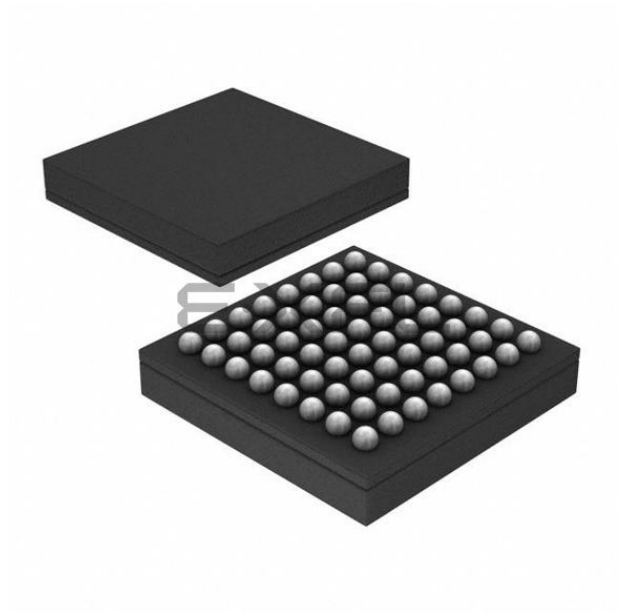

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, I²C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	DMA, Motor Control PWM, PDR, POR, PVD, PWM, Temp Sensor, WDT
Number of I/O	51
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TFBGA
Supplier Device Package	64-TFBGA (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f103r4h6a

2 Description

The STM32F103x4 and STM32F103x6 performance line family incorporates the high-performance ARM® Cortex™-M3 32-bit RISC core operating at a 72 MHz frequency, high-speed embedded memories (Flash memory up to 32 Kbytes and SRAM up to 6 Kbytes), and an extensive range of enhanced I/Os and peripherals connected to two APB buses. All devices offer two 12-bit ADCs, three general purpose 16-bit timers plus one PWM timer, as well as standard and advanced communication interfaces: up to two I^2Cs and SPIs, three USARTs, an USB and a CAN.

The STM32F103xx low-density performance line family operates from a 2.0 to 3.6 V power supply. It is available in both the –40 to +85 °C temperature range and the –40 to +105 °C extended temperature range. A comprehensive set of power-saving mode allows the design of low-power applications.

The STM32F103xx low-density performance line family includes devices in four different package types: from 36 pins to 64 pins. Depending on the device chosen, different sets of peripherals are included, the description below gives an overview of the complete range of peripherals proposed in this family.

These features make the STM32F103xx low-density performance line microcontroller family suitable for a wide range of applications such as motor drives, application control, medical and handheld equipment, PC and gaming peripherals, GPS platforms, industrial applications, PLCs, inverters, printers, scanners, alarm systems, video intercoms, and HVACs.

2.3 Overview

2.3.1 ARM® Cortex™-M3 core with embedded Flash and SRAM

The ARM® Cortex™-M3 processor is the latest generation of ARM® processors for embedded systems. It has been developed to provide a low-cost platform that meets the needs of MCU implementation, with a reduced pin count and low-power consumption, while delivering outstanding computational performance and an advanced system response to interrupts.

The ARM® Cortex™-M3 32-bit RISC processor features exceptional code-efficiency, delivering the high-performance expected from an ARM core in the memory size usually associated with 8- and 16-bit devices.

The STM32F103xx performance line family having an embedded ARM core, is therefore compatible with all ARM tools and software.

Figure 1 shows the general block diagram of the device family.

2.3.2 Embedded Flash memory

16 or 32 Kbytes of embedded Flash is available for storing programs and data.

2.3.3 CRC (cyclic redundancy check) calculation unit

The CRC (cyclic redundancy check) calculation unit is used to get a CRC code from a 32-bit data word and a fixed generator polynomial.

Among other applications, CRC-based techniques are used to verify data transmission or storage integrity. In the scope of the EN/IEC 60335-1 standard, they offer a means of verifying the Flash memory integrity. The CRC calculation unit helps compute a signature of the software during runtime, to be compared with a reference signature generated at link-time and stored at a given memory location.

2.3.4 Embedded SRAM

Six or ten Kbytes of embedded SRAM accessed (read/write) at CPU clock speed with 0 wait states.

2.3.5 Nested vectored interrupt controller (NVIC)

The STM32F103xx performance line embeds a nested vectored interrupt controller able to handle up to 43 maskable interrupt channels (not including the 16 interrupt lines of Cortex™-M3) and 16 priority levels.

- Closely coupled NVIC gives low-latency interrupt processing
- Interrupt entry vector table address passed directly to the core
- Closely coupled NVIC core interface
- Allows early processing of interrupts
- Processing of *late arriving* higher priority interrupts
- Support for tail-chaining
- Processor state automatically saved
- Interrupt entry restored on interrupt exit with no instruction overhead

Table 5. Low-density STM32F103xx pin definitions (continued)

