

Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	40MHz
Connectivity	I²C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	32
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.85V ~ 3.8V
Data Converters	A/D 24x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-VFQFN Exposed Pad
Supplier Device Package	48-QFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32pg1b200f128gm48-b0r

4.1.4 DC-DC Converter

Test conditions: $L_{DCDC}=4.7\ \mu H$ (Murata LQH3NPN4R7MM0L), $C_{DCDC}=1.0\ \mu F$ (Murata GRM188R71A105KA61D), $V_{DCDC_I}=3.3\ V$, $V_{DCDC_O}=1.8\ V$, $I_{DCDC_LOAD}=50\ mA$, Heavy Drive configuration, $F_{DCDC_LN}=7\ MHz$, unless otherwise indicated.

Table 4.4. DC-DC Converter

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input voltage range	V_{DCDC_I}	Bypass mode, $I_{DCDC_LOAD} = 50\ mA$	1.85	—	$V_{VREGVDD_MAX}$	V
		Low noise (LN) mode, 1.8 V output, $I_{DCDC_LOAD} = 100\ mA$, or Low power (LP) mode, 1.8 V output, $I_{DCDC_LOAD} = 10\ mA$	2.4	—	$V_{VREGVDD_MAX}$	V
		Low noise (LN) mode, 1.8 V output, $I_{DCDC_LOAD} = 200\ mA$	2.6	—	$V_{VREGVDD_MAX}$	V
Output voltage programmable range ¹	V_{DCDC_O}		1.8	—	$V_{VREGVDD}$	V
Regulation DC Accuracy	ACC_{DC}	Low noise (LN) mode, 1.8 V target output	1.7	—	1.9	V
Regulation Window ²	WIN_{REG}	Low power (LP) mode, $LPCMPBIAS^3 = 0$, 1.8 V target output, $I_{DCDC_LOAD} \leq 75\ \mu A$	1.63	—	2.2	V
		Low power (LP) mode, $LPCMPBIAS^3 = 3$, 1.8 V target output, $I_{DCDC_LOAD} \leq 10\ mA$	1.63	—	2.1	V
Steady-state output ripple	V_R		—	3	—	mVpp
Output voltage under/overshoot	V_{ov}	CCM Mode ($LNFORCECCM^3 = 1$), Load changes between 0 mA and 100 mA	—	—	150	mV
		DCM Mode ($LNFORCECCM^3 = 0$), Load changes between 0 mA and 10 mA	—	—	150	mV
		Overshoot during LP to LN CCM/DCM mode transitions compared to DC level in LN mode	—	200	—	mV
		Undershoot during BYP/LP to LN CCM ($LNFORCECCM^3 = 1$) mode transitions compared to DC level in LN mode	—	50	—	mV
		Undershoot during BYP/LP to LN DCM ($LNFORCECCM^3 = 0$) mode transitions compared to DC level in LN mode	—	125	—	mV
DC line regulation	V_{REG}	Input changes between $V_{VREGVDD_MAX}$ and 2.4 V	—	0.1	—	%
DC load regulation	I_{REG}	Load changes between 0 mA and 100 mA in CCM mode	—	0.1	—	%

4.1.5 Current Consumption

4.1.5.1 Current Consumption 3.3 V without DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = DVDD = 3.3 V. T_{OP} = 25 °C. EMU_PWRCFG_PWRCG=NODCDC. EMU_DCDCCTRL_DCDCMODE=BYPASS. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T_{OP} = 25 °C. See [Figure 5.1 EFM32PG1 Typical Application Circuit, Direct Supply, No DC-DC Converter on page 47](#).

Table 4.5. Current Consumption 3.3V without DC/DC

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 Active mode with all peripherals disabled	I _{ACTIVE}	38.4 MHz crystal, CPU running while loop from flash ¹	—	127	—	µA/MHz
		38 MHz HFRCO, CPU running Prime from flash	—	88	—	µA/MHz
		38 MHz HFRCO, CPU running while loop from flash	—	100	105	µA/MHz
		38 MHz HFRCO, CPU running CoreMark from flash	—	112	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	102	106	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	222	350	µA/MHz
Current consumption in EM1 Sleep mode with all peripherals disabled	I _{EM1}	38.4 MHz crystal ¹	—	61	—	µA/MHz
		38 MHz HFRCO	—	35	38	µA/MHz
		26 MHz HFRCO	—	37	41	µA/MHz
		1 MHz HFRCO	—	157	275	µA/MHz
Current consumption in EM2 Deep Sleep mode.	I _{EM2}	Full RAM retention and RTCC running from LFXO	—	3.3	—	µA
		4 kB RAM retention and RTCC running from LFRCO	—	3	6.3	µA
Current consumption in EM3 Stop mode	I _{EM3}	Full RAM retention and CRYO-TIMER running from ULFRCO	—	2.8	6	µA
Current consumption in EM4H Hibernate mode	I _{EM4}	128 byte RAM retention, RTCC running from LFXO	—	1.1	—	µA
		128 byte RAM retention, CRYO-TIMER running from ULFRCO	—	0.65	—	µA
		128 byte RAM retention, no RTCC	—	0.65	1.3	µA
Current consumption in EM4S Shutoff mode	I _{EM4S}	no RAM retention, no RTCC	—	0.04	0.11	µA
Note:						
1. CMU_HFXOCTRL_LOWPPOWER=1						

4.1.8.2 HFXO

Table 4.11. HFXO

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Crystal Frequency	f_{HFXO}		38	38.4	40	MHz
Supported crystal equivalent series resistance (ESR)	ESR_{HFXO}	Crystal frequency 38.4 MHz	—	—	60	Ω
Supported range of crystal load capacitance ¹	C_{HFXO_CL}		6	—	12	pF
On-chip tuning cap range ²	C_{HFXO_T}	On each of HFXTAL_N and HFXTAL_P pins	9	20	25	pF
On-chip tuning capacitance step	SS_{HFXO}		—	0.04	—	pF
Startup time	t_{HFXO}	38.4 MHz, ESR = 50 Ω , C_L = 10 pF	—	300	—	μs
Frequency Tolerance for the crystal	FT_{HFXO}	38.4 MHz, ESR = 50 Ω , CL = 10 pF	-40	—	40	ppm
Note:						
1. Total load capacitance as seen by the crystal						
2. The effective load capacitance seen by the crystal will be $C_{HFXO_T} / 2$. This is because each XTAL pin has a tuning cap and the two caps will be seen in series by the crystal.						

4.1.8.3 LFRCO

Table 4.12. LFRCO

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit	
Oscillation frequency	f_{LFRCO}	ENVREF = 1 in CMU_LFRCOCTRL, $T_{AMB} \leq 85^{\circ}\text{C}$	30.474	32.768	34.243	kHz	
		ENVREF = 1 in CMU_LFRCOCTRL, $T_{AMB} > 85^{\circ}\text{C}$	30.474	—	39.7	kHz	
		ENVREF = 0 in CMU_LFRCOCTRL	30.474	32.768	33.915	kHz	
Startup time	t_{LFRCO}		—	500	—	μs	
Current consumption ¹	I_{LFRCO}	ENVREF = 1 in CMU_LFRCOCTRL	—	342	—	nA	
		ENVREF = 0 in CMU_LFRCOCTRL	—	494	—	nA	
Note:							
1. Block is supplied by AVDD if ANASW = 0, or DVDD if ANASW=1 in EMU_PWRCTRL register							

