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Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	85
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 32x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24hj128gp210a-e-pt

PIC24HJXXXGPX06A/X08A/X10A

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PIC24HJXXXGPX06A/X08A/X10A

1.0 DEVICE OVERVIEW

Note: This data sheet summarizes the features of the PIC24HJXXXGPX06A/X08A/X10A family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the latest family reference sections of the “dsPIC33F/PIC24H Family Reference Manual”, which is available from the Microchip web site (www.microchip.com).

This document contains device specific information for the following devices:

- PIC24HJ64GP206A
- PIC24HJ64GP210A
- PIC24HJ64GP506A
- PIC24HJ64GP510A
- PIC24HJ128GP206A
- PIC24HJ128GP210A
- PIC24HJ128GP506A
- PIC24HJ128GP510A
- PIC24HJ128GP306A
- PIC24HJ128GP310A
- PIC24HJ256GP206A
- PIC24HJ256GP210A
- PIC24HJ256GP610A

The PIC24HJXXXGPX06A/X08A/X10A device family includes devices with different pin counts (64 and 100 pins), different program memory sizes (64 Kbytes, 128 Kbytes and 256 Kbytes) and different RAM sizes (8 Kbytes and 16 Kbytes).

This makes these families suitable for a wide variety of high-performance digital signal control applications. The devices are pin compatible with the dsPIC33F family of devices, and also share a very high degree of compatibility with the dsPIC30F family devices. This allows easy migration between device families as may be necessitated by the specific functionality, computational resource and system cost requirements of the application.

The PIC24HJXXXGPX06A/X08A/X10A device family employs a powerful 16-bit architecture, ideal for applications that rely on high-speed, repetitive computations, as well as control.

The 17 x 17 multiplier, hardware support for division operations, multi-bit data shifter, a large array of 16-bit working registers and a wide variety of data addressing modes, together provide the PIC24HJXXXGPX06A/X08A/X10A Central Processing Unit (CPU) with extensive mathematical processing capability. Flexible and deterministic interrupt handling, coupled with a powerful array of peripherals, renders the PIC24HJXXXGPX06A/X08A/X10A devices suitable for control applications. Further, Direct Memory Access (DMA) enables overhead-free transfer of data between several peripherals and a dedicated DMA RAM. Reliable, field programmable Flash program memory ensures scalability of applications that use PIC24HJXXXGPX06A/X08A/X10A devices.

Figure 1-1 shows a general block diagram of the various core and peripheral modules in the PIC24HJXXXGPX06A/X08A/X10A family of devices, while Table 1-1 lists the functions of the various pins shown in the pinout diagrams.

TABLE 4-17: DMA REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
DMA0CON	0380	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA0REQ	0382	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA0STA	0384	STA<15:0>																	0000
DMA0STB	0386	STB<15:0>																	0000
DMA0PAD	0388	PAD<15:0>																	0000
DMA0CNT	038A	—	—	—	—	—	—	CNT<9:0>											0000
DMA1CON	038C	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA1REQ	038E	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA1STA	0390	STA<15:0>																	0000
DMA1STB	0392	STB<15:0>																	0000
DMA1PAD	0394	PAD<15:0>																	0000
DMA1CNT	0396	—	—	—	—	—	—	CNT<9:0>											0000
DMA2CON	0398	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA2REQ	039A	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA2STA	039C	STA<15:0>																	0000
DMA2STB	039E	STB<15:0>																	0000
DMA2PAD	03A0	PAD<15:0>																	0000
DMA2CNT	03A2	—	—	—	—	—	—	CNT<9:0>											0000
DMA3CON	03A4	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA3REQ	03A6	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA3STA	03A8	STA<15:0>																	0000
DMA3STB	03AA	STB<15:0>																	0000
DMA3PAD	03AC	PAD<15:0>																	0000
DMA3CNT	03AE	—	—	—	—	—	—	CNT<9:0>											0000
DMA4CON	03B0	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA4REQ	03B2	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA4STA	03B4	STA<15:0>																	0000
DMA4STB	03B6	STB<15:0>																	0000
DMA4PAD	03B8	PAD<15:0>																	0000
DMA4CNT	03BA	—	—	—	—	—	—	CNT<9:0>											0000
DMA5CON	03BC	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA5REQ	03BE	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA5STA	03C0	STA<15:0>																	0000
DMA5STB	03C2	STB<15:0>																	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

TABLE 4-17: DMA REGISTER MAP (CONTINUED)

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
DMA5PAD	03C4	PAD<15:0>																0000	
DMA5CNT	03C6	—	—	—	—	—	—	CNT<9:0>										0000	
DMA6CON	03C8	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA6REQ	03CA	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA6STA	03CC	STA<15:0>																0000	
DMA6STB	03CE	STB<15:0>																0000	
DMA6PAD	03D0	PAD<15:0>																0000	
DMA6CNT	03D2	—	—	—	—	—	—	CNT<9:0>										0000	
DMA7CON	03D4	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA7REQ	03D6	FORCE	—	—	—	—	—	—	—	—	IRQSEL<6:0>								0000
DMA7STA	03D8	STA<15:0>																0000	
DMA7STB	03DA	STB<15:0>																0000	
DMA7PAD	03DC	PAD<15:0>																0000	
DMA7CNT	03DE	—	—	—	—	—	—	CNT<9:0>										0000	
DMACS0	03E0	PWCOL7	PWCOL6	PWCOL5	PWCOL4	PWCOL3	PWCOL2	PWCOL1	PWCOL0	XWCOL7	XWCOL6	XWCOL5	XWCOL4	XWCOL3	XWCOL2	XWCOL1	XWCOL0	0000	
DMACS1	03E2	—	—	—	—	LSTCH<3:0>				PPST7	PPST6	PPST5	PPST4	PPST3	PPST2	PPST1	PPST0	0000	
DSADR	03E4	DSADR<15:0>																0000	

