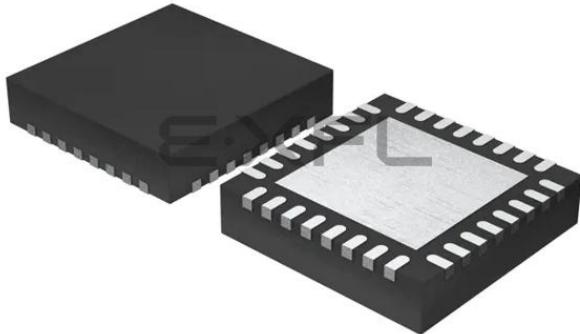


Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?



"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	I²C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	24
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.85V ~ 3.8V
Data Converters	A/D 24x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-VFQFN Exposed Pad
Supplier Device Package	32-QFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32pg1b100f128gm32-b0

1. Feature List

The EFM32PG1 highlighted features are listed below.

- **ARM Cortex-M4 CPU platform**

- High performance 32-bit processor @ up to 40 MHz
- DSP instruction support and Floating Point Unit
- Memory Protection Unit
- Wake-up Interrupt Controller

- **Flexible Energy Management System**

- 63 μ A/MHz in Energy Mode 0 (EM0)
- 2.5 μ A EM2 DeepSleep current (RTCC running with state and RAM retention)
- 0.58 μ A EM4H Hibernate Mode (128 byte RAM retention)

- **Up to 256 kB flash program memory**

- **32 kB RAM data memory**

- **Up to 32 General Purpose I/O Pins**

- Configurable push-pull, open-drain, pull-up/down, input filter, drive strength
- Configurable peripheral I/O locations
- Asynchronous external interrupts
- Output state retention and wake-up from Shutoff Mode

- **Hardware Cryptography**

- AES 128/256-bit keys
- ECC B/K163, B/K233, P192, P224, P256
- SHA-1 and SHA-2 (SHA-224 and SHA-256)

- **Timers/Counters**

- 2× 16-bit Timer/Counter
 - 3 + 4 Compare/Capture/PWM channels
- 1× 32-bit Real Time Counter and Calendar
- 1× 32-bit Ultra Low Energy CRYOTIMER for periodic wake-up from any Energy Mode
- 16-bit Low Energy Timer for waveform generation
- 16-bit Pulse Counter with asynchronous operation
- Watchdog Timer with dedicated RC oscillator

- **8 Channel DMA Controller**

- **12 Channel Peripheral Reflex System (PRS) for autonomous inter-peripheral signaling**

- **Communication Interfaces**

- 2× Universal Synchronous/Asynchronous Receiver/ Transmitter
 - UART/SPI/SmartCard (ISO 7816)/IrDA/I2S/LIN
 - Triple buffered full/half-duplex operation with flow control
- Low Energy UART
 - Autonomous operation with DMA in Deep Sleep Mode
- I²C Interface with SMBus support
 - Address recognition in EM3 Stop Mode

- **Ultra Low-Power Precision Analog Peripherals**

- 12-bit 1 Msamples/s Analog to Digital Converter
- 2× Analog Comparator
- Digital to Analog Current Converter
- Up to 32 pins connected to analog channels (APORT) shared between Analog Comparators, ADC, and IDAC

- **Ultra efficient Power-on Reset and Brown-Out Detector**

- **Debug Interface**

- 2-pin Serial Wire Debug interface
- 1-pin Serial Wire Viewer
- JTAG (programming only)

- **Wide Operating Range**

- 1.85 V to 3.8 V single power supply
- Integrated dc-dc, down to 1.8 V output with up to 200 mA load current for system
- Standard (-40 °C to 85 °C T_{AMB}) and Extended (-40 °C to 125 °C T_J) temperature grades available

- **Packages**

- 7 mm × 7 mm QFN48
- 5 mm × 5 mm QFN32

- **Pre-Programmed UART Bootloader**

- **Full Software Support**

- CMSIS register definitions
- Low-power Hardware Abstraction Layer (HAL)
- Portable software components
- Third-party middleware
- Free and available example code

3.6.3 Inter-Integrated Circuit Interface (I²C)

The I²C module provides an interface between the MCU and a serial I²C bus. It is capable of acting as both a master and a slave and supports multi-master buses. Standard-mode, fast-mode and fast-mode plus speeds are supported, allowing transmission rates from 10 kbit/s up to 1 Mbit/s. Slave arbitration and timeouts are also available, allowing implementation of an SMBus-compliant system. The interface provided to software by the I²C module allows precise timing control of the transmission process and highly automated transfers. Automatic recognition of slave addresses is provided in active and low energy modes.

3.6.4 Peripheral Reflex System (PRS)

The Peripheral Reflex System provides a communication network between different peripheral modules without software involvement. Peripheral modules producing Reflex signals are called producers. The PRS routes Reflex signals from producers to consumer peripherals which in turn perform actions in response. Edge triggers and other functionality can be applied by the PRS. The PRS allows peripheral to act autonomously without waking the MCU core, saving power.

3.7 Security Features

3.7.1 GPCRC (General Purpose Cyclic Redundancy Check)

The GPCRC module implements a Cyclic Redundancy Check (CRC) function. It supports both 32-bit and 16-bit polynomials. The supported 32-bit polynomial is 0x04C11DB7 (IEEE 802.3), while the 16-bit polynomial can be programmed to any value, depending on the needs of the application.

3.7.2 Crypto Accelerator (CRYPTO)

The Crypto Accelerator is a fast and energy-efficient autonomous hardware encryption and decryption accelerator. EFM32PG1 devices support AES encryption and decryption with 128- or 256-bit keys, ECC over both GF(P) and GF(2^m), and SHA-1 and SHA-2 (SHA-224 and SHA-256).

Supported block cipher modes of operation for AES include: ECB, CTR, CBC, PCBC, CFB, OFB, GCM, CBC-MAC, GMAC and CCM.

Supported ECC NIST recommended curves include P-192, P-224, P-256, K-163, K-233, B-163 and B-233.

The CRYPTO module allows fast processing of GCM (AES), ECC and SHA with little CPU intervention. CRYPTO also provides trigger signals for DMA read and write operations.

3.8 Analog

3.8.1 Analog Port (APORT)

The Analog Port (APORT) is an analog interconnect matrix allowing access to many analog modules on a flexible selection of pins. Each APORT bus consists of analog switches connected to a common wire. Since many clients can operate differentially, buses are grouped by X/Y pairs.

3.8.2 Analog Comparator (ACMP)

The Analog Comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. Inputs are selected from among internal references and external pins. The tradeoff between response time and current consumption is configurable by software. Two 6-bit reference dividers allow for a wide range of internally-programmable reference sources. The ACMP can also be used to monitor the supply voltage. An interrupt can be generated when the supply falls below or rises above the programmable threshold.

