Target Address	Block Being Programmed
1	00	$\geq 2000\text{H}$ (Block 0)	$\geq 2000\text{H}$ (Block 0)	None <sup>1</sup>
1	00	$\geq 2000\text{H}$ (Block 0)	$< 2000\text{H}$ (Block 1)	Block 1
1	00	$< 2000\text{H}$ (Block 1)	Any (Block 0)	Block 0
1	01, 10, 11	Any (Block 0)	$\geq 2000\text{H}$ (Block 0)	None <sup>1</sup>
1	01, 10, 11	Any (Block 0)	$< 2000\text{H}$ (Block 1)	Block 1
0	00	From external	$\geq 2000\text{H}$ (Block 0)	Block 0
0	00	From external	$< 2000\text{H}$ (Block 1)	Block 1
0	01, 10, 11	From external	Any (Block 0)	Block 0

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1. No operation is performed because code from one block may not program the same originating block

### In-Application Programming Mode Commands

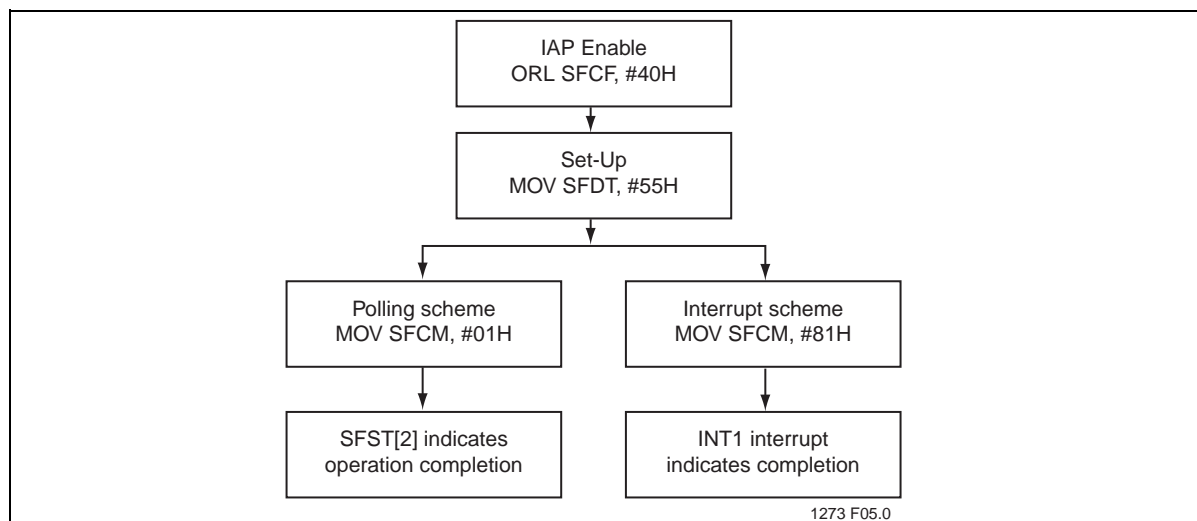
All of the following commands can only be initiated in the IAP mode. In all situations, writing the control byte to the SFCM register will initiate all of the operations. All commands will not be enabled if the security locks are enabled on the selected memory block.

The Program command is for programming new data into the memory array. The portion of the memory array to be programmed should be in the erased state, FFH. If the memory is not erased, it should first be erased with an appropriate Erase command. **Warning: Do not attempt to write (program or erase) to a block that the code is currently fetching from. This will cause unpredictable program behavior and may corrupt program data.**