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

TABLE 4-18: ECAN1 REGISTER MAP WHEN C1CTRL1.WIN = 0 OR 1 FOR PIC24HJXXXGP506A/510A/610A DEVICES ONLY

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
C1CTRL1	0400	—	—	CSIDL	ABAT	—	REQOP<2:0>			OPMODE<2:0>			—	CANCAP	—	—	WIN	0480	
C1CTRL2	0402	—	—	—	—	—	—	—	—	—	—	—	DNCNT<4:0>					0000	
C1VEC	0404	—	—	—	FILHIT<4:0>					—	ICODE<6:0>							0000	
C1FCTRL	0406	DMABS<2:0>			—	—	—	—	—	—	—	—	FSA<4:0>					0000	
C1FIFO	0408	—	—	FBP<5:0>						—	—	FNRB<5:0>						0000	
C1INTF	040A	—	—	TXBO	TXBP	RXBP	TXWAR	RXWAR	EWARN	IVRIF	WAKIF	ERRIF	—	FIFOIF	RBOVIF	RBIF	TBIF	0000	
C1INTE	040C	—	—	—	—	—	—	—	—	IVRIE	WAKIE	ERRIE	—	FIFOIE	RBOVIE	RBIE	TBIE	0000	
C1EC	040E	TERRCNT<7:0>								RERRCNT<7:0>								0000	
C1CFG1	0410	—	—	—	—	—	—	—	—	SJW<1:0>		BRP<5:0>							0000
C1CFG2	0412	—	WAKFIL	—	—	—	SEG2PH<2:0>			SEG2PHTS	SAM	SEG1PH<2:0>			PRSEG<2:0>			0000	
C1FEN1	0414	FLTEN15	FLTEN14	FLTEN13	FLTEN12	FLTEN11	FLTEN10	FLTEN9	FLTEN8	FLTEN7	FLTEN6	FLTEN5	FLTEN4	FLTEN3	FLTEN2	FLTEN1	FLTEN0	FFFF	
C1FMSKSEL1	0418	F7MSK<1:0>		F6MSK<1:0>		F5MSK<1:0>		F4MSK<1:0>		F3MSK<1:0>		F2MSK<1:0>		F1MSK<1:0>		F0MSK<1:0>		0000	
C1FMSKSEL2	041A	F15MSK<1:0>		F14MSK<1:0>		F13MSK<1:0>		F12MSK<1:0>		F11MSK<1:0>		F10MSK<1:0>		F9MSK<1:0>		F8MSK<1:0>		0000	

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

TABLE 4-19: ECAN1 REGISTER MAP WHEN C1CTRL1.WIN = 0 FOR PIC24HJXXXGP506A/510A/610A DEVICES ONLY

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
	0400-041E	See definition when WIN = x																
C1RXFUL1	0420	RXFUL15	RXFUL14	RXFUL13	RXFUL12	RXFUL11	RXFUL10	RXFUL9	RXFUL8	RXFUL7	RXFUL6	RXFUL5	RXFUL4	RXFUL3	RXFUL2	RXFUL1	RXFUL0	0000
C1RXFUL2	0422	RXFUL31	RXFUL30	RXFUL29	RXFUL28	RXFUL27	RXFUL26	RXFUL25	RXFUL24	RXFUL23	RXFUL22	RXFUL21	RXFUL20	RXFUL19	RXFUL18	RXFUL17	RXFUL16	0000
C1RXOVF1	0428	RXOVF15	RXOVF14	RXOVF13	RXOVF12	RXOVF11	RXOVF10	RXOVF9	RXOVF8	RXOVF7	RXOVF6	RXOVF5	RXOVF4	RXOVF3	RXOVF2	RXOVF1	RXOVF0	0000
C1RXOVF2	042A	RXOVF31	RXOVF30	RXOVF29	RXOVF28	RXOVF27	RXOVF26	RXOVF25	RXOVF24	RXOVF23	RXOVF22	RXOVF21	RXOVF20	RXOVF19	RXOVF18	RXOVF17	RXOVF16	0000
C1TR01CON	0430	TXEN1	TX ABT1	TX LARB1	TX ERR1	TX REQ1	RTREN1	TX1PRI<1:0>		TXEN0	TX ABAT0	TX LARB0	TX ERR0	TX REQ0	RTREN0	TX0PRI<1:0>		0000
C1TR23CON	0432	TXEN3	TX ABT3	TX LARB3	TX ERR3	TX REQ3	RTREN3	TX3PRI<1:0>		TXEN2	TX ABAT2	TX LARB2	TX ERR2	TX REQ2	RTREN2	TX2PRI<1:0>		0000
C1TR45CON	0434	TXEN5	TX ABT5	TX LARB5	TX ERR5	TX REQ5	RTREN5	TX5PRI<1:0>		TXEN4	TX ABAT4	TX LARB4	TX ERR4	TX REQ4	RTREN4	TX4PRI<1:0>		0000
C1TR67CON	0436	TXEN7	TX ABT7	TX LARB7	TX ERR7	TX REQ7	RTREN7	TX7PRI<1:0>		TXEN6	TX ABAT6	TX LARB6	TX ERR6	TX REQ6	RTREN6	TX6PRI<1:0>		xxxx
C1RXD	0440	Recieved Data Word																xxxx
C1TXD	0442	Transmit Data Word																xxxx