3.8.3 Analog to Digital Converter (ADC)

The ADC is a Successive Approximation Register (SAR) architecture, with a resolution of up to 12 bits at up to 1 Msps. The output sample resolution is configurable and additional resolution is possible using integrated hardware for averaging over multiple samples. The ADC includes integrated voltage references and an integrated temperature sensor. Inputs are selectable from a wide range of sources, including pins configurable as either single-ended or differential.

4. Electrical Specifications

4.1 Electrical Characteristics

All electrical parameters in all tables are specified under the following conditions, unless stated otherwise:

- Typical values are based on $T_{AMB}=25\text{ }^{\circ}\text{C}$ and $V_{DD}=3.3\text{ V}$, by production test and/or technology characterization.
- Minimum and maximum values represent the worst conditions across supply voltage, process variation, and operating temperature, unless stated otherwise.

Refer to [Table 4.2 General Operating Conditions on page 11](#) for more details about operational supply and temperature limits.

4.1.1 Absolute Maximum Ratings

Stresses above those listed below may cause permanent damage to the device. This is a stress rating only and functional operation of the devices at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability. For more information on the available quality and reliability data, see the Quality and Reliability Monitor Report at <http://www.silabs.com/support/quality/pages/default.aspx>.

Table 4.1. Absolute Maximum Ratings

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Storage temperature range	T_{STG}		-50	—	150	$^{\circ}\text{C}$
External main supply voltage	V_{DDMAX}		0	—	3.8	V
External main supply voltage ramp rate	$V_{DDRAMPMAX}$		—	—	1	$\text{V}/\mu\text{s}$
Voltage on any 5V tolerant GPIO pin ¹	V_{DIGPIN}		-0.3	—	Min of 5.25 and $IOVDD+2$	V
Voltage on non-5V tolerant GPIO pins			-0.3	—	$IOVDD+0.3$	V
Voltage on HFXO pins	$V_{HFXOPIN}$		-0.3	—	1.4	V
Total current into VDD power lines (source)	I_{VDDMAX}		—	—	200	mA
Total current into VSS ground lines (sink)	I_{VSSMAX}		—	—	200	mA
Current per I/O pin (sink)	I_{IOMAX}		—	—	50	mA
Current per I/O pin (source)			—	—	50	mA
Current for all I/O pins (sink)	$I_{IOALLMAX}$		—	—	200	mA
Current for all I/O pins (source)			—	—	200	mA
Voltage difference between AVDD and VREGVDD	ΔV_{DD}		—	—	0.3	V
Junction Temperature for -G grade devices	T_J		-40	—	105	$^{\circ}\text{C}$
Junction Temperature for -I grade devices			-40	—	125	$^{\circ}\text{C}$
Note:						
1. When a GPIO pin is routed to the analog module through the APOR, the maximum voltage = IOVDD.						

4.1.2 Operating Conditions

When assigning supply sources, the following requirements must be observed:

- VREGVDD must be the highest voltage in the system
- VREGVDD = AVDD
- DVDD ≤ AVDD
- IOVDD ≤ AVDD

4.1.2.1 General Operating Conditions

Table 4.2. General Operating Conditions

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit	
Operating temperature range	TOP	-G temperature grade, Ambient Temperature	-40	25	85	°C	
		-I temperature grade, Junction Temperature	-40	25	125	°C	
AVDD Supply voltage ¹	V _{AVDD}		1.85	3.3	3.8	V	
VREGVDD Operating supply voltage ^{1,2}	V _{VREGVDD}	DCDC in regulation	2.4	3.3	3.8	V	
		DCDC in bypass, 50mA load	1.85	3.3	3.8	V	
		DCDC not in use. DVDD externally shorted to VREGVDD	1.85	3.3	3.8	V	
VREGVDD Current	I _{VREGVDD}	DCDC in bypass, T _{amb} ≤ 85 °C	—	—	200	mA	
		DCDC in bypass, T _{amb} > 85 °C	—	—	100	mA	
DVDD Operating supply voltage	V _{DVDD}		1.62	—	V _{VREGVDD}	V	
IOVDD Operating supply voltage	V _{IOVDD}		1.62	—	V _{VREGVDD}	V	
Difference between AVDD and VREGVDD, ABS(AVDD-VREGVDD)	dV _{DD}		—	—	0.1	V	
HFCLK frequency	f _{CORE}	0 wait-states (MODE = WS0) ³	—	—	26	MHz	
		1 wait-states (MODE = WS1) ³	—	—	40	MHz	
Note:							
1. VREGVDD must be tied to AVDD. Both VREGVDD and AVDD minimum voltages must be satisfied for the part to operate.							
2. The minimum voltage required in bypass mode is calculated using R _{BYP} from the DCDC specification table. Requirements for other loads can be calculated as V _{DVDD_min} +I _{LOAD} * R _{BYP_max}							
3. In MSC_READCTRL register							

4.1.5.3 Current Consumption 1.85 V without DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = DVDD = 1.85 V. T_{OP} = 25 °C. EMU_PWRCFG_PWRCG=NODCDC. EMU_DCDCCTRL_DCDCMODE=BYPASS. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T_{OP} = 25 °C. See [Figure 5.1 EFM32PG1 Typical Application Circuit, Direct Supply, No DC-DC Converter on page 47](#).

Table 4.7. Current Consumption 1.85V without DC/DC

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 Active mode with all peripherals disabled	I _{ACTIVE}	38.4 MHz crystal, CPU running while loop from flash ¹	—	127	—	µA/MHz
		38 MHz HFRCO, CPU running Prime from flash	—	88	—	µA/MHz
		38 MHz HFRCO, CPU running while loop from flash	—	100	—	µA/MHz
		38 MHz HFRCO, CPU running CoreMark from flash	—	112	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	102	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	220	—	µA/MHz
Current consumption in EM1 Sleep mode with all peripherals disabled	I _{EM1}	38.4 MHz crystal ¹	—	61	—	µA/MHz
		38 MHz HFRCO	—	35	—	µA/MHz
		26 MHz HFRCO	—	37	—	µA/MHz
		1 MHz HFRCO	—	154	—	µA/MHz
Current consumption in EM2 Deep Sleep mode	I _{EM2}	Full RAM retention and RTCC running from LFXO	—	3.2	—	µA
		4 kB RAM retention and RTCC running from LFRCO	—	2.8	—	µA
Current consumption in EM3 Stop mode	I _{EM3}	Full RAM retention and CRYO-TIMER running from ULFRCO	—	2.7	—	µA
Current consumption in EM4H Hibernate mode	I _{EM4}	128 byte RAM retention, RTCC running from LFXO	—	1	—	µA
		128 byte RAM retention, CRYO-TIMER running from ULFRCO	—	0.62	—	µA
		128 byte RAM retention, no RTCC	—	0.62	—	µA
Current consumption in EM4S Shutoff mode	I _{EM4S}	No RAM retention, no RTCC	—	0.02	—	µA
Note:						
1. CMU_HFXOCTRL_LOWPOWER=1						