### Chip-Erase

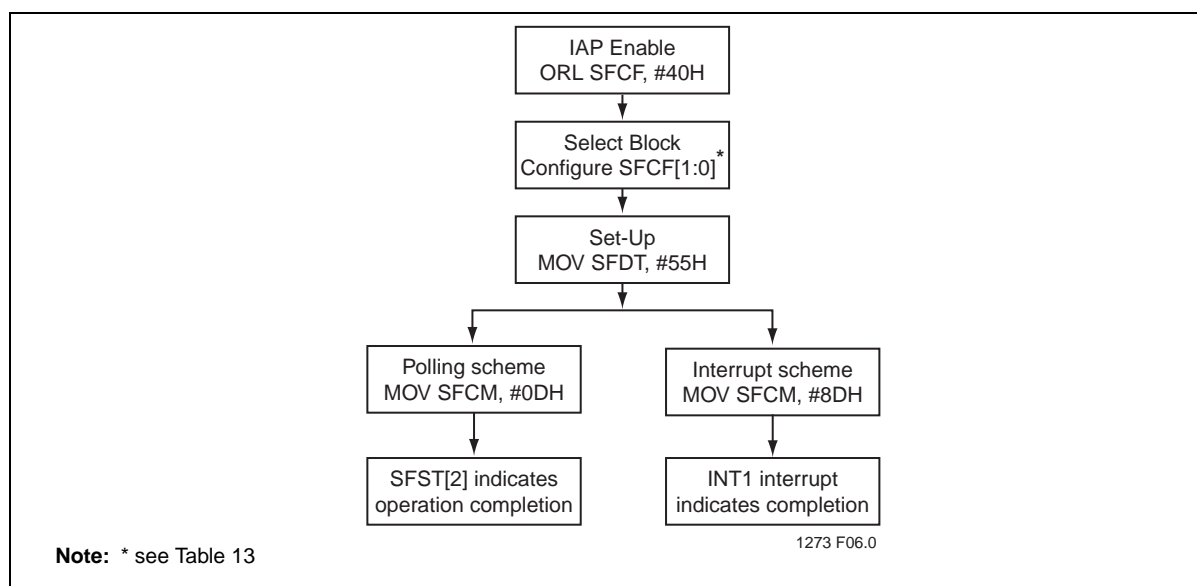
The Chip-Erase command erases all bytes in both memory blocks. This command is only allowed when EA#=0 (external memory execution). Additionally this command is not permitted when the device is in level 4 locking. In all other instances, this command ignores the Security Lock status and will erase the security lock bits and re-map bits.



**Figure 9:** Chip Erase

### Block-Erase

The Block-Erase command erases all bytes in one of two memory blocks (Block 0 or Block 1). The selection of the memory block to be erased is determined by the SFCF[1:0]. The Block-Erase command sequence for SST89x516RDx is as follows:



**Figure 10:**Block Erase

## Timers/Counters

### Timers

The device has three 16-bit registers that can be used as either timers or event counters. The three timers/counters are denoted Timer 0 (T0), Timer 1 (T1), and Timer 2 (T2). Each is designated a pair of 8-bit registers in the SFRs. The pair consists of a most significant (high) byte and least significant (low) byte. The respective registers are TL0, TH0, TL1, TH1, TL2, and TH2.

### Timer Set-up

Refer to Table 9 for TMOD, TCON, and T2CON registers regarding timers T0, T1, and T2. The following tables provide TMOD values to be used to set up Timers T0, T1, and T2.

Except for the baud rate generator mode, the values given for T2CON do not include the setting of the TR2 bit. Therefore, bit TR2 must be set separately to turn the timer on.

**Table 15: Timer/Counter 0**

	Mode	Function	TMOD	
			Internal Control <sup>1</sup>	External Control <sup>2</sup>
Used as Timer	0	13-bit Timer	00H	08H
	1	16-bit Timer	01H	09H
	2	8-bit Auto-Reload	02H	0AH
	3	Two 8-bit Timers	03H	0BH
Used as Counter	0	13-bit Timer	04H	0CH
	1	16-bit Timer	05H	0DH
	2	8-bit Auto-Reload	06H	0EH
	3	Two 8-bit Timers	07H	0FH

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1. The Timer is turned ON/OFF by setting/clearing bit TR0 in the software.
2. The Timer is turned ON/OFF by the 1 to 0 transition on INT0# (P3.2) when TR0 = 1 (hardware control).

**Table 16: Timer/Counter 1**

	Mode	Function	TMOD	
			Internal Control <sup>1</sup>	External Control <sup>2</sup>
Used as Timer	0	13-bit Timer	00H	80H
	1	16-bit Timer	10H	90H
	2	8-bit Auto-Reload	20H	A0H
	3	Does not run	30H	B0H
Used as Counter	0	13-bit Timer	40H	C0H
	1	16-bit Timer	50H	D0H
	2	8-bit Auto-Reload	60H	E0H
	3	Not available	-	-

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1. The Timer is turned ON/OFF by setting/clearing bit TR1 in the software.
2. The Timer is turned ON/OFF by the 1 to 0 transition on INT1# (P3.3) when TR1 = 1 (hardware control).