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

TABLE 4-20: ECAN1 REGISTER MAP WHEN C1CTRL1.WIN = 1 FOR PIC24HJXXXGP506A/510A/610A DEVICES ONLY

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
	0400-041E	See definition when WIN = x																	
C1BUFPNT1	0420	F3BP<3:0>				F2BP<3:0>				F1BP<3:0>				F0BP<3:0>				0000	
C1BUFPNT2	0422	F7BP<3:0>				F6BP<3:0>				F5BP<3:0>				F4BP<3:0>				0000	
C1BUFPNT3	0424	F11BP<3:0>				F10BP<3:0>				F9BP<3:0>				F8BP<3:0>				0000	
C1BUFPNT4	0426	F15BP<3:0>				F14BP<3:0>				F13BP<3:0>				F12BP<3:0>				0000	
C1RXM0SID	0430	SID<10:3>								SID<2:0>			—	MIDE	—	EID<17:16>		xxxx	
C1RXM0EID	0432	EID<15:8>								EID<7:0>									xxxx
C1RXM1SID	0434	SID<10:3>								SID<2:0>			—	MIDE	—	EID<17:16>		xxxx	
C1RXM1EID	0436	EID<15:8>								EID<7:0>									xxxx
C1RXM2SID	0438	SID<10:3>								SID<2:0>			—	MIDE	—	EID<17:16>		xxxx	
C1RXM2EID	043A	EID<15:8>								EID<7:0>									xxxx
C1RXF0SID	0440	SID<10:3>								SID<2:0>			—	EXIDE	—	EID<17:16>		xxxx	
C1RXF0EID	0442	EID<15:8>								EID<7:0>									xxxx
C1RXF1SID	0444	SID<10:3>								SID<2:0>			—	EXIDE	—	EID<17:16>		xxxx	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

TABLE 4-28: PORTE REGISTER MAP⁽¹⁾

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISE	02D8	—	—	—	—	—	—	—	—	TRISE7	TRISE6	TRISE5	TRISE4	TRISE3	TRISE2	TRISE1	TRISE0	00FF
PORTE	02DA	—	—	—	—	—	—	—	—	RE7	RE6	RE5	RE4	RE3	RE2	RE1	RE0	xxxx
LATE	02DC	—	—	—	—	—	—	—	—	LATE7	LATE6	LATE5	LATE4	LATE3	LATE2	LATE1	LATE0	xxxx

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

Note 1: The actual set of I/O port pins varies from one device to another. Please refer to the corresponding pinout diagrams.

TABLE 4-29: PORTF REGISTER MAP⁽¹⁾

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISF	02DE	—	—	TRISF13	TRISF12	—	—	—	TRISF8	TRISF7	TRISF6	TRISF5	TRISF4	TRISF3	TRISF2	TRISF1	TRISF0	31FF
PORTF	02E0	—	—	RF13	RF12	—	—	—	RF8	RF7	RF6	RF5	RF4	RF3	RF2	RF1	RF0	xxxx
LATF	02E2	—	—	LATF13	LATF12	—	—	—	LATF8	LATF7	LATF6	LATF5	LATF4	LATF3	LATF2	LATF1	LATF0	xxxx
ODCF ⁽²⁾	06DE	—	—	ODCF13	ODCF12	—	—	—	ODCF8	ODCF7	ODCF6	ODCF5	ODCF4	ODCF3	ODCF2	ODCF1	ODCF0	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

Note 1: The actual set of I/O port pins varies from one device to another. Please refer to the corresponding pinout diagrams.

TABLE 4-30: PORTG REGISTER MAP⁽¹⁾

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISG	02E4	TRISG15	TRISG14	TRISG13	TRISG12	—	—	TRISG9	TRISG8	TRISG7	TRISG6	—	—	TRISG3	TRISG2	TRISG1	TRISG0	F3CF
PORTG	02E6	RG15	RG14	RG13	RG12	—	—	RG9	RG8	RG7	RG6	—	—	RG3	RG2	RG1	RG0	xxxx
LATG	02E8	LATG15	LATG14	LATG13	LATG12	—	—	LATG9	LATG8	LATG7	LATG6	—	—	LATG3	LATG2	LATG1	LATG0	xxxx
ODCG ⁽²⁾	06E4	ODCG15	ODCG14	ODCG13	ODCG12	—	—	ODCG9	ODCG8	ODCG7	ODCG6	—	—	ODCG3	ODCG2	ODCG1	ODCG0	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

Note 1: The actual set of I/O port pins varies from one device to another. Please refer to the corresponding pinout diagrams.

PIC24HJXXXGPX06A/X08A/X10A

4.4.3 READING DATA FROM PROGRAM MEMORY USING PROGRAM SPACE VISIBILITY

The upper 32 Kbytes of data space may optionally be mapped into any 16K word page of the program space. This option provides transparent access of stored constant data from the data space without the need to use special instructions (i.e., TBLRDH/H).

Program space access through the data space occurs if the Most Significant bit of the data space EA is '1' and program space visibility is enabled by setting the PSV bit in the Core Control register (CORCON<2>). The location of the program memory space to be mapped into the data space is determined by the Program Space Visibility Page register (PSVPAG). This 8-bit register defines any one of 256 possible pages of 16K words in program space. In effect, PSVPAG functions as the upper 8 bits of the program memory address, with the 15 bits of the EA functioning as the lower bits. Note that by incrementing the PC by 2 for each program memory word, the lower 15 bits of data space addresses directly map to the lower 15 bits in the corresponding program space addresses.

Data reads to this area add an additional cycle to the instruction being executed, since two program memory fetches are required.

Although each data space address, 0x8000 and higher, maps directly into a corresponding program memory address (see Figure 4-8), only the lower 16 bits of the

24-bit program word are used to contain the data. The upper 8 bits of any program space location used as data should be programmed with '1111 1111' or '0000 0000' to force a NOP. This prevents possible issues should the area of code ever be accidentally executed.

Note: PSV access is temporarily disabled during table reads/writes.

