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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	53
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 18x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24hj128gp306a-e-pt">https://www.e-xfl.com/product-detail/microchip-technology/pic24hj128gp306a-e-pt</a>

TABLE 4-15: ADC1 REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUF0	0300	ADC Data Buffer 0																xxxx
AD1CON1	0320	ADON	—	ADSIDL	ADDMABM	—	AD12B	FORM<1:0>		SSRC<2:0>			—	SIMSAM	ASAM	SAMP	DONE	0000
AD1CON2	0322	VCFG<2:0>			—	—	CSCNA	CHPS<1:0>		BUFS	—	SMPI<3:0>				BUFM	ALTS	0000
AD1CON3	0324	ADRC	—	—	SAMC<4:0>					ADCS<7:0>							0000	
AD1CHS123	0326	—	—	—	—	—	CH123NB<1:0>		CH123SB	—	—	—	—	—	CH123NA<1:0>		CH123SA	0000
AD1CHS0	0328	CH0NB	—	—	CH0SB<4:0>					CH0NA	—	—	CH0SA<4:0>					0000
AD1PCFGH <sup>(1)</sup>	032A	PCFG31	PCFG30	PCFG29	PCFG28	PCFG27	PCFG26	PCFG25	PCFG24	PCFG23	PCFG22	PCFG21	PCFG20	PCFG19	PCFG18	PCFG17	PCFG16	0000
AD1PCFGL	032C	PCFG15	PCFG14	PCFG13	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8	PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0	0000
AD1CSSH <sup>(1)</sup>	032E	CSS31	CSS30	CSS29	CSS28	CSS27	CSS26	CSS25	CSS24	CSS23	CSS22	CSS21	CSS20	CSS19	CSS18	CSS17	CSS16	0000
AD1CSSL	0330	CSS15	CSS14	CSS13	CSS12	CSS11	CSS10	CSS9	CSS8	CSS7	CSS6	CSS5	CSS4	CSS3	CSS2	CSS1	CSS0	0000
AD1CON4	0332	—	—	—	—	—	—	—	—	—	—	—	—	—	DMABL<2:0>			0000
Reserved	0334-033E	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

**Note 1:** Not all ANx inputs are available on all devices. See the device pin diagrams for available ANx inputs.

TABLE 4-16: ADC2 REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC2BUF0	0340	ADC Data Buffer 0																xxxx
AD2CON1	0360	ADON	—	ADSIDL	ADDMABM	—	AD12B	FORM<1:0>		SSRC<2:0>			—	SIMSAM	ASAM	SAMP	DONE	0000
AD2CON2	0362	VCFG<2:0>			—	—	CSCNA	CHPS<1:0>		BUFS	—	SMPI<3:0>				BUFM	ALTS	0000
AD2CON3	0364	ADRC	—	—	SAMC<4:0>				ADCS<7:0>									0000
AD2CHS123	0366	—	—	—	—	—	CH123NB<1:0>		CH123SB	—	—	—	—	—	CH123NA<1:0>		CH123SA	0000
AD2CHS0	0368	CH0NB	—	—	—	CH0SB<3:0>				CH0NA	—	—	—	CH0SA<3:0>				0000
Reserved	036A	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
AD2PCFGL	036C	PCFG15	PCFG14	PCFG13	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8	PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0	0000
Reserved	036E	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
AD2CSSL	0370	CSS15	CSS14	CSS13	CSS12	CSS11	CSS10	CSS9	CSS8	CSS7	CSS6	CSS5	CSS4	CSS3	CSS2	CSS1	CSS0	0000
AD2CON4	0372	—	—	—	—	—	—	—	—	—	—	—	—	—	DMABL<2:0>			0000
Reserved	0374-037E	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal for PinHigh devices.

## 7.0 INTERRUPT CONTROLLER

**Note 1:** This data sheet summarizes the features of the PIC24HJXXXGPX06A/X08A/X10A family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 6. “Interrupts”** (DS70184) of the *“dsPIC33F/PIC24H Family Reference Manual”*, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The PIC24HJXXXGPX06A/X08A/X10A interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the PIC24HJXXXGPX06A/X08A/X10A CPU. It has the following features:

- Up to 8 processor exceptions and software traps
- 7 user-selectable priority levels
- Interrupt Vector Table (IVT) with up to 118 vectors
- A unique vector for each interrupt or exception source
- Fixed priority within a specified user priority level
- Alternate Interrupt Vector Table (AIVT) for debug support
- Fixed interrupt entry and return latencies

### 7.1 Interrupt Vector Table

The Interrupt Vector Table (IVT) is shown in Figure 7-1. The IVT resides in program memory, starting at location 000004h. The IVT contains 126 vectors consisting of 8 nonmaskable trap vectors plus up to 118 sources of interrupt. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority; this priority is linked to their position in the vector table. All other things being equal, lower addresses have a higher natural priority. For example, the interrupt associated with vector 0 will take priority over interrupts at any other vector address.

PIC24HJXXXGPX06A/X08A/X10A devices implement up to 61 unique interrupts and 5 nonmaskable traps. These are summarized in Table 7-1 and Table 7-2.

#### 7.1.1 ALTERNATE VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT) is located after the IVT, as shown in Figure 7-1. Access to the AIVT is provided by the ALTIVT control bit (INTCON2<15>). If the ALTIVT bit is set, all interrupt and exception processes use the alternate vectors instead of the default vectors. The alternate vectors are organized in the same manner as the default vectors.

