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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I ² C, IrDA, LINbus, Microwire, SmartCard, SPI, SSP, UART/USART
Peripherals	Brown-out Detect/Reset, Cap Sense, LCD, LVD, POR, PWM, SmartSense, WDT
Number of I/O	51
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 5.5V
Data Converters	A/D 16x12b SAR; D/A 4x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c4247axi-m485

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PSoC 4200M Block Diagram



The PSoC 4200-M devices include extensive support for programming, testing, debugging, and tracing both hardware and firmware.

The ARM Serial_Wire Debug (SWD) interface supports all programming and debug features of the device.

Complete debug-on-chip functionality enables full-device debugging in the final system using the standard production device. It does not require special interfaces, debugging pods, simulators, or emulators. Only the standard programming connections are required to fully support debug.

The PSoC Creator Integrated Development Environment (IDE) provides fully integrated programming and debug support for PSoC 4200-M devices. The SWD interface is fully compatible with industry-standard third-party tools. The PSoC 4200-M family provides a level of security not possible with multi-chip application solutions or with microcontrollers. This is due to its ability to disable debug features, robust flash protection, and because it allows customer-proprietary functionality to be implemented in on-chip programmable blocks.

The debug circuits are enabled by default and can only be disabled in firmware. If not enabled, the only way to re-enable them is to erase the entire device, clear flash protection, and reprogram the device with new firmware that enables debugging.

Additionally, all device interfaces can be permanently disabled (device security) for applications concerned about phishing attacks due to a maliciously reprogrammed device or attempts to defeat security by starting and interrupting flash programming sequences. Because all programming, debug, and test interfaces are disabled when maximum device security is enabled, PSoC 4200-M with device security enabled may not be returned for failure analysis. This is a trade-off the PSoC 4200-M allows the customer to make.



UDBs can be clocked from a clock divider block, from a port interface (required for peripherals such as SPI), and from the DSI network directly or after synchronization.

A port interface is defined, which acts as a register that can be clocked with the same source as the PLDs inside the UDB array. This allows faster operation because the inputs and outputs can be registered at the port interface close to the I/O pins and at the edge of the array. The port interface registers can be clocked by one of the I/Os from the same port. This allows interfaces such as SPI to operate at higher clock speeds by eliminating the delay for the port input to be routed over DSI and used to register other inputs. The port interface is shown in Figure 6.

The UDBs can generate interrupts (one UDB at a time) to the interrupt controller. The UDBs can connect to any pin on Ports 0, 1, 2, and 3 (each port interconnect requires one UDB) through the DSI.

Figure 6. Port Interface



Fixed Function Digital

Timer/Counter/PWM (TCPWM) Block

The TCPWM block uses a16-bit counter with user-programmable period length. There is a Capture register to record the count value at the time of an event (which may be an I/O event), a period register which is used to either stop or auto-reload the counter when its count is equal to the period register, and compare registers to generate compare value signals, which are used as PWM duty cycle outputs. The block also provides true and complementary outputs with programmable offset between them to allow use as deadband programmable complementary PWM outputs. It also has a Kill input to force outputs to a predetermined state; for example, this is used in motor drive systems when an overcurrent state is indicated and the PWMs driving the FETs need to be shut off immediately with no time for software intervention. The PSoC 4200M has eight TCPWM blocks.

Serial Communication Blocks (SCB)

The PSoC 4200M has four SCBs, which can each implement an I^2 C, UART, or SPI interface.

I²C Mode: The hardware I²C block implements a full multi-master and slave interface (it is capable of multimaster arbitration). This block is capable of operating at speeds of up to 1 Mbps (Fast Mode Plus) and has flexible buffering options to reduce interrupt overhead and latency for the CPU. It also supports EzI²C that creates a mailbox address range in the memory of the PSoC 4200M and effectively reduces I²C communication to reading from and writing to an array in memory. In

addition, the block supports an 8-deep FIFO for receive and transmit which, by increasing the time given for the CPU to read data, greatly reduces the need for clock stretching caused by the CPU not having read data on time. The FIFO mode is available in all channels and is very useful in the absence of DMA.

The I²C peripheral is compatible with the I²C Standard-mode, Fast-mode, and Fast-mode Plus devices as defined in the NXP I²C-bus specification and user manual (UM10204). The I²C bus I/O is implemented with GPIO in open-drain modes.

UART Mode: This is a full-feature UART operating at up to 1 Mbps. It supports automotive single-wire interface (LIN), infrared interface (IrDA), and SmartCard (ISO7816) protocols, all of which are minor variants of the basic UART protocol. In addition, it supports the 9-bit multiprocessor mode that allows addressing of peripherals connected over common RX and TX lines. Common UART functions such as parity error, break detect, and frame error are supported. An 8-deep FIFO allows much greater CPU service latencies to be tolerated.

SPI Mode: The SPI mode supports full Motorola SPI, TI SSP (essentially adds a start pulse used to synchronize SPI Codecs), and National Microwire (half-duplex form of SPI). The SPI block can use the FIFO and also supports an EzSPI mode in which data interchange is reduced to reading and writing an array in memory.

CAN Blocks

There are two independent CAN 2.0B blocks, which are certified CAN conformant.



Pinouts

The following is the pin list for the PSoC 4200M. This shows the power supply and port pins (for example, P0.0 is Pin 0 of Port 0).