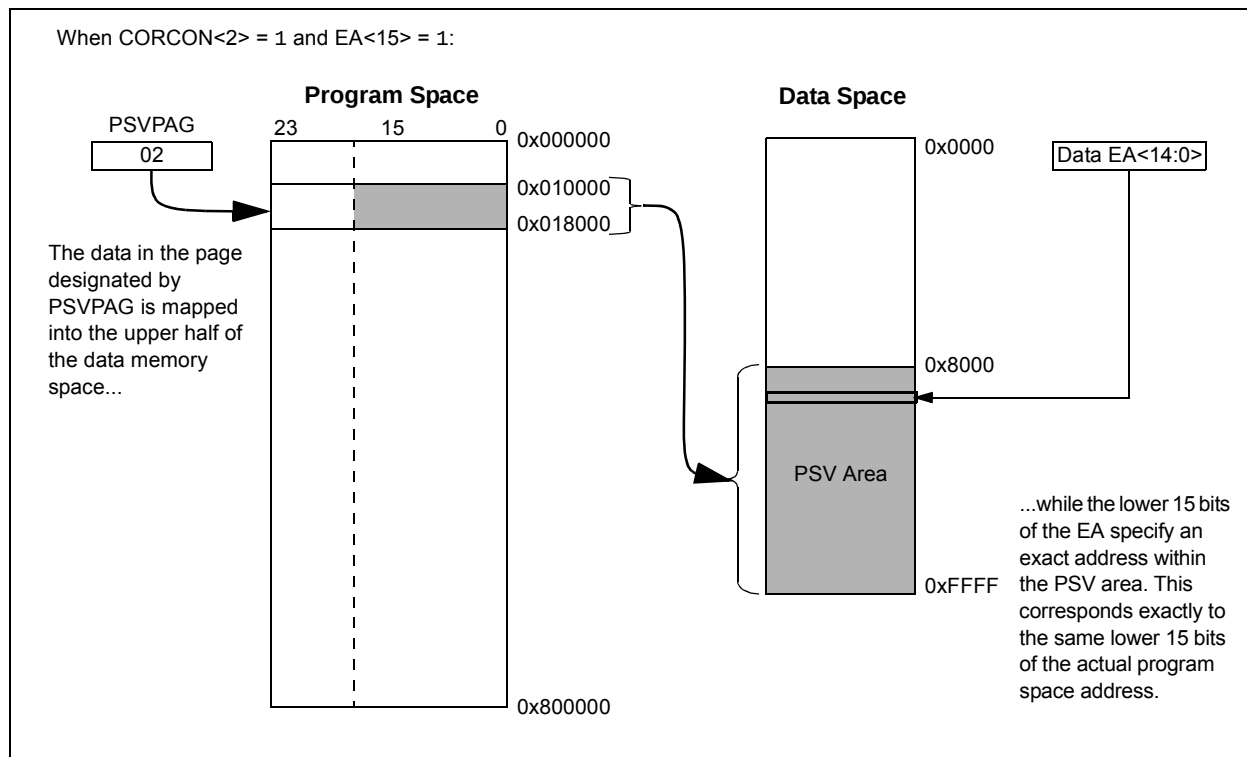
For operations that use PSV and are executed outside a REPEAT loop, the MOV and MOV.D instructions require one instruction cycle in addition to the specified execution time. All other instructions require two instruction cycles in addition to the specified execution time.

For operations that use PSV, which are executed inside a REPEAT loop, there will be some instances that require two instruction cycles in addition to the specified execution time of the instruction:

- Execution in the first iteration
- Execution in the last iteration
- Execution prior to exiting the loop due to an interrupt
- Execution upon re-entering the loop after an interrupt is serviced

Any other iteration of the REPEAT loop will allow the instruction accessing data, using PSV, to execute in a single cycle.

FIGURE 4-8: PROGRAM SPACE VISIBILITY OPERATION



PIC24HJXXXGPX06A/X08A/X10A

REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	DMA21IF
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
IC8IF	IC7IF	AD2IF	INT1IF	CNIF	—	MI2C1IF	SI2C1IF
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