The AIVT supports debugging by providing a means to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications for evaluation of different software algorithms at run time. If the AIVT is not needed, the AIVT should be programmed with the same addresses used in the IVT.

## 7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The PIC24HJXXXGPX06A/X08A/X10A device clears its registers in response to a Reset which forces the PC to zero. The digital signal controller then begins program execution at location 0x000000. The user programs a GOTO instruction at the Reset address which redirects program execution to the appropriate start-up routine.

**Note:** Any unimplemented or unused vector locations in the IVT and AIVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.

# PIC24HJXXXGPX06A/X08A/X10A

## REGISTER 7-13: IEC3: INTERRUPT ENABLE CONTROL REGISTER 3

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0
—	—	DMA5IE	—	—	—	—	C2IE
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
C2RXIE	INT4IE	INT3IE	T9IE	T8IE	MI2C2IE	SI2C2IE	T7IE
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **DMA5IE:** DMA Channel 5 Data Transfer Complete Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 12-9 **Unimplemented:** Read as '0'

bit 8 **C2IE:** ECAN2 Event Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 7 **C2RXIE:** ECAN2 Receive Data Ready Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 6 **INT4IE:** External Interrupt 4 Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 5 **INT3IE:** External Interrupt 3 Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 4 **T9IE:** Timer9 Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 3 **T8IE:** Timer8 Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 2 **MI2C2IE:** I2C2 Master Events Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 1 **SI2C2IE:** I2C2 Slave Events Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

bit 0 **T7IE:** Timer7 Interrupt Enable bit

1 = Interrupt request enabled

0 = Interrupt request not enabled

# PIC24HJXXXGPX06A/X08A/X10A

## REGISTER 7-17: IPC2: INTERRUPT PRIORITY CONTROL REGISTER 2

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	U1RXIP<2:0>			—	SPI1IP<2:0>		
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	SPI1EIP<2:0>			—	T3IP<2:0>		
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **U1RXIP<2:0>:** UART1 Receiver Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **SPI1IP<2:0>:** SPI1 Event Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **SPI1EIP<2:0>:** SPI1 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **T3IP<2:0>:** Timer3 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

# PIC24HJXXXGPX06A/X08A/X10A

## REGISTER 7-24: IPC9: INTERRUPT PRIORITY CONTROL REGISTER 9

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	IC5IP<2:0>			—	IC4IP<2:0>		
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	IC3IP<2:0>			—	DMA3IP<2:0>		
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **IC5IP<2:0>:** Input Capture Channel 5 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **IC4IP<2:0>:** Input Capture Channel 4 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **IC3IP<2:0>:** Input Capture Channel 3 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **DMA3IP<2:0>:** DMA Channel 3 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

# PIC24HJXXXGPX06A/X08A/X10A

**REGISTER 8-5: DMAxPAD: DMA CHANNEL x PERIPHERAL ADDRESS REGISTER<sup>(1)</sup>**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PAD<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PAD<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **PAD<15:0>**: Peripheral Address Register bits

**Note 1:** If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

**REGISTER 8-6: DMAxCNT: DMA CHANNEL x TRANSFER COUNT REGISTER<sup>(1)</sup>**

U-0		U-0		U-0		U-0		U-0		U-0		R/W-0		R/W-0	
—		—		—		—		—		—		CNT<9:8> <sup>(2)</sup>			
bit 15												bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CNT<7:0> <sup>(2)</sup>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-10      **Unimplemented:** Read as '0'

bit 9-0      **CNT<9:0>**: DMA Transfer Count Register bits<sup>(2)</sup>

**Note 1:** If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

**2:** Number of DMA transfers = CNT<9:0> + 1.

# PIC24HJXXXGPX06A/X08A/X10A

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## REGISTER 10-2: PMD2: PERIPHERAL MODULE DISABLE CONTROL REGISTER 2 (CONTINUED)

bit 3	<b>OC4MD:</b> Output Compare 4 Module Disable bit 1 = Output Compare 4 module is disabled 0 = Output Compare 4 module is enabled
bit 2	<b>OC3MD:</b> Output Compare 3 Module Disable bit 1 = Output Compare 3 module is disabled 0 = Output Compare 3 module is enabled
bit 1	<b>OC2MD:</b> Output Compare 2 Module Disable bit 1 = Output Compare 2 module is disabled 0 = Output Compare 2 module is enabled
bit 0	<b>OC1MD:</b> Output Compare 1 Module Disable bit 1 = Output Compare 1 module is disabled 0 = Output Compare 1 module is enabled



# PIC24HJXXXGPX06A/X08A/X10A

**REGISTER 15-1: OCxCON: OUTPUT COMPARE x CONTROL REGISTER (x = 1, 2)**

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	—	OCSIDL	—	—	—	—	—
bit 15						bit 8	

U-0	U-0	U-0	R-0, HC	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	OCFLT	OCTSEL	OCM<2:0>		
bit 7						bit 0	