	68-QFN		64-TQFP	48-TQFP			44-TQFP		
Pin	Name	Pin	Name	Pin	Name	Pin	Name		
42	P0.0	39	P0.0	28	P0.0	24	P0.0		
43	P0.1	40	P0.1	29	P0.1	25	P0.1		
44	P0.2	41	P0.2	30	P0.2	26	P0.2		
45	P0.3	42	P0.3	31	P0.3	27	P0.3		
46	P0.4	43	P0.4	32	P0.4	28	P0.4		
47	P0.5	44	P0.5	33	P0.5	29	P0.5		
48	P0.6	45	P0.6	34	P0.6	30	P0.6		
49	P0.7	46	P0.7	35	P0.7	31	P0.7		
50	XRES	47	XRES	36	XRES	32	XRES		
51	VCCD	48	VCCD	37	VCCD	33	VCCD		
52	VSSD	49	VSSD	38	VSSD	DN	VSSD		
53	VDDD	50	VDDD	39	VDDD	34	VDDD		
				40	VDDA	35	VDDA		
54	P5.0	51	P5.0						
55	P5.1	52	P5.1						
56	P5.2	53	P5.2						
57	P5.3	54	P5.3						
58	P5.4								
59	P5.5	55	P5.5						
60	VDDA	56	VDDA	40	VDDA	35	VDDA		
61	VSSA	57	VSSA	41	VSSA	36	VSSA		
62	P1.0	58	P1.0	42	P1.0	37	P1.0		
63	P1.1	59	P1.1	43	P1.1	38	P1.1		
64	P1.2	60	P1.2	44	P1.2	39	P1.2		
65	P1.3	61	P1.3	45	P1.3	40	P1.3		
66	P1.4	62	P1.4	46	P1.4	41	P1.4		
67	P1.5	63	P1.5	47	P1.5	42	P1.5		
68	P1.6	64	P1.6	48	P1.6	43	P1.6		
1	P1.7/VREF	1	P1.7/VREF	1	P1.7/VREF	44	P1.7/VREF		
						1	VSSD		
2	P2.0	2	P2.0	2	P2.0	2	P2.0		
3	P2.1	3	P2.1	3	P2.1	3	P2.1		
4	P2.2	4	P2.2	4	P2.2	4	P2.2		
5	P2.3	5	P2.3	5	P2.3	5	P2.3		
6	P2.4	6	P2.4	6	P2.4	6	P2.4		
7	P2.5	7	P2.5	7	P2.5	7	P2.5		



	68-QFN		64-TQFP	48-TQFP			44-TQFP		
Pin	Name	Pin	Name	Pin	Name	Pin	Name		
8	P2.6	8	P2.6	8	P2.6	8	P2.6		
9	P2.7	9	P2.7	9	9 P2.7		P2.7		
10	VSSA	10	VSSA	10	VSSD	10	VSSD		
11	VDDA	11	VDDA						
12	P6.0	12	P6.0						
13	P6.1	13	P6.1						
14	P6.2	14	P6.2						
15	P6.3								
16	P6.4	15	P6.4						
17	P6.5	16	P6.5						
18	VSSIO	17	VSSIO	10	VSSD	10	VSSD		
19	P3.0	18	P3.0	12	P3.0	11	P3.0		
20	P3.1	19	P3.1	13	P3.1	12	P3.1		
21	P3.2	20	P3.2	14	P3.2	13	P3.2		
22	P3.3	21	P3.3	16	P3.3	14	P3.3		
23	P3.4	22	P3.4	17	P3.4	15	P3.4		
24	P3.5	23	P3.5	18	P3.5	16	P3.5		
25	P3.6	24	P3.6	19	P3.6	17	P3.6		
26	P3.7	25	P3.7	20	P3.7	18	P3.7		
27	VDDIO	26	VDDIO	21	VDDIO	19	VDDD		
28	P4.0	27	P4.0	22	P4.0	20	P4.0		
29	P4.1	28	P4.1	23	P4.1	21	P4.1		
30	P4.2	29	P4.2	24	P4.2	22	P4.2		
31	P4.3	30	P4.3	25	P4.3	23	P4.3		
32	P4.4	31	P4.4						
33	P4.5	32	P4.5						
34	P4.6	33	P4.6						
35	P4.7								
39	P7.0	37	P7.0	26	P7.0				
40	P7.1	38	P7.1	27	P7.1				
41	P7.2								

The pins of Port 6 are overvoltage-tolerant. Pins 36, 37, and 38 are No-Connects on the 68-pin QFN. Pins 34, 35, and 36 are No-Connects on the 64-pin TQFP. Pins 11 and 15 are No-connects in the 48-pin TQFP. All VSS pins must be tied together.

The output drivers of I/O Ports P0 and P7 are connected to VDDD. Output drivers of I/O Ports 1, 2, and 5 are connected to VDDA. Output drivers of I/O Ports 3, 4, and 6 are connected to VDDIO.



Each of the pins shown in the previous table can have multiple programmable functions as shown in the following table. Column headings refer to Analog and Alternate pin functions.:

Port/Pin	Analog	Alt. Function 1	Alt. Function 2	Alt. Function 3	Alt. Function 4	Alt. Function 5
P0.0	lpcomp.in_p[0]			can[1].can_rx:0		scb[0].spi_select1:0
P0.1	lpcomp.in_n[0]			can[1].can_tx:0		scb[0].spi_select2:0
P0.2	lpcomp.in_p[1]					scb[0].spi_select3:0
P0.3	lpcomp.in_n[1]					
P0.4	wco_in		scb[1].uart_rx:0		scb[1].i2c_scl:0	scb[1].spi_mosi:1
P0.5	wco_out		scb[1].uart_tx:0		scb[1].i2c_sda:0	scb[1].spi_miso:1
P0.6		ext_clk:0	scb[1].uart_cts:0			scb[1].spi_clk:1
P0.7			scb[1].uart_rts:0	can[1].can_tx_enb_n:0	wakeup	scb[1].spi_select0:1
P5.0	ctb1.oa0.inp	tcpwm.line[4]:2	scb[2].uart_rx:0		scb[2].i2c_scl:0	scb[2].spi_mosi:0
P5.1	ctb1.oa0.inm	tcpwm.line_compl[4]:2	scb[2].uart_tx:0		scb[2].i2c_sda:0	scb[2].spi_miso:0
P5.2	ctb1.oa0.out	tcpwm.line[5]:2	scb[2].uart_cts:0		lpcomp.comp[0]:1	scb[2].spi_clk:0
P5.3	ctb1.oa1.out	tcpwm.line_compl[5]:2	scb[2].uart_rts:0		lpcomp.comp[1]:1	scb[2].spi_select0:0
P5.4	ctb1.oa1.inm	tcpwm.line[6]:2				scb[2].spi_select1:0
P5.5	ctb1.oa1.inp	tcpwm.line_compl[6]:2				scb[2].spi_select2:0
P5.6	ctb1.oa0.inp_alt	tcpwm.line[7]:0				scb[2].spi_select3:0
P5.7	ctb1.oa1.inp_alt	tcpwm.line_compl[7]:0				
P1.0	ctb0.oa0.inp	tcpwm.line[2]:1	scb[0].uart_rx:1		scb[0].i2c_scl:0	scb[0].spi_mosi:1
P1.1	ctb0.oa0.inm	tcpwm.line_compl[2]:1	scb[0].uart_tx:1		scb[0].i2c_sda:0	scb[0].spi_miso:1
P1.2	ctb0.oa0.out	tcpwm.line[3]:1	scb[0].uart_cts:1			scb[0].spi_clk:1
P1.3	ctb0.oa1.out	tcpwm.line_compl[3]:1	scb[0].uart_rts:1			scb[0].spi_select0:1
P1.4	ctb0.oa1.inm	tcpwm.line[6]:1				scb[0].spi_select1:1
P1.5	ctb0.oa1.inp	tcpwm.line_compl[6]:1				scb[0].spi_select2:1
P1.6	ctb0.oa0.inp_alt	tcpwm.line[7]:1				scb[0].spi_select3:1
P1.7	ctb0.oa1.inp_alt	tcpwm.line_compl[7]:1				
P2.0	sarmux.0	tcpwm.line[4]:1			scb[1].i2c_scl:1	scb[1].spi_mosi:2
P2.1	sarmux.1	tcpwm.line_compl[4]:1			scb[1].i2c_sda:1	scb[1].spi_miso:2
P2.2	sarmux.2	tcpwm.line[5]:1				scb[1].spi_clk:2
P2.3	sarmux.3	tcpwm.line_compl[5]:1				scb[1].spi_select0:2
P2.4	sarmux.4	tcpwm.line[0]:1				scb[1].spi_select1:1
P2.5	sarmux.5	tcpwm.line_compl[0]:1				scb[1].spi_select2:1
P2.6	sarmux.6	tcpwm.line[1]:1				scb[1].spi_select3:1