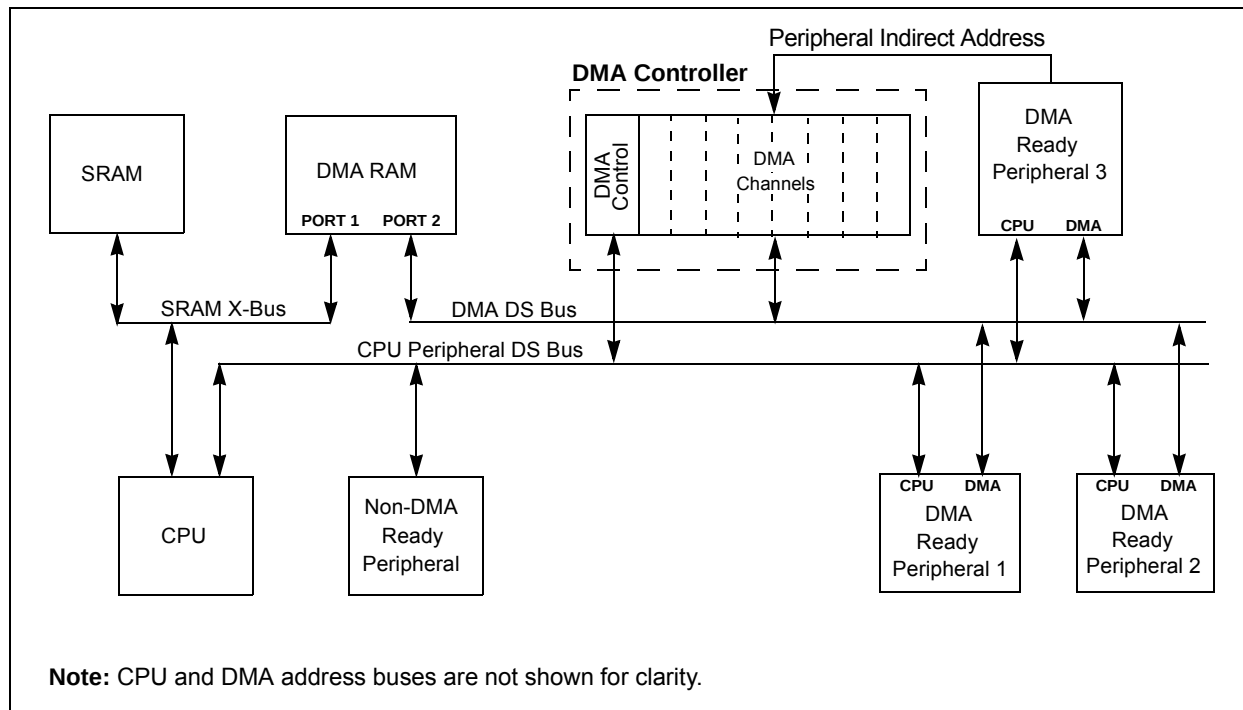
'0' = Bit is cleared

x = Bit is unknown

- bit 15 **U2TXIF:** UART2 Transmitter Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 14 **U2RXIF:** UART2 Receiver Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 13 **INT2IF:** External Interrupt 2 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 12 **T5IF:** Timer5 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 11 **T4IF:** Timer4 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 10 **OC4IF:** Output Compare Channel 4 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 9 **OC3IF:** Output Compare Channel 3 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 8 **DMA21IF:** DMA Channel 2 Data Transfer Complete Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 7 **IC8IF:** Input Capture Channel 8 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 6 **IC7IF:** Input Capture Channel 7 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 5 **AD2IF:** ADC2 Conversion Complete Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 4 **INT1IF:** External Interrupt 1 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

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FIGURE 8-1: TOP LEVEL SYSTEM ARCHITECTURE USING A DEDICATED TRANSACTION BUS



8.1 DMAC Registers

Each DMAC Channel x ($x = 0, 1, 2, 3, 4, 5, 6$ or 7) contains the following registers:

- A 16-bit DMA Channel Control register (DMAxCON)
- A 16-bit DMA Channel IRQ Select register (DMAxREQ)
- A 16-bit DMA RAM Primary Start Address Offset register (DMAxSTA)
- A 16-bit DMA RAM Secondary Start Address Offset register (DMAxSTB)
- A 16-bit DMA Peripheral Address register (DMAxPAD)
- A 10-bit DMA Transfer Count register (DMAxCNT)

An additional pair of status registers, DMACS0 and DMACS1 are common to all DMAC channels.

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REGISTER 15-1: OCxCON: OUTPUT COMPARE x CONTROL REGISTER (x = 1, 2)

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	—	OCSIDL	—	—	—	—	—
bit 15						bit 8	

U-0	U-0	U-0	R-0, HC	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	OCFLT	OCTSEL	OCM<2:0>		
bit 7						bit 0	

Legend:	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13	OCSIDL: Stop Output Compare in Idle Mode Control bit 1 = Output Compare x halts in CPU Idle mode 0 = Output Compare x continues to operate in CPU Idle mode
bit 12-5	Unimplemented: Read as '0'
bit 4	OCFLT: PWM Fault Condition Status bit 1 = PWM Fault condition has occurred (cleared in hardware only) 0 = No PWM Fault condition has occurred (this bit is only used when OCM<2:0> = 111)
bit 3	OCTSEL: Output Compare Timer Select bit 1 = Timer3 is the clock source for Compare x 0 = Timer2 is the clock source for Compare x
bit 2-0	OCM<2:0>: Output Compare Mode Select bits 111 = PWM mode on OCx, Fault pin enabled 110 = PWM mode on OCx, Fault pin disabled 101 = Initialize OCx pin low, generate continuous output pulses on OCx pin 100 = Initialize OCx pin low, generate single output pulse on OCx pin 011 = Compare event toggles OCx pin 010 = Initialize OCx pin high, compare event forces OCx pin low 001 = Initialize OCx pin low, compare event forces OCx pin high 000 = Output compare channel is disabled

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18.3 UART Control Registers

REGISTER 18-1: UxMODE: UARTx MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN ⁽¹⁾	—	USIDL	IREN ⁽²⁾	RTSMD	—	UEN<1:0>	
bit 15							bit 8

R/W-0 HC	R/W-0	R/W-0 HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL<1:0>		STSEL
bit 7							bit 0

Legend:	HC = Hardware cleared
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set
	U = Unimplemented bit, read as '0'
	'0' = Bit is cleared
	x = Bit is unknown

- bit 15 **UARTEN:** UARTx Enable bit⁽¹⁾
1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>
0 = UARTx is disabled; all UARTx pins are controlled by port latches; UARTx power consumption minimal
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **USIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode
- bit 12 **IREN:** IrDA[®] Encoder and Decoder Enable bit⁽²⁾
1 = IrDA[®] encoder and decoder enabled
0 = IrDA[®] encoder and decoder disabled
- bit 11 **RTSMD:** Mode Selection for $\overline{\text{UxRTS}}$ Pin bit
1 = $\overline{\text{UxRTS}}$ pin in Simplex mode
0 = $\overline{\text{UxRTS}}$ pin in Flow Control mode
- bit 10 **Unimplemented:** Read as '0'
- bit 9-8 **UEN<1:0>:** UARTx Enable bits
11 = UxTX, UxRX and BCLK pins are enabled and used; $\overline{\text{UxCTS}}$ pin controlled by port latches
10 = UxTX, UxRX, $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins are enabled and used
01 = UxTX, UxRX and $\overline{\text{UxRTS}}$ pins are enabled and used; $\overline{\text{UxCTS}}$ pin controlled by port latches
00 = UxTX and UxRX pins are enabled and used; $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS/BCLK}}$ pins controlled by port latches
- bit 7 **WAKE:** Wake-up on Start bit Detect During Sleep Mode Enable bit
1 = UARTx will continue to sample the UxRX pin; interrupt generated on falling edge; bit cleared in hardware on following rising edge
0 = No wake-up enabled
- bit 6 **LPBACK:** UARTx Loopback Mode Select bit
1 = Enable Loopback mode
0 = Loopback mode is disabled
- bit 5 **ABAUD:** Auto-Baud Enable bit
1 = Enable baud rate measurement on the next character – requires reception of a Sync field (0x55) before any data; cleared in hardware upon completion
0 = Baud rate measurement disabled or completed

Note 1: Refer to **Section 17. “UART”** (DS70188) in the “*dsPIC33F/PIC24H Family Reference Manual*” for information on enabling the UART module for receive or transmit operation.