<b>Legend:</b>	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-14    **Unimplemented:** Read as '0'
- bit 13    **OCSIDL:** Stop Output Compare in Idle Mode Control bit  
           1 = Output Compare x halts in CPU Idle mode  
           0 = Output Compare x continues to operate in CPU Idle mode
- bit 12-5    **Unimplemented:** Read as '0'
- bit 4    **OCFLT:** PWM Fault Condition Status bit  
           1 = PWM Fault condition has occurred (cleared in hardware only)  
           0 = No PWM Fault condition has occurred (this bit is only used when OCM<2:0> = 111)
- bit 3    **OCTSEL:** Output Compare Timer Select bit  
           1 = Timer3 is the clock source for Compare x  
           0 = Timer2 is the clock source for Compare x
- bit 2-0    **OCM<2:0>:** Output Compare Mode Select bits  
           111 = PWM mode on OCx, Fault pin enabled  
           110 = PWM mode on OCx, Fault pin disabled  
           101 = Initialize OCx pin low, generate continuous output pulses on OCx pin  
           100 = Initialize OCx pin low, generate single output pulse on OCx pin  
           011 = Compare event toggles OCx pin  
           010 = Initialize OCx pin high, compare event forces OCx pin low  
           001 = Initialize OCx pin low, compare event forces OCx pin high  
           000 = Output compare channel is disabled

# PIC24HJXXXGPX06A/X08A/X10A

## REGISTER 19-19: CifMSKSEL2: ECAN™ FILTER 15-8 MASK SELECTION REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F15MSK<1:0>		F14MSK<1:0>		F13MSK<1:0>		F12MSK<1:0>	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F11MSK<1:0>		F10MSK<1:0>		F9MSK<1:0>		F8MSK<1:0>	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