Power

The supply voltage range is 1.71 to 5.5 V with all functions and circuits operating over that range.

The PSoC 4200M family allows two distinct modes of power supply operation: Unregulated External Supply and Regulated External Supply modes.

Unregulated External Supply

In this mode, the PSoC 4200M is powered by an External Power Supply that can be anywhere in the range of 1.8 to 5.5 V. This range is also designed for battery-powered operation, for instance, the chip can be powered from a battery system that starts at 3.5V and works down to 1.8 V. In this mode, the internal regulator of the PSoC 4200M supplies the internal logic and the VCCD output of the PSoC 4200M must be bypassed to ground via an external Capacitor (in the range of 1 to 1.6 μ F; X5R ceramic or better).

The grounds, VSSA and VSS, must be shorted together. Bypass capacitors must be used from VDDD and VDDA to ground, typical practice for systems in this frequency range is to use a capacitor in the 1 μ F range in parallel with a smaller capacitor (0.1 μ F, for example). Note that these are simply rules of thumb and that, for critical applications, the PCB layout, lead inductance, and the Bypass capacitor parasitic should be simulated to design and obtain optimal bypassing.

Power Supply	Bypass Capacitors					
VDDD–VSS and VDDIO-VSS	0.1 μ F ceramic at each pin plus bulk capacitor 1 to 10 μ F.					
VDDA-VSSA	0.1 μ F ceramic at pin. Additional 1 μ F to 10 μ F bulk capacitor					
VCCD-VSS	1 μ F ceramic capacitor at the VCCD pin					
VREF–VSSA (optional)	The internal bandgap may be bypassed with a 1 μ F to 10 μ F capacitor for better ADC performance.					

Regulated External Supply

In this mode, the PSoC 4200M is powered by an external power supply that must be within the range of 1.71 to 1.89 V (1.8 \pm 5%); note that this range needs to include power supply ripple. VCCD and VDDD pins are shorted together and bypassed. The internal regulator is disabled in firmware.



Development Support

The PSoC 4200M family has a rich set of documentation, development tools, and online resources to assist you during your development process. Visit www.cypress.com/go/psoc4 to find out more.

Documentation

A suite of documentation supports the PSoC 4200M family to ensure that you can find answers to your questions quickly. This section contains a list of some of the key documents.

Software User Guide: A step-by-step guide for using PSoC Creator. The software user guide shows you how the PSoC Creator build process works in detail, how to use source control with PSoC Creator, and much more.

Component Datasheets: The flexibility of PSoC allows the creation of new peripherals (components) long after the device has gone into production. Component data sheets provide all of the information needed to select and use a particular component, including a functional description, API documentation, example code, and AC/DC specifications.

Application Notes: PSoC application notes discuss a particular application of PSoC in depth; examples include brushless DC motor control and on-chip filtering. Application notes often include example projects in addition to the application note document.

Technical Reference Manual: The Technical Reference Manual (TRM) contains all the technical detail you need to use a PSoC device, including a complete description of all PSoC registers.

Online

In addition to print documentation, the Cypress PSoC forums connect you with fellow PSoC users and experts in PSoC from around the world, 24 hours a day, 7 days a week.

Tools

With industry standard cores, programming, and debugging interfaces, the PSoC 4200M family is part of a development tool ecosystem. Visit us at www.cypress.com/go/psoccreator for the latest information on the revolutionary, easy to use PSoC Creator IDE, supported third party compilers, programmers, debuggers, and development kits.



Table 2. DC Specifications (continued)