4.1.12 ADC

Table 4.18. ADC

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Resolution	V _{RESOLUTION}		6	—	12	Bits
Input voltage range	V _{ADCIN}	Single ended	0	—	2*V _{REF}	V
		Differential	-V _{REF}	—	V _{REF}	V
Input range of external reference voltage, single ended and differential	V _{ADCREFIN_P}		1	—	V _{AVDD}	V
Power supply rejection ¹	PSRR _{ADC}	At DC	—	80	—	dB
Analog input common mode rejection ratio	CMRR _{ADC}	At DC	—	80	—	dB
Current from all supplies, using internal reference buffer. Continous operation. WARMUPMODE ² = KEEPADC-WARM	I _{ADC_CONTINUOUS_LP}	1 Msps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	301	350	µA
		250 ksps / 4 MHz ADCCLK, BIASPROG = 6, GPBIASACC = 1 ³	—	149	—	µA
		62.5 ksps / 1 MHz ADCCLK, BIASPROG = 15, GPBIASACC = 1 ³	—	91	—	µA
Current from all supplies, using internal reference buffer. Duty-cycled operation. WARMUPMODE ² = NORMAL	I _{ADC_NORMAL_LP}	35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	51	—	µA
		5 ksps / 16 MHz ADCCLK BIASPROG = 0, GPBIASACC = 1 ³	—	9	—	µA
Current from all supplies, using internal reference buffer. Duty-cycled operation. AWARMUPMODE ² = KEEPINSTANDBY or KEEPIN-SLOWACC	I _{ADC_STANDBY_LP}	125 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	117	—	µA
		35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	79	—	µA
Current from all supplies, using internal reference buffer. Continous operation. WARMUPMODE ² = KEEPADC-WARM	I _{ADC_CONTINUOUS_HP}	1 Msps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	345	—	µA
		250 ksps / 4 MHz ADCCLK, BIASPROG = 6, GPBIASACC = 0 ³	—	191	—	µA
		62.5 ksps / 1 MHz ADCCLK, BIASPROG = 15, GPBIASACC = 0 ³	—	132	—	µA

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current from all supplies, using internal reference buffer. Duty-cycled operation. WARMUPMODE ² = NORMAL	I _{ADC_NORMAL_HP}	35 kspS / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ₃	—	102	—	µA
		5 kspS / 16 MHz ADCCLK BIASPROG = 0, GPBIASACC = 0 ₃	—	17	—	µA
Current from all supplies, using internal reference buffer. Duty-cycled operation. AWARMUPMODE ² = KEEP-INSTANDBY or KEEPIN-SLOWACC	I _{ADC_STAND-BY_HP}	125 kspS / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ₃	—	162	—	µA
		35 kspS / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ₃	—	123	—	µA
Current from HPERCLK	I _{ADC_CLK}	HPERCLK = 16 MHz	—	140	—	µA
ADC Clock Frequency	f _{ADCCLK}		—	—	16	MHz
Throughput rate	f _{ADCRATE}		—	—	1	MspS
Conversion time ⁴	t _{ADCCONV}	6 bit	—	7	—	cycles
		8 bit	—	9	—	cycles
		12 bit	—	13	—	cycles
Startup time of reference generator and ADC core	t _{ADCSTART}	WARMUPMODE ² = NORMAL	—	—	5	µs
		WARMUPMODE ² = KEEPIN-STANDBY	—	—	2	µs
		WARMUPMODE ² = KEEPINSLOWACC	—	—	1	µs
SNDR at 1MspS and f _{in} = 10kHz	SNDR _{ADC}	Internal reference, 2.5 V full-scale, differential (-1.25, 1.25)	58	67	—	dB
		vrefp_in = 1.25 V direct mode with 2.5 V full-scale, differential	—	68	—	dB
Spurious-Free Dynamic Range (SFDR)	SFDR _{ADC}	1 MSamples/s, 10 kHz full-scale sine wave	—	75	—	dB
Input referred ADC noise, rms	V _{REF_NOISE}	Including quantization noise and distortion	—	380	—	µV
Offset Error	V _{ADCOFFSETERR}		-3	0.25	3	LSB
Gain error in ADC	V _{ADC_GAIN}	Using internal reference	—	-0.2	5	%
		Using external reference	—	-1	—	%
Differential non-linearity (DNL)	DNL _{ADC}	12 bit resolution, No Missing Codes	-1	—	2	LSB
Integral non-linearity (INL), End point method	INL _{ADC}	12 bit resolution	-6	—	6	LSB
Temperature Sensor Slope	V _{TS_SLOPE}		—	-1.84	—	mV/°C

4.1.14 Analog Comparator (ACMP)

Table 4.20. ACMP

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input voltage range	V _{ACMPIN}	ACMPVDD = ACMPn_CTRL_PWRSEL ¹	0	—	V _{ACMPVDD}	V
Supply Voltage	V _{ACMPVDD}	BIASPROG ² ≤ 0x10 or FULL-BIAS ² = 0	1.85	—	V _{VREGVDD_MAX}	V
		0x10 < BIASPROG ² ≤ 0x20 and FULLBIAS ² = 1	2.1	—	V _{VREGVDD_MAX}	V
Active current not including voltage reference	I _{ACMP}	BIASPROG ² = 1, FULLBIAS ² = 0	—	50	—	nA
		BIASPROG ² = 0x10, FULLBIAS ² = 0	—	306	—	nA
		BIASPROG ² = 0x20, FULLBIAS ² = 1	—	74	95	μA
Current consumption of internal voltage reference	I _{ACMPREF}	VLP selected as input using 2.5 V Reference / 4 (0.625 V)	—	50	—	nA
		VLP selected as input using VDD	—	20	—	nA
		VBDIV selected as input using 1.25 V reference / 1	—	4.1	—	μA
		VADIV selected as input using VDD/1	—	2.4	—	μA
Hysteresis (V _{CM} = 1.25 V, BIASPROG ² = 0x10, FULL-BIAS ² = 1)	V _{ACMPHYST}	HYSTSEL ³ = HYST0	-1.75	0	1.75	mV
		HYSTSEL ³ = HYST1	10	18	26	mV
		HYSTSEL ³ = HYST2	21	32	46	mV
		HYSTSEL ³ = HYST3	27	44	63	mV
		HYSTSEL ³ = HYST4	32	55	80	mV
		HYSTSEL ³ = HYST5	38	65	100	mV
		HYSTSEL ³ = HYST6	43	77	121	mV
		HYSTSEL ³ = HYST7	47	86	148	mV
		HYSTSEL ³ = HYST8	-4	0	4	mV
		HYSTSEL ³ = HYST9	-27	-18	-10	mV
		HYSTSEL ³ = HYST10	-47	-32	-18	mV
		HYSTSEL ³ = HYST11	-64	-43	-27	mV
		HYSTSEL ³ = HYST12	-78	-54	-32	mV
		HYSTSEL ³ = HYST13	-93	-64	-37	mV
		HYSTSEL ³ = HYST14	-113	-74	-42	mV
		HYSTSEL ³ = HYST15	-135	-85	-47	mV