**Table 17: Timer/Counter 2**

	Mode	T2CON	
		Internal Control <sup>1</sup>	External Control <sup>2</sup>
<b>Used as Timer</b>	16-bit Auto-Reload	00H	08H
	16-bit Capture	01H	09H
	Baud rate generator receive and transmit same baud rate	34H	36H
	Receive only	24H	26H
	Transmit only	14H	16H
<b>Used as Counter</b>	16-bit Auto-Reload	02H	0AH
	16-bit Capture	03H	0BH

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1. Capture/Reload occurs only on timer/counter overflow.
2. Capture/Reload occurs on timer/counter overflow and a 1 to 0 transition on T2EX (P1.1) pin except when Timer 2 is used in the baud rate generating mode.

## Programmable Clock-Out

A 50% duty cycle clock can be programmed to come out on P1.0. This pin, besides being a regular I/O pin, has two alternate functions. It can be programmed:

1. to input the external clock for Timer/Counter 2, or
2. to output a 50% duty cycle clock ranging from 122 Hz to 8 MHz at a 16 MHz operating frequency (61 Hz to 4 MHz in 12 clock mode).

To configure Timer/Counter 2 as a clock generator, bit C/#T2 (in T2CON) must be cleared and bit T2OE in T2MOD must be set. Bit TR2 (T2CON.2) also must be set to start the timer.

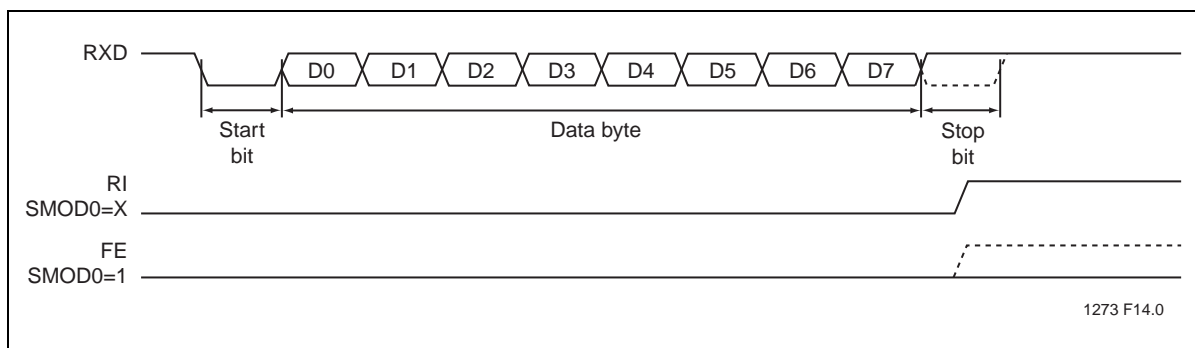
The Clock-Out frequency depends on the oscillator frequency and the reload value of Timer 2 capture registers (RCAP2H, RCAP2L) as shown in this equation:

$$\frac{\text{Oscillator Frequency}}{n \times (65536 - \text{RCAP2H}, \text{RCAP2L})}$$

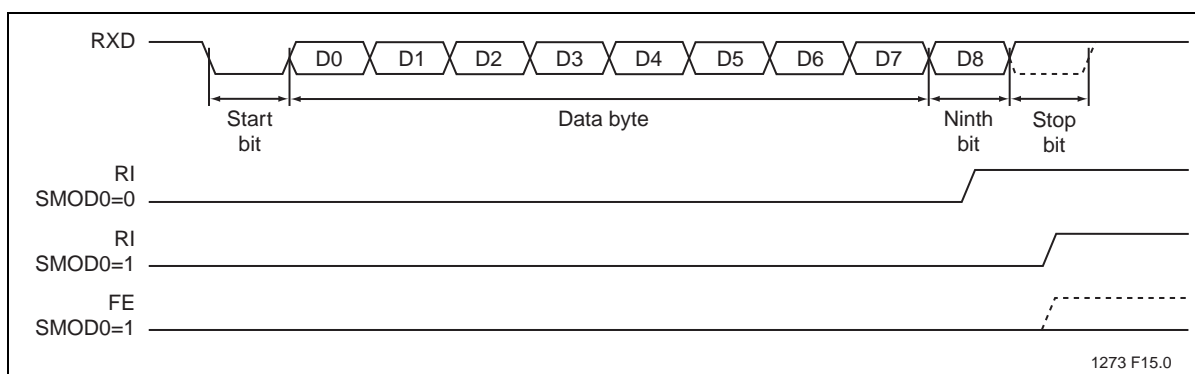
n =2 (in 6 clock mode)  
4 (in 12 clock mode)

Where (RCAP2H, RCAP2L) = the contents of RCAP2H and RCAP2L taken as a 16-bit unsigned integer.