Spec ID#	Parameter	Description	Min	Тур	Max	Units	Details / Conditions		
Deep Sleep Mode, -40 °C to + 60 °C									
SID30	I _{DD25}	I ² C wakeup and WDT on. Regulator Off.	-	1.55	20	μA	V _{DD} = 1.71 to 1.89		
SID31	I _{DD26}	I ² C wakeup and WDT on.	-	1.35	15	μA	V _{DD} = 1.8 to 3.6		
SID32	I _{DD27}	I ² C wakeup and WDT on.	-	1.5	15	μA	V _{DD} = 3.6 to 5.5		
Deep Sleep Mode, +85 °C									
SID33	I _{DD28}	I ² C wakeup and WDT on. Regulator Off.	-	-	60	μA	V _{DD} = 1.71 to 1.89		
SID34	I _{DD29}	I ² C wakeup and WDT on.	_	-	45	μA	V _{DD} = 1.8 to 3.6		
SID35	I _{DD30}	I ² C wakeup and WDT on.	-	-	30	μA	V _{DD} = 3.6 to 5.5		
Deep Sleep	o Mode, +105 °C	· · · · · · · · · · · · · · · · · · ·							
SID33Q	I _{DD28Q}	I ² C wakeup and WDT on. Regulator Off.	_	-	135	μA	V _{DD} = 1.71 to 1.89		
SID34Q	I _{DD29Q}	I ² C wakeup and WDT on.	-	-	180	μA	V _{DD} = 1.8 to 3.6		
SID35Q	I _{DD30Q}	I ² C wakeup and WDT on.	-	-	140	μA	V _{DD} = 3.6 to 5.5		
Hibernate	Mode, -40 °C to +	- 60 °C			•				
SID39	I _{DD34}	Regulator Off.	-	150	3000	nA	V _{DD} = 1.71 to 1.89		
SID40	I _{DD35}		_	150	1000	nA	V _{DD} = 1.8 to 3.6		
SID41	I _{DD36}		_	150	1100	nA	V _{DD} = 3.6 to 5.5		
Hibernate	Mode, +85 °C								
SID42	I _{DD37}	Regulator Off.	-	_	4500	nA	V _{DD} = 1.71 to 1.89		
SID43	I _{DD38}		-	-	3500	nA	V _{DD} = 1.8 to 3.6		
SID44	I _{DD39}		-	-	3500	nA	V _{DD} = 3.6 to 5.5		
Hibernate	Mode, +105 °C								
SID42Q	I _{DD37Q}	Regulator Off.	-	1	19.4	μA	V _{DD} = 1.71 to 1.89		
SID43Q	I _{DD38Q}		-	-	17	μA	V _{DD} = 1.8 to 3.6		
SID44Q	I _{DD39Q}		-	-	16	μA	V _{DD} = 3.6 to 5.5		
Stop Mode									
SID304	I _{DD43A}	Stop Mode current; V_{DD} = 3.6 V	-	35	85	nA	T = -40 °C to +60 °C		
SID304A	I _{DD43B}	Stop Mode current; V_{DD} = 3.6 V	_	-	1450	nA	T = +85 °C		
Stop Mode	, +105 °C								
SID304Q	I _{DD43AQ}	Stop Mode current; V _{DD} = 3.6 V	-	-	5645	nA			
XRES curr	ent								
SID307	I _{DD_XR}	Supply current while XRES asserted	_	2	5	mA			



Table 3. AC Specifications

Spec ID#	Parameter	Description	Min	Тур	Мах	Units	Details/ Conditions
SID48	F _{CPU}	CPU frequency	DC	-	48	MHz	$1.71 \leq V_{DD} \leq 5.5$
SID49	T _{SLEEP}	Wakeup from sleep mode	-	0	_	μs	Guaranteed by characterization
SID50	T _{DEEPSLEEP}	Wakeup from Deep Sleep mode	-	_	25	μs	24 MHz IMO. Guaranteed by characterization
SID51	T _{HIBERNATE}	Wakeup from Hibernate mode	-	-	0.7	ms	Guaranteed by characterization
SID51A	T _{STOP}	Wakeup from Stop mode	-	-	2	ms	Guaranteed by characterization
SID52	T _{RESETWIDTH}	External reset pulse width	1	_	_	μs	Guaranteed by characterization

GPIO

Table 4. GPIO DC Specifications

Spec ID#	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID57	V _{IH} ^[2]	Input voltage high threshold	0.7 × V _{DDD}	-	-	V	CMOS Input
SID57A	IIHS	Input current when Pad > V _{DDIO} for OVT inputs	-	_	10	μA	Per I ² C Spec
SID58	V _{IL}	Input voltage low threshold	-	-	0.3 × V _{DDD}	V	CMOS Input
SID241	V _{IH} ^[2]	LVTTL input, V _{DDD} < 2.7 V	0.7× V _{DDD}	-	_	V	
SID242	V _{IL}	LVTTL input, V _{DDD} < 2.7 V	_	_	0.3 × V _{DDD}	V	
SID243	V _{IH} ^[2]	LVTTL input, $V_{DDD} \ge 2.7 \text{ V}$	2.0	-	-	V	
SID244	V _{IL}	LVTTL input, $V_{DDD} \ge 2.7 \text{ V}$	-	-	0.8	V	
SID59	V _{OH}	Output voltage high level	V _{DDD} -0.6	-	-	V	I _{OH} = 4 mA at 3-V V _{DDD}
SID60	V _{OH}	Output voltage high level	V _{DDD} -0.5	_	-	V	I _{OH} = 1 mA at 1.8-V V _{DDD}
SID61	V _{OL}	Output voltage low level	-	-	0.6	V	I _{OL} = 4 mA at 1.8-V V _{DDD}
SID62	V _{OL}	Output voltage low level	_	-	0.6	V	I _{OL} = 8 mA at 3-V V _{DDD}
SID62A	V _{OL}	Output voltage low level	-	_	0.4	V	I _{OL} = 3 mA at 3-V V _{DDD}
SID63	R _{PULLUP}	Pull-up resistor	3.5	5.6	8.5	kΩ	
SID64	R _{PULLDOWN}	Pull-down resistor	3.5	5.6	8.5	kΩ	
SID65	IIL	Input leakage current (absolute value)	-	-	2	nA	25 °C, V _{DDD} = 3.0 V. Guaranteed by Characterization
SID65A	I _{IL_CTBM}	Input leakage current (absolute value) for CTBM pins	-	-	4	nA	Guaranteed by Characterization
SID66	C _{IN}	Input capacitance	-	-	7	pF	
SID67	V _{HYSTTL}	Input hysteresis LVTTL	25	40	_	mV	$V_{DDD} \ge 2.7 V$

Note 2. V_{IH} must not exceed V_{DDD} + 0.2 V.



Table 8. Opamp Specifications

(Guaranteed by Characterization) (continued)

Spec ID#	Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
SID_DS_15	VOS_LOW_M1	Mode 1, Low current	_	5	-	mV	With trim 25 °C, 0.2 V to V _{DDA} -1.5 V
SID_DS_16	VOS_HI_M2	Mode 2, High current	_	5	-	mV	With trim 25 °C, 0.2 V to V _{DDA} -1.5 V
SID_DS_17	VOS_MED_M2	Mode 2, Medium current	-	5	-	mV	With trim 25 °C, 0.2 V to V _{DDA} -1.5 V
SID_DS_18	VOS_LOW_M2	Mode 2, Low current	-	5	-	mV	With trim 25 °C, 0.2 V to V _{DDA} -1.5 V
SID_DS_19	IOUT_HI_M1	Mode 1, High current	-	10	-	mA	Output is 0.5 V to V _{DDA} -0.5 V
SID_DS_20	IOUT_MED_M1	Mode 1, Medium current	_	10	-	mA	Output is 0.5 V to V _{DDA} -0.5 V
SID_DS_21	IOUT_LOW_M1	Mode 1, Low current	-	4	-	mA	Output is 0.5 V to V _{DDA} -0.5 V
SID_DS_22	IOUT_HI_M2	Mode 2, High current	_	1	_	mA	Output is 0.5 V to V _{DDA} -0.5 V
SID_DS_23	IOUT_MED_M2	Mode 2, Medium current	-	1	-	mA	Output is 0.5 V to V _{DDA} -0.5 V
SID_DS_24	IOUT_LOW_M2	Mode 2, Low current	_	0.5	_	mA	Output is 0.5 V to V _{DDA} -0.5 V