4.1.10 GPIO

Table 4.16. GPIO

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input low voltage	V _{IOIL}		—	—	IOVDD*0.3	V
Input high voltage	V _{IOIH}		IOVDD*0.7	—	—	V
Output high voltage relative to IOVDD	V _{IOOH}	Sourcing 3 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = WEAK	IOVDD*0.8	—	—	V
		Sourcing 1.2 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = WEAK	IOVDD*0.6	—	—	V
		Sourcing 20 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = STRONG	IOVDD*0.8	—	—	V
		Sourcing 8 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = STRONG	IOVDD*0.6	—	—	V
Output low voltage relative to IOVDD	V _{IOOL}	Sinking 3 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = WEAK	—	—	IOVDD*0.2	V
		Sinking 1.2 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = WEAK	—	—	IOVDD*0.4	V
		Sinking 20 mA, IOVDD \geq 3 V, DRIVESTRENGTH ¹ = STRONG	—	—	IOVDD*0.2	V
		Sinking 8 mA, IOVDD \geq 1.62 V, DRIVESTRENGTH ¹ = STRONG	—	—	IOVDD*0.4	V
Input leakage current	I _{IOLEAK}	All GPIO except LFXO pins, GPIO \leq IOVDD, T _{amb} \leq 85 °C	—	0.1	30	nA
		LFXO Pins, GPIO \leq IOVDD, T _{amb} \leq 85 °C	—	0.1	50	nA
		All GPIO except LFXO pins, GPIO \leq IOVDD, T _{AMB} > 85 °C	—	—	110	nA
		LFXO Pins, GPIO \leq IOVDD, T _{AMB} > 85 °C	—	—	250	nA
Input leakage current on 5VTOL pads above IOVDD	I _{5VTOLLEAK}	IOVDD < GPIO \leq IOVDD + 2 V	—	3.3	15	µA
I/O pin pull-up resistor	R _{PU}		30	43	65	kΩ
I/O pin pull-down resistor	R _{PD}		30	43	65	kΩ
Pulse width of pulses removed by the glitch suppression filter	t _{IOGLITCH}		20	25	35	ns