In the Clock-Out mode, Timer 2 roll-overs will not generate an interrupt. This is similar to when it is used as a baud-rate generator. It is possible to use Timer 2 as a baud-rate generator and a clock generator simultaneously. Note, however, that the baud-rate and the Clock-Out frequency will not be the same.



**Figure 18:**UART Timings in Mode 1



**Figure 19:**UART Timings in Modes 2 and 3

## Automatic Address Recognition

Automatic Address Recognition helps to reduce the MCU time and power required to talk to multiple serial devices. Each device is hooked together sharing the same serial link with its own address. In this configuration, a device is only interrupted when it receives its own address, thus eliminating the software overhead to compare addresses.

This same feature helps to save power because it can be used in conjunction with idle mode to reduce the system's overall power consumption. Since there may be multiple slaves hooked up serial to one master, only one slave would have to be interrupted from idle mode to respond to the master's transmission. Automatic Address Recognition (AAR) allows the other slaves to remain in idle mode while only one is interrupted. By limiting the number of interruptions, the total current draw on the system is reduced.

There are two ways to communicate with slaves: a group of them at once, or all of them at once. To communicate with a group of slaves, the master sends out an address called the given address. To communicate with all the slaves, the master sends out an address called the "broadcast" address.

AAR can be configured as mode 2 or 3 (9-bit modes) and setting the SM2 bit in SCON. Each slave has its own SM2 bit set waiting for an address byte (9th bit = 1). The Receive Interrupt (RI) flag will only be set when the received byte matches either the given address or the broadcast address. Next, the slave then clears its SM2 bit to enable reception of the data bytes (9th bit = 0) from the master. When the 9th bit = 1, the master is sending an address. When the 9th bit = 0, the master is sending actual data.

If the user added a third slave such as the example below:

### Slave 3

SADDR = 1111 1001

SADEN = 1111 0101

GIVEN = 1111 X0X1

Select Slave 3 Only		
Slave 2	Given Address	Possible Addresses
	1111 X0X1	1111 1011 1111 1001

The user could use the possible addresses above to select slave 3 only. Another combination could be to select slave 2 and 3 only as shown below.

Select Slaves 2 & 3 Only	
Slaves 2 & 3	Possible Addresses
	1111 0011

More than one slave may have the same SADDR address as well, and a given address could be used to modify the address so that it is unique.

### Using the Broadcast Address to Select Slaves

Using the broadcast address, the master can communicate with all the slaves at once. It is formed by performing a logical OR of SADDR and SADEN with '0's in the result treated as "don't cares".

### Slave 1

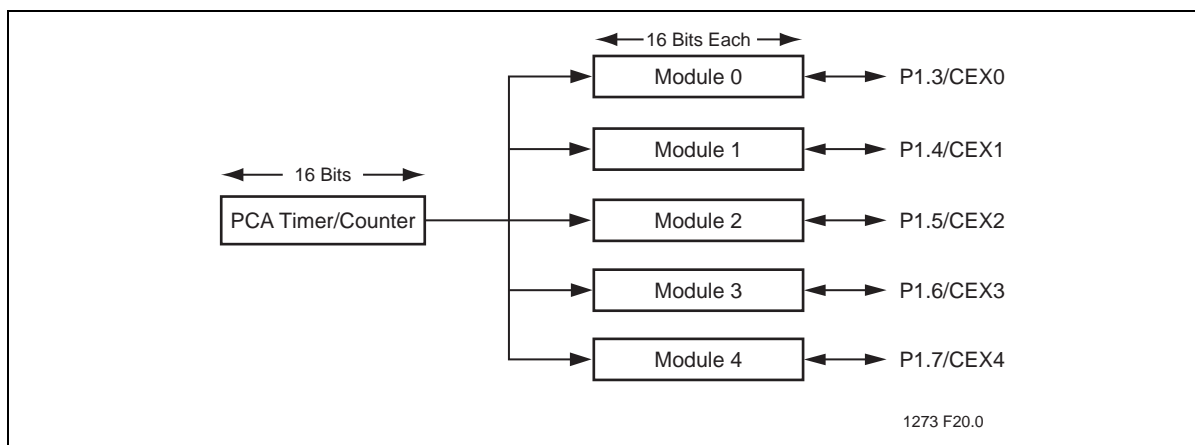
1111 0001 = SADDR

+1111 1010 = SADEN

1111 1X11 = Broadcast

"Don't cares" allow for a wider range in defining the broadcast address, but in most cases, the broadcast address will be FFH.