Comparator

Table 9. Comparator DC Specifications

Spec ID#	Parameter	Description	Min	Тур	Max	Units	Details/ Conditions
SID85	V _{OFFSET2}	Input offset voltage, Common Mode voltage range from 0 to V _{DD} -1	_	-	±4	mV	
SID85A	V _{OFFSET3}	Input offset voltage. Ultra low-power mode ($V_{DDD} \ge 2.2$ V for Temp < 0 °C, $V_{DDD} \ge 1.8$ V for Temp > 0 °C)	_	±12	-	mV	
SID86	V _{HYST}	Hysteresis when enabled, Common Mode voltage range from 0 to V _{DD} -1.	-	10	35	mV	Guaranteed by characterization
SID87	V _{ICM1}	Input common mode voltage in normal mode	0	-	V _{DDD} – 0.1	V	Modes 1 and 2.
SID247	V _{ICM2}	Input common mode voltage in low power mode ($V_{DDD} \ge 2.2 \text{ V}$ for Temp < 0 °C, $V_{DDD} \ge 1.8 \text{ V}$ for Temp > 0 °C)	0	-	V _{DDD}	V	
SID247A	V _{ICM3}	Input common mode voltage in ultra low power mode	0	-	V _{DDD} – 1.15	V	
SID88	CMRR	Common mode rejection ratio	50	_	-	dB	$V_{DDD} \ge 2.7 V.$ Guaranteed by characterization
SID88A	CMRR	Common mode rejection ratio	42	_	-	dB	V _{DDD} < 2.7 V. Guaranteed by characterization
SID89	I _{CMP1}	Block current, normal mode	_	-	400	μA	Guaranteed by characterization



Table 13. SAR ADC AC Specifications

(Guaranteed by Characterization)

Spec ID#	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID106	A_PSRR	Power supply rejection ratio	70	-	-	dB	
SID107	A_CMRR	Common mode rejection ratio	66	-	-	dB	Measured at 1 V
SID108	A_SAMP_1	Sample rate with external reference bypass cap	-	-	1	Msps	
SID108A	A_SAMP_2	Sample rate with no bypass cap. Reference = V _{DD}	-	-	1	Msps	
SID108B	A_SAMP_3	Sample rate with no bypass cap. Internal reference	-	-	100	Ksps	
SID109	A_SNDR	Signal-to-noise and distortion ratio (SINAD)	66	-	-	dB	F _{IN} = 10 kHz
SID111	A_INL	Integral non linearity	-1.4	-	+1.4	LSB	V _{DD} = 1.71 to 5.5, 1 Msps, Vref = 1 to 5.5.
SID111A	A_INL	Integral non linearity	-1.4	-	+1.4	LSB	V _{DDD} = 1.71 to 3.6, 1 Msps, Vref = 1.71 to V _{DDD} .
SID111B	A_INL	Integral non linearity	-1.4	-	+1.4	LSB	V _{DDD} = 1.71 to 5.5, 500 ksps, Vref = 1 to 5.5.
SID112	A_DNL	Differential non linearity	-0.9	-	+1.35	LSB	V _{DDD} = 1.71 to 5.5, 1 Msps, Vref = 1 to 5.5.
SID112A	A_DNL	Differential non linearity	-0.9	-	+1.35	LSB	V _{DDD} = 1.71 to 3.6, 1 Msps, Vref = 1.71 to V _{DDD} .
SID112B	A_DNL	Differential non linearity	-0.9	-	+1.35	LSB	V _{DDD} = 1.71 to 5.5, 500 ksps, Vref = 1 to 5.5.
SID113	A_THD	Total harmonic distortion	_	_	-65	dB	F _{IN} = 10 kHz.

CSD

Table 14. CSD Block Specification

Spec ID#	Parameter	Description	Min	Тур	Max	Units	Details/Conditions	
CSD Specification								
SID308	VCSD	Voltage range of operation	1.71	_	5.5	V		
SID309	IDAC1	DNL for 8-bit resolution	-1	_	1	LSB		
SID310	IDAC1	INL for 8-bit resolution	-3	_	3	LSB		
SID311	IDAC2	DNL for 7-bit resolution	-1	_	1	LSB		
SID312	IDAC2	INL for 7-bit resolution	-3	_	3	LSB		
SID313	SNR	Ratio of counts of finger to noise. Guaranteed by characterization	5	-	_	Ratio	Capacitance range of 9 to 35 pF, 0.1-pF sensitivity	
SID314	IDAC1_CRT1	Output current of Idac1 (8-bits) in High range	-	612	-	μA		
SID314A	IDAC1_CRT2	Output current of Idac1(8-bits) in Low range	-	306	-	μA		
SID315	IDAC2_CRT1	Output current of Idac2 (7-bits) in High range	_	304.8	-	μA		
SID315A	IDAC2_CRT2	Output current of Idac2 (7-bits) in Low range	_	152.4	_	μA		



LCD Direct Drive

Table 18. LCD Direct Drive DC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID154	ILCDLOW	Operating current in low power mode	-	5	-	μA	16 × 4 small segment disp. at 50 Hz
SID155	C _{LCDCAP}	LCD capacitance per segment/common driver	_	500	5000	pF	Guaranteed by Design
SID156	LCD _{OFFSET}	Long-term segment offset	-	20	-	mV	
SID157	I _{LCDOP1}	PWM Mode current. 5-V bias. 24-MHz IMO	-	0.6	-	mA	32 × 4 segments. 50 Hz, 25 °C
SID158	I _{LCDOP2}	PWM Mode current. 3.3-V bias. 24-MHz IMO.	-	0.5	-	mA	32 × 4 segments. 50 Hz, 25 °C

Table 19. LCD Direct Drive AC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID159	F _{LCD}	LCD frame rate	10	50	150	Hz	

Table 20. Fixed UART DC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID160	I _{UART1}	Block current consumption at 100 Kbps	-	-	55	μA	
SID161	I _{UART2}	Block current consumption at 1000 Kbps	_	_	312	μA	