2: This feature is only available for the 16x BRG mode (BRGH = 0).

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REGISTER 18-1: UxMODE: UARTx MODE REGISTER (CONTINUED)

bit 4	URXINV: Receive Polarity Inversion bit 1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	BRGH: High Baud Rate Enable bit 1 = BRG generates 4 clocks per bit period (4x baud clock, High-Speed mode) 0 = BRG generates 16 clocks per bit period (16x baud clock, Standard mode)
bit 2-1	PDSEL<1:0>: Parity and Data Selection bits 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	STSEL: Stop Bit Selection bit 1 = Two Stop bits 0 = One Stop bit

- Note 1:** Refer to **Section 17. "UART"** (DS70188) in the *"dsPIC33F/PIC24H Family Reference Manual"* for information on enabling the UART module for receive or transmit operation.
- 2:** This feature is only available for the 16x BRG mode (BRGH = 0).

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REGISTER 19-14: CiBUPNT3: ECAN™ MODULE FILTER 8-11 BUFFER POINTER REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F11BP<3:0>				F10BP<3:0>			
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F9BP<3:0>				F8BP<3:0>			
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12 **F11BP<3:0>**: RX Buffer Written when Filter 11 Hits bits

1111 = Filter hits received in RX FIFO buffer

1110 = Filter hits received in RX Buffer 14

•
•
•

0001 = Filter hits received in RX Buffer 1

0000 = Filter hits received in RX Buffer 0

bit 11-8 **F10BP<3:0>**: RX Buffer Written when Filter 10 Hits bits

1111 = Filter hits received in RX FIFO buffer

1110 = Filter hits received in RX Buffer 14

•
•
•

0001 = Filter hits received in RX Buffer 1

0000 = Filter hits received in RX Buffer 0

bit 7-4 **F9BP<3:0>**: RX Buffer Written when Filter 9 Hits bits

1111 = Filter hits received in RX FIFO buffer

1110 = Filter hits received in RX Buffer 14

•
•
•

0001 = Filter hits received in RX Buffer 1

0000 = Filter hits received in RX Buffer 0

bit 3-0 **F8BP<3:0>**: RX Buffer Written when Filter 8 Hits bits

1111 = Filter hits received in RX FIFO buffer

1110 = Filter hits received in RX Buffer 14

•
•
•

0001 = Filter hits received in RX Buffer 1

0000 = Filter hits received in RX Buffer 0

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REGISTER 19-20: CiRXMnSID: ECAN™ MODULE ACCEPTANCE FILTER MASK n STANDARD IDENTIFIER

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
SID<10:3>							
bit 15				bit 8			

R/W-x	R/W-x	R/W-x	U-0	R/W-x	U-0	R/W-x	R/W-x
SID<2:0>			—	MIDE	—	EID<17:16>	
bit 7			bit 0				

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-5 **SID<10:0>**: Standard Identifier bits
 1 = Include bit SIDx in filter comparison
 0 = Bit SIDx is don't care in filter comparison
- bit 4 **Unimplemented**: Read as '0'
- bit 3 **MIDE**: Identifier Receive Mode bit
 1 = Match only message types (standard or extended address) that correspond to EXIDE bit in filter
 0 = Match either standard or extended address message if filters match
 (i.e., if (Filter SID) = (Message SID) or if (Filter SID/EID) = (Message SID/EID))
- bit 2 **Unimplemented**: Read as '0'
- bit 1-0 **EID<17:16>**: Extended Identifier bits
 1 = Include bit EIDx in filter comparison
 0 = Bit EIDx is don't care in filter comparison

REGISTER 19-21: CiRXMnEID: ECAN™ TECHNOLOGY ACCEPTANCE FILTER MASK n EXTENDED IDENTIFIER

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID<15:8>							
bit 15				bit 8			

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-0 **EID<15:0>**: Extended Identifier bits
 1 = Include bit EIDx in filter comparison
 0 = Bit EIDx is don't care in filter comparison

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21.0 SPECIAL FEATURES

- Note 1:** This data sheet summarizes the features of the PIC24HJXXXGPX06A/X08A/X10A families of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 23. “CodeGuard™ Security”** (DS70199), **Section 24. “Programming and Diagnostics”** (DS70207), and **Section 25. “Device Configuration”** (DS70194) in the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site (www.microchip.com).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

PIC24HJXXXGPX06A/X08A/X10A devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection and CodeGuard™ Security
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming™ (ICSP™) programming capability
- In-Circuit Emulation

21.1 Configuration Bits

PIC24HJXXXGPX06A/X08A/X10A devices provide nonvolatile memory implementation for device configuration bits. Refer to **Section 25. “Device Configuration”** (DS70194) of the “*dsPIC33F/PIC24H Family Reference Manual*”, for more information on this implementation.

The Configuration bits can be programmed (read as ‘0’), or left unprogrammed (read as ‘1’), to select various device configurations. These bits are mapped starting at program memory location 0xF80000.

The device Configuration register map is shown in Table 21-1.

The individual Configuration bit descriptions for the Configuration registers are shown in Table 21-2.

Note that address 0xF80000 is beyond the user program memory space. In fact, it belongs to the configuration memory space (0x800000-0xFFFFF), which can only be accessed using table reads and table writes.