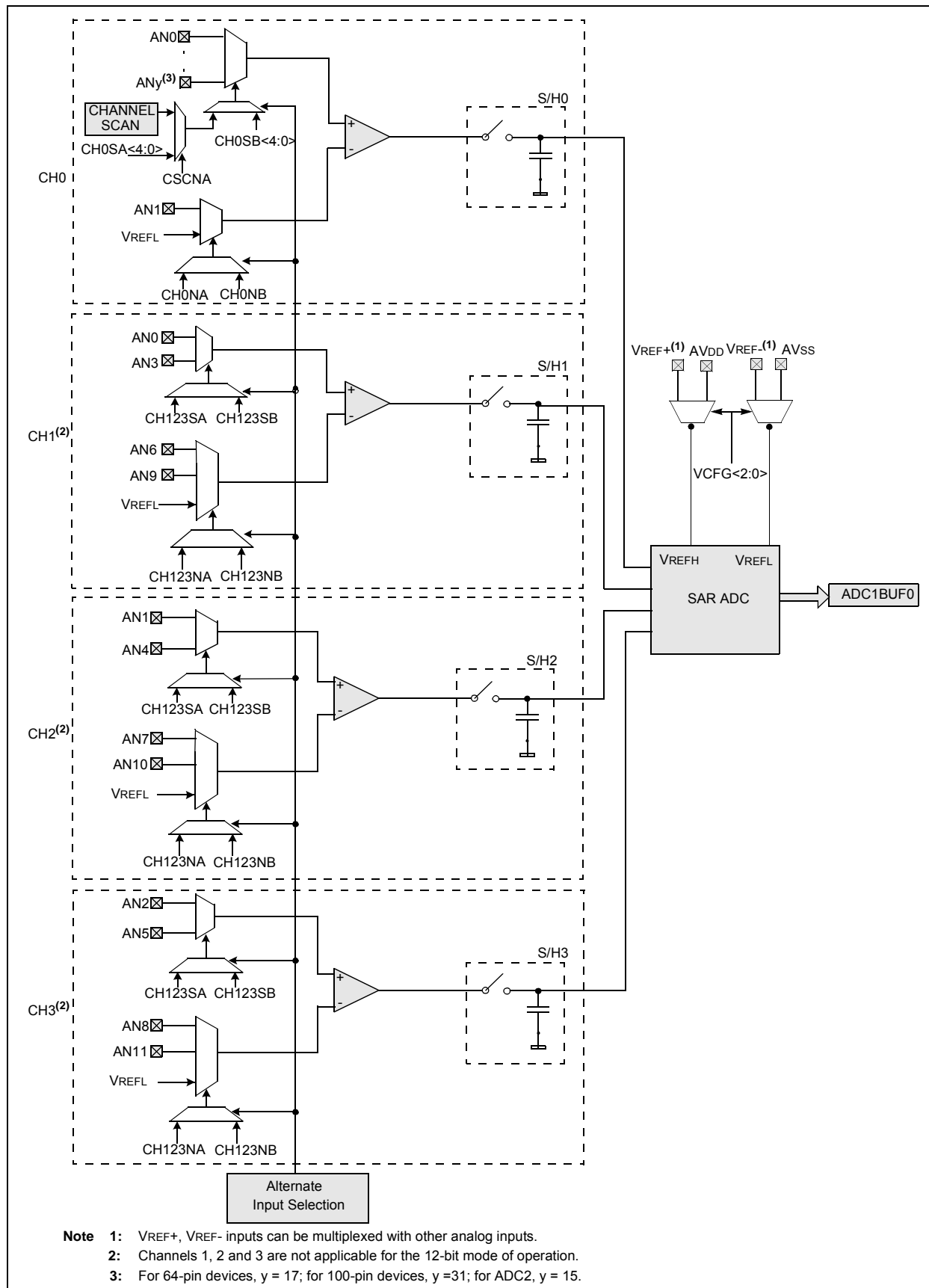
'0' = Bit is cleared

x = Bit is unknown

- bit 15-14      **F15MSK<1:0>**: Mask Source for Filter 15 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask
- bit 13-12      **F14MSK<1:0>**: Mask Source for Filter 14 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask
- bit 11-10      **F13MSK<1:0>**: Mask Source for Filter 13 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask
- bit 9-8        **F12MSK<1:0>**: Mask Source for Filter 12 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask
- bit 7-6        **F11MSK<1:0>**: Mask Source for Filter 11 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask
- bit 5-4        **F10MSK<1:0>**: Mask Source for Filter 10 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask
- bit 3-2        **F9MSK<1:0>**: Mask Source for Filter 9 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask
- bit 1-0        **F8MSK<1:0>**: Mask Source for Filter 8 bit  
11 = Reserved; do not use  
10 = Acceptance Mask 2 registers contain mask  
01 = Acceptance Mask 1 registers contain mask  
00 = Acceptance Mask 0 registers contain mask

# PIC24HJXXXGPX06A/X08A/X10A

**FIGURE 20-1: ADCx MODULE BLOCK DIAGRAM**



# PIC24HJXXXGPX06A/X08A/X10A

## 20.6 ADC Control Registers

**REGISTER 20-1: ADxCON1: ADCx CONTROL REGISTER 1(where x = 1 or 2)**

R/W-0	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
ADON	—	ADSIDL	ADDMABM	—	AD12B	FORM<1:0>	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0 HC,HS	R/C-0 HC, HS
SSRC<2:0>			—	SIMSAM	ASAM	SAMP	DONE
bit 7							bit 0

<b>Legend:</b>	HC = Cleared by hardware	HS = Set by hardware
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15 **ADON:** ADC Operating Mode bit  
1 = ADC module is operating  
0 = ADC module is off
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **ADSIDL:** Stop in Idle Mode bit  
1 = Discontinue module operation when device enters Idle mode  
0 = Continue module operation in Idle mode
- bit 12 **ADDMABM:** DMA Buffer Build Mode bit  
1 = DMA buffers are written in the order of conversion. The module will provide an address to the DMA channel that is the same as the address used for the non-DMA stand-alone buffer  
0 = DMA buffers are written in Scatter/Gather mode. The module will provide a scatter/gather address to the DMA channel, based on the index of the analog input and the size of the DMA buffer
- bit 11 **Unimplemented:** Read as '0'
- bit 10 **AD12B:** 10-Bit or 12-Bit Operation Mode bit  
1 = 12-bit, 1-channel ADC operation  
0 = 10-bit, 4-channel ADC operation
- bit 9-8 **FORM<1:0>:** Data Output Format bits  
For 10-bit operation:  
11 = Reserved  
10 = Reserved  
01 = Signed integer (DOUT = ssss sssd dddd dddd, where s = .NOT.d<9>)  
00 = Integer (DOUT = 0000 00dd dddd dddd)  
For 12-bit operation:  
11 = Reserved  
10 = Reserved  
01 = Signed Integer (DOUT = ssss sddd dddd dddd, where s = .NOT.d<11>)  
00 = Integer (DOUT = 0000 dddd dddd dddd)
- bit 7-5 **SSRC<2:0>:** Sample Clock Source Select bits  
111 = Internal counter ends sampling and starts conversion (auto-convert)  
110 = Reserved  
101 = Reserved  
100 = GP timer (Timer5 for ADC1, Timer3 for ADC2) compare ends sampling and starts conversion  
011 = Reserved  
010 = GP timer (Timer3 for ADC1, Timer5 for ADC2) compare ends sampling and starts conversion  
001 = Active transition on INT0 pin ends sampling and starts conversion  
000 = Clearing sample bit ends sampling and starts conversion

# PIC24HJXXXGPX06A/X08A/X10A

## REGISTER 20-10: ADxPCFGL: ADCx PORT CONFIGURATION REGISTER LOW<sup>(1,2,3,4)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCFG15	PCFG14	PCFG13	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **PCFG<15:0>**: ADC Port Configuration Control bits

1 = Port pin in Digital mode, port read input enabled, ADC input multiplexer connected to AVss

0 = Port pin in Analog mode, port read input disabled, ADC samples pin voltage

- Note 1:** On devices without 16 analog inputs, all PCFG bits are R/W by user. However, PCFG bits are ignored on ports without a corresponding input on device.
- 2:** On devices with 2 analog-to-digital modules, both AD1PCFGL and AD2PCFGL will affect the configuration of port pins multiplexed with AN0-AN15.
- 3:** PCFGx = ANx, where x = 0 through 15.
- 4:** PCFGx bits will have no effect if ADC module is disabled by setting ADxMD bit in the PMDx register. In this case all port pins multiplexed with ANx will be in Digital mode.

# PIC24HJXXXGPX06A/X08A/X10A

## 21.0 SPECIAL FEATURES

- Note 1:** This data sheet summarizes the features of the PIC24HJXXXGPX06A/X08A/X10A families of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 23. “CodeGuard™ Security”** (DS70199), **Section 24. “Programming and Diagnostics”** (DS70207), and **Section 25. “Device Configuration”** (DS70194) in the “dsPIC33F/PIC24H Family Reference Manual”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

PIC24HJXXXGPX06A/X08A/X10A devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection and CodeGuard™ Security
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming™ (ICSP™) programming capability
- In-Circuit Emulation

## 21.1 Configuration Bits

PIC24HJXXXGPX06A/X08A/X10A devices provide nonvolatile memory implementation for device configuration bits. Refer to **Section 25. “Device Configuration”** (DS70194) of the “dsPIC33F/PIC24H Family Reference Manual”, for more information on this implementation.