On reset, SADDR and SADEN are "0". This produces an given address of all "don't cares" as well as a broadcast address of all "don't cares." This effectively disables Automatic Addressing mode and allows the microcontroller to function as a standard 8051, which does not make use of this feature.



**Figure 24:**PCA Timer/Counter and Compare/Capture Modules

The table below summarizes various clock inputs at two common frequencies.

**Table 19:** PCA Timer/Counter Inputs

PCA Timer/Counter Mode	Clock Increments	
	12 MHz	16 MHz
Mode 0: $f_{osc}/12$	1 $\mu$ sec	0.75 $\mu$ sec
Mode 1:	330 nsec	250 nsec
Mode 2: Timer 0 Overflows <sup>1</sup>		
Timer 0 programmed in:		
8-bit mode	256 $\mu$ sec	192 $\mu$ sec
16-bit mode	65 msec	49 $\mu$ sec
8-bit auto-reload	1 to 255 $\mu$ sec	0.75 to 191 $\mu$ sec
Mode 3: External Input MAX	0.66 $\mu$ sec	0.50 $\mu$ sec

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1. In Mode 2, the overflow interrupt for Timer 0 does not need to be enabled.

The four possible CMOD timer modes with and without the overflow interrupt enabled are shown below. This list assumes that PCA will be left running during idle mode.

**Table 20:** CMOD Values

PCA Count Pulse Selected	CMOD Value	
	Without Interrupt Enabled	With Interrupt Enabled
Internal clock, $f_{osc}/12$	00H	01H
Internal clock, $f_{osc}/4$	02H	03H
Timer 0 overflow	04H	05H
External clock at P1.2	06H	07H

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The CCON register is associated with all PCA timer functions. It contains run control bits and flags for the PCA timer (CF) and all modules. To run the PCA the CR bit (CCON.6) must be set by software. Clearing the bit, will turn off PCA. When the PCA counter overflows, the CF (CCON.7) will be set, and

**Table 22: PCA Module Modes**

Without Interrupt enabled								
<sup>-1</sup>	ECOMy <sup>2</sup>	CAPPy <sup>2</sup>	CAPNy <sup>2</sup>	MATy <sup>2</sup>	TOGy <sup>2</sup>	PWMy <sup>2</sup>	ECCFy <sup>2</sup>	Module Code
-	0	0	0	0	0	0	0	No Operation
-	0	1	0	0	0	0	0	16-bit capture on positive-edge trigger at CEX[4:0]
-	0	0	1	0	0	0	0	16-bit capture on negative-edge trigger at CEX[4:0]
-	0	1	1	0	0	0	0	16-bit capture on positive/negative-edge trigger at CEX[4:0]
-	1	0	0	1	0	0	0	Compare: software timer
-	1	0	0	1	1	0	0	Compare: high-speed output
-	1	0	0	0	0	1	0	Compare: 8-bit PWM
-	1	0	0	1	0 or <sup>13</sup>	0	0	Compare: PCA WDT (CCAPM4 only) <sup>4</sup>

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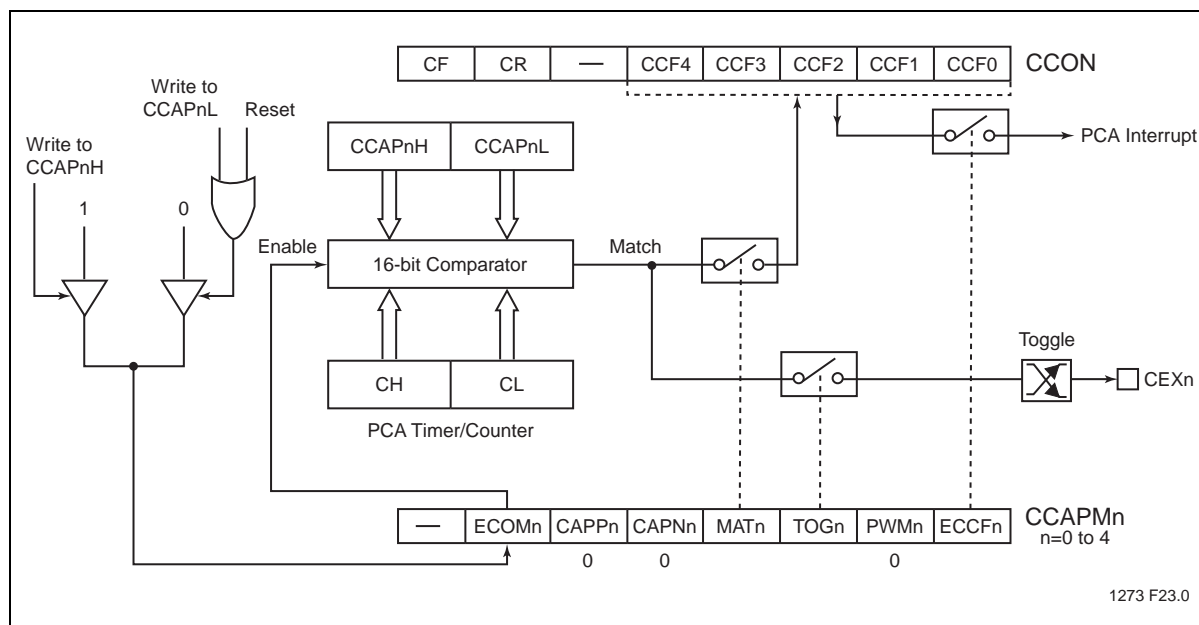
1. User should not write '1's to reserved bits. The value read from a reserved bit is indeterminate.
2. y = 0, 1, 2, 3, 4
3. A 0 disables toggle function. A 1 enables toggle function on CEX[4:0] pin.
4. For PCA WDT mode, also set the WDTE bit in the CMOD register to enable the reset output signal.