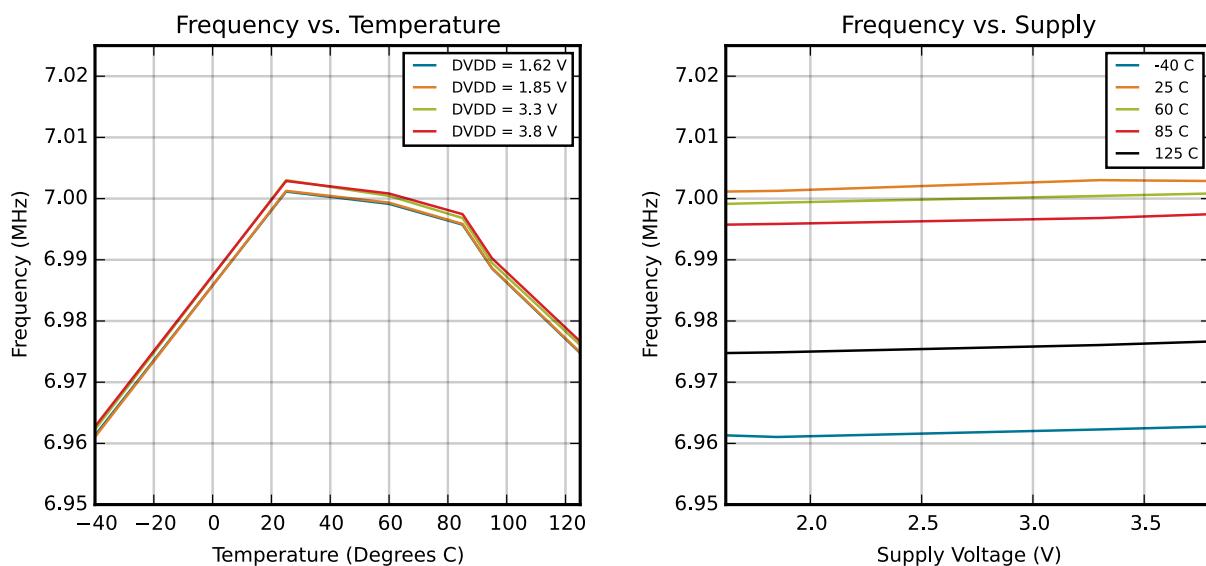


Figure 4.14. HFRCO and AUXHFRCO Typical Performance at 7 MHz

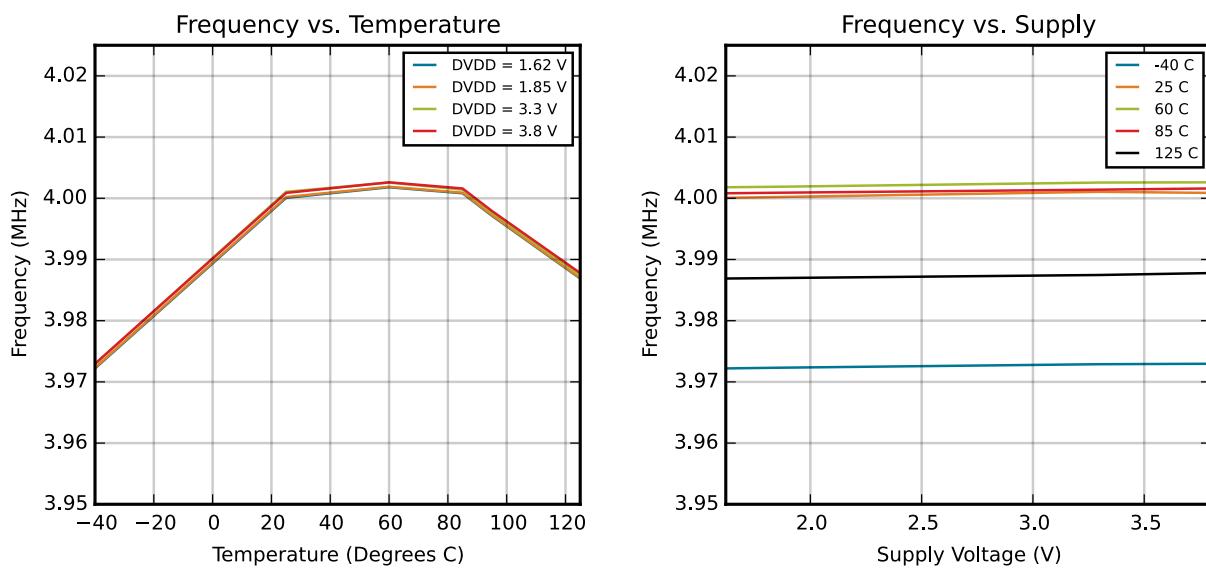


Figure 4.15. HFRCO and AUXHFRCO Typical Performance at 4 MHz