4.2.1 Supply Current

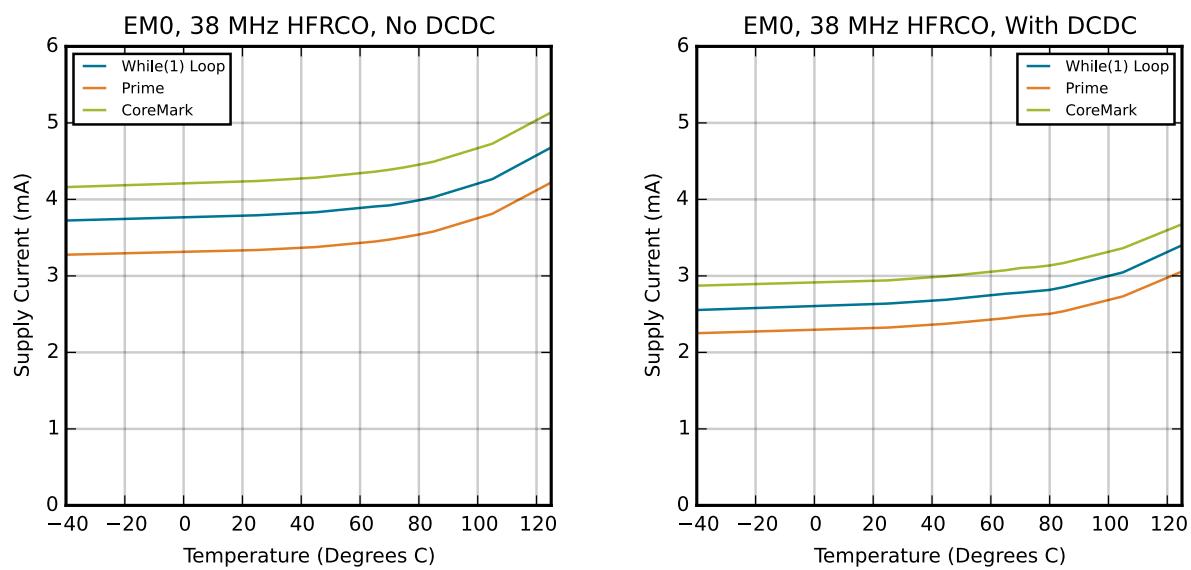


Figure 4.3. EM0 Active Mode Typical Supply Current

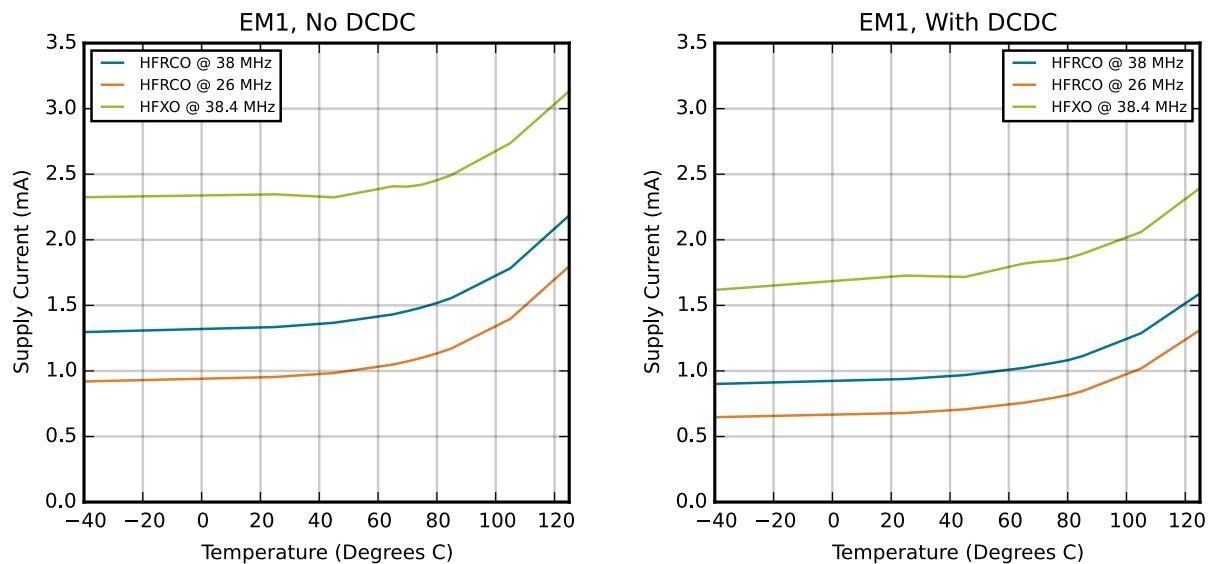
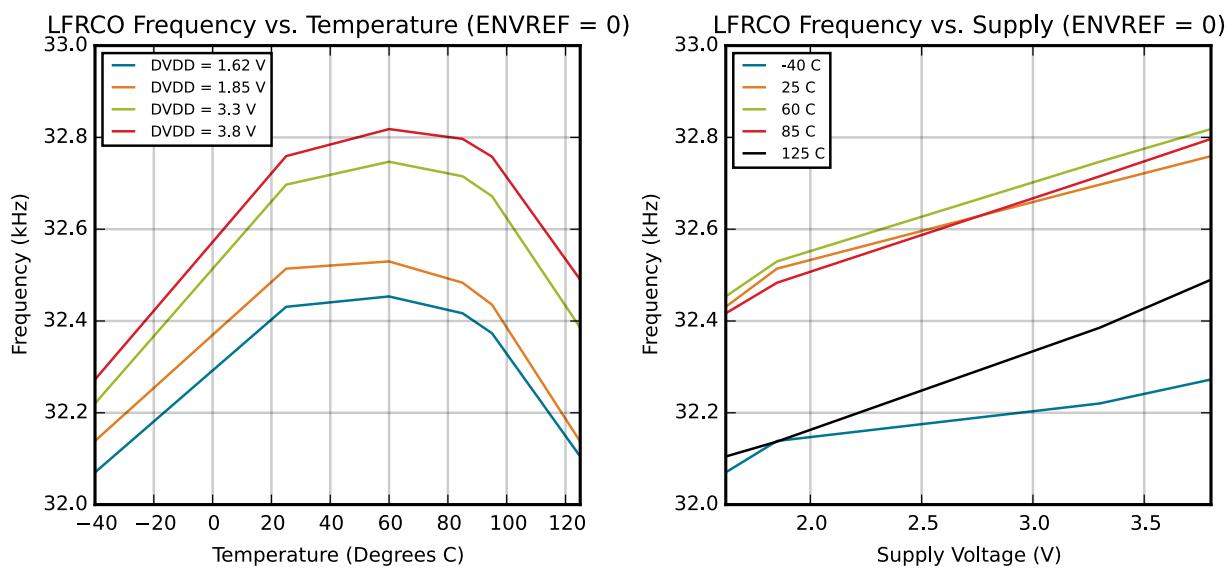
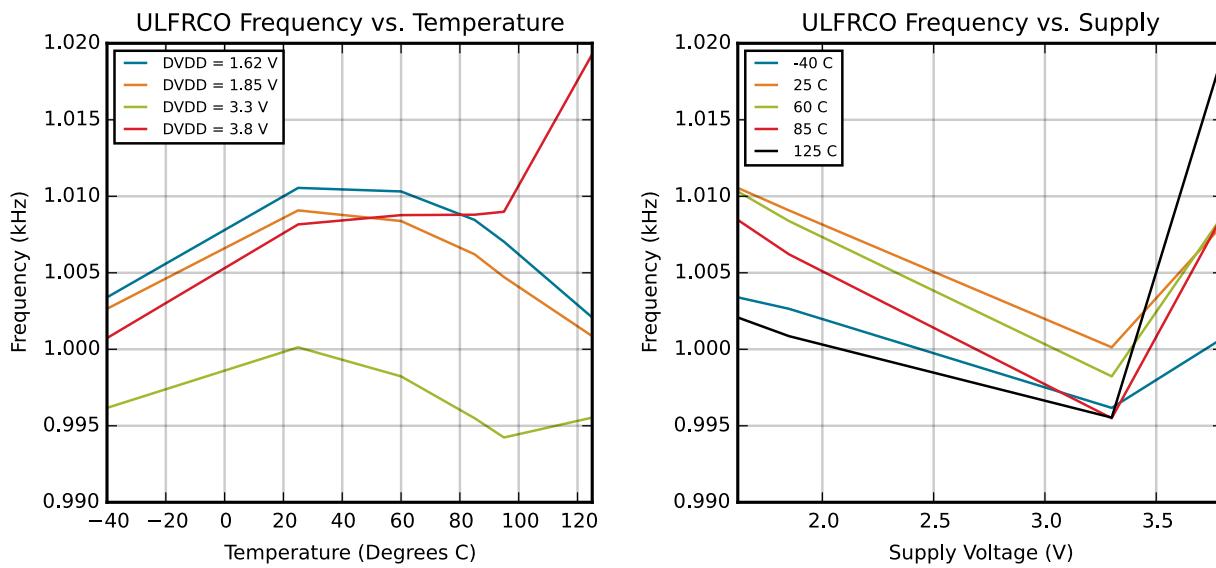


Figure 4.4. EM1 Sleep Mode Typical Supply Current

Typical supply current for EM2, EM3 and EM4H using standard software libraries from Silicon Laboratories.

**Figure 4.18. LFRCO Typical Performance at 32.768 kHz****Figure 4.19. ULFRCO Typical Performance at 1 kHz**

5. Typical Connection Diagrams

5.1 Power

Typical power supply connections for direct supply, without using the internal dc-dc converter, are shown in [Figure 5.1 EFM32PG1 Typical Application Circuit, Direct Supply, No DC-DC Converter on page 47](#).

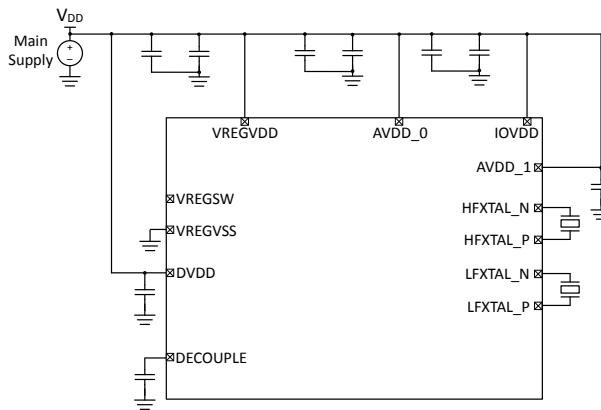


Figure 5.1. EFM32PG1 Typical Application Circuit, Direct Supply, No DC-DC Converter

A typical application circuit using the internal dc-dc converter is shown in [Figure 5.2 EFM32PG1 Typical Application Circuit Using the DC-DC Converter on page 47](#). The MCU operates from the dc-dc converter supply.

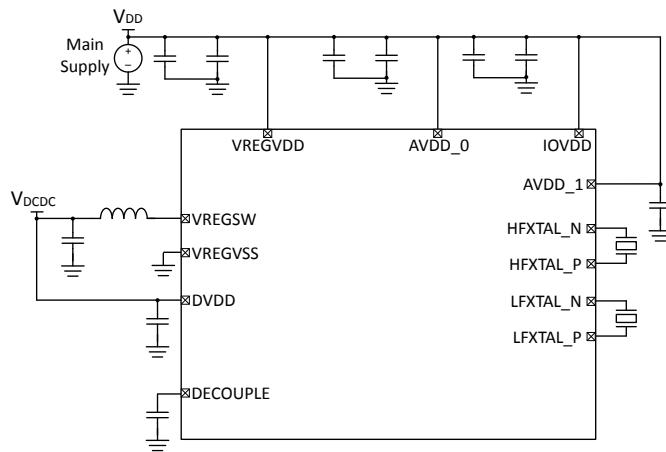


Figure 5.2. EFM32PG1 Typical Application Circuit Using the DC-DC Converter

5.2 Other Connections

Other components or connections may be required to meet the system-level requirements. Application Note AN0002: "Hardware Design Considerations" contains detailed information on these connections. Application Notes can be accessed on the Silicon Labs website (www.silabs.com/32bit-appnotes).