**Table 23: PCA Module Modes**

With Interrupt enabled								
<sup>-1</sup>	ECOMy <sup>2</sup>	CAPPy <sup>2</sup>	CAPNy <sup>2</sup>	MATy <sup>2</sup>	TOGy <sup>2</sup>	PWMy <sup>2</sup>	ECCFy <sup>2</sup>	Module Code
-	0	1	0	0	0	0	1	16-bit capture on positive-edge trigger at CEX[4:0]
-	0	0	1	0	0	0	1	16-bit capture on negative-edge trigger at CEX[4:0]
-	0	1	1	0	0	0	1	16-bit capture on positive/negative-edge trigger at CEX[4:0]
-	1	0	0	1	0	0	1	Compare: software timer
-	1	0	0	1	1	0	1	Compare: high-speed output
-	1	0	0	0	0	1	X <sup>3</sup>	Compare: 8-bit PWM
-	1	0	0	1	0 or <sup>14</sup>	0	X <sup>5</sup>	Compare: PCA WDT (CCAPM4 only) <sup>6</sup>

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1. User should not write '1's to reserved bits. The value read from a reserved bit is indeterminate.
2. y = 0, 1, 2, 3, 4
3. No PCA interrupt is needed to generate the PWM.
4. A 0 disables toggle function. A 1 enables toggle function on CEX[4:0] pin.
5. Enabling an interrupt for the Watchdog Timer would defeat the purpose of the Watchdog Timer.
6. For PCA WDT mode, also set the WDTE bit in the CMOD register to enable the reset output signal.



**Figure 27:**PCA High Speed Output Mode

## Pulse Width Modulator

The Pulse Width Modulator (PWM) mode is used to generate 8-bit PWMs by comparing the low byte of the PCA timer (CL) with the low byte of the compare register (CCAPnL). When  $CL < CCAPnL$  the output is low. When  $CL \geq CCAPnL$  the output is high. To activate this mode, the user must set the PWM and ECOM bits in the module's CCAPMn SFR. (See Figure 28 and Table 24)

In PWM mode, the frequency of the output depends on the source for the PCA timer. Since there is only one set of CH and CL registers, all modules share the PCA timer and frequency. Duty cycle of the output is controlled by the value loaded into the high byte (CCAPnH). Since writes to the CCAPnH register are asynchronous, a new value written to the high byte will not be shifted into CCAPnL for comparison until the next period of the output (when CL rolls over from 255 to 00).

To calculate values for CCAPnH for any duty cycle, use the following equation:

$$CCAPnH = 256(1 - \text{Duty Cycle})$$

where CCAPnH is an 8-bit integer and Duty Cycle is a fraction.



## Security Lock

The security lock protects against software piracy and prevents the contents of the flash from being read by unauthorized parties. It also protects against code corruption resulting from accidental erasing and programming to the internal flash memory. There are two different types of security locks in the device security lock system: hard lock and SoftLock.

### Hard Lock

When hard lock is activated, MOV<sub>C</sub> or IAP instructions executed from an unlocked or soft locked program address space, are disabled from reading code bytes in hard locked memory blocks (See Table 26). Hard lock can either lock both flash memory blocks or just lock the 8 KByte flash memory block (Block 1). All external host and IAP commands except for Chip-Erase are ignored for memory blocks that are hard locked.