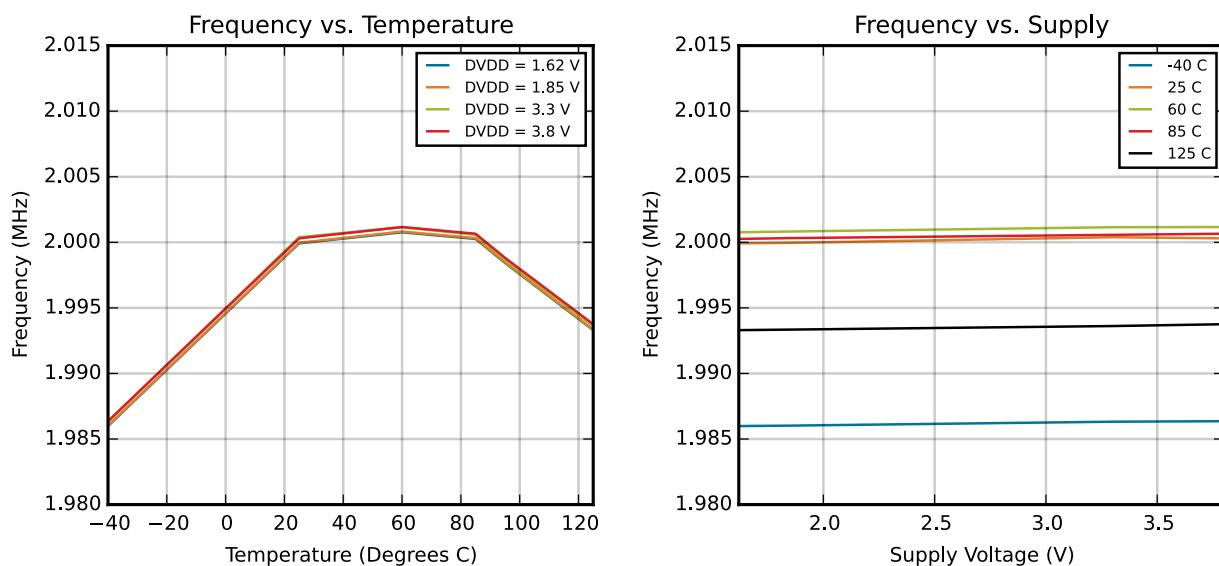


Figure 4.16. HFRCO and AUXHFRCO Typical Performance at 2 MHz

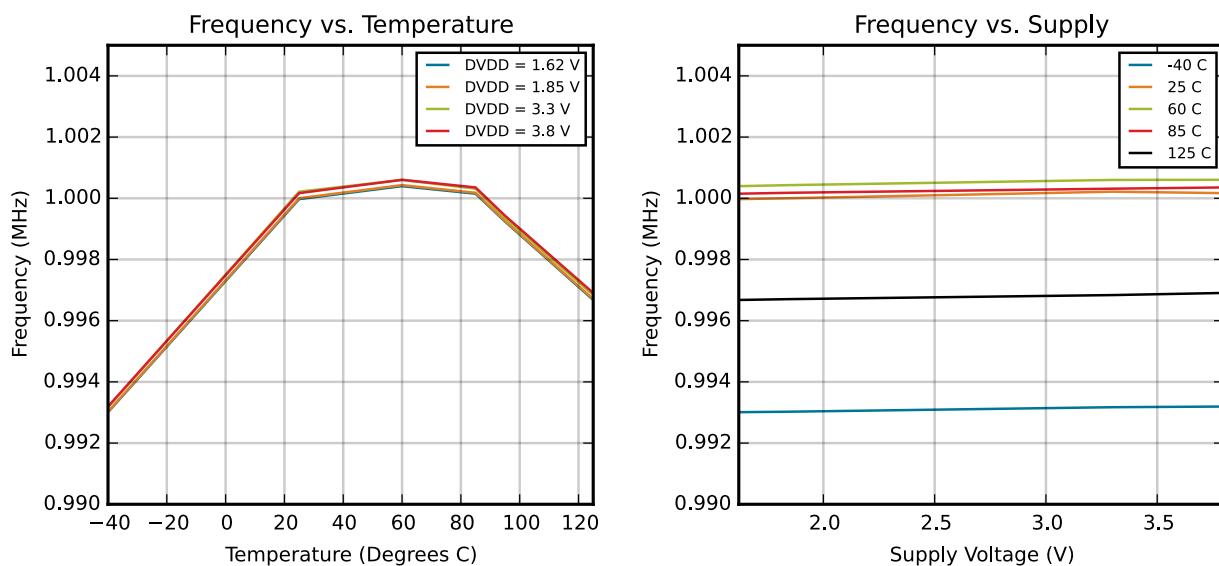
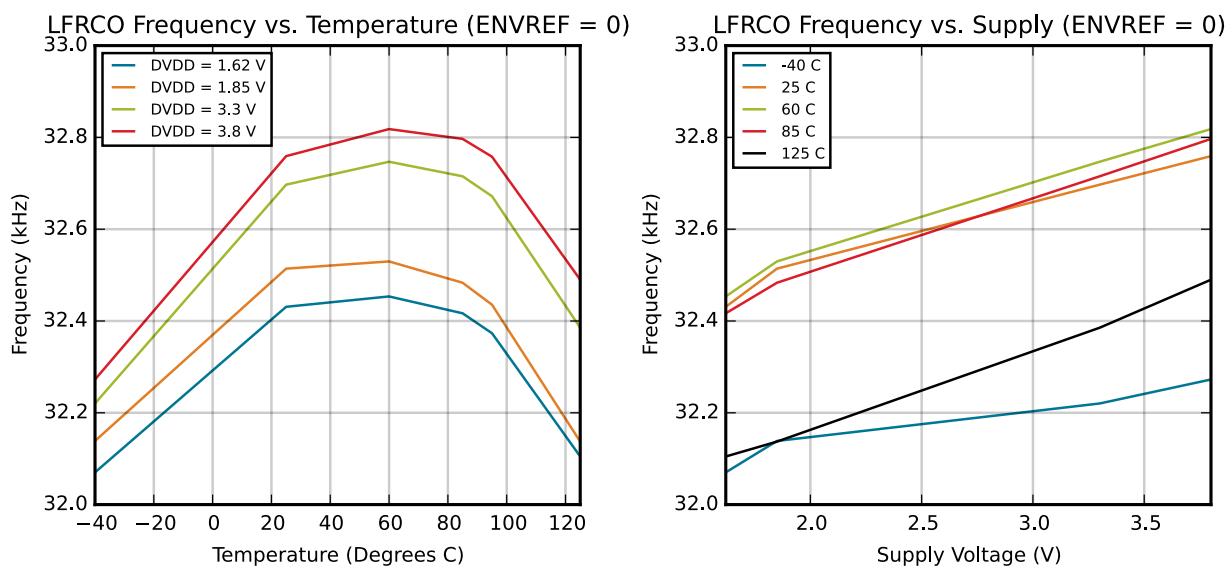
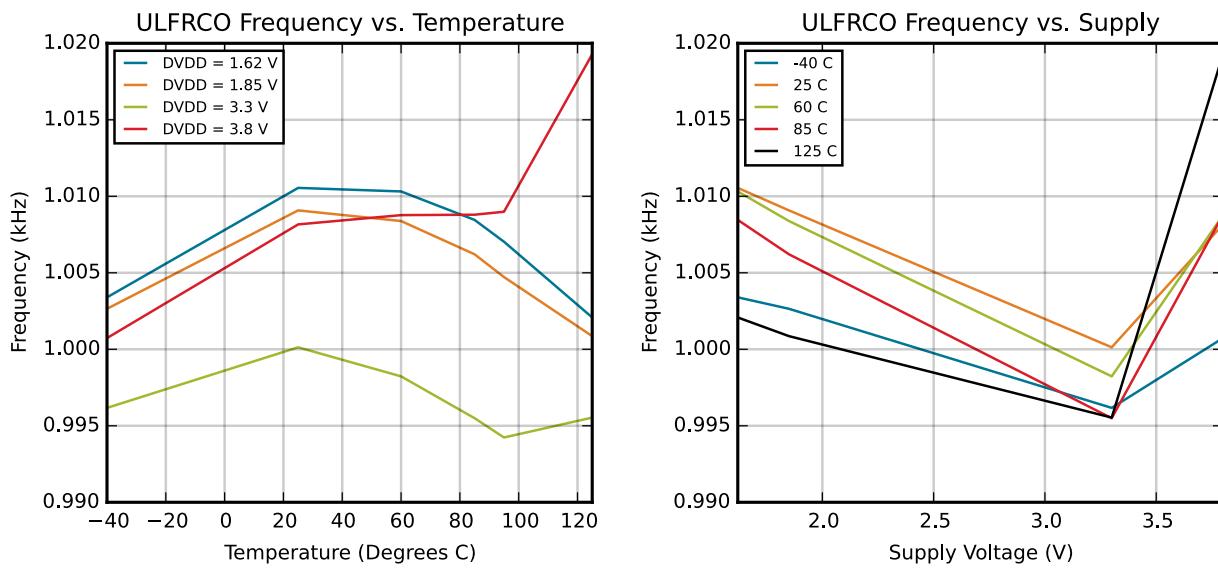