Pins				Pin name	Type[1]	I / O Level[2]	Main function[3] (after reset)	Alternate functions[4]	
LQFP48/ UFQFPN48	LQFP64	TFBGA64	VFQFPN36					Default	Remap
18	26	F5	15	PB0	I/O	-	PB0	ADC12_IN8/TIM3_CH3[9]	TIM1_CH2N
19	27	G5	16	PB1	I/O	-	PB1	ADC12_IN9/TIM3_CH4[9]	TIM1_CH3N
20	28	G6	17	PB2	I/O	FT	PB2/BOOT1	-	-
21	29	G7	-	PB10	I/O	FT	PB10	-	TIM2_CH3
22	30	H7	-	PB11	I/O	FT	PB11	-	TIM2_CH4
23	31	D6	18	V_{SS_1}	S	-	V_{SS_1}	-	-
24	32	E6	19	V_{DD_1}	S	-	V_{DD_1}	-	-
25	33	H8	-	PB12	I/O	FT	PB12	TIM1_BKIN[9]	-
26	34	G8	-	PB13	I/O	FT	PB13	TIM1_CH1N [9]	-
27	35	F8	-	PB14	I/O	FT	PB14	TIM1_CH2N [9]	-
28	36	F7	-	PB15	I/O	FT	PB15	TIM1_CH3N[9]	-
-	37	F6	-	PC6	I/O	FT	PC6	-	TIM3_CH1
-	38	E7	-	PC7	I/O	FT	PC7	-	TIM3_CH2
-	39	E8	-	PC8	I/O	FT	PC8	-	TIM3_CH3
-	40	D8	-	PC9	I/O	FT	PC9	-	TIM3_CH4
29	41	D7	20	PA8	I/O	FT	PA8	USART1_CK/ TIM1_CH1/MCO	-
30	42	C7	21	PA9	I/O	FT	PA9	USART1_TX[9]/ TIM1_CH2[9]	-
31	43	C6	22	PA10	I/O	FT	PA10	USART1_RX[9]/ TIM1_CH3	-
32	44	C8	23	PA11	I/O	FT	PA11	USART1_CTS/ CAN_RX[9]/ TIM1_CH4 / USBDM	-
33	45	B8	24	PA12	I/O	FT	PA12	USART1_RTS/ CAN_TX[9] / TIM1_ETR / USBDP	-
34	46	A8	25	PA13	I/O	FT	JTMS/SWDIO		PA13
35	47	D5	26	V_{SS_2}	S	-	V_{SS_2}	-	-
36	48	E5	27	V_{DD_2}	S	-	V_{DD_2}	-	-
37	49	A7	28	PA14	I/O	FT	JTCK/SWCLK	-	PA14
38	50	A6	29	PA15	I/O	FT	JTDI	-	TIM2_CH1_ETR/ PA15 / SPI1_NSS
-	51	B7	-	PC10	I/O	FT	PC10	-	-
-	52	B6	-	PC11	I/O	FT	PC11	-	-
-	53	C5	-	PC12	I/O	FT	PC12	-	-
-	-	C1	2	PD0	I/O	FT	PD0	-	-

Figure 9. Pin loading conditions

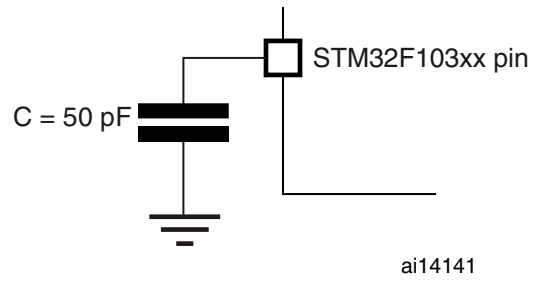
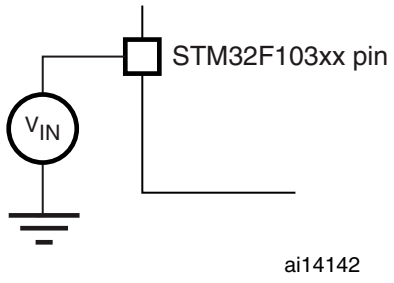
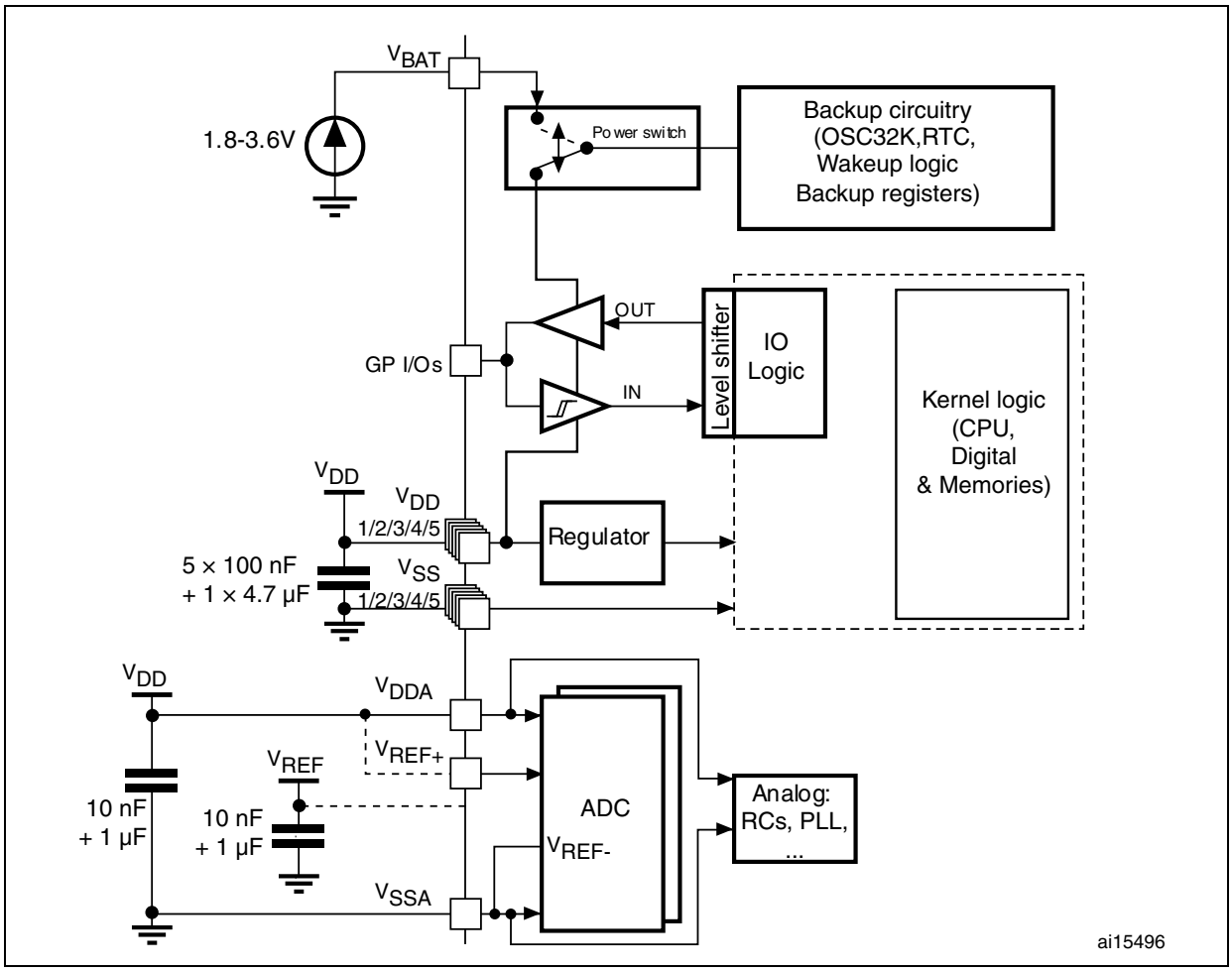


Figure 10. Pin input voltage



5.1.6 Power supply scheme

Figure 11. Power supply scheme



Caution: In *Figure 11*, the 4.7 µF capacitor must be connected to V_{DD3}.