### SoftLock

SoftLock allows flash contents to be altered under a secure environment. This lock option allows the user to update program code in the soft locked memory block through in-application programming mode under a predetermined secure environment. For example, if Block 1 (8K) memory block is locked (hard locked or soft locked), and Block 0 memory block is soft locked, code residing in Block 1 can program Block 0. The following IAP mode commands issued through the command mailbox register, SFCM, executed from a Locked (hard locked or soft locked) block, can be operated on a soft locked block: Block-Erase, Sector-Erase, Byte-Program and Byte-Verify.

In external host mode, SoftLock behaves the same as a hard lock.

## Security Lock Status

The three bits that indicate the device security lock status are located in SFST[7:5]. As shown in Figure 30 and Table 25, the three security lock bits control the lock status of the primary and secondary blocks of memory. There are four distinct levels of security lock status. In the first level, none of the security lock bits are programmed and both blocks are unlocked. In the second level, although both blocks are now locked and cannot be programmed, they are available for read operation via Byte-Verify. In the third level, three different options are available: Block 1 hard lock / Block 0 SoftLock, SoftLock on both blocks, and hard lock on both blocks. Locking both blocks is the same as Level 2, Block 1 except read operation isn't available. The fourth level of security is the most secure level. It doesn't allow read/program of internal memory or boot from external memory. For details on how to program the security lock bits refer to the external host mode and in-application programming sections.

## Software Reset

The software reset is executed by changing SFCF[1] (SWR) from “0” to “1”. A software reset will reset the program counter to address 0000H. All SFR registers will be set to their reset values, except SFCF[1] (SWR), WDTC[2] (WDTS), and RAM data will not be altered.

## Brown-out Detection Reset

The device includes a brown-out detection circuit to protect the system from severed supplied voltage  $V_{DD}$  fluctuations. SST89E516RDx internal brown-out detection threshold is 3.85V, SST89V516RDx brown-out detection threshold is 2.35V. For brown-out voltage parameters, please refer to Table 36.

When  $V_{DD}$  drops below this voltage threshold, the brown-out detector triggers the circuit to generate a brown-out interrupt but the CPU still runs until the supplied voltage returns to the brown-out detection voltage  $V_{BOD}$ . The default operation for a brown-out detection is to cause a processor reset.

$V_{DD}$  must stay below  $V_{BOD}$  at least four oscillator clock periods before the brown-out detection circuit will respond.

Brown-out interrupt can be enabled by setting the EBO bit in IEA register (address E8H, bit 3). If EBO bit is set and a brown-out condition occurs, a brown-out interrupt will be generated to execute the program at location 004BH. It is required that the EBO bit be cleared by software after the brown-out interrupt is serviced. Clearing EBO bit when the brown-out condition is active will properly reset the device. If brown-out interrupt is not enabled, a brown-out condition will reset the program to resume execution at location 0000H.

## Power-Saving Modes

The device provides two power saving modes of operation for applications where power consumption is critical. The two modes are idle and power-down, see Table 28.

### Idle Mode

Idle mode is entered setting the IDL bit in the PCON register. In idle mode, the program counter (PC) is stopped. The system clock continues to run and all interrupts and peripherals remain active. The on-chip RAM and the special function registers hold their data during this mode.

The device exits idle mode through either a system interrupt or a hardware reset. Exiting idle mode via system interrupt, the start of the interrupt clears the IDL bit and exits idle mode. After exit the Interrupt Service Routine, the interrupted program resumes execution beginning at the instruction immediately following the instruction which invoked the idle mode. A hardware reset starts the device similar to a power-on reset.

### Power-down Mode

The power-down mode is entered by setting the PD bit in the PCON register. In the power-down mode, the clock is stopped and external interrupts are active for level sensitive interrupts only. SRAM contents are retained during power-down, the minimum  $V_{DD}$  level is 2.0V.

The device exits power-down mode through either an enabled external level sensitive interrupt or a hardware reset. The start of the interrupt clears the PD bit and exits power-down. Holding the external interrupt pin low restarts the oscillator, the signal must hold low at least 1024 clock cycles before bringing back high to complete the exit. Upon interrupt signal being restored to logic  $V_{IH}$ , the first instruction of the interrupt service routine will execute. A hardware reset starts the device similar to power-on reset.

To exit properly out of power-down, the reset or external interrupt should not be executed before the  $V_{DD}$  line is restored to its normal operating voltage. Be sure to hold  $V_{DD}$  voltage long enough at its normal operating level for the oscillator to restart and stabilize (normally less than 10 ms).