Figure 4.17. HFRCO and AUXHFRCO Typical Performance at 1 MHz

**Figure 4.18. LFRCO Typical Performance at 32.768 kHz****Figure 4.19. ULFRCO Typical Performance at 1 kHz**

6.2 EFM32PG1 QFN32 without DC-DC Definition

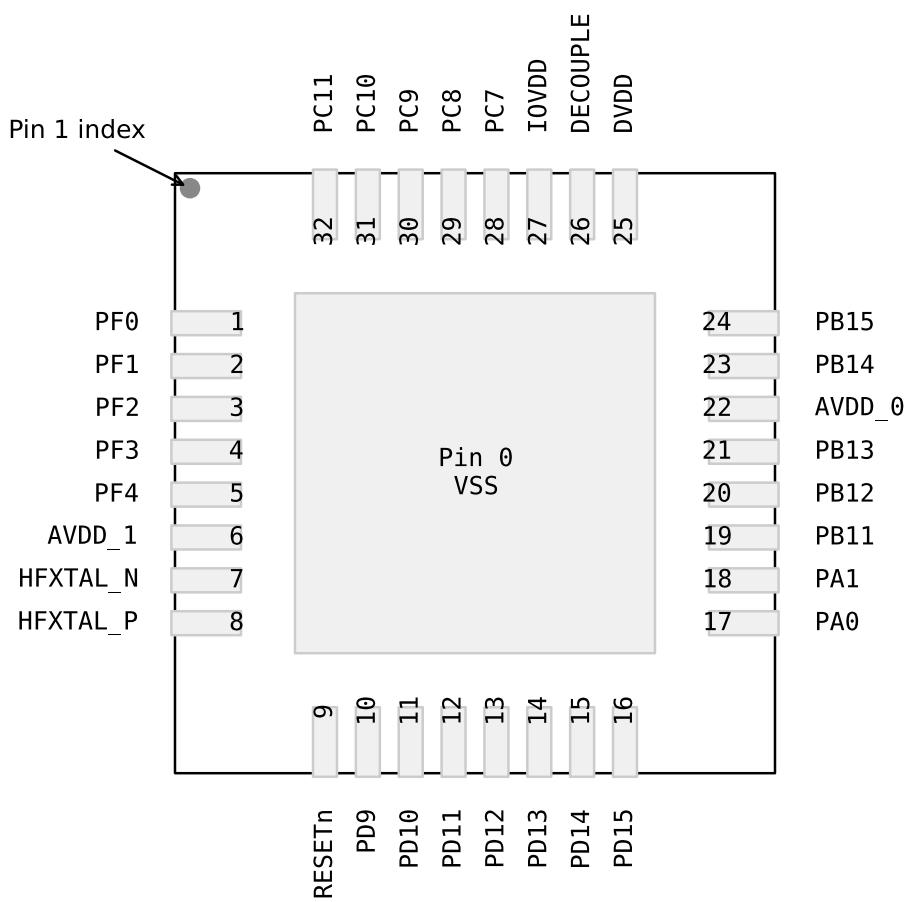


Figure 6.2. EFM32PG1 QFN32 without DC-DC Pinout

QFN32 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
4	PF3	BUSAY BUSBX	TIMO_CC0 #27 TIMO_CC1 #26 TIMO_CC2 #25 TIMO_CDTI0 #24 TIMO_CDTI1 #23 TIMO_CDTI2 #22 TIM1_CC0 #27 TIM1_CC1 #26 TIM1_CC2 #25 TIM1_CC3 #24 LE- Timo_OUT0 #27 LE- Timo_OUT1 #26 PCNT0_SOIN #27 PCNT0_S1IN #26	US0_TX #27 US0_RX #26 US0_CLK #25 US0_CS #24 US0_CTS #23 US0_RTS #22 US1_TX #27 US1_RX #26 US1_CLK #25 US1_CS #24 US1_CTS #23 US1_RTS #22 LEU0_TX #27 LEU0_RX #26 I2C0_SDA #27 I2C0_SCL #26	CMU_CLK1 #6 PRS_CH0 #3 PRS_CH1 #2 PRS_CH2 #1 PRS_CH3 #0 ACMP0_O #27 ACMP1_O #27 DBG_TDI #0
5	PF4	BUSAX BUSBY	TIMO_CC0 #28 TIMO_CC1 #27 TIMO_CC2 #26 TIMO_CDTI0 #25 TIMO_CDTI1 #24 TIMO_CDTI2 #23 TIM1_CC0 #28 TIM1_CC1 #27 TIM1_CC2 #26 TIM1_CC3 #25 LE- Timo_OUT0 #28 LE- Timo_OUT1 #27 PCNT0_SOIN #28 PCNT0_S1IN #27	US0_TX #28 US0_RX #27 US0_CLK #26 US0_CS #25 US0_CTS #24 US0_RTS #23 US1_TX #28 US1_RX #27 US1_CLK #26 US1_CS #25 US1_CTS #24 US1_RTS #23 LEU0_TX #28 LEU0_RX #27 I2C0_SDA #28 I2C0_SCL #27	PRS_CH0 #4 PRS_CH1 #3 PRS_CH2 #2 PRS_CH3 #1 ACMP0_O #28 ACMP1_O #28
6	AVDD_1	Analog power supply 1.			
7	HFXTAL_N	High Frequency Crystal input pin.			
8	HFXTAL_P	High Frequency Crystal output pin.			
9	RESETn	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.			
10	PD9	BUSCY BUSDX	TIMO_CC0 #17 TIMO_CC1 #16 TIMO_CC2 #15 TIMO_CDTI0 #14 TIMO_CDTI1 #13 TIMO_CDTI2 #12 TIM1_CC0 #17 TIM1_CC1 #16 TIM1_CC2 #15 TIM1_CC3 #14 LE- Timo_OUT0 #17 LE- Timo_OUT1 #16 PCNT0_SOIN #17 PCNT0_S1IN #16	US0_TX #17 US0_RX #16 US0_CLK #15 US0_CS #14 US0_CTS #13 US0_RTS #12 US1_TX #17 US1_RX #16 US1_CLK #15 US1_CS #14 US1_CTS #13 US1_RTS #12 LEU0_TX #17 LEU0_RX #16 I2C0_SDA #17 I2C0_SCL #16	CMU_CLK0 #4 PRS_CH3 #8 PRS_CH4 #0 PRS_CH5 #6 PRS_CH6 #11 ACMP0_O #17 ACMP1_O #17

QFN32 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
11	PD10	BUSCX BUSDY	TIMO_CC0 #18 TIMO_CC1 #17 TIMO_CC2 #16 TIMO_CDTI0 #15 TIMO_CDTI1 #14 TIMO_CDTI2 #13 TIM1_CC0 #18 TIM1_CC1 #17 TIM1_CC2 #16 TIM1_CC3 #15 LE- Timo_OUT0 #18 LE- Timo_OUT1 #17 PCNT0_S0IN #18 PCNT0_S1IN #17	US0_TX #18 US0_RX #17 US0_CLK #16 US0_CS #15 US0_CTS #14 US0_RTS #13 US1_TX #18 US1_RX #17 US1_CLK #16 US1_CS #15 US1_CTS #14 US1_RTS #13 LEU0_TX #18 LEU0_RX #17 I2C0_SDA #18 I2C0_SCL #17	CMU_CLK1 #4 PRS_CH3 #9 PRS_CH4 #1 PRS_CH5 #0 PRS_CH6 #12 ACMP0_O #18 ACMP1_O #18
12	PD11	BUSCY BUSDX	TIMO_CC0 #19 TIMO_CC1 #18 TIMO_CC2 #17 TIMO_CDTI0 #16 TIMO_CDTI1 #15 TIMO_CDTI2 #14 TIM1_CC0 #19 TIM1_CC1 #18 TIM1_CC2 #17 TIM1_CC3 #16 LE- Timo_OUT0 #19 LE- Timo_OUT1 #18 PCNT0_S0IN #19 PCNT0_S1IN #18	US0_TX #19 US0_RX #18 US0_CLK #17 US0_CS #16 US0_CTS #15 US0_RTS #14 US1_TX #19 US1_RX #18 US1_CLK #17 US1_CS #16 US1_CTS #15 US1_RTS #14 LEU0_TX #19 LEU0_RX #18 I2C0_SDA #19 I2C0_SCL #18	PRS_CH3 #10 PRS_CH4 #2 PRS_CH5 #1 PRS_CH6 #13 ACMP0_O #19 ACMP1_O #19
13	PD12	BUSCX BUSDY	TIMO_CC0 #20 TIMO_CC1 #19 TIMO_CC2 #18 TIMO_CDTI0 #17 TIMO_CDTI1 #16 TIMO_CDTI2 #15 TIM1_CC0 #20 TIM1_CC1 #19 TIM1_CC2 #18 TIM1_CC3 #17 LE- Timo_OUT0 #20 LE- Timo_OUT1 #19 PCNT0_S0IN #20 PCNT0_S1IN #19	US0_TX #20 US0_RX #19 US0_CLK #18 US0_CS #17 US0_CTS #16 US0_RTS #15 US1_TX #20 US1_RX #19 US1_CLK #18 US1_CS #17 US1_CTS #16 US1_RTS #15 LEU0_TX #20 LEU0_RX #19 I2C0_SDA #20 I2C0_SCL #19	PRS_CH3 #11 PRS_CH4 #3 PRS_CH5 #2 PRS_CH6 #14 ACMP0_O #20 ACMP1_O #20
14	PD13	BUSCY BUSDX	TIMO_CC0 #21 TIMO_CC1 #20 TIMO_CC2 #19 TIMO_CDTI0 #18 TIMO_CDTI1 #17 TIMO_CDTI2 #16 TIM1_CC0 #21 TIM1_CC1 #20 TIM1_CC2 #19 TIM1_CC3 #18 LE- Timo_OUT0 #21 LE- Timo_OUT1 #20 PCNT0_S0IN #21 PCNT0_S1IN #20	US0_TX #21 US0_RX #20 US0_CLK #19 US0_CS #18 US0_CTS #17 US0_RTS #16 US1_TX #21 US1_RX #20 US1_CLK #19 US1_CS #18 US1_CTS #17 US1_RTS #16 LEU0_TX #21 LEU0_RX #20 I2C0_SDA #21 I2C0_SCL #20	PRS_CH3 #12 PRS_CH4 #4 PRS_CH5 #3 PRS_CH6 #15 ACMP0_O #21 ACMP1_O #21