Table 9. General operating conditions (continued)

Symbol	Parameter	Conditions		Min	Max	Unit
V_{IN}	I/O input voltage	Standard IO		–0.3	V_{DD}+ 0.3	V
		FT IO(3)	2 V < V_{DD} ≤ 3.6 V	–0.3	5.5	
			V_{DD} = 2 V	–0.3	5.2	
		BOOT0		0	5.5	
P_D	Power dissipation at T_A = 85 °C for suffix 6 or T_A = 105 °C for suffix 7(4)	TFBGA64		-	308	mW
		LQFP64		-	444	
		LQFP48		-	363	
		UFQFPN48		-	624	
		VFQFPN36		-	1000	
T_A	Ambient temperature for 6 suffix version	Maximum power dissipation		–40	85	°C
		Low power dissipation(5)		–40	105	
	Ambient temperature for 7 suffix version	Maximum power dissipation		–40	105	
		Low power dissipation(5)		–40	125	
T_J	Junction temperature range	6 suffix version		–40	105	
		7 suffix version		–40	125	

1. When the ADC is used, refer to *Table 46: ADC characteristics*.
2. It is recommended to power V_{DD} and V_{DDA} from the same source. A maximum difference of 300 mV between V_{DD} and V_{DDA} can be tolerated during power-up and operation.
3. To sustain a voltage higher than V_{DD}+0.3 V, the internal pull-up/pull-down resistors must be disabled.
4. If T_A is lower, higher P_D values are allowed as long as T_J does not exceed $T_J$max (see *Table 6.6: Thermal characteristics on page 92*).
5. In low power dissipation state, T_A can be extended to this range as long as T_J does not exceed $T_J$max (see *Table 6.6: Thermal characteristics on page 92*).

5.3.2 Operating conditions at power-up / power-down

Subject to general operating conditions for T_A.

Table 10. Operating conditions at power-up / power-down

Symbol	Parameter	Conditions	Min	Max	Unit
t_{VDD}	V_{DD} rise time rate	-	0	¥	µs/V
	V_{DD} fall time rate		20	¥	

5.3.3 Embedded reset and power control block characteristics

The parameters given in *Table 11* are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 9*.

Figure 16. Typical current consumption in Stop mode with regulator in Run mode versus temperature at V_{DD} = 3.3 V and 3.6 V

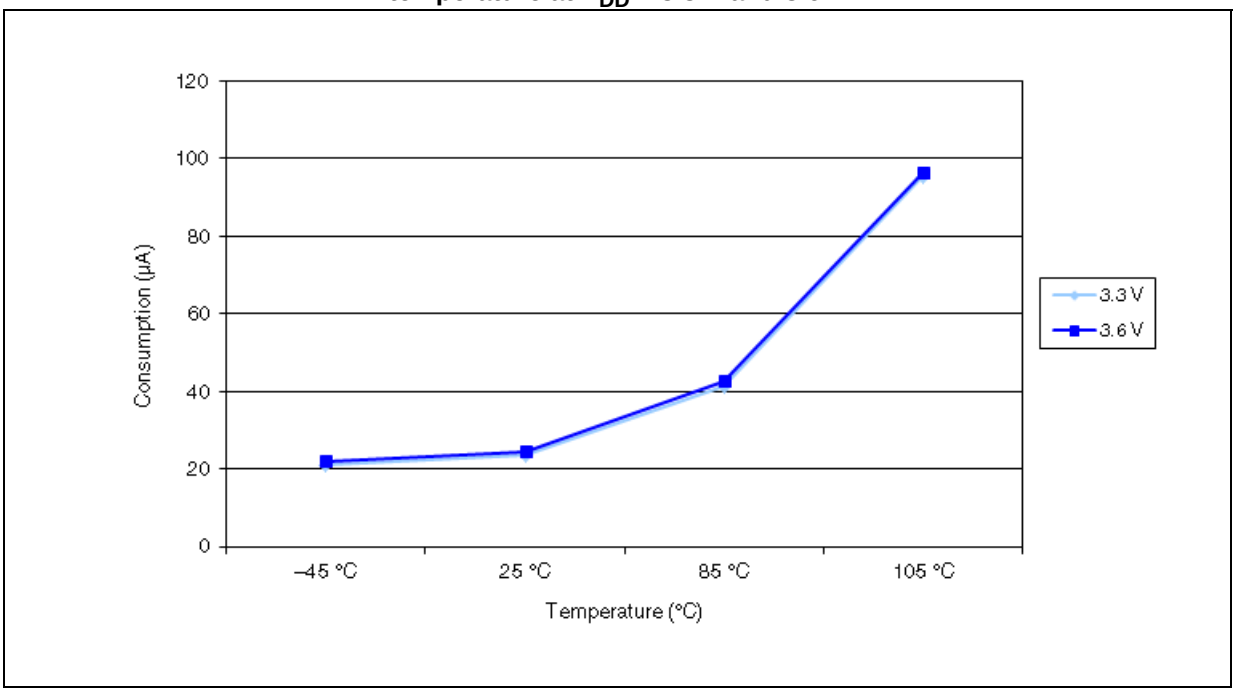


Figure 17. Typical current consumption in Stop mode with regulator in Low-power mode versus temperature at V_{DD} = 3.3 V and 3.6 V