6. Pin Definitions

6.1 EFM32PG1 QFN48 with DC-DC Definition

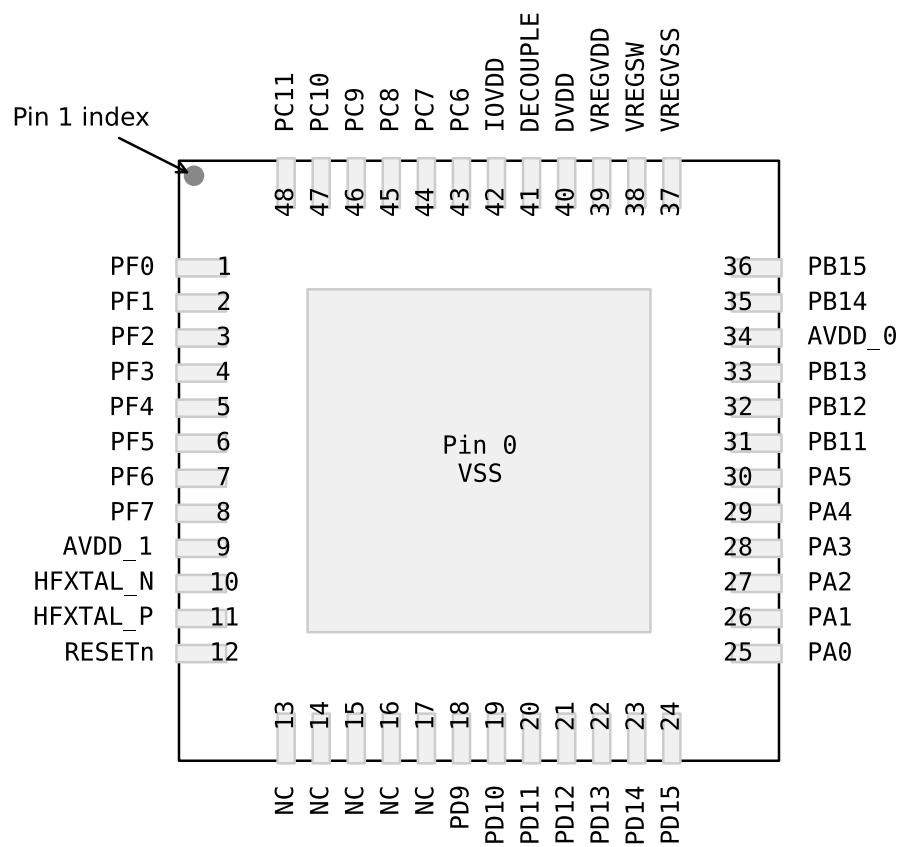


Figure 6.1. EFM32PG1 QFN48 with DC-DC Pinout

QFN48 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
28	PA3	BUSCY BUSDX	TIM0_CC0 #3 TIM0_CC1 #2 TIM0_CC2 #1 TIM0_CDTI0 #0 TIM0_CDTI1 #31 TIM0_CDTI2 #30 TIM1_CC0 #3 TIM1_CC1 #2 TIM1_CC2 #1 TIM1_CC3 #0 LE- TIM0_OUT0 #3 LE- TIM0_OUT1 #2 PCNT0_S0IN #3 PCNT0_S1IN #2	US0_TX #3 US0_RX #2 US0_CLK #1 US0_CS #0 US0_CTS #31 US0_RTS #30 US1_TX #3 US1_RX #2 US1_CLK #1 US1_CS #0 US1_CTS #31 US1_RTS #30 LEU0_TX #3 LEU0_RX #2 I2C0_SDA #3 I2C0_SCL #2	PRS_CH6 #3 PRS_CH7 #2 PRS_CH8 #1 PRS_CH9 #0 ACMP0_O #3 ACMP1_O #3 GPIO_EM4WU8
29	PA4	BUSCX BUSDY	TIM0_CC0 #4 TIM0_CC1 #3 TIM0_CC2 #2 TIM0_CDTI0 #1 TIM0_CDTI1 #0 TIM0_CDTI2 #31 TIM1_CC0 #4 TIM1_CC1 #3 TIM1_CC2 #2 TIM1_CC3 #1 LE- TIM0_OUT0 #4 LE- TIM0_OUT1 #3 PCNT0_S0IN #4 PCNT0_S1IN #3	US0_TX #4 US0_RX #3 US0_CLK #2 US0_CS #1 US0_CTS #0 US0_RTS #31 US1_TX #4 US1_RX #3 US1_CLK #2 US1_CS #1 US1_CTS #0 US1_RTS #31 LEU0_TX #4 LEU0_RX #3 I2C0_SDA #4 I2C0_SCL #3	PRS_CH6 #4 PRS_CH7 #3 PRS_CH8 #2 PRS_CH9 #1 ACMP0_O #4 ACMP1_O #4
30	PA5	BUSCY BUSDX	TIM0_CC0 #5 TIM0_CC1 #4 TIM0_CC2 #3 TIM0_CDTI0 #2 TIM0_CDTI1 #1 TIM0_CDTI2 #0 TIM1_CC0 #5 TIM1_CC1 #4 TIM1_CC2 #3 TIM1_CC3 #2 LE- TIM0_OUT0 #5 LE- TIM0_OUT1 #4 PCNT0_S0IN #5 PCNT0_S1IN #4	US0_TX #5 US0_RX #4 US0_CLK #3 US0_CS #2 US0_CTS #1 US0_RTS #0 US1_TX #5 US1_RX #4 US1_CLK #3 US1_CS #2 US1_CTS #1 US1_RTS #0 LEU0_TX #5 LEU0_RX #4 I2C0_SDA #5 I2C0_SCL #4	PRS_CH6 #5 PRS_CH7 #4 PRS_CH8 #3 PRS_CH9 #2 ACMP0_O #5 ACMP1_O #5
31	PB11	BUSCY BUSDX	TIM0_CC0 #6 TIM0_CC1 #5 TIM0_CC2 #4 TIM0_CDTI0 #3 TIM0_CDTI1 #2 TIM0_CDTI2 #1 TIM1_CC0 #6 TIM1_CC1 #5 TIM1_CC2 #4 TIM1_CC3 #3 LE- TIM0_OUT0 #6 LE- TIM0_OUT1 #5 PCNT0_S0IN #6 PCNT0_S1IN #5	US0_TX #6 US0_RX #5 US0_CLK #4 US0_CS #3 US0_CTS #2 US0_RTS #1 US1_TX #6 US1_RX #5 US1_CLK #4 US1_CS #3 US1_CTS #2 US1_RTS #1 LEU0_TX #6 LEU0_RX #5 I2C0_SDA #6 I2C0_SCL #5	PRS_CH6 #6 PRS_CH7 #5 PRS_CH8 #4 PRS_CH9 #3 ACMP0_O #6 ACMP1_O #6