The Configuration bits can be programmed (read as ‘0’), or left unprogrammed (read as ‘1’), to select various device configurations. These bits are mapped starting at program memory location 0xF80000.

The device Configuration register map is shown in Table 21-1.

The individual Configuration bit descriptions for the Configuration registers are shown in Table 21-2.

Note that address 0xF80000 is beyond the user program memory space. In fact, it belongs to the configuration memory space (0x800000-0xFFFFF), which can only be accessed using table reads and table writes.

**TABLE 21-1: DEVICE CONFIGURATION REGISTER MAP**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xF80000	FBS	RBS<1:0>		—	—	BSS<2:0>			BWRP
0xF80002	FSS	RSS<1:0>		—	—	SSS<2:0>			SWRP
0xF80004	FGS	—	—	—	—	—	GSS<1:0>		GWRP
0xF80006	FOSCSEL	IESO	Reserved <sup>(2)</sup>	—	—	—	FNOSC<2:0>		
0xF80008	FOSC	FCKSM<1:0>		—	—	—	OSCIOFNC	POSCMD<1:0>	
0xF8000A	FWDT	FWDTEN	WINDIS	PLLKEN <sup>(3)</sup>	WDTPRE	WDTPOST<3:0>			
0xF8000C	FPOR	Reserved <sup>(4)</sup>			—	—	FPWRT<2:0>		
0xF8000E	FICD	Reserved <sup>(1)</sup>		JTAGEN	—	—	—	ICS<1:0>	
0xF80010	FUID0	User Unit ID Byte 0							
0xF80012	FUID1	User Unit ID Byte 1							
0xF80014	FUID2	User Unit ID Byte 2							
0xF80016	FUID3	User Unit ID Byte 3							

**Legend:** — = unimplemented bits, read as ‘0’.

**Note 1:** These bits are reserved for use by development tools and must be programmed as ‘1’.

**2:** When read, this bit returns the current programmed value.

**3:** This bit is unimplemented on PIC24HJ64GPX06A/X08A/X10A and PIC24HJ128GPX06A/X08A/X10A devices and reads as ‘0’.

**4:** These bits are reserved and always read as ‘1’.

# PIC24HJXXXGPX06A/X08A/X10A

**TABLE 22-2: INSTRUCTION SET OVERVIEW**

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
1	ADD	ADD <i>f</i>	$f = f + WREG$	1	1	C,DC,N,OV,Z
		ADD <i>f</i> , WREG	$WREG = f + WREG$	1	1	C,DC,N,OV,Z
		ADD #lit10, Wn	$Wd = lit10 + Wd$	1	1	C,DC,N,OV,Z
		ADD Wb, Ws, Wd	$Wd = Wb + Ws$	1	1	C,DC,N,OV,Z
		ADD Wb, #lit5, Wd	$Wd = Wb + lit5$	1	1	C,DC,N,OV,Z
2	ADDC	ADDC <i>f</i>	$f = f + WREG + (C)$	1	1	C,DC,N,OV,Z
		ADDC <i>f</i> , WREG	$WREG = f + WREG + (C)$	1	1	C,DC,N,OV,Z
		ADDC #lit10, Wn	$Wd = lit10 + Wd + (C)$	1	1	C,DC,N,OV,Z
		ADDC Wb, Ws, Wd	$Wd = Wb + Ws + (C)$	1	1	C,DC,N,OV,Z
		ADDC Wb, #lit5, Wd	$Wd = Wb + lit5 + (C)$	1	1	C,DC,N,OV,Z
3	AND	AND <i>f</i>	$f = f .AND. WREG$	1	1	N,Z
		AND <i>f</i> , WREG	$WREG = f .AND. WREG$	1	1	N,Z
		AND #lit10, Wn	$Wd = lit10 .AND. Wd$	1	1	N,Z
		AND Wb, Ws, Wd	$Wd = Wb .AND. Ws$	1	1	N,Z
		AND Wb, #lit5, Wd	$Wd = Wb .AND. lit5$	1	1	N,Z
4	ASR	ASR <i>f</i>	$f = \text{Arithmetic Right Shift } f$	1	1	C,N,OV,Z
		ASR <i>f</i> , WREG	$WREG = \text{Arithmetic Right Shift } f$	1	1	C,N,OV,Z
		ASR Ws, Wd	$Wd = \text{Arithmetic Right Shift } Ws$	1	1	C,N,OV,Z
		ASR Wb, Wns, Wnd	$Wnd = \text{Arithmetic Right Shift } Wb \text{ by } Wns$	1	1	N,Z
		ASR Wb, #lit5, Wnd	$Wnd = \text{Arithmetic Right Shift } Wb \text{ by } lit5$	1	1	N,Z
5	BCLR	BCLR <i>f</i> , #bit4	Bit Clear <i>f</i>	1	1	None
		BCLR Ws, #bit4	Bit Clear Ws	1	1	None
6	BRA	BRA C, Expr	Branch if Carry	1	1 (2)	None
		BRA GE, Expr	Branch if greater than or equal	1	1 (2)	None
		BRA GEU, Expr	Branch if unsigned greater than or equal	1	1 (2)	None
		BRA GT, Expr	Branch if greater than	1	1 (2)	None
		BRA GTU, Expr	Branch if unsigned greater than	1	1 (2)	None
		BRA LE, Expr	Branch if less than or equal	1	1 (2)	None
		BRA LEU, Expr	Branch if unsigned less than or equal	1	1 (2)	None
		BRA LT, Expr	Branch if less than	1	1 (2)	None
		BRA LTU, Expr	Branch if unsigned less than	1	1 (2)	None
		BRA N, Expr	Branch if Negative	1	1 (2)	None
		BRA NC, Expr	Branch if Not Carry	1	1 (2)	None
		BRA NN, Expr	Branch if Not Negative	1	1 (2)	None
		BRA NZ, Expr	Branch if Not Zero	1	1 (2)	None
		BRA Expr	Branch Unconditionally	1	2	None
		BRA Z, Expr	Branch if Zero	1	1 (2)	None
		BRA Wn	Computed Branch	1	2	None
7	BSET	BSET <i>f</i> , #bit4	Bit Set <i>f</i>	1	1	None
		BSET Ws, #bit4	Bit Set Ws	1	1	None
8	BSW	BSW.C Ws, Wb	Write C bit to Ws<Wb>	1	1	None
		BSW.Z Ws, Wb	Write Z bit to Ws<Wb>	1	1	None
9	BTG	BTG <i>f</i> , #bit4	Bit Toggle <i>f</i>	1	1	None
		BTG Ws, #bit4	Bit Toggle Ws	1	1	None
10	BTSC	BTSC <i>f</i> , #bit4	Bit Test <i>f</i> , Skip if Clear	1	1 (2 or 3)	None
		BTSC Ws, #bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None
11	BTSS	BTSS <i>f</i> , #bit4	Bit Test <i>f</i> , Skip if Set	1	1 (2 or 3)	None
		BTSS Ws, #bit4	Bit Test Ws, Skip if Set	1	1 (2 or 3)	None