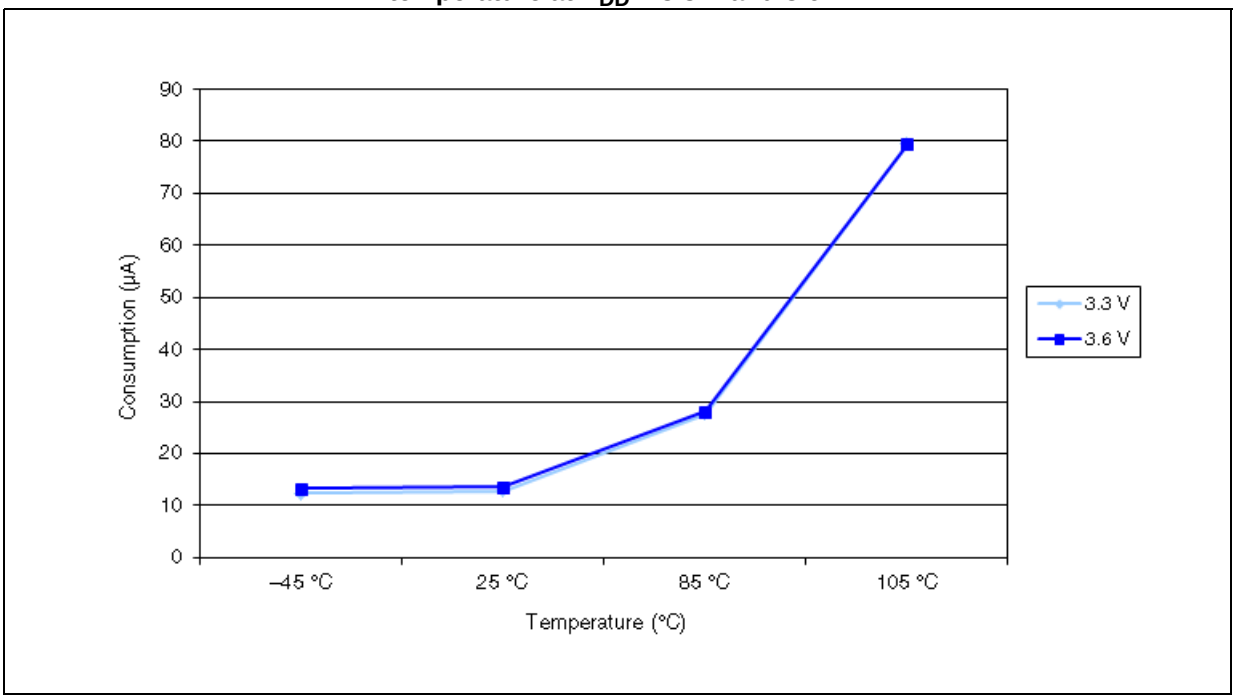


Table 30. EMS characteristics

Symbol	Parameter	Conditions	Level/ Class
V_{FESD}	Voltage limits to be applied on any I/O pin to induce a functional disturbance	V_{DD} = 3.3 V, T_A = +25 °C, f_{HCLK} = 72 MHz conforms to IEC 61000-4-2	2B
V_{EFTB}	Fast transient voltage burst limits to be applied through 100 pF on V_{DD} and V_{SS} pins to induce a functional disturbance	V_{DD} = 3.3 V, T_A = +25 °C, f_{HCLK} = 72 MHz conforms to IEC 61000-4-4	4A

Designing hardened software to avoid noise problems

EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. It should be noted that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user applies EMC software optimization and prequalification tests in relation with the EMC level requested for his application.

Software recommendations

The software flowchart must include the management of runaway conditions such as:

- Corrupted program counter
- Unexpected reset
- Critical Data corruption (control registers...)

Prequalification trials

Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the NRST pin or the Oscillator pins for 1 second.

To complete these trials, ESD stress can be applied directly on the device, over the range of specification values. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring (see application note AN1015).

Electromagnetic Interference (EMI)

The electromagnetic field emitted by the device are monitored while a simple application is executed (toggling 2 LEDs through the I/O ports). This emission test is compliant with IEC 61967-2 standard which specifies the test board and the pin loading.

Table 31. EMI characteristics

Symbol	Parameter	Conditions	Monitored frequency band	Max vs. [f_{HSE}/f_{HCLK}]		Unit
				8/48 MHz	8/72 MHz	
S_{EMI}	Peak level	V_{DD} = 3.3 V, T_A = 25 °C	0.1 to 30 MHz	12	12	dBµV
			30 to 130 MHz	22	19	
			130 MHz to 1GHz	23	29	
			SAE EMI Level	4	4	-

5.3.12 I/O current injection characteristics

As a general rule, current injection to the I/O pins, due to external voltage below V_{SS} or above V_{DD} (for standard, 3 V-capable I/O pins) should be avoided during normal product operation. However, in order to give an indication of the robustness of the microcontroller in cases when abnormal injection accidentally happens, susceptibility tests are performed on a sample basis during device characterization.

Functional susceptibilty to I/O current injection

While a simple application is executed on the device, the device is stressed by injecting current into the I/O pins programmed in floating input mode. While current is injected into the I/O pin, one at a time, the device is checked for functional failures.

The failure is indicated by an out of range parameter: ADC error above a certain limit (>5 LSB TUE), out of spec current injection on adjacent pins or other functional failure (for example reset, oscillator frequency deviation).

The test results are given in *Table 34*

Table 34. I/O current injection susceptibility

Symbol	Description	Functional susceptibility		Unit
		Negative injection	Positive injection	
I_{INJ}	Injected current on OSC_IN32, OSC_OUT32, PA4, PA5, PC13	-0	+0	mA
	Injected current on all FT pins	-5	+0	
	Injected current on any other pin	-5	+5	

5.3.13 I/O port characteristics

General input/output characteristics

Unless otherwise specified, the parameters given in *Table 35* are derived from tests performed under the conditions summarized in *Table 9*. All I/Os are CMOS and TTL compliant.