Table 21. Fixed UART AC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID162	F _{UART}	Bit rate	_	Ι	1	Mbps	

SPI Specifications

Table 22. Fixed SPI DC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID163	I _{SPI1}	Block current consumption at 1 Mbps	-	-	360	μA	
SID164	I _{SPI2}	Block current consumption at 4 Mbps	-	-	560	μA	
SID165	I _{SPI3}	Block current consumption at 8 Mbps	-	-	600	μA	

Table 23. Fixed SPI AC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID166	F _{SPI}	SPI operating frequency (master; 6X oversampling)	Ι	Ι	8	MHz	



Table 24. Fixed SPI Master mode AC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID167	Т _{DMO}	MOSI valid after Sclock driving edge	-	-	15	ns	
SID168	T _{DSI}	MISO valid before Sclock capturing edge. Full clock, late MISO Sampling used	20	-	-	ns	
SID169	Т _{НМО}	Previous MOSI data hold time with respect to capturing edge at Slave	0	_	-	ns	

Table 25. Fixed SPI Slave mode AC Specifications

(Guaranteed by Characterization)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID170	Т _{DMI}	MOSI valid before Sclock capturing edge	40	-	-	ns	
SID171	T _{DSO}	MISO valid after Sclock driving edge	-	-	42 + 3 × (1/FCPU)	ns	
SID171A	T _{DSO_ext}	MISO valid after Sclock driving edge in Ext. Clock mode	-	-	48	ns	
SID172	T _{HSO}	Previous MISO data hold time	0	-	-	ns	
SID172A	T _{SSELSCK}	SSEL Valid to first SCK Valid edge	100	-	_	ns	

Memory

Table 26. Flash DC Specifications

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID173	V _{PE}	Erase and program voltage	1.71	-	5.5	V	

Table 27. Flash AC Specifications

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID174	T _{ROWWRITE}	Row (block) write time (erase and program)	-	_	20	ms	Row (block) = 128 bytes
SID175	T _{ROWERASE}	Row erase time	-	-	13	ms	
SID176	T _{ROWPROGRAM}	Row program time after erase	-	-	7	ms	
SID178	T _{BULKERASE}	Bulk erase time (128 KB)	-	_	35	ms	
SID179	T _{SECTORERASE}	Sector erase time (8 KB)	-	-	15	ms	
SID180	T _{DEVPROG}	Total device program time	-	_	15	seconds	Guaranteed by charac- terization
SID181	F _{END}	Flash endurance	100 K	_	_	cycles	Guaranteed by charac- terization
SID182	F _{RET}	Flash retention. $T_A \le 55 \degree$ C, 100 K P/E cycles	20	_	_	years	Guaranteed by charac- terization
SID182A		Flash retention. $T_A \le 85$ °C, 10 K P/E cycles	10	_	_	years	Guaranteed by charac- terization
SID182B	F _{RETQ}	Flash retention. $T_A \le 105$ °C, 10K P/E cycles, \le three years at $T_A \ge$ 85 °C	10	20	-	years	Guaranteed by charac- terization.



System Resources

Power-on-Reset (POR) with Brown Out

Table 28. Imprecise Power On Reset (PRES)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID185	V _{RISEIPOR}	Rising trip voltage	0.80	-	1.45	V	Guaranteed by charac- terization
SID186	V _{FALLIPOR}	Falling trip voltage	0.75	-	1.4	V	Guaranteed by charac- terization
SID187	V _{IPORHYST}	Hysteresis	15	-	200	mV	Guaranteed by charac- terization

Table 29. Precise Power On Reset (POR)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID190	V _{FALLPPOR}	BOD trip voltage in active and sleep modes	1.64	_	_	V	Guaranteed by charac- terization
SID192	V _{FALLDPSLP}	BOD trip voltage in Deep Sleep	1.4	-	-	V	Guaranteed by charac- terization

Voltage Monitors

Table 30. Voltage Monitors DC Specifications

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID195	V _{LVI1}	LVI_A/D_SEL[3:0] = 0000b	1.71	1.75	1.79	V	
SID196	V _{LVI2}	LVI_A/D_SEL[3:0] = 0001b	1.76	1.80	1.85	V	
SID197	V _{LVI3}	LVI_A/D_SEL[3:0] = 0010b	1.85	1.90	1.95	V	
SID198	V _{LVI4}	LVI_A/D_SEL[3:0] = 0011b	1.95	2.00	2.05	V	
SID199	V _{LVI5}	LVI_A/D_SEL[3:0] = 0100b	2.05	2.10	2.15	V	
SID200	V _{LVI6}	LVI_A/D_SEL[3:0] = 0101b	2.15	2.20	2.26	V	
SID201	V _{LVI7}	LVI_A/D_SEL[3:0] = 0110b	2.24	2.30	2.36	V	
SID202	V _{LVI8}	LVI_A/D_SEL[3:0] = 0111b	2.34	2.40	2.46	V	
SID203	V _{LVI9}	LVI_A/D_SEL[3:0] = 1000b	2.44	2.50	2.56	V	
SID204	V _{LVI10}	LVI_A/D_SEL[3:0] = 1001b	2.54	2.60	2.67	V	
SID205	V _{LVI11}	LVI_A/D_SEL[3:0] = 1010b	2.63	2.70	2.77	V	
SID206	V _{LVI12}	LVI_A/D_SEL[3:0] = 1011b	2.73	2.80	2.87	V	
SID207	V _{LVI13}	LVI_A/D_SEL[3:0] = 1100b	2.83	2.90	2.97	V	
SID208	V _{LVI14}	LVI_A/D_SEL[3:0] = 1101b	2.93	3.00	3.08	V	
SID209	V _{LVI15}	LVI_A/D_SEL[3:0] = 1110b	3.12	3.20	3.28	V	
SID210	V _{LVI16}	LVI_A/D_SEL[3:0] = 1111b	4.39	4.50	4.61	V	
SID211	LVI_IDD	Block current	_	_	100	μA	Guaranteed by charac- terization

Table 31. Voltage Monitors AC Specifications

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID212	T _{MONTRIP}	Voltage monitor trip time	1	-	1	μs	Guaranteed by charac- terization