TABLE 21-1: DEVICE CONFIGURATION REGISTER MAP

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xF80000	FBS	RBS<1:0>		—	—	BSS<2:0>			BWRP
0xF80002	FSS	RSS<1:0>		—	—	SSS<2:0>			SWRP
0xF80004	FGS	—	—	—	—	—	GSS<1:0>		GWRP
0xF80006	FOSCSEL	IESO	Reserved ⁽²⁾	—	—	—	FNOSC<2:0>		
0xF80008	FOSC	FCKSM<1:0>		—	—	—	OSCIOFNC	POSCMD<1:0>	
0xF8000A	FWDT	FWDTEN	WINDIS	PLLKEN ⁽³⁾	WDTPRE	WDTPOST<3:0>			
0xF8000C	FPOR	Reserved ⁽⁴⁾			—	—	FPWRT<2:0>		
0xF8000E	FICD	Reserved ⁽¹⁾		JTAGEN	—	—	—	ICS<1:0>	
0xF80010	FUID0	User Unit ID Byte 0							
0xF80012	FUID1	User Unit ID Byte 1							
0xF80014	FUID2	User Unit ID Byte 2							
0xF80016	FUID3	User Unit ID Byte 3							

Legend: — = unimplemented bits, read as ‘0’.

Note 1: These bits are reserved for use by development tools and must be programmed as ‘1’.

2: When read, this bit returns the current programmed value.

3: This bit is unimplemented on PIC24HJ64GPX06A/X08A/X10A and PIC24HJ128GPX06A/X08A/X10A devices and reads as ‘0’.

4: These bits are reserved and always read as ‘1’.

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TABLE 22-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
47	RCALL	RCALL Expr	Relative Call	1	2	None
		RCALL Wn	Computed Call	1	2	None
48	REPEAT	REPEAT #lit14	Repeat Next Instruction lit14 + 1 times	1	1	None
		REPEAT Wn	Repeat Next Instruction (Wn) + 1 times	1	1	None
49	RESET	RESET	Software device Reset	1	1	None
50	RETFIE	RETFIE	Return from interrupt	1	3 (2)	None
51	RETLW	RETLW #lit10, Wn	Return with literal in Wn	1	3 (2)	None
52	RETURN	RETURN	Return from Subroutine	1	3 (2)	None
53	RLC	RLC f	f = Rotate Left through Carry f	1	1	C,N,Z
		RLC f, WREG	WREG = Rotate Left through Carry f	1	1	C,N,Z
		RLC Ws, Wd	Wd = Rotate Left through Carry Ws	1	1	C,N,Z
54	RLNC	RLNC f	f = Rotate Left (No Carry) f	1	1	N,Z
		RLNC f, WREG	WREG = Rotate Left (No Carry) f	1	1	N,Z
		RLNC Ws, Wd	Wd = Rotate Left (No Carry) Ws	1	1	N,Z
55	RRC	RRC f	f = Rotate Right through Carry f	1	1	C,N,Z
		RRC f, WREG	WREG = Rotate Right through Carry f	1	1	C,N,Z
		RRC Ws, Wd	Wd = Rotate Right through Carry Ws	1	1	C,N,Z
56	RRNC	RRNC f	f = Rotate Right (No Carry) f	1	1	N,Z
		RRNC f, WREG	WREG = Rotate Right (No Carry) f	1	1	N,Z
		RRNC Ws, Wd	Wd = Rotate Right (No Carry) Ws	1	1	N,Z
57	SE	SE Ws, Wnd	Wnd = sign-extended Ws	1	1	C,N,Z
58	SETM	SETM f	f = 0xFFFF	1	1	None
		SETM WREG	WREG = 0xFFFF	1	1	None
		SETM Ws	Ws = 0xFFFF	1	1	None
59	SL	SL f	f = Left Shift f	1	1	C,N,OV,Z
		SL f, WREG	WREG = Left Shift f	1	1	C,N,OV,Z
		SL Ws, Wd	Wd = Left Shift Ws	1	1	C,N,OV,Z
		SL Wb, Wns, Wnd	Wnd = Left Shift Wb by Wns	1	1	N,Z
		SL Wb, #lit5, Wnd	Wnd = Left Shift Wb by lit5	1	1	N,Z
60	SUB	SUB f	f = f – WREG	1	1	C,DC,N,OV,Z
		SUB f, WREG	WREG = f – WREG	1	1	C,DC,N,OV,Z
		SUB #lit10, Wn	Wn = Wn – lit10	1	1	C,DC,N,OV,Z
		SUB Wb, Ws, Wd	Wd = Wb – Ws	1	1	C,DC,N,OV,Z
		SUB Wb, #lit5, Wd	Wd = Wb – lit5	1	1	C,DC,N,OV,Z
61	SUBB	SUBB f	f = f – WREG – ($\overline{C}$)	1	1	C,DC,N,OV,Z
		SUBB f, WREG	WREG = f – WREG – ($\overline{C}$)	1	1	C,DC,N,OV,Z
		SUBB #lit10, Wn	Wn = Wn – lit10 – ($\overline{C}$)	1	1	C,DC,N,OV,Z
		SUBB Wb, Ws, Wd	Wd = Wb – Ws – ($\overline{C}$)	1	1	C,DC,N,OV,Z
		SUBB Wb, #lit5, Wd	Wd = Wb – lit5 – ($\overline{C}$)	1	1	C,DC,N,OV,Z
62	SUBR	SUBR f	f = WREG – f	1	1	C,DC,N,OV,Z
		SUBR f, WREG	WREG = WREG – f	1	1	C,DC,N,OV,Z
		SUBR Wb, Ws, Wd	Wd = Ws – Wb	1	1	C,DC,N,OV,Z
		SUBR Wb, #lit5, Wd	Wd = lit5 – Wb	1	1	C,DC,N,OV,Z
63	SUBBR	SUBBR f	f = WREG – f – ($\overline{C}$)	1	1	C,DC,N,OV,Z
		SUBBR f, WREG	WREG = WREG – f – ($\overline{C}$)	1	1	C,DC,N,OV,Z
		SUBBR Wb, Ws, Wd	Wd = Ws – Wb – ($\overline{C}$)	1	1	C,DC,N,OV,Z
		SUBBR Wb, #lit5, Wd	Wd = lit5 – Wb – ($\overline{C}$)	1	1	C,DC,N,OV,Z
64	SWAP	SWAP.b Wn	Wn = nibble swap Wn	1	1	None
		SWAP Wn	Wn = byte swap Wn	1	1	None
65	TBLRDH	TBLRDH Ws, Wd	Read Prog<23:16> to Wd<7:0>	1	2	None

23.7 MPLAB SIM Software Simulator

The MPLAB SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC® DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB SIM Software Simulator fully supports symbolic debugging using the MPLAB C Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

23.8 MPLAB REAL ICE In-Circuit Emulator System

MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs PIC® Flash MCUs and dsPIC® Flash DSCs with the easy-to-use, powerful graphical user interface of the MPLAB Integrated Development Environment (IDE), included with each kit.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB IDE. In upcoming releases of MPLAB IDE, new devices will be supported, and new features will be added. MPLAB REAL ICE offers significant advantages over competitive emulators including low-cost, full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, a ruggedized probe interface and long (up to three meters) interconnection cables.