Table 35. I/O static characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{IL}	Low level input voltage	Standard IO input low level voltage	-	-	$0.28*(V_{DD}-2\ V)+0.8\ V$(1)	V
		IO FT(3) input low level voltage	-	-	$0.32*(V_{DD}-2V)+0.75\ V$(1)	
		All I/Os except BOOT0	-	-	$0.35V_{DD}$(2)	
V_{IH}	High level input voltage	Standard IO input high level voltage	$0.41*(V_{DD}-2\ V)+1.3\ V$(1)	-	-	
		IO FT(3) input high level voltage	$0.42*(V_{DD}-2\ V)+1\ V$(1)	-	-	
		All I/Os except BOOT0	$0.65V_{DD}$(2)	-	-	
V_{hys}	Standard IO Schmitt trigger voltage hysteresis(4)	-	200	-	-	mV
	IO FT Schmitt trigger voltage hysteresis(4)	-	5% V_{DD}(5)	-	-	
I_{lkg}	Input leakage current (6)	$V_{SS} \le V_{IN} \le V_{DD}$ Standard I/Os	-	-	±1	µA
		V_{IN} = 5 V I/O FT	-	-	3	
R_{PU}	Weak pull-up equivalent resistor(7)	$V_{IN} = V_{SS}$	30	40	50	kΩ
R_{PD}	Weak pull-down equivalent resistor(7)	$V_{IN} = V_{DD}$	30	40	50	
C_{IO}	I/O pin capacitance	-	-	5	-	pF

1. Data based on design simulation.
2. Tested in production.
3. FT = Five-volt tolerant. In order to sustain a voltage higher than V_{DD}+0.3 the internal pull-up/pull-down resistors must be disabled.
4. Hysteresis voltage between Schmitt trigger switching levels. Based on characterization, not tested in production.
5. With a minimum of 100 mV.
6. Leakage could be higher than max. if negative current is injected on adjacent pins.
7. Pull-up and pull-down resistors are designed with a true resistance in series with a switchable PMOS/NMOS. This PMOS/NMOS contribution to the series resistance is minimum (~10% order).

All I/Os are CMOS and TTL compliant (no software configuration required). Their characteristics cover more than the strict CMOS-technology or TTL parameters. The coverage of these requirements is shown in *Figure 23* and *Figure 24* for standard I/Os, and in *Figure 25* and *Figure 26* for 5 V tolerant I/Os.