QFN48 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
37	VREGVSS	Voltage regulator VSS			
38	VREGSW	DCDC regulator switching node			
39	VREGVDD	Voltage regulator VDD input			
40	DVDD	Digital power supply.			
41	DECOPPLE	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.			
42	IOVDD	Digital IO power supply.			
43	PC6	BUSAX BUSBY	TIM0_CC0 #11 TIM0_CC1 #10 TIM0_CC2 #9 TIM0_CDTI0 #8 TIM0_CDTI1 #7 TIM0_CDTI2 #6 TIM1_CC0 #11 TIM1_CC1 #10 TIM1_CC2 #9 TIM1_CC3 #8 LE- TIM0_OUT0 #11 LE- TIM0_OUT1 #10 PCNT0_S0IN #11 PCNT0_S1IN #10	US0_TX #11 US0_RX #10 US0_CLK #9 US0_CS #8 US0_CTS #7 US0_RTS #6 US1_TX #11 US1_RX #10 US1_CLK #9 US1_CS #8 US1_CTS #7 US1_RTS #6 LEU0_TX #11 LEU0_RX #10 I2C0_SDA #11 I2C0_SCL #10	CMU_CLK0 #2 PRS_CH0 #8 PRS_CH9 #11 PRS_CH10 #0 PRS_CH11 #5 ACMP0_O #11 ACMP1_O #11
44	PC7	BUSAY BUSBX	TIM0_CC0 #12 TIM0_CC1 #11 TIM0_CC2 #10 TIM0_CDTI0 #9 TIM0_CDTI1 #8 TIM0_CDTI2 #7 TIM1_CC0 #12 TIM1_CC1 #11 TIM1_CC2 #10 TIM1_CC3 #9 LE- TIM0_OUT0 #12 LE- TIM0_OUT1 #11 PCNT0_S0IN #12 PCNT0_S1IN #11	US0_TX #12 US0_RX #11 US0_CLK #10 US0_CS #9 US0_CTS #8 US0_RTS #7 US1_TX #12 US1_RX #11 US1_CLK #10 US1_CS #9 US1_CTS #8 US1_RTS #7 LEU0_TX #12 LEU0_RX #11 I2C0_SDA #12 I2C0_SCL #11	CMU_CLK1 #2 PRS_CH0 #9 PRS_CH9 #12 PRS_CH10 #1 PRS_CH11 #0 ACMP0_O #12 ACMP1_O #12
45	PC8	BUSAX BUSBY	TIM0_CC0 #13 TIM0_CC1 #12 TIM0_CC2 #11 TIM0_CDTI0 #10 TIM0_CDTI1 #9 TIM0_CDTI2 #8 TIM1_CC0 #13 TIM1_CC1 #12 TIM1_CC2 #11 TIM1_CC3 #10 LE- TIM0_OUT0 #13 LE- TIM0_OUT1 #12 PCNT0_S0IN #13 PCNT0_S1IN #12	US0_TX #13 US0_RX #12 US0_CLK #11 US0_CS #10 US0_CTS #9 US0_RTS #8 US1_TX #13 US1_RX #12 US1_CLK #11 US1_CS #10 US1_CTS #9 US1_RTS #8 LEU0_TX #13 LEU0_RX #12 I2C0_SDA #13 I2C0_SCL #12	PRS_CH0 #10 PRS_CH9 #13 PRS_CH10 #2 PRS_CH11 #1 ACMP0_O #13 ACMP1_O #13

QFN32 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
15	PD14	BUSCX BUSDY	TIMO_CC0 #22 TIMO_CC1 #21 TIMO_CC2 #20 TIMO_CDTI0 #19 TIMO_CDTI1 #18 TIMO_CDTI2 #17 TIM1_CC0 #22 TIM1_CC1 #21 TIM1_CC2 #20 TIM1_CC3 #19 LE- Timo_OUT0 #22 LE- Timo_OUT1 #21 PCNT0_S0IN #22 PCNT0_S1IN #21	US0_TX #22 US0_RX #21 US0_CLK #20 US0_CS #19 US0_CTS #18 US0_RTS #17 US1_TX #22 US1_RX #21 US1_CLK #20 US1_CS #19 US1_CTS #18 US1_RTS #17 LEU0_TX #22 LEU0_RX #21 I2C0_SDA #22 I2C0_SCL #21	CMU_CLK0 #5 PRS_CH3 #13 PRS_CH4 #5 PRS_CH5 #4 PRS_CH6 #16 ACMP0_O #22 ACMP1_O #22 GPIO_EM4WU4
16	PD15	BUSCY BUSDX	TIMO_CC0 #23 TIMO_CC1 #22 TIMO_CC2 #21 TIMO_CDTI0 #20 TIMO_CDTI1 #19 TIMO_CDTI2 #18 TIM1_CC0 #23 TIM1_CC1 #22 TIM1_CC2 #21 TIM1_CC3 #20 LE- Timo_OUT0 #23 LE- Timo_OUT1 #22 PCNT0_S0IN #23 PCNT0_S1IN #22	US0_TX #23 US0_RX #22 US0_CLK #21 US0_CS #20 US0_CTS #19 US0_RTS #18 US1_TX #23 US1_RX #22 US1_CLK #21 US1_CS #20 US1_CTS #19 US1_RTS #18 LEU0_TX #23 LEU0_RX #22 I2C0_SDA #23 I2C0_SCL #22	CMU_CLK1 #5 PRS_CH3 #14 PRS_CH4 #6 PRS_CH5 #5 PRS_CH6 #17 ACMP0_O #23 ACMP1_O #23 DBG_SWO #2
17	PA0	ADC0_EXTN BUSCX BUSDY	TIMO_CC0 #0 TIMO_CC1 #31 TIMO_CC2 #30 TIMO_CDTI0 #29 TIMO_CDTI1 #28 TIMO_CDTI2 #27 TIM1_CC0 #0 TIM1_CC1 #31 TIM1_CC2 #30 TIM1_CC3 #29 LE- Timo_OUT0 #0 LE- Timo_OUT1 #31 PCNT0_S0IN #0 PCNT0_S1IN #31	US0_TX #0 US0_RX #31 US0_CLK #30 US0_CS #29 US0_CTS #28 US0_RTS #27 US1_TX #0 US1_RX #31 US1_CLK #30 US1_CS #29 US1_CTS #28 US1_RTS #27 LEU0_TX #0 LEU0_RX #31 I2C0_SDA #0 I2C0_SCL #31	CMU_CLK1 #0 PRS_CH6 #0 PRS_CH7 #10 PRS_CH8 #9 PRS_CH9 #8 ACMP0_O #0 ACMP1_O #0
18	PA1	ADC0_EXTP BUSCY BUSDX	TIMO_CC0 #1 TIMO_CC1 #0 TIMO_CC2 #31 TIMO_CDTI0 #30 TIMO_CDTI1 #29 TIMO_CDTI2 #28 TIM1_CC0 #1 TIM1_CC1 #0 TIM1_CC2 #31 TIM1_CC3 #30 LE- Timo_OUT0 #1 LE- Timo_OUT1 #0 PCNT0_S0IN #1 PCNT0_S1IN #0	US0_TX #1 US0_RX #0 US0_CLK #31 US0_CS #30 US0_CTS #29 US0_RTS #28 US1_TX #1 US1_RX #0 US1_CLK #31 US1_CS #30 US1_CTS #29 US1_RTS #28 LEU0_RX #1 LEU0_RX #0 I2C0_SDA #1 I2C0_SCL #0	CMU_CLK0 #0 PRS_CH6 #1 PRS_CH7 #0 PRS_CH8 #10 PRS_CH9 #9 ACMP0_O #1 ACMP1_O #1