6.3 EFM32PG1 QFN32 with DC-DC Definition

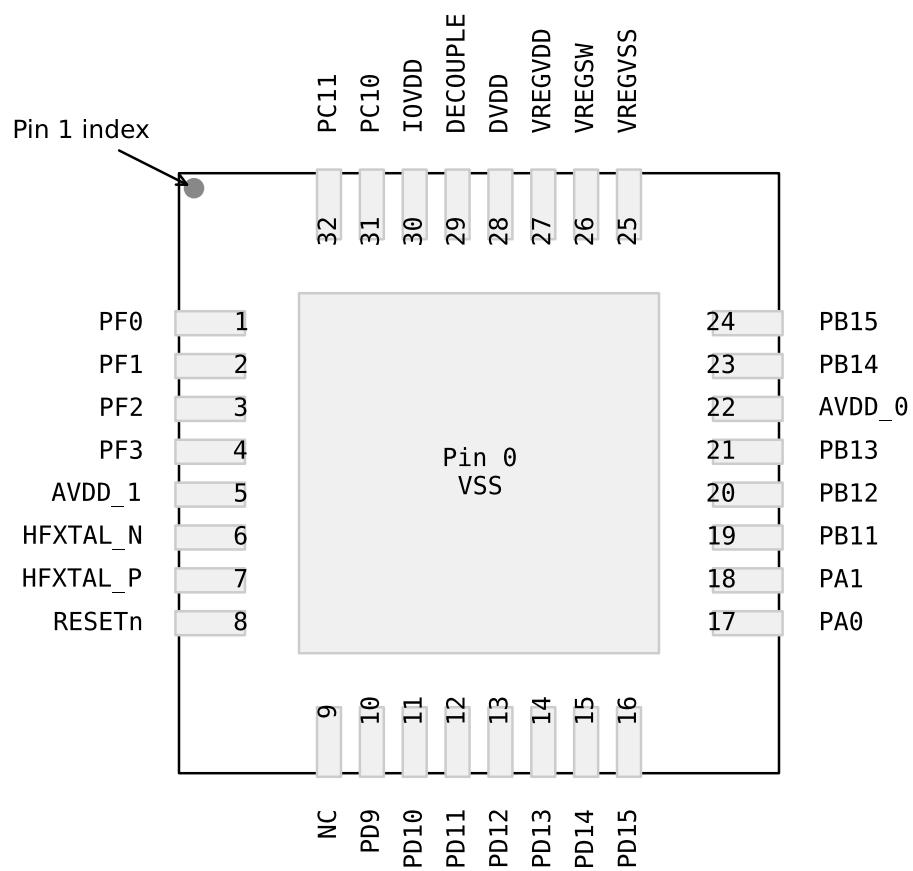


Figure 6.3. EFM32PG1 QFN32 with DC-DC Pinout

QFN32 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
12	PD11	BUSCY BUSDX	TIMO_CC0 #19 TIMO_CC1 #18 TIMO_CC2 #17 TIMO_CDTI0 #16 TIMO_CDTI1 #15 TIMO_CDTI2 #14 TIM1_CC0 #19 TIM1_CC1 #18 TIM1_CC2 #17 TIM1_CC3 #16 LE- Timo_OUT0 #19 LE- Timo_OUT1 #18 PCNT0_S0IN #19 PCNT0_S1IN #18	US0_TX #19 US0_RX #18 US0_CLK #17 US0_CS #16 US0_CTS #15 US0_RTS #14 US1_TX #19 US1_RX #18 US1_CLK #17 US1_CS #16 US1_CTS #15 US1_RTS #14 LEU0_TX #19 LEU0_RX #18 I2C0_SDA #19 I2C0_SCL #18	PRS_CH3 #10 PRS_CH4 #2 PRS_CH5 #1 PRS_CH6 #13 ACMP0_O #19 ACMP1_O #19
13	PD12	BUSCX BUSDY	TIMO_CC0 #20 TIMO_CC1 #19 TIMO_CC2 #18 TIMO_CDTI0 #17 TIMO_CDTI1 #16 TIMO_CDTI2 #15 TIM1_CC0 #20 TIM1_CC1 #19 TIM1_CC2 #18 TIM1_CC3 #17 LE- Timo_OUT0 #20 LE- Timo_OUT1 #19 PCNT0_S0IN #20 PCNT0_S1IN #19	US0_TX #20 US0_RX #19 US0_CLK #18 US0_CS #17 US0_CTS #16 US0_RTS #15 US1_TX #20 US1_RX #19 US1_CLK #18 US1_CS #17 US1_CTS #16 US1_RTS #15 LEU0_TX #20 LEU0_RX #19 I2C0_SDA #20 I2C0_SCL #19	PRS_CH3 #11 PRS_CH4 #3 PRS_CH5 #2 PRS_CH6 #14 ACMP0_O #20 ACMP1_O #20
14	PD13	BUSCY BUSDX	TIMO_CC0 #21 TIMO_CC1 #20 TIMO_CC2 #19 TIMO_CDTI0 #18 TIMO_CDTI1 #17 TIMO_CDTI2 #16 TIM1_CC0 #21 TIM1_CC1 #20 TIM1_CC2 #19 TIM1_CC3 #18 LE- Timo_OUT0 #21 LE- Timo_OUT1 #20 PCNT0_S0IN #21 PCNT0_S1IN #20	US0_TX #21 US0_RX #20 US0_CLK #19 US0_CS #18 US0_CTS #17 US0_RTS #16 US1_TX #21 US1_RX #20 US1_CLK #19 US1_CS #18 US1_CTS #17 US1_RTS #16 LEU0_TX #21 LEU0_RX #20 I2C0_SDA #21 I2C0_SCL #20	PRS_CH3 #12 PRS_CH4 #4 PRS_CH5 #3 PRS_CH6 #15 ACMP0_O #21 ACMP1_O #21
15	PD14	BUSCX BUSDY	TIMO_CC0 #22 TIMO_CC1 #21 TIMO_CC2 #20 TIMO_CDTI0 #19 TIMO_CDTI1 #18 TIMO_CDTI2 #17 TIM1_CC0 #22 TIM1_CC1 #21 TIM1_CC2 #20 TIM1_CC3 #19 LE- Timo_OUT0 #22 LE- Timo_OUT1 #21 PCNT0_S0IN #22 PCNT0_S1IN #21	US0_TX #22 US0_RX #21 US0_CLK #20 US0_CS #19 US0_CTS #18 US0_RTS #17 US1_TX #22 US1_RX #21 US1_CLK #20 US1_CS #19 US1_CTS #18 US1_RTS #17 LEU0_TX #22 LEU0_RX #21 I2C0_SDA #22 I2C0_SCL #21	CMU_CLK0 #5 PRS_CH3 #13 PRS_CH4 #5 PRS_CH5 #4 PRS_CH6 #16 ACMP0_O #22 ACMP1_O #22 GPIO_EM4WU4