Figure 23. Standard I/O input characteristics - CMOS port

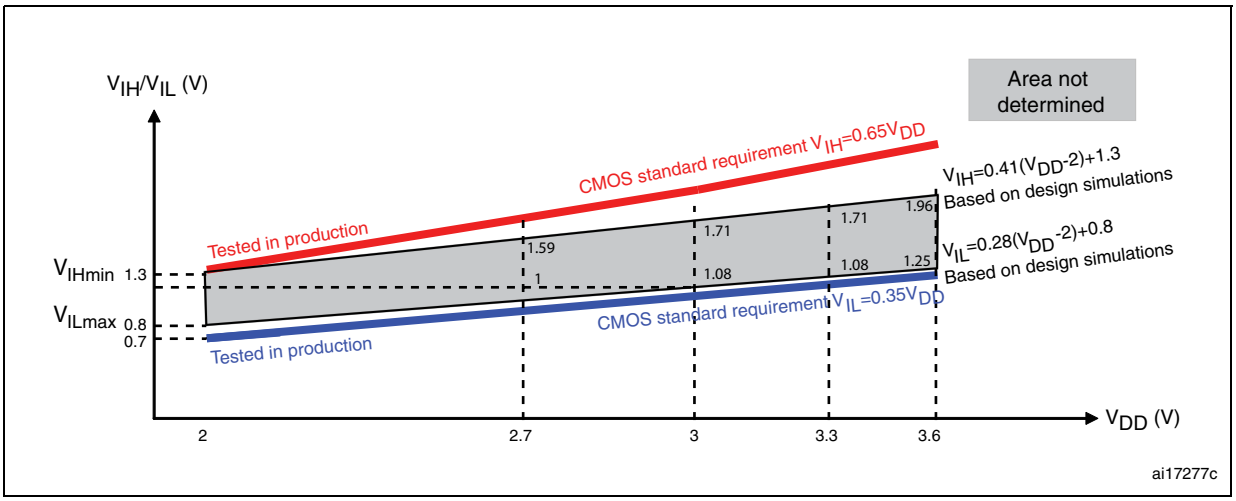


Figure 24. Standard I/O input characteristics - TTL port

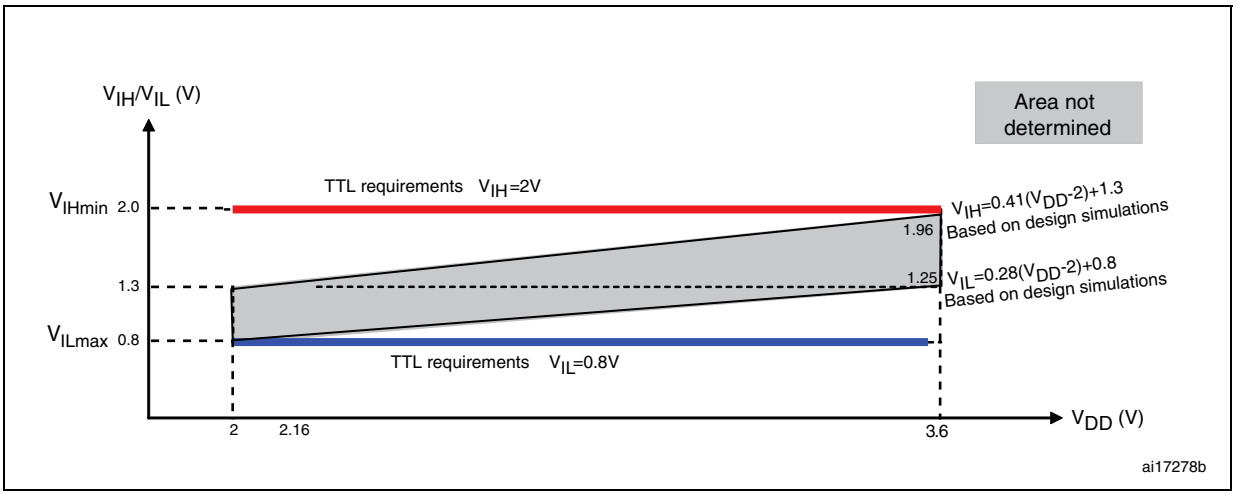


Figure 25. 5 V tolerant I/O input characteristics - CMOS port

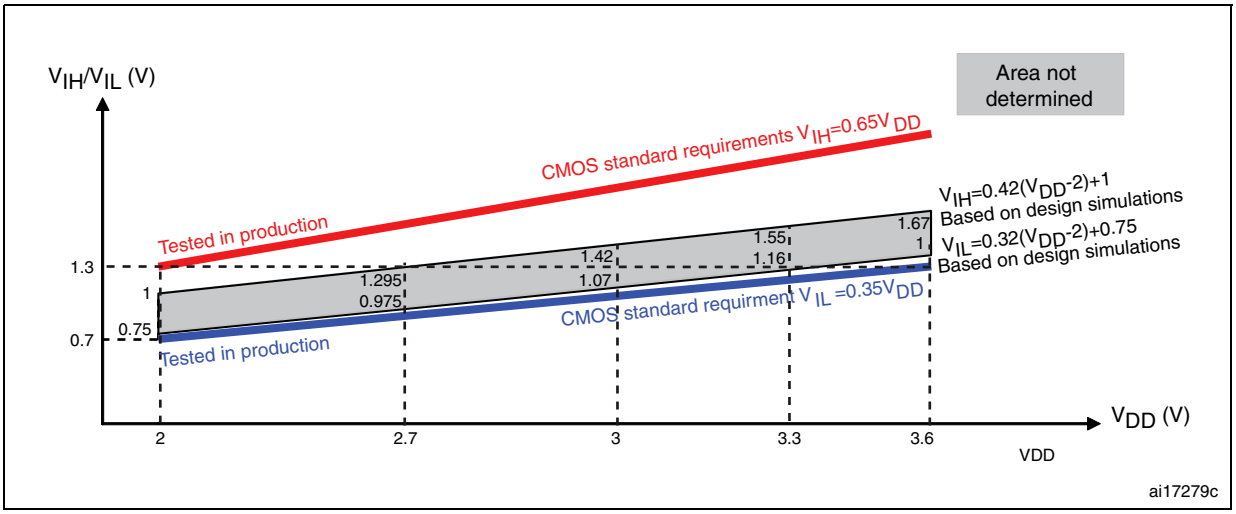
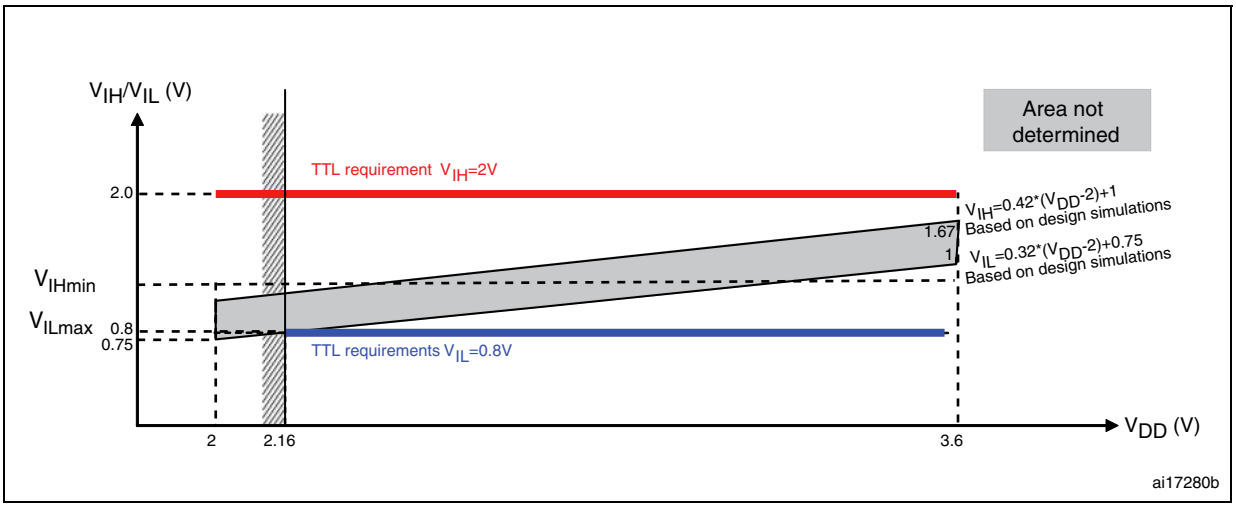


Figure 26. 5 V tolerant I/O input characteristics - TTL port



SPI interface characteristics

Unless otherwise specified, the parameters given in *Table 42* are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and V_{DD} supply voltage conditions summarized in *Table 9*.

Refer to *Section 5.3.12: I/O current injection characteristics* for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO).

Table 42. SPI characteristics

Symbol	Parameter	Conditions	Min	Max	Unit
f_{SCK} $1/t_{c(SCK)}$	SPI clock frequency	Master mode	-	18	MHz
		Slave mode	-	18	
$t_{r(SCK)}$ $t_{f(SCK)}$	SPI clock rise and fall time	Capacitive load: C = 30 pF		8	ns
DuCy(SCK)	SPI slave input clock duty cycle	Slave mode	30	70	%
$t_{su(NSS)}$ (1)	NSS setup time	Slave mode	$4t_{PCLK}$	-	ns
$t_{h(NSS)}$ (1)	NSS hold time	Slave mode	$2t_{PCLK}$	-	
$t_{w(SCKH)}$ (1) $t_{w(SCKL)}$ (1)	SCK high and low time	Master mode, f_{PCLK} = 36 MHz, presc = 4	50	60	
$t_{su(MI)}$ (1) $t_{su(SI)}$ (1)	Data input setup time	Master mode	5	-	
		Slave mode	5	-	
$t_{h(MI)}$ (1)	Data input hold time	Master mode	5	-	
$t_{h(SI)}$ (1)		Slave mode	4	-	
$t_{a(SO)}$ (1)(2)	Data output access time	Slave mode, f_{PCLK} = 20 MHz	0	$3t_{PCLK}$	
$t_{dis(SO)}$ (1)(3)	Data output disable time	Slave mode	2	10	
$t_{v(SO)}$ (1)	Data output valid time	Slave mode (after enable edge)	-	25	
$t_{v(MO)}$ (1)	Data output valid time	Master mode (after enable edge)	-	5	
$t_{h(SO)}$ (1)	Data output hold time	Slave mode (after enable edge)	15	-	
$t_{h(MO)}$ (1)		Master mode (after enable edge)	2	-	

1. Based on characterization, not tested in production.
2. Min time is for the minimum time to drive the output and the max time is for the maximum time to validate the data.
3. Min time is for the minimum time to invalidate the output and the max time is for the maximum time to put the data in Hi-Z

Equation 1: R_{AIN} max formula:

$$R_{AIN} < \frac{T_S}{f_{ADC} \times C_{ADC} \times \ln(2^{N+2})} - R_{ADC}$$

The formula above (*Equation 1*) is used to determine the maximum external impedance allowed for an error below 1/4 of LSB. Here N = 12 (from 12-bit resolution).