SWD Interface

Table 32. SWD Interface Specifications

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID213	F_SWDCLK1	$3.3 \text{ V} \leq \text{V}_{DD} \leq 5.5 \text{ V}$	-	-	14	MHz	SWDCLK ≤ 1/3 CPU clock frequency
SID214	F_SWDCLK2	$1.71~V \leq V_{DD} \leq 3.3~V$	-	-	7	MHz	SWDCLK ≤ 1/3 CPU clock frequency
SID215	T_SWDI_SETUP	T = 1/f SWDCLK	0.25*T	-	-	ns	Guaranteed by characterization
SID216	T_SWDI_HOLD	T = 1/f SWDCLK	0.25*T	-	-	ns	Guaranteed by characterization
SID217	T_SWDO_VALID	T = 1/f SWDCLK	-	-	0.5*T	ns	Guaranteed by characterization
SID217A	T_SWDO_HOLD	T = 1/f SWDCLK	1	-	_	ns	Guaranteed by characterization

Internal Main Oscillator

Table 33. IMO DC Specifications

(Guaranteed by Design)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID218	I _{IMO1}	IMO operating current at 48 MHz	_	-	1000	μA	
SID219	I _{IMO2}	IMO operating current at 24 MHz	_	-	325	μA	
SID220	I _{IMO3}	IMO operating current at 12 MHz	_	-	225	μA	
SID221	I _{IMO4}	IMO operating current at 6 MHz	_	-	180	μA	
SID222	I _{IMO5}	IMO operating current at 3 MHz	_	-	150	μΑ	

Table 34. IMO AC Specifications

Spec ID	Parameter	ameter Description		Тур	Max	Units	Details/Conditions
SID223	F _{IMOTOL1}	Frequency variation from 3 to 48 MHz	-	-	±2	%	±3% if T _A > 85 °C and IMO frequency < 24 MHz
SID226	T _{STARTIMO}	IMO startup time	-	-	12	μs	
SID227	T _{JITRMSIMO1}	RMS Jitter at 3 MHz	-	156	-	ps	
SID228	T _{JITRMSIMO2}	RMS Jitter at 24 MHz	-	145	-	ps	
SID229	T _{JITRMSIMO3}	RMS Jitter at 48 MHz	-	139	-	ps	

Internal Low-Speed Oscillator

Table 35. ILO DC Specifications

(Guaranteed by Design)

Spec ID	Parameter	Description	Min	Тур	Max	Units	Details/Conditions
SID231	I _{ILO1}	ILO operating current at 32 kHz	-	0.3	1.05	μA	Guaranteed by Characterization
SID233	I _{ILOLEAK}	ILO leakage current	-	2	15	nA	Guaranteed by Design



Ordering Information

The PSoC 4200M family part numbers and features are listed in the following table.

								F	eatu	res						F	Packa	ages	
Category	NGM	Max CPU Speed (MHz)	Flash (KB)	SRAM (KB)	UDB	Opamp (CTBm)	CSD	IDAC (1X7-Bit, 1-8-Bit)	Direct LCD Drive	12-bit SAR ADC	LP Comparators	TCPWM Blocks	SCB Blocks	CAN	GPIO	48-TQFP	64-TQFP (0.5-mm pitch)	64-TQFP (0.8-mm pitch)	68-QFN
	CY8C4245AZI-M433	48	32	4	4	2	-	-	-	1000 ksps	2	8	4	-	38	~	-	-	-
	CY8C4245AZI-M443	48	32	4	4	2	~	-	~	1000 ksps	2	8	4	-	38	~	-	-	-
4245	CY8C4245AZI-M445	48	32	4	4	2	~	-	~	1000 ksps	2	8	4	-	51	-	~	-	-
	CY8C4245LTI-M445	48	32	4	4	2	~	-	~	1000 ksps	2	8	4	-	55	-	_	-	~
	CY8C4245AXI-M445	48	32	4	4	2	~	-	~	1000 ksps	2	8	4	-	51	-	-	~	-
	CY8C4246AZI-M443	48	64	8	4	2	~	-	~	1000 ksps	2	8	4	-	38	~	-	-	-
	CY8C4246AZI-M445	48	64	8	4	2	~	-	~	1000 ksps	2	8	4	-	51	-	~	-	-
1216	CY8C4246AZI-M475	48	64	8	4	4	-	~	-	1000 ksps	2	8	4	-	51	Ι	~	-	-
4240	CY8C4246LTI-M445	48	64	8	4	2	~	-	~	1000 ksps	2	8	4	-	55	Ι	-	-	~
	CY8C4246LTI-M475	48	64	8	4	4	-	~	_	1000 ksps	2	8	4	-	55	-	-	-	~
	CY8C4246AXI-M445	48	64	8	4	2	~	-	~	1000 ksps	2	8	4	-	51	Ι	-	~	-
	CY8C4247LTI-M475	48	128	16	4	4	~	~	_	1000 ksps	2	8	4	-	55	-	-	-	~
	CY8C4247AZI-M475	48	128	16	4	4	-	~	_	1000 ksps	2	8	4	-	51	-	~	-	-
4247	CY8C4247AZI-M485	48	128	16	4	4	~	~	~	1000 ksps	2	8	4	~	51	-	~	-	-
	CY8C4247AXI-M485	48	128	16	4	4	~	~	~	1000 ksps	2	8	4	~	51	-	-	~	-
	CY8C4247LTQ-M475	48	128	16	4	4	~	~	~	1000 ksps	2	8	4	-	55	-	-	-	~

The nomenclature used in the preceding table is based on the following part numbering convention:

Field	Description	Values	Meaning
CY8C	Cypress Prefix		
4	Architecture	4	PSoC 4
А	Family	2	4200 Family
В	CPU Speed	4	48 MHz
		4	16 KB
C	Elech Consoity	5 32 KB	
C	Flash Capacity	6	64 KB
		7	128 KB
		AX, AZ	TQFP
DE	Baakaga Cada	LT	QFN
	Fachage Coue	BU	BGA
		FD	CSP



Field	Description	Values	Meaning		
F	Temperature Range	I	Industrial		
	r remperature Range (Extended Industrial		
		N/A	PSoC 4 Base Series		
S	Silicon Family	L PSoC 4 L-Series			
3	Shicon Farmiy	BL	PSoC 4 BLE		
		М	PSoC 4 M-Series		
XYZ	Attributes Code	000-999	Code of feature set in the specific family		

Part Numbering Conventions

The part number fields are defined as follows.

	CY8C	4	Α	В	<u>C</u>	D	E	F ·	· <u>s</u>	XYZ
Cypress Prefix –									T	
Architecture –										
Family Group within Architecture –										
Speed Grade –										
Flash Capacity –										
Package Code –										
Silicon Family								-		
Attributes Code										



Packaging

The description of the PSoC4200M package dimensions follows.