**Table 32: Reliability Characteristics**

Symbol	Parameter	Minimum Specification	Units	Test Method
$N_{END}^1$	Endurance	10,000	Cycles	JEDEC Standard A117
$T_{DR}^1$	Data Retention	100	Years	JEDEC Standard A103
$I_{LTH}^1$	Latch Up	$100 + I_{DD}$	mA	JEDEC Standard 78

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1. This parameter is measured only for initial qualification and after a design or process change that could affect this parameter.

**Table 33: AC Conditions of Test<sup>1</sup>**

Input Rise/Fall Time	Output Load
10 ns	$C_L = 100 \text{ pF}$

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1. See Figures 41 and 43

**Table 34: Recommended System Power-up Timings**

Symbol	Parameter	Minimum	Units
$T_{PU-READ}^1$	Power-up to Read Operation	100	$\mu\text{s}$
$T_{PU-WRITE}^1$	Power-up to Write Operation	100	$\mu\text{s}$

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1. This parameter is measured only for initial qualification and after a design or process change that could affect this parameter

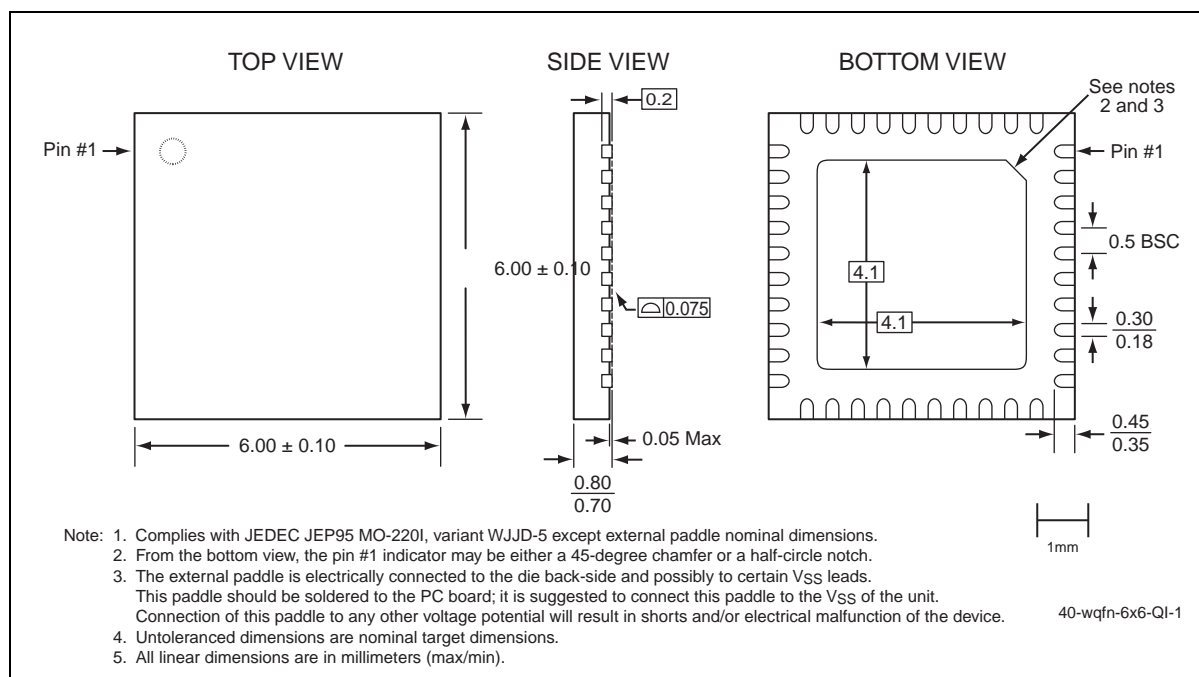
**Table 35: Pin Impedance ( $V_{DD}=3.3V$ ,  $T_A=25^\circ\text{C}$ ,  $f=1 \text{ Mhz}$ , other pins open)**

Parameter	Description	Test Condition	Maximum
$C_{I/O}^1$	I/O Pin Capacitance	$V_{I/O} = 0V$	15 pF
$C_{IN}^1$	Input Capacitance	$V_{IN} = 0V$	12 pF
$L_{PIN}^2$	Pin Inductance		20 nH

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1. This parameter is measured only for initial qualification and after a design or process change that could affect this parameter.
2. Refer to PCI spec.

## Packaging Diagrams



**Figure 47:**40-contact Very-very-thin Quad Flat No-lead (WQFN)  
SST Package Code: QI