Table 47. R_{AIN} max for f_{ADC} = 14 MHz(1)

T_s (cycles)	t_S (µs)	R_{AIN} max (kΩ)
1.5	0.11	0.4
7.5	0.54	5.9
13.5	0.96	11.4
28.5	2.04	25.2
41.5	2.96	37.2
55.5	3.96	50
71.5	5.11	NA
239.5	17.1	NA

1. Based on characterization, not tested in production.

Table 48. ADC accuracy - limited test conditions(1) (2)

Symbol	Parameter	Test conditions	Typ	Max(3)	Unit
ET	Total unadjusted error	f_{PCLK2} = 56 MHz, f_{ADC} = 14 MHz, R_{AIN} < 10 kΩ, V_{DDA} = 3 V to 3.6 V T_A = 25 °C Measurements made after ADC calibration	±1.3	±2	LSB
EO	Offset error		±1	±1.5	
EG	Gain error		±0.5	±1.5	
ED	Differential linearity error		±0.7	±1	
EL	Integral linearity error		±0.8	±1.5	

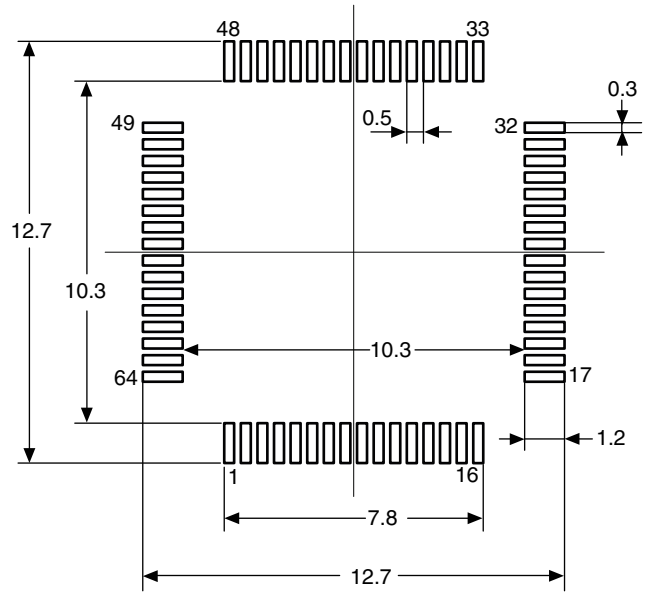
1. ADC DC accuracy values are measured after internal calibration.
2. ADC Accuracy vs. Negative Injection Current: Injecting a negative current on any analog input pins should be avoided as this significantly reduces the accuracy of the conversion being performed on another analog input. It is recommended to add a Schottky diode (pin to ground) to analog pins which may potentially inject negative currents.
   Any positive injection current within the limits specified for $I_{INJ(PIN)}$ and $\Sigma I_{INJ(PIN)}$ in *Section 5.3.12* does not affect the ADC accuracy.
3. Based on characterization, not tested in production.

Table 53. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
E3	-	7.500	-	-	0.2953	-
e	-	0.500	-	-	0.0197	-
K	0°	3.5°	7°	0°	3.5°	7°
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 45. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package recommended footprint



1. Dimensions are expressed in millimeters.

Table 54. TFBGA64 – 64-ball, 5 x 5 mm, 0.5 mm pitch, thin profile fine pitch ball grid array package mechanical data (continued)

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
e	-	0.500	-	-	0.0197	-
F	-	0.750	-	-	0.0295	-
ddd	-	-	0.080	-	-	0.0031
eee	-	-	0.150	-	-	0.0059
fff	-	-	0.050	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 48. TFBGA64 – 64-ball, 5 x 5 mm, 0.5 mm pitch, thin profile fine pitch ball grid array, recommended footprint

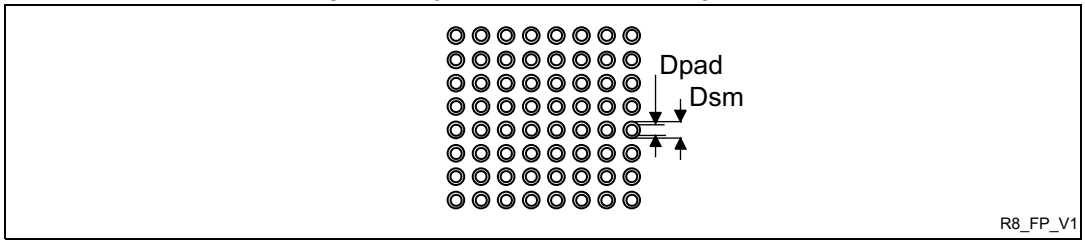


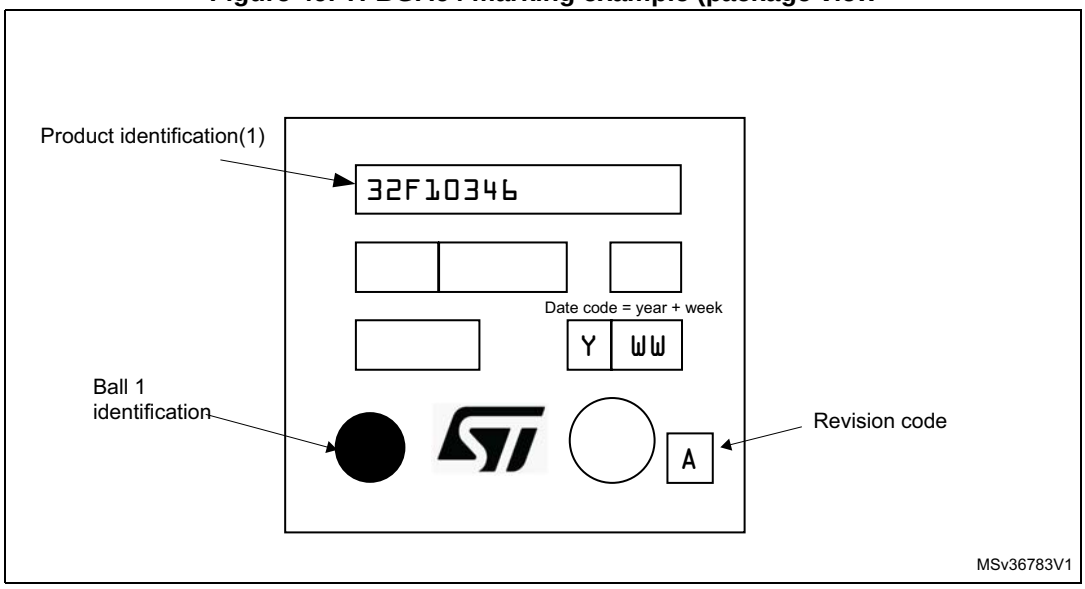
Table 55. TFBGA64 recommended PCB design rules (0.5 mm pitch BGA)