Spec ID#	Package	Description	Package Dwg #
PKG_1	68-pin QFN	68-pin QFN, 8 mm x 8 mm x 1.0 mm height with 0.4 mm pitch	001-09618
PKG_2	64-pin TQFP	64-pin TQFP, 10 mm x10 mm x 1.4 mm height with 0.5 mm pitch	51-85051
PKG_4	64-pin TQFP	64-pin TQFP, 14 mm x14 mm x 1.4 mm height with 0.8 mm pitch	51-85046
PKG_5	48-pin TQFP	48-pin TQFP, 7 mm x 7 mm x 1.4 mm height with 0.5 mm pitch	51-85135
PKG_6	44-pin TQFP	44-pin TQFP, 10 mm x 10 mm x 1.4 mm height with 0.8 mm pitch	51-85064

Table 43. Package Characteristics

Parameter	Description	Conditions	Min	Тур	Max	Units
T _A	Operating ambient temperature		-40	25	85	°C
TJ	Operating junction temperature		-40		100	°C
T _{JA}	Package θ _{JA} (68-pin QFN)		-	16.8	-	°C/Watt
T _{JC}	Package θ_{JC} (68-pin QFN)		-	2.9	-	°C/Watt
T _{JA}	Package θ _{JA} (64-pin TQFP, 0.5-mm pitch)		-	56	-	°C/Watt
T _{JC}	Package θ _{JC} (64-pin TQFP, 0.5-mm pitch)		-	19.5	-	°C/Watt
T _{JA}	Package θ _{JA} (64-pin TQFP, 0.8-mm pitch)		-	66.4	-	°C/Watt
T _{JC}	Package θ_{JC} (64-pin TQFP, 0.8-mm pitch)		-	18.2	-	°C/Watt
T _{JA}	Package θ _{JA} (48-pin TQFP, 0.5-mm pitch)		-	67.3	-	°C/Watt
T _{JC}	Package θ _{JC} (48-pin TQFP, 0.5-mm pitch)		-	30.4	-	°C/Watt
T _{JA}	Package θ _{JA} (44-pin TQFP, 0.8-mm pitch)		-	57	-	°C/Watt
T _{JC}	Package θ _{JC} (44-pin TQFP, 0.8-mm pitch)		-	25.9	-	°C/Watt

Table 44. Solder Reflow Peak Temperature

Package	Maximum Peak Temperature	Maximum Time at Peak Temperature
All packages	260 °C	30 seconds

Table 45. Package Moisture Sensitivity Level (MSL), IPC/JEDEC J-STD-2

Package	MSL
All packages	MSL 3



Acronyms

Table 46. Acronyms Used in this Document

Acronym	Description
abus	analog local bus
ADC	analog-to-digital converter
AG	analog global
АНВ	AMBA (advanced microcontroller bus archi- tecture) high-performance bus, an ARM data transfer bus
ALU	arithmetic logic unit
AMUXBUS	analog multiplexer bus
API	application programming interface
APSR	application program status register
ARM®	advanced RISC machine, a CPU architecture
ATM	automatic thump mode
BW	bandwidth
CAN	Controller Area Network, a communications protocol
CMRR	common-mode rejection ratio
CPU	central processing unit
CRC	cyclic redundancy check, an error-checking protocol
DAC	digital-to-analog converter, see also IDAC, VDAC
DFB	digital filter block
DIO	digital input/output, GPIO with only digital capabilities, no analog. See GPIO.
DMIPS	Dhrystone million instructions per second
DMA	direct memory access, see also TD
DNL	differential nonlinearity, see also INL
DNU	do not use
DR	port write data registers
DSI	digital system interconnect
DWT	data watchpoint and trace
ECC	error correcting code
ECO	external crystal oscillator
EEPROM	electrically erasable programmable read-only memory
EMI	electromagnetic interference
EMIF	external memory interface
EOC	end of conversion
EOF	end of frame
EPSR	execution program status register
ESD	electrostatic discharge

Table 46. Acronyms Used in this Document (continu	ied)
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Acronym	Description
ETM	embedded trace macrocell
FIR	finite impulse response, see also IIR
FPB	flash patch and breakpoint
FS	full-speed
GPIO	general-purpose input/output, applies to a PSoC pin
HVI	high-voltage interrupt, see also LVI, LVD
IC	integrated circuit
IDAC	current DAC, see also DAC, VDAC
IDE	integrated development environment
I ² C, or IIC	Inter-Integrated Circuit, a communications protocol
lir	infinite impulse response, see also FIR
ILO	internal low-speed oscillator, see also IMO
IMO	internal main oscillator, see also ILO
INL	integral nonlinearity, see also DNL
I/O	input/output, see also GPIO, DIO, SIO, USBIO
IPOR	initial power-on reset
IPSR	interrupt program status register
IRQ	interrupt request
ITM	instrumentation trace macrocell
LCD	liquid crystal display
LIN	Local Interconnect Network, a communications protocol.
LR	link register
LUT	lookup table
LVD	low-voltage detect, see also LVI
LVI	low-voltage interrupt, see also HVI
LVTTL	low-voltage transistor-transistor logic
MAC	multiply-accumulate
MCU	microcontroller unit
MISO	master-in slave-out
NC	no connect
NMI	nonmaskable interrupt
NRZ	non-return-to-zero
NVIC	nested vectored interrupt controller
NVL	nonvolatile latch, see also WOL
opamp	operational amplifier
PAL	programmable array logic, see also PLD
PC	program counter
РСВ	printed circuit board



Document Conventions

Units of Measure

Table 47. Units of Measure

Symbol	Unit of Measure
°C	degrees Celsius
dB	decibel
fF	femto farad
Hz	hertz
KB	1024 bytes
kbps	kilobits per second
Khr	kilohour
kHz	kilohertz
kΩ	kilo ohm
ksps	kilosamples per second
LSB	least significant bit
Mbps	megabits per second
MHz	megahertz
MΩ	mega-ohm
Msps	megasamples per second
μA	microampere
μF	microfarad
μH	microhenry
μs	microsecond
μV	microvolt
μW	microwatt
mA	milliampere
ms	millisecond
mV	millivolt
nA	nanoampere
ns	nanosecond
nV	nanovolt
Ω	ohm
pF	picofarad
ppm	parts per million
ps	picosecond
s	second
sps	samples per second
sqrtHz	square root of hertz
V	volt