Alternate	LOCATION								
Functionality	0 - 3	4 - 7	8 - 11	12 - 15	16 - 19	20 - 23	24 - 27	28 - 31	Description
PRS_CH1	0: PF1 1: PF2 2: PF3 3: PF4	4: PF5 5: PF6 6: PF7 7: PF0							Peripheral Reflex System PRS, channel 1.
PRS_CH2	0: PF2 1: PF3 2: PF4 3: PF5	4: PF6 5: PF7 6: PF0 7: PF1							Peripheral Reflex System PRS, channel 2.
PRS_CH3	0: PF3 1: PF4 2: PF5 3: PF6	4: PF7 5: PF0 6: PF1 7: PF2	8: PD9 9: PD10 10: PD11 11: PD12	12: PD13 13: PD14 14: PD15					Peripheral Reflex System PRS, channel 3.
PRS_CH4	0: PD9 1: PD10 2: PD11 3: PD12	4: PD13 5: PD14 6: PD15							Peripheral Reflex System PRS, channel 4.
PRS_CH5	0: PD10 1: PD11 2: PD12 3: PD13	4: PD14 5: PD15 6: PD9							Peripheral Reflex System PRS, channel 5.
PRS_CH6	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PD9	12: PD10 13: PD11 14: PD12 15: PD13	16: PD14 17: PD15				Peripheral Reflex System PRS, channel 6.
PRS_CH7	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PA0						Peripheral Reflex System PRS, channel 7.
PRS_CH8	0: PA2 1: PA3 2: PA4 3: PA5	4: PB11 5: PB12 6: PB13 7: PB14	8: PB15 9: PA0 10: PA1						Peripheral Reflex System PRS, channel 8.
PRS_CH9	0: PA3 1: PA4 2: PA5 3: PB11	4: PB12 5: PB13 6: PB14 7: PB15	8: PA0 9: PA1 10: PA2 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11				Peripheral Reflex System PRS, channel 9.
PRS_CH10	0: PC6 1: PC7 2: PC8 3: PC9	4: PC10 5: PC11							Peripheral Reflex System PRS, channel 10.
PRS_CH11	0: PC7 1: PC8 2: PC9 3: PC10	4: PC11 5: PC6							Peripheral Reflex System PRS, channel 11.
TIM0_CC0	0: PA0 1: PA1 2: PA2 3: PA3	4: PA4 5: PA5 6: PB11 7: PB12	8: PB13 9: PB14 10: PB15 11: PC6	12: PC7 13: PC8 14: PC9 15: PC10	16: PC11 17: PD9 18: PD10 19: PD11	20: PD12 21: PD13 22: PD14 23: PD15	24: PF0 25: PF1 26: PF2 27: PF3	28: PF4 29: PF5 30: PF6 31: PF7	Timer 0 Capture Compare input / output channel 0.
TIM0_CC1	0: PA1 1: PA2 2: PA3 3: PA4	4: PA5 5: PB11 6: PB12 7: PB13	8: PB14 9: PB15 10: PC6 11: PC7	12: PC8 13: PC9 14: PC10 15: PC11	16: PD9 17: PD10 18: PD11 19: PD12	20: PD13 21: PD14 22: PD15 23: PF0	24: PF1 25: PF2 26: PF3 27: PF4	28: PF5 29: PF6 30: PF7 31: PA0	Timer 0 Capture Compare input / output channel 1.

6.5 Analog Port (APORT) Client Maps

The Analog Port (APORT) is an infrastructure used to connect chip pins with on-chip analog clients such as analog comparators, ADCs, DACs, etc. The APORT consists of a set of shared buses, switches, and control logic needed to configurably implement the signal routing. A complete description of APORT functionality can be found in the Reference Manual.

Client maps for each analog circuit using the APORT are shown in the following tables. The maps are organized by bus, and show the peripheral's port connection, the shared bus, and the connection from specific bus channel numbers to GPIO pins.

In general, enumerations for the pin selection field in an analog peripheral's register can be determined by finding the desired pin connection in the table and then combining the value in the Port column (APORT_{__}), and the channel identifier (CH_{__}). For example, if pin PF7 is available on port APOR2X as CH23, the register field enumeration to connect to PF7 would be APOR2XCH23. The shared bus used by this connection is indicated in the Bus column.

Table 6.8. ACMP0 Bus and Pin Mapping

APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	Bus
PB15	PB15	PB14						CH31
PB14	PB13	PB12						CH30
PB12	PB11	PB11						CH29
								CH28
								CH26
								CH25
								CH24
								CH23
				PF7	PF7			PF7
				PF6		PF6		CH22
				PF5	PF5			CH21
				PF4		PF4		CH20
				PF3	PF3			CH19
				PF2		PF2		CH18
				PF1	PF1			CH17
				PF0		PF0		CH16
								CH15
								CH14
								CH13
								CH12
								CH11
								CH10
PA5	PA5	PA4				PC11	PC11	PC11
PA4	PA3	PA3		PA2	PA2	PC10		PC10
PA2	PA1	PA1				PC9	PC9	PC9
PA0				PA0	PA0	PC8		PC8
PD15	PD15	PD15				PC7	PC7	PC7
PD14				PD14	PD14			PC6
PD12	PD13	PD13						CH6
PD11	PD11	PD11						CH5
PD10	PD9	PD9						CH4
								CH3
								CH2
								CH1
								CH0

Table 6.9. ACMP1 Bus and Pin Mapping

APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	Bus
PB15	PB15							CH31
PB14		PB14						CH30
PB13	PB13	PB12	PB12					CH29
PB12	PB11	PB11						CH28
								CH27
								CH26
								CH25
								CH24
								CH23
					PF7	PF7		CH22
				PF6			PF6	CH22
					PF5	PF5		CH21
					PF4		PF4	CH20
					PF3	PF3		CH19
				PF2			PF2	CH18
					PF1	PF1		CH17
				PF0			PF0	CH16
								CH15
								CH14
PA5	PA5	PA4						CH13
PA4		PA3	PA3	PC11	PC11			CH12
PA2		PA2	PA2	PC10	PC10		PC10	CH10
PA1	PA1			PC9	PC9			CH9
PA0		PA0	PA0	PC8			PC8	CH8
PD15	PD15	PD15		PC7	PC7			CH7
PD14		PD14	PD14	PC6			PC6	CH6
PD13	PD13							CH5
PD12		PD12	PD12					CH4
PD11	PD11							CH3
PD10		PD10	PD10					CH2
PD9	PD9	PD9						CH1
								CH0