# PIC24HJXXXGPX06A/X08A/X10A

## 24.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of PIC24HJXXXGPX06A/X08A/X10A electrical characteristics. Additional information is provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the PIC24HJXXXGPX06A/X08A/X10A family are listed below. Exposure to these maximum rating conditions for extended periods can affect device reliability. Functional operation of the device at these or any other conditions above the parameters indicated in the operation listings of this specification is not implied.

### Absolute Maximum Ratings

(See Note 1 )

Ambient temperature under bias .....	-40°C to +125°C
Storage temperature .....	-65°C to +160°C
Voltage on VDD with respect to VSS .....	-0.3V to +4.0V
Voltage on any pin that is not 5V tolerant with respect to VSS <sup>(4)</sup> .....	-0.3V to (VDD + 0.3V)
Voltage on any 5V tolerant pin with respect to VSS when VDD ≥ 3.0V <sup>(4)</sup> .....	-0.3V to +5.6V
Voltage on any 5V tolerant pin with respect to VSS when VDD < 3.0V <sup>(4)</sup> .....	-0.3V to 3.6V
Maximum current out of VSS pin .....	300 mA
Maximum current into VDD pin <sup>(2)</sup> .....	250 mA
Maximum current sourced/sunk by any 2x I/O pin <sup>(3)</sup> .....	8 mA
Maximum current sourced/sunk by any 4x I/O pin <sup>(3)</sup> .....	15 mA
Maximum current sourced/sunk by any 8x I/O pin <sup>(3)</sup> .....	25 mA
Maximum current sunk by all ports .....	200 mA
Maximum current sourced by all ports <sup>(2)</sup> .....	200 mA

**Note 1:** Stresses above those listed under “Absolute Maximum Ratings” can cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods can affect device reliability.

**2:** Maximum allowable current is a function of device maximum power dissipation (see Table 24-2).

**3:** Exceptions are CLKOUT, which is able to sink/source 25 mA, and the VREF+, VREF-, SCLx, SDAX, PGECx and PGEDx pins, which are able to sink/source 12 mA.