Dimension	Recommended values
Pitch	0.5
Dpad	0.280 mm
Dsm	0.370 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.280 mm
Stencil thickness	Between 0.100 mm and 1.125 mm
Pad trace width	0.100 mm

Device Marking for TFBGA64

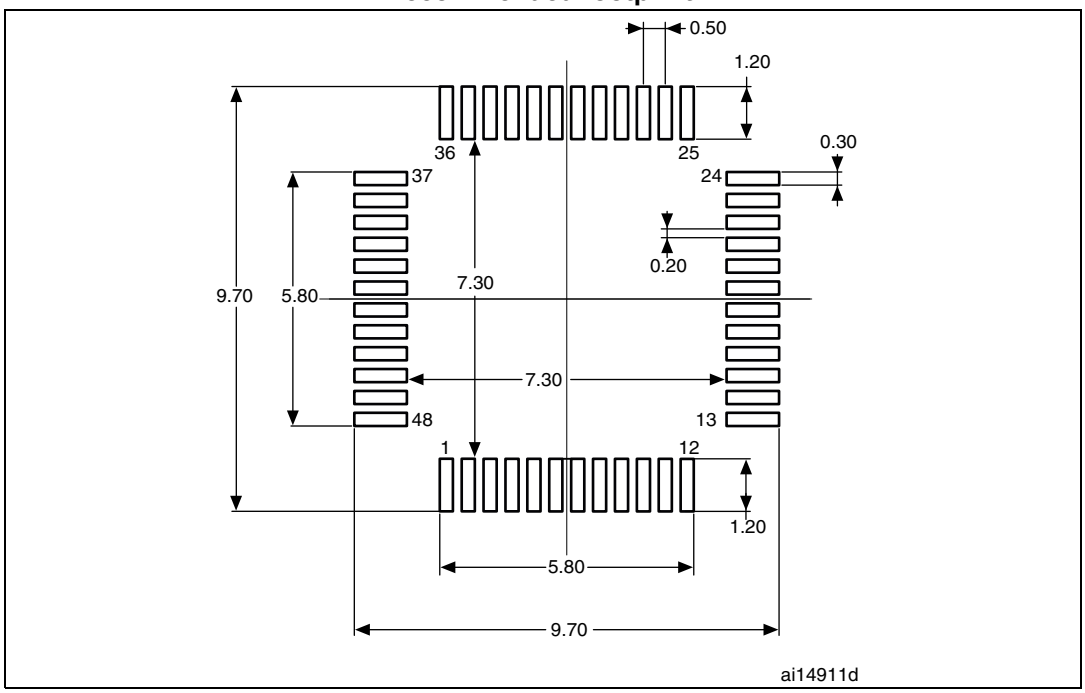
The following figure gives an example of topside marking orientation versus ball 1 identifier location.

Figure 49. TFBGA64 marking example (package view



1. Parts marked as “ES”, “E” or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

Figure 51. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package recommended footprint



1. Dimensions are expressed in millimeters.

8 Revision history

Table 59. Document revision history

Date	Revision	Changes
22-Sep-2008	1	Initial release.
30-Mar-2009	2	"96-bit unique ID" feature added and I/O information clarified *on page 1*. Timers specified *on page 1* (Motor control capability mentioned). *Table 4: Timer feature comparison* added. PB4, PB13, PB14, PB15, PB3/TRACESWO moved from Default column to Remap column, plus small additional changes in *Table 5: Low-density STM32F103xx pin definitions*. *Figure 8: Memory map* modified. References to V_{REF-} removed: – *Figure 1: STM32F103xx performance line block diagram* modified, – *Figure 11: Power supply scheme* modified – *Figure 34: ADC accuracy characteristics* modified – Note modified in *Table 49: ADC accuracy*. *Table 20: High-speed external user clock characteristics* and *Table 21: Low-speed external user clock characteristics* modified. Note modified in *Table 13: Maximum current consumption in Run mode, code with data processing running from Flash* and *Table 15: Maximum current consumption in Sleep mode, code running from Flash or RAM*. *Figure 17* shows a typical curve (title modified). ACC_{HSI} max values modified in *Table 24: HSI oscillator characteristics*. TFBGA64 package added (see *Table 54* and *Table 47*). Small text changes.
24-Sep-2009	3	*Note 5* updated and *Note 4* added in *Table 5: Low-density STM32F103xx pin definitions*. V_{RERINT} and T_{Coeff} added to *Table 12: Embedded internal reference voltage*. Typical I_{DD_VBAT} value added in *Table 16: Typical and maximum current consumptions in Stop and Standby modes*. *Figure 15: Typical current consumption on V_{BAT} with RTC on versus temperature at different V_{BAT} values* added. f_{HSE_ext} min modified in *Table 20: High-speed external user clock characteristics*. C_{L1} and C_{L2} replaced by C in *Table 22: HSE 4-16 MHz oscillator characteristics* and *Table 23: LSE oscillator characteristics (f_{LSE} = 32.768 kHz)*, notes modified and moved below the tables. *Table 24: HSI oscillator characteristics* modified. Conditions removed from *Table 26: Low-power mode wakeup timings*. *Note 1* modified below *Figure 21: Typical application with an 8 MHz crystal*. *Figure 28: Recommended NRST pin protection* modified. Jitter added to *Table 27: PLL characteristics on page 52*. IEC 1000 standard updated to IEC 61000 and SAE J1752/3 updated to IEC 61967-2 in *Section 5.3.10: EMC characteristics on page 53*. C_{ADC} and R_{AIN} parameters modified in *Table 46: ADC characteristics*. R_{AIN} max values modified in *Table 47: R_{AIN} max for f_{ADC} = 14 MHz*. Small text changes.