23.9 MPLAB ICD 3 In-Circuit Debugger System

MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost effective high-speed hardware debugger/programmer for Microchip Flash Digital Signal Controller (DSC) and microcontroller (MCU) devices. It debugs and programs PIC® Flash microcontrollers and dsPIC® DSCs with the powerful, yet easy-to-use graphical user interface of MPLAB Integrated Development Environment (IDE).

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

23.10 PICkit 3 In-Circuit Debugger/Programmer and PICkit 3 Debug Express

The MPLAB PICkit 3 allows debugging and programming of PIC® and dsPIC® Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB Integrated Development Environment (IDE). The MPLAB PICkit 3 is connected to the design engineer's PC using a full speed USB interface and can be connected to the target via an Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the reset line to implement in-circuit debugging and In-Circuit Serial Programming™.

The PICkit 3 Debug Express include the PICkit 3, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

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TABLE 24-11: ELECTRICAL CHARACTERISTICS: BOR

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic ⁽¹⁾	Min ⁽¹⁾	Typ	Max ⁽¹⁾	Units	Conditions
BO10	VBOR	BOR Event on VDD transition high-to-low	2.40	—	2.55	V	VDD

Note 1: Parameters are for design guidance only and are not tested in manufacturing.

TABLE 24-12: DC CHARACTERISTICS: PROGRAM MEMORY

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ ⁽¹⁾	Max	Units	Conditions
D130	EP	Program Flash Memory Cell Endurance	10,000	—	—	E/W	VMIN = Minimum operating voltage VMIN = Minimum operating voltage Provided no other specifications are violated TRW = 11064 FRC cycles, TA = +85°C, See Note 2 TRW = 11064 FRC cycles, TA = +150°C, See Note 2 TPE = 168517 FRC cycles, TA = +85°C, See Note 2 TPE = 168517 FRC cycles, TA = +150°C, See Note 2 TWW = 355 FRC cycles, TA = +85°C, See Note 2 TWW = 355 FRC cycles, TA = +150°C, See Note 2
D131	VPR	VDD for Read	VMIN	—	3.6	V	
D132b	VPEW	VDD for Self-Timed Write	VMIN	—	3.6	V	
D134	TRETD	Characteristic Retention	20	—	—	Year	
D135	IDDP	Supply Current during Programming	—	10	—	mA	
D136a	TRW	Row Write Time	1.32	—	1.74	ms	
D136b	TRW	Row Write Time	1.28	—	1.79	ms	
D137a	TPE	Page Erase Time	20.1	—	26.5	ms	
D137b	TPE	Page Erase Time	19.5	—	27.3	ms	
D138a	TWW	Word Write Cycle Time	42.3	—	55.9	μs	
D138b	TWW	Word Write Cycle Time	41.1	—	57.6	μs	

Note 1: Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

2: Other conditions: FRC = 7.37 MHz, TUN<5:0> = b' 011111 (for Min), TUN<5:0> = b' 100000 (for Max). This parameter depends on the FRC accuracy (see Table 24-19) and the value of the FRC Oscillator Tuning register (see Register 9-4). For complete details on calculating the Minimum and Maximum time see Section 5.3 “Programming Operations”.

TABLE 24-13: INTERNAL VOLTAGE REGULATOR SPECIFICATIONS

Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended							
Param.	Symbol	Characteristics	Min	Typ	Max	Units	Comments
	CEFC	External Filter Capacitor Value	4.7	10	—	μF	Capacitor must be low series resistance (< 5 Ohms)

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TABLE 24-41: ADC MODULE SPECIFICATIONS (10-BIT MODE)⁽¹⁾

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ	Max.	Units	Conditions
ADC Accuracy (10-bit Mode) – Measurements with external VREF+/VREF-							
AD20b	Nr	Resolution	10 data bits			bits	
AD21b	INL	Integral Nonlinearity	-1.5	—	+1.5	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD22b	DNL	Differential Nonlinearity	>-1	—	<1	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD23b	GERR	Gain Error	—	3	6	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD24b	EOFF	Offset Error	—	2	5	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD25b	—	Monotonicity	—	—	—	—	Guaranteed
ADC Accuracy (10-bit Mode) – Measurements with internal VREF+/VREF-							
AD20b	Nr	Resolution	10 data bits			bits	
AD21b	INL	Integral Nonlinearity	-1	—	+1	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD22b	DNL	Differential Nonlinearity	>-1	—	<1	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD23b	GERR	Gain Error	—	7	15	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD24b	EOFF	Offset Error	—	3	7	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD25b	—	Monotonicity	—	—	—	—	Guaranteed
Dynamic Performance (10-bit Mode)							
AD30b	THD	Total Harmonic Distortion	—	—	-64	dB	—
AD31b	SINAD	Signal to Noise and Distortion	57	58.5	—	dB	—
AD32b	SFDR	Spurious Free Dynamic Range	72	—	—	dB	—
AD33b	FNYQ	Input Signal Bandwidth	—	—	550	kHz	—
AD34b	ENOB	Effective Number of Bits	9.16	9.4	—	bits	—

Note 1: Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts (i.e., VIH source > (VDD + 0.3) or VIL source < (VSS – 0.3)).

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