**4:** See the “Pin Diagrams” section for 5V tolerant pins.



# PIC24HJXXXGPX06A/X08A/X10A

**TABLE 24-9: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)**

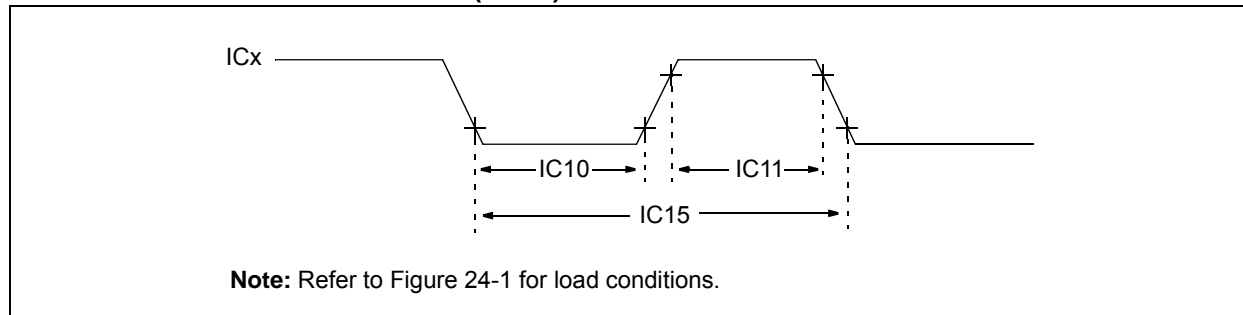
DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DI60a	I <sub>ICL</sub>	Input Low Injection Current	0	—	-5 <sup>(5,8)</sup>	mA	All pins except V <sub>DD</sub> , V <sub>SS</sub> , AV <sub>DD</sub> , AV <sub>SS</sub> , MCLR, V <sub>CAP</sub> , SOSC <sub>I</sub> , SOSC <sub>O</sub> , and RB11
DI60b	I <sub>ICH</sub>	Input High Injection Current	0	—	+5 <sup>(6,7,8)</sup>	mA	All pins except V <sub>DD</sub> , V <sub>SS</sub> , AV <sub>DD</sub> , AV <sub>SS</sub> , MCLR, V <sub>CAP</sub> , SOSC <sub>I</sub> , SOSC <sub>O</sub> , RB11, and all 5V tolerant pins <sup>(7)</sup>
DI60c	$\sum I_{ICT}$	Total Input Injection Current (sum of all I/O and control pins)	-20 <sup>(9)</sup>	—	+20 <sup>(9)</sup>	mA	Absolute instantaneous sum of all $\pm$ input injection currents from all I/O pins ( $ I_{ICL}  +  I_{ICH} $ ) $\leq \sum I_{ICT}$

**Note 1:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

- 2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
- 3:** Negative current is defined as current sourced by the pin.
- 4:** See “Pin Diagrams” for a list of 5V tolerant pins.
- 5:** V<sub>IL</sub> source < (V<sub>SS</sub> – 0.3). Characterized but not tested.
- 6:** Non-5V tolerant pins V<sub>IH</sub> source > (V<sub>DD</sub> + 0.3), 5V tolerant pins V<sub>IH</sub> source > 5.5V. Characterized but not tested.
- 7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.
- 8:** Injection currents > |0| can affect the ADC results by approximately 4-6 counts.
- 9:** Any number and/or combination of I/O pins not excluded under I<sub>ICL</sub> or I<sub>ICH</sub> conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

# PIC24HJXXXGPX06A/X08A/X10A

**FIGURE 24-6: INPUT CAPTURE (CAPx) TIMING CHARACTERISTICS**

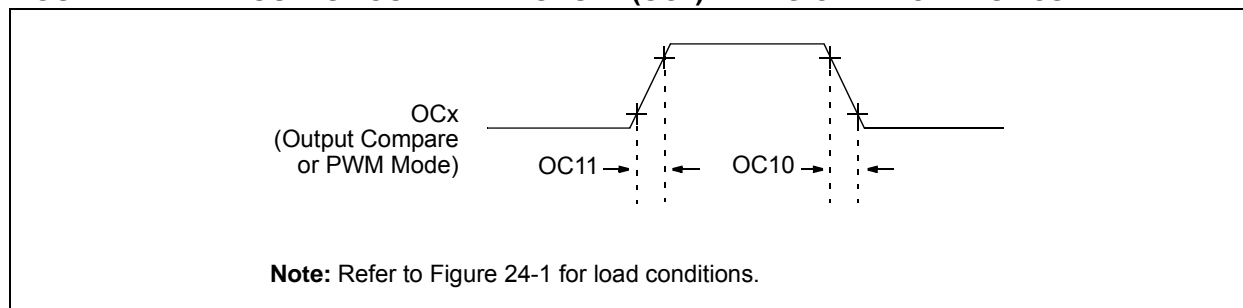


**TABLE 24-25: INPUT CAPTURE TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Max	Units	Conditions
IC10	TccL	ICx Input Low Time	No Prescaler	$0.5 T_{CY} + 20$	—	ns	—
			With Prescaler	10	—	ns	
IC11	TccH	ICx Input High Time	No Prescaler	$0.5 T_{CY} + 20$	—	ns	—
			With Prescaler	10	—	ns	
IC15	TccP	ICx Input Period		$(T_{CY} + 40)/N$	—	ns	N = prescale value (1, 4, 16)

**Note 1:** These parameters are characterized but not tested in manufacturing.

**FIGURE 24-7: OUTPUT COMPARE MODULE (OCx) TIMING CHARACTERISTICS**



**TABLE 24-26: OUTPUT COMPARE MODULE TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
OC10	TccF	OCx Output Fall Time	—	—	—	ns	See parameter D032
OC11	TccR	OCx Output Rise Time	—	—	—	ns	See parameter D031

**Note 1:** These parameters are characterized but not tested in manufacturing.

# PIC24HJXXXGPX06A/X08A/X10A

**TABLE 24-34: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 2.4V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP70	TscP	Maximum SCK Input Frequency	—	—	15	MHz	See <b>Note 3</b>
SP72	TscF	SCKx Input Fall Time	—	—	—	ns	See parameter DO32 and <b>Note 4</b>
SP73	TscR	SCKx Input Rise Time	—	—	—	ns	See parameter DO31 and <b>Note 4</b>
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See parameter DO32 and <b>Note 4</b>
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See parameter DO31 and <b>Note 4</b>
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	—
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns	—
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns	—
SP50	TssL2scH, TssL2scL	$\overline{SSx} \downarrow$ to SCKx $\uparrow$ or SCKx Input	120	—	—	ns	—
SP51	TssH2doZ	$\overline{SSx} \uparrow$ to SDOx Output High-Impedance <sup>(4)</sup>	10	—	50	ns	—
SP52	Tsch2ssH TscL2ssH	$\overline{SSx}$ after SCKx Edge	1.5 TCY + 40	—	—	ns	See <b>Note 4</b>