QFN32 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
16	PD15	BUSCY BUSDX	TIMO_CC0 #23 TIMO_CC1 #22 TIMO_CC2 #21 TIMO_CDTI0 #20 TIMO_CDTI1 #19 TIMO_CDTI2 #18 TIM1_CC0 #23 TIM1_CC1 #22 TIM1_CC2 #21 TIM1_CC3 #20 LE- TIMO_OUT0 #23 LE- TIMO_OUT1 #22 PCNT0_S0IN #23 PCNT0_S1IN #22	US0_TX #23 US0_RX #22 US0_CLK #21 US0_CS #20 US0_CTS #19 US0_RTS #18 US1_TX #23 US1_RX #22 US1_CLK #21 US1_CS #20 US1_CTS #19 US1_RTS #18 LEU0_TX #23 LEU0_RX #22 I2C0_SDA #23 I2C0_SCL #22	CMU_CLK1 #5 PRS_CH3 #14 PRS_CH4 #6 PRS_CH5 #5 PRS_CH6 #17 ACMP0_O #23 ACMP1_O #23 DBG_SWO #2
17	PA0	ADC0_EXTN BUSCX BUSDY	TIMO_CC0 #0 TIMO_CC1 #31 TIMO_CC2 #30 TIMO_CDTI0 #29 TIMO_CDTI1 #28 TIMO_CDTI2 #27 TIM1_CC0 #0 TIM1_CC1 #31 TIM1_CC2 #30 TIM1_CC3 #29 LE- TIMO_OUT0 #0 LE- TIMO_OUT1 #31 PCNT0_S0IN #0 PCNT0_S1IN #31	US0_TX #0 US0_RX #31 US0_CLK #30 US0_CS #29 US0_CTS #28 US0_RTS #27 US1_TX #0 US1_RX #31 US1_CLK #30 US1_CS #29 US1_CTS #28 US1_RTS #27 LEU0_TX #0 LEU0_RX #31 I2C0_SDA #0 I2C0_SCL #31	CMU_CLK1 #0 PRS_CH6 #0 PRS_CH7 #10 PRS_CH8 #9 PRS_CH9 #8 ACMP0_O #0 ACMP1_O #0
18	PA1	ADC0_EXTP BUSCY BUSDX	TIMO_CC0 #1 TIMO_CC1 #0 TIMO_CC2 #31 TIMO_CDTI0 #30 TIMO_CDTI1 #29 TIMO_CDTI2 #28 TIM1_CC0 #1 TIM1_CC1 #0 TIM1_CC2 #31 TIM1_CC3 #30 LE- TIMO_OUT0 #1 LE- TIMO_OUT1 #0 PCNT0_S0IN #1 PCNT0_S1IN #0	US0_TX #1 US0_RX #0 US0_CLK #31 US0_CS #30 US0_CTS #29 US0_RTS #28 US1_TX #1 US1_RX #0 US1_CLK #31 US1_CS #30 US1_CTS #29 US1_RTS #28 LEU0_RX #1 LEU0_RX #0 I2C0_SDA #1 I2C0_SCL #0	CMU_CLK0 #0 PRS_CH6 #1 PRS_CH7 #0 PRS_CH8 #10 PRS_CH9 #9 ACMP0_O #1 ACMP1_O #1
19	PB11	BUSCY BUSDX	TIMO_CC0 #6 TIMO_CC1 #5 TIMO_CC2 #4 TIMO_CDTI0 #3 TIMO_CDTI1 #2 TIMO_CDTI2 #1 TIM1_CC0 #6 TIM1_CC1 #5 TIM1_CC2 #4 TIM1_CC3 #3 LE- TIMO_OUT0 #6 LE- TIMO_OUT1 #5 PCNT0_S0IN #6 PCNT0_S1IN #5	US0_TX #6 US0_RX #5 US0_CLK #4 US0_CS #3 US0_CTS #2 US0_RTS #1 US1_TX #6 US1_RX #5 US1_CLK #4 US1_CS #3 US1_CTS #2 US1_RTS #1 LEU0_RX #6 LEU0_RX #5 I2C0_SDA #6 I2C0_SCL #5	PRS_CH6 #6 PRS_CH7 #5 PRS_CH8 #4 PRS_CH9 #3 ACMP0_O #6 ACMP1_O #6

6.3.1 EFM32PG1 QFN32 with DC-DC GPIO Overview

The GPIO pins are organized as 16-bit ports indicated by letters (A, B, C...), and the individual pins on each port are indicated by a number from 15 down to 0.