7. QFN48 Package Specifications

7.1 QFN48 Package Dimensions

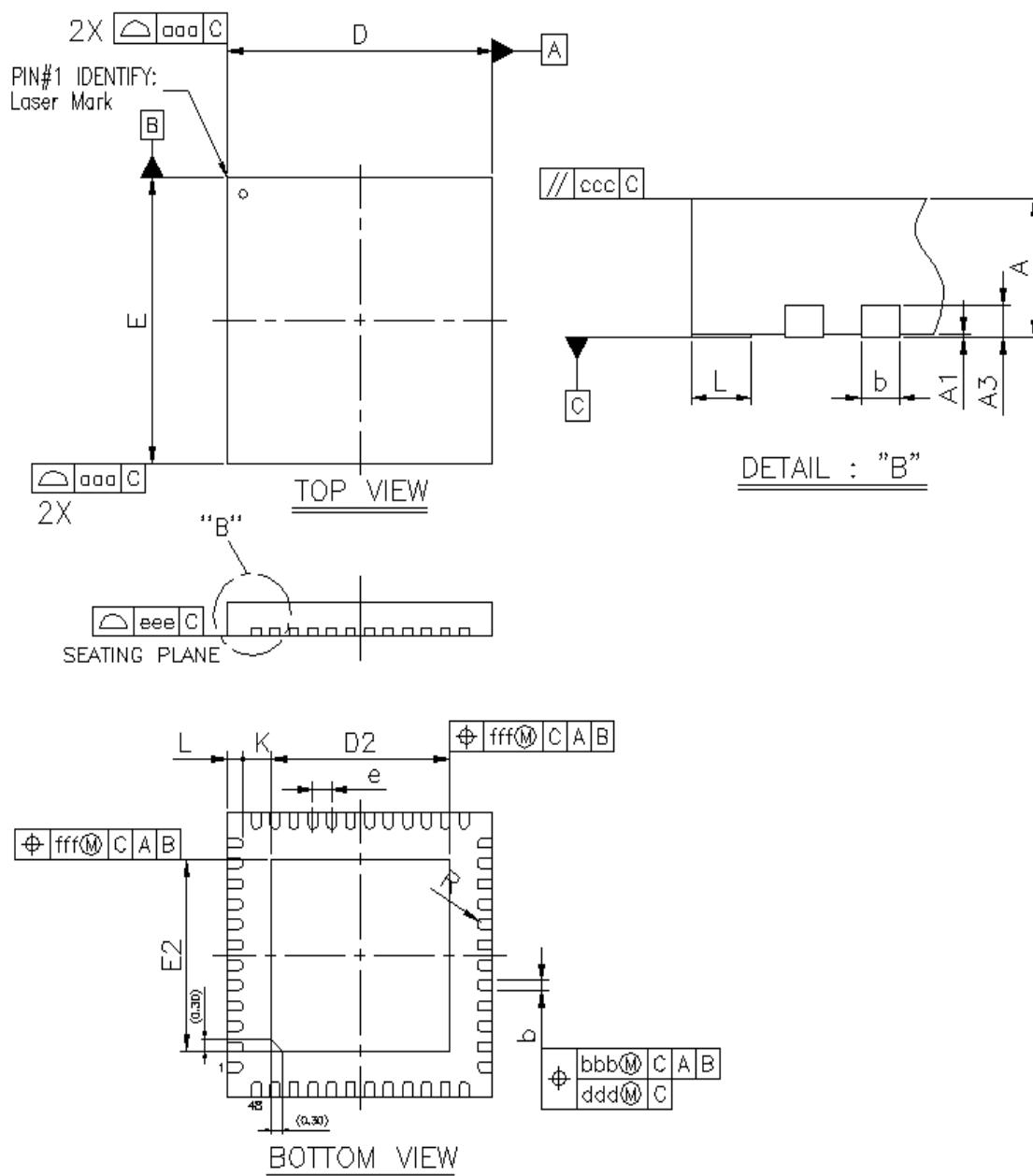


Figure 7.1. QFN48 Package Drawing

8.2 QFN32 PCB Land Pattern

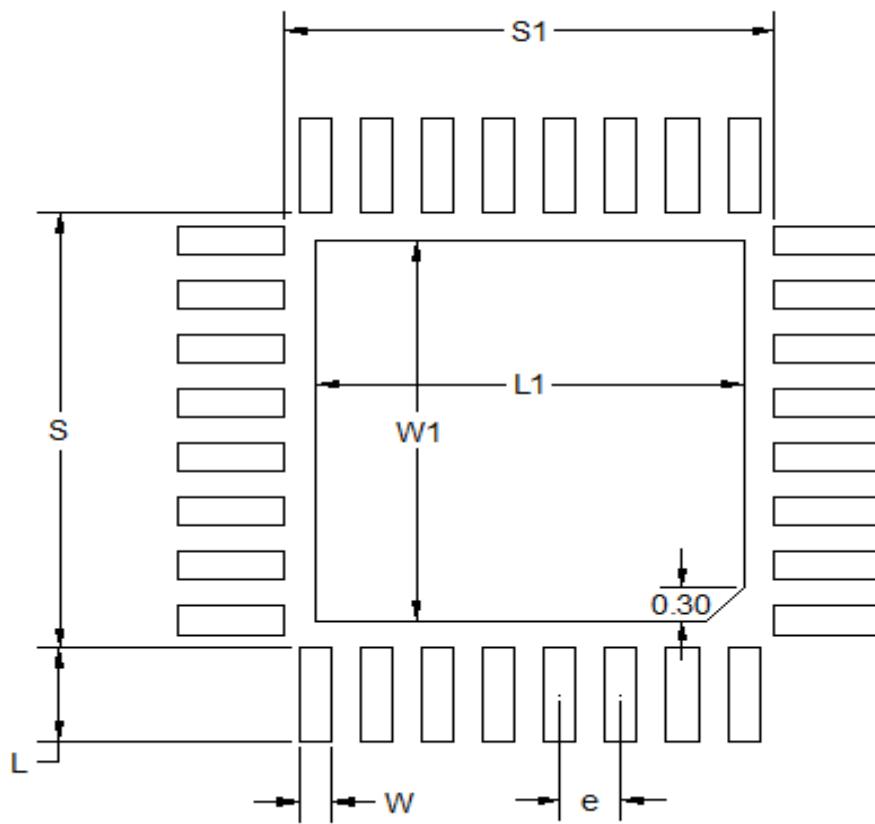


Figure 8.2. QFN32 PCB Land Pattern Drawing

Table of Contents

1. Feature List	1
2. Ordering Information	2
3. System Overview	3
3.1 Introduction.	3
3.2 Power	4
3.2.1 Energy Management Unit (EMU)	4
3.2.2 DC-DC Converter	4
3.3 General Purpose Input/Output (GPIO).	4
3.4 Clocking.	4
3.4.1 Clock Management Unit (CMU)	4
3.4.2 Internal and External Oscillators	4
3.5 Counters/Timers and PWM	5
3.5.1 Timer/Counter (TIMER)	5
3.5.2 Real Time Counter and Calendar (RTCC)	5
3.5.3 Low Energy Timer (LETIMER)	5
3.5.4 Ultra Low Power Wake-up Timer (CRYOTIMER)	5
3.5.5 Pulse Counter (PCNT)	5
3.5.6 Watchdog Timer (WDOG)	5
3.6 Communications and Other Digital Peripherals	5
3.6.1 Universal Synchronous/Asynchronous Receiver/Transmitter (USART)	5
3.6.2 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)	5
3.6.3 Inter-Integrated Circuit Interface (I ² C)	6
3.6.4 Peripheral Reflex System (PRS)	6
3.7 Security Features.	6
3.7.1 GPCRC (General Purpose Cyclic Redundancy Check)	6
3.7.2 Crypto Accelerator (CRYPTO)	6
3.8 Analog	6
3.8.1 Analog Port (APORT)	6
3.8.2 Analog Comparator (ACMP)	6
3.8.3 Analog to Digital Converter (ADC)	6
3.8.4 Digital to Analog Current Converter (IDAC)	7
3.9 Reset Management Unit (RMU)	7
3.10 Core and Memory	7
3.10.1 Processor Core	7
3.10.2 Memory System Controller (MSC)	7
3.10.3 Linked Direct Memory Access Controller (LDMA)	7
3.11 Memory Map	8
3.12 Configuration Summary	9
4. Electrical Specifications	10
4.1 Electrical Characteristics	10
4.1.1 Absolute Maximum Ratings	10