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

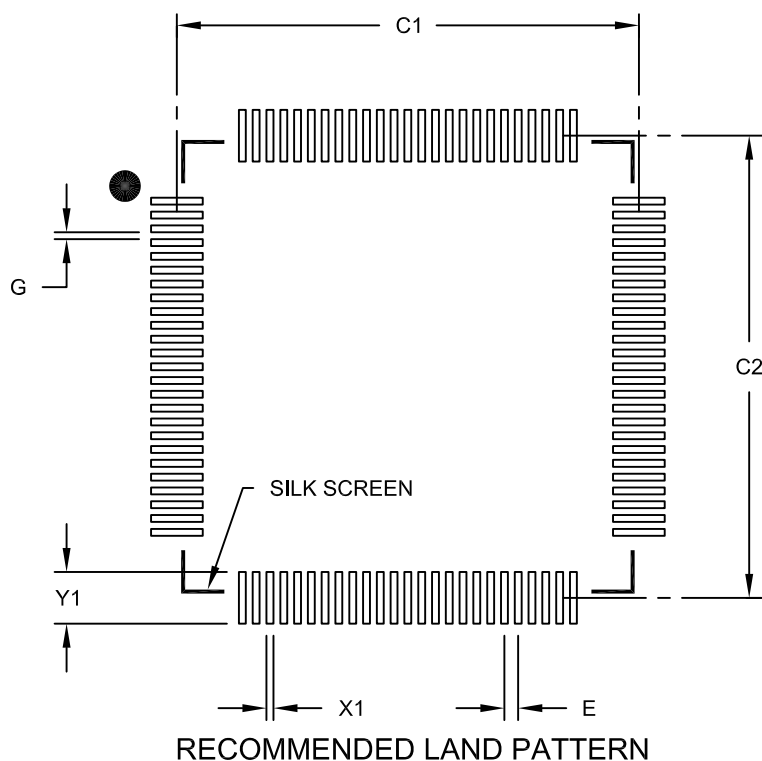
**3:** The minimum clock period for SCKx is 66.7 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

# PIC24HJXXXGPX06A/X08A/X10A

100-Lead Plastic Thin Quad Flatpack (PT)-12x12x1mm Body, 2.00 mm Footprint [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.40 BSC		
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X100)	X1			0.20
Contact Pad Length (X100)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2100B

# PIC24HJXXXGPX06A/X08A/X10A

## APPENDIX B: REVISION HISTORY

### Revision A (April 2009)

This is the initial released version of the document.

### Revision B (October 2009)

The revision includes the following global update:

- Added Note 2 to the shaded table that appears at the beginning of each chapter. This new note provides information regarding the availability of registers and their associated bits

This revision also includes minor typographical and formatting changes throughout the data sheet text.

All other major changes are referenced by their respective section in the following table.

TABLE B-1: MAJOR SECTION UPDATES

Section Name	Update Description
“High-Performance, 16-bit Microcontrollers”	Added information on high temperature operation (see “ <b>Operating Range:</b> ”).
Section 10.0 “Power-Saving Features”	Updated the last paragraph to clarify the number of cycles that occur prior to the start of instruction execution (see <b>Section 10.2.2 “Idle Mode”</b> ).
Section 11.0 “I/O Ports”	Changed the reference to digital-only pins to 5V tolerant pins in the second paragraph of <b>Section 11.2 “Open-Drain Configuration”</b> .
Section 18.0 “Universal Asynchronous Receiver Transmitter (UART)”	Updated the two baud rate range features to: 10 Mbps to 38 bps at 40 MIPS.
Section 20.0 “10-bit/12-bit Analog-to-Digital Converter (ADC)”	Updated the ADCx block diagram (see Figure 20-1).
Section 21.0 “Special Features”	Updated the second paragraph and removed the fourth paragraph in <b>Section 21.1 “Configuration Bits”</b> .  Updated the Device Configuration Register Map (see Table 21-1).
Section 24.0 “Electrical Characteristics”	Updated the Absolute Maximum Ratings for high temperature and added Note 4.  Updated Power-Down Current parameters DC60d, DC60a, DC60b, and DC60d (see Table 24-7).  Added I2Cx Bus Data Timing Requirements (Master Mode) parameter IM51 (see Table 24-36).  Updated the SPIx Module Slave Mode (CKE = 1) Timing Characteristics (see Figure 24-12).  Updated the Internal LPRC Accuracy parameters (see Table 24-18 and Table 24-19).  Updated the ADC Module Specifications (12-bit Mode) parameters AD23a and AD24a (see Table 24-40).  Updated the ADC Module Specifications (10-bit Mode) parameters AD23b and AD24b (see Table 24-41).
Section 25.0 “High Temperature Electrical Characteristics”	Added new chapter with high temperature specifications.
“Product Identification System”	Added the “H” definition for high temperature.