Table 6.6. QFN32 with DC-DC GPIO Pinout

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	-	-	-	-	-	-	-	-	-	-	-	-	-	-	PA1	PA0
Port B	PB15	PB14	PB13 (5V)	PB12 (5V)	PB11 (5V)	-	-	-	-	-	-	-	-	-	-	-
Port C	-	-	-	-	PC11 (5V)	PC10 (5V)	-	-	-	-	-	-	-	-	-	-
Port D	PD15 (5V)	PD14 (5V)	PD13 (5V)	PD12 (5V)	PD11 (5V)	PD10 (5V)	PD9 (5V)	-	-	-	-	-	-	-	-	-
Port F	-	-	-	-	-	-	-	-	-	-	-	-	PF3 (5V)	PF2 (5V)	PF1 (5V)	PF0 (5V)

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The pins PB13, PB12, PB11, PD15, PD14, and PD13 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

Alternate	LOCATION									
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description	
GPIO_EM4WU12	0: PC10								Pin can be used to wake the system up from EM4	
I2C0_SCL	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	I2C0 Serial Clock Line input / output.	
I2C0_SDA	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	I2C0 Serial Data input / output.	
LETIM0_OUT0	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	Low Energy Timer LETIM0, output channel 0.	
LETIM0_OUT1	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	Low Energy Timer LETIM0, output channel 1.	
LEU0_RX	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	LEUART0 Receive input.	
LEU0_TX	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	LEUART0 Transmit output. Also used as receive input in half duplex communication.	
LFXTAL_N	0: PB14								Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.	
LFXTAL_P	0: PB15								Low Frequency Crystal (typically 32.768 kHz) positive pin.	
PCNT0_S0IN	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	Pulse Counter PCNT0 input number 0.	
PCNT0_S1IN	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	Pulse Counter PCNT0 input number 1.	
PRS_CH0	0: PF0 1: PF1 2: PF2 3: PF3	4: PF4 5: PF5 6: PF6 7: PF7	8: PC6 9: PC7 10: PC8 11: PC9	12: PC10 13: PC11					Peripheral Reflex System PRS, channel 0.	

Table 6.9. ACMP1 Bus and Pin Mapping

APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	Bus
PB15	PB15							CH31
PB14		PB14						CH30
PB13	PB13	PB12	PB12					CH29
PB12	PB11	PB11						CH28
								CH27
								CH26
								CH25
								CH24
								CH23
				PF7	PF7			CH22
				PF6		PF6		CH21
				PF5	PF5			CH20
				PF4		PF4		CH19
				PF3	PF3			CH18
				PF2		PF2		CH17
				PF1	PF1			CH16
				PF0		PF0		CH15
								CH14
								CH13
PA5	PA5	PA4						CH12
PA4	PA3	PA3	PC11	PC11				CH11
PA2		PA2	PC10	PC10		PC10	CH10	CH10
PA1	PA1		PC9	PC9			CH9	CH9
PA0		PA0	PC8		PC8		CH8	CH8
PD15	PD15	PD15	PC6	PC7	PC7		CH7	CH7
PD14		PD14				PC6	CH6	CH6
PD13	PD13						CH5	CH5
PD12		PD12					CH4	CH4
PD11	PD11						CH3	CH3
PD10		PD10					CH2	CH2
PD9	PD9	PD9					CH1	CH1
							CH0	CH0

8.2 QFN32 PCB Land Pattern

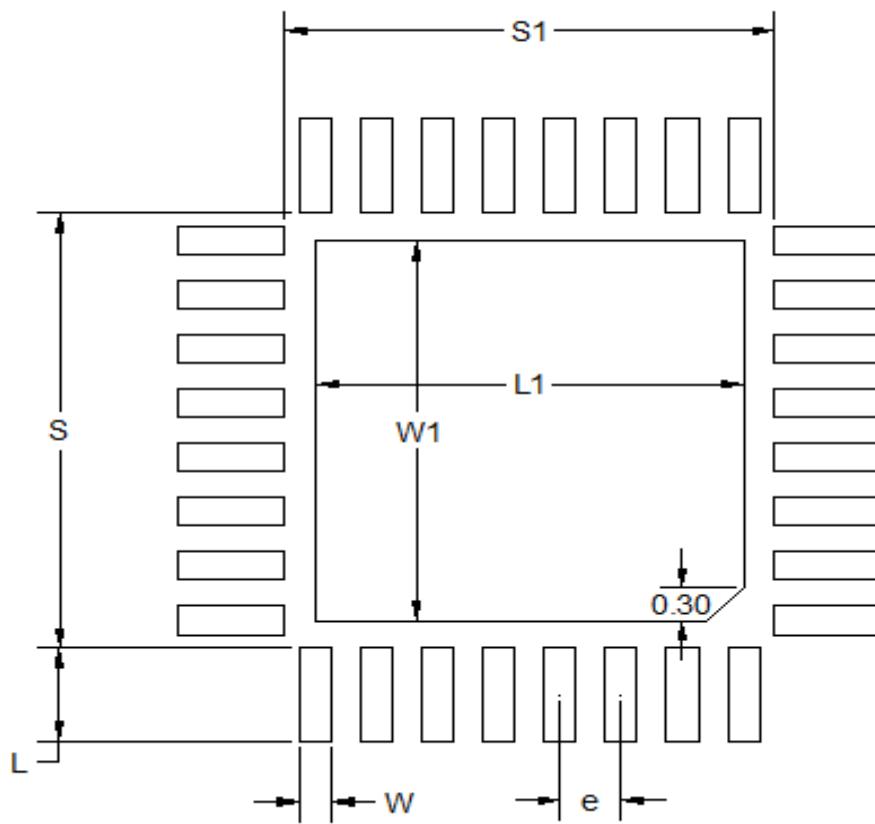


Figure 8.2. QFN32 PCB Land Pattern Drawing

9.7 Revision 0.1

Initial release.

Table of Contents

1. Feature List	1
2. Ordering Information	2
3. System Overview	3
3.1 Introduction.	3
3.2 Power	4
3.2.1 Energy Management Unit (EMU)	4
3.2.2 DC-DC Converter	4
3.3 General Purpose Input/Output (GPIO).	4
3.4 Clocking.	4
3.4.1 Clock Management Unit (CMU)	4
3.4.2 Internal and External Oscillators	4
3.5 Counters/Timers and PWM	5
3.5.1 Timer/Counter (TIMER)	5
3.5.2 Real Time Counter and Calendar (RTCC)	5
3.5.3 Low Energy Timer (LETIMER)	5
3.5.4 Ultra Low Power Wake-up Timer (CRYOTIMER)	5
3.5.5 Pulse Counter (PCNT)	5
3.5.6 Watchdog Timer (WDOG)	5
3.6 Communications and Other Digital Peripherals	5
3.6.1 Universal Synchronous/Asynchronous Receiver/Transmitter (USART)	5
3.6.2 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)	5
3.6.3 Inter-Integrated Circuit Interface (I ² C)	6
3.6.4 Peripheral Reflex System (PRS)	6
3.7 Security Features.	6
3.7.1 GPCRC (General Purpose Cyclic Redundancy Check)	6
3.7.2 Crypto Accelerator (CRYPTO)	6
3.8 Analog	6
3.8.1 Analog Port (APORT)	6
3.8.2 Analog Comparator (ACMP)	6
3.8.3 Analog to Digital Converter (ADC)	6
3.8.4 Digital to Analog Current Converter (IDAC)	7
3.9 Reset Management Unit (RMU)	7
3.10 Core and Memory	7
3.10.1 Processor Core	7
3.10.2 Memory System Controller (MSC)	7
3.10.3 Linked Direct Memory Access Controller (LDMA)	7
3.11 Memory Map	8
3.12 Configuration Summary	9
4. Electrical Specifications	10
4.1 Electrical Characteristics	10
4.1.1 Absolute Maximum Ratings	10